



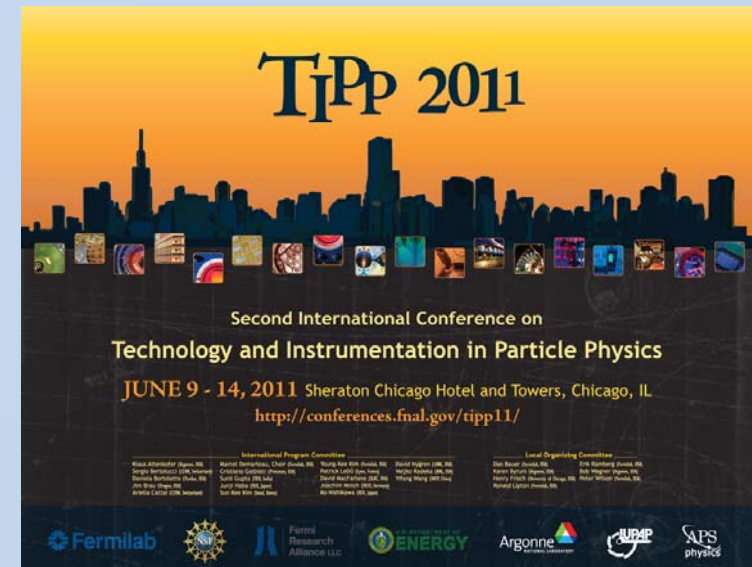
Design of the ATLAS IBL Readout System



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Outline:

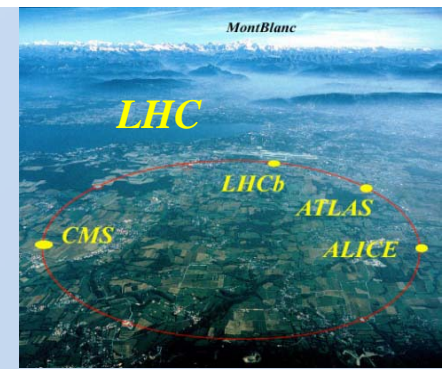
- Detector Introduction
- Architecture Description
- Comparison to the Present Pixel System
- Test, Readout and Calibration Procedures
- Roadmap, Status and Outlook



1) INFN Bologna
2) CERN
3) Fachbereich C Physik, Bergische Universitaet Wuppertal
4) University of Bologna

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6) LNBL, Berkeley, U.S.A
7) ZITI, LS Informatik V, Heidelberg University, Mannheim
8) INFN Genova

The ATLAS Detector



Barrel region

25 meters diameter

Endcap region

Endcap region

44 meters length

ATLAS Insertable B-Layer

Atlas Pixel Detector

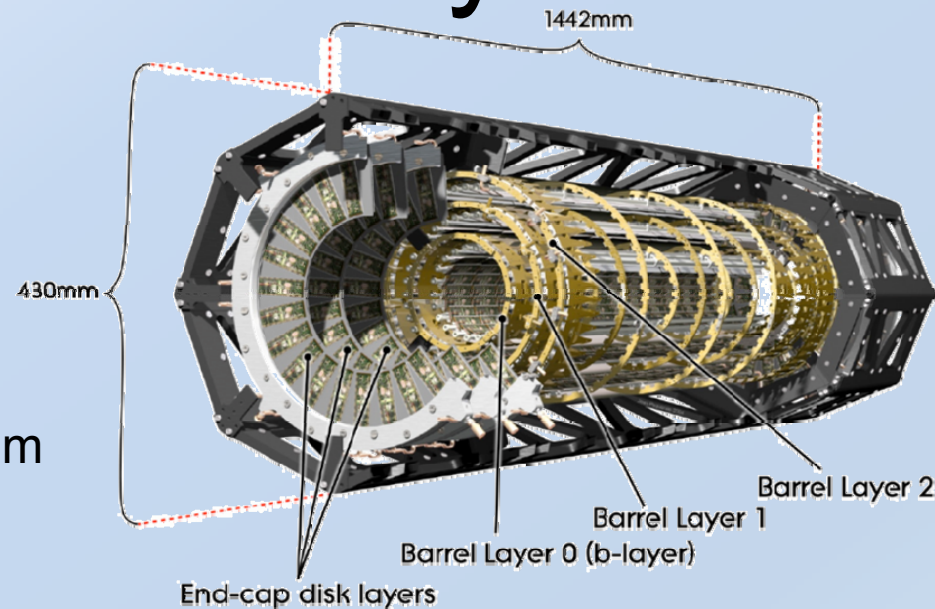
- The innermost detector with
- 3 tracking points up to $|\eta| < 2.5$ layers barrel and 3+3 disks
- 1744 modules with 46080 pixel $50 \times 400 \mu\text{m}^2$
- 80 millions channels total.
- 16.9 KW cooled via an evaporative C_3F_8 system

IBL:

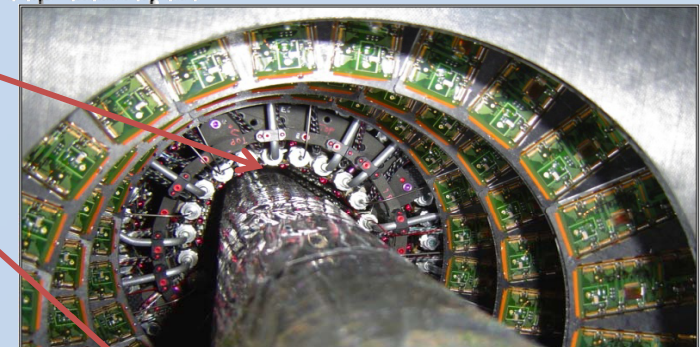
- Add a fourth innermost layer
 - New smaller Beryllium Beampipe
 - Old Pixel detector kept in till Phase 2

Time schedule

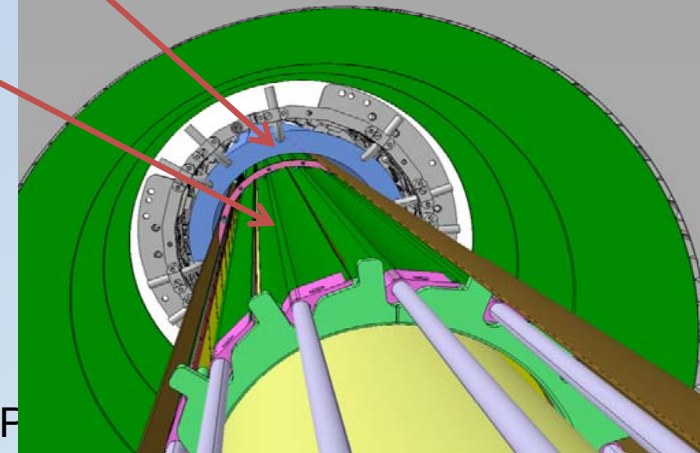
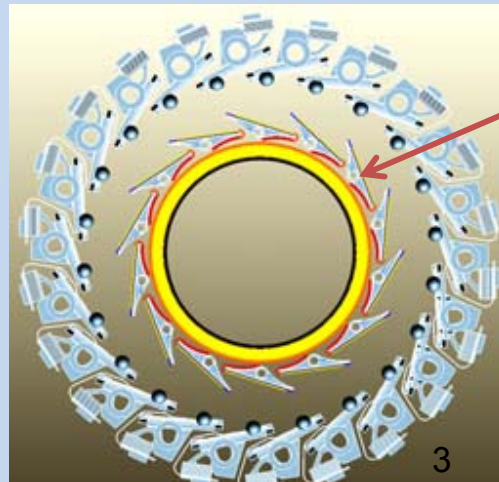
- 2015-17 → moved to the shutdown in 2013-14 !!!



