



Low-Latency High-Bandwidth Circuit and System Design for Trigger Systems in High Energy Physics

February 26th, 2021

PhD public presentation of Marcos Vinicius Silva Oliveira

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Agenda

- ▶ Introduction
- ▶ Requirements
- ▶ Part I: Data Transfer
- ▶ Part II: Data Processing
- ▶ Summary

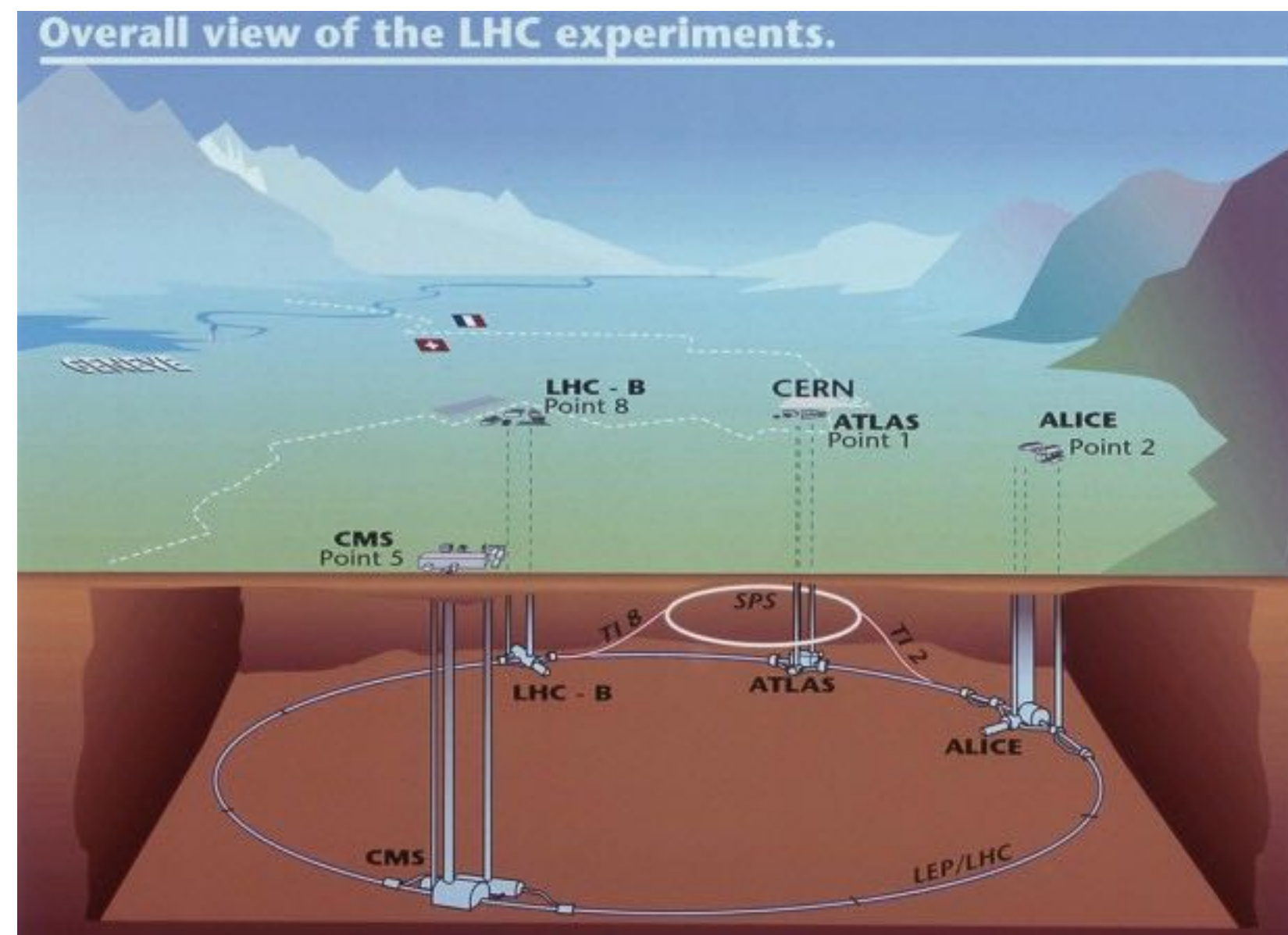
Why We Build Particle Colliders?

- ▶ Caveman can't open a watch, but he can break many
- ▶ He can analyse the debris from each of the collisions



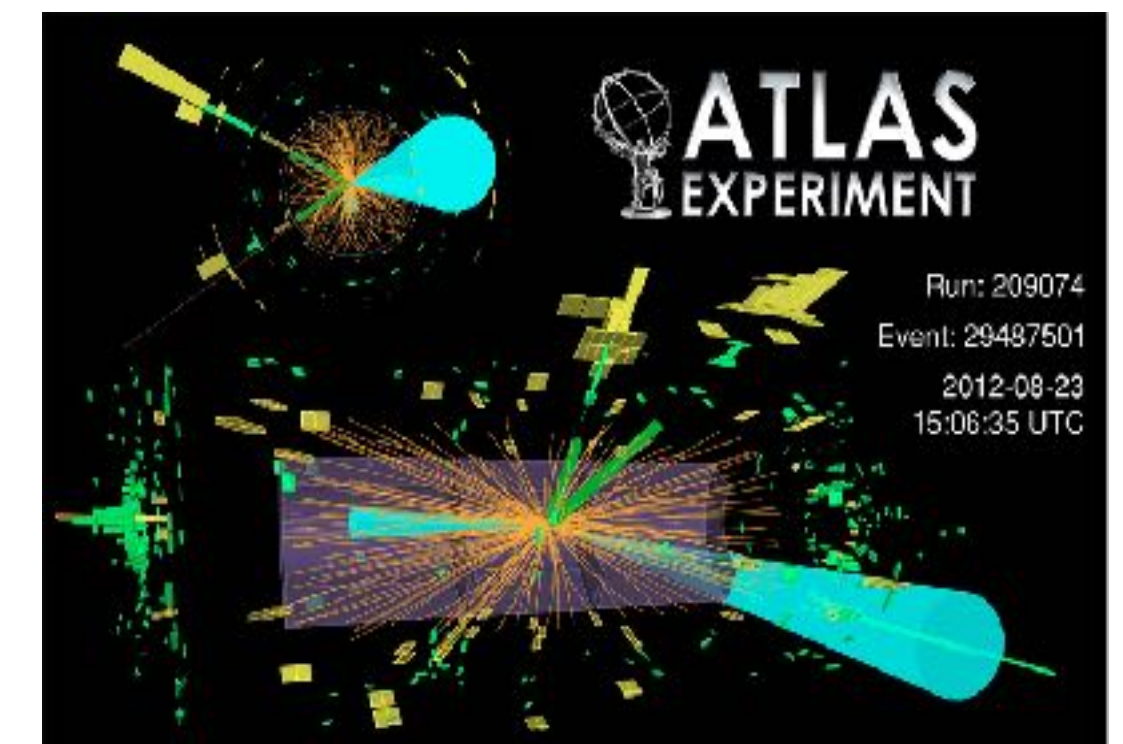
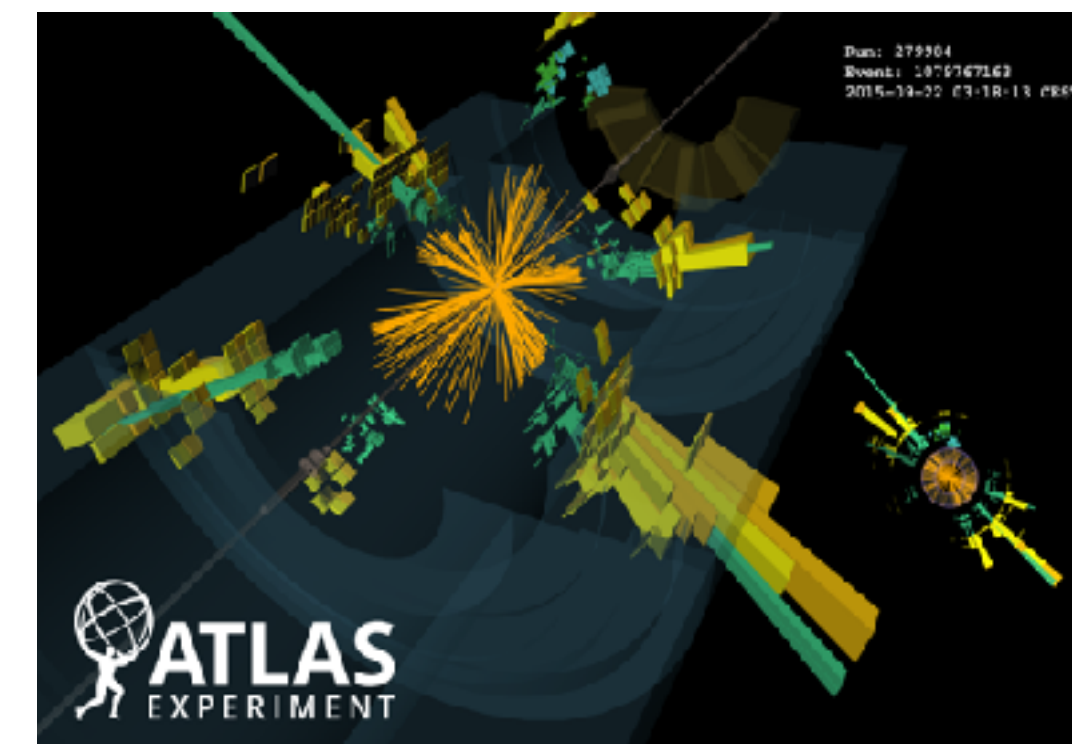
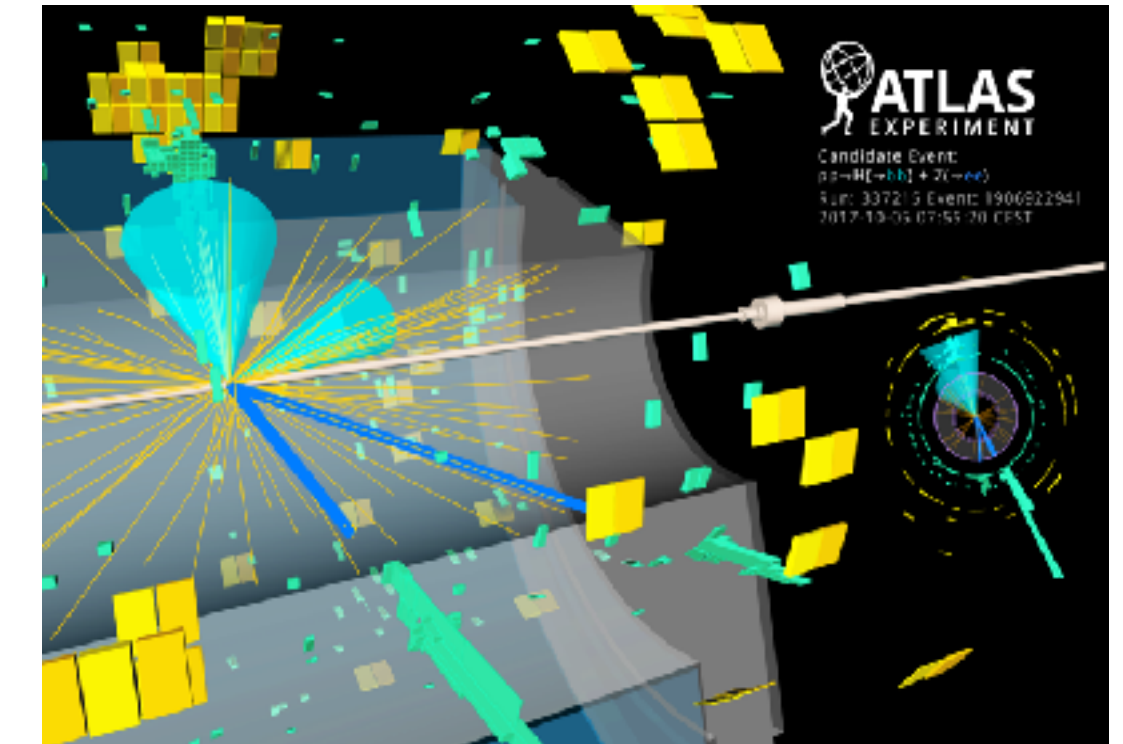
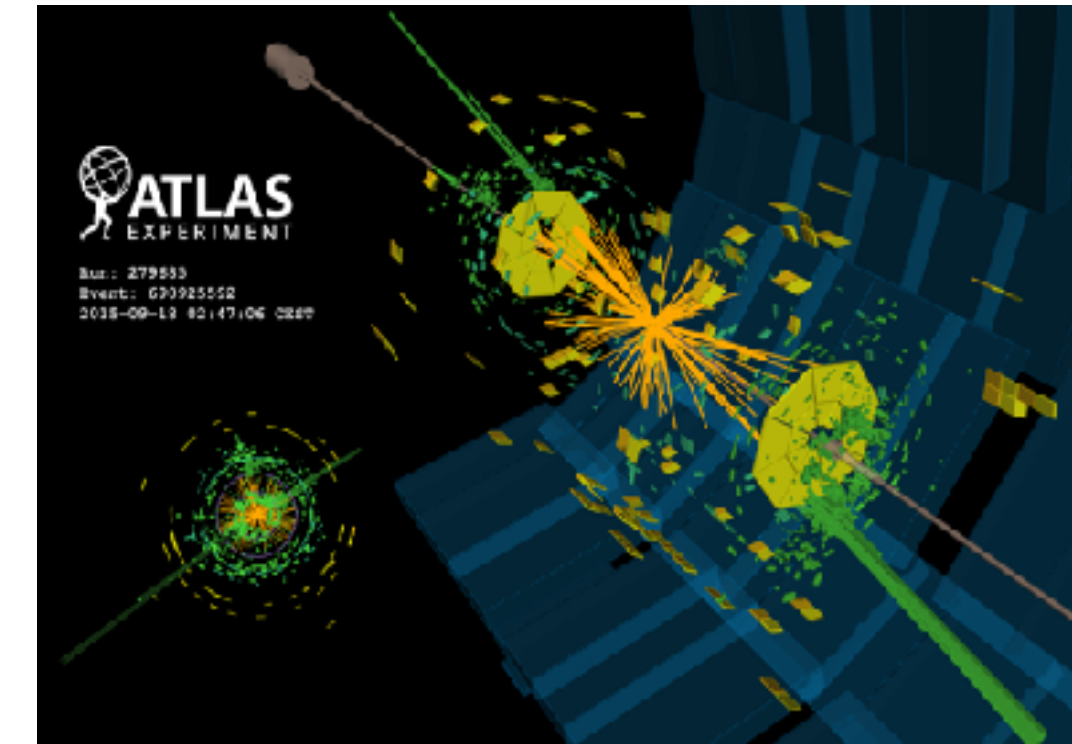
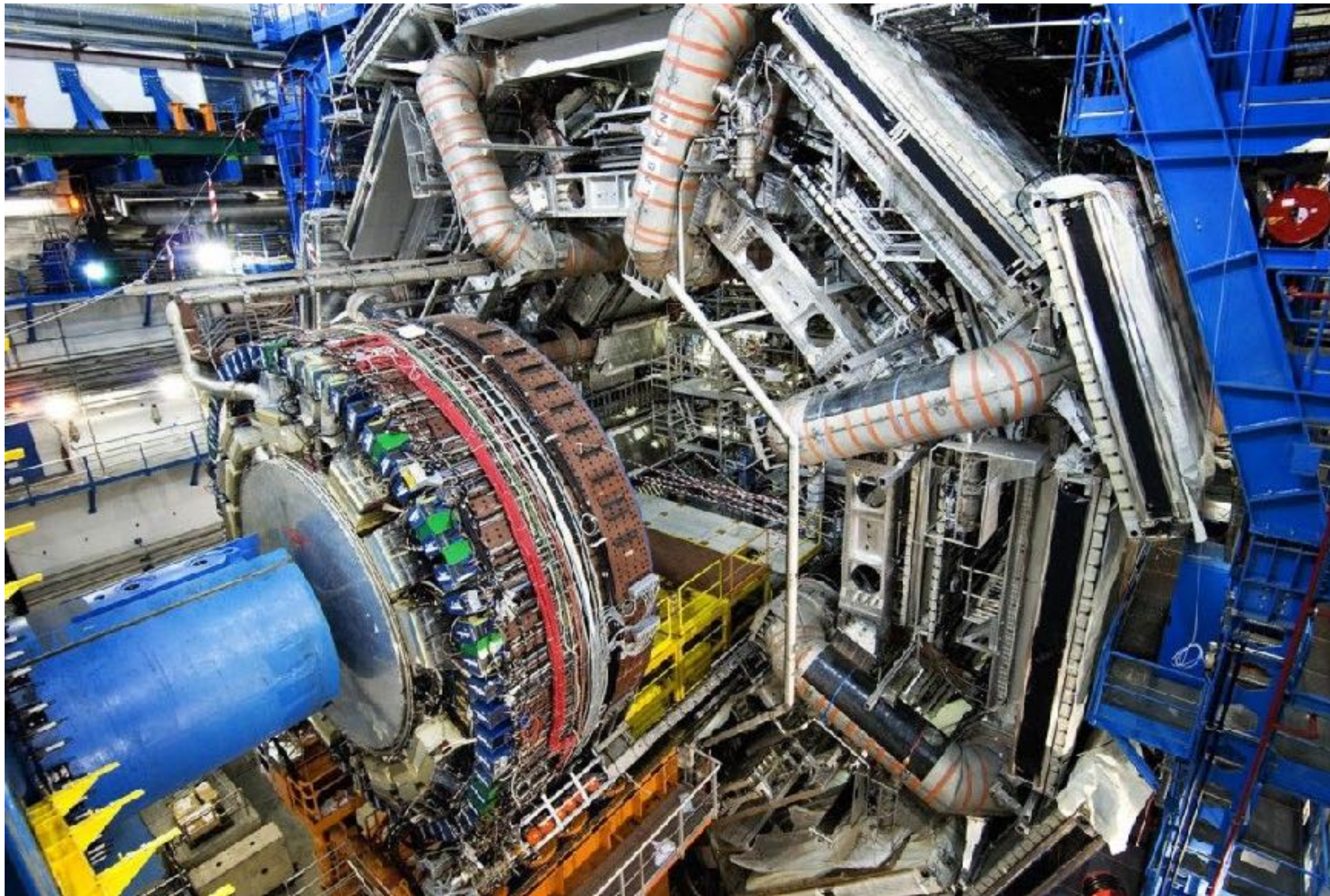
Large Hadron Collider (LHC)

