

Towards Sampling Complex Actions

Kades, Gärtner, Gasenzer, Pawłowski, [arXiv:2106.09367](https://arxiv.org/abs/2106.09367)

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Motivation

Sign problem

- Goal: Numerically access observables

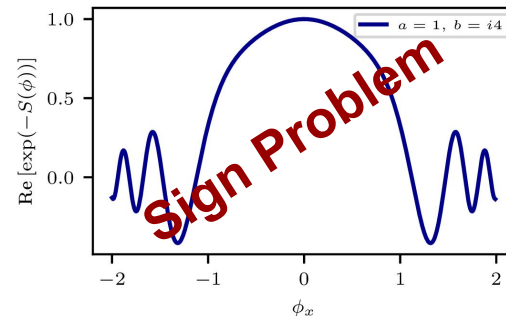
$$\langle \mathcal{O}(\phi) \rangle = \frac{1}{Z} \int \mathcal{D}\phi \mathcal{O}(\phi) e^{-S(\phi)}$$

with $S(\phi) \in \mathbb{C}$

- Problem:

No probability distribution!

- Standard Monte Carlo algorithms fail, with one exception: Langevin dynamics



Complex Langevin dynamics

$$\langle \mathcal{O}(\phi) \rangle_\rho = \int_a^b d\phi \mathcal{O}(\phi) \rho(\phi)$$

What is complex Langevin dynamics:

G. Parisi, Phys. Lett. B 131, 393–395 (1983)

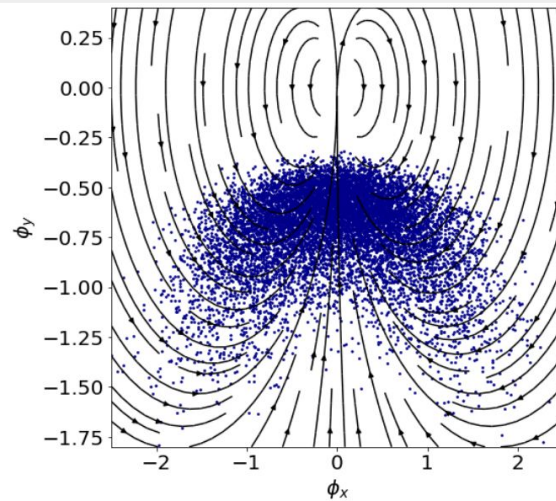
Klauder, Recent Developments in High-Energy Physics (1983) pp. 251–281.

➤ A sampling process that allows the numerical computation of complex action problems.

Update rules (CLE)

$$\frac{d\phi_x}{d\tau} = - \left. \frac{\delta S_{\text{Re}}(\phi)}{\delta \phi} \right|_{\phi_x + i\phi_y} + \eta$$

$$\frac{d\phi_y}{d\tau} = - \left. \frac{\delta S_{\text{Im}}(\phi)}{\delta \phi} \right|_{\phi_x + i\phi_y}$$



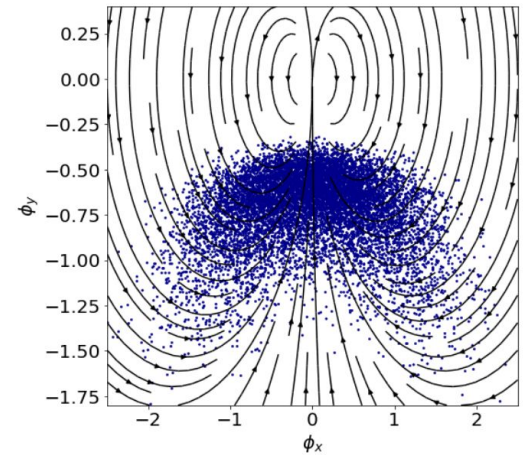
Observables

$$\rightarrow \langle \mathcal{O}(\phi) \rangle_\rho = \langle \mathcal{O}(\phi_x + i\phi_y) \rangle_P \simeq \frac{1}{N} \sum_i^N \mathcal{O}(\phi_{x,i} + i\phi_{y,i}) \quad P(\phi_x, \phi_y; \theta)$$

Complex Langevin dynamics

Big advantage:

- Appeal of general applicability (model-independent)



Problems (model-specific):

- Potential convergence to unphysical fixed points / solutions
- Numerical instabilities

Ambjørn and S.-K. Yang, Phys. Lett. B 165, 140–146 (1985)
Nishimura and S. Shimasaki, Phys. Rev. D 92, 011501 (2015)
Hayata et al., Nucl. Phys. B 911, 94–105 (2016)
Salcedo, Phys. Rev. D 94, 114505 (2016)
E. Seiler, EPJ Web Conf. 175, 01019 (2018)
Nagata et al., J. High Energ. Phys. 2018, 4 (2018)

