

# Digital signal integrity and stability in the ATLAS Level-1 Calorimeter Trigger

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on behalf of

ATLAS Level-1 Calorimeter trigger collaboration:

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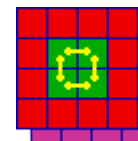
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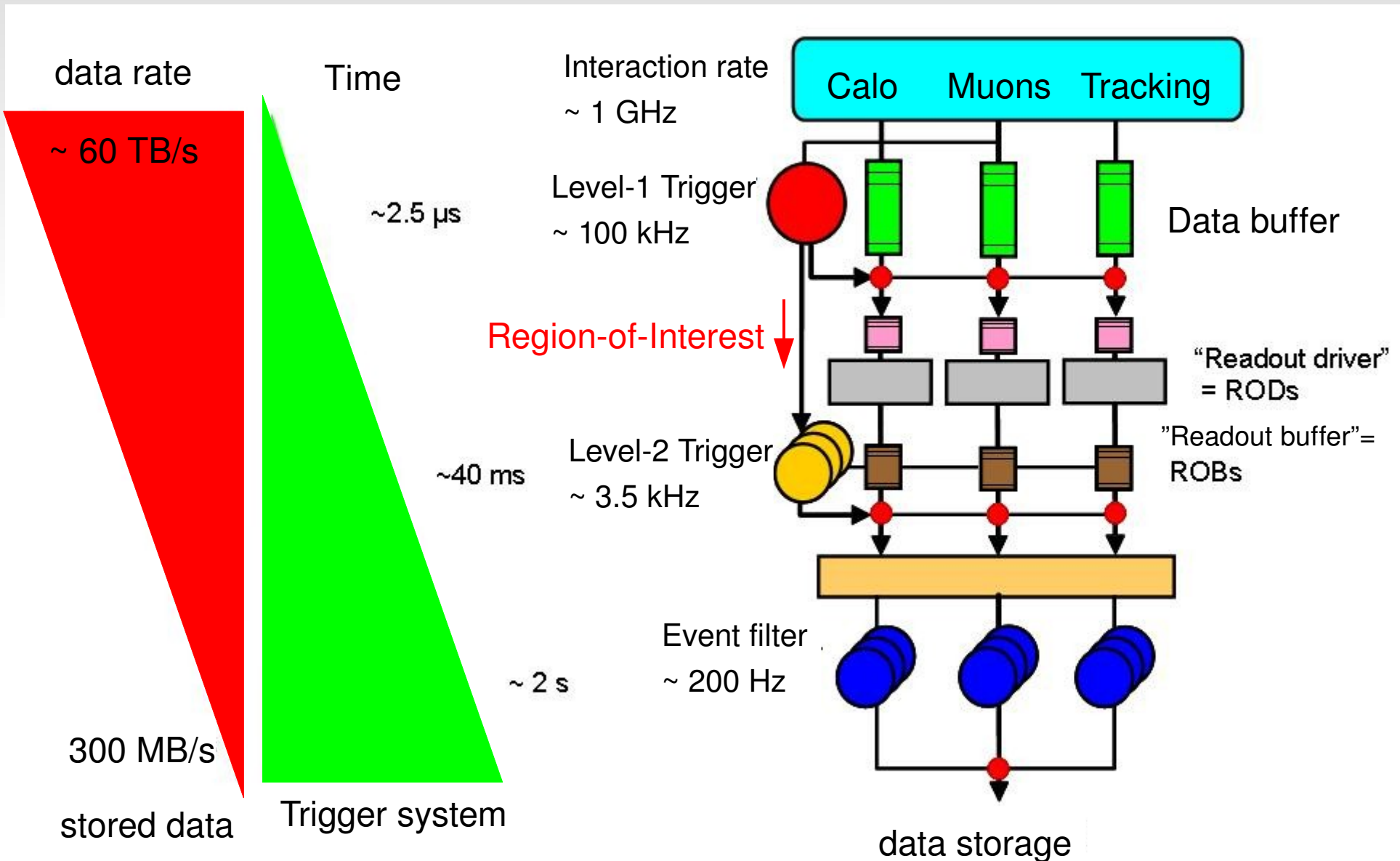


# Outline

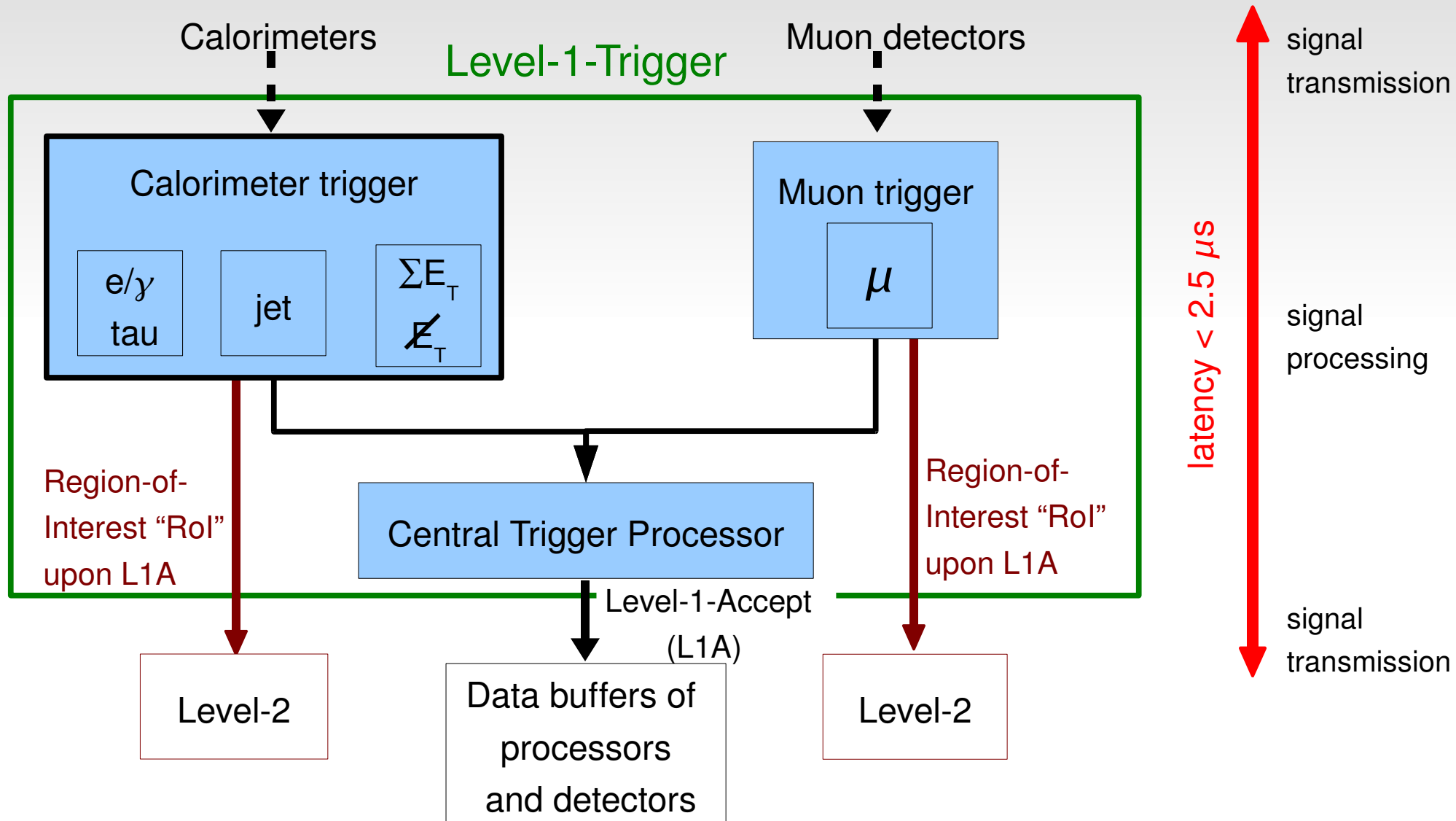
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- Introduction to the trigger system
- Digital signals in the Level-1 Calorimeter trigger
  - Challenges on data treatment
  - Inter-crate connectivity
  - Inter-module connectivity
  - Readout links
- Conclusions

