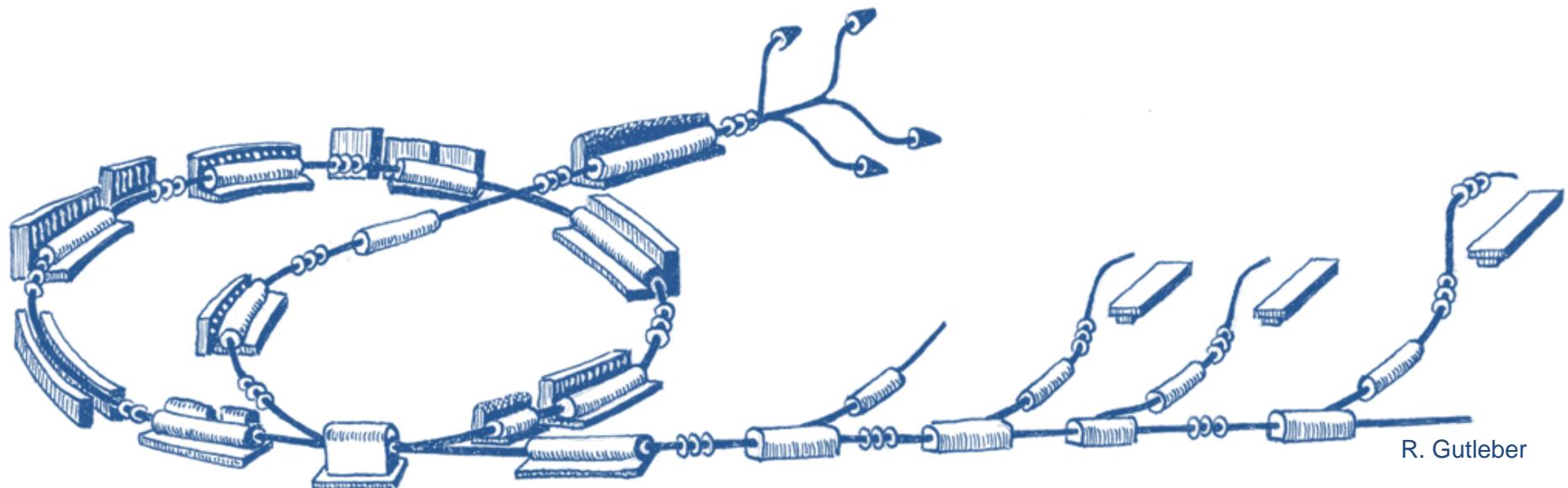


ProShell Procedure Framework Status

MedAustron Control System Week 2

October 7th, 2010

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Overview

- Scope
- Concept
- Architecture
- Status

Scope

- Presents an **overview** of the planned **architecture** of the ProShell Procedure Framework
- Shows the **current status** and **plan** till December



CONCEPTS

General Terms

- **ProShell** Procedure Framework
 - Windows C# Application managing procedures
- **Procedure**
 - a module that performs a task
 - E.g. Emittance measurement, Procedure to change mode to clinical, Quality assurance procedures, etc.
- **Resource**
 - Device, Working Set, Virtual Accelerator
- **Driver**
 - Provides a high-level interface to a component
 - E.g. PVSS

