

CMS Pixel Upgrade

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Pixel upgrade - why?

- The pixel detector was designed from the very beginning to be replaced during the lifetime of the LHC experiments (because of degradation of the sensors by hadronic irradiations)
- After 2017 LHC luminosities beyond the original design are likely - incapable by the present readout electronics
- Stay compatible with current system and installation procedure as much as possible

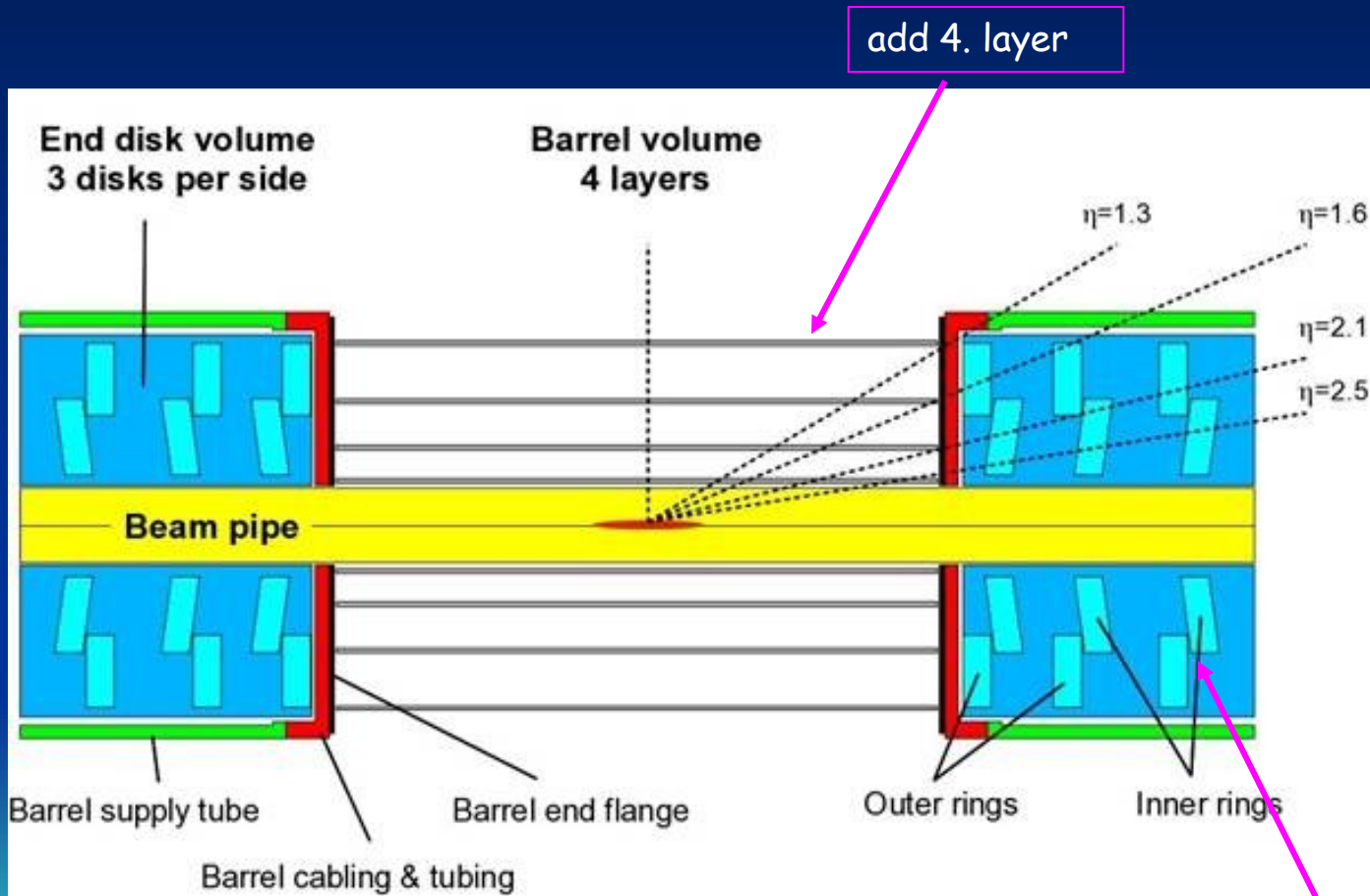
An outline of the pixel upgrade (phase I)

- 1) Pixel tracking ➡ • From 3 hits/track to 4
- 2) Material budget ➡ • Keep it small (smaller!)
- 3) Performance ➡ • impact par., vertex, b-tag
- 4) LHC Luminosity ➡ • Ready to $2 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
- 5) Total Power demands ➡ • Keep within pres. limits
- 6) Scheduling ➡ • use of LHC shutdowns

Constraints for the pixel upgrade

- CMS must be physics-ready after each shutdown used for upgrade work
- minimize risk of damage, radiation exposure and accidents
- minimize start-up time and risk of compromised detector performance
- ➡ consequently replacement impossible for power cables, readout fibers, pipes (from balcony to PP1)

Pixel tracking: from 3 to 4 hits



Benefits of 4 pixel track points

- Efficiency & resolution improvement for **pixel-only tracks** which are
 - important for High Level Triggering
 - seeds for full tracking → resulting in
 - higher full track efficiency
 - lower fake track rate
 - important for primary & secondary vertexing
(pile-up) (b-tagging)

Material budget smaller !(?)

- Upgrade from 3 to 4 track points \Rightarrow
 - \Rightarrow means 50-60% more modules!
- Expected mass ratio $R_m \equiv m_{2017}/m_{2008}$:
 - BPIX: $R_m \sim 0.57$ ($\eta < 1.24$) (~ 0.8 in %RL)
 0.43^* ($\eta < 2.15$)
 - FPIX: $R_m \sim 0.8$ ($\eta < 2.5$) (~ 0.5 in %RL)

How is this possible ?

- cooling by 2-phase CO_2 instead C_6F_{14}
- advanced mechanics + modified design

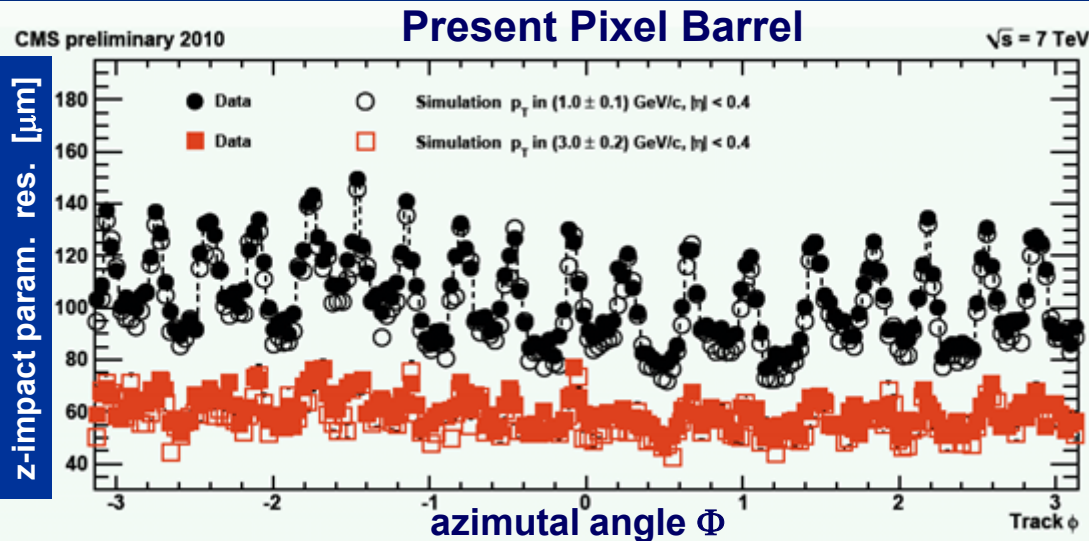
Mat. budget: "cool & mech"

- CO₂ cooling (total mass barrel layers):
 - 3 layers (2008): 3655g (1197g for cooling)
 - 4 layers (2017): 3029g (577g for cooling)
 - 4 layers (C₆F₁₄): 4473g (2021g for cooling)
- other layer mat.:

	2008(3L)	2017(4L)
- mechanics (w/o pipes)	186g	224g
- modules	870g	828g
- cables	159g	141g

Cooling aspects

Present cooling using C_6F_{14} contributes a major fraction to the mat. budget.



Two-phase CO_2 cooling requires only small diameter tubing, despite high pressure operation (up to 70bar).



Therefore changing the C_6F_{14} cooling system into a CO_2 system is rewarded by the largest fraction of material savings.

CO₂ cooling: pros and challenges

•Excellent thermodynamic properties:

- small viscosity
- high heat transfer
- high latent heat
- low liquid/vapor density ratio
- ☹
- small pipes (1.6/1.8mm^ø) possible

•low mass (~half of C₆F₁₄)

•radiation hard

•cheap

• Challenges:

- Two-phase flow: predictions inaccurate; requires close co-operation between experimentalists and system designer.
- cooling plant design (~10kW @ -20°)
- primary cooling system
- pipe from plant → PP1 (pressure!)
- channels from PP1 → PPO (space!)
- control & monitoring
- validation of system operation
- warm start-up
- safety issues

