



### NOvA Data Acquisition System TIPP 2011

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#### and the NOvA Collaboration S. Kasahara, TIPP 2011 in Chicago, IL

Jun 11, 2011

### The NOvA Collaboration



#### 140 Collaborators in 26 Institutions from 4 Countries



Argonne, Athens, Caltech, Charles, CTU Prague, Fermilab, FZU, Harvard, Indiana, Lebedev Physical Institute, Michigan State, Minnesota-Twin Cities, Minnesota-Duluth, INR Moscow, Iowa State, South Carolina, SMU, Stanford, Tennessee, Texas-Austin,Texas-Dallas, Tufts, Virginia, Wichita State, William & Mary

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# **N**uMI **O**ff-Axis $v_e$ **A**ppearance



- NOvA is a second generation neutrino oscillation experiment in the NuMI beam
- Near and Far Detectors placed 14 mrad off the beam axis
- Optimized for the detection of  $v_{\mu} \rightarrow v_{e}$  and  $\overline{v_{\mu}} \rightarrow \overline{v_{e}}$  oscillations
  - Narrow band neutrino beam. L/E ~ 400 km/GeV
  - Primary goals: Measure  $\theta_{13}$ , mass hierarchy,  $\delta_{CP}$
- DAQ systems for both detectors are functionally equivalent

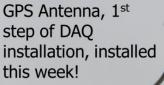


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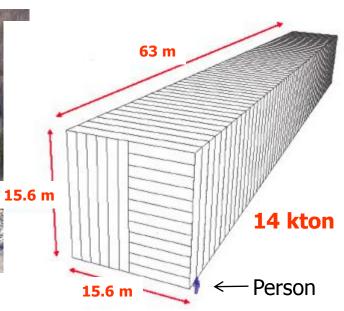


### NOvA Far Detector Ash River, MN

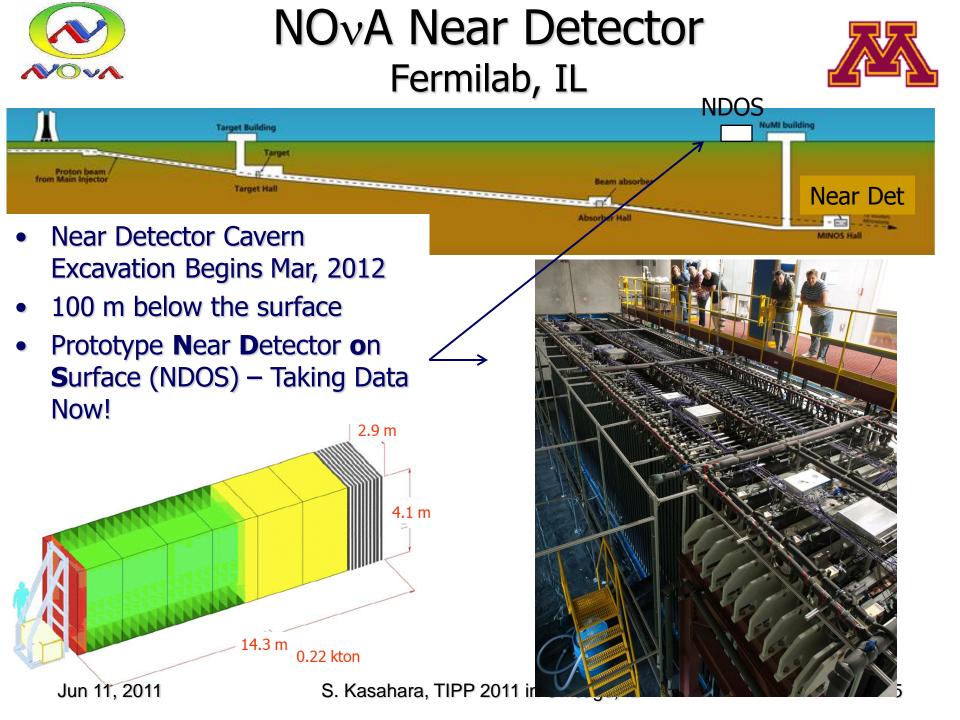








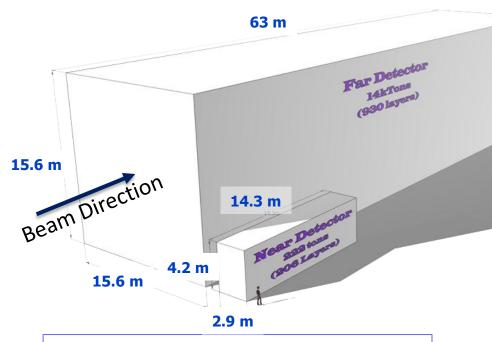
- Beneficial Occupancy of Far Detector Building – Apr, 2011
- Readout of First Detector Block
   ~ Early 2012
- Completion of Detector Assembly ~Early 2014





## NOvA Detectors Side-by-Side





#### Far Detector

- 930 Planes (15.6 m x 15.6 m)
- 360000 cells
- Cosmic Ray Muon Rate:
  - ~200 kHz (2-3 m overburden)
  - Avg Hits/muon ~200
  - Hit Rate/detector = 40 MHz
  - Hit Rate/cell = 110 Hz

#### **Near Detector**

- 196 Planes (3m x 4m)
- + 10 Steel/Scint Plane Pairs ("Muon Catcher")
- 16000 cells
- Cosmic Ray Muon Rate:
  - ~50 Hz (105 m overburden)
  - Avg Hits/muon ~50
  - Hit Rate/detector = 2.5 kHz
  - Hit Rate/cell = 0.2 Hz
- In-Spill Rate:
  - $\bullet$  10  $\mu s$  duration every 1.33 s
  - 30 neutrino events/spill
    - 100 hits/event
  - Hit Rate/cell = 20 kHz

(Instantaneous)

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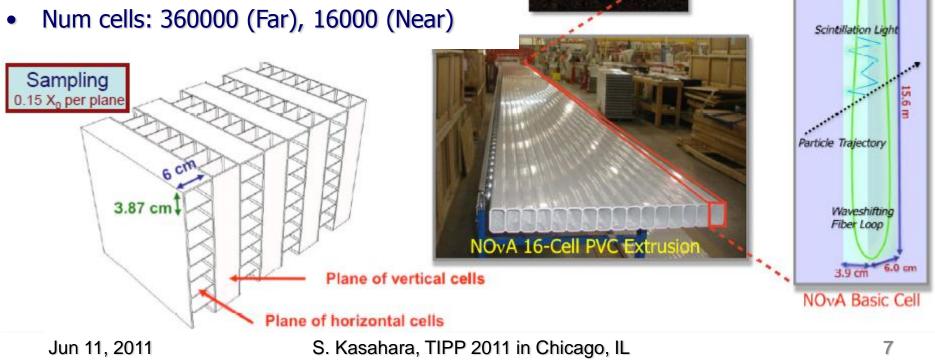