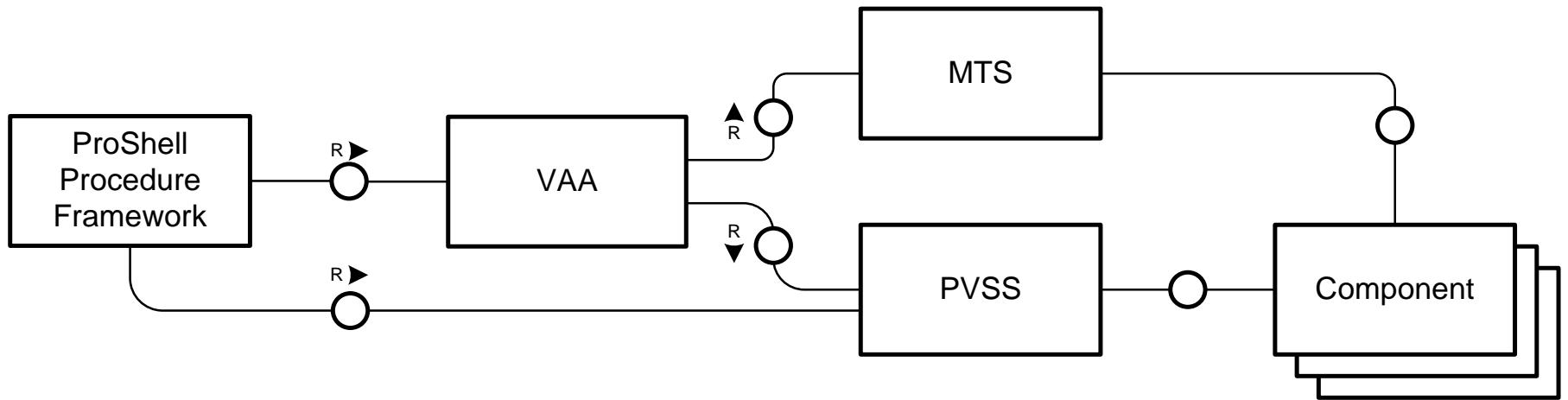
ProShell Procedure Framework

- provides a graphical user interface that
- dynamically loads Procedures,
- manages Procedures,
- provides APIs to interact with control system components
 - Allocate resources through VAA
 - Communicate with resources

