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APS April Meeting



# Object-reconstruction optimisation at Muon Collider

Session B08: Muon Collider Symposium I

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on behalf of the  
**Muon Collider Detector and Physics Group**

# Beam Induced Background: $\sqrt{s} = 1.5 \text{ TeV}$

For 0.75 TeV beams at  $2 \times 10^{12} \mu/\text{bunch}$  →  $4 \times 10^5$  muon decays/m in a single beam crossing

Essential component is the MDI: tungsten nozzles reduce the BIB rate by a factor ~500

Currently using a BIB sample simulated by [MAP](#) with *MARS15* for  $\sqrt{s} = 1.5 \text{ TeV}$

↳ soon to transition to the independent simulation with *FLUKA + FlukaLineBuilder*  
[see the talk by C. Curatolo](#)

Result of a simulation → list of stable particles reaching the detector region in a single bunch crossing (BX) (mostly soft photons, neutrons, electrons)

- collected at the outer surface of the detector and the MDI - - - -
- $2 \times 180\text{M}$  particles → full simulation needed for a realistic detector-performance estimation

Detector geometry based on the CLIC design [DD4hep]

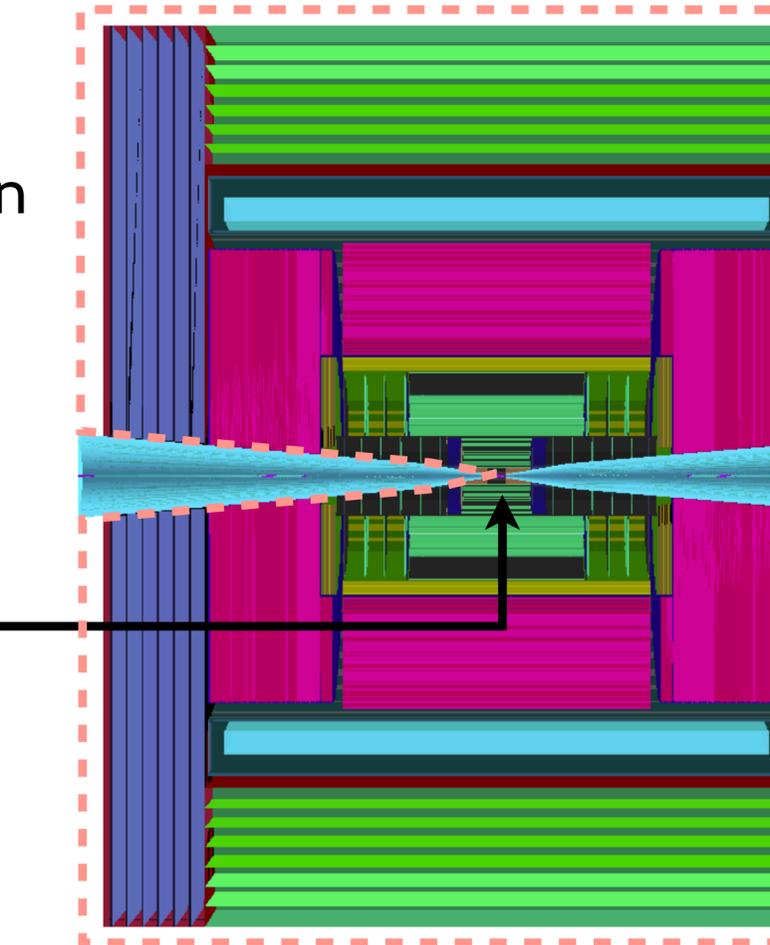
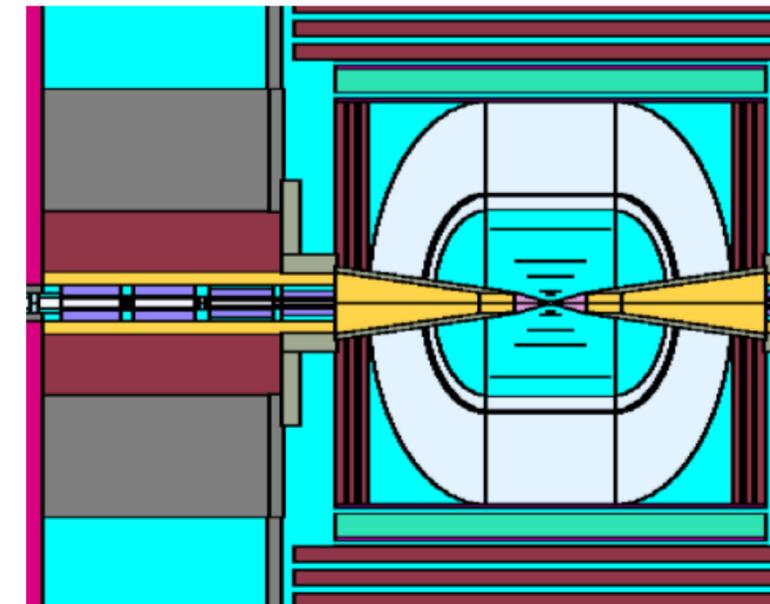
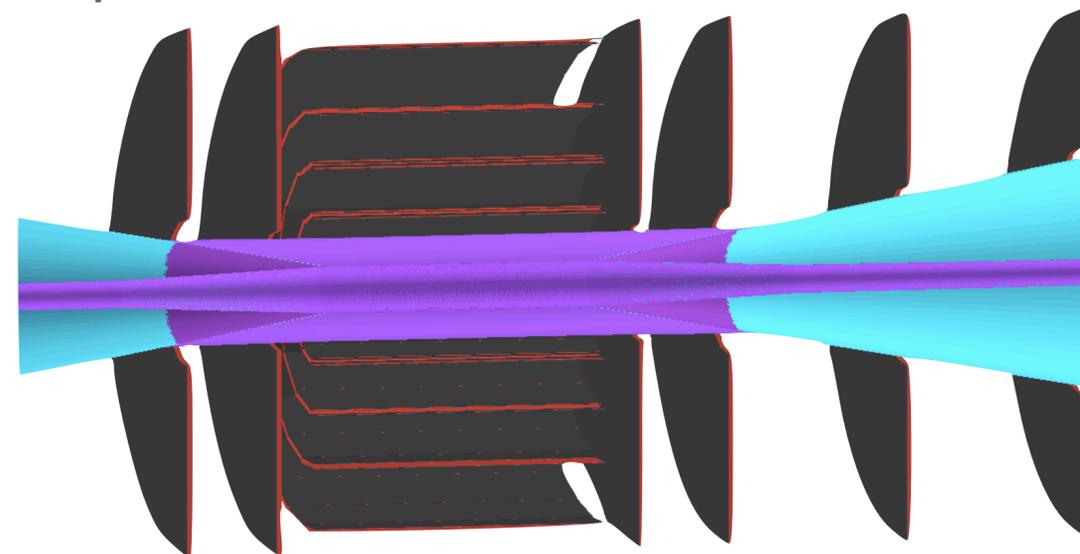
Tungsten nozzles: forward acceptance  $>10^\circ$

