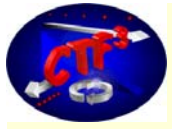


Electromagnetic monitors and acquisition systems

L. Søby



Electromagnetic monitors



Electrostatic Pick-up's (BPE)

Inductive Pick-up's (BPM, BPI, BPS, PBPM)

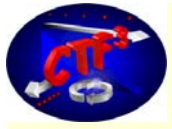
Button Pick-up's (BPR)

Wall current monitors (WCM)

Cavity BPM's

} Low frequency

} High frequency



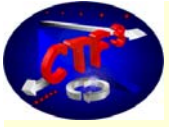
Overview



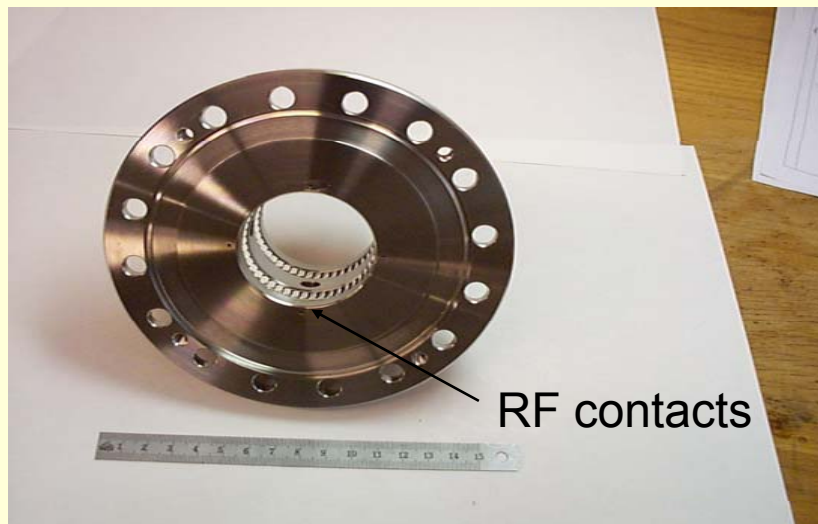
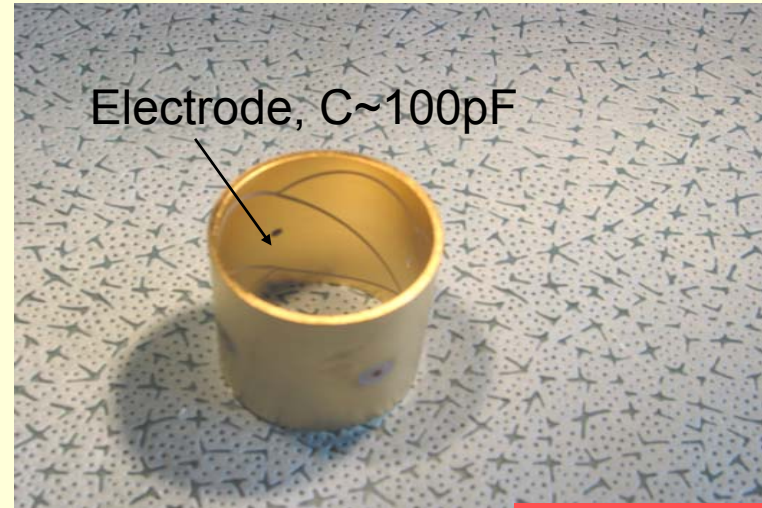
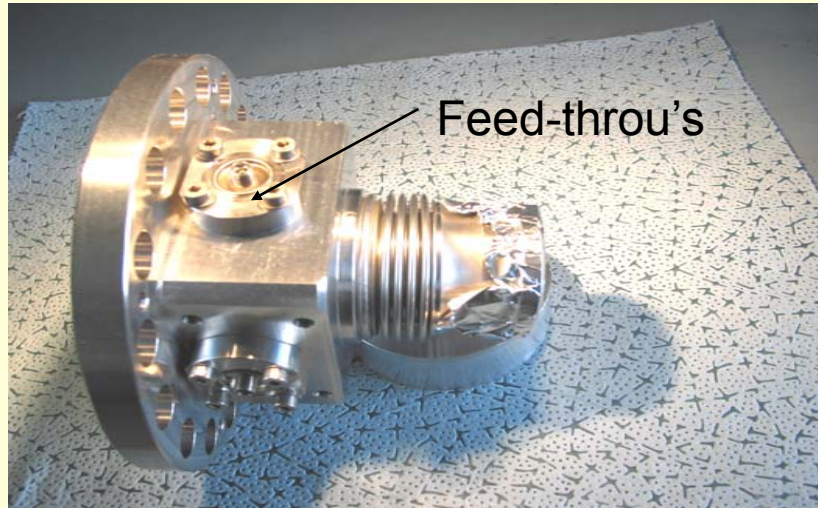
LINAC (CL)	PETS (CP)	CT (CT)	Delay- Loop (CD)	TL1 (CT)	Comb. Ring (CR)	TL2 (CC)	TL2' (CM)
2 * BPE 13 * BPM 2 * BPR 3 * WCM	3 * BPM	5 * BPM 3 * BPI 1 * BPR 1 * WCM 3 * PBPM	16 * BPI	7 * BPI	5 * BPM 20 * BPI 1 * BPR	5 * BPM 6 * BPI 1 * BPR 1 * WCM	3 * BPM

TBL (2008) (CB)	TBTS (CM, CA)	CALIFES (CT)
1 * BPM 1 * BPS	10 * BPM	6* CAV. BPM

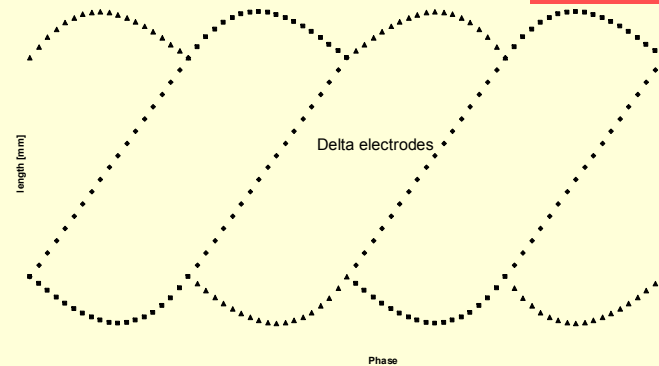
A total of 116 Monitors



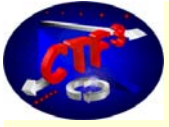
Electrostatic Pick-up (BPE)



$$\hat{V}(t) = \frac{i(t)}{v} \cdot \frac{l_{eff}}{C_{Elec}}$$



Developed by L. Søby, CERN

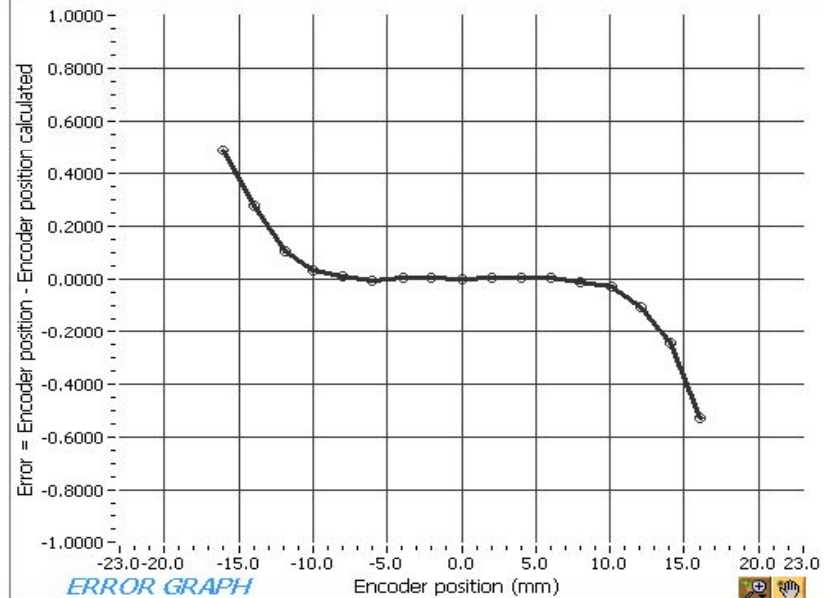
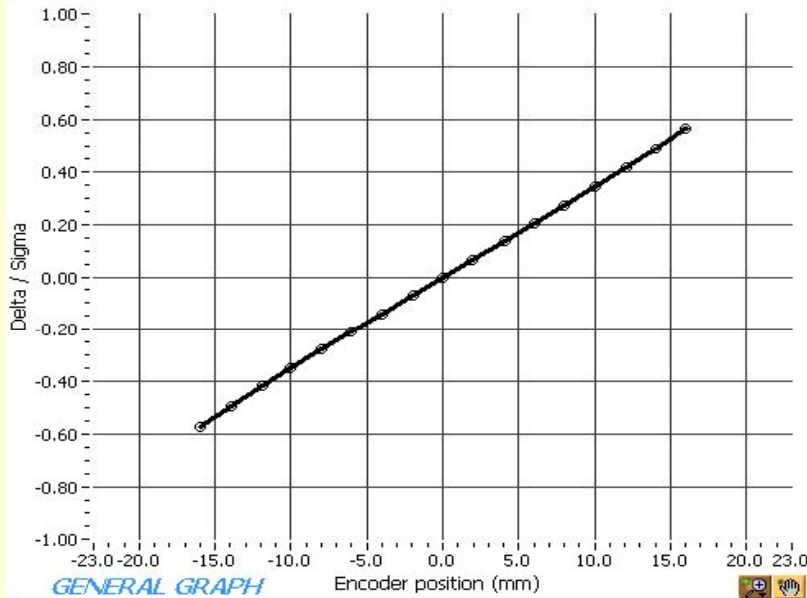


Electrostatic Pick-up (BPE)

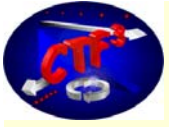


PICK-UP SEMI AUTOMATED CALIBRATION BENCH -- GRAPHS RESULTS

Author's name	Pick-Up name	Front end name	Comments
<input type="text"/>	<input type="text" value="BPE"/>	<input type="text" value="Buffer hybrid"/>	
Date	Pick-Up number	Pick-Up diameter (mm)	Front end number
<input type="text" value="26 09 2003"/>	<input type="text" value="2"/>	<input type="text" value="46"/>	<input type="text" value="1"/>



General			Curve fitting		Polynomial Coefficients b0: 1.027E-1 b1: 2.920E+1	Equation of fitted curve Delta / Sigma Delta / Sigma = +102.661E-3 + 29.200E+0 Pos
Step size	Number of points	Offset (mm)	Polynomial order	Max Error D/S		
<input type="text" value="2"/>	<input type="text" value="17"/>	<input type="text" value="0.00"/>	<input type="text" value="1"/>	<input type="text" value="0.5289"/>		
Mechanical zero (mm)	Scanned		Max Error S (V)	FE installed ? (coef.)		
<input type="text" value="0.00"/>	<input type="button" value="Vertically"/>		<input type="text" value="0.0003"/>	<input type="checkbox"/> <input type="text" value="0.0000"/>		
			Impedance (Ohms)			
			<input type="text" value="0.000E+0"/>			



