

@SaltyBurger

supported by







cooperations



project

A. Salzburger (CERN) for the ACTS project

CERN CERN





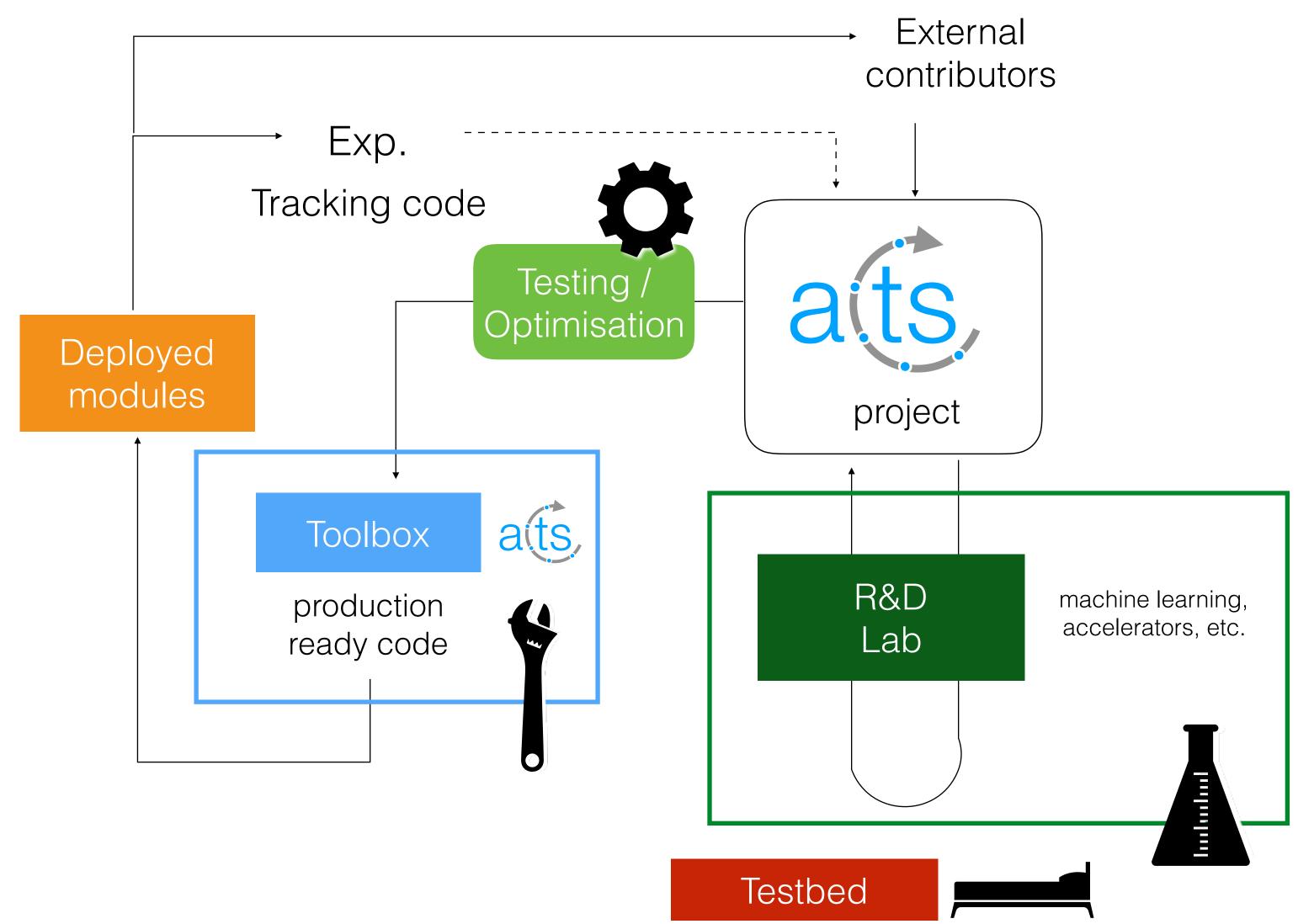


- **Preserve & advance** LHC state of the art track reconstruction software
- Develop & deploy production ready software for HL-LHC and beyond
- Establish R&D testbed for algorithms, technology advance (e.g. ML, GPU, detectors)
- Work & educate in state of the art technology/workflows