High-granularity calorimeter

- **ECAL:** 40 layers of W + Si
- **HCAL:** 60 layers of Fe + scintillator

All-silicon tracker:  $B = 3.57 \text{ T}$

- double-layer vertex detector



Software framework of the CLIC experiment chosen as a starting point

Key components of the full-simulation physics analysis:

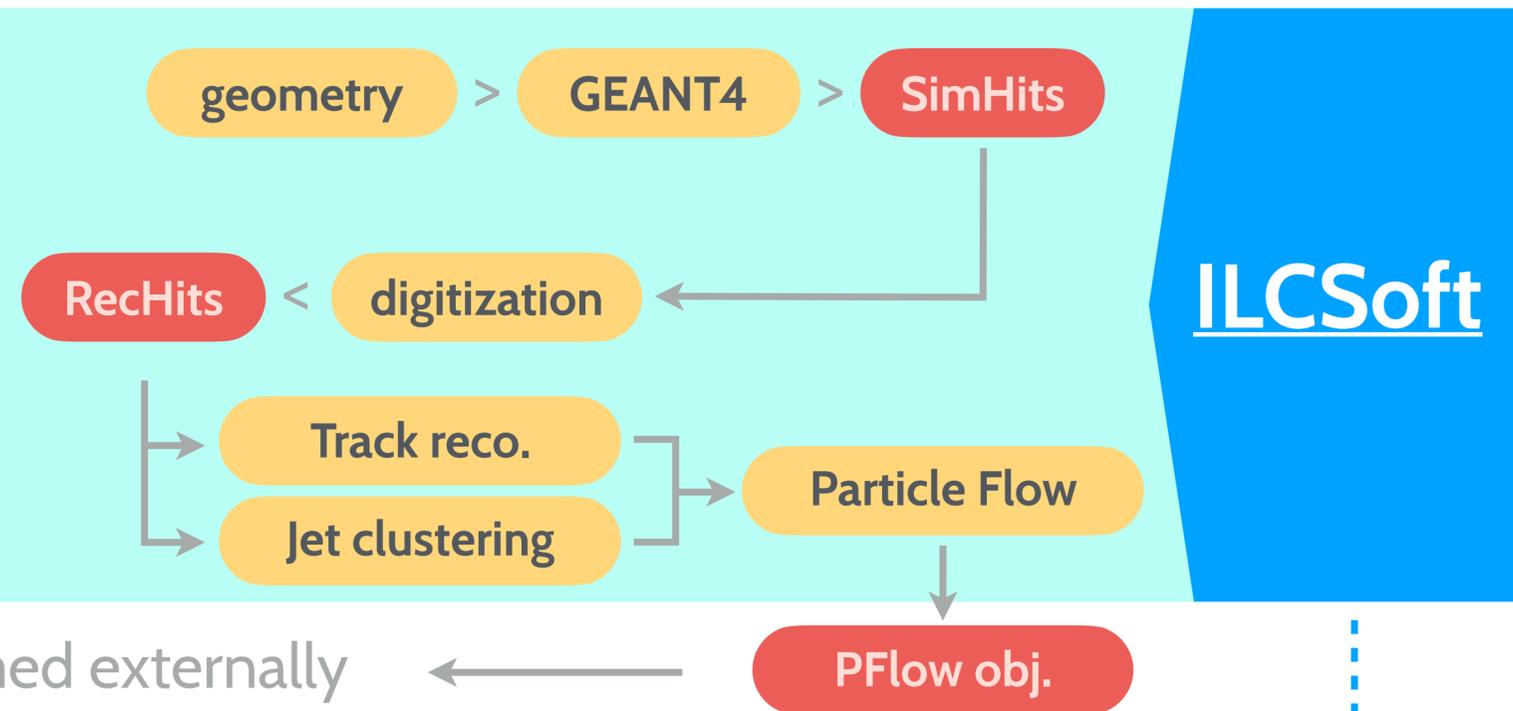
1. generation of the main process (ME + PS) ← done externally (Whizard/Madgraph+Pythia)

2. simulation of the detector response to the incoming particles

3. conversion of simulated hits to reconstructed hits

4. reconstruction of tracks/jets/particles

5. higher-level analysis ← can be performed externally



All the simulation and reconstruction done within a single [framework](#)

Most of custom packages specific to the Muon Collider maintained in the public [Muon Collider Software](#) repository

Large overlap with the [Key4HEP](#) stack: planning full transition in the future

Centralised software revisions distributed through Docker and Singularity containers + [manual build instructions](#)

Tutorial on the simulation software was organised recently: [September 30, 2020](#)

# BIB properties: single beam crossing

BIB has several **characteristic features** → crucial for its effective suppression

**1. Predominantly very soft particles** ( $p \ll 250 \text{ MeV}$ ) except for neutrons

fairly uniform distribution in the detector → no isolated signal-like deposits  
↳ conceptually different from pile-up contributions at the LHC