## **Detector Technology**



To APD Readout

- Detectors composed of highly reflective PVC extrusions
- Filled with liquid scintillator (mineral oil + 5% pseudocumene)
- Each cell readout by a wavelength shifting fiber onto one pixel of a 32-pixel avalanche photodiode (APD)
  - 30 PE from far end of cell into APD for MIP



32-pixel APD



### NOvA DAQ Introduction



### • Design of DAQ driven by goals of experiment:

- Beam Neutrino Events:
  - 10  $\mu$ s beam spill => 30  $\mu$ s trigger window for each spill
  - Period ~1.3 s
  - Beam Spill signal:
    - Near Det: Spill signal sent via ACNET ~200  $\mu s$  before Neutrino Beam
    - Far Det: 90-95% of Spill signals received within 1 s, ~100% within 10 s via Internet
- Calibration Events (Cosmic Rays):
  - 100x Beam Spill trigger window, randomly sampled
- Other Physics Events (not primary goal of experiment):
  - Supernova, Magnetic Monopoles, High Energy v's, ?, ...
  - SN Explosion at 10 kpc (33000 light years) results in thousands of v's within  $\mathcal{O}(10)$  seconds in Far Detector

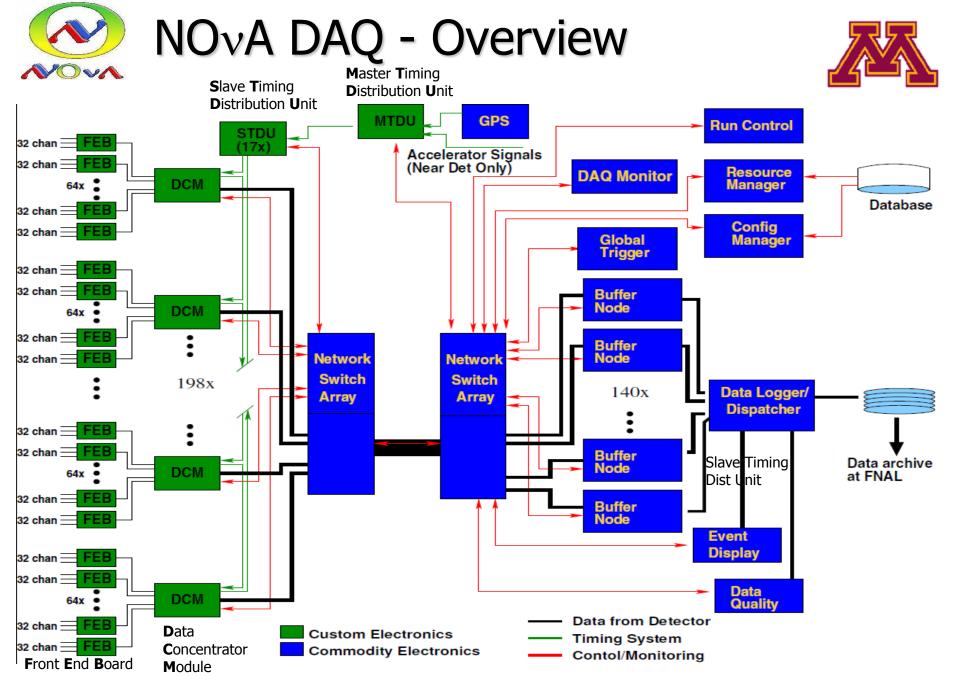


# NOvA DAQ Introduction



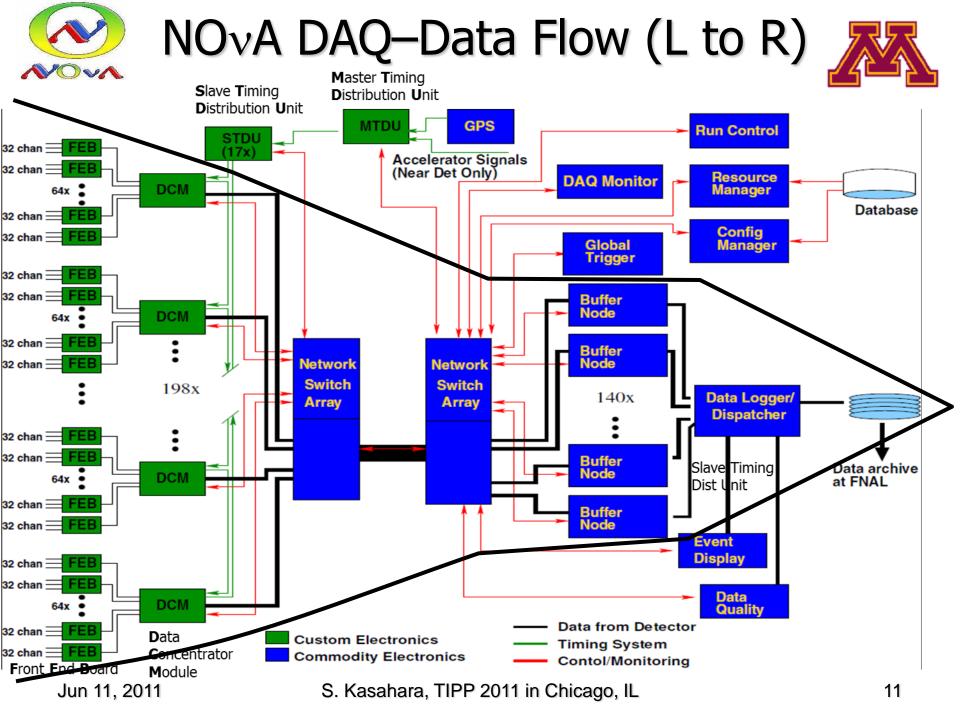
- Design goals met with a DAQ system which has:
  - Front End Electronics which read out continuously with no dead time
    - This allows selection of events to be made downstream in the DAQ Buffer Farm with software applied triggers
  - A Buffer Farm in which data can be stored for 20 seconds or more while waiting for:
    - A remote spill trigger (sent from Fermilab to the Far Detector site)
    - A decision regarding whether or not an interesting physics event has occurred (e.g. Supernova)
  - A Timing System with compensation for the large geographic area covered by the Far Detector
- DAQ Systems for both detectors are functionally equivalent
  - In the following slides, the numbers of components refer to the Far Detector =>

