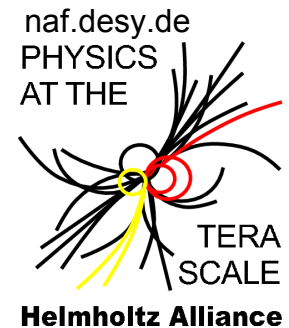




Tracking software status and estimated tracking performance for tau decay products

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- Disclaimer: The tracking software is a common effort of a big group, praise them, not me (I will not mention any names here, otherwise I will certainly miss someone)! You can blame me for the following plots, though...
- Talk concentrates on Inner Detector tracking, because most relevant for taus
- Outline:
 - Status of the New Tracking
 - Developments concerning taus
 - Tracking performance for different Inner Detector alignments
 - Conclusions and Outlook

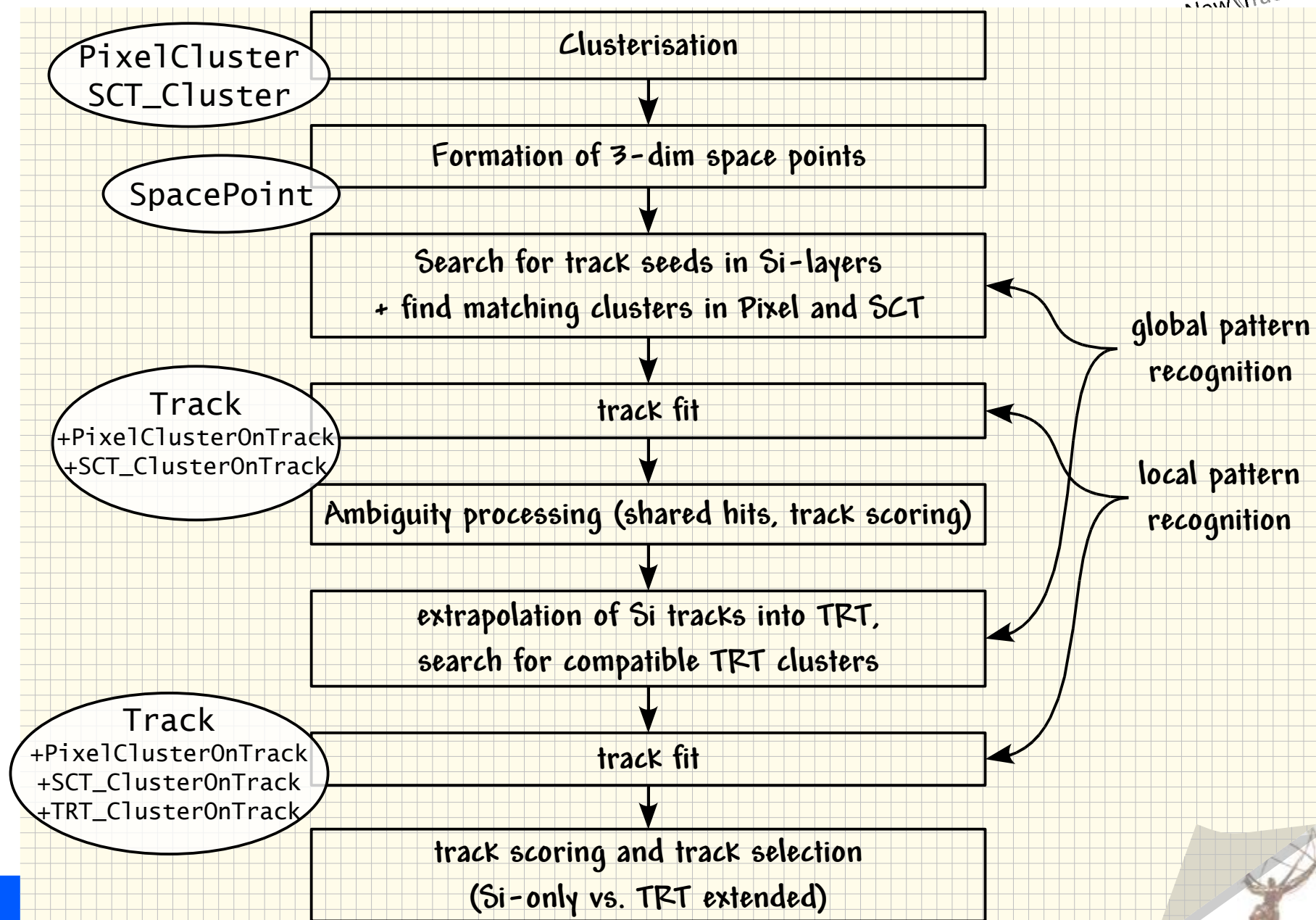


- The Inner Detector track reconstruction (New Tracking) uses a single setup (pattern recognition, track fit, ...) by default, but several different options exist
- Track fitter:
 - Global χ^2 Fitter (GXF, current default)
 - Kalman Filter (KF): iterative fitter with different optional extensions:
 - Dynamic Noise Adjustment (DNA) for recovery of bremsstrahlung: Dynamically increase the estimated uncertainty due to energy loss in the track fit
 - Internal annealing for outlier detection
 - Deterministic Annealing Filter (DAF): Uses annealing procedure for dynamic assignments of measurements to a track
 - Gaussian Sum Filter (GSF) for brem fits: Sum of Gaussians to model Bethe-Heitler energy loss of electrons

