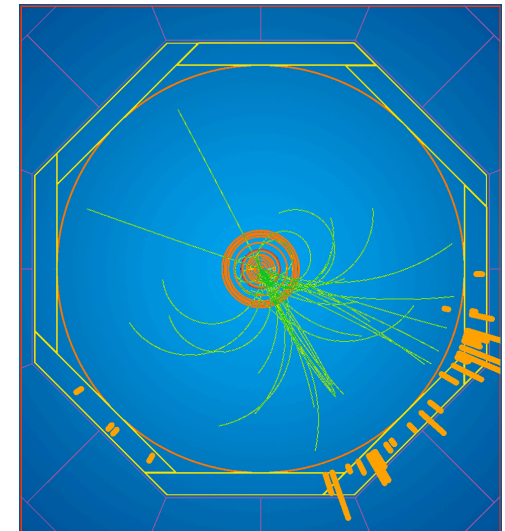


# Tracking: New tracking tools in the context of ILD and how it will evolve to generic tracking

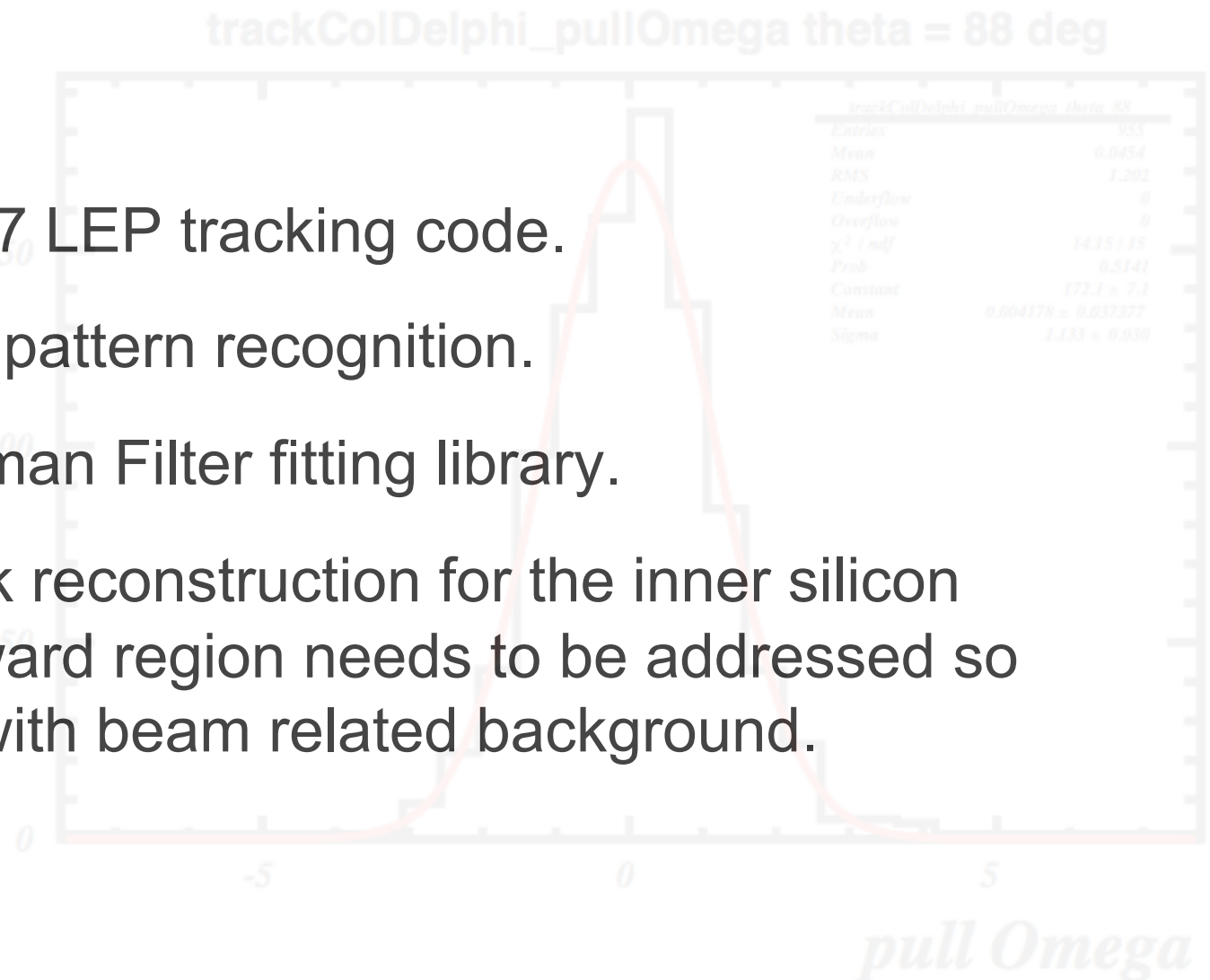
Steve Aplin

Linear Collider Software Meeting  
