

Non-linear dynamics

Phenomenology, applications and examples

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Summary of the 1st lecture

- **Hamiltonian formalism** provides the **natural framework** to analyse (linear and non-linear) beam dynamics
- **Canonical (symplectic) transformations** enable to move from variables describing a distorted phase space to something simpler (ideally circles)
- The **generating functions** passing from the old to the new variables are bounded to **diverge** in the vicinity of **resonances** (emergence of chaos, see 2nd lecture)
- Calculating this generating function with **canonical perturbation theory** becomes **hopeless** for higher orders
- Representing the accelerator (or beam line) like a composition of maps (through **Lie transformations**) enables derivation of the generating functions in an **algorithmic way**, in principle to **arbitrary order**

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Phase space dynamics

- Fixed point analysis

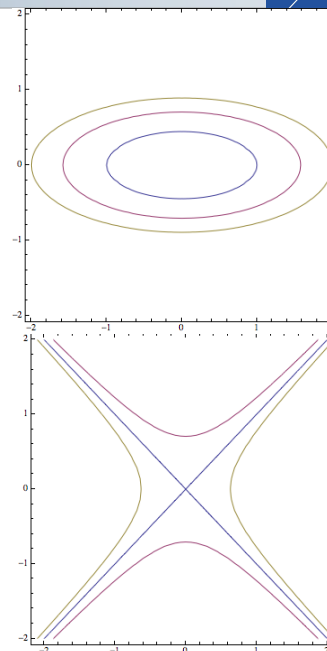
Phase space dynamics


- Valuable description when examining trajectories in **phase space** (u, p_u)
- Existence of integral of motion imposes geometrical constraints on phase flow
- For the simple **harmonic oscillator**

$$H = \frac{1}{2} (p_u^2 + \omega_0^2 u^2)$$


phase space curves are **ellipses** around the equilibrium point parameterized by the integral of motion Hamiltonian (energy)

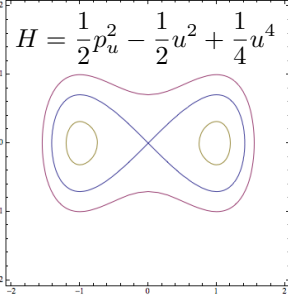
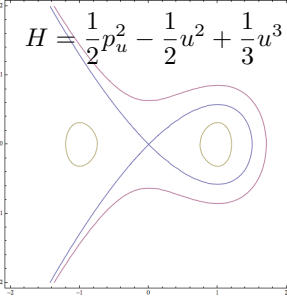
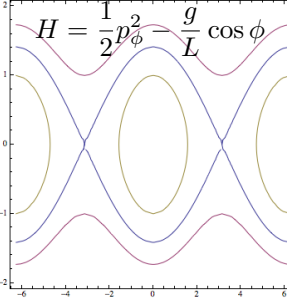
- By simply **changing the sign** of the potential in the harmonic oscillator, the phase trajectories become **hyperbolas**, symmetric around the equilibrium point where two straight lines cross, moving towards and away from it





Non-linear oscillators





- Conservative non-linear oscillators have Hamiltonian

$$H = E = \frac{1}{2}p_u^2 + V(u)$$
 with the potential being a general (polynomial) function of positions
- **Equilibrium points** are associated with extrema of the potential
- Considering three non-linear oscillators
 - **Quartic potential** (left): two minima and one maximum
 - **Cubic potential** (center): one minimum and one maximum
 - **Pendulum** (right): periodic minima and maxima

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Fixed point analysis



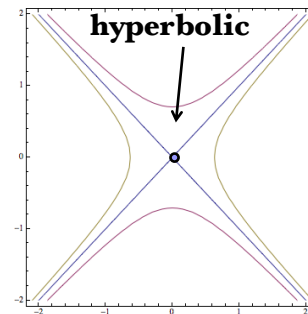
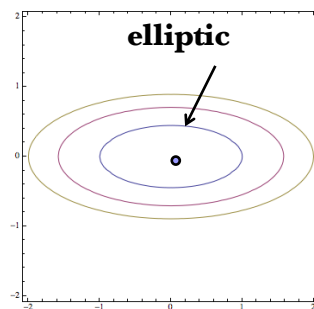
- Consider a general second order system

$$\begin{aligned} \frac{du}{dt} &= f_1(u, p_u) \\ \frac{dp_u}{dt} &= f_2(u, p_u) \end{aligned}$$
- **Equilibrium** or “**fixed**” points $f_1(u_0, p_{u0}) = f_2(u_0, p_{u0}) = 0$ are determinant for topology of trajectories at their vicinity
- The linearized equations of motion at their vicinity are

$$\frac{d}{dt} \begin{bmatrix} \delta u \\ \delta p_u \end{bmatrix} = \mathcal{M}_J \begin{bmatrix} \delta u \\ \delta p_u \end{bmatrix} = \underbrace{\begin{bmatrix} \frac{\partial f_1(u_0, p_{u0})}{\partial u} & \frac{\partial f_1(u_0, p_{u0})}{\partial p_u} \\ \frac{\partial f_2(u_0, p_{u0})}{\partial u} & \frac{\partial f_2(u_0, p_{u0})}{\partial p_u} \end{bmatrix}}_{\text{Jacobian matrix}} \begin{bmatrix} \delta u \\ \delta p_u \end{bmatrix}$$
- Fixed point nature is revealed by eigenvalues of \mathcal{M}_J , i.e. solutions of the characteristic polynomial $\det |\mathcal{M}_J - \lambda \mathbf{I}| = 0$

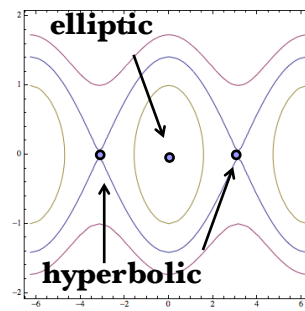
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- For conservative systems of 1 degree of freedom, the second order characteristic polynomial has two solutions:
 - Two **complex eigenvalues** with opposite sign, corresponding to **elliptic** fixed points. Phase space flow is described by **ellipses**, with particles evolving clockwise or anti-clockwise
 - Two **real eigenvalues** with opposite sign, corresponding to **hyperbolic** (or saddle) fixed points. Flow described by two lines (or manifolds), incoming (stable) and outgoing (unstable)



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- The “fixed” points for a pendulum can be found at $(\phi_n, p_\phi) = (\pm n\pi, 0)$, $n = 0, 1, 2 \dots$
- The Jacobian matrix is
$$\begin{bmatrix} 0 & 1 \\ -\frac{g}{L} \cos \phi_n & 0 \end{bmatrix}$$
- The eigenvalues are $\lambda_{1,2} = \pm i \sqrt{\frac{g}{L} \cos \phi_n}$
- Two cases can be distinguished:
 - $\phi_n = 2n\pi$, for which $\lambda_{1,2} = \pm i \sqrt{\frac{g}{L}}$ corresponding to elliptic fixed points
 - $\phi_n = (2n+1)\pi$, for which $\lambda_{1,2} = \pm \sqrt{\frac{g}{L}}$ corresponding to hyperbolic fixed points
 - The **separatrix** are the stable and unstable manifolds passing through the hyperbolic points, separating bounded **librations** and unbounded **rotations**



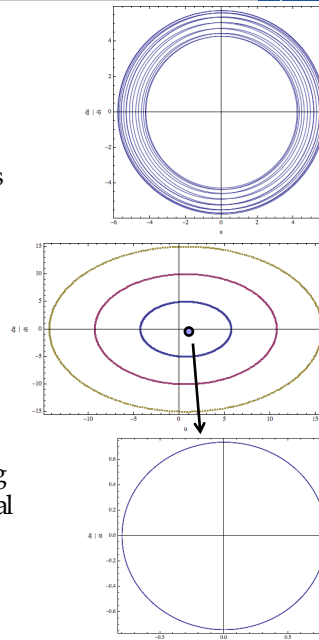
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Phase space for time-dependent systems

- Consider now a simple harmonic oscillator where the frequency is time-dependent

$$H = \frac{1}{2} (p_u^2 + \omega_0^2(t) u^2)$$

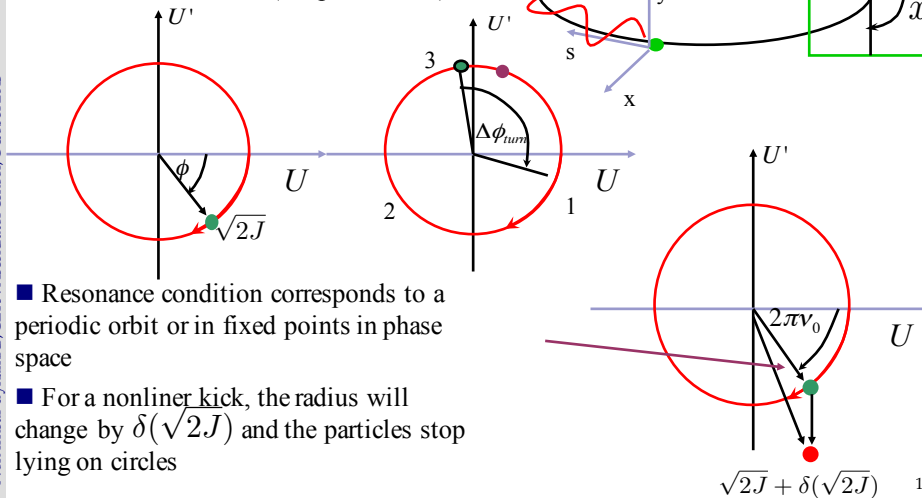
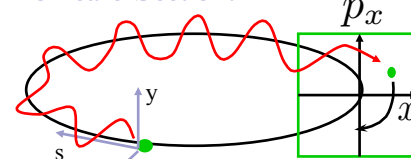
- Plotting the evolution in phase space, provides trajectories that intersect each other (top)
- The phase space has time as extra dimension,
- By rescaling the time to become $\tau = \omega_0 t$ and considering every integer interval of the new time variable, the phase space looks like the one of the harmonic oscillator (middle)
- This is the simplest version of a **Poincaré surface of section**, which is useful for studying geometrically phase space of multi-dimensional systems
- The fixed point in the surface of section is now a periodic orbit (bottom)



Poincaré Section in practice

- Record the particle coordinates at one location (BPM)
- Unperturbed motion lies on a circle in normalized coordinates (simple rotation)

Poincaré Section:



- Resonance condition corresponds to a periodic orbit or in fixed points in phase space
- For a nonlinear kick, the radius will change by $\delta(\sqrt{2J})$ and the particles stop lying on circles

$\sqrt{2J} + \delta(\sqrt{2J})$ 10

Motion close to a resonance

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Secular perturbation theory

- The vicinity of a resonance $n_1\omega_1 + n_2\omega_2 = 0$ can be studied through secular perturbation theory (see appendix)
- A canonical transformation is applied such that the new variables are in a frame remaining on top of the resonance
- If one frequency is slow, one can average the motion and remain only with a 1 degree of freedom Hamiltonian
- Finding the location of the fixed points (J_{10}, ϕ_{10}) (i.e. periodic orbits) in phase space (J_1, ϕ_1) and defining a new action $\Delta J_1 = J_1 - J_{10}$, the resonant Hamiltonian is

$$H_r(\Delta J_1, \phi_1) = \frac{\partial^2 H_0(\mathbf{J})}{\partial J_1^2} \bigg|_{J_1=J_{10}} \frac{(\Delta J_1)^2}{2} + 2\varepsilon \bar{H}_{n_1, -n_2}(\mathbf{J}) \cos \varphi_1$$