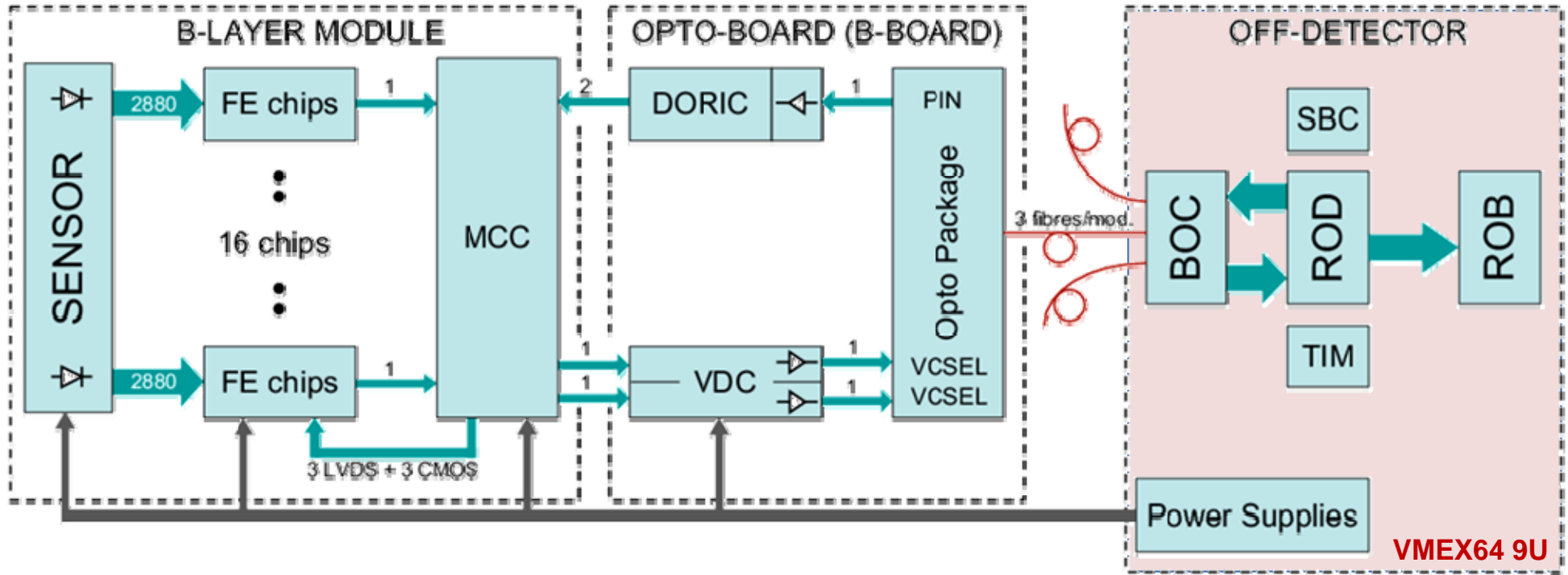
Existing B-Layer



New IBL



Pixel Readout Scheme

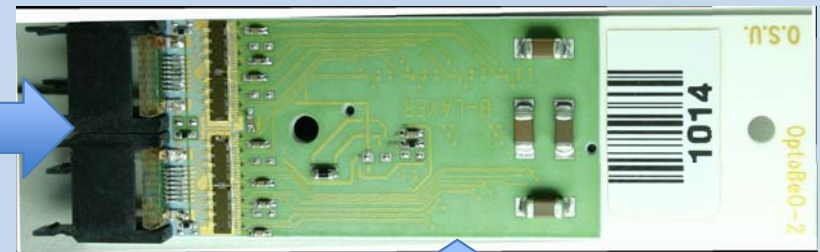


- Each module has 16 FE-chips and 1 module controller chip
- Data transferred to and from modules via 80m optical link
 - 1 downlink per module, 1 uplink for L1, L2, Discs, 2 uplinks for B-Layer
- Each VCSEL array services 6 or 7 modules (both on-detector and off-detector)
- Readout System **VMEx64**:
 - **Back of Crate (BOC) + Readout Driver (ROD)**

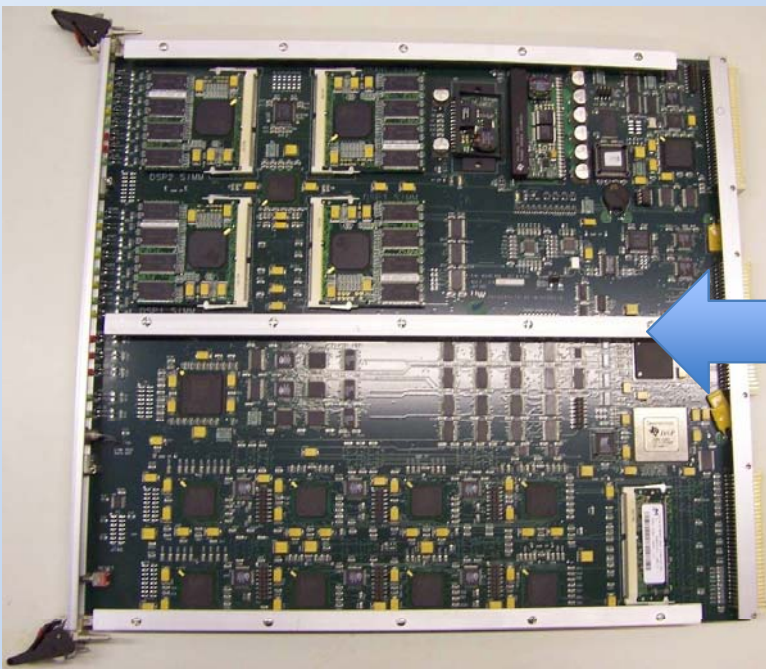
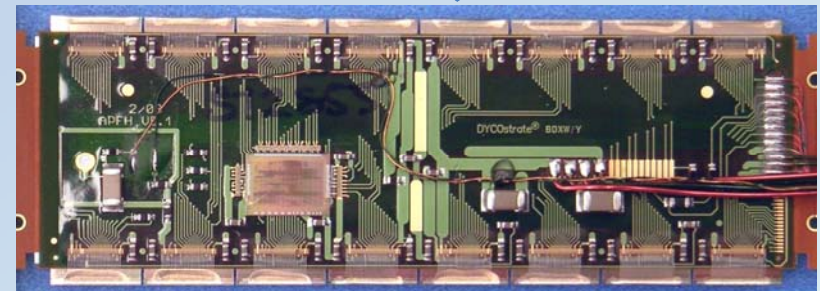
Present Pixel ReadOut

- FE Modules can send data with 40(L2), 80(L1, Disk) or 2x80 Mbit/s(B)
- 4 LVDS connections to Module: Clock, Data In, 2 x Data Out
- OptoBoard services 6/7 modules, converts electrical to optical
- BackOfCrate card encodes clock/data, decodes in 40Mbit/s streams
- ROD with **4 + 1 Digital Signal Processors (4GFlops) and 1GB RAM**

Optoboard



Module



ROD



BOC

New Frontend Chip (FE-I3 → FE-I4)

The smaller radius of the IBL and potential luminosity increase results in higher hit rate

FE-I3 (present pixel detector)

- Column drain architecture saturated
- Total inefficiency would be very high for IBL (>90%) assuming Phase I upgrade of the LHC

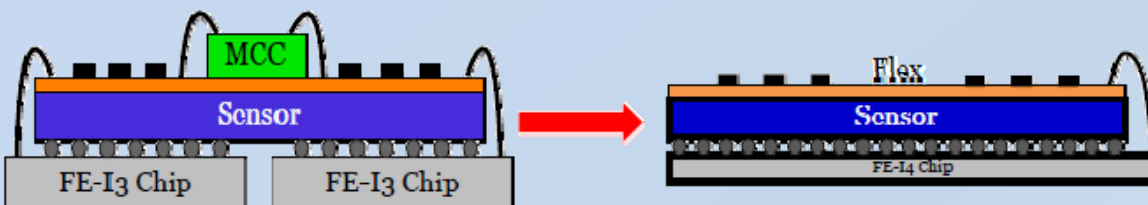
FE-I4 (IBL)

- New digital architecture with local column buffer
- Smaller pixel size
- Thinner chip with reduced inactive surface
- 160 Mbit/s + 10b/8b data encoding

IBL

- 14 staves; each with 16 x 2 chips.

