

CMS Alignment and Calibration Framework

Setup and First Experiences with Data

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(on behalf of the CMS Collaboration)

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Computing in Experimental High Energy Physics





- 1 Introduction
 - Challenges of Alignment and Calibration
 - Example Task: Track-based Alignment
- 2 The Workflow
 - Reduced Datasets for Alignment/Calibration
 - Steps of the Workflow
 - Storage and Distribution of Alignment/Calibration Conditions
- 3 Test of the Framework
 - Simulated Data in 2008
 - Cosmic Ray Data-Taking in 2008

Outline



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Challenges and Requirements

- Event reconstruction at the LHC will be a complex task

Challenges

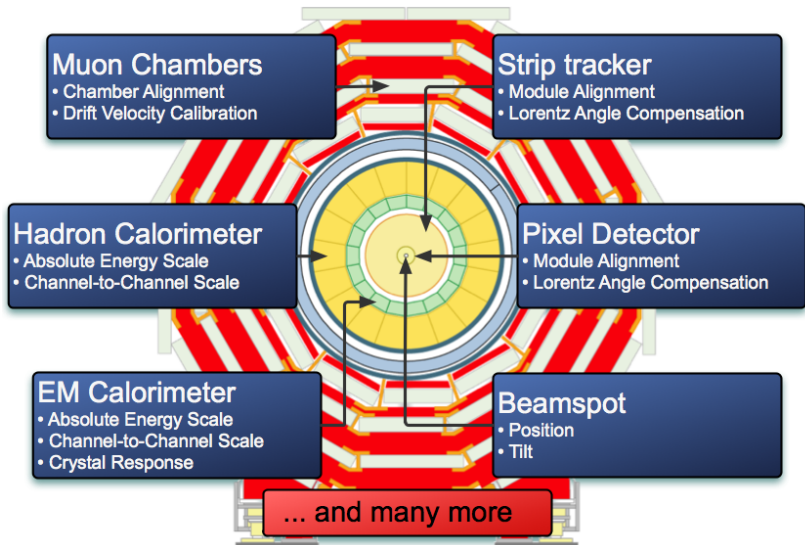
- Design performance of CMS detector requires high precision alignment and calibration
- Fast turnaround for physics studies
- High data rates at LHC \Rightarrow stress on computing infrastructure

Requirements to the Framework

- Provide fast flow of specific data needed for alignment/calibration
- Provide fast turnaround for alignment/calibration tasks
- Ability to handle many tasks in parallel
- Database infrastructure for handling of alignment/calibration conditions

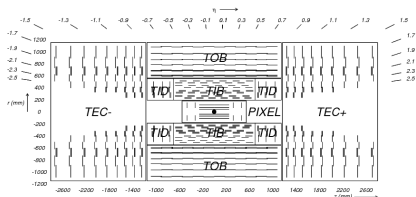
The CMS Detector

and some Example Alignment and Calibration Tasks



Example Alignment and Calibration Task

Track-based Alignment



The Challenge

- 1440 pixel + 15148 strip modules \times 6 degrees of freedom
- High measurement precision $\mathcal{O}(10 \mu\text{m})$
- Sensitive to small changes

The Solution

- Use tracks to measure the module position and orientation
 - Minimize $\chi^2 = \sum \frac{(x_{meas} - x_{reco})^2}{\sigma_{meas}^2}$ for all hits on all tracks
 - Need **many** $\mathcal{O}(10^6)$ tracks
- Large computational problem
 - Streamlined process required (e.g. I/O)

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Alignment & Calibration Skims (AlCaReco) - Selection

Many algorithms need to run (even iterate) on a large number of events (e.g. track-based alignment).

