

Equivariant BV formalism for string worldsheet

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Introduction: “What is string theory?”

What properties should a 2D sigma model satisfy to serve as a string worldsheet theory?

Let us think of it as a BV theory.

Integration over Lagrangian submanifolds

there is canonical integration measure (more precisely, a PDF) on any families of Lagrangian submanifolds, not only on families of conormal bundles. If gauge fermions Ψ_1, \dots, Ψ_n define n tangent vectors to LAG at the point $L \in LAG$ then the measure is:

$$\int_L \Psi_1 \cdots \Psi_n \exp(S_{BV}) \quad (1)$$

Kalkman element

It seems that there is a general theme which plays a role here. It is basically Kalkman map between Cartan and Weyl models of equivariant cohomology.

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Restriction of form to orbit

Let us illustrate it by the following simple example. Consider a manifold M with the action of a Lie group G . Consider differential forms of mixed degree on M . Pick a point $x_0 \in M$ and consider the orbit Gx_0 . Then, for every ω we can consider the differential form on G :

$$x \mapsto g.x, dx \mapsto (dg).x$$

This can be represented as follows:

$$\omega \mapsto (\exp((dgg^{-1})^a \iota_a) \omega) (x = gx_0, dx = 0)$$

(We think of forms on M as functions on ΠTM , and forms on G as functions on ΠTG .) The secret of the formula is:

$$\left(d_M + \frac{1}{2} c^a c^b f_{ab}^c \frac{\partial}{\partial c} + \mathcal{L}\langle c \rangle \right) \exp \iota\langle c \rangle = \exp \iota\langle c \rangle \left(d_M + \frac{1}{2} c^a c^b f_{ab}^c \frac{\partial}{\partial c} \right) \quad (2)$$

Slight generalization

After the first step (which was $\omega \mapsto (\exp((dgg^{-1})^a \iota_a) \omega)$), we could have (instead of putting $dx = 0$) integrated over a submanifold $gN_0 \subset M$ where N_0 is some compact submanifold of M . (Choice of a point x_0 is a particular case, when N_0 is one point.) If we take G the whole group of diffeomorphisms of M , then this prescription cooks out of ω an inhomogeneous differential form on the space of submanifolds $N \subset M$.

Generalization

We have some representation V of Cg . Then Eq. (2) still holds, where d_M should be compatible with the differential of Cg .

PDF on LAG

The group of odd canonical transformations, and its Lie superalgebra \mathfrak{g} , acts on **half-densities** on the BV phase space. Moreover, there is an action of Cg , where $\iota\langle v \rangle$ is multiplication of a half-density by the BV Hamiltonian of v (which we denote \underline{v}):

$$\iota\langle v \rangle \rho_{1/2} = \underline{v} \rho_{1/2}$$

The canonical BV Laplacian Δ_{can} is compatible with $d_{\mathbb{C}g}$.

The Eq. (2) produces the PDF on \mathbb{G} (the string measure):

$$\Omega(g, dg) = \int_{g^{\mathbb{L}_0}} \exp \left(\frac{dg g^{-1}}{\rho_{1/2}} \right) \rho_{1/2} \quad (3)$$

Worksheet diffeomorphisms

We believe that **diffeomorphisms of the string worldsheet** are crucial ingredient in string worldsheet theory.

How do they act in the BV phase space?

They should preserve S_{BV} . As they are gauge symmetries, it is natural to conjecture that their BV hamiltonians should be exact. In other words, for every vector field ξ on the worldsheet we should get some function $\phi\langle\xi\rangle$ on the BV phase space such that $\{S_{BV}, \phi\langle\xi\rangle\}$ generates the action of diffeomorphisms. We should definitely require:

$$\{\{S_{BV}, \phi\langle\xi\rangle\}, \{S_{BV}, \phi\langle\eta\rangle\}\} = \{S_{BV}, \phi\langle[\xi, \eta]\rangle\}$$

where $[\xi, \eta]$ is the commutator of two vector fields on Σ .

What else should we require? We need to turn Ω into a base form. It is already invariant, but it is not horizontal.

But it has some **special property** (which we explain on next slide: [Special properties of \$\Omega\$](#)) which helps to turn it into a base form.

Case of bosonic string

The BV phase space is:

$$M = \Pi T^* \left(\frac{\Pi T H \times X}{H} \right)$$

Here we quotient by the action of H where H acts on $\Pi T H$ **from the right**. The Q_{BRST} comes from the canonical nilpotent vector field on $\Pi T H$. We want Q_{BRST} to preserve the volume on $\frac{\Pi T H \times X}{H}$. This is some condition on the trace of the structure constant and the **div**'s of generators.