	FE-I3	FE-I4
Pixel Size [μm^2]	50x400	50x250
Pixel Array	18x160	80x336
Chip Size [mm^2]	7.6 x10.8	20.2 x 19.0
Active Fraction	74%	89%
Analog Current [$\mu\text{A}/\text{pix}$]	26	10
Digital Current [$\mu\text{A}/\text{pix}$]	17	10
Analog Voltage [V]	1.6	1.5
Digital Voltage [V]	2	1.2
Pseudo-LVDS [Mb/s]	40	160



New (IBL) Readout

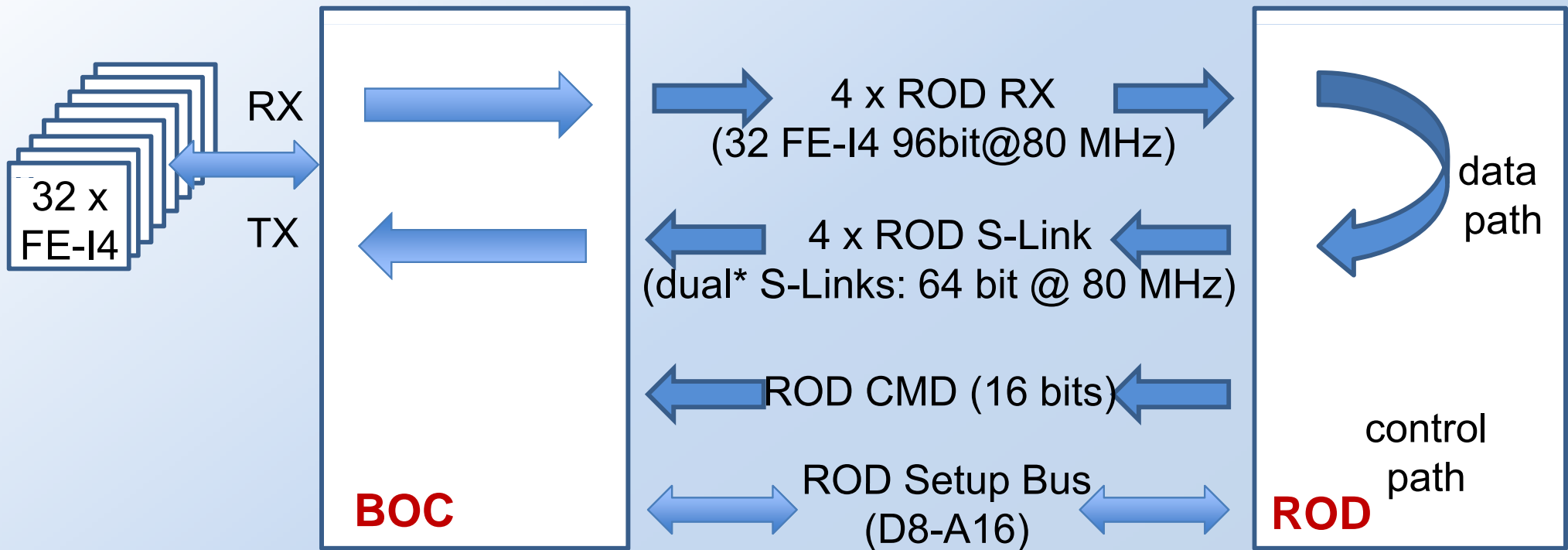
Motivation:

- New front-end chip: Higher data bandwidth + 10bit/8bit encoding
- Limited Spares + components obsolescence
- VME bandwidth limit for monitoring and calibration procedures
- Newer components/technologies available

Goal:

- Keep concept (architecture + integration in ATLAS, TTC) etc:
→ IBL will run as part of Pixel Detector within ATLAS
- **Develop new BOC + ROD**
- Use up-to-date technologies and components improving integration and bandwidth
- 1 Master DSP + 4 Slave DSP (old ROD) → FPGA Virtex + PPC core
- ✓ Only one simulation environment needed
- ✓ Move most of the time consuming processing outside on external PC farm exploiting commodity hardware (PCs) and/or GPU
- ✓ Advantage in software maintainability (same environment as for offline software)

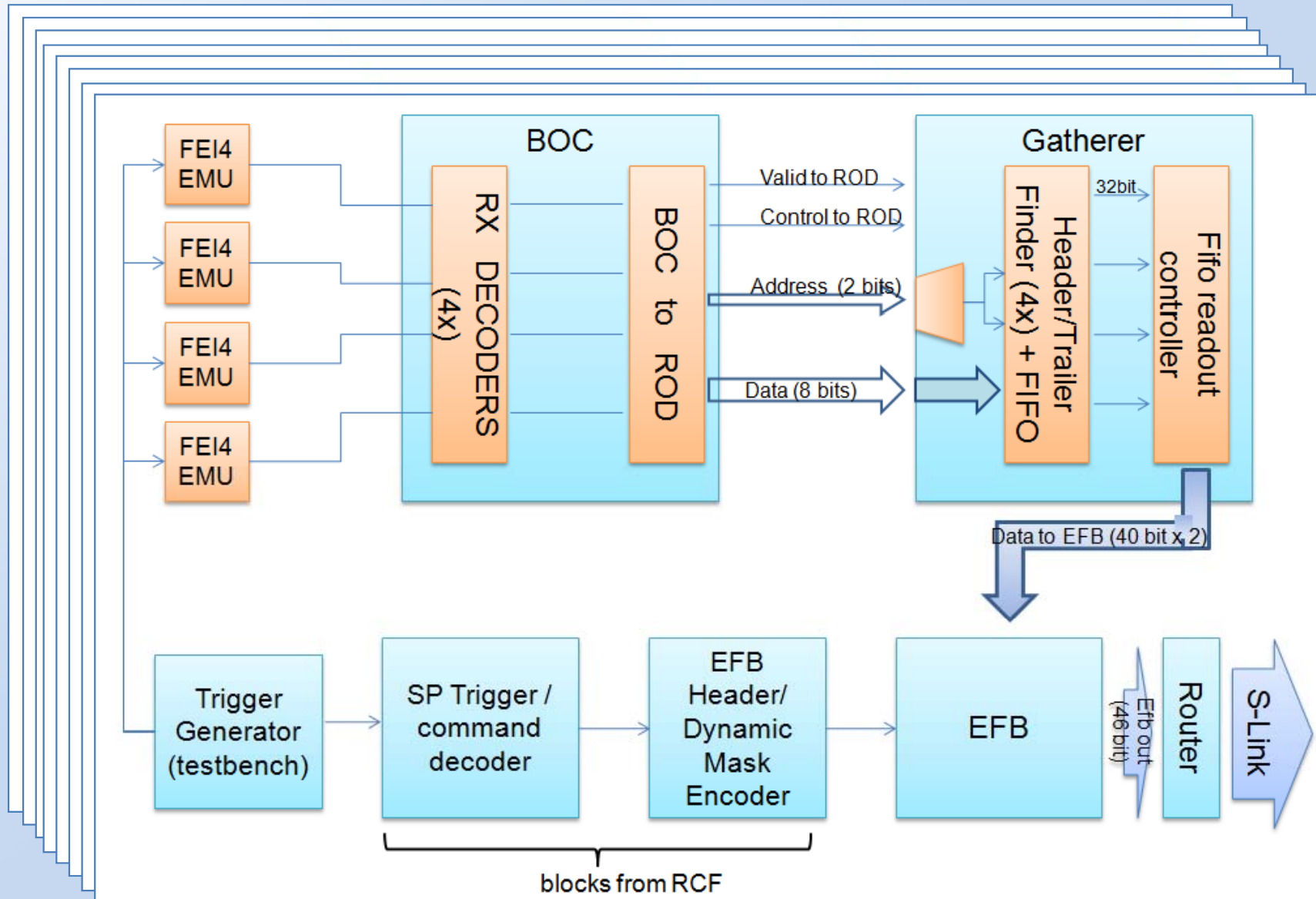
BOC-ROD Intercommunication



New vs Old System

- 4-fold integration (1 crate, 14 RODs for the full IBL system) keeping the same ATLAS environment (Trigger Timing Control and VME Single Board Computers)
- 4 Slave DSP + Master DSP → Embedded PowerPC (in Virtex 5 FPGA)
 - homogeneous simulation environment (Master DPS still available)
 - New external GB links for external Calibration farm and programming
- Common off the shelf products (calibration farm, Tx Rx plugins)
- Backward compatibility (new ROD/BOC can be used for old Strip and Pixel det.)
- BOC ROD SSTL-3 or CMOS communication
- *Duplicated S-Link Output for existing DAQ (ROS) + FTK (Fast Tracking upgrade)