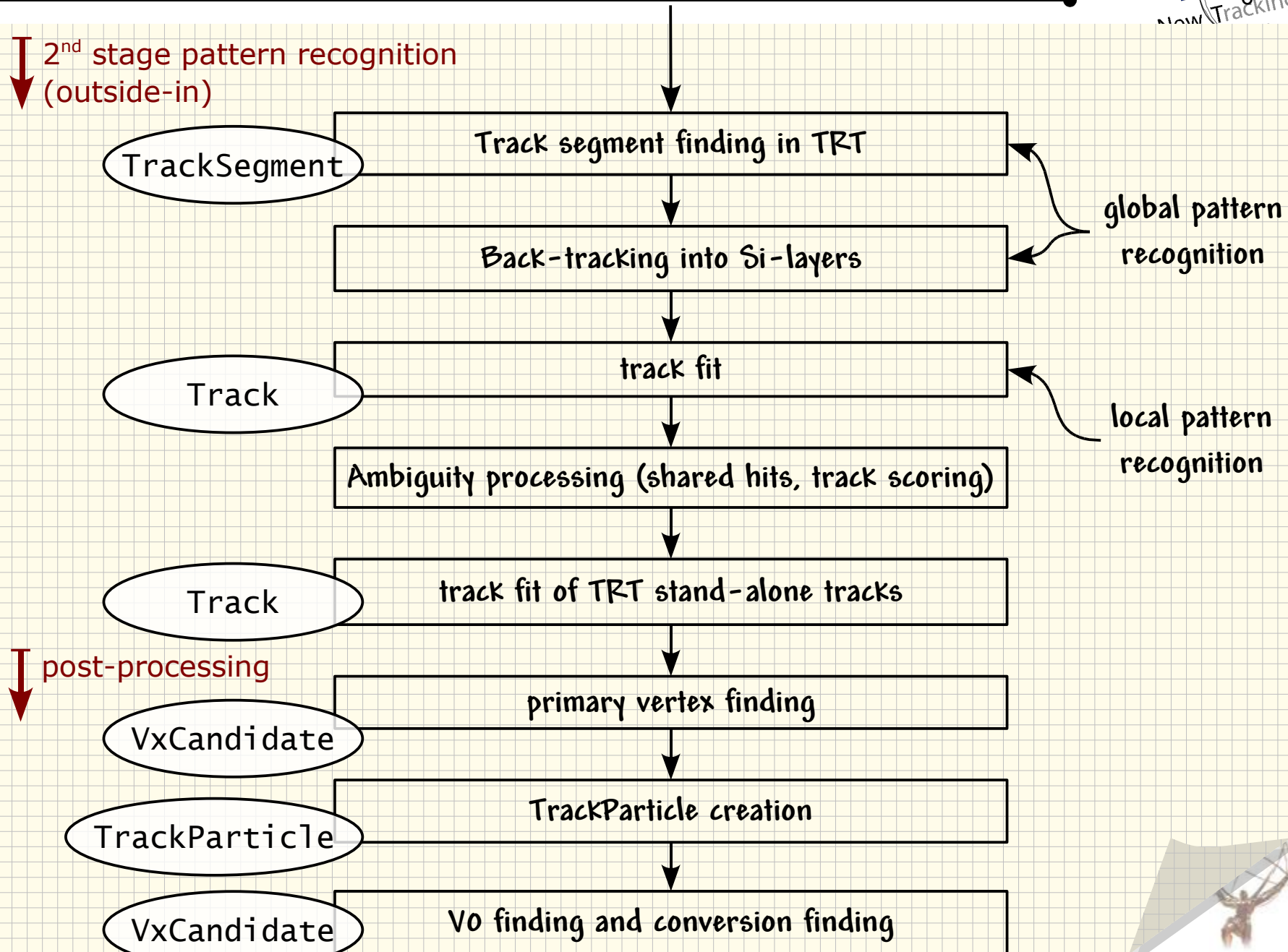


- Pattern recognition:
 - Inside-out tracking: Silicon pattern and track fit + TRT extension
 - Additional outside-in tracking to reconstruct conversions and V0s
 - Special configuration for beam gas / beam halo events, low- p_T tracking
 - Very important: Adapted Combined Test Beam tracking for cosmics
 - New: Heavy ion mode
- A priori it is not clear, whether the default reconstruction is the best choice for tracks from tau decays
 - Especially overlapping tracks in high- p_T 3-prong decays or additional conversion tracks may influence the track reconstruction efficiency
 - The very modular structure allows to easily introduce new algorithms, e.g. a "Multi Track Fitter"
 - Will not go into details on re-running the Inner Detector reconstruction for tau leptons here, see talk by Antonio Limosani





Overview



- Software clean-up for release 15
 - Reduce package dependencies to decrease compile time (private/public use statements)
 - Usage of `AthAlgorithm` and `AthAlgTool` to improve CPU time due to `MessageSvc`, etc
 - Force abstract interfaces, avoid dual-use libraries
 - Drop of `CBNT` and `InDetRecStatistics` ntuples
 - Use standard plots from `InDetPerformanceRTT` or `TrkValidation` ntuple
 - Nearly finished
- Tuning of Global χ^2 Fitter and Kalman Filter regarding efficiency and fake tracks (mainly aimed at b-tagging) and tuning of track scoring / selection
- Modified cuts on MC truth record in simulation to reduce “fake-fakes”
 - Keep in mind: There is a very detailed matching of reconstructed tracks to truth particles. I recommend to use it instead of a simple ΔR match, because it is much more precise in dense environments! Example how to match MC taus to reco taus using tracks can be found in `TauTrackTools`



New features and activities with potential impact on the tau ID



- Electron PID tool (used by conversion ID, see talk by Michael Böhler)
 - Currently uses TRT high-threshold hits only
 - Improved ID possible by using Time over Threshold (ToT) information
 - When using Kalman fitter with DNA: Brem data from the track fit can be used as well
- Refit of conversion electrons with Kalman-DNA and GSF
- Pile-up optimisation ongoing
- Many studies using cosmic data ongoing
 - Needs specialised reco though (vertex constraints, track direction)
- Tracking Material validation
- Tuning of the Combined tracking (Inner Detector + Muon System)
 - Currently mutual validation in the material and energy loss estimates for extrapolations from the ID to the MS for the different muon algorithms



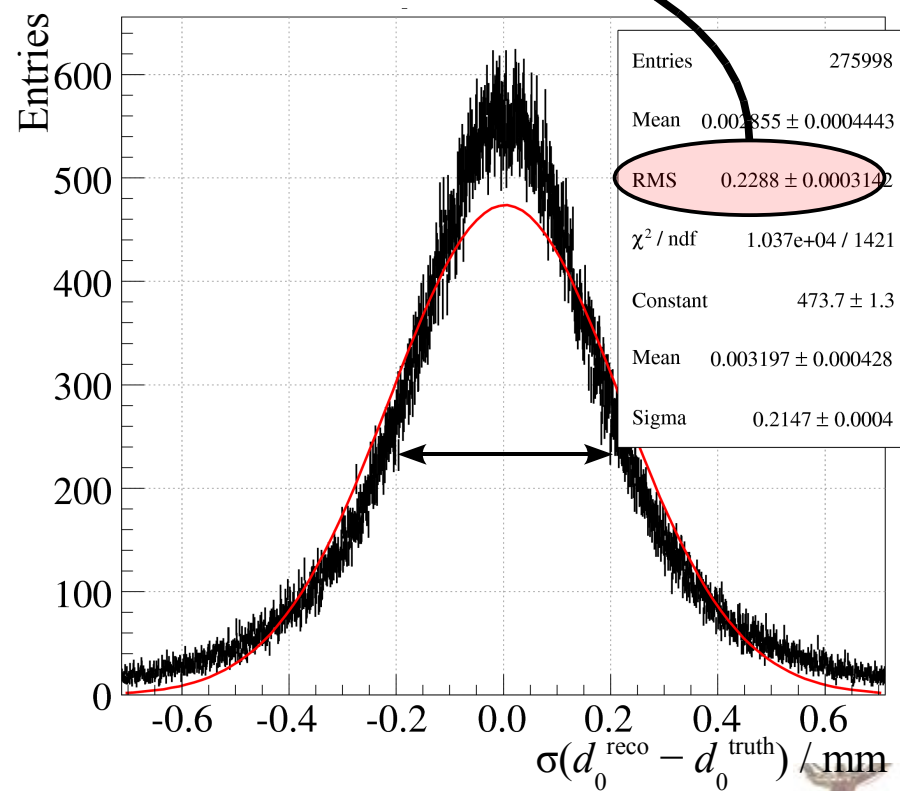
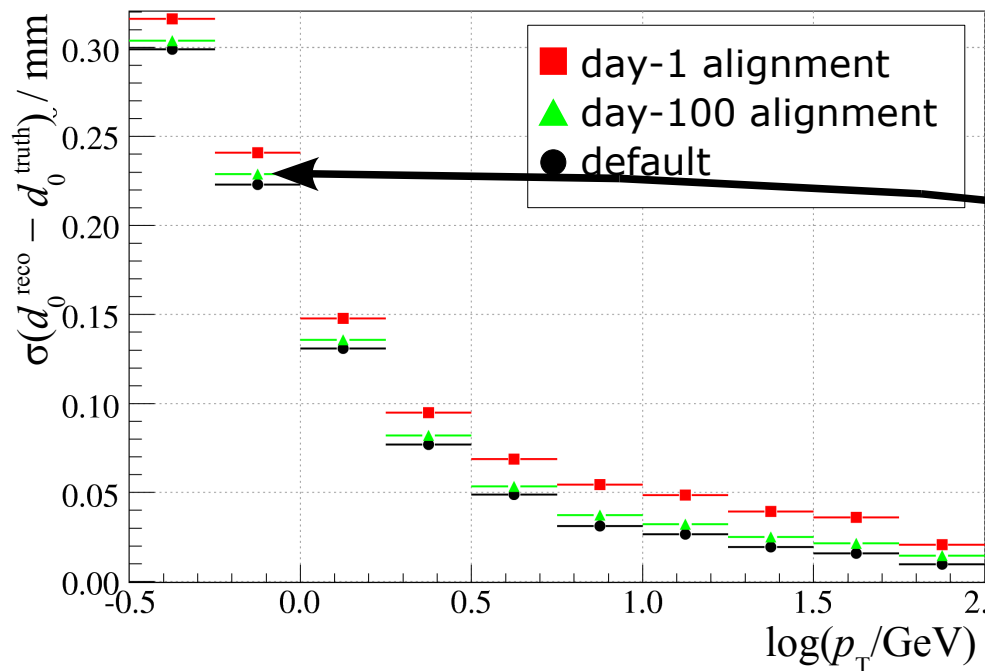
Expected tracking performance in tau events