- ▶ World's largest particle accelerator → 40 M collisions per second
- ▶ 100 m underground 27-kilometre ring of superconducting magnets



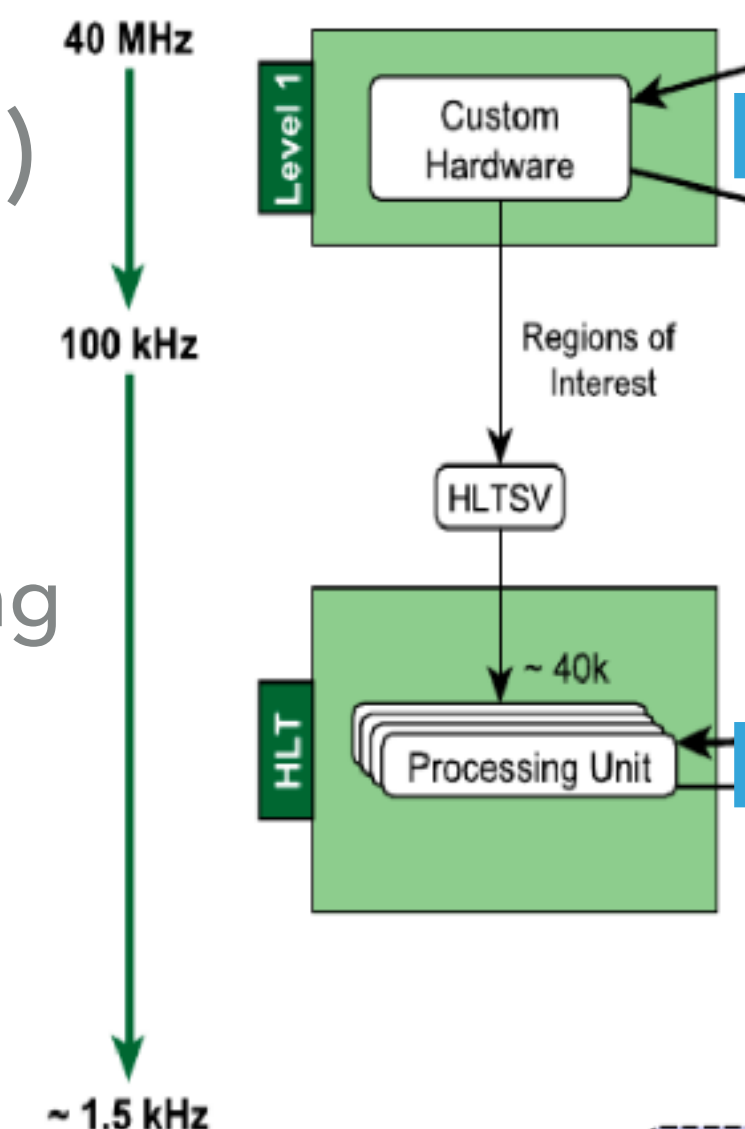
ATLAS

- ▶ ATLAS is the largest detector of the LHC
- ▶ Capture the debris from 40 M bunch crossings per second



Trigger

- ▶ Detector data → 100'000 CDs per second [1]
- ▶ It corresponds to a pile of CDs to the moon in 3 months [1]
- ▶ Higgs Boson decay → only one every 3h [1]
- ▶ Data are selected in two stages:
 - ▶ Level-1: Custom electronics (FPGA, ASIC)
 - ▶ 40 million → 100 thousand per second
 - ▶ Processing $\Delta t = 1.5 \mu s$ → 66k faster than eye blinking
 - ▶ HTL: Commercial computers
 - ▶ 100 thousand → 1 thousand per second ($\Delta t < 1s$)



[1] ATLAS Experiment, "ATLAS Fact Sheet." 2011. Available [here](#).

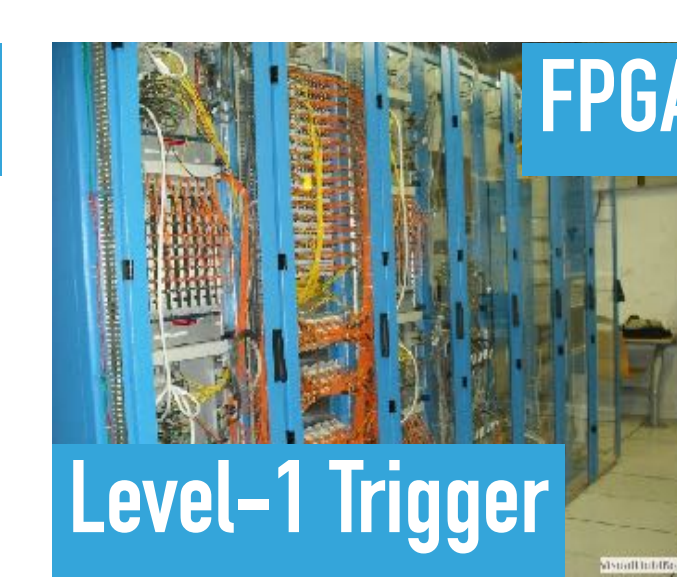
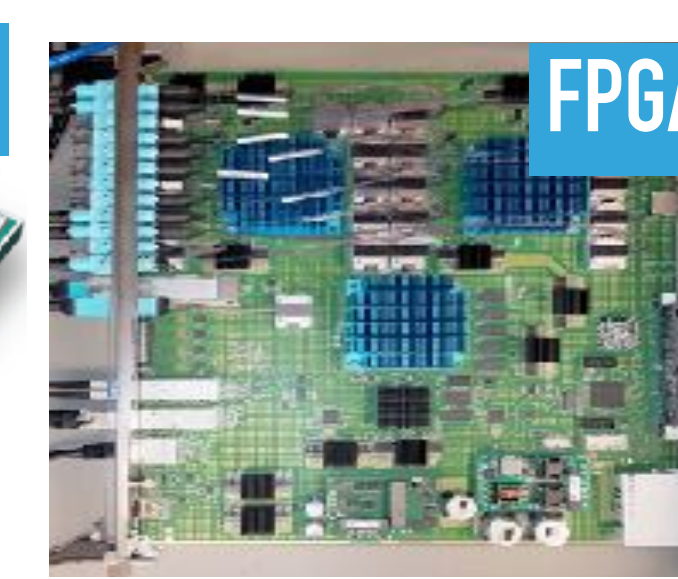
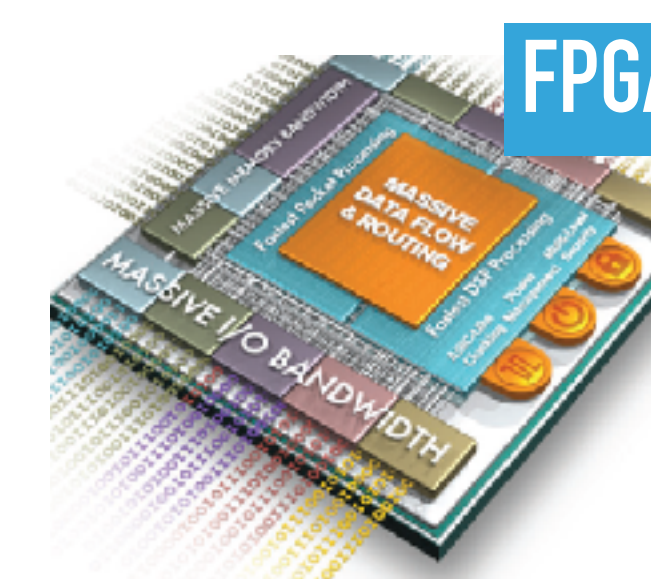
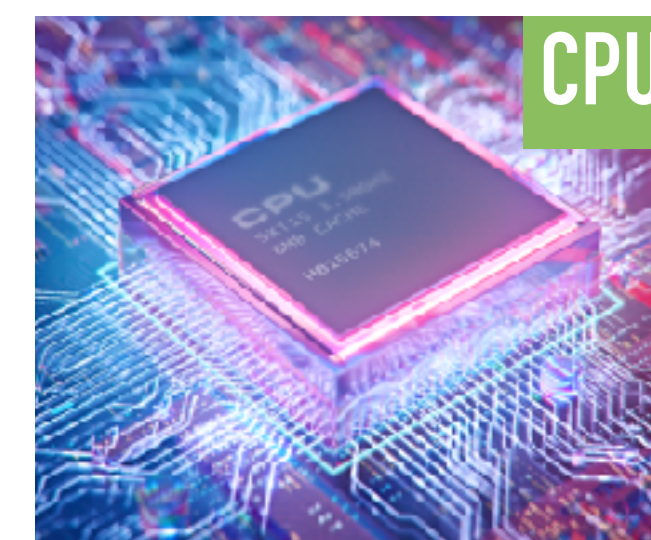
Field-Programmable Gate Array (FPGA)

► Programming with CPUs

- One processor follows instructions one by one

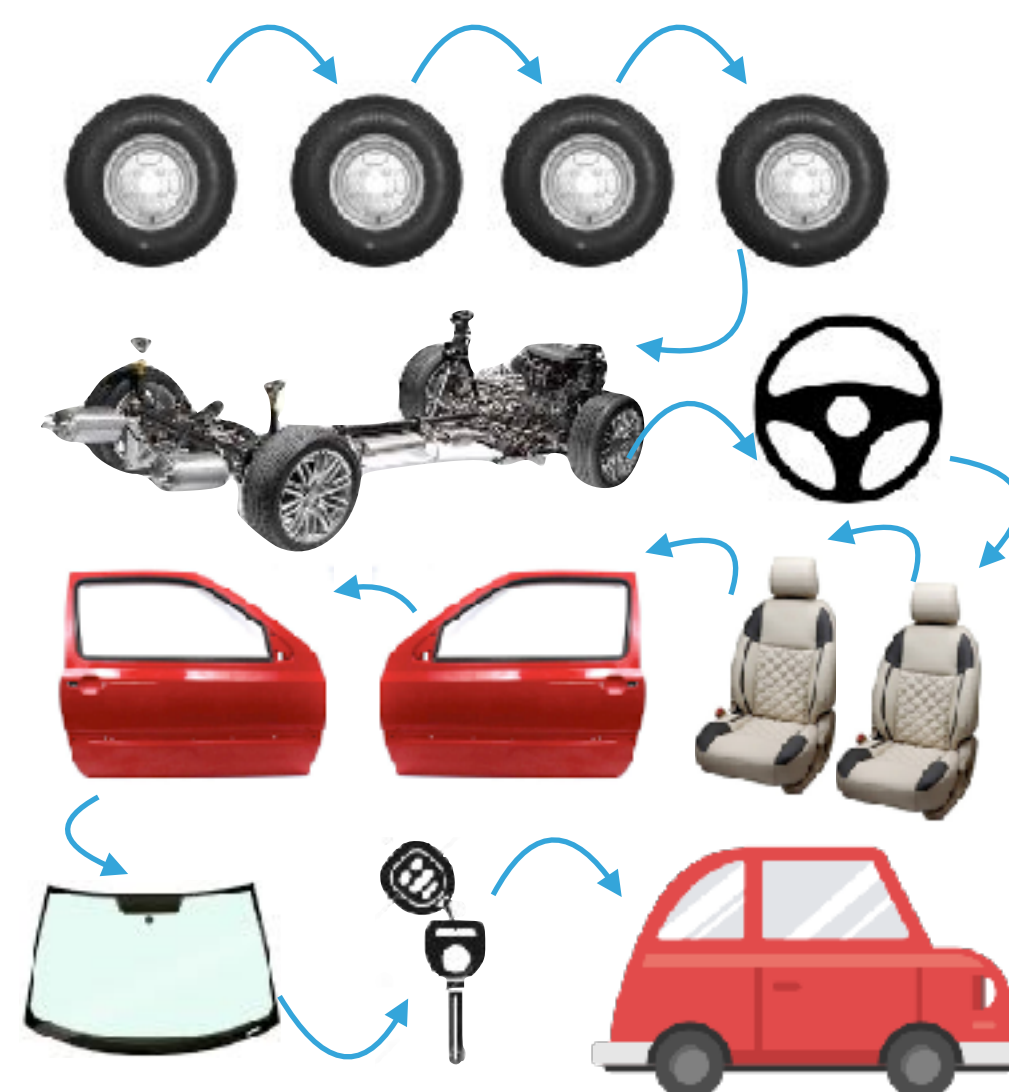
► Synthesis with FPGAs

- Many dedicated blocks work in parallel, each of them performing their part of the task