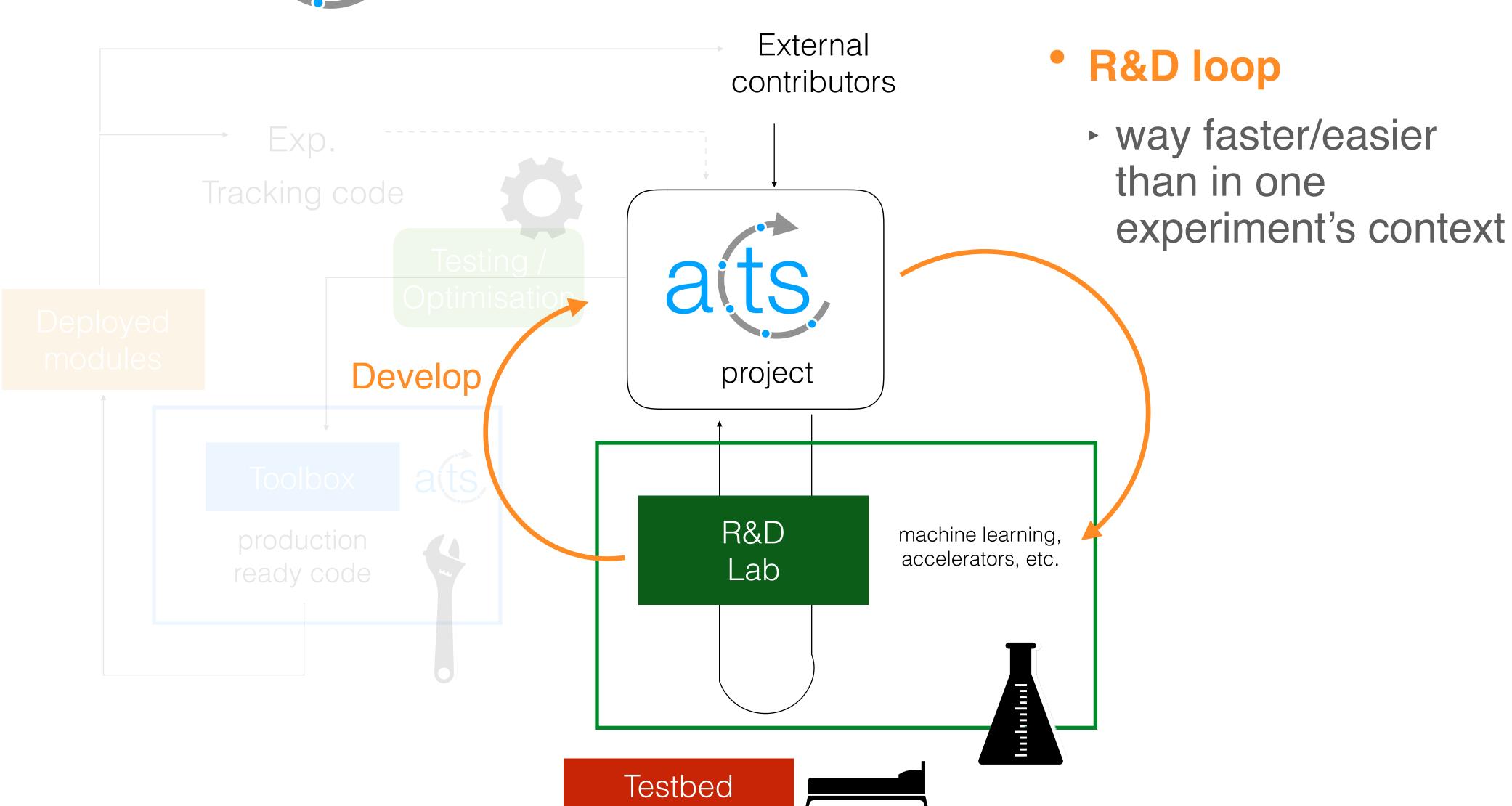


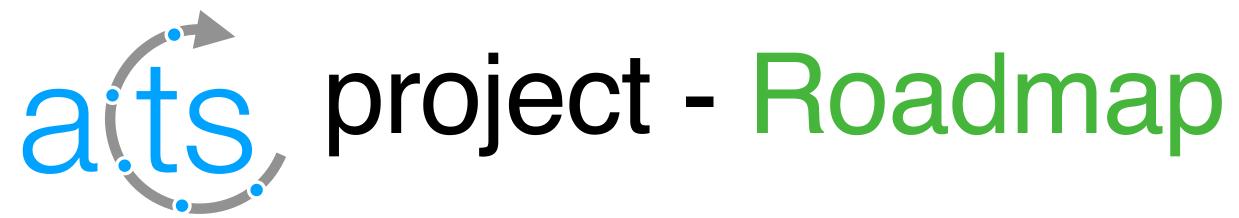


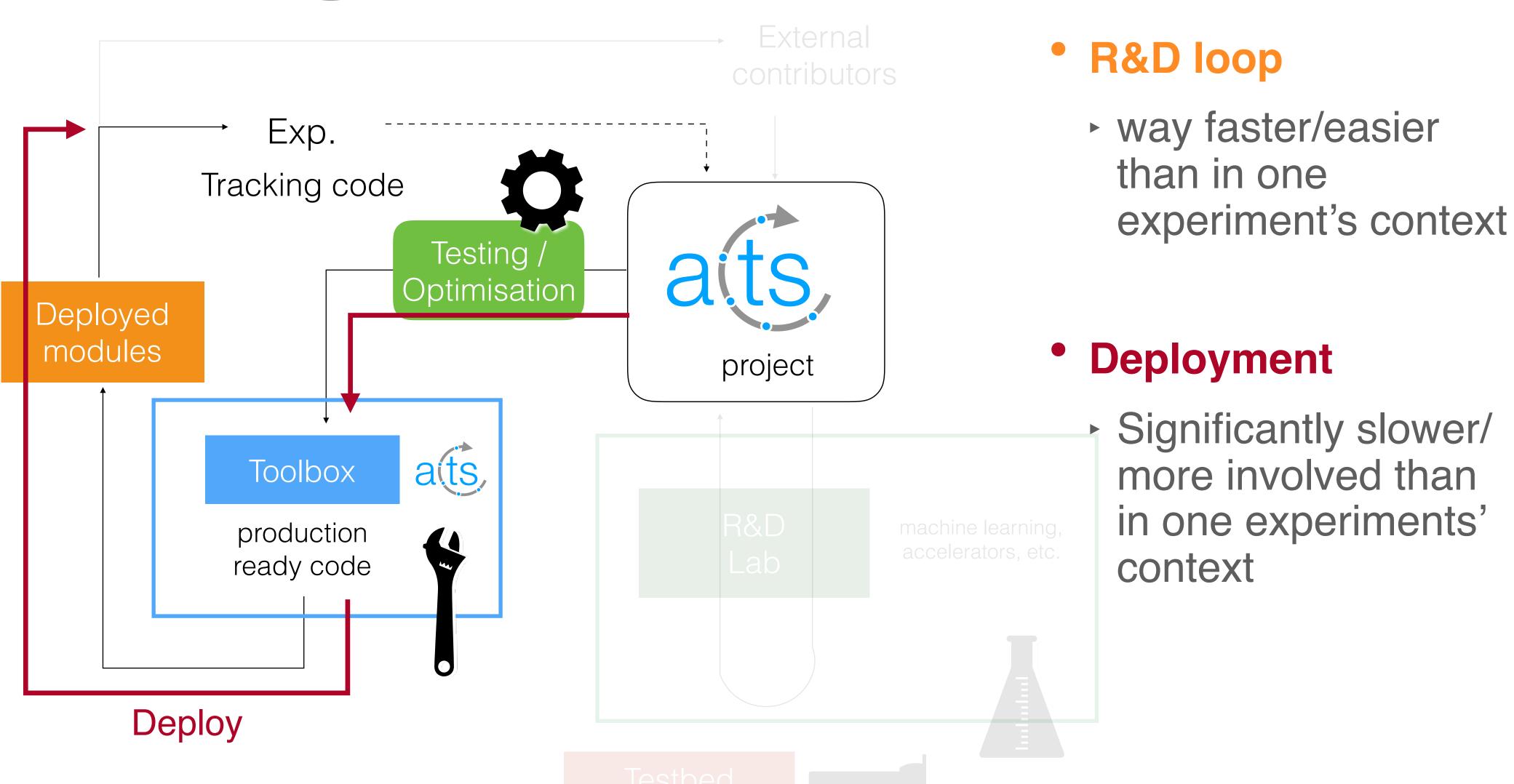










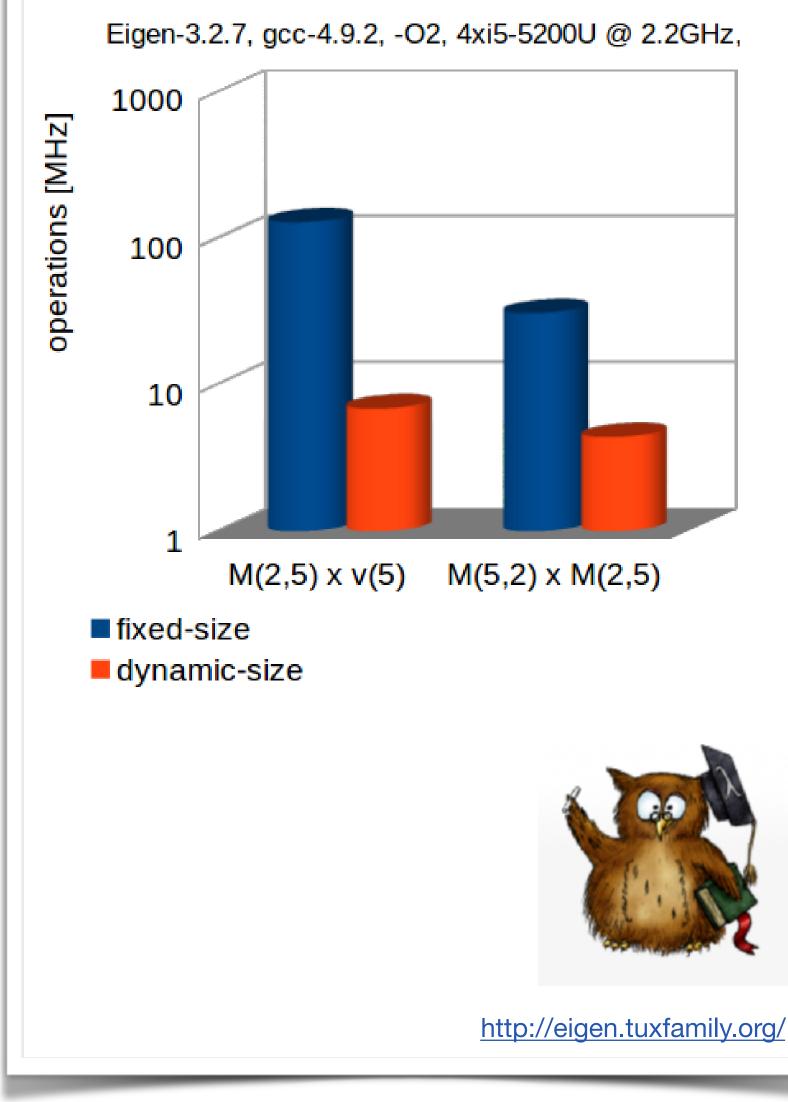




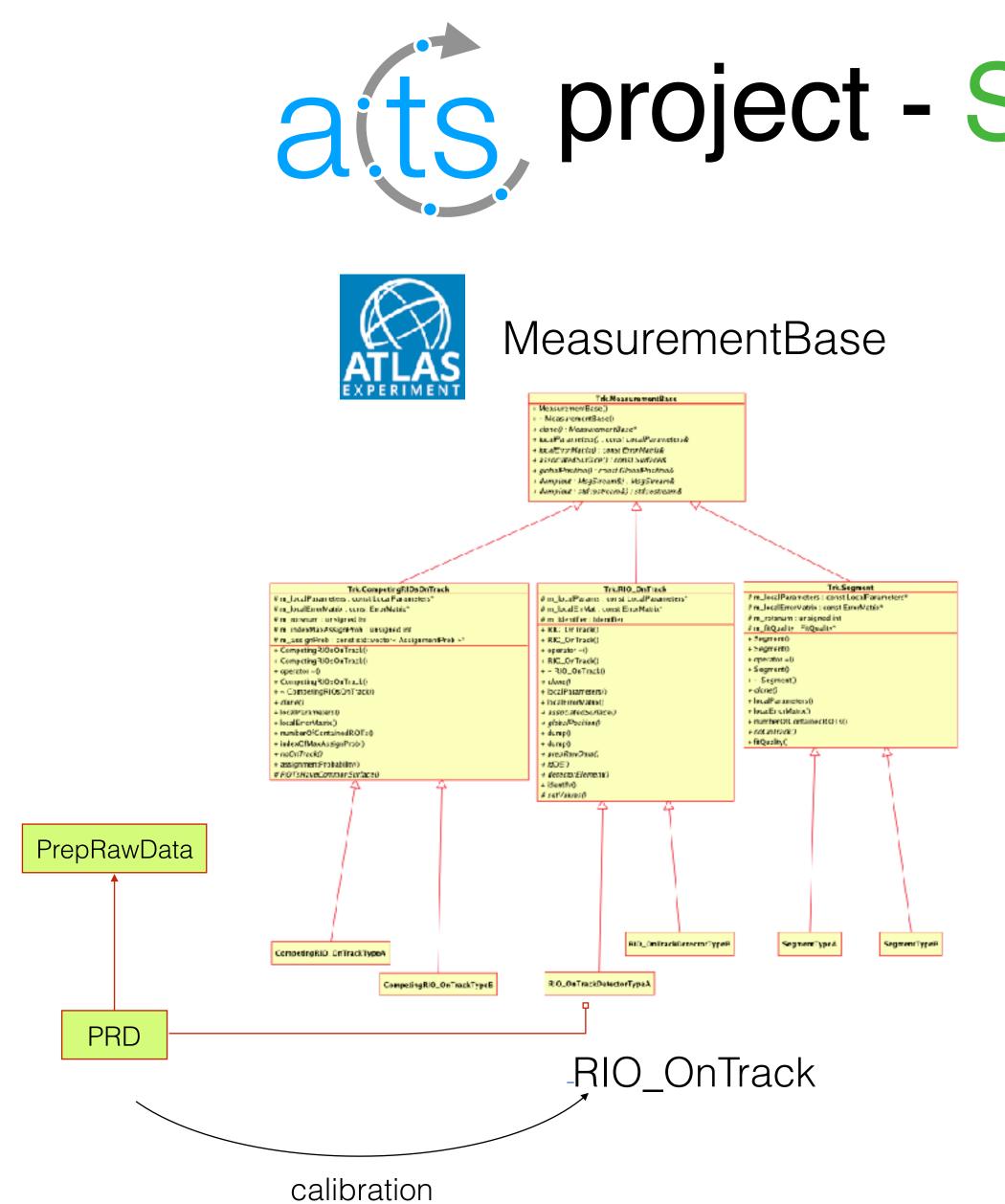




- **Extensive review of existing code**
 - Don't be shy, take what's good!
 - Technical paradigm shift:
 - Flatten data structures
 - Fixed size matrix multiplications
 - Lift runtime polymorphism to compile-time (C++ concepts replacing interfaces)
 - Modernize, simplify & streamline