- The following performance plots show the estimated tracking performance for $Z \rightarrow \tau \tau$ events (106052)
- MC08 simulation with (re-) reconstruction in 15.0.0.2 using the following alignments constants:
 - default (same as in simulation)
 - day-1 (randomly smeared constants with regard to the simulation geometry according to the estimated alignment precision by J. Schieck)
 - day-100
- Partially reconstruction on RDOs ($\sim 19\text{k}$ events), partially re-reconstruction (ID tracking including pattern recognition and tauRec) on ESD ($\sim 180\text{k}$ events), due to large statistics needed for some plots

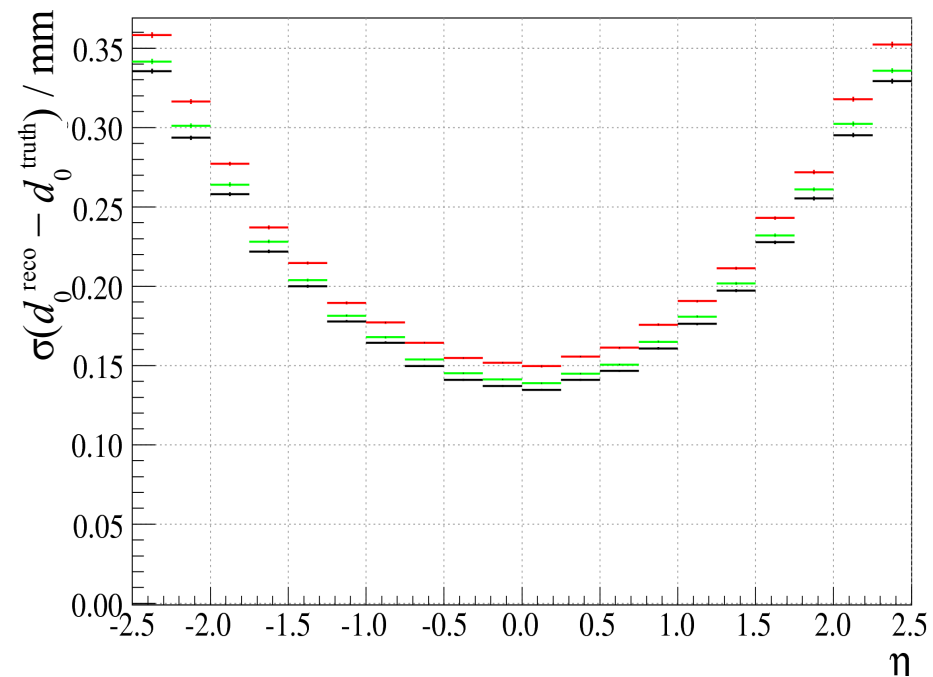
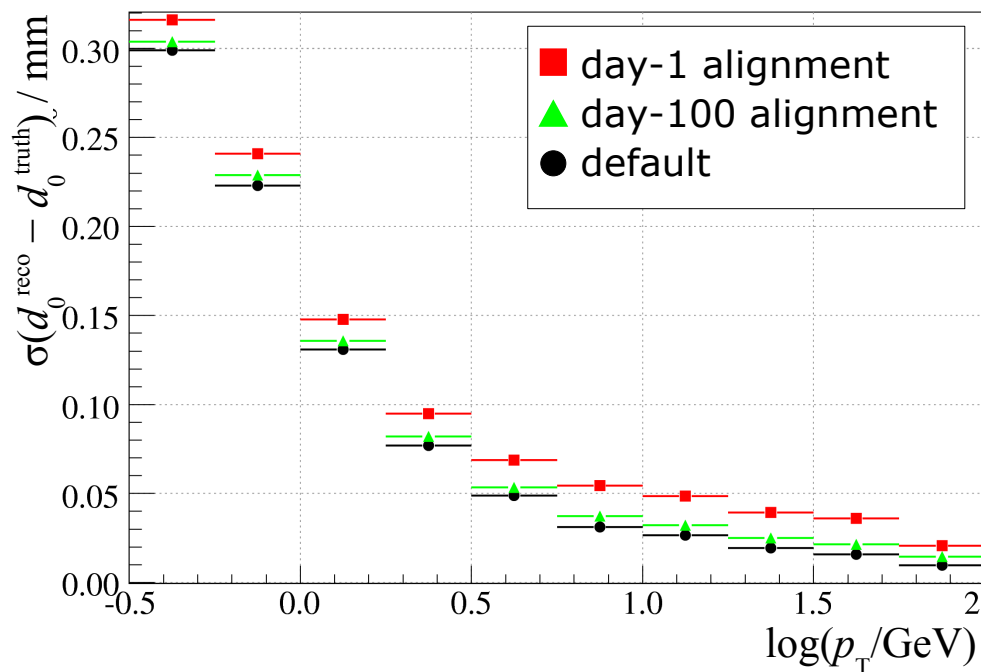


Expected tracking performance in tau events: Transverse impact parameter resolutions



- Track parameter residuals non-Gaussian: take RMS
- pulls (residual/error) are nearly Gaussian, though!