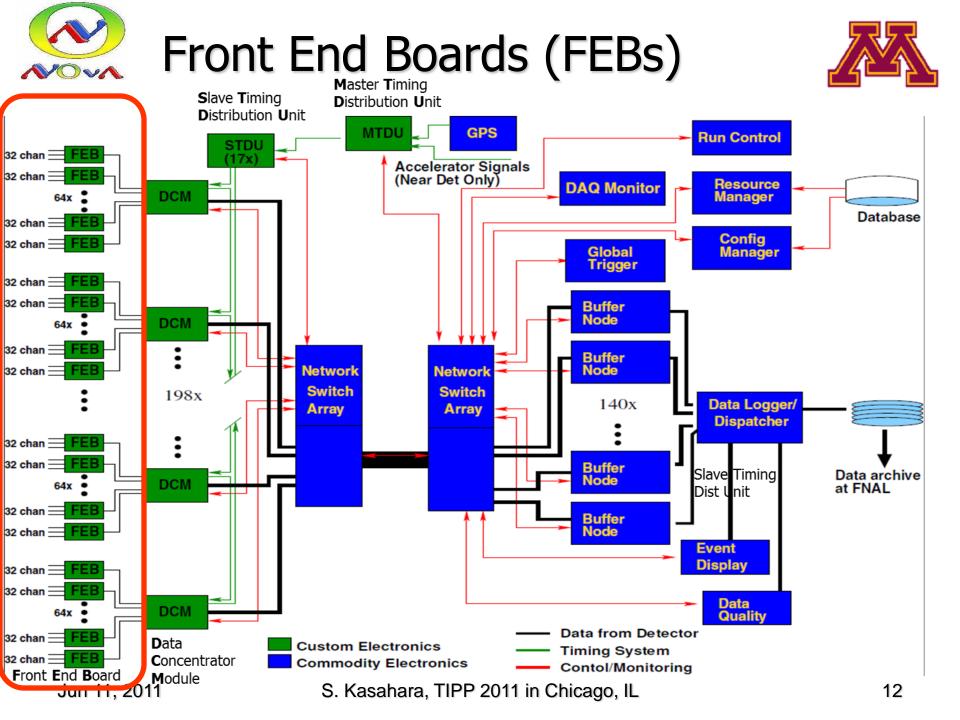
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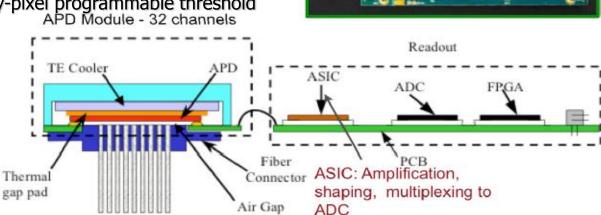






# Front End Boards (FEBs)

- APD pixels sampled at 2 MHz by Front End Boards at Far Det, 8 MHz at Near Det
  - Higher detector activity during beam spill at Near Det requires higher time resolution
- FEB operated in triggerless, continuous readout mode with no dead time
- Signal recognition/zero suppression done in real time by FPGA
  - Data compared to a pixel-by-pixel programmable threshold APD Module - 32 channels



#### Avalanche Photo Diodes:

- 85% Quantum Efficiency
- Gain~100
- cooled to -15C for 2PE dark noise

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- Response :
- ~30 photo-electrons from MIP at far end of cell (10-12 MeV of deposition in the scint)
- 4 PE in total noise => Light yield gives a minimum Sig/Noise
- S. k 10:1 (far end)



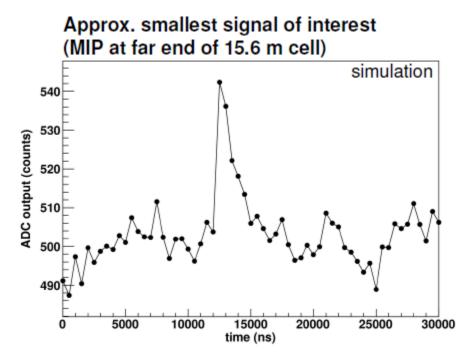




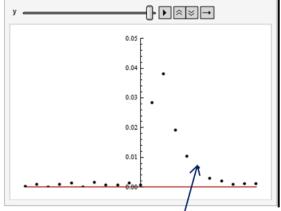
### Front End Boards (FEBs)



- FEB FPGA uses Digital Signal Processing (DSP) to extract pulse height and timing edge
- Timing resolution better than digitization rate using fit of signal to ideal response to interpolate true pulse leading edge
  - Both "Matched Filtering" and "Dual Correlated Sampling" DSP algorithms have been explored.
    - Dual Correlated Sampling in use at Prototype Near Detector