Definition of AlCaReco

- Reduced event rate and size
 - ⇒ Efficient use of computing resources (i.e. fast turnaround, minimize I/O overhead, maximize storage efficiency)
- Filter **events** (exploiting HLT and reconstructed information) and **event content**
 - ⇒ Only necessary information is stored
- HLT selection read from database
 - ⇒ Flexibility to react on changes in HLT menus

Alignment & Calibration Skims (AlCaReco) Content

- Diverse tasks and subsystems
⇒ Input to alignment and calibration tasks differs widely
- Event content according to specific alignment/calibration purpose (e.g. reconstructed data, data not available after reconstruction or non collision data)
- Multiple AlCaReco skims are foreseen, used by ≥ 1 task (e.g 9 during cosmic ray data-taking)
- Contain Data Quality Monitoring (DQM) histograms

Example: Content of Track-based Alignment AlCaRecos

- Only **tracks** and **clusters** are needed to refit tracks
- Special AlCaReco skims containing:
 - Minimum bias tracks
 - Isolated muon tracks
 - Tracks from resonances decaying into muons (Z , J/ψ , Υ)
 - Cosmic ray muon tracks
 - Beam halo muon tracks

Reduced Data Format for Transport (AlCaRaw)

Some (currently calorimetry) calibrations need very high event rates

⇒ If limited by Point5 → Tier0 bandwidth, reduce data format at Point5

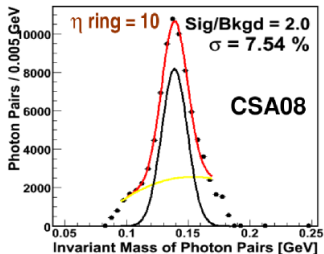
Idea

reduce RAW event size

→ higher rate Point5 to

Tier0 possible

→ partial reconstruction to
AlCaReco

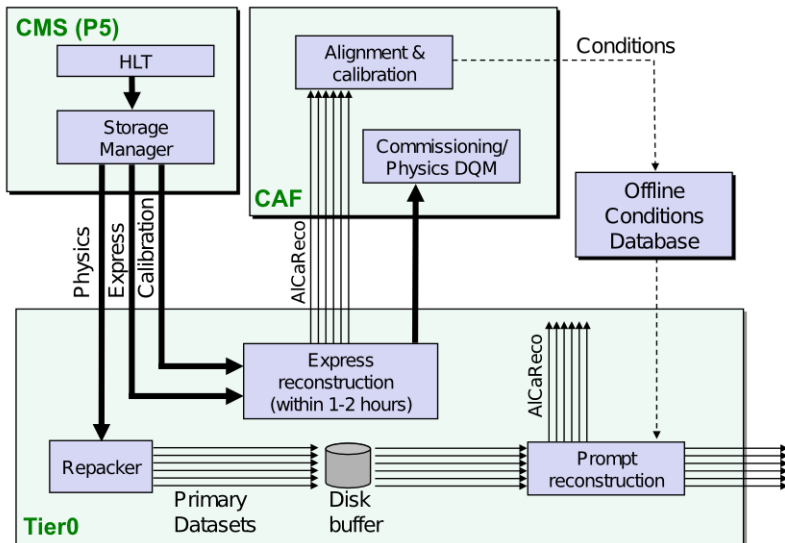


Example:

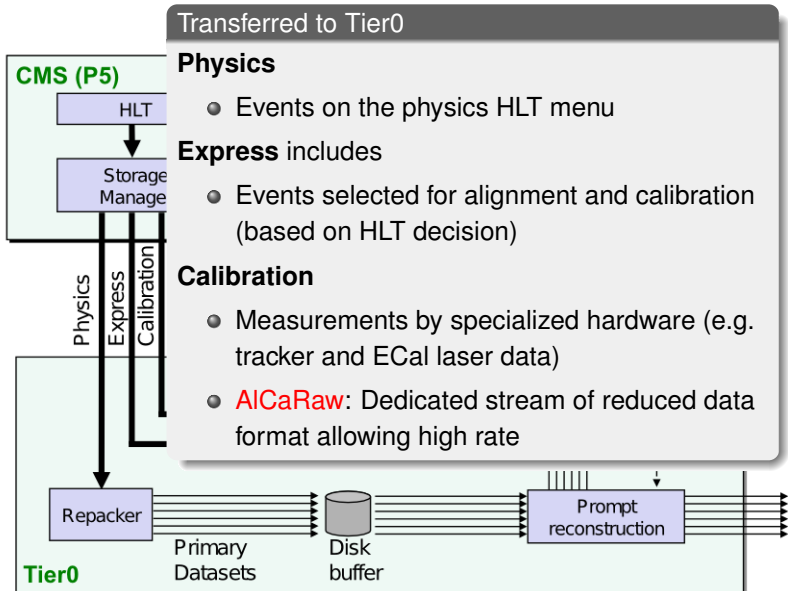
ECal channel-to-channel calibration

- Use $\pi^0 \rightarrow \gamma\gamma$ decay at expected rate of **1 kHz** (special HLT trigger)
- Constrain photon energies to π^0 mass to calibrate
- Allows precise and fast calibration
- Transfer of full data format would saturate bandwidth
- Store 3×3 crystals around photon seed only in **AlCaRaw**

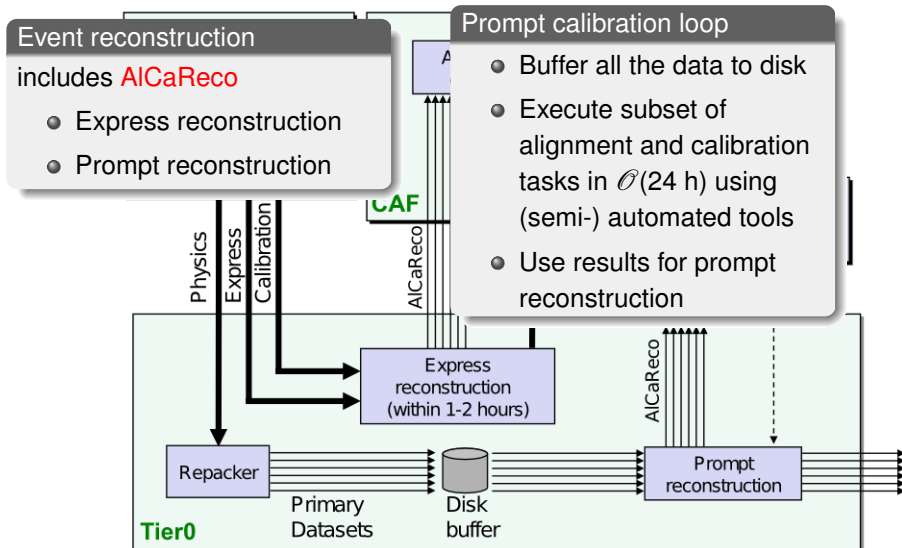
Steps of the Alignment and Calibration Workflow



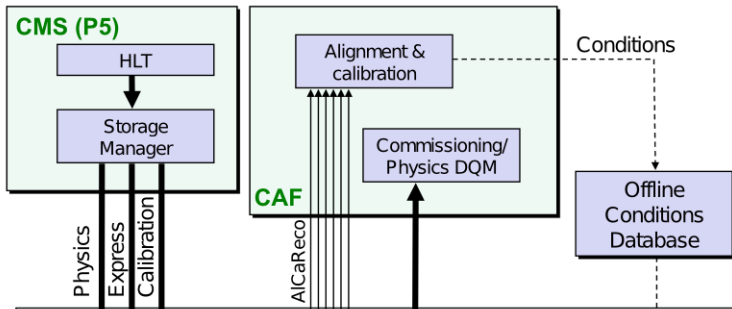
At Point 5



At the Tier0



At the CERN Analysis Facility (CAF)

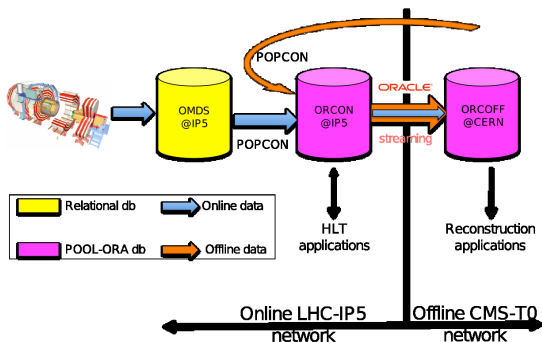


CERN Analysis Facility (CAF)

