



## **Simulations results**

Overview of results collected at  
ELI-NP and POLITO

*Progress meeting for P219 Experiment in PHELIX*

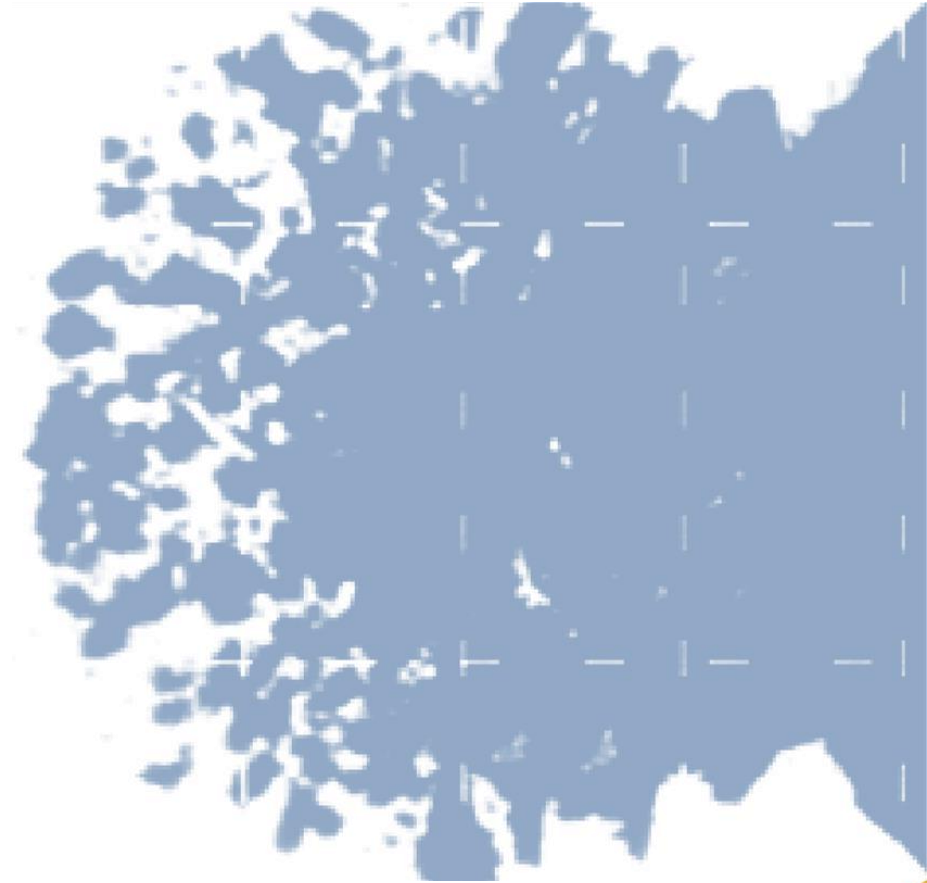
**Lorenzo Peroni**

Martina Scapin and Alberto Morena

# Summary

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- ELI-NP simulations (HELIOS)
- POLITO methodology
- Benchmark and calibration
- GSI experiments predictions
- Conclusions and outcomes

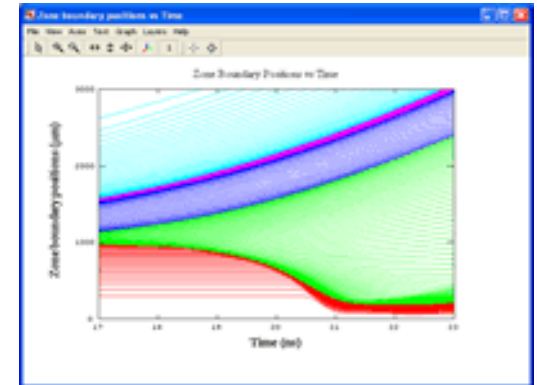


# HELIOS code

- The high-power lasers produce a surface plasma condition which acts as high-pressure loading source condition for the material in the rear portion of the sample.

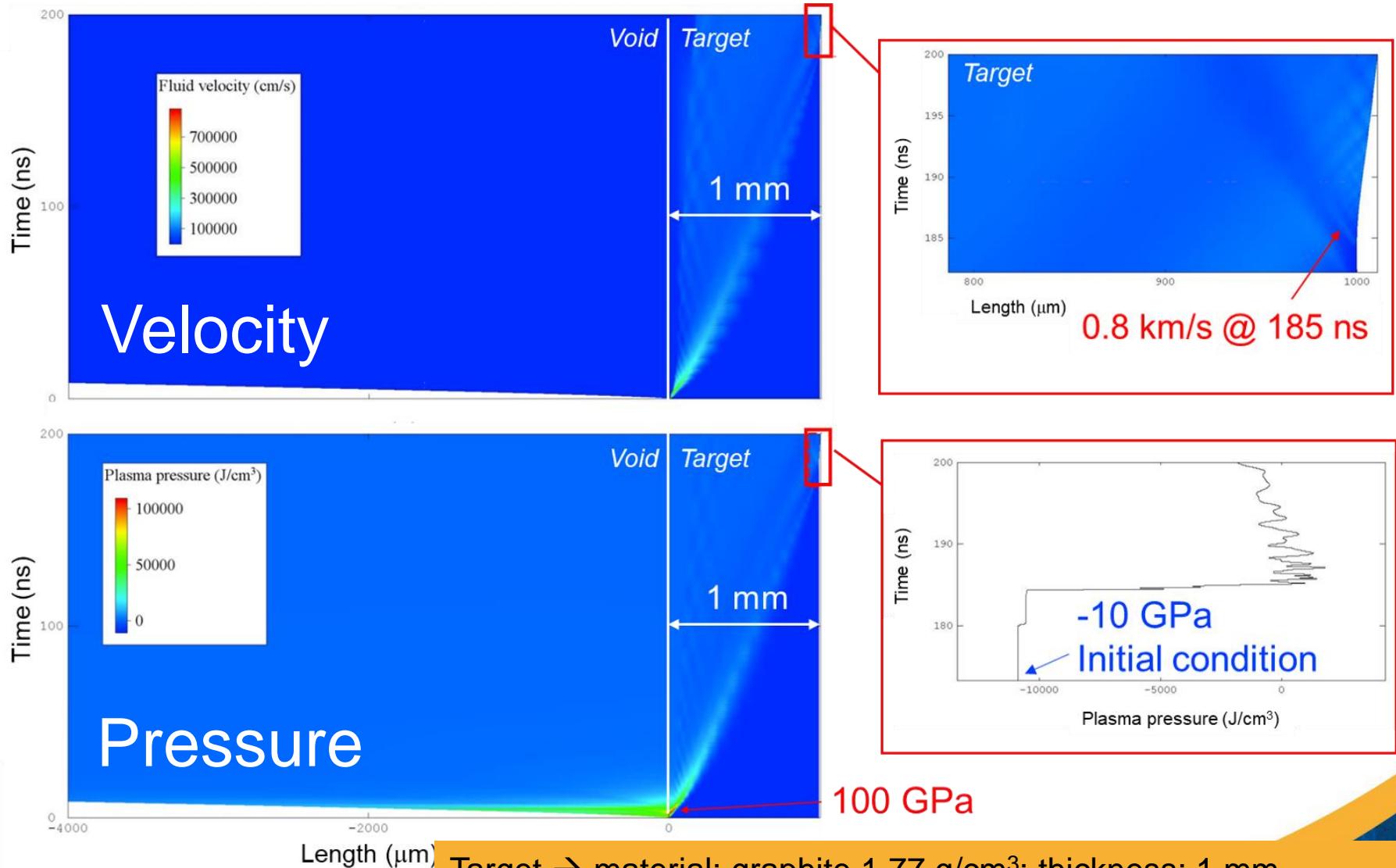
**HELIOS** is a 1-D radiation-hydrodynamics code designed to study the hydrodynamic evolution of radiating plasmas. It can be used to study the evolution of **planar**, cylindrical, or spherical plasmas heated by laser beams.

The code updates energy and momentum conservation equations in a **Lagrangian** reference frame (i.e., grid moves with fluid).



