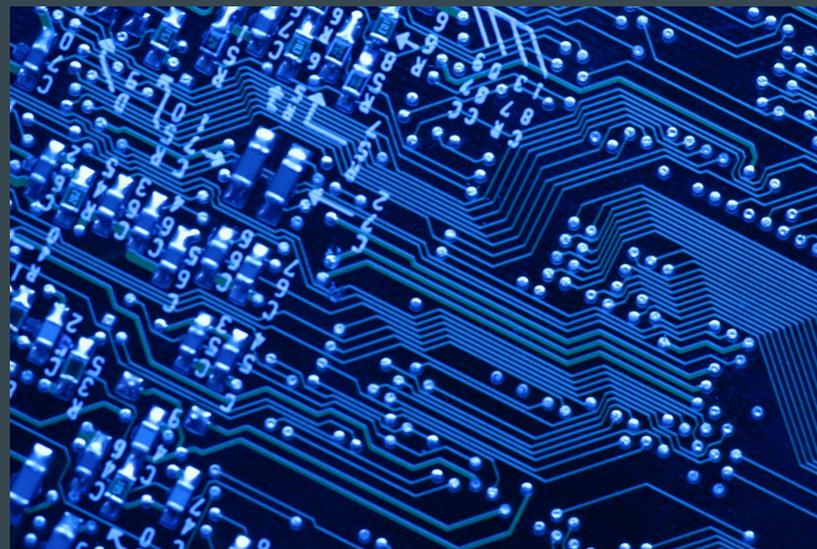
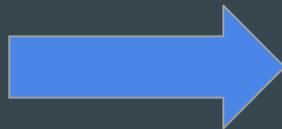
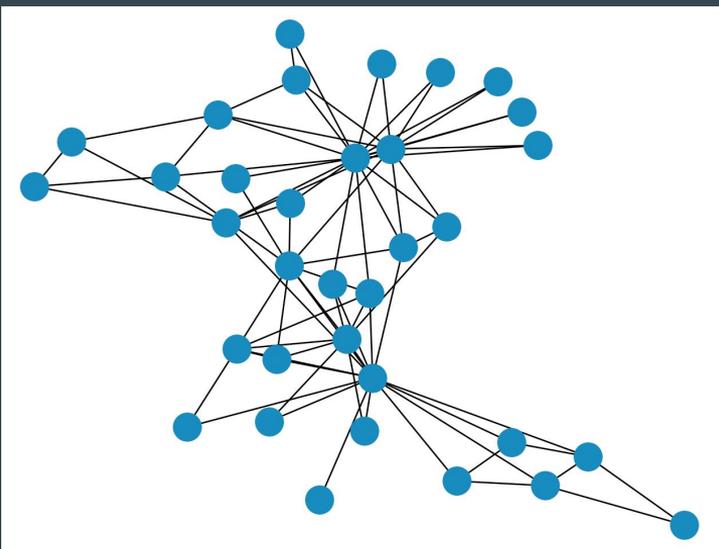


# PyTorch Geometric to HLS

An hls4ml add-on for conversion of Graph Neural Networks



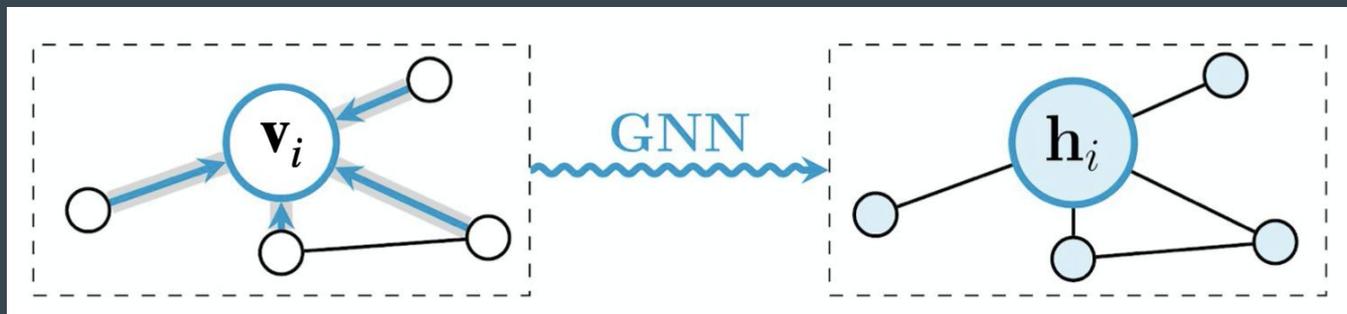
[https://github.com/abdelabd/hls4ml/tree/pyg to hls rebase](https://github.com/abdelabd/hls4ml/tree/pyg%20to%20hls%20rebase)