# Introduction: Trigger System



# Level-1 System

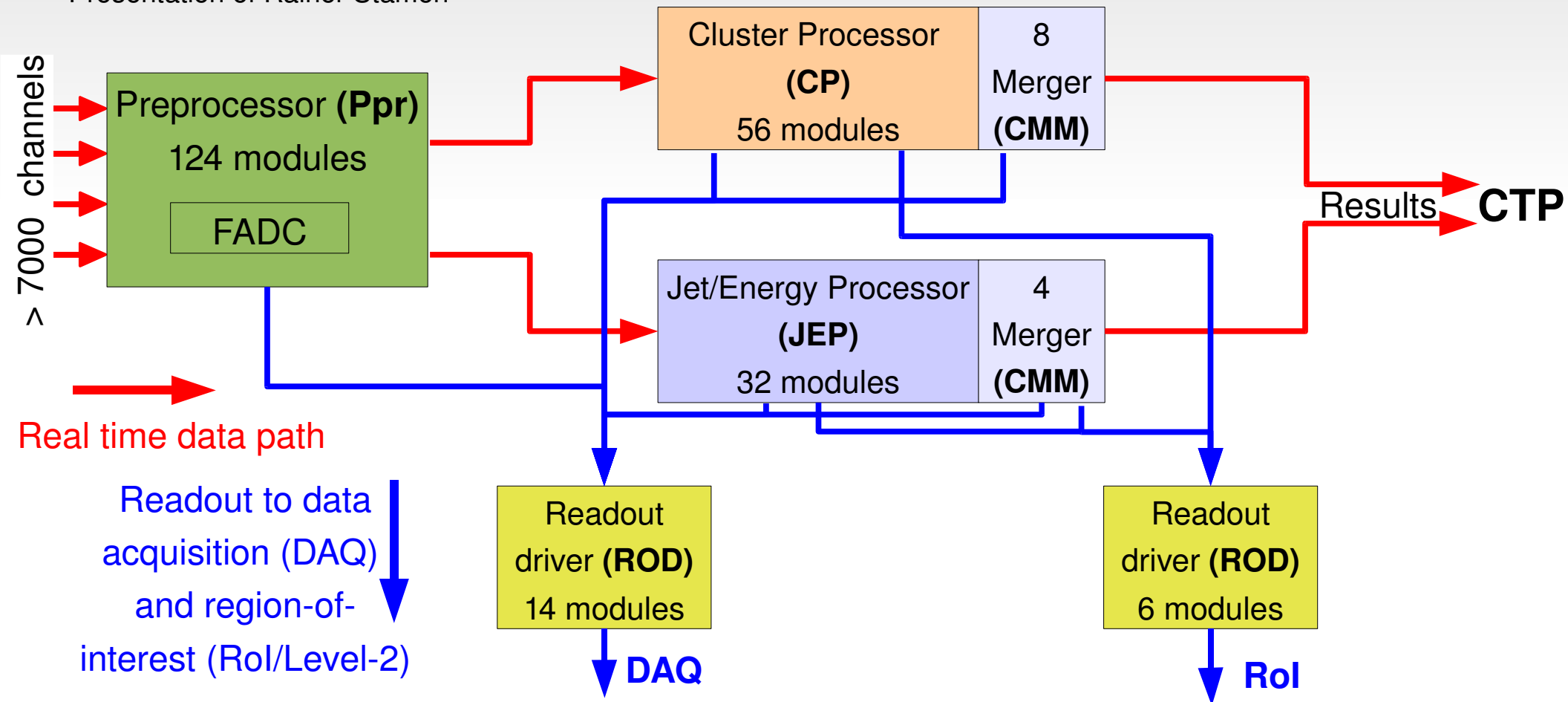


# Level-1 Calorimeter Trigger

Analogue\*

DIGITAL

\* Presentation of Rainer Stamen



# The Electronic cavern

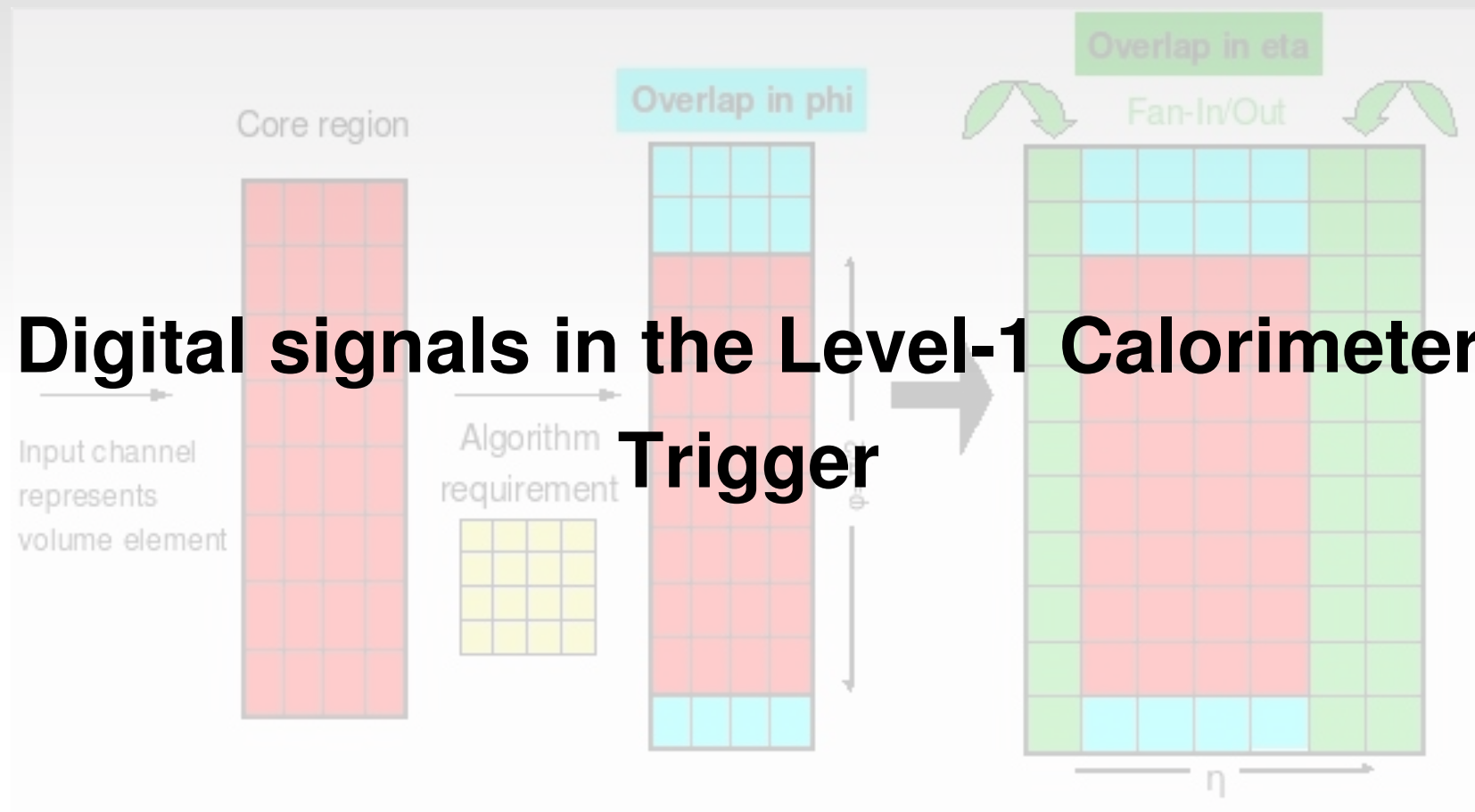


Analogue  
cables

**Complete installation  
in the end of 2007**



# Digital signals in the Level-1 Calorimeter Trigger





# Challenges on data treatment

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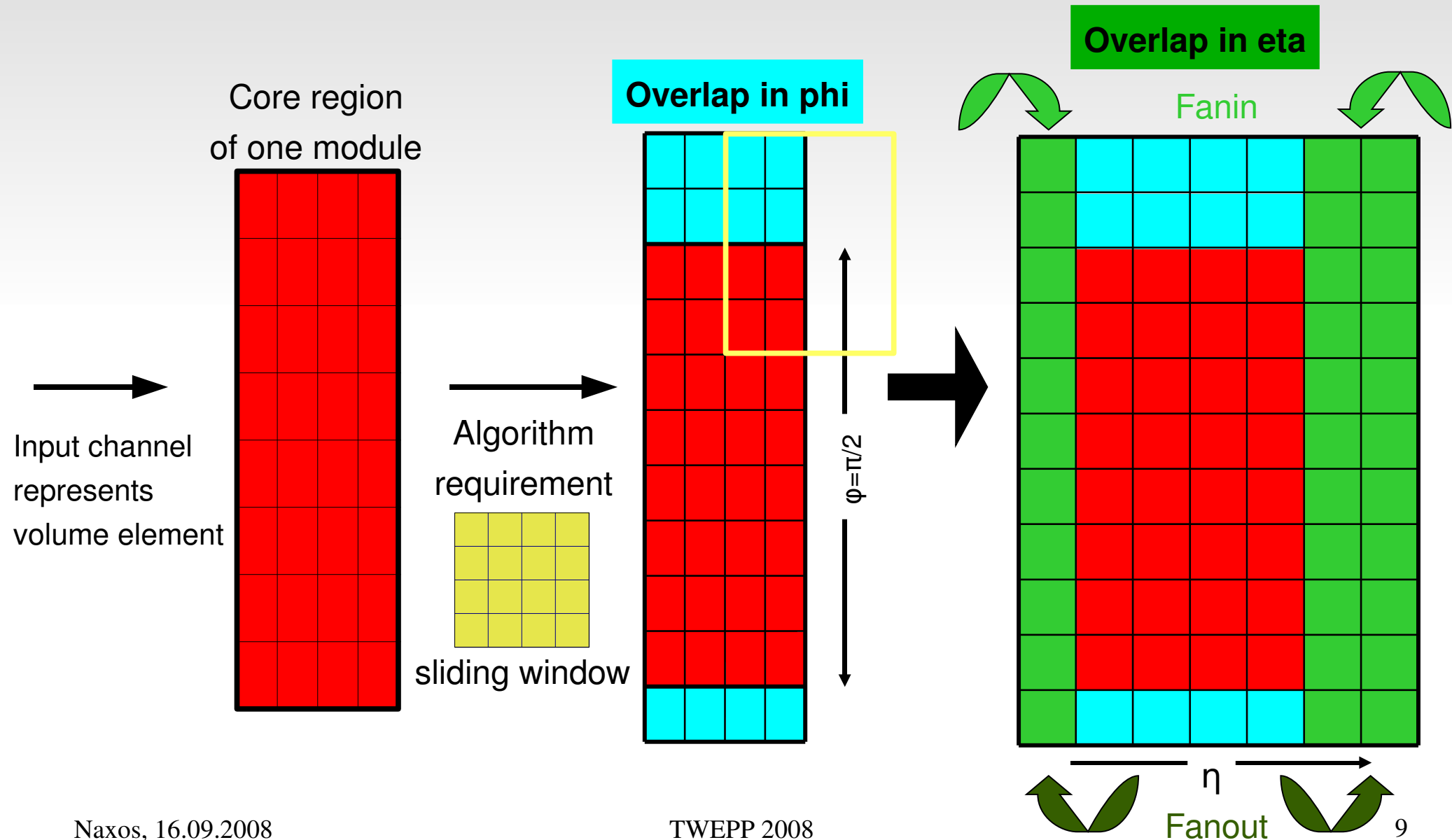
- Two in parallel working processor systems working with 40 MHz bunch clock rate need:
  - more than 1800 serial cables
  - 22000 backplane connectors in each crate
  - more than 350 optical fibres
- Latency in Calorimeter trigger under  $1 \mu\text{s}$
- Time is consumed:
  - signal treatment and conversion
  - in each process/algorithm
  - every transmission

