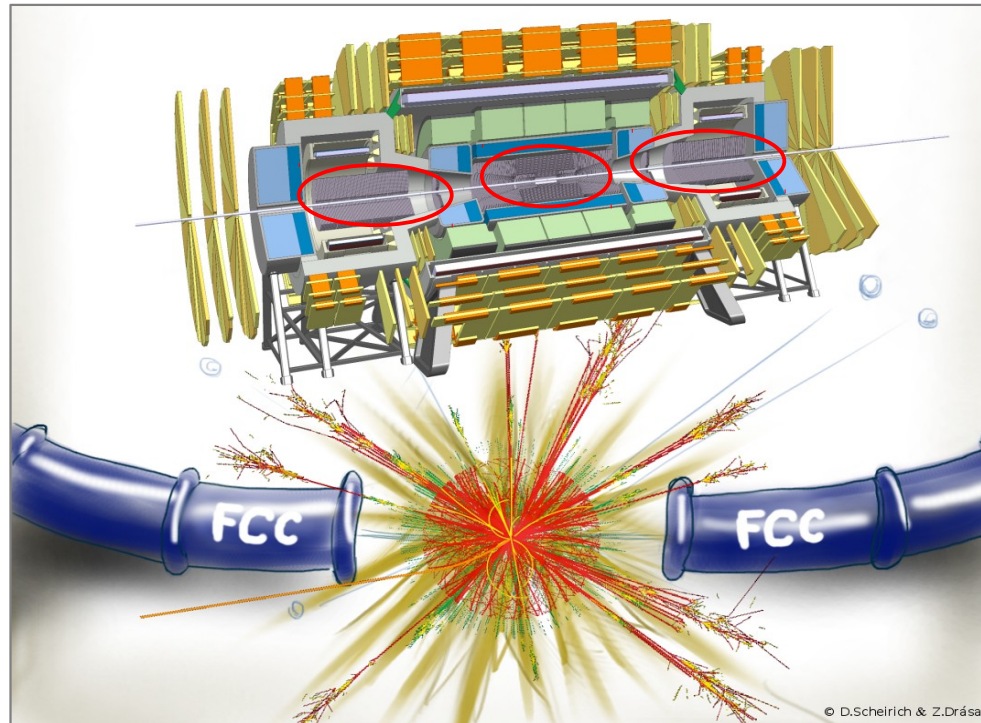


Overview of FCC-hh Tracker Design



Zbyněk Drásal
CERN



On behalf of the FCC-hh detector working group



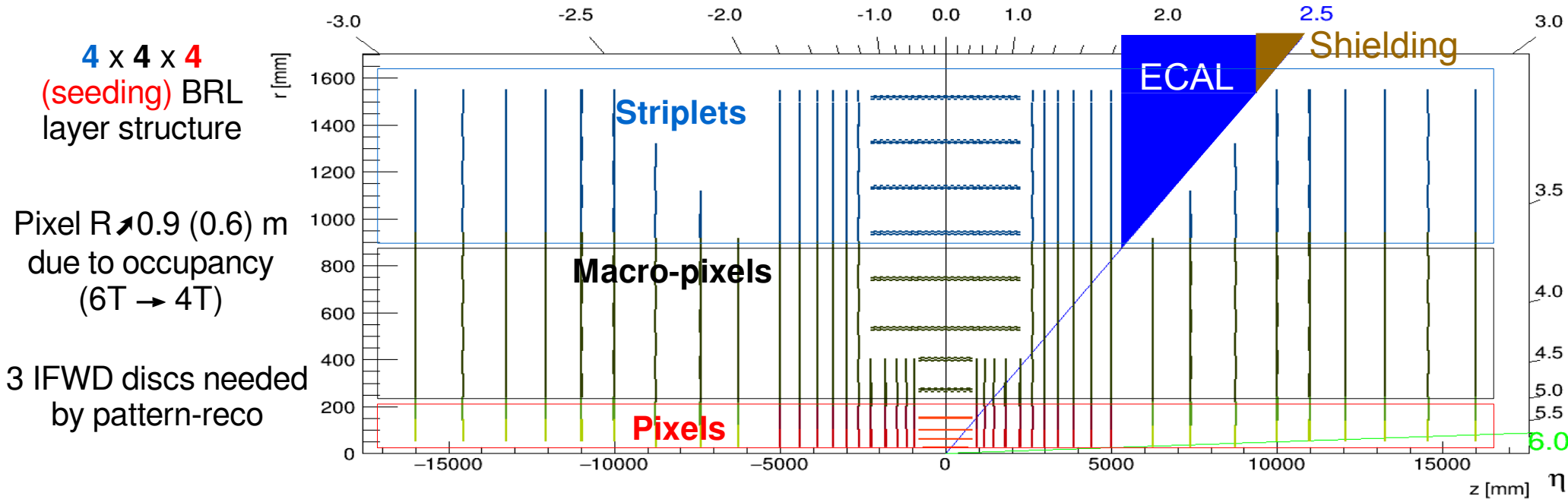
Overview

- Introduction
 - Physics motivation & challenges
- Tracker design & expected tracker performance
 - Baseline tracker layout v3.03 → for details of all layouts see: <http://fcc-tklayout.web.cern.ch>
 - Magnetic field scenarios & tracking resolution
 - Expected tracking performance (see also E. Perez's talk) & material budget
 - b,c, τ -tagging → for details see E. Perez's talk
- Implications of high pile-up & high-rate environment
 - Pattern recognition capabilities & granularity in Z → new tilted layout v4.01
 - Vertexing (see also E. Perez's talk) & timing information
 - Data rates & tracker occupancy
- Software toolkits:
 - tkLayout, FCCSW & ACTS → follow FCC SW session: J.Lingemann, J.Hrdinka & V.Volkl's talks
- Summary & Outlook

Physics Motivation & Challenges

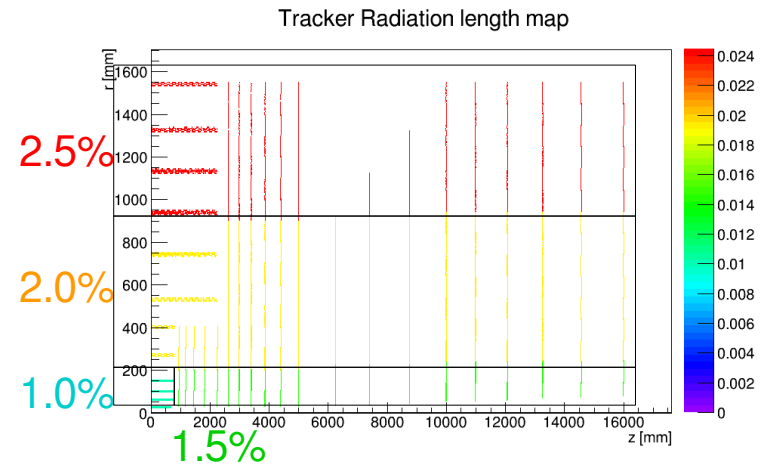
- **A few benchmarks to give us an intuitive hints on key tracker parameters:**
 - e.g. SM & Higgs or VBF
 - Need **extended tracking up-to $|\eta| \sim 4$** , efficient VBF jet measurement **up-to $|\eta| \sim 6$**
 - Need **tracker hermeticity** for all tracks coming from the luminous region ($\sigma_z \sim \pm 75\text{mm}$)
 - **Direct searches (higher mass reach)**, e.g. $Z' \rightarrow \mu\mu$ or $Z' \rightarrow t\bar{t}$ (high boosted objects)
 - Need for **high dp_T/p_T res. $\sim 10\text{-}20\%$ @ $10\text{TeV}/c$** (cf. LHC: 10% @ 1TeV)
 - But still keeping **sensitivity for low p_T tracks**
 - **Precise understanding of SM/New physics** → higher mass reach (**100TeV**)/higher luminosity **$30 \times 10^{34} \text{ cm}^{-2}\text{s}^{-1}$ (@ 25ns)** → **$O(1000)$ pile-up events per bunch crossing expected**
 - **Precision tracking & track association with primary vertex** required
 - **Efficient b, c, τ tagging** despite intense radiation levels at low radii