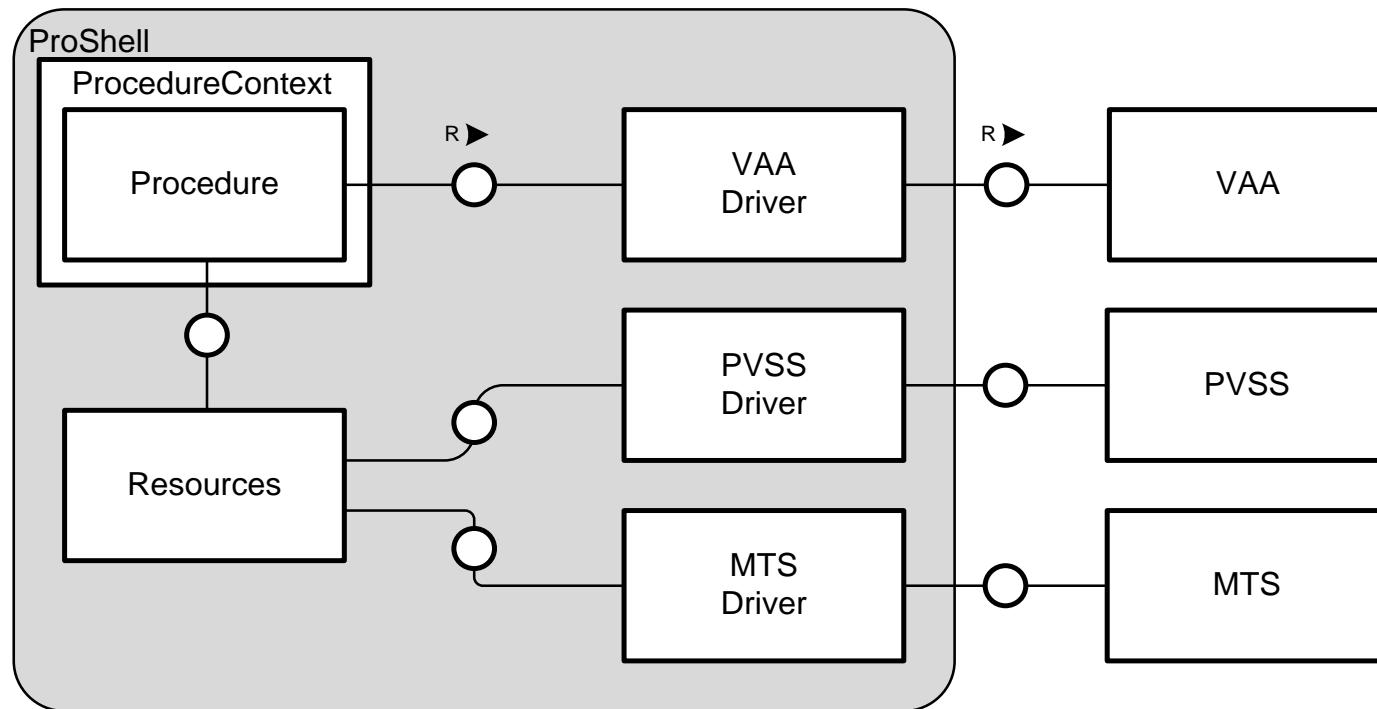


ARCHITECTURE

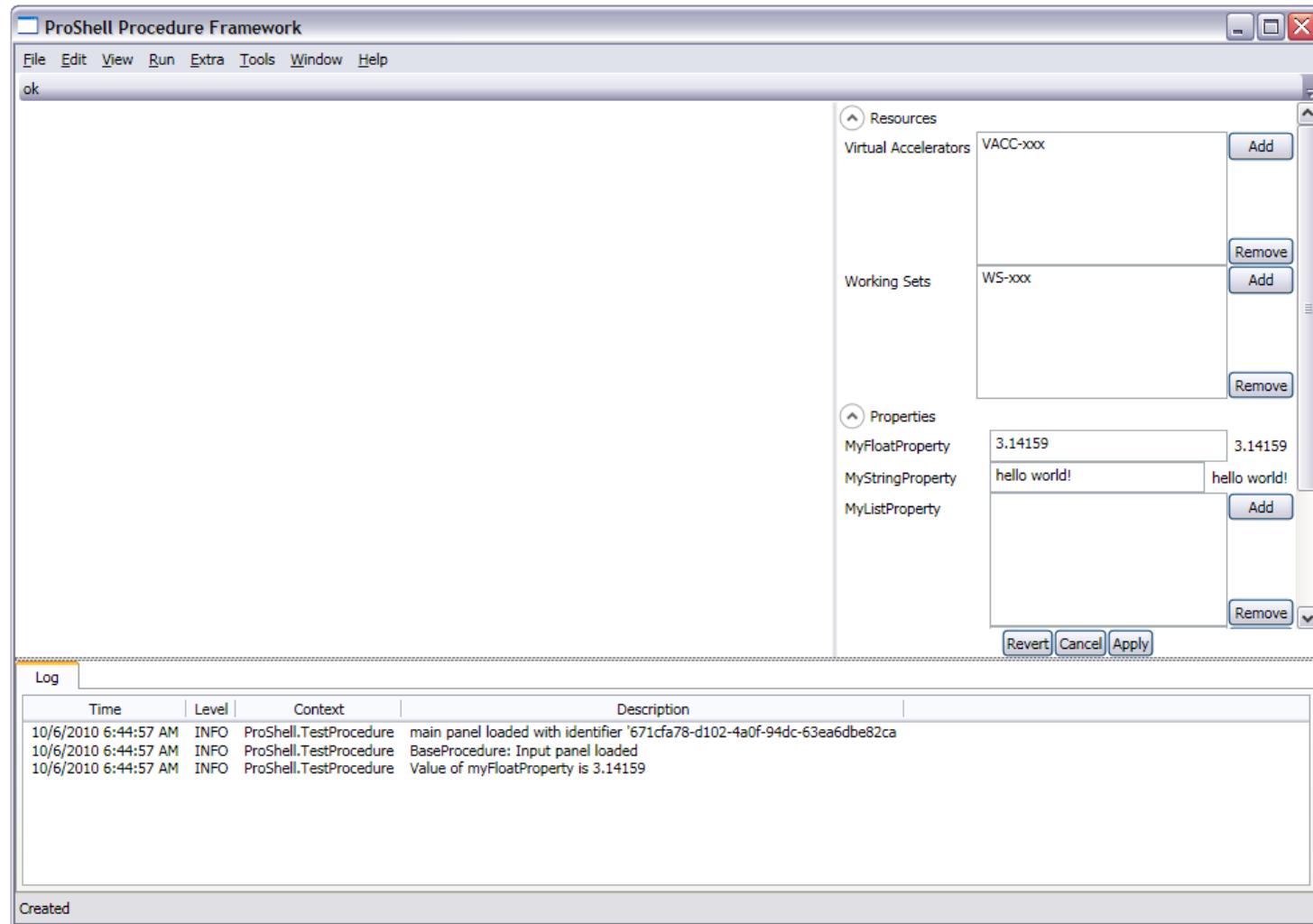
Overview



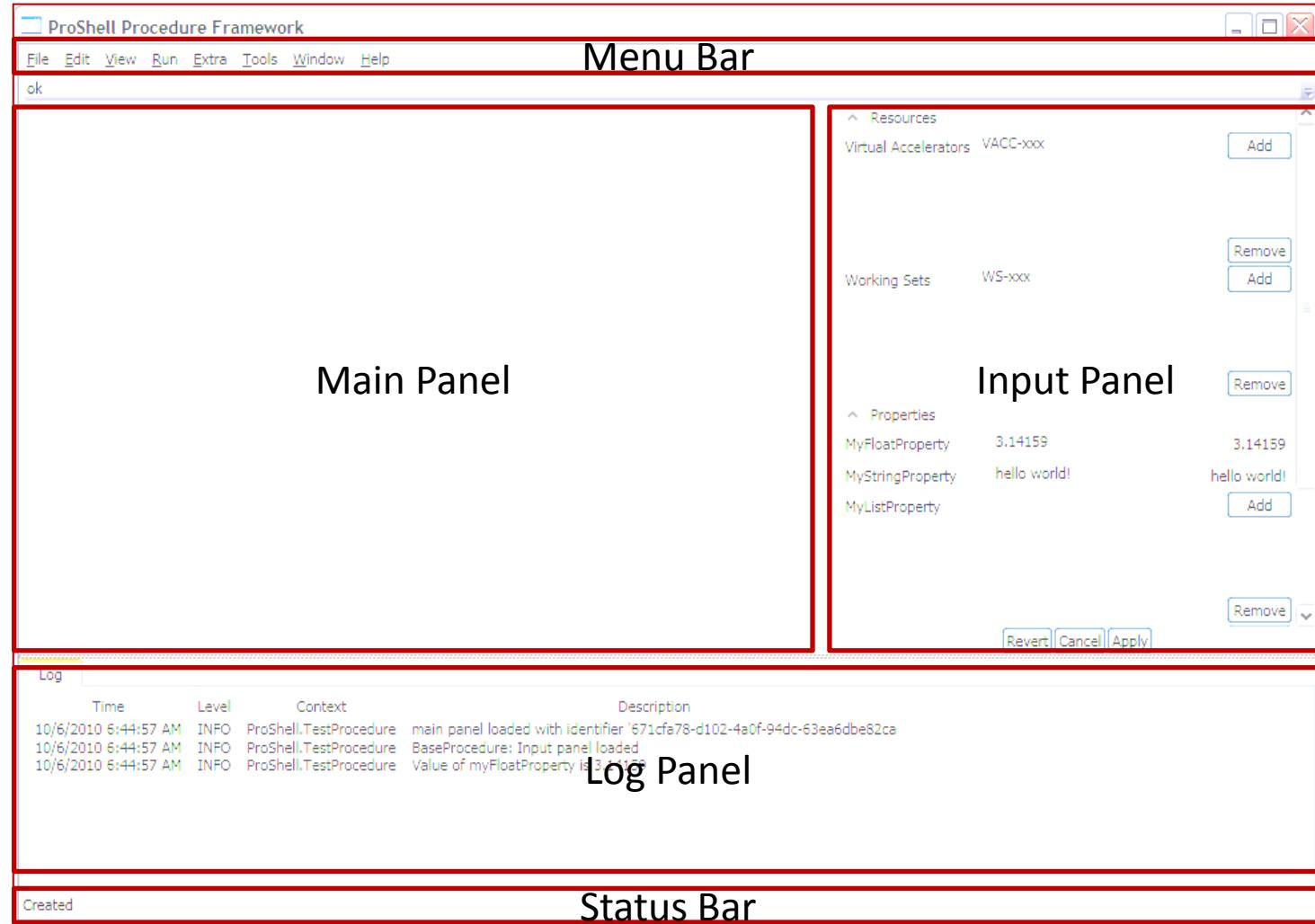
Architecture



Screenshot



Screenshot

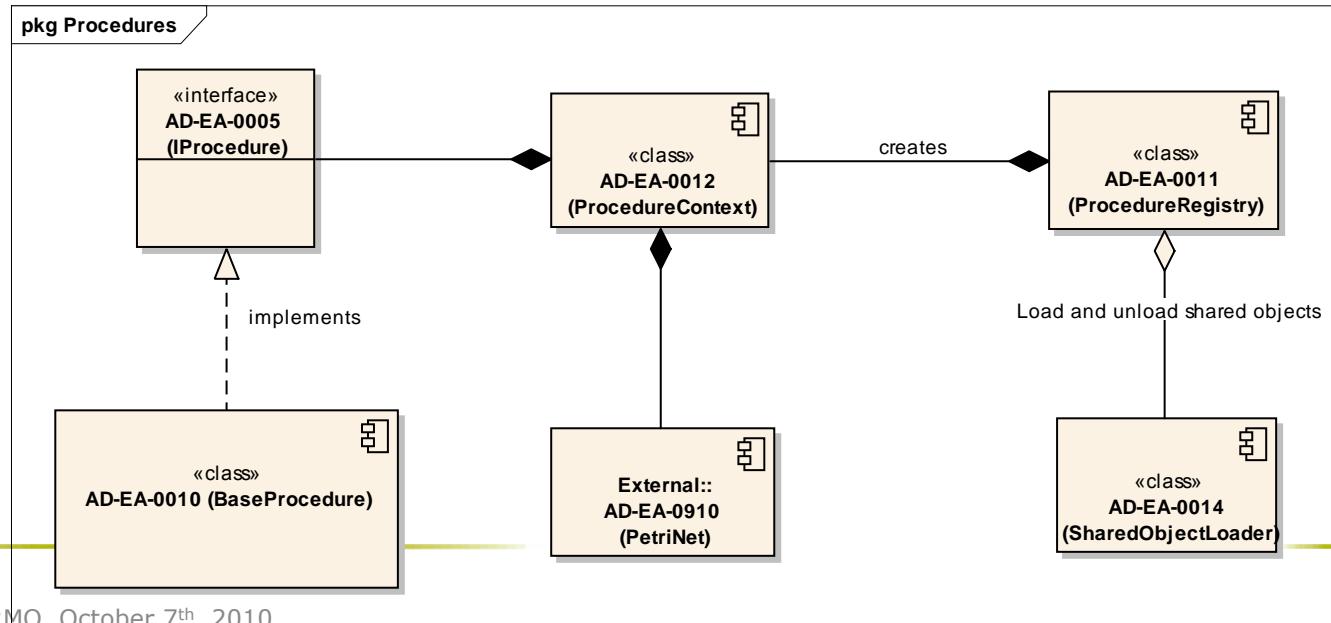


Procedure

- implements a **well-defined API** to perform a task
 - Example: „Emittance measurement“
- operates on **resources** (devices, WS, VAccs)
- inherits from **BaseProcedure** that provides default implementations for each function
