Development of fine shimming technique with magnetorheological fluid





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Introduction

■ Two physics experiments using Muon are proceeded in J-PARC

MuSEUM experiment

> Measure the following values with high precision

Oground state hyperfine structure interval of Muonium : < 3 ppb

Requirements for Magnet

Storage region

○ Field strength: 1.7 T

○ Homogeneity: <±0.1 ppm

Spheroidal volume

very important

Length: 30 cm

Radius: 10 cm

Oratio of muon and proton magnetic moment : < 10 ppb

❖ g-2/EDM experiment

Measure the following values with high precision OAnomalous magnetic moment of positive muon (g-2): < 0.1 ppm ©Electric dipole moment of positive muon (EDM): 1e-21 e.cm

▶ Requirements for Magnet

- Storage region • Field strength: 3 T ○ Homogeneity: <±0.1 ppm
 - Radius: $33.3 \text{ cm} \pm 1.5 \text{ cm}$ Height: ±5 cm
- Injection region $B_{x} \times B_{z} > 0$
- Weak Focus field

 $B_r = -n \frac{D_{0z}}{R} z$ n: $5 \times 10^{-5} - 2 \times 10^{-4}$

Fig. 2: MRI magnet for MuSEUM



Shimming scheme

How to shim magnetic field?

Fig. 1: Superconducting solenoid

magnet for g-2/EDM

- Measure field distribution in target region
- Calculate shim arrangement to cancel error field
- Put iron shims in pockets of shim trays, and insert trays.
- Iron has large magnetization
 - → ~1000 ppm error could be shimmed in general

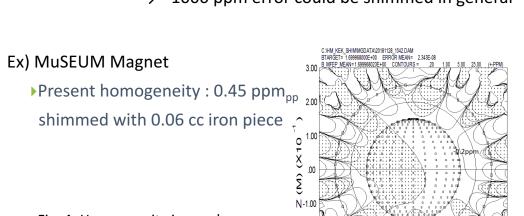
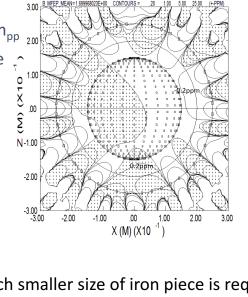
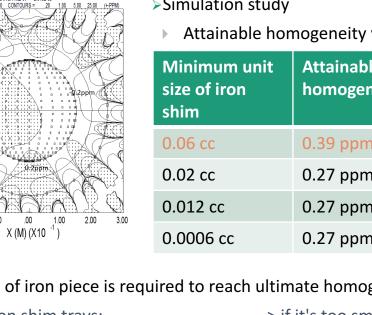


Fig. 4: Homogeneity in x-z plane interpolated from measured data on





NOT suitable for precise shimming : < 1 ppm due to discrete size of pieces and large magnetization

Attainable homogeneity with different size iron shims

Minimum unit size of iron shim	Attainable homogeneity
0.06 cc	0.39 ppm _{pp}
0.02 cc	0.27 ppm _{pp}
0.012 cc	0.27 ppm _{pp}
0.0006 cc	0.27 ppm _{pp}

Limitation of magnet performance

due to discrete size of pieces

 to get maximum homogeneity, size of iron shim has to be smaller than 0.02 cc

In principle, much smaller size of iron piece is required to reach ultimate homogeneity, but...

 Difficult to handle and fix on shim trays; -> if it's too small, misalignment might be occurred frequently

• Optimum size depends on magnet and magnetic condition; -> difficult to expect optimum size beforehand

◆ Ferrofluid material Liquid having magnetism

✓ easy to get arbitrary volume

✓ much smaller magnetization than Fe



One possible candidate for fine shimming

R&D of shimming system with ferrofluid materials

- ☐ Feasibility study on fine shimming with ferrofluid
- ☐ Develop and test prototype shimming system
- ☐ Develop Field mapping system

will report

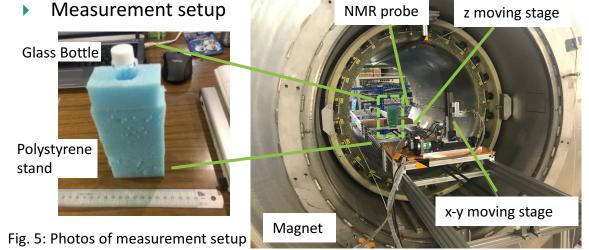
- basic study of ferrofluid
- development status of field mapping CW-NMR probe

The authors would like to thank Dr. T. Nakajima of Echo-denshi for his help. This work was supported by JSPS KAKENHI Grant Number 18H01239.