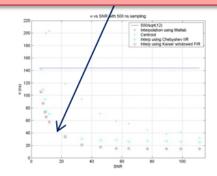


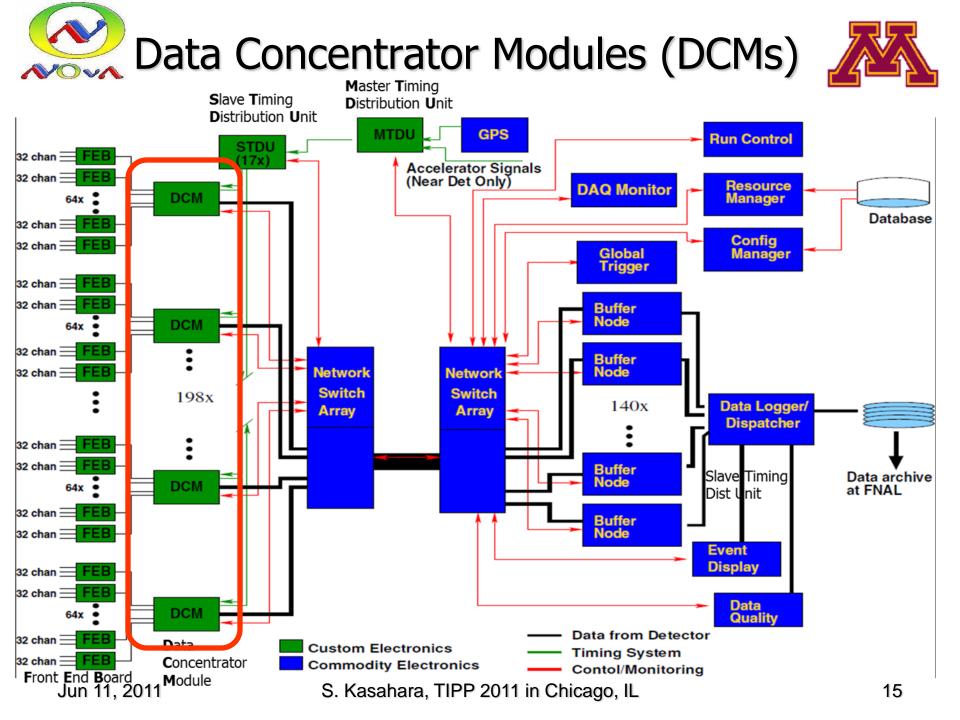




Raw data is matched to ideal response function in the FPGA, to extract pulse height and timing edge.

Timing resolution is a function of Sig/Noise (10:1 min) giving a timing resolution of < 30ns



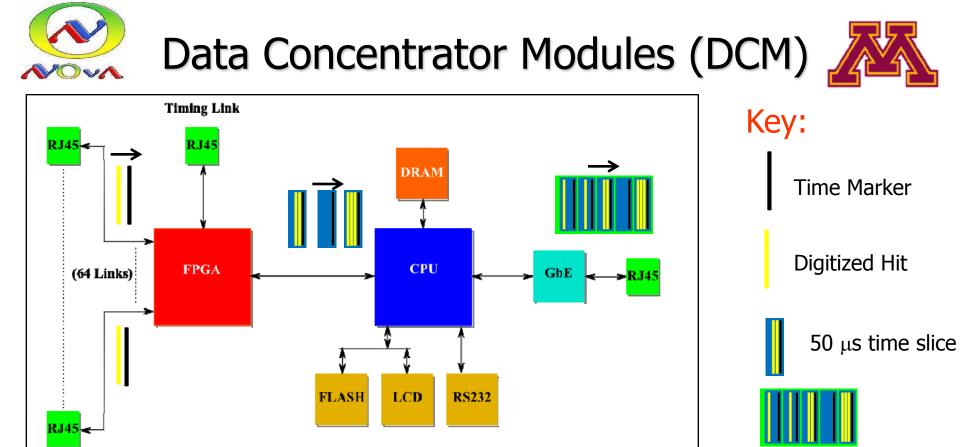


# Data Concentrator Modules (DCMs)

- DCMs attach to racks on sides and top of detector
- One DCM reads out up to 64 FEBs; each of which reads out 32 APD pixels
- Purpose:
  - Consolidate hit data from FEBs into 5 ms time slice optimal for data transfer to downstream Buffer Nodes
  - Program, configure, and monitor FEBs
  - Pass Timing System clock, sync to FEBs



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#### 5 ms time slice

#### • Data Flow is left to right

Data

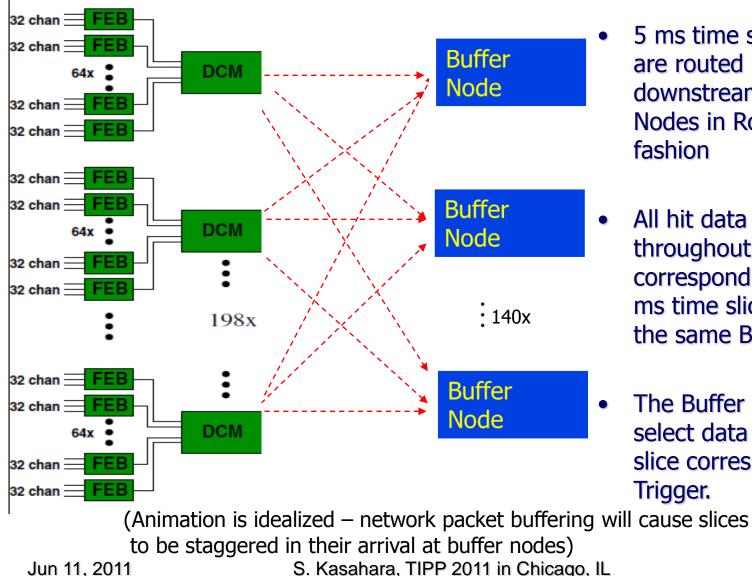
Clock -

- FEB FPGA produces timing markers at periodic intervals (50  $\mu$ s) interspersed with digitized hits

**NOvA Data Concentrator Module Block Diagram** 

- The digitized hits are consolidated by the DCM FPGA to 50  $\mu s$  time slices containing data from all 64 FEBs
- An application running on the DCM PowerPC CPU consolidates this data further to a longer time slice (5 ms) and routes this time slice to downstream buffer node for further processing.
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# Data Concentrator Modules (DCMs)



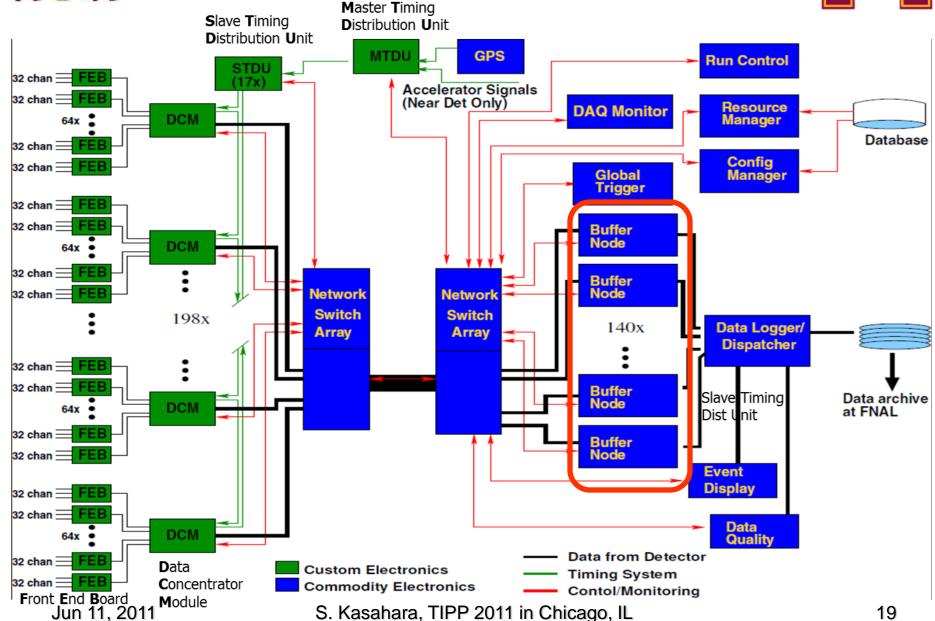
- 5 ms time slices of data are routed by the DCM to downstream Buffer Nodes in Round Robin fashion
- All hit data from throughout the detector corresponding to one 5 ms time slice is routed to the same Buffer Node.
- The Buffer Node will select data from this time slice corresponding to a Trigger.