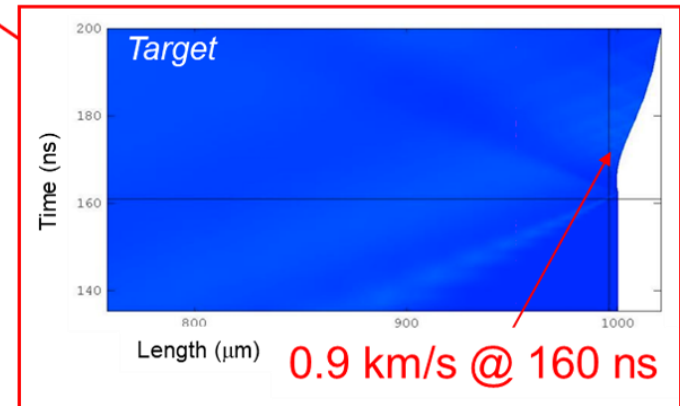
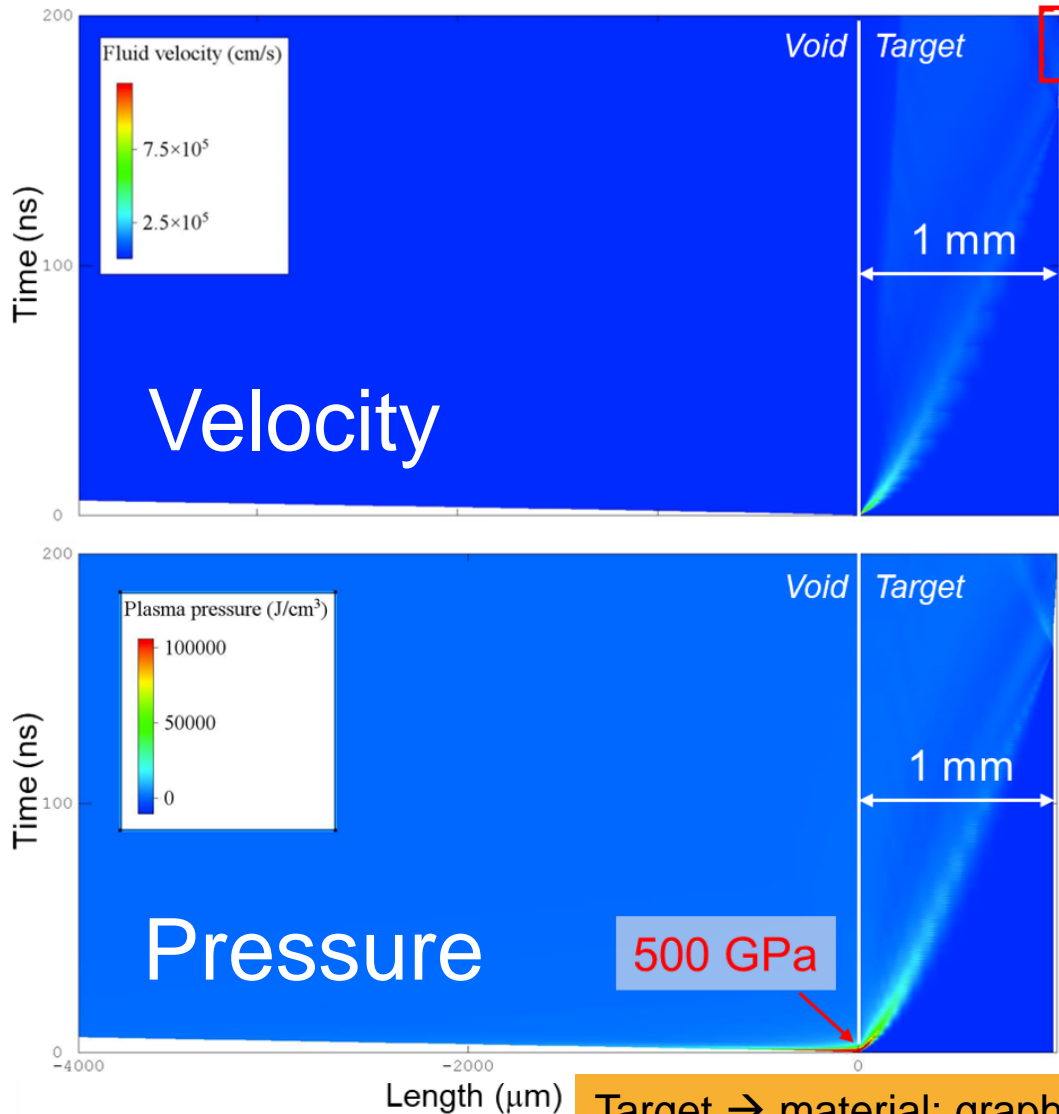
Target → SESAME equation of state, thermal conductivity, and electrical resistivity data.  
Laser → Irradiance ( $\text{W}/\text{m}^2$ ); pulse time history

# ELI-NP preliminary results



Target  $\rightarrow$  material: graphite  $1.77 \text{ g}/\text{cm}^3$ ; thickness: 1 mm  
Laser  $\rightarrow$  energy: 180 J; spot diameter: 1 mm; pulse duration: 5 ns

# ELI-NP preliminary results



## ELI-NP Conclusion:

- Pure hydrodynamic simulations (no mechanical strength of the target)
- 1D code: overestimation of the results on the back surface

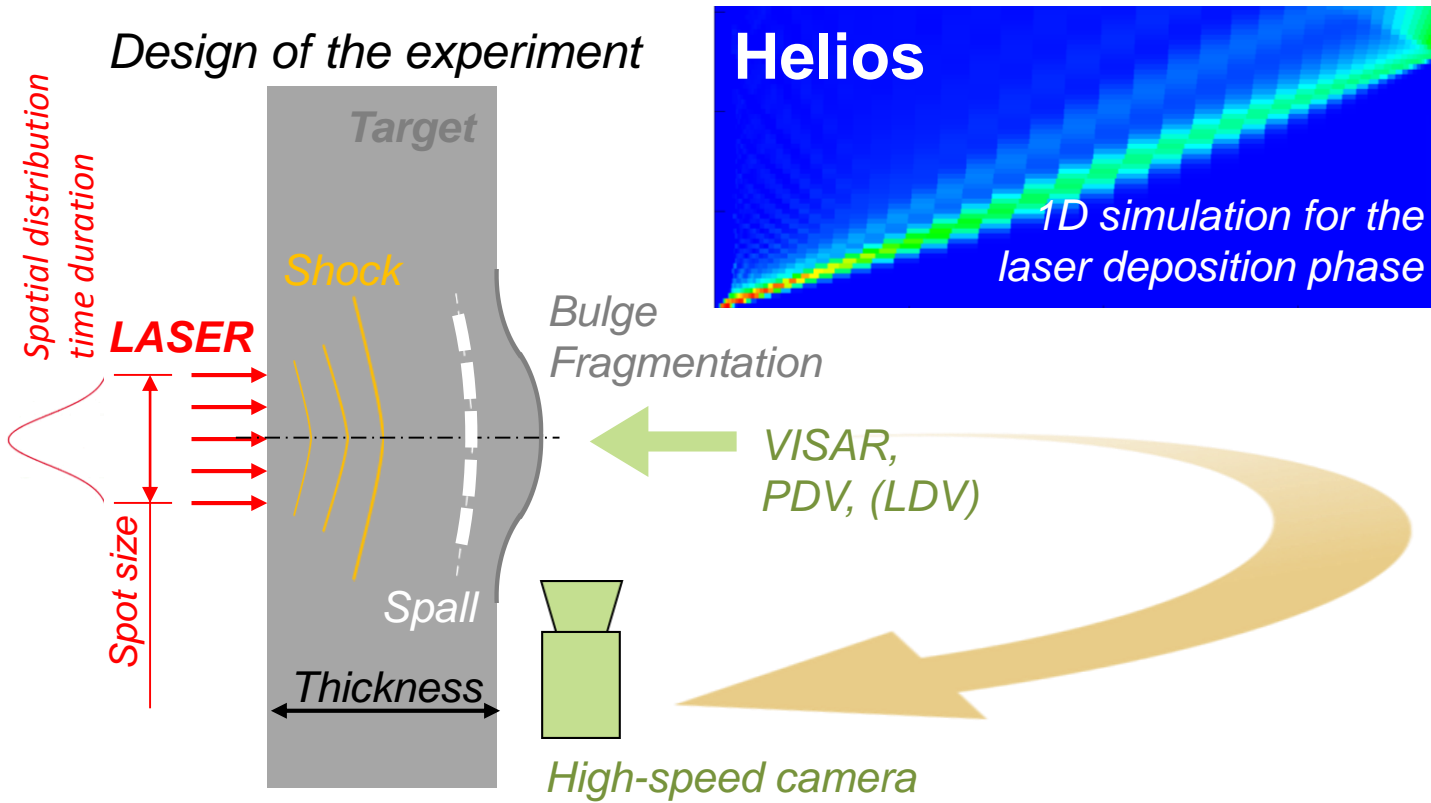
Length (μm)

Target → material: graphite 1.77 g/cm<sup>3</sup>; thickness: 1 mm  
Laser → energy: 180 J; spot diameter: 1 mm; pulse duration: 1 ns

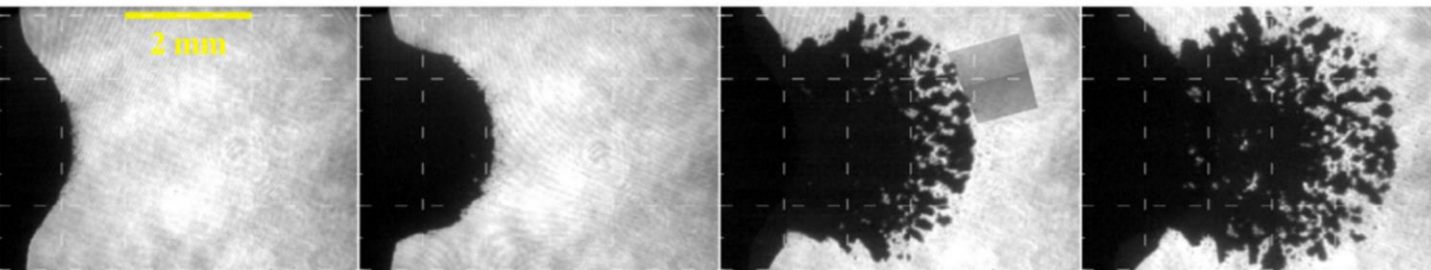
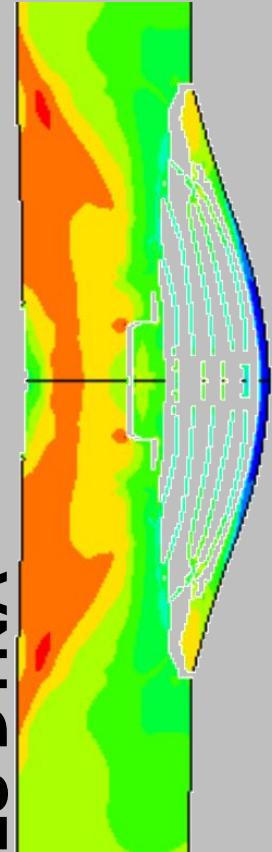


