

SHOWER MOMENTS: A COMPACT REPRESENTATION OF SHOWER SHAPES

Parallel 6-A: Transition region/shower shape

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Geant 4

Approach

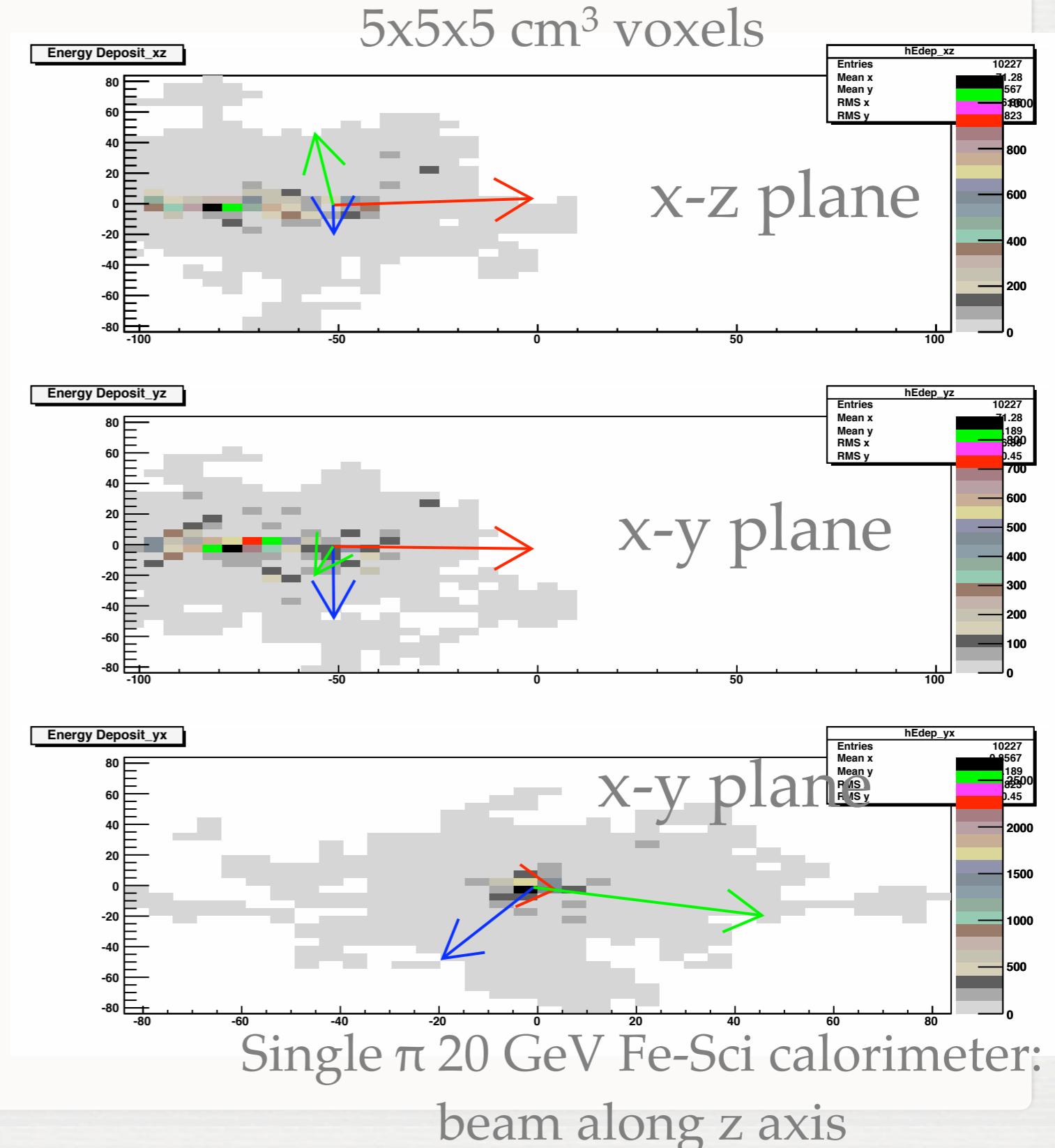
- To study shower shapes we usually make a profile of the energy distribution as a function of L or R
- Difficult to express in a compact form the dimension of the shower
- Depends on how the divisions in L and R are defined
- A different approach can be used to express these quantities in a “read-out” independent way
- Based on an idea from ATLAS EME calorimeters

