# Particle identification method in the BM@N experiment

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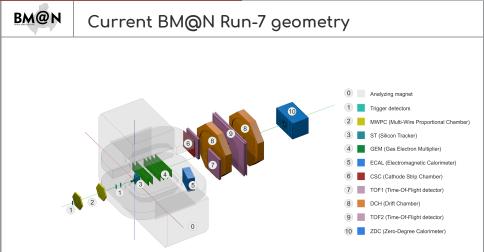
- Particle identification in the BM@N experiment
- Detector system of the BM@N setup
- Adding realistic effects to event simulation
- Distance method implementation
- Summary
- The work is supported by Russian Foundation for Basic Research grant 18-02-40104 mega.





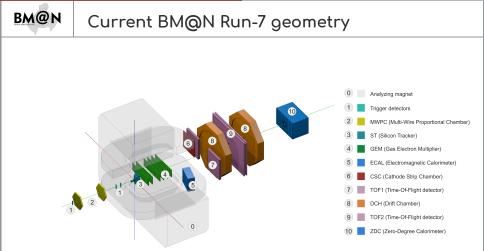
The BM@N (Baryonic Matter at the Nuclotron) is aimed at studying heavy ion collisions with fixed targets.

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#### Silicon + GEM (Gas Electron Multiplier)

Allows to reconstruct the momentum along the trajectories of charged particles. Rigidity  $= \rho/q$ 

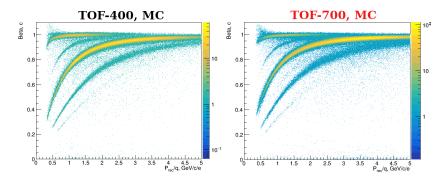


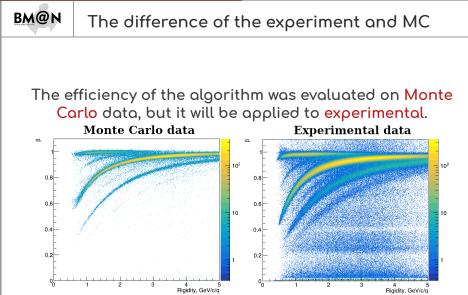
#### TOF(Time-Of-Flight detectors

Allows to calculate the velocity taking into account the measurement of the time.  $\beta = l/tc$ 



The implemented method based on magnetic **rigidity** and particle **velocity**, determines the **probability** for a particle to have a certain type.





Input data are significantly different.

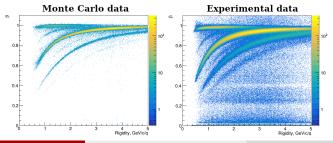
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How to fix

BM@N

In order to bring the properties of the simulated data closer to experimental, we need

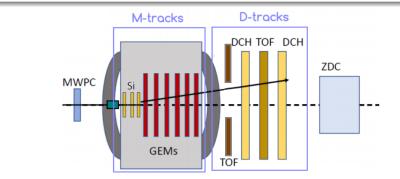
- Implement selection procedures reliable experimental data
- Determine the characteristics of good experimental tracks
- Add realistic effects to Monte Carlo





#### **Re-extrapolating**

# Propagate the inner track through its hits in silicon and GEM.





#### Matching

Tracks from the magnet are matched with the DCH tracks and hits in the TOF detector.

- $\bullet~$  Matching detector chain GEM  $\rightarrow$  DCH  $\rightarrow$  TOF700 ~
- The track is extrapolated to each hit in the detector plane
- Calculate residuals  $\Delta X = x_{track} x_{hit}; \Delta Y = y_{track} y_{hit};$
- Find the nearest hit

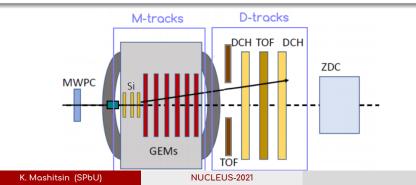


#### Back propagation

Extrapolate track from TOF detector to the vertex.