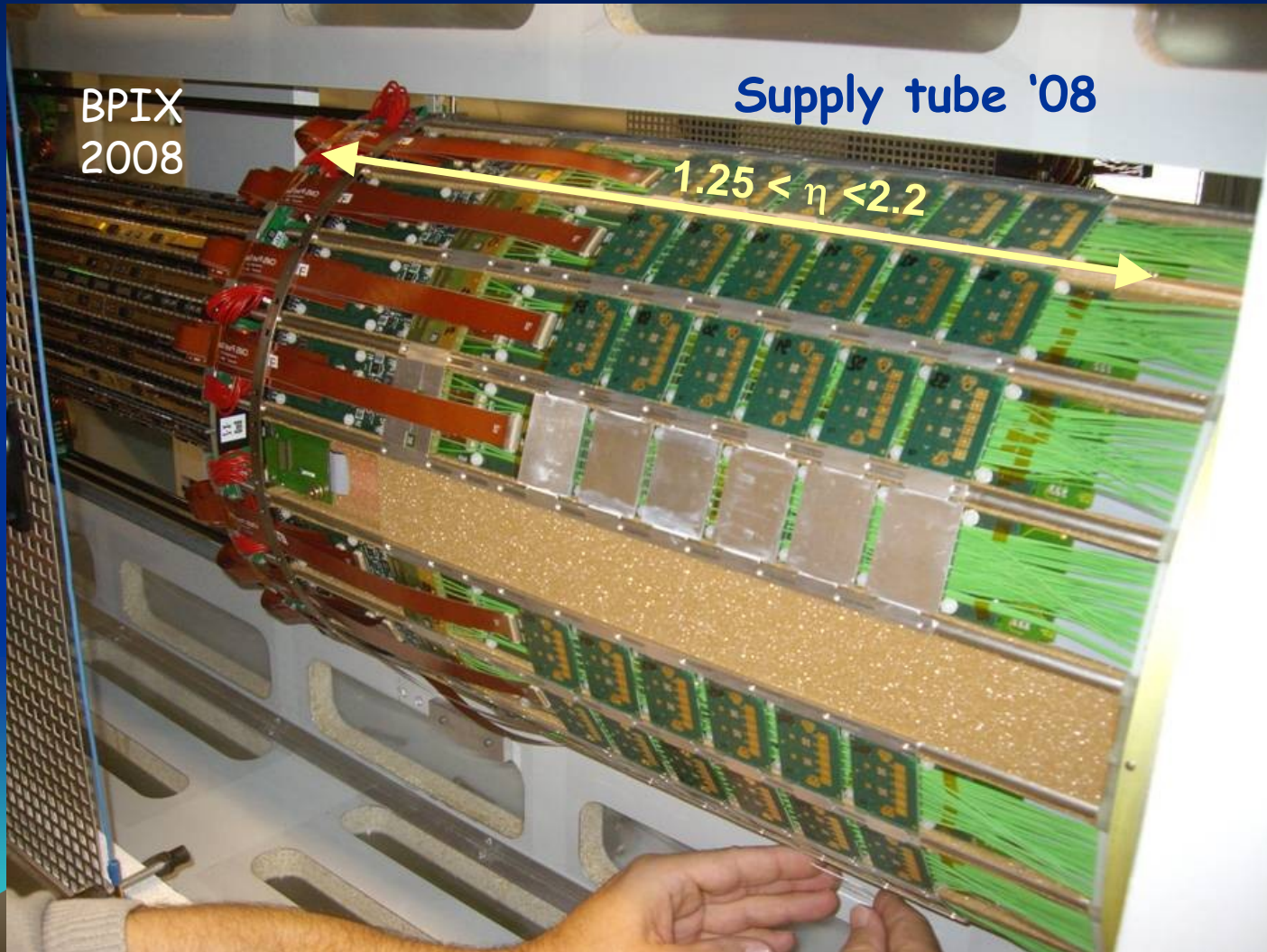
Prototype mechanics 1st layer



← Pipes: 1.6/1.8mm ø st. steel

Weight Layer1 51g + 11g CO₂ → 40% of old first layer

Mat. budget: "shift & save"



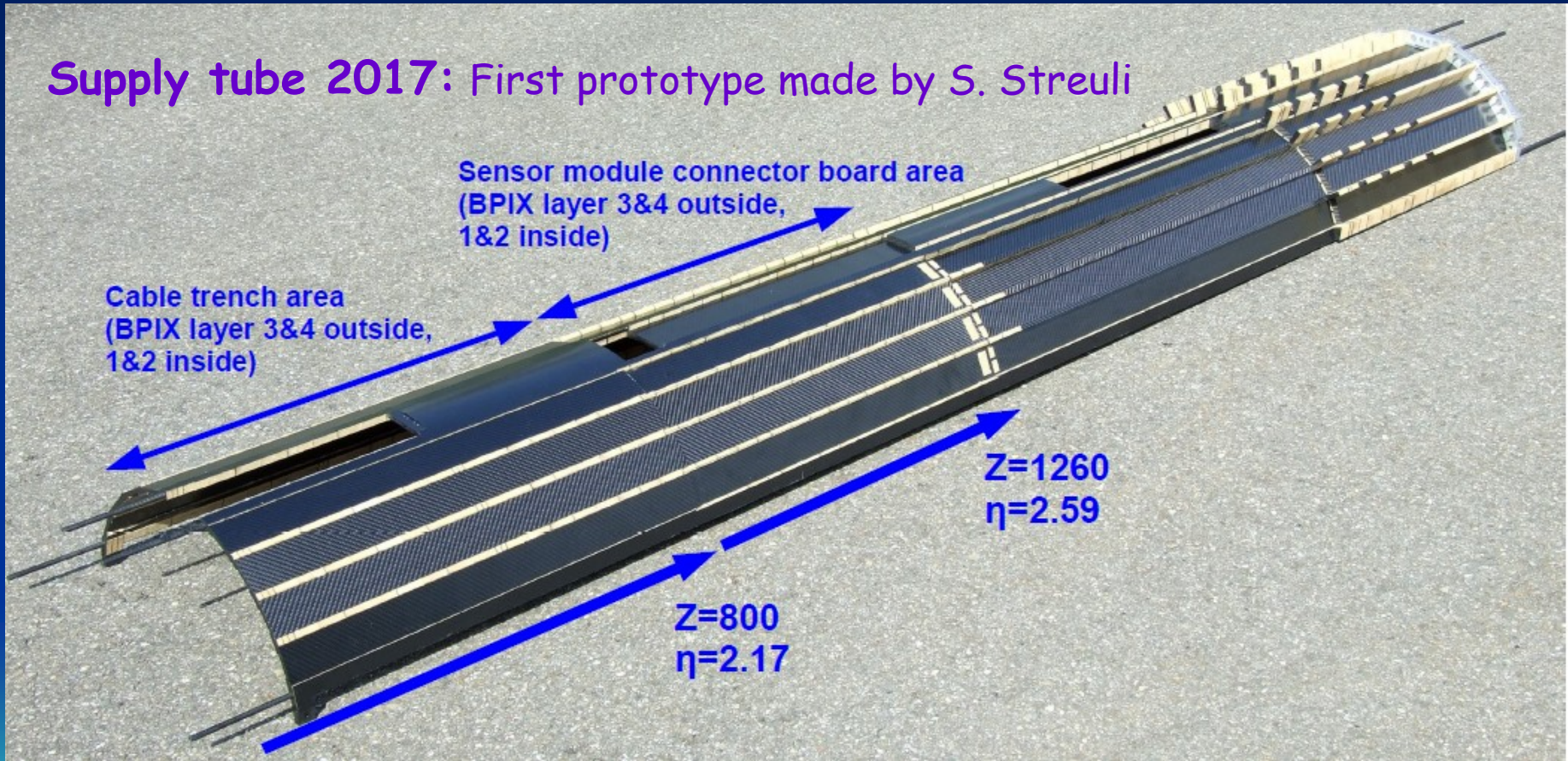
Innermost
section of
supply tube
contains :

AOHs, DOHs,
PCBs, cables,
connectors,
fibers

Total mass:
 $4 \times 2289\text{g}$

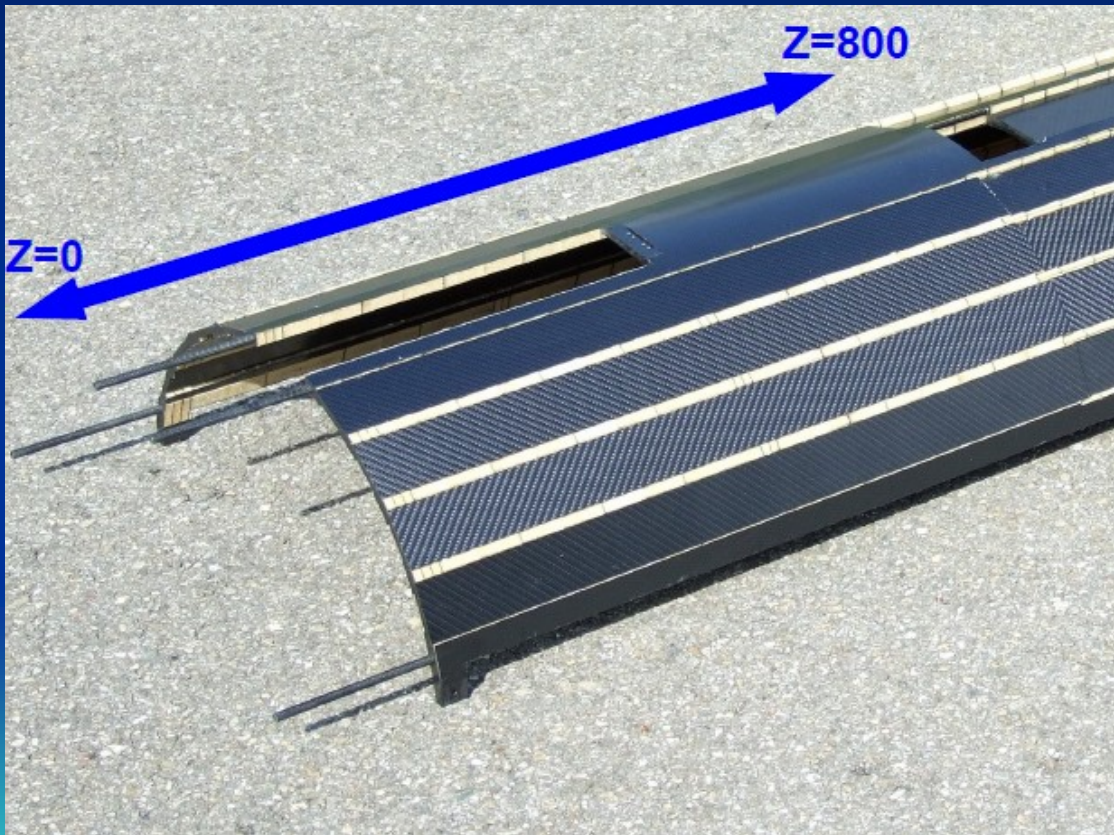
Mat. budget: "shift & save"

Supply tube 2017: First prototype made by S. Streuli



Mat. budget: "shift & save"

Supply tube 2017: Innermost section contains:



Material	Weight
Airex C70/55	83gr.
Carbon fiber ribs	11gr.
Carbon fiber tubes	27gr.
Carbon fiber wheel support	7gr.
Carbon fiber facets	180gr.
Epoxy glue	100gr.
Total weight	<u>408gr.</u>

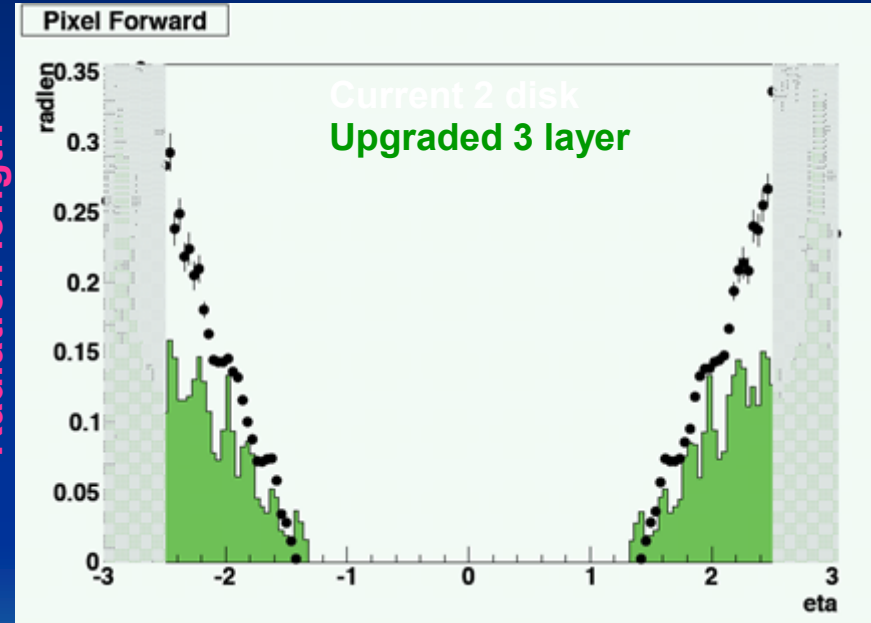
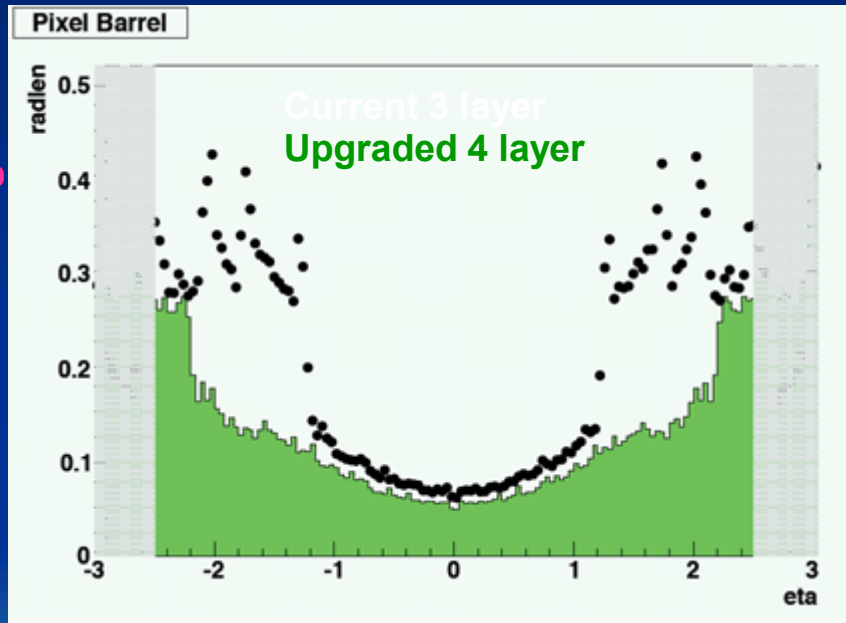
add:

CO2-pipes 38g

cables 280g

Total: 4 x 726g

Expected effect on mat. budget



Remark: the shown budget for the upgrade is probably somewhat pessimistic !

BPIX layout

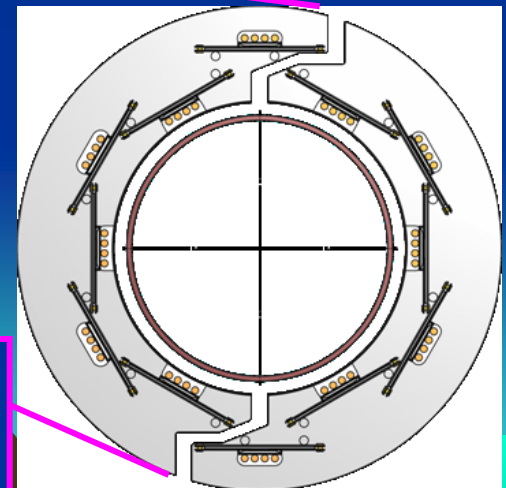
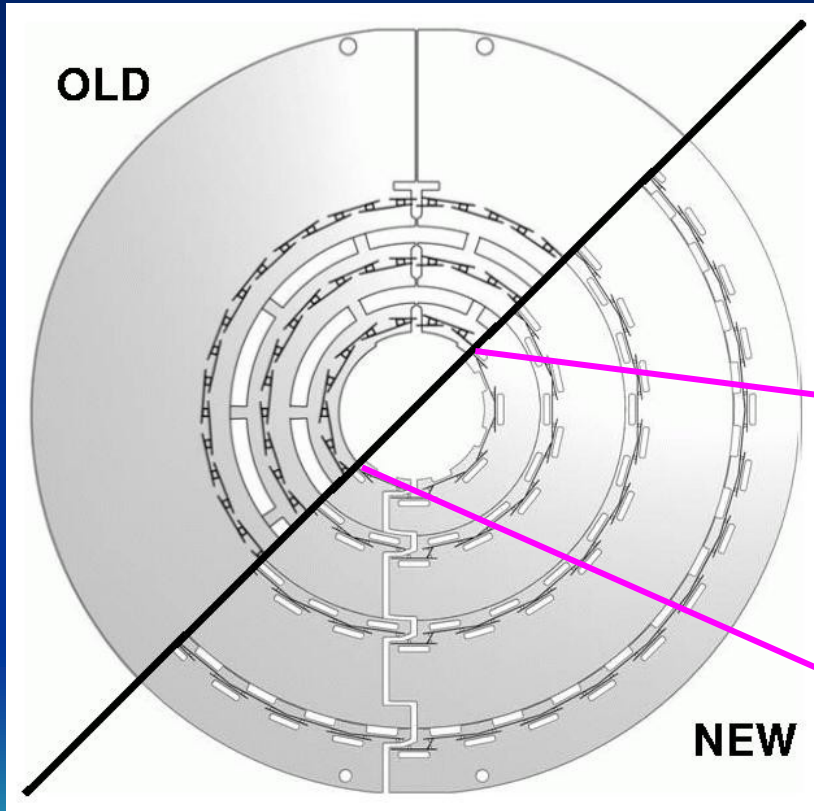
New layout: Full module type only!

Layer	radius	# faces	# modules	# ROCs
1*	39mm	16	128	2048
2	68mm	28	224	3584
3	109mm	44	352	5632
4	160mm	64	512	8192
			Total: 1216	19456

* Clearance to beam pipe 4mm

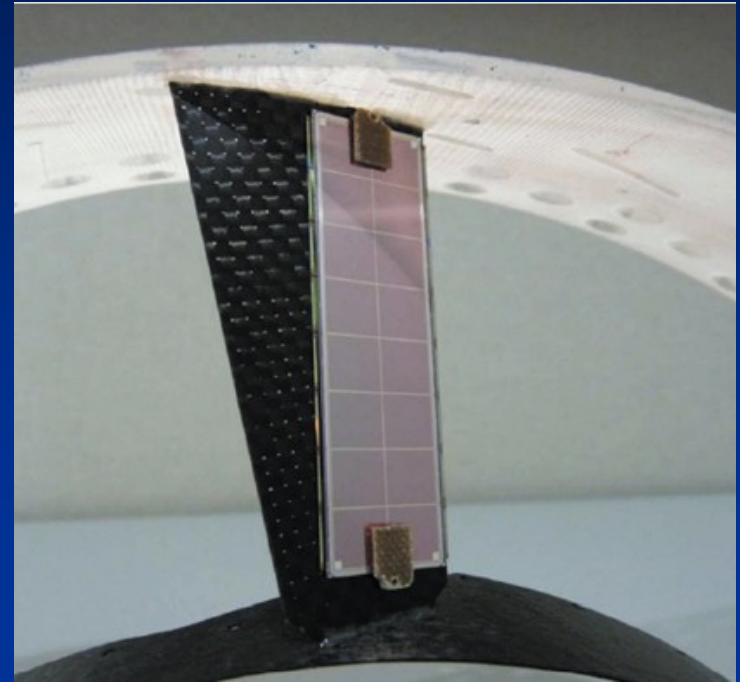
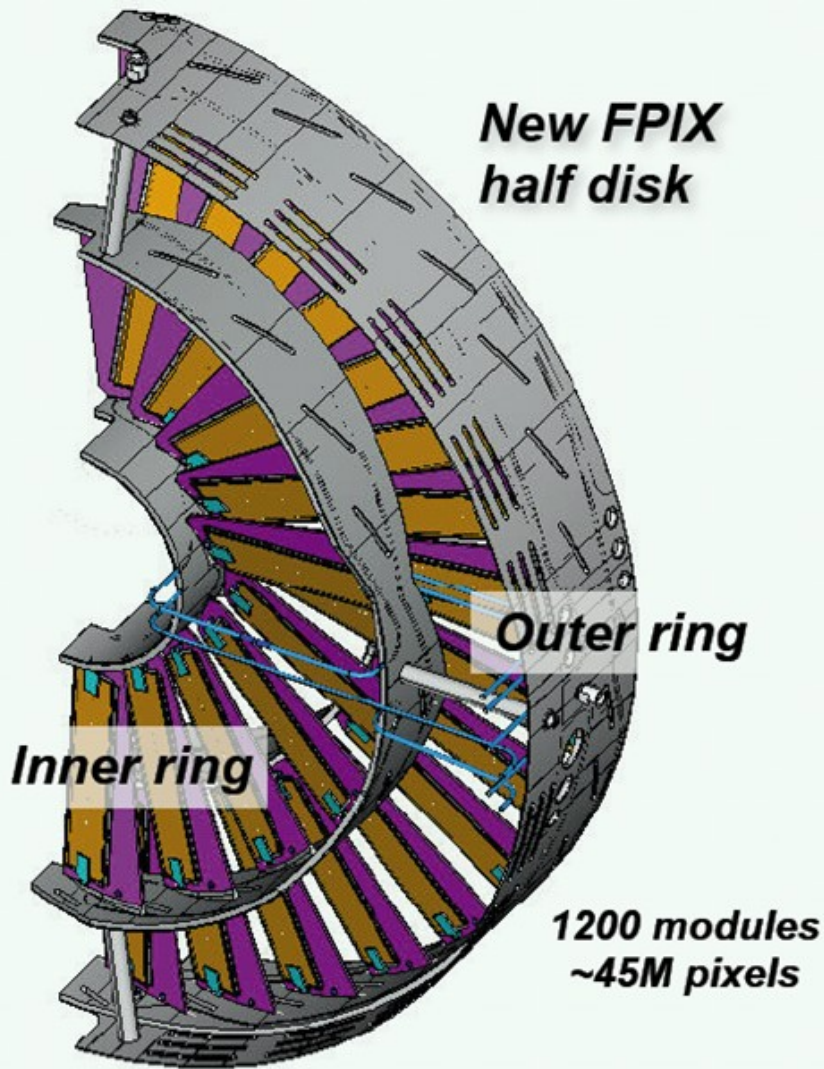
~81M pixel

