



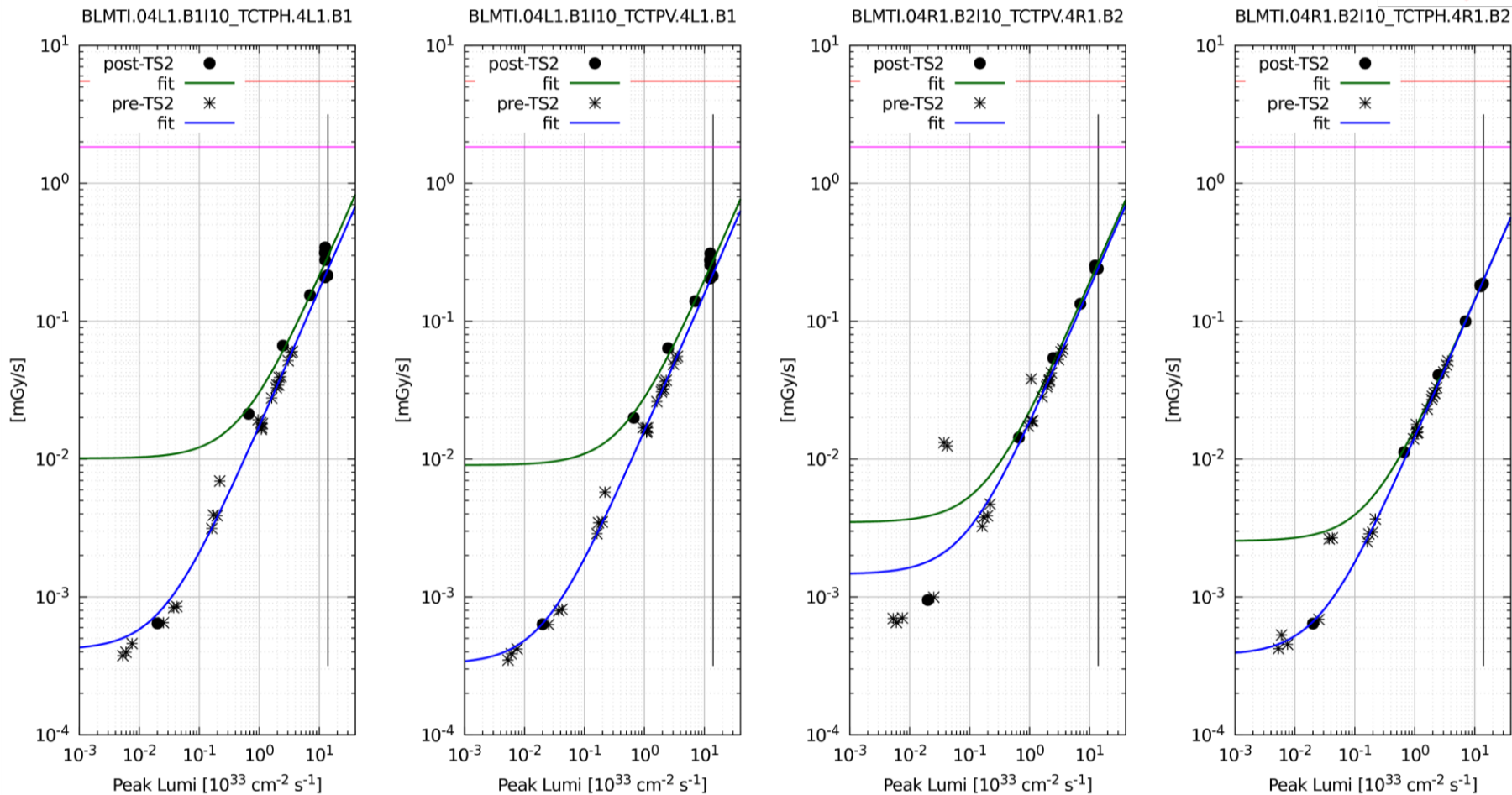
# Effect of IP1/5 Crossing Angle Change on BLM Response at TCLs and TCTs