- Alignment and calibration tasks are executed on CAF
- **Batch farm** with interactive access
- Data and intermediate output stored on **disk**

⇒ Fast task execution, validation and debugging

Storage and Distribution of Alignment/Calibration Conditions



Goals

- Independence of off-site networks
- Robust access to offline conditions

accomplish different aspects using 3 databases

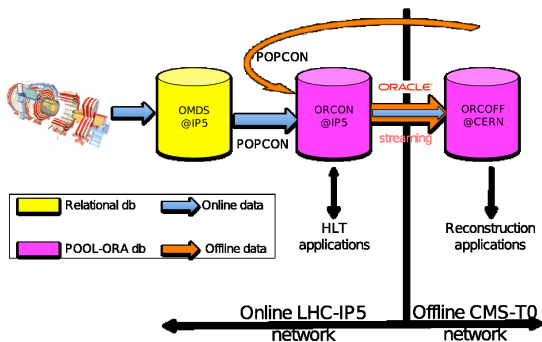
OMDS Central registry for **online conditions**

ORCON For **offline conditions** read by the **online** network

ORCOFF For **offline conditions** read by the **offline** network

POP CON **Service** to populate ORCON from various sources

Storage and Distribution of Alignment/Calibration Conditions



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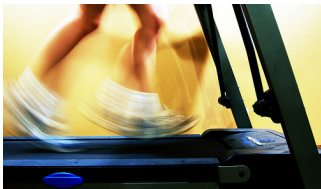
- Offline conditions are updated after sign-off
- Interval of validity (IOV) is stored with every set of conditions
- High level trigger can benefit from updated offline conditions
- Through ORCOFF and a hierarchy of proxies (Frontier) conditions are propagated other sites

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Computing, Software and Analysis Challenge in 2008 (CSA08)

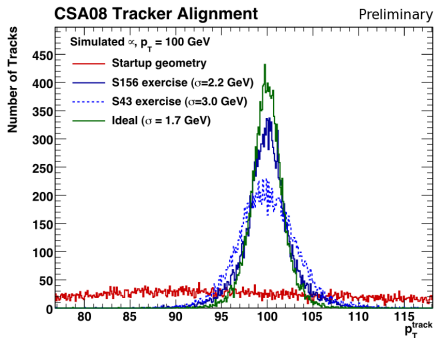
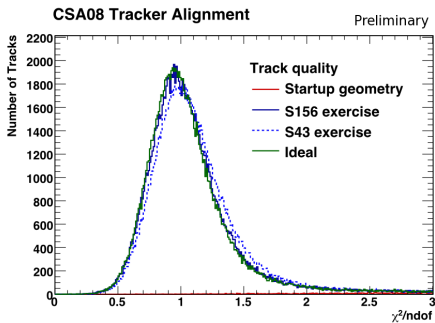


- Simulating two start-up scenarios: 43×43 and 156×156 bunches
- For each scenario the equivalent of one week continuous data taking

Goals

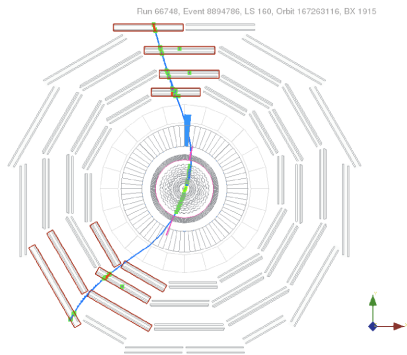
- Large scale Monte-Carlo exercise of all components
- Similar conditions as expected for first data in 2008
- Special emphasis on schedule: The workflow was exercised in the given week, including inter-dependencies of tasks

Track Based Alignment Results



- Track χ^2/ndof of aligned geometry nearly ideal
- Reconstruction of transverse momentum show improvements with statistics and used data sets

