

CMS Tracker Alignment Strategy with Cosmic Muons

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FOR

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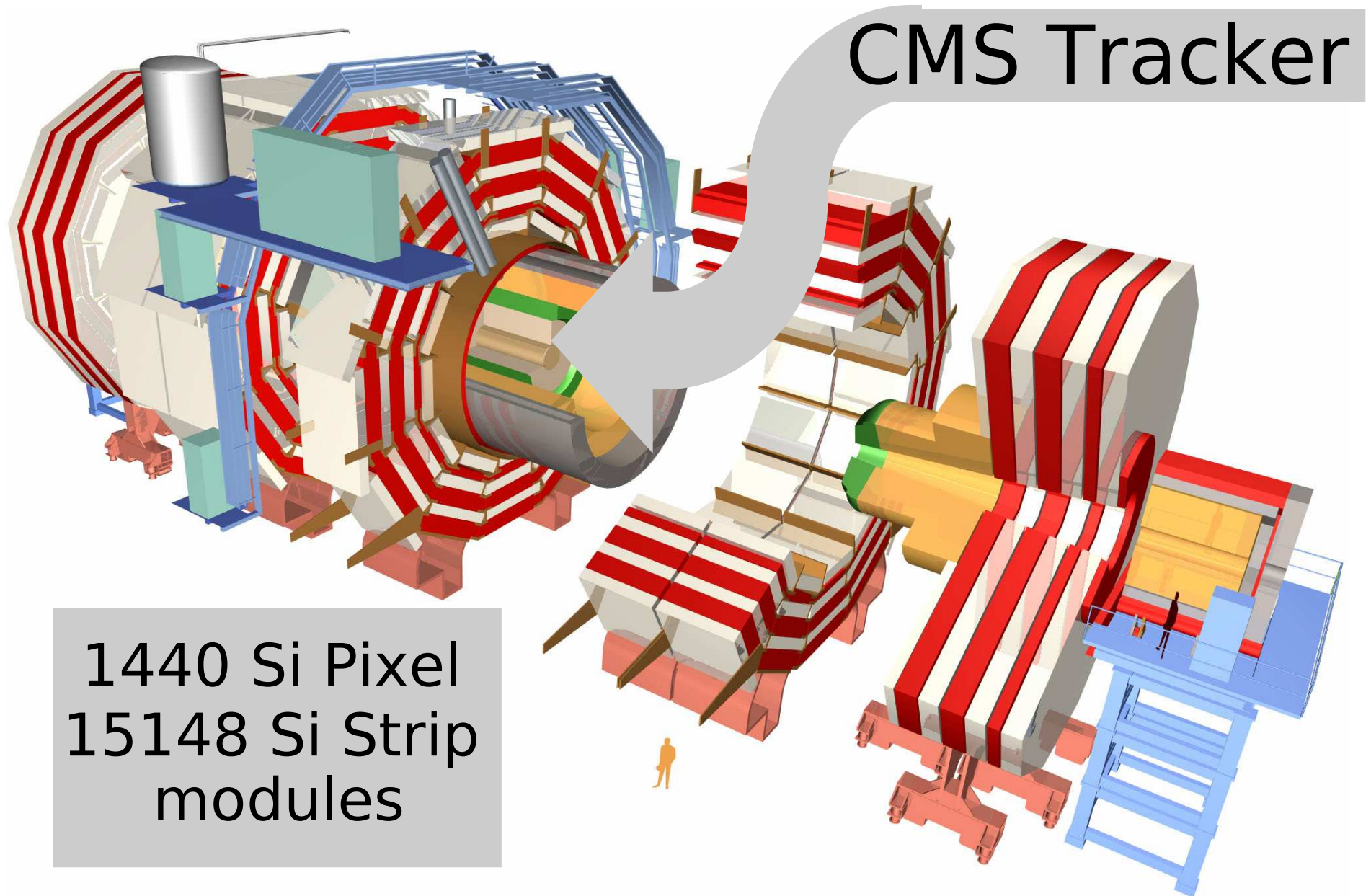


June 15, 2009



3rd LHC Alignment Workshop, CERN, Switzerland

Tracker in the CMS Detector



Outline / Acknowledgment

- Input to CMS Tracker alignment algorithms:
 - Laser Alignment System
 - optical survey
 - tracks from cosmic muon runs \Rightarrow ultimate precision