But the **left** action of H on $\Pi T H$ remains. It is generated by an exact Hamiltonian:

$$H\langle\xi\rangle = \Delta(\xi^\alpha c_\alpha^*)$$

This means that:

Gauge symmetries act on the BV phase space

An equivariant form is given by:

$$\int_L \exp(S_{BV} + \Psi + t^\alpha c_\alpha^*)$$

Special properties of Ω

The string form Ω defined by Eq. (3) is very special. Besides $d\Omega = 0$ it satisfies, for any $v \in \mathfrak{h} \subset \text{Vect}(\text{LAG})$, the following special properties:

$$v \mapsto \iota\langle v \rangle \Omega \quad \text{is injective map} \quad (4)$$

$$\text{exists } d_\Omega : d \iota\langle v \rangle \Omega = \iota\langle d_\Omega v \rangle \Omega \quad (5)$$

where d_Ω corresponds to the BV Laplacian w.r.to the half-density $\rho_{1/2}$. Eqs (4) and (5) are very special. They imply:

$$d e^{\iota\langle v \rangle} \Omega = e^{\iota\langle v \rangle} \iota \left\langle d_\Omega v + \frac{1}{2} [v, v] \right\rangle \Omega$$

Therefore, the **equivariant** analogue of Ω in the Cartan model can be constructed as follows:

$$\Omega^c(\mathbf{t}) = \exp(\iota\langle i(\mathbf{t}) \rangle) \Omega$$

$$\text{where: } d_\Omega i(\mathbf{t}) + \frac{1}{2} [i(\mathbf{t}), i(\mathbf{t})] = l(\mathbf{t})$$

The construction of the Cartan equivariant form is recast as a construction of a representation of $D\mathfrak{h}$ in functions on BV phase space. In other words, we need a morphism

$$D\mathfrak{h} \longrightarrow \mathfrak{g}$$

(where \mathfrak{g} is the Lie superalgebra of infinitesimal BV-canonical transformations) such that $d_{D\mathfrak{h}}$ agrees with d_Ω (remember d_Ω is the same as $\{S_{\text{BV}}, -\}$). We denote it like this:

$$(D\mathfrak{h}, d_{D\mathfrak{h}}) \longrightarrow (\mathfrak{g}, \{S_{\text{BV}}, -\})$$

Deformation complex

Equivariant Master Equation

Let us reformulate. The equivariant Master Equation is:

$$\Delta_{\text{can}}\rho_{1/2}(\mathbf{t}) = \underline{l(\mathbf{t})}\rho_{1/2}(\mathbf{t})$$

where $\underline{l(\mathbf{t})}$ is the odd moment map of \mathfrak{h} . We should also require \mathfrak{h} -covariant dependence on \mathbf{t} . We write:

$$\rho_{1/2}(\mathbf{t}) = \exp\left(S_{\text{BV}} + \underline{i(\mathbf{t})}\right)$$

Deformations of solutions (integrated vertex operators)

Such solutions admit deformations, corresponding to the deformations of string background. Infinitesimal deformations can be represented in the form:

$$\delta\rho_{1/2}(\mathbf{t}) = f(\mathbf{t})\rho_{1/2}(\mathbf{t})$$

where $f(\mathbf{t})$ satisfies the equation:

$$d_{\text{D}\mathfrak{h}}f + \{i(\mathbf{t}), f\} = 0$$

This is Cartan model. If we relax the \mathfrak{h} -covariance of $f(\mathbf{t})$, and allow it to also depend on θ then it is:

$$(d_{\text{D}\mathfrak{h}} + d_{\text{W}})f(\mathbf{t}, \theta) + \{l(\theta), f(\mathbf{t}, \theta)\} + \{i(\mathbf{t}), f(\mathbf{t}, \theta)\} = 0$$

where d_{W} is the differential of the Weyl algebra of \mathfrak{h} formed by letters θ and \mathbf{t} (sometimes θ is denoted A and \mathbf{t} is denoted F). **The differential:**

$$d_{\text{D}\mathfrak{h}} + d_{\text{W}} + \{l(\theta), -\} + \{i(\mathbf{t}), -\} \tag{6}$$

is nilpotent.

Weyl algebra $dA = F + AA$, $dF = AF$ is not minimal, because linearized differential is nonzero: $d_0A = F$. We can turn it into a minimal algebra by adding a central element Z and saying $dA = ZF + AA$, $dF = AF$. This is Koszul dual to the Lie superalgebra $\text{D}\mathfrak{h}' = \text{D}\mathfrak{h} \oplus \mathbf{C}d_{\text{D}\mathfrak{h}}$.

Another point of view on the deformation complex

Unintegrated vertices

Instead of \mathfrak{h} -invariant f , let us consider arbitrary v satisfying $\{S_{\text{BV}}, v\} = 0$. This is "unintegrated vertex operator". We want to construct from v a closed PDF on H . The insertion procedure would require integration of this PDF over an appropriate cycle.