Baseline Tracker Layout (v3.03)



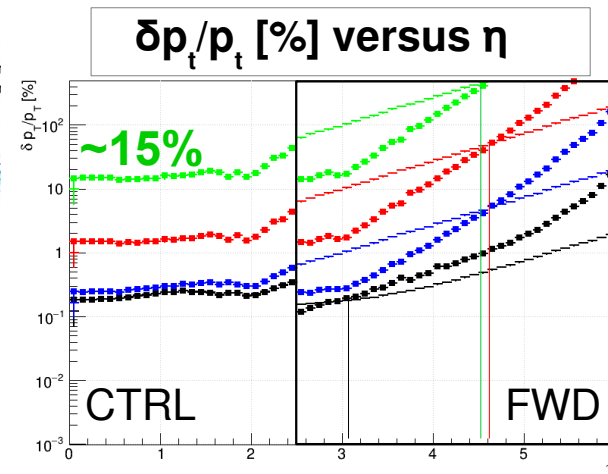
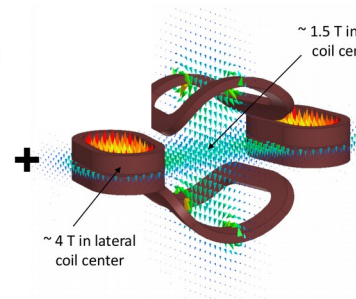
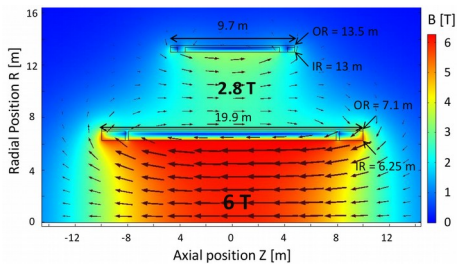
- **Pixels (pitch):** $25 \times 50 \mu\text{m}^2$ (1-4th BRL layers, EC R1), $100/3 \times 100 \mu\text{m}^2$ (R2), $100/3 \times 400 \mu\text{m}^2$ (R3,R4)
- **Macro-pixels (pitch):** $100/3 \times 400 \mu\text{m}^2$
- **Strips (pitch):** $100/3 \mu\text{m} \times 50 \text{mm}$ (BRL), $100/3 \mu\text{m} \times 10 \text{mm}$ (EC)

- \rightarrow **Surface:** 9.6m^2 (pixels), 133m^2 (macro-pixels), 287.8m^2 (strips)
- \rightarrow **#channels:** 5460.9M (pixels), 9964.4M (macro-pixels), 489.4M (strips)



Mag. Field & Tracking Performance

- A snapshot of mag. field scenario a year ago: 6T twin solenoid + balanced conical shape/10Tm dipole in FWD:



- Simulated p_T :
- 10 GeV/c → @ $\eta=5$ $p \sim 700$ GeV/c
 - 100 GeV/c → @ $\eta=5$ $p \sim 7$ TeV/c
 - 1 TeV
 - 10 TeV
 - solenoid
 - dipole

→ Solenoid comparable to dipole in tracking resolution!

→ 6T scenario: **technology challenging & costly** option → focus on scenario with 4T & more aggressive detector design (tilted layout + finer granularity)

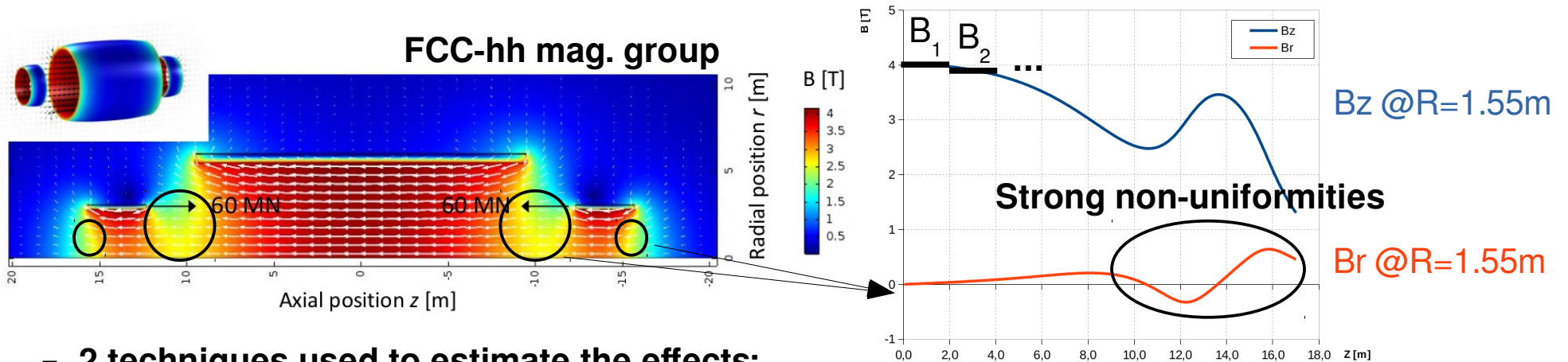
$$\frac{\Delta p_T}{p_T} \approx \frac{\sigma [m] p_T [\text{GeV}/c]}{0.3 B [T] L^2 [m^2]}$$

6T → 4T scenario → L: 2.4 → 1.55m
 B: 6T → 4T
 σ : 25 μ m → 10(7.5) μ m

res. degrades ~ 2.4x
 res. degrades ~ 1.5x
 res. Improves ~ **2.5 (3.3)x** } **3.6x**

Mag. Field & Tracking Performance

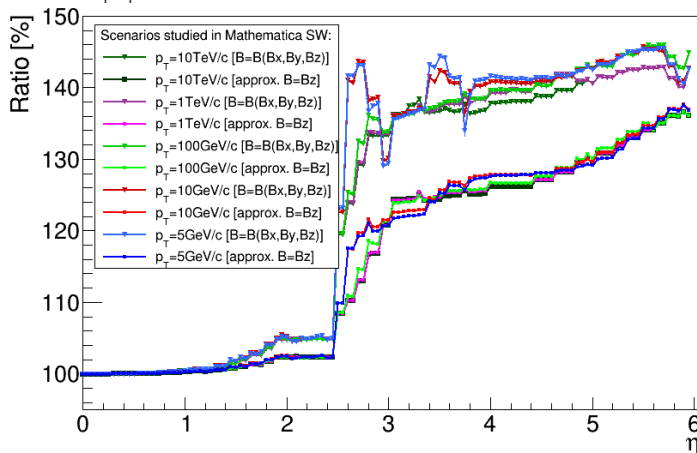
- 4T solenoid option → how do the mag. field non-uniformities affect FWD tracking?