(~1.7x old BPIX)



If beam pipe $r < 22.5$ mm \rightarrow 1st Layer: 12 faces
 $\langle R \rangle = 29.5$ mm (32 modules and 512 ROCs less \rightarrow 1184 / 18944)
 beam pipe clearance 2.25 mm (~79M pixel)

FPIX disk design



- inner & outer ring for easier replacement
 - 6 disk of 112 sensors each → 672 modules
 - one module size with 2x8 ROC / module
- 10'752 ROC's ~ **44M pixel** (2.5 x old FPIX)

Impact parameter

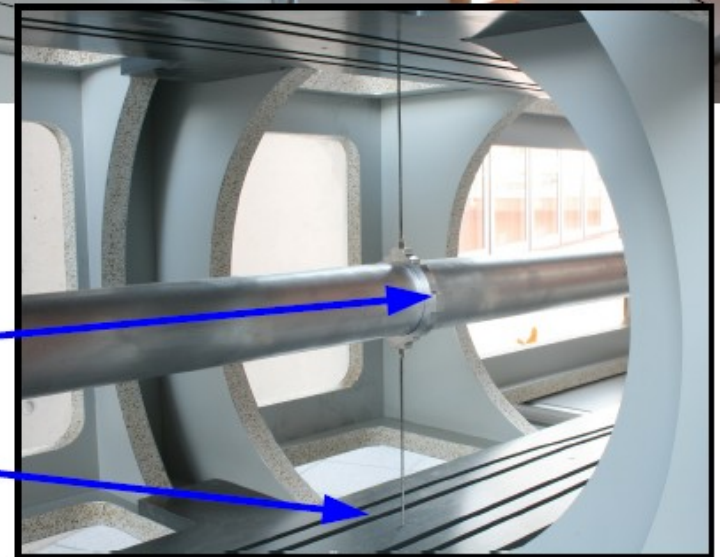
- Improvements by:
 - more hits / lower mass (see above)
 - smaller 1st layer radius (beam pipe radius?)
 - closer approach to beam pipe (difficult and a potential threat to CMS / LHC)
 - ➡
 - direct "blind" insertion into CMS to risky
 - final adjustment system needed
 - test on mock-up