**2. Significant spread in time** (few ns + long tails up to a few  $\mu\text{s}$ )

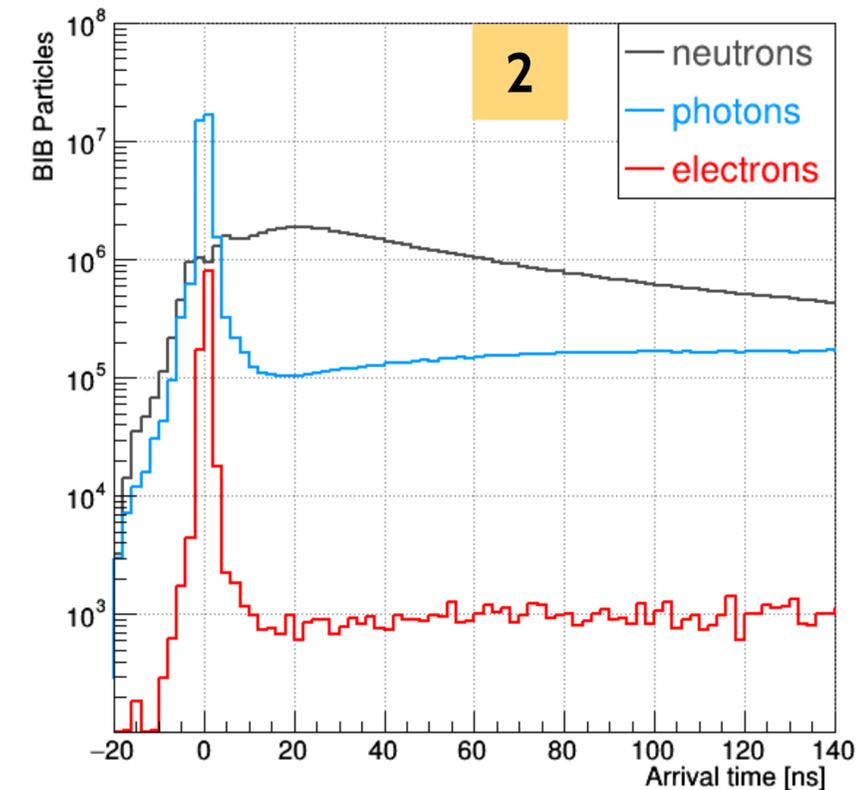
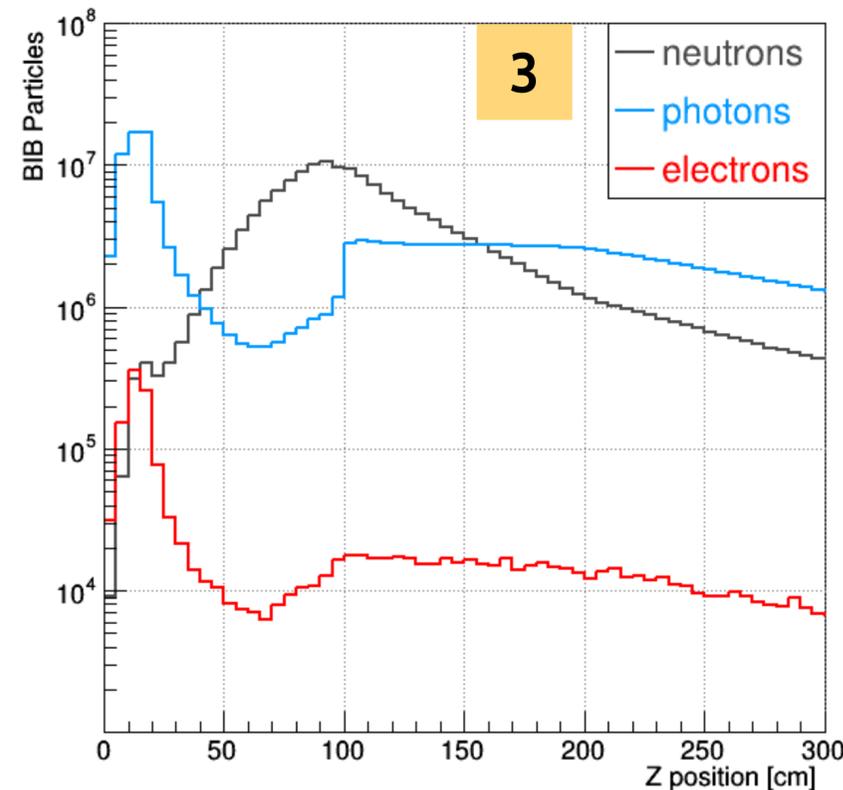
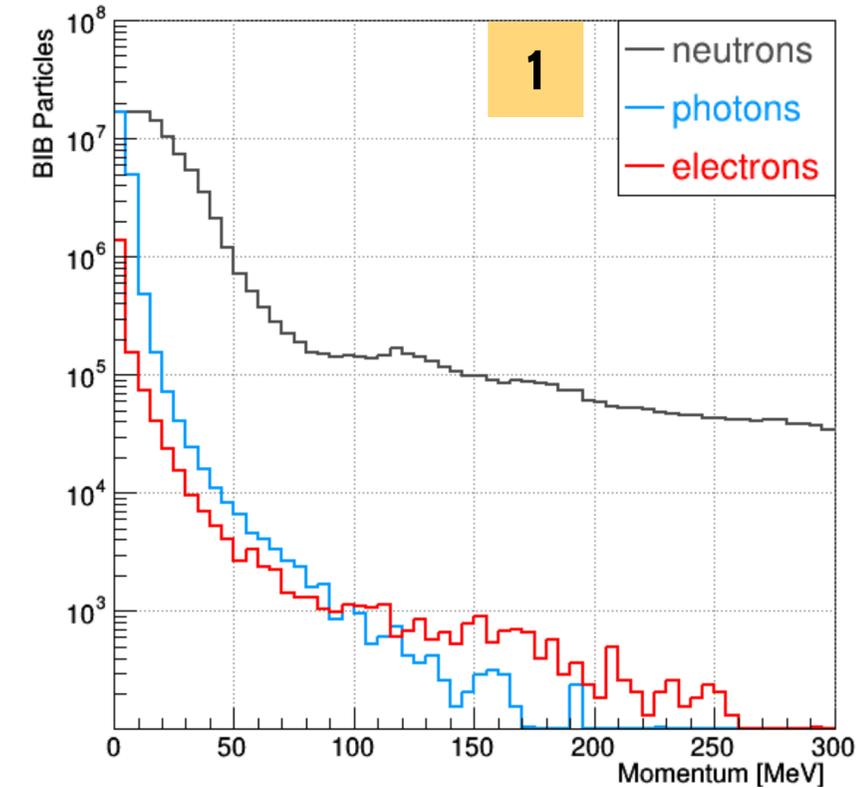
$\mu^+\mu^-$  collision time spread:  $\sim 30\text{ps}$  (defined by the muon-beam properties)  
↳ strong handle on the BIB → requires state-of-the-art timing capabilities

**3. Large spread of the origin along the beam**

different azimuthal angle wrt the detector surface  
+ affecting the time of flight to the detector

**Sophisticated detector technologies and event-reconstruction strategies required to exploit these features**

**4D coordinates of the Interaction Point (IP) define the reference to 2 and 3**



# Hit digitisation: GEANT4 → RecHit

GEANT4 hits produced separately for signal and BIB → merging + detector effects added during digitisation