# The experiment methodology

## Design of the experiment



3D/2D axisymmetric simulation of the shock propagation and the target failure



Comparison of the results and model validation

# Dynamic fragmentation of graphite under laser-driven shocks: Identification of four damage regimes

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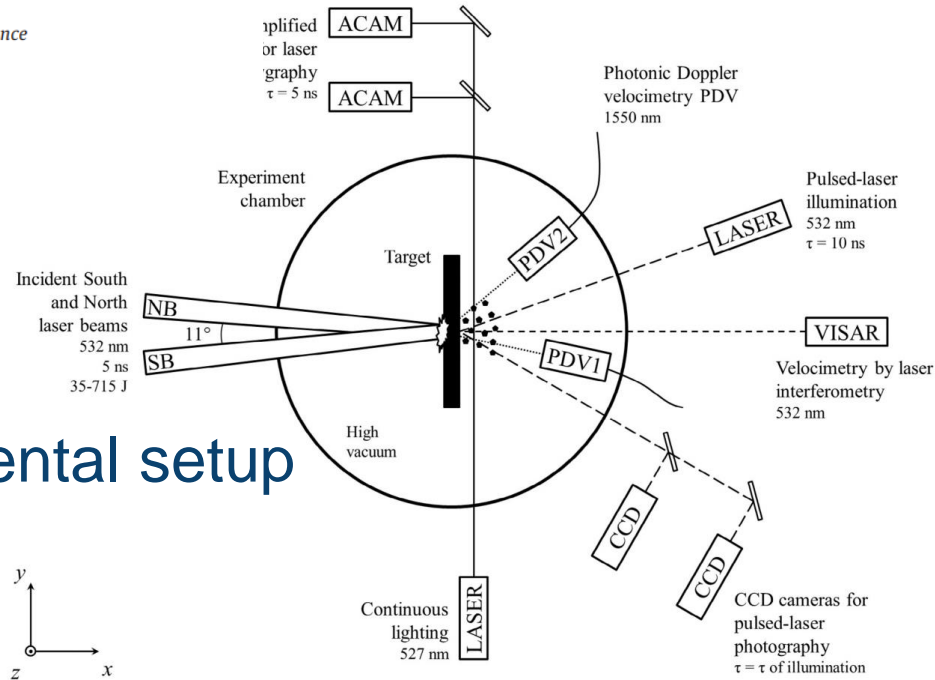
<sup>d</sup> Laboratoire PIMM – UPR8006 CNRS-Arts et Métiers ParisTech, 151 boulevard de l'Hôpital, 75013 Paris, France

# Benchmark

## Validation and tuning of FE simulations based on CEA experiments



## Experimental setup

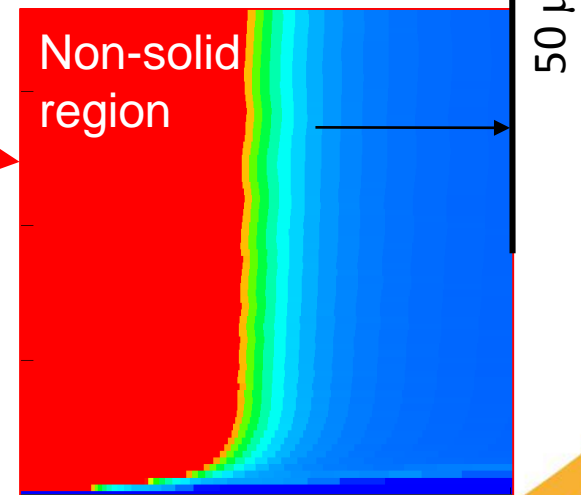
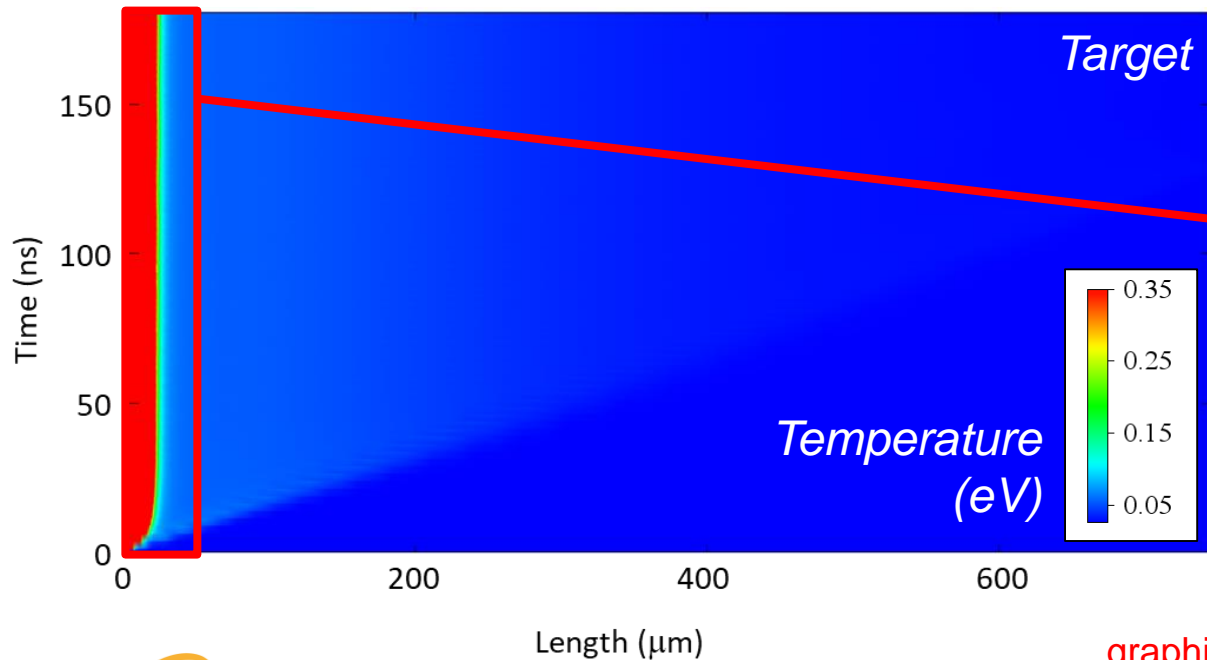
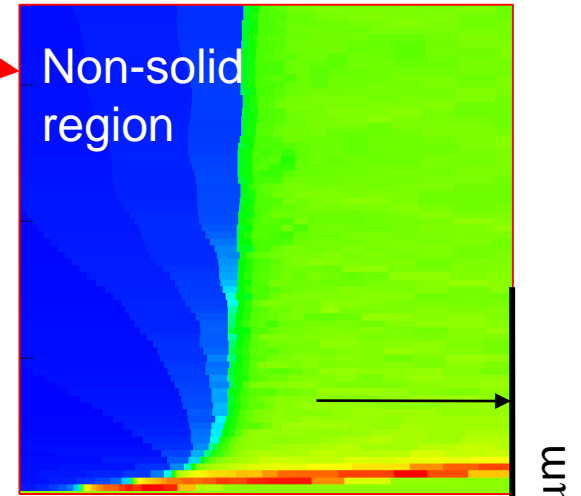
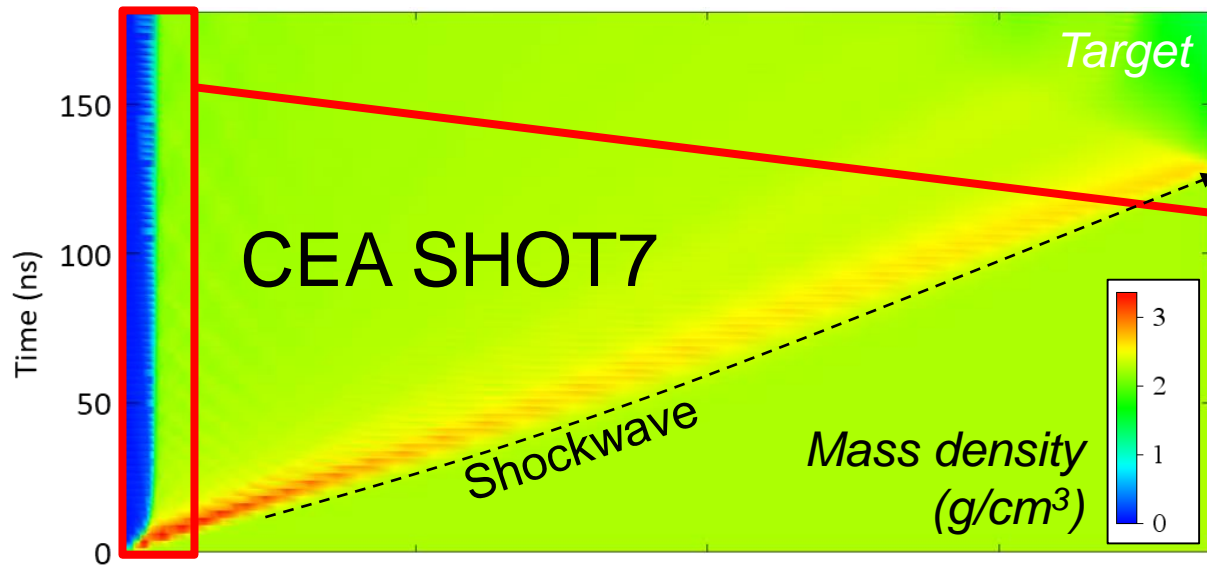