- This is a pendulum where the frequency and the resonance half width are

$$\omega_1 = \left(2\varepsilon H_{n_1, -n_2}(\mathbf{J}) \frac{\partial^2 H_0(\mathbf{J})}{\partial J_1^2} \bigg|_{J_1=J_{10}} \right)^{1/2} \Delta J_{1 \max} = 2 \left(\frac{2\varepsilon H_{n_1, -n_2}(\mathbf{J})}{\frac{\partial^2 H_0(\mathbf{J})}{\partial J_1^2} \bigg|_{J_1=J_{10}}} \right)^{1/2}$$

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- We first introduce the distance to the resonance

$$\nu = \frac{p}{3} + \delta, \quad \delta \ll 1$$

- It is convenient then to eliminate the “time” dependence by passing on a “1-turn” frame, using the generating function

$$F_2(\phi, J_1, s) = \phi J_1 + J_1 \left(\frac{2\pi\nu s}{C} - \int_0^s \frac{ds'}{\beta(s')} \right) = (\phi + \chi(s)) J_1$$

with the new angle $\psi_1 = \phi - \chi(s)$ providing the Hamiltonian

$$H_1 = \frac{\nu}{R} J_1 + \frac{2\sqrt{2}}{3} K_s(s) (J_1 \beta)^{3/2} \cos^3(\psi_1 + \chi(s))$$

- The perturbation can be expanded in a Fourier series, where only the resonant term is kept or,

$$\hat{H}_1 = \nu J_1 + J_1^{3/2} A_{3p} \cos(3\psi_1 - p\theta)$$

in the rotating frame on top of the resonance

$$\hat{H}_2 = \delta J_2 + J_2^{3/2} A_{3p} \cos(3\psi_2)$$

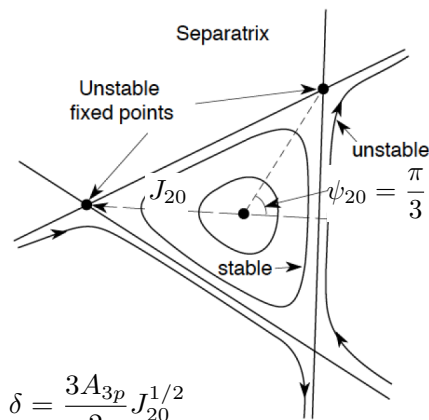
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- By setting the Hamilton's equations equal to zero, three fixed points can be found at $\psi_{20} = \frac{\pi}{3}, \frac{3\pi}{3}, \frac{5\pi}{3}, J_{20} = \left(\frac{2\delta}{3A_{3p}} \right)^2$

- For $\frac{\delta}{A_{3p}} > 0$ all three points are unstable

- Close to the elliptic one at $\psi_{20} = 0$ the motion in phase space is described by circles that they get more and more distorted to end up in the “triangular” separatrix uniting the unstable fixed points

- The tune separation from the resonance (**stop-band width**) is $\delta = \frac{3A_{3p}}{2} J_{20}^{1/2}$



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Fixed points for general multi-pole

- For any polynomial perturbation of the form x^k the “resonant” Hamiltonian is written as

$$\hat{H}_2 = \delta J_2 + \alpha(J_2) + J_2^{k/2} A_{kp} \cos(k\psi_2)$$

- Note now that in contrast to the sextupole there is a non-linear detuning term $\alpha(J_2)$

- The conditions for the fixed points are

$$\sin(k\psi_2) = 0, \quad \delta + \frac{\partial \alpha(J_2)}{\partial J_2} + \frac{k}{2} J_2^{k/2-1} A_{kp} \cos(k\psi_2) = 0$$

- There are k fixed points for which $\cos(k\psi_{20}) = -1$ and the fixed points are stable (elliptic). They are surrounded by ellipses

- There are also k fixed points for which $\cos(k\psi_{20}) = 1$ and the fixed points are unstable (hyperbolic). The trajectories are hyperbolas

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Fixed points for an octupole

- The resonant Hamiltonian close to the 4th order resonance is written as

$$\hat{H}_2 = \delta J_2 + cJ_2^2 + J_2^2 A_{kp} \cos(4\psi_2)$$

- The fixed points are found by taking the derivative over the two variables and setting them to zero, i.e.

$$\sin(4\psi_2) = 0, \quad \delta + 2cJ_2 + 2J_2 A_{kp} \cos(4\psi_2) = 0$$

- The fixed points are at

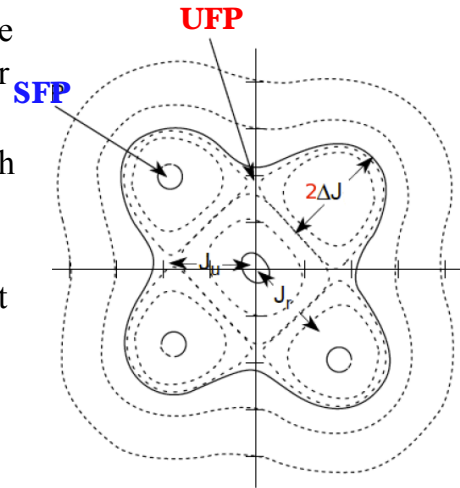
$$\psi_{20} = \frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}, \pi, \frac{5\pi}{4}, \frac{3\pi}{2}, \frac{7\pi}{4}, 2\pi$$

- For half of them, there is a minimum in the potential as

$$\cos(4\psi_{20}) = -1 \text{ and they are elliptic and half of them they are hyperbolic as } \cos(4\psi_{20}) = 1$$

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- Regular motion near the center, with curves getting more deformed towards a rectangular shape
- The separatrix passes through 4 unstable fixed points, but motion seems well contained
- Four stable fixed points exist and they are surrounded by stable motion (islands of stability)
- Question: Can the central fixed point become hyperbolic (answer in the appendix)



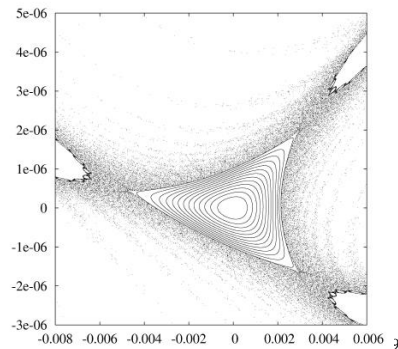
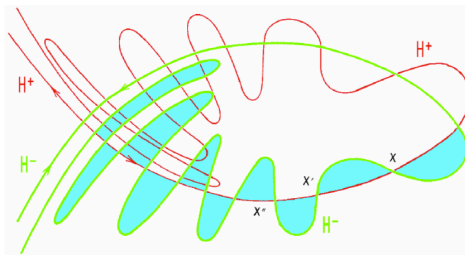
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Onset of chaos

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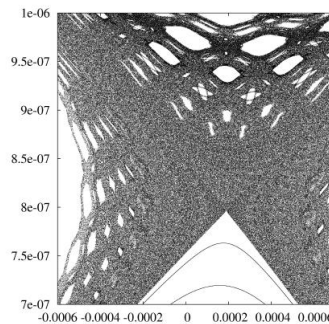
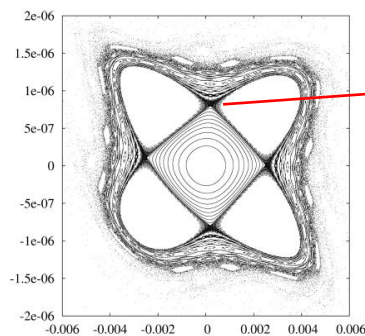
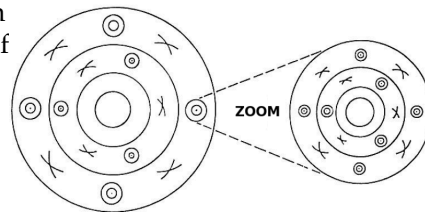
Path to chaos


- When perturbation becomes higher, motion around the separatrix becomes chaotic (producing tongues or splitting of the separatrix)
- Unstable fixed points are indeed the source of chaos when a perturbation is added




Chaotic motion

- Poincare-Birkhoff theorem states that under perturbation of a resonance only an even number of fixed points survives (half stable and the other half unstable)
- Themselves get destroyed when perturbation gets higher, etc. (self-similar fixed points)
- Resonance islands grow and resonances can overlap allowing diffusion of particles



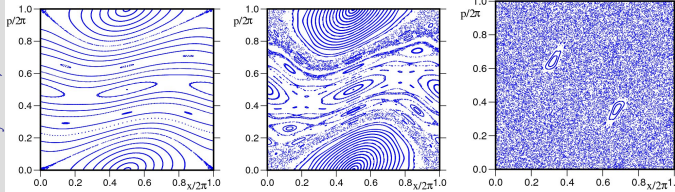
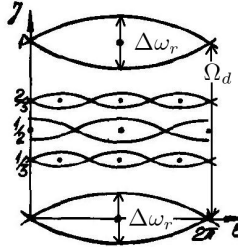


Resonance overlap criterion




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- When perturbation grows, the resonance island width grows
- **Chirikov** (1960, 1979) proposed a criterion for the overlap of two neighboring resonances and the onset of orbit diffusion
- The distance between two resonances is $\delta \hat{J}_{1\ n,n'} = \frac{2 \left(\frac{1}{n_1+n_2} - \frac{1}{n'_1+n'_2} \right)}{\left| \frac{\partial^2 \bar{H}_0(\hat{\mathbf{J}})}{\partial \hat{J}_1^2} \right|_{\hat{J}_1=\hat{J}_{10}}}$
- The simple overlap criterion is $\Delta \hat{J}_{n\ max} + \Delta \hat{J}_{n'\ max} \geq \delta \hat{J}_{n,n'}$
- Considering the width of chaotic layer and secondary islands, the “two thirds” rule apply $\Delta \hat{J}_{n\ max} + \Delta \hat{J}_{n'\ max} \geq \frac{2}{3} \delta \hat{J}_{n,n'}$
- The main limitation is the geometrical nature of the criterion (difficulty to be extended for > 2 degrees of freedom)

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Chaos detection methods



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- Computing/measuring dynamic aperture (DA) or particle survival

A. Chao et al., PRL 61, 24, 2752, 1988;
 F. Willeke, PAC95, 24, 109, 1989.
- Computation of Lyapunov exponents

F. Schmidt, F. Willeke and F. Zimmermann, PA, 35, 249, 1991;
 M. Giovannozzi, W. Scandale and E. Todesco, PA 56, 195, 1997
- Variance of unperturbed action (a la Chirikov)

B. Chirikov, J. Ford and F. Vivaldi, AIP CP-57, 323, 1979
 J. Tennyson, SSC-155, 1988;
 J. Irwin, SSC-233, 1989
- Fokker-Planck diffusion coefficient in actions