Basic study on ferrofluid

Easy controllability of magnetization, that is, volume

(a) Measure magnetization of commercial ferrofluid for feasibility study of ferrofluid



• Ferrofluid : DS-50 Iron oxide, Isostearic acid and

Relative density: 1.36-1.40 •Saturated magnetization: 45 –55 mT

Cap : Polypropylene • Size: φ25 mm, 50 mm height

Body : Borosilicate glass

Polystyrene Table for probe Table for sample

➤ Moderate magnetic susceptibility compared with iron

Suitable material for fine shimming

Schematic view of setup

itting function

 $P_0 = 2 \times 10^{-7} \times m_z$

B₂: Magnetic field

Fig. 6: Schematic side view of measurement setup

- Scan in x-y plane to search the position where the effect of sample
- Probe is fixed, and sample is moved in z direction by moving stage Measure magnetic field with and without samples

NMR probe Field strength: 1.7 T

Calculate magnetic moment from measured distribution

How to calculate magnetic moment

*Assume point Magnetic moment Magnetic flux density created by magnetic moment

 $B = -\frac{\mu_0}{4\pi} \nabla \frac{m \cdot r}{r^3}$

- Check the measurement error

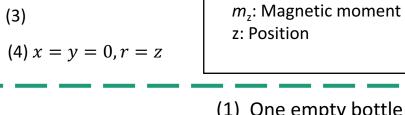
- Check individual differences between bottles

Check the consistency of ferrofluid volumes

Check the controllability of ferrofluid volume

 $\mathbf{B} = -10^{-7} \times \nabla \frac{\mathbf{m} \cdot \mathbf{r}}{r^3}$ (2) $m = (0,0,m_z)$

 $\mathbf{B} = -10^{-7} \times \frac{m_z}{r^3} (-3xz, -3yz, r^2 - 3z^2)$ (3) $B_z = 2 \times 10^{-7} \times \frac{m_z}{3}$



(1) One empty bottle: 5 times

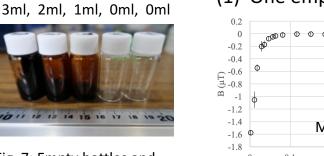


Fig. 7: Empty bottles and bottles filled with ferrofluid

(3) 5 bottles with Ferrofluid of 1 cc

Symbol: Average of 5 meas. Error bar: Standard dev. of 5 meas. $\rightarrow m_7$: -7.649e-5 ± 2.314e-6 (Am²) P_1 : -1.309e-2 ± 3.162e-4 (m) Max. stdev : 0.12 μT P_2 : -3.264e-9 \pm 7.715e-10 (T)

(4) Ferrofluid 1, 2, 3 cc

 P_1 : Error of position

 P_2 : Error of magnetic field

m, of Fe: 1.711 Am²

Fig. 8: Magnetic field shift due to empty bottle; z represents distance from bottle center.

(2) 5 empty bottles

(4) Ferrofluid 1,2,3 cc

Measurement results

(1) One empty bottle: 5 times

(2) 5 empty bottles: 1 time each

(3) 5 bottles with Ferrofluid of 1 cc

Bottles	M _z (Am²)	P ₁ (m)	P ₂ (T)
#1	-7.598e-5	-1.186e-2	-2.721e-9
#2	-7.549e-5	-1.213e-2	-3.715e-9
#3	-9.369e-5	-1.419e-2	3.467e-9
#4	-6.811e-5	-1.061e-2	-8.768e-9
#5	-9.067e-5	-1.385e-2	8.129e-9
Avg.	-8.079e-5	-1.253e-2	-7.217e-10
St. dev.	1.091e-5	1.483e-3	5.587e-9
 Bottle variation : ~ 13 % of average 			

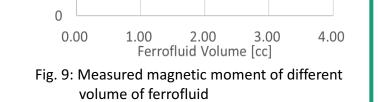
 Sufficiently smaller than ferrofluid - > can be neglected

> Next step: increase number of data to decrease statistical uncertainty

Bottles M, (Am²) P_2 (T) -1.136e-2 -2.358e-8 3.593e-2 -2.249e-2 -2.882e-8 -2.371e-2 -3.666e-8 -2.211e-2 -3.528e-8 4.100e-2 -2.180e-2 -3.979e-8 -2.029e-2 -3.283e-8 (4.100e-2) (-3.514e-8) (-2.253e-2) 5.044e-3 6.533e-9 (8.350e-4) (4.616e-9) (5.131e-4)

- m, of 1cc ferrofluid : ~1/40 of iron of 1 cc Almost agree with specification
- #1 : large difference from others
- #1 : filled by syringe, #2-#5 : filled by spoon Density might be different —

0.12 0.08 0.06



y = 0.0411x + 0.0086

 $R^2 = 0.9996$

- m_{τ} : almost linear relative to volume
- Magnetization can be controlled by volume y-intercept should be zero
- Caused by different density?
- Next step: check reproducibility considering density control

R&D of field mapping CW-NMR probe

➤ Need quick measurement to neglect time variation of B.