Timing is crucial for performance of system

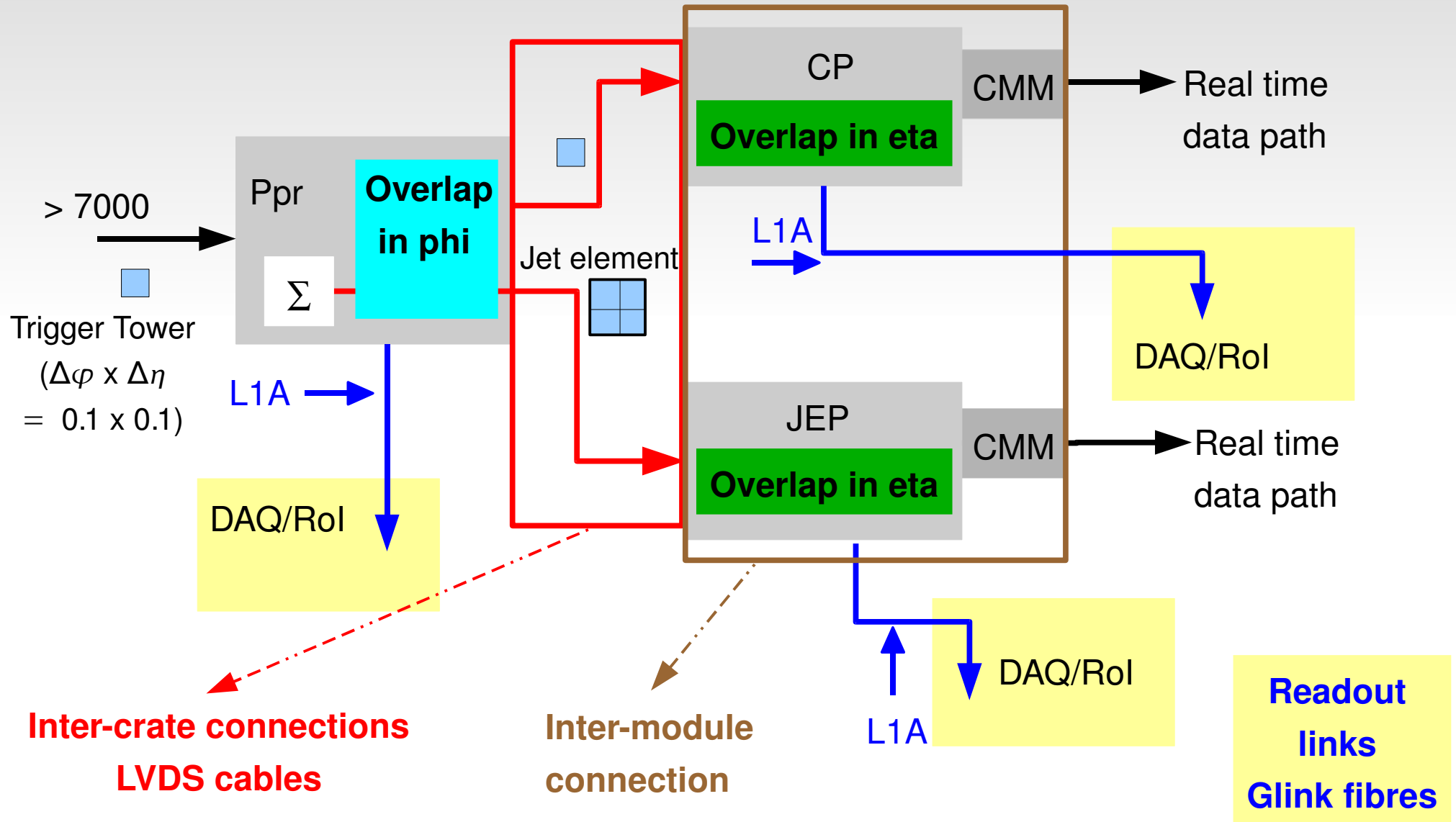


# Processor data environment

Example of JEP system: (CP is similar) for jet, e/ $\gamma$  and tau algorithm



# Digital signals

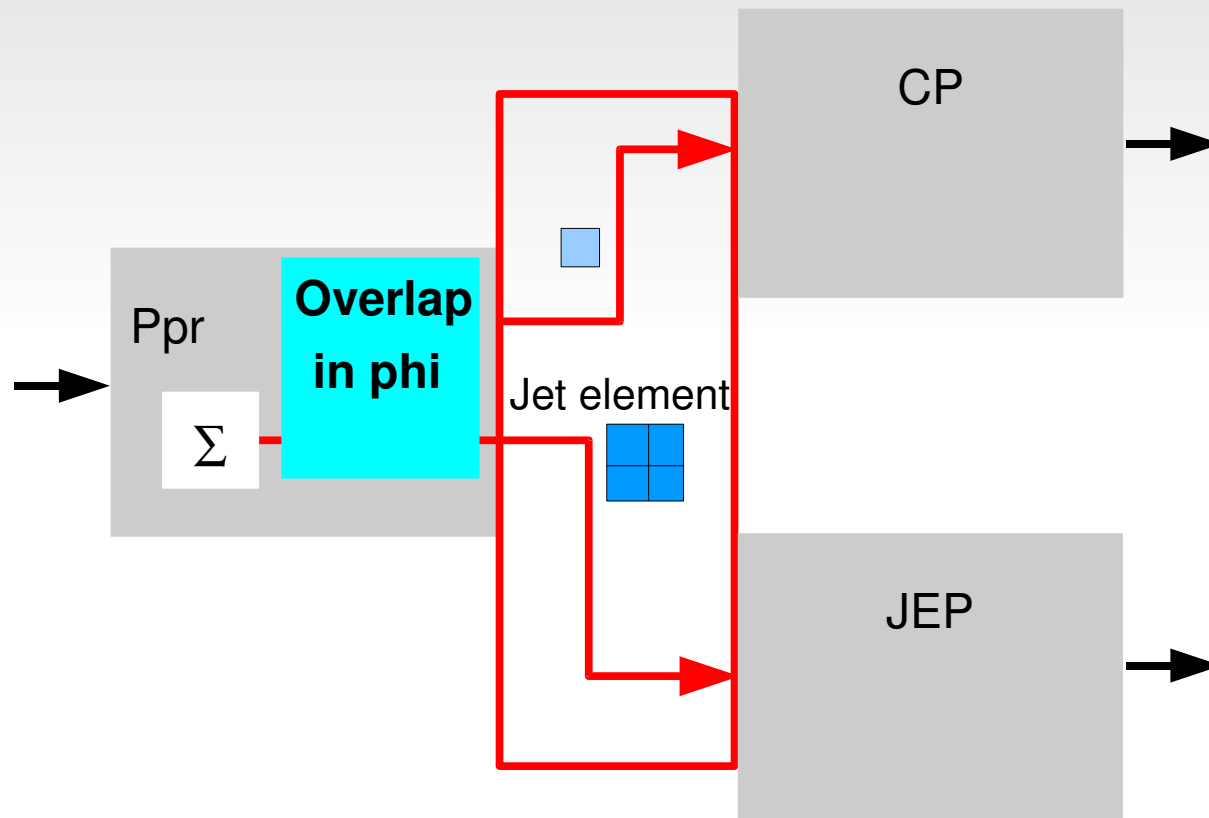


# Timing issues

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- Real time path timing:
  - input data for each processor (input timing scan)
  - sharing data between neighbouring modules (Fanin/Fanout timing scan)
  - connection of merger modules through backplane and cable links (JEP/CP-CMM, CMM-CMM, CMM-CTP) (parity errors)
- Readout timing:
  - settings for readout pointers for every processing stage (alignment of data)

# Inter-crate connectivity



# Inter-crate connectivity

- established through serial links (LVDS cables 400 Mb/s)
- transmission of the trigger towers (8-bit digitized transverse energy from PPr to CP) and jet elements (2x2 sums of trigger towers from PPr to JEP)
- timing for all input data is required