# Graph Neural Networks

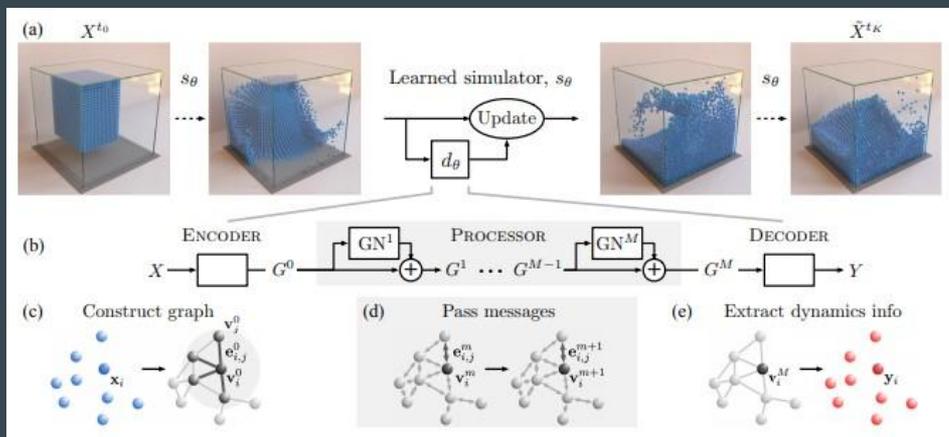


PyTorch  
geometric

- $G = (V, E, \text{edge\_index})$ ;
  - $V[i,j]$  =  $j$ th attribute of  $i$ th vertex
  - $E[i,j]$  =  $j$ th attribute of  $i$ th edge
  - $\text{edge\_index}[0,i]$  = the index of the sending node for the  $i$ th edge
  - $\text{edge\_index}[1,i]$  = the index of the receiving node for the  $i$ th edge
- We can represent arbitrary-dimensional objects as ‘nodes’
- We can represent arbitrary-dimensional relationships as ‘edges’
- Benefits: efficient encoding of context, generalizability, permutation invariance