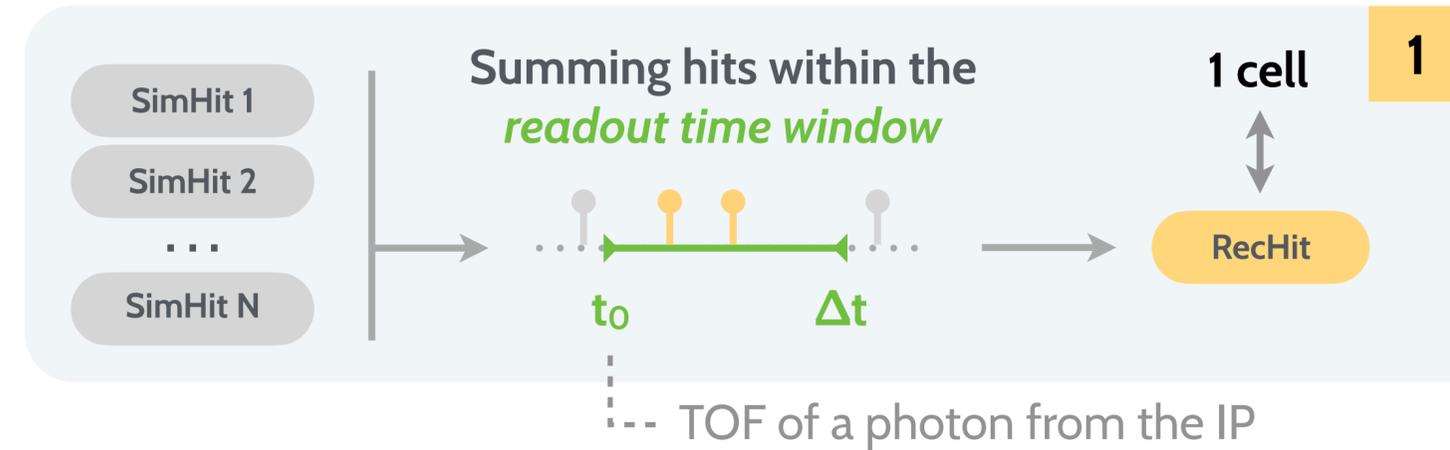
↳ two distinct classes of hits: **CalorimeterHit** (ECAL, HCAL, Muon detector) + **TrackerHit** (Tracking detector)

**1. Calorimeter hits:** cell ID +  $E_{dep}$  + timestamp  
 large cells (0.5×0.5 - 3×3 cm) → manageable # of cells  
 ↳ merge hits within the fixed readout time window

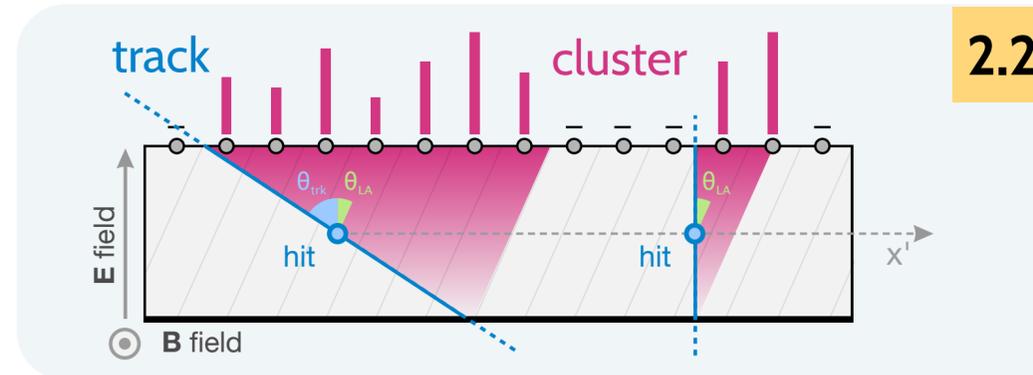
**2. TrackerHits:** sensor ID +  $E_{dep}$  + position + time *and more*  
 small pixels (50×50 μm) to macro-pixels (0.05×10 mm)  
 ↳ too many channels to treat them individually

**2.1. Simple 4D smearing** by  $\sigma_U | \sigma_V | \sigma_t$   
 simple and fast → the present baseline  
 NO charge sharing, pile-up and electronics effects

**2.2. Realistic simulation of sensor + readout-chip response**  
 slower → in the development-testing stage  
 allows cluster-shape analysis for further BIB suppression  
 effects of readout-electronics properly taken into accounts



↑  
 .....  
 advanced



# Workflow optimisation: detector simulation

BIB introduces  $\sim 10^8$  particles in a single event  $\rightarrow$  a tremendous computation load: CPU, RAM, disk space  
 $\hookrightarrow$  contributions not relevant for the end result have to be **excluded from the chain** as early as possible

