- readout : I've mostly fixed the AHRS issues, however, it sometimes just fails to respond. I guess I should put this issue in the elog. Temperature and humidity should be okay.
Issue to discuss: should the AHRS run even if we are not in the running state? If so, should we be able to disable it. What would be the default?
- multiboot: coming along. Kintex behavior not well understood in some cases. Currently it just waits for a connection, and then after 30 seconds it will boot the runtime image. A special 'stop' command will then prevent the golden image from booting further. Also: I am going to try to make the LM32 and WhiteRabbit shells accessable through telnet. Its a bit of work now, but will simplify a lot of things later on.

- last item. What do you mean by 'slow control sender'? You should ask peter about the destination IP per channel. I am not sure he is working on it. For me its quite trivial to implement in the slow-control

Other than that Cristiano and I are further in our investigation into the issues concerning threading. In the last version I have recreated Cristiano's test code in Java, and I have not seen an increase in thread usage. Cristiano should now use the last version of the API and repeat the test in Mono, and see if they differ. It may be a KVM issue (KVM is the Java runtime in .NET)