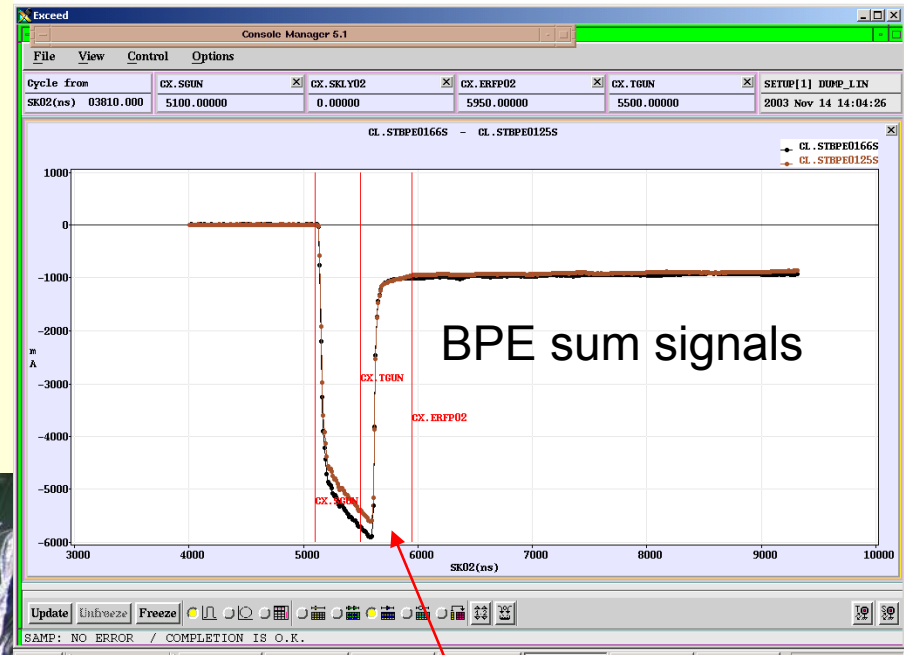
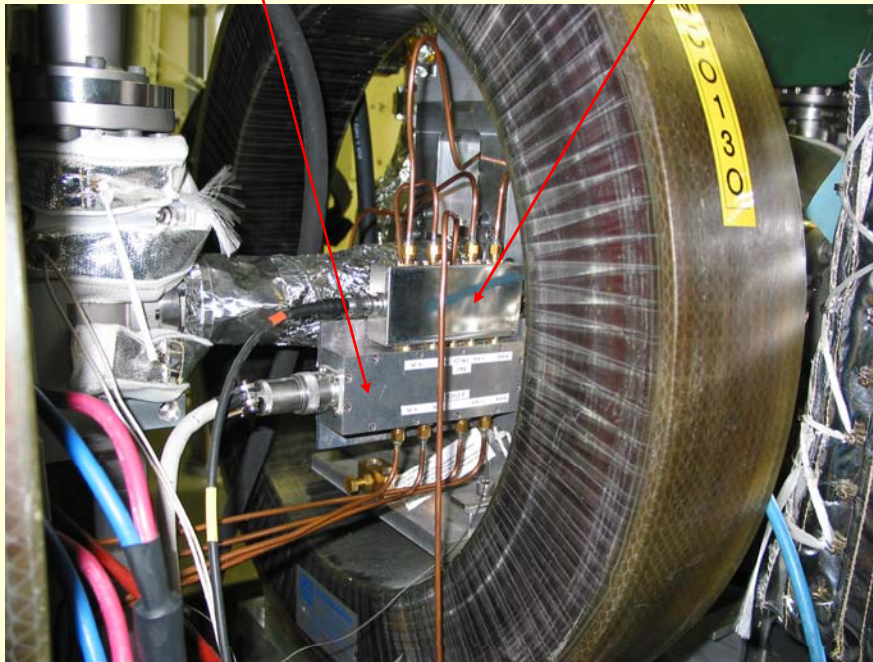
Electrostatic PU (BPE)



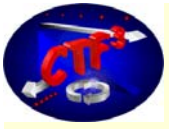
$$F_{Low} = \frac{1}{2 \cdot \pi \cdot R_L \cdot C_{Elec}}$$

Buffer amplifier, $R_L = 1M\Omega$

HT bias



Electrodes charging up due to beam halo!



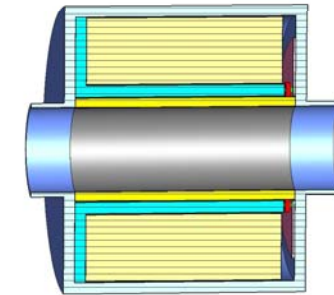
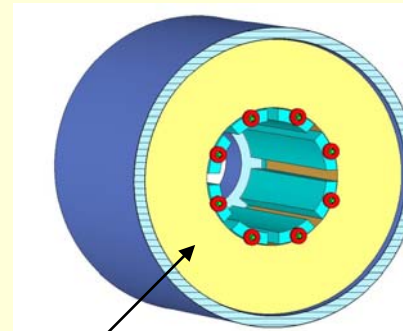
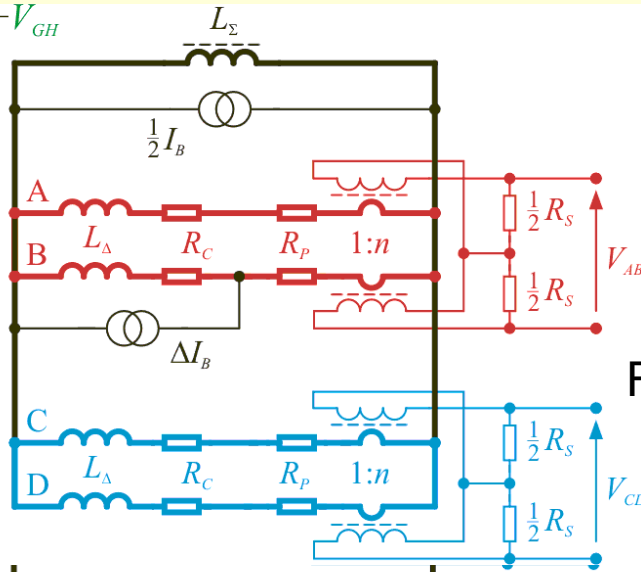
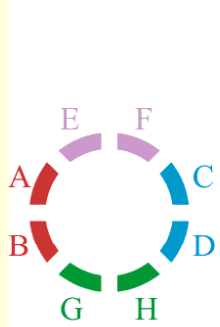
Inductive Pick-Up's (BPM, BPS)



$$V_{\Sigma} = V_{AB} + V_{CD} + V_{EF} + V_{GH}$$

$$V_{\Delta H} = V_{AB} - V_{CD}$$

$$V_{\Delta V} = V_{EF} - V_{GH}$$



Ferrite

$$R_P = \frac{R_S}{2n^2}$$

$$R_T = \frac{V_{\Sigma}}{I_B} = \frac{R_S}{2n}$$

- Electrodes are combined in pairs so that each transformer sees half of the load
- Frequency low cut-offs are limited by connection parasitic resistances
- Each transformer has one calibration turn (not shown)

$n = 30$, $R_S \cong 7 \Omega$ giving $R_T \cong 0.1 \Omega$ and $R_P \cong 4 \text{ m}\Omega$

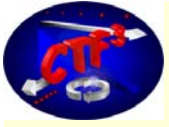
$f_{L\Sigma} \cong 150 \text{ Hz}$ (R_P with $L_{\Sigma} \cong 5 \mu\text{H}$)

$f_{L\Delta} \cong 10 \text{ kHz}$ (R_P with $L_{\Delta} \cong 70 \text{ nH}$)

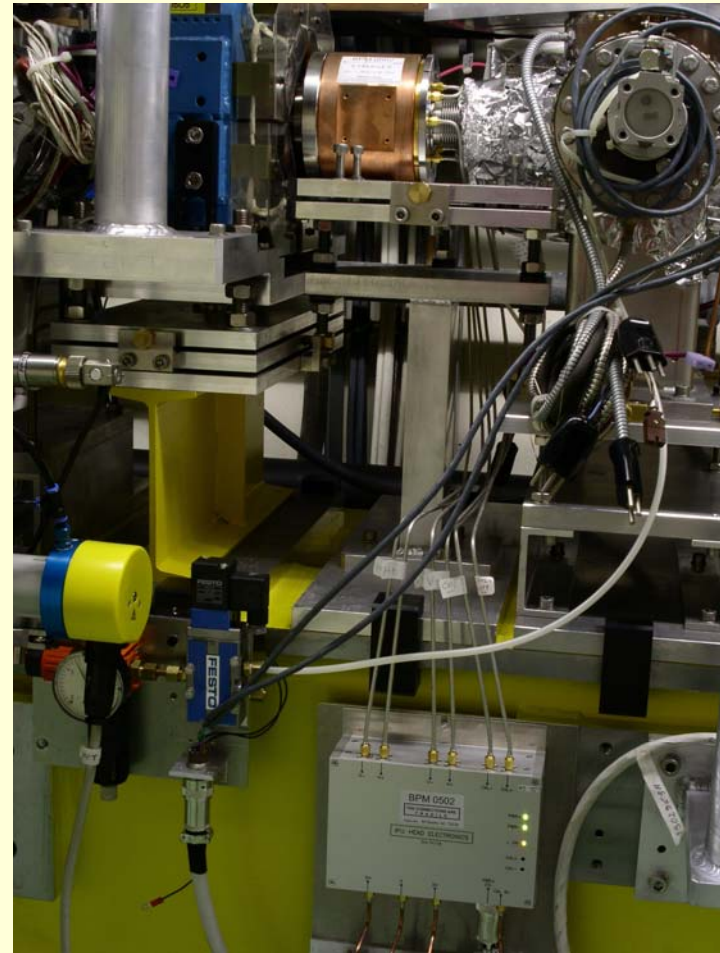
$$f_{L\Sigma} = \frac{1}{2\pi L_{\Sigma}} \left(\frac{R_S}{2n^2} + R_C \right)$$

$$f_{L\Delta} = \frac{1}{2\pi L_{\Delta}} \left(\frac{R_S}{2n^2} + R_C \right)$$

Slide by M. Gasior

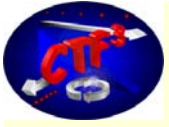


Inductive pick-up's (BPM)