Tracker Integration Facility (TIF) with partial Tracker in 2007

CMS at Point-5 (“CRAFT” cosmic run) with full Tracker in 2008

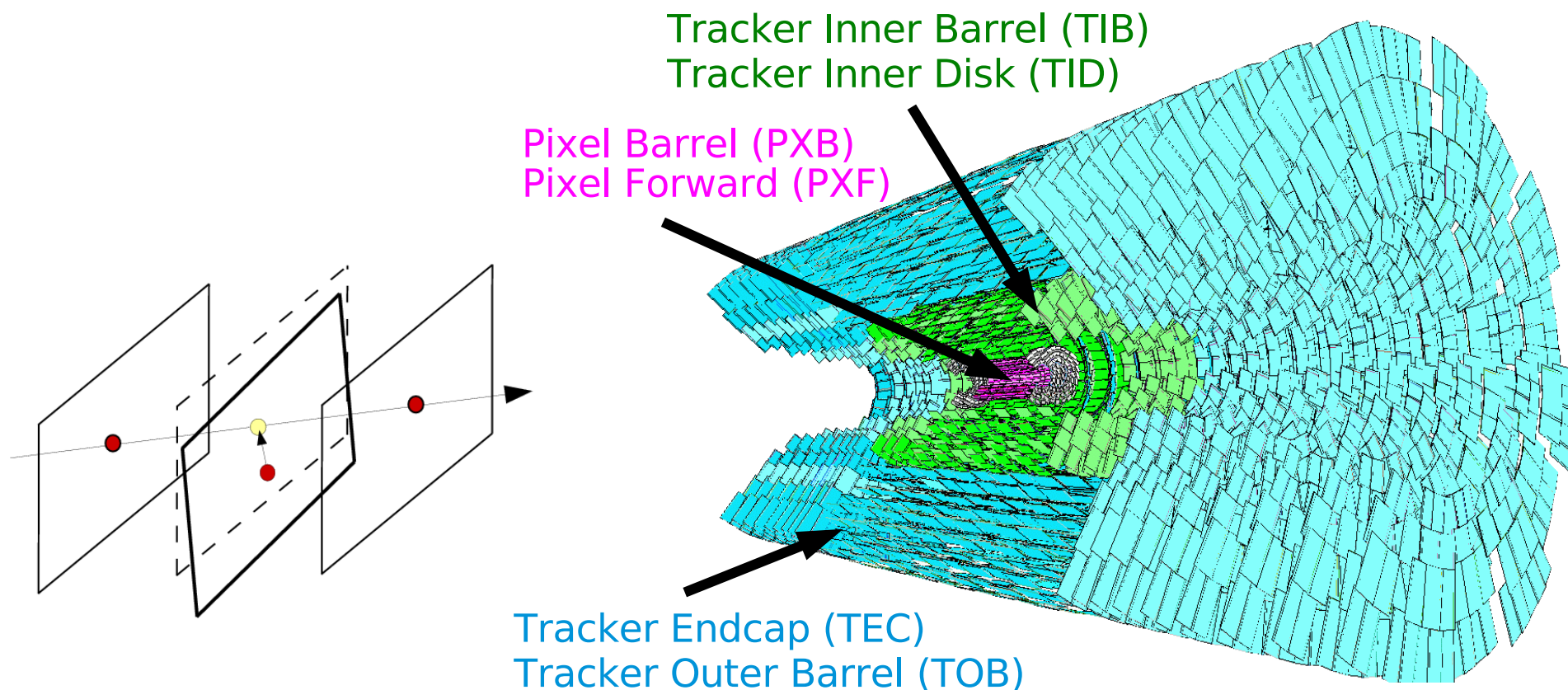
- Detailed results in the next talk (by E. Migliore)
- Alignment is a big project, but only the final step in commissioning



part of the CMS tracker alignment team “on the ground”

CMS Tracker Alignment Goal

- Alignment goal: **nail down** (few μm) all **16,588** modules ($\times 6$ dof)

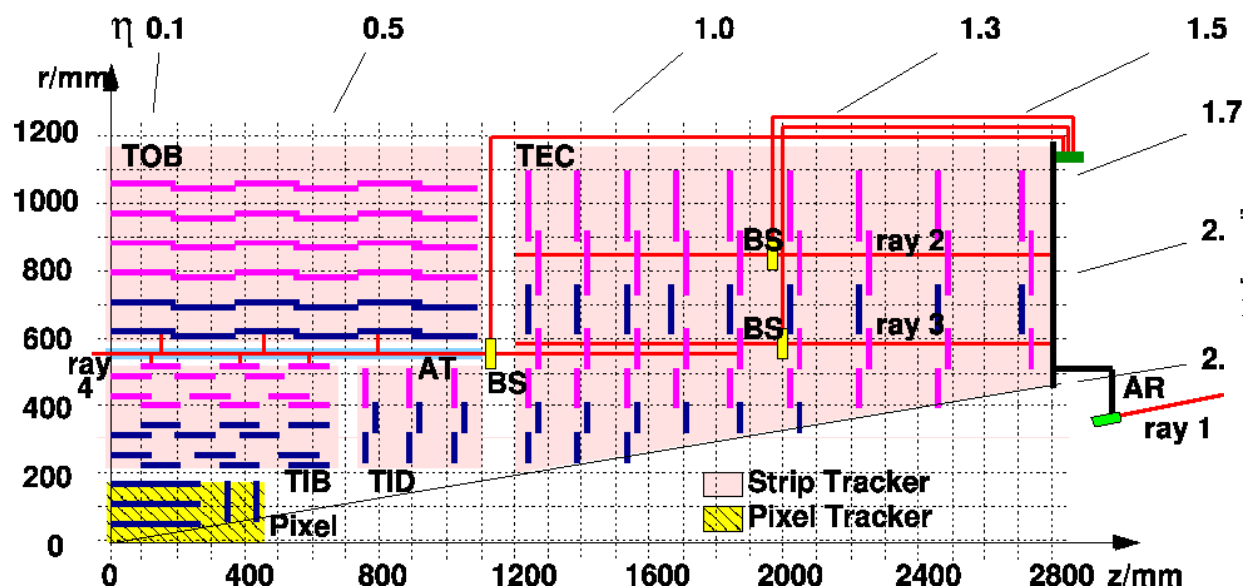


- Minimize **residuals**

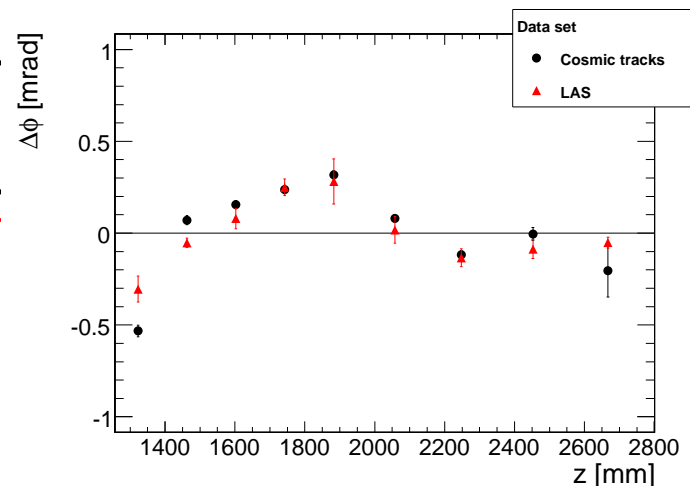
$$\chi^2(\mathbf{p}_{\text{modules}}, \mathbf{q}_{\text{tracks}}) = \sum_{i=1}^{N_{\text{residuals}}} \mathbf{r}_i^T \mathbf{V}_i^{-1} \mathbf{r}_i$$