## 1. No GEANT4 simulation of particles arriving too late ×6 less CPU

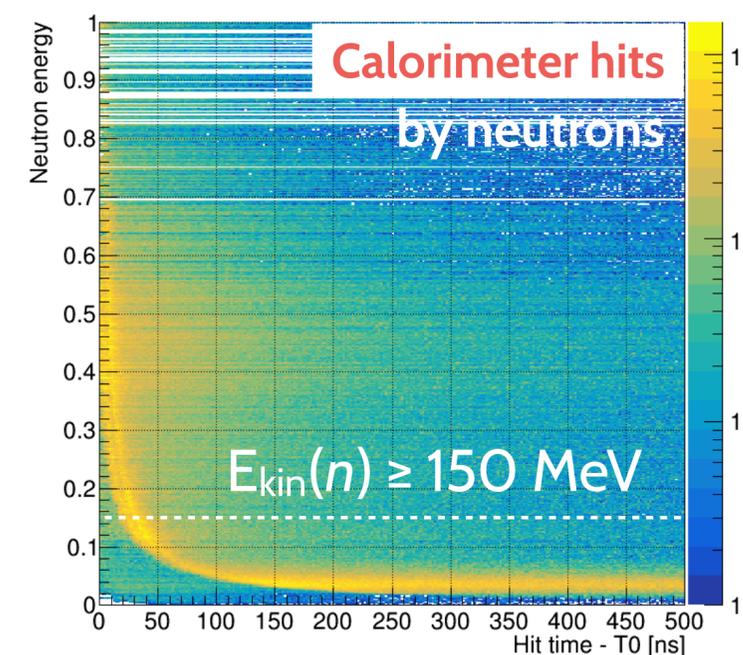
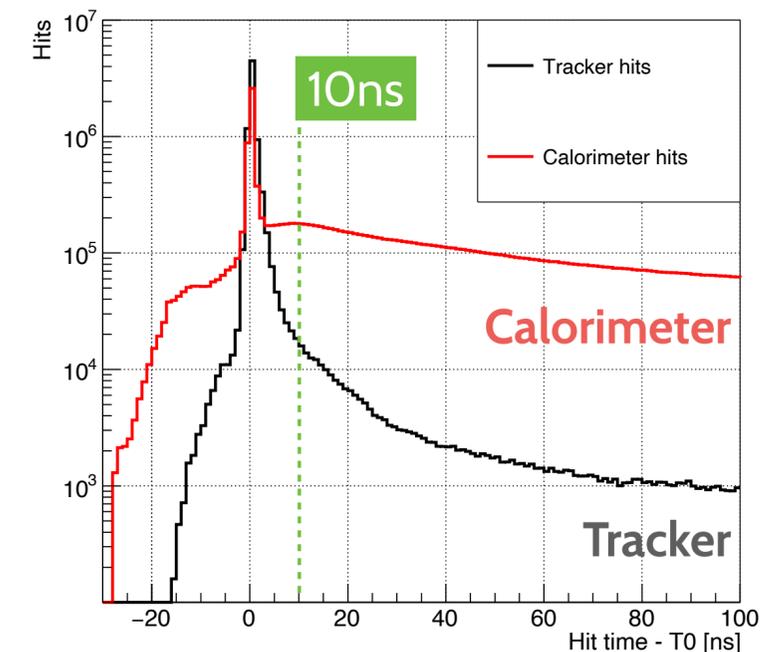
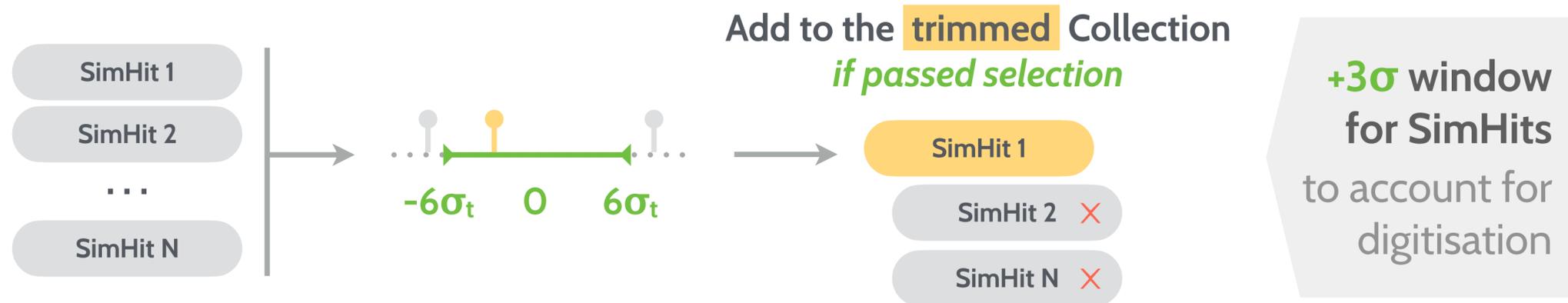
hits at  $t > 10\text{ns}$  will be outside the realistic readout time windows  
 $\hookrightarrow$  accounting for TOF: particles with  $t > 25\text{ns}$  at MDI are ignored

## 2. No GEANT4 simulation of slow neutrons ×20 less CPU

low-energy neutrons reach the calorimeter too late  
 $\hookrightarrow$  neutrons with  $E_{kin} < 150\text{ MeV}$  can be safely excluded

## 3. Trimming of SimHits before digitisation ×10 less RAM

many SimHits don't pass the readout timing cuts during digitisation  
 $\hookrightarrow$  storing **trimmed SimHit** collections  $\rightarrow$  less processing during digitisation



1

2

# Track reconstruction: optimisation strategies

Reconstruction of tracks suffers from large combinatorial background

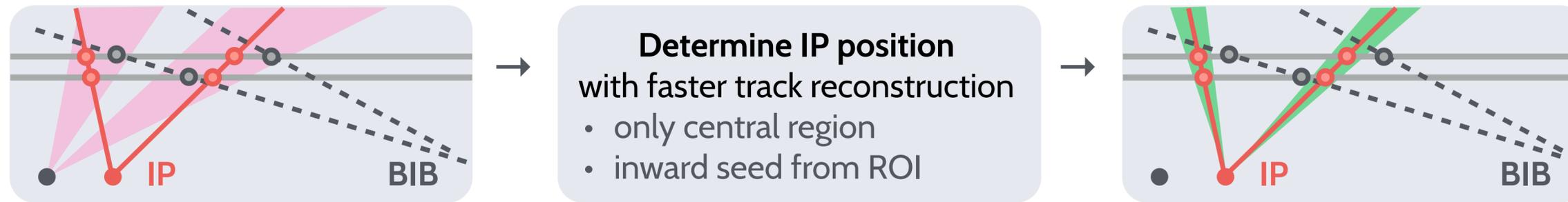
↳ suppression of BIB hits is crucial to reconstruct events in reasonable time