- Get time of flight from a TOF hit
- Calculate velocity  $\beta = l/tc$

Save track parameters if it belongs to the vertex range

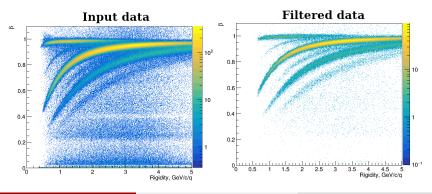


11/31

### Before/After

BM@N

- Vertex in range  $V_{\text{x}} \in (-2,4) \text{cm}; V_{\text{y}} \in (-6,-1)\text{cm}; V_{\text{z}} \in (-5,5)\text{cm}$
- $\ge 1$  Silicon +  $\ge 4$  GEM + 1 DCH + 1 TOF Hits
- Back extrapolation with parameter update

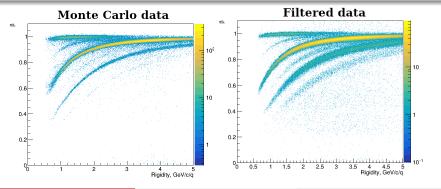


Exp and MC comparison parameters

#### Data parameters

BM@N

- Number of hits in Silicon and GEM tracks
- Station efficiency
- Residuals





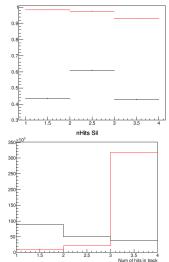
#### Comparison of Exp and MC

#### Monte Carlo

- Generator: DCMSMM
- System: Ar + Cu
- Energy: 3.2 AGeV
- Selected tracks only

#### Exp data

- System: Ar + Cu
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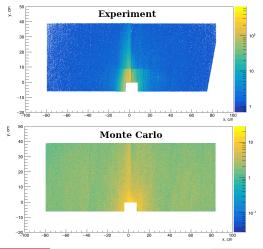


Efficiency of silicon stations

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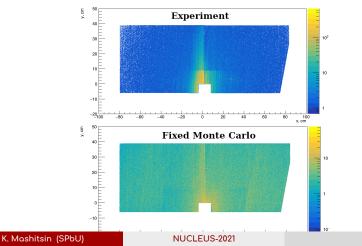
# The efficiency of a station depends on 1)Tracks passed through the station and 2) Tracks in acceptance.



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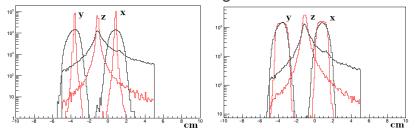


- A list of non-working strips was received
- Strips from this list were disabled during the simulation stage.





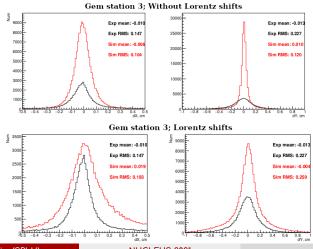
### Initially, the peaks of the vertex coordinates are very narrow and high.



The vertex width was obtained from experimental data and added to the simulation.



## Lorentz shifts simulate the displacement of electron avalanches in a magnetic field. Residuals become wider.





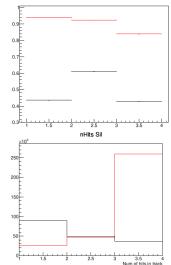
#### Comparison of Exp and MC

#### Monte Carlo

- Generator: DCMSMM
- System: Ar + Cu
- Energy: 3.2 AGeV
- Smearing Vertex
- Lorentz Shifts
- Dead strips

#### Exp data

- System: Ar + Cu
- Energy: 3.2 AGeV

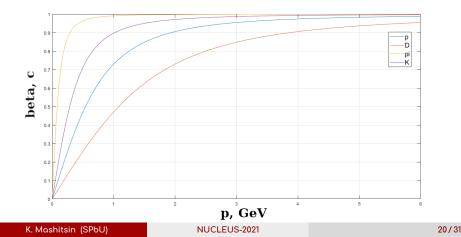


Efficiency of silicon stations

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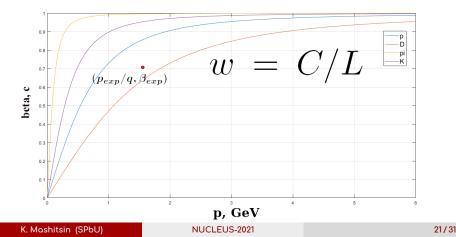
Method based on calculation of distance between experimental velocity and theoretical one for each particle type.