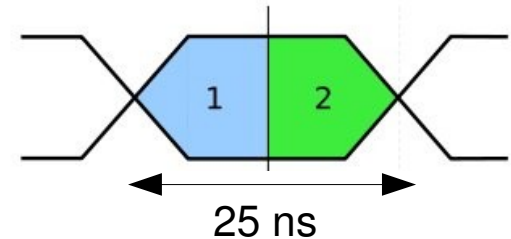
# Inter-crate connectivity

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- Testing of connectivity:
  - firmware integrated status of link
  - firmware integrated parity error counters
  - verifying correct data reception and processing through readout and comparison
  - specific mapping pattern (unique pattern for every channel) checks correct cabling
- This checks on: misconnected cables (very few), hardware problems (cable, source or receiver, backplanes)

# Inter-crate connectivity

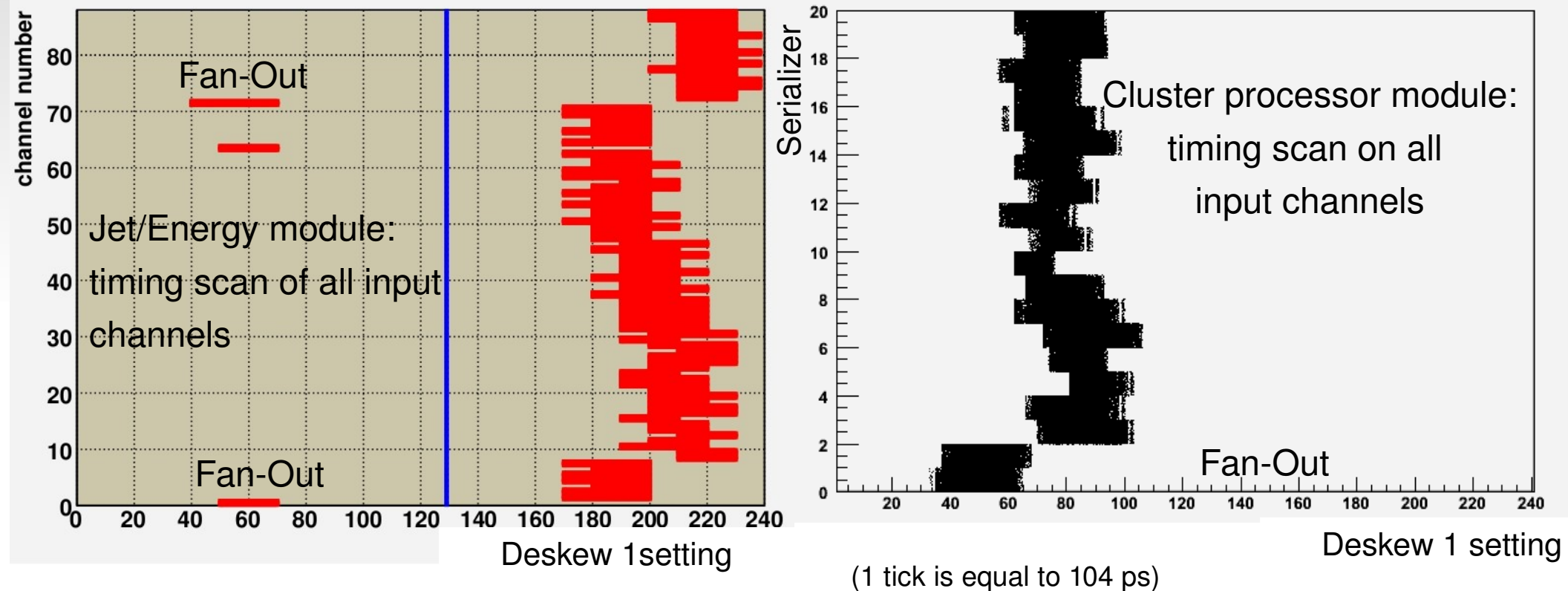
- CP and JEP are driven by 2 Deskew clocks derived from the overall bunch clock timing (40.08 MHz): Deskew 1 + 2 (240 steps of 104 ps)
  - Deskew 1: global timing responsible for input timing
  - Deskew 2: time setting for processing shared data in eta for jet,  $e/\gamma$  and tau algorithm
- Adjusting input timing by:
  - 2 phases (through parity errors)
  - delay (analysing synchronous data pattern)





