



Design & Studies of μ -strip stacked module prototypes for tracking at S-LHC

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on the behalf of the CMS collaboration at CERN

Talk Outlines

~> Tracking on high luminosities hadron colliders

>> Constraints at S-LHC

~> A first (rough) tracking estimation at module level: stacked modules

>> Working principles & theoretical aspects

>> Presentation of few prototypes designs

~> Tests on real prototypes built with Si sensors & electronics used in the present CMS tracker

>> Study in terms of S/N & tracking performances

>> Validation of the method with CMS Tk modules at 7 TeV LHC collisions

>> Results of first prototypes with Cosmic Rays & a dedicated beam test experiment

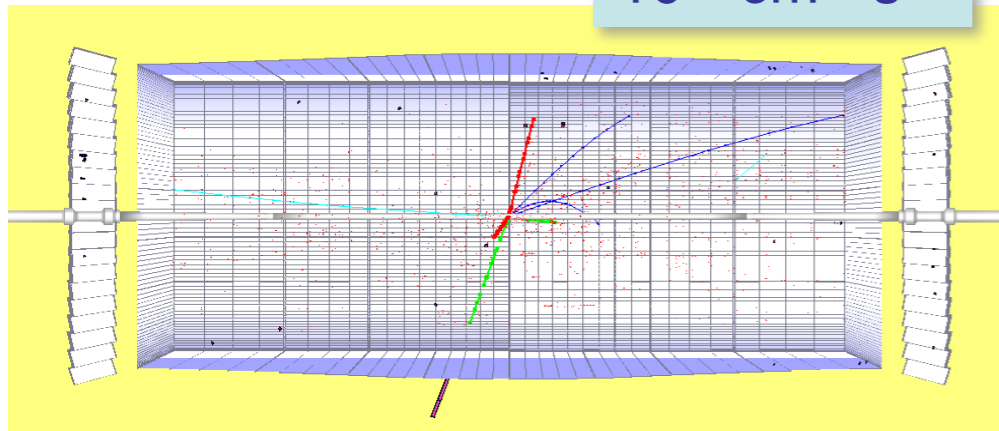
~> Simulation of stacked modules, study of trigger capabilities

>> A cylindrical barrel three-layers layout equipped with stacked modules considered here

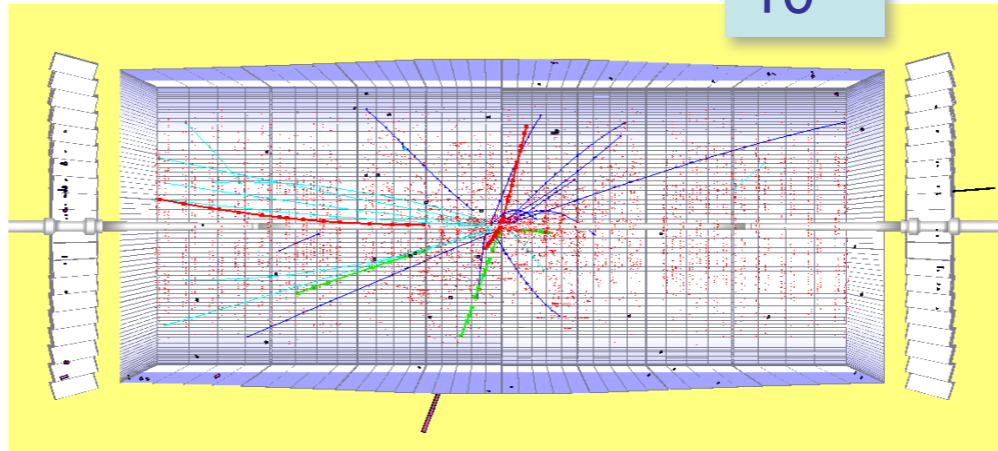
>> Preliminary results about performances discussed in terms of p_T resolution & trigger capabilities (STUB definition as a trigger primitive, data rates, ...)

The S-LHC Scenario

$10^{32} \text{ cm}^{-2} \text{ s}^{-1}$

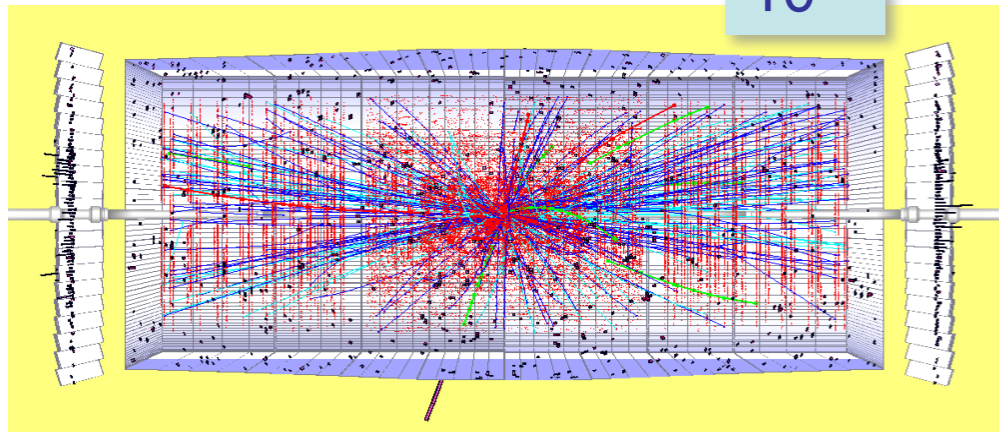


10^{33}

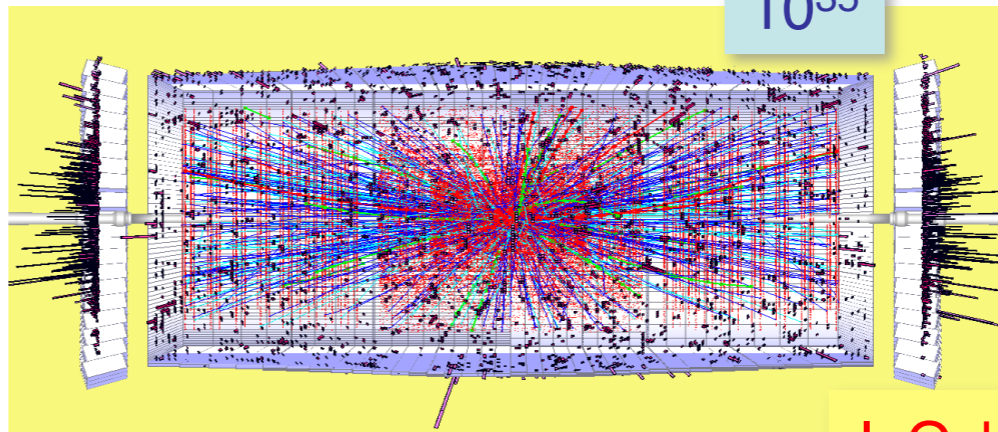


Present
 track density
 in CMS Tk

10^{34}



10^{35}

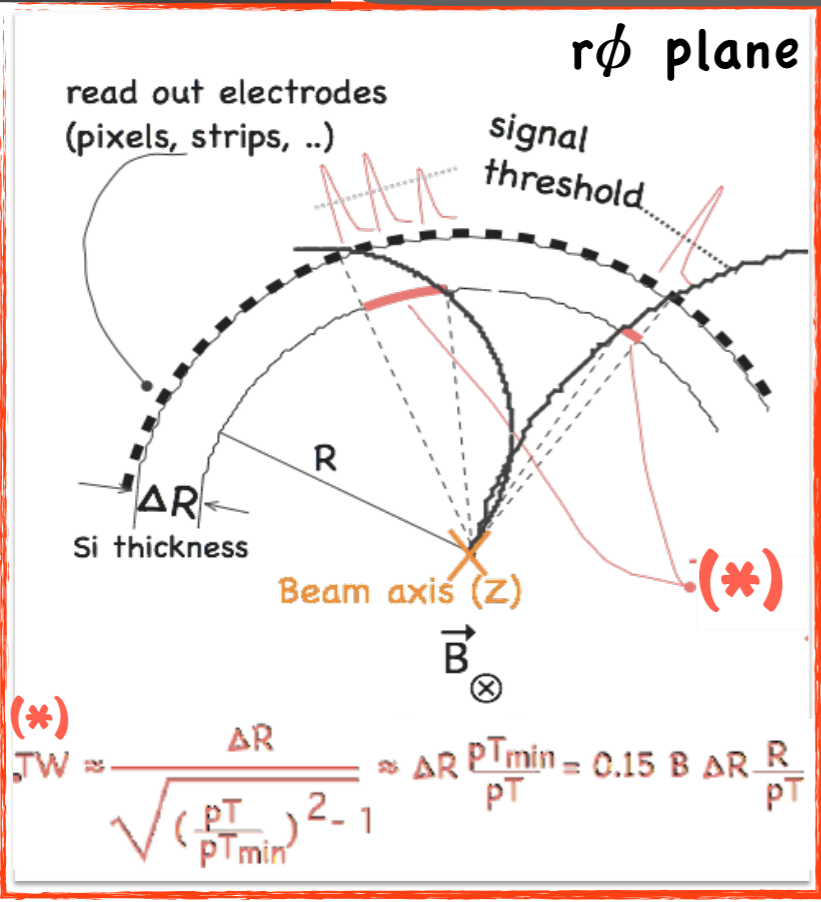


SLHC
 track density
 foreseen
 in CMS Tk

I. Osborne

- The Tracker (Tk) is the key detector which will require upgrading in SLHC
 - >> The Challenge: Build a replacement Tk for $\mathcal{L} > 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$ with L1 trigger capabilities
 - >> Develop sensors able to give infos about track p_T & direction, with high radiation hardness to keep detector occupancy as low as possible for a further good fine tracking

Basic Idea: p_T measure



→ In a B field, ideal case of cylindrical layers with non-flat modules

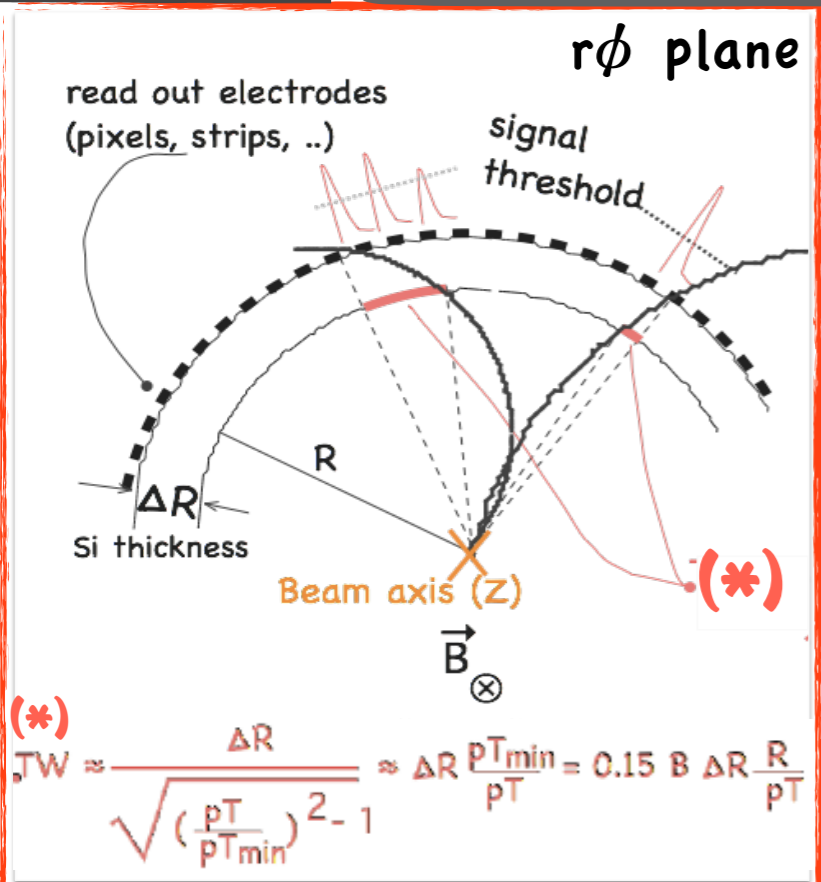
→ TW is the cluster size in terms of pitches

$$p_T^{meas} [GeV/c] = 0.15 B [T] R [m] \frac{\Delta R [\mu m]}{TW [\mu m]} \equiv$$

$$\equiv \frac{0.15 B [T] R [m]}{TW [\# \text{ of pitches}]} \cdot ToP \quad \left(ToP \equiv \frac{\Delta R [\mu m]}{\text{pitch} [\mu m]} \right)$$

→ ToP ratio sets the (p_T) discriminating power of the method

Basic Idea: p_T measure



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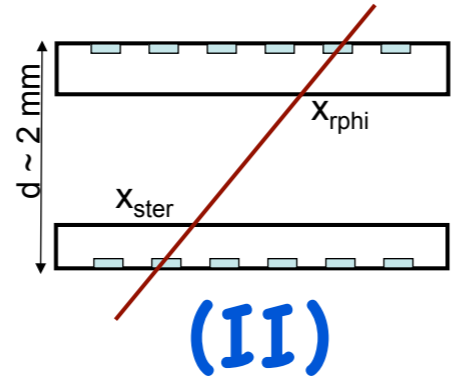
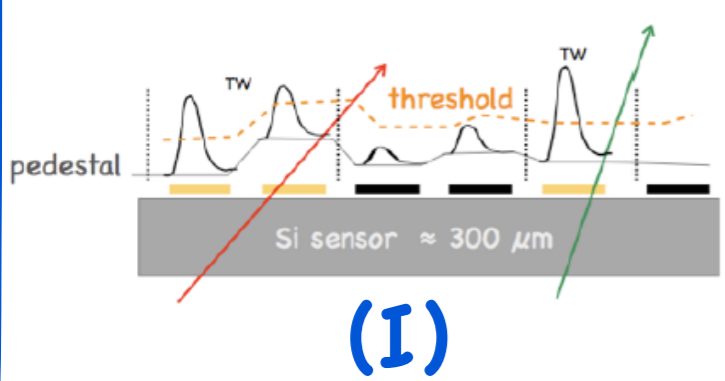
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→ ToP ratio sets the (p_T) discriminating power of the method

- Two possibility can be used in p_T measurement with a single module:
- >> CASE I: Module based on single sensor ($\Delta R \sim$ Si thickness, $TW \sim$ reconstructed Cluster Width (CW))
 - >> CASE II: Module based on 2 stacked sensor ($\Delta R \sim d$, $TW \sim$ distance reconstructed Cluster Centroids)



→ Case II represents a 2-in-1 module that can:

- >> bring to improved values of ToP in the p_T measurement at module level
- >> achieve good angular resolution ($\sim 100 \mu m$ strip pitch over 2 mm lever arm)

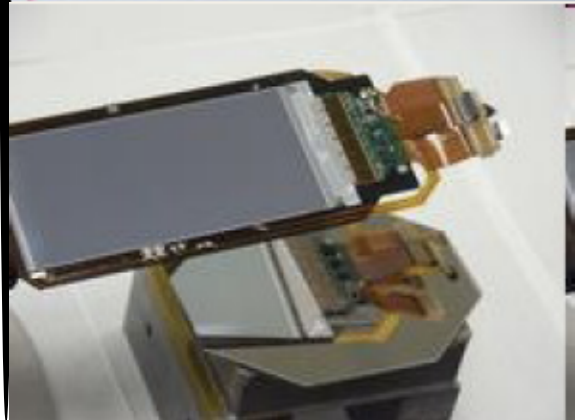
⇒ p_T & direction infos for trigger purposes!