BOC-ROD Block Diagram



- Simulation of full chain
- Final system: One BOC-ROD pair: 8 of the above slices

FE Chip Calibration

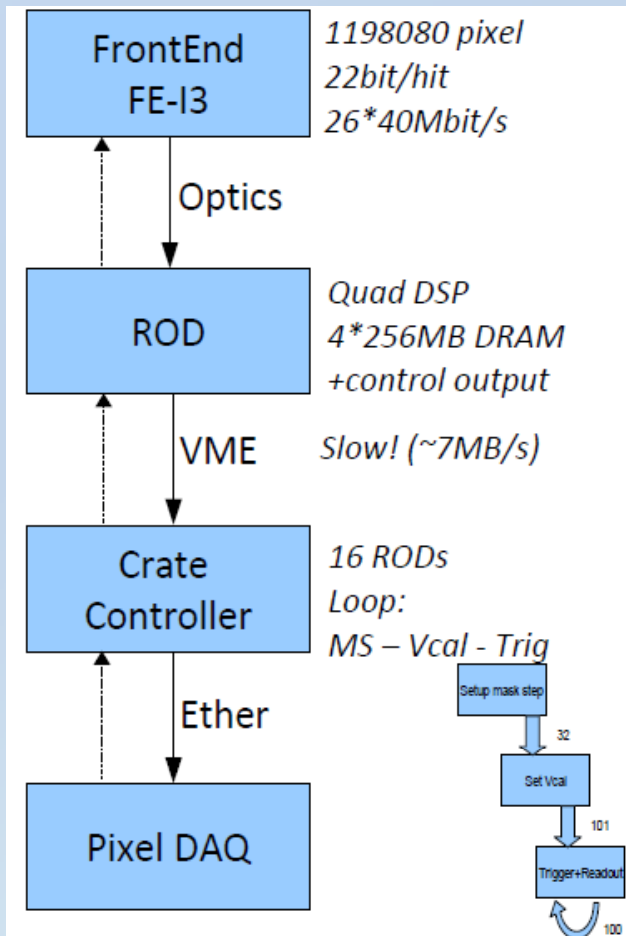
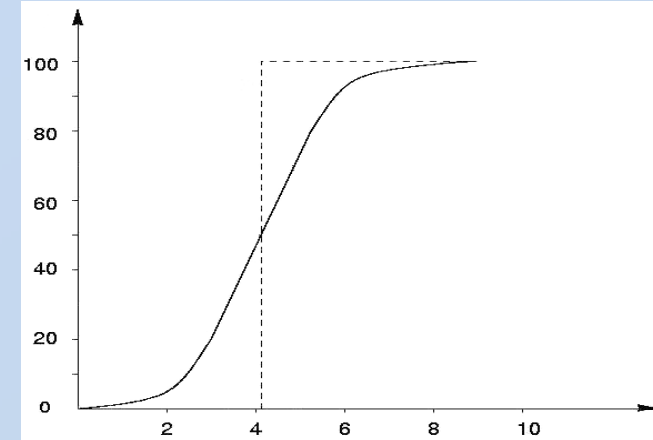
- The analog part of the read-out electronics on the FE chips allows to adjust the threshold and the feedback current of the pixel read-out circuits to create homogeneous behavior
- For calibration well defined charges are injected into the preamplifier of each circuit and the comparator response is measured, this is repeatedly done for different charge values
- Measurement results are collected in histograms and analyzed

Present System:

- ~10 minutes for one scan of 100 Vcal/Triggers
- Bandwidth Limitations (VME, fitting procedure)
- Occupancy, Time over threshold, $(ToT)^2$

New System:

- Faster control and data transmission to/from FE-I4
- Collect partial histograms on FPGA (for selected scans)
- Accumulate OCC, optional ToT and ToT^2 data per Vcal step
- No DSP use
- fast interface (GE) to DAQ + execute fit on remote processing unit, PC and/or GPU
- Improved flexibility for code development, more convenient tools compared to DSP environment