Complex Langevin dynamics

Theoretical understanding:

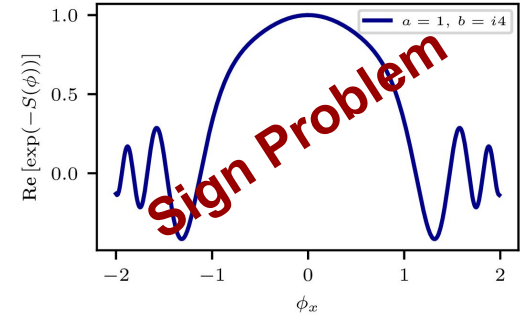
- Rather heuristic derivation from Langevin dynamics
- Subsequent theoretical justification and derivation of criteria for correctness based on Fokker-Planck equation

Aarts, J. High Energy. Phys. 2008, 018–018 (2008)
Aarts et al., Phys. Rev. D 81, 054508 (2010).

- No thorough understanding in terms of a Markov chain Monte Carlo algorithm

Key question:

- How to define a sampling process based on the first principles of a Markov chain Monte Carlo algorithm (detailed-balance equation) for complex action problems?



$$S(\phi) \in \mathbb{C}$$

Key insights

$$\langle \mathcal{O}(\phi) \rangle = \frac{1}{Z} \int \mathcal{D}\phi \mathcal{O}(\phi) e^{-S(\phi)}$$

Key insights for a possible sampling process

- Reformulation as a **mean over several integrals in the complex plane**

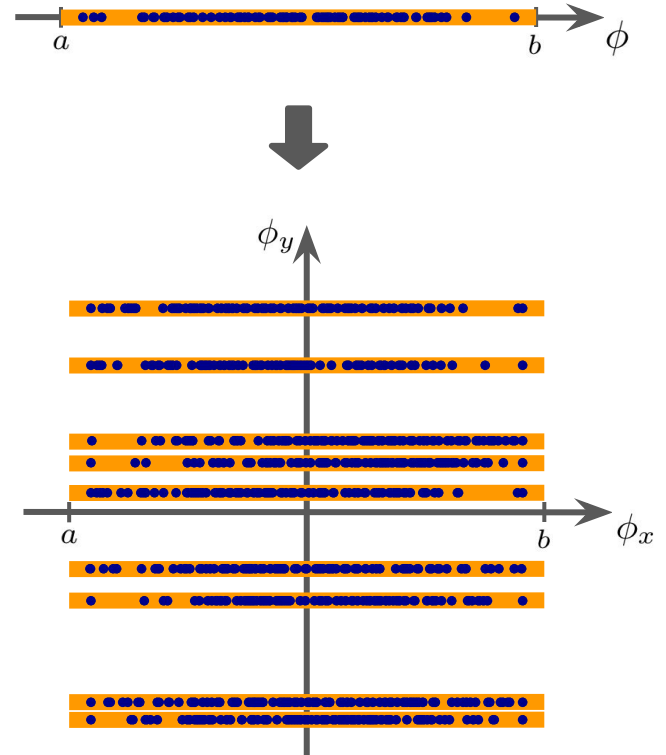
$$\langle \mathcal{O}(\phi) \rangle_\rho = \int_a^b d\phi \mathcal{O}(\phi) \rho(\phi)$$



$$\phi = \phi(\phi_x) = \phi_x + i\phi_{y,i}, \quad d\phi = d\phi_x$$



$$\langle \mathcal{O}(\phi) \rangle_\rho = \frac{1}{N} \sum_{i=1}^N \int_{a-i\phi_{y,i}}^{b-i\phi_{y,i}} d\phi_x \mathcal{O}(\phi_x + i\phi_{y,i}) \rho(\phi_x + i\phi_{y,i})$$

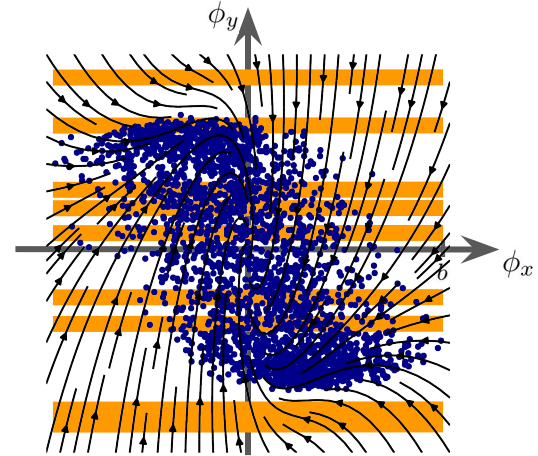


$$\langle \mathcal{O}(\phi) \rangle = \frac{1}{Z} \int \mathcal{D}\phi \mathcal{O}(\phi) e^{-S(\phi)}$$