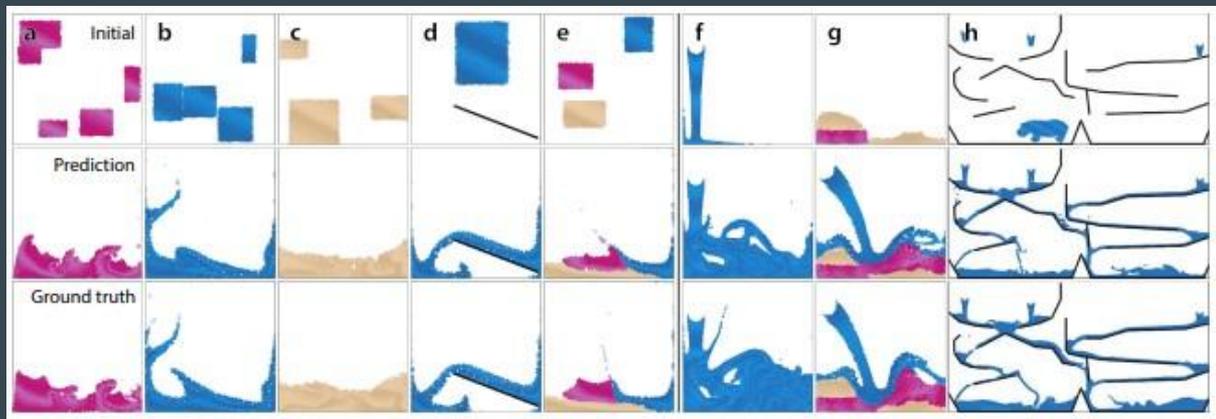


# Generalizable, Contextual

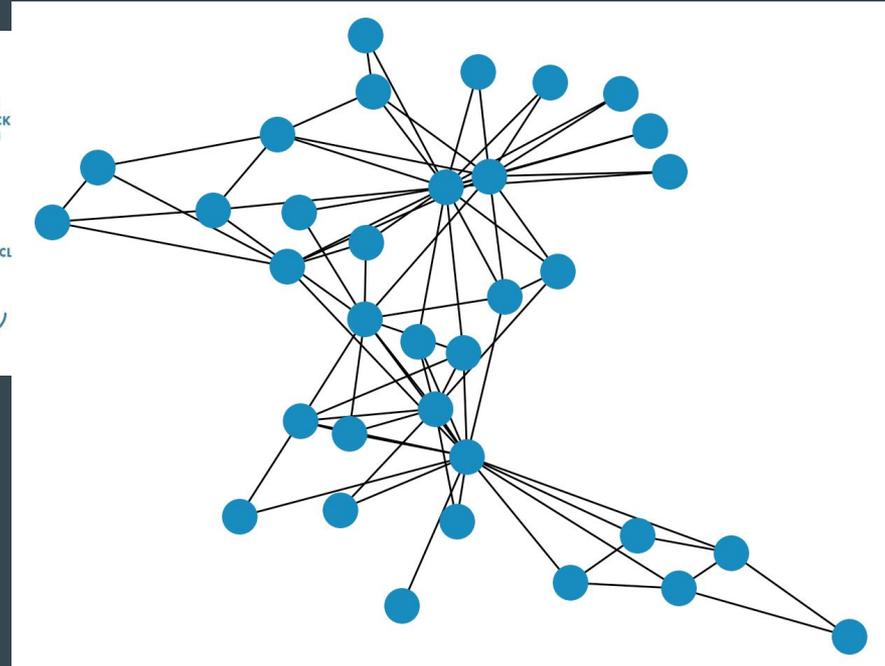
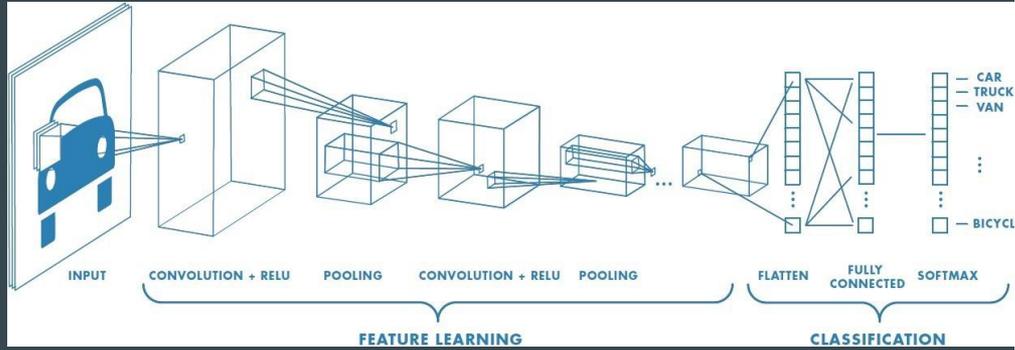