3<sup>rd</sup> January 2011

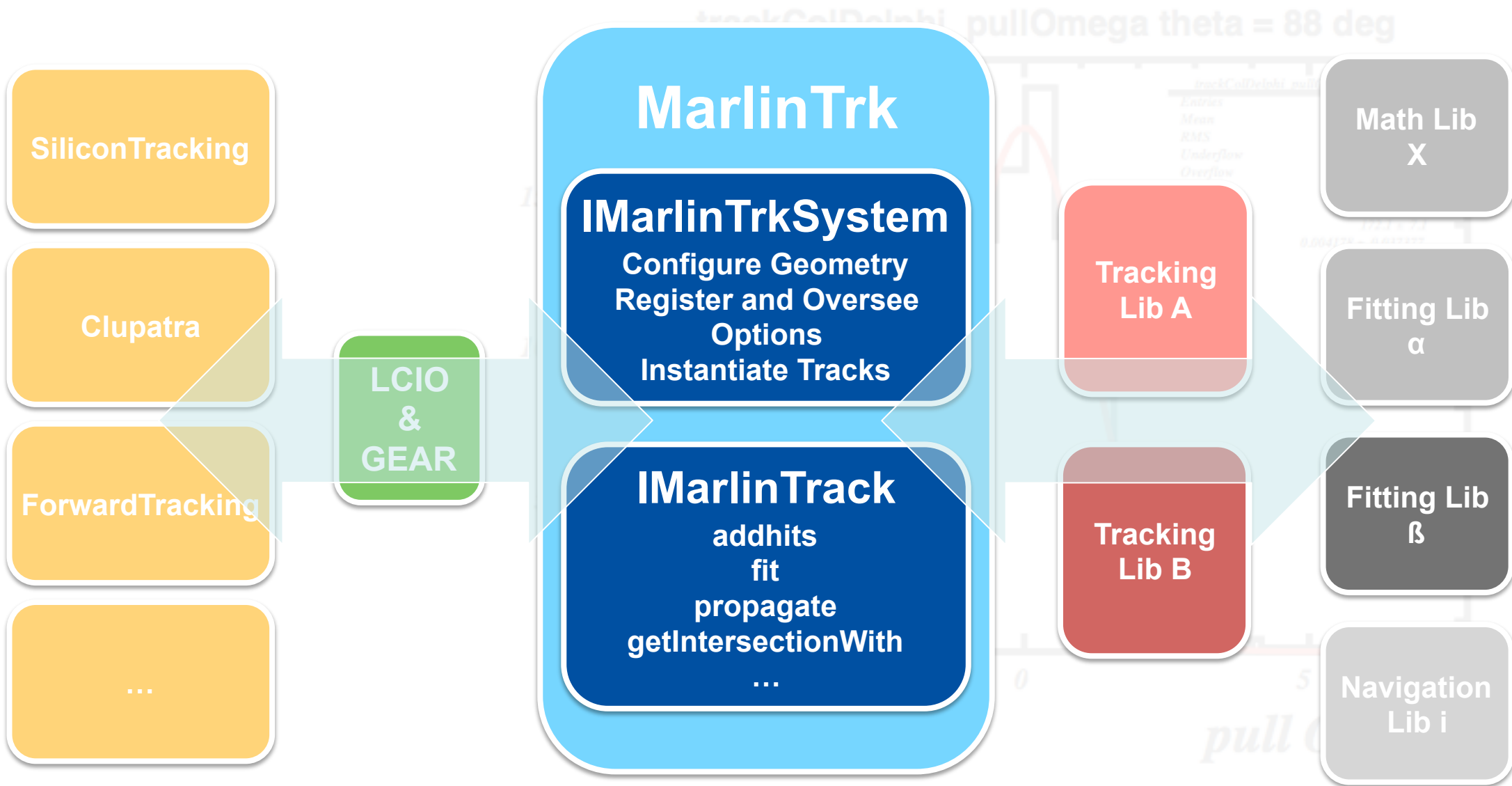


# Tracking Code rewrite for the DBD

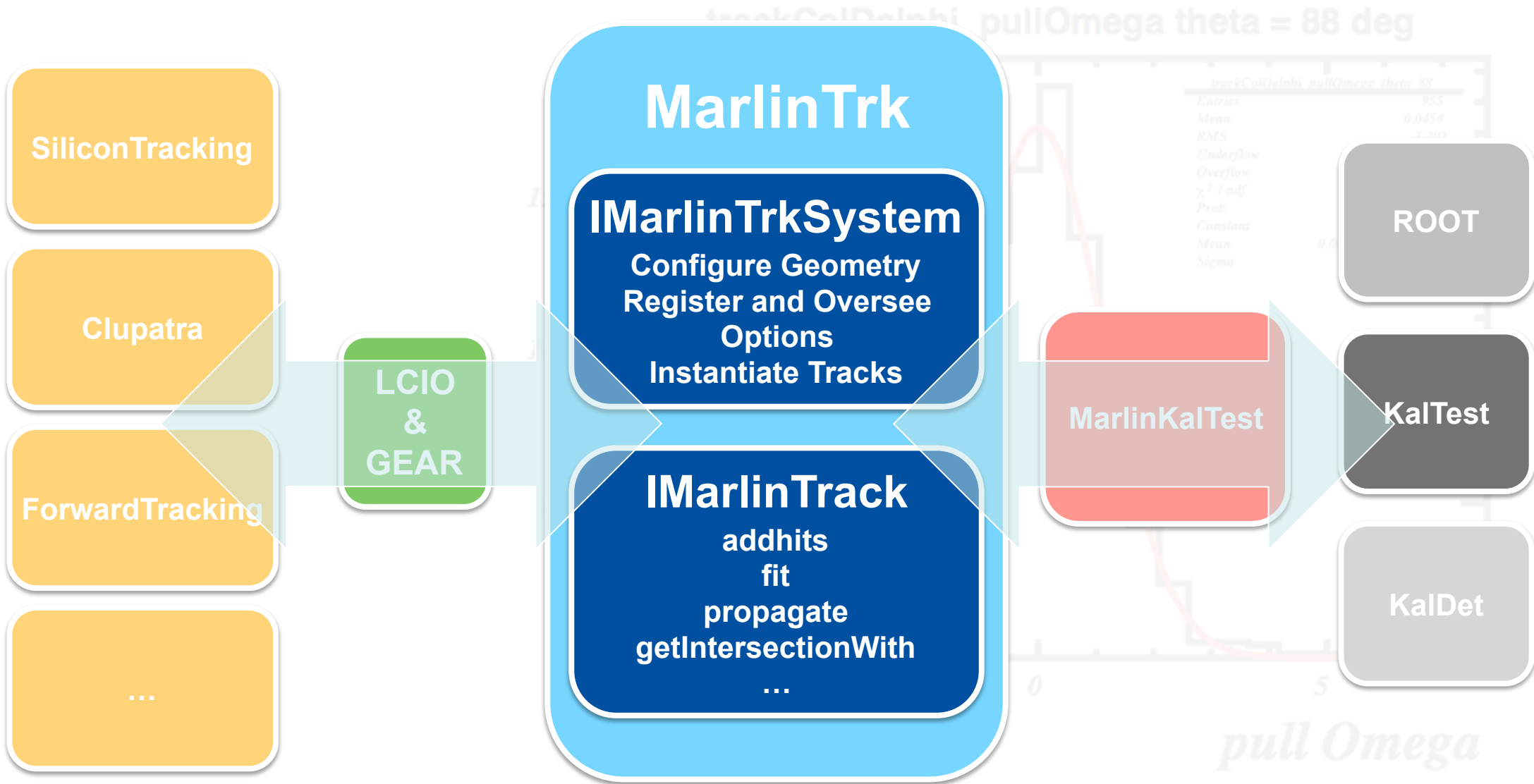
- Leave behind F77 LEP tracking code.
- Rewrite the TPC pattern recognition.
- Use KalTest Kalman Filter fitting library.
- Stand alone track reconstruction for the inner silicon trackers and forward region needs to be addressed so that it can cope with beam related background.