- 2 techniques used to estimate the effects:

- N-parabola approx. (tkLayout) & numerical solution by W.Riegler (Mathematica SW)

Ratio of $\delta p_T/p_T$: (Real 4T)/(Const. 4T) - triangles [B=B(Bx,By,Bz)] x rectangles [B=B(0,0,Bz)]



- Deterioration due to $B_z(r,z) \sim 25-35\%$
- **Total deterioration in $\delta p_T/p_T$ due to non-uniformity of B field (B_z & B_r) $\sim 35-45\%$ @ $\eta=2.5$ or higher**
- **Overall negligible effect!**

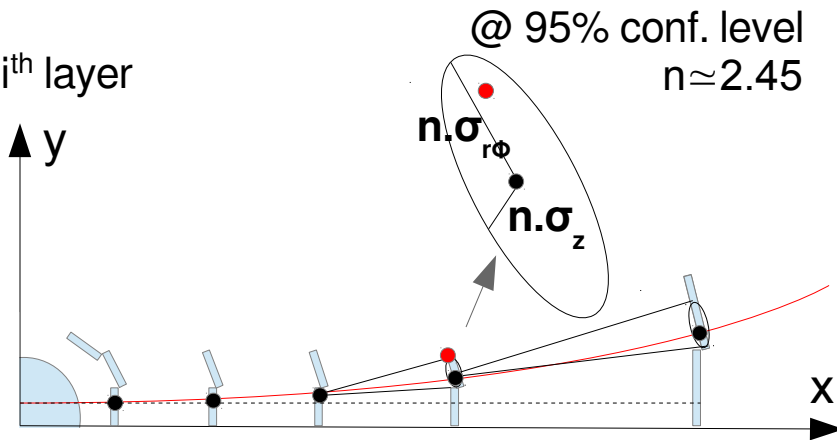
Pattern recognition (PR) Capabilities

- Granularity in Z strongly affects **pattern recognition capabilities**, so how to study PR analytically? Strategy: study “**weak**” spots in layout!

→ Assume **perfect seeding** (triplet) → propagate $\sigma_{r\phi}$, σ_z to i^{th} layer

→ Calculate probability **p** to mis-match a **real hit anywhere on the track** with a **bkg hit @95% CL in PU=1000**

$$p = 1 - \prod_{i=4}^N (1 - p_{\text{bkg95\%}}^i)$$



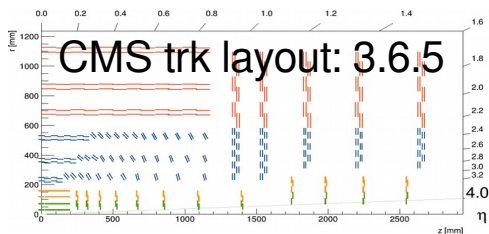
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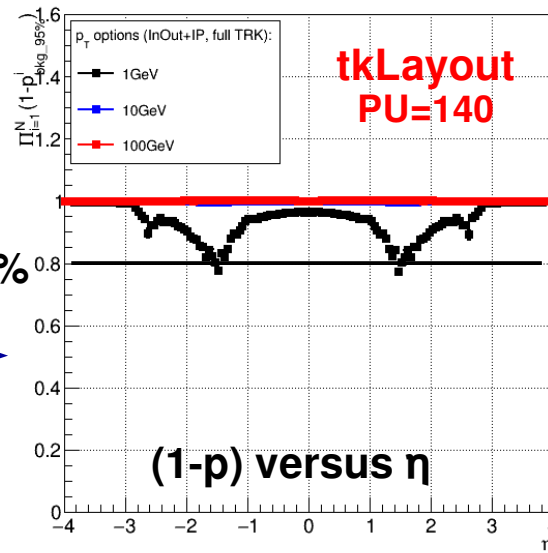
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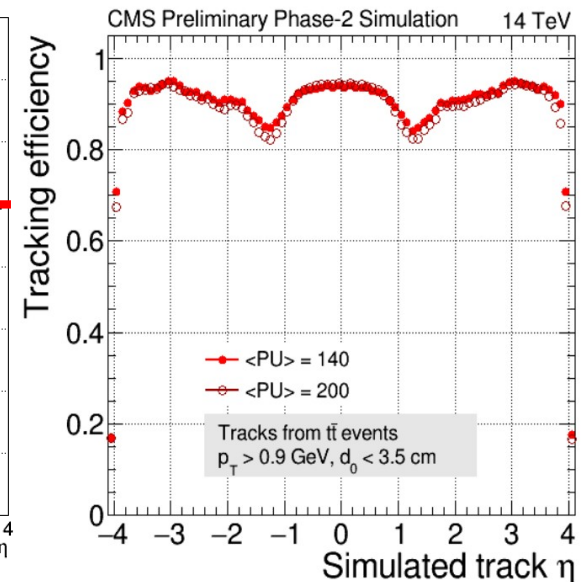
- How to “**qualitatively**” interpret **p**?
c.f. CMS Ph2 layout @PU~140...



(1-p) ~ 80%



(1-p) versus η



E.Brondolin:
CMS DP-2017/010

- To keep **similar PR** for **FCCh @PU~1000**, set **bkg. prob. contamination p @20%**

Understanding Pattern Recognition Results

- 4 key parameters affecting propagation of error ellipse:
 - Multiple scattering & **material effect @ ϑ** (tilt angle α)
 - **Propagation distance**
 - **Projection factor** on det. plane
 - **Detector resolution**

$$\sigma_{MS}^2 \approx \langle \vartheta_{pT}^2 \rangle \frac{d/X_0}{\sin(\vartheta + \alpha)} \Delta r^2 f_{proj}$$

$$\langle \vartheta_{pT}^2 \rangle = \left(\frac{13.6 \text{ MeV}}{\beta p_T c} \right)^2 \left(1 + 0.038 \ln \frac{d/X_0}{\sin(\vartheta + \alpha)} \right)^2$$

$$f_{proj} = \left(\frac{1}{\sin \vartheta} \right)^2 \text{ proj. in Z}$$

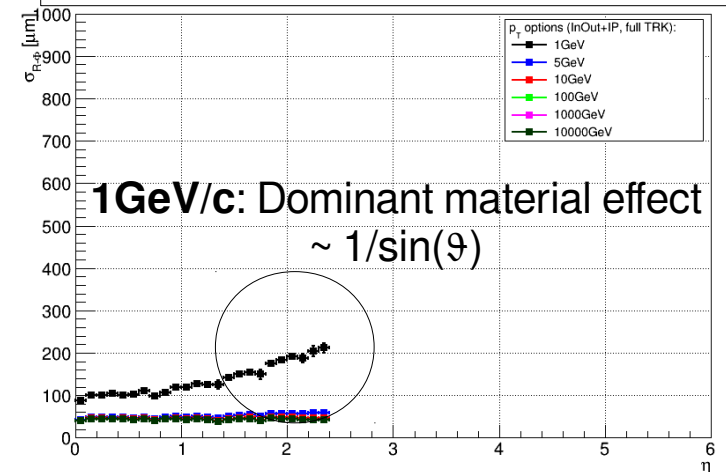
$$f_{proj} = 1 \text{ proj. in R-}\Phi$$

$$\sigma_{R\Phi} = \sqrt{\sigma_{R\Phi_{loc}}^2 + (A/\sqrt{1 - A^2 \sin^2 \alpha})^2 \sigma_{Z_{loc}}^2}$$