 - Loading **configuration** parameters
 - Generating the **graphical user interface** and handling on changes
 - **Allocating** of VAccs and Working Sets
- may **override default implementations** to customize functions
- Handling of **user events** (button pressed)

ProcedureContext

- Manages a minimal set of data required by every procedure
 - User Interface Elements
 - Reading Configuration
 - Provide logging capabilities
 - A coloured PetriNet used for executing a procedure

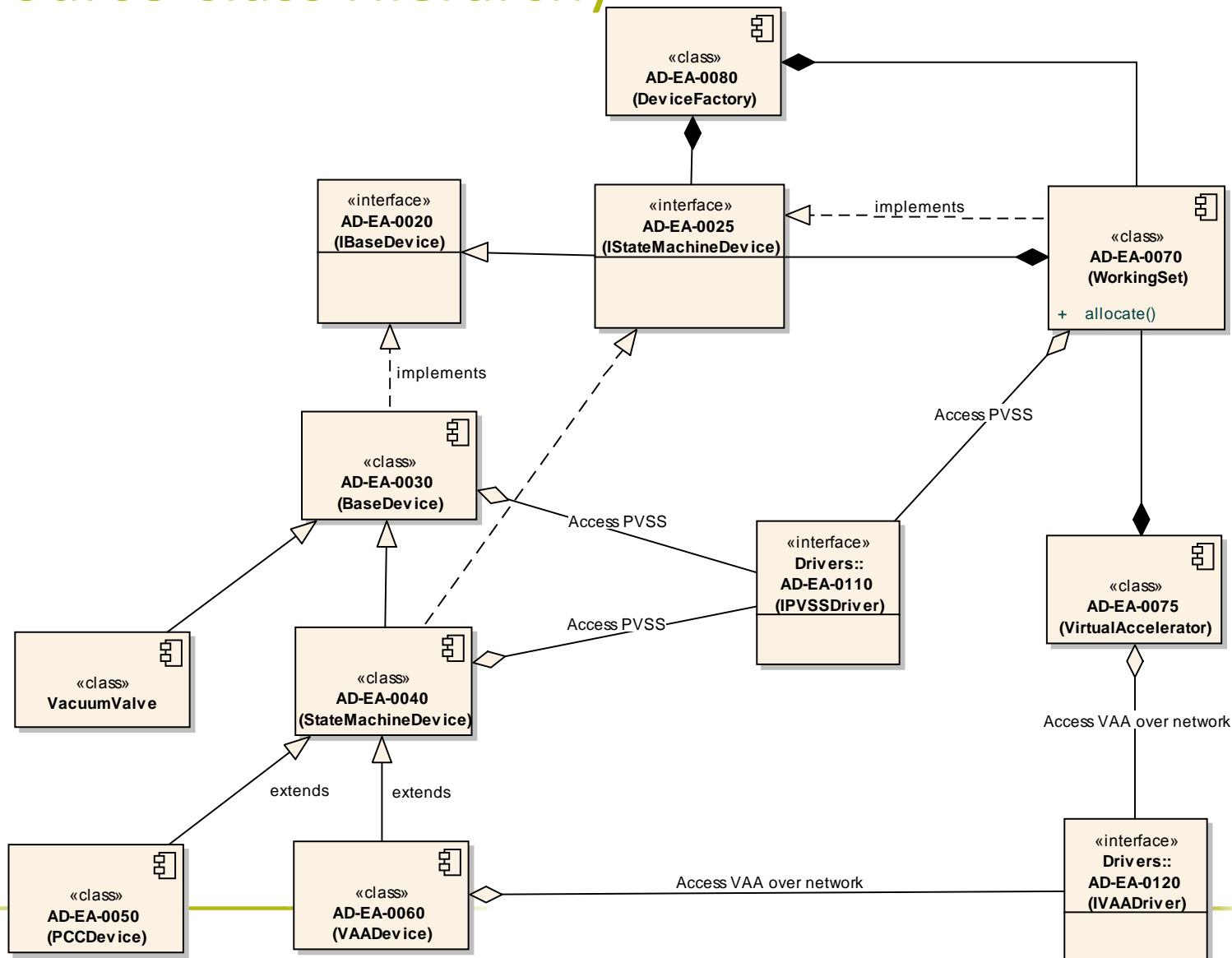


Resources

Procedures operate on the following types of resources

- **Virtual Accelerators**
 - List of working sets
- **Working Sets**
 - List of state machine devices
- **State Machine Devices**
 - May contain a list of base devices
 - E.g. Vacuum Control System for a sector
- **Base Devices**
 - E.g. Vacuum Valve