Developed by M. Gasior, CERN

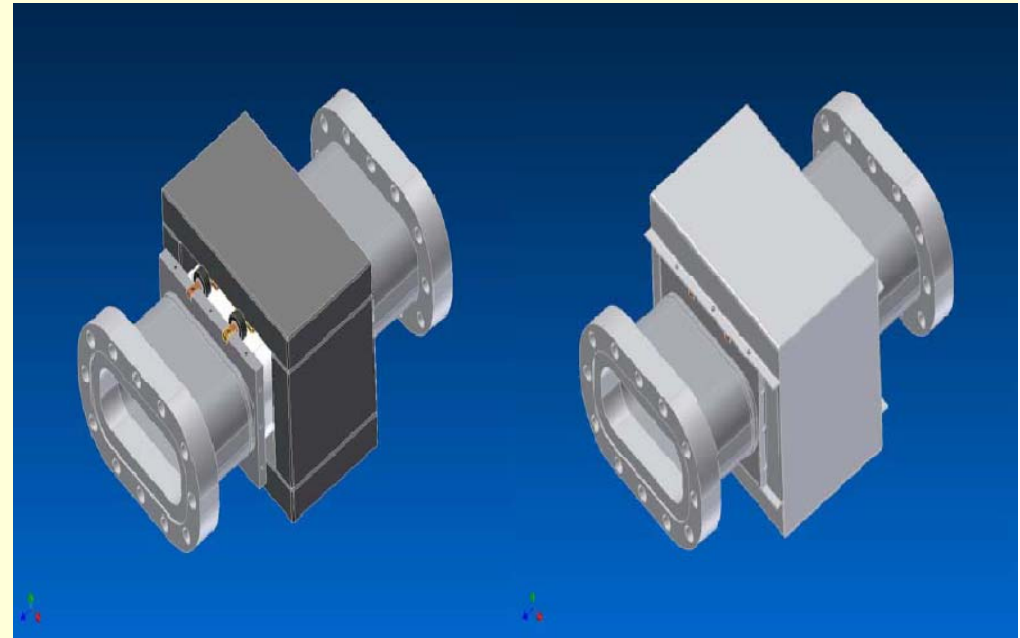
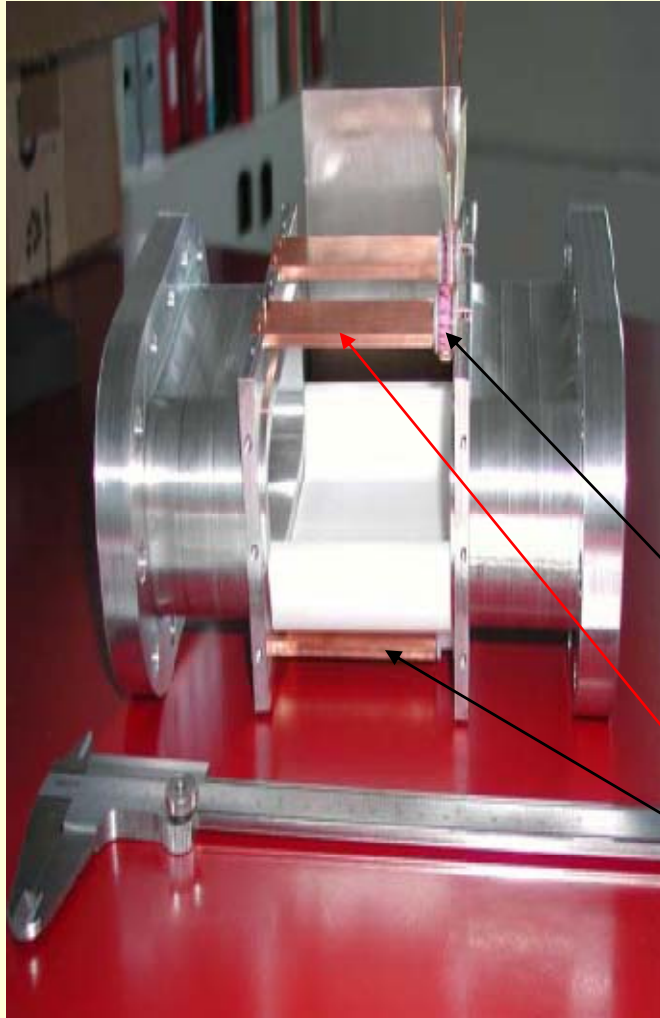
45 BPM's installed as from march 2008



Inductive Pick-up's (BPI)



Developed by A. Stella, Frascati



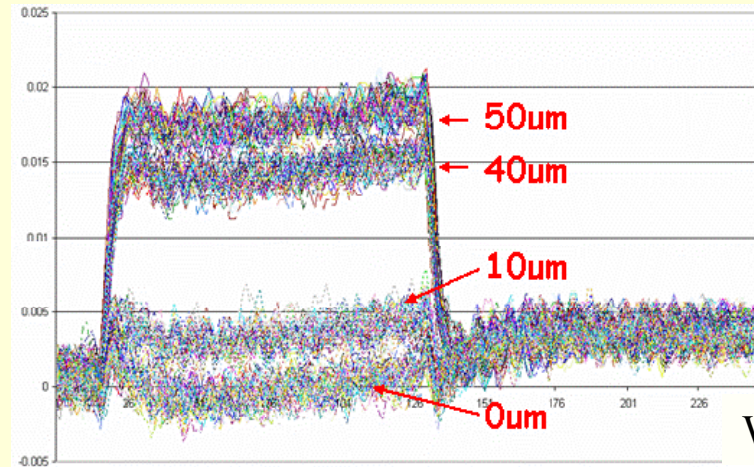
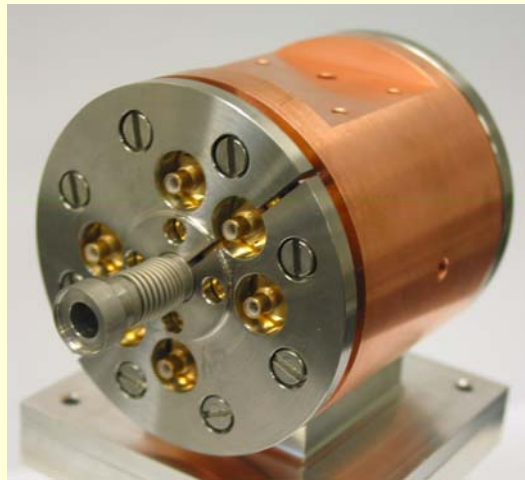
Current transformer with 30 turns and $R_L=14\Omega$

4 electrodes installed on racetrack chamber

52 BPI's installed as from march 2008



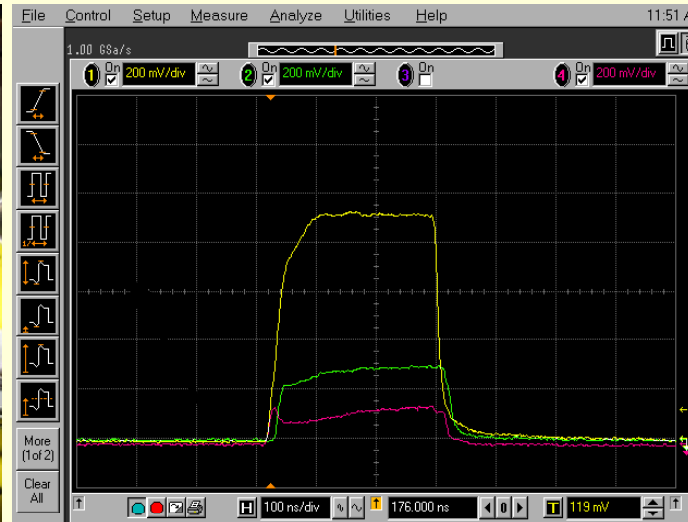
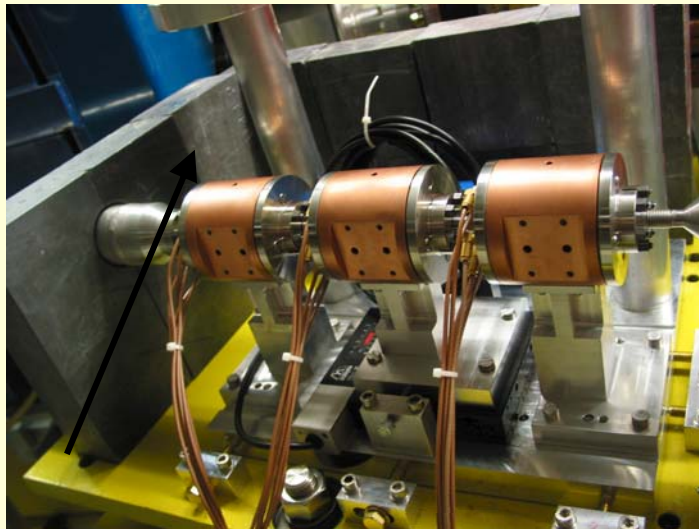
Inductive pick-ups, PBPM