Laser Alignment System (LAS)

- See talk at [2nd LHC alignment workshop](#) (June 2007):
B. Wittmer “The Laser Alignment System of the CMS Tracker”
- Connect large structures (8 sectors in ϕ): TIB - TOB - TEC
- Cosmic runs for commissioning: standalone $\sim 100\mu\text{m}$, relative $\sim 20\mu\text{m}$
- Tracker geometry: note 2D (100 mrad strip angle) and 1D modules



- LAS vs. Track-based ϕ of TEC disks



Optical Survey of CMS Tracker

- See talk at [2nd LHC alignment workshop](#) (June 2007):
A.G. “First CMS Alignment Geometry: Survey Data and Their Implementation”

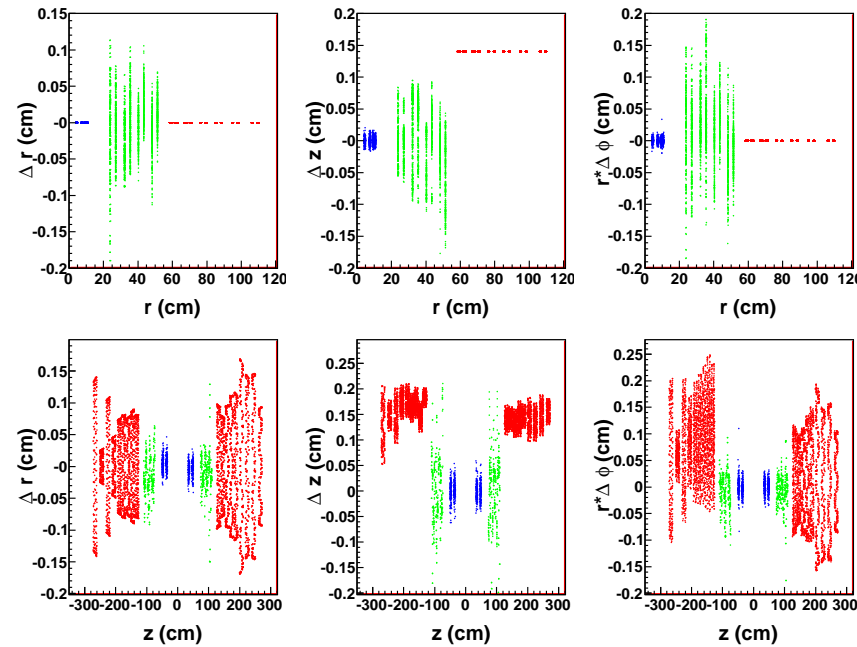
Barrels:

PXB - modules (2D only)
TIB - modules and up
TOB - barrel

Endcaps:

PXF - modules and up
TID - modules and up
TEC - disks and endcap

survey vs. design geometry



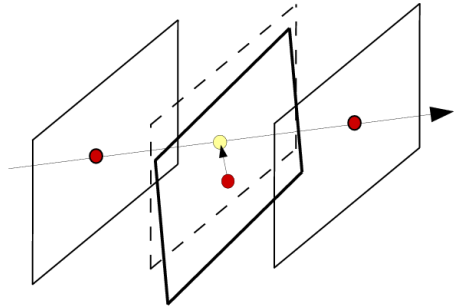
- Tracks + **Survey** in “local algorithm”, to constrain all 6 dof:

$$\chi^2_{\text{module}} = \sum_i^{\text{hits}} r_i^T(\mathbf{p}_m) \mathbf{V}_i^{-1} r_i(\mathbf{p}_m) + \sum_j^{\text{survey}} r_{*j}^T(\mathbf{p}_m) \mathbf{V}_{*j}^{-1} r_{*j}(\mathbf{p}_m)$$

following *BABAR* implementation: [arXiv:0809.3823](#)

Statistical Methods in CMS Tracker Alignment

- Local iterative method (“Hits & Impact Points”) CMS-NOTE-2006/018



$$\mathbf{p}_m = \left[\sum_i \mathbf{J}_i^T \mathbf{V}_i^{-1} \mathbf{J}_i \right]^{-1} \left[\sum_i \mathbf{J}_i^T \mathbf{V}_i^{-1} \mathbf{r}_i \right]$$

pros	full Kalman Filter track model	simple implementation, all dof
cons	ignore correlations in one iteration	large CPU with many iterations

- Global method (“Millepede II”) NIM A 566, 5 (2006), talk by V. Blobel

$$\chi^2(\mathbf{p}, \mathbf{q}) = \sum_j^{\text{tracks}} \sum_i^{\text{hits}} \frac{(y_{ji} - f_{ji}(\mathbf{p}, \mathbf{q}_j))^2}{\sigma_{ji}^2}$$

CMS implementation

pros	model module correlations	less CPU with one or few iterations
cons	simple helix trajectory model	large matrix may limit N parameters