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### **Buffer Nodes**



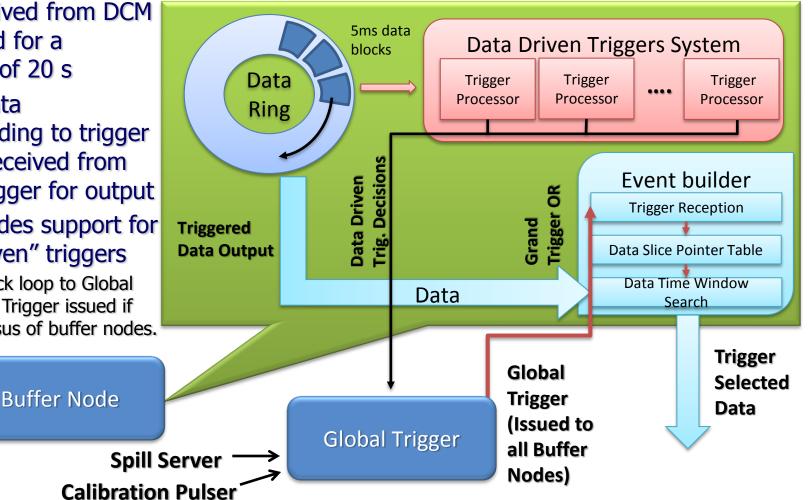




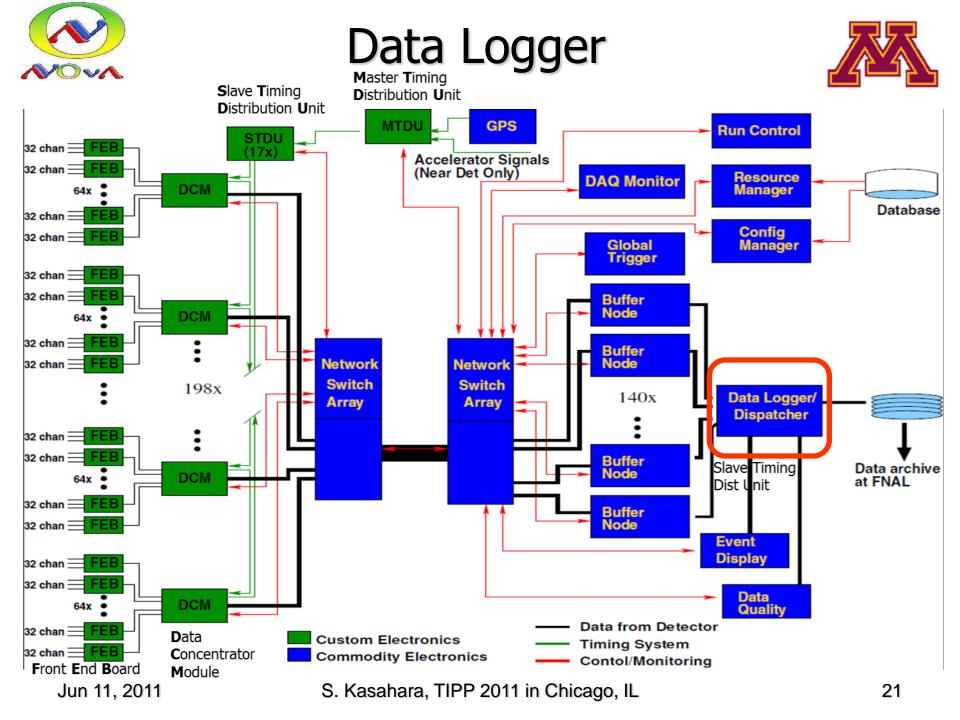
## **Buffer Nodes & Trigger**

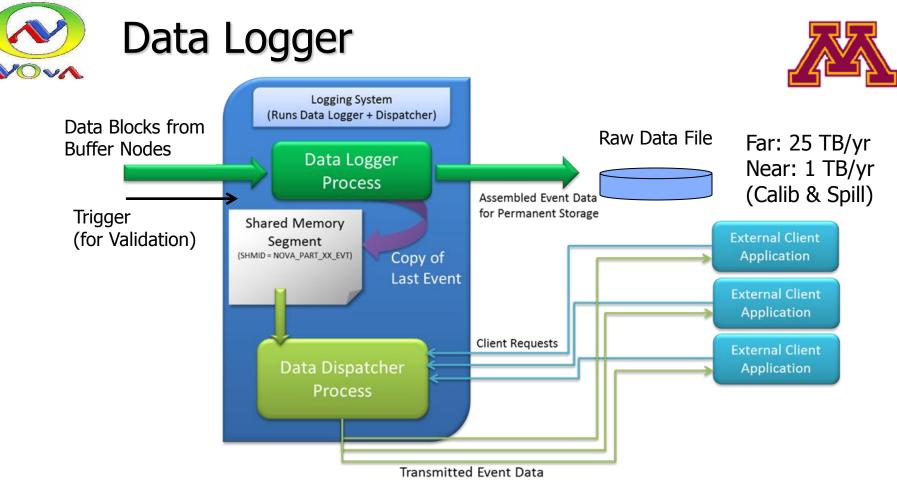


- A Buffer Node is a commodity server
- Data received from DCM is buffered for a minimum of 20 s
- Selects data corresponding to trigger window received from Global Trigger for output
- Also provides support for "Data Driven" triggers
  - Feedback loop to Global Trigger. Trigger issued if consensus of buffer nodes.