# IMarlinTrack and IMarlinTrkSystem



# MarlinTrk KalTest Implementation



# IMarlinTrack Interface

- **IMarlinTrack** interface provides a convenient interface when using an iterative fitter and also during pattern recognition.
- Examples of methods provided:

```
/** initialise the fit using the supplied hits only, using the given order to determine the direction of the track
```

```
virtual int initialise( bool direction ) = 0 ;
```

```
/** initialise the fit with a track state
```

```
virtual int initialise( const IMPL::TrackStateImpl& ts ) = 0 ;
```

```
/** update the current fit using the supplied hit, return code via int. Provides the Chi2 increment to the fit from adding the hit via reference.
```

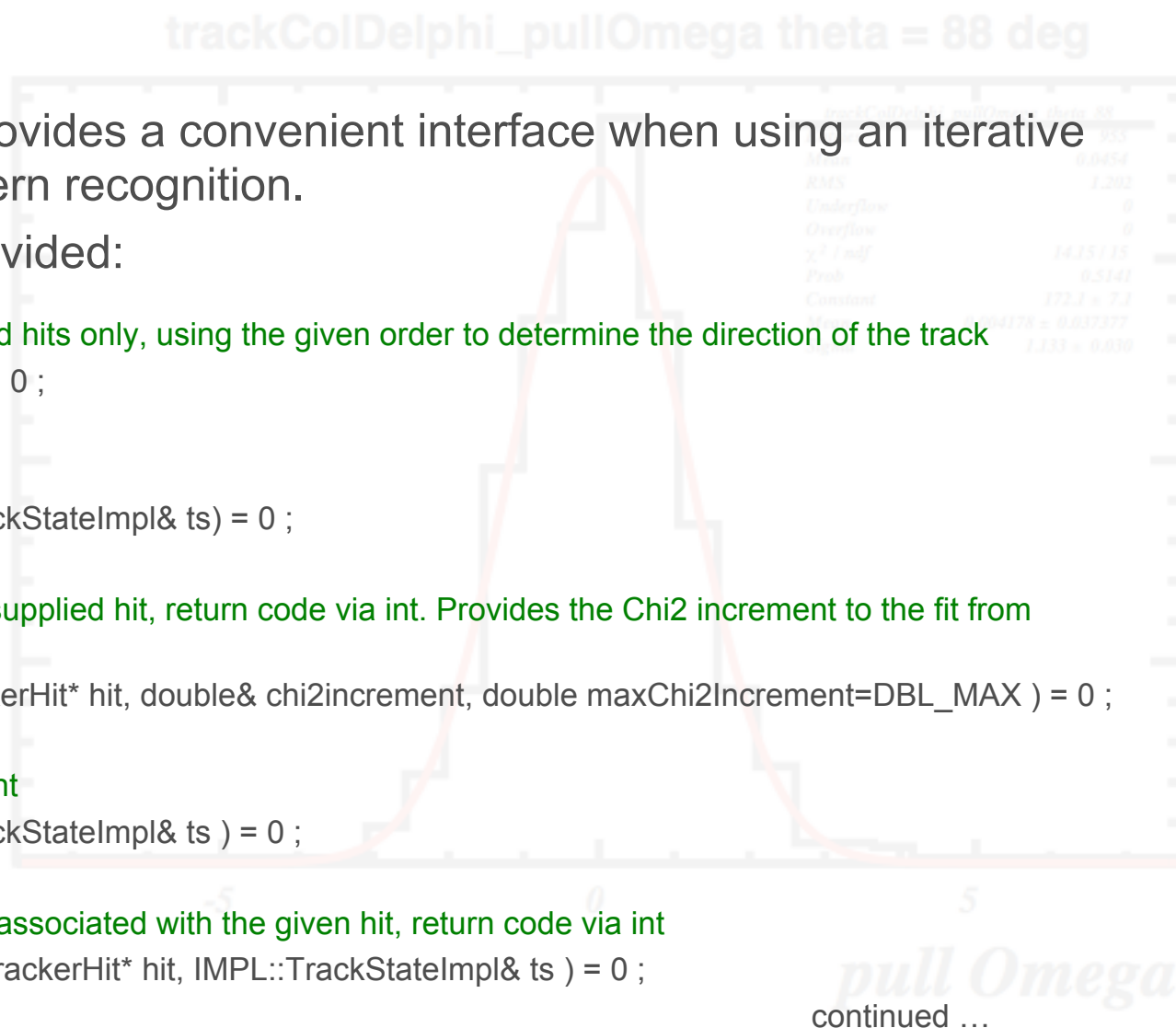
```
virtual int addAndFit( EVENT::TrackerHit* hit, double& chi2increment, double maxChi2Increment=DBL_MAX ) = 0 ;
```

```
/** get track state, return code via int
```

```
virtual int getTrackState( IMPL::TrackStateImpl& ts ) = 0 ;
```

```
/** get track state at measurement associated with the given hit, return code via int
```

```
virtual int getTrackState( EVENT::TrackerHit* hit, IMPL::TrackStateImpl& ts ) = 0 ;
```



# IMarlinTrack and IMarlinTrkSystem

**trackColDelphi\_pullOmega** theta = 88 deg

/\*\* propagate track state at measurement associated with the given hit, the fit to the point of closest approach to the given point.

```
virtual int propagate( const gear::Vector3D& point, EVENT::TrackerHit* hit, IMPL::TrackStateImpl& ts) = 0 ;
```

/\*\* propagate track state at measurement associated with the given hit, to numbered sensitive layer, returning TrackState via provided reference

```
virtual int propagateToLayer( bool direction, int layerNumber, EVENT::TrackerHit* hit, IMPL::TrackStateImpl& ts) = 0 ;
```

/\*\* extrapolate track state at measurement associated with the given hit, to the point of closest approach to the given point.