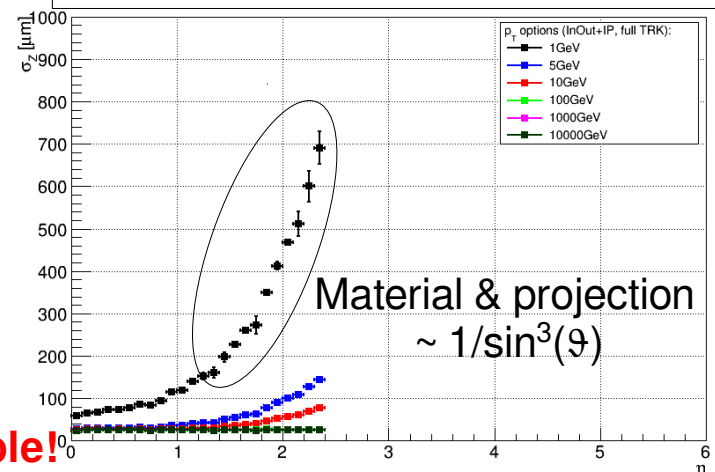
$$A = \Delta r / 2R$$

→ **To minimize mat. effects, tracker in tilted layout inevitable!**

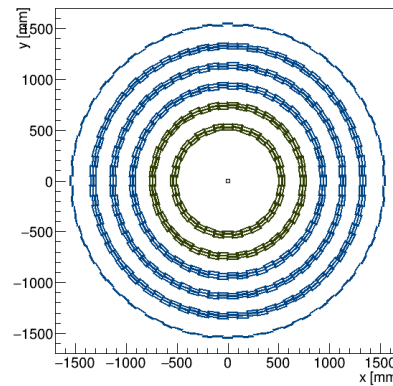
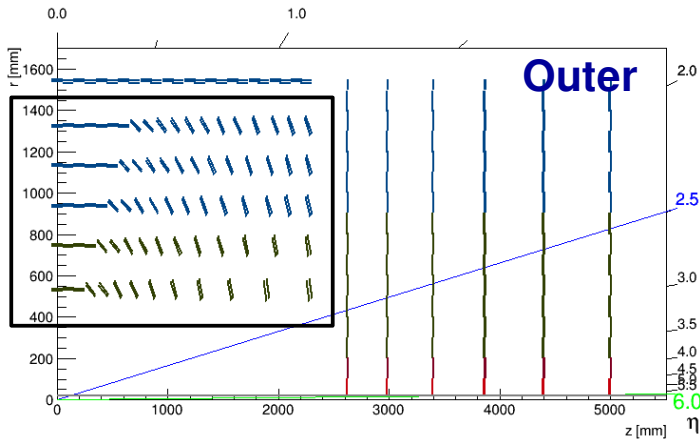
Propagated $\sigma_{R-\Phi}$ on 4th BRL layer



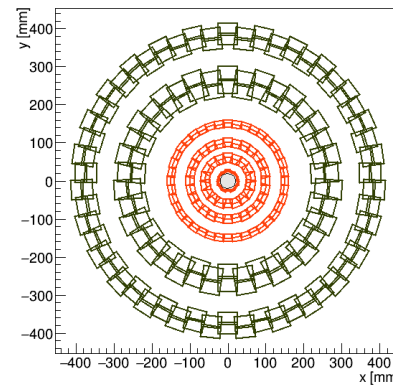
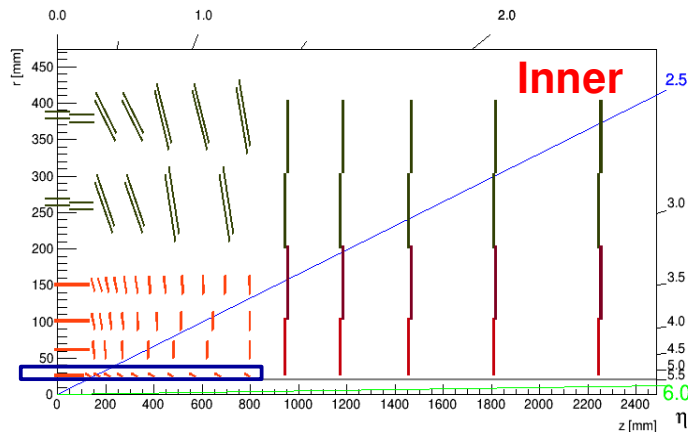
Propagated σ_z on 4th BRL layer



Tilted Geometry: Design Proposal v4.01



- Tilted layout of **outer tracker** driven by requirement to achieve **~0.2 bkg. contam. level** (BCL) in PR:
 - uppermost layer designed non-tilted to keep the highest possible lever-arm
 - modules positioned to hermetically cover full luminous region $\pm 75\text{mm}$
 - ECs strips res. in Z needed to be set to $\sim 500\mu\text{m}$ ($\sim 1\text{mm}$ OK)

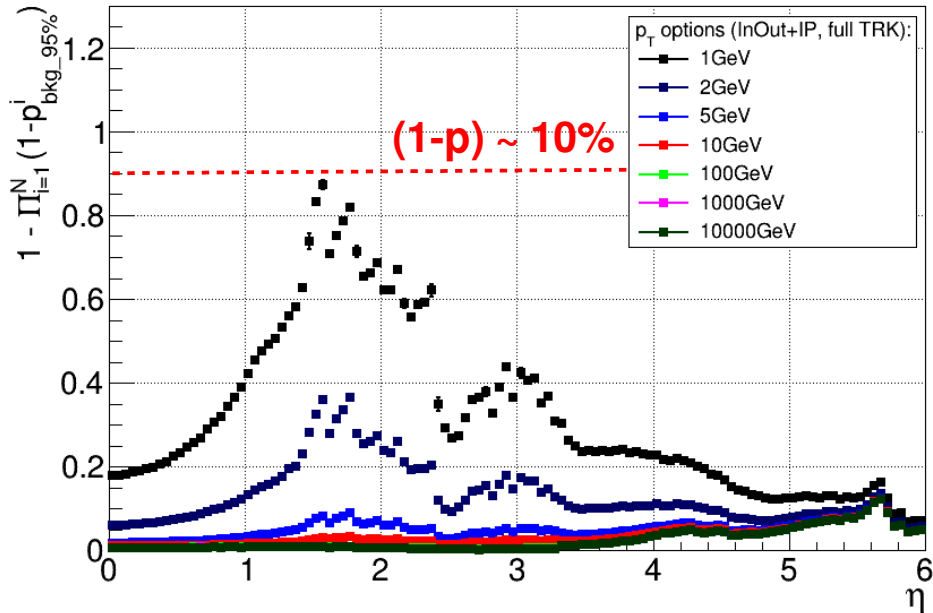


- Tilted layout of **inner tracker** driven by ~ 0.2 BCL in PR & **highest achievable z0 res.** (to deal with primary vertexing @PU ~ 1000):
 - tilt angle of 1st layer: $\theta_{\text{tilt}} \simeq 10^\circ$ optimized to achieve a compromise between low MB & higher radial position

