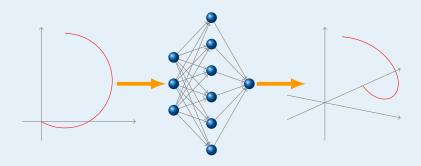
# Track vertex reconstruction with neural networks at the first level trigger of Belle II

Connecting the Dots / Intelligent Trackers 2017

Mar 6 - 9, 2017







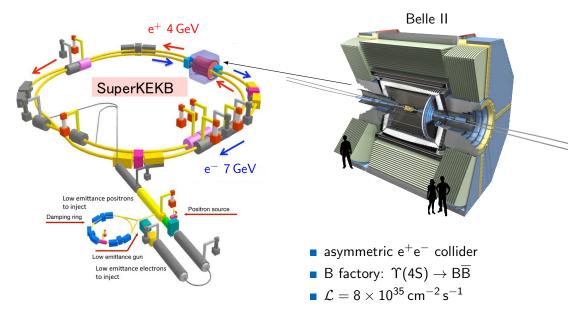












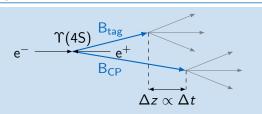


## Task for the first level trigger





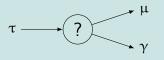




- time dependent CP violation in BB
- typically  $\approx 3 9$  tracks

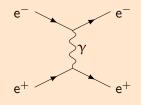
max. trigger rate 30 kHz total latency 5 μs pipelined, FPGA

low track multiplicity:  $e^+e^- \to \tau^+\tau^-$ 



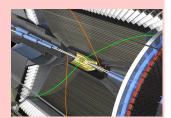
- lepton flavor violation
- genuine 2 track trigger