Definitions

- Step 1: define an appropriate segmentation of the calorimeter (ReadOut) voxels, define Edep for each voxel
- Step 2: measure, for each voxel O: an observable that can be defined for each voxel (e.g. position, energy density, ...)
- Step 3: for each shower define the n -th order moment in O as:

$$E_{cl} = \sum_{v \in \{voxels\}} E_v$$

$$\langle O^n \rangle = \frac{1}{E_{cl}} \sum_{v \in \{voxels\}} E_v \times O_v^n$$



Shower Center And Shower Axis

- It is useful to define the shower center: $\vec{C} = (\langle x \rangle, \langle y \rangle, \langle z \rangle)$

$$M_{i,j} = \frac{1}{w} \sum_{v \in \{\text{voxels}\}} E_v^2 (i_v - \langle i \rangle) (j_v - \langle j \rangle)$$

- Let's also define the 3x3 matrix: $i, j \in \{x, y, z\}$

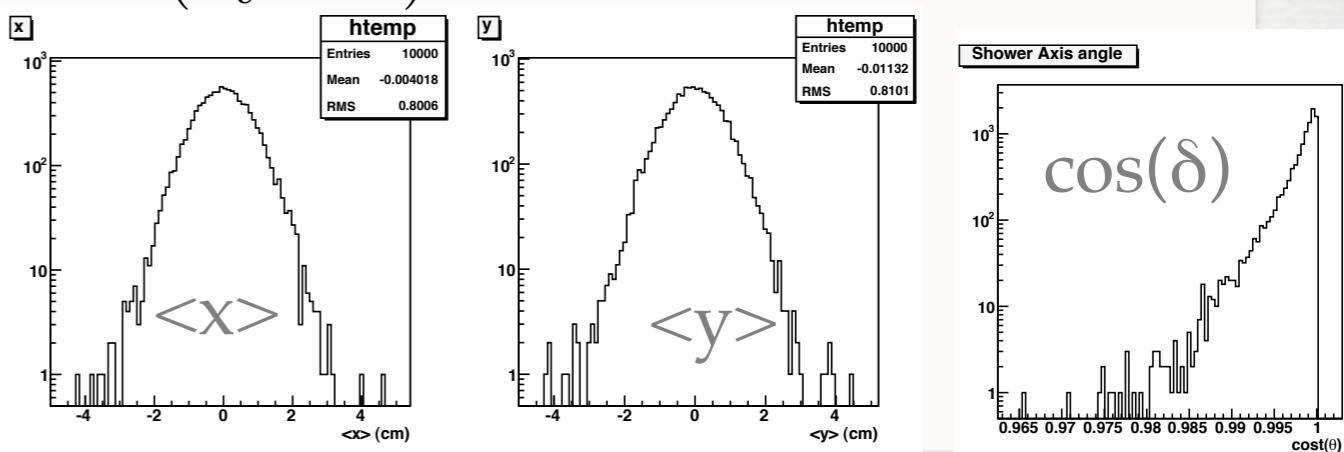
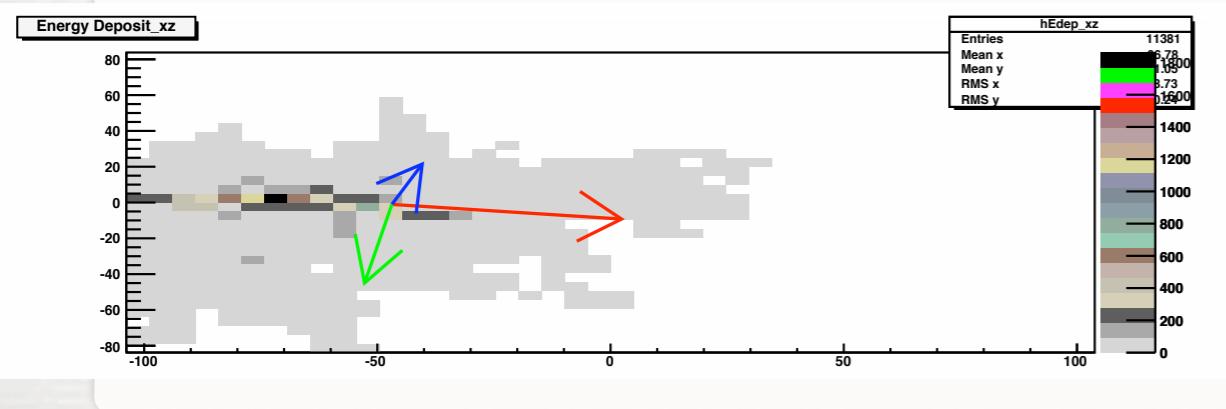
$$w = \sum_{v \in \{\text{voxels}\}}$$

