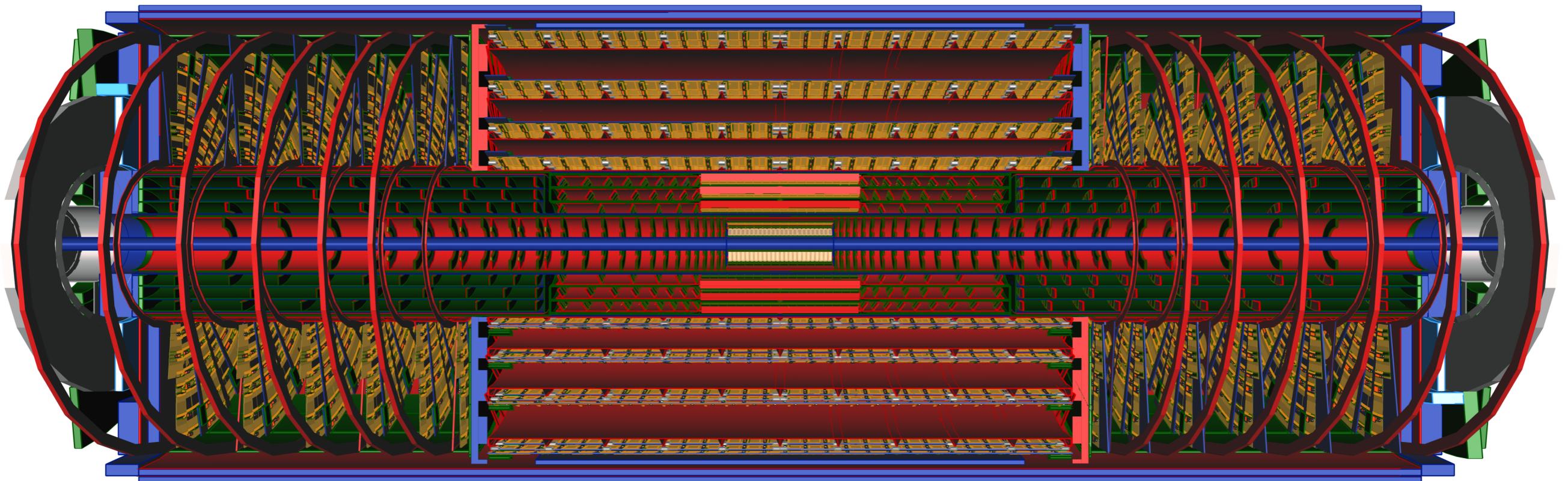
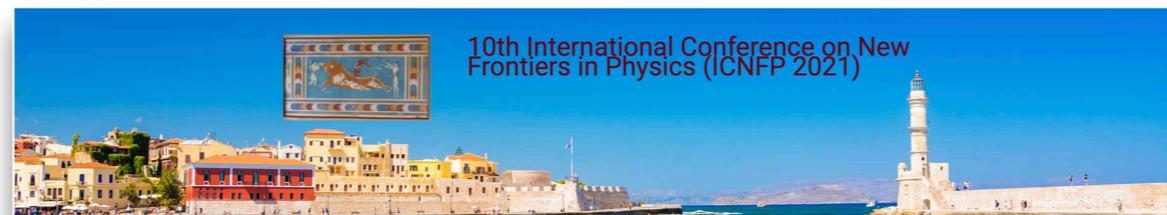


# ATLAS Track and Vertex Reconstruction for Run-3 and High-Luminosity LHC

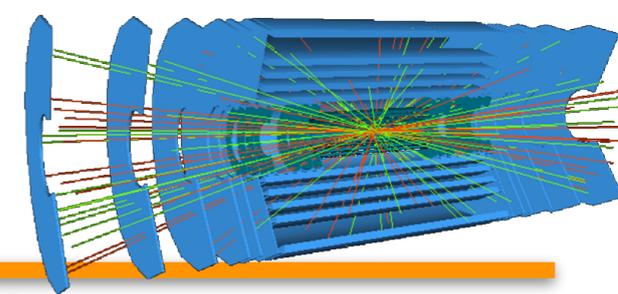
by Markus Elsing on behalf of the ATLAS Collaboration



ATLAS ITk : HL-LHC upgrade of the inner tracking system

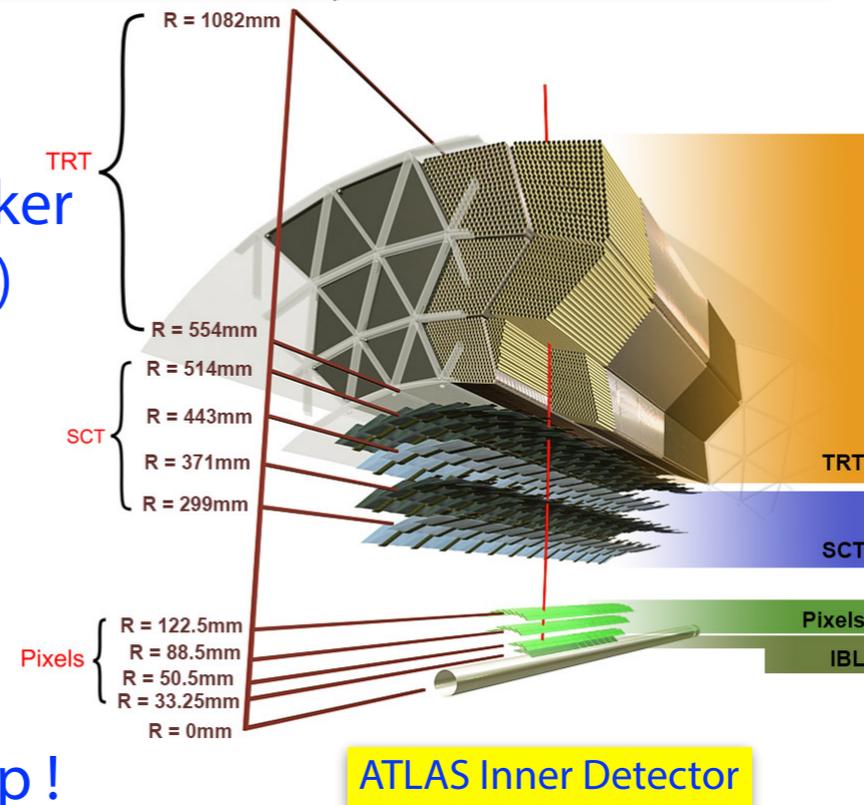


# Experience from Run-2 and Outlook



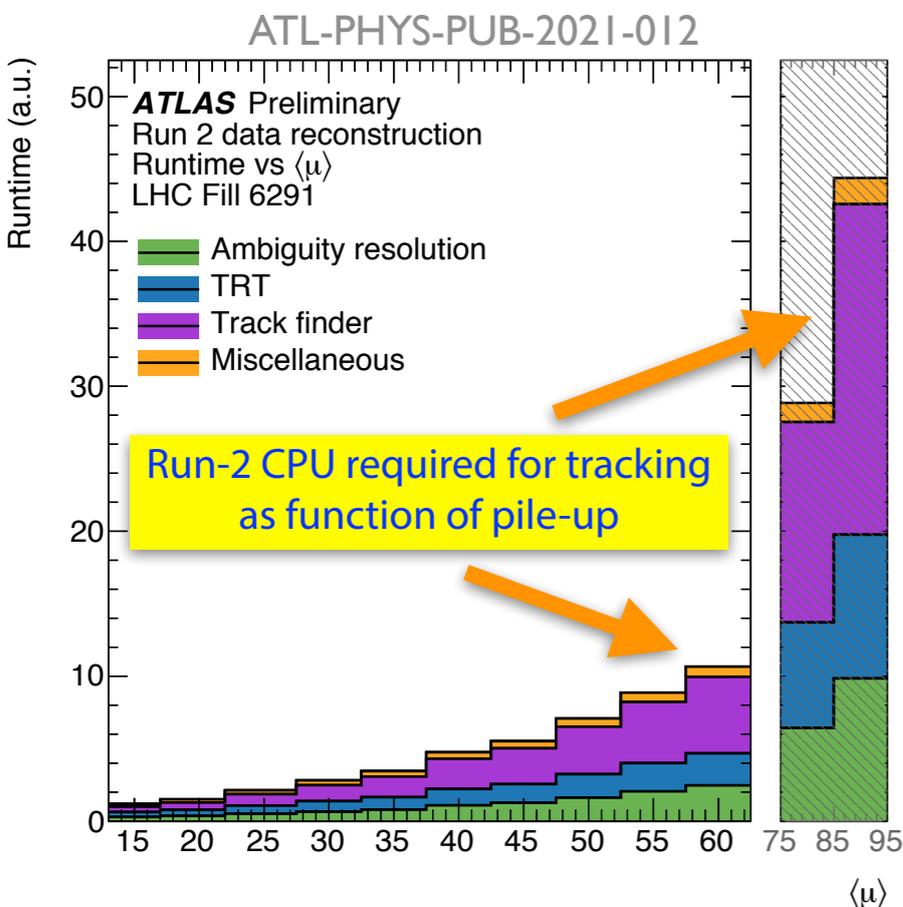
## ● current ATLAS Inner Detector

- ➔ 4 Pixel layers, 4 double sided Strips, Transition Radiation Tracker
  - was upgraded in Long Shutdown-1 with 4th Pixel layer (IBL)
- ➔ designed for excellent performance at pile-up of 23
  - during Run-2 operated routinely at pile-up well above 35

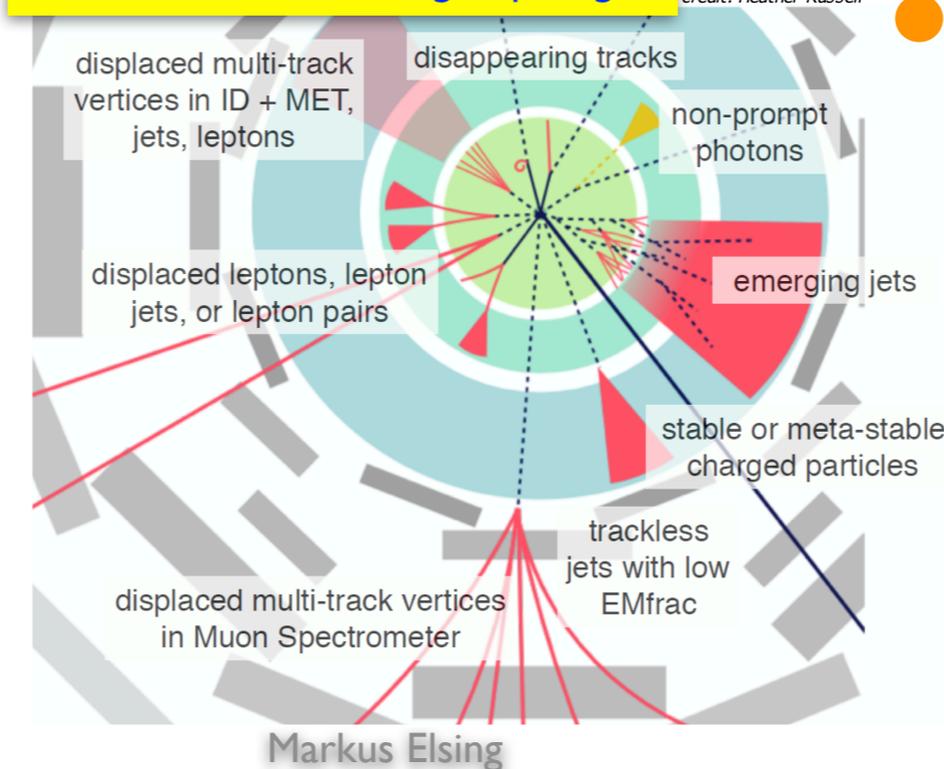


## ● preserving performance is a challenge !

- ➔ tracking and vertexing needs to be robust against pile-up
- ➔ CPU required for reconstruction increases rapidly with pile-up !