Mean=17.4mV
 $\sigma=0.87\text{mV}$
 $\sigma=2.5\mu\text{m}$

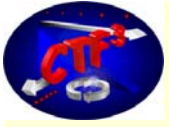
Wire current 100mA

PBPM proto type with 6mm inner diameter and 4 electrodes, resolution 200nm

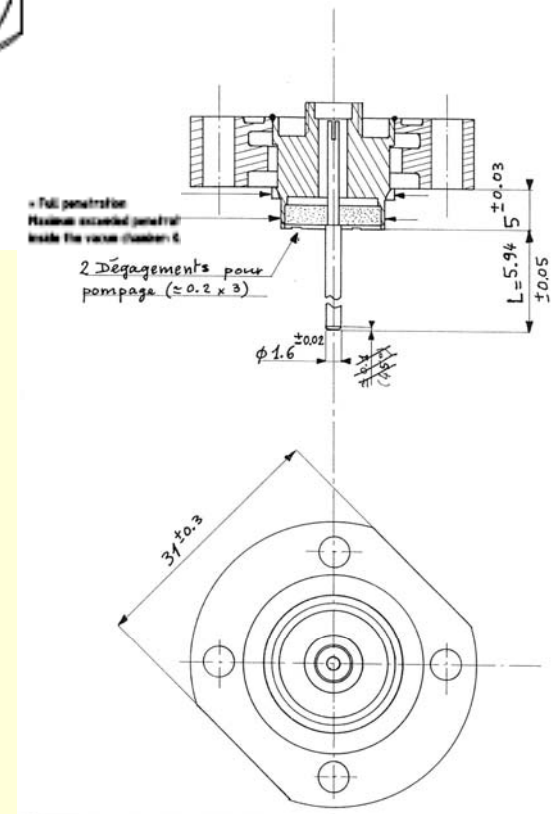
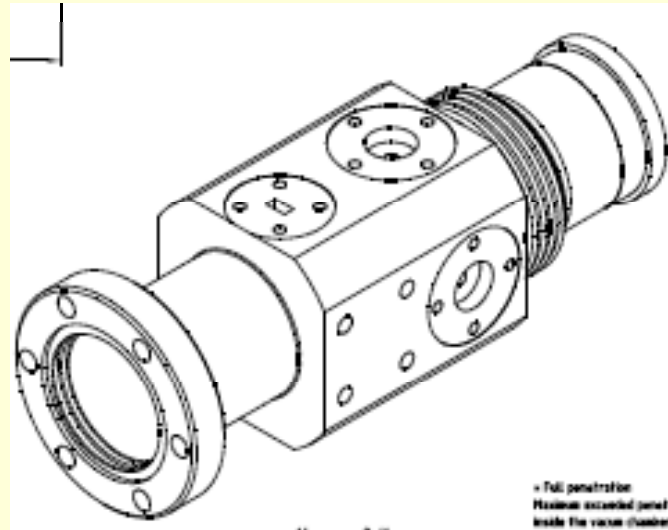
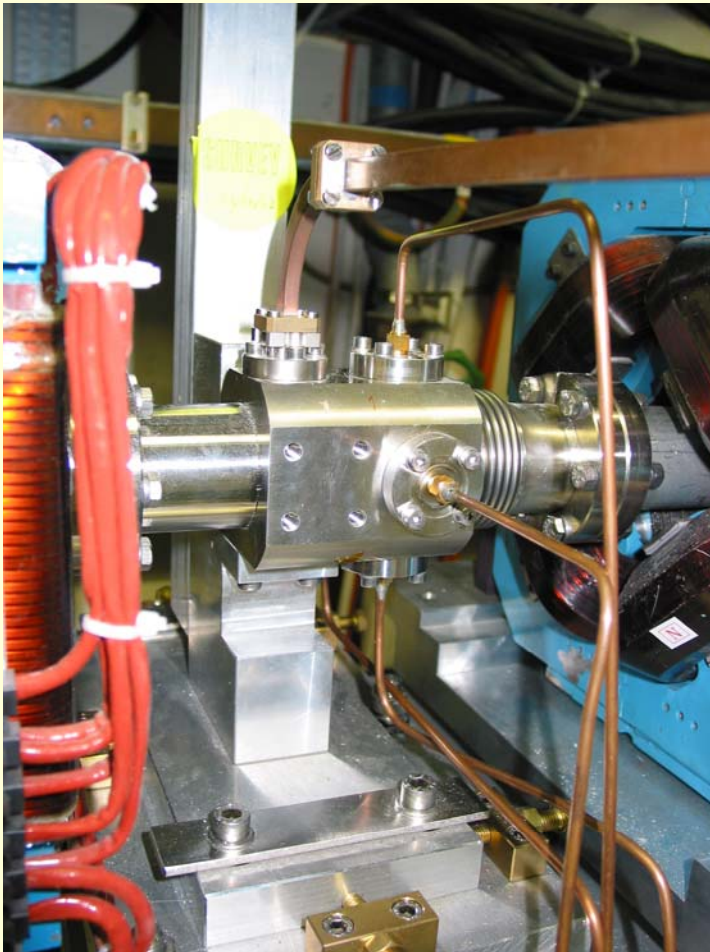


1st beam with
 poor transmission
 3rd December 2007.
 3rd PBPM only 10%

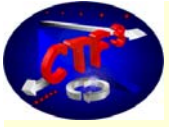
Developed by I.
 Podadera
 L. Søyby



Button Pick-up's (BPR)



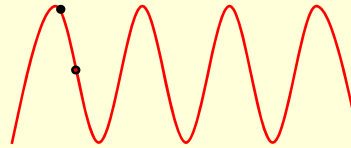
Developed by L. Thorndahl et al.



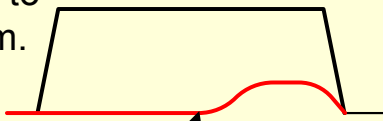
Button Pick-up's (BPR)



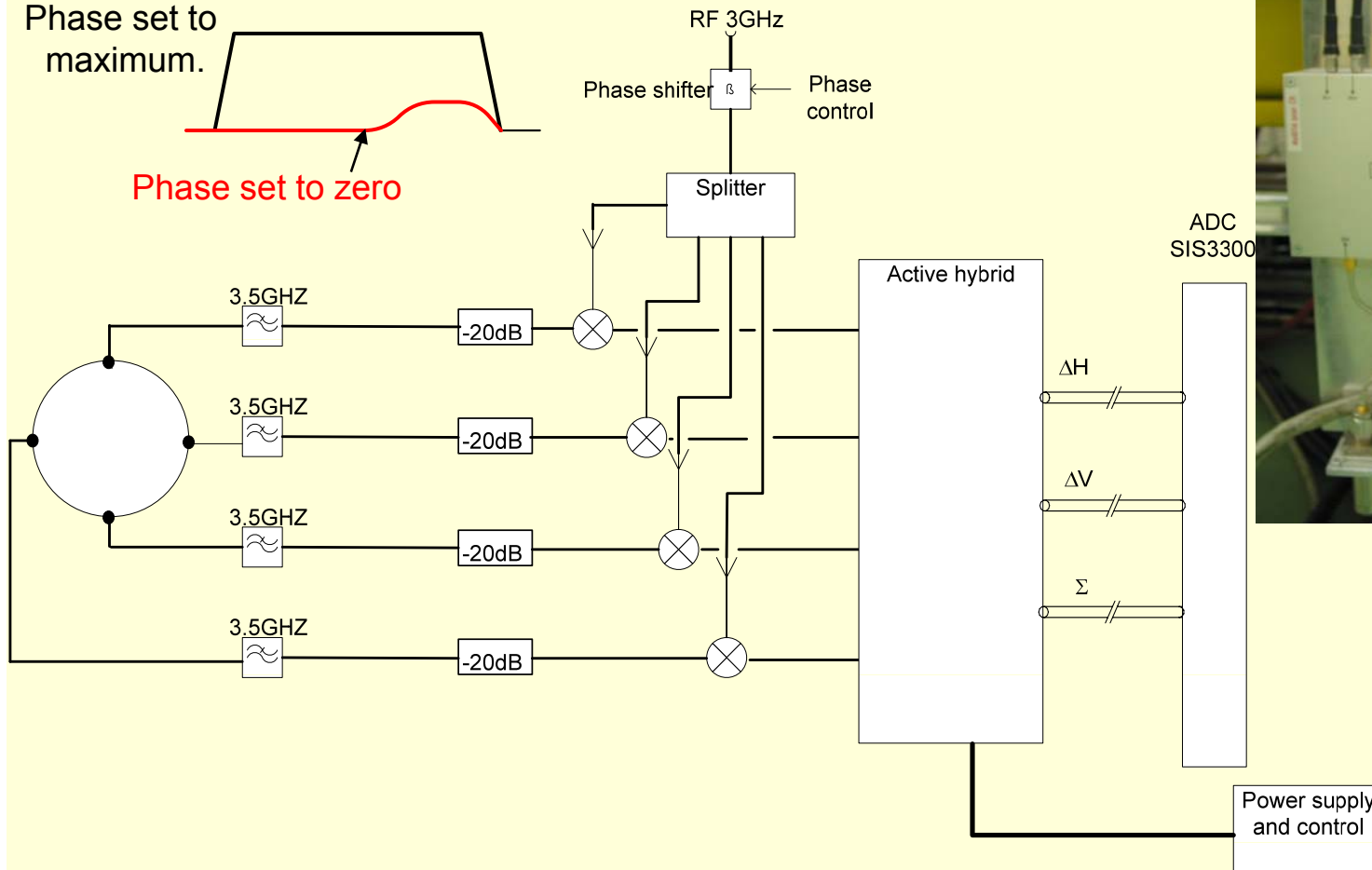
Button electronics

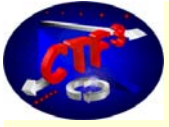


Phase set to maximum.

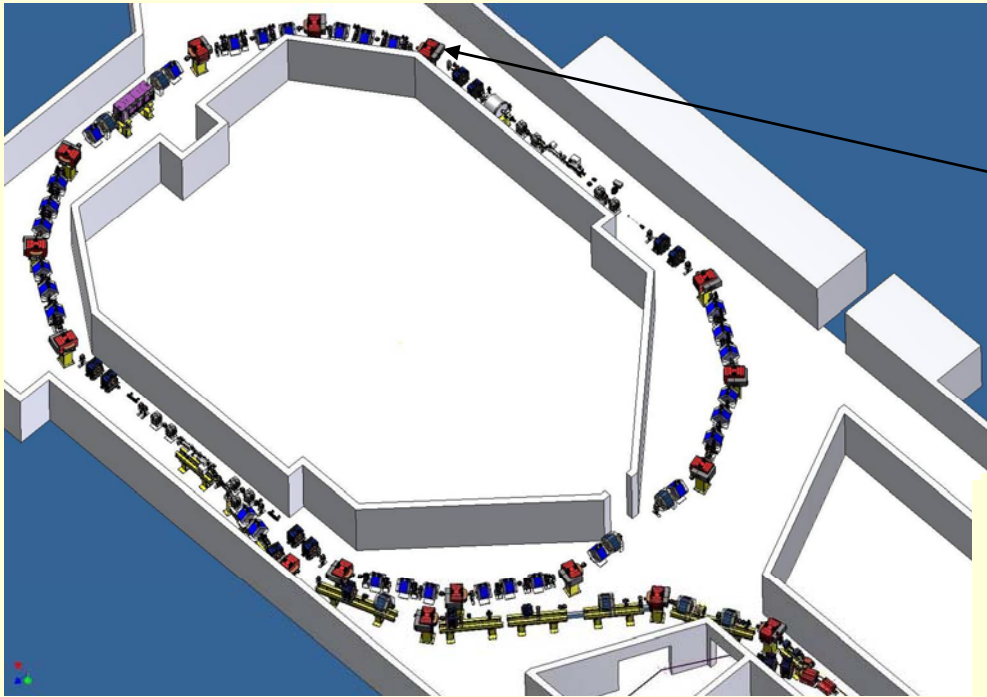


Phase set to zero



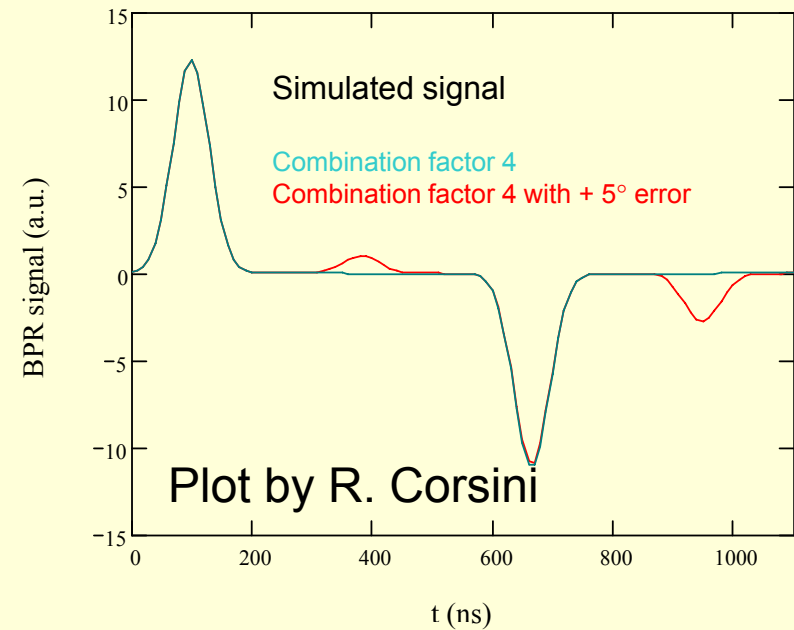


Button Pick-up's (BPR)