# Inter-crate connectivity

Input signal speed 400 Mb/s



→ good time margin 15 out of 25 ns

- phase with less errors is chosen
- delay aligns all channels

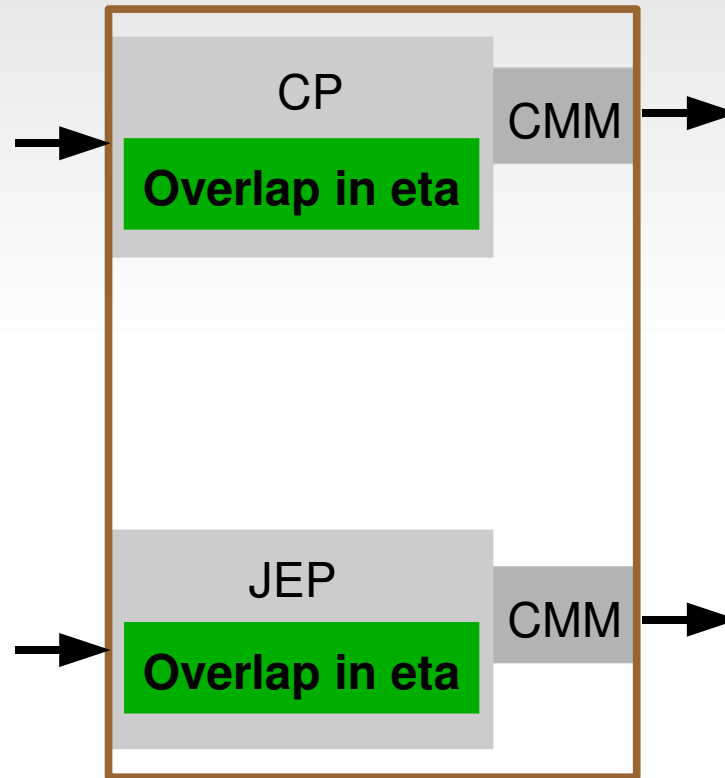
# Inter-crate connectivity

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- Input calibration needs valid data
- Problems which occurred:
  - link loss and parity errors on processor modules (only a very few)
  - defective source modules (a few)
  - found misconnected cable (about 0.5 %)
- Problems are all corrected

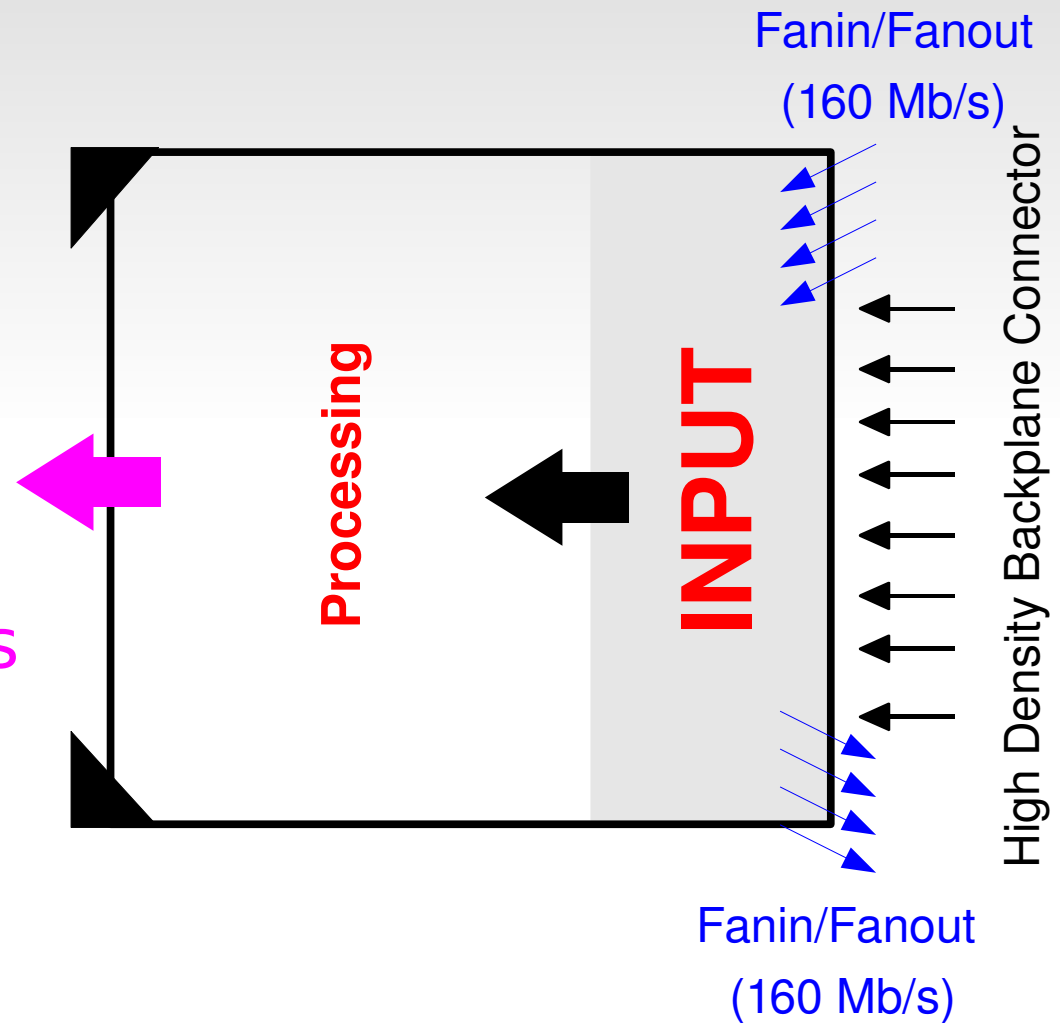
# Inter-module connectivity

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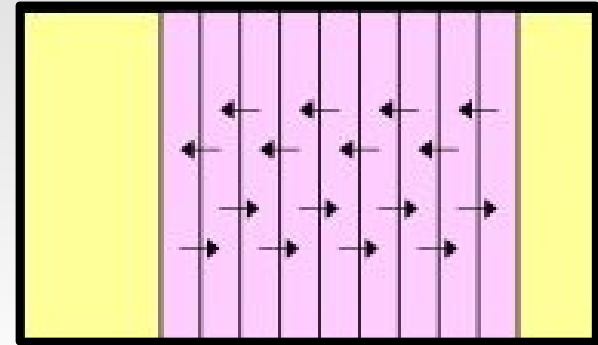
# Module Design