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- Single Data Logger is a commodity server
- Data Blocks received from Buffer Nodes are merged to form Event
- Events written to file. Archived to FNAL mass storage via separate File Transfer system.
- Events also written to shared memory for Dispatch to quasi-online consumers such as Online Monitoring and Online Event Display.
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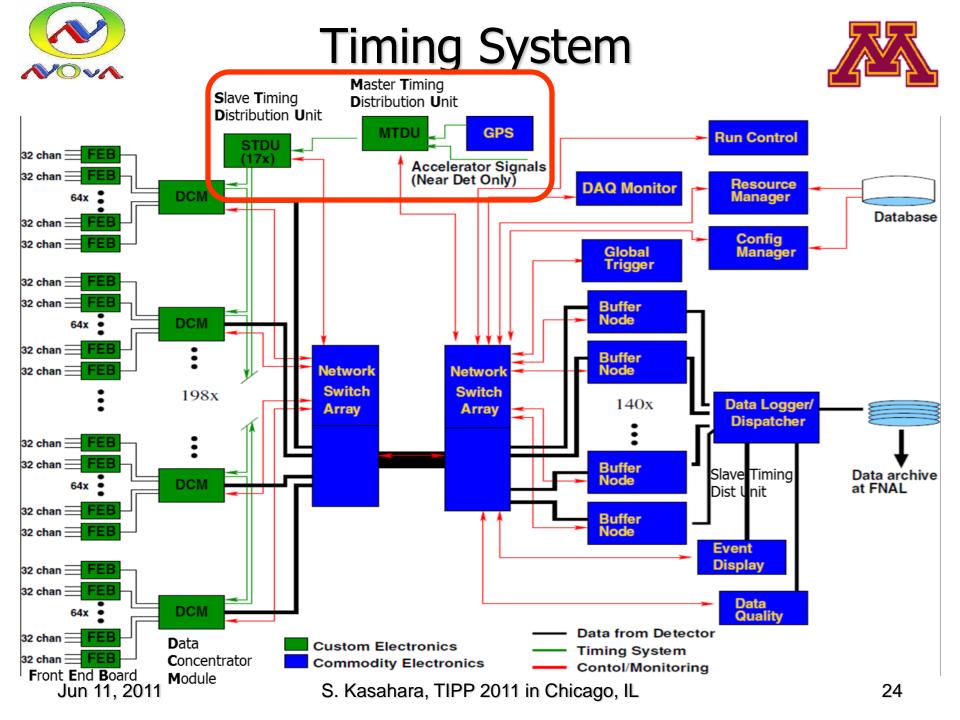


### **Expected Data Rates**



	Near		Far	
	Data Rate/ Component (kB/s)	Number	Data Rate/ Component (kB/s)	Number
FEB	120	500	160	11250
DCM	250	9	3000	180
Buffer Node In/ Out*	300/ 4	8	3800/ 8	140
Data Logger	30	1	1100	1

\*Buffer Node Output rates consider Beam Spill + Calibration Triggers only





### Timing System



- All FEBs/DCMs are sync'ed to a common high precision 16 MHz clock reference
- Clock distributed to DCMs by Slave Timing Distribution Units (STDUs) daisy-chained along backbone of detector
  - Two outputs per STDU supply clocks to two groups of 6 daisy-chained DCMs
- Master Timing Distribution Unit (MTDU) derives clock from GPS, distributes to first STDU in chain
- g Distribution derives clock tributes to first
  - Signal regenerated at each step in chain.

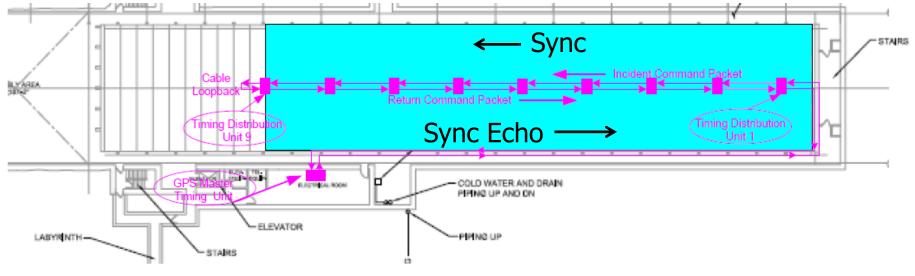
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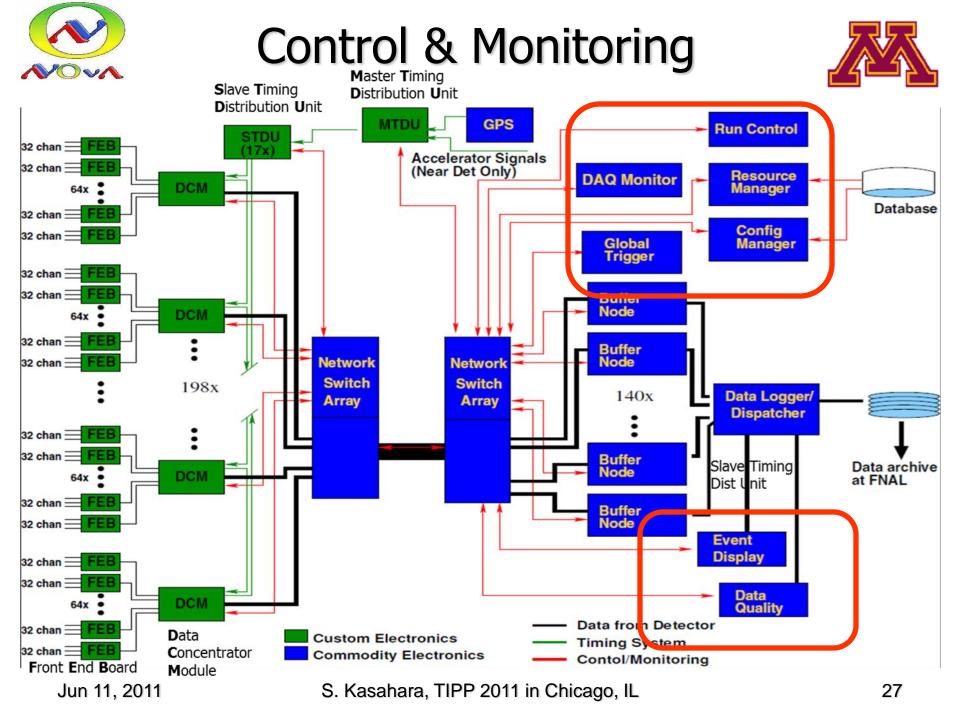




- TDUs have 4 differential pairs for communication: Sync, Command, Clock, and Sync Echo
- STDUs have "Delay Learn" feature to compensate for cable length propagation delays using TOF/2 method
  - When in Learn mode, each STDU will start a timer on next Sync that will run until it receives a Sync Echo
  - This time can be used to self-correct for propagation delays => synchronization within +/- <sup>1</sup>/<sub>2</sub> clock cycle