**1. Selection of hits in the narrow time window** tailored to the sensor position

↳ limited by the tracker time resolution + acceptance for slow particles

**2. Selection of hit doublets aligned with the IP** (double layers in the Vertex Detector)

↳ limited by the IP position resolution → requires multi-stage tracking strategy



**3. Cluster-based BIB suppression** (shape and charge of hit clusters)

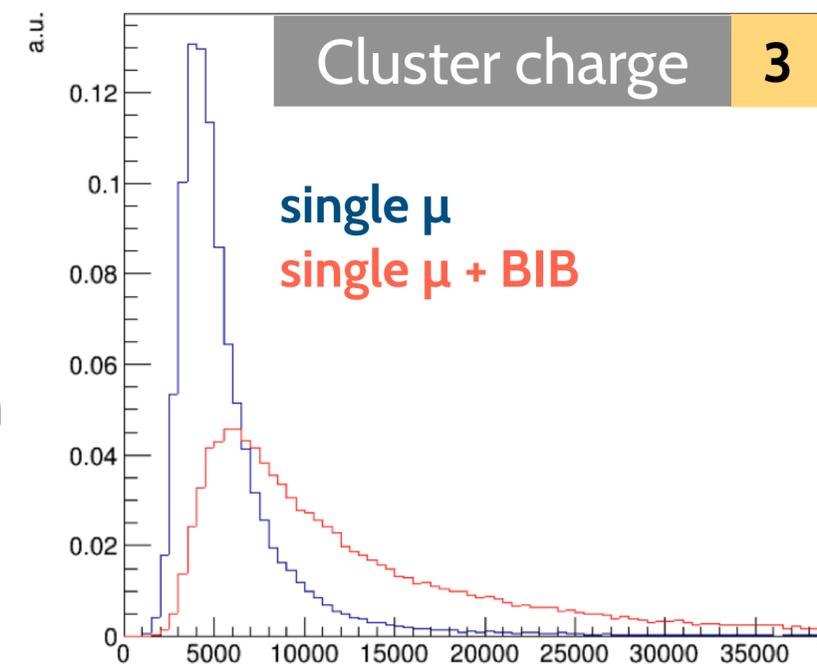
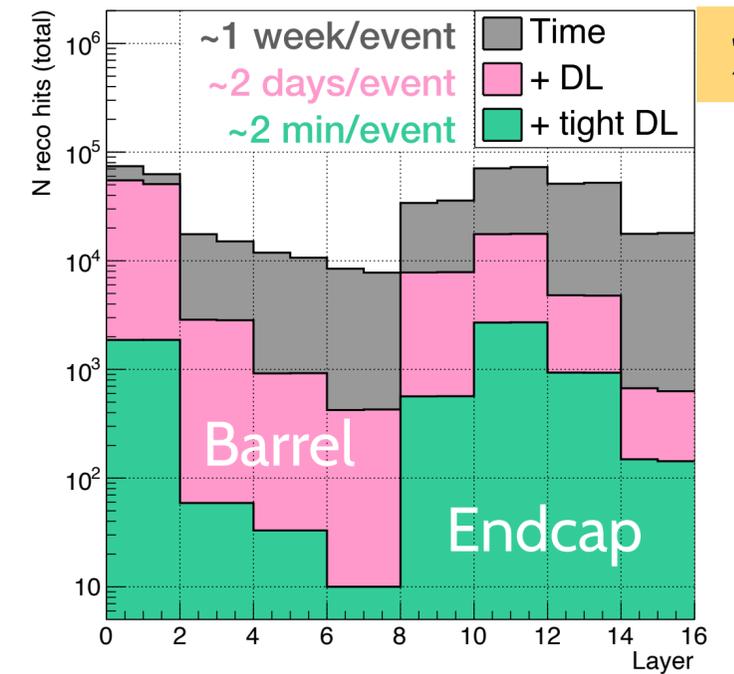
sensitivity to the particle direction in a single layer → requires realistic Tracker digitisation

All these strategies require a challenging detector design

↳ high spatial and time resolution + low occupancy ← *more in the talk by [H. Weber](#)*

Currently using Conformal Tracking with state-of-the-art timing detectors ← *more in the talk by [M. Casarsa](#)*

Potential performance boost with ACTS tracking software ← *more in the talk by [K. Krizka](#)*



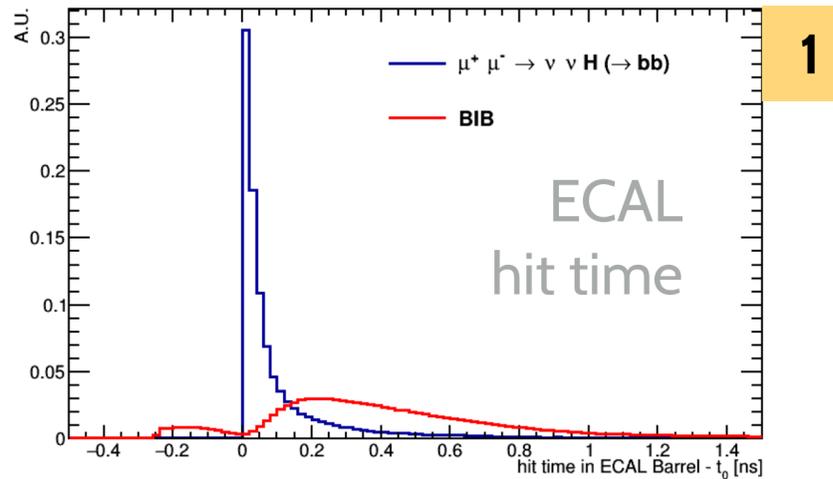
About 6 TeV (2.5 TeV) of energy deposited in ECAL (HCAL) by BIB

↳ effective BIB subtraction necessary for jet reconstruction

## 1. Timing can be exploited

BIB particles arrive later,  
but shower development takes time

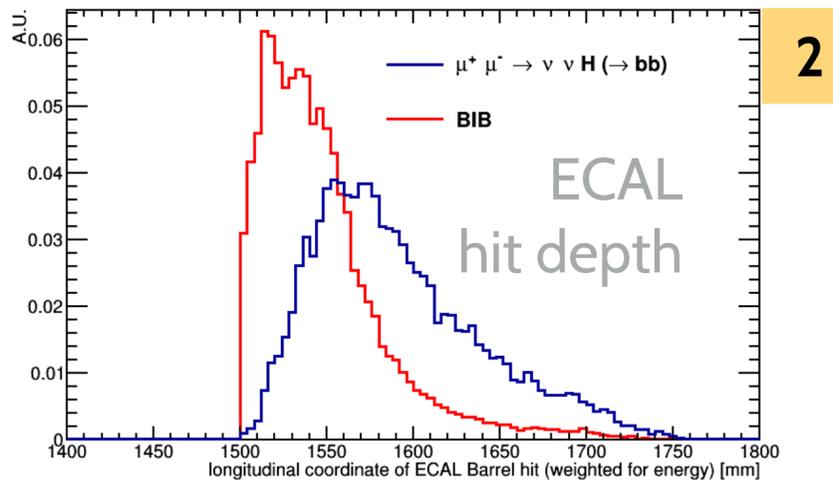
↳ sharp time cut is not the best solution