Key insights for a possible sampling process

- Mixing the sampling process of each integral allows the definition of **real-valued transition probabilities**

- Key for an interpretation as a Markov chain Monte Carlo algorithm



- Basis for a numerical sampling scheme in the complex plane

$$\langle \mathcal{O}(\phi) \rangle_\rho = \frac{1}{MN} \sum_{i=1}^{MN} \mathcal{O}(\phi_{x;i} + i\phi_{y;i})$$

Implications

Main Results

$$\langle \mathcal{O}(\phi) \rangle_\rho = \frac{1}{MN} \sum_{i=1}^{MN} \mathcal{O}(\phi_{x;i} + i\phi_{y;i})$$

➤ Mathematical framework for a Markov chain Monte Carlo sampling algorithm for complex action problems based on **four constraints**:


1. Satisfaction of the following detailed-balance equation for a fixed hidden state w

Adapted detailed-balance equation

$$= p(v', w)g(w'|v, v', w)T(v|v', w). \quad (37)$$

2. The distribution ρ is updated with an infinitesimal step in *Infinitesimally small step sizes in imaginary direction*

3. The $\langle \mathcal{O}(\phi) \rangle_\rho = \int_{a-i\phi_y}^{b-i\phi_y} d\phi_x \mathcal{O}(\phi_x + i\phi_y) \rho(\phi_x + i\phi_y)$
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4. The distribution $p(v, w)$ and the transition probabilities T and g need to satisfy μ constraint, cf. Eq. (26),

Equilibrium

$$p(v', w', \tau) \stackrel{!}{=} \int_{J'} p(v, w, \tau) g(w'|v', v, w) T(v'|v, w). \quad (38)$$

➤ Substitution sampling algorithm

Main Results

The substitution sampling algorithm

- allows a novel **mathematically well-founded** derivation of complex Langevin dynamics as a Markov chain Monte Carlo algorithm

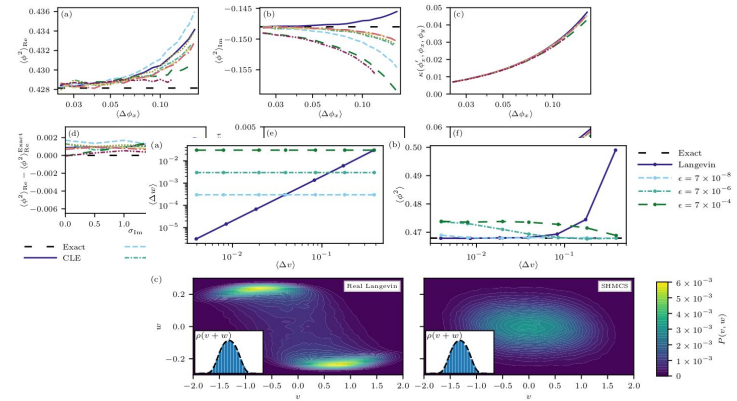
$$\begin{aligned}\frac{d\phi_x}{d\tau} &= -\left. \frac{\delta S_{\text{Re}}(\phi)}{\delta\phi} \right|_{\phi_x+i\phi_y} + \eta \\ \frac{d\phi_y}{d\tau} &= -\left. \frac{\delta S_{\text{Im}}(\phi)}{\delta\phi} \right|_{\phi_x+i\phi_y}\end{aligned}$$

- is in strong contrast to the standard, rather heuristic derivation from Langevin dynamics

Main Results

Proof of concept of the mathematical framework by the derivation of

- complex Langevin-like algorithms (similar to CLD)
- another algorithm called substitution Hamiltonian Monte Carlo algorithm (only for real actions)



- Why is it interesting to take a closer look at a Markov chain Monte Carlo framework for complex action problems?

Conclusion and Outlook

Appeal of a Markov chain Monte Carlo algorithm for complex action problems:

- Explicit access to the underlying sampling process
- Finite step sizes in configuration space
- Potential solution to the problem of wrong convergence

Possible future developments:

- Derivation of novel sampling algorithms for complex action problems
- Potential improvement of the presented sampling framework by more theoretical insights



Thank you!