Installation mock-up

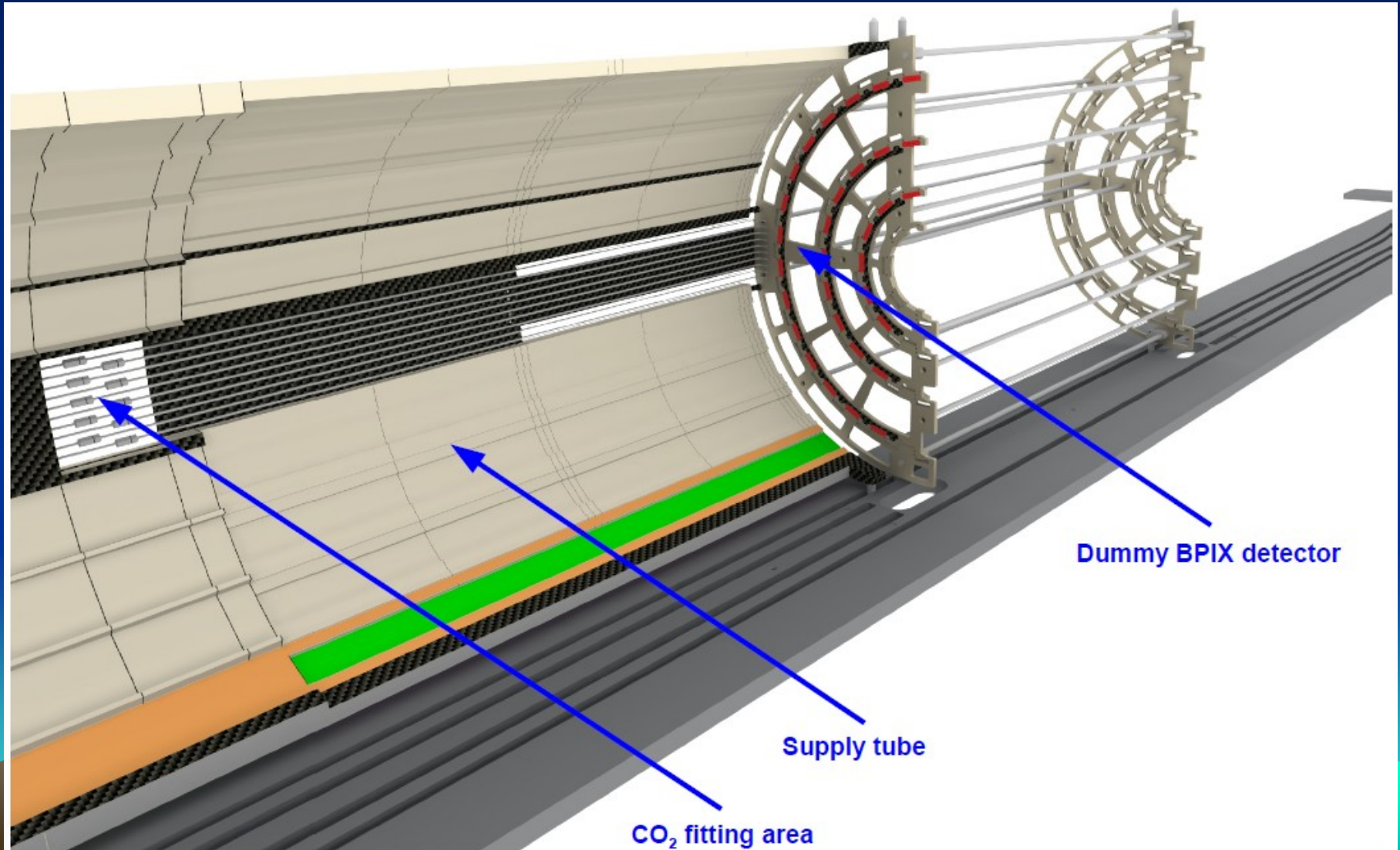


Beam pipe support

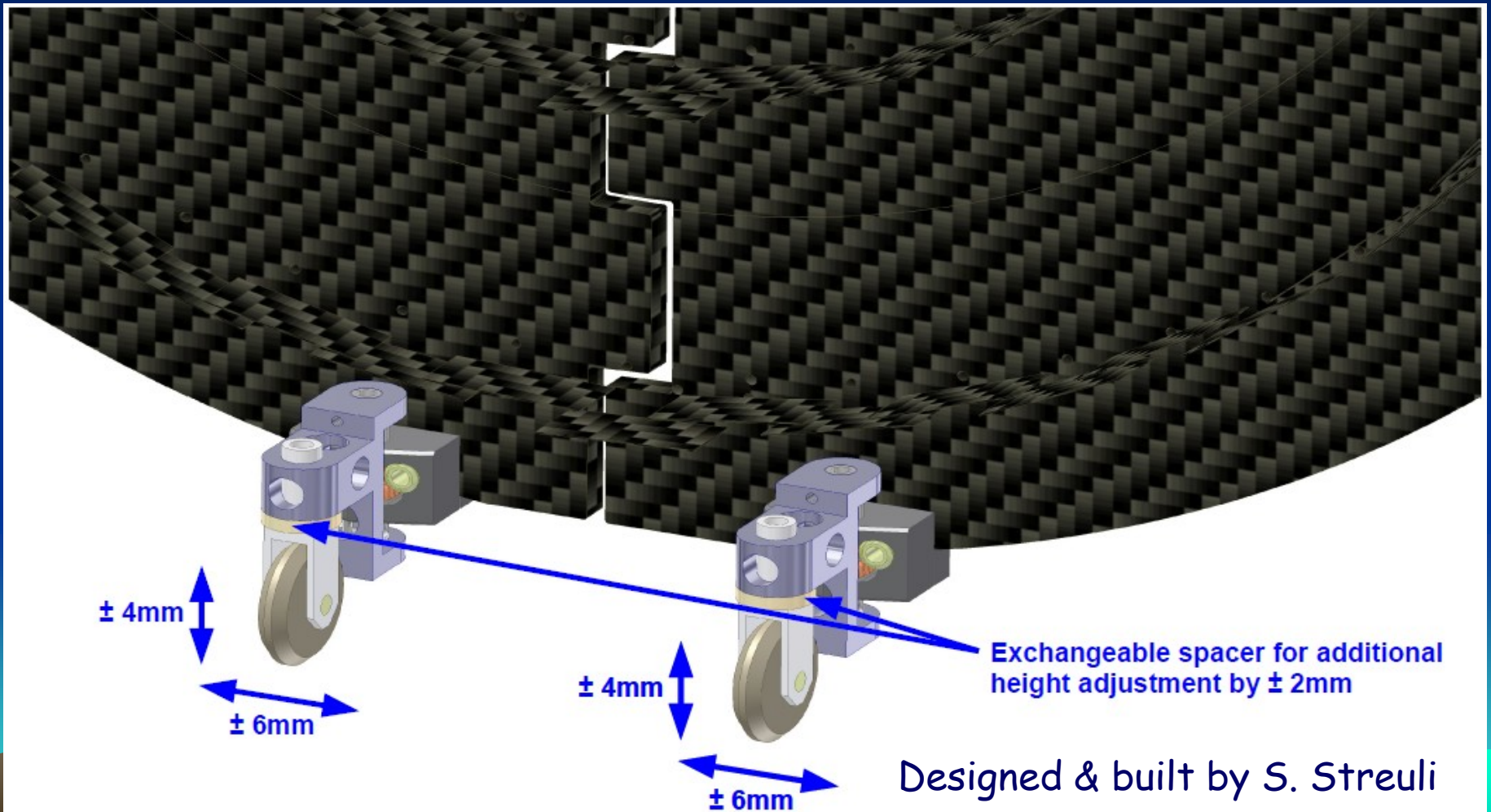
Rails



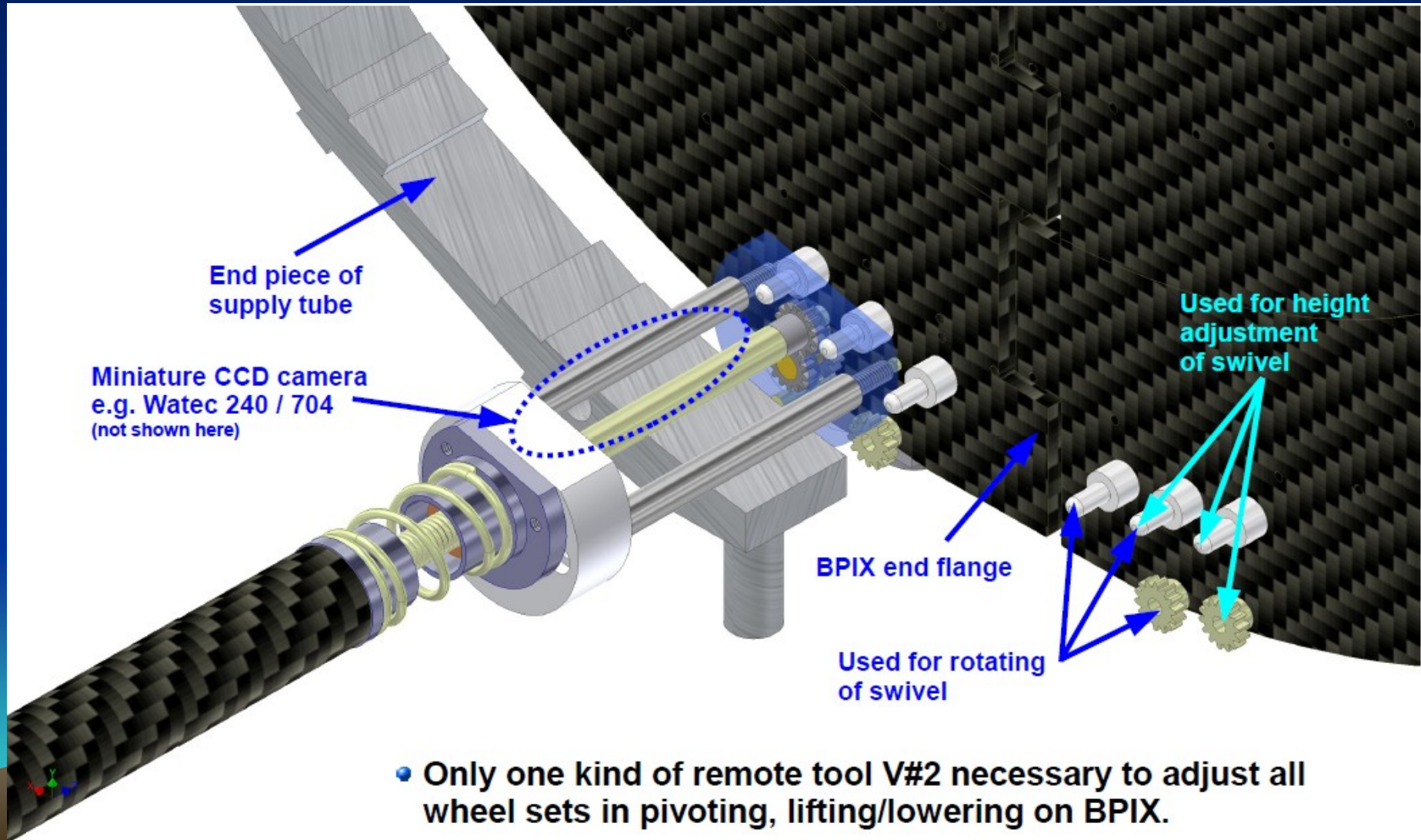
BPIX dummy + Supp. Tube



Adjustable wheel set for BPIX

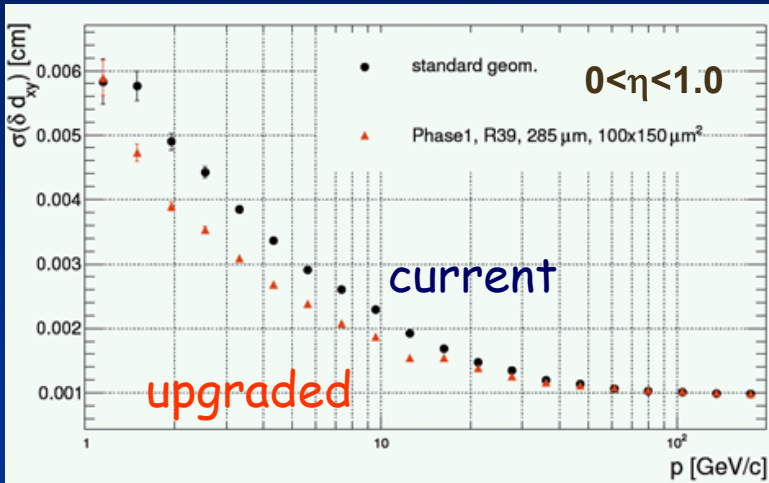


Precise BPIX shell adjustment

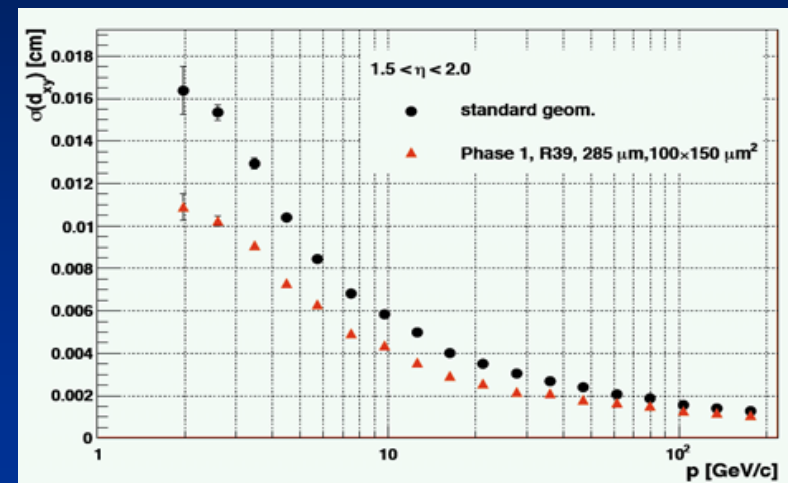


Improved Impact parameter

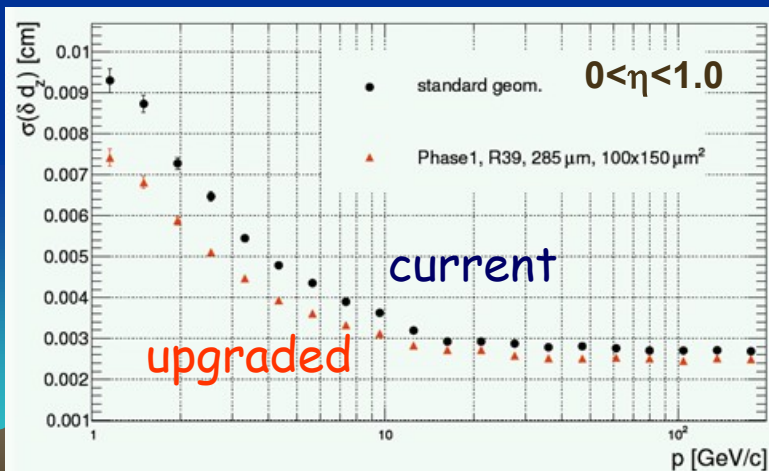
Barrel region



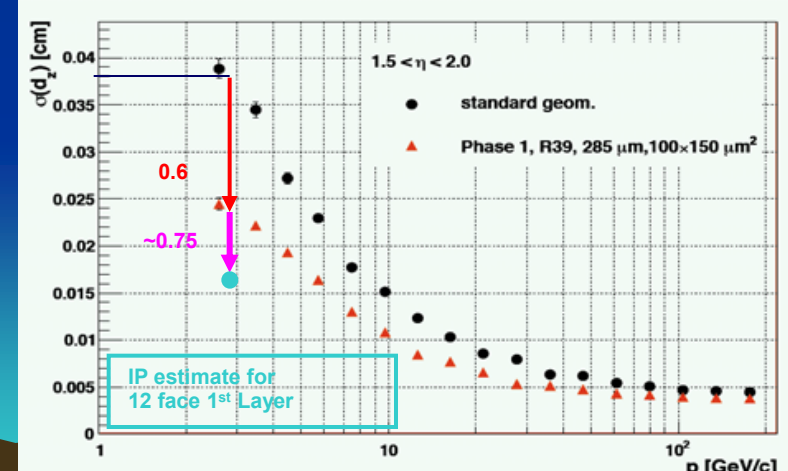
Forward region



transverse IP



longitudinal IP

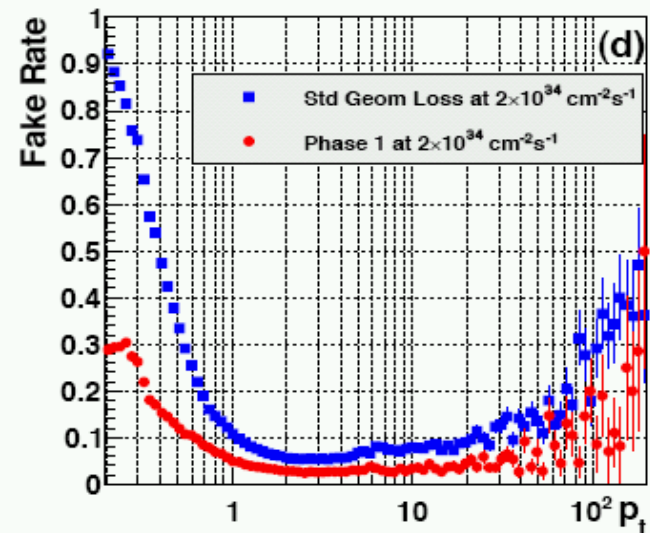
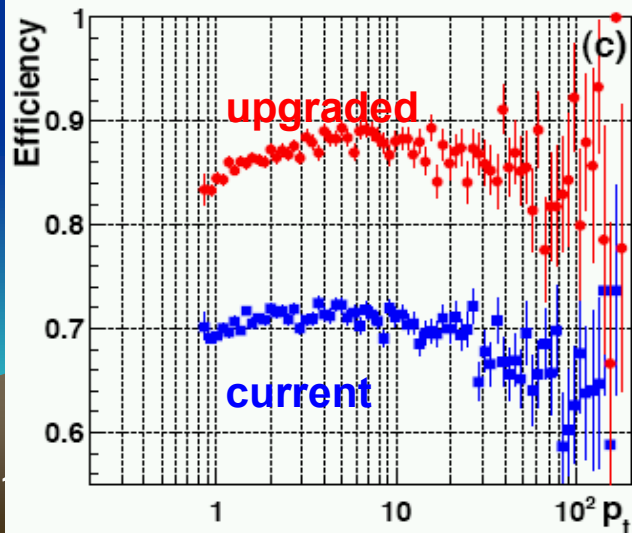
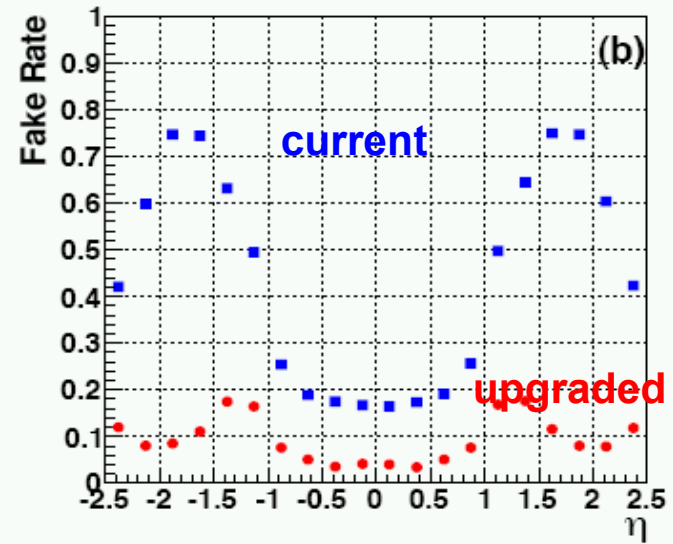