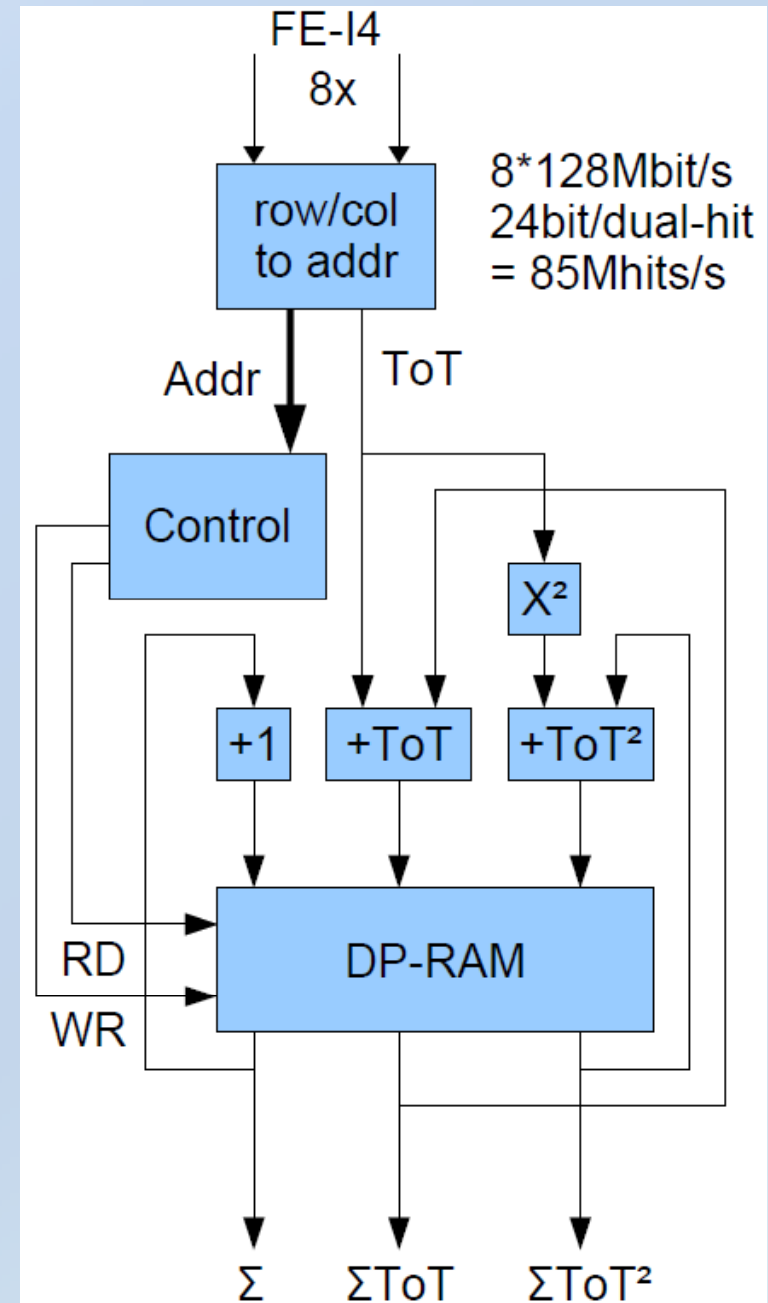
Histogramming on FPGA

Full simulation of histogramming on FPGA

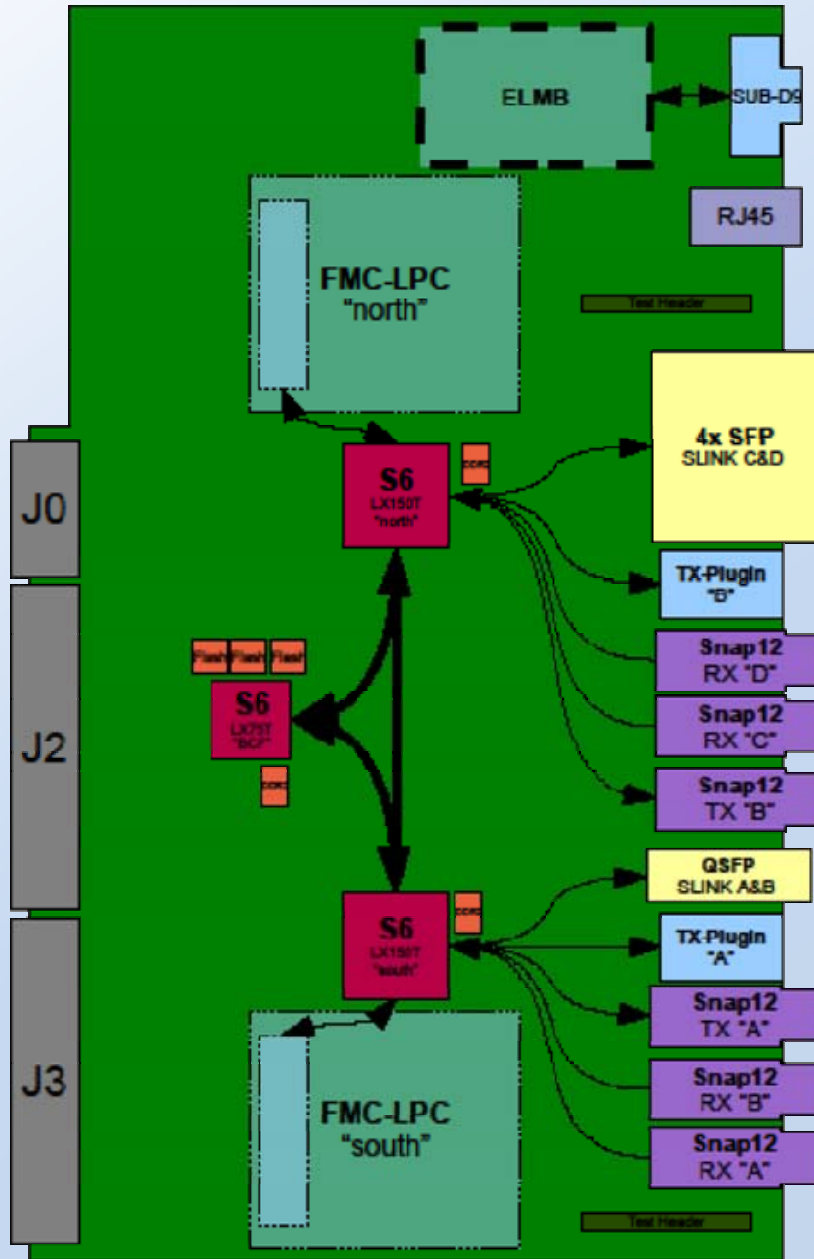
- Convert 24 bit FE-I4 format to direct addresses
- Pipelined update of Occupancy, ToT and ToT² sums
- RAM init during setup and readout
- 32k pixel on Spartan6-LX150T
 - DSP48A1s: 1%, 1 out of 180
 - BRAMs: 32%, 86 out of 268
 - slices: 1%, 191 out of 23,038
 - 100MHz operation
 - FE-I4: 2 units/FPGA & slower or 8 mask steps
- Readout after each Vcal step to GE/PCI

Histogramming

- Feasible on FPGAs with very little resource consumption (except for BRAM)
- Histogramming yields good data reduction, thus validating data transfer and analysis on remote processing units
- A lot of potential to accelerate the analysis by optimization of the code