Following the [\[Kalkman element\]](#) we would write something like:

$\omega \stackrel{?}{=} \int_{\text{hL}} \exp \left\{ \iota \langle \text{dhh}^{-1} \rangle, - \right\} \nu$ But there is no $\iota \langle . . . \rangle$... We only have $i \langle . . . \rangle$. In bosonic string $i \langle \xi \rangle = \int_{\Sigma} \xi^\alpha c_\alpha^*$, and it works:

Bosonic string:

$$\Omega_C = \int_{\text{gL}} \exp \left(S_{\text{BV}} + \text{dgg}^{-1} + c_\alpha^* \mathbf{t}^\alpha \right)$$

$$\left\{ \iota \langle \text{dhh}^{-1} \rangle, - \right\} \text{ gives } \left\{ \int_{\Sigma} \xi^\alpha c_\alpha^*, - \right\} \text{ (Just "strips" } c \text{ and } \bar{c} \text{)}$$

Remember the [Kalkman element](#) required a representation of $\mathcal{C}\mathfrak{h}$; any representation of $\mathcal{C}\mathfrak{h}$ gives a representation of $\mathcal{D}\mathfrak{h}$, but not vice-versa.

But will it work in general case, when $i \langle \xi \rangle$ is nonlinear in ξ and $[i \langle \xi \rangle, i \langle \xi \rangle] \neq 0$? It turns out that the answer is "yes", although the naive $\exp \left\{ \iota \langle \text{dhh}^{-1} \rangle, - \right\}$ (whatever it would mean) will not work. But actually exists a generalization of the Kalkman formula which only requires a representation of $\mathcal{D}\mathfrak{h}$:

$$\omega \langle V \rangle = \int_{\text{hL}} \left[\left(\text{P exp} \int_0^1 \mathcal{A}_\tau d\tau \right) V \right] \rho_{1/2} \quad (7)$$

$$\text{where } \mathcal{A}_\tau d\tau = \left\{ \frac{d}{du} \Big|_{u=0} \frac{i(u d\tau \text{dgg}^{-1} + (\tau - \tau^2)(\text{dgg}^{-1})^2)}{, -} \right\}$$

Derivation

We know that $\{l(A), -\} + \{i(F), -\}$ is Maurer-Cartan (because the differential given by Eq. (6) is the differential in the deformation complex of the equivariant half-density!).

Then we consider the Kalkman embedding:

$$\begin{aligned} W\mathfrak{g} &\rightarrow W\mathfrak{g} \otimes \Omega^1(\mathbf{R}_s) \\ \theta_a &\mapsto \tilde{\theta}_a = \tau \theta_a \\ \mathbf{t}_a &\mapsto \tilde{\mathbf{t}}_a = d\tau \theta_a + \tau \mathbf{t}_a + (\tau^2 - \tau) f_a^{bc} \theta_b \theta_c \end{aligned}$$

We have:

$$\left(d_{\mathcal{D}\mathfrak{h}} + d_W + d\tau \frac{\partial}{\partial \tau} + \{l(\tilde{\theta}), -\} + \{i(\tilde{\mathbf{t}}), -\} \right)^2 = 0 \quad (8)$$

This implies:

$$\left(\text{P exp} \int_0^1 \mathcal{A}_\tau d\tau \right) (d_{\mathcal{D}\mathfrak{h}} + d_W) = \left(d_{\mathcal{D}\mathfrak{h}} + d_W + \{l(\underline{\theta}), -\} + \{i(\underline{\mathbf{t}}), -\} \right) \left(\text{P exp} \int_0^1 \mathcal{A}_\tau d\tau \right)$$

Remember that $d_{Dh} = \Delta_{SBV} = \Delta_0 + \{S_{BV}, -\}$.

Let us put $\mathbf{t} = 0$ and $\boldsymbol{\theta} = dhh^{-1}$.

Let us put $\mathbf{F} = 0$ and $\mathbf{A} = dhh^{-1}$. But, consider some vertex operator \mathbf{V} which is **not** \mathbf{H} -invariant. Our \mathbf{V} will not contain any \mathbf{A} and \mathbf{F} , and will satisfy the Master Equation for vertex operators:

$$d_{Dg}\mathbf{V} = 0$$

Then:

$$(d_{\text{Weyl}} + \{I(dhh^{-1}), -\}) \int_{hL} \left[\text{P exp} \left(\int_0^1 \mathcal{A}_\tau d\tau \right) \mathbf{V} \right] \rho_{1/2} = 0$$

This is the same as to say:

$$d_{(h)} \int_{hL} \left[\text{P exp} \left(\int_0^1 \mathcal{A}_\tau d\tau \right) \mathbf{V} \right] \rho_{1/2} = 0$$

In other words, we have constructed a closed differential form on \mathbf{H} . When we are inserting an unintegrated vertex \mathbf{V} , we have to integrate this closed form over an appropriate cycle in \mathbf{H} .

Applications

At this time we do not have a single example of string worldsheet theory where $i(\mathbf{t})$ would not be linear. We suspect that pure spinor formalism is an example. We [constructed](#) $i(\mathbf{t})$ [for pure spinor string in](#) $\text{AdS}_5 \times S^5$, but only to the first order in \mathbf{t} .