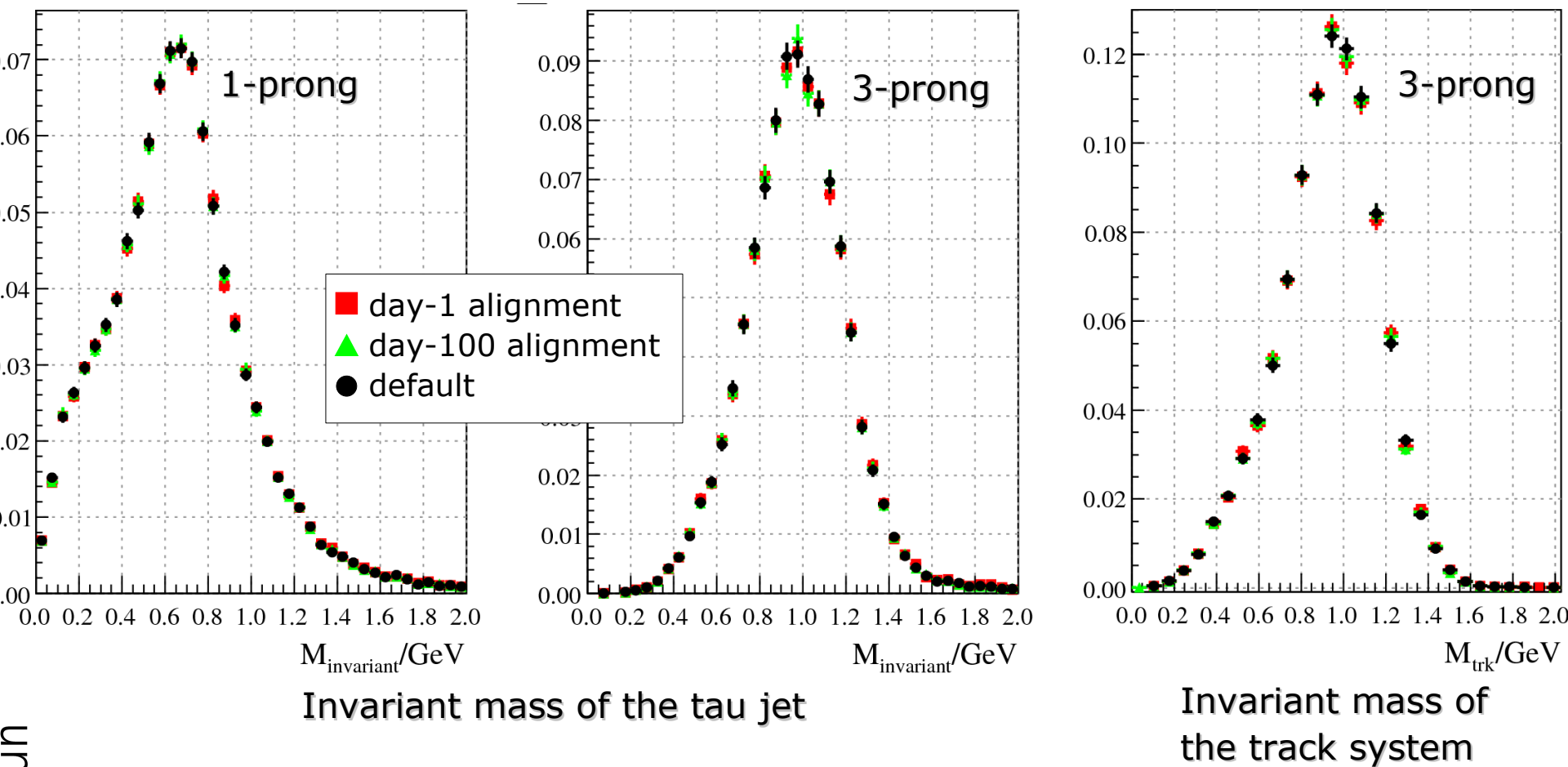
Expected tracking performance in tau events: Transverse impact parameter resolutions



- 15.0.0.2 InDetRecExample reconstruction on RDO with “standard plots”
 - Global χ^2 Fitter, all “good” tracks after TRT extension (no backtracking)
- Only a very slight degradation in the impact parameter resolution



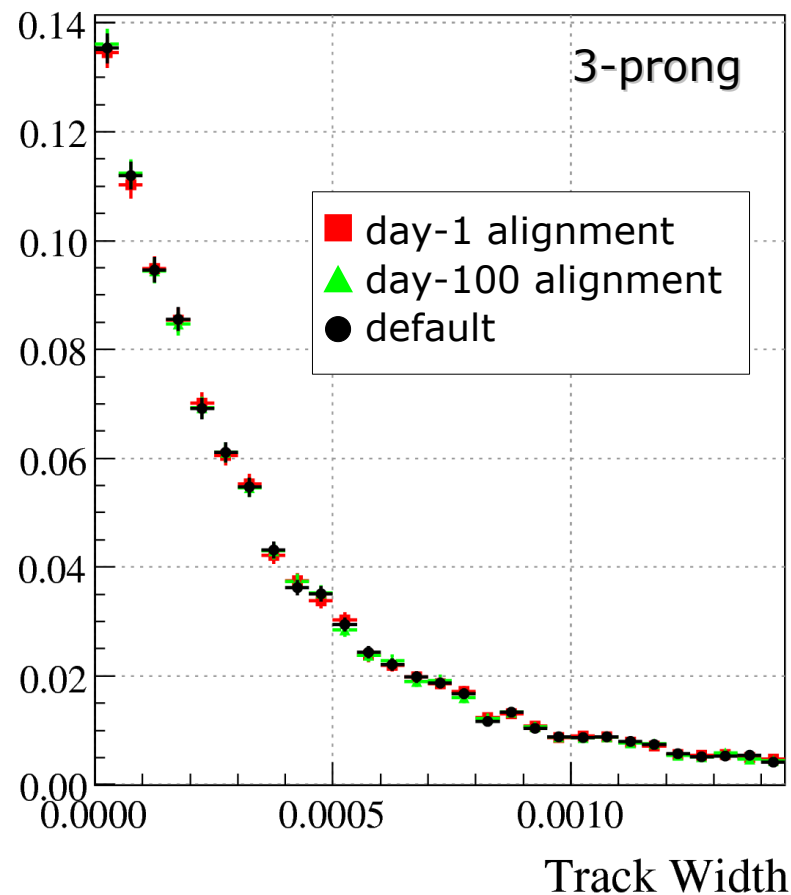
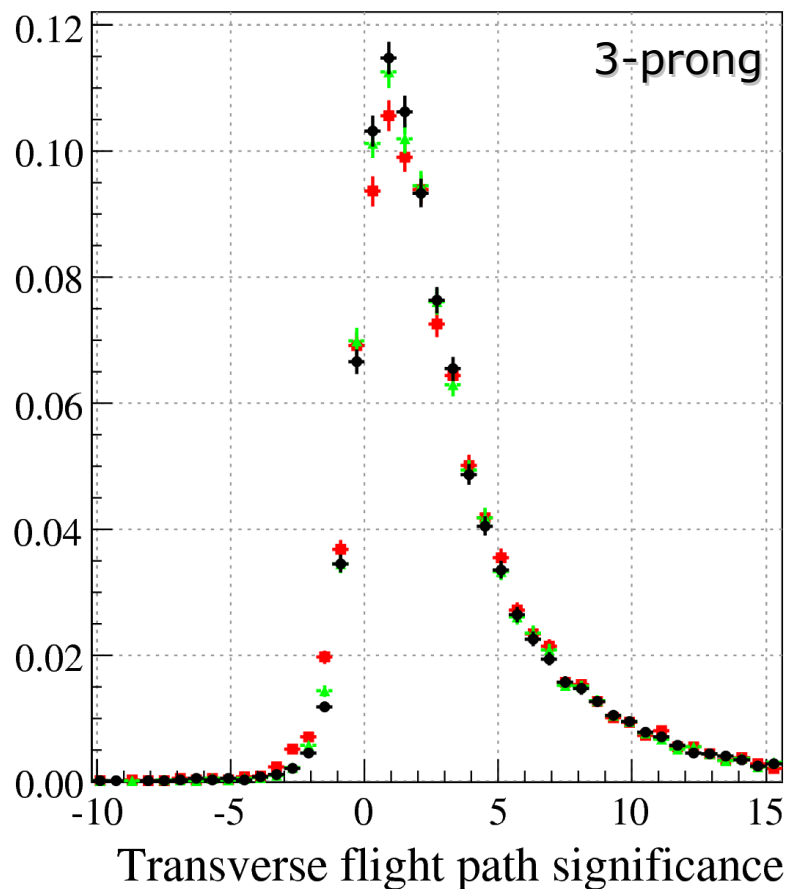
Expected tracking performance in tau events: Impact on tau variables