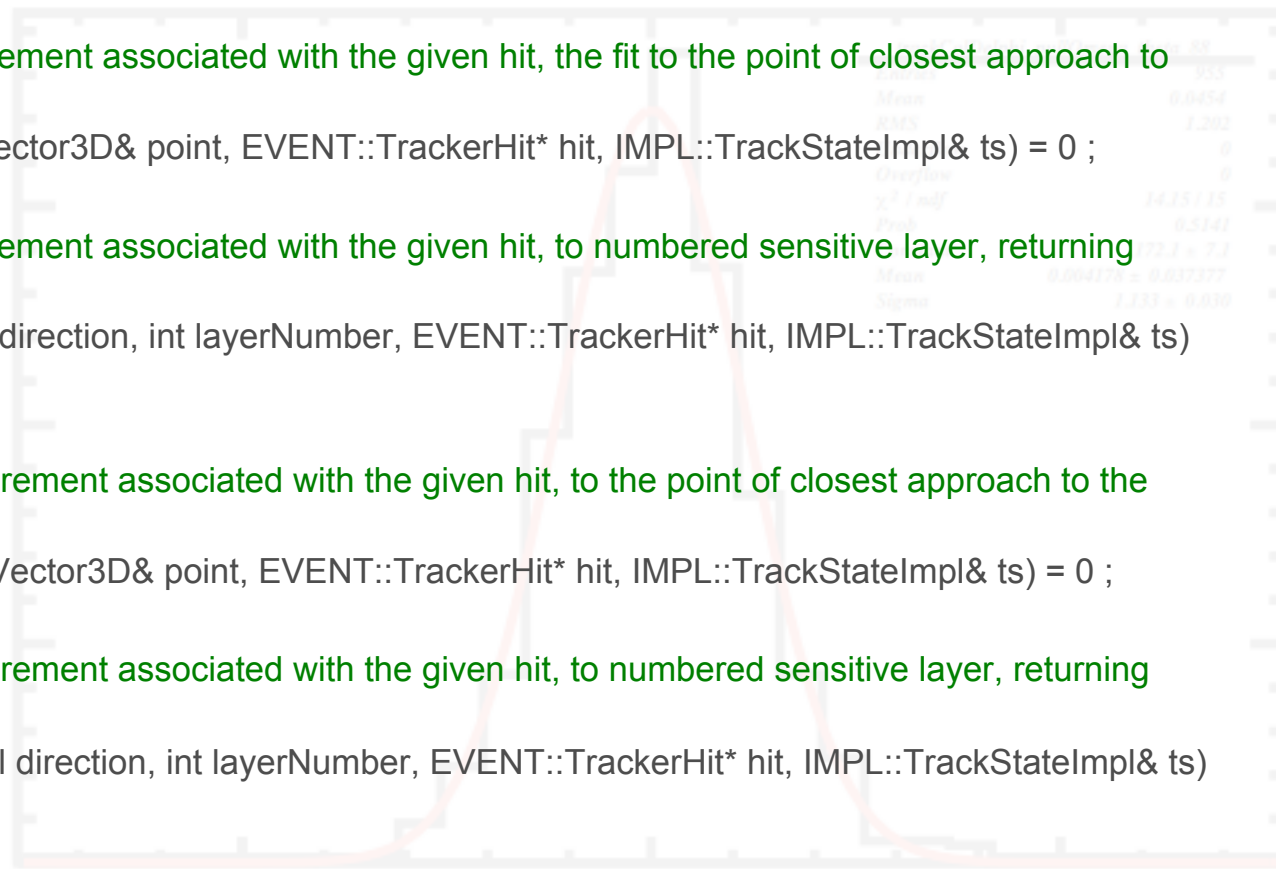
```
virtual int extrapolate( const gear::Vector3D& point, EVENT::TrackerHit* hit, IMPL::TrackStateImpl& ts) = 0 ;
```

/\*\* extrapolate track state at measurement associated with the given hit, to numbered sensitive layer, returning TrackState via provided reference

```
virtual int extrapolateToLayer( bool direction, int layerNumber, EVENT::TrackerHit* hit, IMPL::TrackStateImpl& ts) = 0 ;
```