- The shower 3D axes are the eigenvectors of the symmetric matrix M (principal component analysis)

- The shower axis is the eigenvector that forms the smallest angle with respect to the (beam origin-shower center) vector ($\sim z$ axis): \vec{S}

$$r_v = |(\vec{x}_v - \vec{C}) \times \vec{S}| \quad \begin{matrix} \text{Position of the cell, w.r.t.} \\ \text{shower center and axis} \end{matrix}$$

- For each voxel we define: $\lambda_v = (\vec{x}_v - \vec{C}) \cdot \vec{S}$



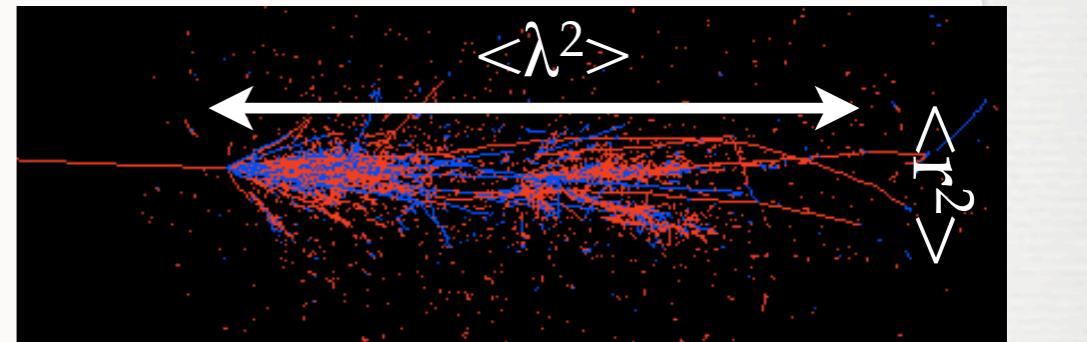
Shower Moments

$$\langle \lambda^2 \rangle = \frac{\sum_{cell} E_{cell} \lambda_{cell}^2}{\sum_{cell} E_{cell}}$$

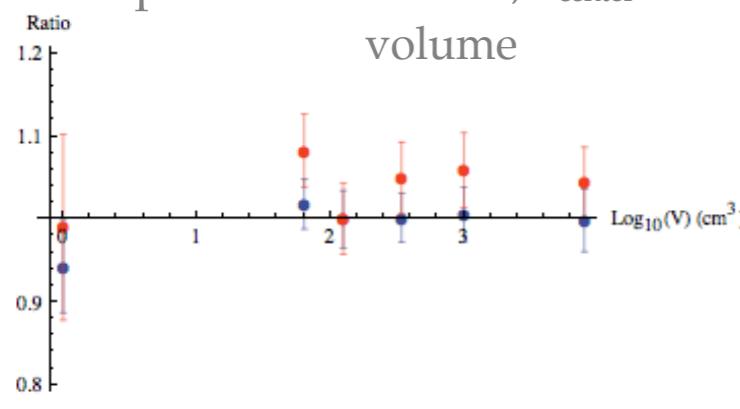
$$\langle r^2 \rangle = \frac{\sum_{cell} E_{cell} r_{cell}^2}{\sum_{cell} E_{cell}}$$

For each shower calculate some moments:

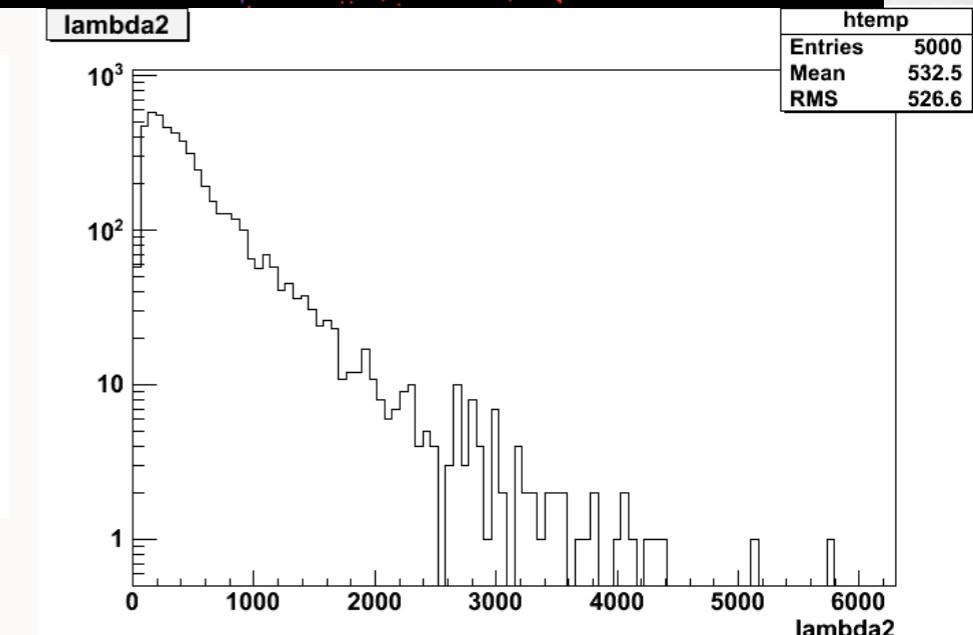
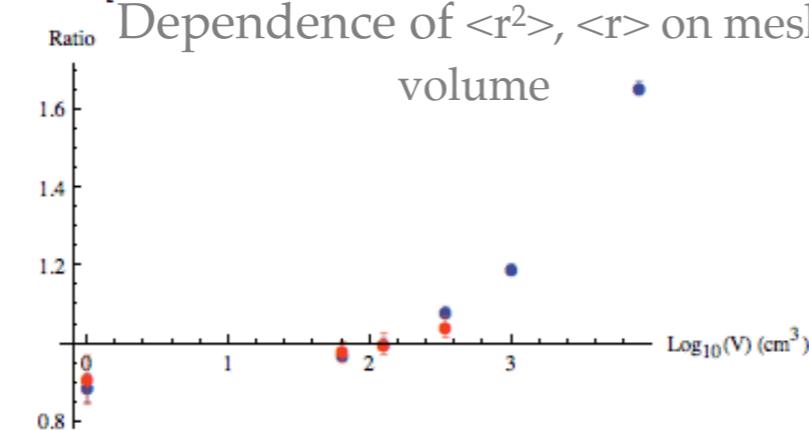
- $\langle r^2 \rangle, \langle \lambda^2 \rangle, \lambda_{center}$ ($\langle z \rangle$ -FrontFace)
- Reduce dependence on mesh dimension



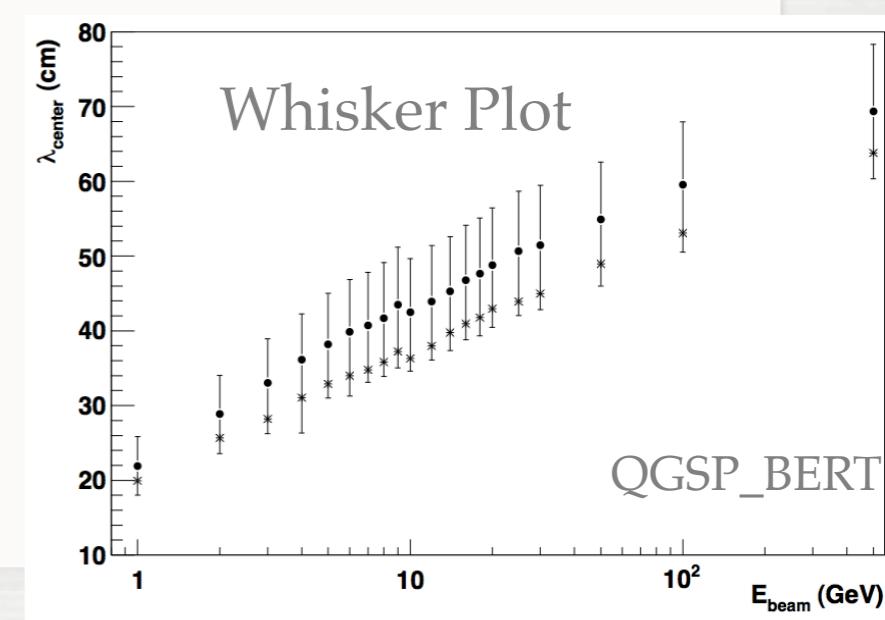
Dependence of $\langle \lambda^2 \rangle, \lambda_{center}$ on mesh volume