Target → material: graphite ( $\rho_0=1.754 \text{ g/cm}^3$ )  
Laser → spot diameter: 4 mm; pulse duration: 5 ns

Shot number	05	06	07	08	09	10	11	12	13	14	15*	16	17	18	26*	27*
Laser beam	S	N	S	N	N	S	N	S	N	S	S	N	S	N	N	S
Thickness (mm)	2.5	2.5	0.75	0.75	1	1	1.5	1.5	2	0.75	0.75	0.75	0.75	1	1	1
$U_m$ (m/s)	51	77	169	511	332	201	163	78	99	97	272	162	564	194	190	320
$P_m$ (MPa)	99	149	327	991	644	390	316	151	192	188	528	314	1094	376	369	621
$I_m$ (TW/cm <sup>2</sup> )	1.57	3.94	0.89	3.59	3.50	1.72	3.35	1.38	3.11	0.26	1.89	0.92	4.00	1.88	2.29	3.42
$P_{ab}$ (GPa)	43.5	90.6	27.4	84.2	82.5	46.7	79.6	39.2	74.9	10.2	50.4	28.3	91.7	50.2	58.6	80.8

## Shot conditions

# Helios results

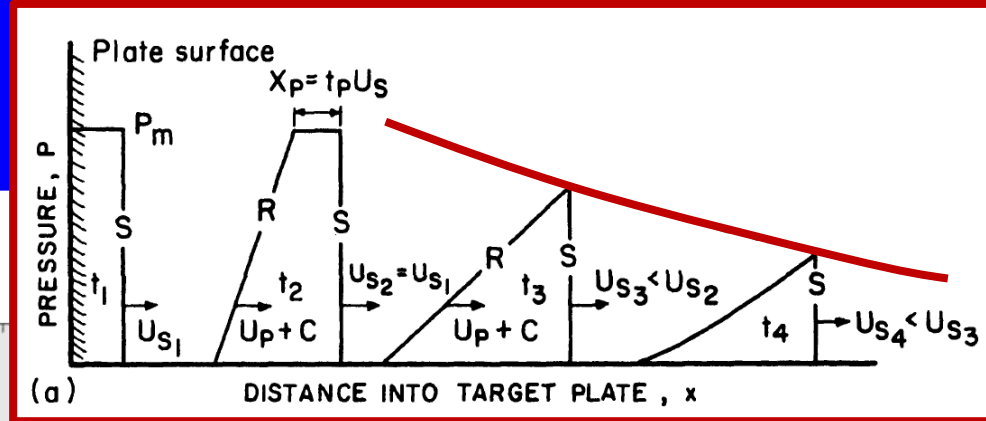
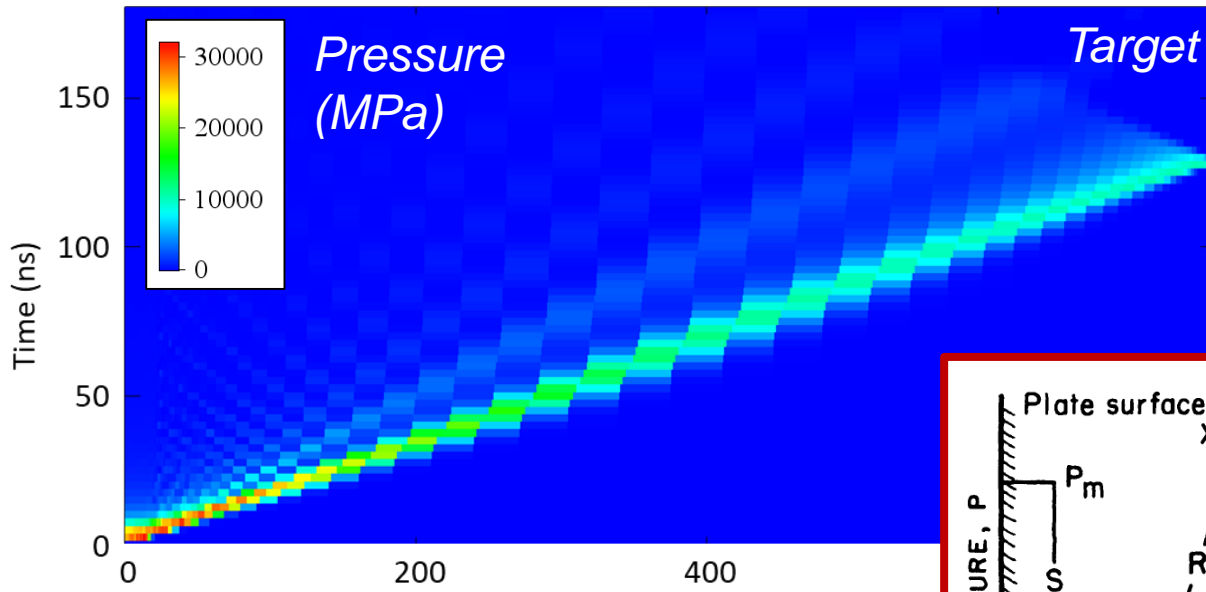


0.35 eV  $\approx$  4000 K  
graphite melting temperature



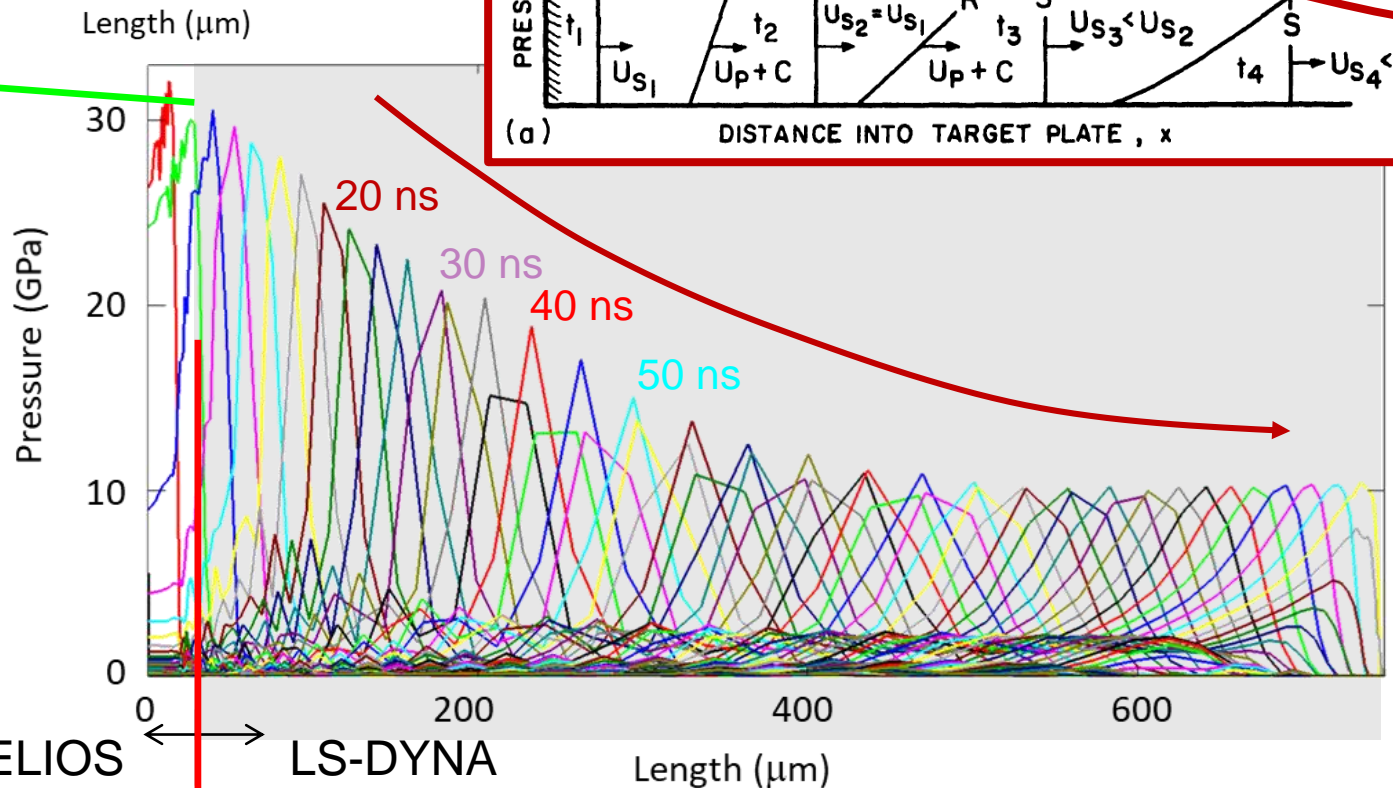
# HELIOS results

Decay of the pressure peak



5 ns

At the end deposition time of 5 ns the shock wave front is at 35 microns far from the front surface