Method Validation

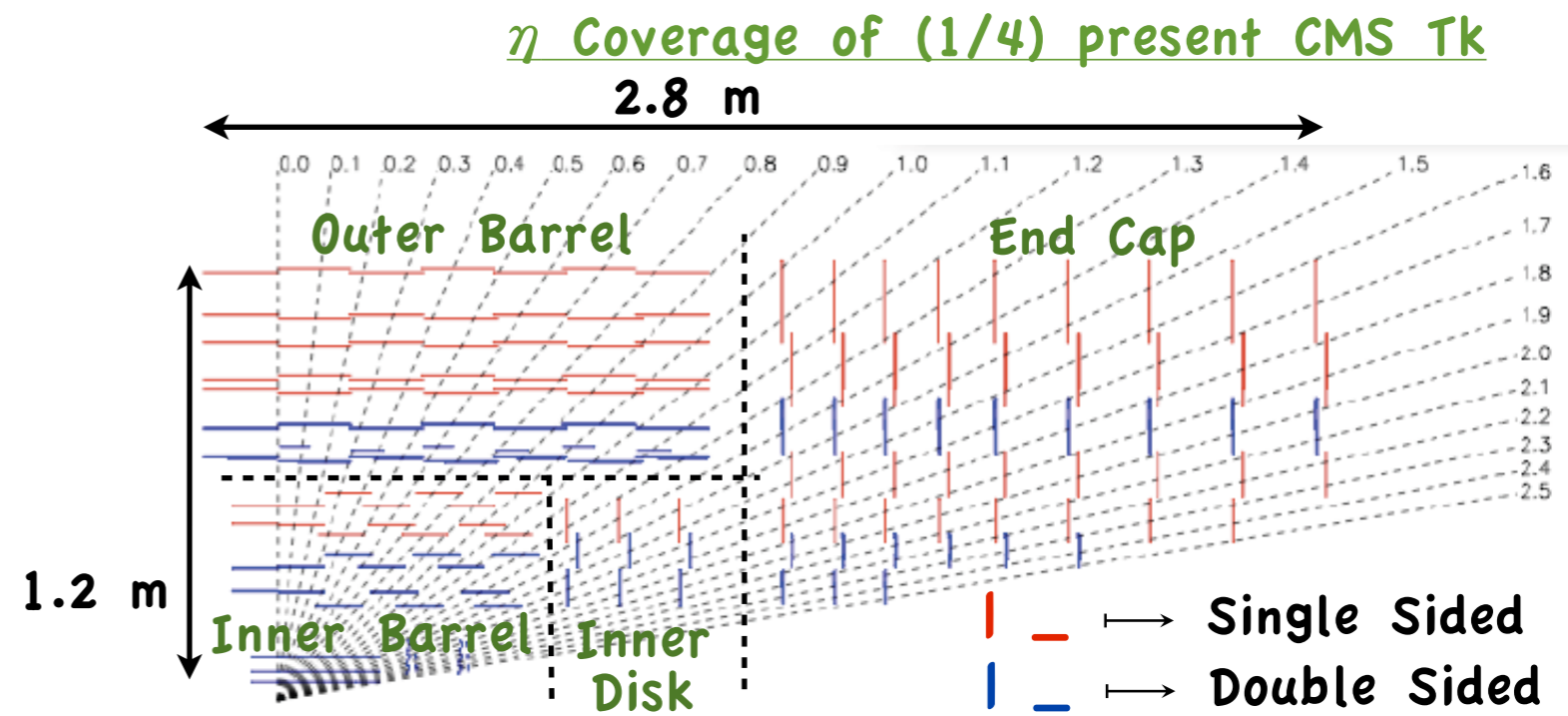
- ~> Performance of 2-in-1 modules measured in CMS data (7 TeV p-p collisions)
 - >> Firstly MinBias/QCD events, π 's & μ 's (from B/D semileptonic decays) tracks inside hadronic jets
 - >> good quality tracks selected: $\chi^2 < 2$, $\#_{hits} > 11$, $\#_{pixel} > 1$, $z_0 < 10$ cm, $d_0 < 0.1$ cm (π 's) \ 5 cm (μ 's)



Single Sided Module



Double Sided Module



Method Validation

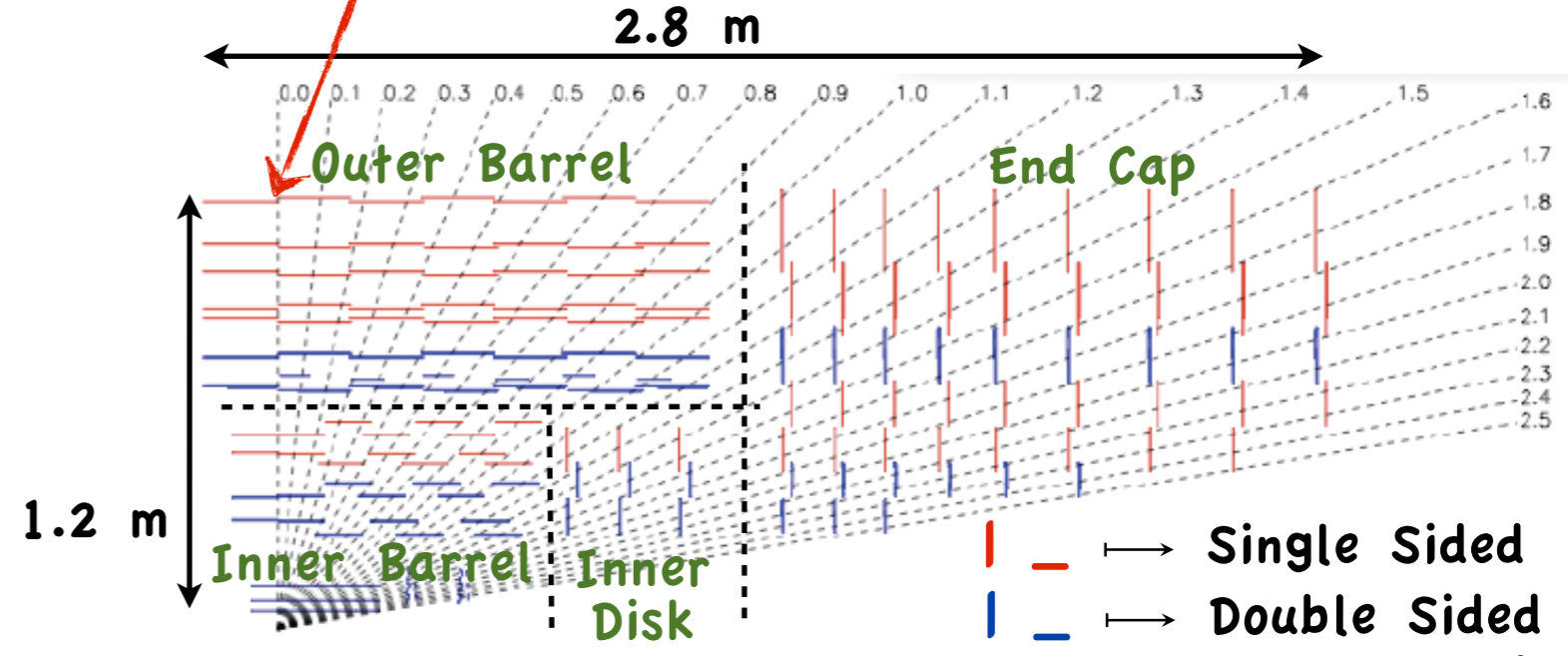
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Single Sided (SS) modules considered to study CW (CW=TW in SS) selection

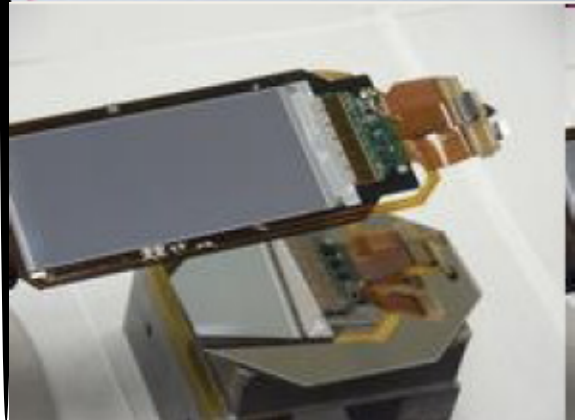
>> TOB Layer 6

- R = 108 cm
- ToP = 4.2

η Coverage of (1/4) present CMS Tk



Single Sided Module



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Double Sided (DS) modules considered to mimic the 2-in-1 stacked modules

- >> TOB Layer 2
 - R = 70 cm
 - ToP = 21.9

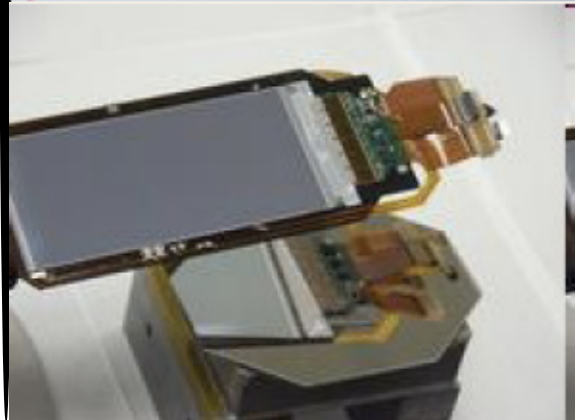
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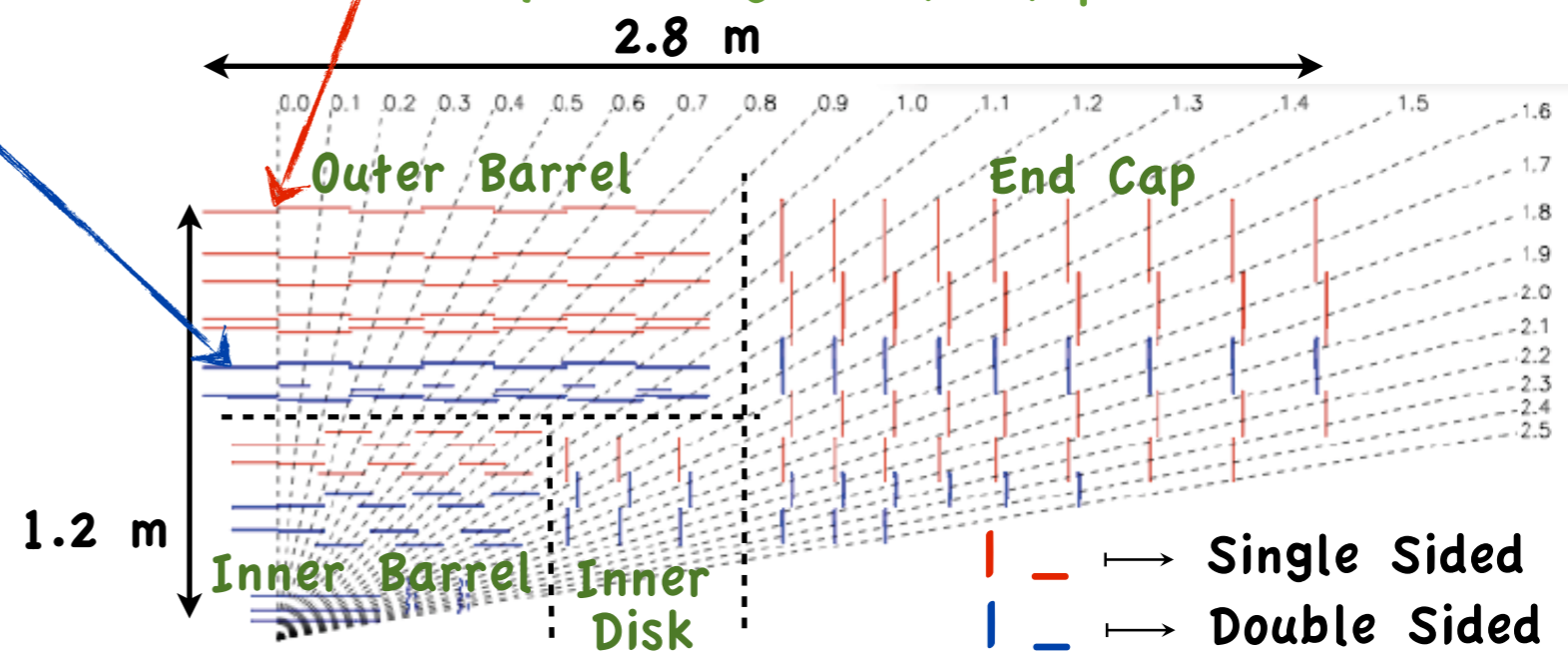
η Coverage of (1/4) present CMS Tk



Single Sided Module

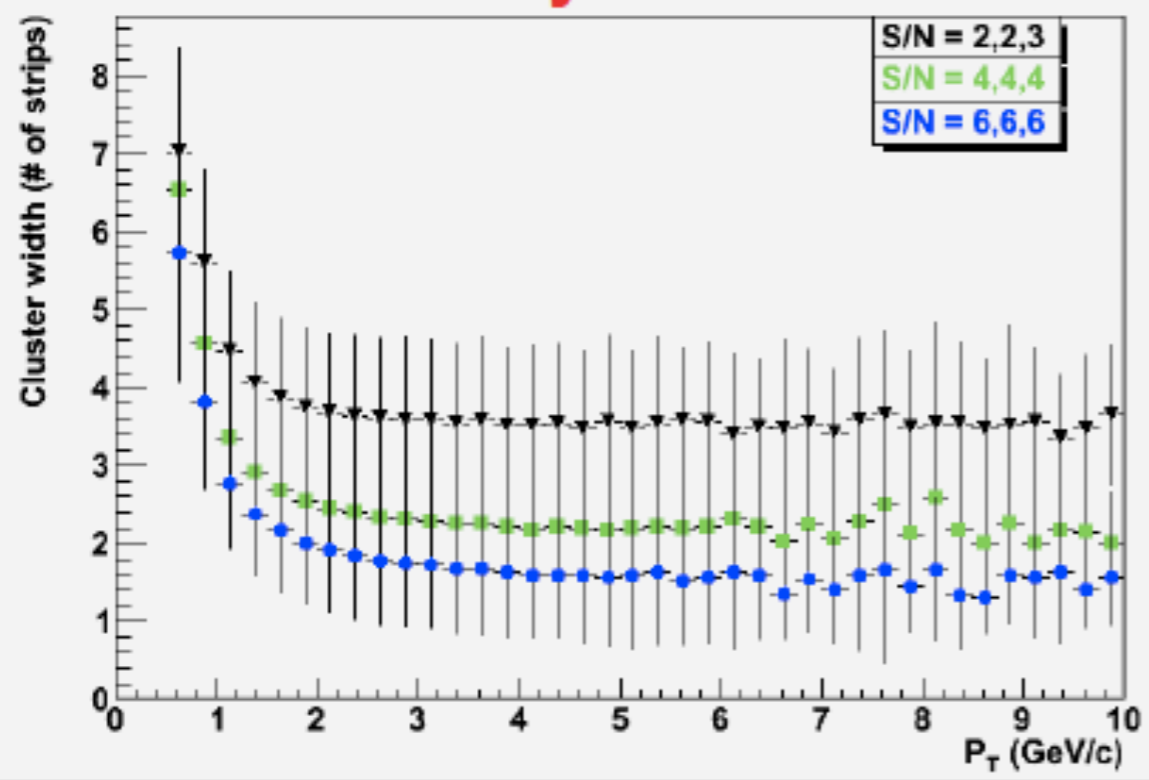


Double Sided Module



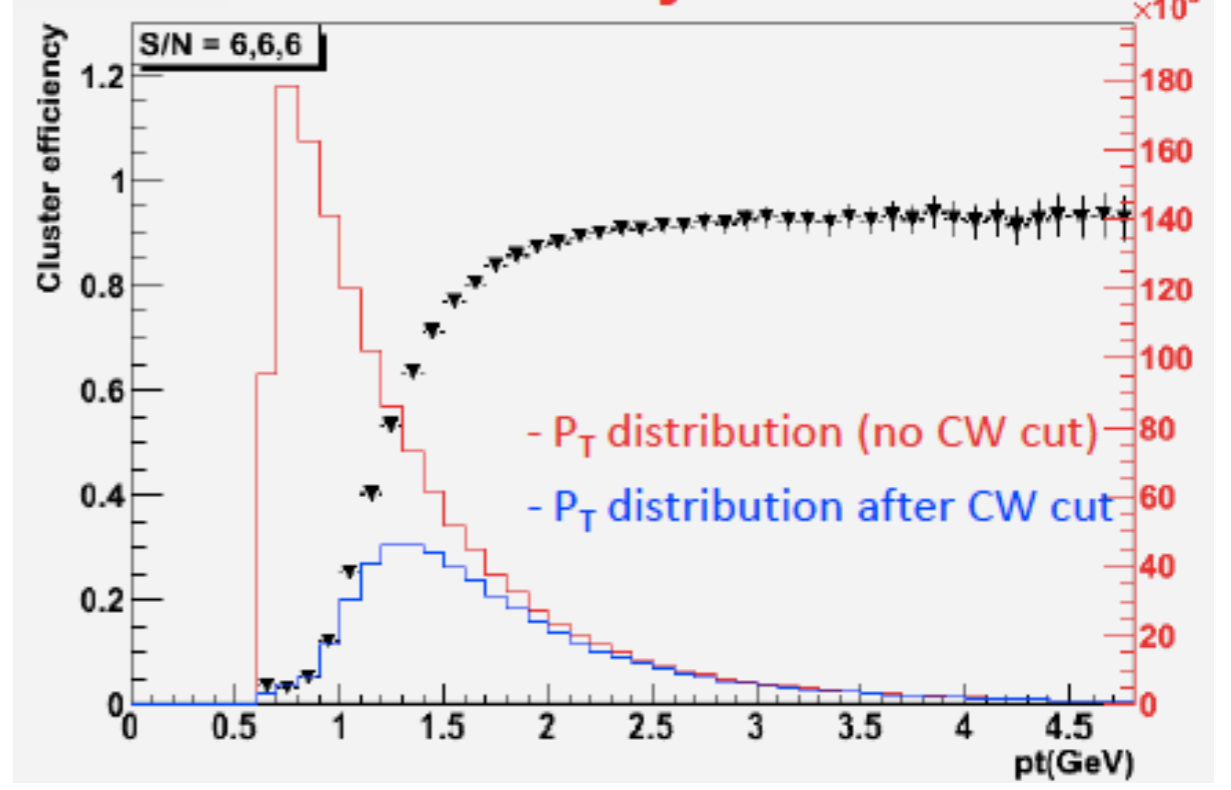
SS: Sensitivity to CW

TOB Layer 6



- ~> Tracks CW correlated with reco p_T for various clustering thresholds
 - >> CW decreases with p_T , as foreseen from theoretical model
 - >> Good p_T sensitivity for higher clustering thresholds ($S/N > 6$) due to suppression of capacitive couplings effects on FE electronics generating false large clusters