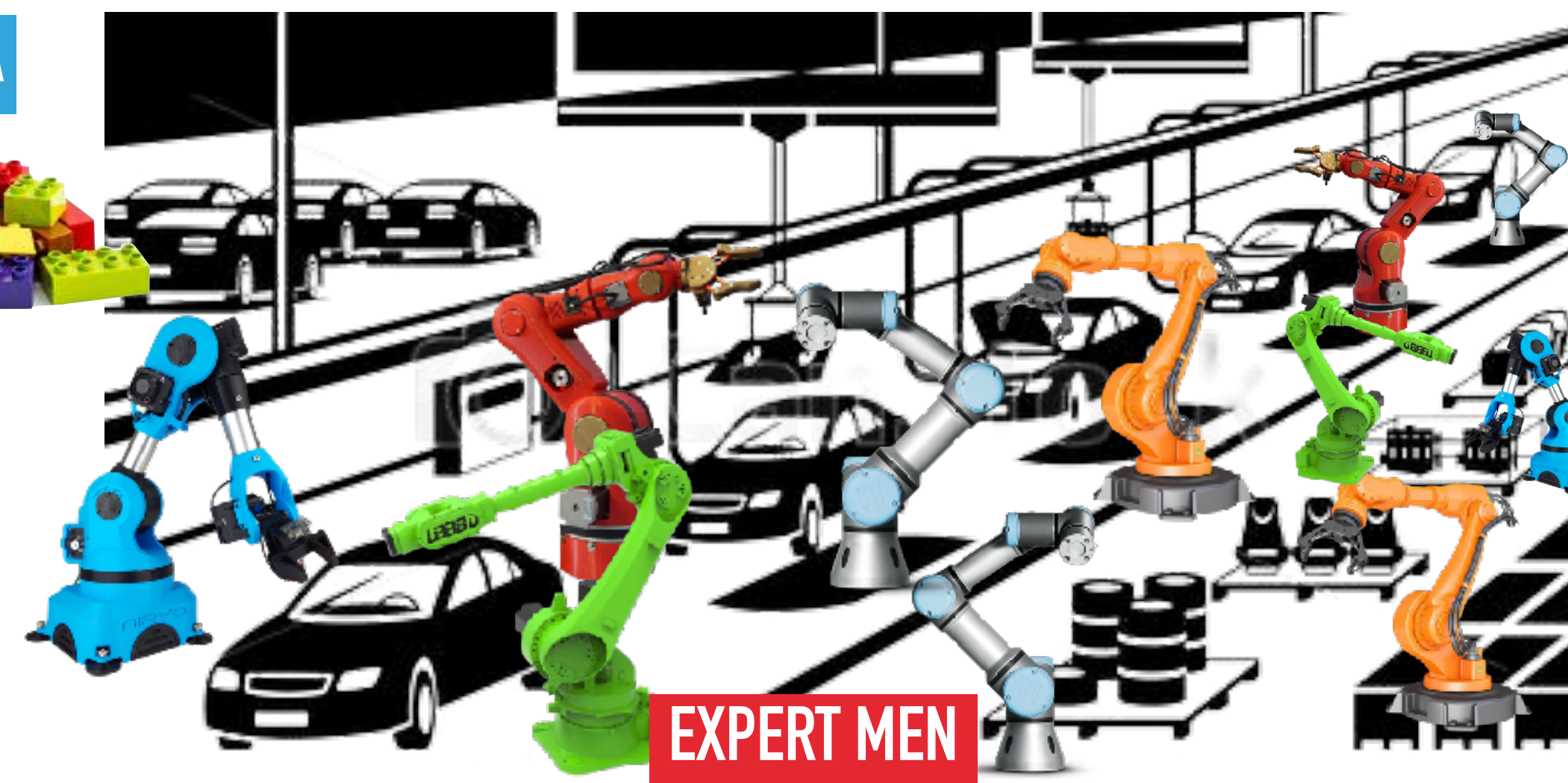


----- Car factory analogy -----

CPU



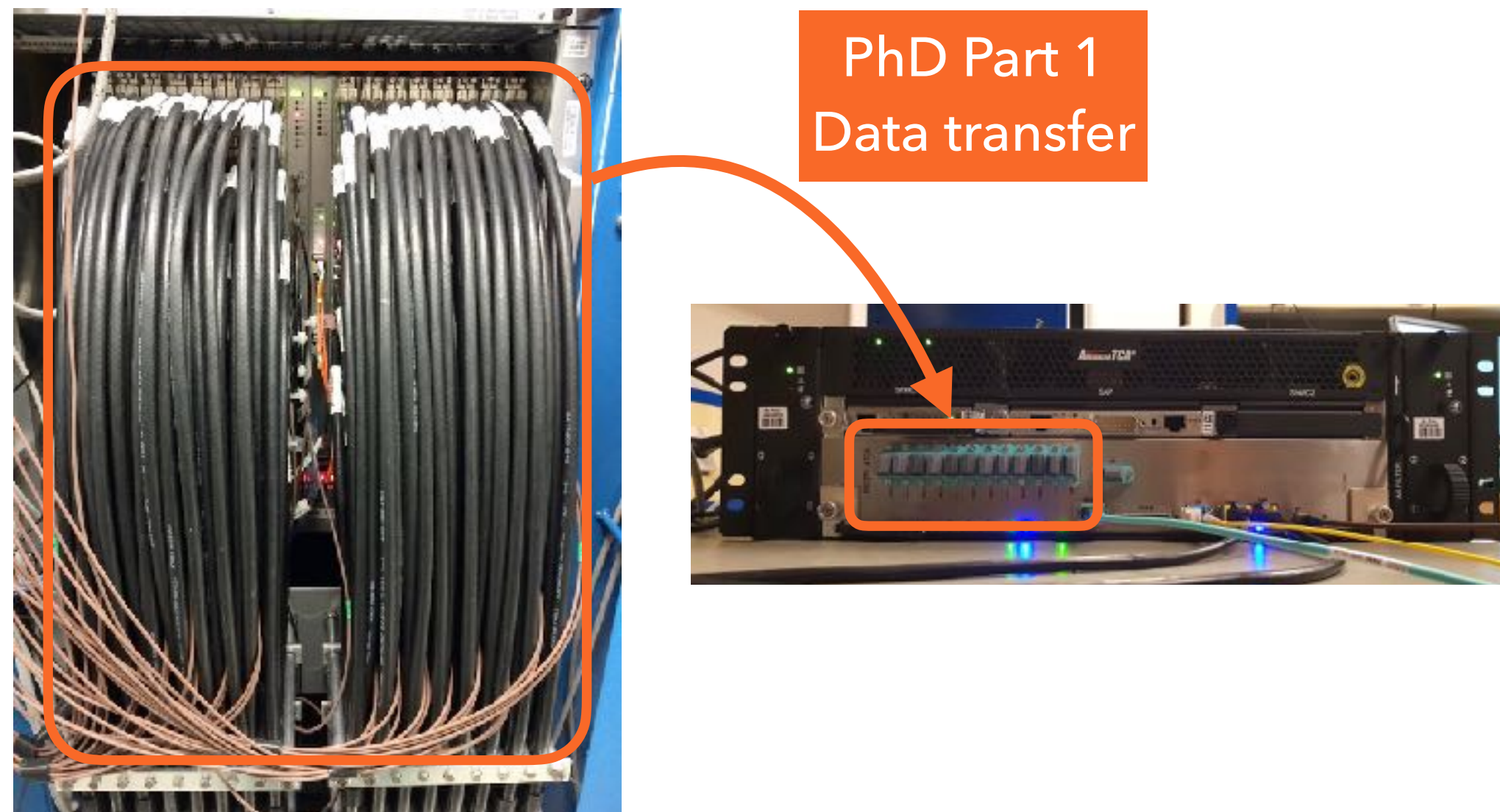
FPGA



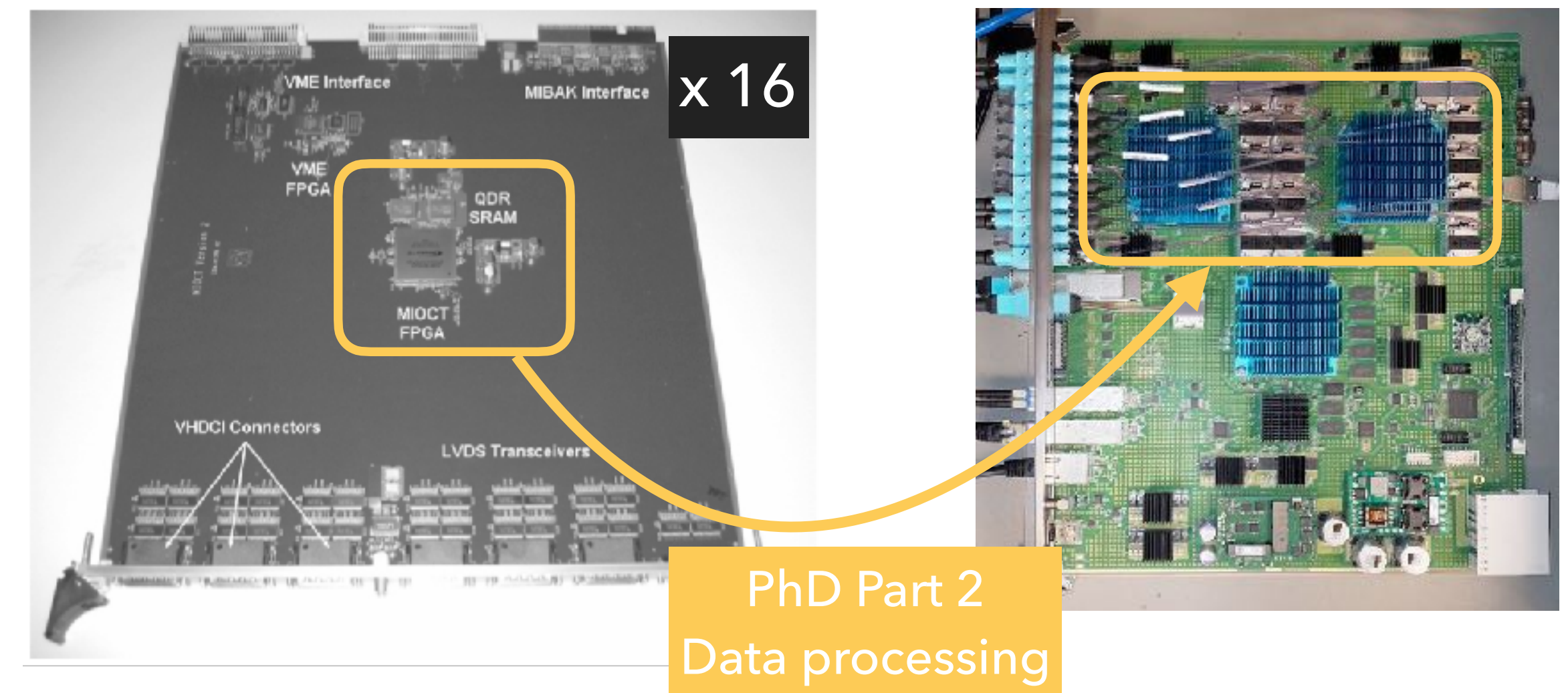
MUCTPI

- ▶ Combines and processes the entire trigger data from the muon detector
- ▶ 18 VME 9U cards replaced to a single ATCA blade
- ▶ High bandwidth and density with high-speed serial links
- ▶ High integration enables enhancing existing functionalities