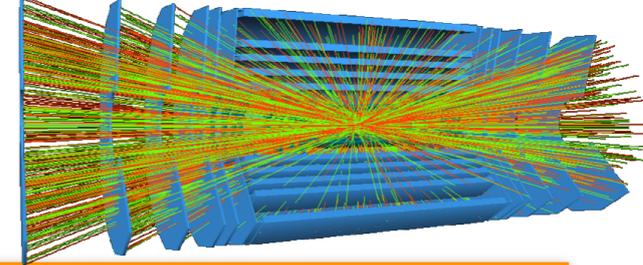
## unconventional tracking topologies



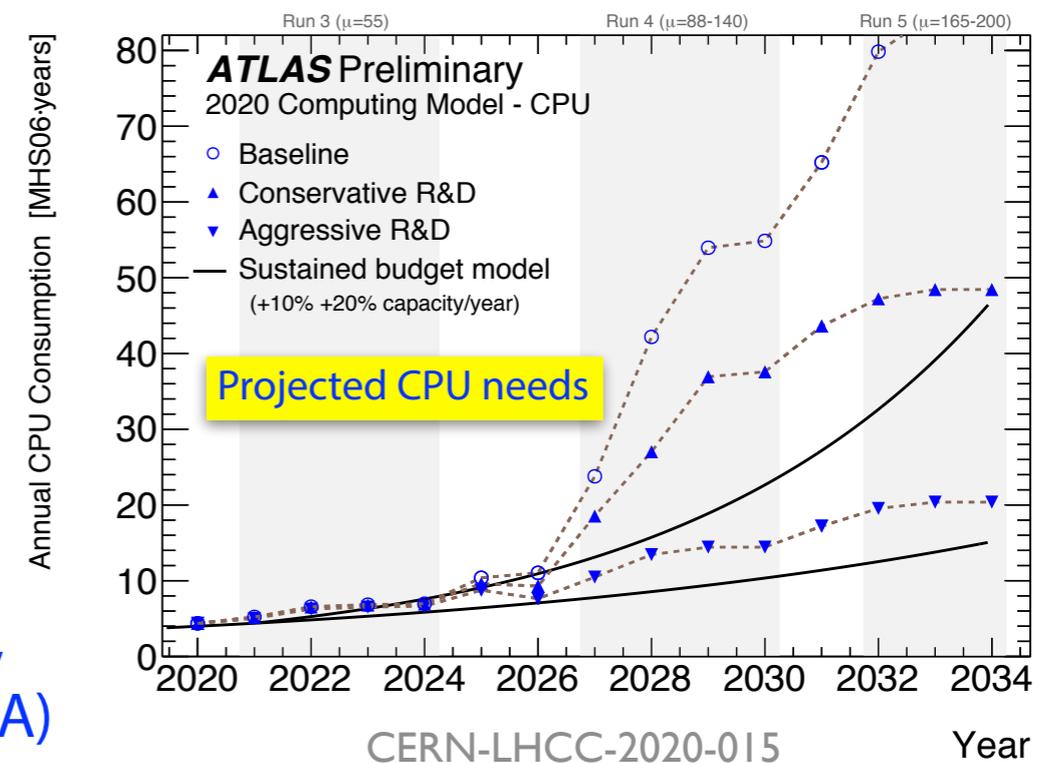
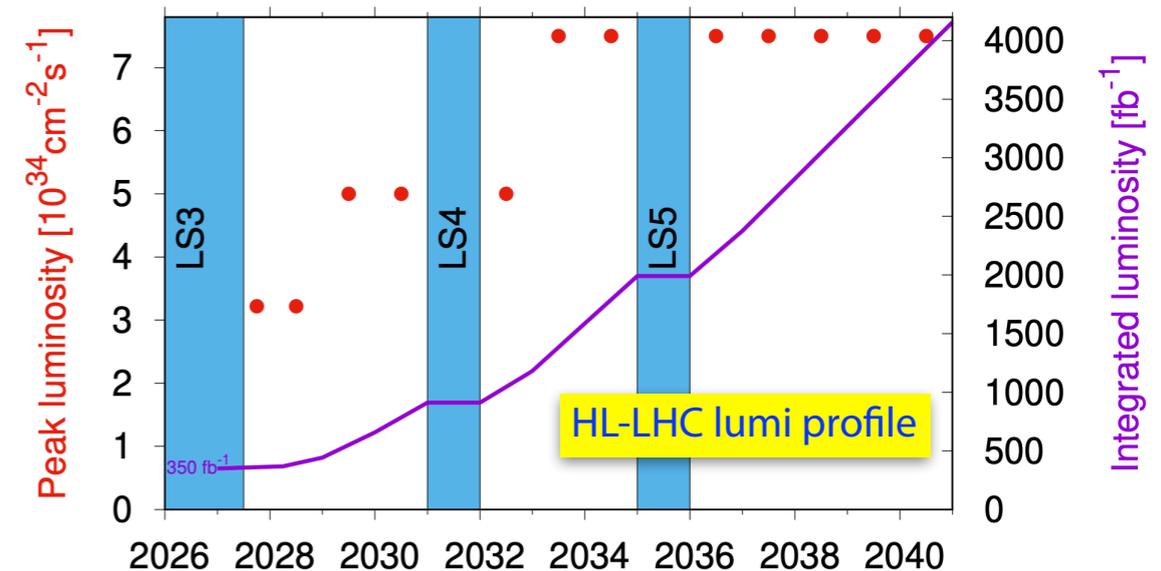
## ● large radius tracking

- ➔ searches for long-lived particles !
- ➔ significant CPU for additional tracking pass
- ➔ not possible in Tier-0 during Run-2
- ➔ required dedicated stream, processed on the Grid

# Outlook to Run-3 and HL-LHC



- Run-3 expected av. pile-up is  $\sim 50$ 
  - ➔ double total integrated luminosity until 2025
  - ➔ end-of-lifetime of current Inner Detector
- goal of LH-LHC is to collect  $4 \text{ ab}^{-1}$ 
  - ➔ average pile-up will rise to 140 to 200 !
  - ➔ radiation levels and data rates unprecedented
  - ➔ ATLAS Inner Tracker (ITk) upgrade (all silicon)
- a challenge !
  - ➔ require excellent tracking performance, despite harsh pile-up environment
  - ➔ CPU for reconstruction and disk space needs will exceed computing budget extrapolations
  - ➔ computing technology becoming heterogenous, with many core CPUs and accelerators (GPU, FPGA)



- tracking developments for Run-3 are also a preparation towards HL-LHC

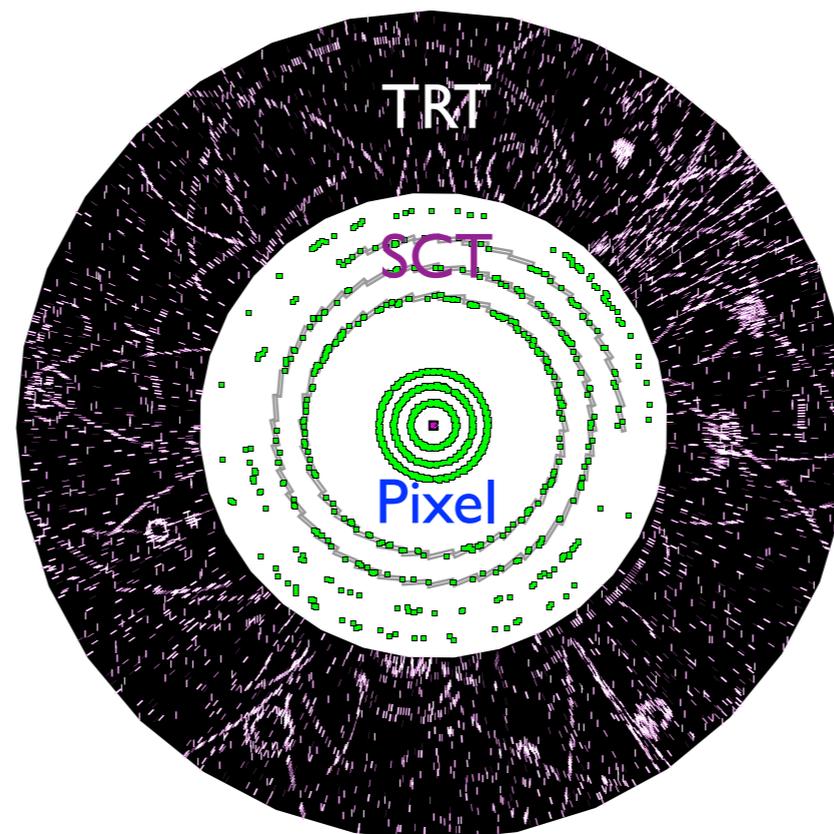




# Run-2(3) Tracking and Vertexing Chain

## pre-processing

- ➔ Pixel+SCT clustering
- ➔ TRT drift circle formation
- ➔ space points formation





# Run-2(3) Tracking and Vertexing Chain

## pre-processing

- ➔ Pixel+SCT clustering
- ➔ TRT drift circle formation
- ➔ space points formation



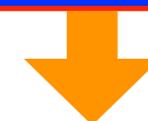
## combinatorial track finder

- ➔ iterative :
  1. Pixel seeds
  2. Pixel+SCT seeds
  3. SCT seeds
- ➔ restricted to roads
- ➔ Brem.recovery in EM Regions-of-Interest



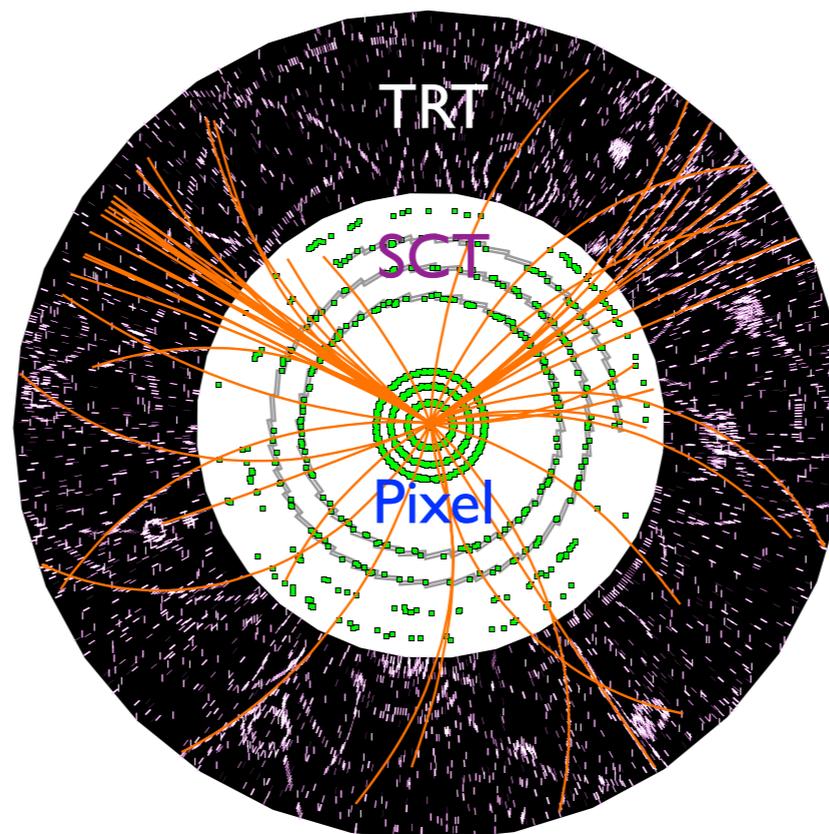
## ambiguity solution

- ➔ runs hole search
- ➔ scores tracks according to quality
- ➔ NN cluster splitting in jets
- ➔ precise least square fit with Brem.recovery
- ➔ final selection cuts



## extension into TRT

- ➔ progressive finder
- ➔ refit of track with Brem.
- ➔ scoring and selection cuts





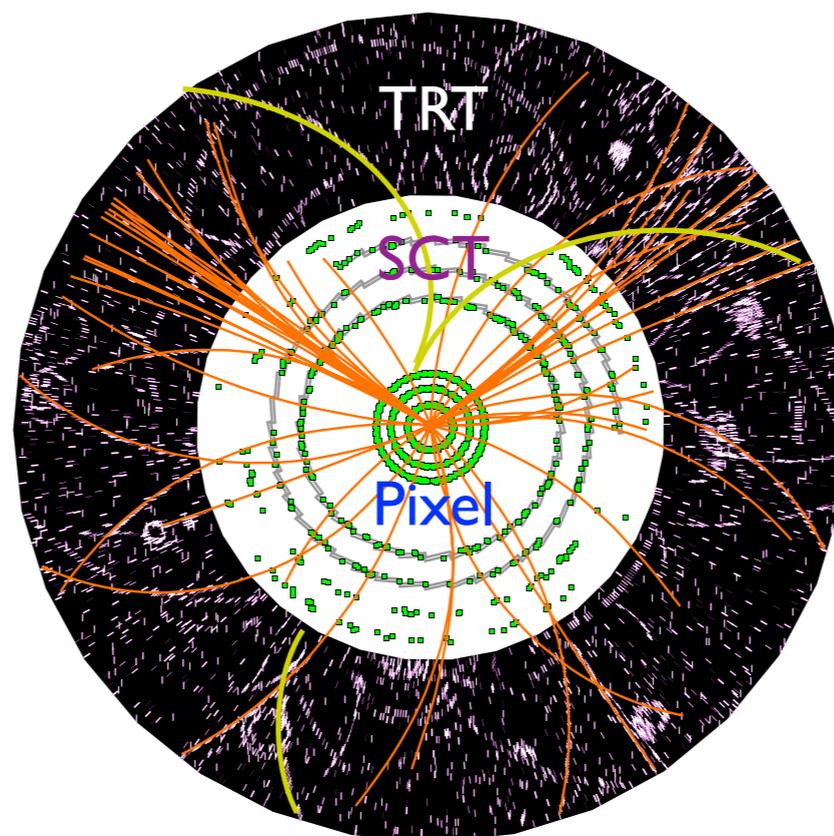
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- ➔ NN cluster splitting in jets
- ➔ precise least square fit with Brem.recovery
- ➔ final selection cuts

## ambiguity solution

- ➔ precise fit and selection
- ➔ TRT seeded tracks

## TRT seeded finder

- ➔ from TRT into SCT+Pixels
- ➔ combinatorial finder

## TRT segment finder

- ➔ in EM Regions-of-Interest
- ➔ on remaining drift circles
- ➔ uses Hough transform

## extension into TRT

- ➔ progressive finder
- ➔ refit of track with Brem.
- ➔ scoring and selection cuts





# Run-2(3) Tracking and Vertexing Chain

## pre-processing

- ➔ Pixel+SCT clustering
- ➔ TRT drift circle formation
- ➔ space points formation

## combinatorial track finder

- ➔ iterative :
  1. Pixel seeds
  2. Pixel+SCT seeds
  3. SCT seeds
- ➔ restricted to roads
- ➔ Brem.recovery in EM Regions-of-Interest