Cosmic Ray Data-Taking in 2008

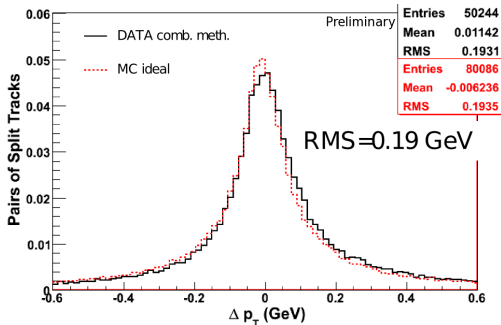
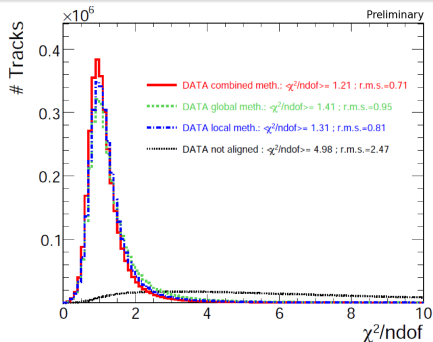


- **23 days** of data-taking with magnet, strip tracker and drift tube muon system at nominal operation
- Triggered **270 M Events**
- Executed a great variety of alignment and calibration tasks
- Opportunity to study **real detector effects**

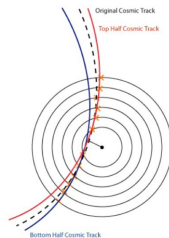
- Data has been studied to great detail
- Many paper drafts in their final stages

Track Based Alignment Results

Using Cosmic Data from 2008



- Track χ^2/ndof greatly improved using cosmic ray data
- Split long track, use two halves to estimate Δp_T
 - Transverse momentum resolution measured from data shows large improvement, too.

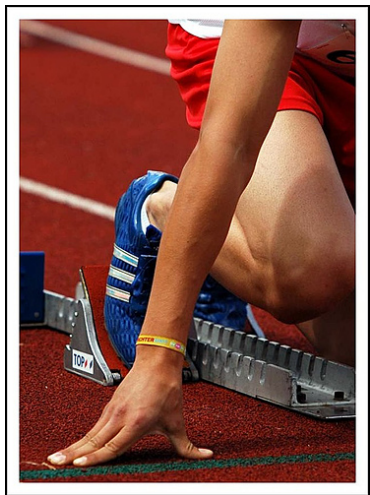


Toward LHC Start-up in 2009



- Cosmic ray data were taken again in 2009
- Prompt alignment and calibration workflow of 3 tasks exercised for the first time
- Conditions were written to the databases in time for prompt reconstruction
- Longer term studies on their way to validate 2008 studies
- Results of cosmic run alignment and calibration to be used with first data
- Further tests of improved software with simulated collision data during fall 2009

Summary



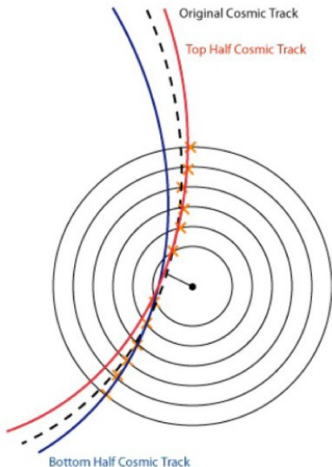
- Detector alignment and calibration is a challenging task at the LHC
- CMS has developed and commissioned a powerful framework for alignment & calibration
 - dedicated skims (AICaReco)
 - algorithms performed at the CAF
 - prompt calibration concept
 - distributed conditions database
- The framework has been tested extensively on simulated and real data

Conclusion

Results show that the alignment and calibration framework is well prepared for collision data

The End

Measuring Track p_T Resolution from Data



- Only use tracks going through the pixel detector
- Split each track at the point of closest approach
- Refit both half on their own
- Compare transverse momentum measurements of both halves