T. Sen and J.A. Elisson, PRL 77, 1051, 1996
- Frequency map analysis

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Dynamic aperture

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Dynamic Aperture

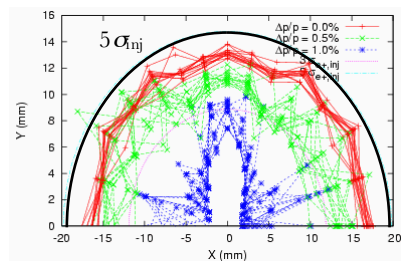
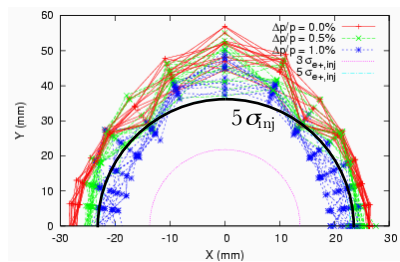
- The most direct way to evaluate the non-linear dynamics performance of a ring is the computation of **Dynamics Aperture**
- Particle motion due to multi-pole errors is generally non-bounded, so chaotic particles can **escape to infinity**
- This is not true for all non-linearities (e.g. the beam-beam force)
- Need a **symplectic** tracking code to follow particle trajectories (a lot of initial conditions) for a **number of turns** (depending on the given problem) until the particles start getting lost
- As multi-pole errors may not be completely known, one has to track through **several machine models** built by **random distribution** of these errors
- One could start with 4D (only transverse) tracking but certainly needs to simulate 5D (constant energy deviation) and finally 6D (synchrotron motion included)

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Dynamic Aperture plots

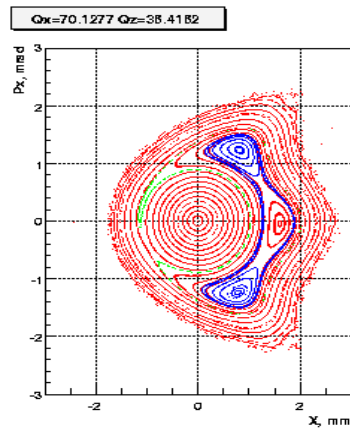
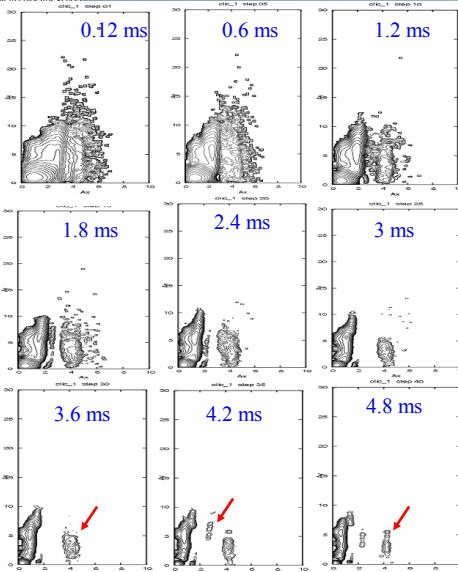
■ Dynamic aperture plots show the maximum initial values of stable trajectories in x-y coordinate space at a particular point in the lattice, for a range of energy errors.

- The beam size (injected or equilibrium) can be shown on the same plot.
- Generally, the goal is to allow some significant margin in the design - the measured dynamic aperture is often smaller than the predicted dynamic aperture.



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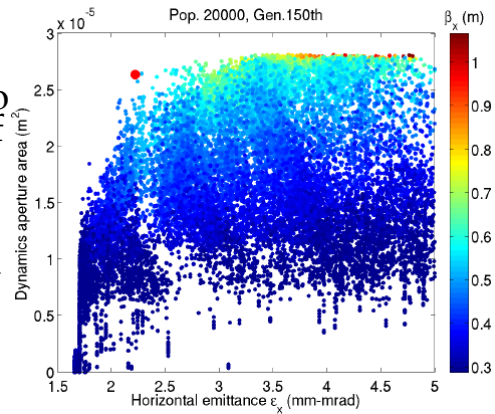
Dynamic aperture including damping



- Including radiation damping and excitation shows that 0.7% of the particles are lost during the damping
- Certain particles seem to damp away from the beam core, on resonance islands

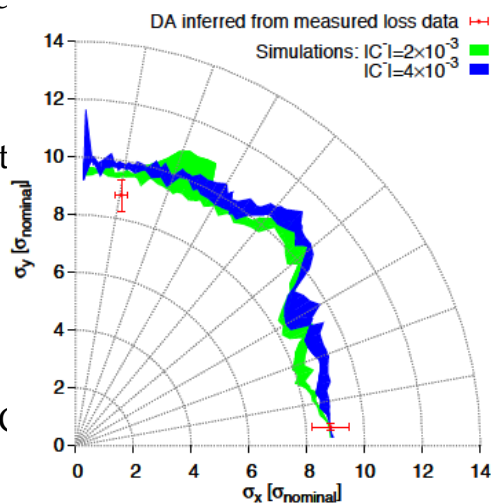
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- MOGA –Multi Objective Genetic Algorithms are being recently used to optimise linear but also non-linear dynamics of electron low emittance storage rings
- Use knobs quadrupole strengths, chromaticity sextupoles and correctors with some constraints
- Target ultra-low horizontal emittance, increased lifetime and high dynamic aperture



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- During LHC design phase DA target was 2x higher than collimator position, due to statistical fluctuation, finite mesh, linear imperfections, short tracking time, multi-pole time dependence, ripple and a 20% safety margin
- Better knowledge of the model led to good agreement between measurements and simulations for actual LHC
- Necessity to build an accurate magnetic model (from beam based measurements)



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Frequency Map Analysis

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Frequency map analysis

- Frequency Map Analysis (FMA) is a numerical method which springs from the studies of J. Laskar (Paris Observatory) putting in evidence the
- chaotic motion in the Solar Systems
- FMA was successively applied to several dynamical systems
 - Stability of Earth Obliquity and climate stabilization (Laskar, Robutel, 1993)
 - 4D maps (Laskar 1993)
 - Galactic Dynamics (Y.P and Laskar, 1996 and 1998)
 - Accelerator beam dynamics: lepton and hadron rings (Dumas, Laskar, 1993, Laskar, Robin, 1996, Y.P, 1999, Nadolski and Laskar 2001)

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Motion on torus

- Consider an integrable Hamiltonian system of the usual form

$$H(\mathbf{J}, \varphi, \theta) = H_0(\mathbf{J})$$

- Hamilton's equations give $\dot{\phi}_j = \frac{\partial H_0(\mathbf{J})}{\partial J_j} = \omega_j(\mathbf{J}) \Rightarrow \phi_j = \omega_j(\mathbf{J})t + \phi_{j0}$
 $\dot{J}_j = -\frac{\partial H_0(\mathbf{J})}{\partial \phi_j} = 0 \Rightarrow J_j = \text{const.}$

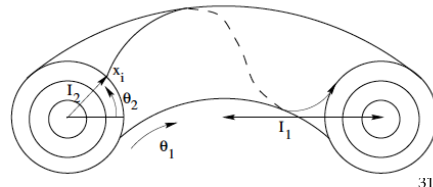
- The actions define the surface of an invariant torus

- In complex coordinates the motion is described by

$$\zeta_j(t) = J_j(0)e^{i\omega_j t} = z_{j0}e^{i\omega_j t}$$

- For a **non-degenerate** system $\det \left| \frac{\partial \omega(J)}{\partial J} \right| = \det \left| \frac{\partial^2 H_0(J)}{\partial J^2} \right| \neq 0$
there is a one-to-one correspondence between the actions and the frequency, a frequency map can be defined parameterizing the tori in the frequency space

$$F : (\mathbf{I}) \longrightarrow (\omega)$$



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Quasi-periodic motion

- If a transformation is made to some new variables

$$\zeta_j = I_j e^{i\theta_j t} = z_j + \epsilon G_j(\mathbf{z}) = z_j + \epsilon \sum_{\mathbf{m}} c_{\mathbf{m}} z_1^{m_1} z_2^{m_2} \dots z_n^{m_n}$$

- The system is still integrable but the tori are distorted

- The motion is then described by

$$\zeta_j(t) = z_{j0} e^{i\omega_j t} + \sum_{\mathbf{m}} a_{\mathbf{m}} e^{i(\mathbf{m} \cdot \omega) t}$$

i.e. a **quasi-periodic** function of time, with

$$a_{\mathbf{m}} = \epsilon c_{\mathbf{m}} z_{10}^{m_1} z_{20}^{m_2} \dots z_{n0}^{m_n} \text{ and } \mathbf{m} \cdot \omega = m_1 \omega_1 + m_2 \omega_2 + \dots + m_n \omega_n$$

- For a non-integrable Hamiltonian, $H(\mathbf{I}, \theta) = H_0(\mathbf{I}) + \epsilon H'(\mathbf{I}, \theta)$ and especially if the perturbation is small, most tori persist (**KAM** theory)

- In that case, the motion is still quasi-periodic and a frequency map can be built

- The regularity (or not) of the map reveals stable (or chaotic) motion

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Building the frequency map

- When a quasi-periodic function $f(t) = q(t) + ip(t)$ in the complex domain is given numerically, it is possible to recover a quasi-periodic approximation

$$f'(t) = \sum_{k=1}^N a'_k e^{i\omega'_k t}$$

in a very precise way over a finite time span $[-T, T]$ several orders of magnitude more precisely than simple Fourier techniques

- This approximation is provided by the Numerical Analysis of Fundamental Frequencies – **NAFF** algorithm
- The frequencies ω'_k and complex amplitudes a'_k are computed through an iterative scheme.

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The NAFF algorithm

- The first frequency ω'_1 is found by the location of the maximum of

$$\phi(\sigma) = \langle f(t), e^{i\sigma t} \rangle = \frac{1}{2T} \int_{-T}^T f(t) e^{-i\sigma t} \chi(t) dt$$