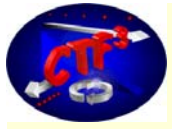
BPR – RF phase monitor

Combiner ring path length



$$N * \lambda + \frac{\pi}{2}$$

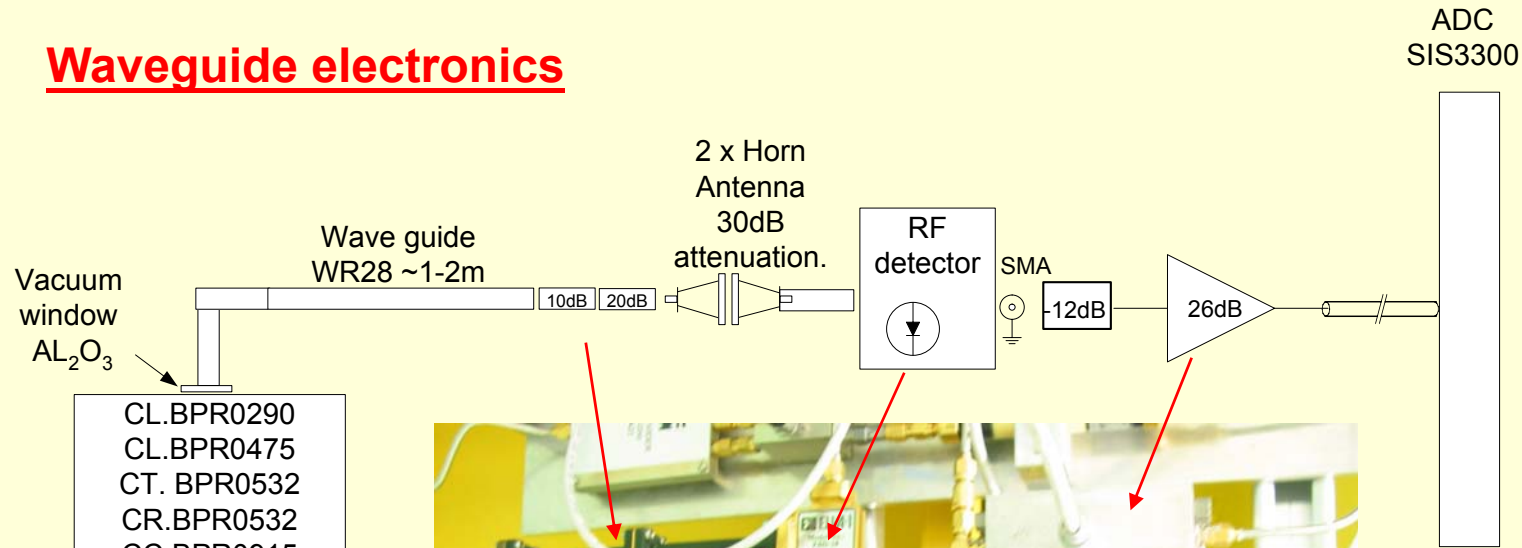
Phase advance per turn (3GHz)



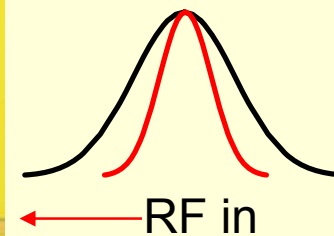
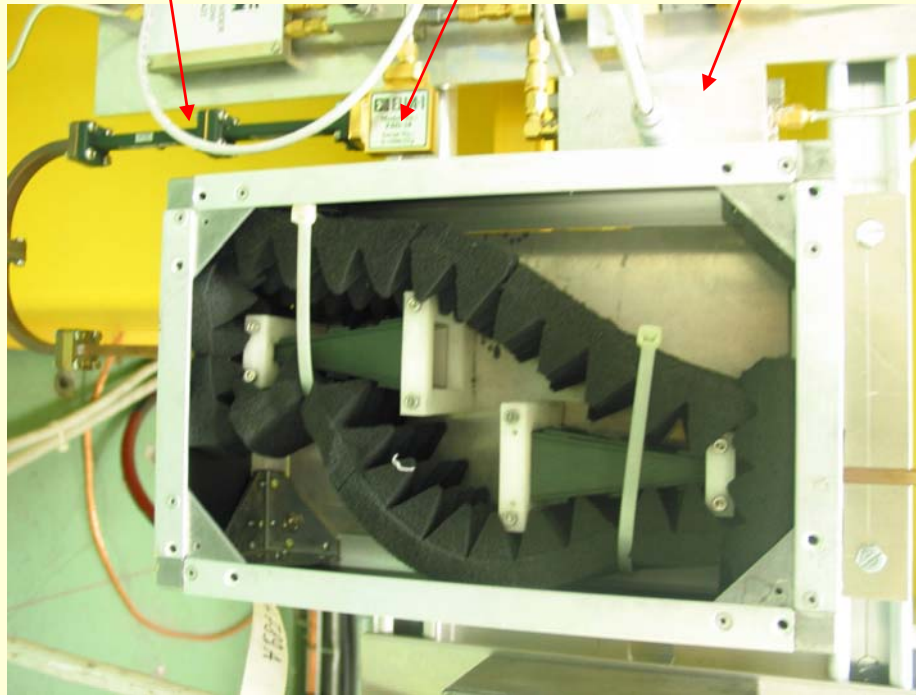
Button Pick-up's (BPR)



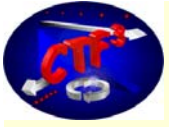
Waveguide electronics



- CL.BPR0290
- CL.BPR0475
- CT. BPR0532
- CR.BPR0532
- CC.BPR0915



Shorter bunches means more power in the WR28

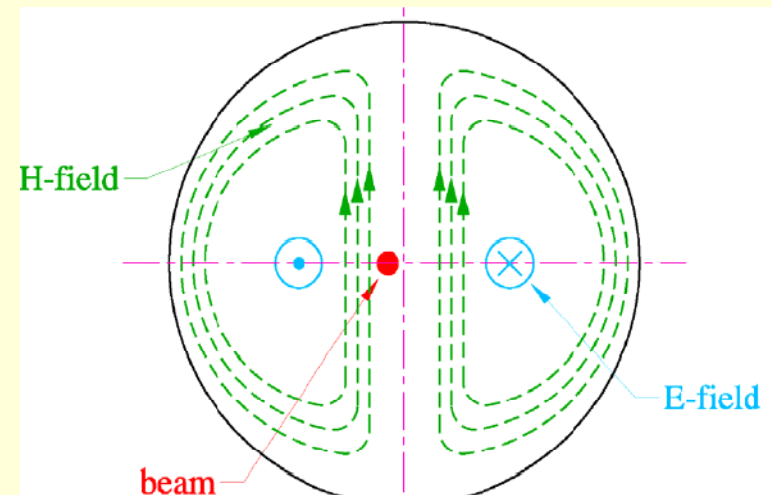
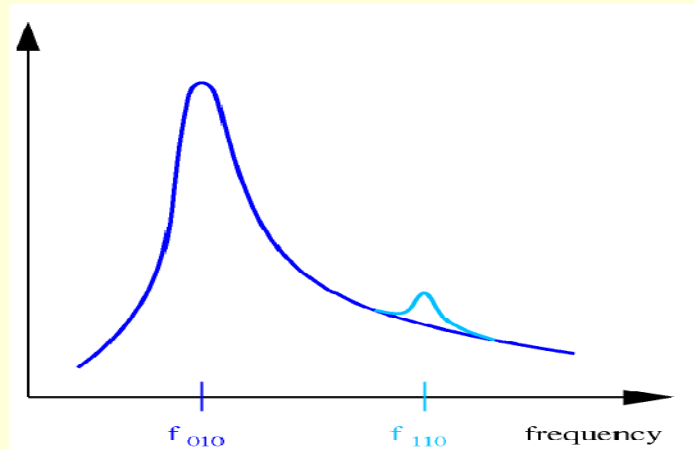
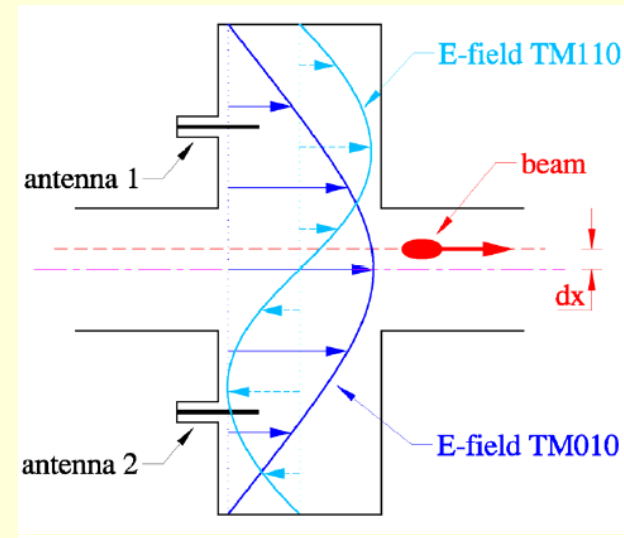


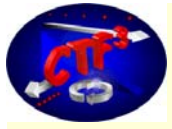
Re-entrant Cavity BPM (CALIFES)



- + Difference of large numbers problem reduced to rejection of the primary fundamental peak. Frequency domain.
- + Damping time quite high due to intrinsic high Q. $Q_L \rightarrow < 50$

$$\tau = \frac{Q_{ld}}{\pi * f_{Dip}} \rightarrow \text{Poor time resolution } (\sim 100\text{ns})$$

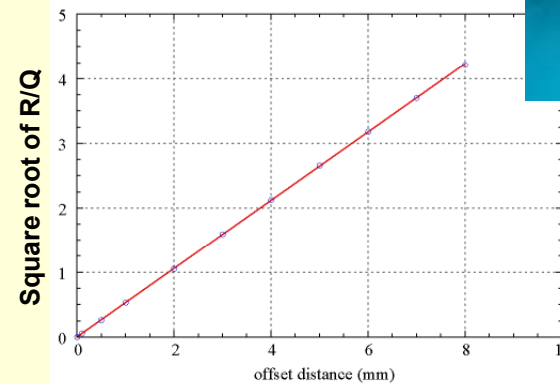




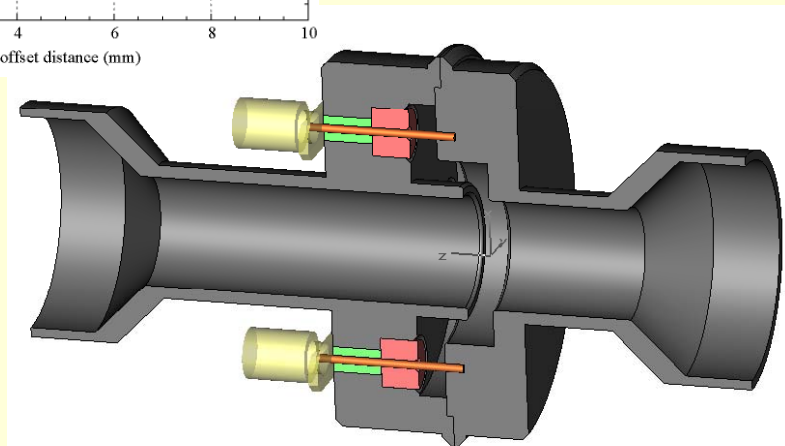
Re-entrant Cavity BPM (CALIFES)



- ✚ Re-entrant geometry for a higher frequency separation between the monopole and dipole modes. → Better CMRR
- ✚ Resolution: ~ 1 μ m (CALIFES ~5 μ m)
- ✚ $Q_{ld} = 50$ → Time resolution ~ 2-3ns
- ✚ ID 18mm; Length ~100mm.