### PID algorithm description

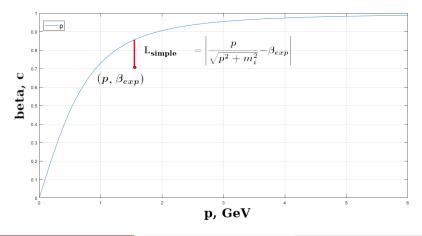
BM@N

The probability with which a particle will belong to a certain type is calculated by the formula  $w_i=C/L_i$ , where  $C=1/\sum \frac{1}{L_i}$  and L is the distance to the theoretical curve.

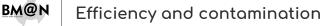


BM@N PID algorithm description

Distance is calculated as the difference between theoretical and experimental velocity  $L_i = |\beta_{th}^i - \beta_{exp}|$ .



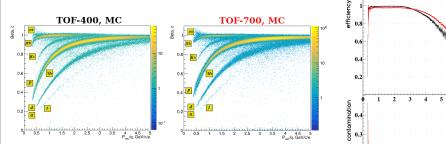
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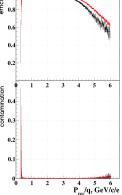
 $\begin{array}{l} \mbox{Efficiency} = \frac{N_{true}}{N_{sim}} \\ \mbox{Contamination} = \frac{N_{folse}}{N_{id}} \\ N_{true} \mbox{-} number of correctly identified particles of a given type} \\ N_{folse} \mbox{-} number of folsely identified particles of a given type} \\ N_{sim} \mbox{-} total number of simulated particles of a given type} \\ N_{id} = N_{true} + N_{folse} \mbox{-} total number of particles identified as a given type} \end{array}$ 

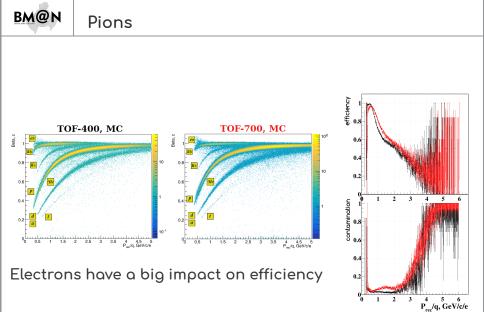
Protons

BM@N



Protons are mixing with kaons and pions after 3 GeV/c but are still well identified

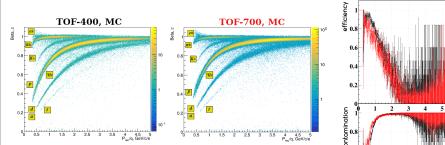




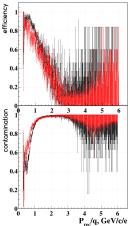
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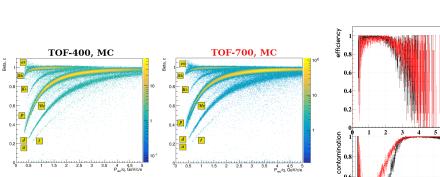
**Electrons** 

BM@N

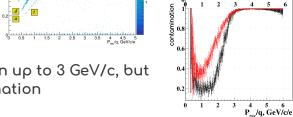


It is practically impossible to separate electrons due to the closeness of the pion line



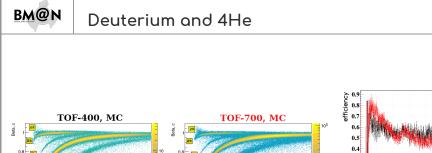


Quite good separation up to 3 GeV/c, but high level of contamination



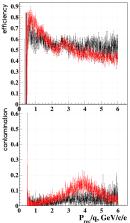
BM@N

Kaons





3.5 4 4.5 5 P..../g. GeV/c/e 0.4



10

4 4.5 5 P.,.../q, GeV/c/e

0.6

0.4

0.2

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0 0.5 1 15 2 25 3 3



#### Strengths

- Executes quickly
- Gives a probabilistic estimate
- High efficiency for protons and kaons at low momenta.

#### Weaknesses

- Decreased efficiency when merging clusters at large momenta
- Cannot separate pi from e
- Not enough information to split d and  $\alpha$

#### Ways to improve efficiency

• Take into account the a priori particle distribution densities depending on the momentum



- Algorithms for filtering experimental data have been implemented
- Realistic effects have been added to the modeling process
  - Smearing Vertex
  - Lorentz Shifts
  - Dead strips
- Particle identification method was implemented and tested

### Thank you for the attention!