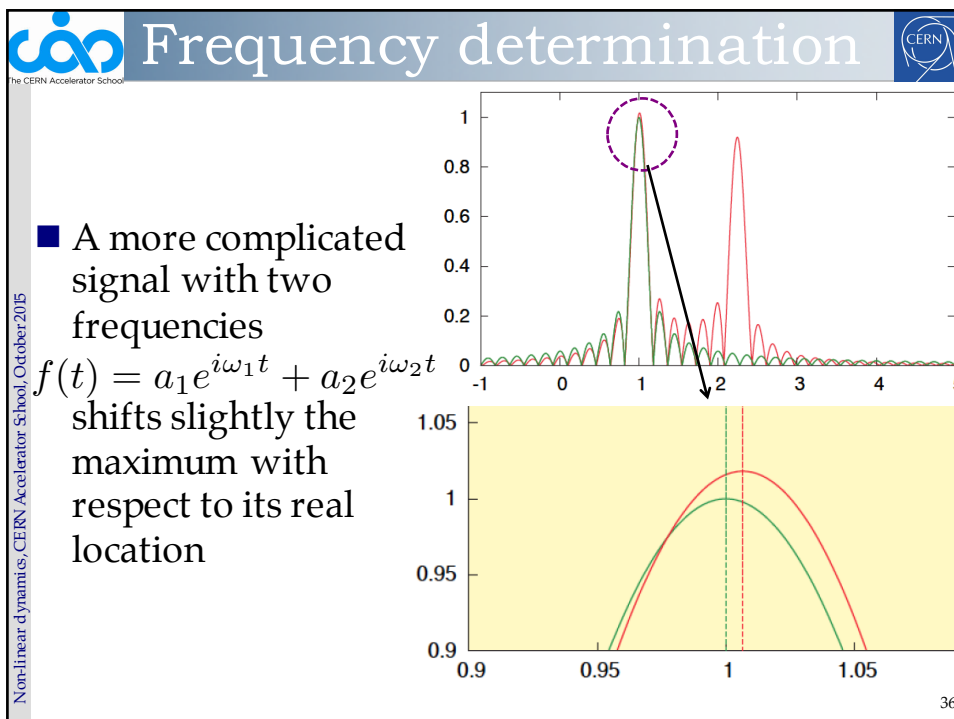
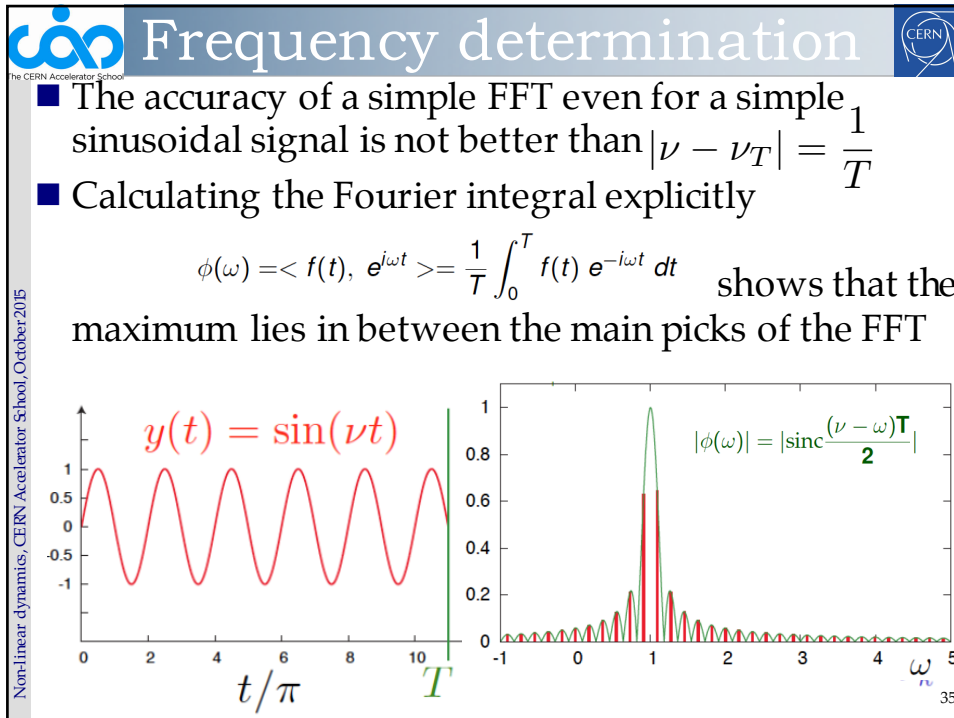
where $\chi(t)$ is a weight function

- In most of the cases the Hanning window filter is used $\chi_1(t) = 1 + \cos(\pi t/T)$
- Once the first term $e^{i\omega'_1 t}$ is found, its complex amplitude a'_1 is obtained and the process is restarted on the remaining part of the function

$$f_1(t) = f(t) - a'_1 e^{i\omega'_1 t}$$

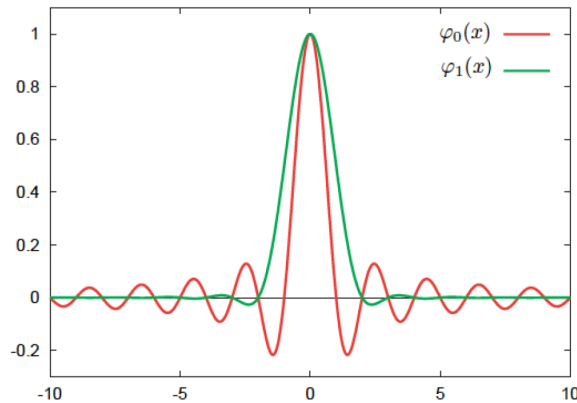
- The procedure is continued for the number of desired terms, or until a required precision is reached

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Window function

- A window function like the Hanning filter $\chi_1(t) = 1 + \cos(\pi t/T)$ kills side-lobes and allows a very accurate determination of the frequency



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Precision of NAFF

- For a general window function of order p

$$\chi_p(t) = \frac{2^p (p!)^2}{(2p)!} (1 + \cos \pi t)^p$$

Laskar (1996) proved a theorem stating that the solution provided by the NAFF algorithm converges asymptotically towards the real KAM quasi-periodic solution with precision

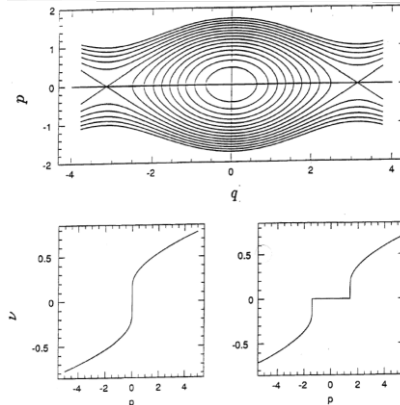
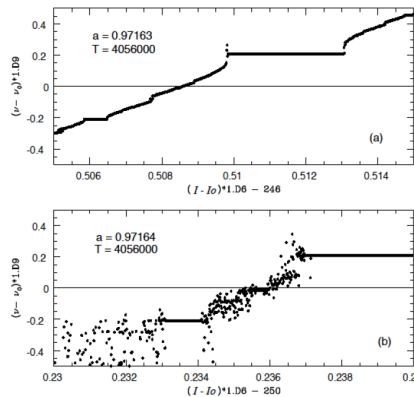
$$\nu_1 - \nu_1^T \propto \frac{1}{T^{2p+2}}$$

- In particular, for no filter (i.e. $p = 0$) the precision is $\frac{1}{T^2}$, whereas for the Hanning filter ($p = 1$), the precision is of the order of $\frac{1}{T^4}$

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Aspects of the frequency map

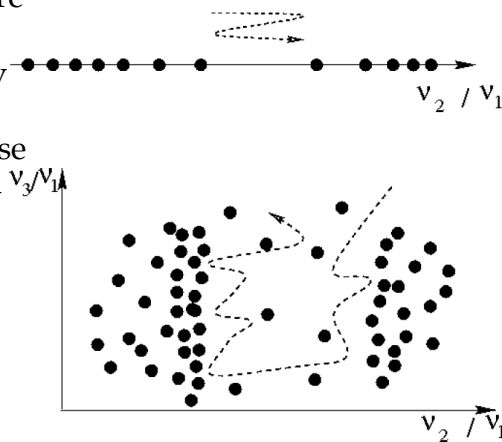
- In the vicinity of a resonance the system behaves like a pendulum
- Passing through the elliptic point for a fixed angle, a fixed frequency (or rotation number) is observed
- Passing through the hyperbolic point, a frequency jump is observed



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Diffusion in frequency space

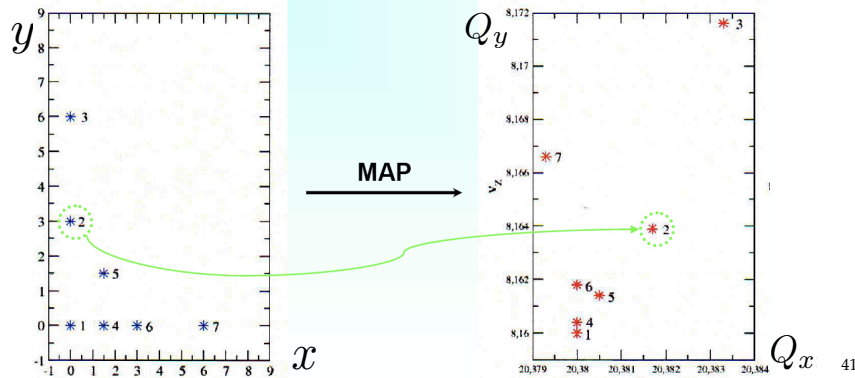
- For a 2 degrees of freedom Hamiltonian system, the frequency space is a line, the tori are dots on this lines, and the chaotic zones are confined by the existing KAM tori
- For a system with 3 or more degrees of freedom, KAM tori are still represented by dots but do not prevent chaotic trajectories to diffuse
- This topological possibility of particles diffusing is called **Arnold diffusion**
- This diffusion is supposed to be extremely small in their vicinity, as tori act as effective barriers (**Nechoroshev theory**)



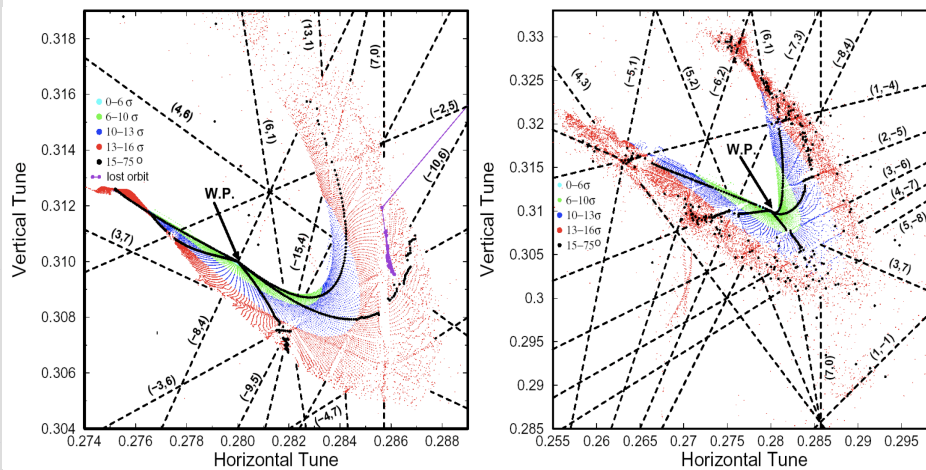
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Building the frequency map

- Choose initial conditions (x_i, y_i) with $(p_{x;i}, p_{y;i})$
- Numerically integrate trajectories for sufficient number of turns
- Compute through NAFF $(Q_{x;i}, Q_{y;i})$ after sufficient number of turns
- Plot them in the tune diagram



Frequency maps for the LHC



- Frequency maps for the target error table (left) and an increased random skew octupole error in the superconducting dipoles (right)

Diffusion Maps

- Calculate frequencies for two equal and successive time spans and compute frequency diffusion vector:

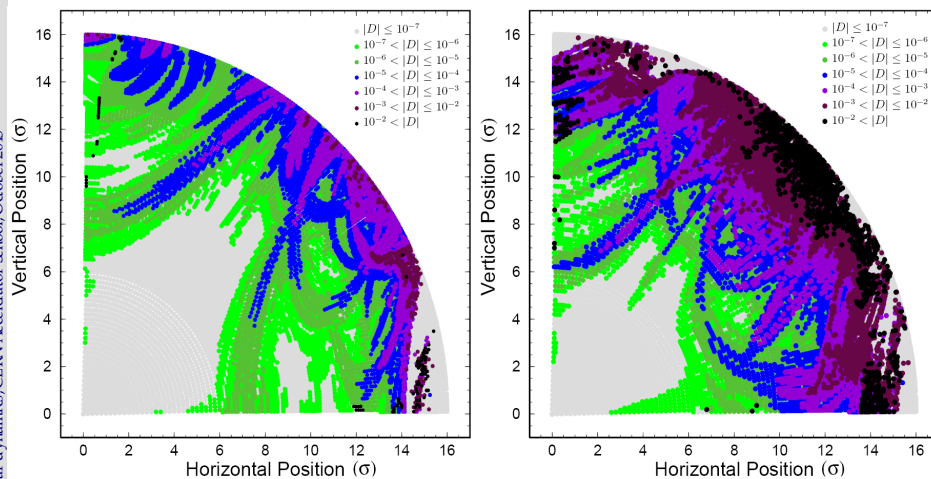
$$\mathbf{D}|_{t=\tau} = \boldsymbol{\nu}|_{t \in (0, \tau/2]} - \boldsymbol{\nu}|_{t \in (\tau/2, \tau]}$$