Front view



Side view



Data Transfer and Processing Requirements

- ▶ Both have to be reliable, and with low and fixed latency

RELIABLE



**IN A GOOD
SHAPE**

LOW-LATENCY



**VERY
FAST**

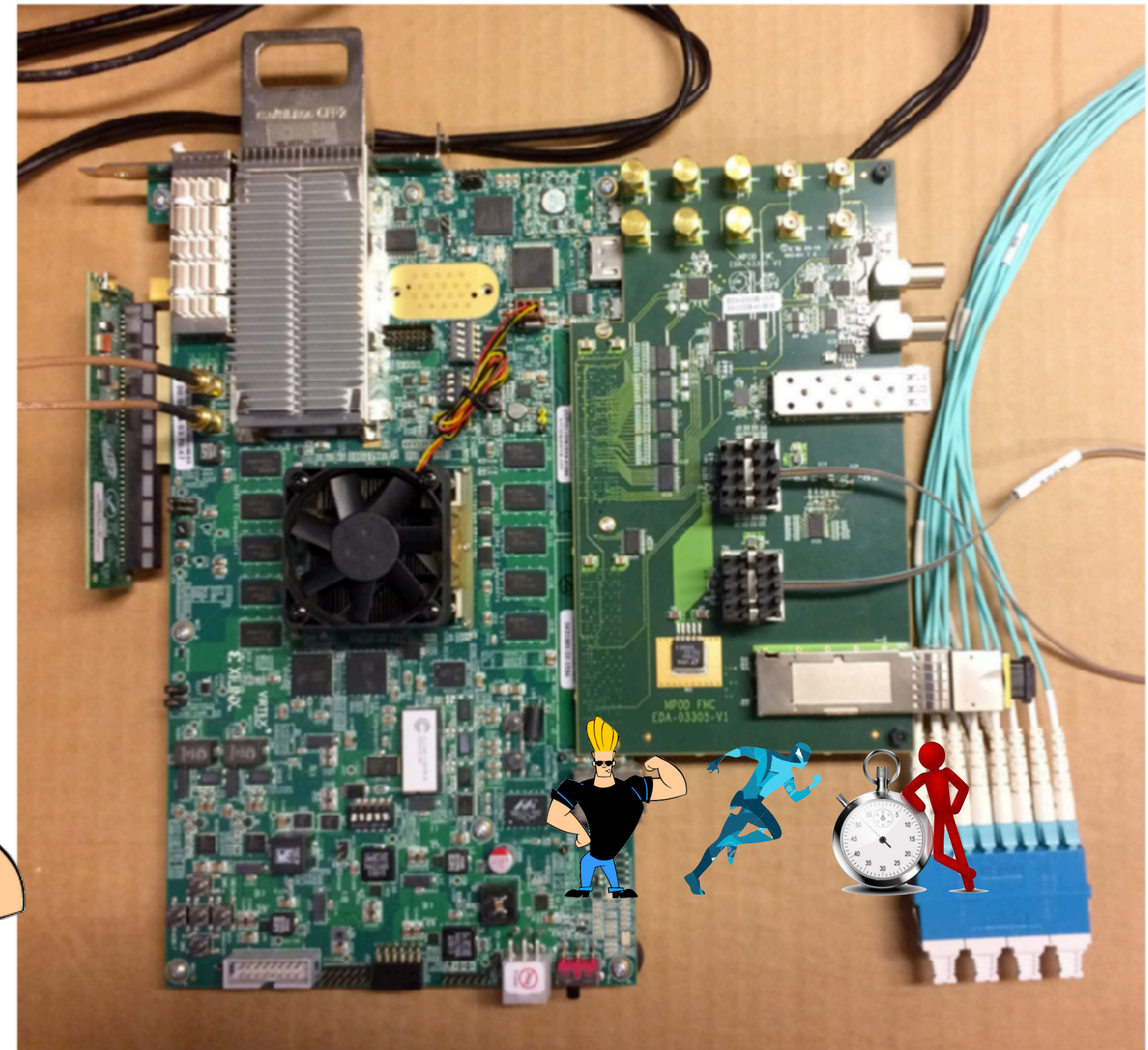
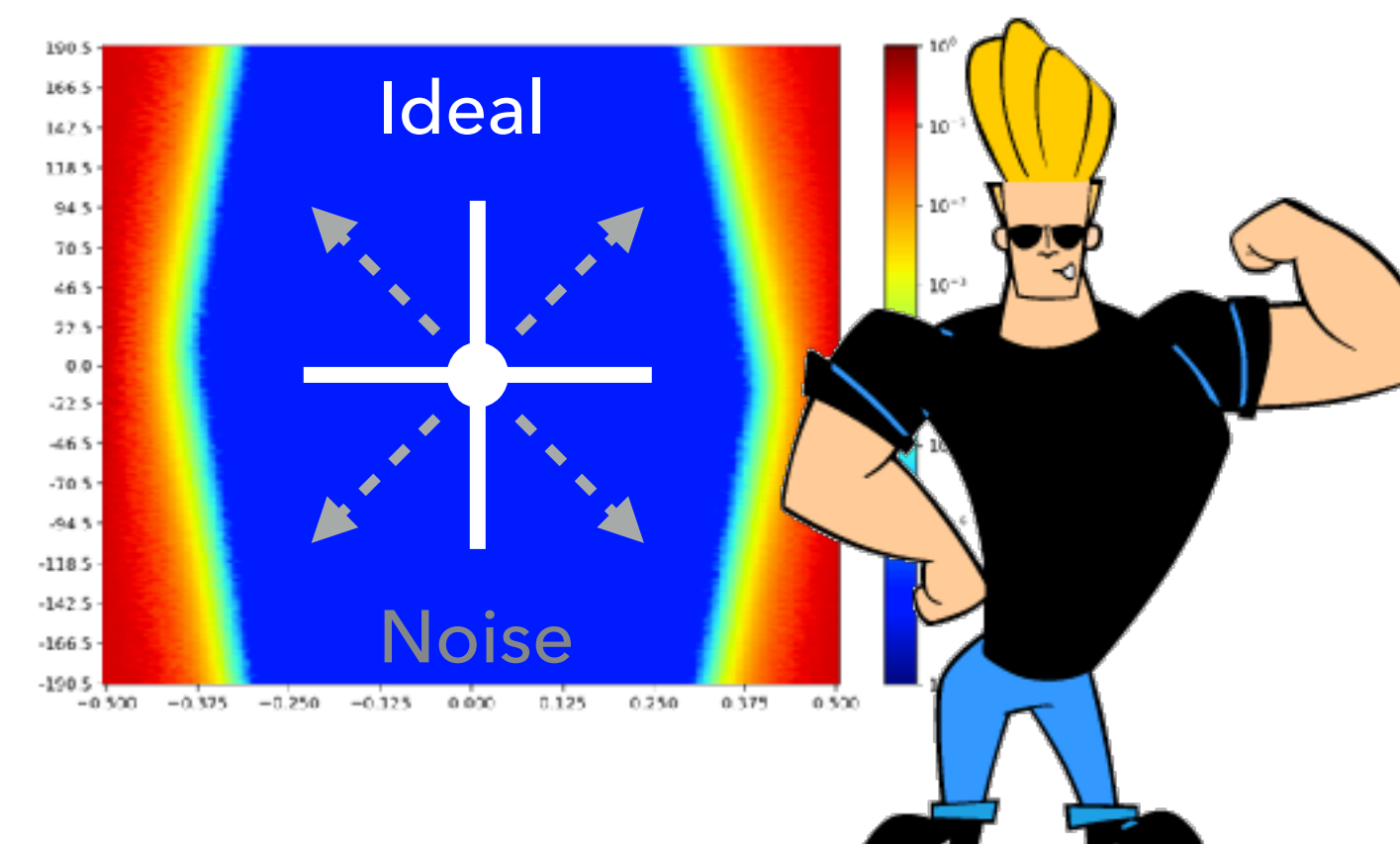
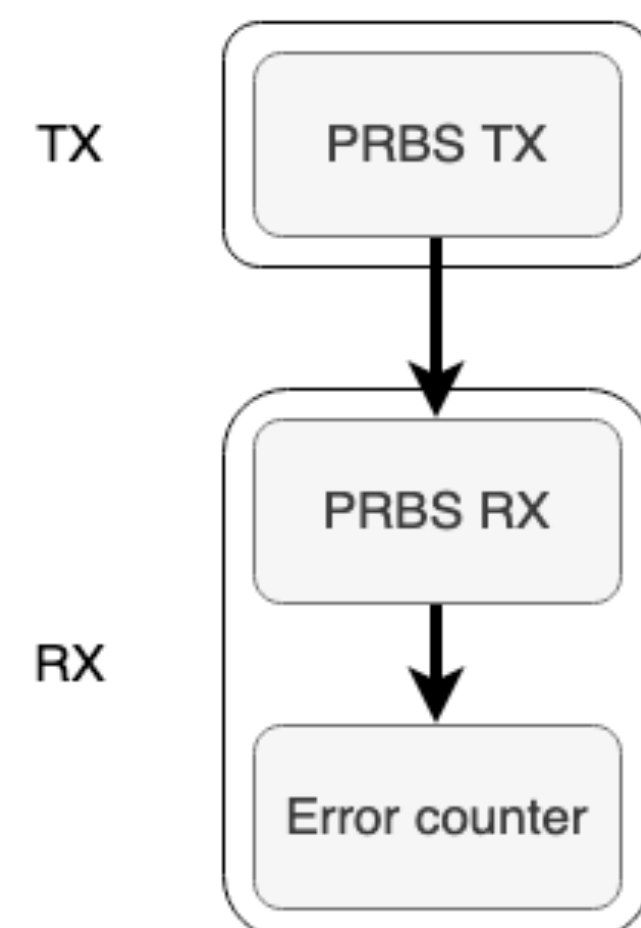
FIXED-LATENCY



**VERY
PUNCTUAL**

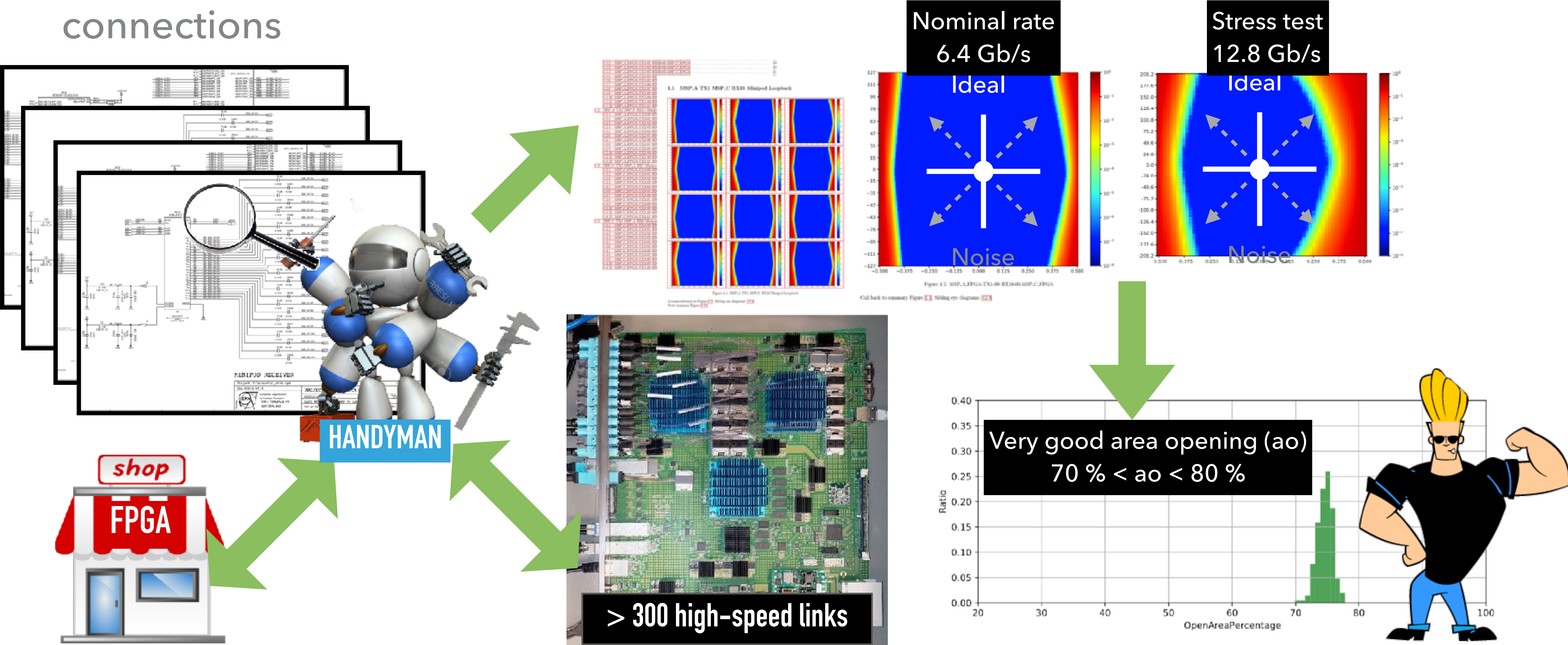
Data Transfer Reliability - MUCTPI Demonstrator

- ▶ Custom double-width FMC for prototyping MUCTPI high-speed connectivity
- ▶ Data reliability measured with BER tests and eye-diagrams
 - ▶ BER of less than one bit error per day with 95% confidence level



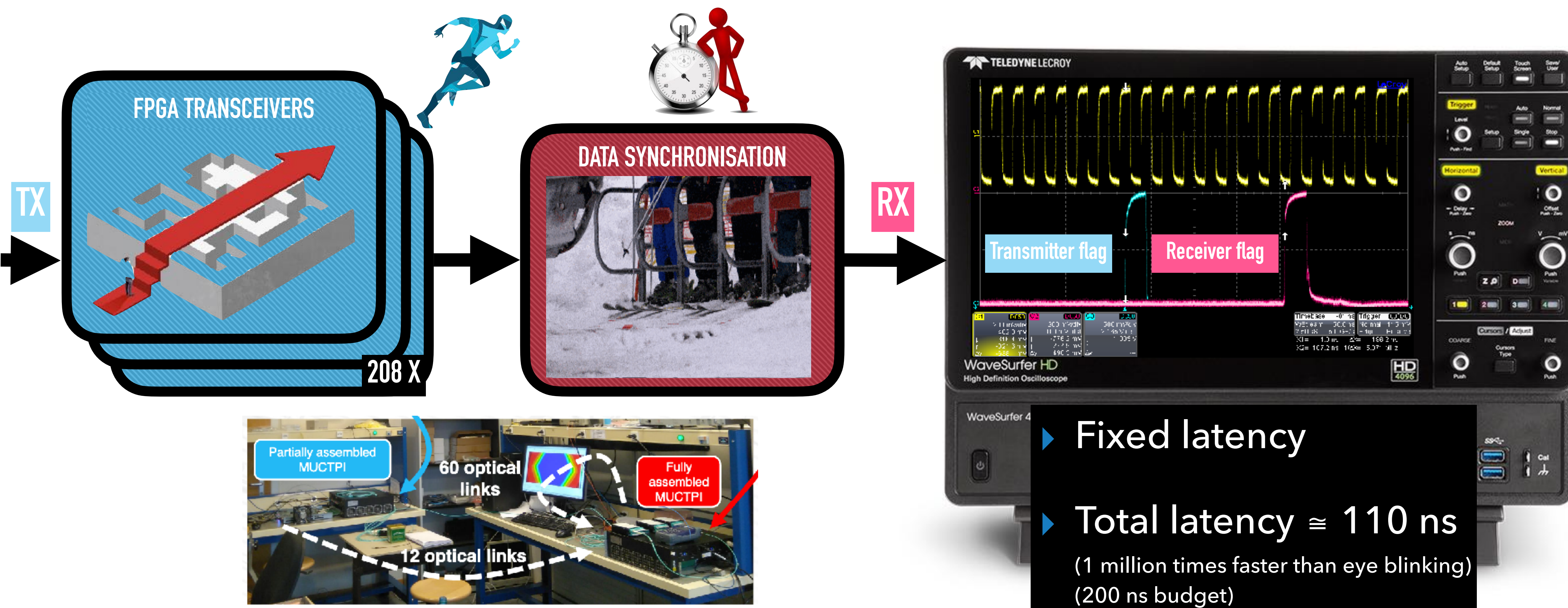
Data Transfer Reliability - Testing Automation

- ▶ MUCTPI requires complex test configuration due to many high-speed connections