## tracklet finder

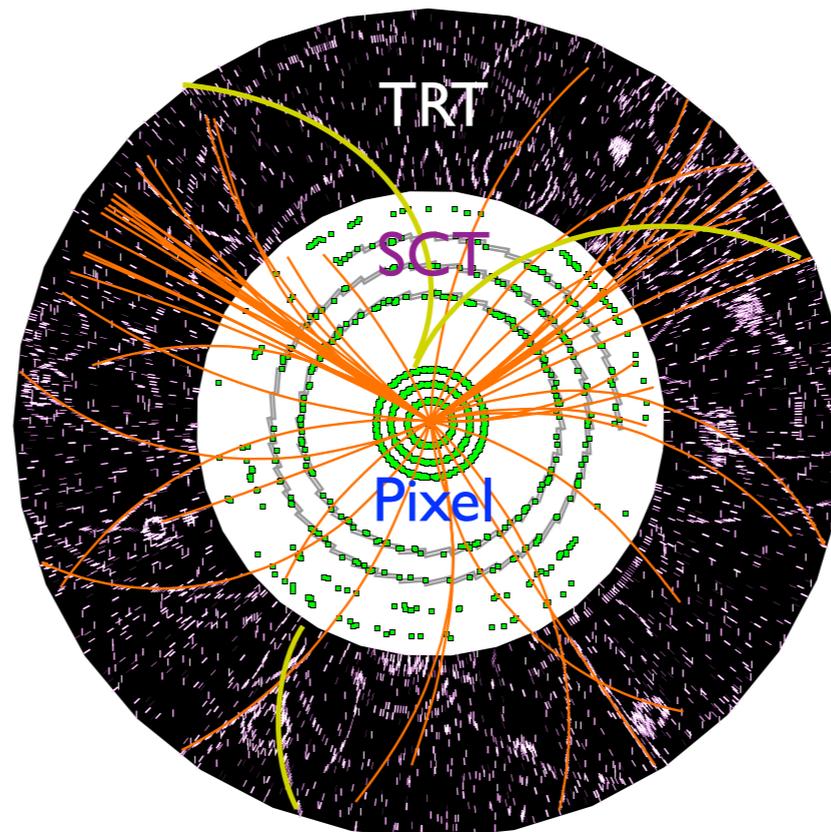
- ➔ muon candidates  $|\eta| > 2.5$
- ➔ short tracks

## ambiguity solution

- ➔ precise fit and selection
- ➔ TRT seeded tracks

## TRT seeded finder

- ➔ from TRT into SCT+Pixels
- ➔ combinatorial finder



## ambiguity solution

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## TRT segment finder

- ➔ in EM Regions-of-Interest
- ➔ on remaining drift circles
- ➔ uses Hough transform





# Run-2(3) Tracking and Vertexing Chain

**vertexing**

- ➔ primary vertexing
- ➔ conversion and V0 search

**tracklet finder**

- ➔ muon candidates  $|\eta| > 2.5$
- ➔ short tracks

**ambiguity solution**

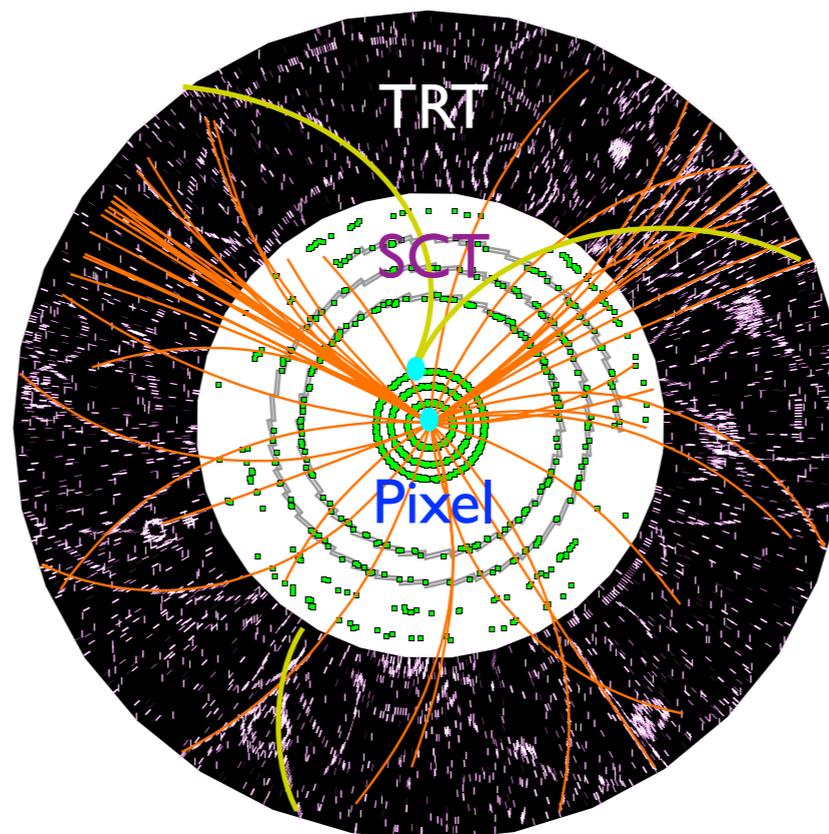
- ➔ precise fit and selection
- ➔ TRT seeded tracks

**TRT seeded finder**

- ➔ from TRT into SCT+Pixels
- ➔ combinatorial finder

**pre-processing**

- ➔ Pixel+SCT clustering
- ➔ TRT drift circle formation
- ➔ space points formation



**combinatorial track finder**

- ➔ iterative :
  1. Pixel seeds
  2. Pixel+SCT seeds
  3. SCT seeds
- ➔ restricted to roads
- ➔ Brem.recovery in EM Regions-of-Interest

**ambiguity solution**

- ➔ runs hole search
- ➔ scores tracks according to quality
- ➔ NN cluster splitting in jets
- ➔ precise least square fit with Brem.recovery
- ➔ final selection cuts

**extension into TRT**

- ➔ progressive finder
- ➔ refit of track with Brem.
- ➔ scoring and selection cuts

**TRT segment finder**

- ➔ in EM Regions-of-Interest
- ➔ on remaining drift circles
- ➔ uses Hough transform





# Run-2(3) Tracking and Vertexing Chain

**vertexing**

- ➔ primary vertexing
- ➔ conversion and V0 search

**tracklet finder**

- ➔ muon candidates  $|\eta| > 2.5$
- ➔ short tracks

**ambiguity solution**

- ➔ precise fit and selection
- ➔ TRT seeded tracks

**TRT seeded finder**

- ➔ from TRT into SCT+Pixels
- ➔ combinatorial finder

**pre-processing**

- ➔ Pixel+SCT clustering
- ➔ TRT drift circle formation
- ➔ space points formation

**Large Radius Tracking (LRT) as a additional iteration**

- ➔ combinatorial track finder, ambiguity solution, extension, secondary vertexing
- ➔ different track selection strategy adopted to event topology

**combinatorial track finder**

- ➔ iterative :
  1. Pixel seeds
  2. Pixel+SCT seeds
  3. SCT seeds
- ➔ restricted to roads
- ➔ Brem.recovery in EM Regions-of-Interest

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- ➔ scoring and selection cuts



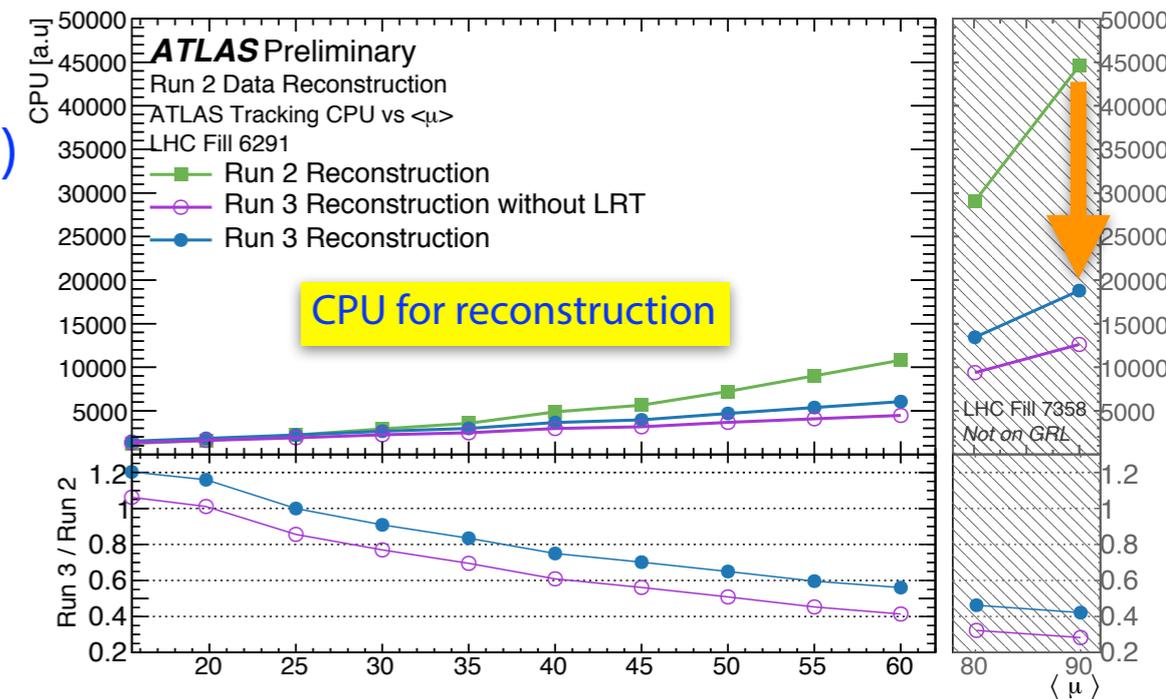
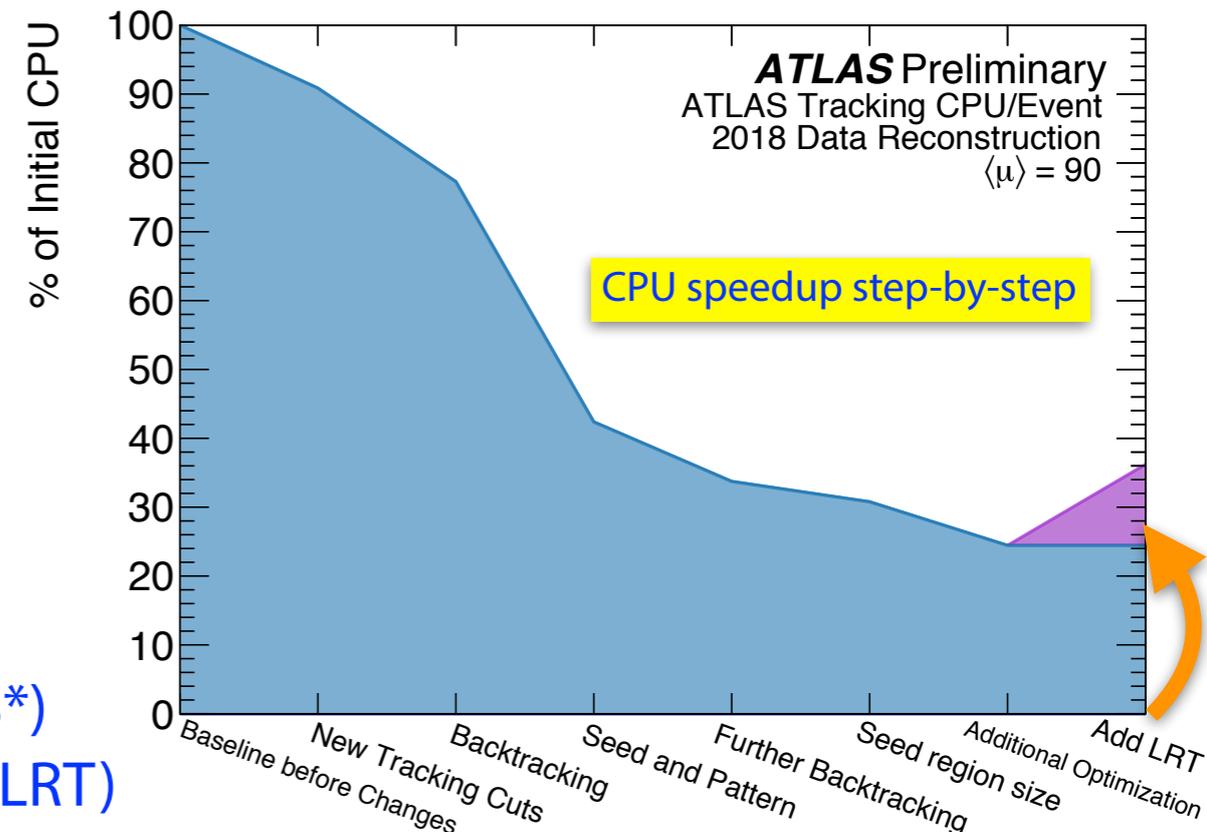
# Optimisation of Run-3 Tracking Software

## ● intensive development programme

- ➔ software technology changed to multi-threading
- ➔ optimisation of primary tracking:
  - stricter cuts: at least 8 hits and  $|d_0| < 5$  mm
  - Back-Tracking and TRT optimised and seeded using EM calorimeter deposits with  $E_T > 6$  GeV
  - seeding and pattern recognition tuning: stricter cuts, narrower roads, seed confirmation
  - novel primary vertex finder (first time using ACTS\*)
- ➔ apply optimisations also to Large Radius Tracking (LRT)