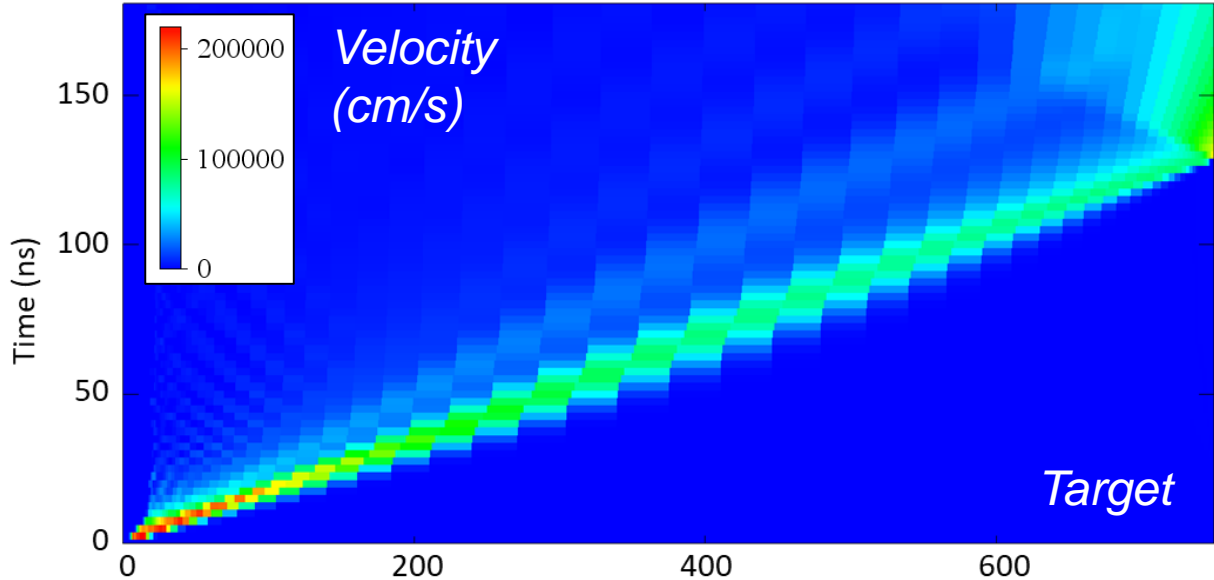


HELIOS

LS-DYNA

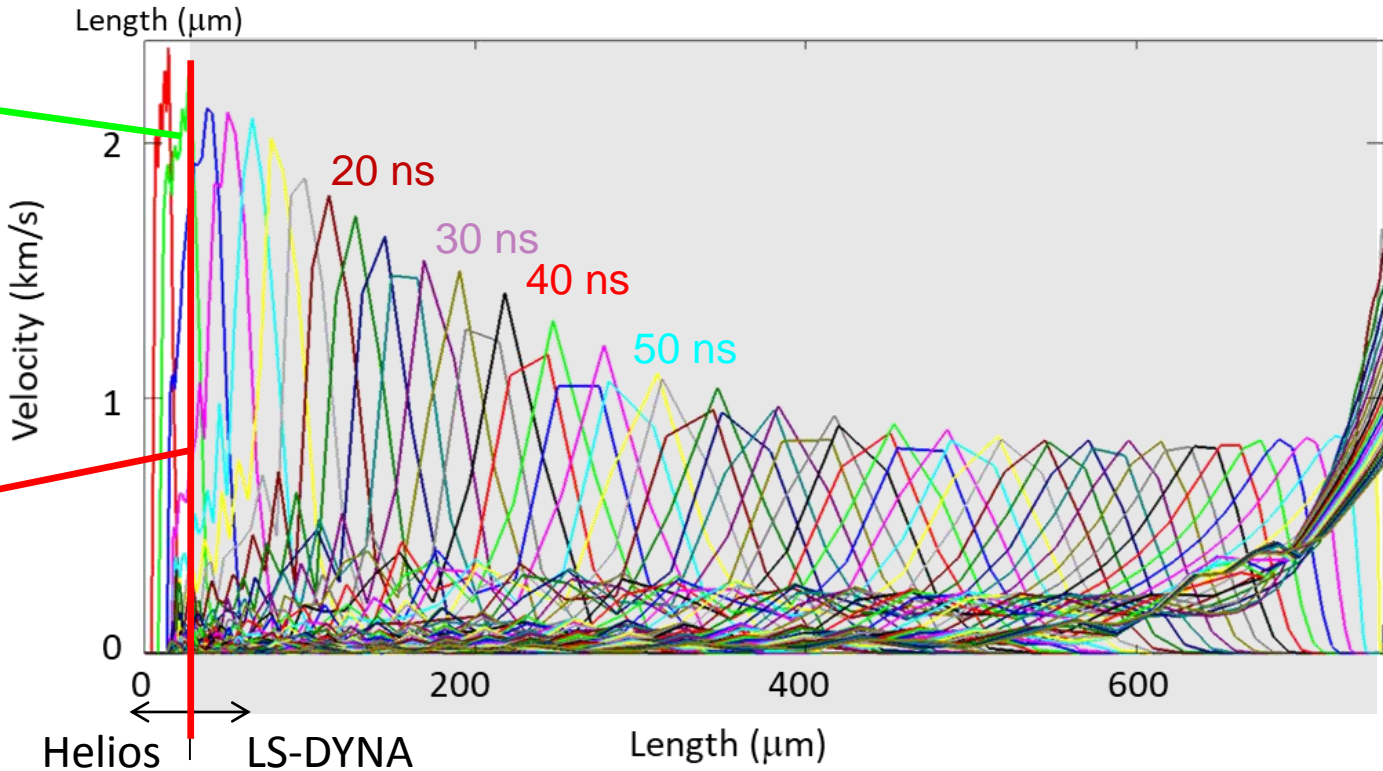
Length (μm)