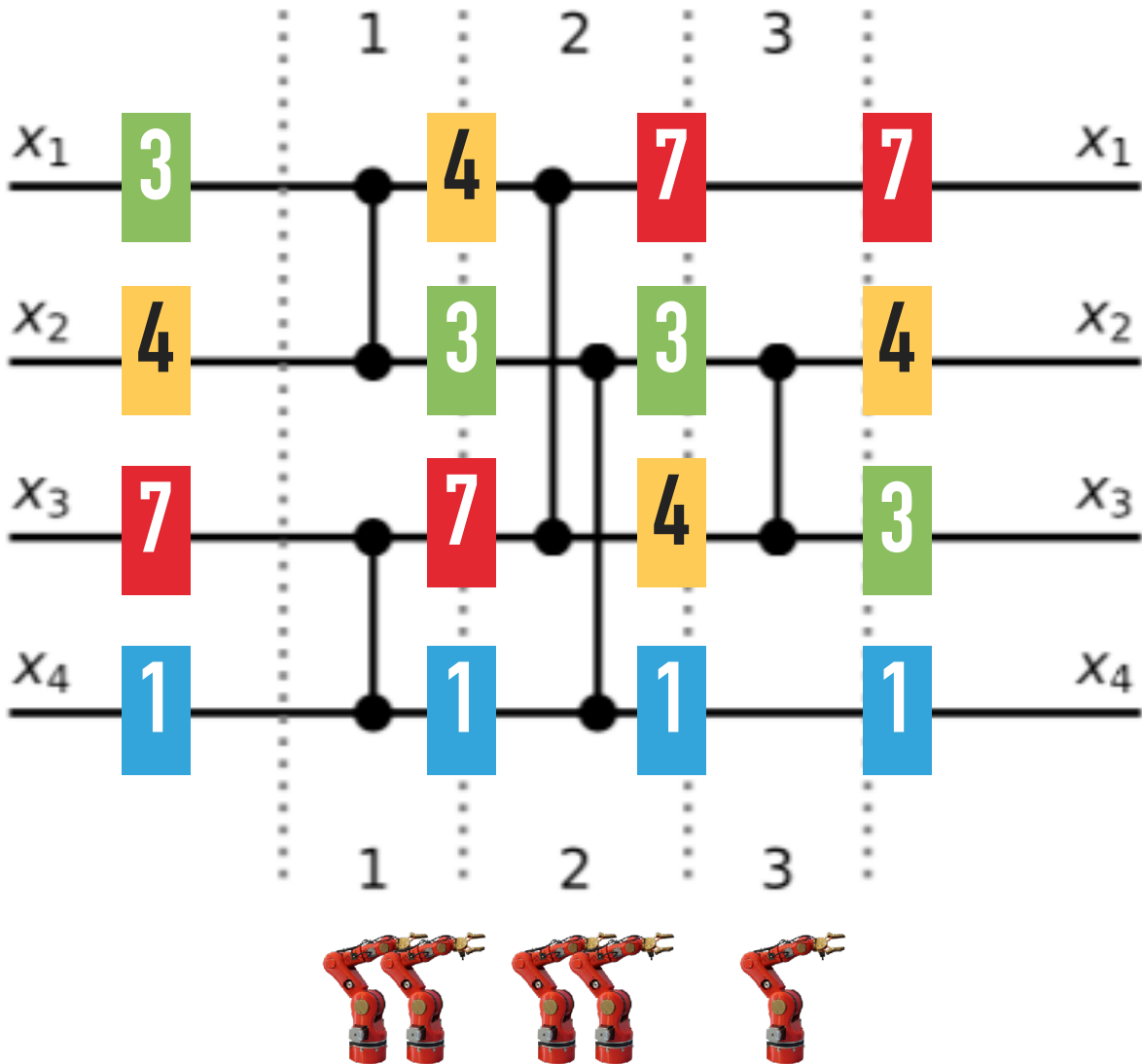
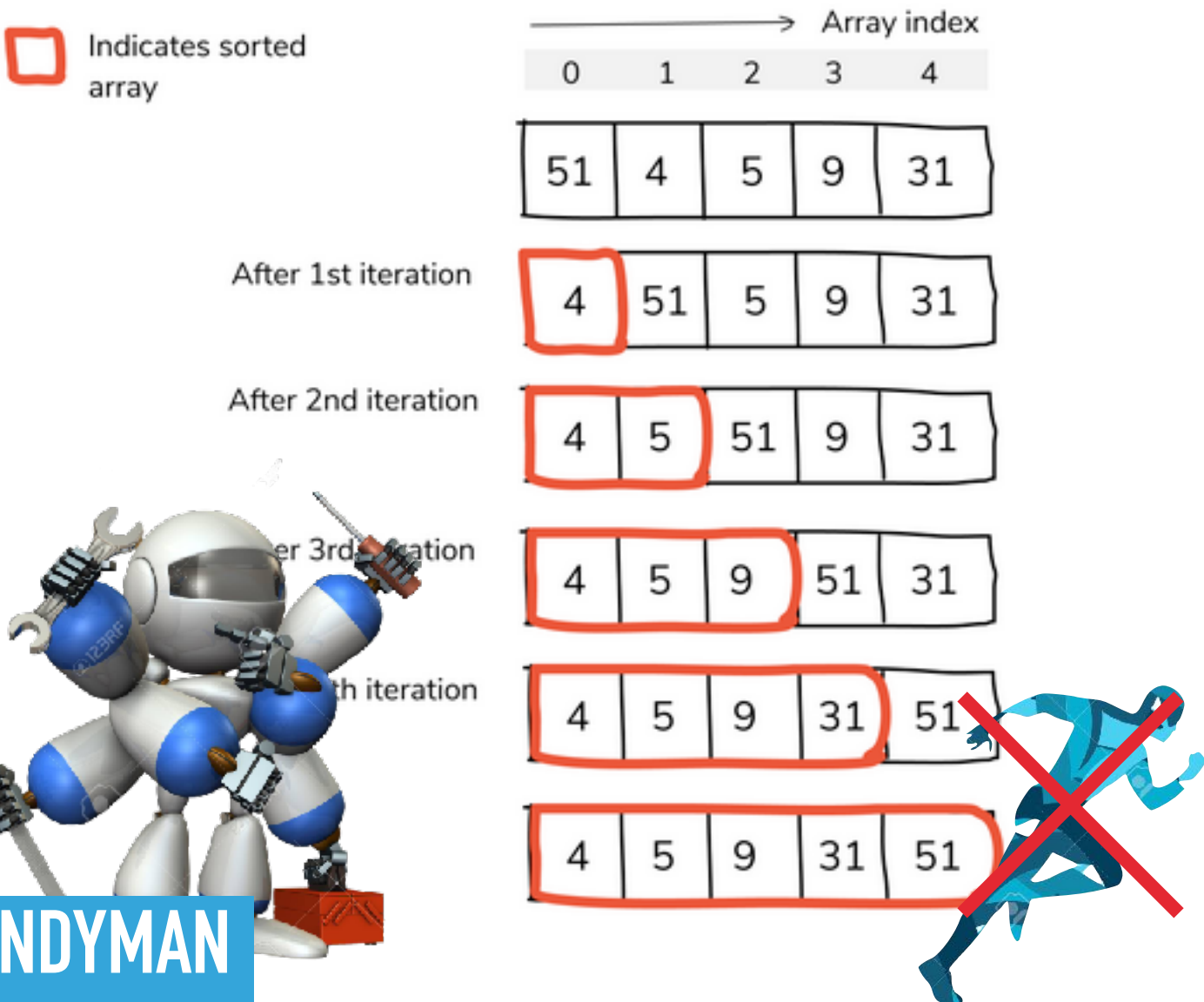
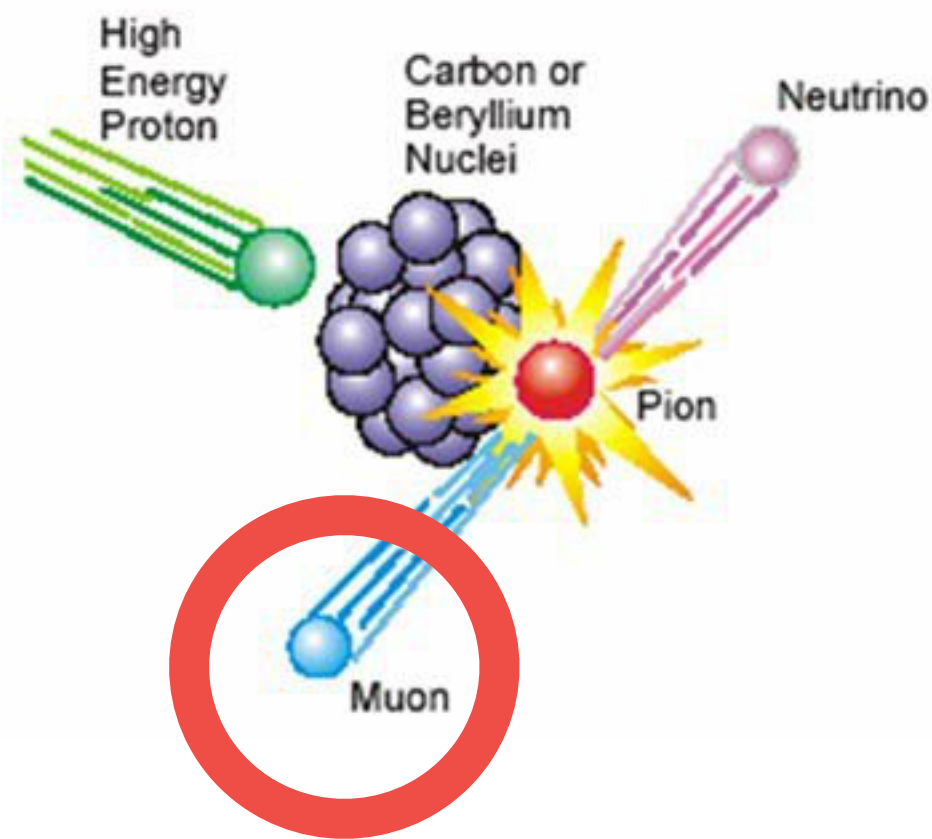
Data Transfer Low and Fixed Latency

- ▶ Transceiver configuration optimised and designed IP to synchronise data



Data Processing

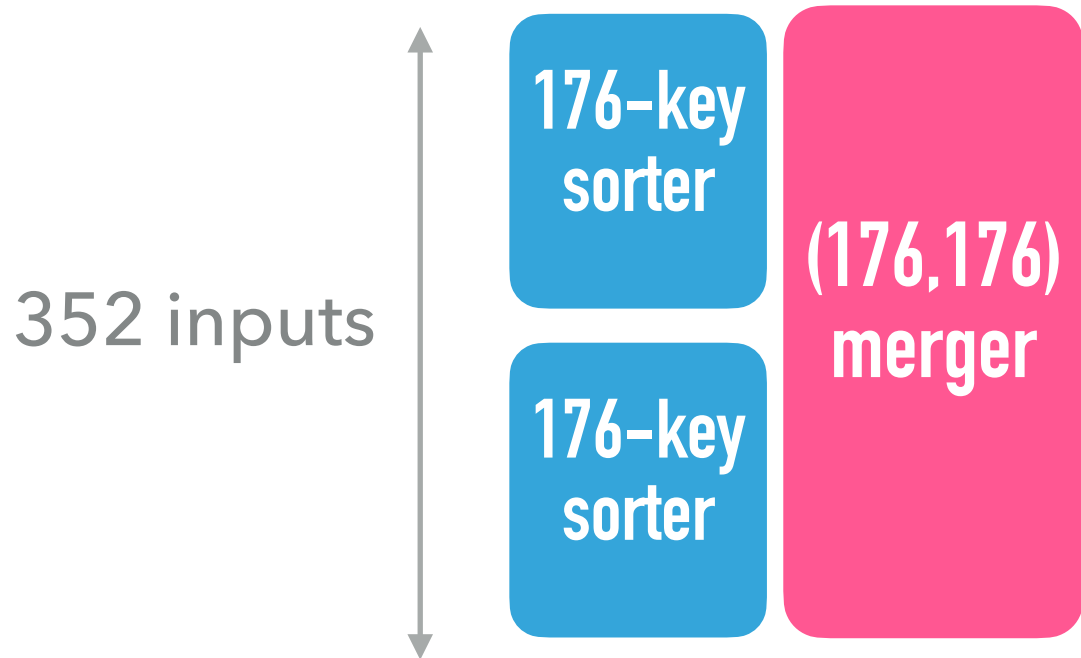
- ▶ 40 millions of bunch crossings per second
- ▶ In average, there are 25 proton-proton collisions per crossing
- ▶ Not all will generate muons, also not with same energy
- ▶ The trigger processing requires a sorted list of the muons



MUCTPI
needs
352-to-16
sorting

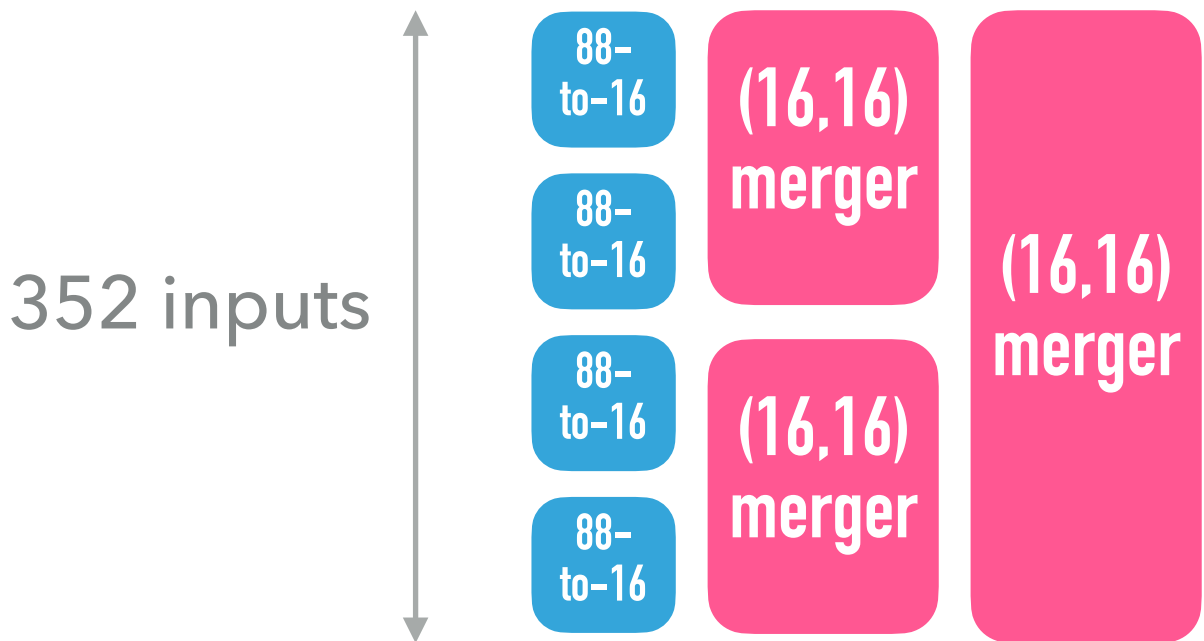


Divide-and-Conquer Method

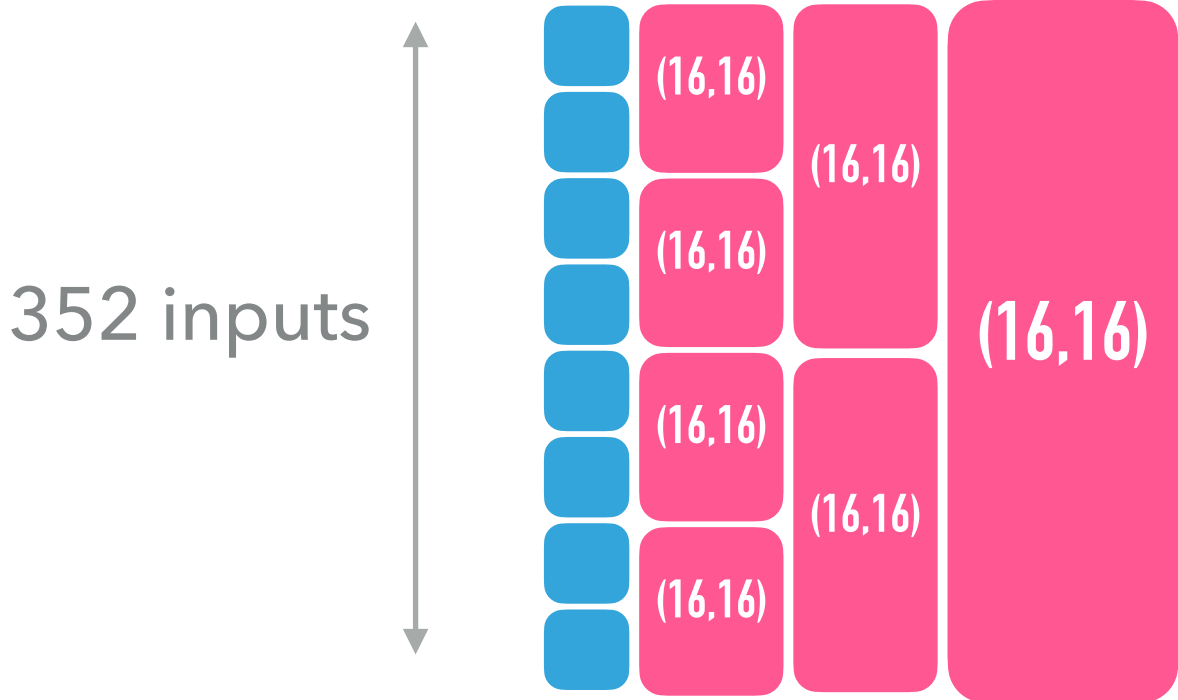


Big groups of robots are slow !!!!

Given that only the 16 highest outputs are needed, is it better sorting small groups first?



Yes, but there are many options !
Can we select the best options before implementing them in hardware ?