#### Bhabha scattering



- for calibration
- needs to be prescaled
- Bhabha veto

- z-vertex  $\neq 0$
- suppression requires3D tracking

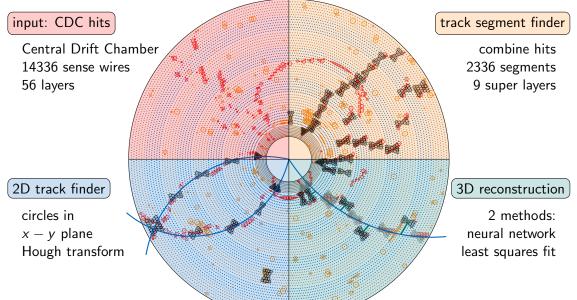
















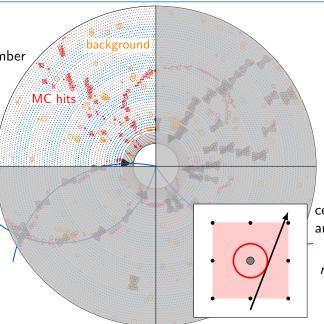






Central Drift Chamber 14336 sense wires

56 layers



cells of sense wires and field wires

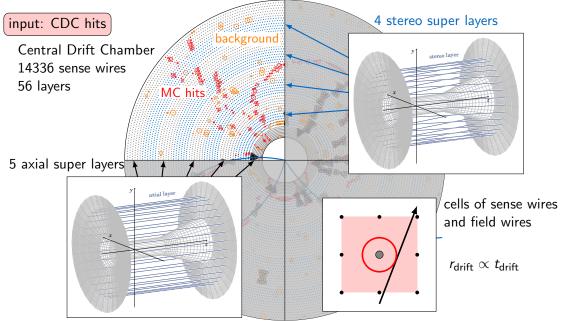
 $r_{
m drift} \propto t_{
m drift}$ 











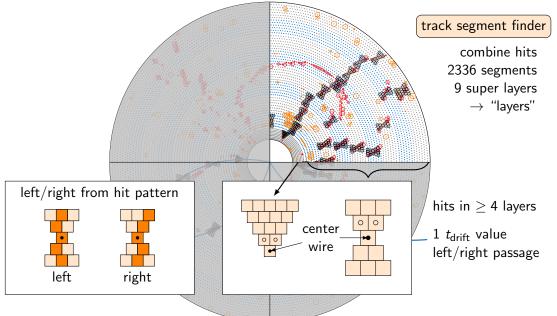


## Track trigger – track segment finder









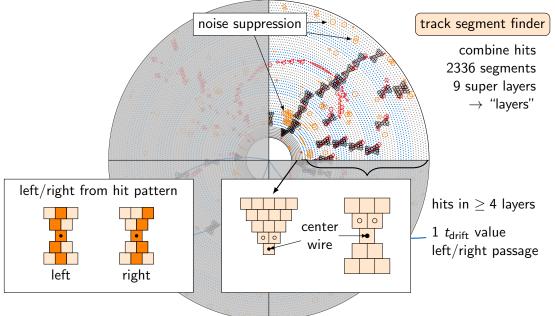


## Track trigger – track segment finder









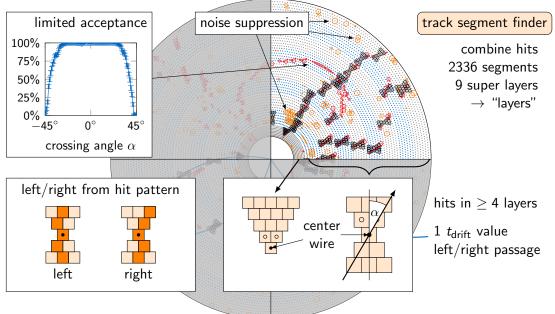


## Track trigger – track segment finder









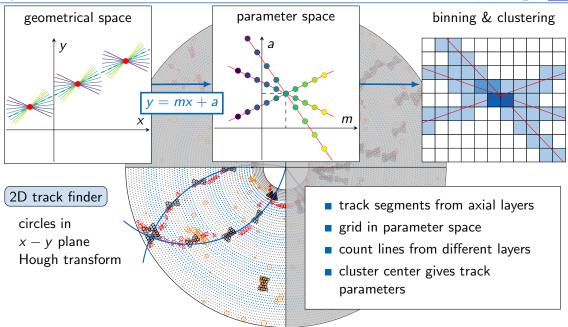


## Track trigger – 2D track finder











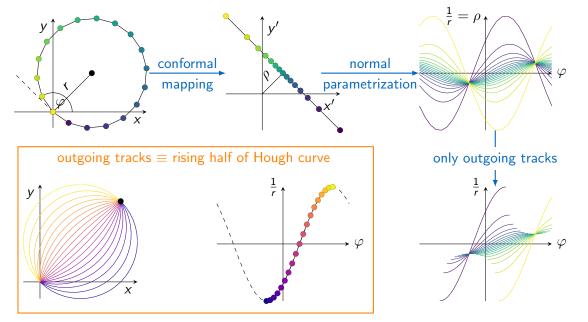
S. Neuhaus

## Hough transform for circles







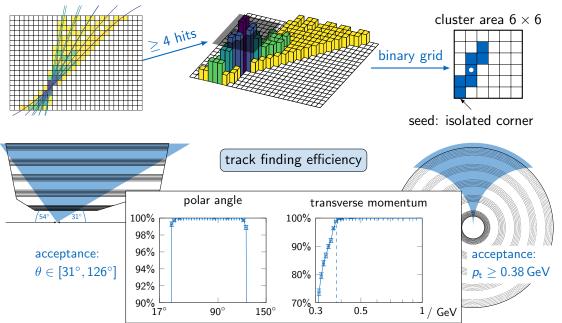












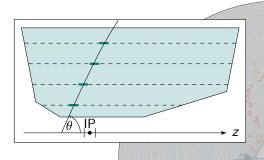


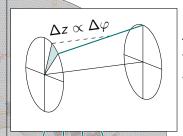
## Track trigger – 3D reconstruction











4 z-coordinates from stereo hits and 2D tracks

- precise position: drift time
- event time determined parallel to track finding
- problems with fit: approximations, background

#### 3D reconstruction

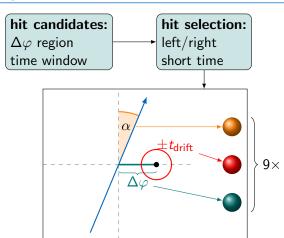
2 methods: neural network least squares fit











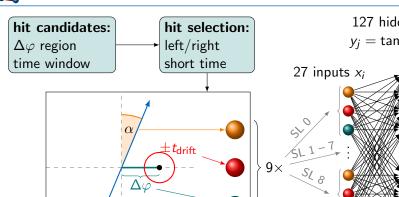
- $lue{}$  drift time separately ightarrow nonlinear corrections
- $lue{}$  crossing angle  $\alpha$ : track curvature
- axial inputs: 2D track corrections











- 127 hidden nodes  $y_i = \tanh \sum_i x_i w_{ii}$
- 2 output nodes  $z_k = \tanh \sum_j y_j w_{jk}$   $z_k = \tanh \sum_j y_j w_{jk}$  weights  $w_{ij}$ ,  $w_{jk}$  trained with backpropagation
- $lue{}$  drift time separately o nonlinear corrections
- crossing angle  $\alpha$ : track curvature
- axial inputs: 2D track corrections

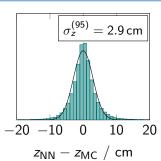
- missing axial hit: default inputs (0,0,0)
- missing stereo hit: expert network