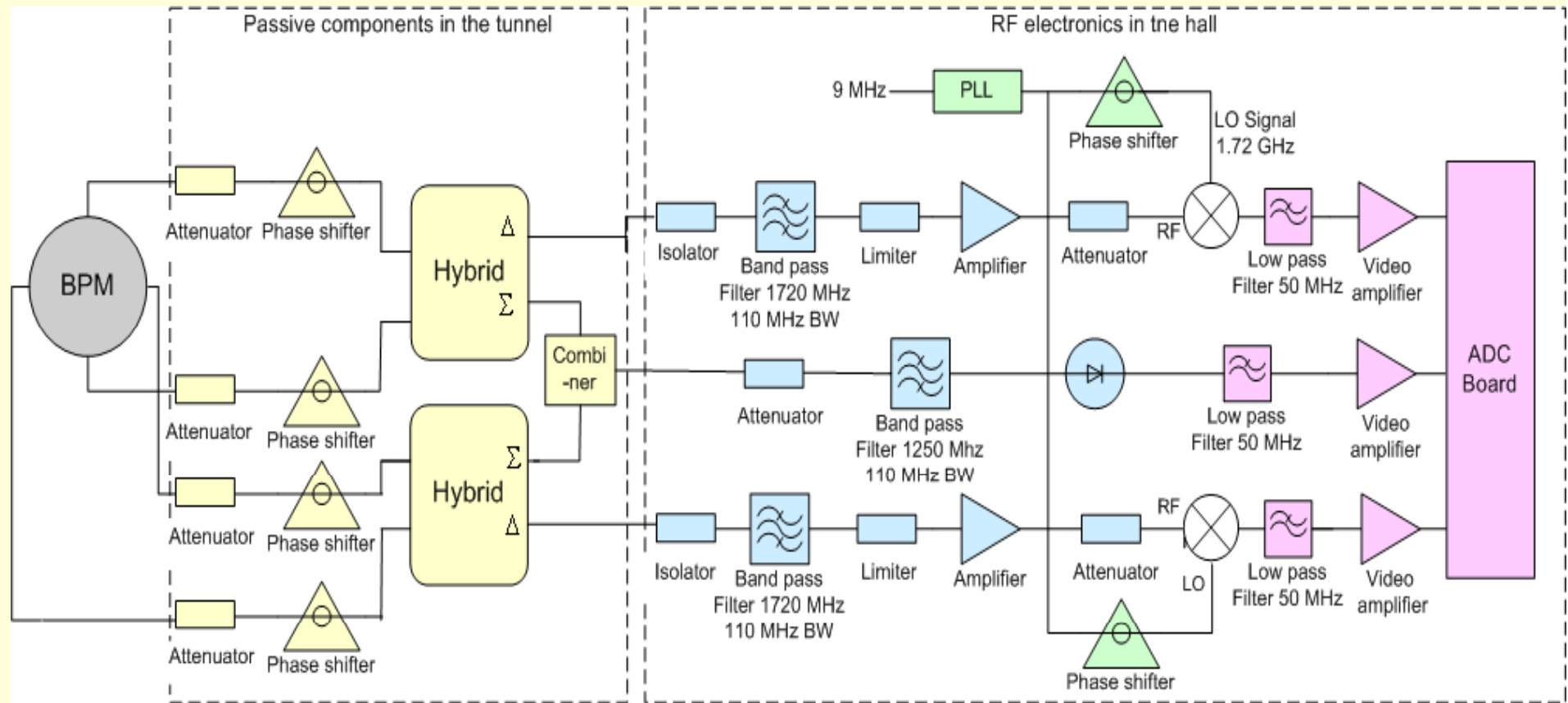
Offset (mm)	Monopolar mode (3.851 GHz)		Dipolar mode (5.942 GHz)	
	X direction	Y direction	X direction	Y direction
0.0	22.26	22.26	2.441e-6	2.441e-6
0.1	22.24	22.19	3.115e-3	4.895e-6
0.5	22.13	22.18	6.843e-2	3.359e-6
1.0	22.24	22.21	2.816e-1	7.891e-6
2.0	22.19	22.23	1.117	4.880e-7
3.0	22.19	22.19	2.532	4.124e-6
4.0	22.27	22.21	4.524	9.080e-7
5.0	22.26	22.23	7.059	1.174e-5
6.0	22.19	22.21	10.13	3.217e-6
7.0	22.09	22.05	13.70	6.641e-6
8.0	21.94	22.34	17.77	5.918e-5

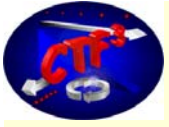


Developed by M. Loung, C. Simon, Sacle



Re-entrant cavity BPM electronics





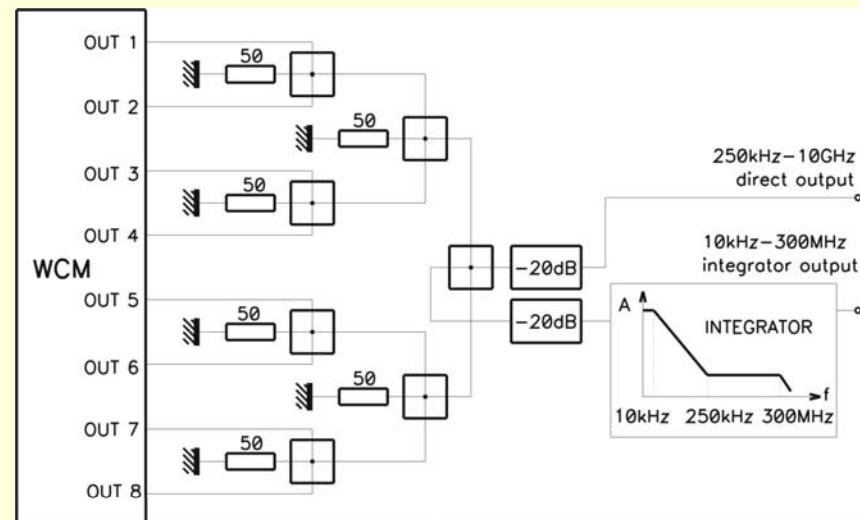
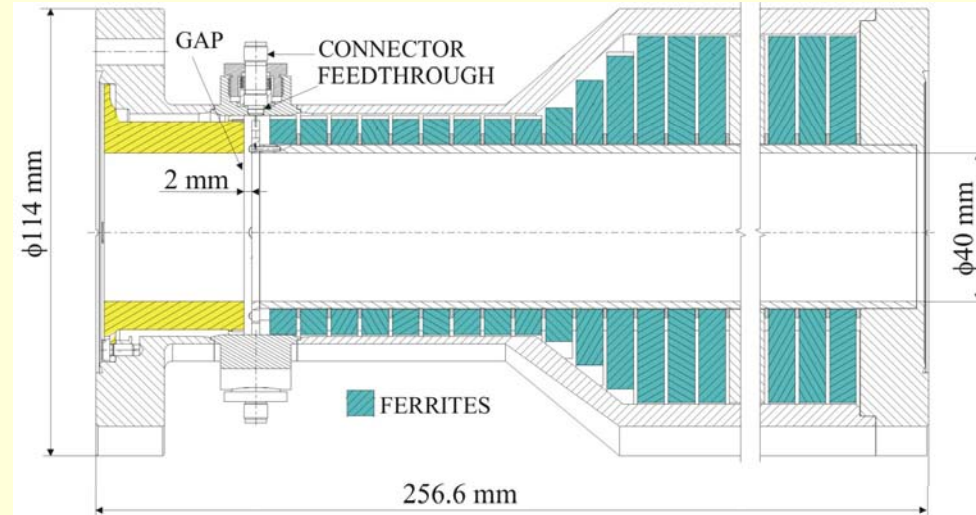
Wall current monitor, WCM