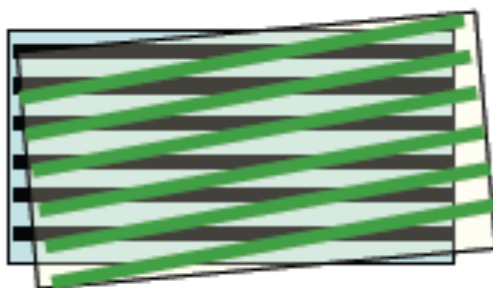
TOB Layer 6



- ~> Tracks selected with $CW < 3$
 - >> Selection efficiency as a function of p_T superimposed to track p_T distributions
 - >> Efficiency > 90% yet from 2 GeV/c

DS: Sensitivity to p_T

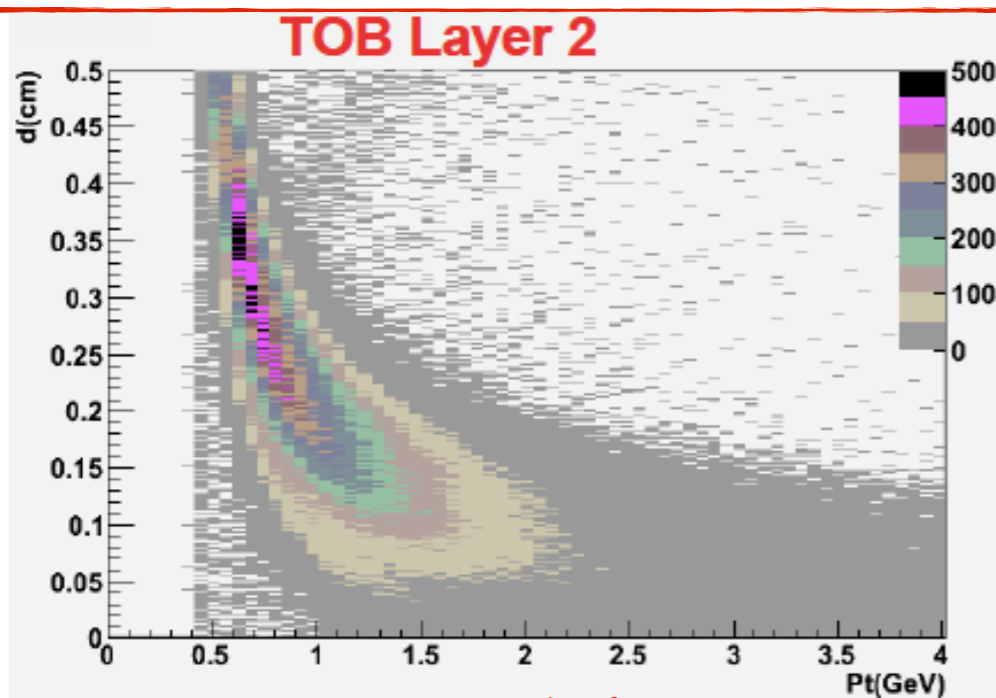
~> DS in CMS are used to get z info



tilt angle: 100 mrad

>> 2 SS modules are in “stereo” configuration
 i.e. rotated by 100 mrad

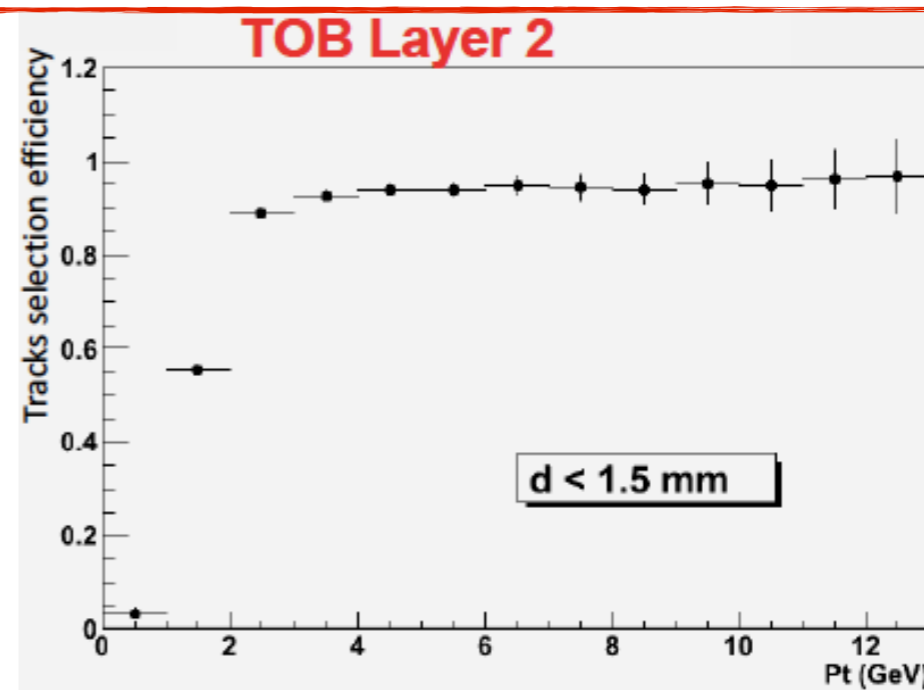
>> Correcting off-line for the stereo angle, we can
 use DS modules as double layer detectors



~> Correlation TW(“d”) vs. track p_T

>> High p_T (>2 GeV/c) tracks have clusters
 almost overlapping

>> Clusters for low p_T ones are far
 each other



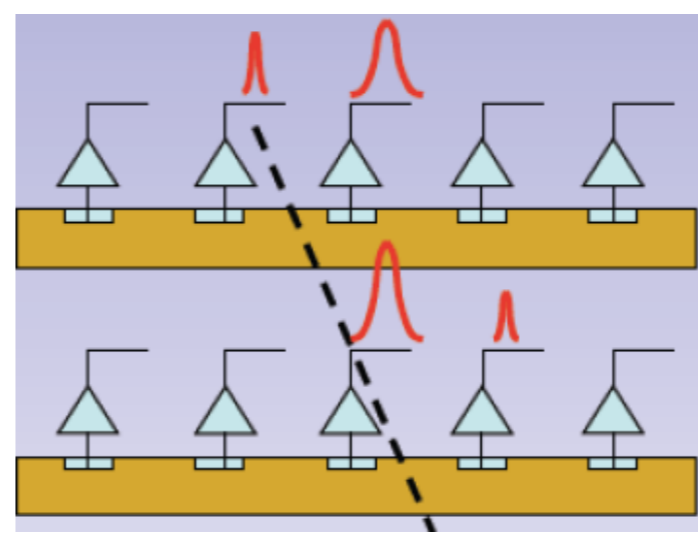
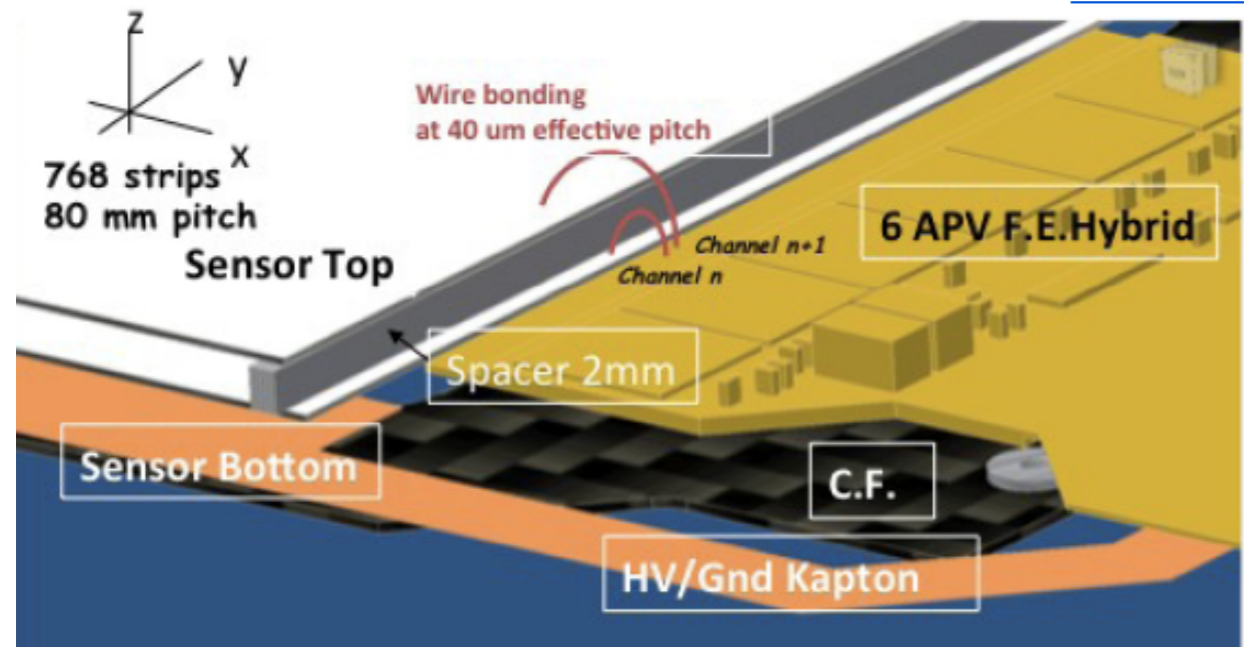
~> Tracks selected with TW(“d”) < 1.5 mm

>> Selection efficiency vs. track p_T

>> Efficient selection (~100%) for
 high (> 5 GeV/c) p_T tracks

First Prototypes

Module A

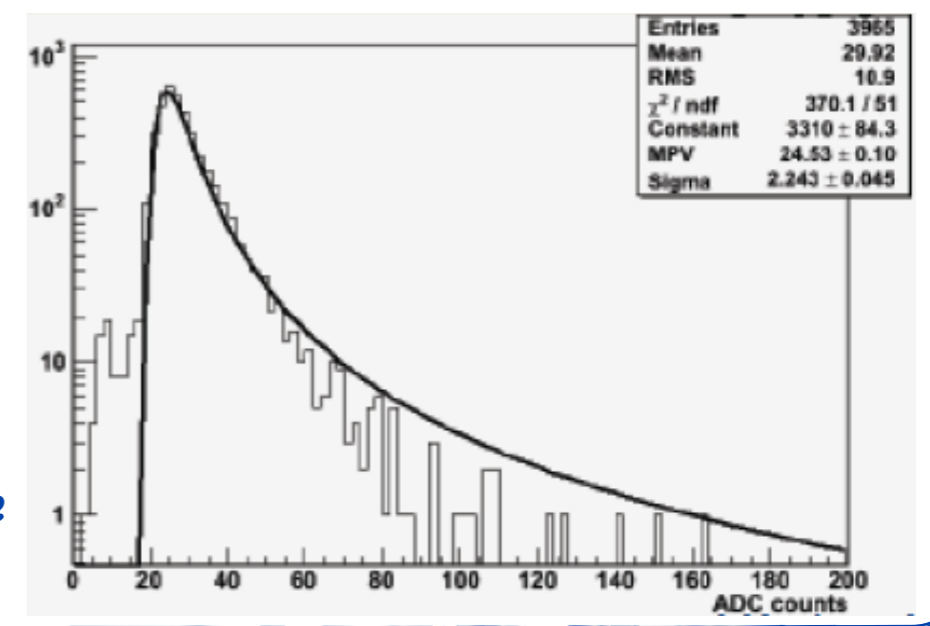


- ~> Tracks generate signals on both sensors
- ~> Signals collected independently
- ~> Top & Bottom Cluster position & CW reco independently
- ~> Top & Bottom sensors correlation needed

- ~> Pair of corresponding strips wire-bonded to a pair of neighboring read-out channels
- ~> Sensor pairs with:
 - >> 80 μ m pitch \ 768 μ -strip

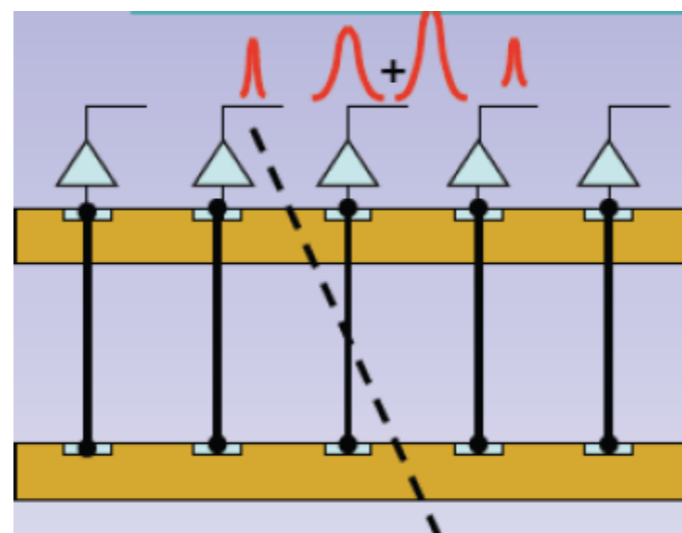
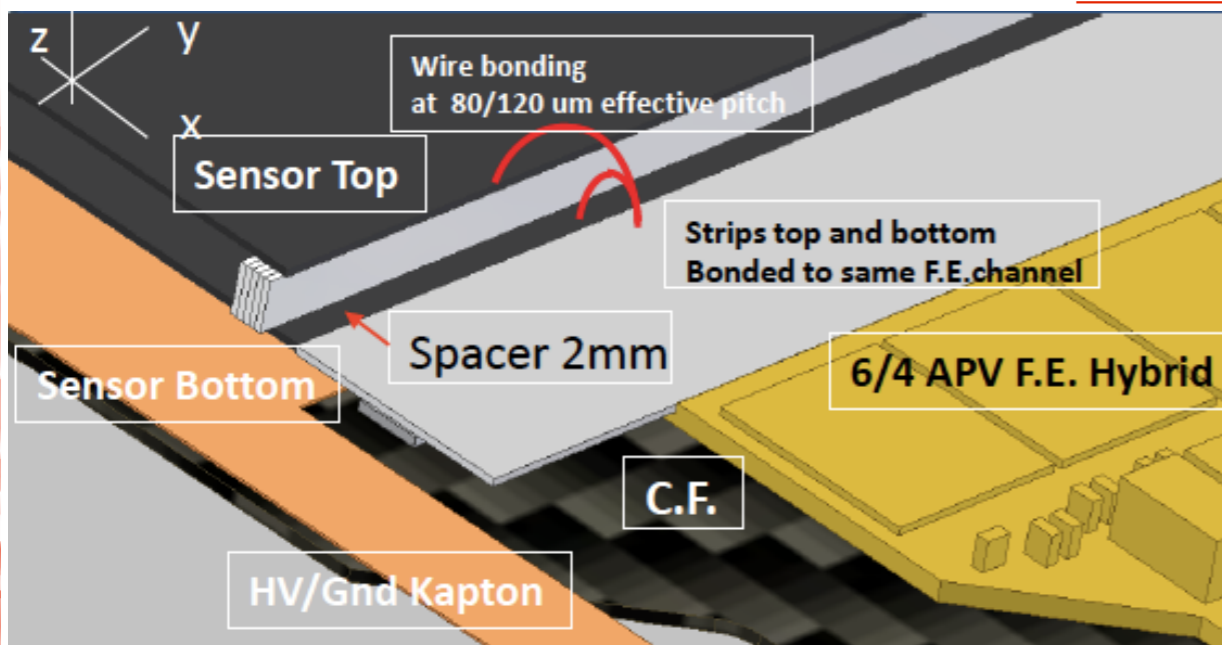
Off-detector Cluster Analysis:

- >> Select event with 2 clusters only
- >> No Cross-Talk between strips affects performance
- >> Fit on S/N distribution: Landau, MPV=24.5 \pm 0.1



First Prototypes

Module B



- ~> Tracks generate signals on both sensors
- ~> Signals are summed by wire bonding
- ~> Cluster position & CW reco as for SS
- ~> Limit case: only 1 cluster/track reco for too close clusters

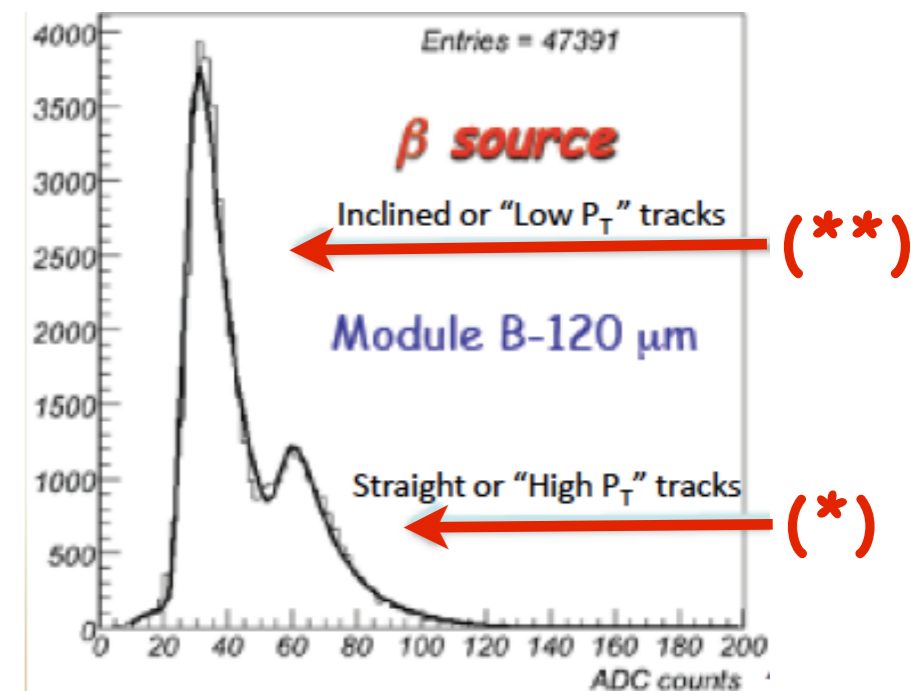
~> Pair of corresponding strips wire-bonded to the same read-out channel

~> Sensor pairs with:

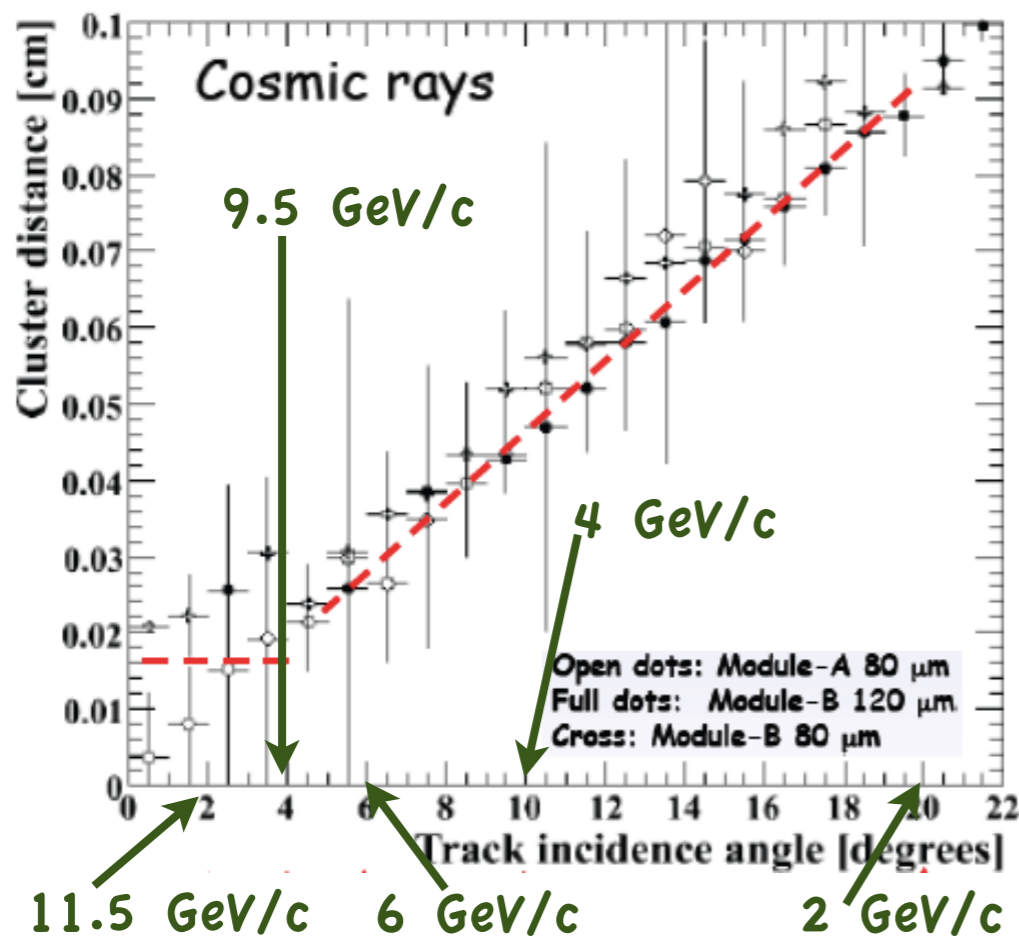
- >> 80 μm pitch \ 768 $\mu\text{-strip}$
- >> 120 μm pitch \ 512 $\mu\text{-strip}$

Off-detector Cluster Analysis:

- >> Clustering performed for track with 1^(*) or 2^(**) clusters
- >> Fit on S/N distribution: (*) Landau, MPV=39.2 \pm 0.5
 (**) Landau, MPV=20.8 \pm 0.2

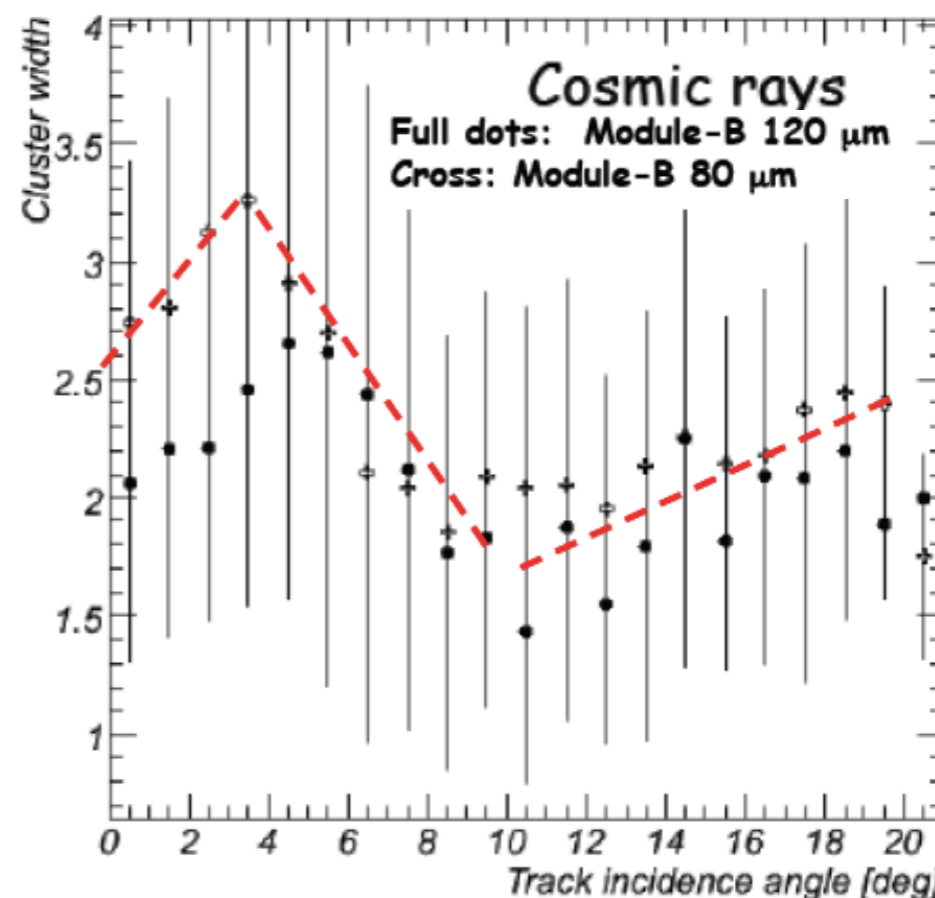


Cosmic Rays



~> Cluster Distance (TW) vs. inc. angle

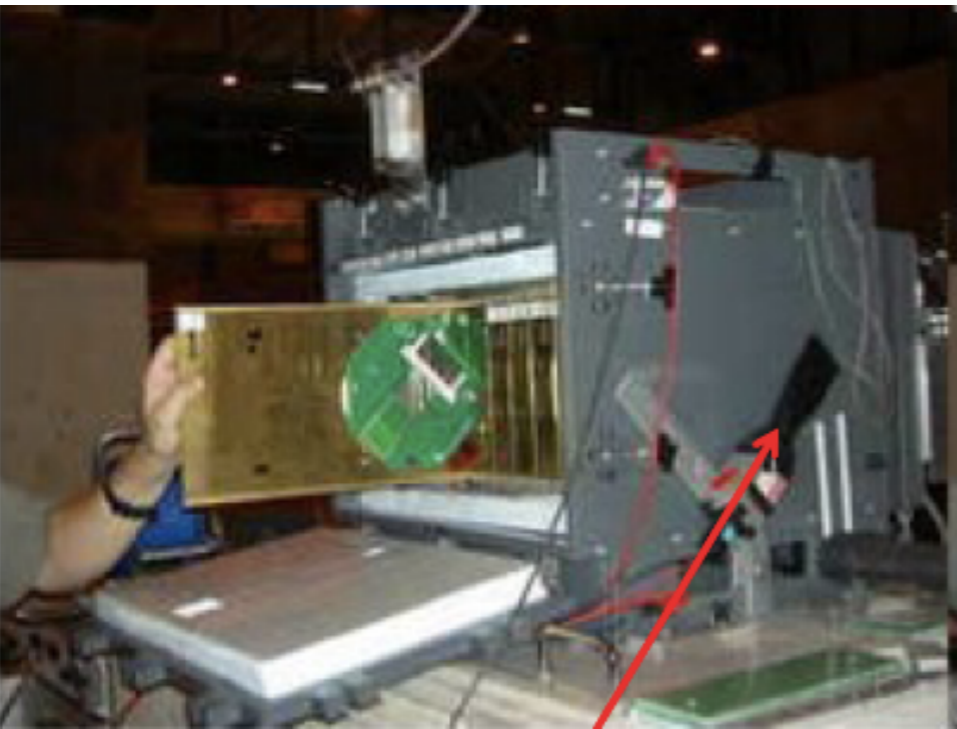
- >> **Module A** linear in the full range of incidence angle
 - >> **Module B** non linear for small incidence angle values (where clusters overlap)
 - >> This allows p_T discrimination in a B field
- Example of p_T discrimination for $B=4$ T at $R=108$ cm**



~> CW (# of strips) vs. inc. angle

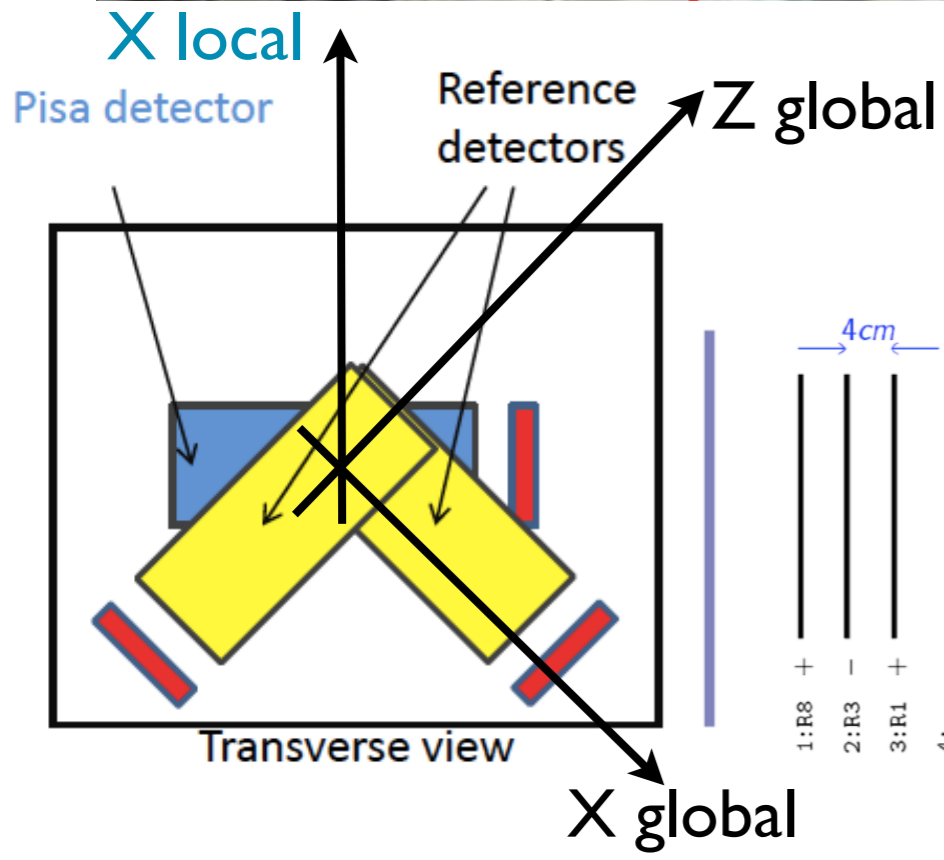
- >> Increases until top & bottom sensor produces events with 1 cluster
- >> Drops for angles with 2 clusters splitting
- >> Then follows a standard behavior at larger angle (where 2 clusters event are collected)

Beam Test (Setup)