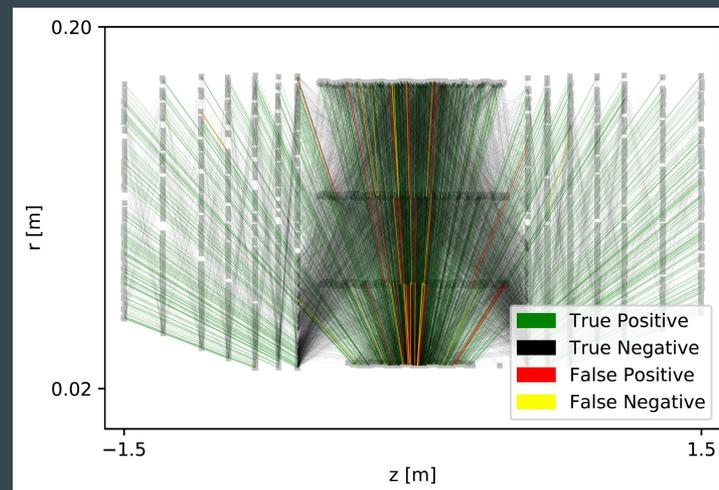
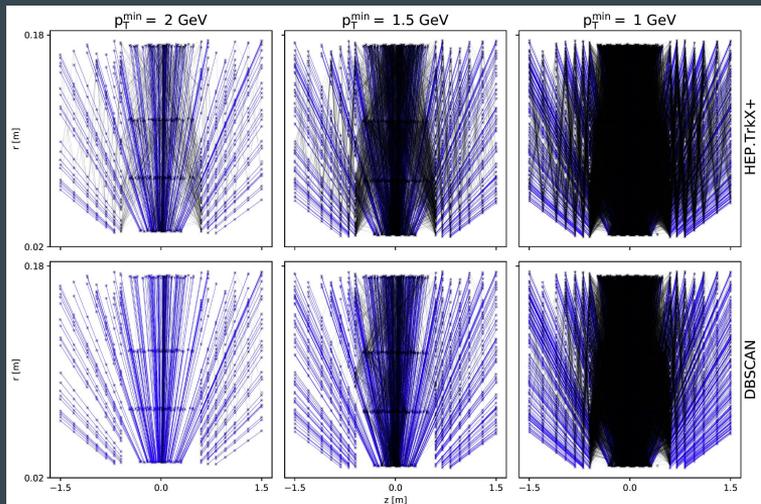
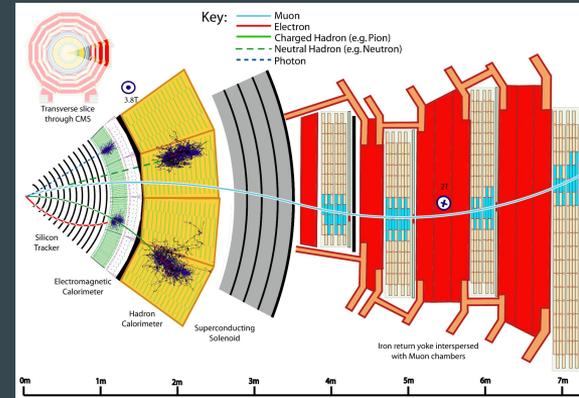
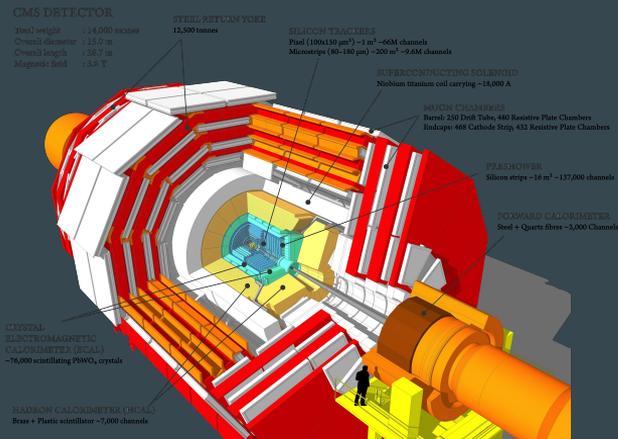
*Learning to Simulate Complex Physics with Graph Networks, DeepMind 2020*