- Plot the initial condition space color-coded with the norm of the diffusion vector
- Compute a diffusion quality factor by averaging all diffusion coefficients normalized with the initial conditions radius

$$D_{QF} = \left\langle \frac{|\mathbf{D}|}{(I_{x0}^2 + I_{y0}^2)^{1/2}} \right\rangle_R$$

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Diffusion maps for the LHC



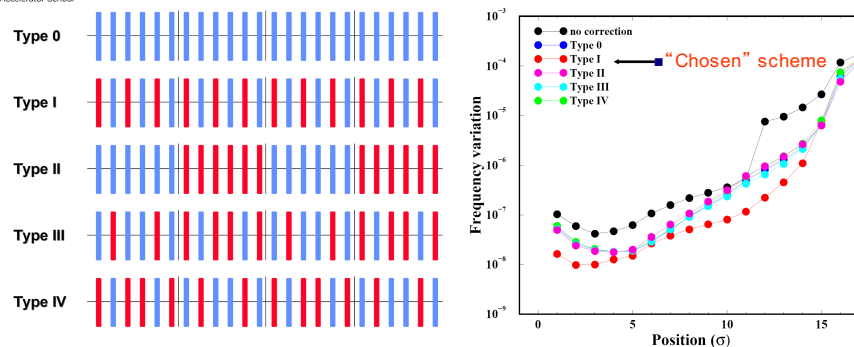
Diffusion maps for the target error table (left) and an increased random skew octupole error in the super-conducting dipoles (right)

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Numerical Applications


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Correction schemes efficiency




- Comparison of correction schemes for b_4 and b_5 errors in the LHC dipoles
- Frequency maps, resonance analysis, tune diffusion estimates, survival plots and short term tracking, proved that only half of the correctors are needed

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Beam-Beam interaction



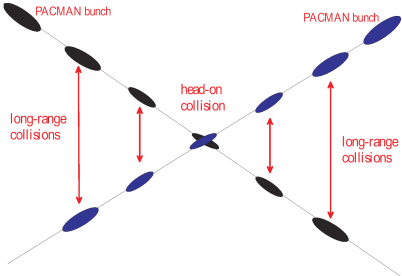
Variable	Symbol	Value
Beam energy	E	7 TeV
Particle species	...	protons
Full crossing angle	θ_c	300 μ rad
rms beam divergence	σ'_x	31.7 μ rad
rms beam size	σ_x	15.9 μ m
Normalized transv. rms emittance	$\gamma\epsilon$	3.75 μ m
IP beta function	β^*	0.5 m
Bunch charge	N_b	$(1 \times 10^{11} - 2 \times 10^{12})$
Betatron tune	Q_0	0.31

■ Long range beam-beam interaction represented by a 4D kick-map

$$\Delta x = -n_{par} \frac{2r_p N_b}{\gamma} \left[\frac{x' + \theta_c}{\theta_t^2} \left(1 - e^{-\frac{\theta_t^2}{2\theta_{x,y}^2}} \right) - \frac{1}{\theta_c} \left(1 - e^{-\frac{\theta_t^2}{2\theta_{x,y}^2}} \right) \right]$$


$$\Delta y = -n_{par} \frac{2r_p N_b}{\gamma} \frac{y'}{\theta_t^2} \left(1 - e^{-\frac{\theta_t^2}{2\theta_{x,y}^2}} \right)$$

with $\theta_t \equiv \left((x' + \theta_c)^2 + y'^2 \right)^{1/2}$




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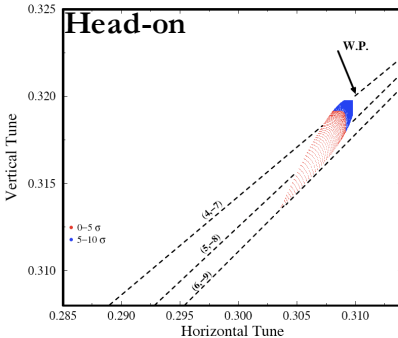


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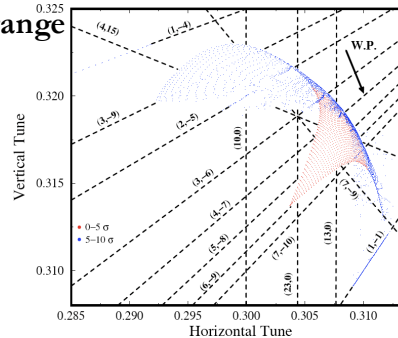
Head-on vs Long range interaction



Head-on



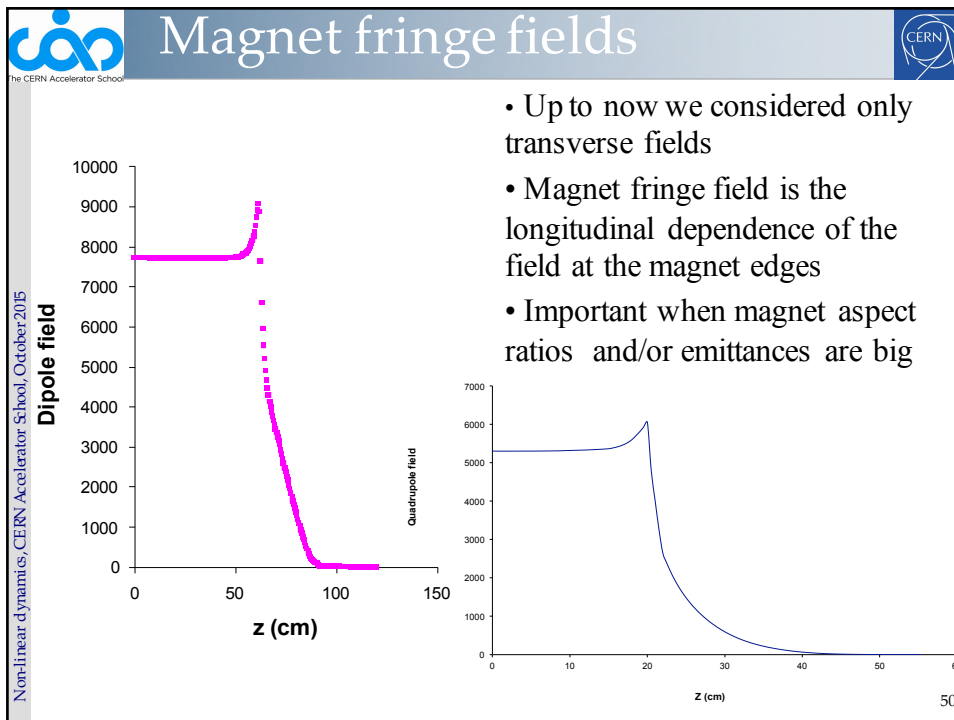
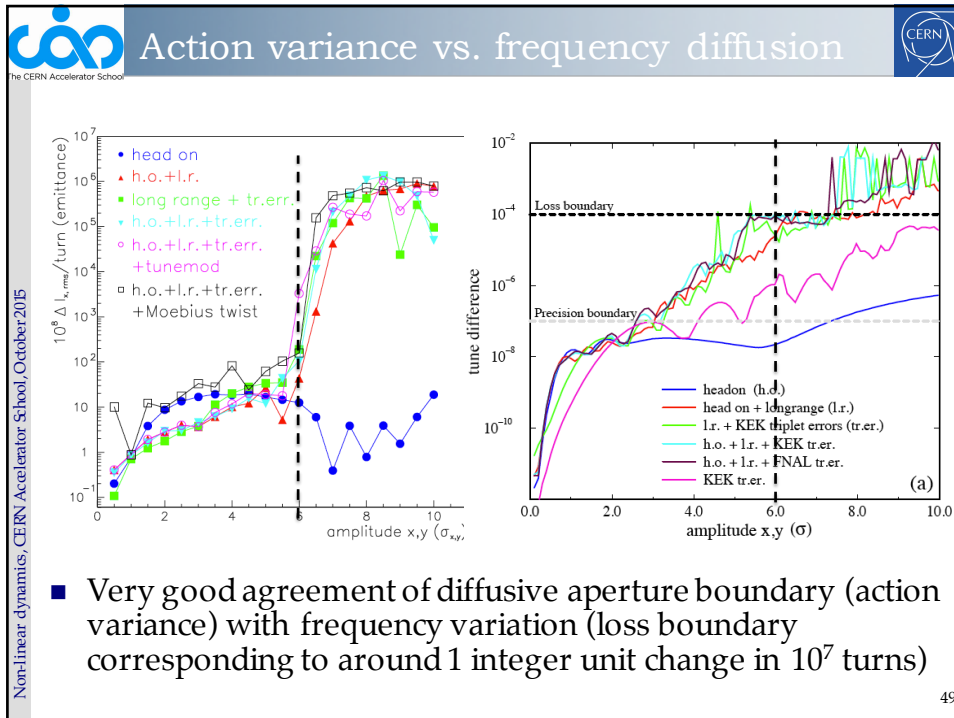
Long range



- Proved dominant effect of long range beam-beam effect
- Dynamics dominated by the 1/r part of the force, reproduced by electrical wire, which was proposed for correcting the effect
- Experimental verification in SPS and installation to the LHC IPs

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Quadrupole fringe field

General field expansion for a quadrupole magnet:

$$B_x = \sum_{m,n=0}^{\infty} \sum_{l=0}^m \frac{(-1)^m x^{2n} y^{2m+1}}{(2n)!(2m+1)!} \binom{m}{l} b_{2n+2m+1-2l}^{[2l]}$$

$$B_y = \sum_{m,n=0}^{\infty} \sum_{l=0}^m \frac{(-1)^m x^{2n+1} y^{2m}}{(2n+1)!(2m)!} \binom{m}{l} b_{2n+2m+1-2l}^{[2l]} \quad .$$

$$B_z = \sum_{m,n=0}^{\infty} \sum_{l=0}^m \frac{(-1)^m x^{2n+1} y^{2m+1}}{(2n+1)!(2m+1)!} \binom{m}{l} b_{2n+2m+1-2l}^{[2l+1]}$$

and to leading order

$$B_x = y \left[b_1 - \frac{1}{12} (3x^2 + y^2) b_1^{[2]} \right] + O(5)$$

$$B_y = x \left[b_1 - \frac{1}{12} (3y^2 + x^2) b_1^{[2]} \right] + O(5)$$

$$B_z = xy b_1^{[1]} + O(4)$$

The quadrupole fringe to leading order has an octupole-like effect

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Magnet fringe fields

From the hard-edge Hamiltonian

$$H_f = \frac{\pm Q}{12B\rho(1+\frac{\delta p}{p})} (y^3 p_y - x^3 p_x + 3x^2 y p_y - 3y^2 x p_x),$$

the first order shift of the frequencies with amplitude can be computed analytically

$$\begin{pmatrix} \delta\nu_x \\ \delta\nu_y \end{pmatrix} = \begin{pmatrix} a_{hh} & a_{hv} \\ a_{hv} & a_{vv} \end{pmatrix} \begin{pmatrix} 2J_x \\ 2J_y \end{pmatrix},$$