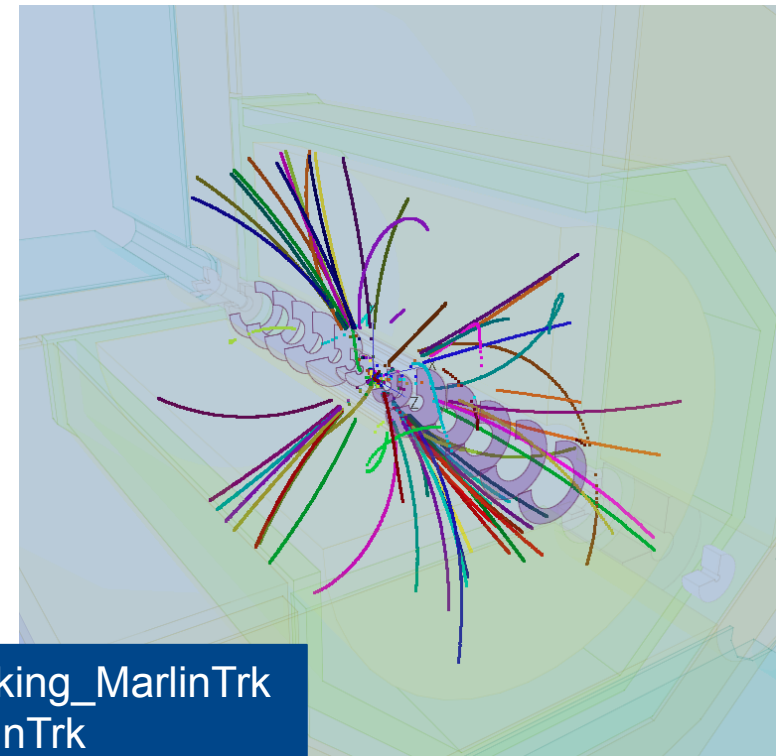
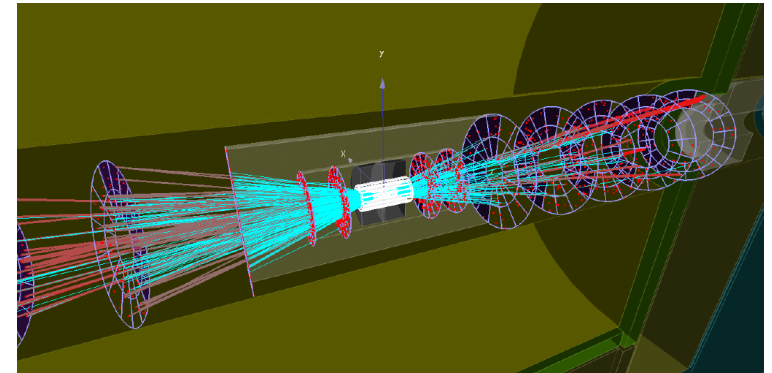
/\*\* extrapolate track state at measurement associated with the given hit, to numbered sensitive layer, returning intersection point in global coordinates

```
virtual int intersectionWithLayer( bool direction, int layerNumber, EVENT::TrackerHit* hit, gear::Vector3D& point) = 0 ;
```



# Complete Track Reconstruction

- TPC Pattern Recognition, Clupatra being refined for running on dense jets at the TeV scale.
- Both SiliconTracking and FullLDCTracking have been fully adapted to use MarlinTrk.
- Tracks produced by Forward Tracking still to be incorporated into the final track collection.
- Validation On-going.



ttbar event @ 500 GeV reconstructed using Clupatra and SiliconTracking\_MarlinTrk then combined into full tracks using FullLDCTracking\_MarlinTrk

# Plans for Tracking Package in Aida

- We need to design it in a way that it is generic enough such that it could be used for other such studies into detector R&D.
- This places the emphasis on providing a toolkit which includes the necessary building blocks needed to put together a realistic track reconstruction.
- Joint activity between DESY and OEAW.



# Summary

- Of course we need to have a fully working tracking package available at all times.
- We continue to prototype ideas in the iLCSoft framework, which can then be implemented within the Tracking Toolkit for AIDA as it develops.
- Interaction between tracking, geometry and clients will be key ...