<https://arxiv.org/abs/2002.09405>

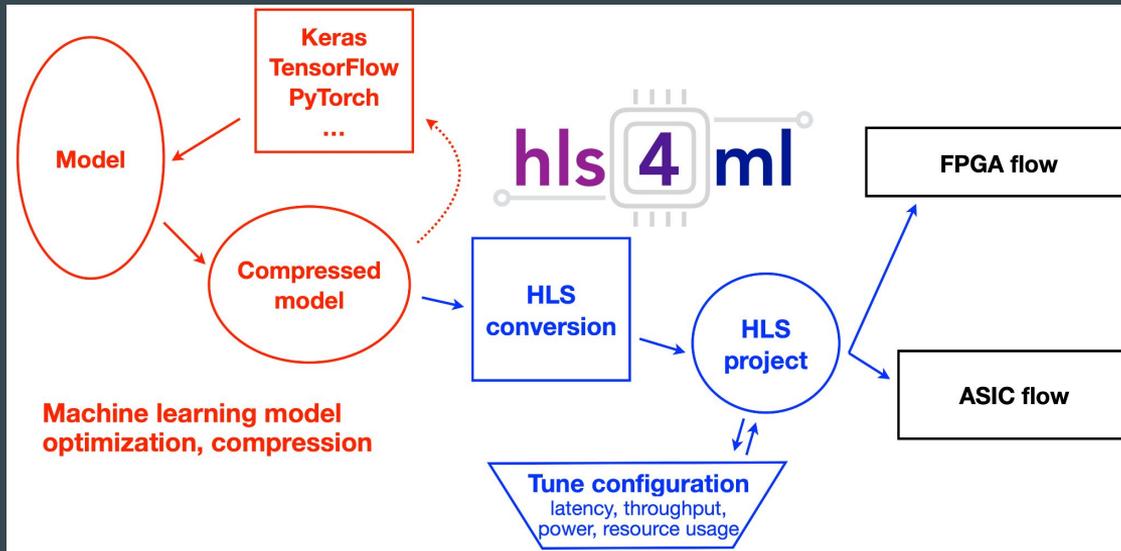
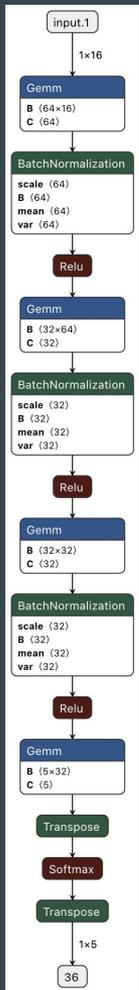