## 2. Depth profile is different

BIB particles are stopped earlier  
inside the calorimeter

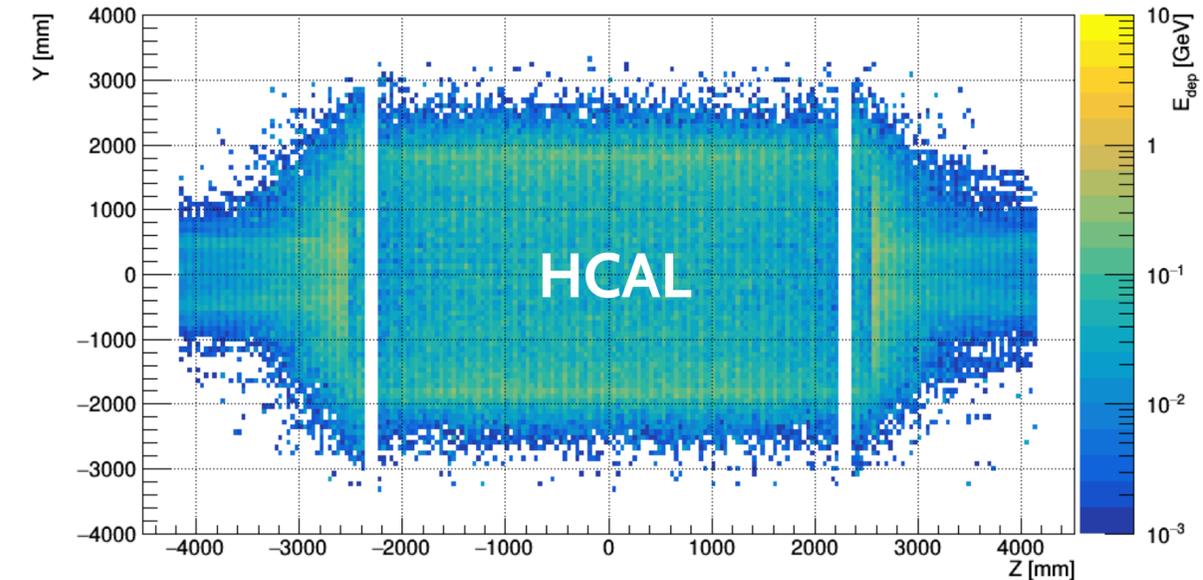
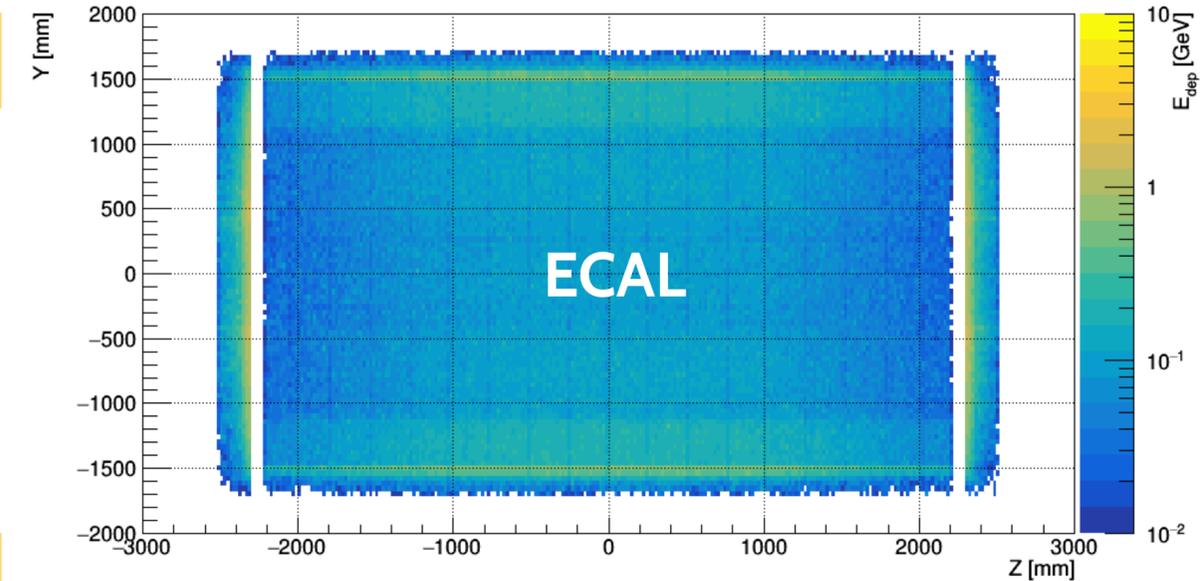
↳ longitudinal segmentation is crucial



Optimal BIB suppression achievable with  
multivariate analysis techniques

Currently average BIB contribution is parameterised as a function of  
the azimuthal angle and depth → subtracted from the total deposition

← more in the talk by [L. Sestini](#)



