

Second Order Kalman filtering

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Ref: <https://www.diva-portal.org/smash/get/diva2:511843/FULLTEXT01.pdf>

Kalman filtering in second order

Kalman gain matrix:

$$\mathbf{K}_k = \mathbf{C}_k^{k-1} \mathbf{H}_k^T \left(\mathbf{V}_k + \mathbf{H}_k \mathbf{C}_k^{k-1} \mathbf{H}_k^T \right)^{-1}$$

The updated measurement covariance S element

$$S_k^{lm} = \left(\nabla_x h_l(\hat{\delta}_{k|k-1}) \right)^T P_{k|k-1} \nabla_x h_m(\hat{\delta}_{k|k-1}) + \left(\nabla_e h_l(\hat{\delta}_{k|k-1}) \right)^T R_k \nabla_e h_m(\hat{\delta}_{k|k-1})$$

The first order

$$+ \frac{1}{2} \text{tr} \left(\nabla_x^2 h_l(\hat{\delta}_{k|k-1}) P_{k|k-1} \nabla_x^2 h_m(\hat{\delta}_{k|k-1}) P_{k|k-1} \right) + \frac{1}{2} \text{tr} \left(\nabla_e^2 h_l(\hat{\delta}_{k|k-1}) R_k \nabla_e^2 h_m(\hat{\delta}_{k|k-1}) R_k \right). \quad (6)$$

The second order

Update of the state vector:

$$\mathbf{x}_k = \mathbf{x}_k^{k-1} + \mathbf{K}_k \left(\mathbf{m}_k - \mathbf{H}_k \mathbf{x}_k^{k-1} \right).$$

Update of the covariance matrix:

$$\mathbf{C}_k = (\mathbf{I} - \mathbf{K}_k \mathbf{H}_k) \mathbf{C}_k^{k-1}.$$

Hessian matrix in approximation ?

$$\frac{1}{2} \text{tr} \left(\nabla_x^2 h_l(\hat{\delta}_{k|k-1}) P_{k|k-1} \nabla_x^2 h_m(\hat{\delta}_{k|k-1}) P_{k|k-1} \right) + \frac{1}{2} \text{tr} \left(\nabla_e^2 h_l(\hat{\delta}_{k|k-1}) R_k \nabla_e^2 h_m(\hat{\delta}_{k|k-1}) R_k \right). \quad (6)$$

- Suppose P is the covariance of x , H is the Hessian matrix, then:

$$\begin{aligned} \text{tr}(\mathcal{H}_l \mathcal{P} \mathcal{H}_m \mathcal{P}) = & \lim_{\alpha \rightarrow 0} \frac{1}{\alpha^4 n_x^2} \left(\sum_{i=1}^{n_x} \left(z_l^{(i)} + z_l^{(-i)} - 2z_l^{(0)} \right) \right. \\ & \left(z_m^{(i)} + z_m^{(-i)} - 2z_m^{(0)} \right) + \frac{1}{4} \sum_{i=1}^{n_x} \sum_{j=1, j \neq i}^{n_x} \left(z_l^{(ij)} + z_l^{(-ij)} \right. \\ & \left. - z_l^{(i)} - z_l^{(-i)} - z_l^{(j)} - z_l^{(-j)} + 2z_l^{(0)} \right) \left(z_m^{(ij)} + z_m^{(-ij)} \right. \\ & \left. - z_m^{(i)} - z_m^{(-i)} - z_m^{(j)} - z_m^{(-j)} + 2z_m^{(0)} \right) \left. \right). \quad (12d) \end{aligned}$$

$z^0, z^i, z^{ij} \dots$ are the values of $h(x)$ evaluated at $x^0, x^i, x^{ij} \dots$ (central and sigma points of x)

How to choose sigma points?

One approach: Singular value decomposition

Let $\hat{x} = E(x)$ and $\mathcal{P} = \text{cov}(x)$. Using the singular value decomposition, the symmetric $n_x \times n_x$ covariance matrix can be written as

$$\mathcal{P} = \mathcal{U} \mathcal{S} \mathcal{U}^T = \sum_{i=1}^{n_x} s_i u_i u_i^T. \quad (10)$$

Here, s_i is the i -th singular value of \mathcal{P} and u_i the i -th column of the unitary matrix \mathcal{U} .

$2n_x^2$ sigma points. For free track parameter, $2*8*8 = 128$ points?
Or $2*8 = 16$ using just Eq. (11b) might be enough?

Next, a set of sigma points around \hat{x} , as used in the unscented transformation [3], can be chosen systematically. With hindsight that the conventional set comprising $2n_x + 1$ vectors in x will not suffice for our purpose, the set is extended by adding $n_x^2 - n_x$ distinct sigma points. The set members are constructed according to:

$$x^{(0)} = \hat{x}, \quad (11a)$$

$$x^{(\pm i)} = \hat{x} \pm \alpha \sqrt{n_x s_i} u_i, \quad (11b)$$

$$i = 1, \dots, n_x,$$

$$x^{(\pm ij)} = \hat{x} \pm \alpha \sqrt{n_x} (\sqrt{s_i} u_i + \sqrt{s_j} u_j), \quad (11c)$$

$$i, j = 1, \dots, n_x, \quad i \neq j.$$