- Kalman filter algorithm with MC and TIF data: see talk by E. Widl

Tracker Alignment at Integration Facility

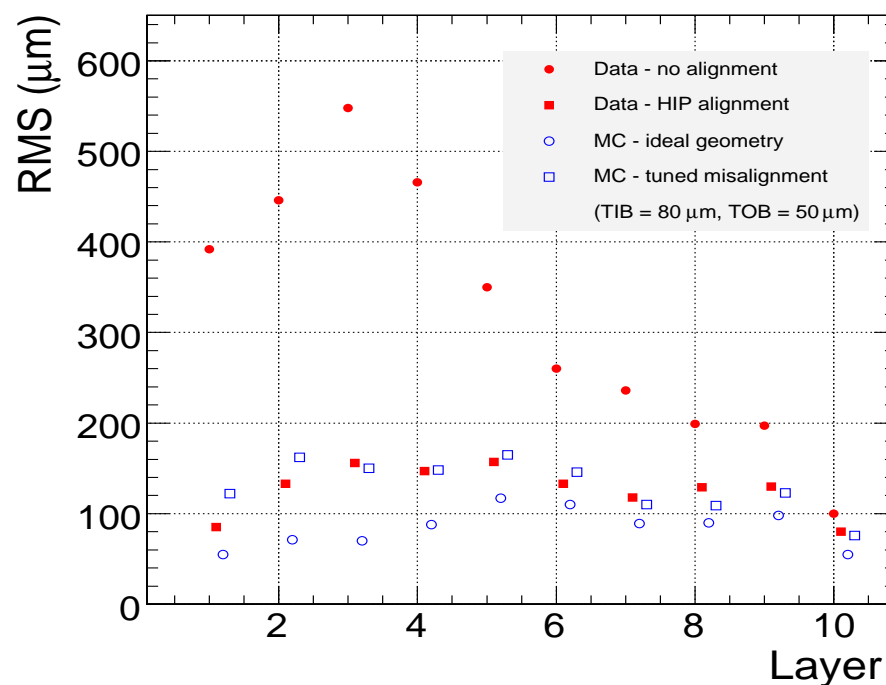
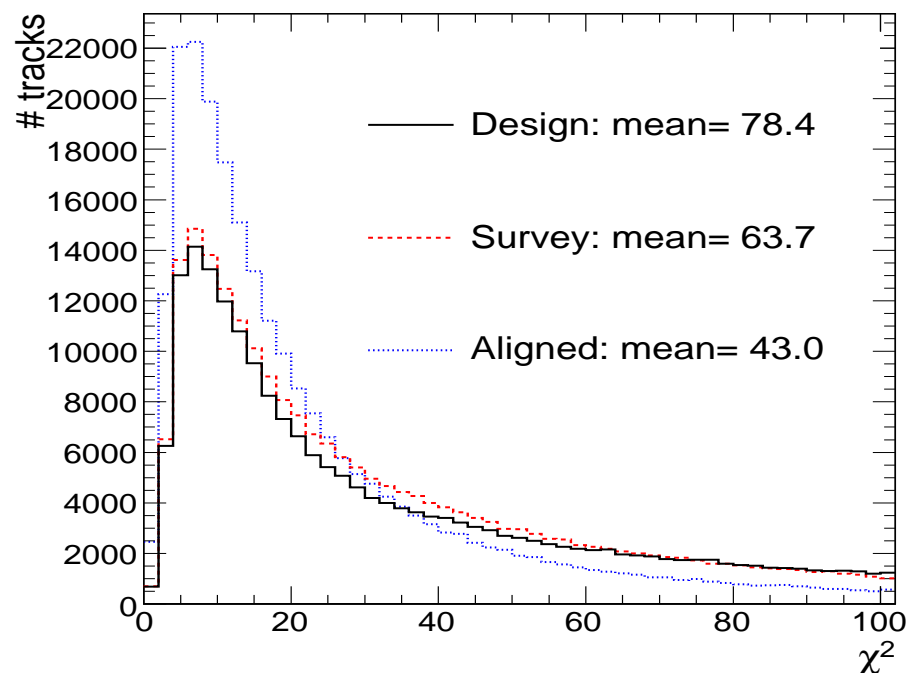
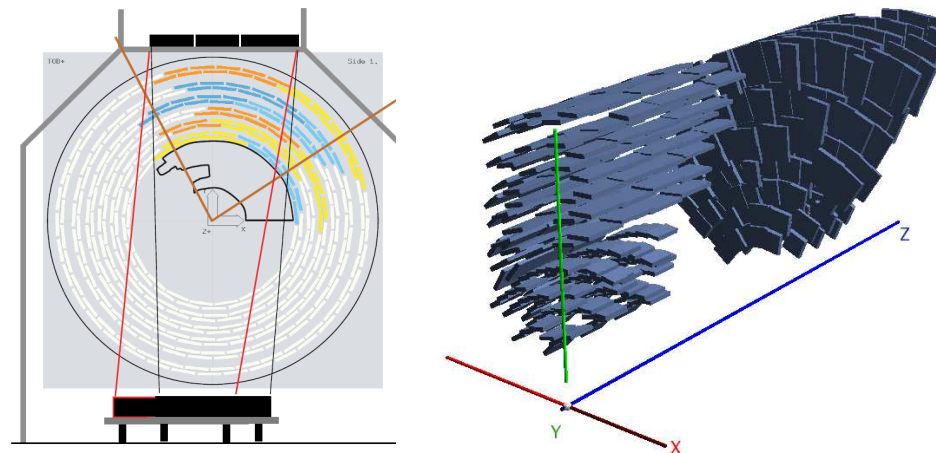
- First integrated tracker: **spring-summer 2007** [arXiv:0904.1220](https://arxiv.org/abs/0904.1220)

