

Reproducible Open Benchmarks

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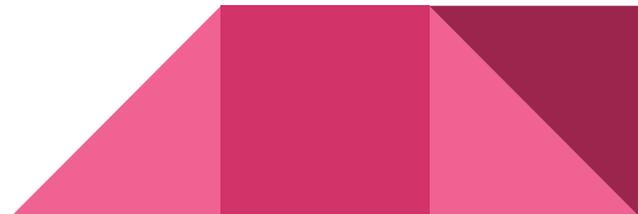
Background

- Inspired by the “Machine Learning Landscape of Top Taggers Paper”
 - <https://arxiv.org/abs/1902.09914v2>
 - They compiled and compared multiple top tagging models
- A significant amount of time is required to organize and evaluate large benchmarks
- Goal of the ROB is to provide a platform that **automates the collection, execution and comparison of submissions** of participants in the benchmark



How the ROB works

1. A workflow is defined by the coordinator of the benchmark along with input data
2. The users provide code that satisfy the steps in the workflow
3. The ROB back-end processes the workflow using the code provided by the user, and evaluates the metrics set by the coordinator
4. The Front end displays the results



Example Workflow: Top Tagging

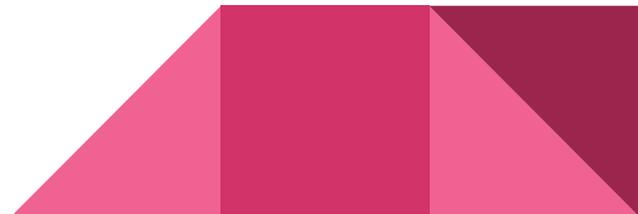
- Coordinator provides: input data
- Coordinator provides 2 steps for submission:
 - Preprocessing
 - Tagger
- Coordinator Provides: Result evaluation task, which is displayed in the front end

User provides code to preprocess the input data, and a top tagging model which is used to evaluate the data



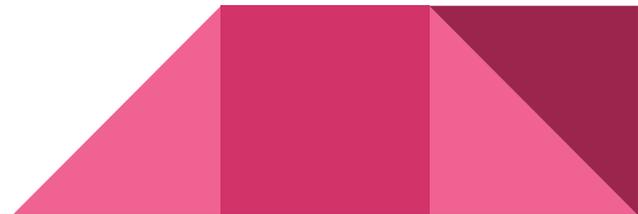
Current Problem:

- ROB currently requires participants to package their submissions into docker containers
 - Steep learning curve for people unfamiliar



Solution

- In order to increase ease of use, we implement support for the commonly used Jupyter Notebooks
 - We allow users to submit their implementations directly as Jupyter Notebooks



How to run a Jupyter Notebook?

- Jupyter Notebook executions are cell by cell
- Cannot be run like a python script

Issues we needed to solve:

- How to define parameters within a jupyter notebook
 - How to run the same jupyter notebook with new parameters without needing to open and edit the notebook it self
 - How to run the Jupyter Notebook within the ROB without the need to open the python notebook using the Jupyter Notebook Editor
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Papermill!



- Papermill is a convenient way to run Jupyter Notebooks
 - It is a tool that parametrizes, and executes notebooks in its entirety
 - <https://papermill.readthedocs.io/en/latest/>

How Papermill Works

- Users are required to define one cell in their Jupyter Notebook with the tag “parameters”

```
In [1]: parameters ✕  ...  Add tag
```

```
1 # This cell is tagged `parameters`  
2 alpha = 0.1  
3 ratio = 0.1
```

- Users need to ensure that the entire notebook runs with no errors (just like any python script)
- Ensure that all parameters that can or might be changed in the future is included in the parameters cell

How Papermill Works Continued.

- Users can then execute the notebook using the papermill “execute notebook function”
 - Inputs are:
 - Path to the input
 - Path to the output notebook
 - Dictionary of parameters
- Will execute your notebook similar to how scripts can be executed
- Will generate an output notebook at the path of the output notebook, with an output that is exactly like if you pressed “run all cells” in the Jupyter Notebooks
- Parameter values in the notebook will be replaced by the values defined in the function

```
execute_notebook(<input notebook>, <output notebook>, <dictionary of parameters>)
```

```
import papermill as pm

pm.execute_notebook(
    'path/to/input.ipynb',
    'path/to/output.ipynb',
    parameters=dict(alpha=0.6, ratio=0.1)
)
```