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# Change of Crossing Angle in IP1/5

- BLM signals at TCTs / TCLs affected by debris:
  - Once in collisions;
  - Especially on longest RSs;
- A change in crossing conditions implies a re-distribution of debris particles hitting accelerator components; in particular, if crossing angle is reduced, naively one would expect:
  - Less debris intercepted by the IT;
  - More debris intercepted in MS/DS;
- Let's anyway check measurements!
- Results presented here are based on RS12, the one most affected by debris;
- It will be shown that there is no need to change BLM thresholds;

# Example: IR1 TCTs



Slightly higher calibration factor wrt pre-TS2...

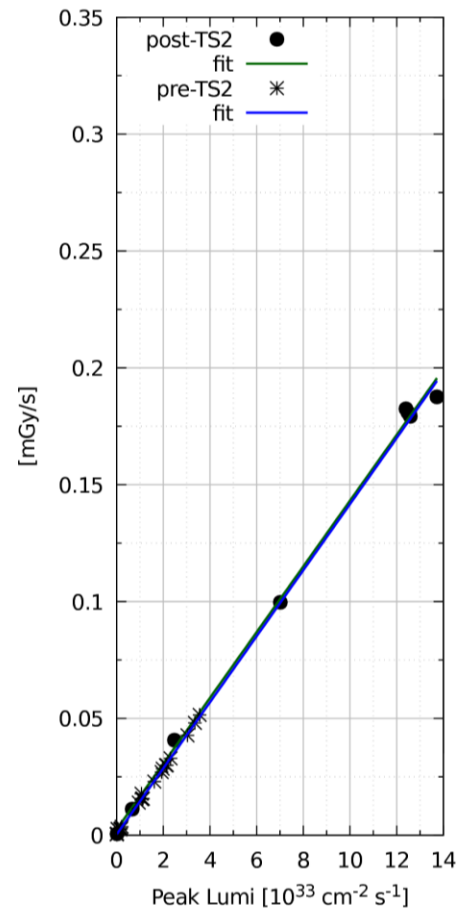
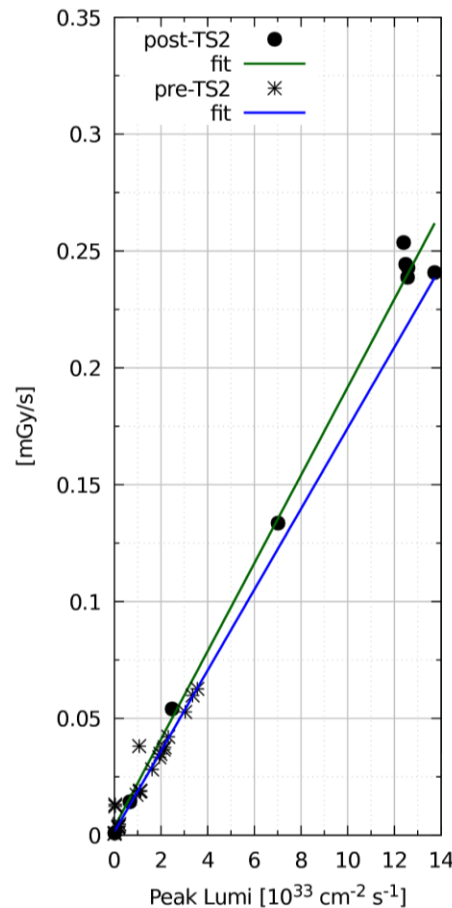
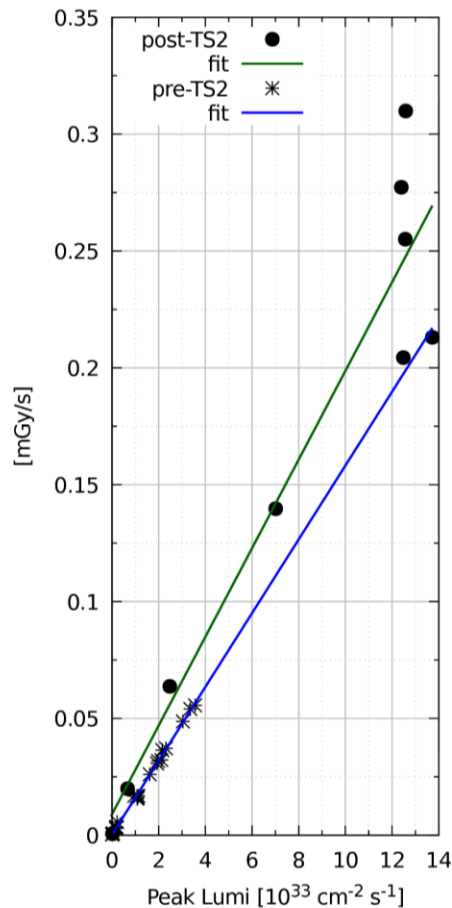
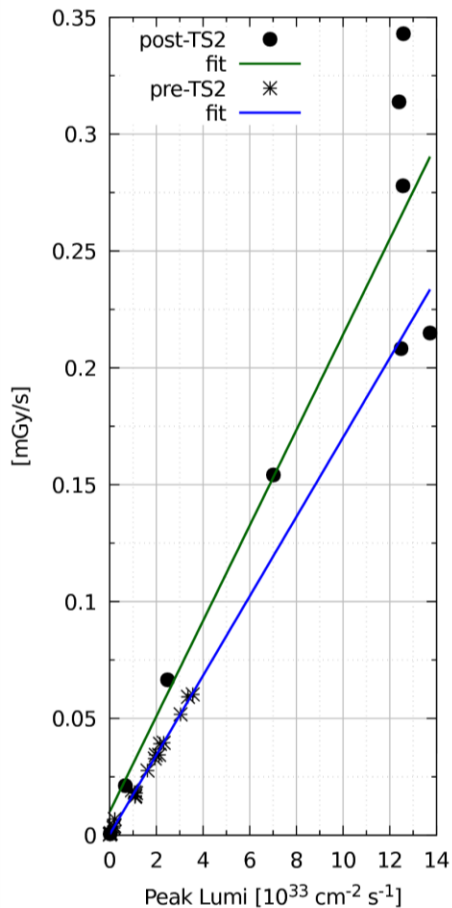
# Example: IR1 TCTs (II)