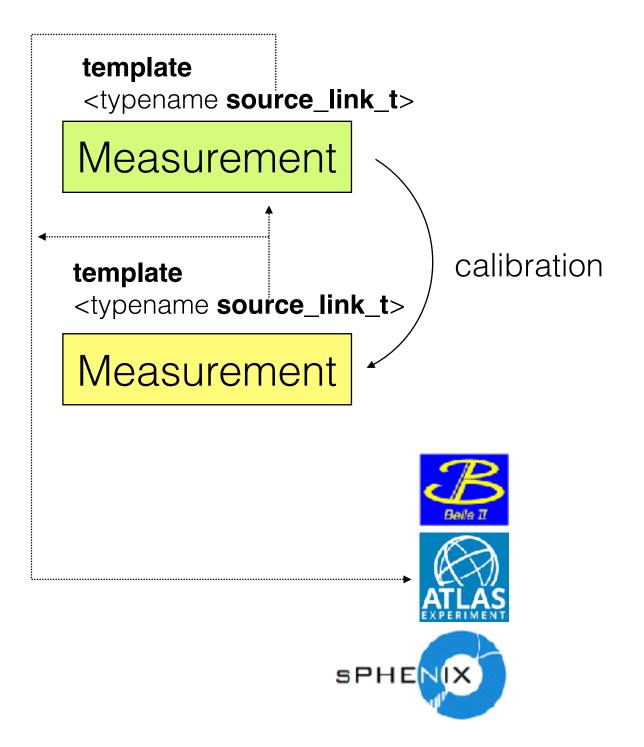


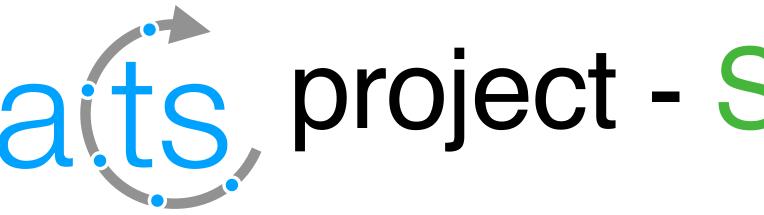




ats project - Simplify & Streamline









Extrapolator

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~ 360 lines interface in IExtrapolator.h ~ 4700 lines of code in Extrapolator.cxx

a(ts, project - Simplify & Streamline

Propagator

/// @brief Propagate track parameters - User method

/// This function performs the propagation of the track parameters according /// to the internal implementation object until at least one abort condition /// is fulfilled, the destination surface is hit or the maximum number of /// steps/path length as given in the propagation options is reached. 111 /// @tparam parameters_t Type of initial track parameters to propagate /// @tparam surface_t Type of target surface /// @tparam action_list_t Type list of actions /// @tparam aborter_list_t Type list of abort conditions /// @tparam propagator_options_t Type of the propagator options 111 /// @param [in] start Initial track parameters to propagate /// @param [in] target Target surface of to propagate to /// @param [in] options Propagation options 111 /// @return Propagation result containing the propagation status, final track parameters, and output of actions (if they produce any) 111 template <typename parameters_t, typename propagator_options_t,</pre> typename target_aborter_t = SurfaceReached, typename path_aborter_t = PathLimitReached> Result<action_list_t_result_t< BoundTrackParameters, typename propagator_options_t::action_list_type>>> propagate(const parameters_t& start, const Surface& target, const propagator_options_t& options) const;

~ 2 public interface methods, same functionality

code!

document the



Example: modernize

```
// projection of direction onto normal vector of reference frame
double PC = pVector[4] * C[0] + pVector[5] * C[1] + pVector[6] >
double Bn = 1. / PC;
double Bx2 = -A[2] * pVector[29];
double Bx3 = A[1] * pVector[38] - A[2] * pVector[37];
double By2 = A[2] * pVector[28];
double By3 = A[2] * pVector[36] - A[0] * pVector[38];
double Bz2 = A[0] * pVector[29] - A[1] * pVector[28];
double Bz3 = A[0] * pVector[37] - A[1] * pVector[36];
double B2 = B[0] * Bx2 + B[1] * By2 + B[2] * Bz2;
double B3 = B[0] * Bx3 + B[1] * By3 + B[2] * Bz3;
```

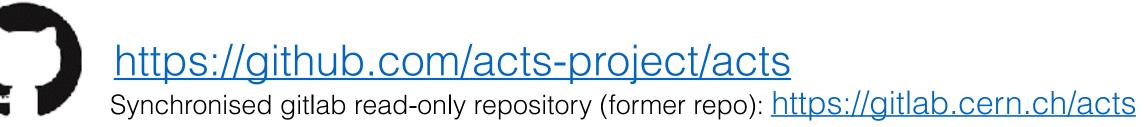
AtlasStepper, transcript in ACTS project

void covarianceTransport(Covariance& covarianceMatrix, Jacobian& jacobian, FreeMatrix& transportJacobian, FreeVector& derivatives, BoundToFreeMatrix& jacobianLocalToGlobal, const Vector3D& direction) { // Build the full jacobian jacobianLocalToGlobal = transportJacobian * jacobianLocalToGlobal; const FreeToBoundMatrix jacToLocal = surfaceDerivative(direction, jacobianLocalToGlobal, derivatives); const Jacobian jacFull = jacToLocal * jacobianLocalToGlobal; // Apply the actual covariance transport covarianceMatrix = jacFull * covarianceMatrix * jacFull.transpose(); // Reinitialize jacobian components reinitializeJacobians(transportJacobian, derivatives, jacobianLocalToGlobal, direction); // Store The global and bound jacobian (duplication for the moment) jacobian = jacFull;





Hosted on github.com



Repository Structure:

- **Core:** Toolbox with production-ready code
- Fatras: Fast simulation extension
- **Tests:** Unit & Integration tests for
- Plugins: third party dependent plugins, e.g. Geant4, DD4Hep, ROOT, ...
- Examples: Test framework with examples (FCC-hh, ITk, sPhenix, ...)

Dependencies

- **Core:** Eigen, BOOST (for unit testing only)

Standards

- C++17

CERN officially recommends using an outside provider for development including non-CERN contributors ...