$\sim 15\%$ of **strip tracker** only
no B-field, assume $p = 1 \text{ GeV}/c$

\Rightarrow **multiple scattering**

cannot be predicted per event

- Reach $\sim 50/80 \mu\text{m}$ in TOB/TIB



Alignment at Point-5 without Magnetic Field

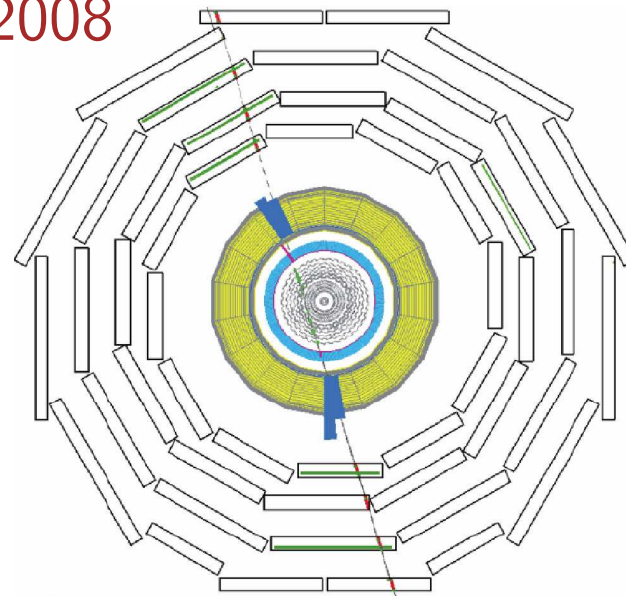
- First experience with **full Tracker**: summer 2008

~**600k cosmic tracks** for Tracker alignment
still **no B-field**

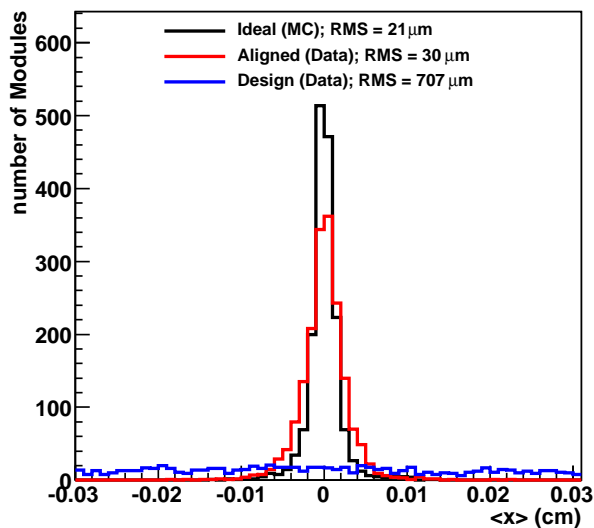
- Achieved ~**30-40 μm** in TIB/TOB
low statistics in Pixels and Endcaps

- Measure of alignment precision

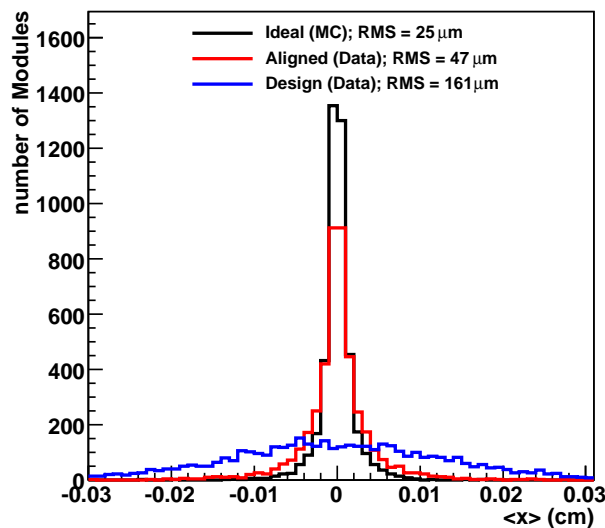
Distribution of **M**ean of the **R**esiduals (“**DMR**”, more later)