BLMTI.04L1.B1I10\_TCTPH.4L1.B1

BLMTI.04L1.B1I10\_TCTPV.4L1.B1

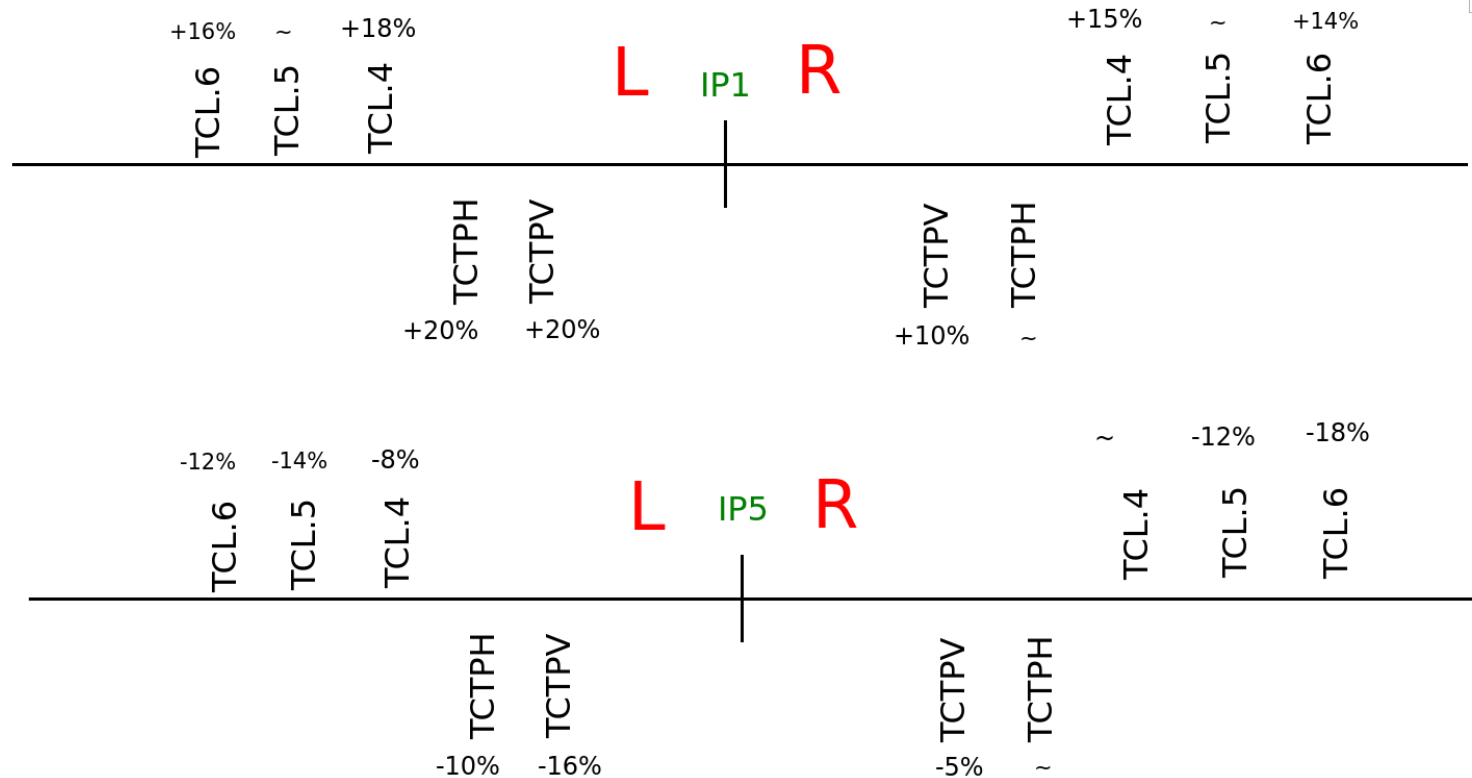
BLMTI.04R1.B2I10\_TCTPV.4R1.B2

BLMTI.04R1.B2I10\_TCTPH.4R1.B2



Slightly higher calibration factor wrt pre-TS2...