# Permutation Invariant





# hls4ml



```
layer2_t layer2_out[N_LAYER_2];
#pragma HLS ARRAY_PARTITION variable=layer2_out complete dim=0
nnet::dense<input_t, layer2_t, config2>(input1, layer2_out, w2, b2); // fc1

layer4_t layer4_out[N_LAYER_2];
#pragma HLS ARRAY_PARTITION variable=layer4_out complete dim=0
nnet::relu<layer2_t, layer4_t, ReLU_config4>(layer2_out, layer4_out); // act1

layer5_t layer5_out[N_LAYER_5];
#pragma HLS ARRAY_PARTITION variable=layer5_out complete dim=0
nnet::dense<layer4_t, layer5_t, config5>(layer4_out, layer5_out, w5, b5); // fc2

layer7_t layer7_out[N_LAYER_5];
#pragma HLS ARRAY_PARTITION variable=layer7_out complete dim=0
nnet::relu<layer5_t, layer7_t, ReLU_config7>(layer5_out, layer7_out); // act2

layer8_t layer8_out[N_LAYER_8];
#pragma HLS ARRAY_PARTITION variable=layer8_out complete dim=0
nnet::dense<layer7_t, layer8_t, config8>(layer7_out, layer8_out, w8, b8); // fc3

layer10_t layer10_out[N_LAYER_8];
#pragma HLS ARRAY_PARTITION variable=layer10_out complete dim=0
nnet::relu<layer8_t, layer10_t, ReLU_config10>(layer8_out, layer10_out); // act3

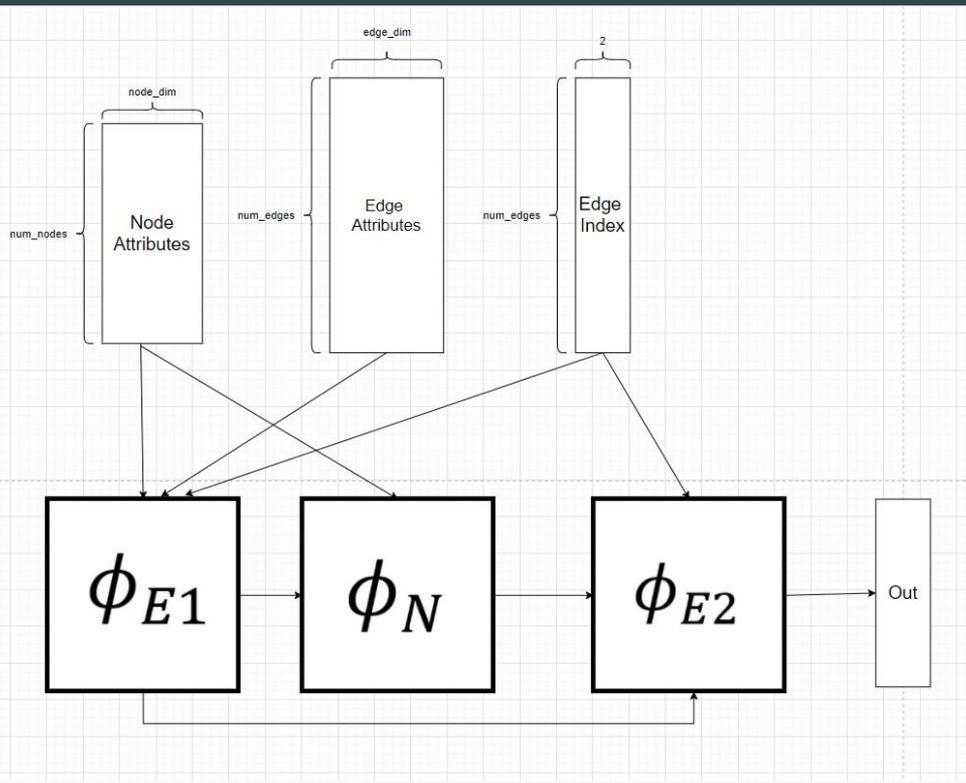
layer11_t layer11_out[N_LAYER_11];
#pragma HLS ARRAY_PARTITION variable=layer11_out complete dim=0
nnet::dense<layer10_t, layer11_t, config11>(layer10_out, layer11_out, w11, b11); // fc4

nnet::softmax<layer11_t, result_t, Softmax_config12>(layer11_out, layer12_out); // softmax
```

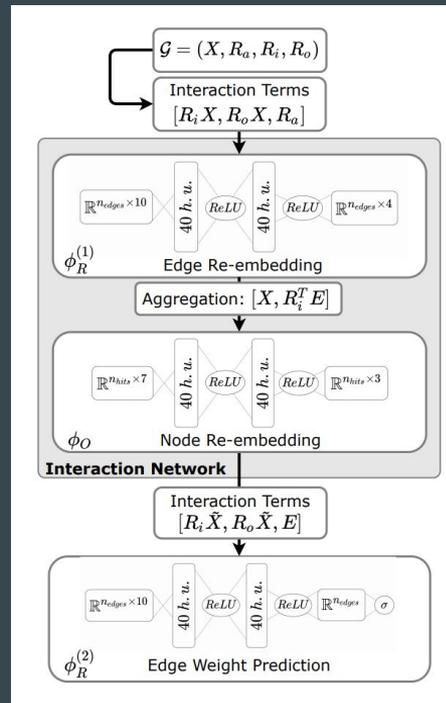
See [https://github.com/jmduarte/pytorch\\_dev\\_hls4ml/tree/commit\\_hls](https://github.com/jmduarte/pytorch_dev_hls4ml/tree/commit_hls)

# Graph Neural Networks: non-feedforward data flow

← Interaction Network



- <https://arxiv.org/abs/1612.00222>
- <https://arxiv.org/abs/2103.16701>
- [https://github.com/GageDeZoort/interaction\\_network\\_paper](https://github.com/GageDeZoort/interaction_network_paper)