- 15.0.0.2 re-reconstruction (ID tracking and tauRec) on ESD with TauValidation
- Only small impact observable



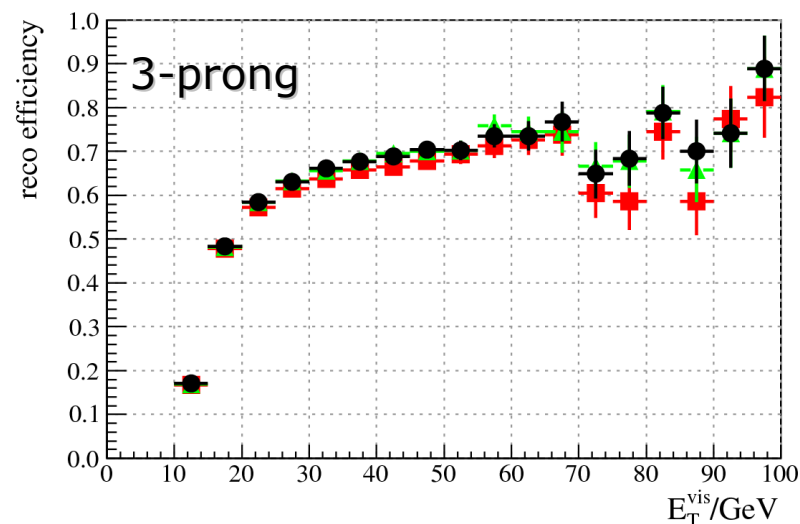
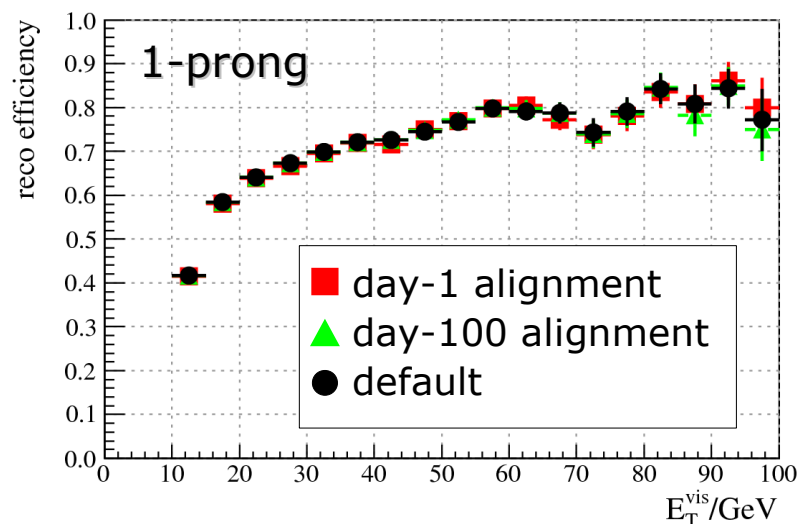
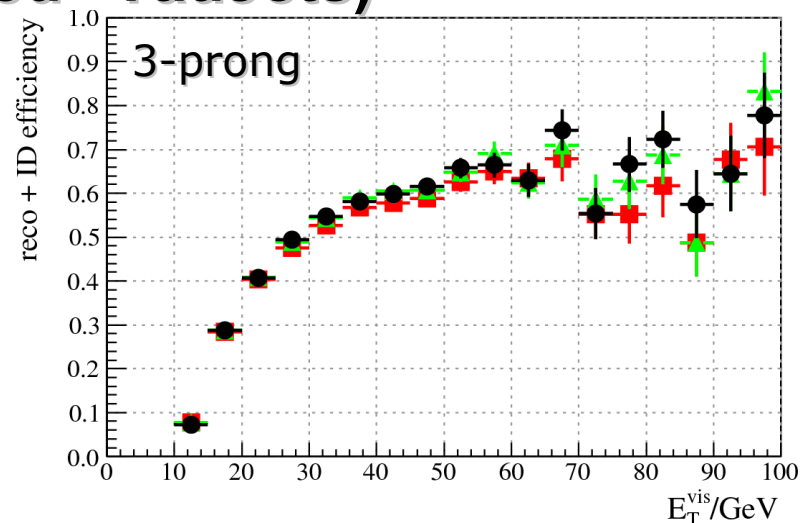
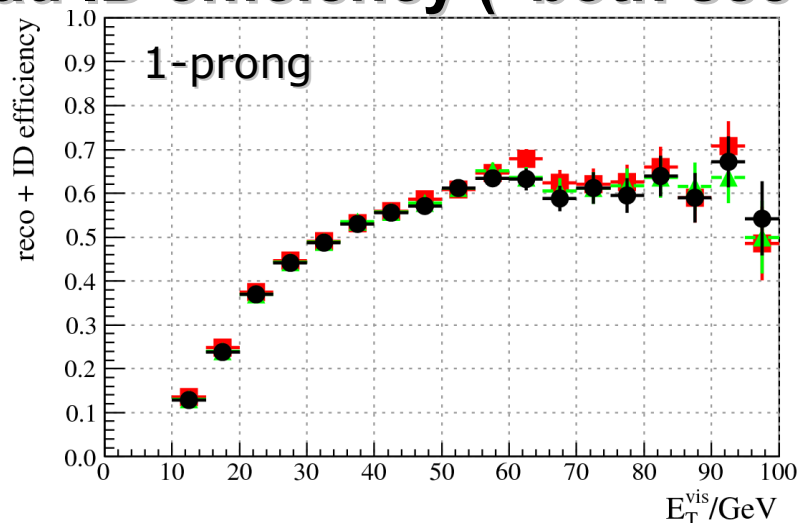
Expected tracking performance in tau events: Impact on tau variables