# HELIOS results

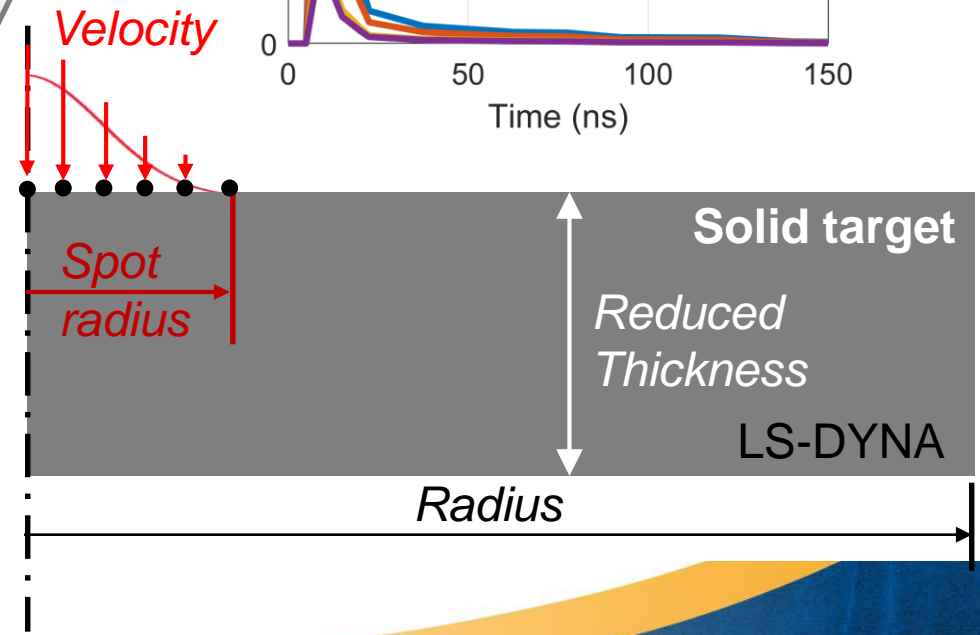
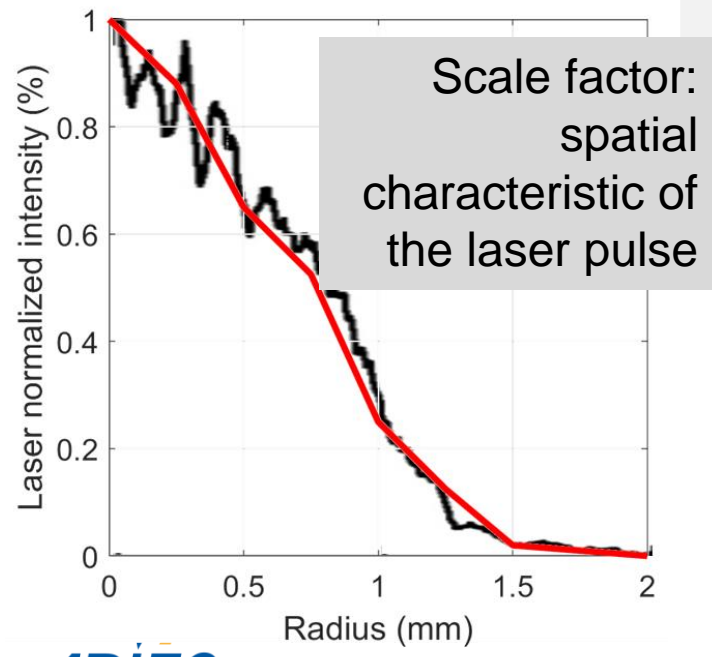
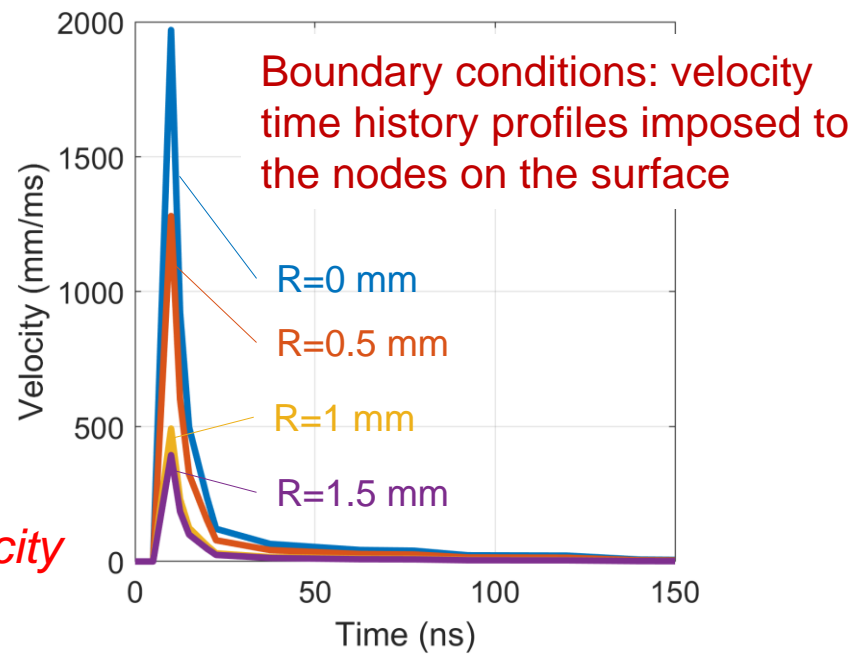
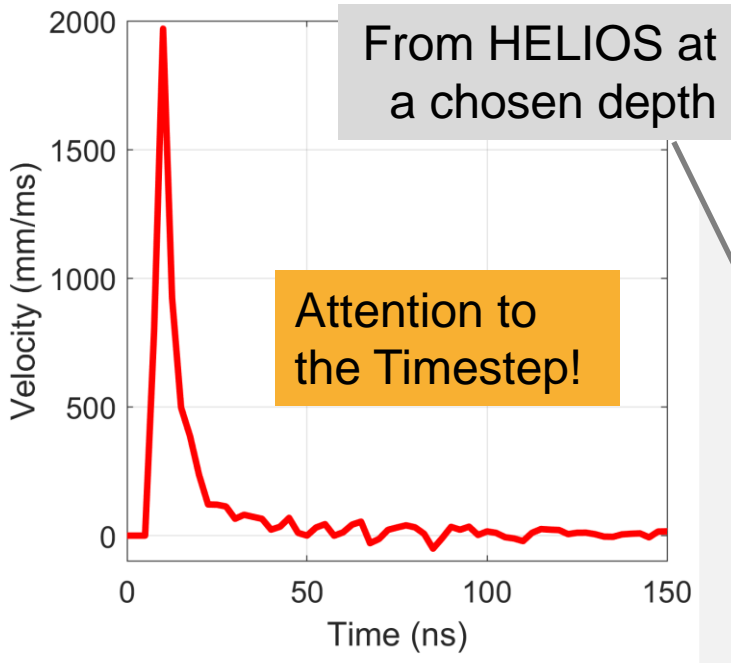


5 ns

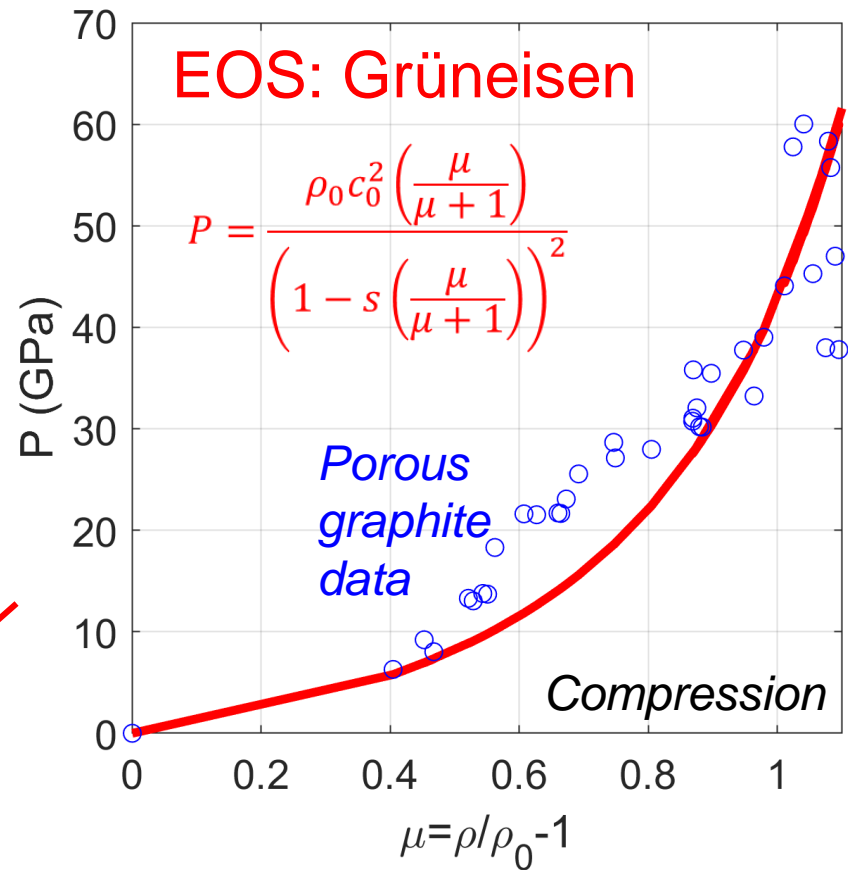
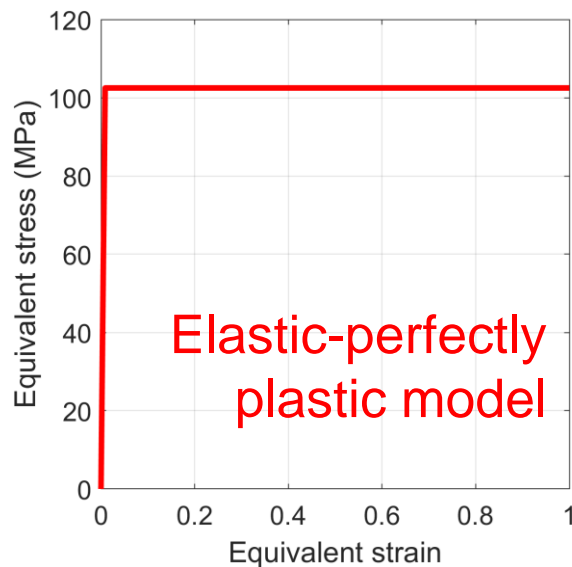
Boundary condition for FE simulations



# HELIOS to LS-DYNA

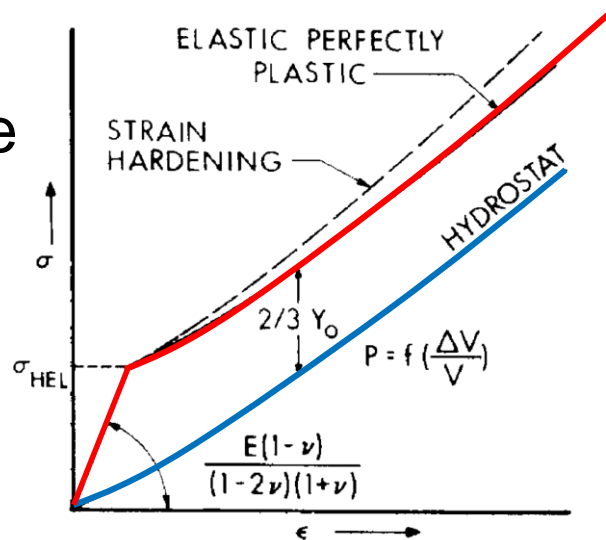


# LS-DYNA material model



In uniaxial strain case

(Compression)