Distribution of mean of residuals for TIB

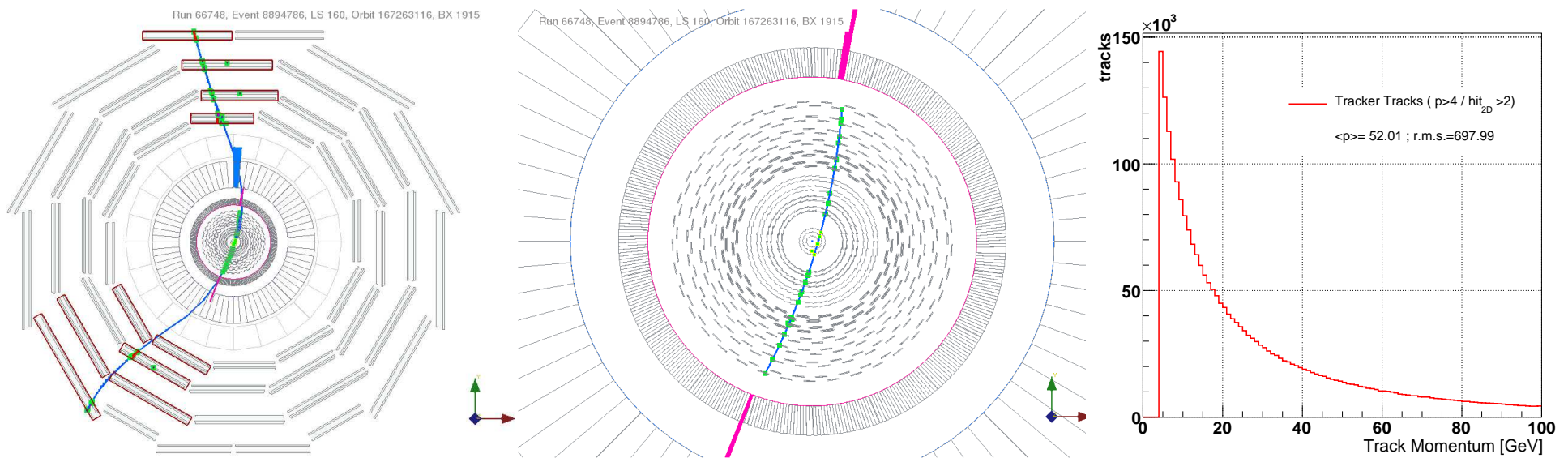


Distribution of mean of residuals for TOB



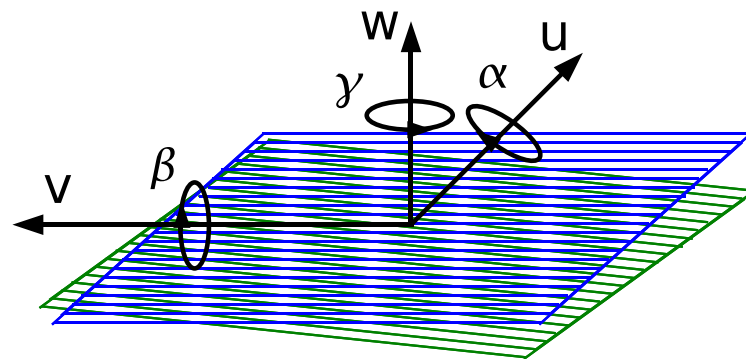
Alignment at Point-5 with Magnetic Field

- Best data for alignment of CMS Tracker: **fall 2008** (“**CRAFT**”)
 - ~ **4M cosmic tracks** for Tracker alignment
 - B-field = 3.8T** \Rightarrow account for **multiple scattering**, $p > 4 \text{ GeV}/c$
- Require good quality tracks and hits:
 - clean** hits, **outlier** hit rejection, χ^2 cut, **min** hits, **2D** hits
 - accept all good tracks (statistics limited): only **3%+1.5%** in **Pixels**



Alignment Strategy during “CRAFT”

- Multi-step approach by both algorithms to address CMS geometry:
 - large **structure** movement: coherent v alignment of 1D modules
 - alignment of two sides of 2D strip **modules** (**units**): u, w, γ

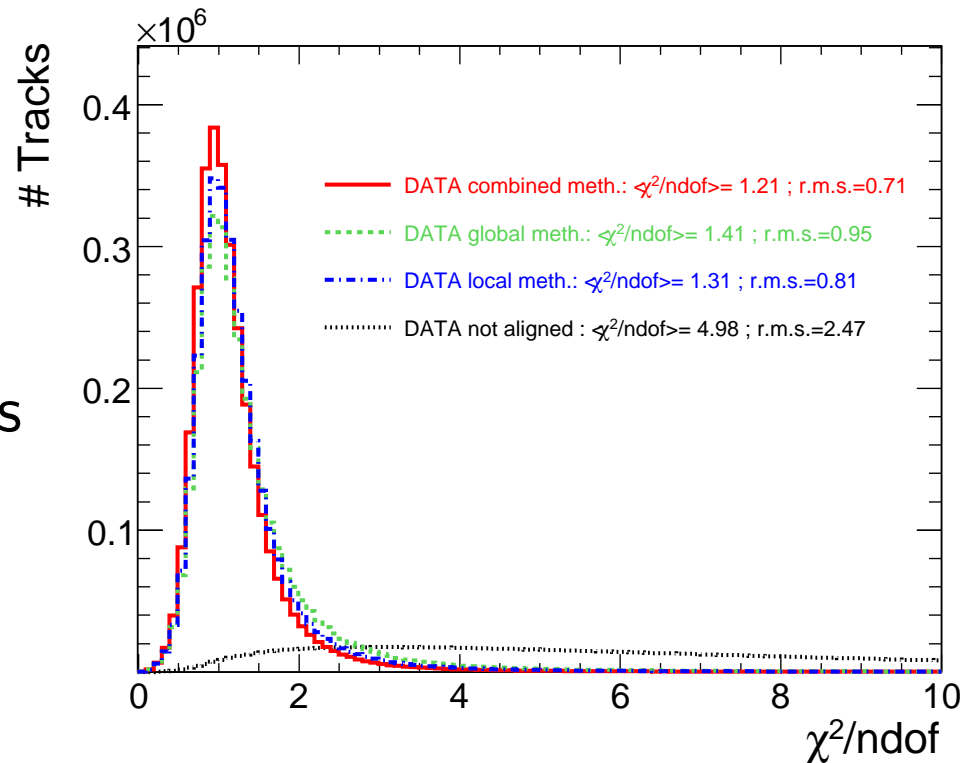


- Global method: 3 steps from “design”
 - (1) large **structures** (6 dof) & **units** (3 dof)
 - (2) **module** alignment: add α, β for TIB; 6 dof for PXB
 - (3) repeat (1); note above: keep $< 46,300$ parameters, use pre-sigma
- Local method: 5 steps from survey; ~ 50 iterations each
 - (1) large **structures** (u, v, w, γ)
 - (2),(3) Strip: **modules** (6 dof) with survey; **units** (3 dof)
 - (4),(5) Pixels: **ladders** (6 dof); **modules** (6 dof)