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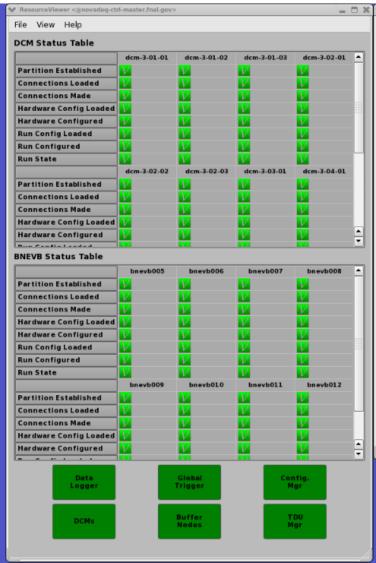




### Run Control

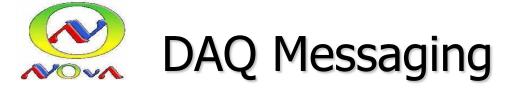


- Provides overall control of the DAQ system.
- All DAQ components implement a well defined state model and, under the command of Run Control, make transitions between states.
  - Implemented as client/server model
  - Written in C++ using QT tools to implement GUI

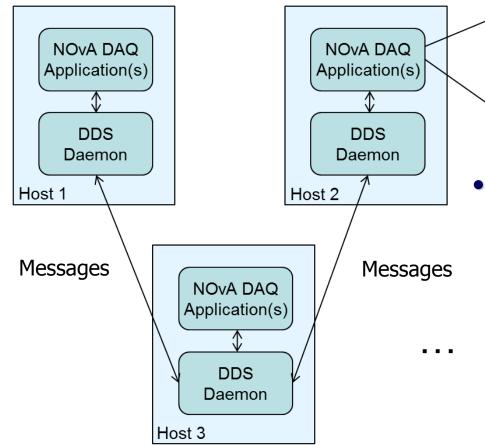


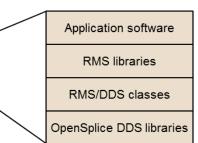


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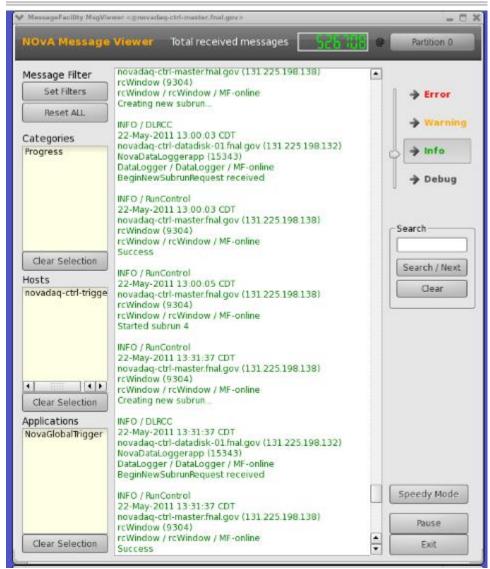
- Message Passing System handles control & status messages
  - Uses OpenSplice DDS from Prism Tech for low level message transmission
  - NOvA specific layers provide ease-ofuse
  - Publish/subscribe methodology
  - Supports 14 kHz message rate as measured at NDOS Prototype Detector
    - This is ~10x that needed for Near Detector
    - Will optimize towards preferred goal of ~2x faster for Far Detector



# Message Facility



- Message Facility for logging Messages
  - Based on CMS Message Logger
- Capable of logging messages to multiple destinations
  - std out, file and/or msg server
  - Uses DDS for sending client messages to msg server
- GUI display for server
  - Allows server-side filtering
  - Used in control room
- Additional package "Message Analyzer" monitors messages to gauge overall detector health
  - Prototype version implemented at NDOS







- Uses Ganglia Monitoring System at its base
  - Ganglia daemons gmetad and gmond collect and distribute metrics
- NOvA specific classes allow client applications to submit custom metrics

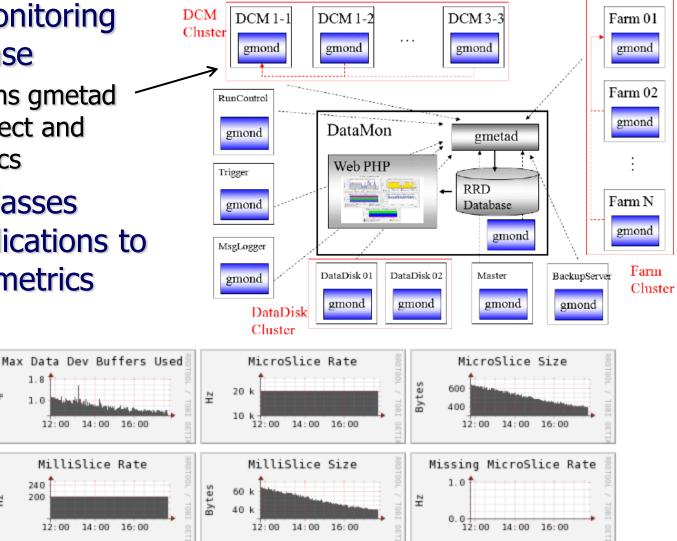
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Data Dev Buffers Used

12:00 14:00 16:00

MicroSlice Size StDev

12:00 14:00 16:00



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300 m

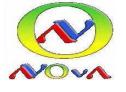
280 m

260 n

200

100

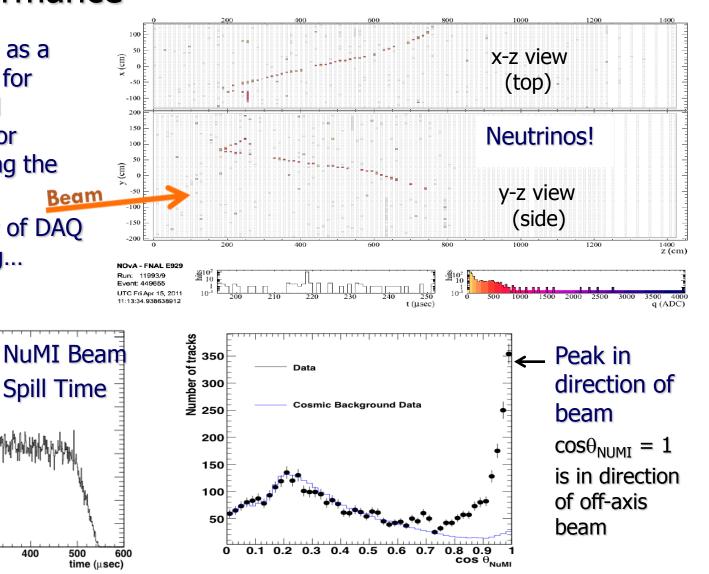
Bytes



### **NDOS Prototype Detector** Performance



- NDOS has served as a valuable test bed for commissioning all aspects of detector operation including the DAQ Beam
- Core functionality of DAQ system is working...