## ● ×4 speedup for tracking at 90 pile-up

- ➔ include faster LRT in Tier-0 reconstruction (all events)
  - huge simplification in computing model and reduction in storage
  - exciting prospects for searches!
- ➔ Run-3 reconstruction overall ×2 faster and improved selection reduces event size by 25%



# Optimisation of Run-3 Tracking Software

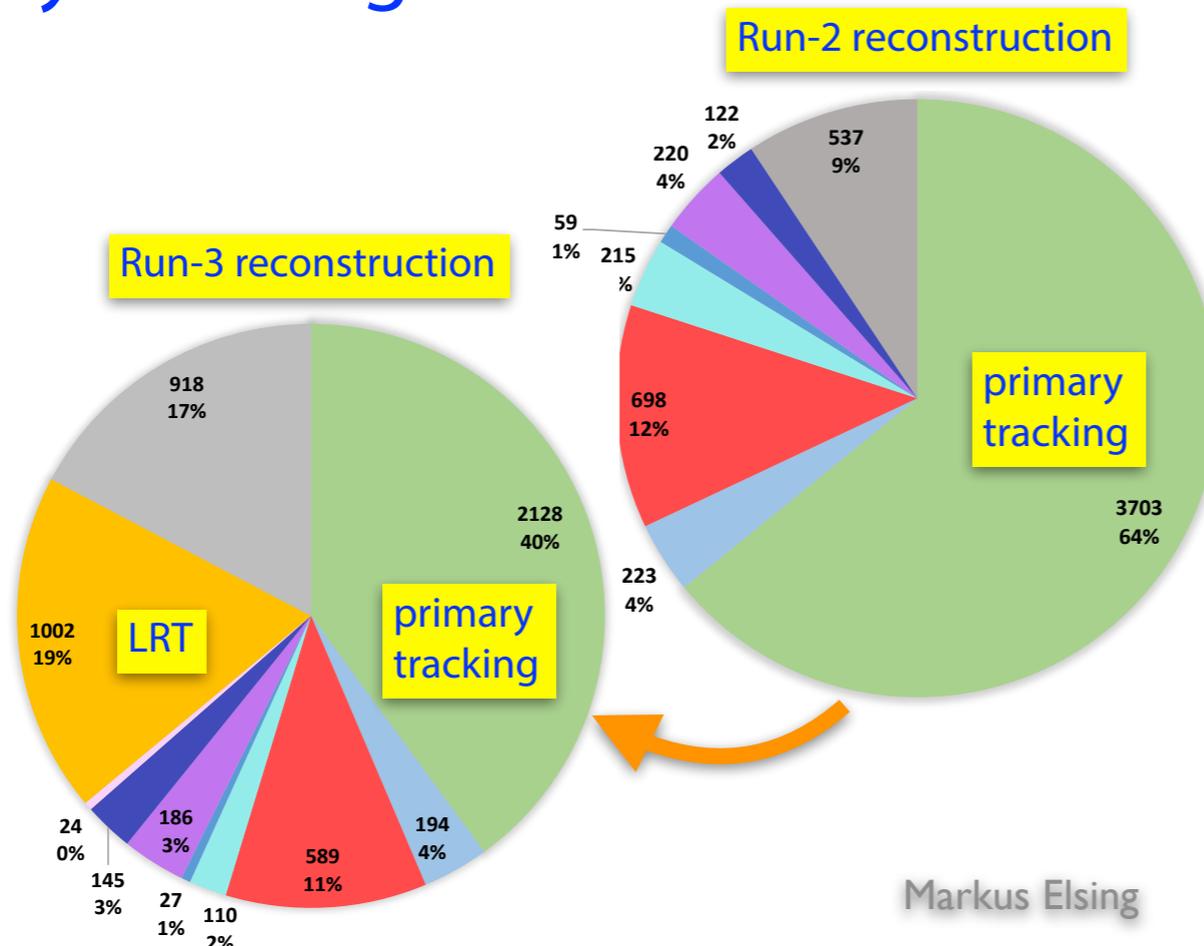
## ● effect on tracking performance

- ➔ CPU improvements largely due to early rejection of fakes and secondaries
- ➔ efficiency loss varies from 1% (4%) at high-(low-) $p_T$  [  $N(\text{hit}) \geq 8$  for Run-3, compared to  $N(\text{hit}) \geq 7$  for Run-2 ]
- ➔ much more linear increase in number of tracks vs pile-up indicates improved pile-up robustness

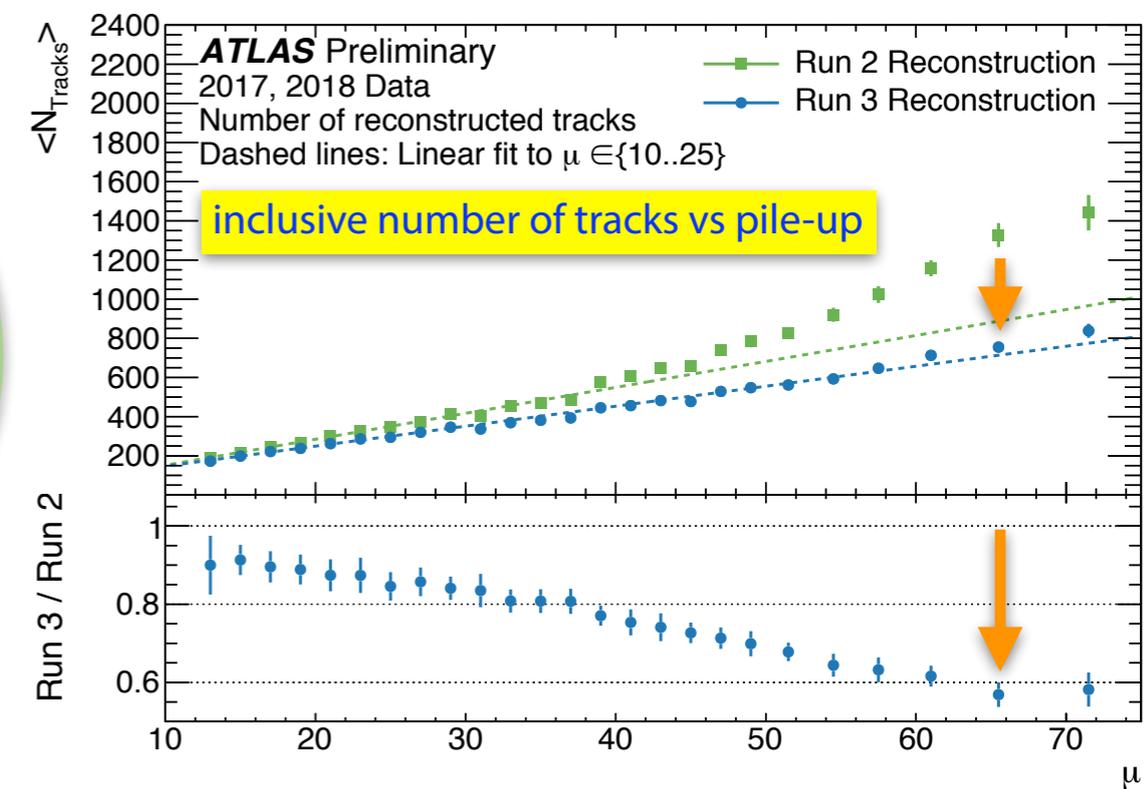
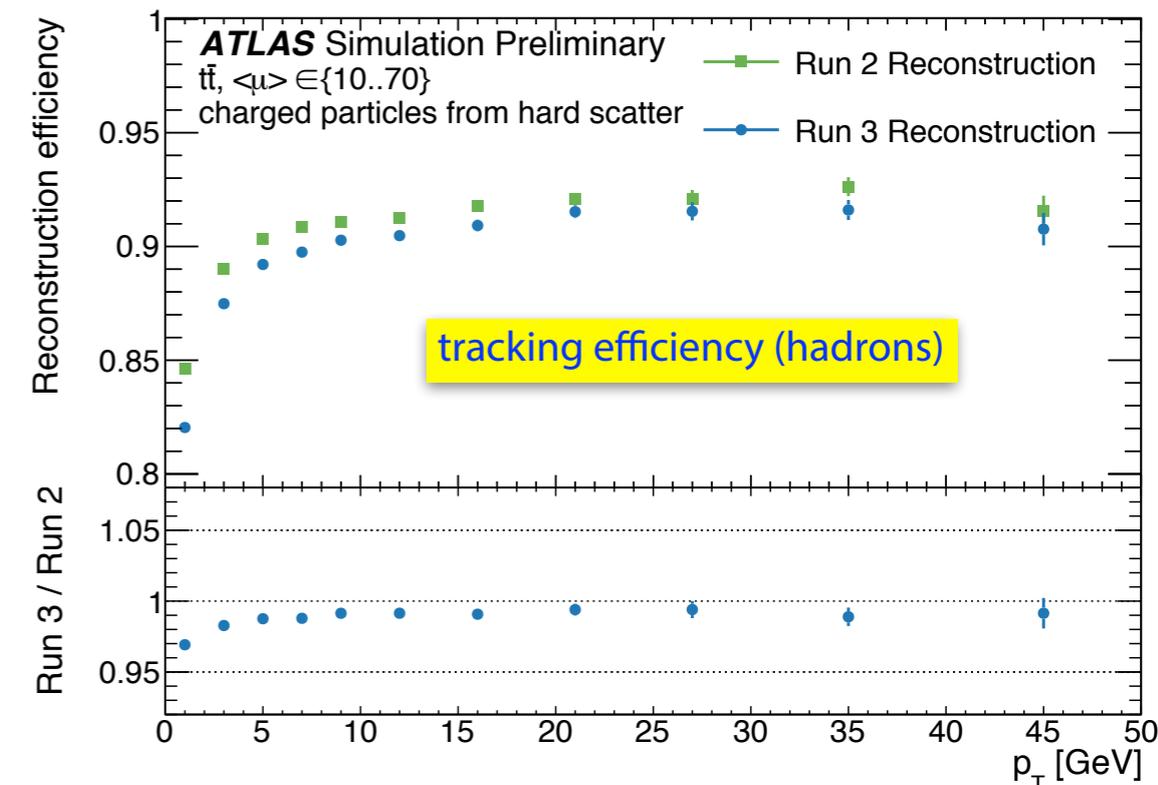
## ● primary tracking + LRT still >50% CPU

ATLAS Preliminary  
RUN 3 RECONSTRUCTION  
CPU TIME [A.U]

■ INDET  
 ■ CALO  
 ■ MUON  
 ■ EGAMMA  
 ■ TAU  
 ■ PFO  
 ■ JETETMISS  
 ■ BTAG  
 ■ LRT  
 ■ OTHER

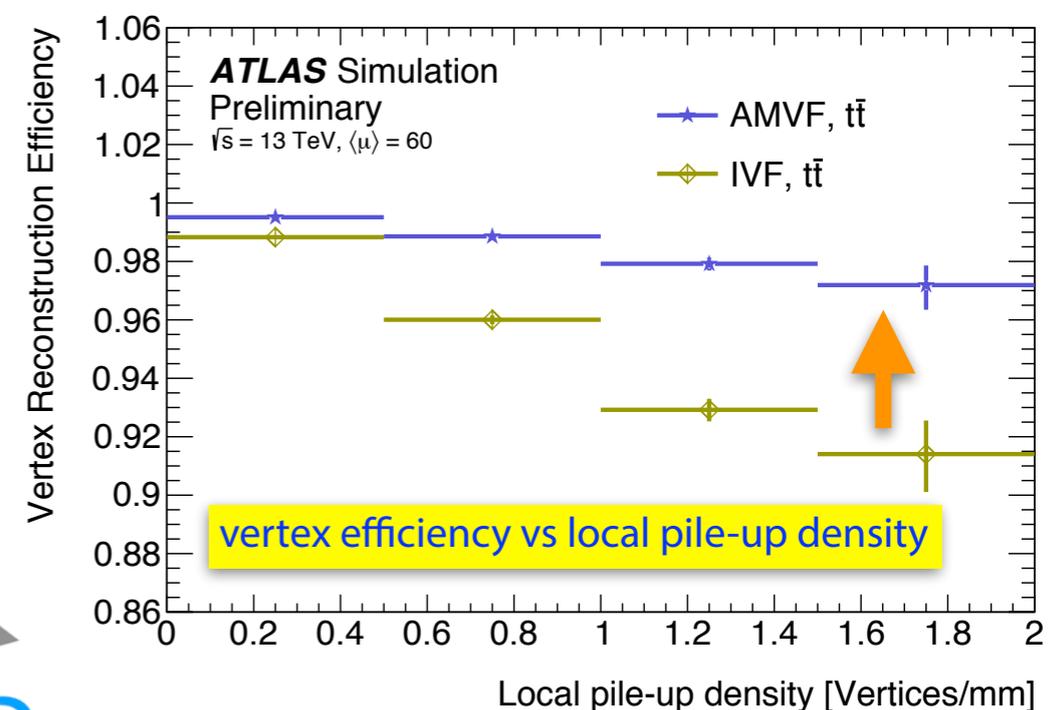
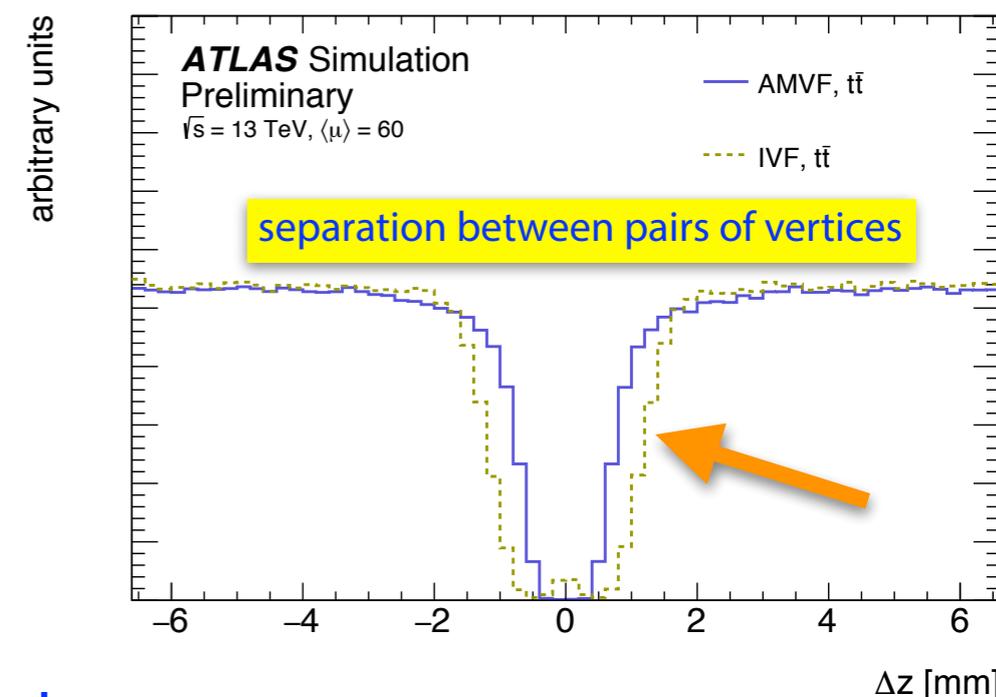