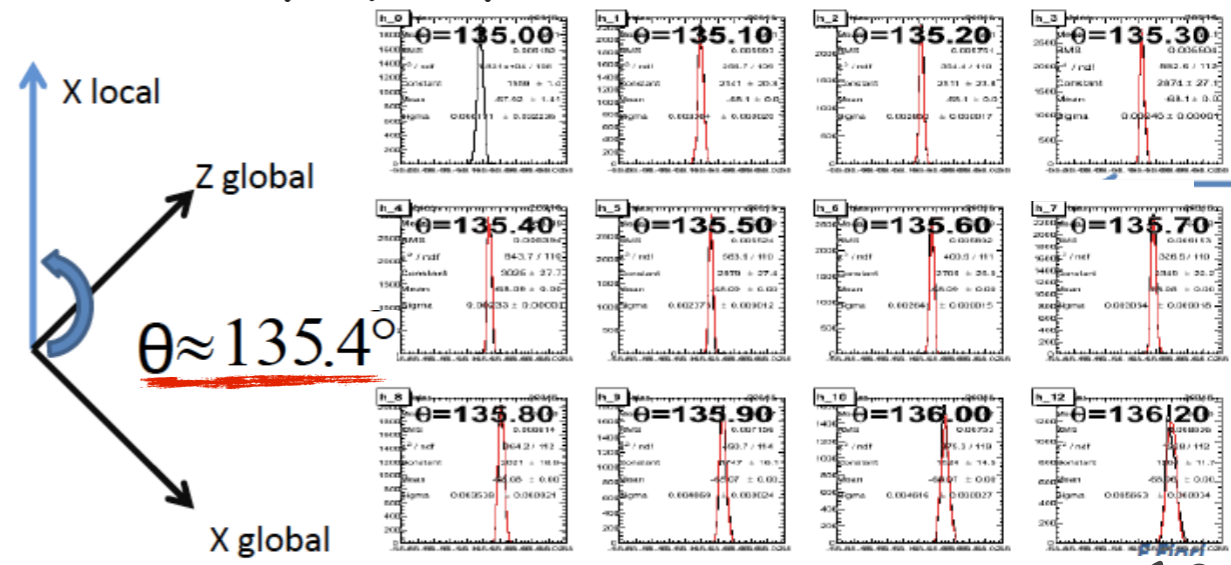
~> Telescope Setup:

- >> Trigger made by coincidence of two scintillators mounted on both sides of the telescope
- >> 8 reference planes (Si μ -strip sensors 50 μ m pitch) rotated by $\pm 45^\circ$, only $8 < \#_{hits} < 13$ tracks retained
- >> reference detectors alignment & clusters\track reco in global reference provided by Helsinki HIP team (thanks to T. Mäenpää et al.)

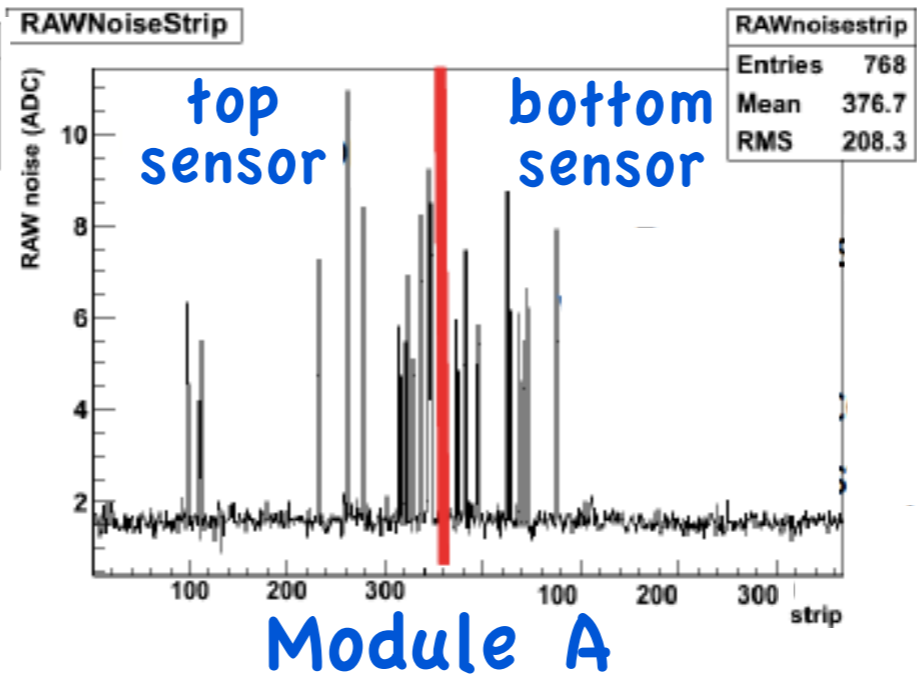
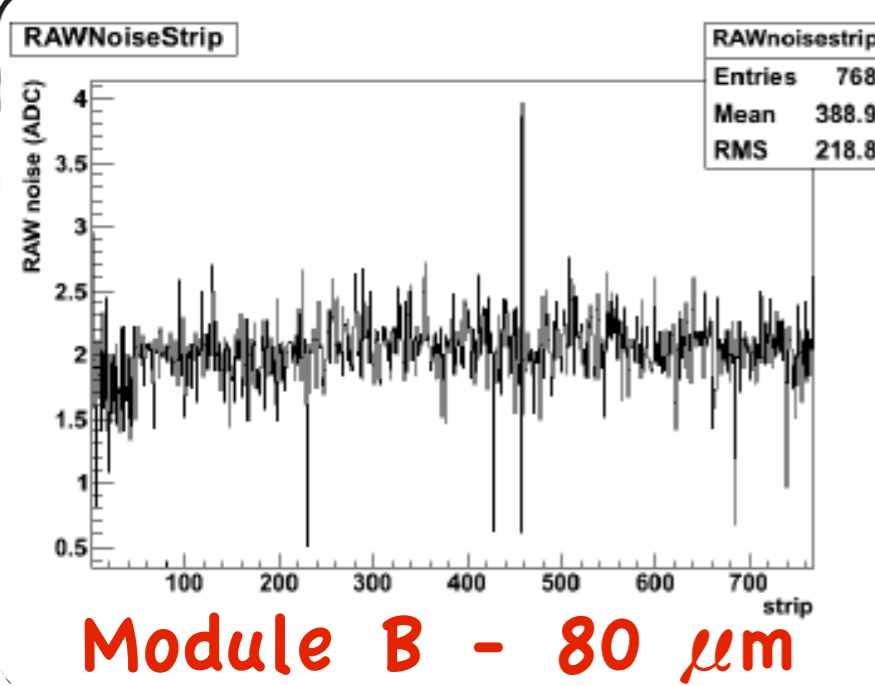


~> To identify fakes & calculate the incidence beam angle we have to align Pisa det. to global frame

>> Minimizing the residuals $x_{loc} - x_{glob}$ rotating frames step-by-step

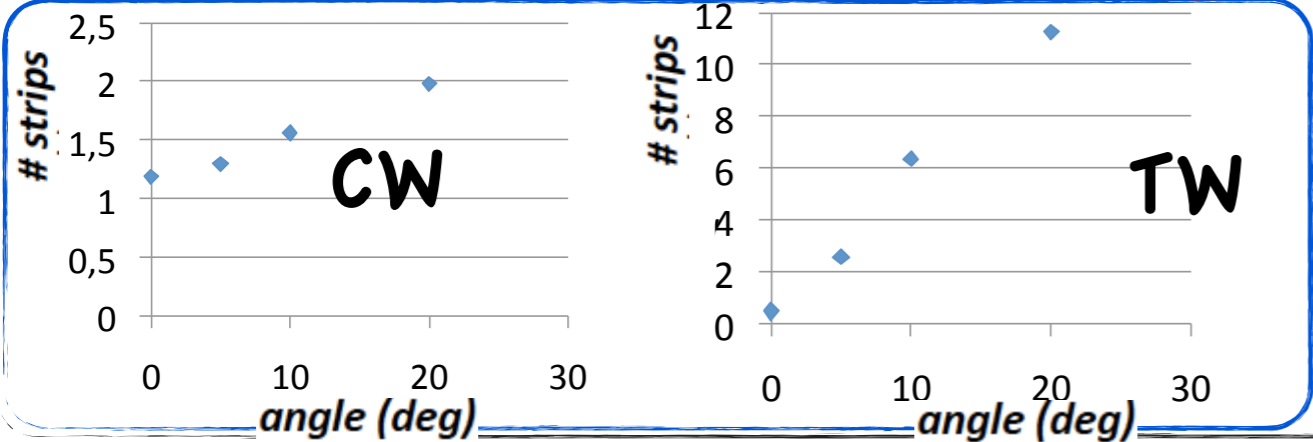
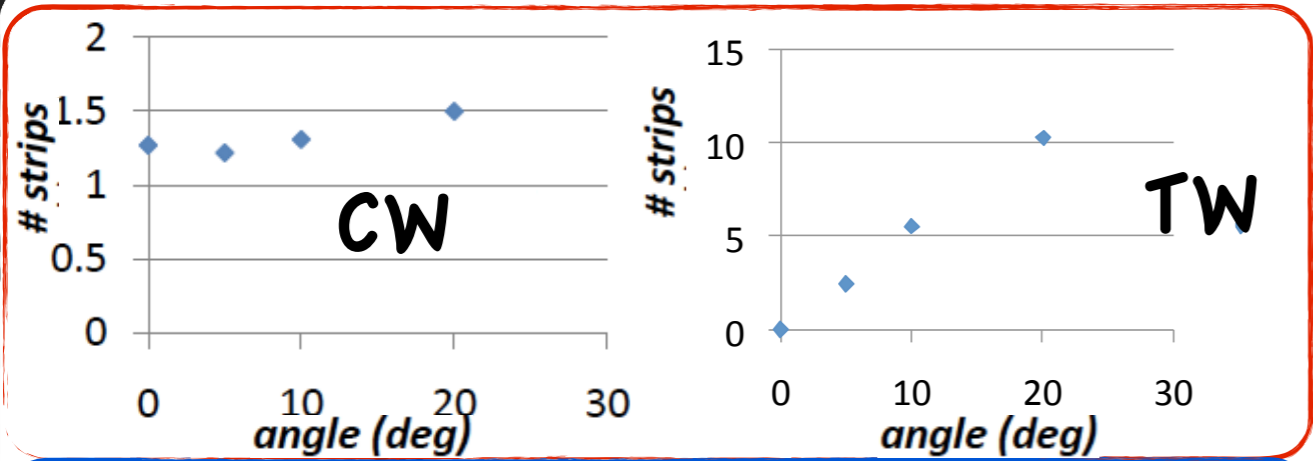


Beam Test (Results)



Noise Performance

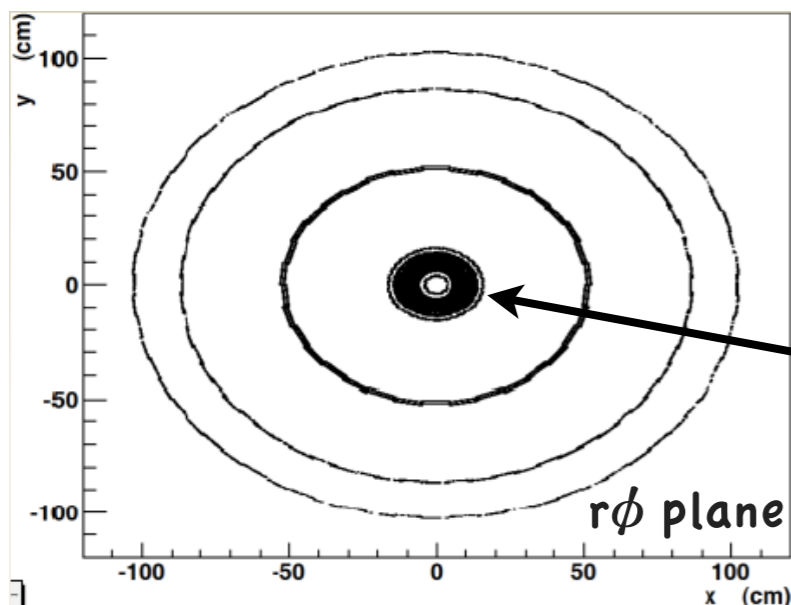
- >> spikes due to unconnected strips
- >> **Module B: RMS~2.03**
Module A: RMS~1.58
- Higher noise due to higher capacitive load in the wire-bonding to the same read-out channel



TW(cluster distance) & CW vs. inc. angle

- >> **Module B**
 - Considered angles: 0°, 5°, 10°, 20° to mimic different p_T tracks
- >> **Module A**
 - Considered angles: 0°, 5°, 10°, 20° to mimic different p_T tracks
- >> Similar behaviors of TW, quite higher CW values for **module A**

Simulation Framework

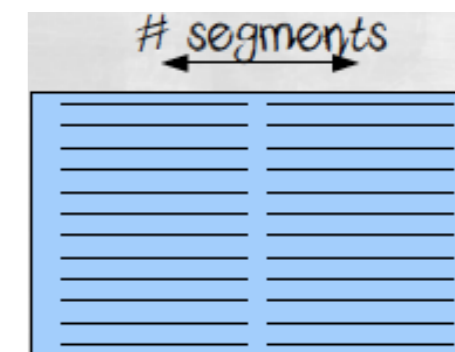


layer	L1	L2	L3
Radius (cm)	51	86	102

Si Pixel Vtx Detector

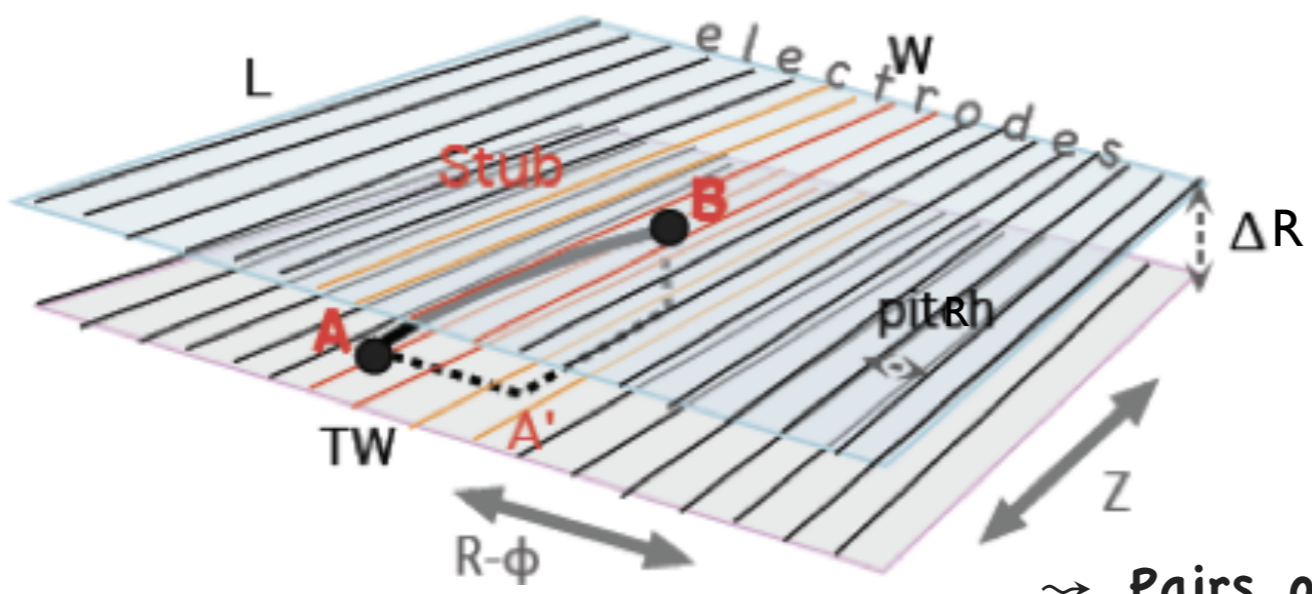
→ Particles 4-momentum propagation inside material based on GEANT4,
 Tk layout geometry & material budget description based on XML files
 architecture