Implementing Papermill Into ROB

- Create a new **Step Type** that uses papermill to execute the notebook
 - Current Step Types: ContainerStep, FunctionStep
 - Added Step Type: NotebookStep
 - This is the function in the ROB that takes defined workflow inputs and user inputs, and runs the functions
 - Done by implementing a subclass of the WorkflowStep Class
 - Create a new “worker” that executes steps of the given context
 - Done by implementing a sub class of the Worker Class in ROB
 - A function that calls the step and executes the function
 - Create another worker that is able to run Jupyter Notebooks contained within docker containers
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Hello World Demo

Inputs:

- Data: list of names
- Jupyter Notebook that reads the list of names and writes greetings to an output file

Output: List of greetings

- List of greetings is then analyzed by counting average characters per line and max output length, which is then put in a json file as the final “output”

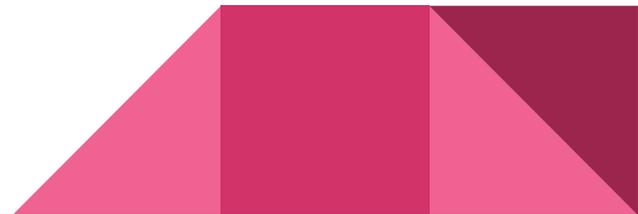


How to run demo:

- Create ROB User
- Create Hello World Workflow
- Start the Hello World Demo Run
- Submit python notebook and data in the command line
- Retrieve Results

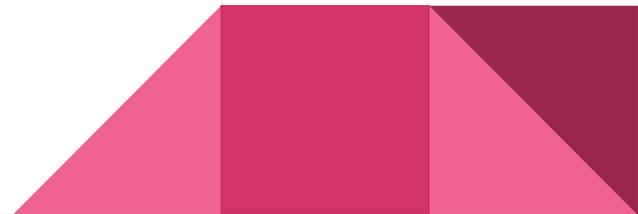
Detailed functions/explanations at:

<https://github.com/scailfin/rob-demo-hello-world>



Jet Flavor Demo

- Implementation of the Jet Flavor Dataset into the ROB
 - http://mlphysics.ics.uci.edu/data/hb_jet_flavor_2016/
- Inspired by the “Jet Flavor Classification in High-Energy Physics with Deep Neural Networks” paper
 - <https://arxiv.org/pdf/1607.08633.pdf>



- Lots of combinations of features that need to be compared
- Hard to compile all the models and train all of them individually
- Implement into the ROB as a workflow to make comparison and training on the same validation set easier and more organized

TABLE I: Performance results for networks using track-level, vertex-level or expert-level information. In each case the jet p_T and pseudorapidity are also used. Shown for each method is the Area Under the Curve (AUC), the integral of the background efficiency versus signal efficiency, which have a statistical uncertainty of 0.001 or less. Signal efficiency and background rejections are shown in Figs. 6-10.

Inputs			Technique	AUC
Tracks	Vertices	Expert		
✓			Feedforward	0.916
✓			LSTM	0.917
✓			Outer	0.915
		✓	Feedforward	0.912
		✓	LSTM	0.911
		✓	Outer	0.911
✓	✓		Feedforward	0.929
✓	✓		LSTM	0.929
✓	✓		Outer	0.928
		✓	Feedforward	0.924
		✓	LSTM	0.925
		✓	Outer	0.924
✓		✓	Feedforward	0.937
✓		✓	LSTM	0.937
✓		✓	Outer	0.936
	✓	✓	Feedforward	0.931
	✓	✓	LSTM	0.930
	✓	✓	Outer	0.929
✓	✓	✓	Feedforward	0.939
✓	✓	✓	LSTM	0.939
✓	✓	✓	Outer	0.937

Workflow

User inputs:

- Model architectures
- Preprocessing script
- Training script

Workflow Coordinator inputs:

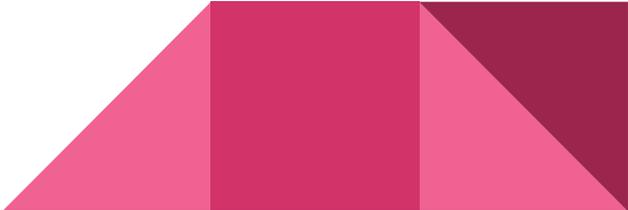
- Training and validation data
- Validation script



Summary

- Implemented jupyter notebooks into the ROB as a form of input
- Created demos using Jupyter Notebooks for use of the ROB for
 - Quickdraw dataset
 - Jet Flavor Dataset
 - Top Tagging dataset
 - Mnist Dataset
- Github Repositories: <https://github.com/anrunw/ROB>,
<https://github.com/scailfin/flowserv-core>

Future Work:

- Presenting at the ML4Jets conference on 6/7
 - Fix flask web server for browser input into ROB
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Questions?