\heartsuit Developing high precision multi channels CW-NMR field mapping system for MuSEUM experiment

❖ Need precision field mapping system for fine shimming

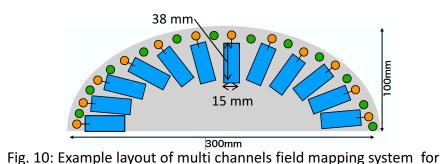
> NMR magnetometer is only solution for precise measurement

CW-NMR with frequency modulation

- Sweep RF frequency to detect NMR signal
- Need to place electronics board including RF detection circuit close to RF coil for high SNR

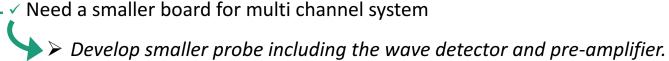
Field mapping probe for MuSEUM

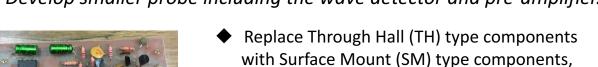
- Spheroidal volume: 30 cm in length, 10 cm in radius NMR probes are aligned on half of ellipse arc and
- they are rotated around the long axis so that the field map could be quickly obtained.

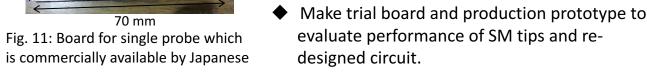


MuSEUM experiment with 24 probes. 12 electronics boards are implemented on this side, and others are implemented on the backside.

MMBTH10-7







which have smaller magnetization



Fig. 11: Trial board to evaluate SM tips performance.



Fig. 12: Production prototype board for evaluating the performance of re-designed circuit and magnetization.

Trial board test

- Resistors and capacitors were replaced with non-magnetic tips commercially available.
- There are no same models of SM tips for several transistors
- ▶ Test different types of SM alternatives considering magnetization 1ss86 -> 1ss154; 2SK19 -> 2SK208-R; 2sc1907 -> DSC2G03;

Ex) 2sc1907: two candidates were tested

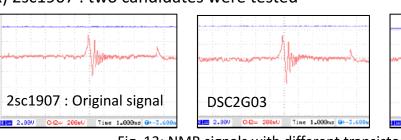
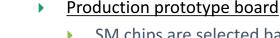


Fig. 13: NMR signals with different transistors. **b** Both candidates show almost the performance as original tip.

- MMBTH10-7 has largeer magnetization than DSC2G03 -> Choose DSC2G03



Preliminary results

- SM chips are selected based on trial board
- Use 4 layers printed circuit board

- Clear resonance peak by vector network analyzer
- Obtain NMR peak signal at 1.7 T
- Magnetization of the circuit is about 21 % of commercial one. (-17.1 ppb -> -3.76 ppb)

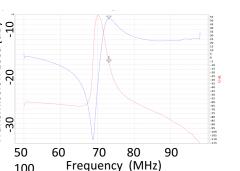
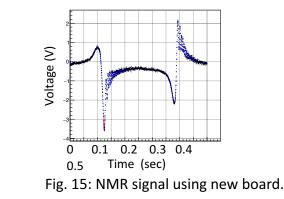


Fig. 14: Transmission response.



✓ Studying shimming system with ferrofluid materials Summary

Basic study of ferrofluid

- measure magnetic moment of glass bottles and bottles filled with ferrofluid
- m_{τ} was sufficiently smaller than ferrofluid so that it could be neglected in fine shimming m_{τ} of ferrofluid DS-50 was about 1/40 of iron, that is consistent
- with specification. m_{τ} of bottle filled with ferrofluid could be changed at will by

\supset Development of high precision multi channel field mapping system

- made production prototype of electronics board
- > TH type components were replaced with SM type components with smaller magnetization
- Could obtain NMR peak signal at 1.7 T

controlling the volume of ferrofluid.

✓ Next step

- Increase number of data to decrease statistical uncertainty
- ♠ Check time variation of magnetization
- Test different ferrofluid samples to determine optimum one for fine
- Design and Build support system for fine shimming with ferrofluid
- Test production prototype board and measure its magnetization in Study the performance when several channels are connected in
- Make and test multi channel system



Try shimming operation with MRI magnet for MuSEUM