## torch\_geometric.nn.conv.MessagePassing

- Message  $\rightarrow$  Aggregate  $\rightarrow$  Update

```
def forward(self, data): #x, edge_index, edge_attr):
    x = data.x
    edge_index = data.edge_index
    edge_attr = data.edge_attr

    # Message
    x_i, x_j = x[edge_index[1]], x[edge_index[0]]
    msg_out = self.message(x_i, x_j, edge_attr) # self.message(edge_index, edge_attr)

    # Aggregate
    index = edge_index[1,:]
    ptr = None
    dim_size = x.shape[0]
    aggr_out = self.aggregate(msg_out, index, ptr, dim_size)

    # Update
    update_out = self.update(aggr_out, x)
    x_tilde = update_out

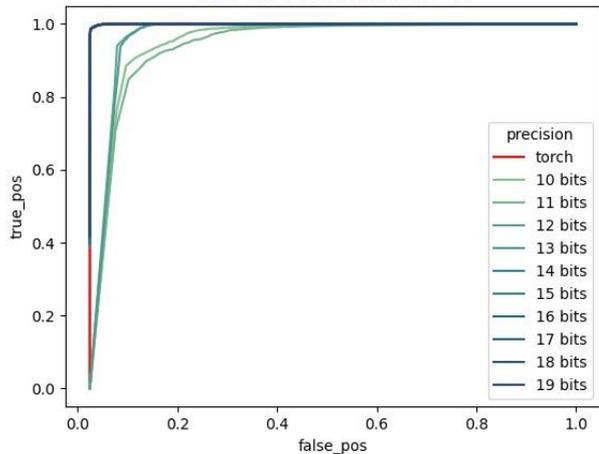
    #return update_out
    m2 = torch.cat([x_tilde[edge_index[1]],
                    x_tilde[edge_index[0]],
                    self.E], dim=1)
    return torch.sigmoid(self.R2(m2))
```

## pyg\_to\_hls: EdgeBlock, NodeBlock, Aggregate

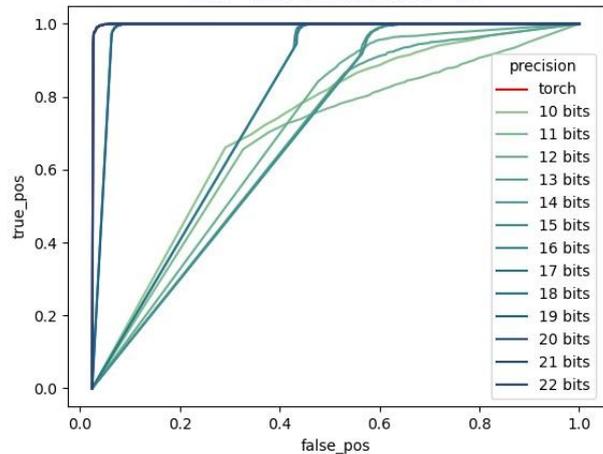
1. class GraphBlock(hls4ml.model.hls\_layers.Layer): packages a torch \*module\* into a form that will be accepted as an HLS \*layer\*
2. class EdgeBlock(GraphBlock):
  - i. Inputs
    1. Node attributes
    2. Edge attributes
    3. Edge Index
  - ii. Function:
    1. For each edge:
      - a. <edge attributes, receiver-node attributes, sender-node attributes> → Neural Network → Edge predictions
      - b. Edge predictions → permutation-invariant aggregation → Aggregate edge predictions
  - iii. Outputs
    1. Edge predictions
    2. Aggregate edge predictions
2. class NodeBlock(GraphBlock):
  - i. Inputs
    1. Node attributes
    2. Aggregate edge attributes (or aggregate messages)
  - ii. Function:
    1. For each node:
      - a. <node attributes, aggregate attributes> → Neural Network → Node predictions
  - iii. Outputs
    1. Node predictions
3. class Aggregate(hls4ml.model.hls\_layers.Layer):
  - a. Edge attributes → permutation-invariant aggregation → Aggregate edge attributes