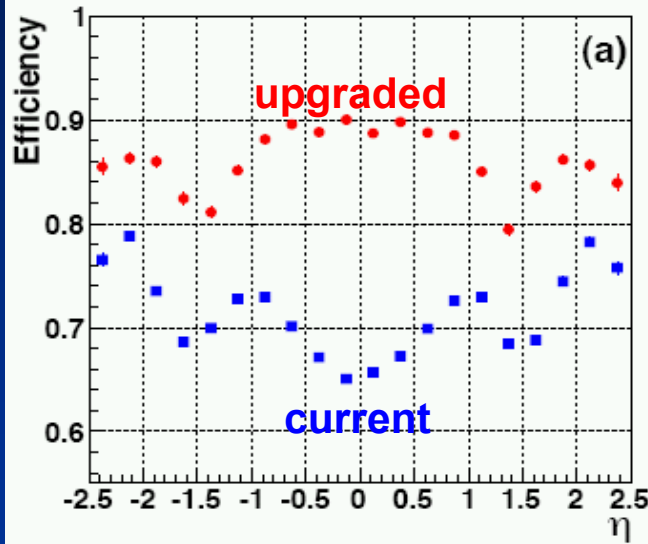


W. Bertl
PSI

Post June 21, 2011

Beam pipe $r < 23\text{mm}$: 16 faces to 12 faces \rightarrow reduce MS term by ~ 0.75 \rightarrow total $0.75 \times 0.6 = 0.45$!

Pixel Track seeding



Reduced data loss and quadruplet seeding
improves efficiency and reduces fake rate!

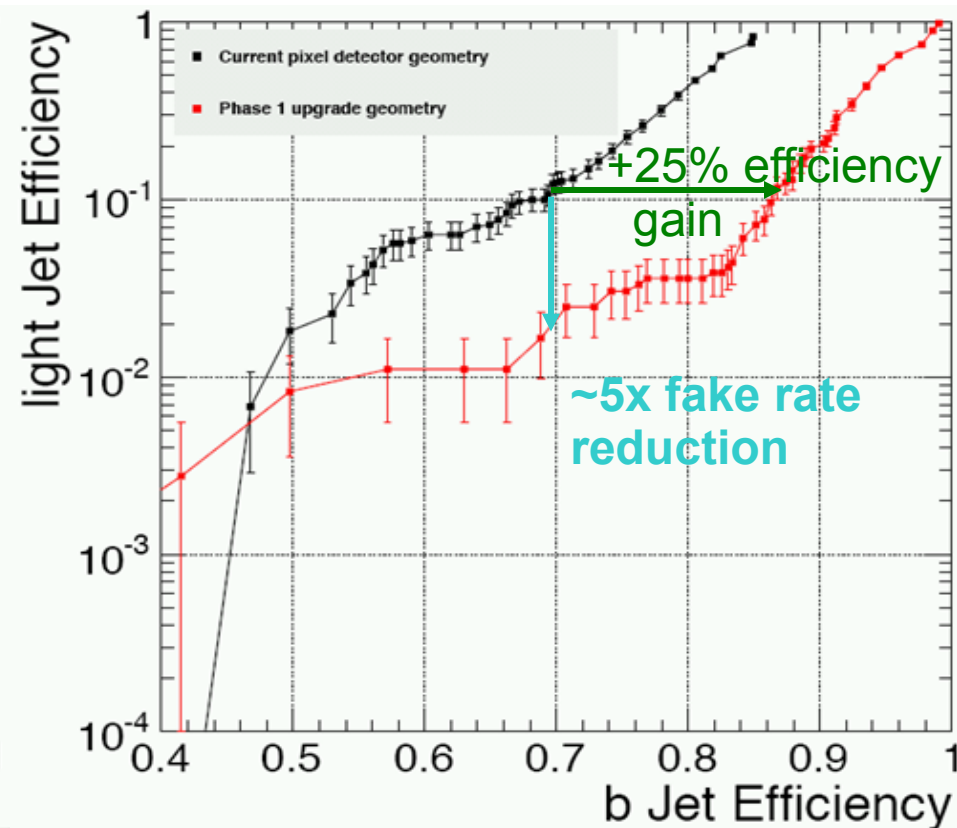
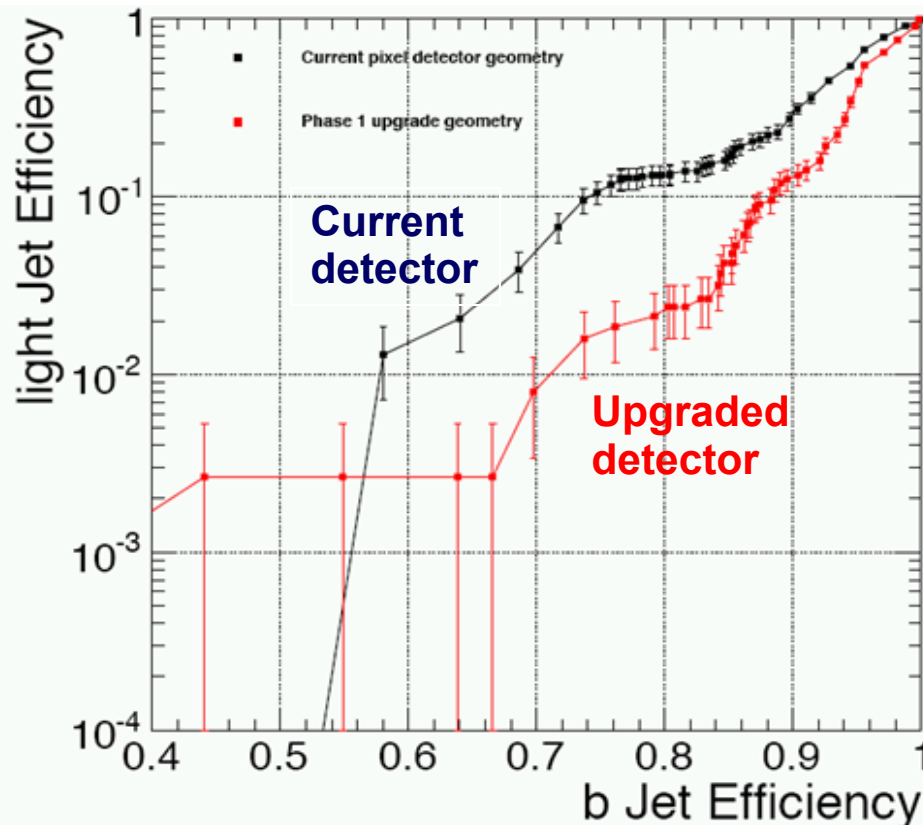
Prediction for
 $2 \times 10^{34} \text{ cm}^{-2}\text{s}^{-1}$
luminosity

b-tagging

$t\bar{t}$ $80 < p_{\perp} < 120 \text{ GeV}$ Combined Secondary Vertex Tagger

No pile up

Lumiosity = $1 \text{E}34 \text{ cm}^{-2}\text{s}^{-1}$



ROC ready for the upgrade?