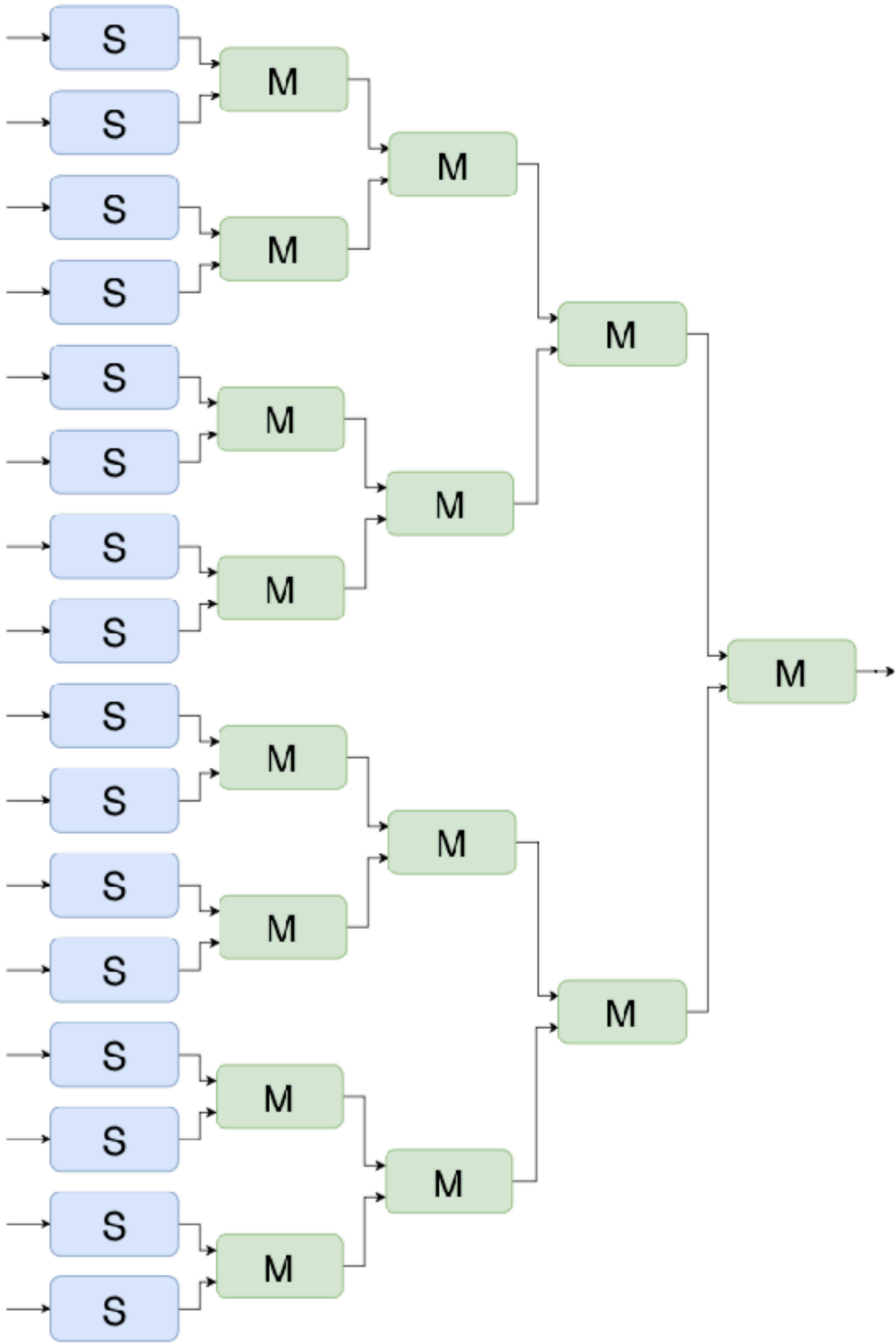
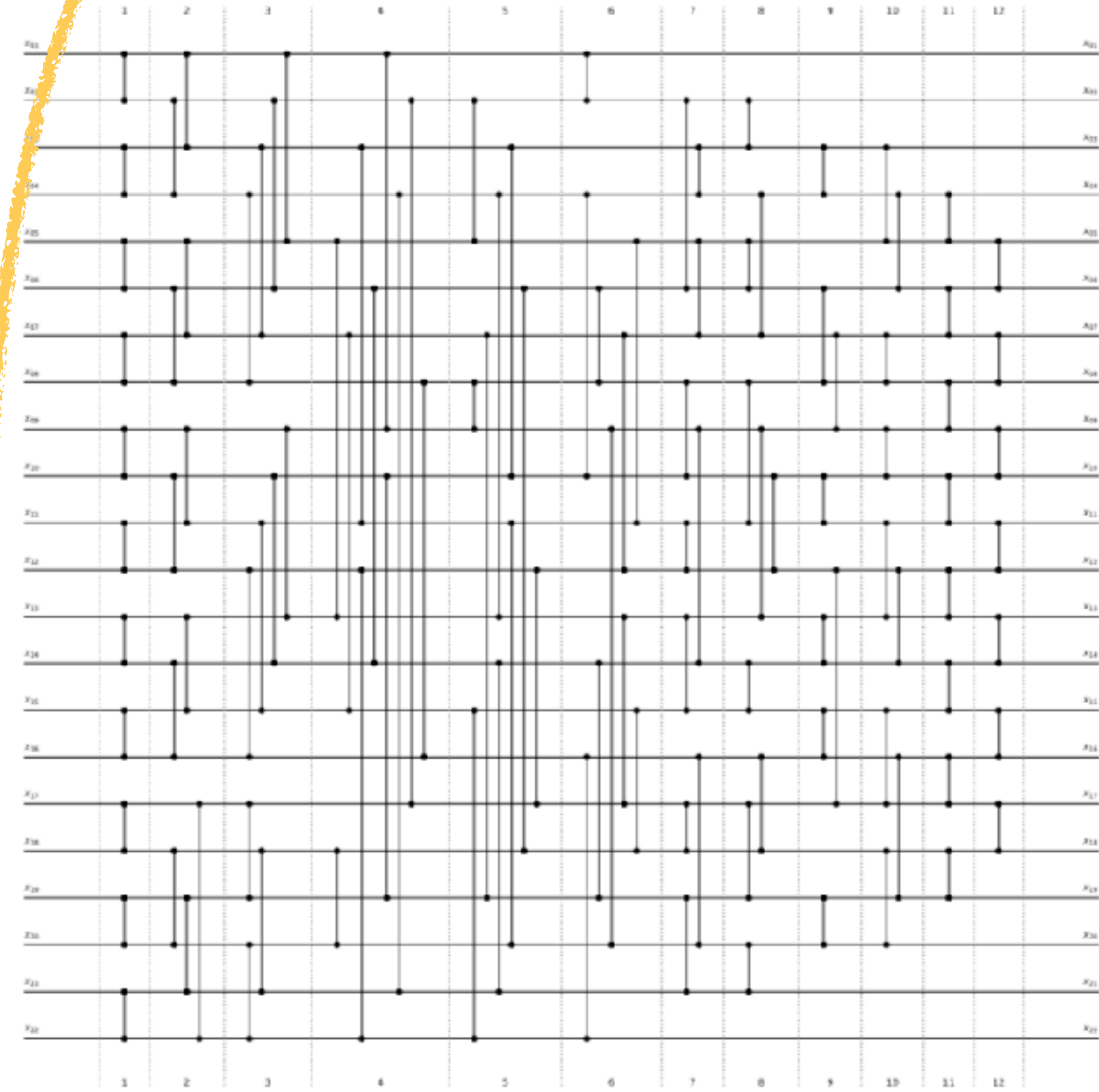
R	Sorting part				Merging part				total	
	I_s	c_s	d_s	C_s	l_m	i_m	C_m	D_m	C	D
1	352	4446	45	4446	0	0	0	0	4446	45
2	176	1792	36	3584	1	1	48	5	3632	41
3	118	1014	28	3042	2	2	96	10	3138	38
4	88	726	28	2904	2	3	144	10	3048	38
5	71	534	26	2670	3	4	192	15	2862	41
6	59	407	21	2442	3	5	240	15	2682	36
7	51	348	21	2436	3	6	288	15	2724	36
8	44	288	21	2304	3	7	336	15	2640	36
9	40	250	20	2250	4	8	384	20	2634	40
10	36	216	19	2160	4	9	432	20	2592	39
11	32	174	15	1914	4	10	480	20	2394	35
12	30	164	15	1968	4	11	528	20	2496	35
13	28	150	15	1950	4	12	576	20	2526	35
14	26	138	15	1932	4	13	624	20	2556	35
15	24	122	15	1830	4	14	672	20	2502	35
16	22	111	15	1776	4	15	720	20	2496	35
17	21	104	15	1768	5	16	768	25	2536	40
18	20	96	14	1728	5	17	816	25	2544	39
19	19	90	14	1710	5	18	864	25	2574	39
20	18	82	13	1640	5	19	912	25	2552	38
21	17	74	12	1554	5	20	960	25	2514	37
22	16	63	10	1386	5	21	1008	25	2394	35



HANDYMAN

Divide-and-Conquer Method - Can We Improve Further?

											2502	35
											2496	35
											2496	34
R	Sorting part					Merging part				Total		
	I_s	method	c_s	d_s	C_s	l_m	i_m	C_m	D_m	C	D	
16	22	baddar22	113	12	1808	4	15	720	20	2528	32	
22	16	voorhis16	61	9	1342	5	21	1008	25	2350	34	



- ▶ What about using the fastest known networks ?
- ▶ 22-key Baddar sorting network (3 stages faster)
- ▶ 32 instead of 45 stages (30 % faster, if compared to 352-key Batcher sorting network)
- ▶ 2528 instead of 4446 comparison-exchanges (–44 %)

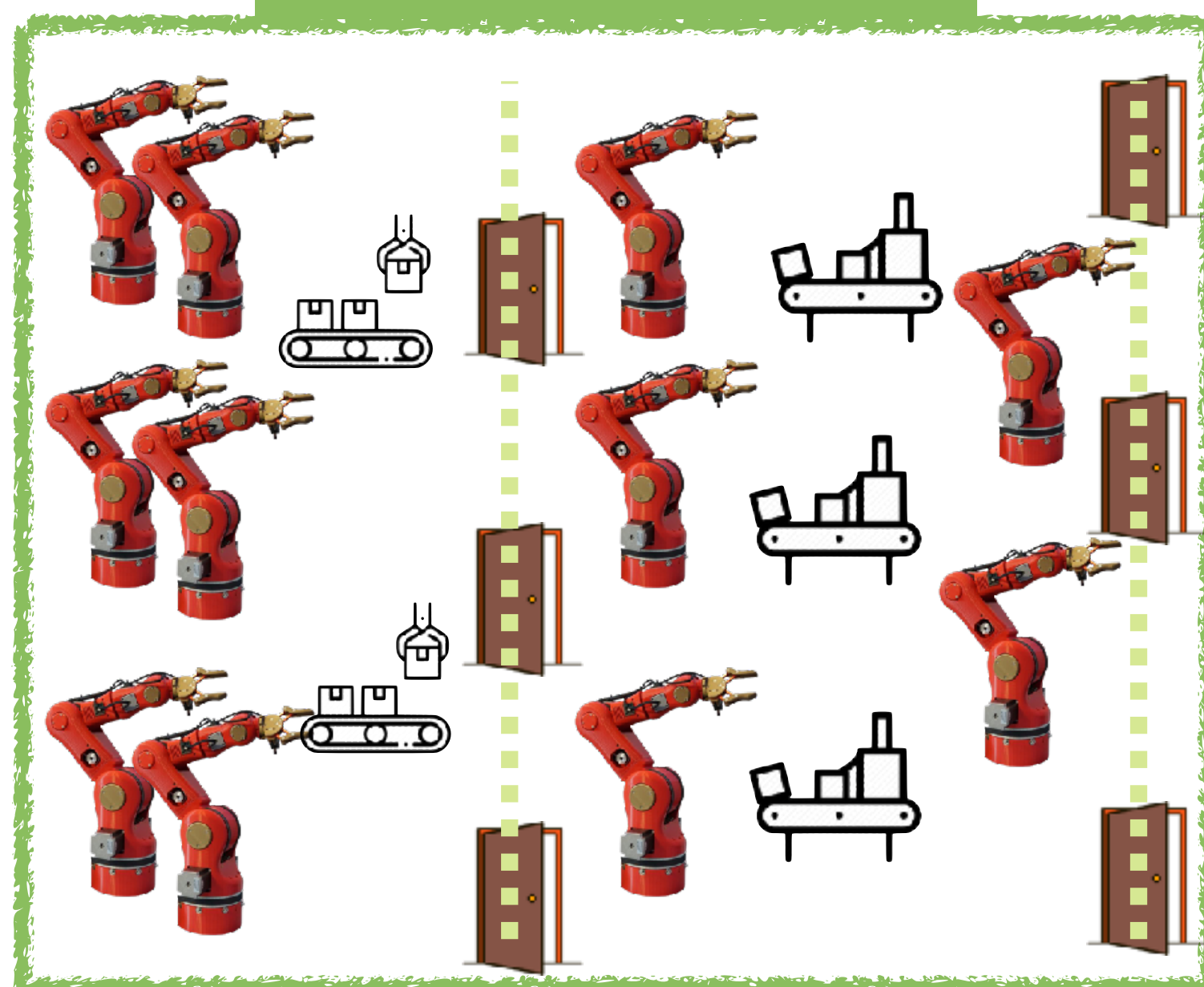


RTL vs HLS

- ▶ The task requires 2528 comparisons (expert men)
- ▶ A factory with 2528 robots can be optimised in many ways
- ▶ Senior engineers can teach handyman to help junior engineers building factories?