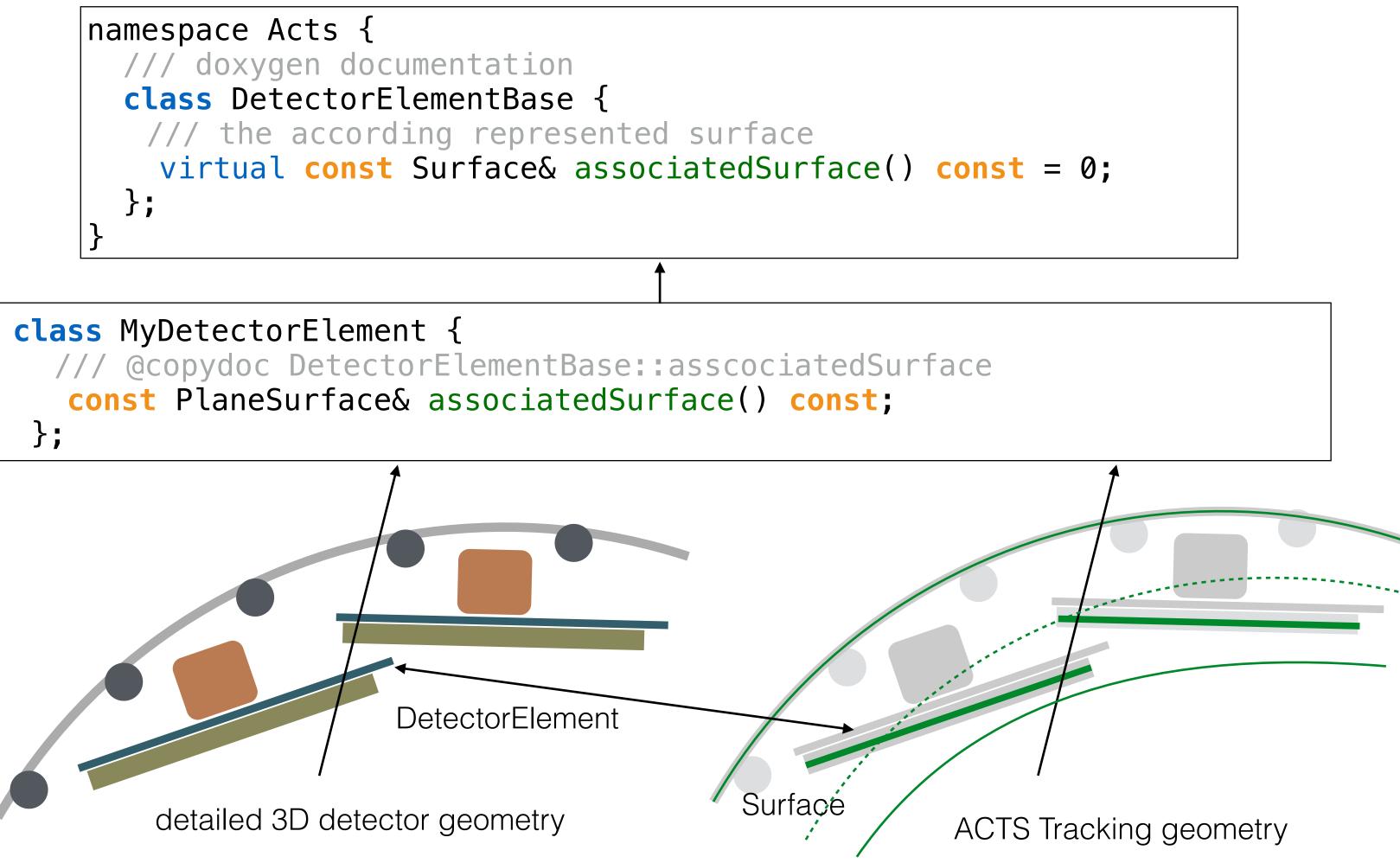


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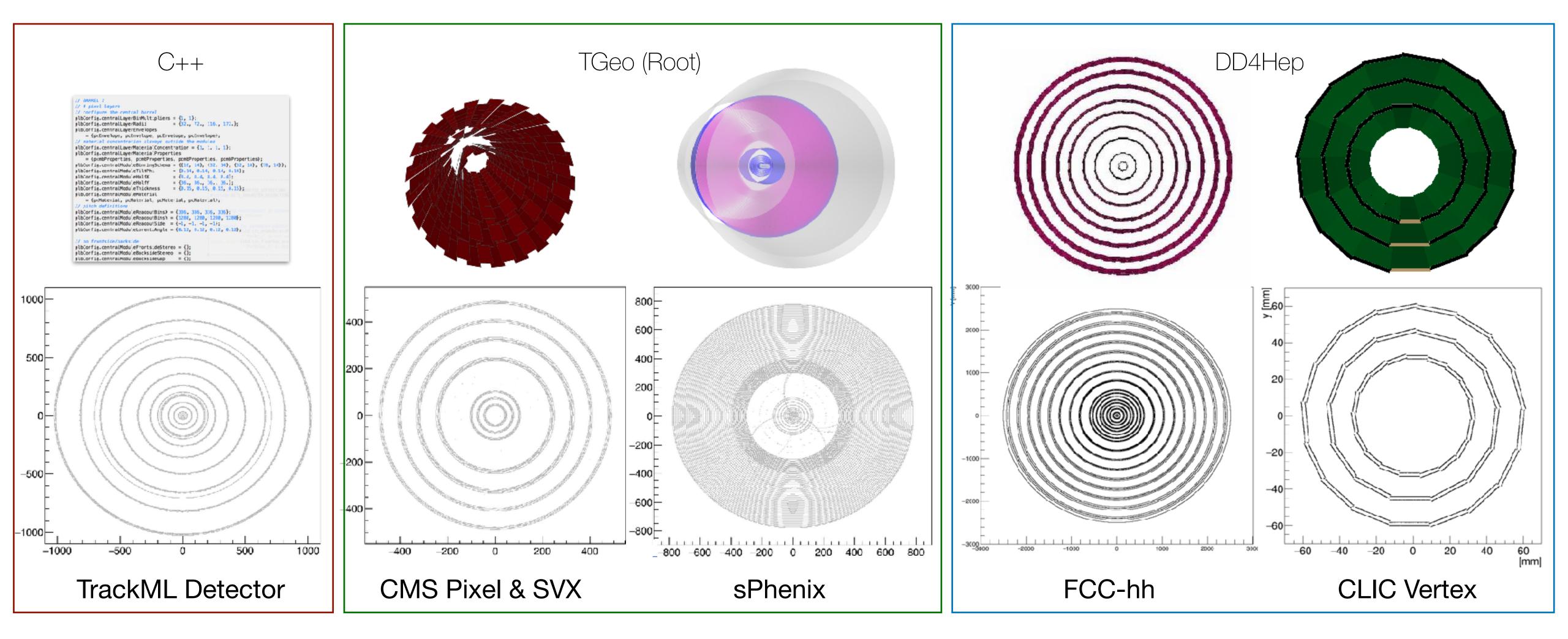


• Flexibility to interface with detector SW & Plugin mechanism





• Flexibility to interface with detector SW & Plugin mechanism





- - Keep it simple, e.g. configuration done with nested Config structs

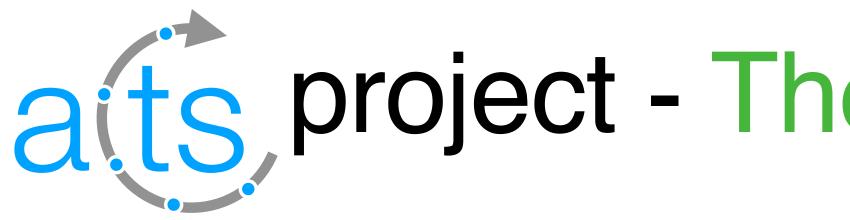
namespace Acts { /// doxygen documentation class WorkHorse { /// @struct Config for To struct Config { }; };

Possible binding to Gaudi(Hive):

feed from Framework into ACTS configuration declareProperty("CoatColor", m_cfg.coatColor); declareProperty("MaxPath", m_cfg.maxPath);

Plumbing & where it usually gets dirty: integration into experiment code base

float coatColor; ///< configure the coat color</pre> float maxPath; ///< set the max path this horse can run</pre>



- Plumbing & where it usually gets dirty: integration into experiment code base
 - Any external code needs to tie in with experiment code base - may sound trivial, but e.g. log messaging needs to work

This macro allows to use a locally defined logging object with the ACTS_* logging macros. The envisaged usage is the following:

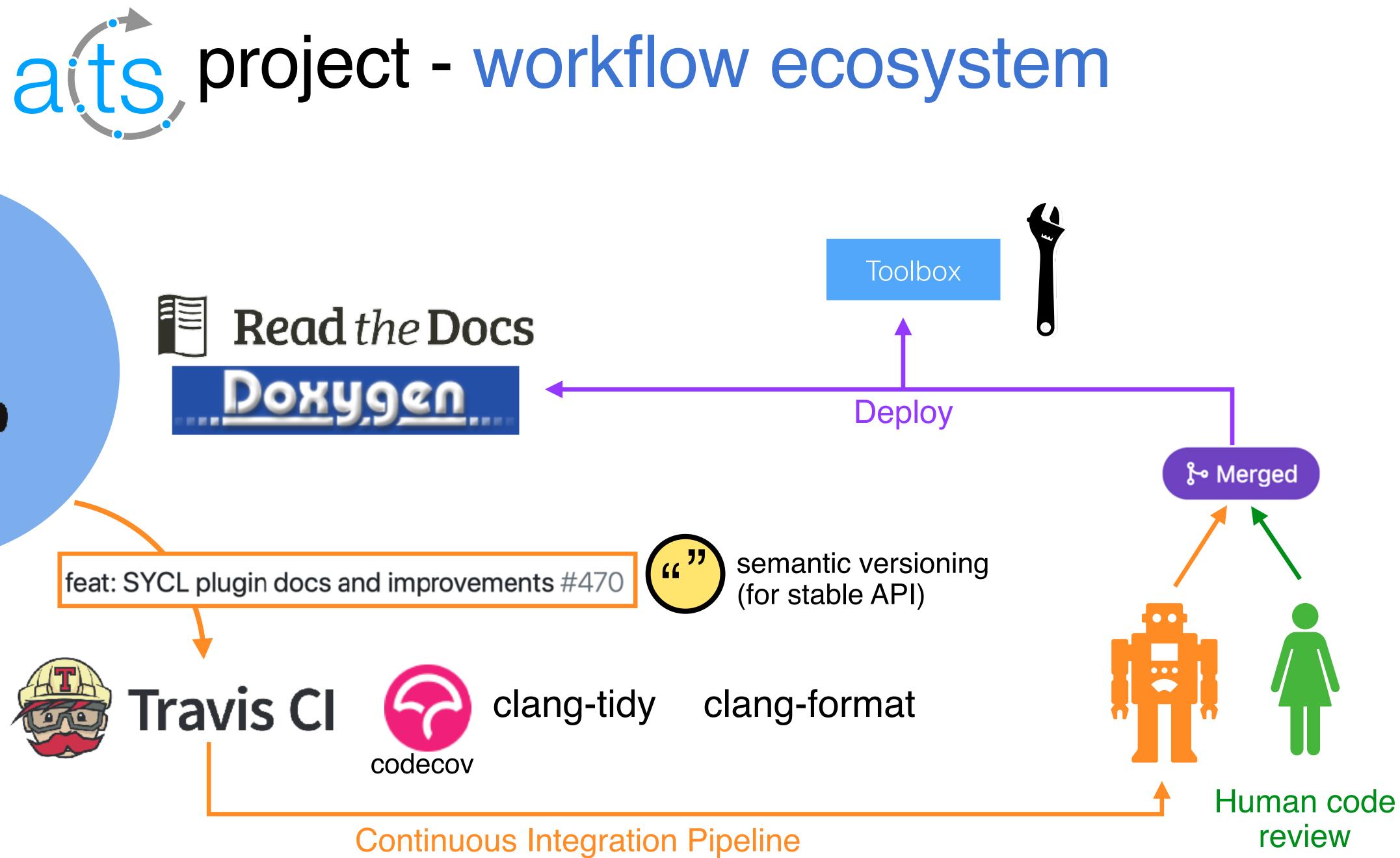
- **General guideline** ("fire brigade design")
 - You call us, we never call you.
 - If you need something from your house, we will bring it to you.

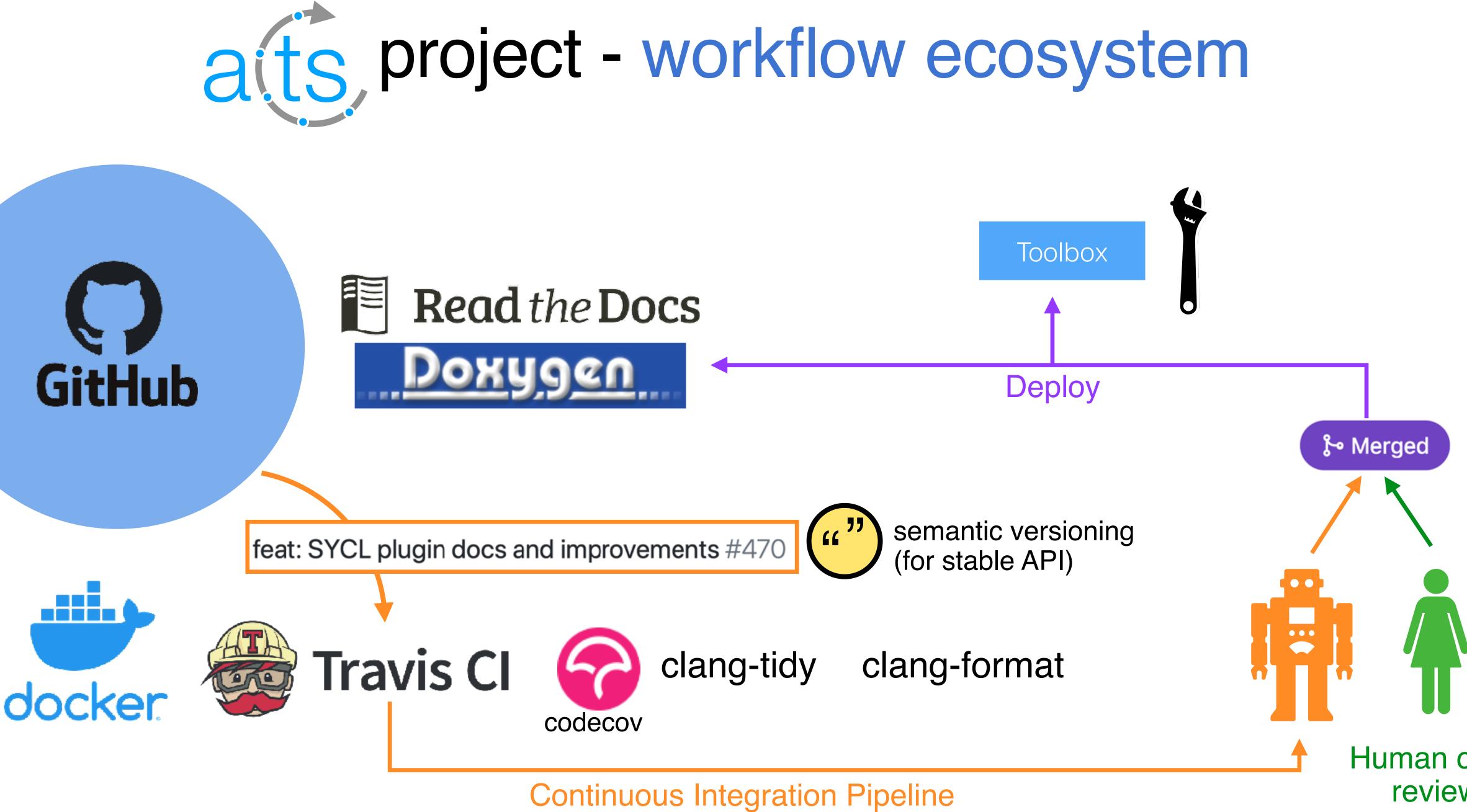
a(ts) project - The toolbox & integration