## FAILURE CONDITIONS

- $\sigma_{MAX}$  In tension!!
- $\epsilon_{MAX}$

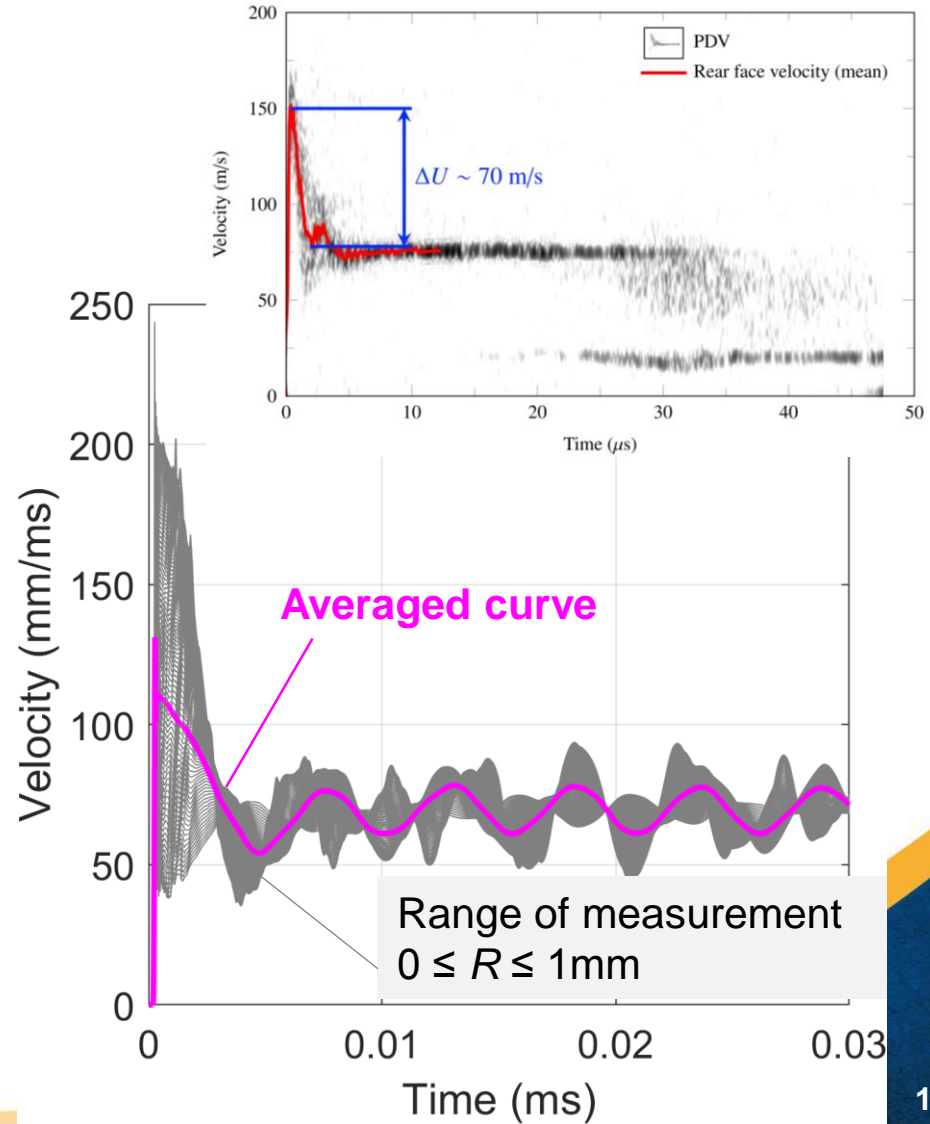
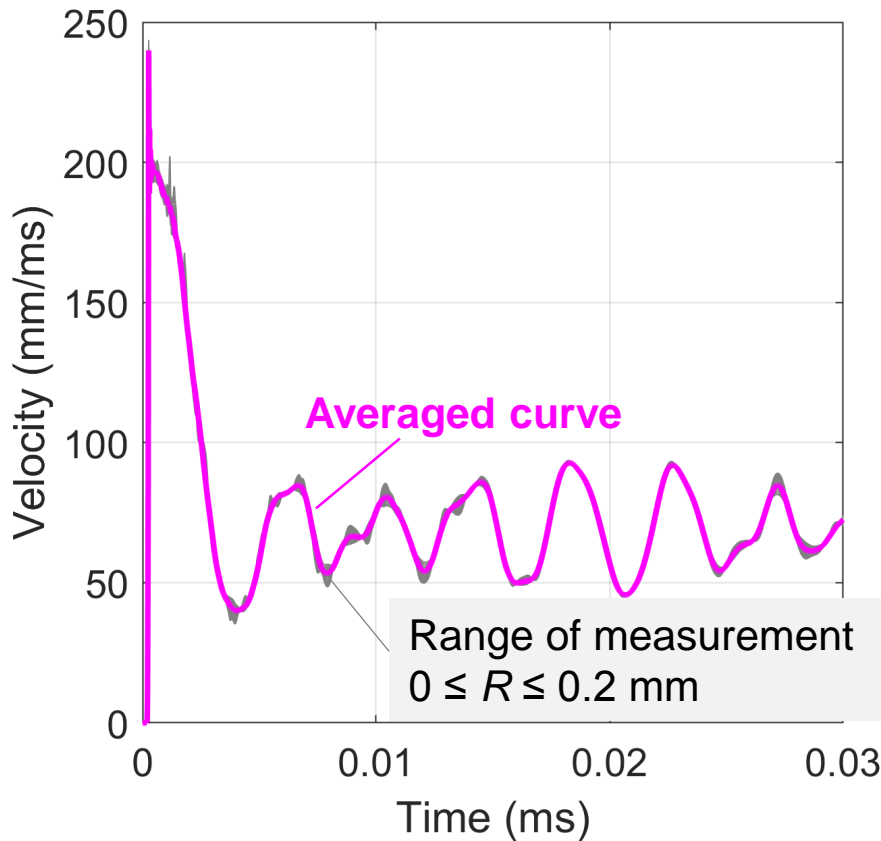




# LS-DYNA results

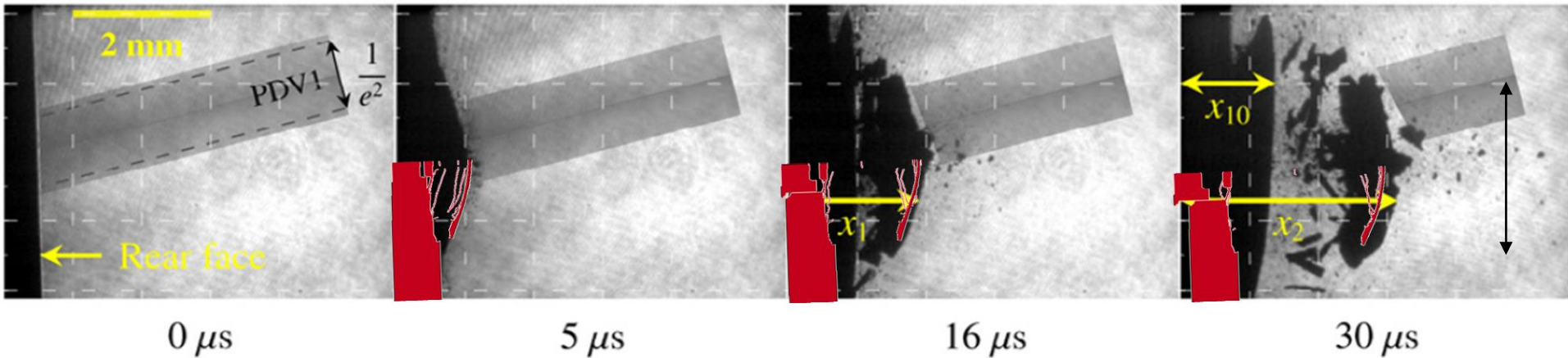
$V_{yMAX} = 1970 \text{ mm/ms}$

## Comparison with experimental results



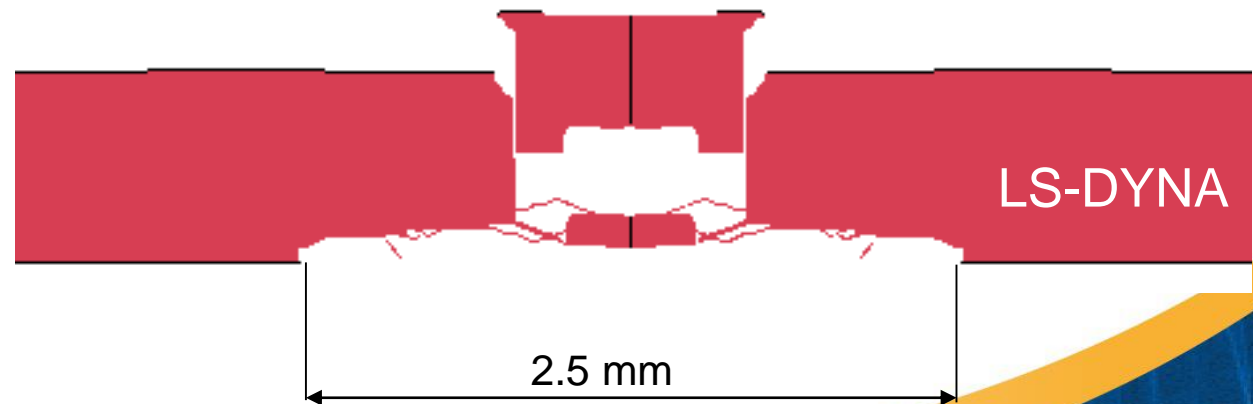
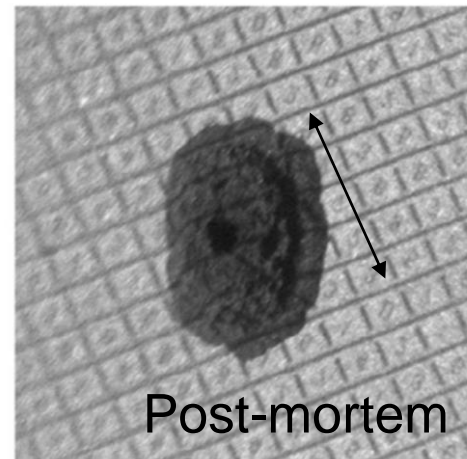
# LS-DYNA results