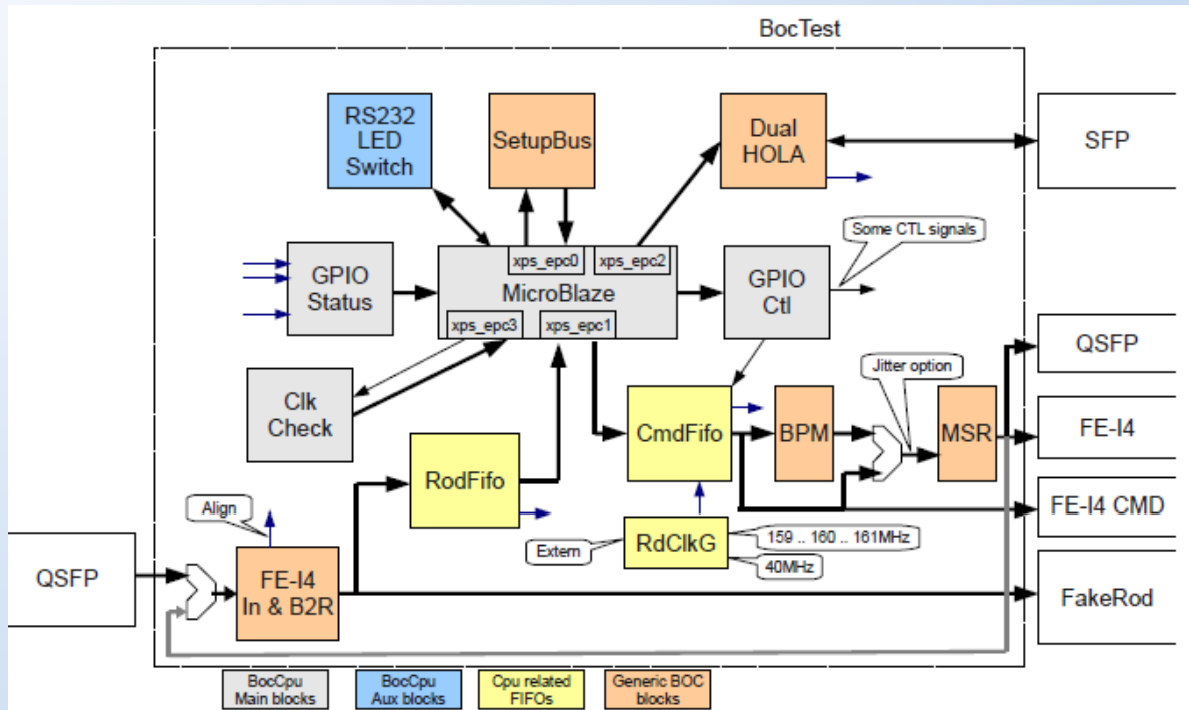


BOC Design

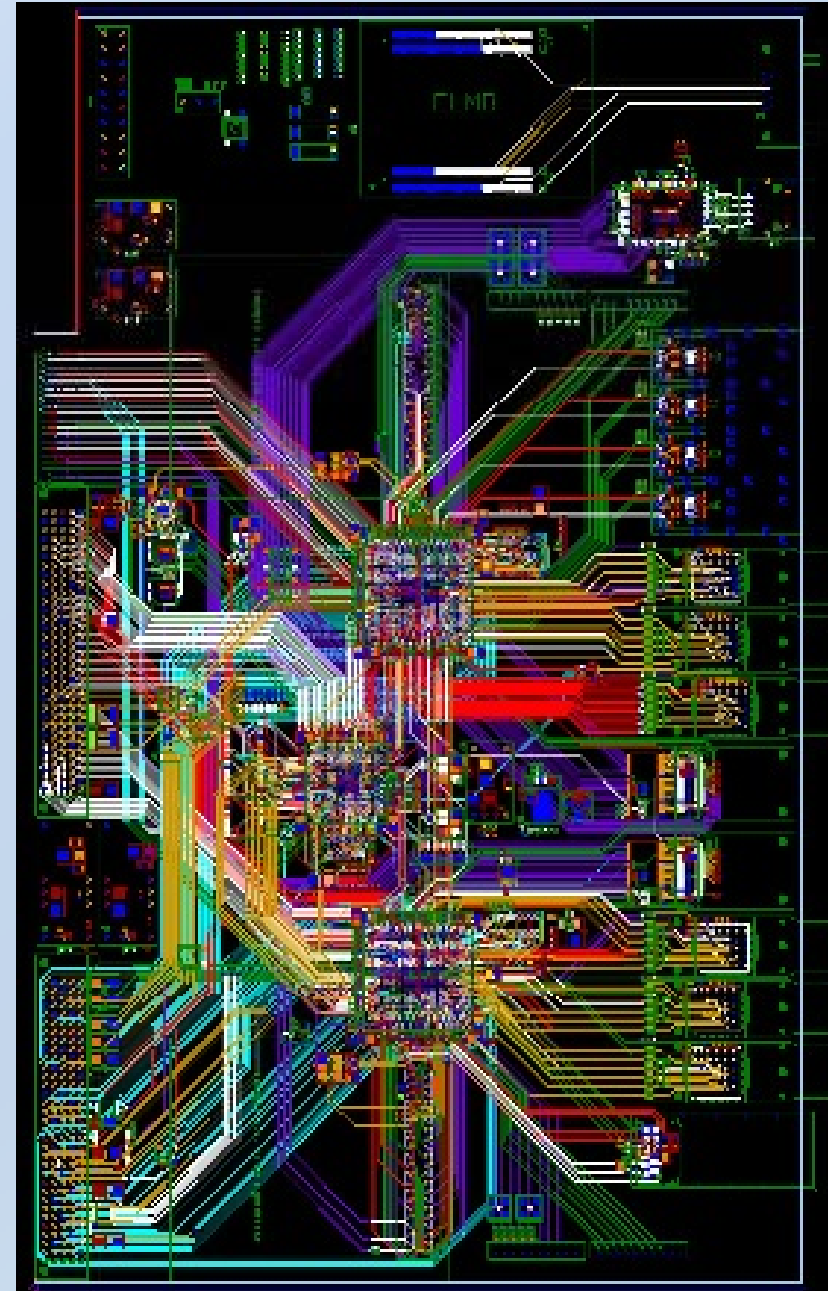


- Segmented into two functionally equivalent sections called "north" & "south"
- The heart/brain of each section is a Spartan6 LX150T device (BPM, synch)
- Receiving data from the FE via two Snap12 RX modules
- Configuration data is sent to the FE either by a Snap12 TX module or a TX plugin like the ones used on the current BOC
- The SLINK connection to the ROS is established either via a QSFP or four SFP transceivers (Small Form-factor Pluggable)
- For testing & debugging a *low pin count FPGA mezzanine connector* (LPC FMC), SE/diff pin header, SMA connectors and GPIO LEDs are available
- Configuration of the two Spartan6 devices is handled by a third Spartan 6 (LX75T), the Board Control FPGA (BCF)
- FLASH memory for configuration data
- MicroBlaze soft processor core
- DDR2 memory
- GbE interface, CAN (ELMB)

BOC Status



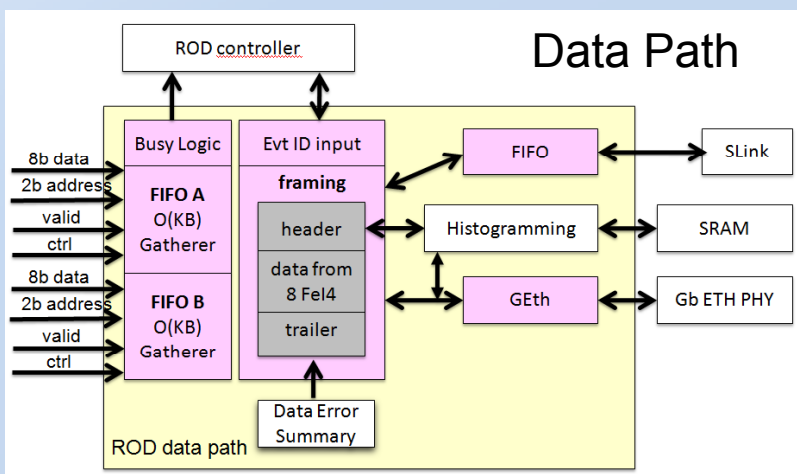
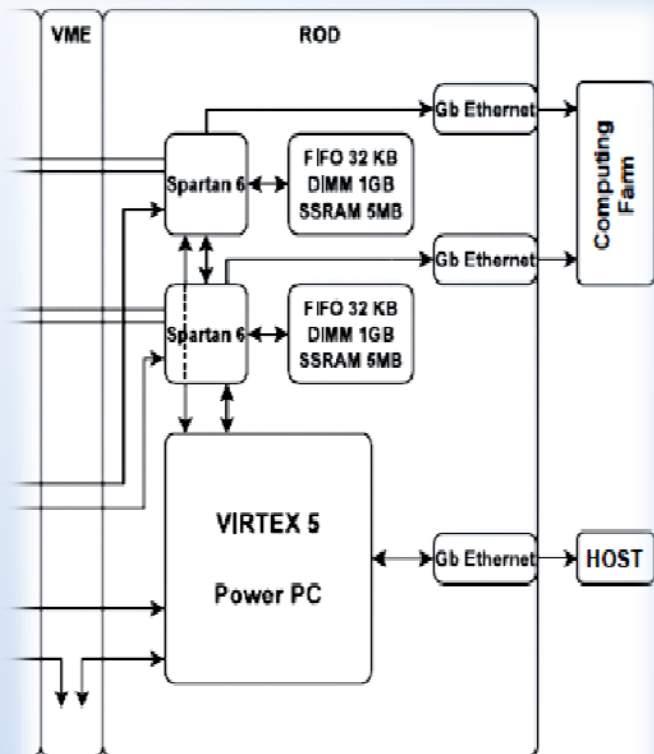
- BOC demonstrator:
 - based on the **XILINX SP605 evaluation card**
 - All Firmware blocks loaded and simulated
- Prototype layout is almost complete
 - PCB production will start in June