# Interaction Network Benchmarks

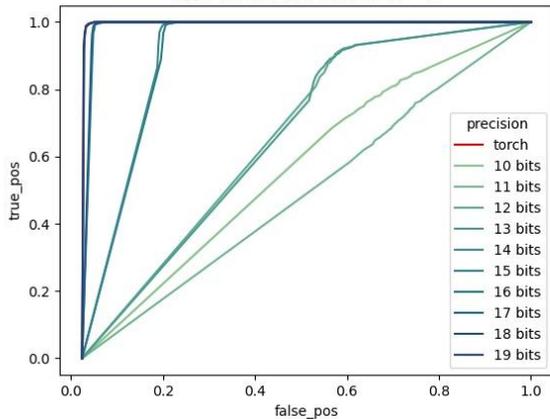
aggr=add, hidden neurons=40



aggr=max, hidden neurons=40



aggr=mean, hidden neurons=40



# User-inputs

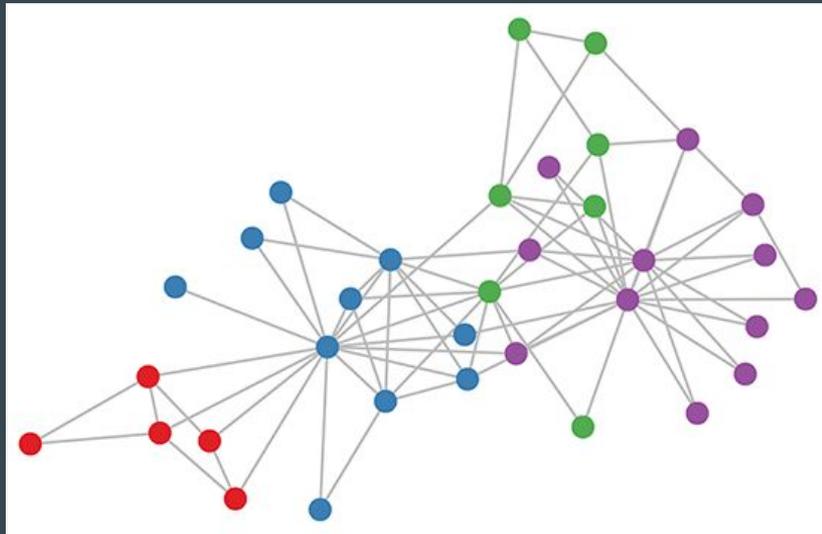
```
def pyg_to_hls(model, forward_dict, graph_dims,  
              activate_final = None,  
              fixed_precision_bits=16,  
              fixed_precision_int_bits=6,  
              int_precision_bits=16,  
              int_precision_signed=False,  
              output_dir = None):
```

```
# model.forward() dictionary  
forward_dict = OrderedDict()  
forward_dict["R1"] = "EdgeBlock"  
forward_dict["0"] = "NodeBlock"  
forward_dict["R2"] = "EdgeBlock"
```

# Graph padding and truncation

Hardware-implementation requires:  $n\_nodes\_max$ ,  $n\_edges\_max$

1. Truncation: removes true nodes, true edges, or both
  - a. Always bad
    - i. Fixes: Look for disconnected nodes, remove the least connected nodes first
      1. Compute ↗
2. Padding: adds dummy nodes, dummy edges, or both
  - a. sometimes bad
    - i.  $n\_nodes \geq n\_nodes\_max$ ,  $n\_edges < n\_edges\_max$ 
      1. Dummy edges must connect true nodes
  - b. sometimes alright
    - i.  $n\_nodes < n\_nodes\_max$ ,  $n\_edges \leq n\_edges\_max$ 
      1. Dummy nodes disconnected, or dummy nodes connected with dummy edges



# Support yet to come

- Non-linear layers
- Arbitrary # of layers per block
  - Currently: 1-->4 layers
- Higher-degree neighbors for “Message” and “Aggregation”
  - Currently only first-degree neighbors
- Different “Message” schemes
  - Currently: `NN_input = concat(receiver attributes, sender attributes, edge attributes)`

# About the author



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- B.A.: Physics, Economics @ U.Penn.
  - Graduation: August 2021
- Research Interests:
  - HEP, Astronomy, Applied ML for experimental Physics
  - Information theory, entropy and thermodynamics
  - Signal processing and hardware design
  - Graph Neural Networks and Graphical Causality
  - Reinforcement learning, Game Theoretic ML
- Hobbies:
  - Mountain biking, hiking, fishing
  - Basketball
  - Electric Guitar (noob)
- Applying to Physics and CS PhD programs!