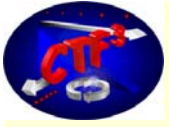


Developed by J. Durand, P. Odier Cern



Non-dismountable WCM





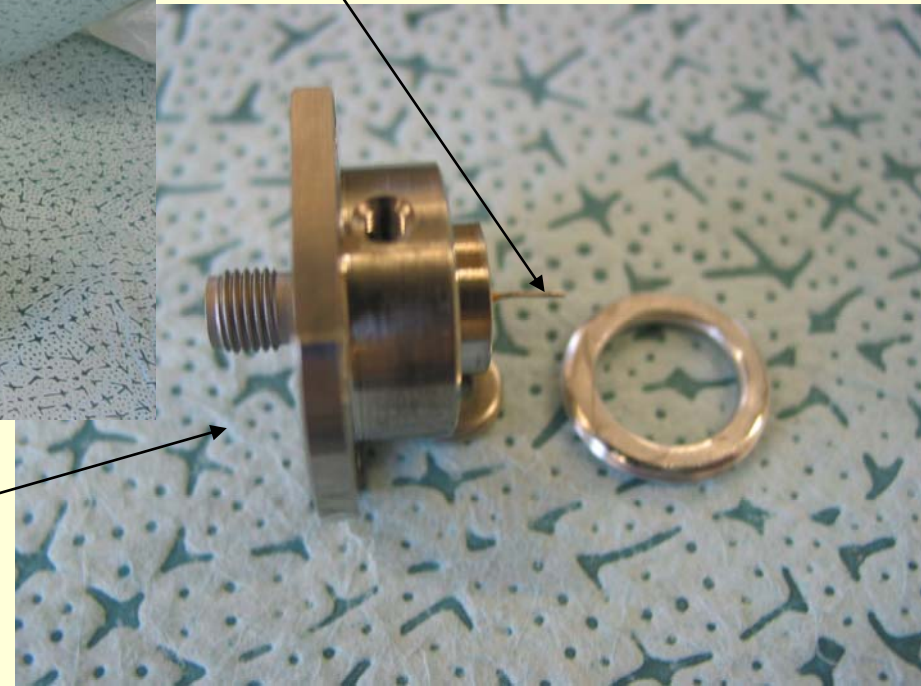
Wall current monitor, WCM

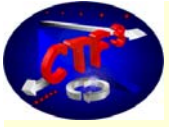


Feed-thru connection

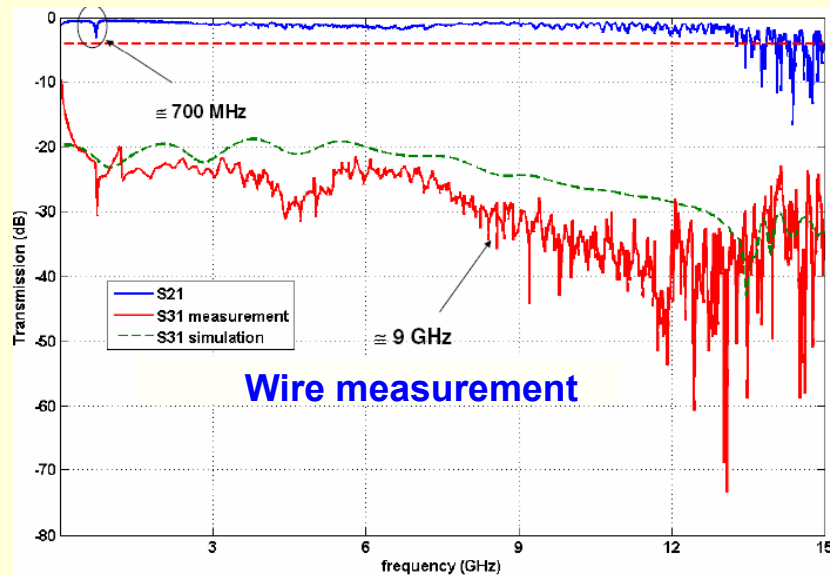
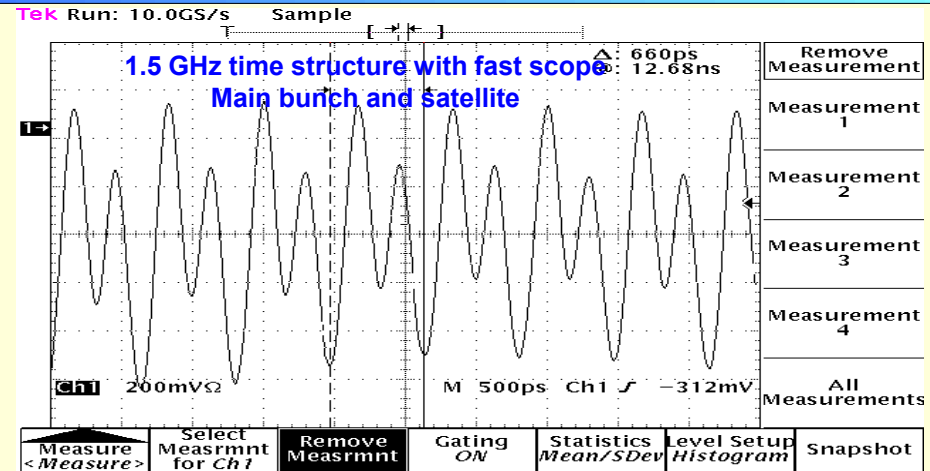
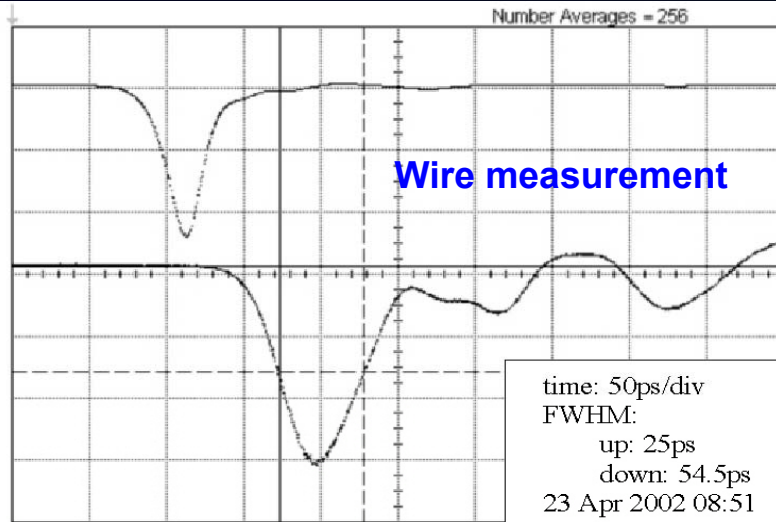
Dismountable WCM

Feed-thru

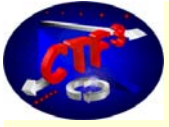




Wall current monitor



Impedance	~5 ohms
Resolution	***
Absolute precision	~ 1%
Low freq. cut off	10kHz
High freq. cut off	7GHz
Calibration	No
Nb. of feed-troughs	8
Gap length	2mm
ID / Length	40mm / 256.6mm
Flange types	DN63CF
Bake-out temp.	165 °C

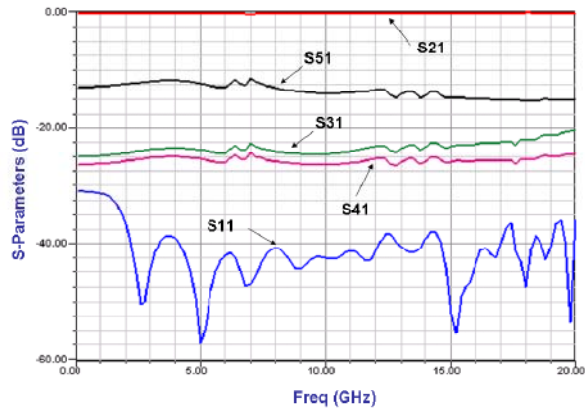
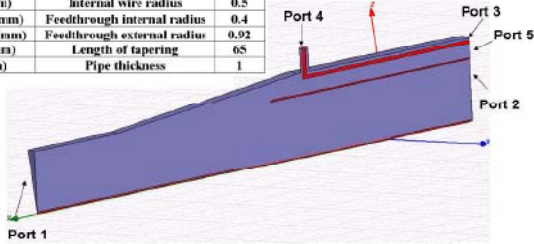


EUROTeV WCM

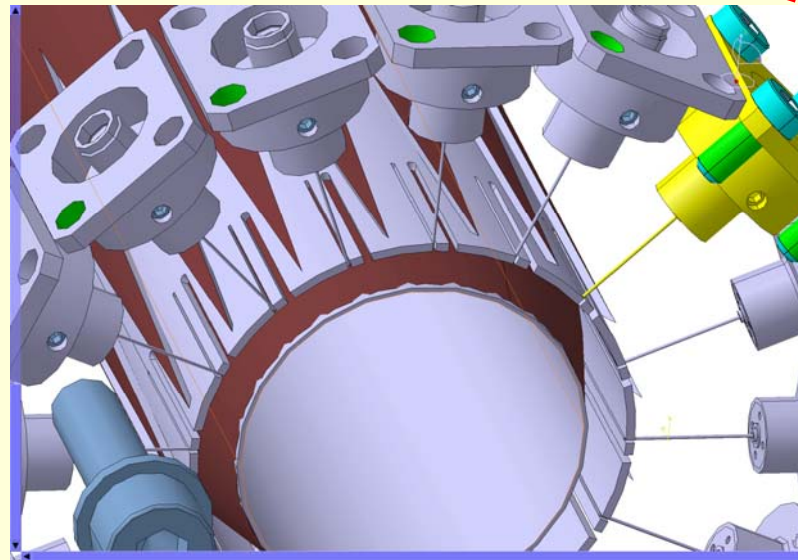
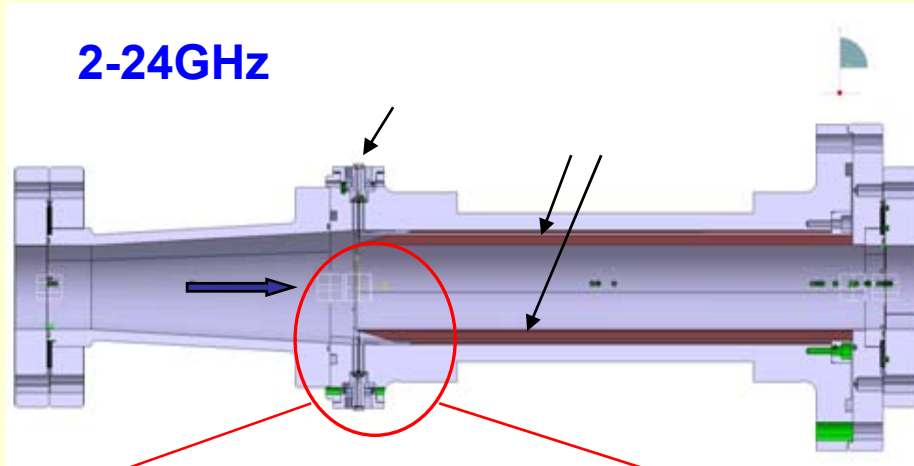


New triaxial structure with tapering, and 16 feed-thru's

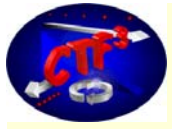
R_i (mm)	Inner coaxial radius	20
$R_{\text{feed, coax}}$ (mm)	Feedthrough coaxial radius	25
R_o (mm)	Outer coaxial radius	27
R_w (mm)	Internal wire radius	0.5
$R_{\text{feed, in}}$ (mm)	Feedthrough internal radius	0.4
$R_{\text{feed, out}}$ (mm)	Feedthrough external radius	0.92
L_{tap} (mm)	Length of tapering	65
t (mm)	Pipe thickness	1