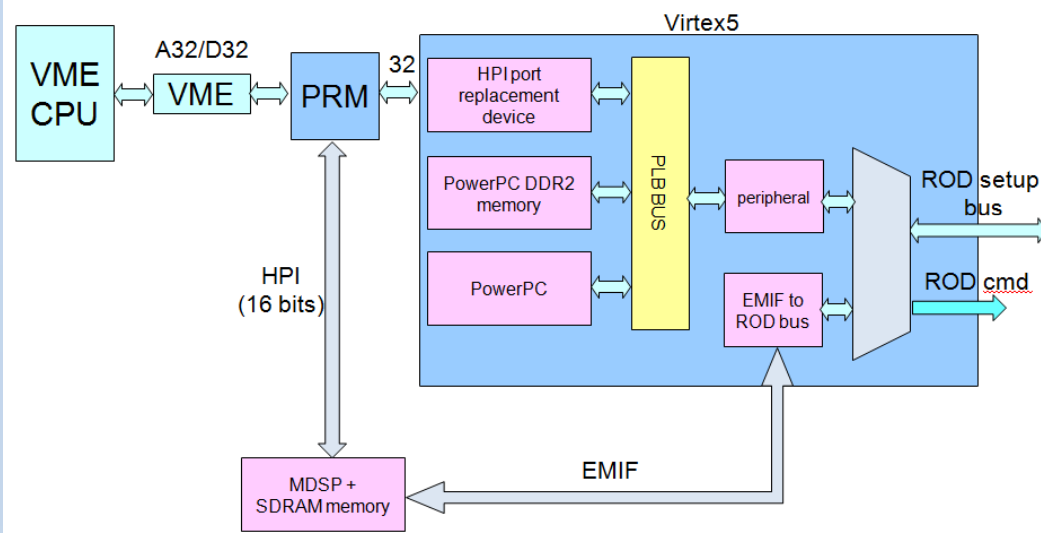
ROD Design

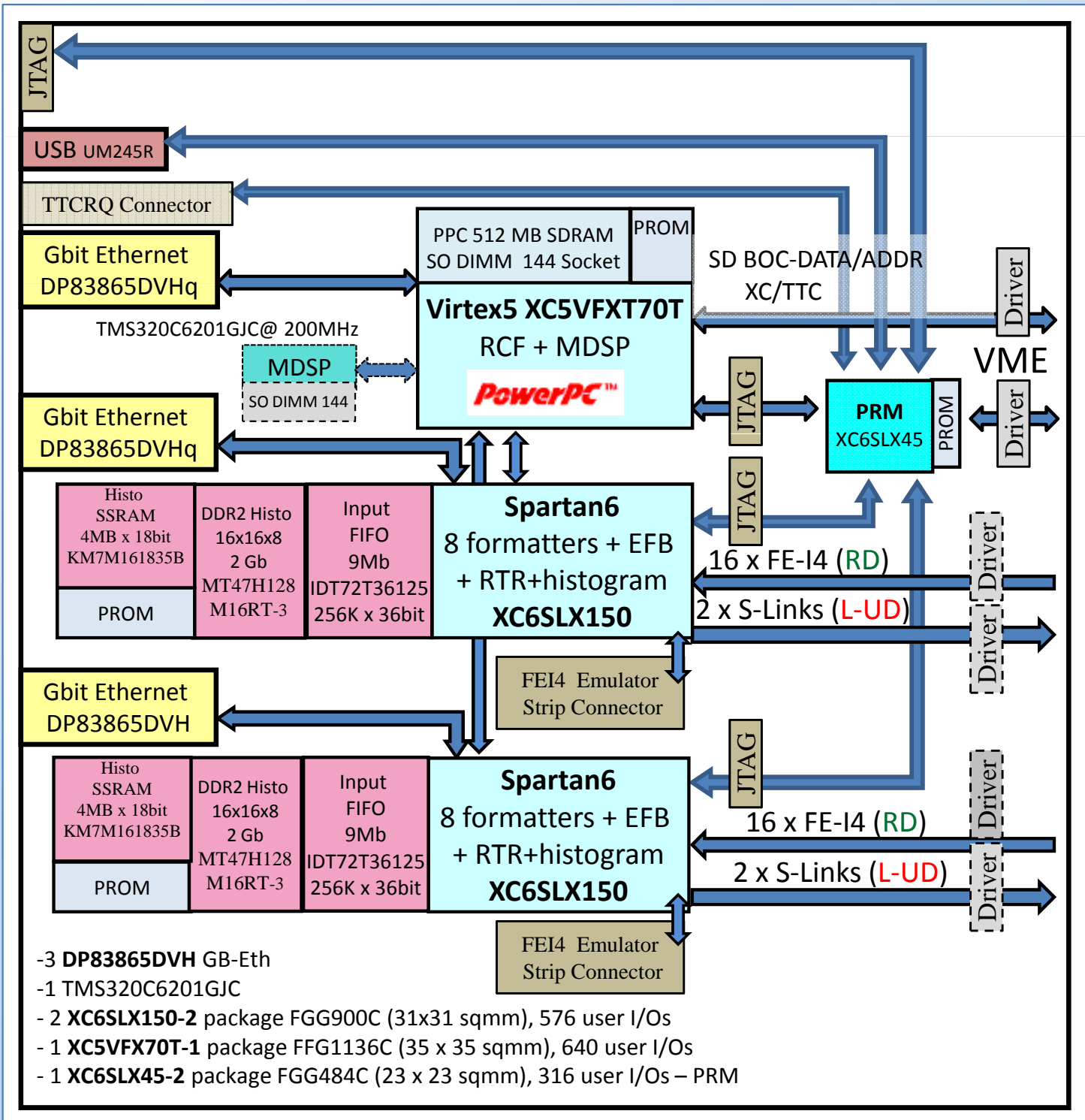
Versatile design:

- Control via VME or GB Ethernet
- Possibility of use w/o VME crate (TTC input, extern
- Avoid the use of DSPs
- Move the task of 4 slave DSP to off ROD processing
- Master DSP or Embedded PPC (Virtex 5)
- External data processing (for calibration)
- Backward compatibility with FE-I3 old DAQ chain
- Conceptually software running on the VME CPU would require minimal modifications