Tilted Layout & Pattern Recognition

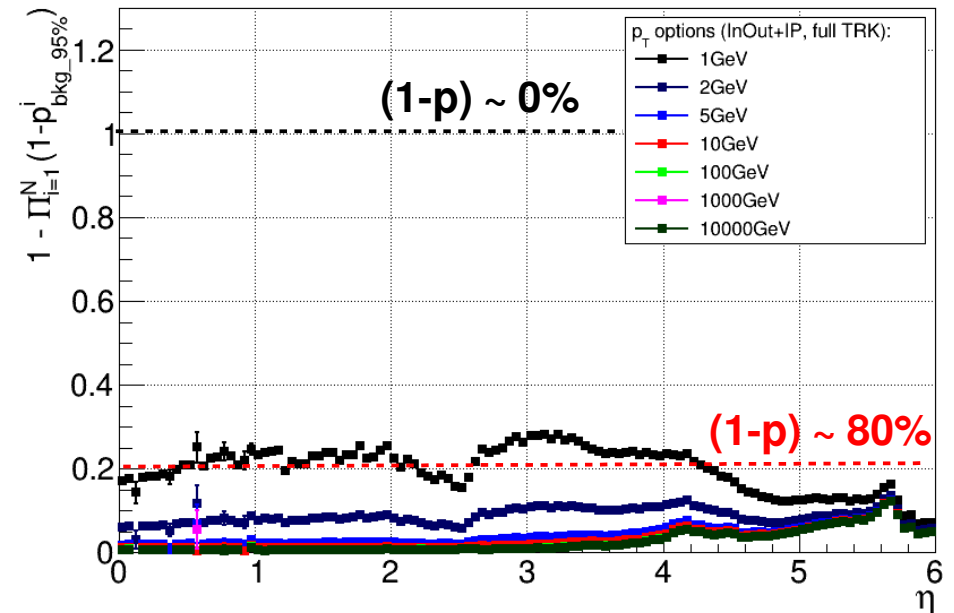
Non-tilted layout v3.03: in→out approach

In-Out: Bkg contam. prob. accumulated across N layers @95% CL



Tilted layout v4.01: in→out approach

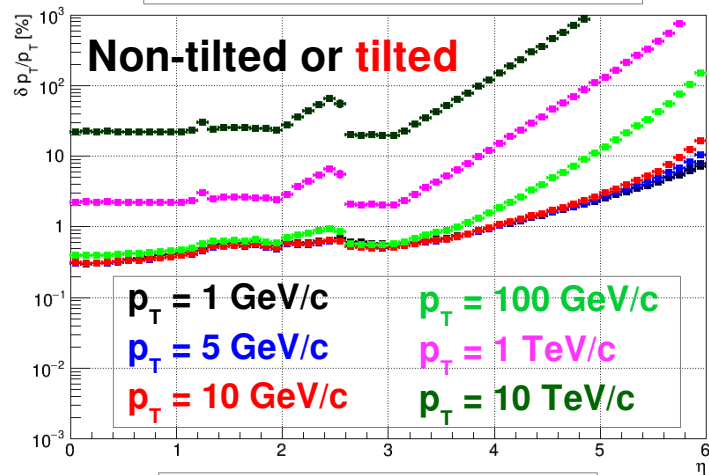
In-Out: Bkg contam. prob. accumulated across N layers @95% CL



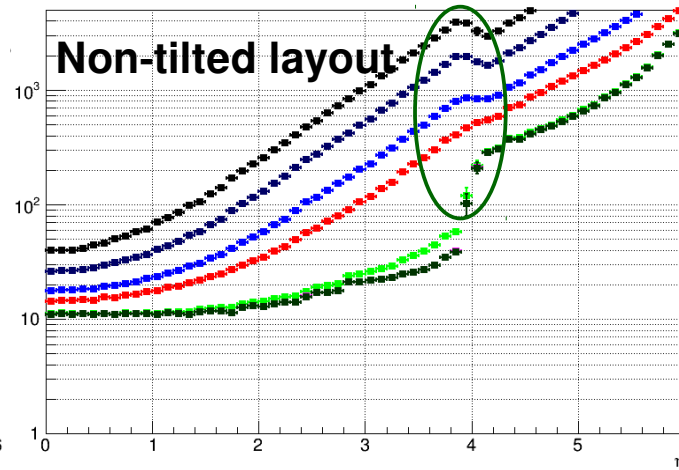
- **With tilted layout** the bkg. contam. level @~20% **achievable in PU~1000** for $p_T=1\text{ GeV}/c$ (limit value driven by HL-LHC scenario with PU~140 & CMS Phase 2 upgrade tracker layout)
- **Limits: Mat. budget assumed per module** → NOT fully realistic tilted design → need to consider services & support structure (engineering input necessary)!