Resource Class Hierarchy

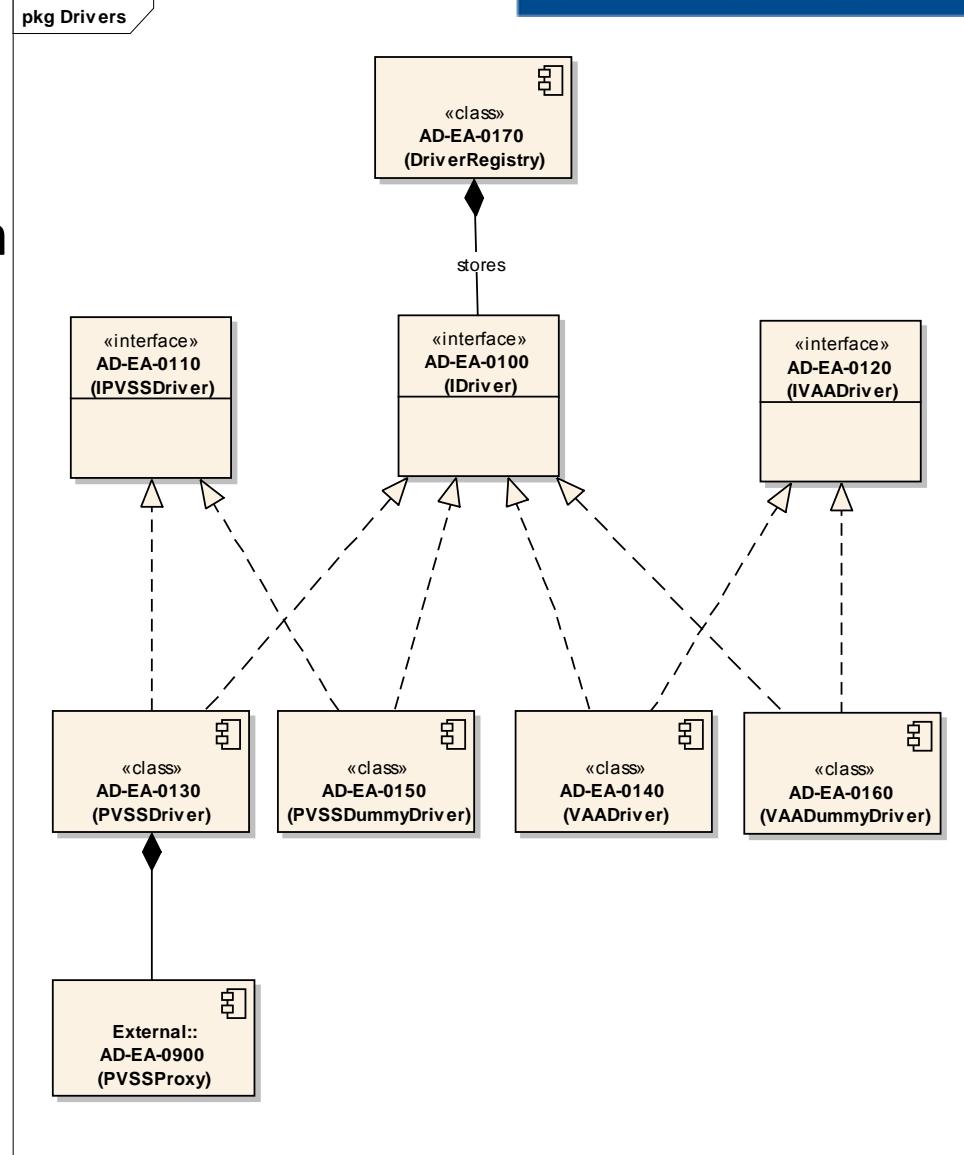


Devices

- **Base devices** provide an **API** to
 - Read default properties (e.g. Name)
- **State machine devices** provide an **API** to
 - control the state machine
 - change the mode
 - etc.
- **Additional device** types can be added with a **custom interface** that extends one of the previous APIs
 - API simplifies the source code in the procedures by not using PVSS dpGet/dpSet directly
 - Power converter: ground(), unground() functions
 - Beam stopper: moveIn() and MoveOut() functions