Present ROC :

Luminosity $\text{cm}^{-2}\text{s}^{-1}$	bx-spacing ns	Data loss (@ 1 st layer)
1×10^{34}	25	4%
	50	16% ←
2×10^{34}	25	15%
	50	~50% ←

Approx. 50% more ROCs in new pixel detector.

Limited number of readout fibers → boost readout frequency

Clearly, the present ROC is not appropriate for luminosities expected in phase-1

This bx-mode was not foreseen in 1998 when ROC architecture has been designed

New ROC : Hit rate capability

Unchanged: front-end amplifier, threshold + trimming, column drain
0.25 μ m technology

Present ROC:

32 data buffer

12 timestamp buffer

no readout buffer (8 ROC seq.)

New ROC:

→ 80 data buffer

→ 32 timestamp buffer

→ 64 x 24 bit static RAM as readout buffer
space for 96 cells (set after simulation)

readout buffer storage:

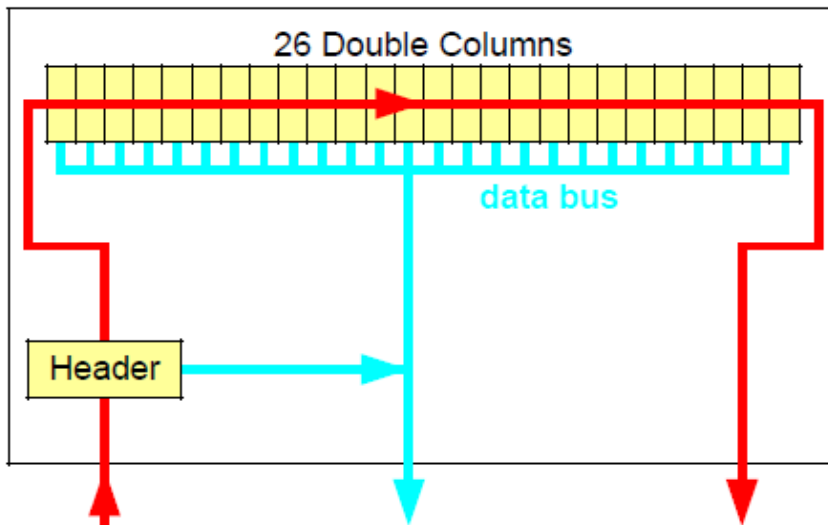
simultaneous read/write (6 bit counters)

Design/simulation done:

integration into ROC "to do"

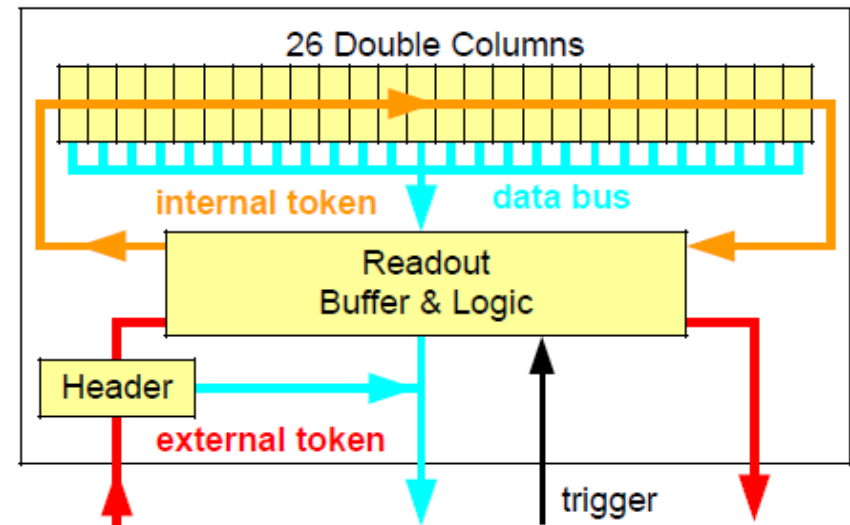
Buffered Readout

present ROC



- Double columns with verified data stops → no more events accepted
- Double columns have to wait for external token → long dead time
- Sequential readout of 8/16 ROCs → high token delay

new ROC



- DCol readout parallel in all ROCs after trigger → reduced waiting time
- ROC readout buffer: read/write simultaneous; data with different time stamps
- Easy implementation in separate buffer on ROC → keep present DCol logic

ROC : Readout bandwidth

Present ROC: 40 MHz analog (6 levels \cong 2.5 bits)
raising frequency risky because limited rise time!

Solution: "GO DIGITAL"



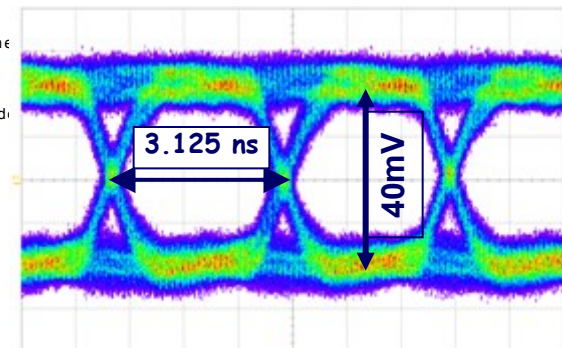
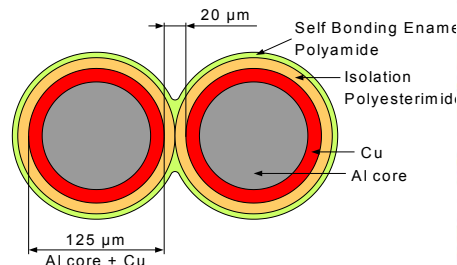
on-chip 8-bit ADC, clock = 80 MHz

ROC readout: 160 MHz

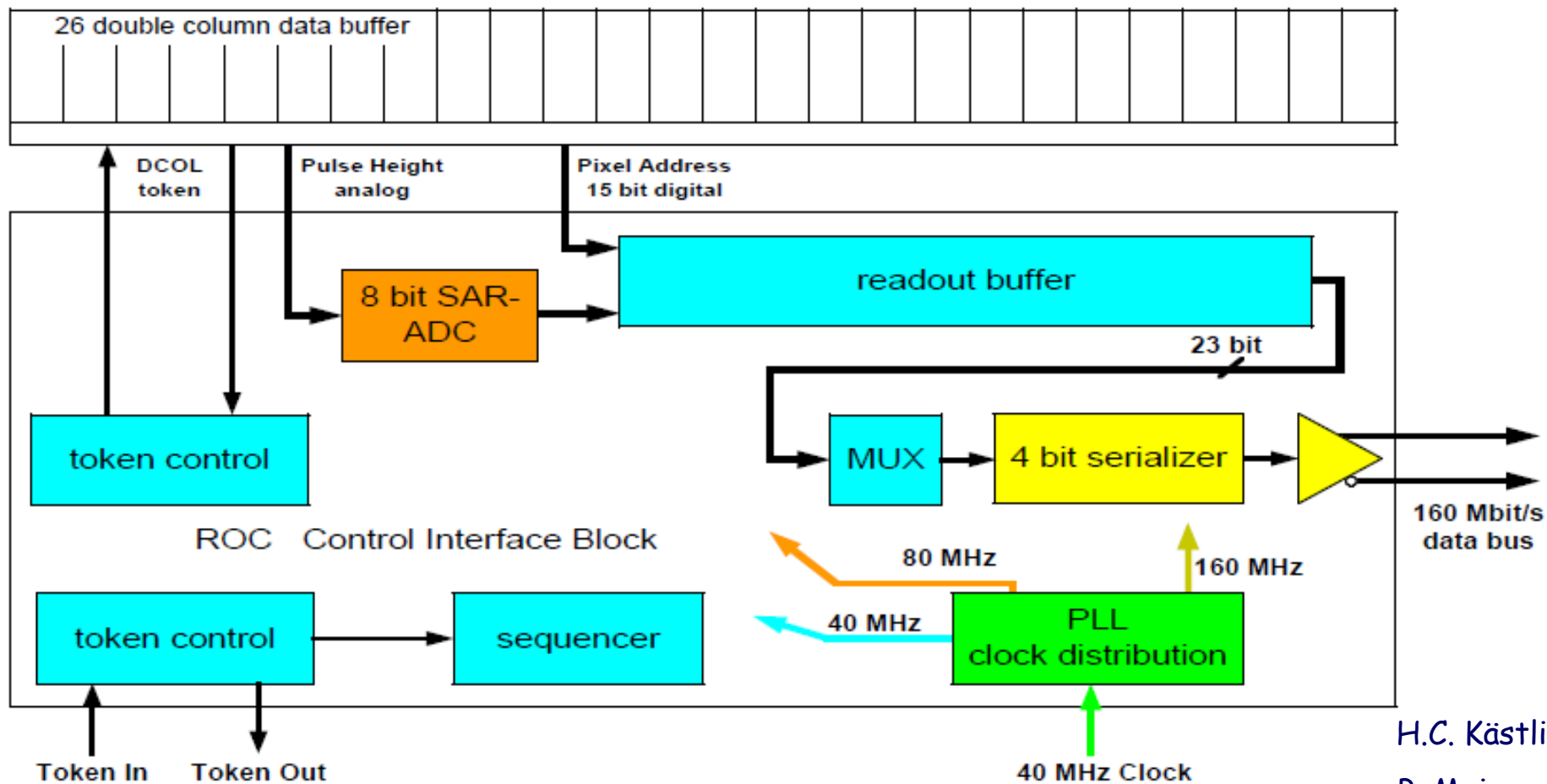
TBM readout: 320 MHz

μ twisted CCA pair (Copper-Cladded Aluminum)

1 m long link at 320 MHz from TBM to POH; chips done



Digital ROC Readout



H.C. Kästli

B. Meier

ROC : Other improvements

- Lower signal threshold ($\sim 3000e^- \rightarrow \sim 150e^-$ amp.noise)
 - chip internal X-talk (analog: identified, easy to solve \rightarrow layout
digital: identified, more simulation req.)
- Linearity of pulse height (understood)
- Power-up behavior
- Removal of unused DACs
- Submission planned for Sept. 2011
- 2nd submission possible in 2012