Expected Tracking Performance

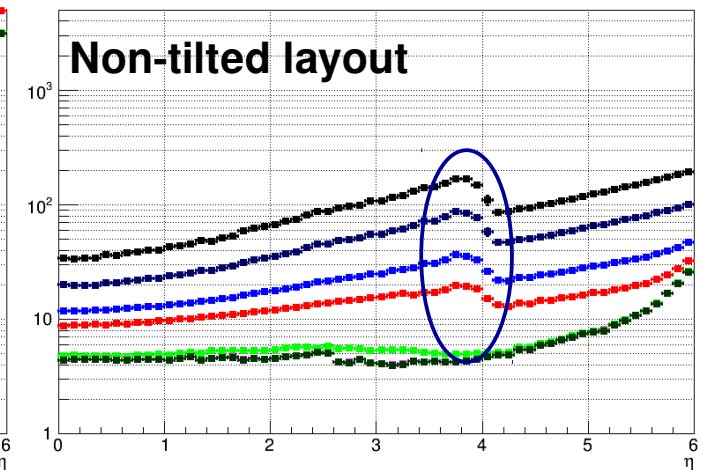
$\delta p_t/p_t$ [%] versus η



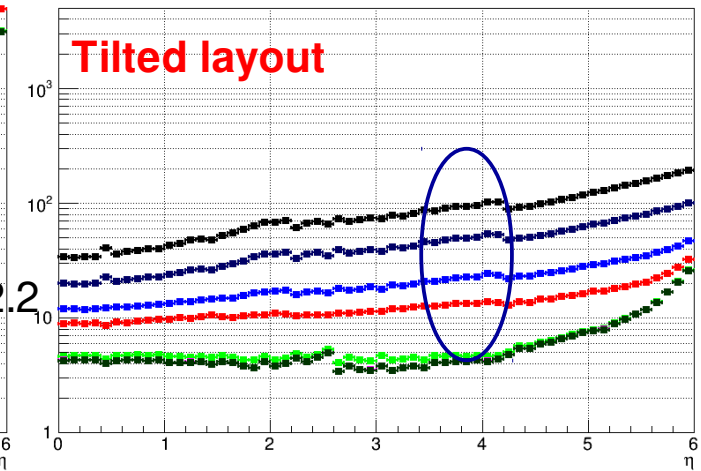
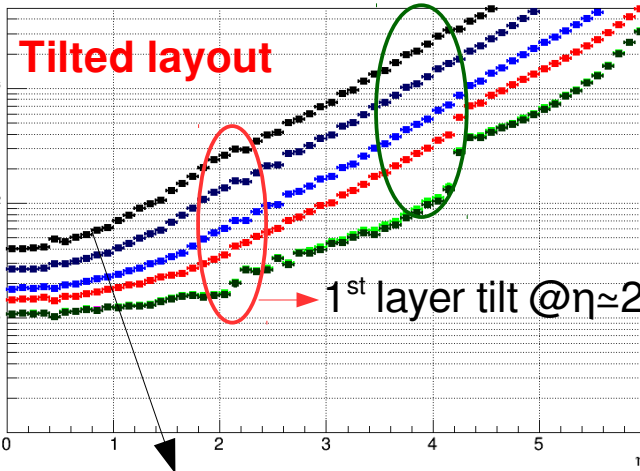
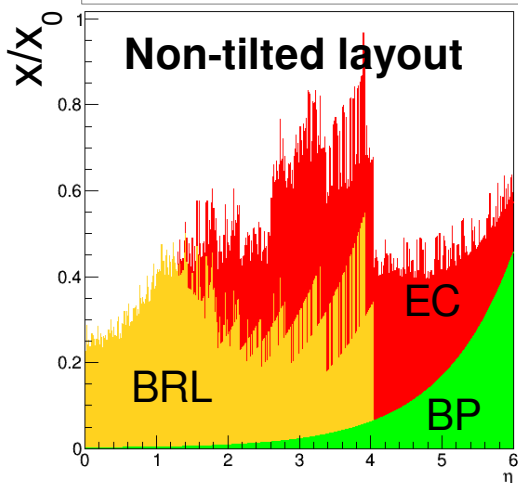
δz_0 [μm] versus η



δd_0 [μm] versus η



Material budget



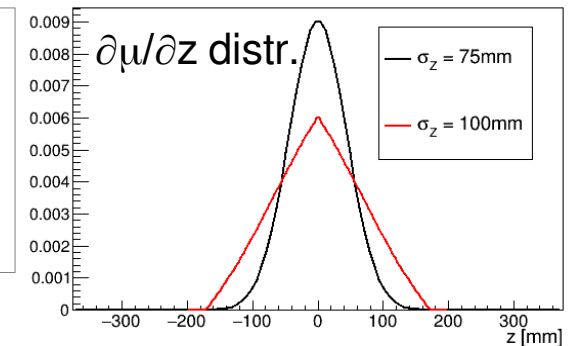
For tilted layout, the shape of 1GeV/c curve dominated by beam-pipe material!

Vertexing @ PU=1000 & Timing Information

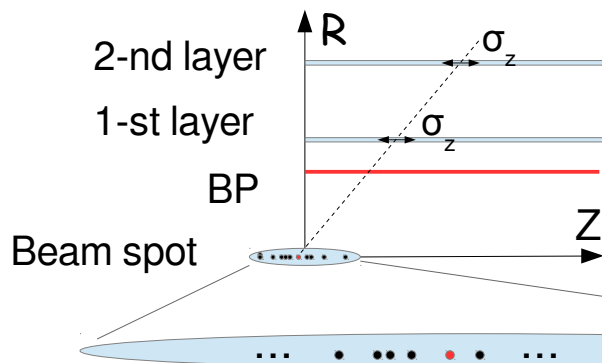
- How the pile-up (PU)~1000 degrades primary vertexing? Does the timing info help?
 - Dependent on scenario for luminous region (Gauss, “rectangular”,...) → simulate **1000 PU** vertices according to Gaussian (HL-LHC) Line & Time PU densities (c.f.: [PhysRevSTAB.17.111001](#))

- **Gauss. bunch:** $\frac{1}{\sqrt{2\pi}\sigma_z} e^{-\frac{1}{2}\left(\frac{z}{\sigma_z}\right)^2}$
 - ▶ **Line PU:** $\frac{\sqrt{1+\phi^2}}{\sqrt{\pi}\sigma_z} e^{-(1+\phi^2)\left(\frac{z}{\sigma_z}\right)^2}$
 - ▶ **Time PU:** $\frac{\sqrt{1+\psi^2}}{\sqrt{\pi}\sigma_z} e^{-(1+\psi^2)\left(\frac{ct}{\sigma_z}\right)^2}$

Line PU distr.: gaussian versus rectangular shaped bunches



- Study what fraction of tracks may be unambiguously assigned to the primary vertex @ 95% CL? Use 2D info (PV assumed to be “precisely” found from e.g. high p_T tracks)



δz_0 & δt_0 play the crucial role!

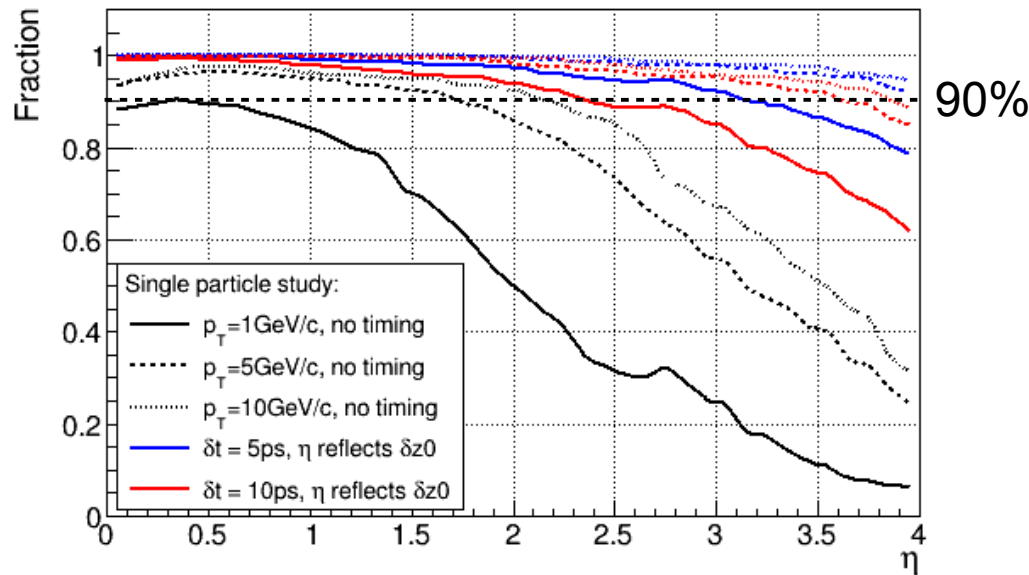
Piwinsky angle $\Phi \sim 0.67$
Time Piw. angle $\Psi \sim 0.40$

Vertexing @ PU=1000 & Timing Information

→ Compare FCC-hh scenario to HL-LHC conditions (PU~140), using e.g. CMS Ph2 upgrade layout