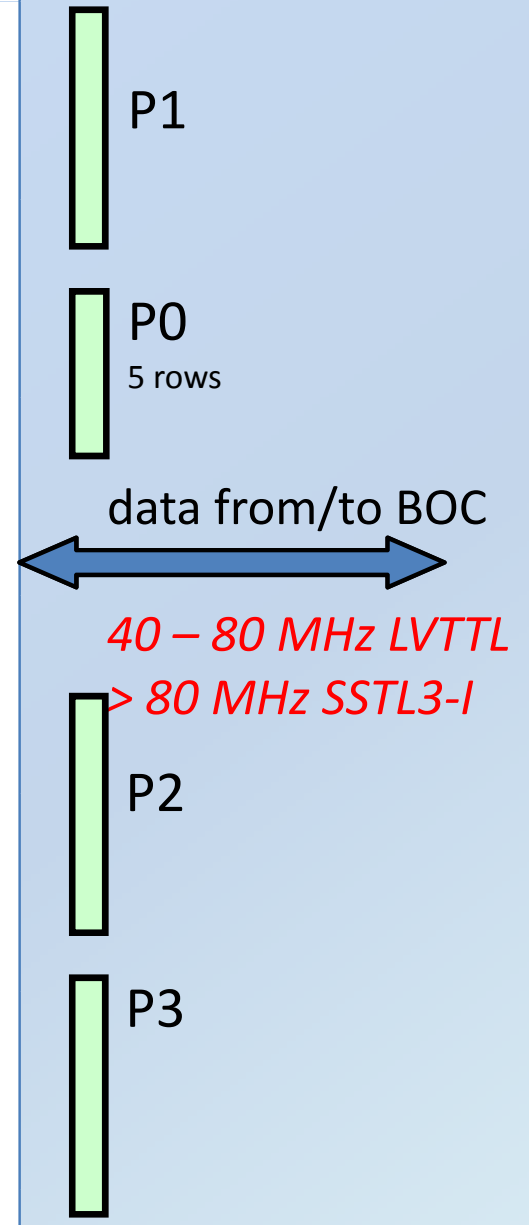


Control Path





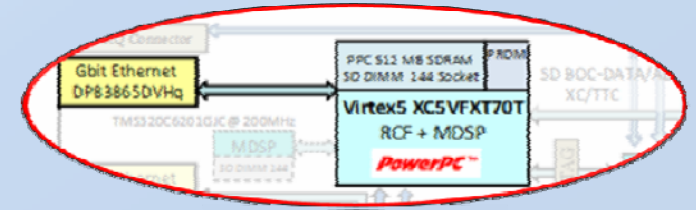
New ROD Block Schematics



PowerPC-based Control

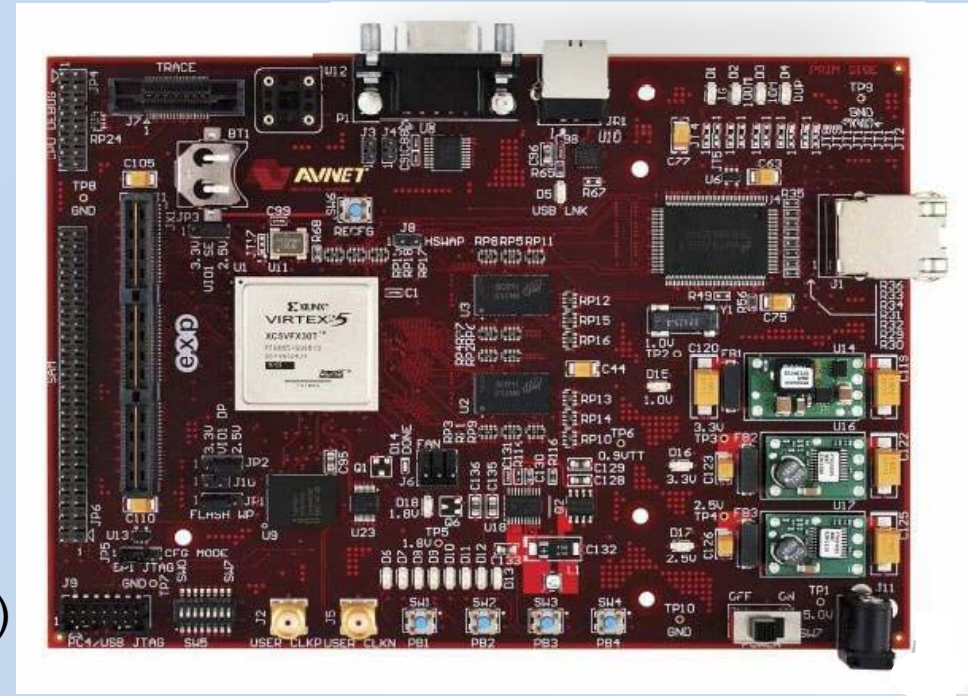
- **Rationale:**

- Enhancing ROD control and monitoring (w.r.t. DSPs)
- Adding Gigabit Ethernet control interface
- Provide a development environment common with the custom FPGA firmware



- **Main activities:**

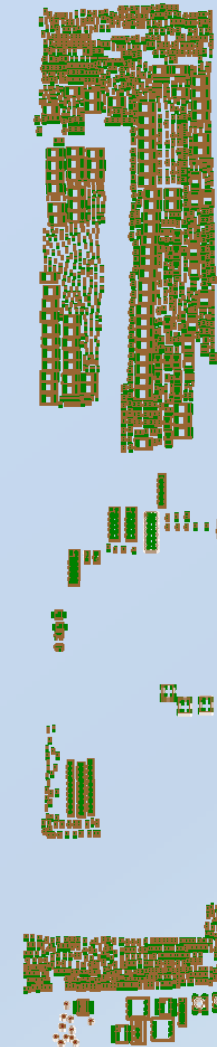
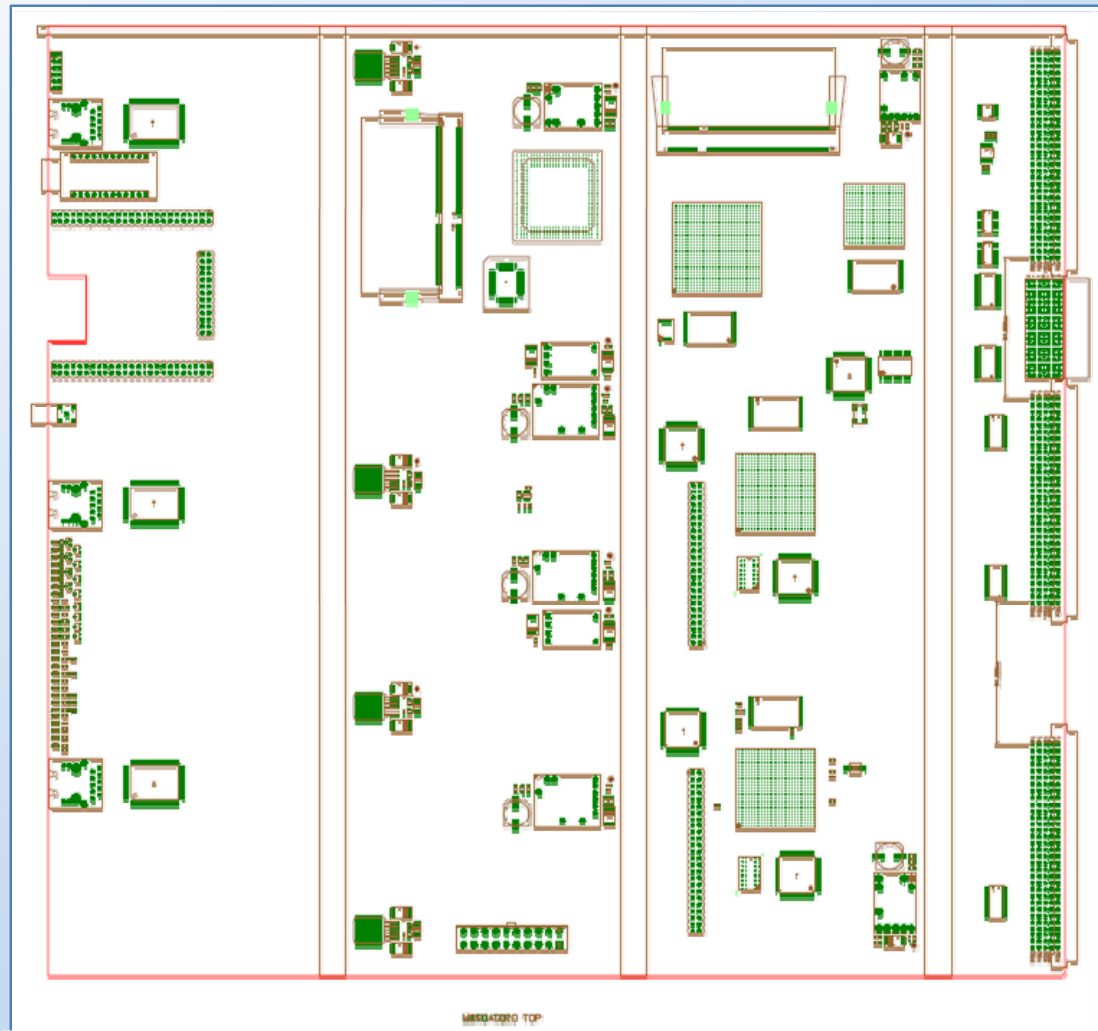
- Increase knowledge on sw and fw design
- Developing ad-hoc peripherals in order to manage custom fw
- Running embedded Linux on PPC (could speed-up Lab and integration tests)
- Provide an integrated hw/sw simulation testbench (FPGA → ROD → whole system)



- **Status:**

- Development system: **AVNET: XILINX Virtex-5 FXT Evaluation Kit**
- Ad-hoc peripheral connecting PPC with actual-ROD VHDL modules is working well
- Able to run and customize Linux on *PowerPC*
- Development of kernel modules for new peripherals ongoing
- Tools providing hw/sw optimized and synchronized simulation is under study (mentor CodeLink)

ROD Layout & Prototype



- ROD schematic close and ROD layout submitted
- 2 fully assembled prototypes expected by end of June
- Firmware, test environment and DAQ software update being addressed
- First BOC – ROD integration of prototypes by mid-end of Summer

Conclusions

- For the ATLAS IBL which is expected to be installed in 2013 a new readout system has been designed.
- The system provides higher bandwidth and integration while keeping fully compatible to the present ATLAS DAQ
- New histogram readout path via GB Ethernet will increase the calibration speed and maintainability
- Total bandwidth of building blocks increases, leading to smaller size systems (IBL readout fits in a single crate)
- Industrial components will replace the custom-made components, recently failing within ATLAS pixel and SCT
- Production of prototypes has been submitted
- First integration of all components expected in mid-end of summer