- 15.0.0.2 re-reconstruction (ID tracking and tauRec) on ESD with TauValidation
- Only small impact observable



Expected tracking performance in tau events: Tau ID efficiency (“both seeded” TauJets)



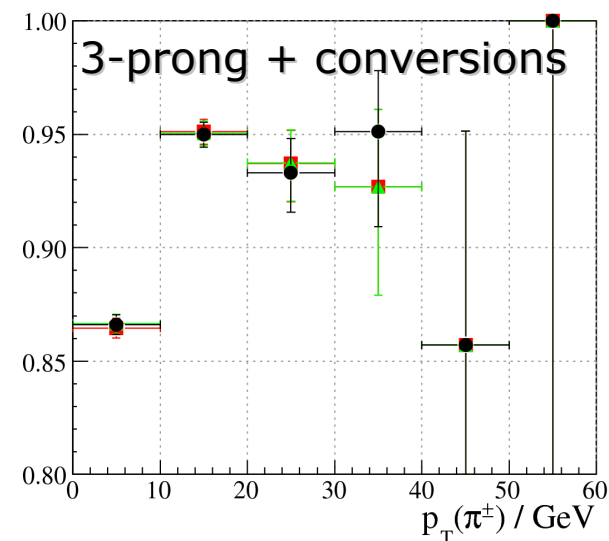
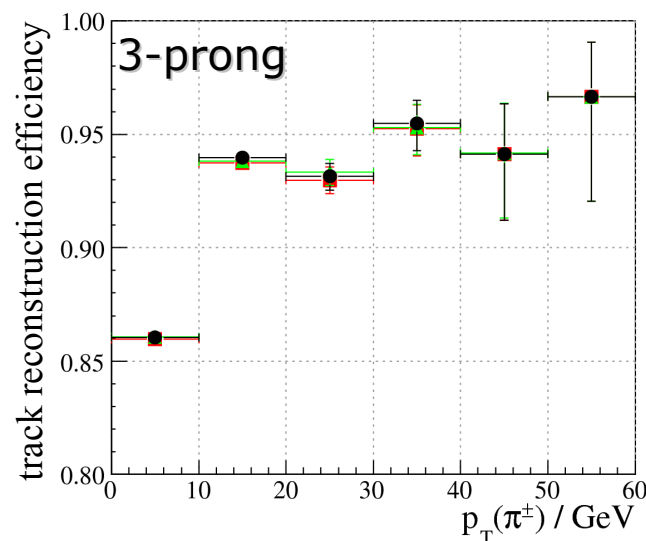
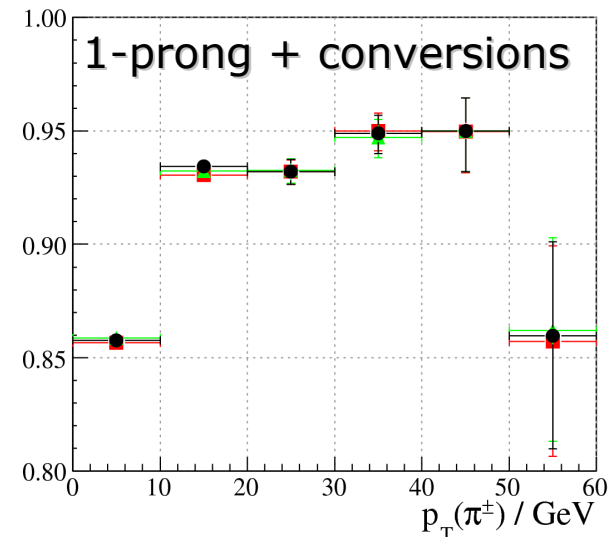
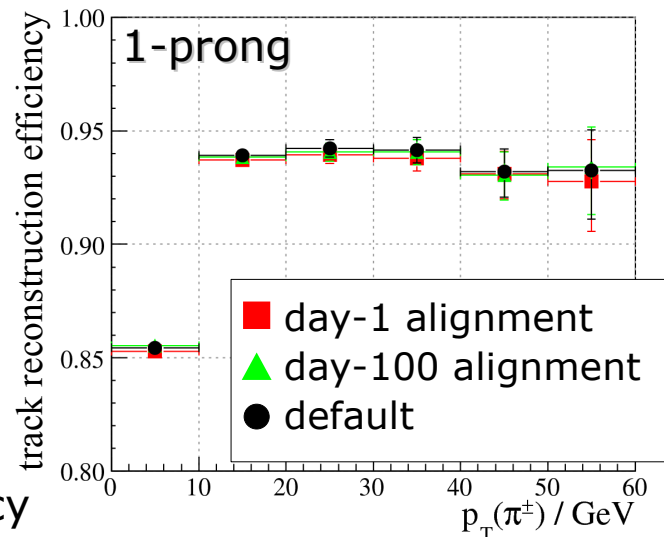
- ID efficiency for 1-prongs even increases with misalignments, may be an effect of worse impact parameter resolution



Expected tracking performance in tau events: Track reconstruction efficiencies for pions