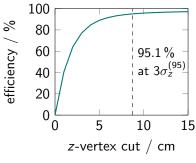


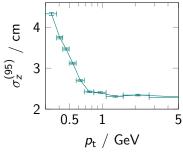






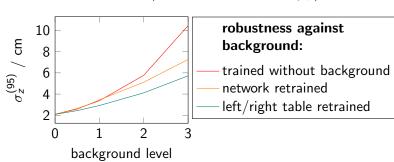






resolution depends on

- missing hits
- track curvature
- background hits

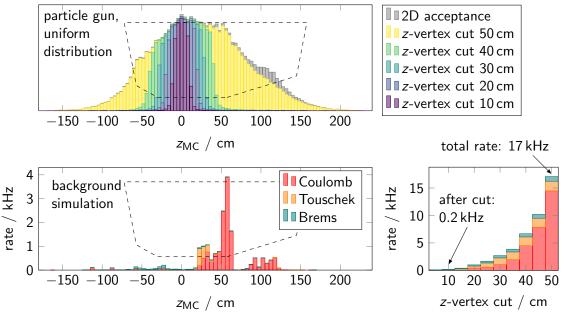












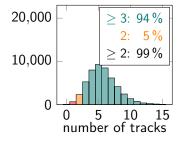




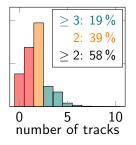




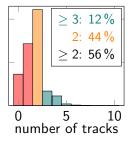
 $B\overline{B} \to generic$ 



$$\tau^+\tau^- \to \text{generic}$$



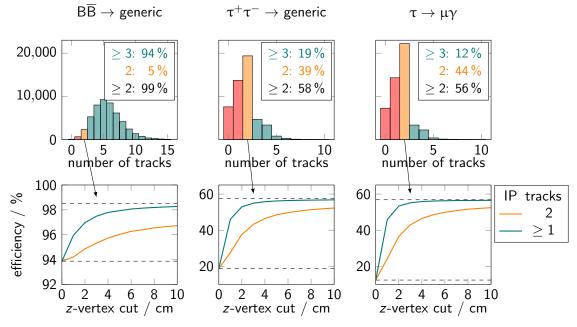
 $\tau \to \mu \gamma$ 









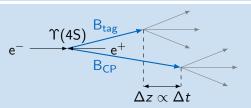






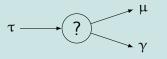






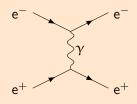
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- typically  $\approx 3 9$  tracks
- 1. track segments
- 2. 2D tracks: Hough
- 3. z-vertex: neural network

low track multiplicity:  $e^+e^- \to \tau^+\tau^-$ 



- lepton flavor violation
- genuine 2 track trigger

#### Bhabha scattering



- for calibration
- needs to be prescaled
- Bhabha veto

- z-vertex  $\neq 0$
- suppression requires3D tracking

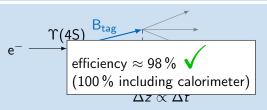






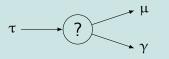






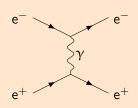
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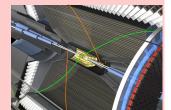
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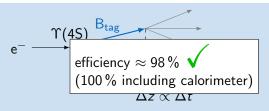










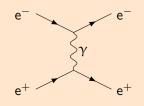


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## 

- lepton flavor violation
- genuine 2 track trigger

#### machine background



Bhabha scattering

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- needs to be prescaled
- Bhabha veto

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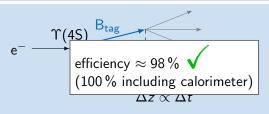




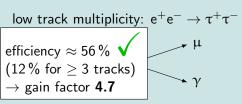






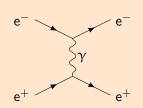


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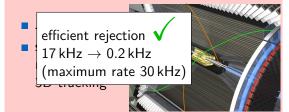
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machine background



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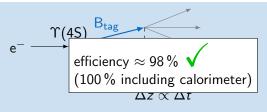








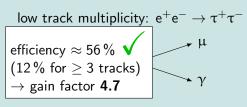




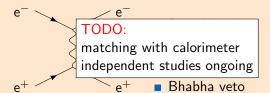
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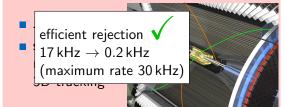
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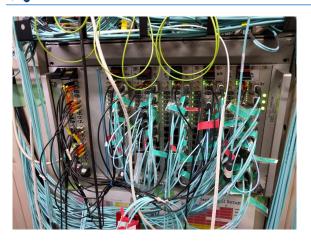


## 🧀 Hardware is waiting for first tests. . .









#### Hardware team: S. Bähr, J. Becker



- neural networks implemented on FPGA
- logic tests with simulated input
- installation planned in spring 2017
- cosmic ray tests in summer 2017

## Thank you for your attention!









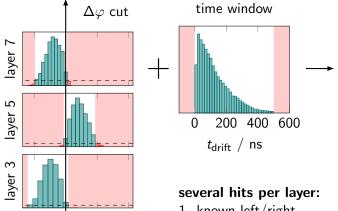
## Backup

## Hit and network selection









hit in layer $1/3/5/7$				expert
$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	#1
$\checkmark$	$\checkmark$	$\checkmark$		#2
$\checkmark$	$\checkmark$	—	$\checkmark$	#3
$\checkmark$	—	$\checkmark$	$\checkmark$	#4
_	$\checkmark$	$\checkmark$	$\checkmark$	#5

- 1. known left/right
- 2. short drift time

MC hits left/right	wrong
correct	unknown

background hits left/right

known unknown

layer 1

10°

 $-10^{\circ} - 20^{\circ}$