Markus Elsing



# New Run-3 Primary Vertex Reconstruction

- change in vertex finding algorithm:
  - ➔ Run-2: Iterative Primary Vertex Finder (IVF)
  - ➔ Run-3: Adaptive Multi-Vertex Finder (AMVF)
- AMVF reconstruction strategy:
  - ➔ novel gaussian track density vertex seed finder
  - ➔ tracks are associated to vertex candidates with weights according to their distance
  - ➔ vertex candidates share tracks and are fitted simultaneously
- much improved pile-up performance:
  - ➔ improved separation of nearby vertices along z
  - ➔ better efficiency for  $t\bar{t}$  and VBF  $H \rightarrow 4\nu$
  - ➔ 20% (10%) better resolution for  $t\bar{t}$  (VBF  $H \rightarrow 4\nu$ )
- AMVF implemented in ACTS\* framework
  - ➔ modern software yields 40% speedup in CPU!



→ number of vertices per unit length within a  $\pm 2 \text{ mm}$  longitudinal window

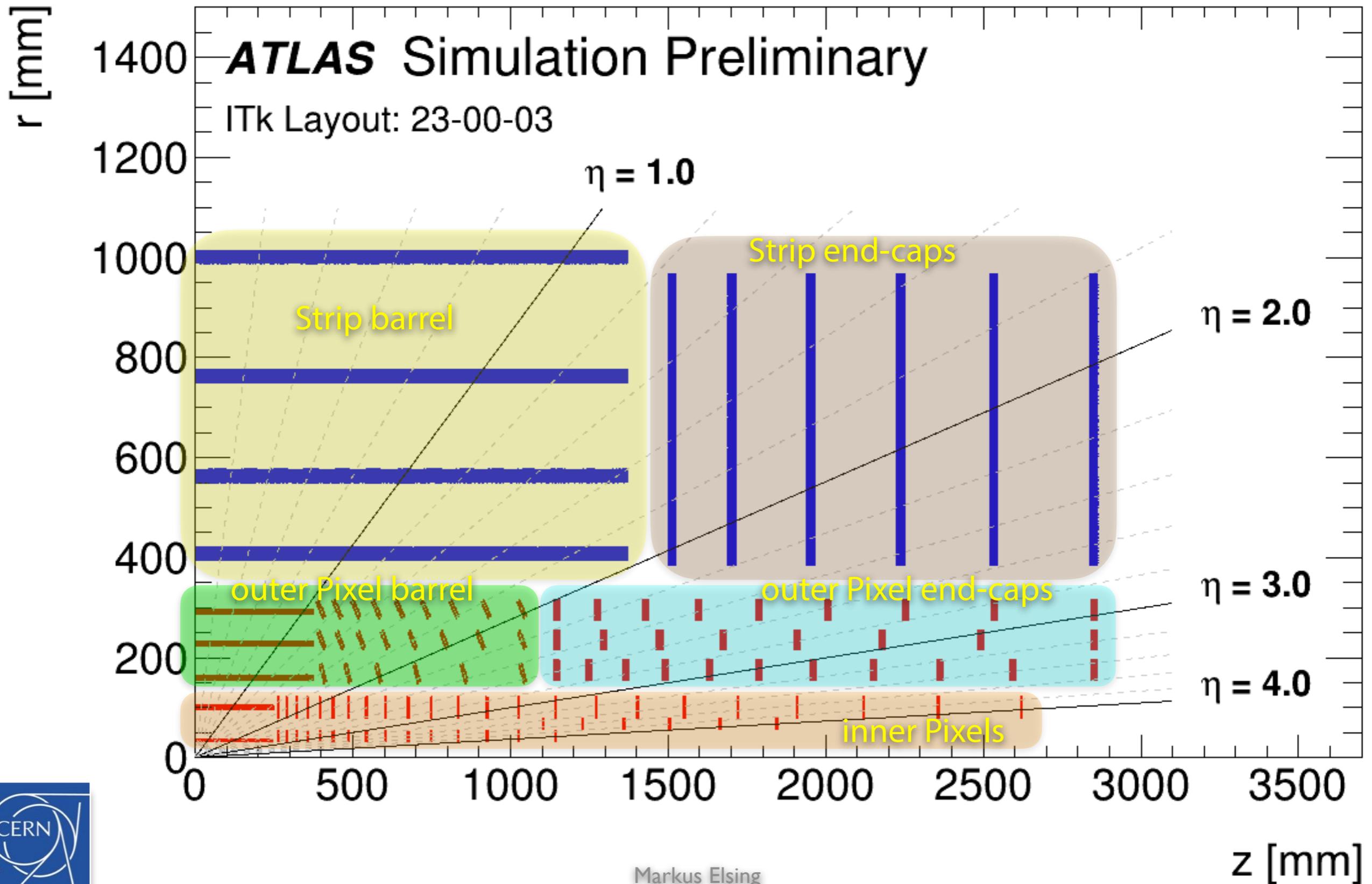


\* I'll come to ACTS later



Markus Elsing

# The ATLAS HL-LHC Tracker (ITk) Upgrade



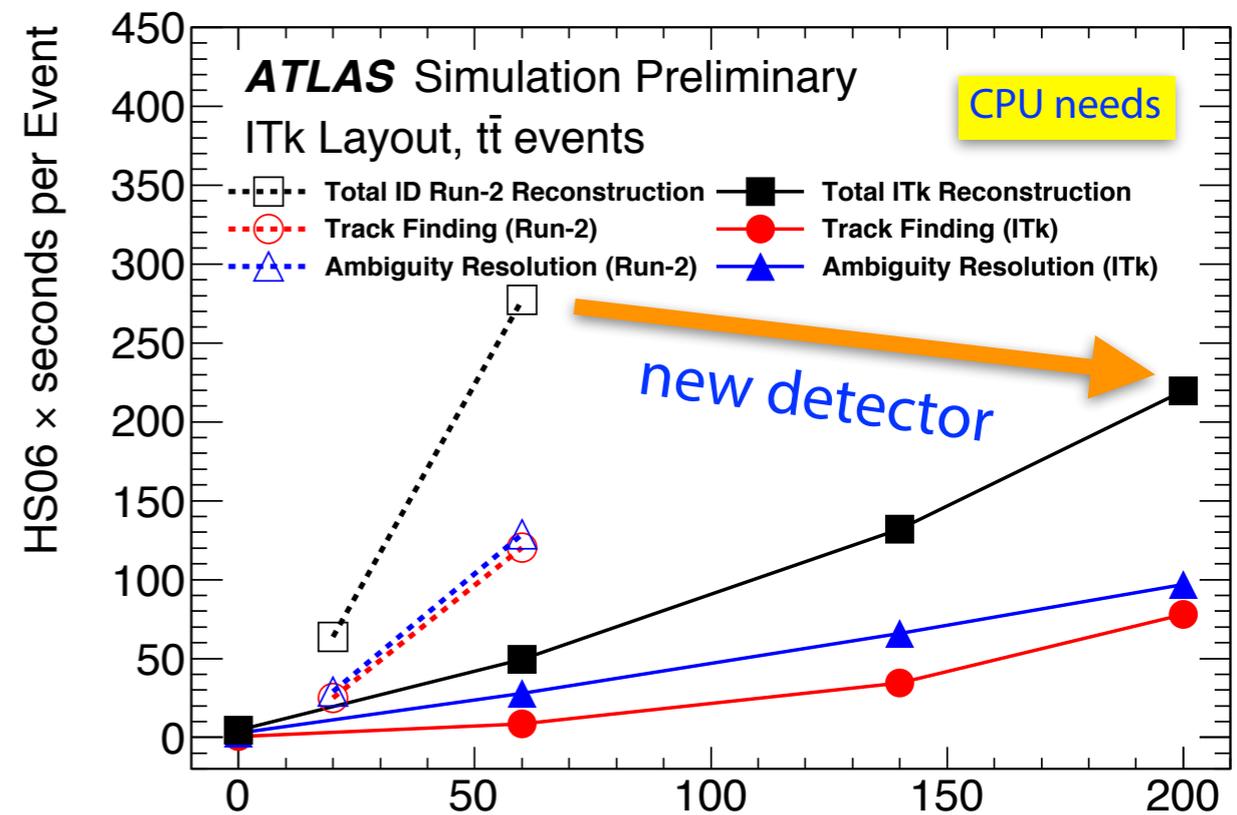
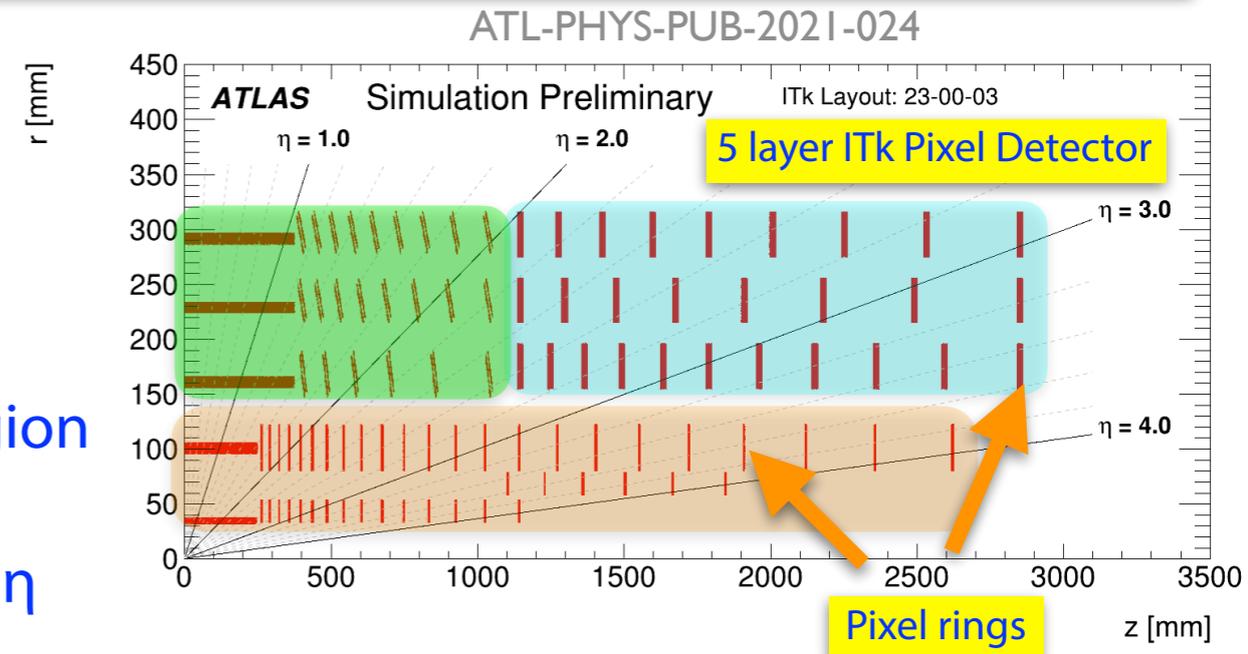
# The ATLAS HL-LHC Tracker (ITk) Upgrade

## ● designed for fast precision tracking

- ➔ 5 Pixel layers, 4 Strip layers (double-sided)
  - extends  $|\eta|$  coverage from 2.5 to 4.0
  - improved granularity and hit redundancy
  - aims to minimise material in active tracking region
- ➔ 5 layer ITk Pixel Detector with ring design:
  - efficient standalone seed finding in Pixels at all  $\eta$
- ➔ flexible Pixel ring placement:
  - keeps hit coverage constant in forward region
  - avoid large gaps between adjacent rings

## ● default ITk track reconstruction:

- ➔ no TRT, hence simplified tracking chain
- ➔ seed finding only in Pixels or in Strips, followed by track finder and ambiguity solution
- ➔ significant speed-up of reconstruction at 200 pile-up, with excellent performance