TBM (Token Bit Manager)

Staged development (Ed Bartz, Rutgers)

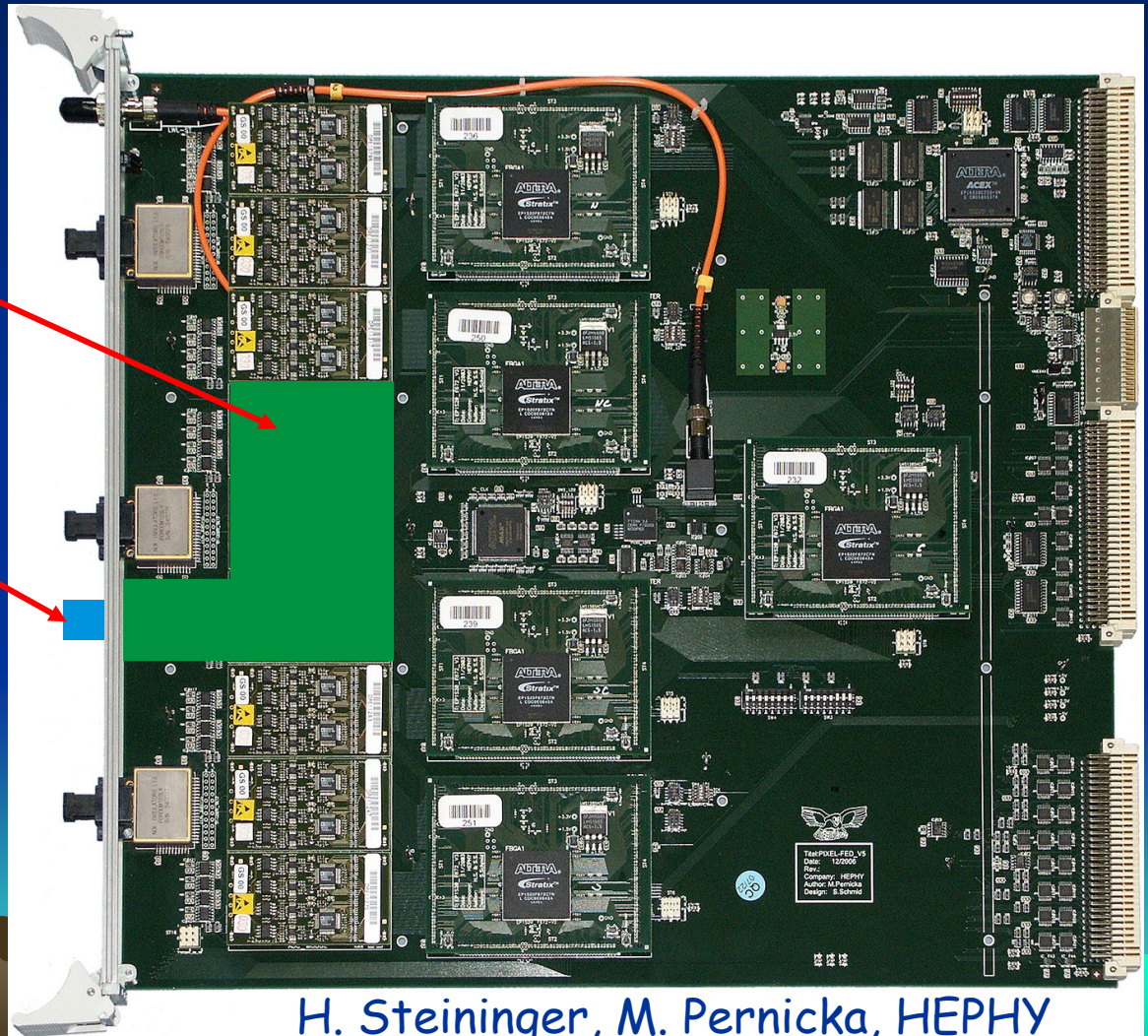
1. Step: keep analog data handling, replace digital TBM core *
 - correct minor impracticability's
 - install handling of PKAM events
2. Step: replace analog section by digital version (160MHz)
3. Step: shift ROC data to 400(320)MHz, 4/5 bit encoding

Modification of Pixel-FED

- Keep single slot size
- Keep VME base board

New daughter board
(instead of 3 ADC cards)
including Zarlink receiver

- Don't need to remove current ARx12 → allows easy swapping between old and new systems
- Need new front panel in any case



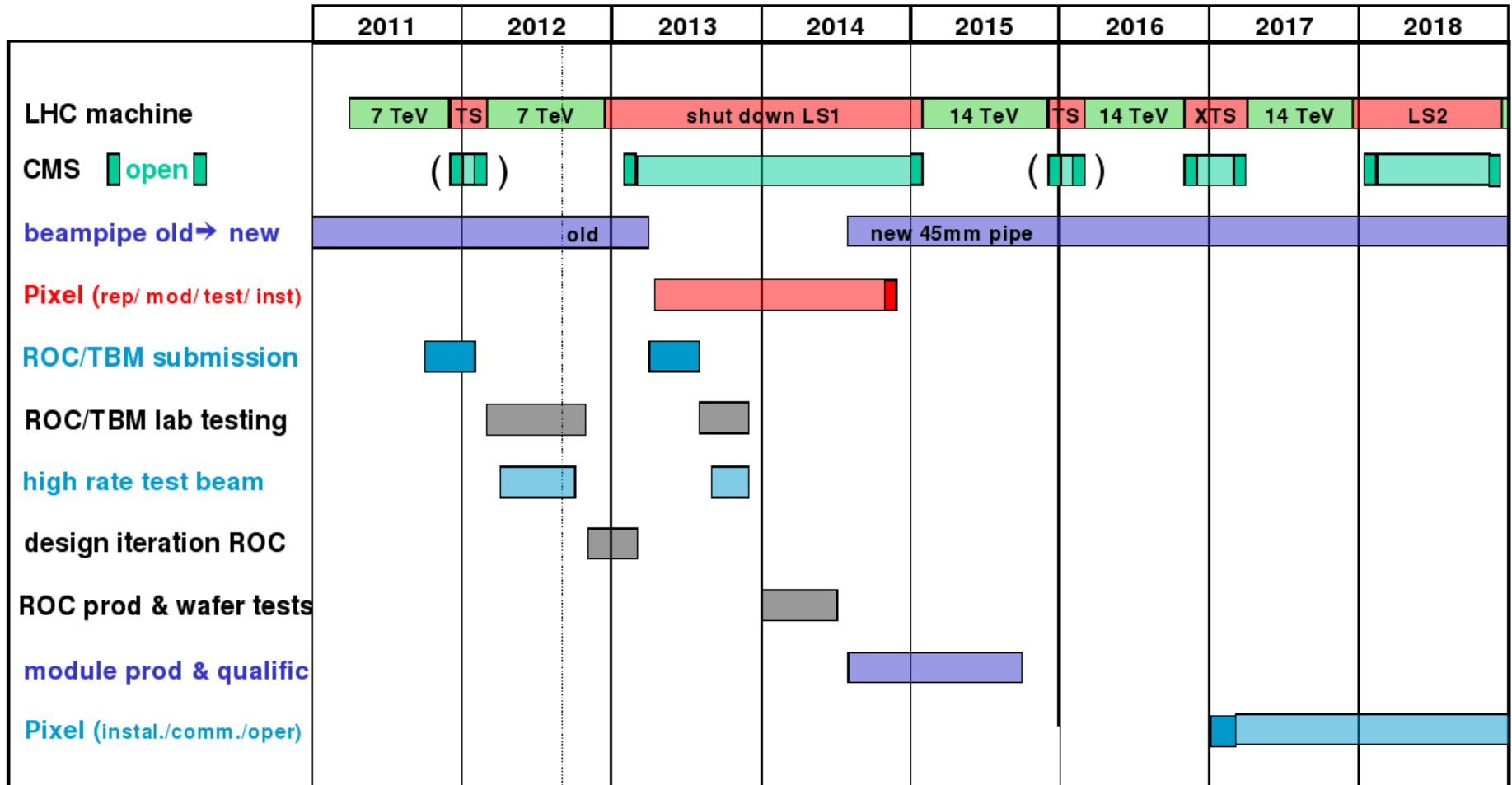
Powering aspects

- LV power demands are based on present ROC data and up scaled
- up scaling existing power system leads to large cable losses (cable overheating !) and lack of power
- ➡
- employ DCDC-converter close to detector and modify power supplies (A4603 from CAEN) to operate at higher voltage (→ less cable losses)

(for details of the converter see talk by Katja Klein)



ROC/TBM submission & Pixel Testbeams



Some duties for LS1 (proposal)

- repair work if needed (BPIX, FPIX)
- install "Pilot system" on 3rd disk place
 - few blades with new FPIX design (2x8 mod.)
 - new HDI, new AI cables, new port card, POHs instead AOHs
 - ➔ test new electronics readout chain, DAQ handling (2014-2016)
- "pixel-cooling-insertion" device
 - full BPIX dummy, correct cooling loops, resistive loads
 - ➔ CO₂ cooling test at TIF (2013-2016)
 - ➔ mechanical insertion test into CMS (2013)
 - ➔ equip few ST-slots with DCDC-conv. test new power system (upgraded A4603 PS-modules + dummy ROCs) (P5 & TIF)
 - ➔ final P5 cooling commissioning in 2017 just before insertion of new BPIX

Summary

- Roots of the CMS pixel upgrade project:
 - limitations for high luminosity & non-stand. LHC modes
 - partial detector replacement (after $\sim 150 \text{ fb}^{-1}$)
- Project has been detailed & enlarged:
 - 4 hit system (improve tracking seed, vertexing, track efficiency)
 - reduce material budget (improve impact parameter, b-tagging)
 - keep inefficiencies low (up to $2 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$, also for $> 25 \text{ ns}$ mode)
- Mandatory constraints:
 - minimize impact on other CMS detectors (no new piping, cabling...)
 - minimize changes of DAQ, DCS and other CMS-global software
 - minimize radiation exposure of service personnel