Alignment Strategy: Merging Algorithms

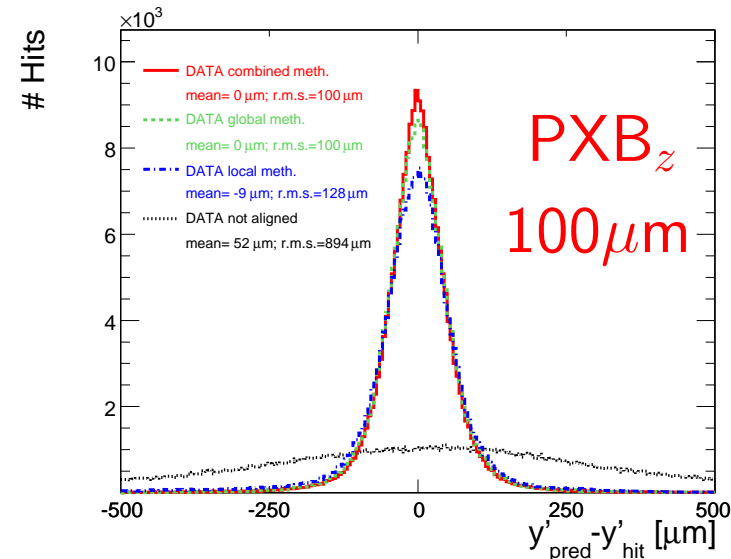
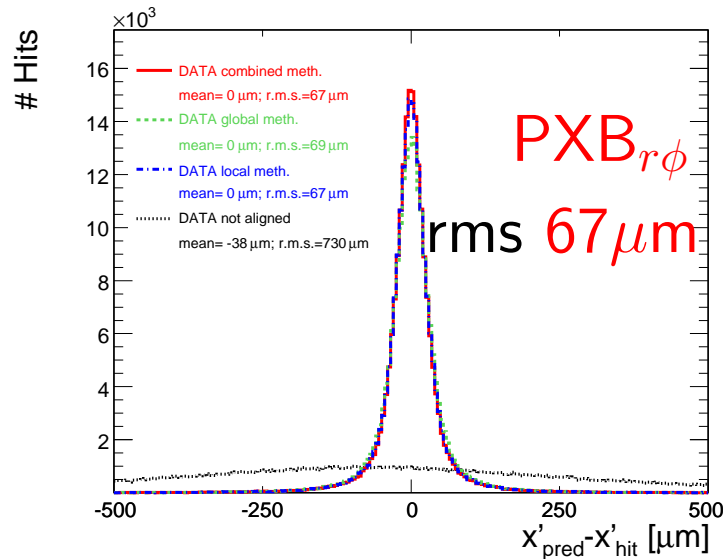
- Combined method
 - (1) run **global** method \Rightarrow **solve global correlations** efficiently
 - (2) run **local** method \Rightarrow **solve locally** to match track model in all dof
- All three results are compatible, but **combined** is the best also compare to “not aligned”

Alignment Position Errors
(APE) set for **combined**
see next talk

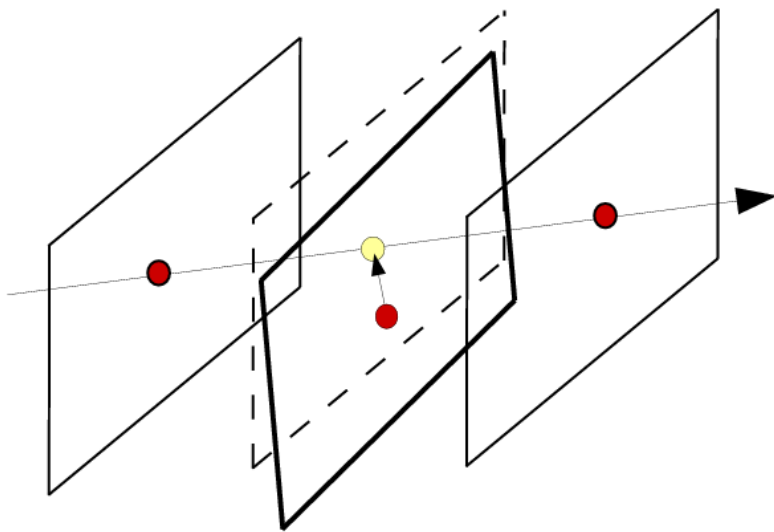


- Reference system: **center-of-gravity** and **rotation** move to design

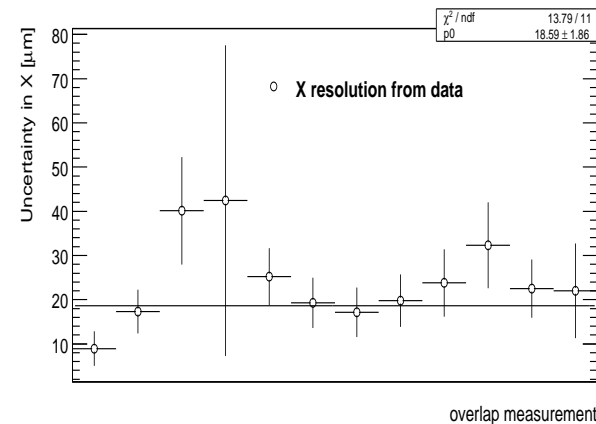
Example: Pixel Residuals (local, global, combined)



- Residuals \Leftarrow multiple scattering (random) + hit errors (random) + alignment errors (systematic)