Dependence of $\langle r^2 \rangle, \langle r \rangle$ on mesh volume



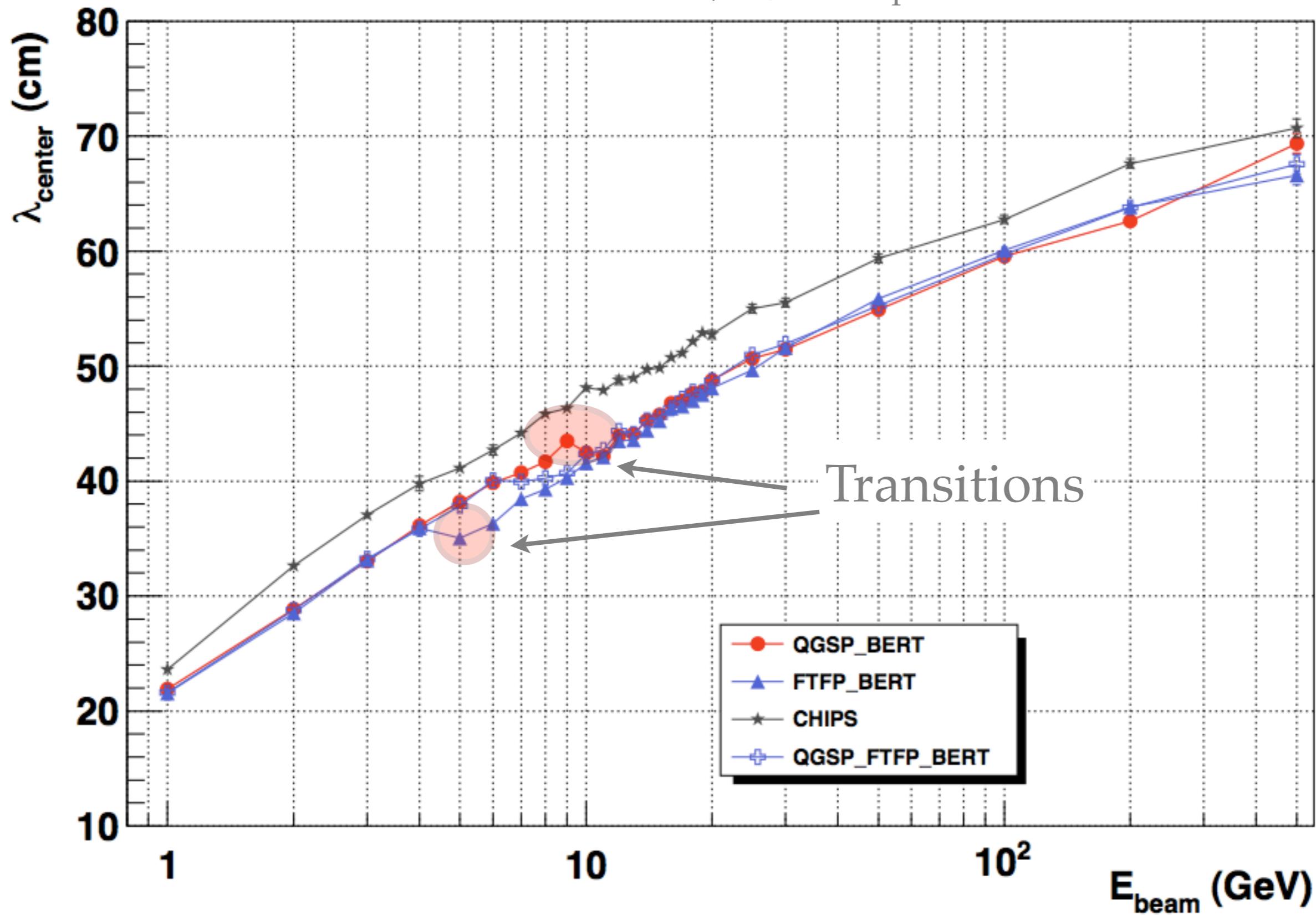
- Distributions of shower moments have **long tail**
- However the distributions are “well-behaved”, i.e. **their statistical quantities (mean, median, quantiles) are a smooth function of primary energy**
- Can summarize shower shapes in terms of e.g. **Mean and Variance** (or median quantiles, skewness and kurtosis,...)