- HEP SW has/had sometimes a bad reputation in being "aged"
 - Same for workflows & technology
 - Some of it is rooted in the long lifetime & necessity of coherent data processing
- We need to stay attractive to the best technical students
 - Deploy modern development workflows
 - Be open to move with technology, new standards
 - A path to publish the work

OpenDataDetector project (backup)









High level of unit testing & CI (coverage steadily increasing)

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| Plugins | |

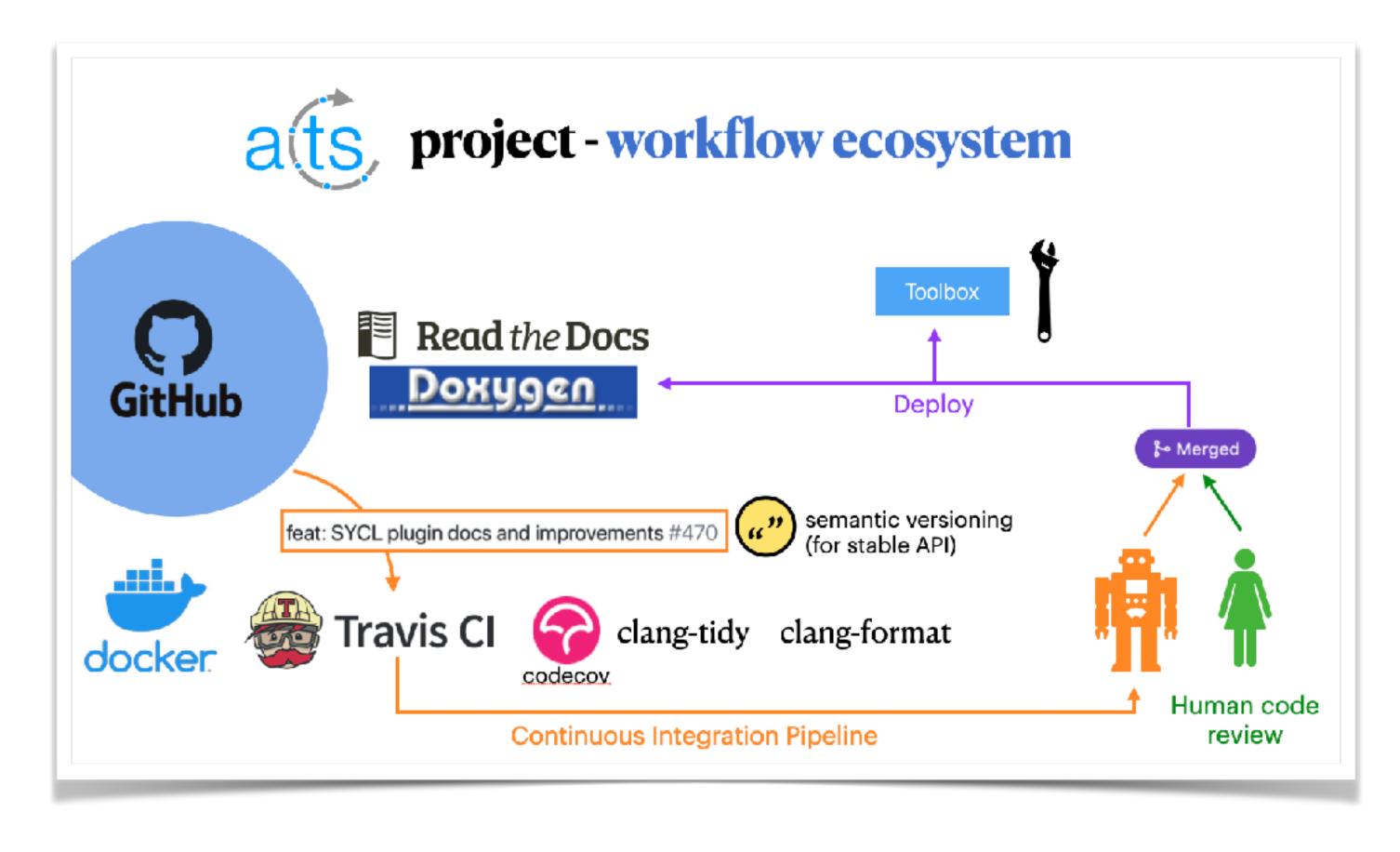
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| = | • | • | • | Coverage | ≡ |
| 14,256 | 6,615 | 4,503 | 3,138 | | 46.40% |
| 448 | 332 | 42 | 74 | | 74.11% |
| 2,000 | 253 | 267 | 1,480 | | 12.65% |
| 16,704 | 7,200 | 4,812 | 4,692 | | 43.10% |



- Directly benefits to involved experiments
 - Highly tested code deployed
 - Experienced developers that eventually co-authored the deployed code
- **ATLAS** example:
 - Migration to git/CI setup pioneered by ACTS developers
 - Vertexing speed-up by 40% being re-deployed to AthenaMT
 - ATLAS phase-2 ITK reconstruction planned with ACTS implementation



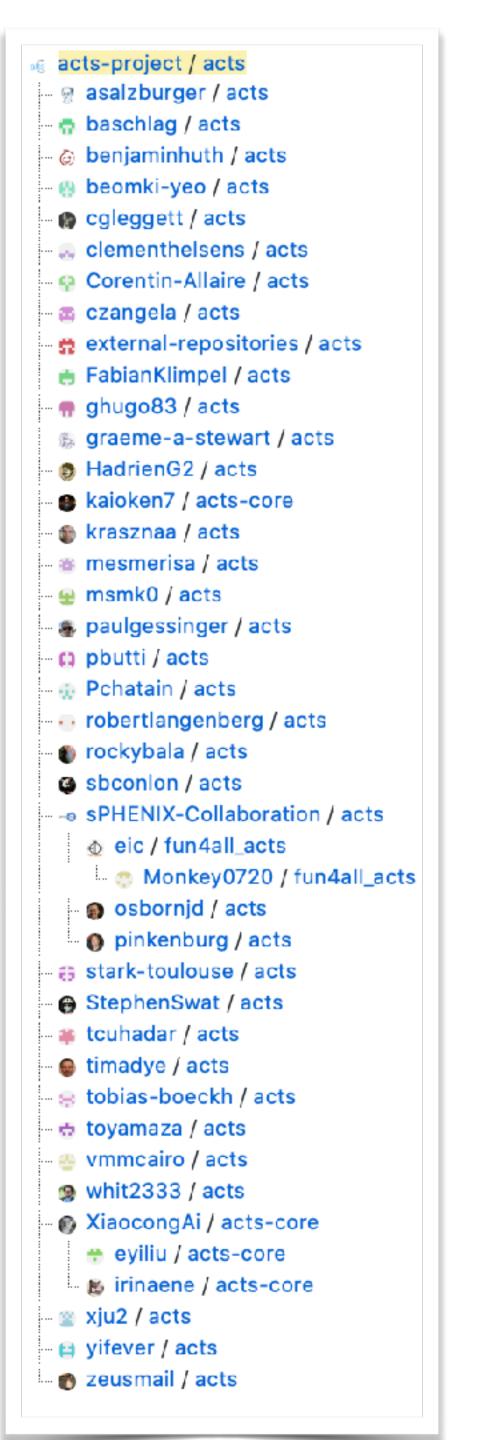
- Modern programming, language, conceptual skills & experience in industry standard workflows
 - Facilitates change between experiments
 - Facilitates careers outside the field
 - open source access make contribution traceable



That is an impressive skillset even/particularly outside HEP.