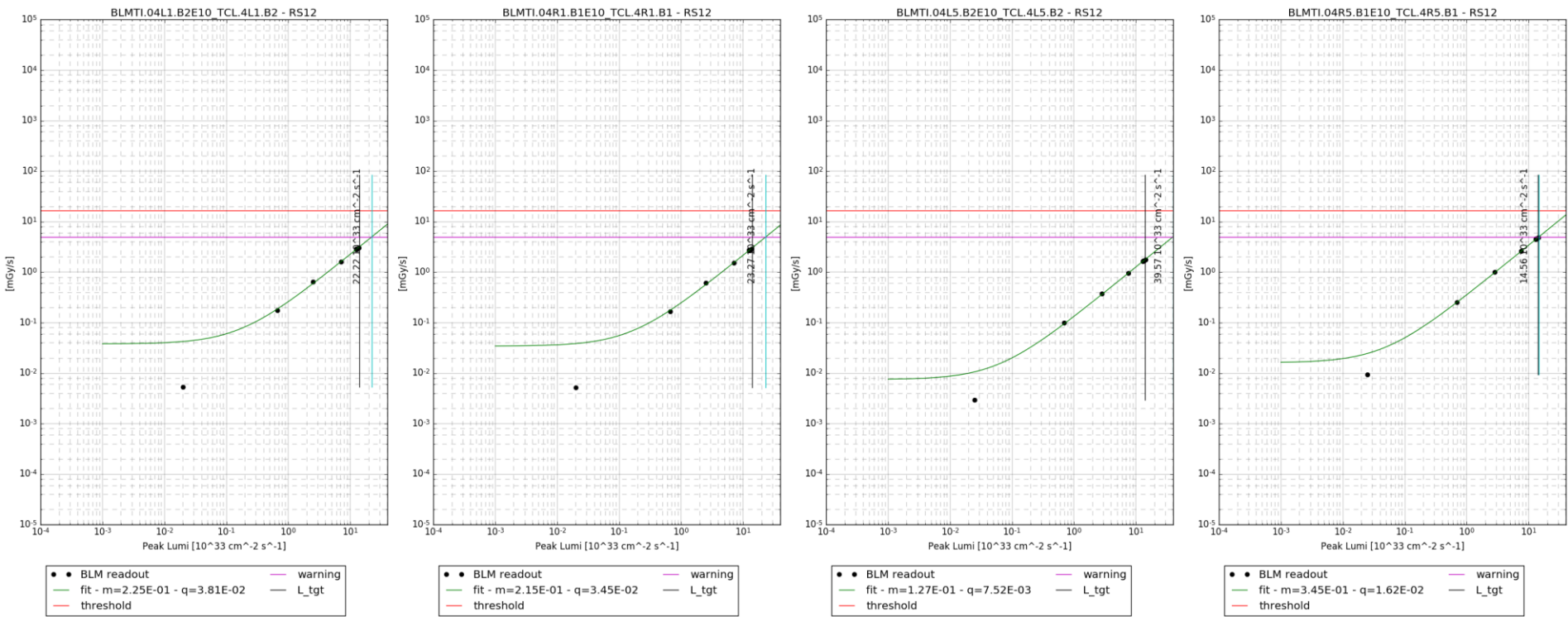
# Summary: IR1&IR5



Details are not always intuitive:

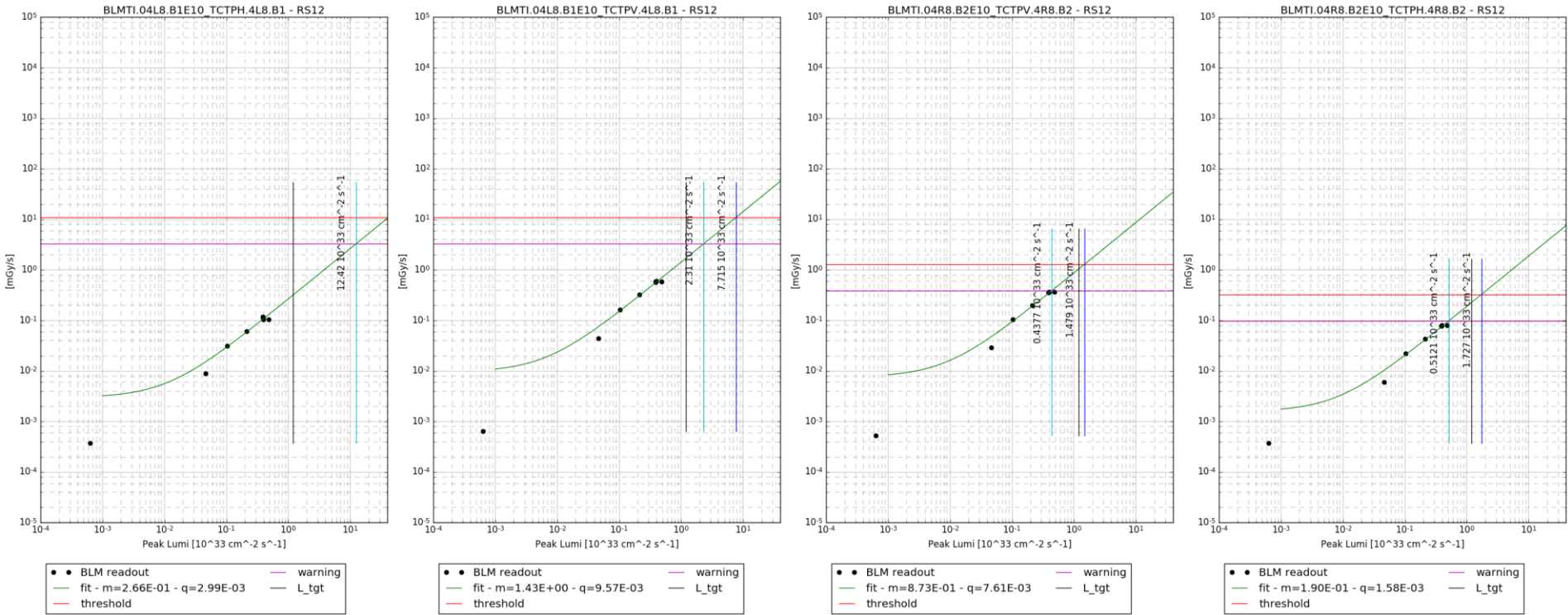
- Real machine conditions have large impact on signals from debris;
- No sensitivity analysis on BLM signals made with simulations which goes that far from the IP;
- Nevertheless: changes not worrying;

# Example: TCL4s



BLM signals at TCL.4R5 just below warning level!

# Example: IR8 TCTs



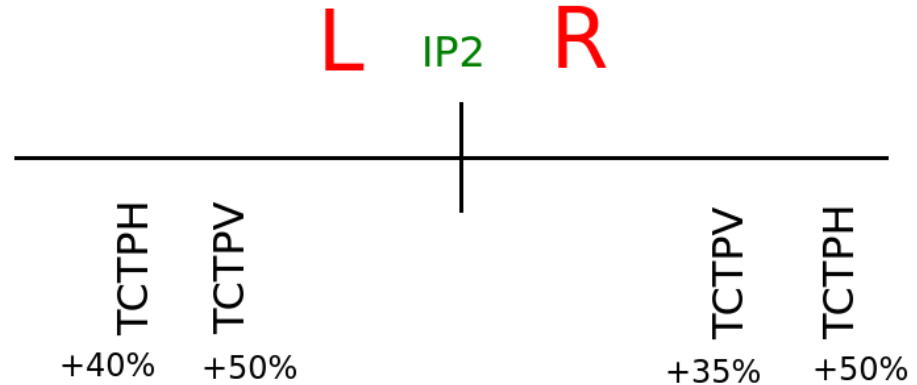
BLM signals at TCTPV.4R8 just below warning level!