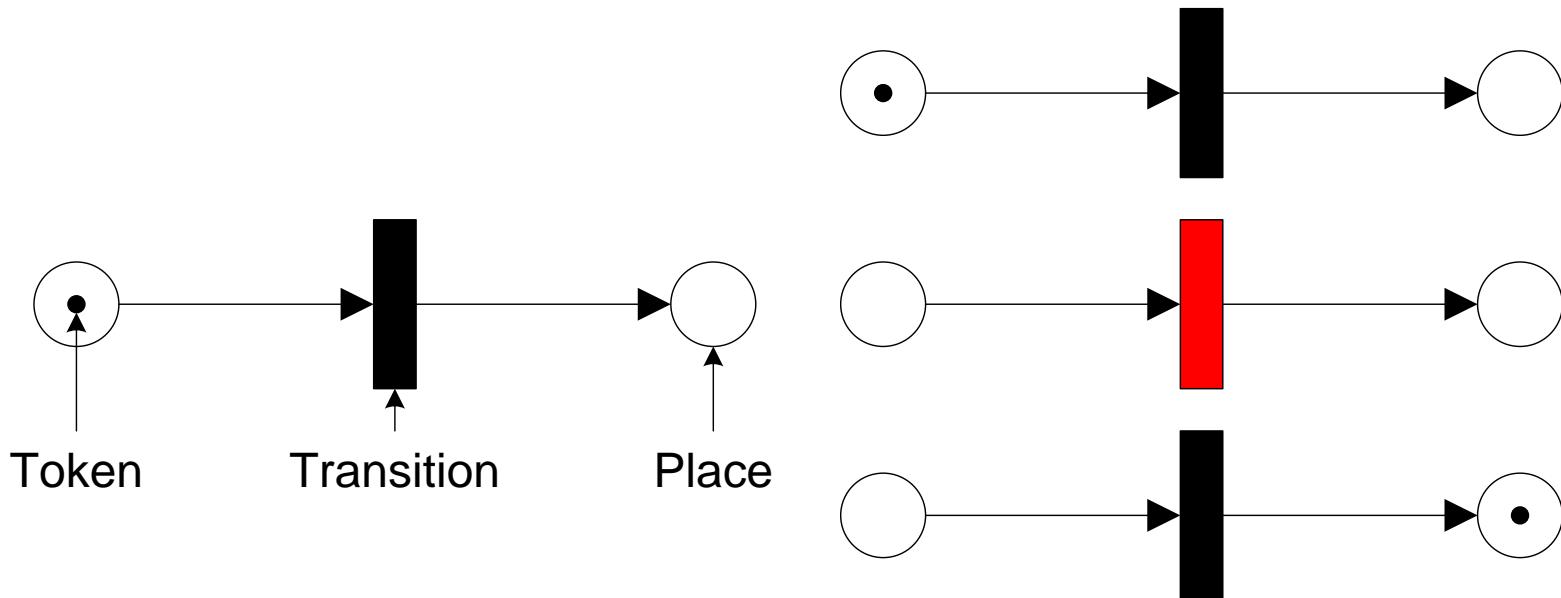
Drivers

- **Encapsulate** communication
 - E.g. PVSS, MTS, VAA, ...
- Two **types** of drivers
 - **Real drivers** communicate to the real system
 - **Dummy drivers** emulate the functionality (for testing **without real system**)