- Currently 42 forks of the acts-project
 - Individuals (in HEP, students) or experiment forks (e.g. sPhenix)
- 10-15 active developers on Core project
 - Still quite ATLAS heavy, though increasing contribution from sPHENIX, Belle-2 or non-associated individuals





- ACTS as one project in a new ecosystem of community driven SW
 - We walk and we learn together
 - interaction between SW projects under the umbrella of HSF is key
 - We should play together
 - Encouragement to put modules together, build systems
 - Example: can ACTS run within on top of PataTrack, within ALLEN, etc...
 - Finally, we should work together

- Example: ACTS report on Eigen compilation restrictions/issues in HSF WG#2 similar issues seen by other Eigen clients (CMS), follow up by HSF

Summary

- ACTS project quite matured in the last 4 years - version v01.00.00 released in Sep 2020 with particle frozen API
- Encapsulation from experiment SW stack comes with a price tag - however, it did what we strived for: enabled R&D in many areas - starting to pay off (e.g. vertex reconstruction in ATLAS)



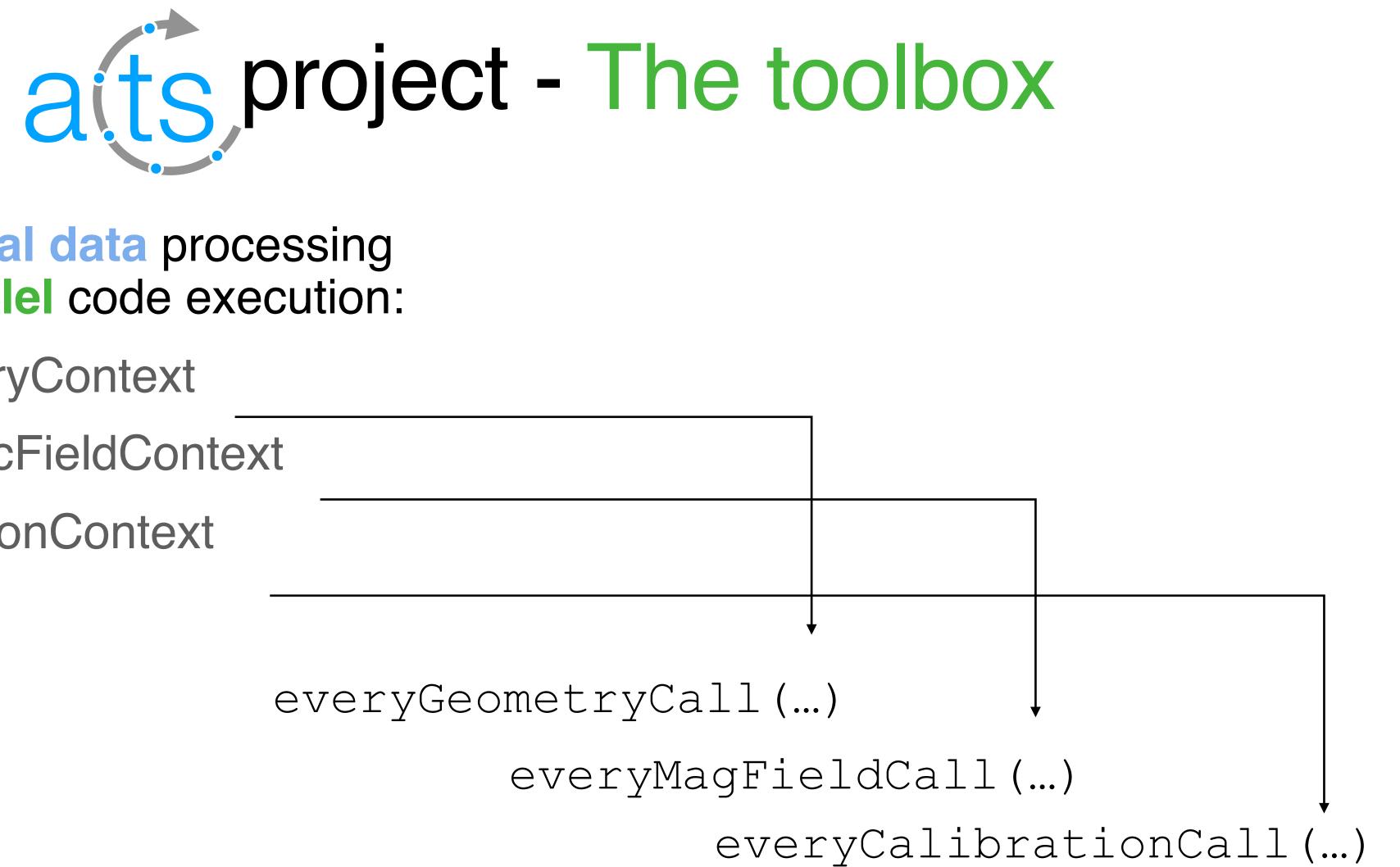
Read the Docs



<u>acts-developers@cern.ch</u>

acts-users@cern.ch

acts-parallelization@cern.ch



- Contextual data processing with **parallel** code execution:
 - GeometryContext
 - MagneticFieldContext
 - CalibrationContext

Quasi-free condition/contextual data handling.



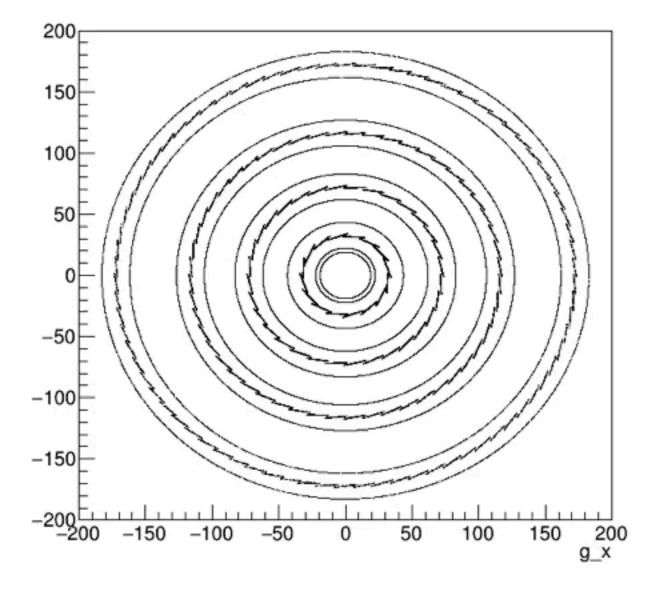
- Contextual data processing with **parallel** code execution:
 - GeometryContext
 - MagneticFieldContext
 - CalibrationContext



GeometryContext In Action

Different alignment in every event









- *Classical* algorithm are **not frozen**, there's room for algorithm R&D
- ACTS aims to provide a testbed for this research:
 - Testbed detectors available for testing
 - Examples (being worked on currently):
 - ray tracing inspired navigation through detector geometry
 - generalised track linearisation in vertex fitting
 - extension of KF into a global measurement formulation

Disclaimer

- Main focus of this talk
 - Lessons learnt from/by developing common software
 - Concepts, benefits & costs of doing so
- Recent talks on ACTS status & performance



Ai X, Tracking with ACTS, CTD2020



Schlag B, ACTS Vertexing and Deep Learning Vertex Finding, CTD2020 27

- Many of current algorithms have roots in **LEP era**:
 - Code base usually in FORTRAN
- Move to C++ in early 2000's
 - Common C++ based libraries
 - Era of object oriented design

Nuclear Instruments and Methods in Physics Research A262 (1987) 444-450 North-Holland, Amsterdam

APPLICATION OF KALMAN FILTERING TO TRACK AND VERTEX FITTING

R. FRÜHWIRTH

444

Institut für Hochenergiephysik der Österreichischen Akademie der Wissenschaften, Vienna, Austria

Received 30 June 1987

Recently iterative procedures have been proposed for track and vertex fitting in counter experiments. We show that the proper theoretical framework for these procedures is the theory of linear filtering, in particular the Kalman filter. Using results from filtering theory we confirm and extend the previous results. We also discuss the detection of outliers and of secondary vertices.

R. Früwirth, Application of Kalman Filtering To Track and Vertex Fitting (1987)

"The Delphi detector was designed for the Kalman Filter"



- Many of current algorithms have roots in LEP era:
 - Code base usually in FORTRAN
- Move to C++ in early 2000's
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 - Era of object oriented design

199

"For all its inelegance, and lack of safety features, it seems certain that FORTRAN will remain the main language for HEP code well into the 1990s...."

Computing at CERN in the 1990s

"FORTRAN is probably the only perennial standard which will never be questioned."

Trends in Computing for HEP

"I don't know what the language of the year 2000 will look like but I know it will be called FOR-TRAN."

Tony Hoare



White, B. The comparison and selection of programming languages for high energy physics application (1991)

- Many of current algorithms have roots in LEP era:
 - Code base usually in FORTRAN
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 - Era of object oriented design

1994

CLHEP - A Class Library for High Energy Physics

Shortcuts to: Documentation Download CLHEP editors Mailing List CLHEP Workshops Bug <u>Reports</u>

The CLHEP project was proposed by Leif Lönnblad at CHEP 92. It is intended to be a set of HEPspecific foundation and utility classes such as random generators, physics vectors, geometry and linear algebra. CLHEP is structured in a set of packages independent of any external package (interdependencies within CLHEP are allowed under certain conditions).

A large fraction of contributions (mainly to the Random, Vector, Geometry and Matrix packages) came from using CLHEP within (in alphabetical order):

- the <u>BaBar experiment</u> @ <u>SLAC</u>
- the Geant4 Collaboration
- the <u>ZOOM Project</u> @ <u>Fermilab</u>

L. Lönnblad, CLHEP—a project for designing a C++ class library for high energy physics (1994)



- Many of current algorithms have roots in LEP era:
 - Code base usually in FORTRAN
- Move to C++ in early 2000's
 - Common C++ based libraries
 - Era of object oriented (OO) design

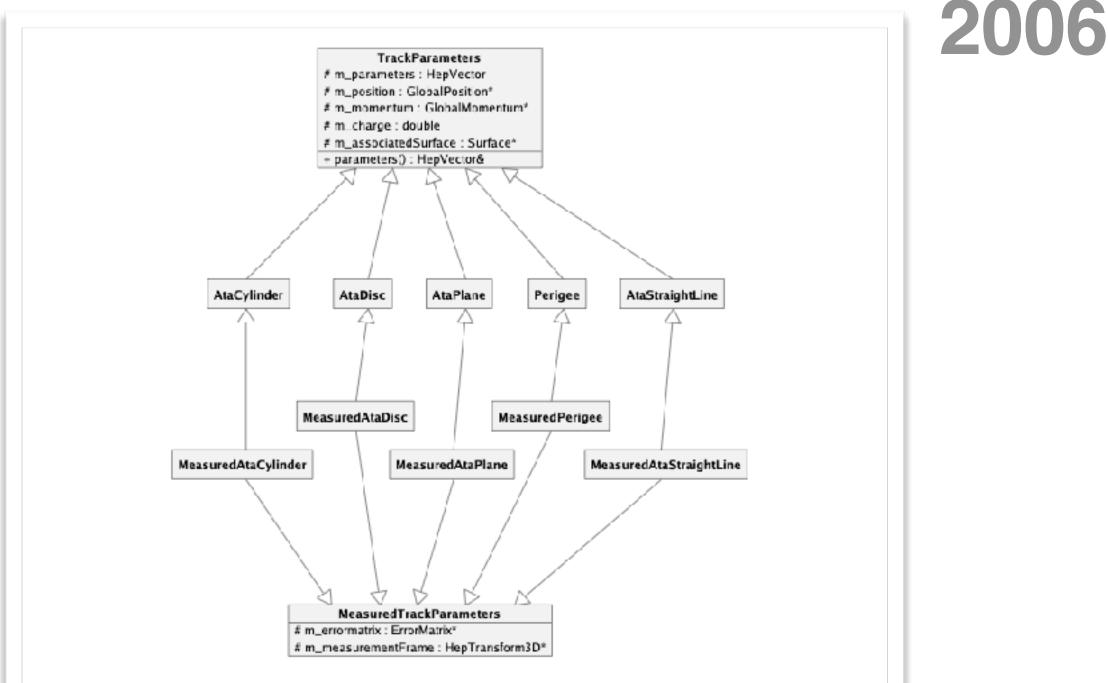


Figure 3: UML diagram showing the inheritance structure of TrackParameters data classes. TrackParameters exist in both, an unmeasured and a measured flavour. The measured track parameter classes follow a double inheritance structure, inheriting from the unmeasured class they represent and a common base class for measured track parameters, holding the error matrix description and the measurement frame definition.