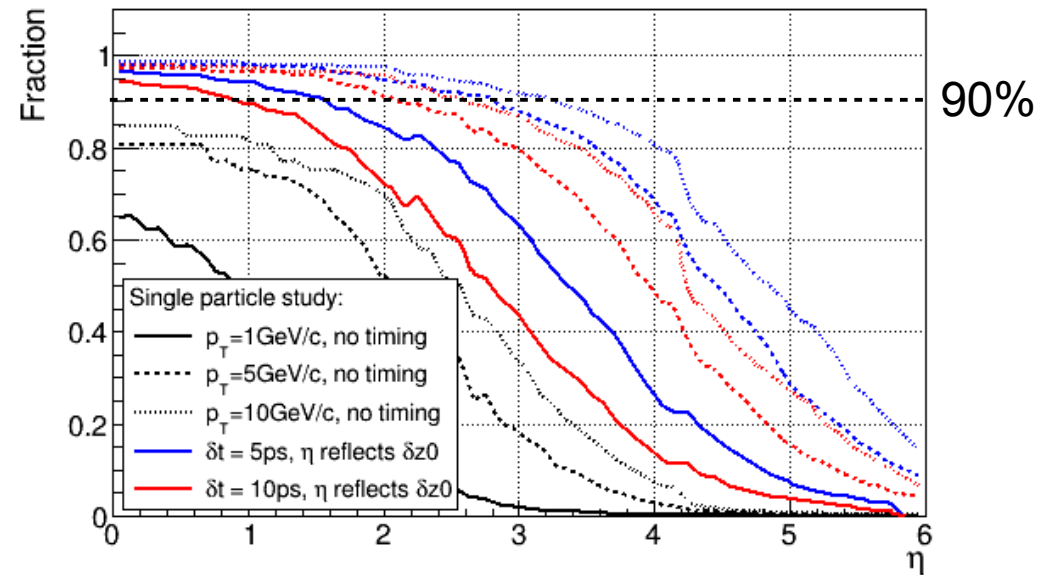
HL-LHC scenario @ PU=140 CMS Ph2 Upgr. tracker

Fraction of tracks being unambiguously assigned to PV @95% CL: $\langle \mu_{\text{tot}} \rangle = 140$



FCC-hh scenario @ PU=1000 Tilted layout

Fraction of tracks being unambiguously assigned to PV @95% CL: $\langle \mu_{\text{tot}} \rangle = 1000$

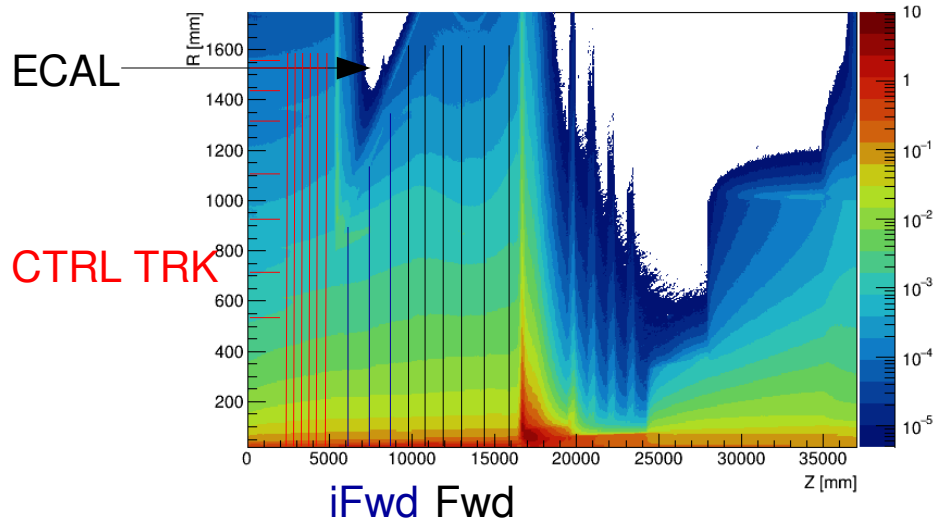


→ With current FCC-hh scheme **the primary vertexing @ PU~1000 seems very difficult for $\eta > 4.0$** , even **with timing res. ~5ps** (several time measurements being assumed per track)

Occupancy & Expected Data Rates @ PU=1000

- Have a look at the tracker granularity in a view of hit occupancy ($\sim <1\%$), what data rates may we expect at **PU~1000**?
 - Use Fluka simulated charged particles fluence per pp collision [cm^{-2}] scaled by 1000 PUs
 - Calculate occupancy & hit rates for 2 scenarios:
 - Non-triggered data @ $f = 40\text{MHz}$
 - Triggered data @ $f \sim 1\text{MHz}$ (given \sim by hardware limits, e.g. FPGA)

Charged particles fluence per pp collision



Long-term damage for Tracker after 30ab^{-1}

R [mm]	z[m]	Dose [MGy]	1 MeV equivalent Fluence [cm^{-2}]
25	0	320	$5.5 \cdot 10^{17}$
60	0	88	$1.25 \cdot 10^{17}$
100	0	40	$6 \cdot 10^{16}$
150	0	23	$3.3 \cdot 10^{16}$
270	0	8.8	$1.51 \cdot 10^{16}$
900	0	0.65	$3.2 \cdot 10^{15}$
25	5	410	$3.7 \cdot 10^{17}$
50	16	250	$2 \cdot 10^{17}$

By M.I.Besana

Inner: Occupancy & Expected Data Rates

Layer no :	1	2	3	4	5	6	Total [TB/s]
Radius [mm] :	25.0	60.0	100.0	150.0	270.0	400.0	
Module max occupancy (max[sen1,sen2])[%] :	0.45	0.11	0.05	0.02	0.08	0.04	
#Hit-channels per module per BX :	2694	741	333	166	314	150	
Module avg occupancy (max[sen1,sen2])[%] :	0.38	0.09	0.04	0.02	0.08	0.04	
Module bandwidth/(addr+clsWidth=2b[b] :	22	22	22	22	21	21	
Mod. bandwidth(#chnls*(addr+clsWidth)[kb] :	57.88	15.93	7.16	3.57	6.44	3.08	
Mod. bandwidth (matrix*1b/channel) [kb] :	685.00	820.00	820.00	820.00	384.00	384.00	
Data rate per layer - 40MHz,spars [Tb/s] :	603.7	379.9	277.3	202.2	138.7	97.5	212.4
Data rate per layer - 1MHz,spars [Tb/s] :	15.1	9.5	6.9	5.1	3.5	2.4	5.3
Data rate per ladder - 40MHz,spars [Gb/s] :	44159.7	24313.2	10920.7	5449.3	4177.1	1996.5	
Data rate per ladder - 1Mhz,spars [Gb/s] :	1104.0	607.8	273.0	136.2	104.4	49.9	
Data rate per module - 40MHz,spars [Gb/s] :	2207.99	607.83	273.02	136.23	245.71	117.44	
Data rate per module - 1Mhz,spars [Gb/s] :	55.20	15.20	6.83	3.41	6.14	2.94	
Data rate per cm ² - 40Mhz,spars [Gb/s/cm ²]:	251.82	57.91	26.01	12.98	4.69	2.24	
Data rate per cm ² - 1Mhz,spars [Gb/s/cm ²]:	6.30	1.45	0.65	0.32	0.12	0.06	

→ Hit occupancy [%] (~ <1%)

→ Layer data rate (40MHz)
→ Layer data rate (1MHz, trigger)

→ Data rate per cm² (40MHz)
→ Data rate per cm² (1MHz, trigger)

Challenge: 6.3 Gb/s/cm²

Ring no :	1	2	3	4	Total [TB/s]
Average radius [mm] :	64.8	153.0	251.1	353.3	
Module max occupancy (max[sen1,sen2])[%]:	0.46	0.13	0.18	0.08	
Data rate per ringLayer-40MHz,spars [Tb/s]:	194.2	148.2	105.1	74.3	65.2
Data rate per ringLayer- 1MHz,spars [Tb/s]:	4.9	3.7	2.6	1.9	1.6
Data rate per cm ² - 40MHz,spars [Gb/s/cm ²]	64.44	15.67	6.62	3.42	
Data rate per cm ² - 1Mhz,spars [Gb/s/cm ²]:	1.61	0.39	0.17	0.09	