- >> **MinBias:** generated with the Pythia MC generator
- single μ^\pm :** generated with “single particle gun” MC generator
- >> **Tk Geometry:** 3 barrel layer (1.2 m long) outside Si Pxl Vtx,
 Si sensors Stacked modules 10 X 10 cm².
- Module Topology:** μ -strip 98 μ m pitch 4.6 cm long, 300 μ m thickness,
 $\Delta R=1$ mm, active area 9.2 X 9.2 cm²
- >> Digital μ -strip read-out via ADC, channels of both sensors read-out independently
 (Module A emulation)



Stub as Trigger primitive

Stub Definition



~> Pairs of clusters are correlated through algorithms based on geometrical constraints with P.V. & \vec{B} field knowledge inside the module ΔR

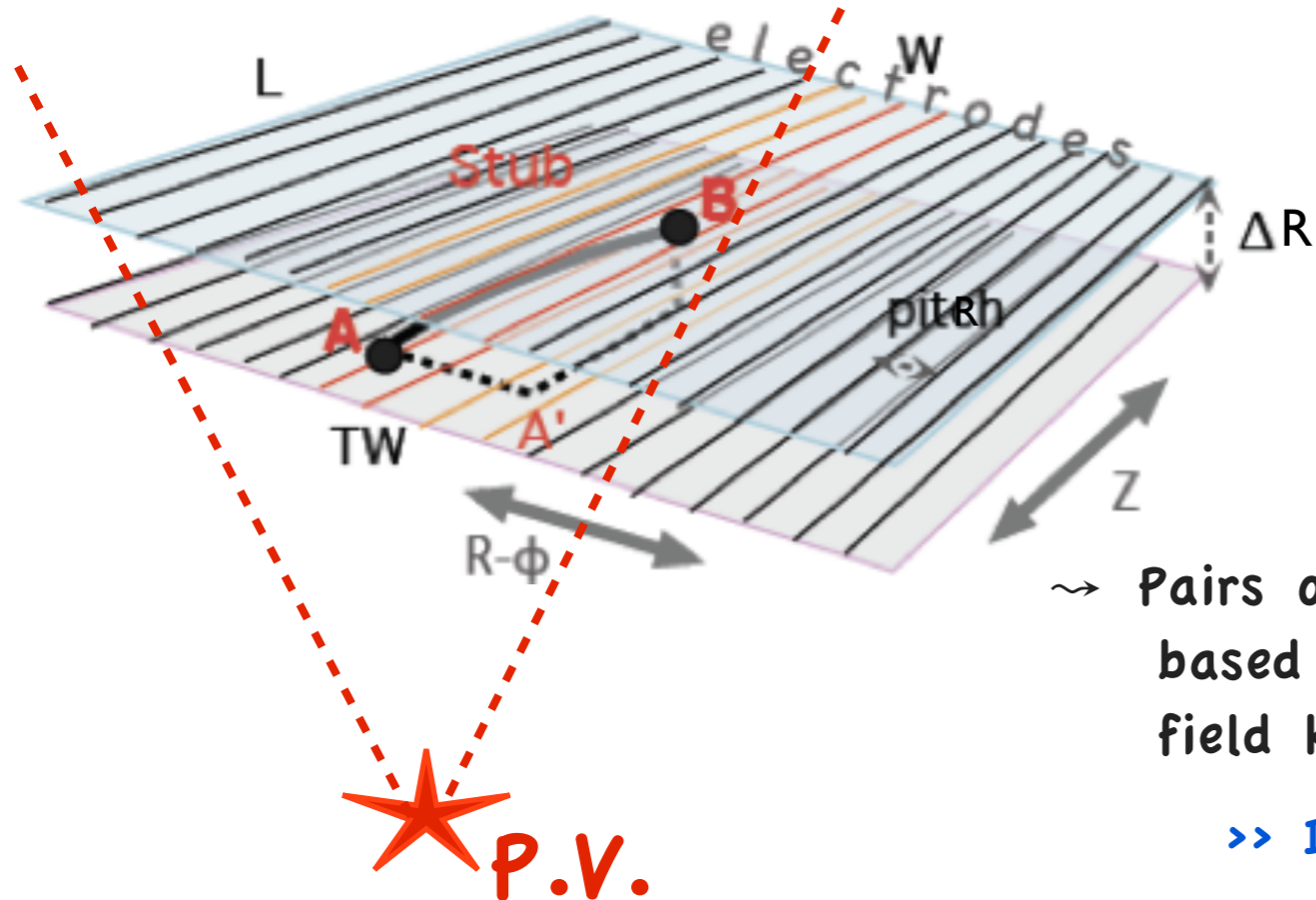
- >> Intrinsic cut ~ 2 GeV/c due to geometrical constraints in stub reconstruction algorithms
- >> Kinematic infos (position, \vec{p}_T , CW of both sensors) are encoded into a single object called "stub"

Stub encoding:

$$\text{Stub} = \text{3-vector}(\text{global pos.}) + \text{2-vector}(\text{flight dir.}) + \text{scalar}(\text{pT}) (+ \text{two scalars}(\text{CW in both sens.}))$$

Stub as Trigger primitive

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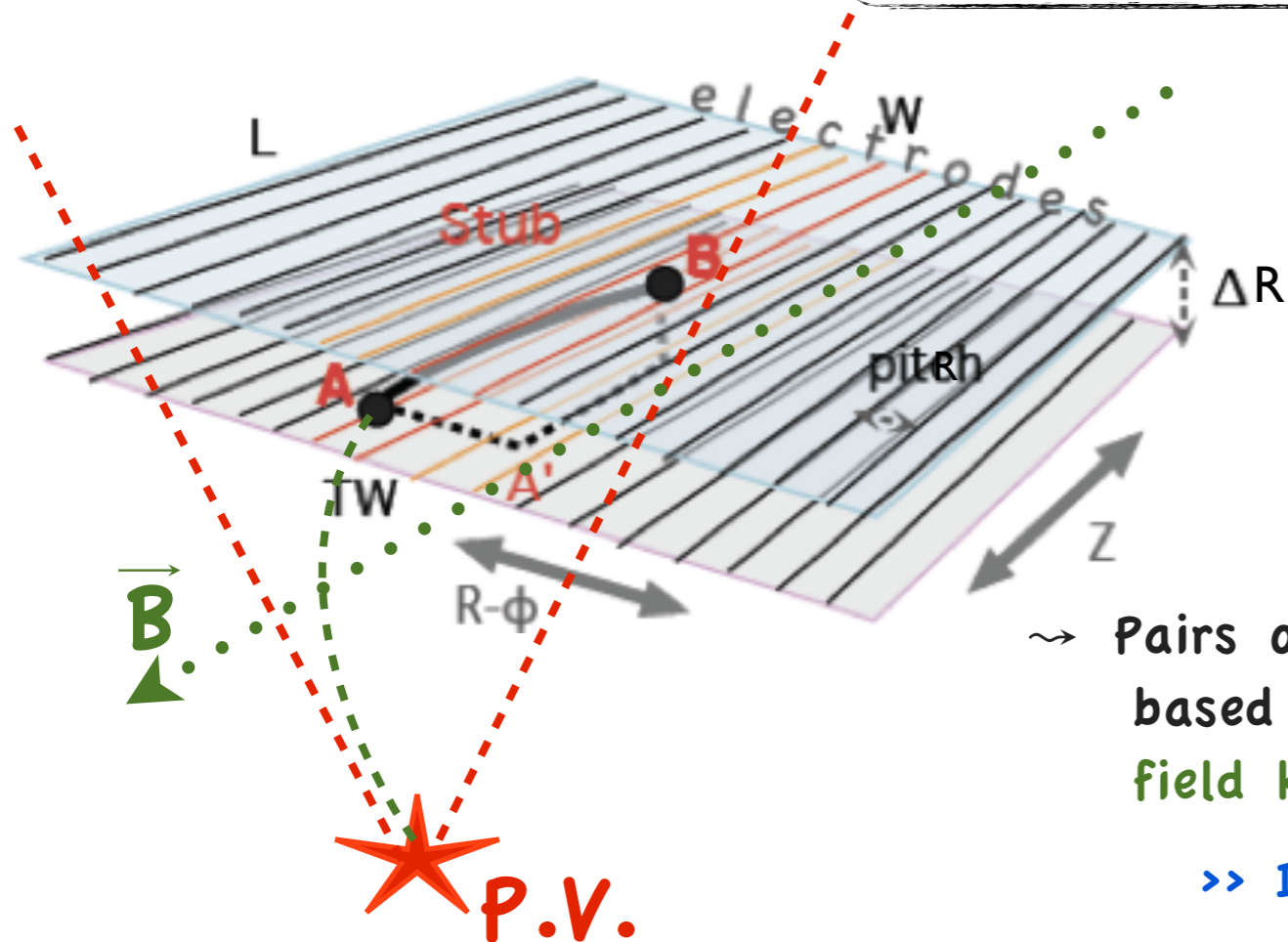
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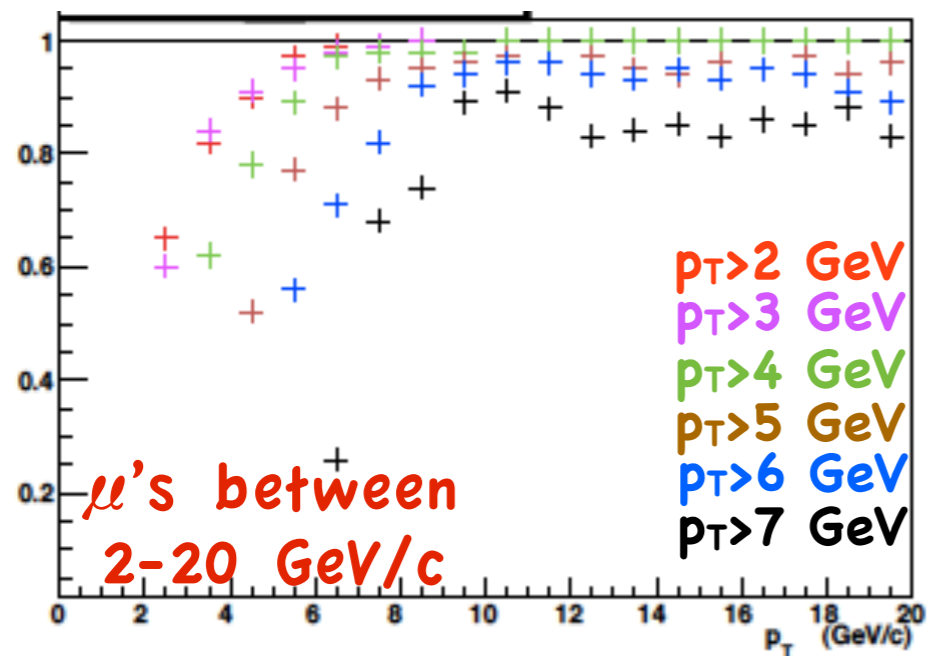
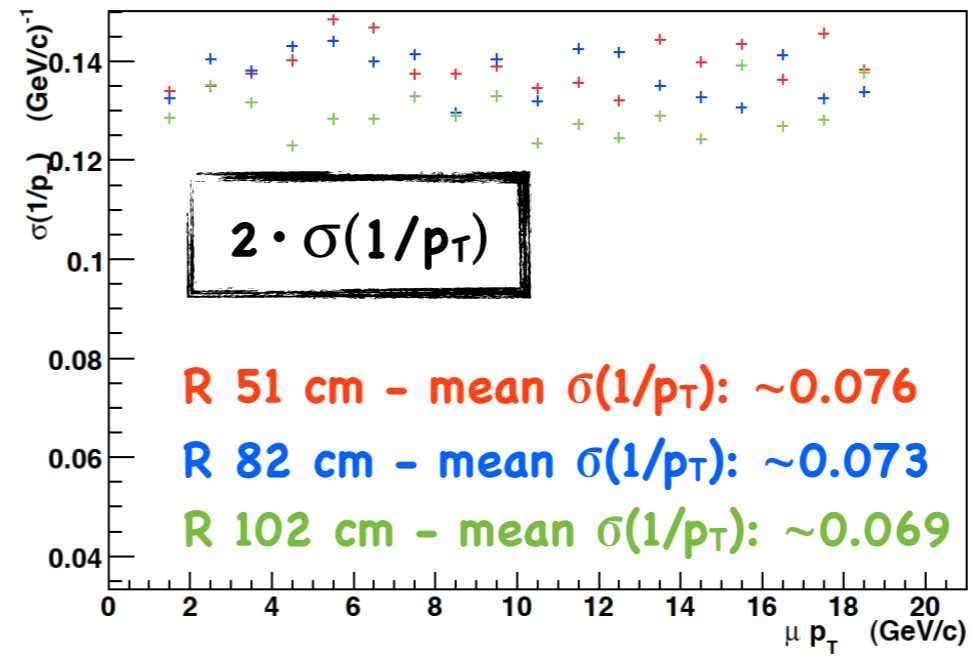
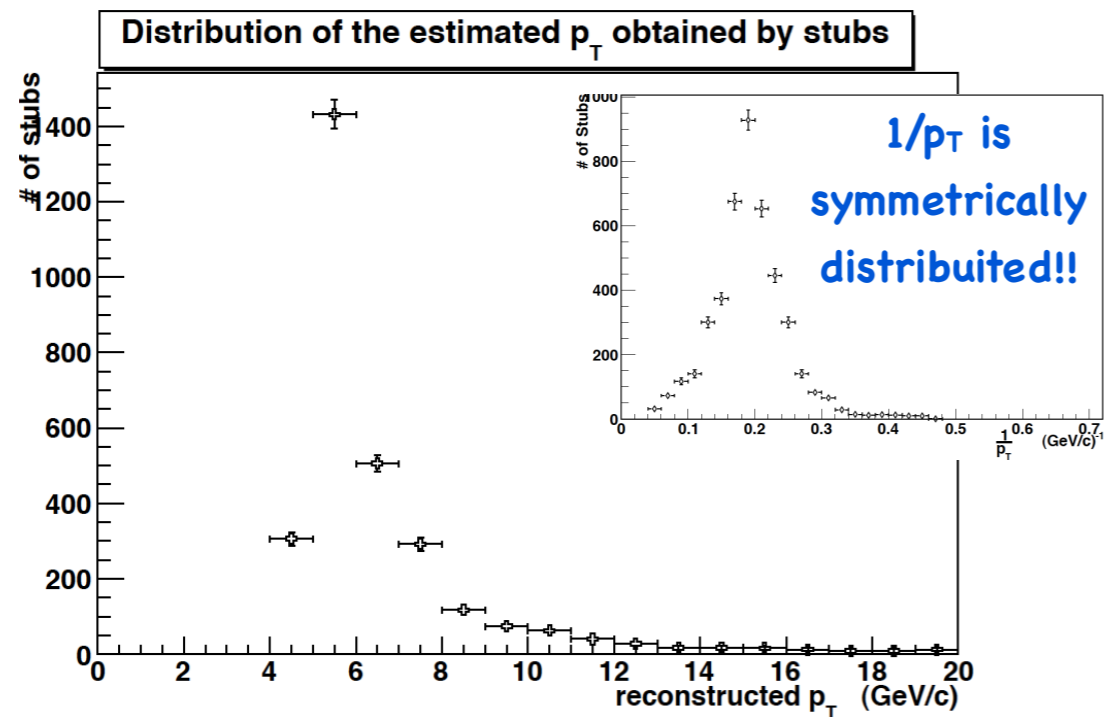
Stub encoding:

$$\text{Stub} = \text{3-vector}(\text{global pos.}) + \text{2-vector}(\text{flight dir.}) + \text{scalar}(\text{PT}) (+ \text{two scalars}(\text{CW in both sens.}))$$

Stub p_T Measurement

→ p_T measurement resolution: Single μ 's @ 5 GeV/c

>> Evaluation of reconstructed p_T from the stub (see slide 1): $\frac{\sigma(p_T^{meas})}{(p_T^{meas})^2} \equiv \sigma\left(\frac{1}{p_T^{meas}}\right) \simeq 5\%$