ATL-PHYS-PUB-2019-041

$\langle \mu \rangle$



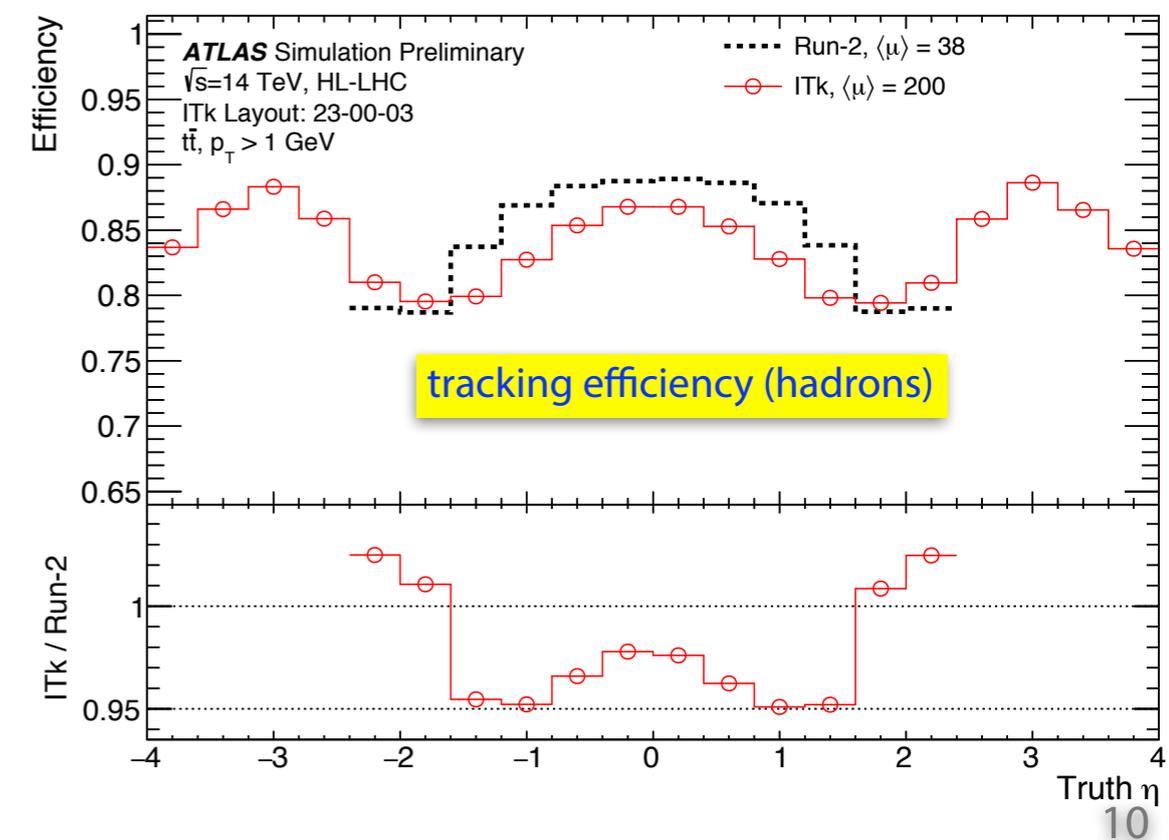
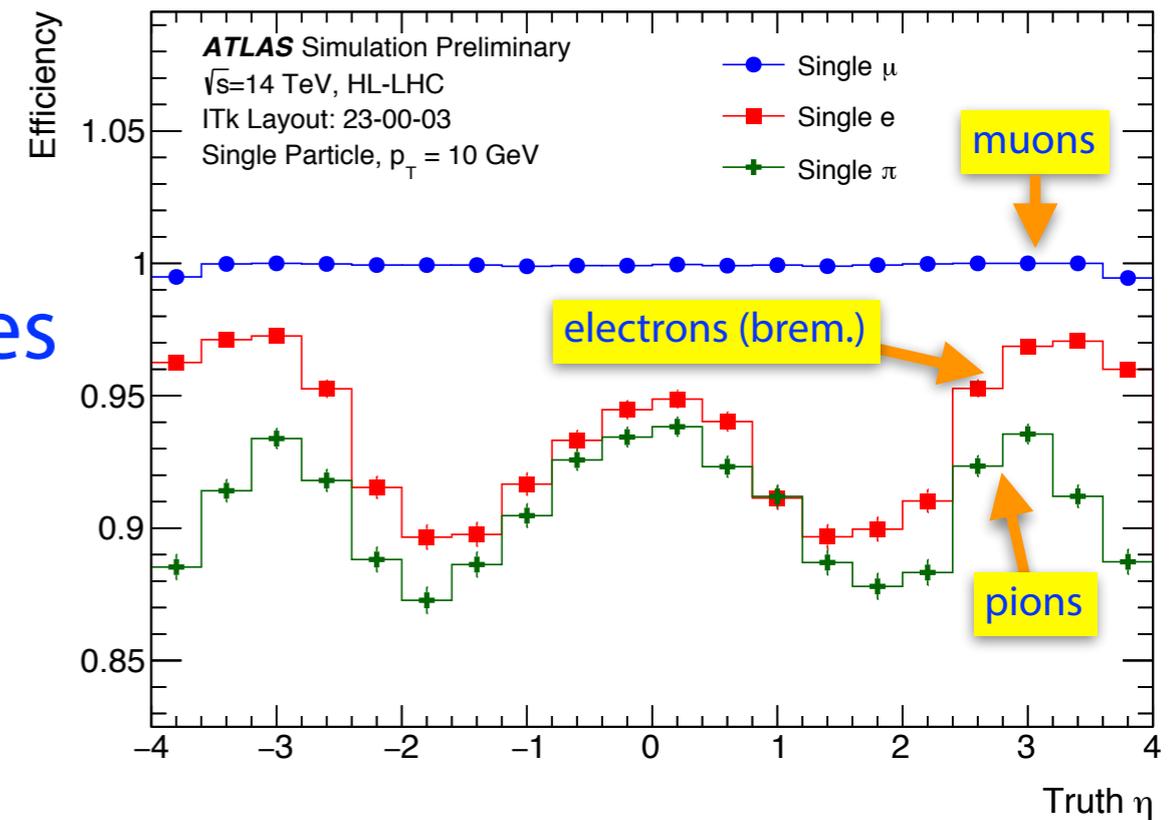
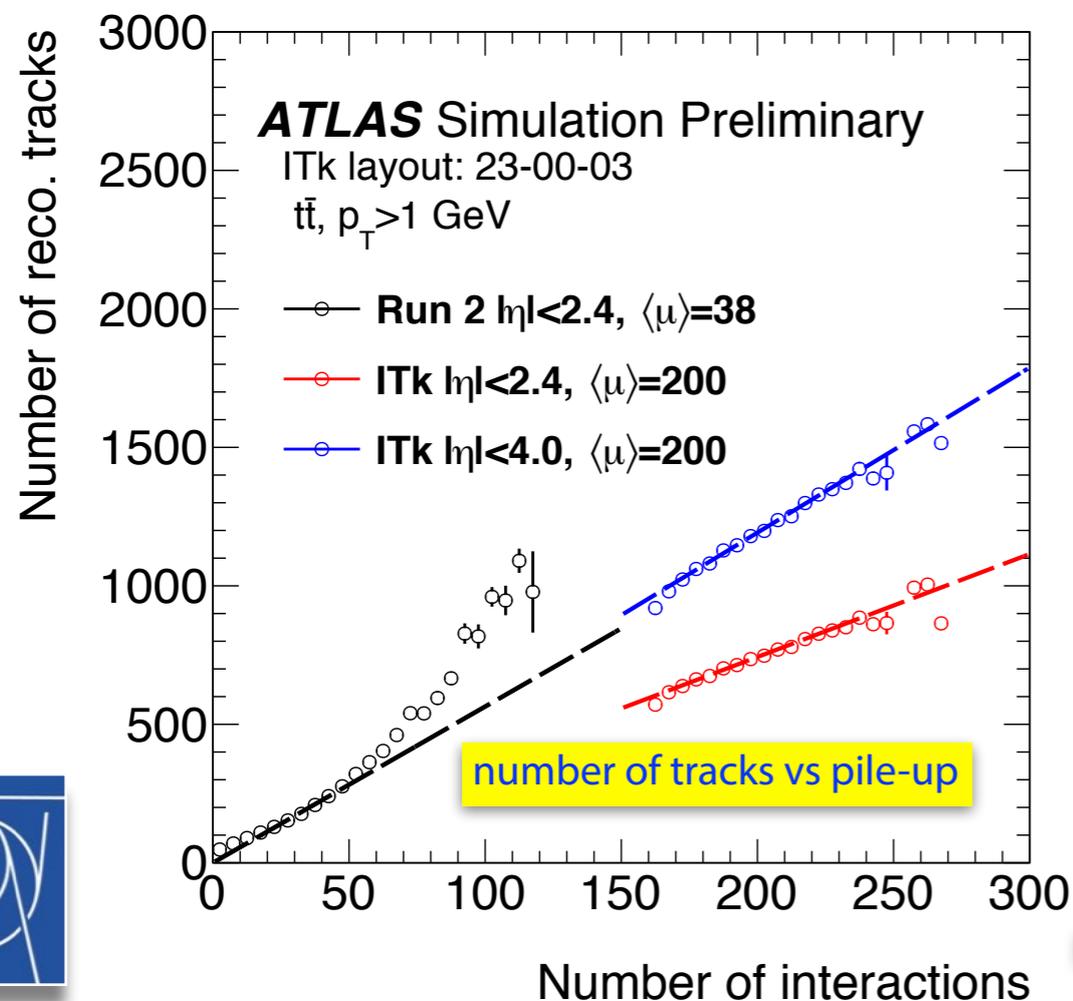
# ITk Tracking Performance (Default Tracking)