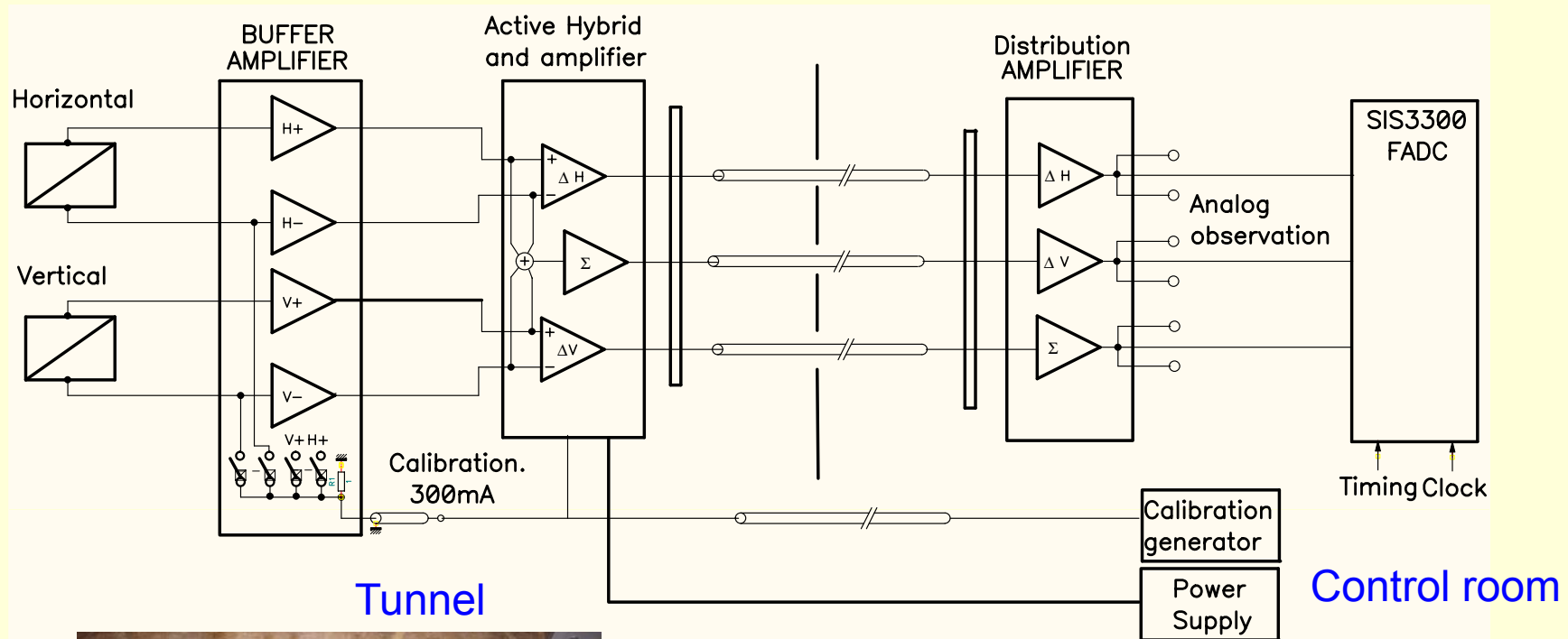
2-24GHz



Developed by A. D'Elia, CERN



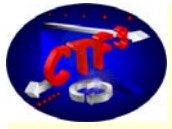
Acquisition system: Linac, CR



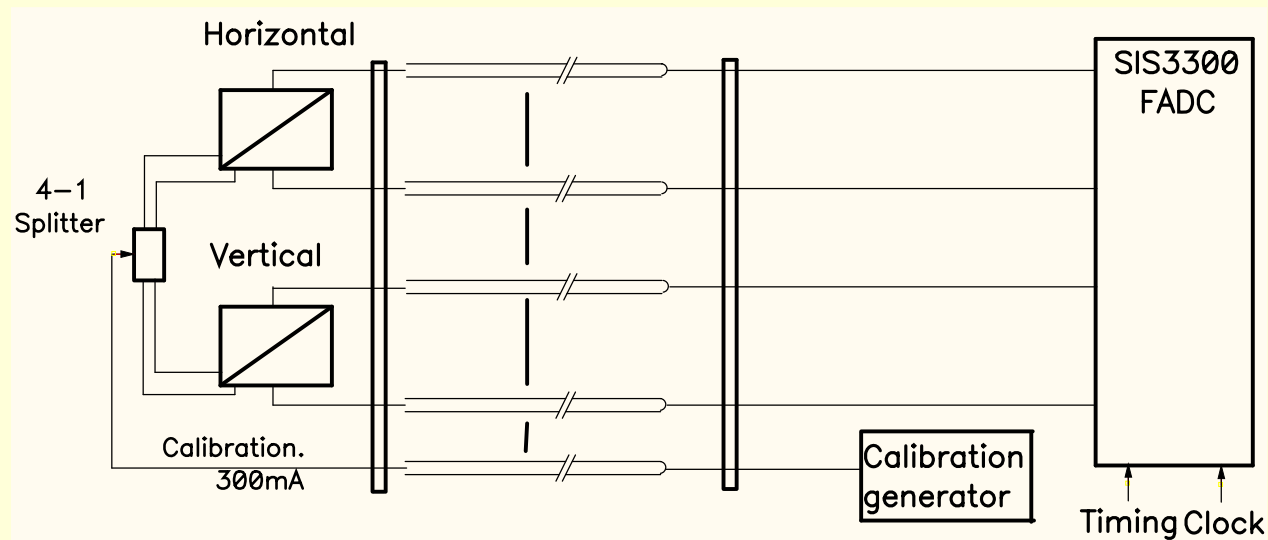
⚡ Front-end electronics gives improved CMRR.

Calibration of position and intensity .

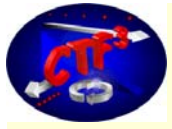
⚡ Observation of analogue signals



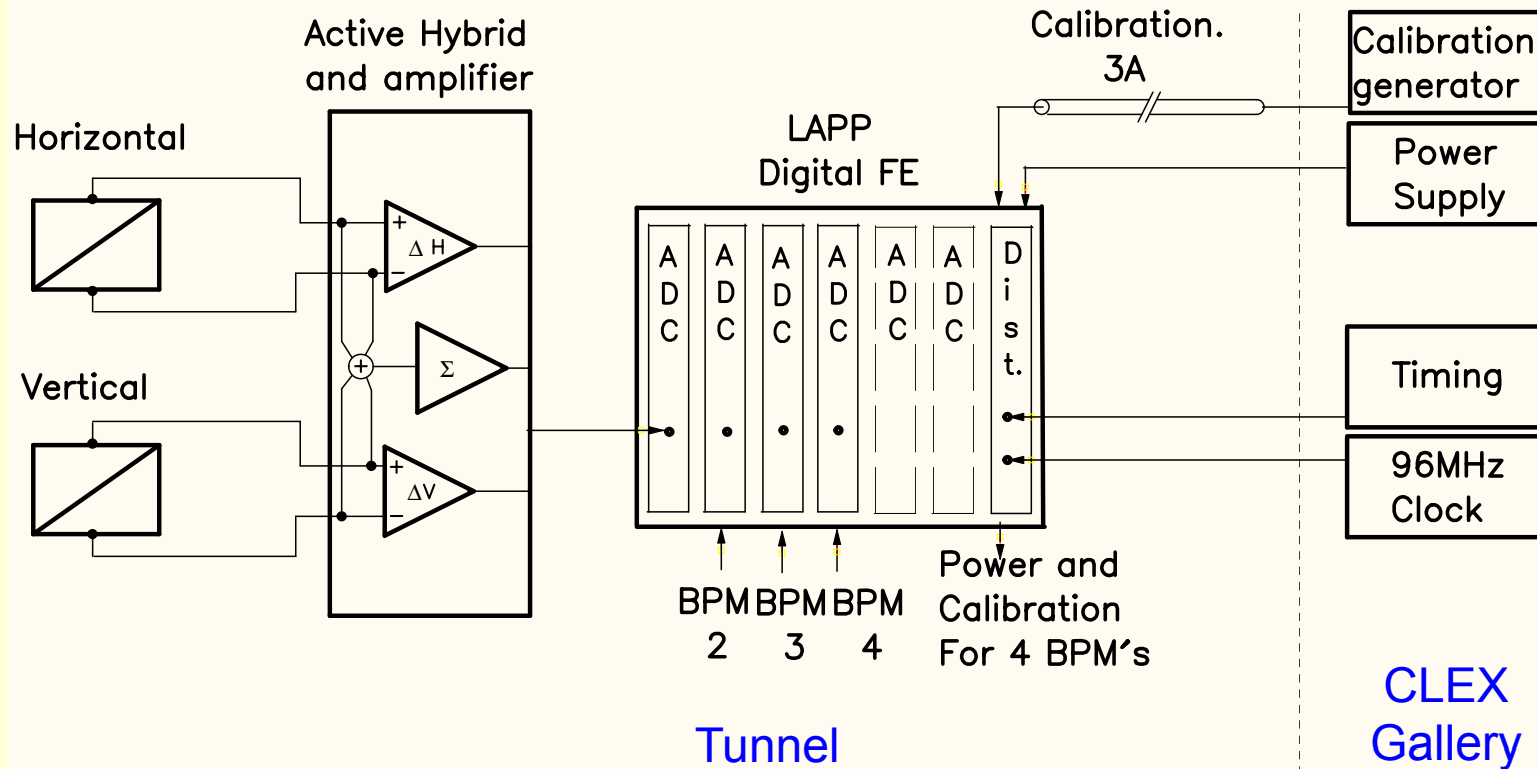
Acquisition system: Delay loop



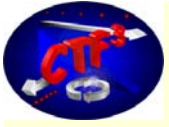
- ✚ No front-end electronics
- ✚ The four electrodes are via long cables directly connected to the 100MS ADC.
- ✚ Calibration of sum only.



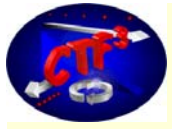
Acquisition system: TL2, CLEX



- **Front-end electronics maintained.**
- ✚ **Signals digitized in tunnel** → **Big reduction in cable costs**
- ✚ **No analogue signal observation .**



Thank you for your attention



Position and intensity monitors



	BPE	BPM	BPI	BPS	PBPM	BPR
Transverse sensitivity, $\Delta = \Sigma$ [mm]	30	30	33 / 50		12	~10
Resolution pos.	0.1mm	0.1mm			200nm	0.1mm
Relative precision (3/4 half aperture)	0.2%	1%	1%	1%	1%	1-5%
Longitudinal transfer impedance [Ω]	0.17 / 1.7	0.1 / 1				0.1 / 1
Resolution current [mA]	12 / 1.2	10 / 3				12 / 1.2
Low frequency cut off Δ / Σ [kHz]	1 / 1	10 / 0.15	~20 / 0.3			1kHz
High frequency cut off	200MHz	200MHz	200MHz		50MHz	200MHz (10MHz)
Calibration	Yes	Yes	Yes	Yes	Yes	No
ID / Length [mm]	46 / 130	40 / 168	90*39/240		6	40 / 196
Number of feedthroughs	4	0	0	0	0	5
Waveguide	--	--	--	--	--	WR28
Flange types	DN40CF / DN100CF	DN40CF	Racetrack		Helicoflex 10.9*7.7	DN40CF
Max. bake-out temperature	130 °C	130 °C	130 °C	130 °C	130 °C	130 °C