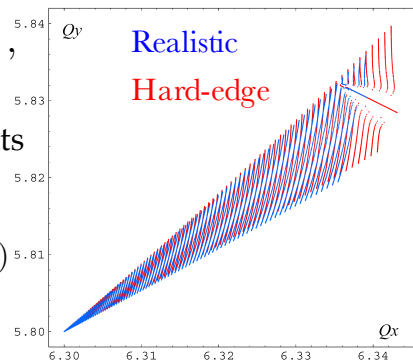
with the "anharmonicity" coefficients (torsion)

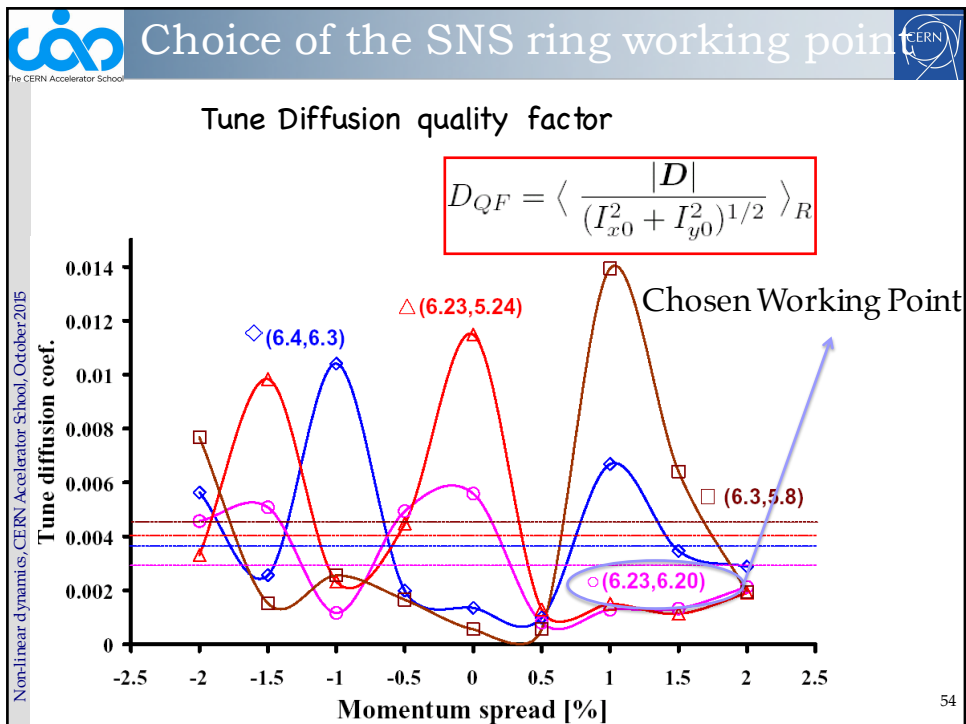
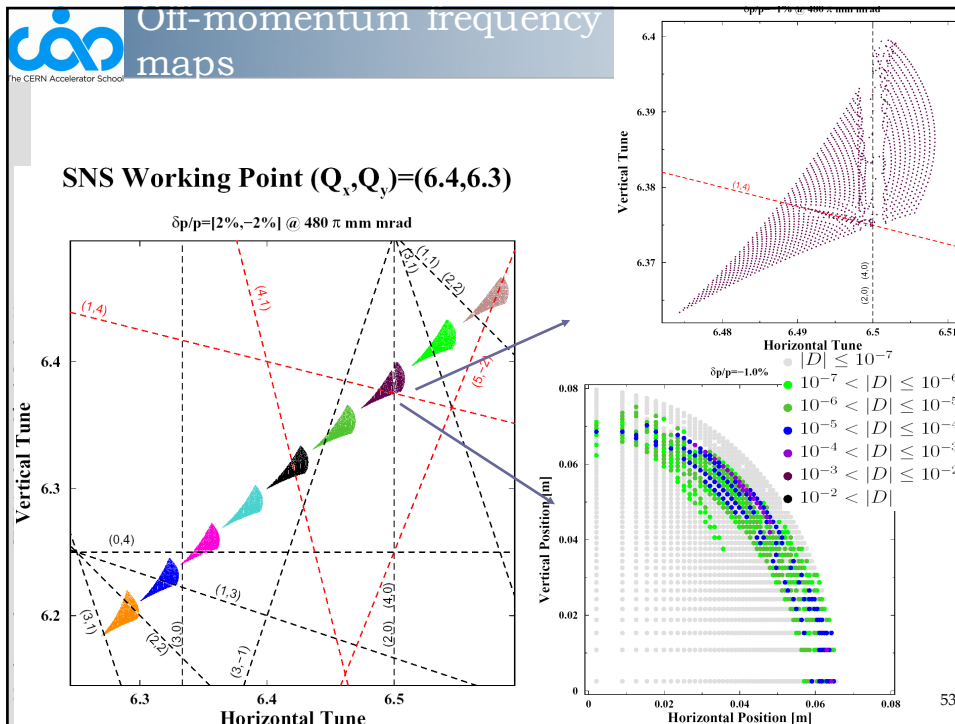
$$a_{hh} = \frac{-1}{16\pi B\rho} \sum_i \pm Q_i \beta_{xi} \alpha_{xi}$$

$$a_{hv} = \frac{1}{16\pi B\rho} \sum_i \pm Q_i (\beta_{xi} \alpha_{yi} - \beta_{yi} \alpha_{xi})$$

$$a_{vv} = \frac{1}{16\pi B\rho} \sum_i \pm Q_i \beta_{yi} \alpha_{yi}$$

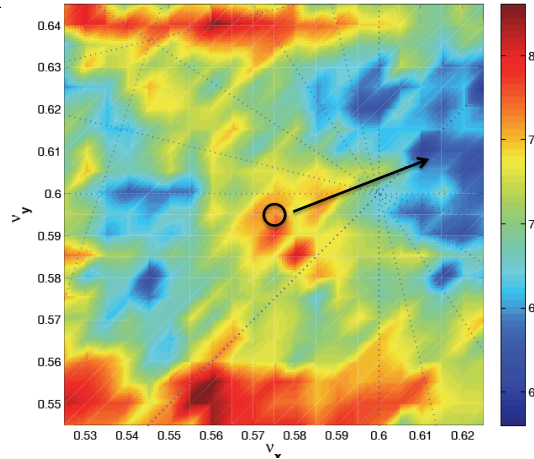
Tune footprint for the SNS based on hard-edge (red) and realistic (blue) quadrupole fringe-field





Global Working point choice

- Figure of merit for choosing best working point is sum of diffusion rates with a constant added for every lost particle
- Each point is produced after tracking 100 particles
- Nominal working point had to be moved towards “blue” area



$$e^D = \sqrt{\frac{(\nu_{x,1} - \nu_{x,2})^2 + (\nu_{y,1} - \nu_{y,2})^2}{N/2}}$$

$$WPS = 0.1N_{lost} + \sum e^D$$

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Advanced symplectic integration schemes

- Symplectic integrators with **positive** steps for Hamiltonian systems $H = A + \epsilon B$ with both A and B **integrable** were proposed by McLachlan (1995).
- Laskar and Robutel (2001) derived all orders of such integrators
- Consider the formal solution of the Hamiltonian system written in the Lie representation

$$\vec{x}(t) = \sum_{n \geq 0} \frac{t^n}{n!} L_H^n \vec{x}(0) = e^{tL_H} \vec{x}(0).$$
- A symplectic integrator of order n from t to $t + \tau$ consists of approximating the Lie map $e^{\tau L_H} = e^{\tau(L_A + L_{\epsilon B})}$ by products of $e^{c_i \tau L_A}$ and $e^{d_i \tau L_{\epsilon B}}$, $i = 1, \dots, n$ which integrate exactly A and B over the time-spans $c_i \tau$ and $d_i \tau$
- The constants c_i and d_i are chosen to reduce the error

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SABA₂ integrator

- The SABA₂ integrator is written as

$$\text{SABA}_2 = e^{c_1 \tau L_A} e^{d_1 \tau L_{\epsilon B}} e^{c_2 \tau L_A} e^{d_1 \tau L_{\epsilon B}} e^{c_1 \tau L_A},$$

with $c_1 = \frac{1}{2} \left(1 - \frac{1}{\sqrt{3}} \right)$, $c_2 = \frac{1}{\sqrt{3}}$, $d_1 = \frac{1}{2}$.

- When $\{\{A, B\}, B\}$ is integrable, e.g. when A is quadratic in momenta and B depends only in positions, the accuracy of the integrator is improved by two small negative kicks

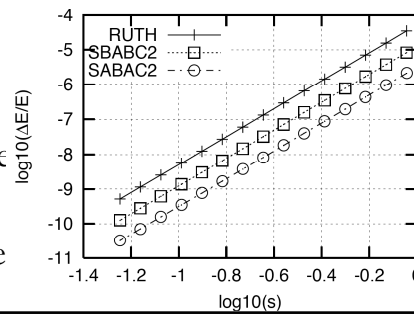
$$\text{SABA}_2\text{C} = e^{-\tau^3 \epsilon^2 \frac{c}{2} L_{\{\{A, B\}, B\}}} (\text{SABA}_2) e^{-\tau^3 \epsilon^2 \frac{c}{2} L_{\{\{A, B\}, B\}}}$$

with $c = (2 - \sqrt{3})/24$

- The accuracy of SABA₂C is one order of magnitude higher than the Forest-Ruth 4th order scheme

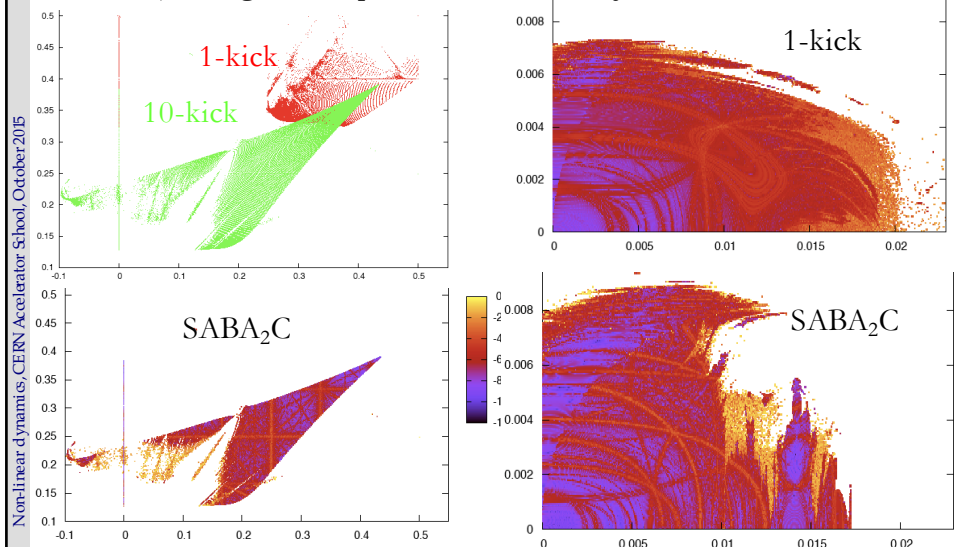
- The usual “drift-kick” scheme corresponds to the 2nd order integrator