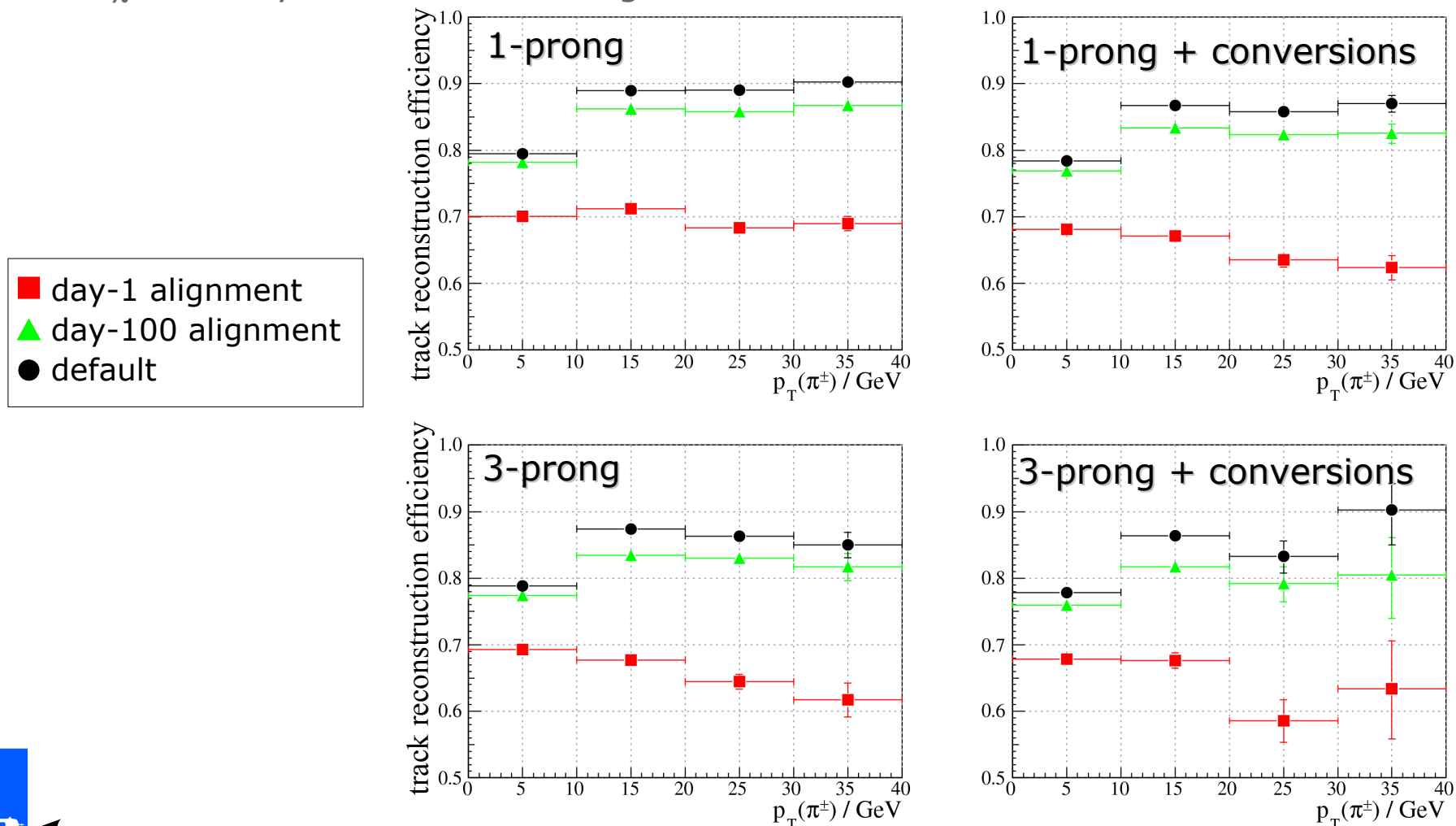
- Efficiency for pions from tau decays using standard track selection cuts

- 15.0.0.2 re-reconstruction (ID tracking and tauRec) on ESD with TauTrackTools
- inefficiencies mainly due to hadronic interactions (efficiency increases to nearly 100%, if pions with hadronic interactions are not counted)



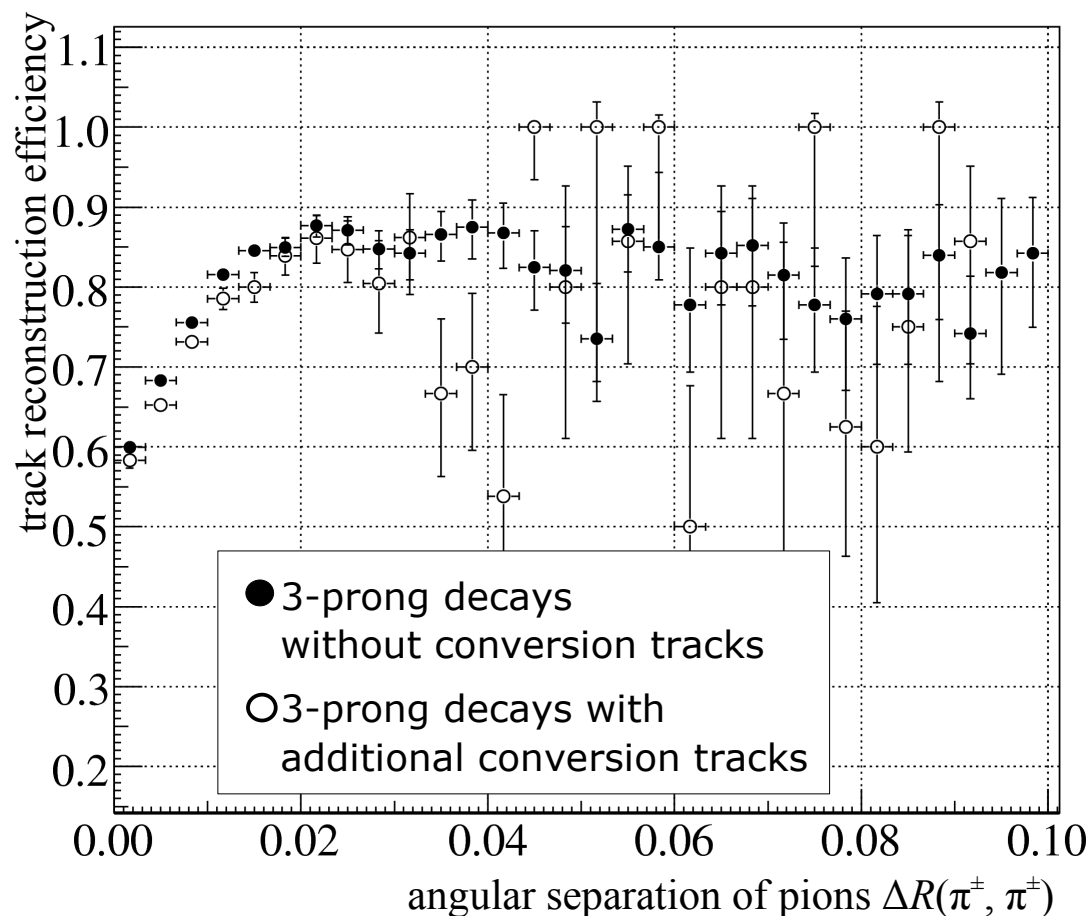
Expected tracking performance in tau events: Track reconstruction efficiencies for pions

- Efficiency for pions from tau decays using track selection cuts with b-layer hit and $\chi^2/\text{ndof} < 1.7$
- χ^2 -cut very sensitive to misalignments



Expected tracking performance in tau events: Track reconstruction efficiencies for pions

- Impact of overlapping tracks on the tracking efficiency for pions from tau decays
- $A \rightarrow \tau \tau$ events reconstructed in 14.2.0 (effect only for high- p_T taus strongly pronounced)



- The ATLAS tracking software is in good shape for collision data
 - no important features missing
 - performance is continuously improving
- No big impact of Inner Detector misalignments as predicted for day-1 on the tau reconstruction is expected
 - BUT: In this study just looked at different alignment sets, the outage of whole detector modules may have a big impact on the track finding efficiency