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n

100

200

300

400

5

250

150

100

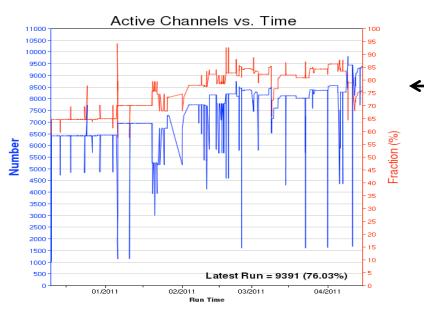
50

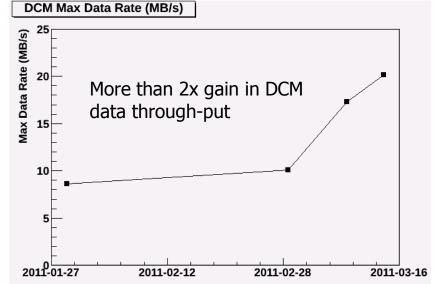
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### NDOS Prototype Detector Performance

- Many performance gains and fixes of bugs have been made as a result of commissioning the Prototype Near Detector
  - This plot shows the through-put gain of the DCM as a result of optimizing software & network usage





- Number of active channels, live time, quality of data continue to improve over time
  - Number: instrumented channels
  - Fraction: fraction of instrumented channels enabled

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- Much of the DAQ system has been implemented and deployed to the NOvA prototype detector (NDOS)
- Now shifting effort towards work to do before deploying at NOvA Far Detector:
  - Automatic Error Recovery
  - Scaling GUIs/Displays for larger number of nodes
  - Stress testing system for Rate capacity (underway)
  - Partition support (operate different sections of detector in different run modes)
  - Learn Delay mechanism of Timing System
  - Data Driven Trigger Support in Buffer Node
  - , etc..

### • Thank you for your time!





### **Backup Slides**

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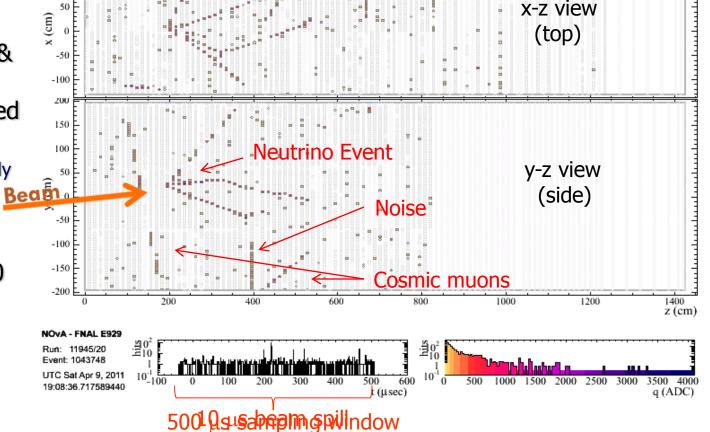
NDOS Prototype Detector Data

200

100



- 500 µs window
   for both Beam &
   Calibration
   Triggers sampled
   at about 15 Hz
  - Beam spills only  $\sim 10 \ \mu s \ \text{long}$
  - Click to see Animation =>
- Will use only 30 µs window at Near and Far Detectors
- Time slicing distinguishes events



600

800

1000



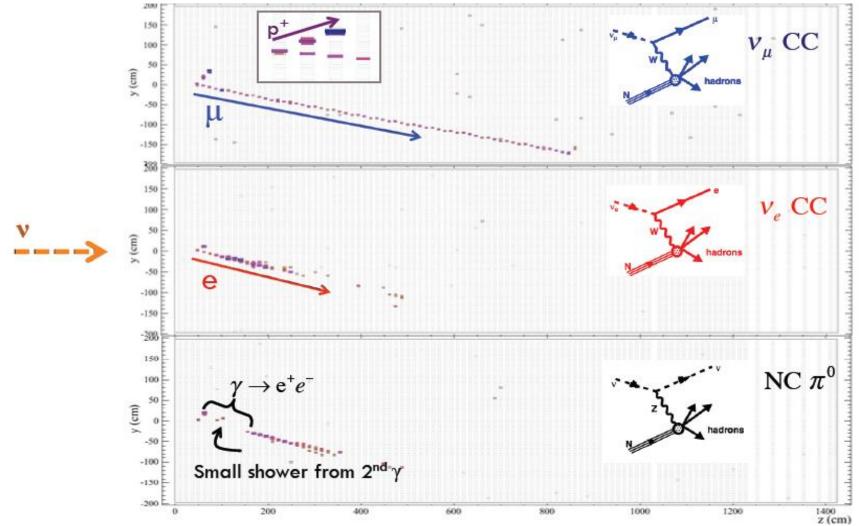
1400

1200



### Neutrino Events in NOvA Simulated

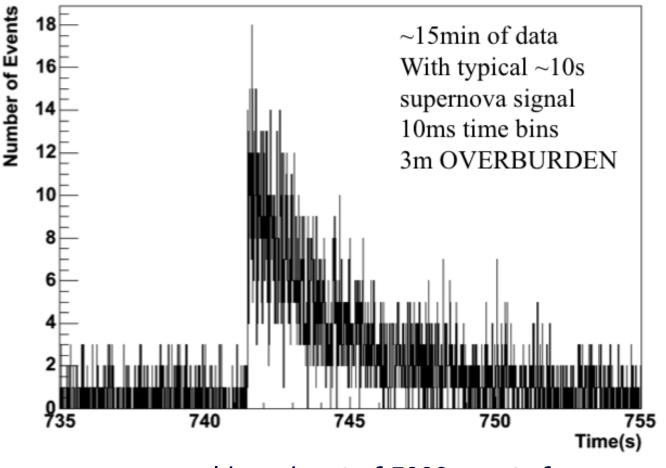






## Galactic Supernova Signal





NOvA would see burst of 5000 events for a supernova at the center of the galaxy

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