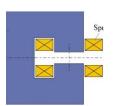
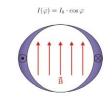
## Recap 1<sup>st</sup> Lecture

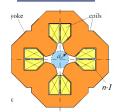
**Magnetic Rigidity**  $B\rho$ : corresponding beam momentum  $p = qB\rho$  defined by the bending magnets

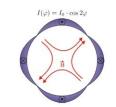
**Beam Guidance**: dipole strength 
$$\kappa = \frac{1}{\rho} = \frac{q}{p} B_0$$
,  $[\kappa] = m^{-1}$  (curvature)





**Beam Focusing:** quadrupole strength 
$$k = -\frac{q}{p} \frac{\partial B_y}{\partial x}$$
,  $[k] = m^{-2} \left(\frac{1}{f} = kL\right)$ 





**Magnetic Multipoles**: 
$$2n$$
 poles, "normal" and "skew", rotational symmetry  $\frac{2\pi}{n}$   $s_n = \frac{q}{p} \frac{\partial^{n-1} B_y}{\partial x^{n-1}}$ ,  $[s_n] = m^{-n}$ 

$$s_n = \frac{q}{p} \frac{\partial^{n-1} B_y}{\partial x^{n-1}}, \quad [s_n] = \mathbf{m}^{-n}$$

trajectory described by offsets (x,x',y,y') from design orbit, displacements  $x,y << \rho$ **Paraxial Optics:** 

Each element *i* is represented by transfer matrix  $\mathbf{M}_i$ , trajectory from  $\vec{x} = \prod_i \mathbf{M}_i \cdot \vec{x}_0$ **Geometric Optics:** 

**Matrices (simple approx)**: dipole and drift 
$$\mathbf{M}_D = \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix}$$
 quadrupole  $\mathbf{M}_Q = \begin{pmatrix} 1 & 0 \\ \pm 1/f & 1 \end{pmatrix}$