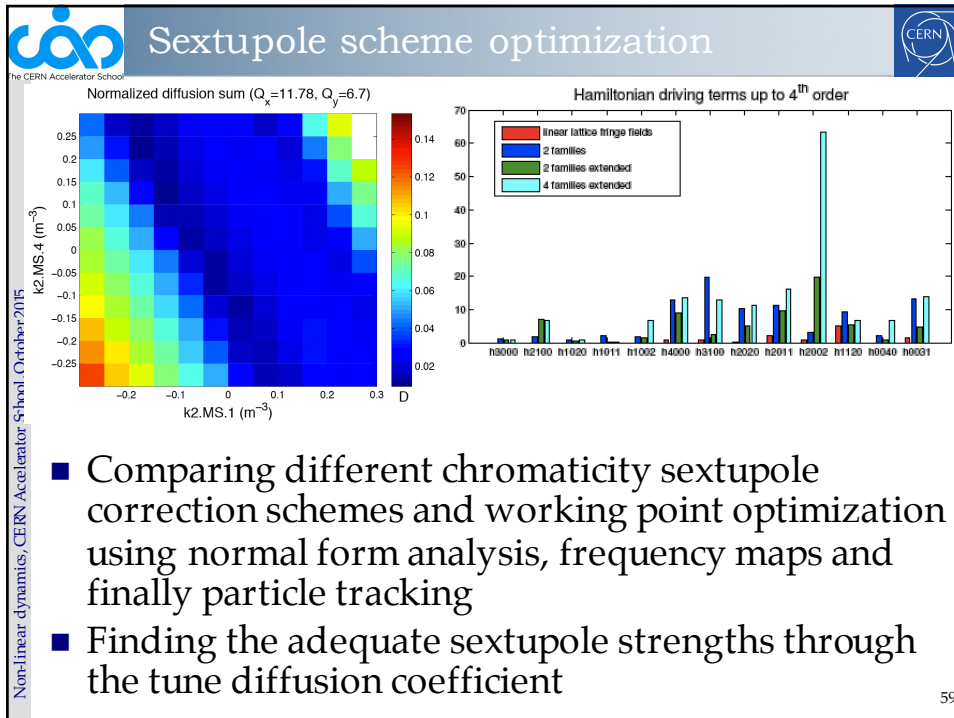
$$\text{SABA}_1 = e^{\frac{\tau}{2} L_A} e^{\tau L_{\epsilon B}} e^{\frac{\tau}{2} L_A},$$



Application of the SABA₂C integrator

- The one kick integrator reveals a completely different dynamics than the 10-kick
- SABA₂C integrator captures the correct dynamics

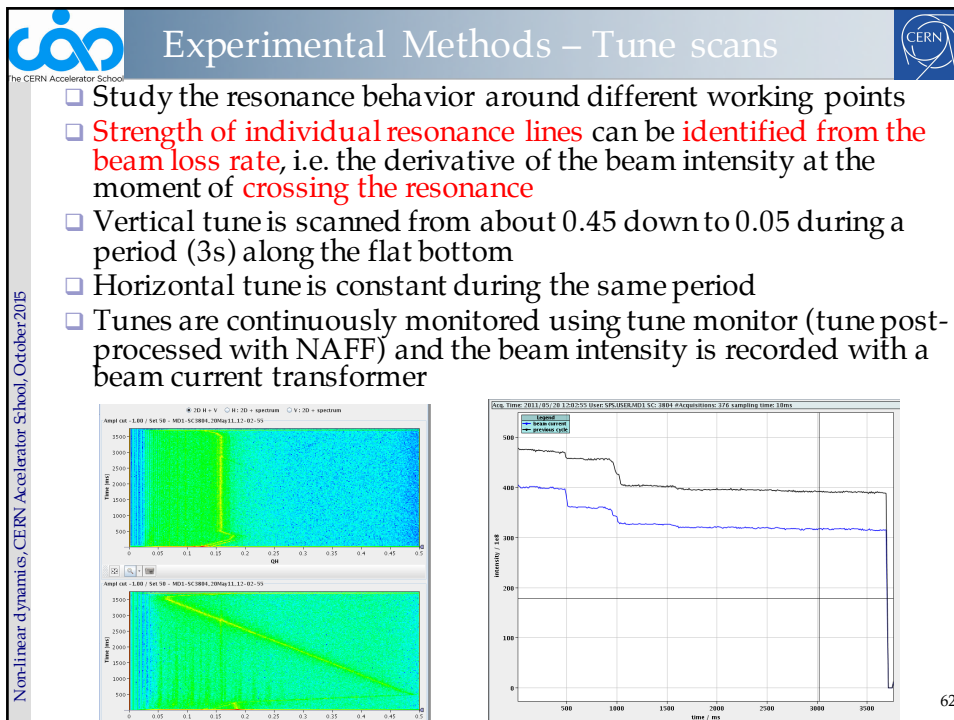
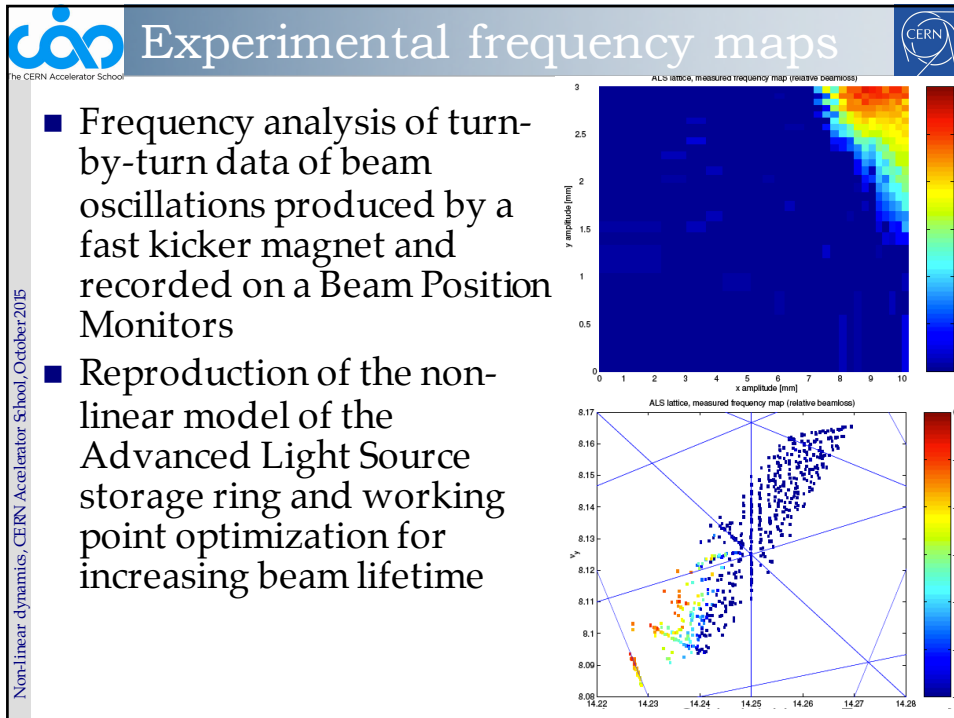




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Experimental methods

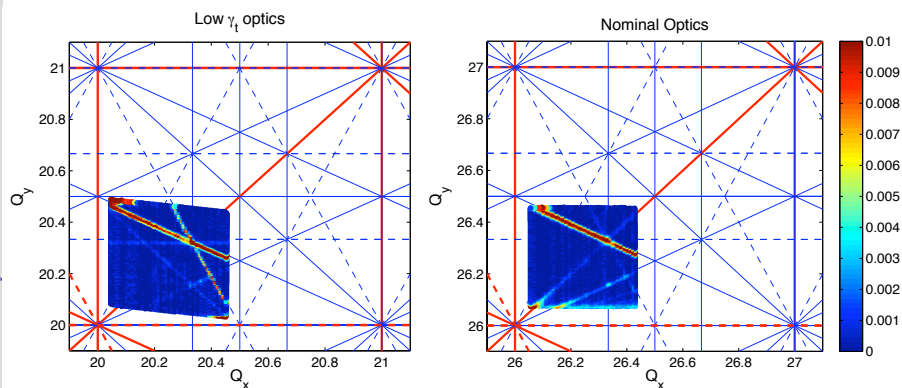
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Tune Scans from the SPS

- Plot the tunes color-coded with the amount of loss
- Identify the dangerous resonances
- Compare between two different optics
- Try to refine the machine model

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Summary

- **Resonances** (stable and unstable fixed points) are responsible for the onset of **chaos**
- **Dynamic aperture** by brute force tracking (with symplectic numerical integrators) is the usual quality criterion for evaluating non-linear dynamics performance of a machine
- **Frequency Map Analysis** is a numerical tool that enables to study in a global way the dynamics, by identifying the excited **resonances** and the extent of **chaotic** regions
- It can be directly applied to **tracking** but also **experimental** data
- A combination of these modern methods enable a thorough analysis of non-linear dynamics and lead to a robust design

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C.Skokos, C.Steier, F.Schmidt,
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Appendix

The pendulum

- An important non-linear equation which can be integrated is the one of the pendulum, for a string of length L and gravitational constant g

$$\frac{d^2\phi}{dt^2} + \frac{g}{L} \sin \phi = 0$$

- For small displacements it reduces to an harmonic oscillator with frequency $\omega_0 = \sqrt{\frac{g}{L}}$

- The integral of motion (scaled energy) is

$$\frac{1}{2} \left(\frac{d\phi}{dt} \right)^2 - \frac{g}{L} \cos \phi = I_1 = E'$$

and the quadrature is written as $t = \int \frac{d\phi}{\sqrt{2(I_1 + \frac{g}{L} \cos \phi)}}$
assuming that for $t = 0$, $\phi = 0$

Solution for the pendulum

- Using the substitutions $\cos \phi = 1 - 2k^2 \sin^2 \theta$ with $k = \sqrt{1/2(1 + I_1 L/g)}$, the integral is

$$t = \sqrt{\frac{L}{g}} \int_0^\theta \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}}$$
 and can be solved using

Jacobi elliptic functions: $\phi(t) = 2 \arcsin \left[k \operatorname{sn} \left(t \sqrt{\frac{g}{L}}, k \right) \right]$

- For recovering the period, the integration is performed between the two extrema, i.e. $\phi = 0$ and $\phi = \arccos(-I_1 L/g)$, corresponding to $\theta = 0$ and $\theta = \pi/2$, for which

$$T = 4 \sqrt{\frac{L}{g}} \int_0^{\pi/2} \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}} = 4 \sqrt{\frac{L}{g}} \mathcal{F}(\pi/2, k)$$

i.e. the complete elliptic integral multiplied by four times the period of the harmonic oscillator

- Consider a general two degrees of freedom Hamiltonian:

$$H(\mathbf{J}, \varphi) = H_0(\mathbf{J}) + \varepsilon H_1(\mathbf{J}, \varphi)$$

with the perturbed part periodic in angles:

$$H_1(\mathbf{J}, \varphi) = \sum_{k_1, k_2} H_{k_1, k_2}(J_1, J_2) \exp[i(k_1 \varphi_1 + k_2 \varphi_2)]$$