- high-purity track selection

- ➔ raise N(hit) cut from 7 (Run-2) to 9 to further reduce fakes

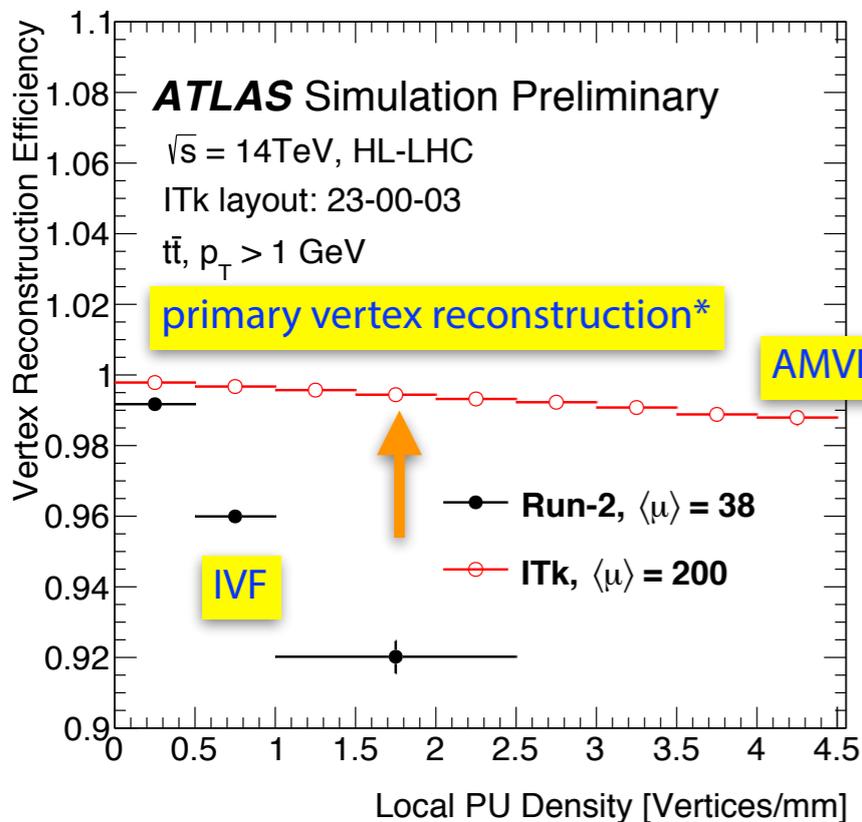
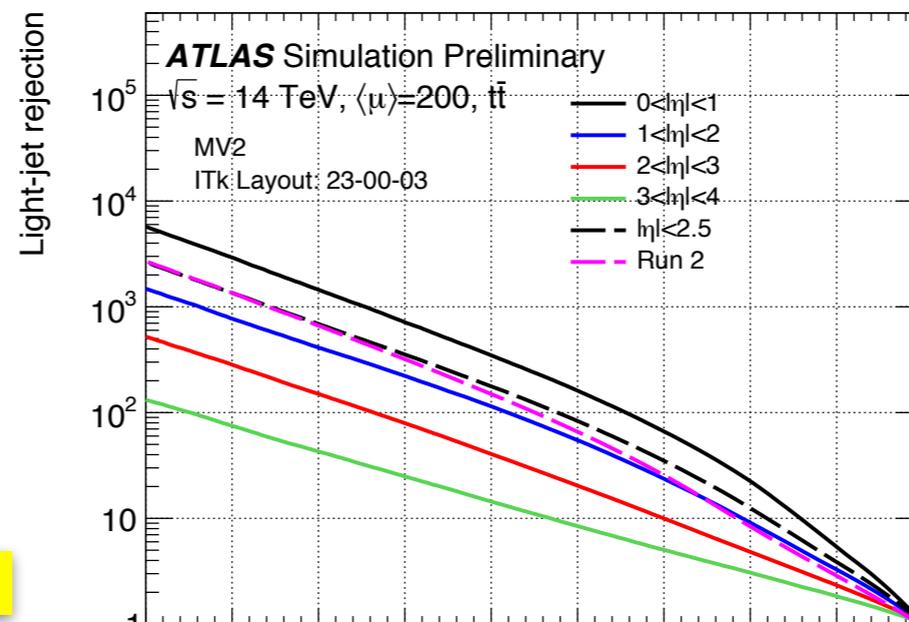
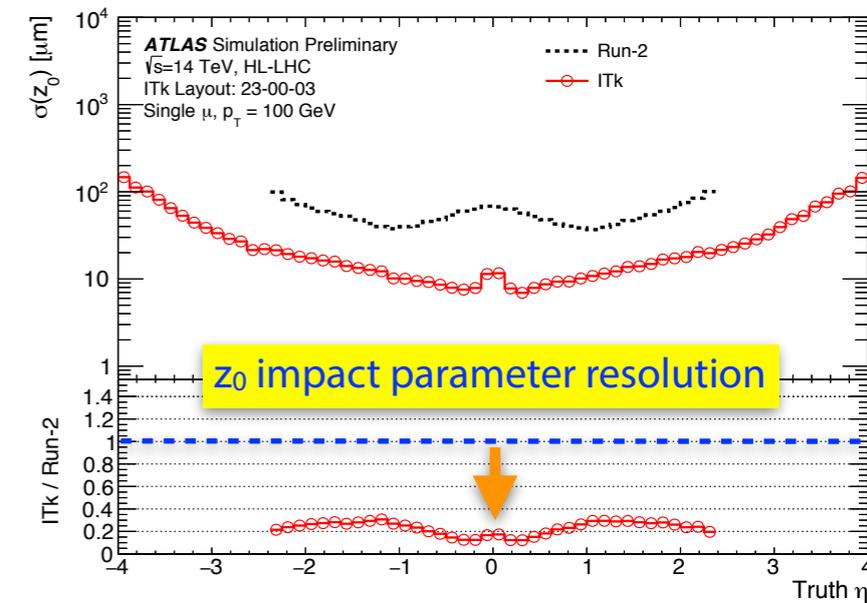
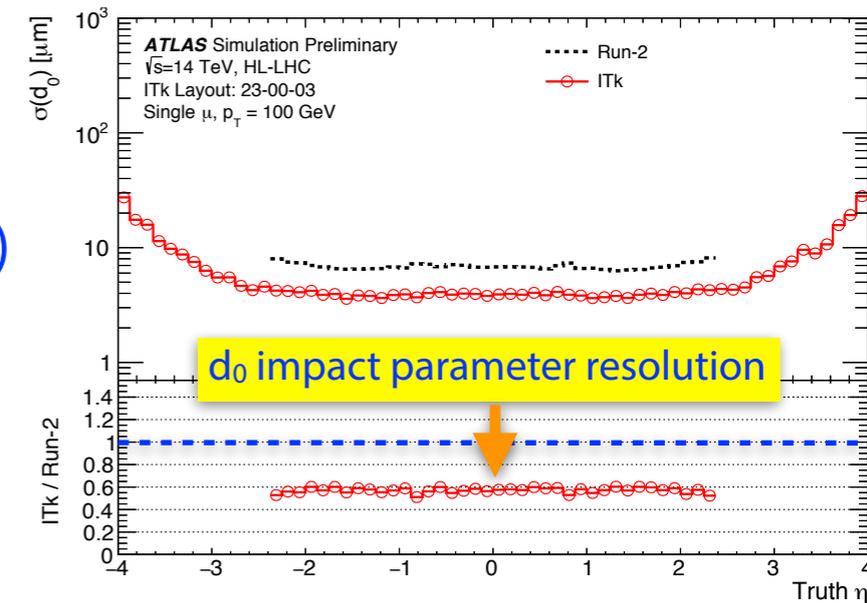
- excellent tracking efficiency and fakes

- ➔ pion efficiency limited by hadronic interactions in detector ITk material
- ➔ excellent linearity in number of tracks vs pile-up, up to the highest pile-up



# ITk Tracking Performance (Default Tracking)

- much better impact parameter resolution
  - ➔ in particular at high- $p_T$  (less affected by multiple scattering)
  - ➔ Pixel pitch:  $25 \times 100 \mu\text{m}^2$  (layer-0 barrel),  $50 \times 50 \mu\text{m}^2$  (elsewhere)
- results in improved performance for physics
  - ➔ primary vertex reconstruction
  - ➔ b-tagging
  - ➔ pile-up jet rejection
  - ➔ ...



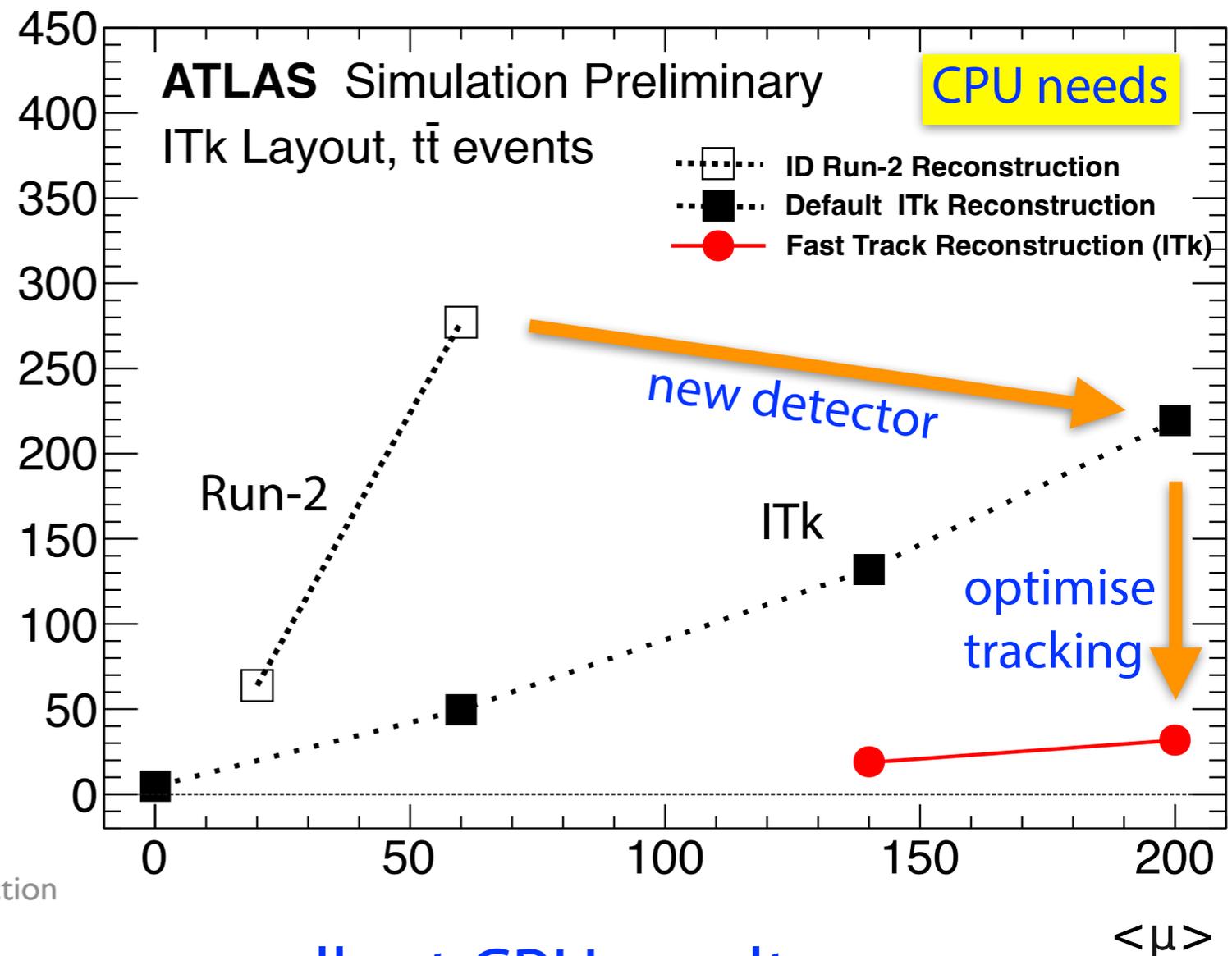
\* Run-2 reference is still IVF, ITk uses AMVF with an alternative vertex seed finder

# Fast ITk Track Reconstruction Prototype

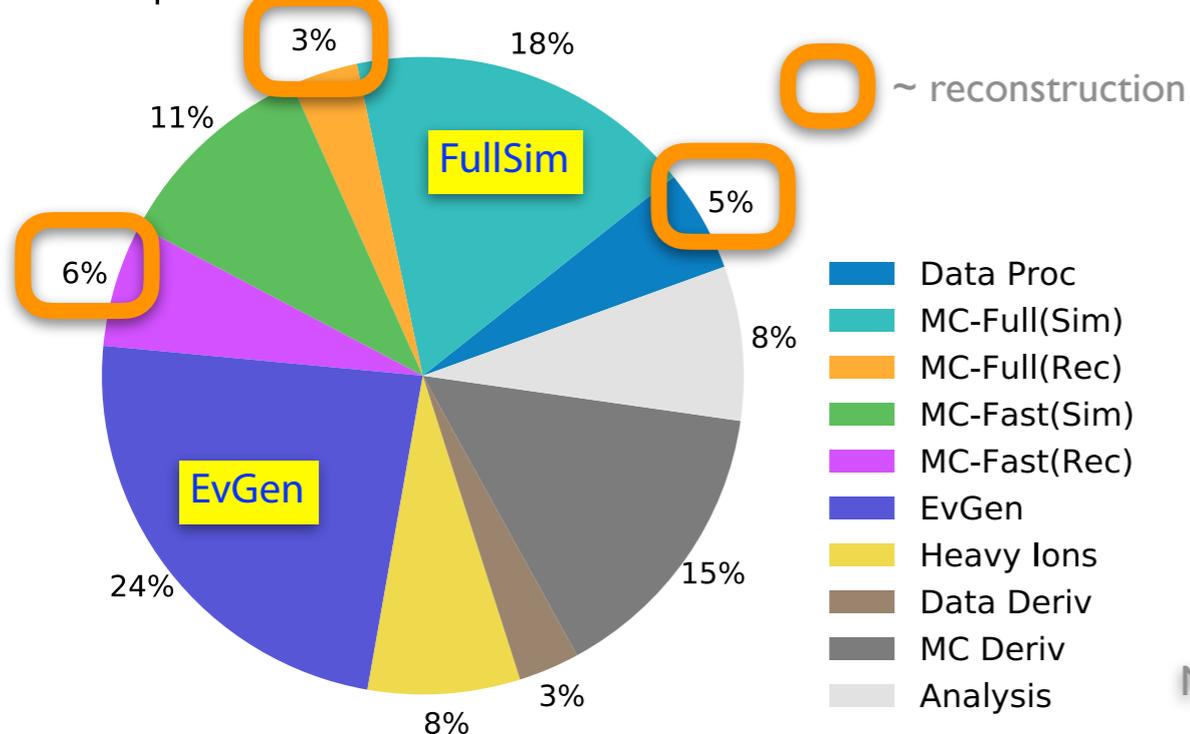
## ● fast ITk tracking strategy

- ➔ drop Strip seeding iteration, rely on 5 layer Pixel seeding (!)
- ➔ drop Ambiguity Solution, move functionality to Track Finding:
  - use Kalman Filter as final fit
  - precise cluster corrections
  - material model (approximate)
  - final track selection
  - duplicate removal (approximate)