→ Layer @ 102 cm equipped with Stacked Modules

- >> p_T selection strongly depends from p_T^{meas} resolution $\sigma(p_T)$ that:
 - (1) increases as $(p_T^{meas})^2$
 - (2) is not gaussian & skewed toward larger p_T^{meas}
- >> Inefficiencies appears for $p_T > 5$ GeV/c because of (1). Anyway, rejection at high p_T is milder because of (2)

Trigger Rates

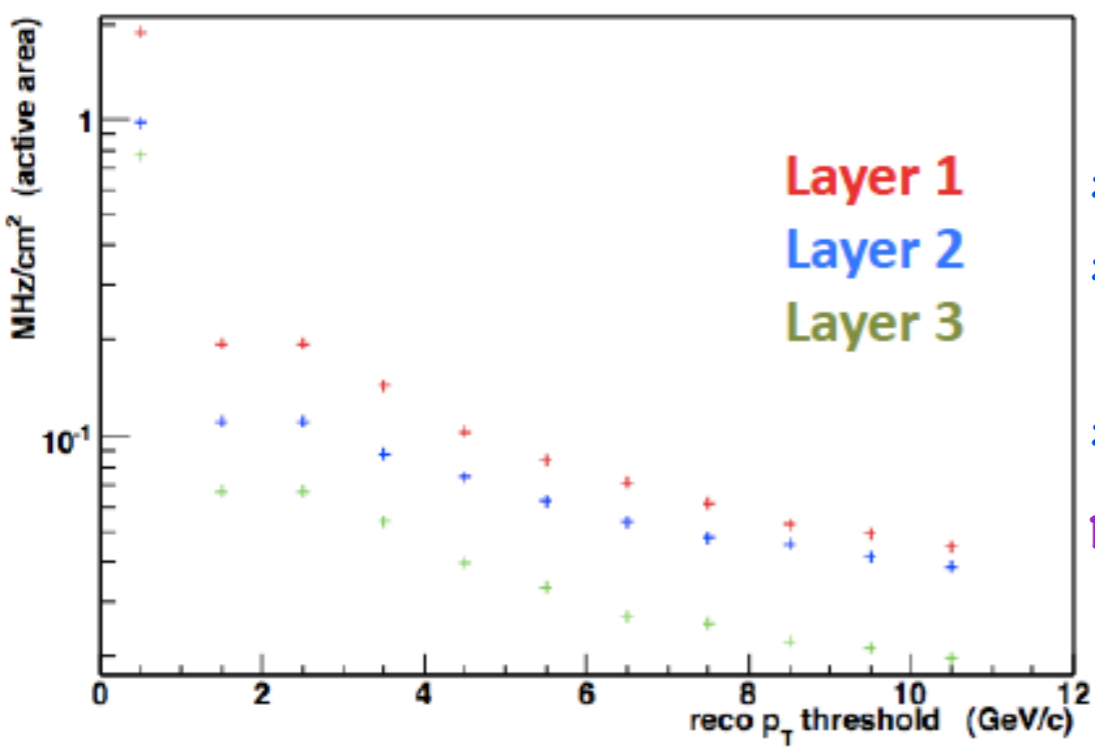
SLHC "Phase II" scenario:
pp @ $\sqrt{s}=14$ TeV, $\mathcal{L}=10^{35}$ cm⁻²s⁻¹, 200 MinBias/BunchX

→ Simulation of 200 MinBias overlapping events (BunchX rate 40 MHz)

layer	L1	L2	L3
Radius (cm)	51	86	102
Strip Occupancy (%)	1.5	1.1	0.9

>> Cut on p_T^{meas} estimated through stubs also at 1 or 2 GeV/c is enough to reduce the information rate to manageable level for trigger purposes:

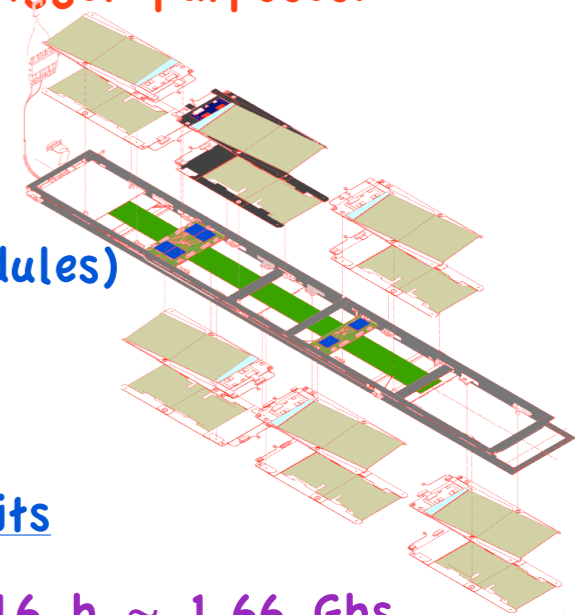
Stub production rate per cm²



- > CMS Tk is read-out per "rods" (12 modules)
- > each module has $9.2 \times 9.2 = 84.64$ cm² active area surface
- > supposing to encode stub infos in 16 bits

$BW_{Read-Out} \sim 100 \text{ kHz/cm}^2 \cdot 84.64 \text{ cm}^2 \cdot 12 \cdot 16 \text{ b} \sim 1.66 \text{ Gb}$

Within the range of available data link speeds



Conclusions & Outlooks

→ **Stacked Modules design is a viable solution for Tracker Trigger. Proven to work with:**

- >> Real LHC collision data
- >> Prototypes involved both in Cosmic Rays & Beam Tests
- >> Full Tracker simulation of foreseen SLHC scenario

→ **Main features:**

- >> Low material budget and hardware optimized
- >> Capable to decrease p_T trigger data rate down to ~ 100 kHz/cm²
- >> Local Trigger & low-level p_T evaluation

→ **Some R&D remains to be done, this activity will continue since is needed**

- >> Implement detector optimized design (module/layout)
- >> Trigger performance simulation study on benchmark channels (e.g. $H \rightarrow WW$)
- >> Optimization of INTRA sensor module connectivity
- >> Optimization of INTER rod\layer module connectivity (hardware, implementation of Associative Memories based on stubs, ...)

References

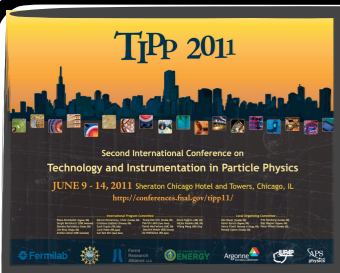
→ Publications:

- >> “Concepts for a tracker trigger based on a multi-layer layout and on-detector data reduction using a cluster size approach”, [JINST 5:C08002, 2010](#)
- >> “Track momentum discrimination using cluster width in silicon strip sensors for SLHC”
[Published in *Prague 2007, Electronics for particle physics* 80](#)
- >> “Tracking in the trigger: From the CDF experience to CMS upgrade”
[Pos VERTEX2007:034, 2007](#)
- >> “Design and development of micro-strip stacked module prototypes for tracking at S-LHC”, [JINST 5:C11018, 2010](#)
- >> “Design and development of micro-strip stacked module prototypes to measure flying particle directions”, [JINST 5:C07014, 2010](#)

→ Talks:

- >> <http://indico.cern.ch/contributionDisplay.py?sessionId=0&contribId=16&confId=68677>
- >> G. Parrini, Talk at Joint SLHC Trigger-Tracker meeting 2007, CERN and TWEPP 2007
- >> <http://indico.cern.ch/getfile.py/accesscontribId=80&sessionId=29&resId=0&materialId=paper&confId=11994>

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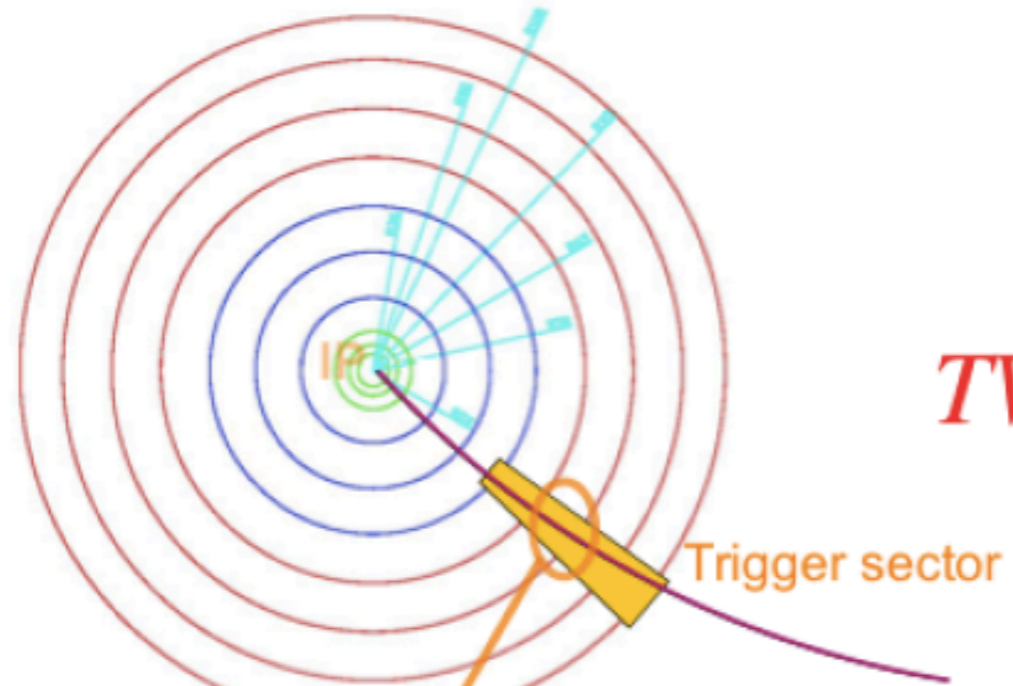


Back Up Slides

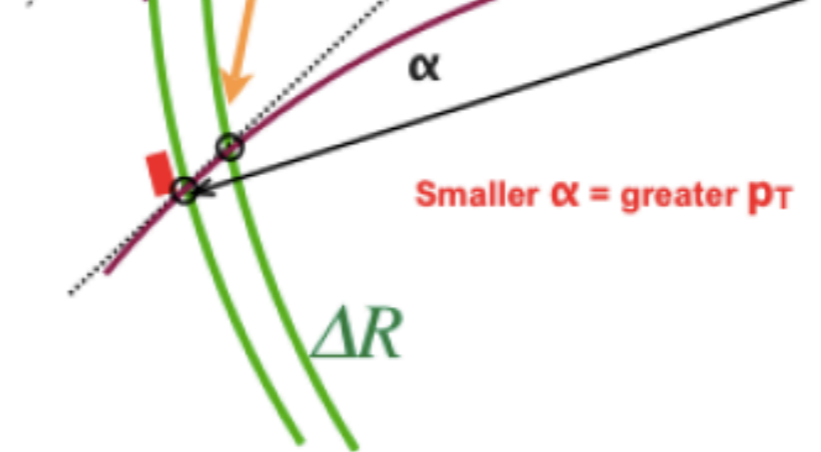
p_T measurement

► The two approaches for a quick "measure" of p_T

Barrel layers with single sensor detector for CW selection



Barrel layer with Stacked sensors' detectors for separation selection



$$TW = \Delta R \alpha$$

p_T measurement

Simplified formulas

Using acceptances $W/R < 0.2$ the stub width formula can be simplified

$$TW_r \approx F + (1 + F^2) (x/R)$$

$$F = \pm \frac{1}{\sqrt{\frac{pT}{\#pT_{min}}}} \left(\pm \sqrt{\frac{pT_{min}}{\#pT}} \times 1 + \frac{1}{2} \sqrt{\frac{pT_{min}}{\#pT}} + \dots \right)$$

If $pT^* \gg 1$

$$TW \approx \pm \frac{\#pT_{min}}{pT} \left(+ x/R = \pm 1/pT \right) + x/R$$

“Linear”
 cylindrical layer (pT^* any)
 +
 flat layer ($pT^* = !$)

p_T measurement

▶ p_T selection : from TW to p_T

$$\left(\frac{TW}{pitch} \right)_{TW_{measured}} = \left(TW_r \frac{''}{pitch} \# \left\{ \begin{array}{l} \% \% 1 \\ ', \pm ', - \\ \& \& pT^* \end{array} \right\} + \frac{X}{R+} + \tan, + (2 D/'') \tan \theta_L \right) \left(\frac{''}{pitch} \right)_{ToP}$$

cylindrical layer
flat layer
rotation
Lorentz spread

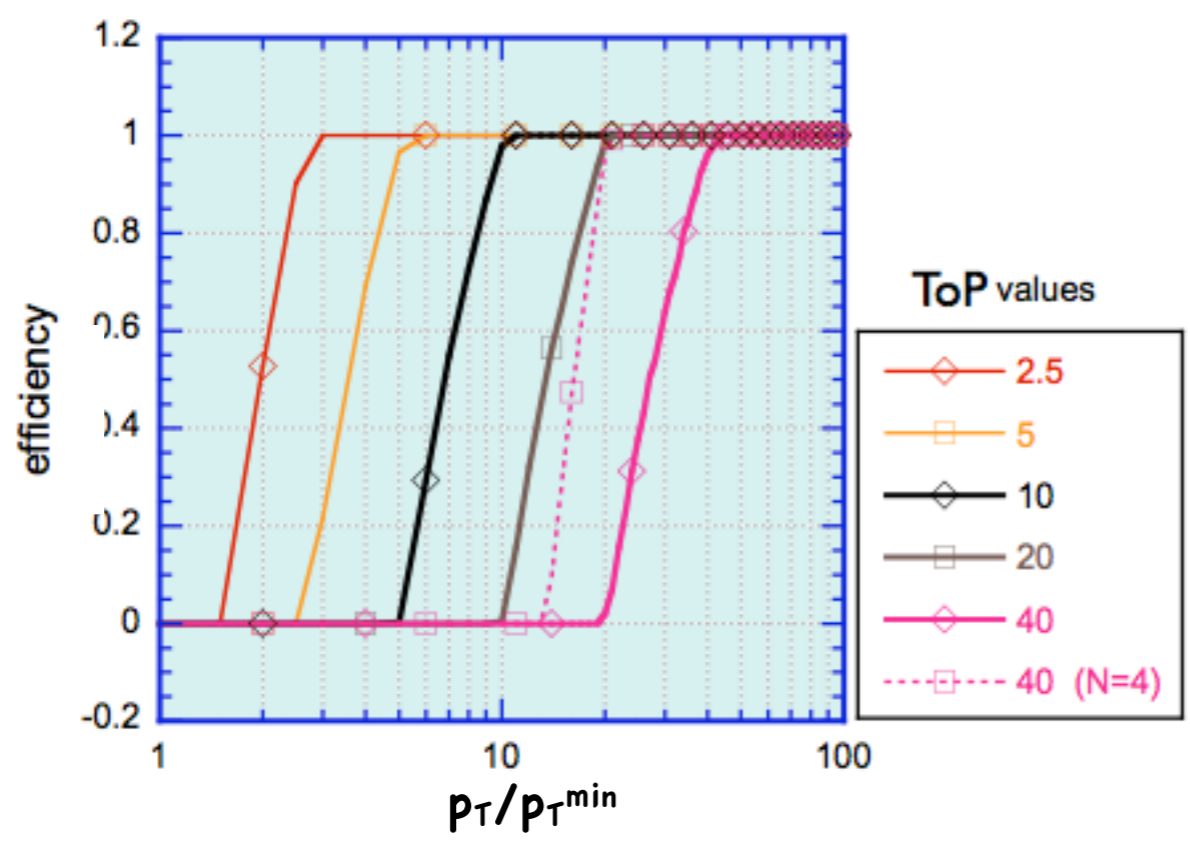
After the digitization the inverse transformation gives not unique results:

if $TW_{measured} = N \times pitch$ we have $N-2 \% TW < N$

This observation is the starting point to calculate the threshold of the selection