- The resonance $n_1 \omega_1 + n_2 \omega_2 = 0$ prevents the convergence of the series
- A canonical transformation can be applied for eliminating one action: $(\mathbf{J}, \varphi) \mapsto (\hat{\mathbf{J}}, \hat{\varphi})$ using the generating function $F_r(\hat{\mathbf{J}}, \varphi) = (n_1 \varphi_1 - n_2 \varphi_2) \hat{J}_1 + \varphi_2 \hat{J}_2$
- The relationships between new and old variables are

$$J_1 = n_1 \hat{J}_1, \quad J_2 = \hat{J}_2 - n_2 \hat{J}_1$$

$$\hat{\varphi}_1 = n_1 \varphi_1 - n_2 \varphi_2, \quad \hat{\varphi}_2 = \varphi_2$$

- This transformation put us in a rotating frame where the rate of change $\dot{\hat{\varphi}}_1 = n_1 \dot{\varphi}_1 - n_2 \dot{\varphi}_2$ measures the deviation from resonance

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- The transformed Hamiltonian is $\hat{H}(\hat{\mathbf{J}}, \hat{\varphi}) = \hat{H}_0(\hat{\mathbf{J}}) + \varepsilon \hat{H}_1(\hat{\mathbf{J}}, \hat{\varphi})$ with the perturbation written as a Fourier series

$$\hat{H}_1(\hat{\mathbf{J}}, \hat{\varphi}) = \sum_{k_1, k_2} H_{k_1, k_2}(\hat{\mathbf{J}}) \exp \left\{ \frac{i}{n_1} [k_1 \hat{\varphi}_1 + (k_1 n_2 + k_2 n_1) \hat{\varphi}_1] \right\}$$

- This transformation assumes that $\dot{\varphi}_2$ is the slow frequency and we can average the Hamiltonian over the corresponding angle to obtain

$$\bar{H}(\hat{\mathbf{J}}, \hat{\varphi}) = \bar{H}_0(\hat{\mathbf{J}}) + \varepsilon \bar{H}_1(\hat{\mathbf{J}}, \hat{\varphi}_1) \quad \text{with} \quad \bar{H}_0(\hat{\mathbf{J}}) = \hat{H}_0(\hat{\mathbf{J}}) \quad \text{and}$$

$$\bar{H}_1(\hat{\mathbf{J}}, \hat{\varphi}_1) = \langle \hat{H}_1(\hat{\mathbf{J}}, \hat{\varphi}_1) \rangle_{\hat{\varphi}_2} = \sum_{p=-\infty}^{+\infty} H_{-pn_1, pn_2}(\hat{\mathbf{J}}) \exp(-ip \hat{\varphi}_1)$$

- The averaging eliminated one angle and thus $\hat{J}_2 = J_2 + J_1 \frac{n_2}{n_1}$ is an invariant of motion
- This means that the Hamiltonian has effectively only one degree of freedom and it is integrable

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Secular perturbation theory

- Assuming that the dominant Fourier harmonics for $p = 0, \pm 1$ the Hamiltonian is written as

$$\bar{H}(\hat{\mathbf{J}}, \hat{\phi}_1) = \bar{H}_0(\hat{\mathbf{J}}) + \varepsilon \bar{H}_{0,0}(\hat{\mathbf{J}}) + 2\varepsilon \bar{H}_{n_1, -n_2}(\hat{\mathbf{J}}) \cos \hat{\phi}_1$$

- Fixed points $(\hat{J}_{10}, \hat{\phi}_{10})$ (i.e. periodic orbits) in phase space $(\hat{J}_1, \hat{\phi}_1)$ are defined by $\frac{\partial \bar{H}}{\partial \hat{J}_1} = 0$, $\frac{\partial \bar{H}}{\partial \hat{\phi}_1} = 0$

- Move the reference on fixed point and expand $\bar{H}(\hat{\mathbf{J}})$ around $\Delta \hat{J}_1 = \hat{J}_1 - \hat{J}_{10}$

- Hamiltonian describing motion near a resonance:

$$\bar{H}_r(\Delta \hat{J}_1, \hat{\phi}_1) = \left. \frac{\partial^2 \bar{H}_0(\hat{\mathbf{J}})}{\partial \hat{J}_1^2} \right|_{\hat{J}_1 = \hat{J}_{10}} \frac{(\Delta \hat{J}_1)^2}{2} + 2\varepsilon \bar{H}_{n_1, -n_2}(\hat{\mathbf{J}}) \cos \hat{\phi}_1$$

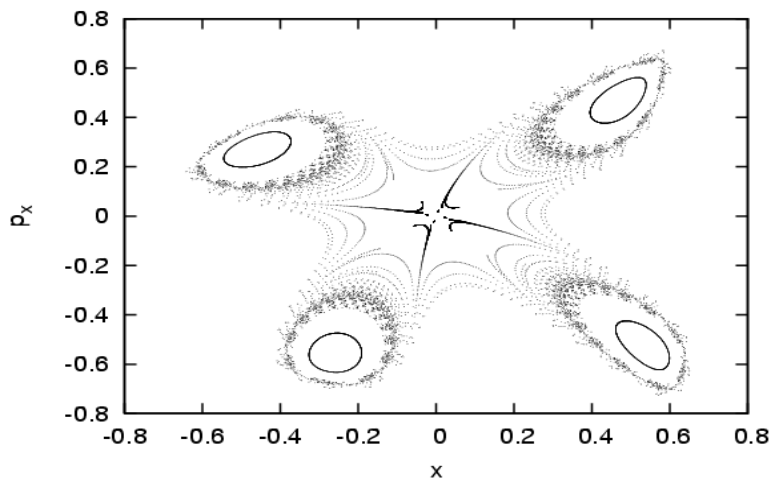
- Motion near a typical resonance is like the one of the pendulum!!! The frequency and the resonance half width are

$$\hat{\omega}_1 = \left(2\varepsilon \bar{H}_{n_1, -n_2}(\hat{\mathbf{J}}) \left. \frac{\partial^2 \bar{H}_0(\hat{\mathbf{J}})}{\partial \hat{J}_1^2} \right|_{\hat{J}_1 = \hat{J}_{10}} \right)^{1/2} \quad \Delta \hat{J}_{1 \max} = 2 \left(\frac{2\varepsilon \bar{H}_{n_1, -n_2}(\hat{\mathbf{J}})}{\left. \frac{\partial^2 \bar{H}_0(\hat{\mathbf{J}})}{\partial \hat{J}_1^2} \right|_{\hat{J}_1 = \hat{J}_{10}}} \right)^{1/2}$$

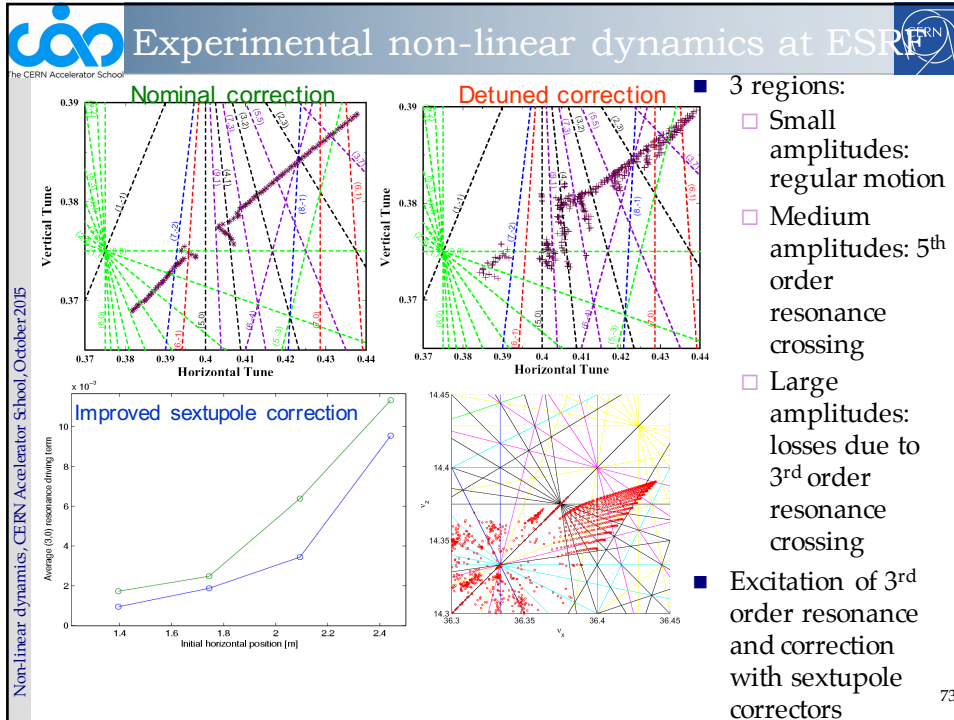
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Octupole with hyperbolic central fixed point

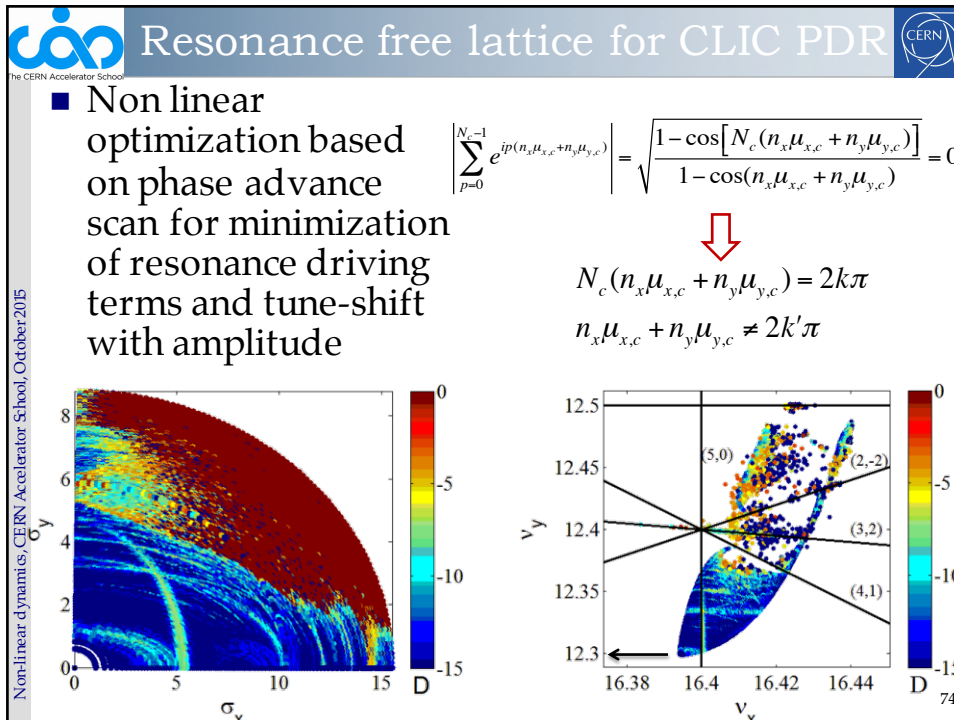
- Now, if $c = 0$ the solution for the action is $J_{20} = 0$
- So there is no minima in the potential, i.e. the central fixed point is hyperbolic



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