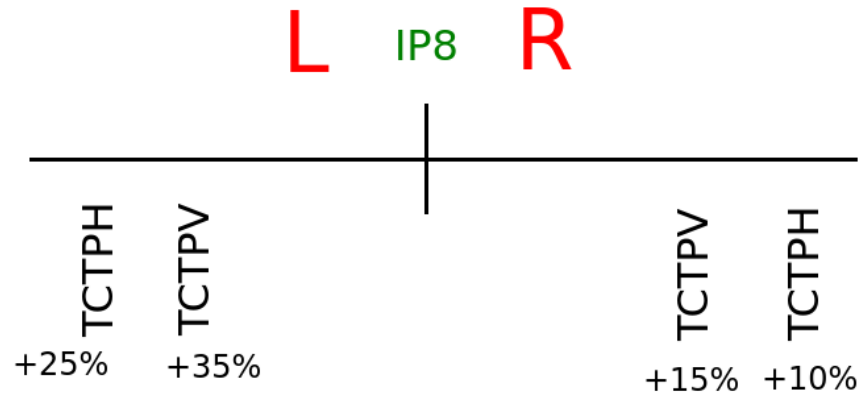
# Reserve Slides

# Summary: IR2&IR8

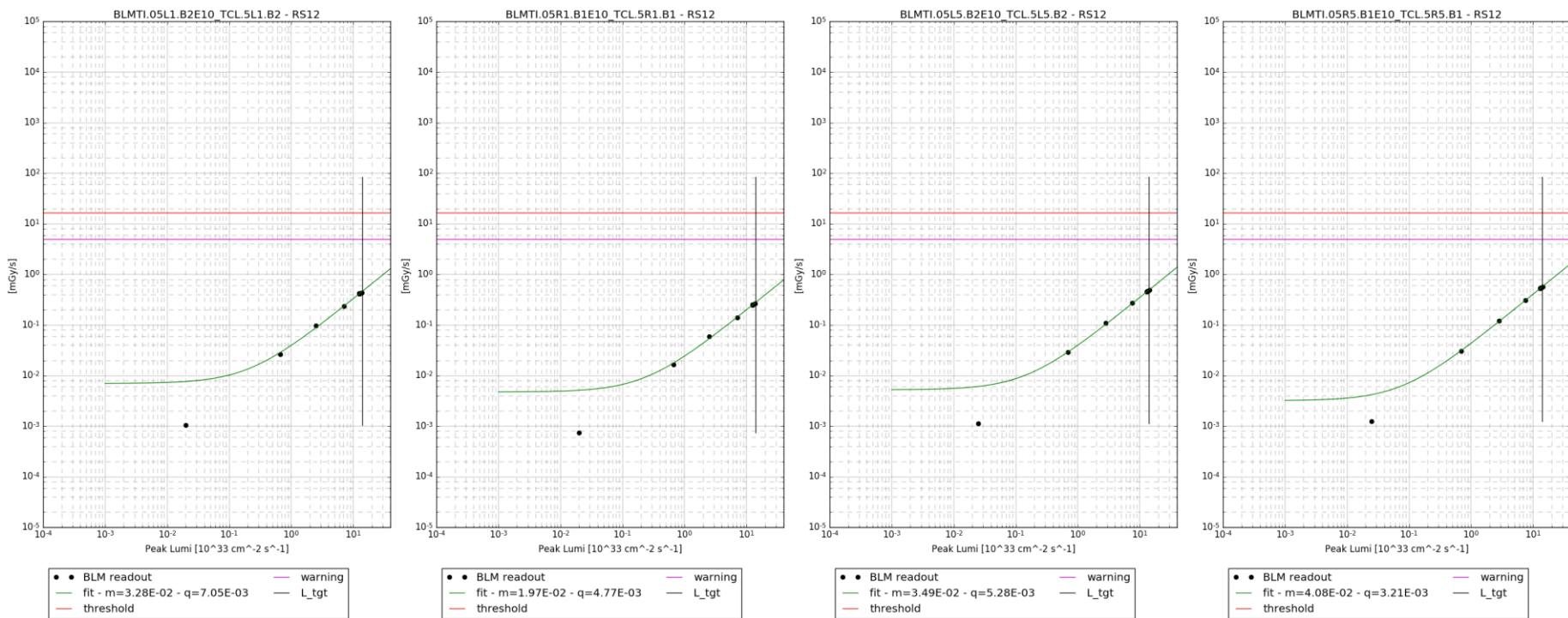
Lumi in IR2 quite low → noisy BLM signals, with large fluctuations...  
Nevertheless, clear increase of calibration factor!



Clear increase of calibration factor → in line with change of polarity...



# Example: TCL5s



# Example: TCL6s (XRPs IN)