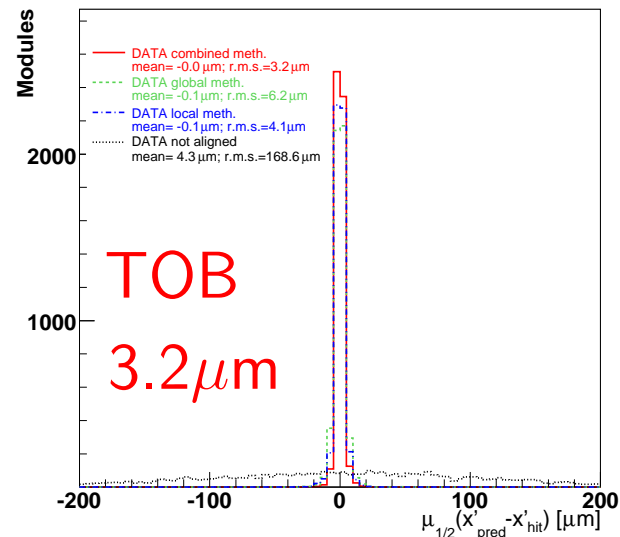
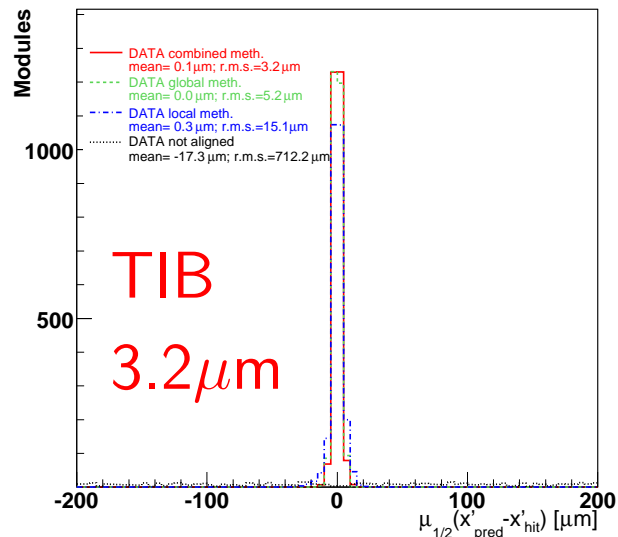
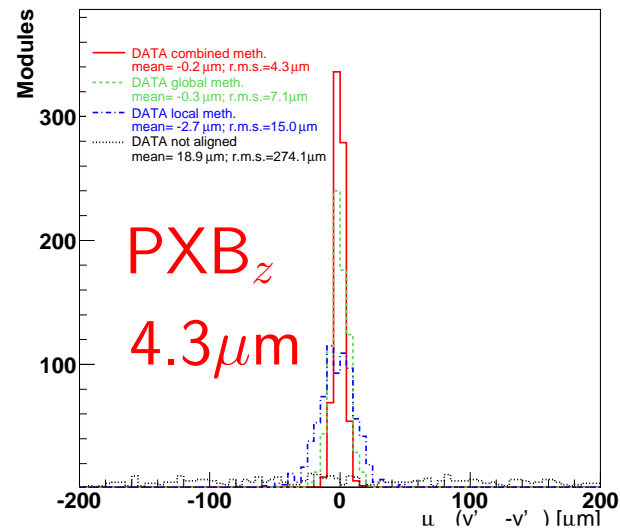
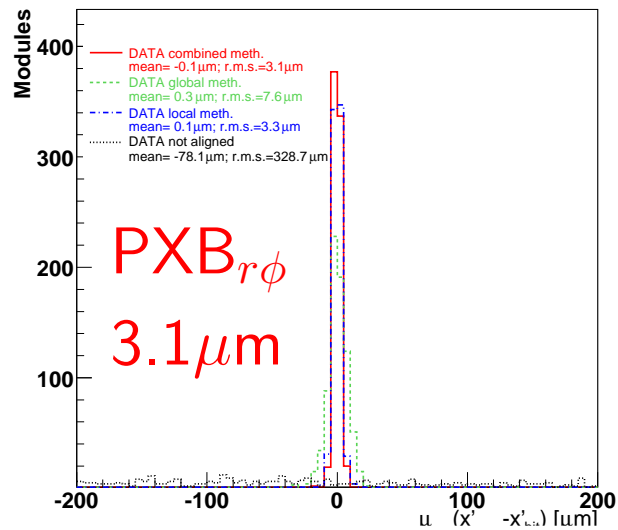


$r\phi$ pixel hit errors $\sim 19\mu m$ here



Median of the Residuals

- Again **global** + **local** \rightarrow best **combined**
for example: PXB better **local** transverse, **global** longitudinal



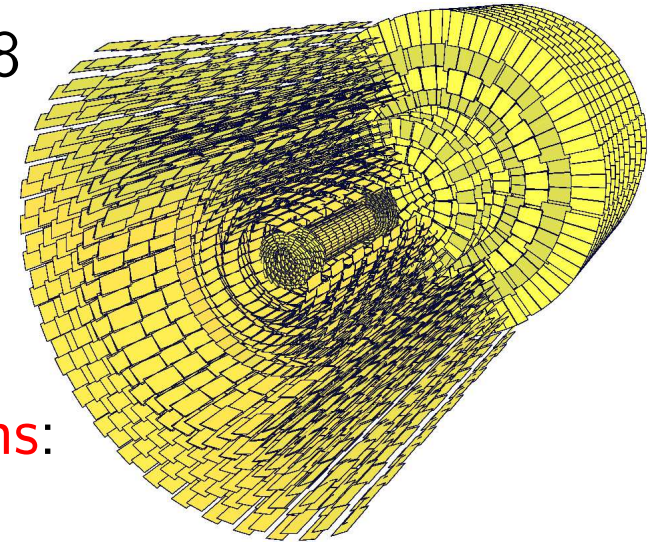
Summary

- CMS Tracker alignment with **first data**:

Tracker construction & **survey** in 2006-2008

Tracker integration **cosmic run** in 2007

global CMS **cosmic runs** in 2008



- Successful CMS Tracker alignment **algorithms**:

several complementary statistical methods

best **combination** of **global** & **local**

combine **track** + **survey** (done) and **LAS** (in progress) data

- Result in successful CMS Tracker alignment with cosmics

but far from being done: **cosmic** and **beam runs** in 2009-2010

cosmics alone has limitations, see **next talk**...

BACKUP

Data Delivery: Alignment Workflow

- Track reco data: reduced skim “AlCaReco” for alignment
see talk by [G. Flucke](#) about workflow tomorrow
- Result: 16,588 module **Positions** (6D) and **Alignment Position Errors** (**APE**, 3D)