Basic Idea: p_T measure

→ Fraction of tracks leaving hits with at least $CW \sim 2$ pitches

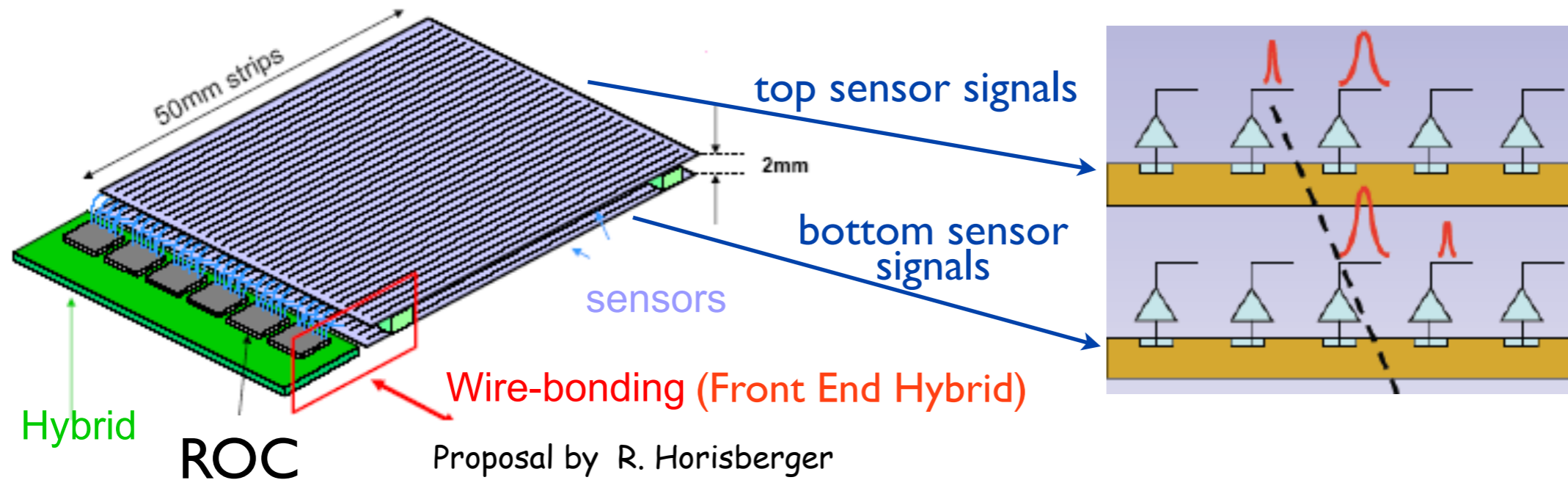


$$p_T^{\min} = 0.15 \text{ B R}$$

→ ToP ratio sets the (p_T) discriminating power of the method
 ⇒ higher values discriminates larger p_T ranges

(G. Parrini, talk given @ TWEPP2007)

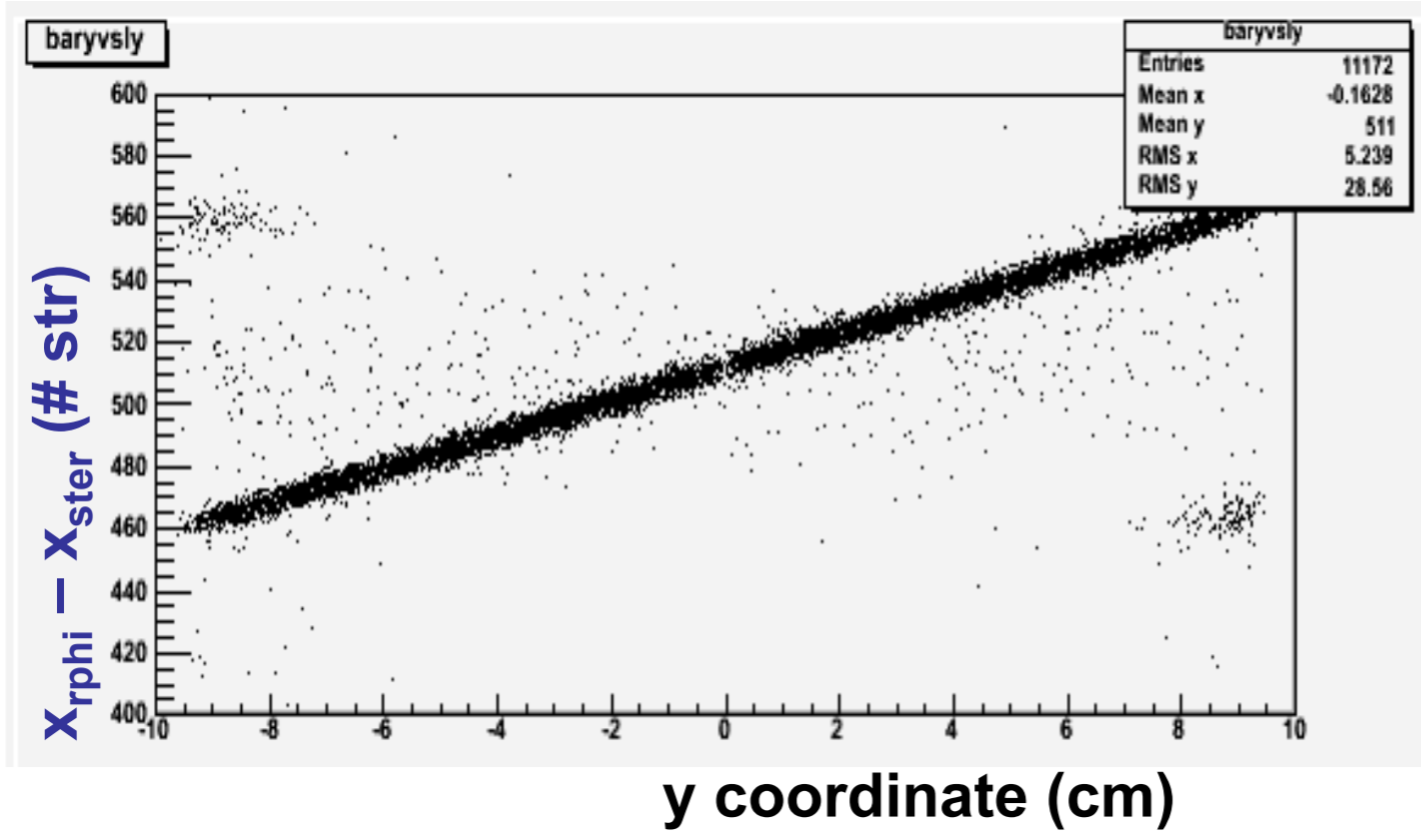
2-in-1 module design



- ~> wire μ -bonding connects the stacked sensors to a single read-out hybrid
- ~> Two clusters of signals produced per charged tracks
 - >> Correlation between sensitive planes needed (see the various prototypes solutions in next slides)

- ~> The 2-in-1 module design optimizes the common use of:
 - >> ASSEMBLY INFRASTRUCTURES: mechanical, material, ROC, cooling, cabling, ...
 - >> READ-OUT ELECTRONICS: brings to a simple logic to correlate hits, no need of high speed links or external correlation circuits, saving power, ...
- ~> In this way it is possible to maximize the benefit/cost ratio

Tilt Angle Correction

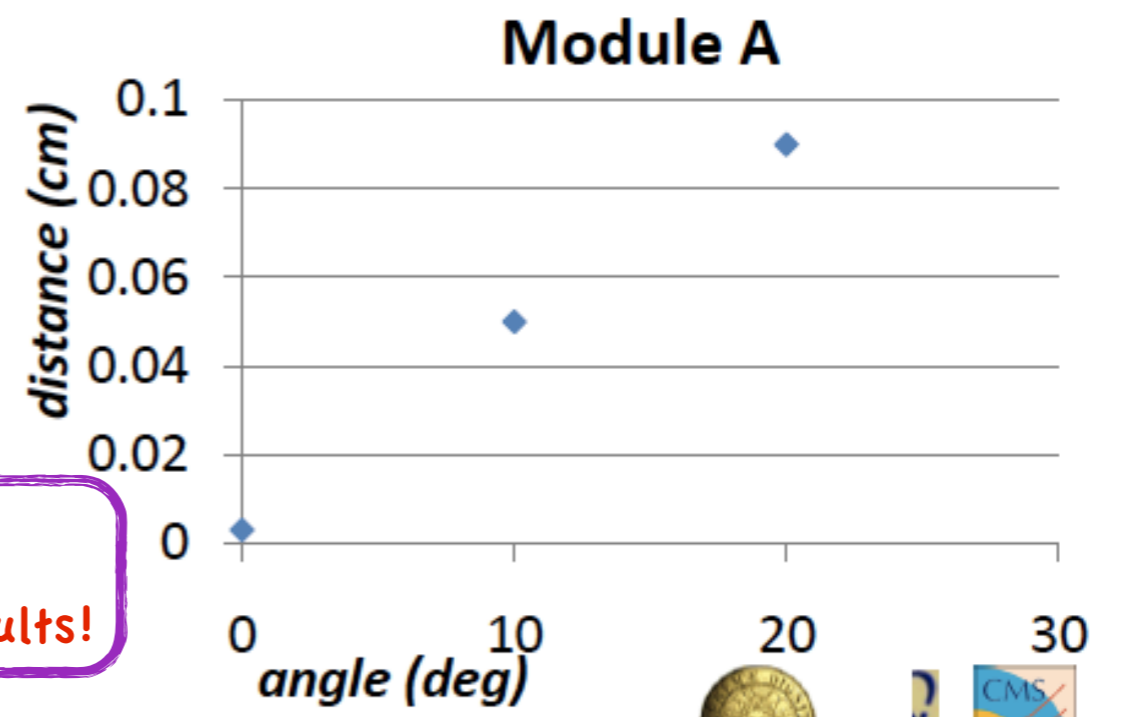
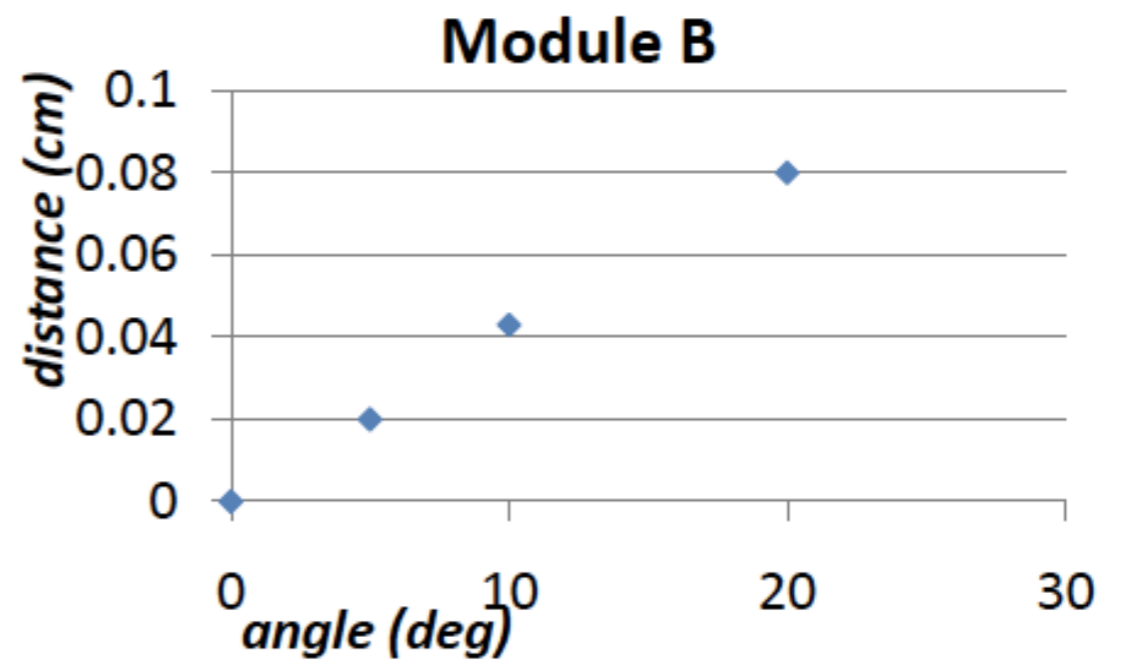
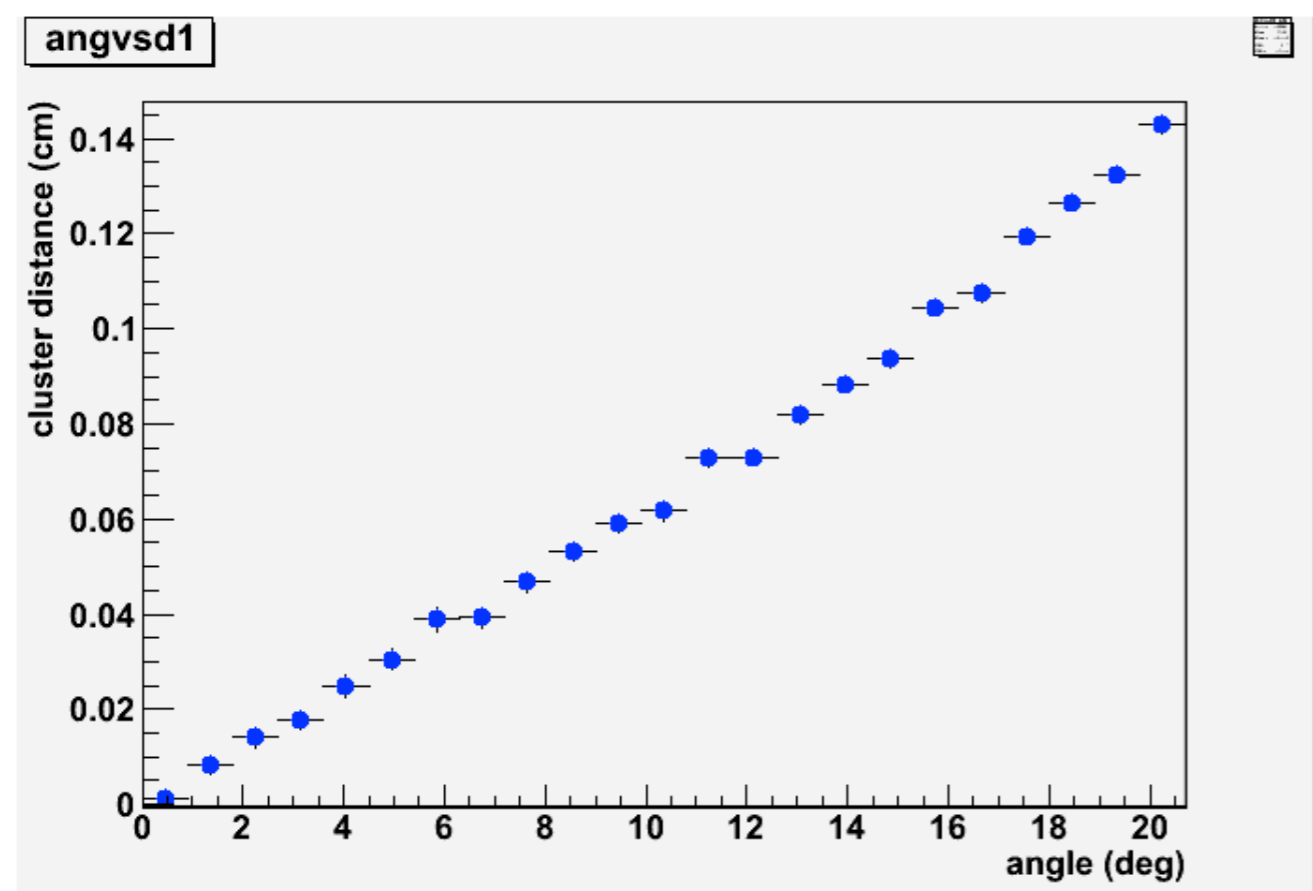


Change of local
 coordinates: $x=A-x'+By$

→ Plotting the correlation between difference of local X (i.e. pitch position in in the sensor) variables and the global Y variable retrieved by reconstructed tracks it is possible to obtain the transformation matrix to rotate and align strips of the tilted sensor

Comparison CMS\Beam

Comparison with CMS stereo module



> $\Delta R^{\text{test beam}} \sim 2 \text{ mm}$
 > $\Delta R^{\text{TOB CMS}} \sim 4 \text{ mm}$ **not directly comparable results!**