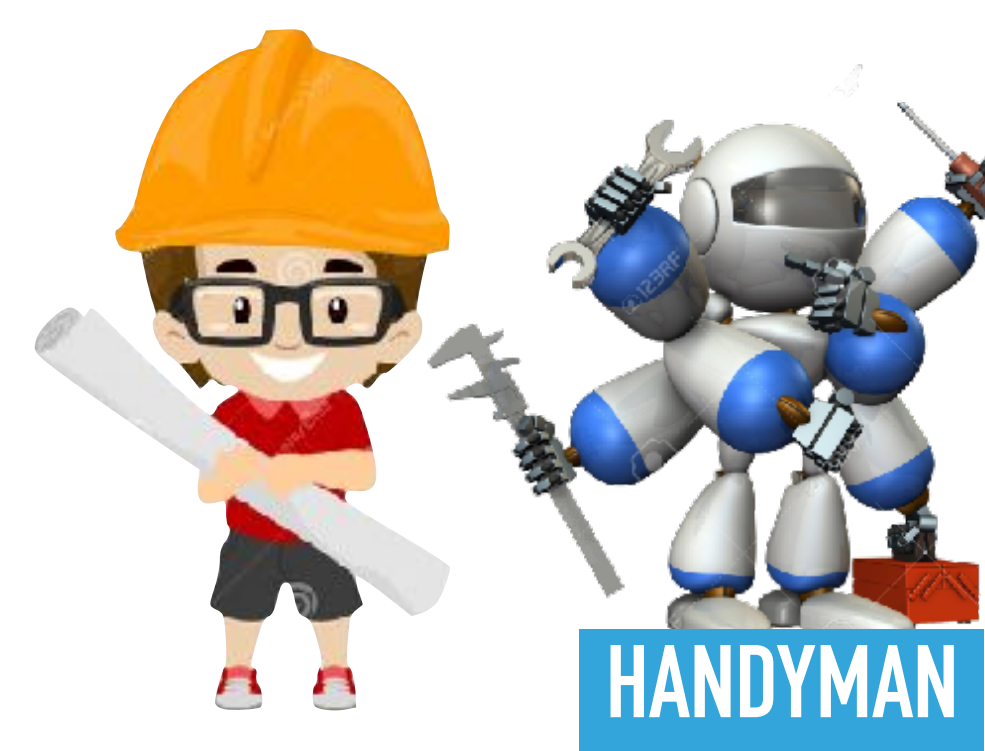


FPGA SYNTHESIS USING RTL

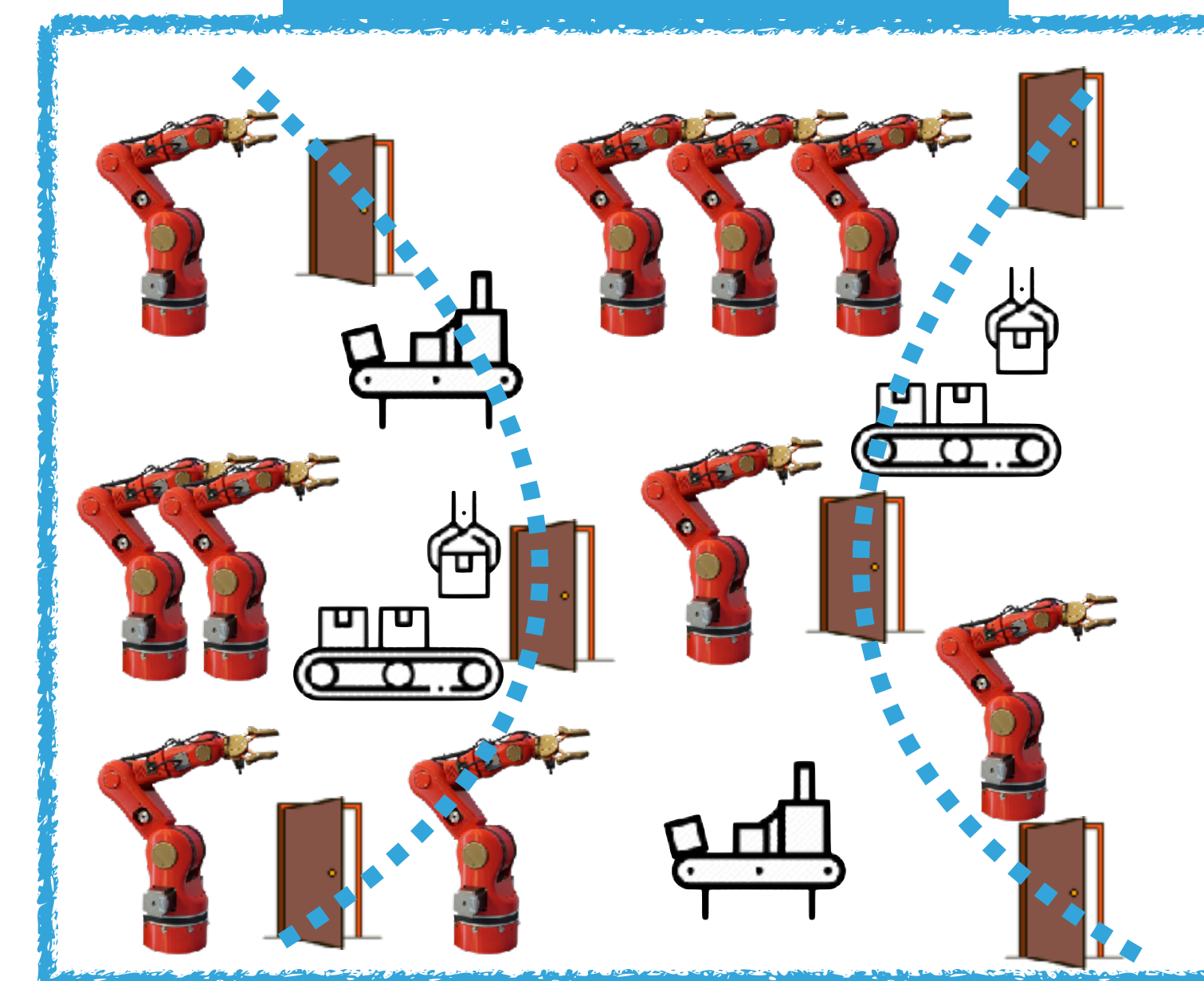


Senior engineer
expert in sorting
and in FPGA


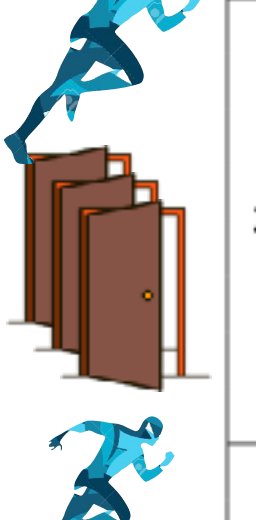
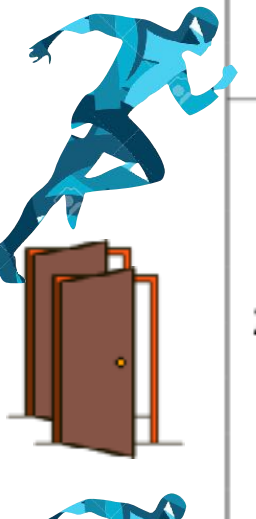

FPGA SYNTHESIS USING HLS

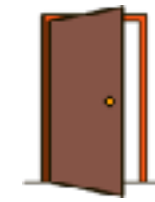




Engineer expert
in sorting but
beginning with
FPGAs

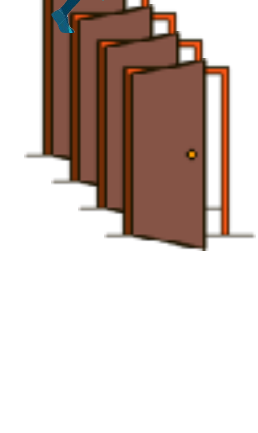

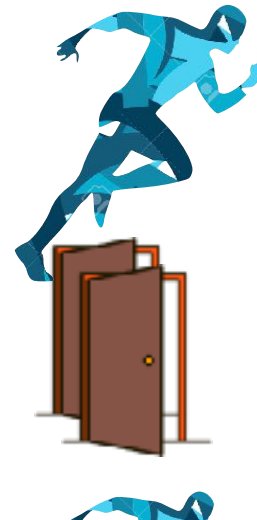
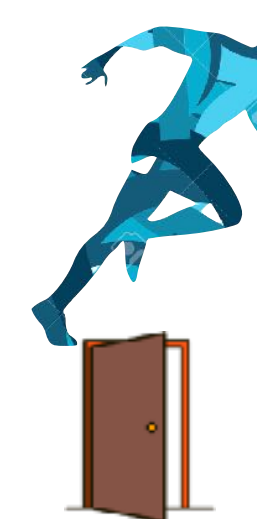




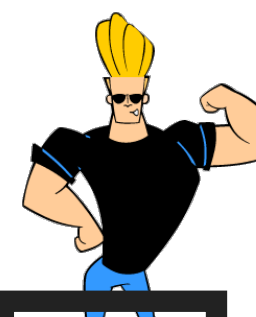
RTL vs HLS



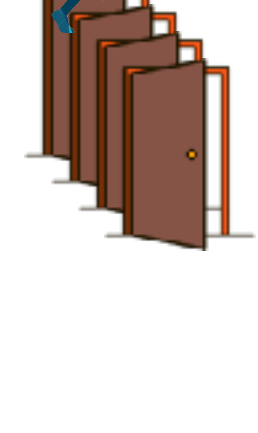

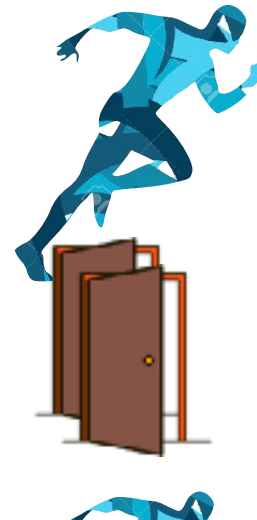
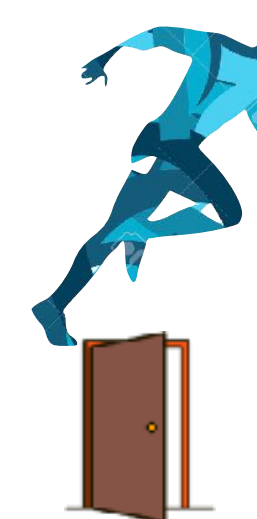




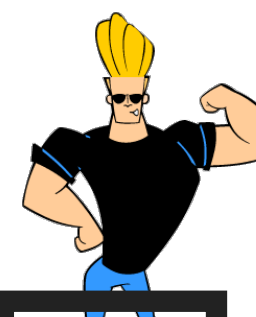
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			1	-17.34	-6547.35	0.05	7.91	60378	6034	0	00:21:19	00:46:00
			2	-	-	-	-	-	-	-	-	-
	1	3	0	-21.1	-7396.16	0.09	5.49	60652	6034	0	00:15:32	02:02:50
			1	-21.86	-7841.56	0.05	6.22	55060	6034	0	00:16:44	02:22:25
			2	-21.57	-7535.19	0.21	5.49	60699	6034	0	00:29:09	12:30:44
2	0	3	0	-28.14	-9649.24	0.05	6.49	60455	6034	0	00:28:38	24:09:38
			1	-5.79	16178.55	0.09	6.96	98301	9146	0	00:20:46	00:53:17
			2	-6.52	18950.93	0.1	7.65	61231	9146	0	00:19:52	00:45:47
	1	3	0	-5.53	15961.54	0.05	6.93	98462	9157	0	72:48:29	00:54:46
			1	-6.18	18225.33	0.05	7.44	72399	9157	0	72:35:57	00:53:00
			2	-14.41	-5496.41	0.04	5.05	63030	10656	0	00:15:55	00:55:54
3	0	3	0	-15.88	10374.03	0.05	5.81	55055	10947	0	00:15:44	00:47:40
			1	-	-	-	-	-	-	-	-	-
			2	-	-	-	-	-	-	-	-	-
	1	3	0	-1.92	-9469.74	0.06	6.62	73507	13567	0	00:19:22	00:47:45
			1	-2.57	12087.92	0.07	7.47	63163	13565	1	00:20:28	00:46:11
			2	-1.78	-8113.61	0.05	6.51	73680	13616	1	38:47:49	00:55:25
4	0	3	0	-2.15	11337.58	0.05	7.37	74694	13616	1	40:50:12	00:55:34
			1	-4.5	-6689.91	0.04	5.02	62277	16331	0	00:17:55	00:46:57
			2	-5.71	10548.47	0.04	5.78	55063	16649	1	00:17:17	00:46:49
	1	3	0	-4.6	-7043.31	0.04	5.08	62585	16332	0	72:42:47	00:48:28
			1	-5.57	10217.15	0.04	5.73	56460	16652	5	72:11:06	00:47:43
			2	0.01	0	0.05	6.39	69663	16740	0	00:12:25	00:39:58
5	0	3	0	-0.52	-1609.48	0.06	7.21	59326	16737	1	00:12:00	00:44:29
			1	0.02	0	0.04	6.42	67995	16774	1	00:12:10	00:45:42
			2	-0.47	-975.85	0.05	7.34	67138	16724	25	00:12:47	00:50:41
	1	3	0	-1.38	-2661.11	0.04	5.02	59492	14136	422	00:17:26	00:45:20
			1	-1.64	-4558.7	0.04	5.71	58139	14397	422	00:18:21	00:47:41
			2	-0.98	-1954.83	0.04	5.03	59553	14149	422	00:18:58	00:49:50
6	0	3	0	-1.98	-5498.06	0.05	5.8	61097	14418	4237	00:40:32	00:43:55
			1	-	-	-	-	-	-	-	-	-
			2	-	-	-	-	-	-	-	-	-
	1	3	0	-	-	-	-	-	-	-	-	-
			1	-	-	-	-	-	-	-	-	-
			2	-	-	-	-	-	-	-	-	-

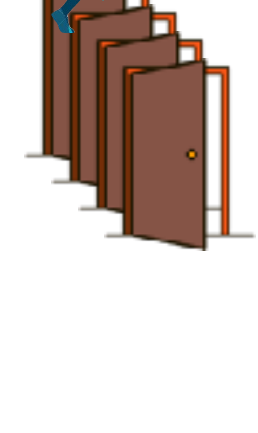

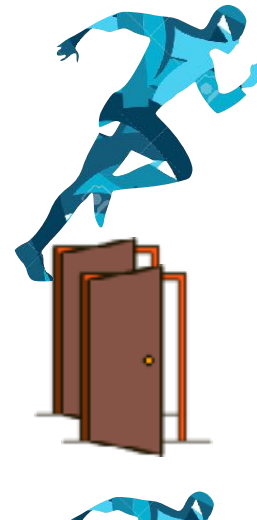
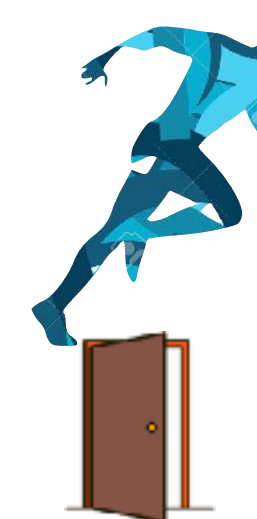




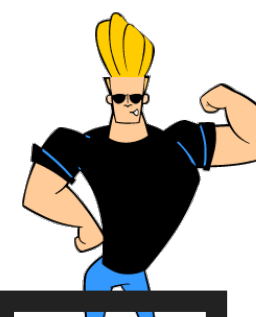


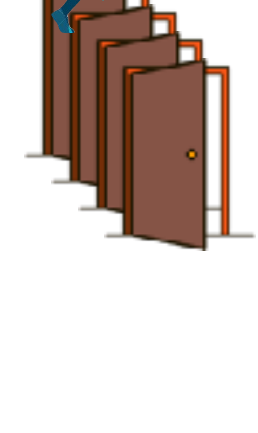

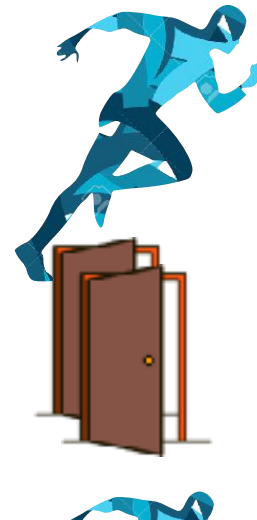
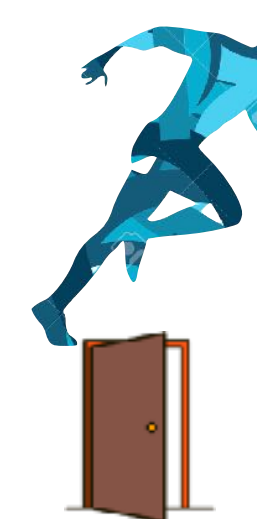
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1	0	4	0	1	-23.12	134521	402		-21.12	-7909.24	0.08	8.11	73329	6036	0	00:23:59	00:50:44	
			1	1	-23.12	134521	402		-22.51	-8472.54	0.13	8.28	73599	6038	0	00:25:40	00:46:12	
			2	2	-23.12	134532	402		-20.23	-7522.05	0.05	8.01	73575	6052	0	00:24:21	00:53:34	
	1	4	0	1	-23.12	134532	402		-21.02	-7913.68	0.06	8.07	72861	6042	0	00:26:43	00:48:25	
			1	1	-24.53	138457	402		-28.25	10357.58	0.23	6.24	65504	6046	0	00:19:30	08:15:06	
			2	2	-24.53	138457	402		-23.36	-8328.31	0.15	6.47	65195	6045	0	00:22:53	00:53:55	
2	0	4	0	2	-24.53	138468	402		-36.57	12005.19	0.06	6.67	67691	6041	0	00:21:30	08:09:28	
			1	1	-24.53	138468	402		-26.06	-9253.09	0.06	6.76	69415	6043	0	00:22:19	00:49:54	
			2	2	-24.53	138468	402		-26.06	-9253.09	0.06	6.76	69415	6043	0	00:22:19	00:49:54	
	1	4	0	1	-11.27	134521	9066		-8.78	11507.93	0.06	7.46	73013	14570	0	00:27:02	00:35:02	
			1	1	-11.27	134521	9066		-7.83	13639.70	0.06	7.30	69597	14557	0	00:22:22	00:43:00	
			2	2	-11.27	134538	9066		-7.39	11226.14	0.05	6.05	66662	14558	0	00:20:50	00:42:29	
3	0	4	0	3	-11.27	134538	9066		-6.89	11390.01	0.05	6.17	67907	14555	0	00:23:26	00:48:05	
			1	1	-12.69	138457	8168		-17.74	19462.54	0.05	6.23	53674	13676	0	00:16:36	08:39:20	
			2	2	-12.69	138457	8168		-11.51	14718.08	0.04	6.06	57962	13686	0	00:20:17	00:48:48	
	1	4	0	3	-12.69	138474	3944		-14.17	16477.29	0.06	5.57	55487	9454	0	00:23:30	09:02:42	
			1	1	-12.69	138474	3944		-13.27	16152.58	0.08	5.64	55951	9455	0	00:26:37	00:39:42	
			2	2	-12.69	138474	3944		-13.27	16152.58	0.08	5.64	55951	9455	0	00:26:37	00:39:42	
4	0	4	0	1	-5.08	134521	12151		-2.39	-1869.97	0.05	6.51	57130	17721	0	00:19:11	00:37:36	
			1	1	-5.08	134521	12151		-2.19	-1924.01	0.04	6.54	57263	17720	0	00:21:42	00:45:01	
			2	2	-5.08	134544	9289		-3.13	-2378.44	0.05	4.48	56203	14884	0	00:17:06	00:40:50	
	1	4	0	4	-5.08	134544	9289		-2.75	-2792.73	0.04	4.58	57212	14876	0	00:18:19	00:40:41	
			1	1	-5.59	138457	14076		-10.05	-5595.34	0.02	5.66	50444	19578	0	00:17:20	08:26:37	
			2	2	-5.59	138457	14076		-7.03	-5403.16	0.04	5.57	50895	19568	0	00:18:25	08:00:30	
5	0	4	0	4	-5.59	138480	5628		-7.38	-4895.43	0.04	4.71	53736	11123	0	00:26:20	03:59:41	
			1	1	-5.59	138480	5628		-5.85	-4292.17	0.04	4.79	52378	11127	0	00:20:48	01:19:19	
			2	2	-5.59	138480	5628		-5.85	-4292.17	0.04	4.79	52378	11127	0	00:20:48	01:19:19	
	1	4	0	1	-2.86	134521	15378		-1.04	-410.06	0.04	6.41	54430	20911	0	00:19:20	00:30:54	
			1	1	-2.86	134521	15378		-0.25	-11.52	0.04	6.52	57197	20911	0	00:25:41	00:44:29	
			2	2	-2.86	134566	11155		-0.46	-62.50	0.04	5.10	55110	16694	0	00:24:41	00:44:29	
6	0	4	0	4	-2.86	134566	11155		-0.52	-133.72	0.05	5.11	55804	16694	0	00:20:21	00:44:29	
			1	1	-2.86	160985	55891		-3.54	-1807.18	0.05	5.56	51798	16381	0	00:21:12	00:44:29	
			2	2	-2.86	160985	55891		-3.41	-1545.52	0.05	5.66	52788	16381	0	00:21:12	00:44:29	
	1	4	0	4	-2.86	138502	6597		-3.35	-1573.54	0.05	4.88	49026	12149	0	00:20:00	00:44:29	
			1	1	-2.86	138502	6597		-2.79	-1210.14	0.04	4.84	49950	12146	0	00:16:59	00:44:29	
			2	2	-2.86	138502	6597		-2.79	-1210.14	0.04	4.84	49950	12146	0	00:16:59	00:44:29	