Shower Maximum depth

π^- beam, Fe/Sci simplified calo

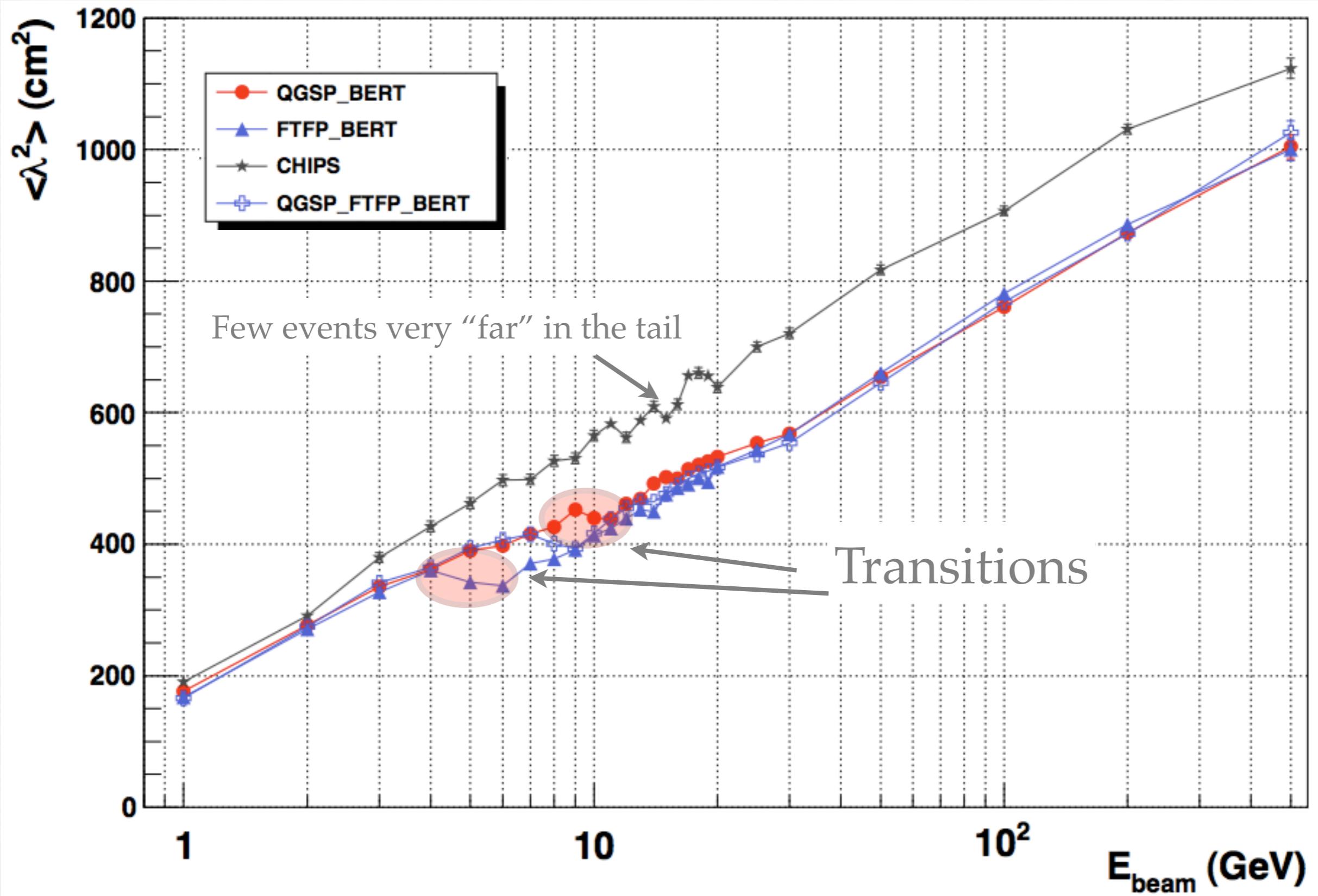
G4 9.3.ref02



Shower "length"