- many FPGAs for processing data
- connectivity:
  - Backplane input: 400 Mb/s
  - Fanin/Fanout: 160 Mb/s
  - Readout links: 800 Mb/s
- implemented diagnostic memories



# Inter-module connectivity

- Transmission is handled by dense custom backplane
- Overlap needs working backplane pins
- Every processor needs to be timed in separately
- Each module needs individual time calibration constants (dependent on configuration)

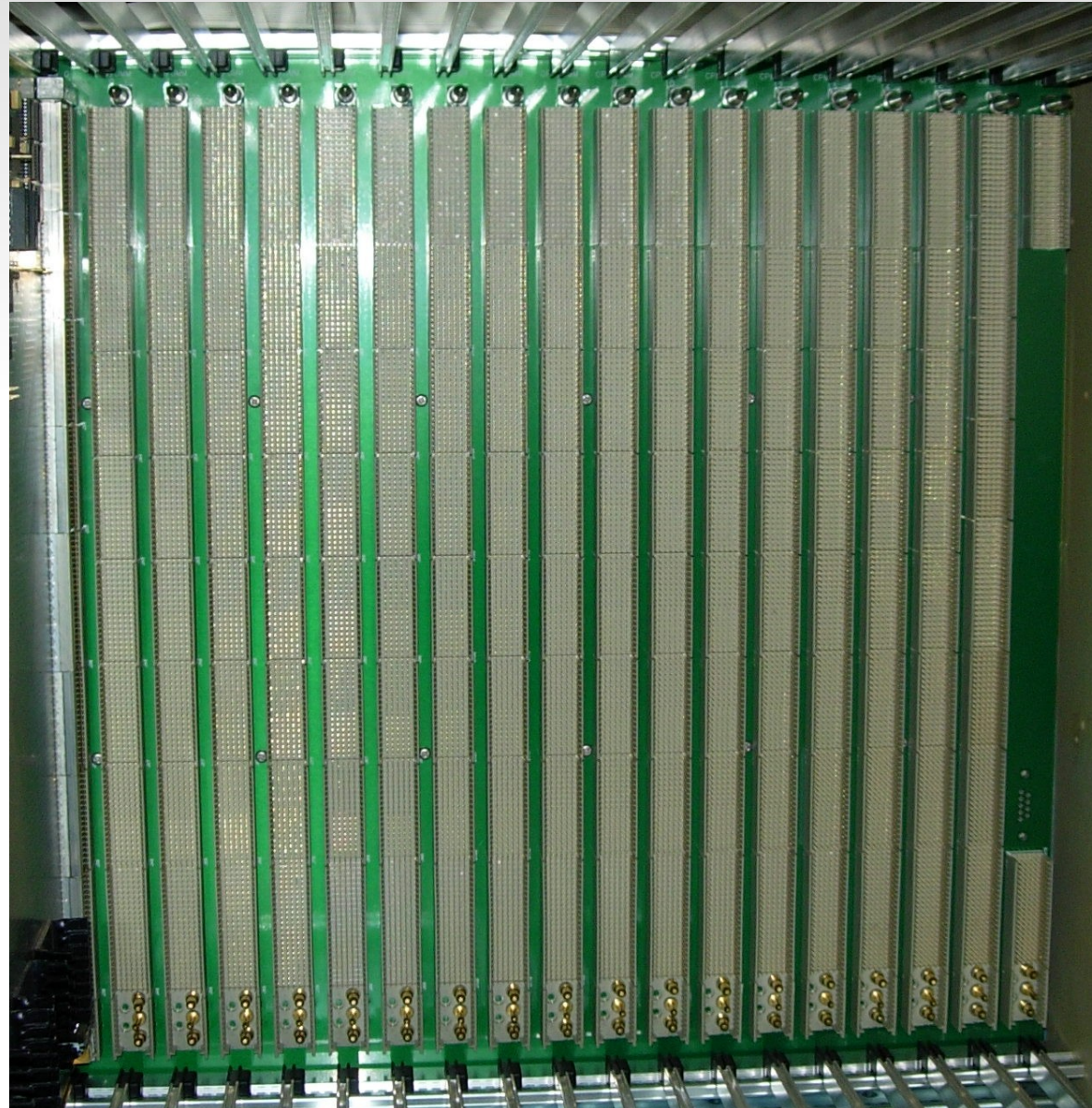


# Picture of a CP/JEP backplane

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Backplane has 22000 pins:

- 1100 pins per slot:
  - 240 pins input data
  - 330 pins fanin/fanout
  - pins between processor and Merger
  - ground pins for cross talk
  - VMEbus
  - CAN data

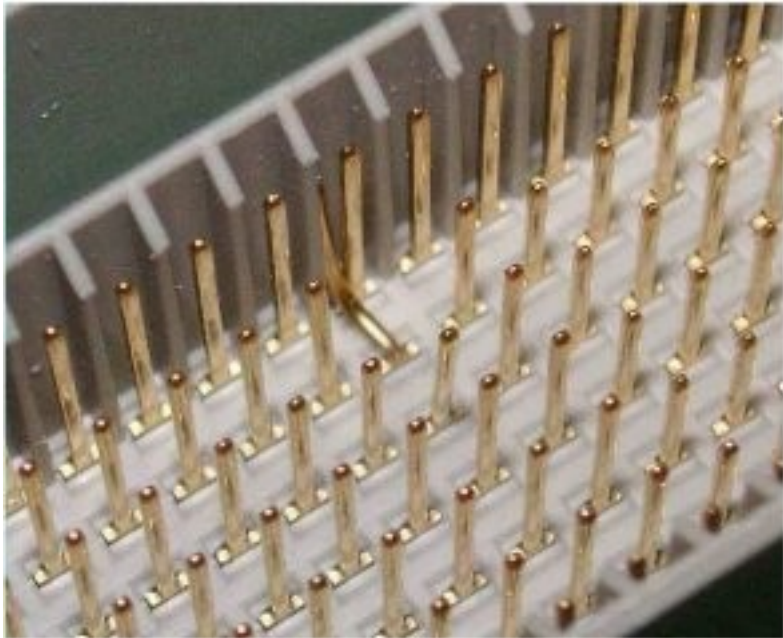




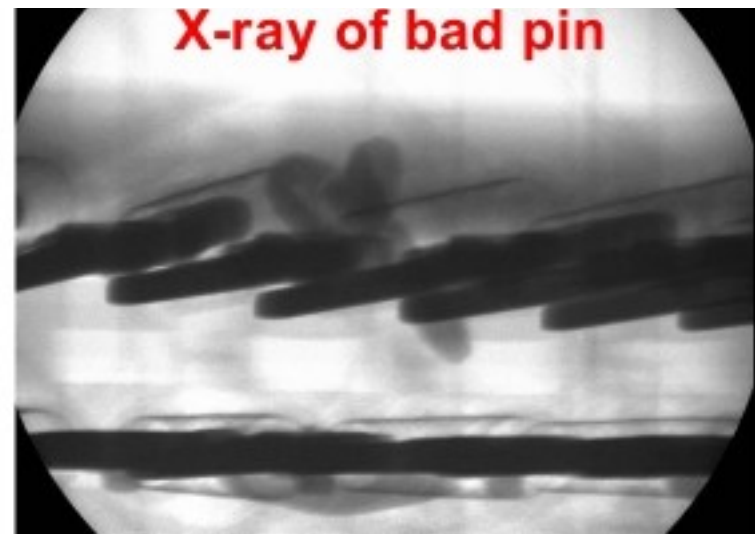
# Hardware problems

- Backplanes had bent pins after production stage or was damaged during usage
- Every backplane was examined by scanning
- Every problem was corrected last year  
(1-2 faults on each backplane)