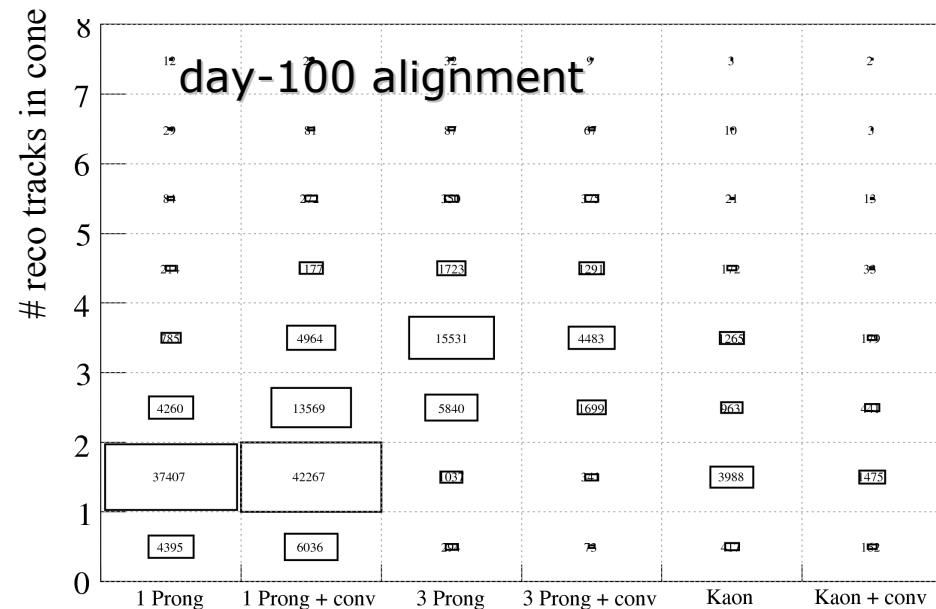
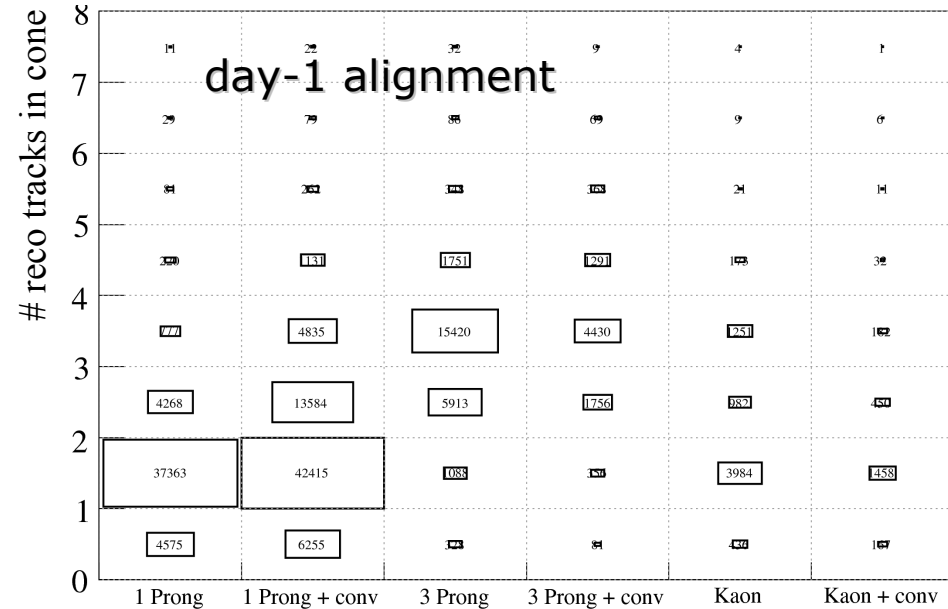


- Thanks to Jochen Schieck for providing the alignment constants
- Thanks to Wolfgang Liebig for valuable input

Expected tracking performance in tau events:

Number of reconstructed tracks

- Number of reconstructed tracks using standard track selection cuts inside $\Delta R < 0.4$ around the visible component of the tau vs. the true decay mode
- 15.0.0.2 re-reconstruction (ID tracking and tauRec) on ESD with TauTrackTools

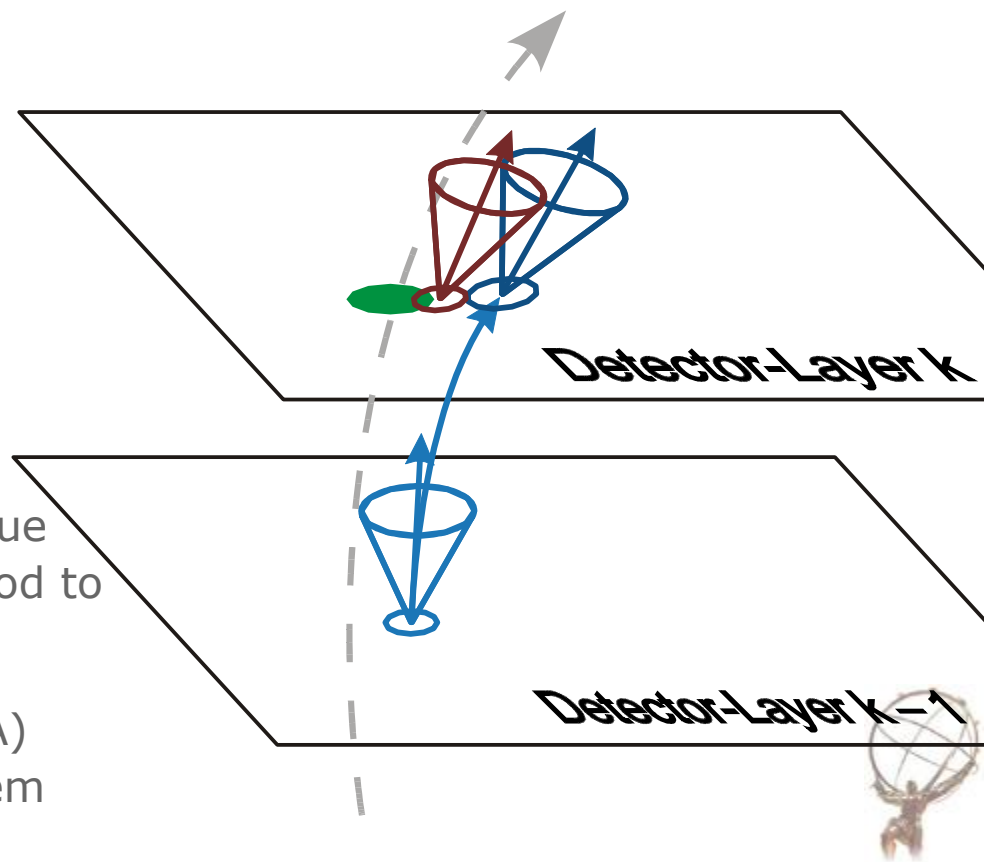


- Navigation problem at $\phi=\pi$ can cause higher number of selected tracks in this region, because less holes are found
 - effect only visible in dense jets
 - see bug#48591, fixed in 15.1.0



Kalman Filter

- Kalman Filter use an iterative approach for the track fit:
 - The track parameters on surface $k-1$ are propagated to surface k (*prediction*)
 - Those track parameters on layer k can be projected to get the predicted measurement position
 - The updated track parameters including the measurement on layer k are calculated as weighted mean (*update*)
- Material effects (MS, Eloss, ...) have to be considered in prediction only
 - Advantage: Prediction follows true position closely, i.e. material good to estimate
 - Dynamic noise adjustment (DNA) increases noise term to take brem into account



- Basic classes:

- `Trk::Track`: contains several `Trk::TrackStateOnSurface`
- `Trk::MeasurementBase`: Base class for all kind of measurements which can be used in a track fit