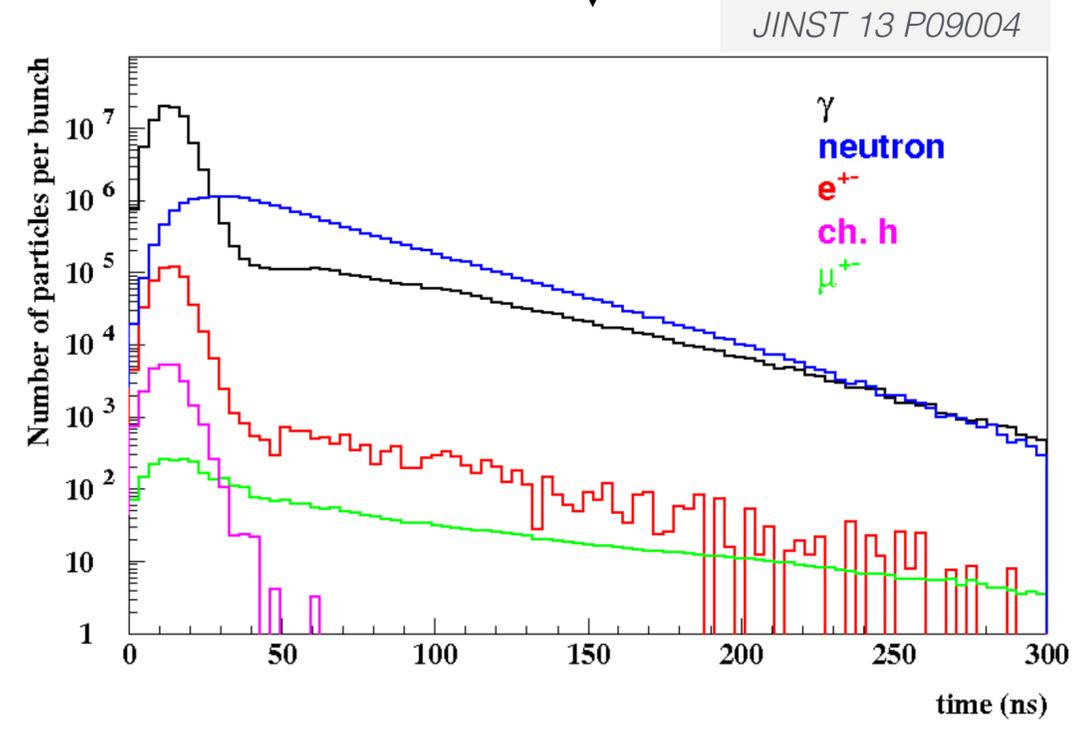
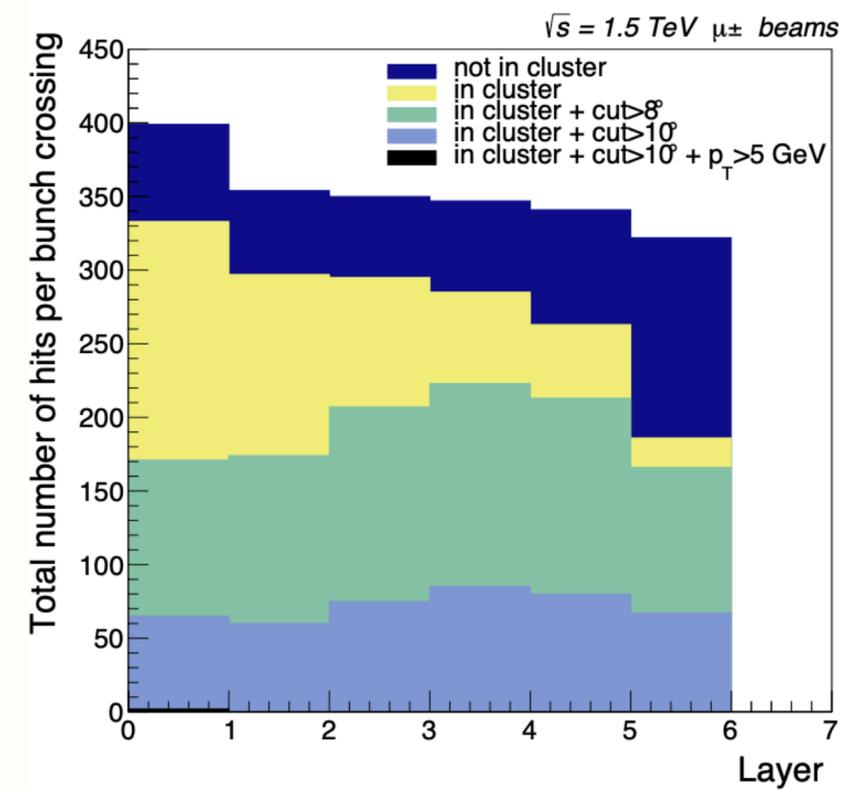
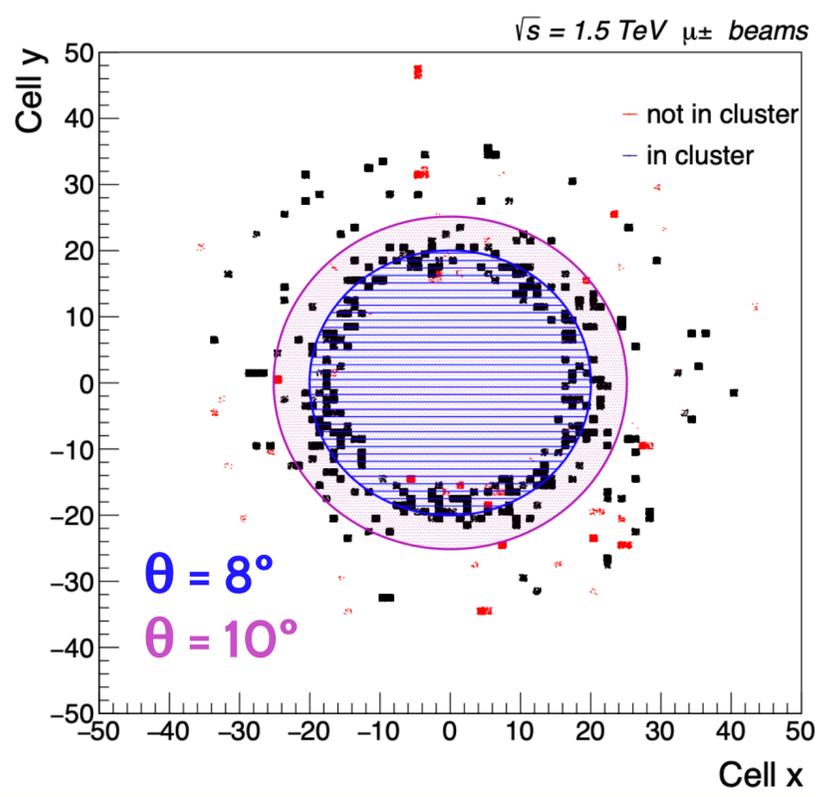
# Muon reconstruction: PANDORA particle flow

Fraction of muons in the the BIB is **fairly small** .....

↳ so serious issues with muon reconstruction

Sizeable BIB contribution only in the very forward region:  $\theta < 10^\circ$

- fully suppressed by cluster selection and  $p_T > 5$  GeV threshold
- using the PANDORA PFA framework to build clusters



← more in the poster by [C. Aimè](#)

Seeding from muon clusters required for efficient muon-track reconstruction

- planning to extend tracking algorithms to support seeding from extrapolated muon clusters

**Beam-induced background poses significant computational challenges at Muon Collider**

**Current simulation studies are based on the iLCSoft framework**

- planned transition to Key4HEP in the future

**BIB suppression crucial at every step of event simulation and reconstruction**

**Track reconstruction is by far the most CPU-intensive and time consuming component**

- intelligent solutions for making it more efficient are under development

**Innovative object-reconstruction strategies are necessary that consistently use data from multiple subdetectors**

**Maximum coherence between detector technologies and the corresponding reconstruction algorithms is crucial for the optimal performance of the experiment**