π^- beam, Fe/Sci simplified calo

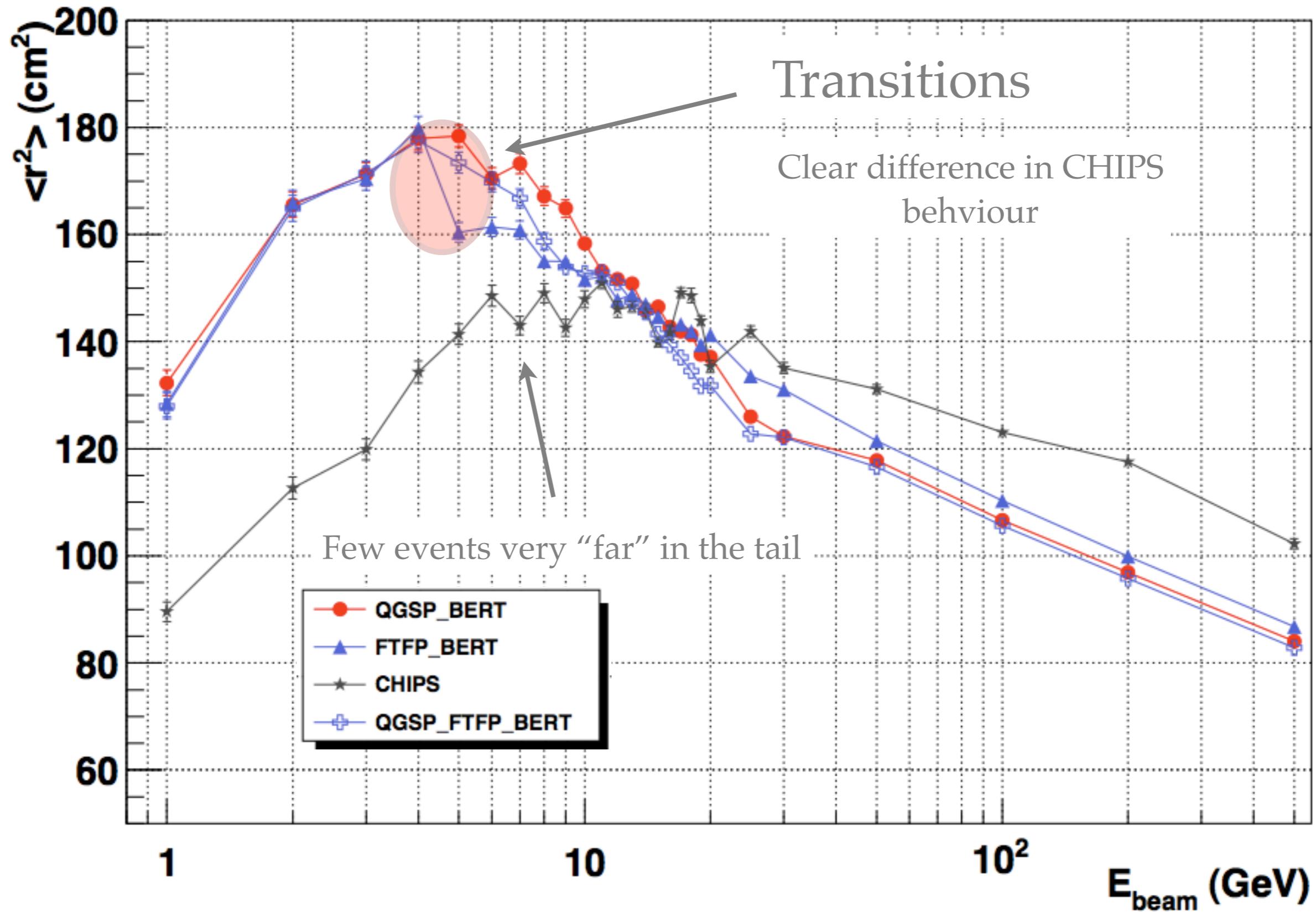
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Shower “width”

π^- beam, Fe/Sci simplified calo

G4 9.3.ref02



Conclusions

- We have developed a method to summarize shower shapes in a compact form (few numbers, **2-3 are enough**: λ_{center} , $\langle \lambda \rangle$, $\langle r^2 \rangle$)
- Weak dependence on “read-out” mesh size
- Some results:
 - FTFP/BERT transition (not seen in response, solved in recent ref. tags)
 - CHIPS fluctuations
- We are now calculating these quantities routinely and store results in a (very simple) DB