HS06 × Seconds per Event



ATLAS Preliminary  
2020 Computing Model -CPU: 2030: Conservative R&D

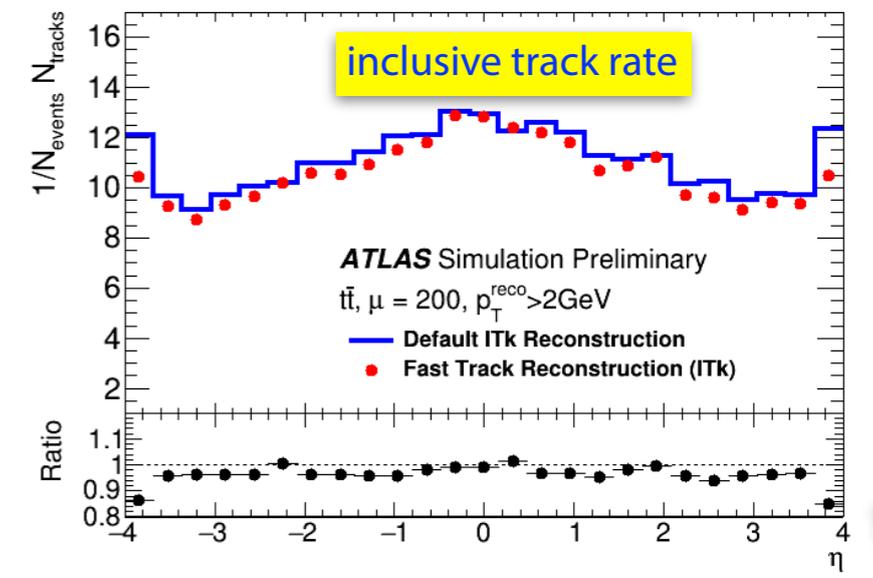
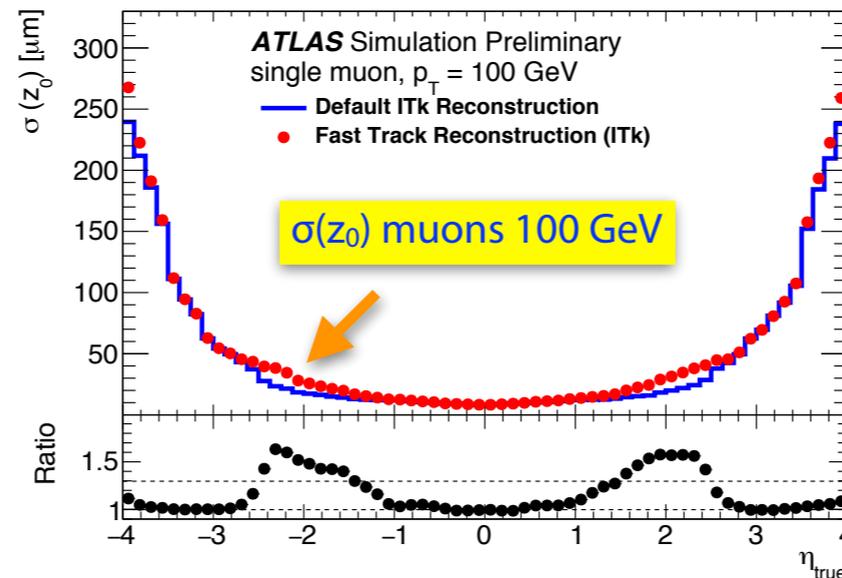
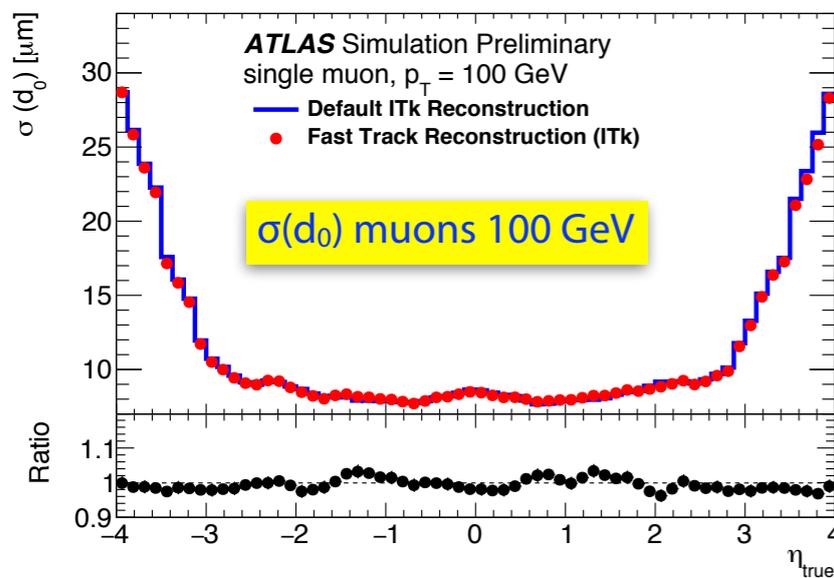
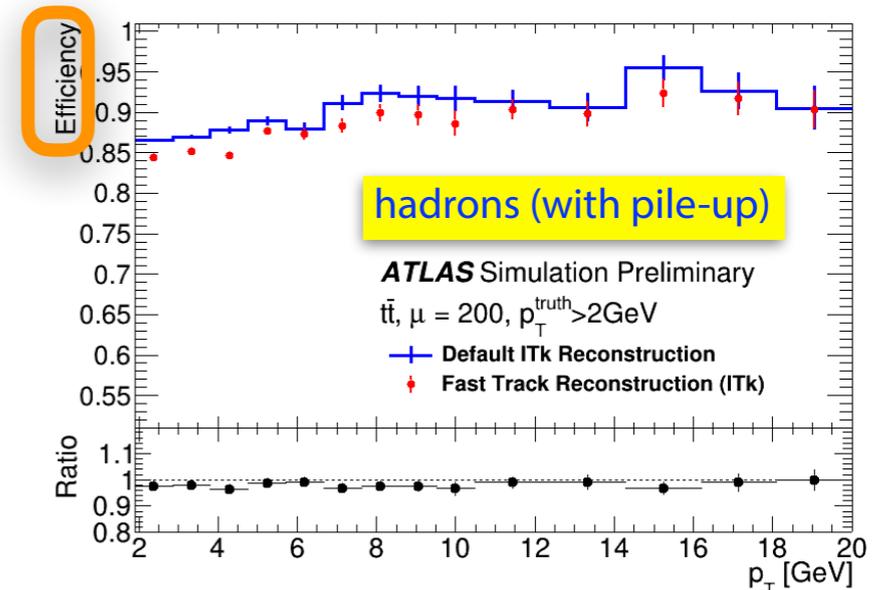
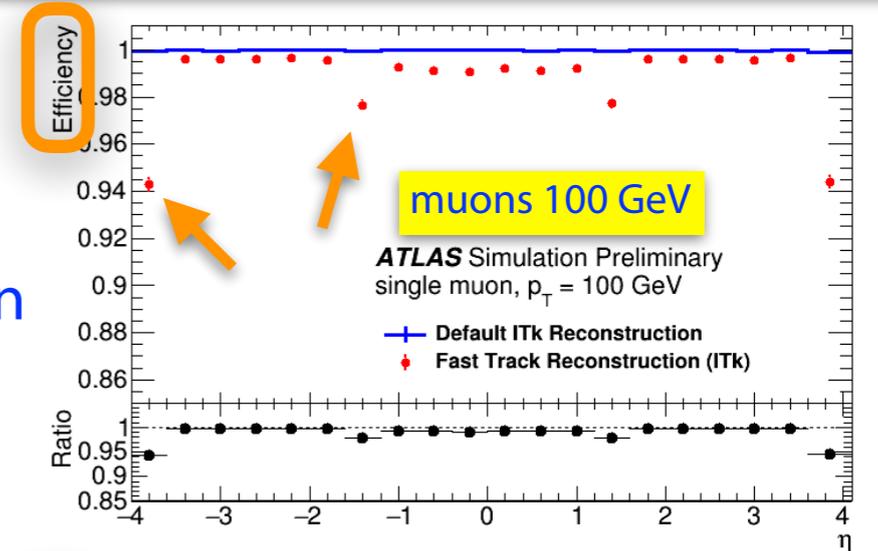


## ● excellent CPU results (8x faster)

- ➔ at cost of some performance
- ➔ CPU for tracking not dominating in event reconstruction anymore
- ➔ QCD generators and Geant4 dominate in total ATLAS CPU budget for HL-LHC (!)

# Performance of Fast ITk Reconstruction

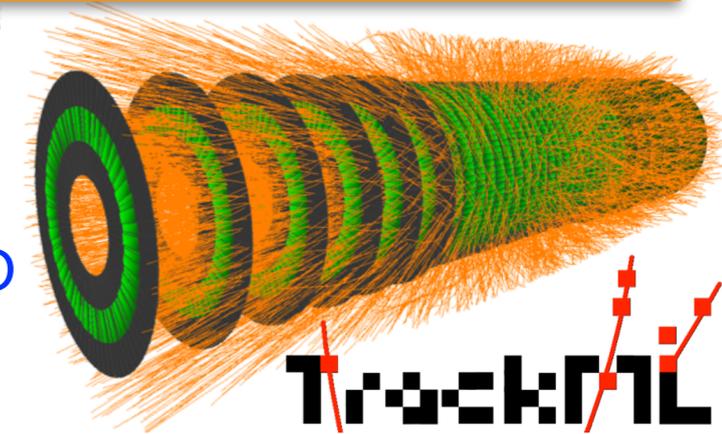
- prototype yields excellent results, despite approximations to achieve CPU savings
  - ➔ some efficiency loss in barrel, transition and forward region
  - ➔ no large rate of additional (fake) tracks
  - ➔ resolutions mostly as default reconstruction, with some exceptions due to approximations in Kalman Filter
- performance of fast ITk reconstruction already satisfies trigger requirements
  - ➔ relevant for Event Filter reconstruction, possible alternative to hardware based tracking at Point-1



# ACTS Tracking Software Project

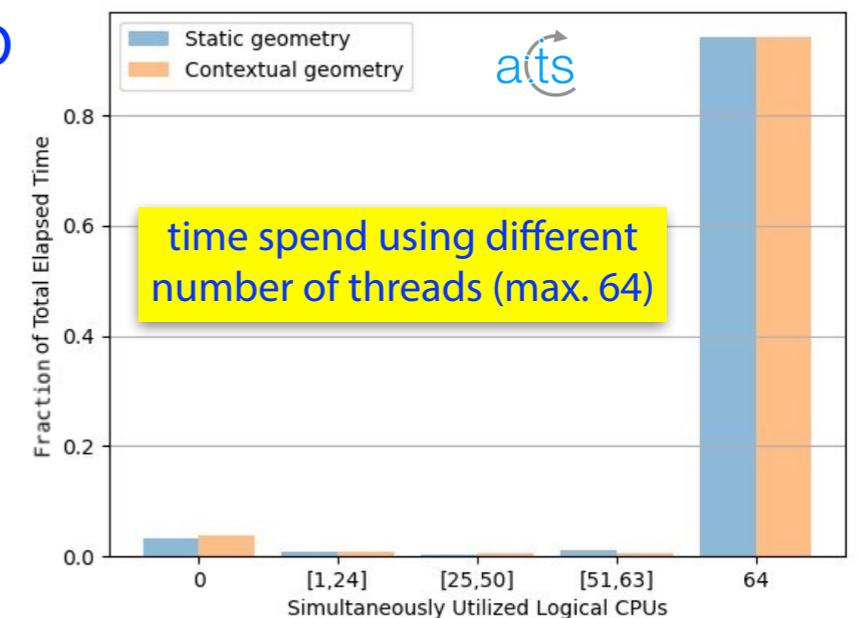
## ● ACTS (A Common Tracking Software)

- ➔ open source project, initially started by ATLAS in view of HL-LHC
- ➔ number of experiments contributing and used as platform for R&D
  - sPHENIX, Belle-II, FASER, LHCb, CEPC, FCC, ...
  - Tracking Machine Learning (TrackingML) challenge
  - Open Data Detector (ODD) allows for generic tracking R&D



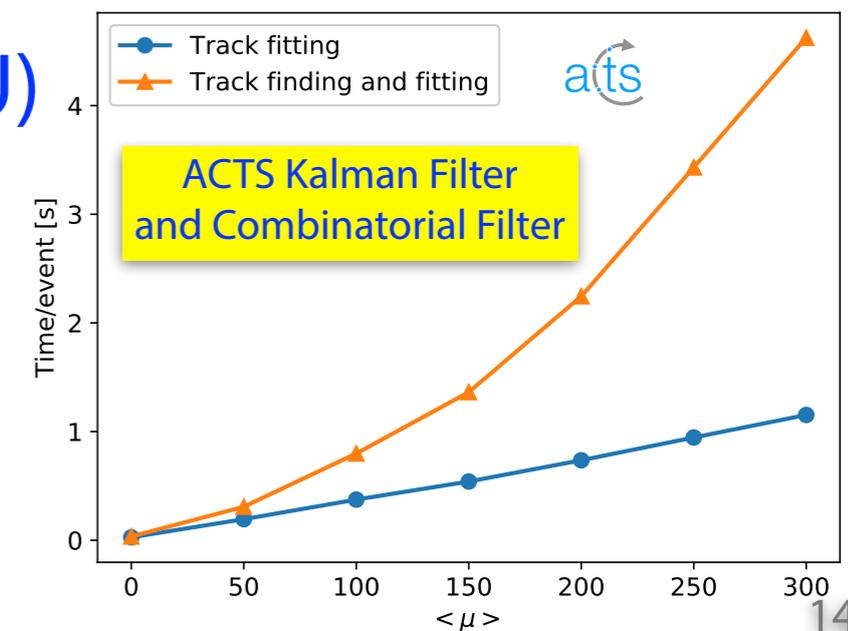
## ● tracking suite for ATLAS Phase-2 software

- ➔ designed ground-up for multi-threading
- ➔ modern data model and code design
- ➔ support for heterogeneous architectures (CPU, GPU, ...)
- ➔ Run-3 primary vertexing first deployment of ACTS code



## ● much improved technical performance (CPU)

- ➔ use fast ACTS (Combinatorial) Kalman Filter to implement a fast ITk reconstruction without approximations
- ➔ goal is to fully recover physics performance without losing excellent CPU results of current prototype



# Summary and Conclusions

---

- tracking and vertexing software is well prepared for Run-3
  - ➔ based on Run-2 experience, significant improvements have been implemented
    - technical migration to multi-threading
    - reconstruction time reduced by more than a factor  $\times 2$
    - large radius tracking will be integrated into prompt reconstruction at Tier-0
    - new Adaptive Multi Vertex Finder deployed (ACTS based)
- tracking software preparation for HL-LHC is advancing well
  - ➔ the ITk upgrade, together with optimised tracking software, will allow to improve on Run-2(3) tracking performance, even in presence of 200 pile-up
  - ➔ fully functional fast ITk reconstruction cuts down CPU time for tracking by factor  $\times 8$ , a game-changer for ATLAS Phase-2 offline computing and for trigger processing
  - ➔ ATLAS is investing strongly into the ACTS open source tracking software project to modernise its tracking software for the HL-LHC