Akeson, P F et al, ATLAS Tracking Event Data Model (2006)

```
Now we'd call it over-object oriented (OOO) ...
```



Legacy of the LHC era

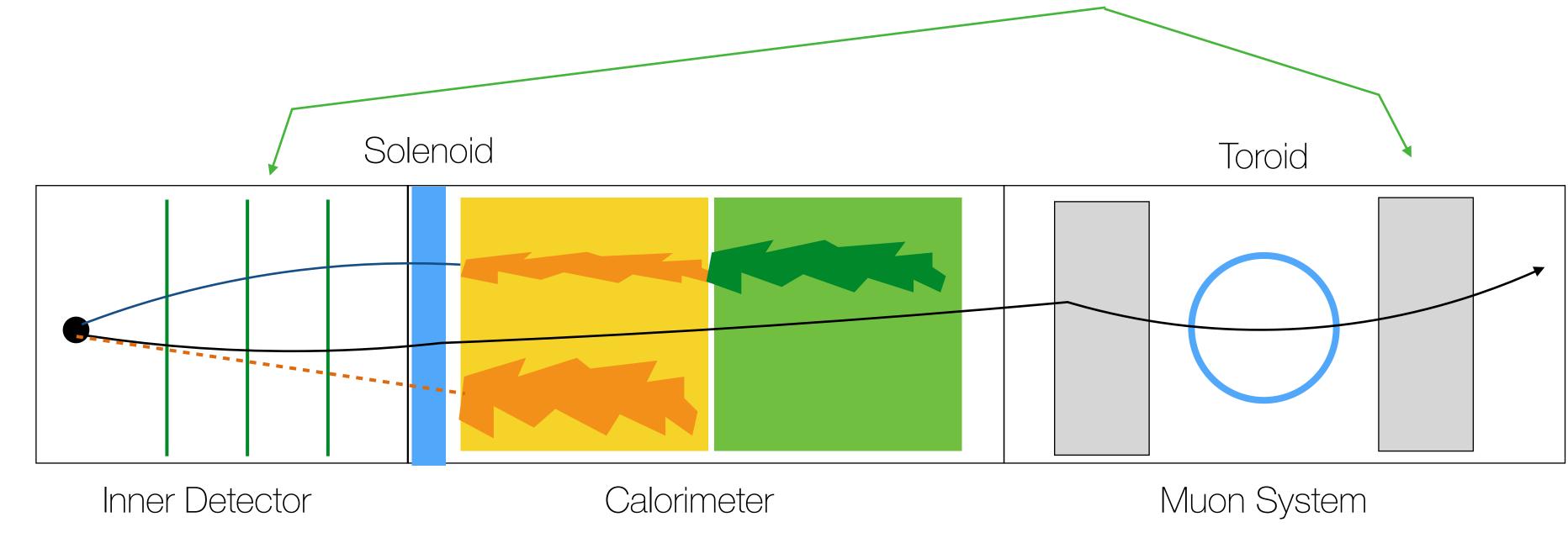
- Extremely ironed-out code
 - Many 10¹⁰ events processed (numerically validated)
- Extremely well performing track reconstruction algorithms
 - Technical track reconstruction (µ) efficiency ~100 %
- A great starting point!

Future challenges

- HL-LHC / FCC-hh studies
 - Way higher particle multiplicities (combinatorics)
- The rise of new technologies
 - C++20 has little to do with C++98
 - Heterogeneous computing
- Robots/AI want to take our jobs!

A great starting point

- ATLAS Track reconstruction SW



Cornelissen T et al, Concepts, Design and Implementation of the ATLAS New Tracking, 2008

Designed/written with common (agnostic) top layer for two tracking devices

Highly polymorphic Tracking reconstruction SW, with common abstraction layer

A great starting point

- ATLAS Track reconstruction SW
 - Designed/written with common (agnostic) top layer for two tracking devices
 - Some very fast algorithms & modules in place

```
// projection of direction onto normal vector of reference frame
double PC = pVector[4] * C[0] + pVector[5] * C[1] + pVector[6] * C[2];
double Bn = 1. / PC;
double Bx2 = -A[2] * pVector[29];
double Bx3 = A[1] * pVector[38] - A[2] * pVector[37];
double By2 = A[2] * pVector[28];
double By3 = A[2] * pVector[36] - A[0] * pVector[38];
double Bz2 = A[0] * pVector[29] - A[1] * pVector[28];
double Bz3 = A[0] * pVector[37] - A[1] * pVector[36];
double B2 = B[0] * Bx2 + B[1] * By2 + B[2] * Bz2;
double B3 = B[0] * Bx3 + B[1] * By3 + B[2] * Bz3;
```

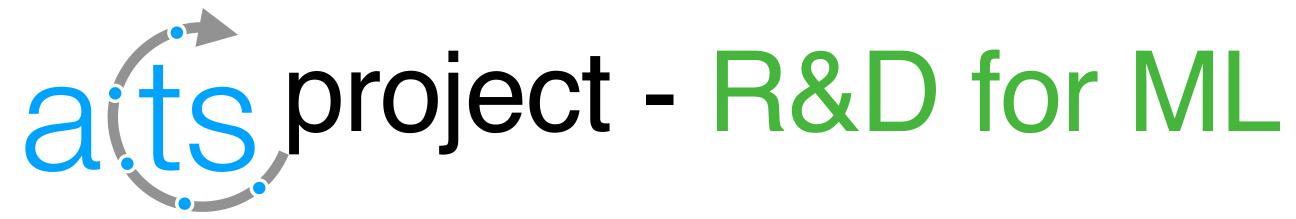


Some of this great CPU performance still roots in the FORTRAN style writing.

A great starting point

- ATLAS Track reconstruction SW

 - Designed/written with common (agnostic) top layer for two tracking devices Some very fast algorithms & modules in place
 - Undergone (like other experiment SW) successful cleanup campaigns - all LHC experiments reduced CPU time significantly since LHC startup
- However, time starts to show its scars
 - Several developers left the project/field
 - Some technology advancements missed/only profited in a limited manner



- Fast simulation extension was used for Tracking Machine Challenge
 - Very successful kaggle & codalab challenges
 - Many interesting ideas & solutions
 - Established a reference data set & format
 - still in use for much of current Tracking R&D