Challenge: 1.6 Gb/s/cm²

**Extreme data flows >>10Gb/s/module
(even triggered @ 1MHz)**

Outer & Fwd: Occupancy & Data Rates

→ Expected huge tracker data rates: 766 TB/s (untriggered), 19 TB/s (triggered @ 1MHz)

Layer no :	Outer:	1	2	3	4	5	6	Total [TB/s]										
Radius [mm] :		530.0	742.4	937.2	1132.0	1326.7	1539.5											
Module max occupancy (max[sen1, sen2])[%] :		0.02	0.01	0.75	0.43	0.27	0.21											
Data rate per layer - 40MHz, spars [Tb/s] :		226.0	134.5	63.6	43.9	31.7	28.1	66.0										
Data rate per layer - 1MHz, spars [Tb/s] :		5.6	3.4	1.6	1.1	0.8	0.7	1.6										
Data rate per cm ² - 40MHz, spars [Gb/s/cm ²]:		1.38	0.61	0.23	0.13	0.08	0.06											
Data rate per cm ² - 1MHz, spars [Gb/s/cm ²]:		0.03	0.02	0.01	0.00	0.00	0.00											
Ring no :		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	Total [TB/s]
Average radius [mm] :		64.6	151.5	251.0	352.0	451.6	553.6	651.1	753.6	850.8	953.5	1049.7	1152.6	1247.6	1350.8	1444.7	1522.8	
Module max occupancy (max[sen1, sen2])[%]:		0.58	0.15	0.21	0.10	0.06	0.04	0.02	0.02	0.01	0.23	0.20	0.13	0.12	0.08	0.08	0.05	
Data rate per ringLayer-40MHz, spars [Tb/s]:		263.8	213.3	153.4	109.8	93.2	63.1	63.8	49.9	42.5	28.5	21.9	19.2	15.7	13.8	11.4	4.6	146.0
Data rate per ringLayer- 1MHz, spars [Tb/s]:		6.6	5.3	3.8	2.7	2.3	1.6	1.6	1.2	1.1	0.7	0.5	0.5	0.4	0.3	0.3	0.1	3.6
Data rate per cm ² - 40MHz, spars [Gb/s/cm ²]:		71.30	18.72	7.98	4.18	2.65	1.54	1.18	0.78	0.62	0.36	0.26	0.21	0.15	0.13	0.10	0.08	
Data rate per cm ² - 1MHz, spars [Gb/s/cm ²]:		1.78	0.47	0.20	0.10	0.07	0.04	0.03	0.02	0.02	0.01	0.01	0.01	0.00	0.00	0.00	0.00	
Ring no :	iFWD:	1	2	3	4	5	6	7	8	9	10	11	12	13	Total [TB/s]			
Average radius [mm] :		72.8	167.5	266.5	366.3	464.9	564.8	664.6	766.8	866.7	969.0	1068.4	1170.9	1269.8				
Module max occupancy (max[sen1, sen2])[%]:		0.99	0.13	0.20	0.11	0.07	0.04	0.03	0.02	0.02	0.48	0.24	0.12	0.07				
Data rate per ringLayer-40MHz, spars [Tb/s]:		165.8	114.5	81.6	64.9	50.6	39.3	42.3	30.0	43.3	16.8	7.8	2.8	1.9	82.7			
Data rate per ringLayer- 1MHz, spars [Tb/s]:		4.1	2.9	2.0	1.6	1.3	1.0	1.1	0.8	1.1	0.4	0.2	0.1	0.0	2.1			
Data rate per cm ² - 40MHz, spars [Gb/s/cm ²]:		65.73	18.17	8.18	4.75	2.92	1.87	1.44	0.94	1.18	0.64	0.27	0.18	0.11				
Data rate per cm ² - 1MHz, spars [Gb/s/cm ²]:		1.64	0.45	0.20	0.12	0.07	0.05	0.04	0.02	0.03	0.02	0.01	0.00	0.00				
Ring no :	FWD:	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	Total [TB/s]	
Average radius [mm] :		97.1	190.1	288.9	388.3	487.1	588.6	689.4	791.4	891.9	994.1	1094.4	1196.6	1296.6	1398.8	1498.5		
Module max occupancy (max[sen1, sen2])[%]:		0.28	0.11	0.20	0.12	0.08	0.05	0.04	0.03	0.02	0.46	0.34	0.25	0.16	0.11	0.09		
Data rate per ringLayer-40MHz, spars [Tb/s]:		318.3	244.3	180.2	149.6	121.5	116.4	101.0	77.1	76.7	54.9	35.5	25.6	19.5	15.2	11.0	193.4	
Data rate per ringLayer- 1MHz, spars [Tb/s]:		8.0	6.1	4.5	3.7	3.0	2.9	2.5	1.9	1.9	1.4	0.9	0.6	0.5	0.4	0.3	4.8	
Data rate per cm ² - 40MHz, spars [Gb/s/cm ²]:		48.67	17.20	8.37	5.17	3.35	2.37	1.71	1.21	1.04	0.66	0.40	0.26	0.19	0.13	0.09		
Data rate per cm ² - 1MHz, spars [Gb/s/cm ²]:		1.22	0.43	0.21	0.13	0.08	0.06	0.04	0.03	0.03	0.02	0.01	0.01	0.00	0.00	0.00		

Summary & Conclusions

- **The key tracker parameters have been studied & optimized:**
 - **Current layout:** $\sim 430\text{m}^2$ (391m^2 in tilted layout) of Si with #channels: 5461M (pixels), 9964M (macro-pixels), 489M (strips)
 - The **granularity in $R-\Phi$** driven mostly by dp_T/p_T @ $\text{p}_T=10\text{TeV}/c$ → achieved $\text{dp}_T/\text{p}_T \sim 20\%$
 - **Non-uniformities of mag. field have a negligible effect on dp_T/p_T res.** → dp_T/p_T degrades in max. by 45% at $\eta > 2.5$ (**solenoid**), dipole in FWD region still remains an option → c.f. PV @ PU=1000
 - The **granularity in Z driven by vertexing & pattern recognition capabilities @ PU=1000:**
 - **Tracker in tilted layout essential** (even for vertex detector) to achieve similar pattern recognition performance as with PU \sim 140 & HL-LHC conditions
 - **Primary vertexing & correct PV assignment @ PU=1000 seems feasible up-to $\eta \sim 4$** , but only with extra timing information (2D vertex fitting)
 - **Current view on PV from $\eta \sim 4$ to 6 seems very difficult** (even with timing information) → need for an intensive discussion on interplay between detector performance & FCC-hh colliding schemes
 - Expected data rates (**766 TB/s untriggered, 19 TB/s triggered @ 1MHz**) implicate need for new read-out technologies (follow J.Brooke's talk on trigger design)
 - Expected **1MeV neq fluence $\sim 5 \times 10^{17} \text{cm}^{-2}$ @ R=25mm** (see M.I.Besana's talk) truly represents **a new challenge** for the tracker technologies and dedicated R&D