## Higher-order event-by-event mean- $p_{\mathrm{T}}$ fluctuations in pp and A-A collisions with ALICE



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## Motivation

Event-by-event mean transverse momentum ( $\left\langle p_{\mathrm{T}}\right\rangle$ ) fluctuations:
$\rightarrow$ related to correlations in particle production
$\rightarrow$ provide evidence for the production of QGP
Henning Heiselberg, Physics Reports 351 (2001) 161-194
previous measurement of event-by-event $\left\langle p_{\mathrm{T}}\right\rangle$ fluctuation up to second order only

Skewness of the $\left\langle p_{\mathrm{T}}\right\rangle$ fluctuations can probe hydrodynamic behaviour in A-A collisions
$\rightarrow$ Hydrodynamics predicts positive skewness

- attributes its origin to the fluctuations of energy of the fluid when hydrodynamic expansion starts
$\rightarrow$ sensitive to the early thermodynamics of the QGP
$\rightarrow$ direct way to observe initial-state fluctuations
$\rightarrow$ measurements will strongly constrain the modeling of the initial stages in hydrodynamic studies
G. Giacalone et al., Phys. Rev. C 103, 024910 (2021)

Second order event-by-event $\left\langle p_{\mathrm{T}}\right\rangle$ fluctuation relative to $\left\langle p_{\mathrm{T}}\right\rangle$ as a func. of $\left\langle\mathrm{d} N_{\mathrm{ch}} / \mathrm{d} \eta\right\rangle$


What is the skewness of $\left\langle p_{\mathrm{T}}\right\rangle$ distribution in A-A, what about pp ?

## Observables

$\left\langle p_{\mathrm{T}}\right\rangle$ correlators: extract dynamical information of $\left\langle p_{\mathrm{T}}\right\rangle$ fluctuation
$\rightarrow\left\langle\Delta p_{i} \Delta p_{j}\right\rangle=\left\langle\frac{\sum_{i, j, i \neq j}^{N_{\mathrm{ch}}}\left(p_{i}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)\left(p_{j}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)}{N_{\mathrm{ch}}\left(N_{\mathrm{ch}}-1\right)}\right\rangle_{\mathrm{ev}} \sim \boldsymbol{\mu}_{\mathbf{2}}$

## $\left\langle p_{\mathrm{T}}\right\rangle$ fluctuation

$\rightarrow\left\langle\Delta p_{i} \Delta p_{j} \Delta p_{k}\right\rangle=\left\langle\frac{\sum_{i, j, k, i \neq j \neq k}^{N}\left(p_{i}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)\left(p_{j}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)\left(p_{k}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right)\right.}{N_{\mathrm{ch}}\left(N_{\mathrm{ch}}-1\right)\left(N_{\mathrm{ch}}-2\right)}\right\rangle_{\mathrm{ev}} \sim \mu_{3}$
$\rightarrow\left\langle\Delta p_{i} \Delta p_{j} \Delta p_{k} \Delta p_{l}\right\rangle=\left\langle\frac{\sum_{i, j, k, l, i \neq j \neq k \neq l}\left(p_{i}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)\left(p_{j}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)\left(p_{k}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle\right)\left(p_{l}-\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right)\right\rangle}{N_{\mathrm{ch}}\left(N_{\mathrm{ch}}-1\right)\left(N_{\mathrm{ch}}-2\right)\left(N_{\mathrm{ch}}-3\right)}\right\rangle_{\mathrm{ev}} \sim \mu_{4}$
where, $\mu_{\mathrm{n}}$ is the $\mathrm{n}^{\text {th }}$ order moment of $\left\langle\mathrm{p}_{\mathrm{T}}\right\rangle$

$$
\begin{aligned}
& \begin{array}{l}
\text { Intensive } \\
\text { skewness }
\end{array} \sim \text { independent of } \boldsymbol{N}_{\mathrm{ch}}
\end{aligned} \begin{gathered}
\begin{array}{c}
\text { Dynamic } \\
\text { kurtosis }
\end{array} \sim \mathbf{1} / \boldsymbol{N}_{\mathrm{ch}} \\
\Gamma_{\left\langle p_{\mathrm{T}}\right\rangle}=\frac{\left\langle\Delta p_{i} \Delta p_{j} \Delta p_{k}\right\rangle\left\langle\left\langle p_{\mathrm{T}}\right\rangle\right\rangle}{\left\langle\Delta p_{i} \Delta p_{j}\right\rangle^{2}} \quad \kappa_{\left\langle p_{\mathrm{T}}\right\rangle}=\frac{\left\langle\Delta p_{i} \Delta p_{j} \Delta p_{k} \Delta p_{l}\right\rangle}{\left\langle\Delta p_{i} \Delta p_{j}\right\rangle^{2}}
\end{gathered}
$$

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## Results: Skewness and kurtosis of $\left\langle p_{\mathrm{T}}\right\rangle$

ALICE

$\rightarrow$ positive skewness excess from its baseline value observed in A-A collisions
$\rightarrow$ indicates hydrodynamic evolution in A-A system
$\rightarrow$ pp collisions and models without hydrodynamics also show excess of the intensive skewness over corresponding baselines
$\rightarrow$ comparable to hydrodynamic model predictions

Dynamic kurtosis

$\rightarrow$ mild dependence on multiplicity in A-A collisions
$\rightarrow$ approaches Gaussian baseline at high multiplicity in A-A collisions
$\rightarrow$ pp collisions remain consistently above the Gaussian baseline indicating that it is a more correlated system
$\rightarrow$ HIJING qualitatively describes data but shows no quantitative agreement

## Skewness of $\left\langle p_{\mathrm{T}}\right\rangle$ - is it trivial?

$\left\langle p_{\mathrm{T}}\right\rangle=\frac{\sum_{i=1}^{N_{\mathrm{ch}}} p_{i}}{N_{\mathrm{ch}}} \square$
Does the fluctuations of e-by-e $\left\langle p_{\mathrm{T}}\right\rangle$ arise from trivial stochastic effects of multiplicity ( $N_{\mathrm{ch}}$ )?


ALI-PREL-503530
$\rightarrow$ Black points: Distributions obtained by fixing $N_{\mathrm{ch}}$ to $N_{\mathrm{ch}}{ }^{\min }{ }^{(*)}$ ) in a given centrality class, to disentangle statistical fluctuations of $N_{\mathrm{ch}}$. Black and red dashed lines indicate Gaussian fit. * $N_{\mathrm{ch}}{ }^{\text {min }}$ is the minimum number of charged particle per event for a centrality class
$\left\langle p_{\mathrm{T}}\right\rangle$ distribution continues to have a positive skew even after removing the stochastic effect of $N_{\mathrm{ch}}$, which shows that the skewness is not a trivial consequence of e-b-e $N_{\mathrm{ch}}$ fluctuations

## Summary :

$\rightarrow$ First measurement of skewness and kurtosis of $\left\langle p_{\mathrm{T}}\right\rangle$ in $\mathrm{pp}, \mathrm{Pb}-\mathrm{Pb}$ and Xe-Xe collisions at LHC energies.
$\rightarrow$ Positive intensive skewness in A-A collisions shows significant excess from its independent baseline - existence of hydrodynamic evolution in the system.
$\rightarrow$ Measurements in pp collisions and HIJING simulations also show excess of intensive skewness over their corresponding baselines.
$\rightarrow$ Measurement of the dynamic kurtosis may help distinguish particle production mechanisms in different systems.

THANK YOU


[^0]:    G. Giacalone et al., Phys. Rev. C 103, 024910 (2021)