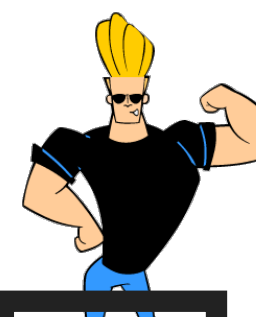




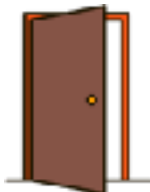
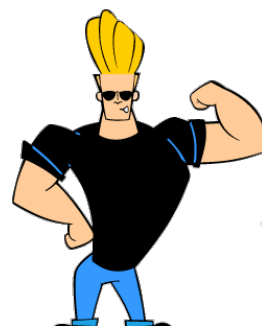
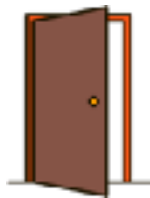




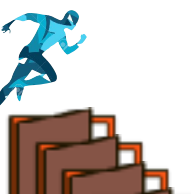





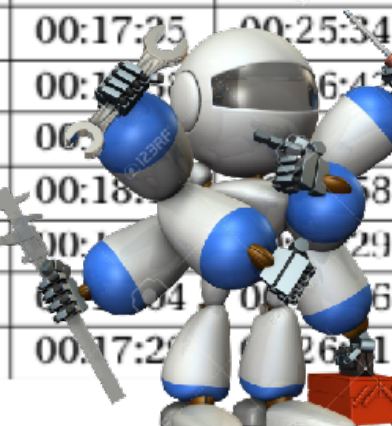



RTL vs HLS

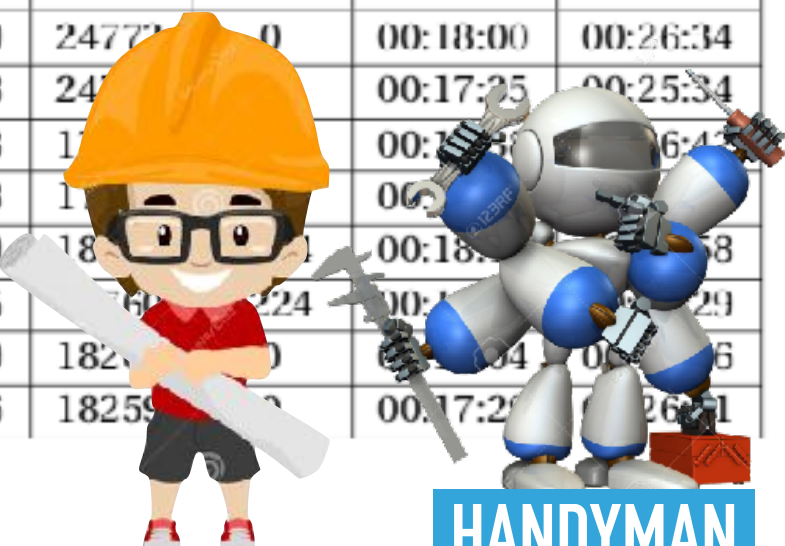


	L	M	H	R	WNS	TNS	WHS	Power	LUT	FF	LUTR	Δ _{TS}	Δ _{TI}
	5	0	3	0	0.37	0	0.08	6.3	63593	20281	0	00:21:12	00:35:18
				1	0.36	0	0.06	7.25	62280	20277	1	00:22:55	00:35:22
			2	0	0.16	0	0.05	6.32	64401	20311	1	15:48:26	00:36:54
				1	0.04	0	0.05	7.22	61425	20186	49	16:33:34	00:41:42
		1	3	0	0.06	0	0.04	5.02	56818	15591	4224	00:17:53	00:37:28
				1	-0.42	-220.17	0.04	5.61	53696	15889	4225	00:17:50	00:42:44
2	0		0.01	0	0.04	4.96	57958	15583	4225	23:31:01	00:38:21		
	1		0.03	0	0.04	5.68	59333	15896	4237	23:32:48	00:42:50		
	6	0	3	0	0.9	0	0.05	6.13	56395	24147	0	00:22:31	00:34:22
				1	0.7	0	0.04	6.84	53216	24142	1	00:21:22	00:33:57
			2	0	0.54	0	0.05	6.16	56567	24223	1	13:22:25	00:36:19
				1	0.66	0	0.05	6.93	59281	23950	97	13:07:54	00:35:52
		1	3	0	0.46	0	0.04	4.93	50741	17251	4224	00:18:59	00:32:54
				1	0.02	0	0.05	5.58	54394	17581	4225	00:18:22	00:37:28
2	0		0.67	0	0.04	4.87	50597	17316	4225	15:46:06	00:33:54		
	1		0.45	0	0.04	5.59	54490	17550	4250	16:23:50	00:38:51		
	7	0	3	0	1.14	0	0.05	6.17	56342	28644	0	00:22:35	00:33:51
				1	0.79	0	0.05	6.97	56359	28638	1	00:22:42	00:33:16
			2	0	1.08	0	0.04	6.07	56336	28704	1	13:12:33	00:36:24
				1	0.55	0	0.05	6.76	65765	28192	191	13:28:43	00:40:00
		1	3	0	0.63	0	0.04	4.86	48350	18964	4224	00:18:55	00:32:09
				1	0.61	0	0.04	5.35	49684	19262	4225	00:18:50	00:40:22
2	0		0.66	0	0.04	4.87	48303	19022	4225	13:26:41	00:38:50		
	1		0.44	0	0.04	5.35	52831	19202	4274	13:43:12	00:37:51		
	8	0	3	0	1.61	0	0.04	6.12	56335	31984	1	00:23:59	00:33:45
				1	1.29	0	0.05	6.63	57272	31979	1	00:23:37	00:32:31
			2	0	1.36	0	0.05	6.03	56336	32103	1	11:26:42	00:39:59
				1	1.28	0	0.0	6.66	64134	31590	191	10:14:37	00:37:38
		1	3	0	0.89	0	0.04	4.82	48283	20999	4224	00:20:08	00:32:33
				1	0.75	0	0.04	5.36	50649	21262	4225	00:20:06	00:32:09
2	0		0.8	0	0.04	4.83	48309	21021	4225	13:29:24	00:39:47		
	1		0.76	0	0.04	5.28	53886	21187	4274	12:22:54	00:39:40		

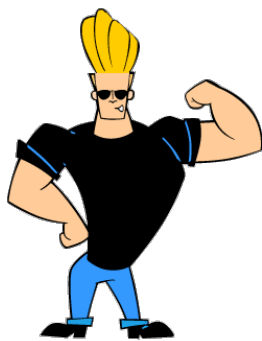
Options				HLS				HLS-driven RTL								
L	M	II	R	II'	WNS	LUT	FF	WNS	TNS	WHS	Power	LUT	FF	LUTR	Δ _{TS}	Δ _{TI}
5	0	1	0	1	-0.85	134521	17568	0.40	0.00	0.04	6.37	54291	23144	0	00:17:26	00:24:50
			1	1	-0.85	134521	17568	0.54	0.00	0.04	6.33	54216	23144	0	00:17:22	00:24:32
		4	0	4	-0.85	134568	10073	0.13	0.00	0.04	4.04	56348	15675	0	00:19:28	00:26:44
			1	4	-0.85	134568	10073	0.24	0.00	0.04	3.96	54017	15675	0	00:16:25	00:26:07
	1	1	0	1	-0.84	160985	57012	-2.26	-651.56	0.04	5.66	51354	17504	4224	00:17:02	02:20:03
			1	1	-0.84	160985	57012	-2.39	-675.54	0.04	5.67	52423	17498	4224	00:20:55	07:42:51
		4	0	4	-0.84	138504	11692	-0.63	-107.41	0.05	4.45	48141	17236	0	00:16:22	00:49:01
			1	4	-0.84	138504	11692	-1.00	-182.66	0.04	4.45	48648	17235	0	00:16:33	01:13:16
6	0	1	0	1	0.83	134521	18392	0.50	0.00	0.04	6.27	52301	23968	0	00:19:23	00:24:22
			1	1	0.83	134521	18392	0.51	0.00	0.04	6.33	52815	23968	0	00:19:59	00:24:41
		4	0	4	0.81	134568	11020	0.35	0.00	0.05	4.47	51219	16621	0	00:19:10	00:25:30
			1	4	0.81	134568	11020	0.33	0.00	0.04	4.44	51457	16621	0	00:16:58	00:26:11
	1	1	0	1	0.79	160985	57604	-0.53	-44.08	0.04	5.61	51194	18124	4224	00:14:53	00:54:10
			1	1	0.79	160985	57604	0.04	0.00	0.04	5.53	51228	18124	4224	00:14:57	00:35:35
		4	0	4	0.79	138504	12164	-0.27	-2.88	0.05	4.40	46335	17745	0	00:15:29	00:55:11
			1	4	0.79	138504	12164	0.04	0.00	0.05	4.41	46864	17745	0	00:15:46	00:26:13
7	0	1	0	1	0.83	134521	18796	0.64	0.00	0.04	6.32	53134	24374	0	00:22:25	00:25:46
			1	1	0.83	134521	18796	0.54	0.00	0.04	6.29	53069	24374	0	00:19:27	00:26:14
		4	0	4	0.81	134559	11000	0.51	0.00	0.05	4.64	52489	16603	0	00:16:13	00:27:01
			1	4	0.81	134559	11000	0.29	0.00	0.05	4.64	52811	16603	0	00:16:31	00:26:33
	1	1	0	1	0.83	160985	57797	0.14	0.00	0.04	5.50	50419	18330	4224	00:16:54	01:50:51
			1	1	0.83	160985	57797	0.20	0.00	0.04	5.53	50947	18330	4224	00:17:10	00:33:30
		4	0	4	0.83	138495	12245	0.12	0.00	0.04	4.41	46432	17839	0	00:17:17	02:12:08
			1	4	0.83	138495	12245	0.52	0.00	0.04	4.39	46818	17865	0	00:16:31	00:31:57
8	0	1	0	1	0.83	135033	20120	0.41	0.00	0.05	6.42	52949	24777	0	00:18:00	00:26:34
			1	1	0.83	135033	20120	0.72	0.00	0.03	6.30	52688	24777	0	00:17:25	00:25:34
		4	0	4	0.81	134566	11487	0.31	0.00	0.05	4.68	54463	18259	0	00:16:38	00:26:44
			1	4	0.81	134566	11487	0.38	0.00	0.04	4.68	53873	18259	0	00:16:06	00:26:44
	1	1	0	1	0.83	161049	58315	0.46	0.00	0.04	5.59	50499	18259	4224	00:18:00	00:33:30
			1	1	0.83	161049	58315	0.37	0.00	0.04	5.61	50595	18259	4224	00:17:25	00:25:34
		4	0	4	0.83	138502	12636	0.62	0.00	0.04	4.36	45869	18259	0	00:16:04	00:26:44
			1	4	0.83	138502	12636	0.62	0.00	0.04	3.88	45896	18259	0	00:17:25	00:26:44



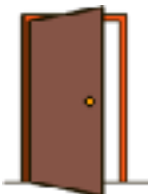
HANDYMAN



Comparative Study



HLS → 12% ↑ FFs



Option	WNS	TNS	WHS	Power	LUT	FF	LUTR
RTL { $L = 5, M = 0, H = 3, R = 0$ }	0.37	0	0.08	6.3	63593	20281	0
HLS { $L = 5, M = 0, II = 1, R = 1$ }	0.54	0	0.04	6.3	54216	23144	0

L = 5 → Latency = 31.25 ns

HLS → 50% ↑ WNS

HLS → 15% ↓ LUTs



- ▶ RTL and HLS have equiparable performance for this example
- ▶ HLS has 50% better timing slack and 15% better LUT utilisation
- ▶ HLS requires a little more registers but overall utilisation is < 1%
- ▶ RTL requires more knowledge and development time
- ▶ HLS requires less knowledge and development time

Comparative Study

- ▶ RTL requires more knowledge and development time
 - ▶ Engineer must define clocking and hardware resources explicitly
 - ▶ Design exploration is performed manually (long)
- ▶ HLS requires less knowledge and development time
 - ▶ HLS tool defines clocking and hardware resources (scheduling and binding)
 - ▶ HLS facilitates design exploration by automatising code generation and synthesis

Summary

- ▶ Part I
 - ▶ Development of MUCTPI demonstrator
 - ▶ Testing automation of hundreds of high-speed serial links
 - ▶ BER of less than one bit per day with 95% confidence level
 - ▶ Synchronizer IP, 208 SL inputs with low and fixed latency.
Total data transfer latency 110 ns (200 ns total latency budget)

Summary

- ▶ Part II
 - ▶ Using divide-and-conquer method and Baddar 22-key sorting network
 - ▶ MUCTPI sorting network, 13 fewer steps than the 45-step 352-key Batcher
 - ▶ FPGA implementation MUCTPI sorting network, 31.25 ns, RTL and HLS
- ▶ Part I & II already integrated to MUCTPI firmware and tested

Thank You Very Much !