Bent pin was caused by module insertion



Missing pin: stuck between layers



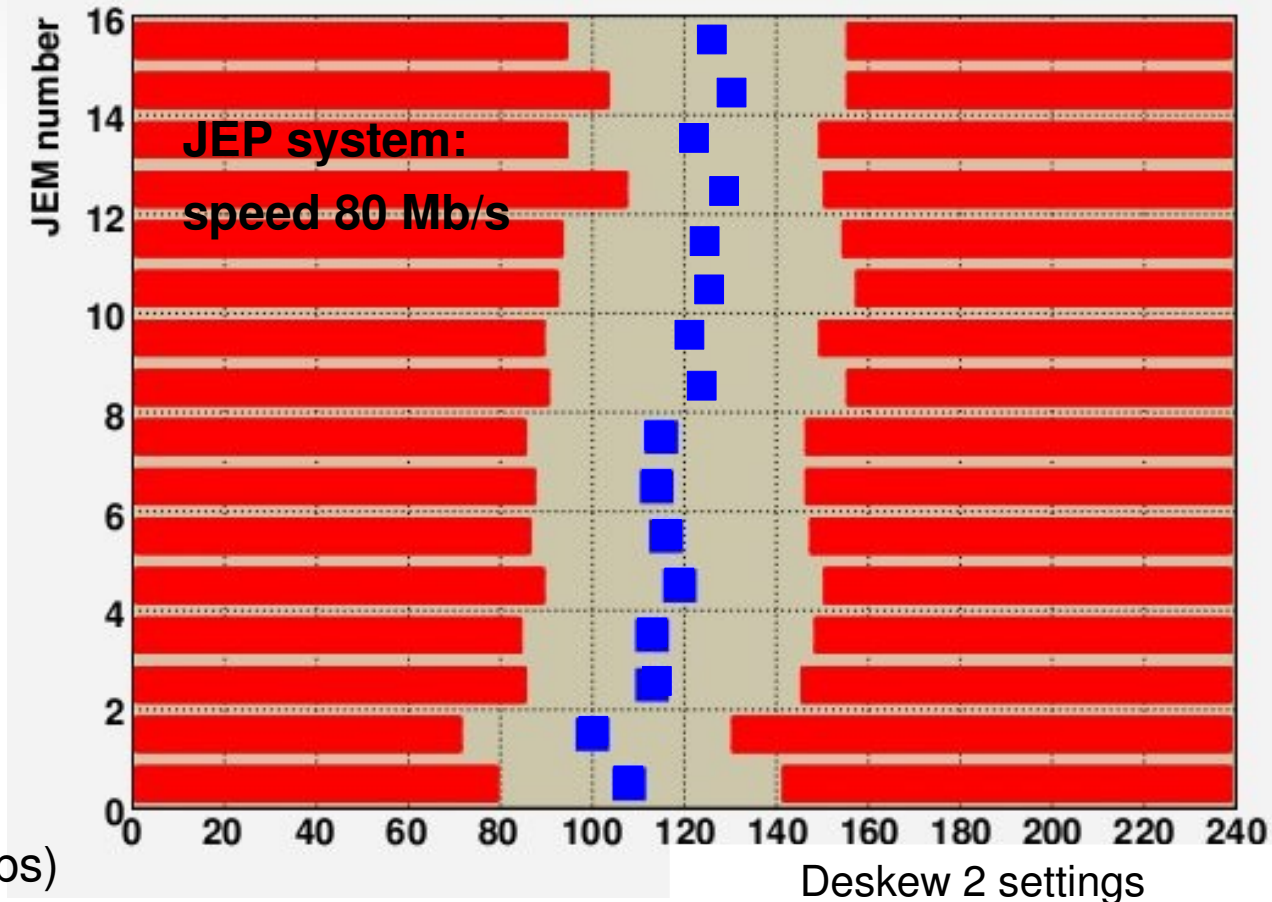


# Inter-module connectivity

- Calibration procedure to determine Deskew 2

Clock for Fanin/Fanout:

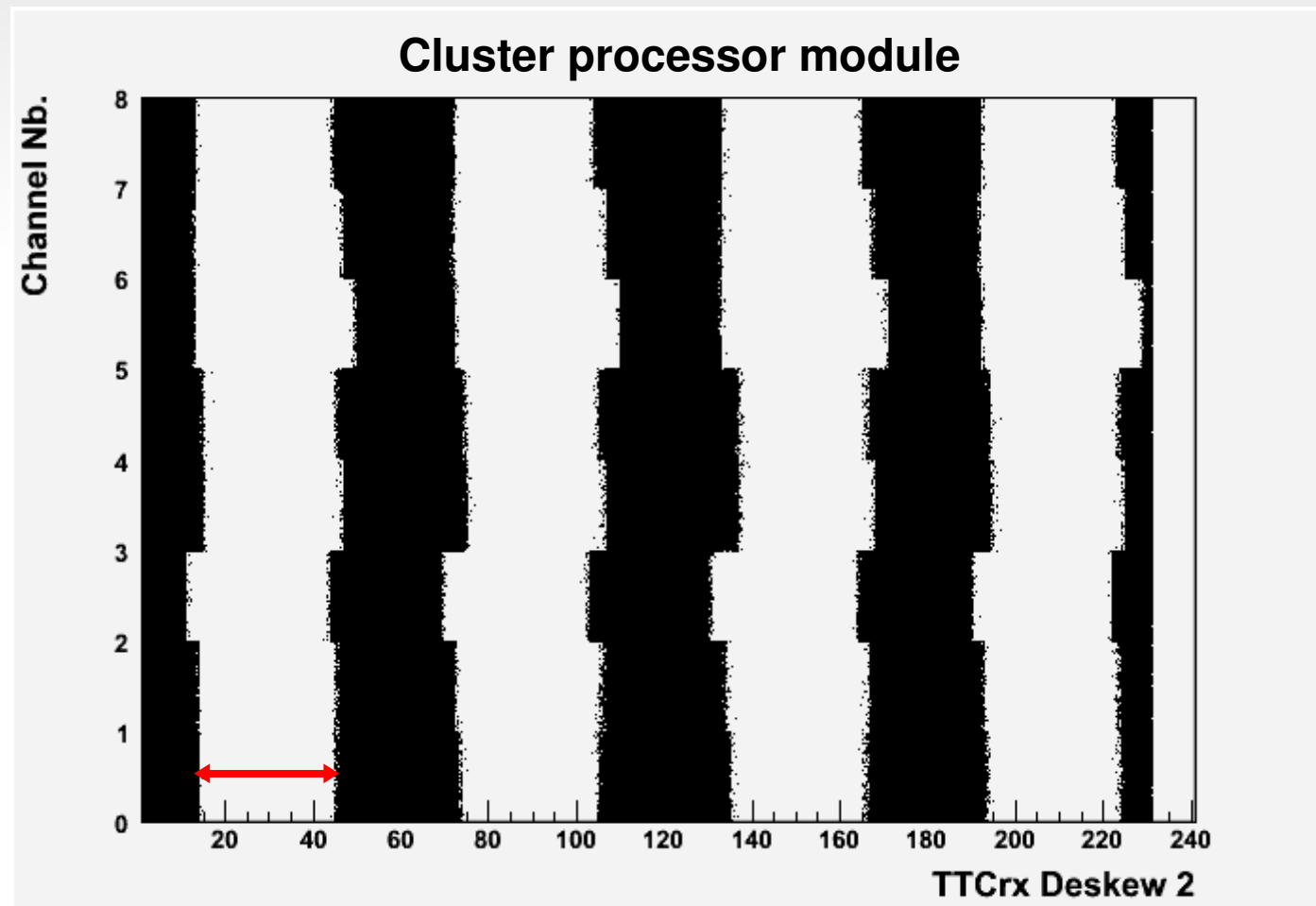
- On input channels 10-bit counter is enabled
- Stepping through time settings
- Parity errors are sampled for each time setting
- Find valid time setting (5-7 ns)