Petri-Nets

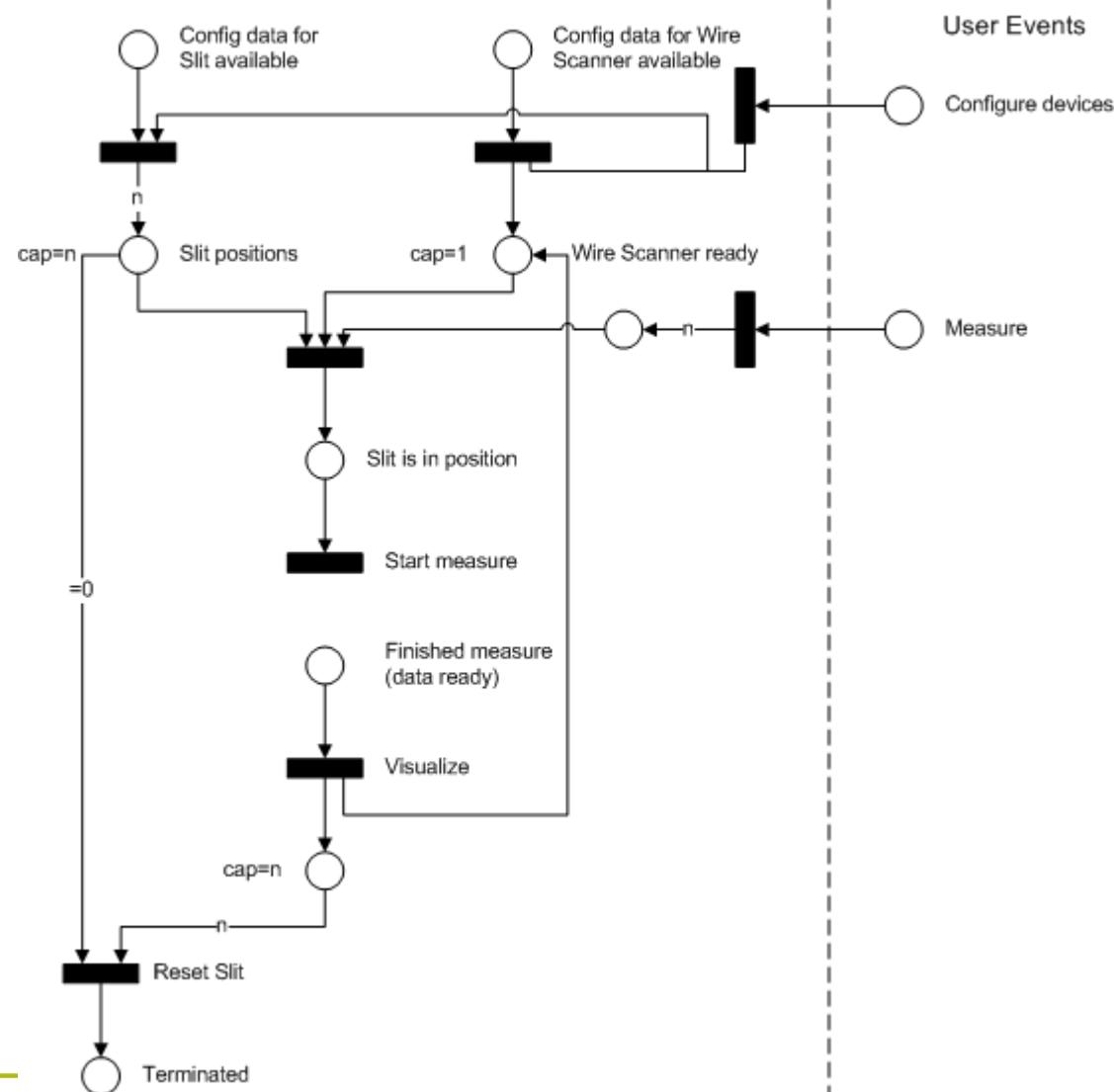
- A Petri net is a **mathematical model** language to describe a **distributed system**. It is a graph where nodes are either
 - **Transitions** represent events that may occur
 - **Places** represent conditions to fire transitions
 - Allows **parallel execution**



Coloured Petri-Nets

- Procedures use **Coloured-Petri Nets** where
 - Tokens may carry additional information (**coloured**)
 - **Callbacks** are attached to **transitions** and are executed **synchronously**
 - **Places** can be filled on **user action** (pressing a button) or **programmatically** (e.g. Asynchronous measurement finished)
 - Petri nets can be executed step-by-step (e.g. Debugging) or started where the net runs until its terminal condition is satisfied
 - **Parameterization** of the petri net

Example: Emittance Measurement





STATUS

Current Status

- First draft of ProShell **Enterprise Architect Model** contains
 - Initial **Requirements** gathering
 - Initial **Architecture and Design** document
- **Current implementation** of ProShell contains
 - A first draft of the **procedure interface** including
 - Loading of **configurations**
 - Automatic **creation input panel** based on configuration
 - Handling **multiple procedures** concurrently
 - Initial **Petri Net** support (programmatic creation and execution)
 - Driver interface provided with **dummy drivers**
 - Resource hierarchy available for the **generic devices**
 - Custom device interfaces to be provided on demand

Plan till December 2010

- Working on the **Enterprise Architect Model**
 - **requirements**
 - **architecture** and design
- Provide an initial ProShell **skeleton**
 - **Procedure interface** finalized
 - Eventually provide **integration** with **PVSS**
 - Dynamic loading of procedures (Cosylab)
 - Editor for Coloured PetriNets (Cosylab)

Summary

- **Ahead of Time**
 - None
- **In-Time**
 - ProShell implementation
- **Behind schedule**
 - ProShell requirements
 - ProShell architecture and design

Additional Information

- can be found on SVN
 - ES-100722-a-RMO ProShell Enterprise Architect Model
 - Source code can be found at /trunk/SCS/ProShell

Questions?



ADDITIONAL SLIDES