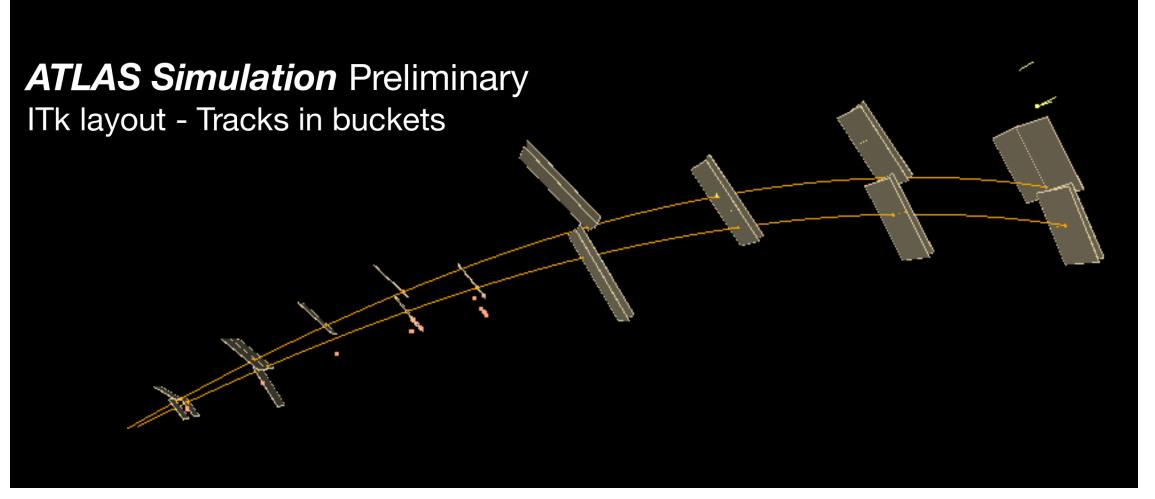


28 July 2020 to 6 August 2020, virtual conference

AS, Conclusion of the TrackML Challenge, ICHEP2020

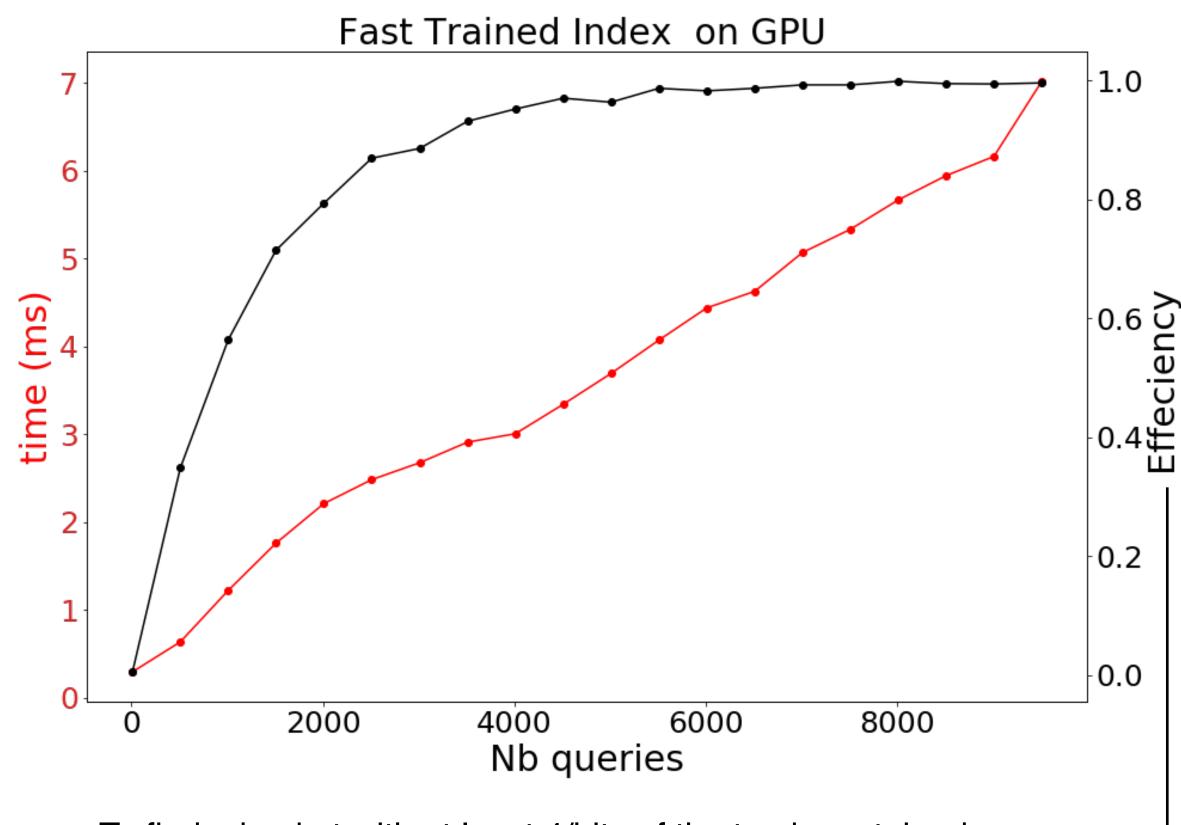


- Standalone examples allow for novel (ML) algorithm R&D
 - Example: track seeding using approximate nearest neighbourhood

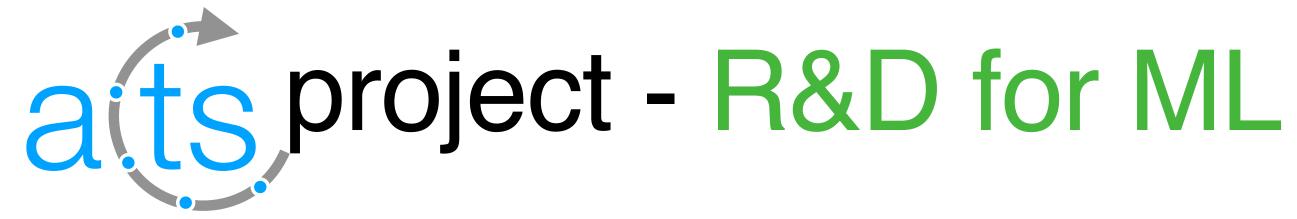


These tracks are brought to you by

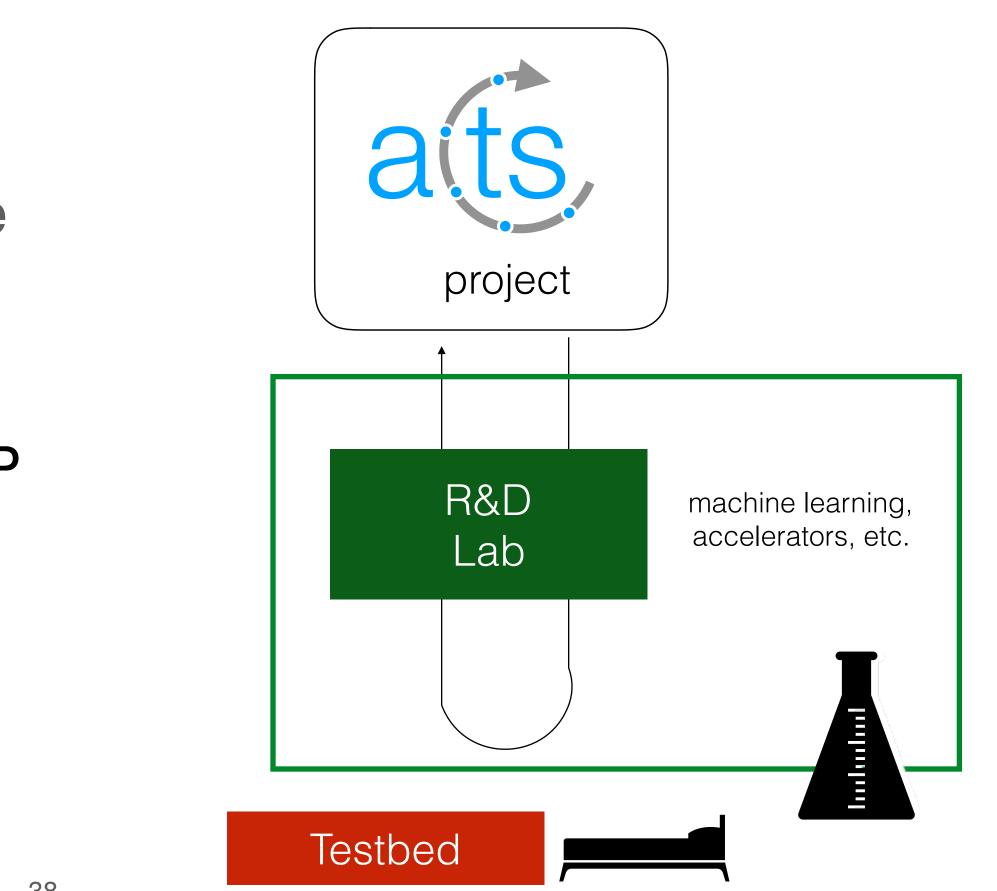




To find a bucket with at least 4/hits of the track contained (good enough for track seeding)



- Standalone examples allow for novel (ML) algorithm R&D
 - Example: track seeding using approximate nearest neighbourhood
 - Aim to have a path way of these R&D projects back into the ACTS code base - eventually even production code
- Learn how to integrate external non-HEP software into HEP reconstruction code

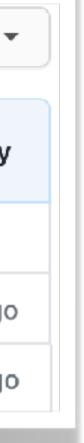




Dedicated sub-group for parallelisation (<u>acts-parallelization@cern.ch</u>) Evolving code to run on different hardware

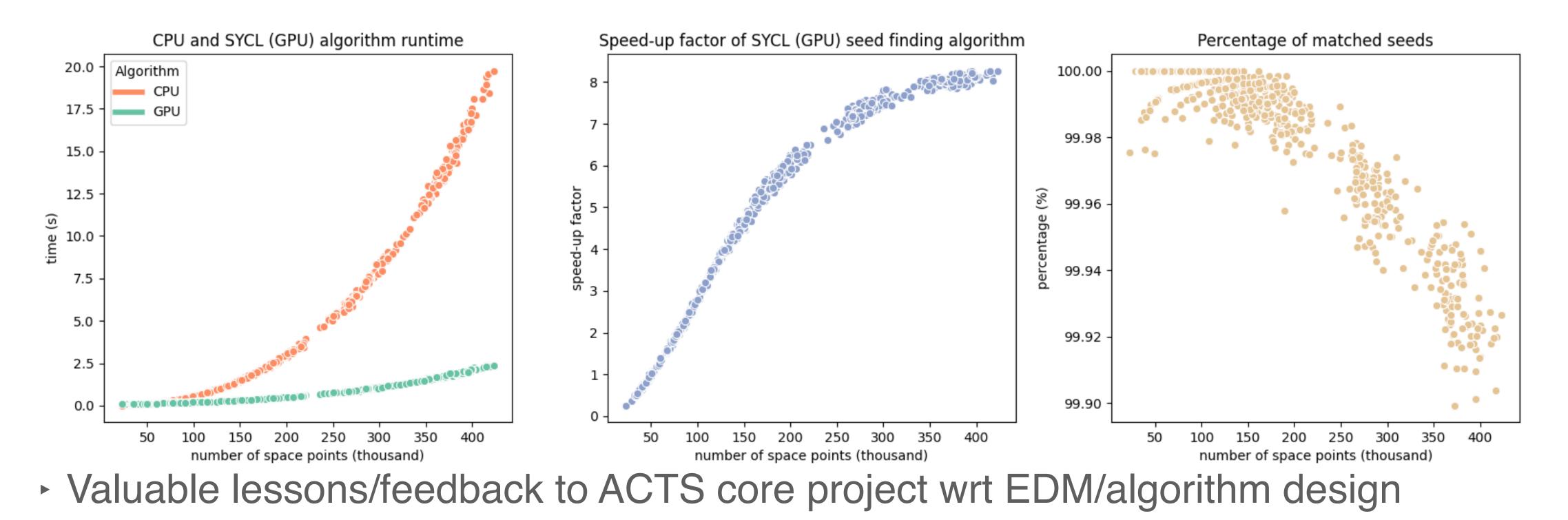
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| 3 authors feat: SYCL plugin docs and improvements (#470) | ••• | ✓ ca513ea 5 days ago | 🕓 History |
| •• | | | |
| Cuda build | I: ensure consistent CMake options and target names (#406) | | 28 days ag |
| Sycl feat: | SYCL plugin docs and improvements (#470) | | 5 days ag |







Example: SYCL/oneAPI implementation of track seeding algorithm Reference to CPU implementation (ATLAS implementation)





- Stand-alone character of the repository eases R&D
 - Even larger scale inclusions, tests, expansions are simplified
 - Testbeds allow for rapid feedback on development
- Example: ACTS auto-diff within propagation
 - auto-diff is a rather recent development coming from the ML sector - relies on the fact that machine instructions are per definition differentiable
 - Test implementation in track propagation for derivative/jacobian calculation done