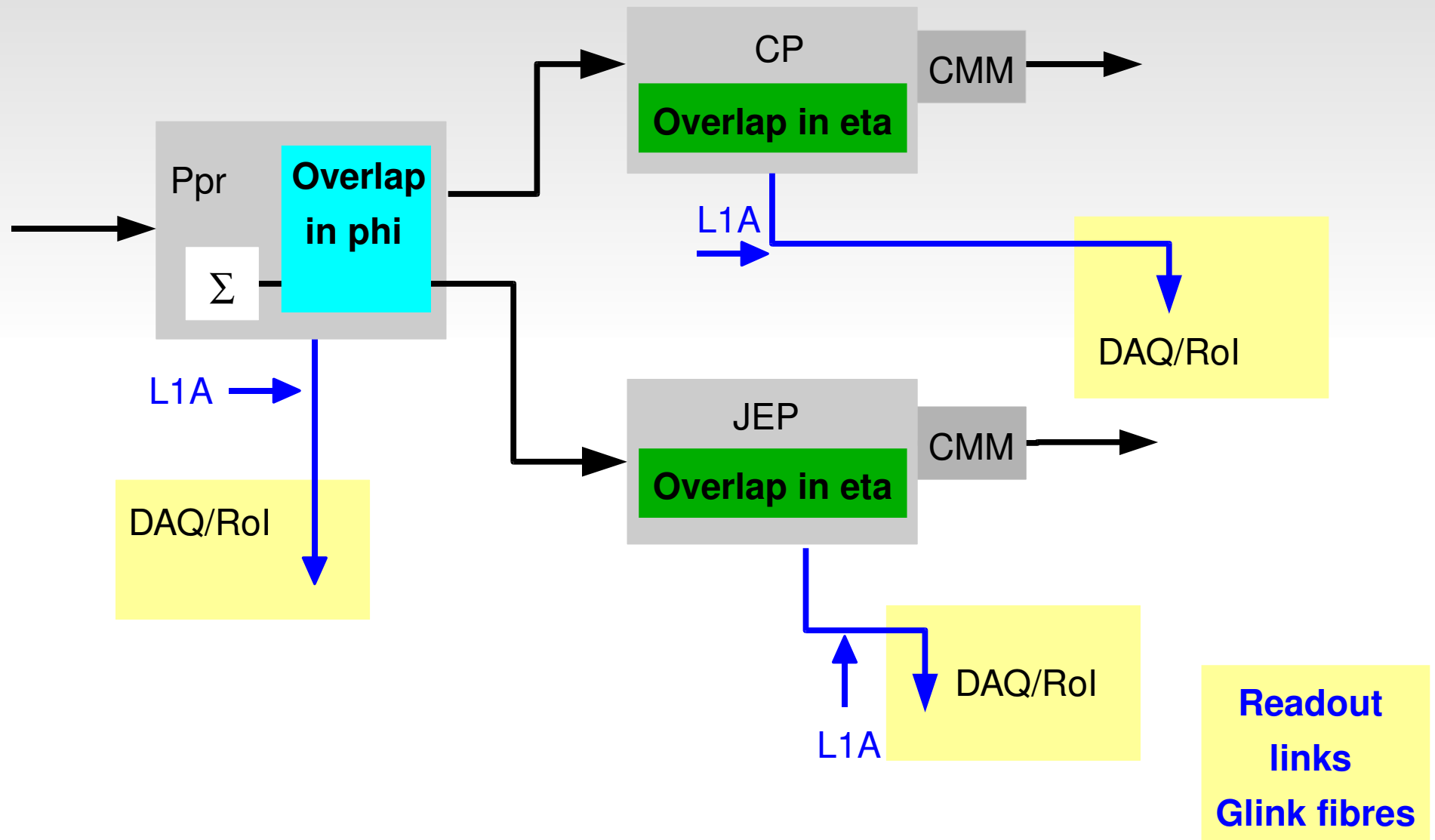
# Inter-module connectivity

- Similar timing procedure in the CP system for signal speed of 160 Mb/s

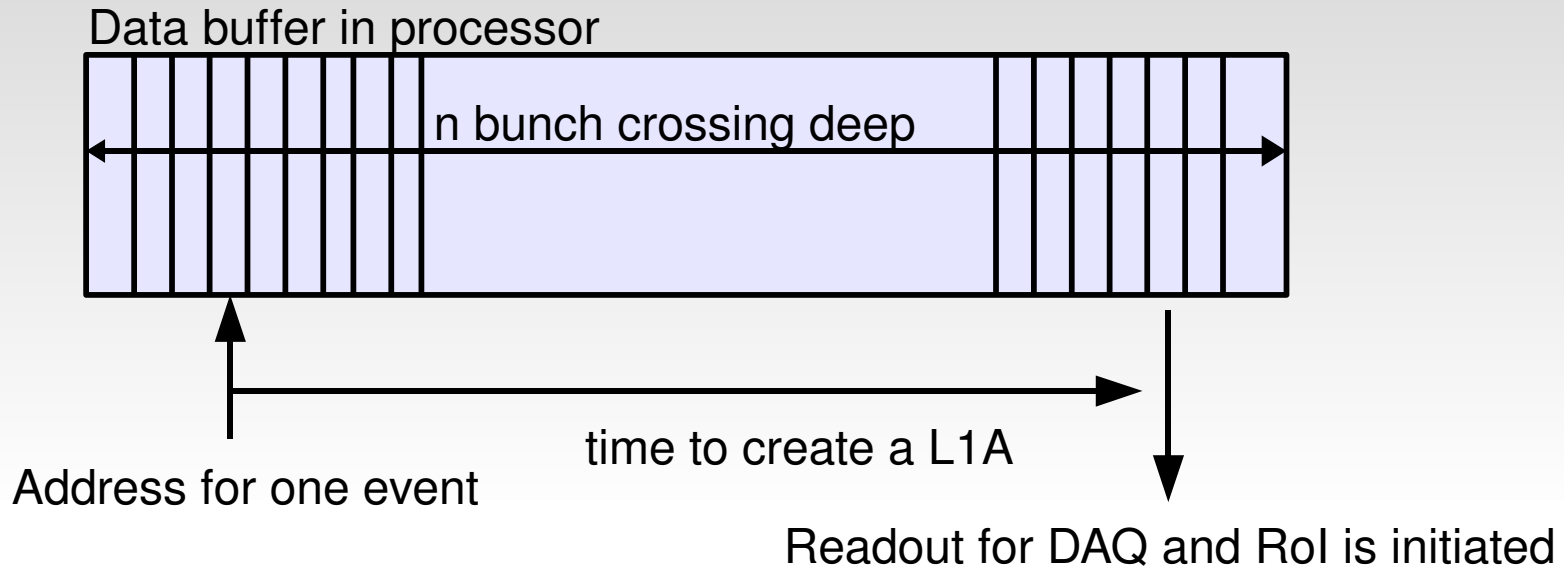
valid data in  
window of  
2-3 ns



# Readout links



# Readout links



- Need to determine readout pointers to fetch the correct event for each subsystem
- Offline analysis of data and its alignment

# Readout links

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- Determining the readout pointers with fake L1A rate in standalone testing
- Only one event has data
- 5 subsequent time slices are read out
- Looking at the DAQ and RoI data in the data stream determines the necessary delays

For example:

Default	0	0	23	0	0
Output	0	23	0	0	0

- Bunch crossing is checked in readout path

Readout tested up to 60 kHz with random triggers and event synchronisation is stable

# Conclusions

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- Installation finished in December 2007
- Signal integrity is proven:
  - Inter-crate connectivity: cabling and processors have been completely tested
  - Inter-module connectivity: backplane connectivity is fully functional
  - Readout links: readout pointers for the system established
- Every subsystem is calibrated with respect to input data and duplicated data
- System is being prepared for taking first data\*

\* Further presentations from Rainer Stamen, Damien Prieur and Murrough Landon