## Comparison with experimental results



SHOT 7 @ CEA

Target → material: porous graphite; thickness: 0.75 mm  
Laser → energy: 121 J; pulse duration: 5 ns



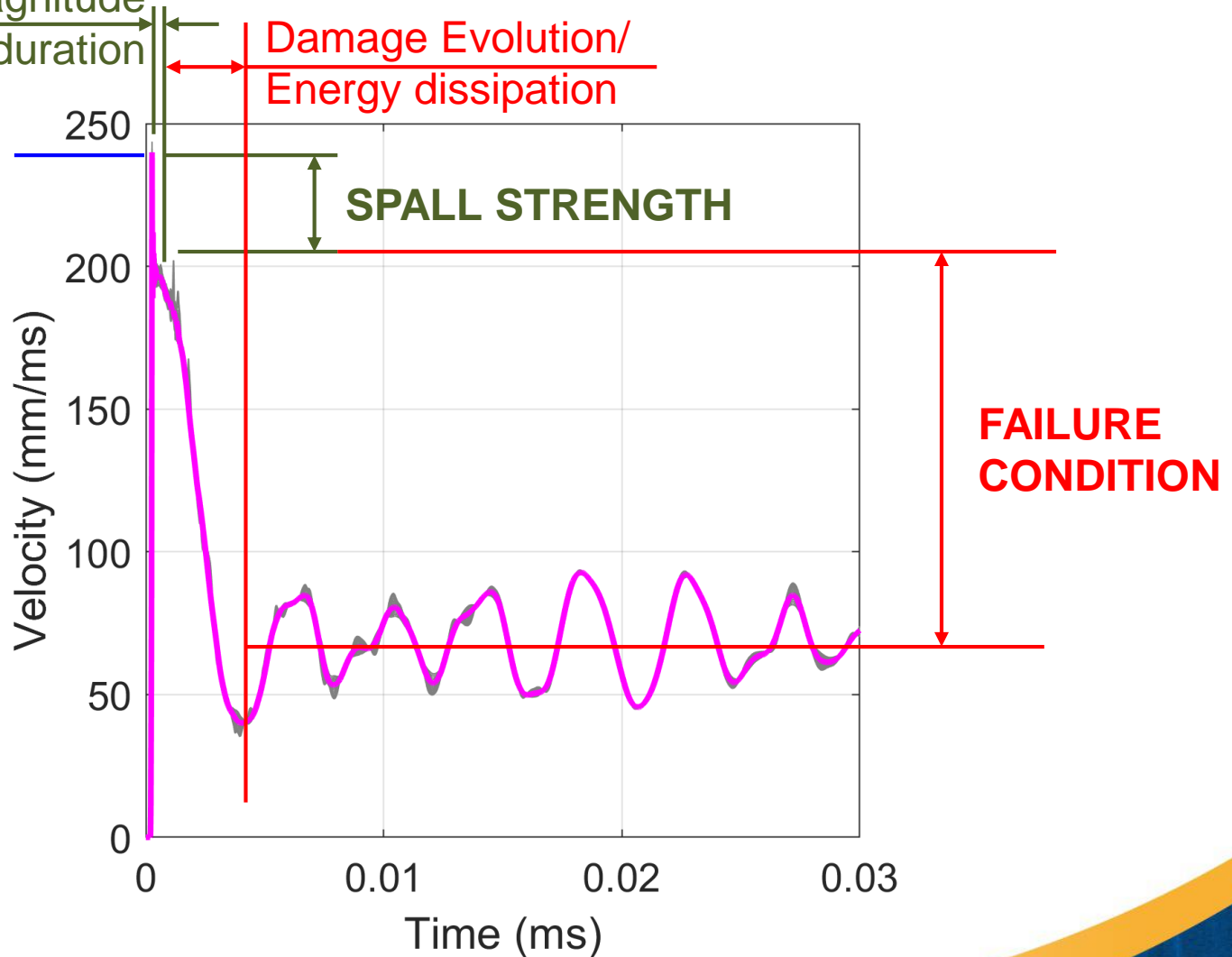
# Results analysis: back surface velocity

Same order of magnitude  
of the pulse duration

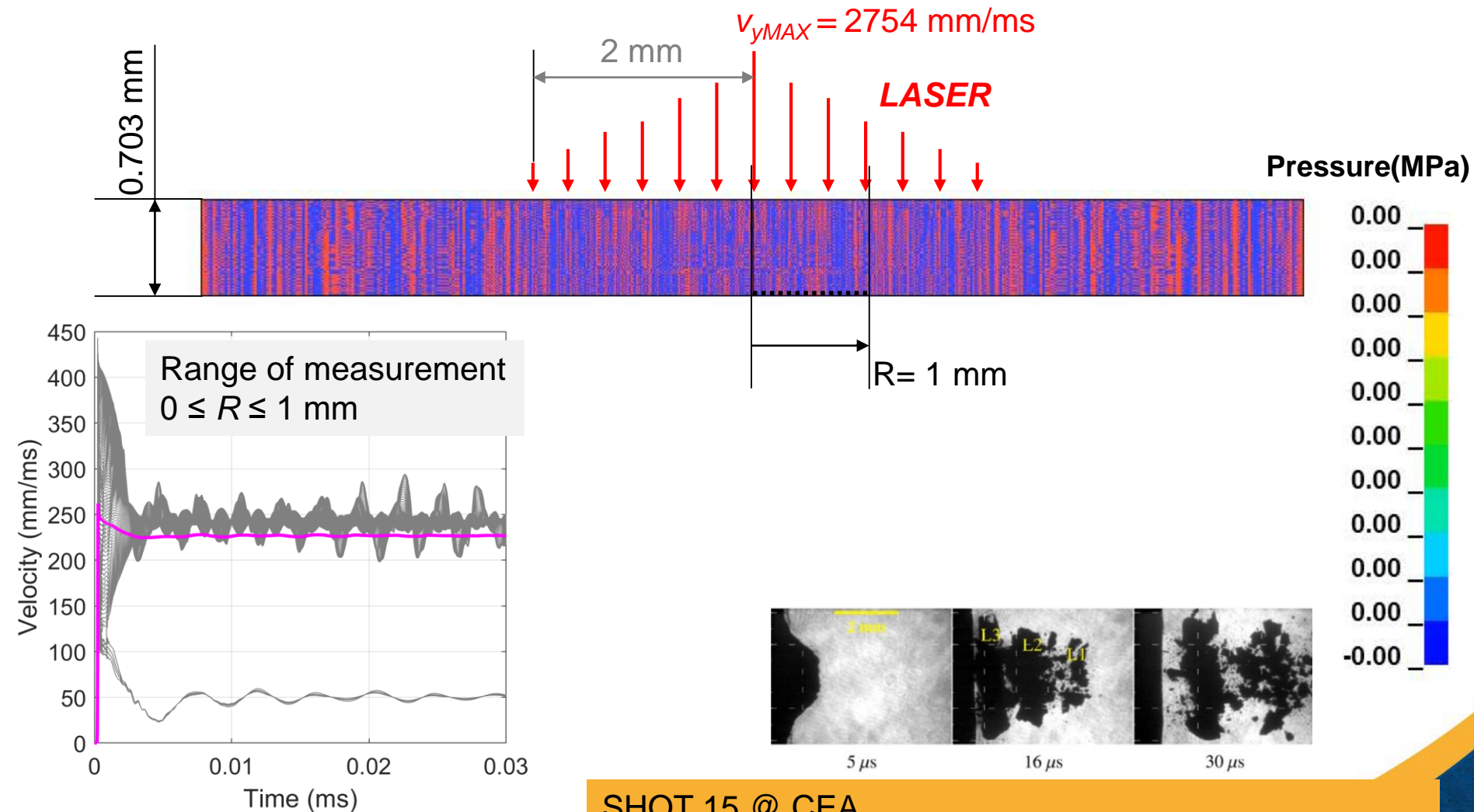
**DAMPING**  
(model  
dependent)

*Rayleigh  
damping  
coefficient  
for stiffness  
weighted  
damping*

(0.06)



# LS-DYNA results

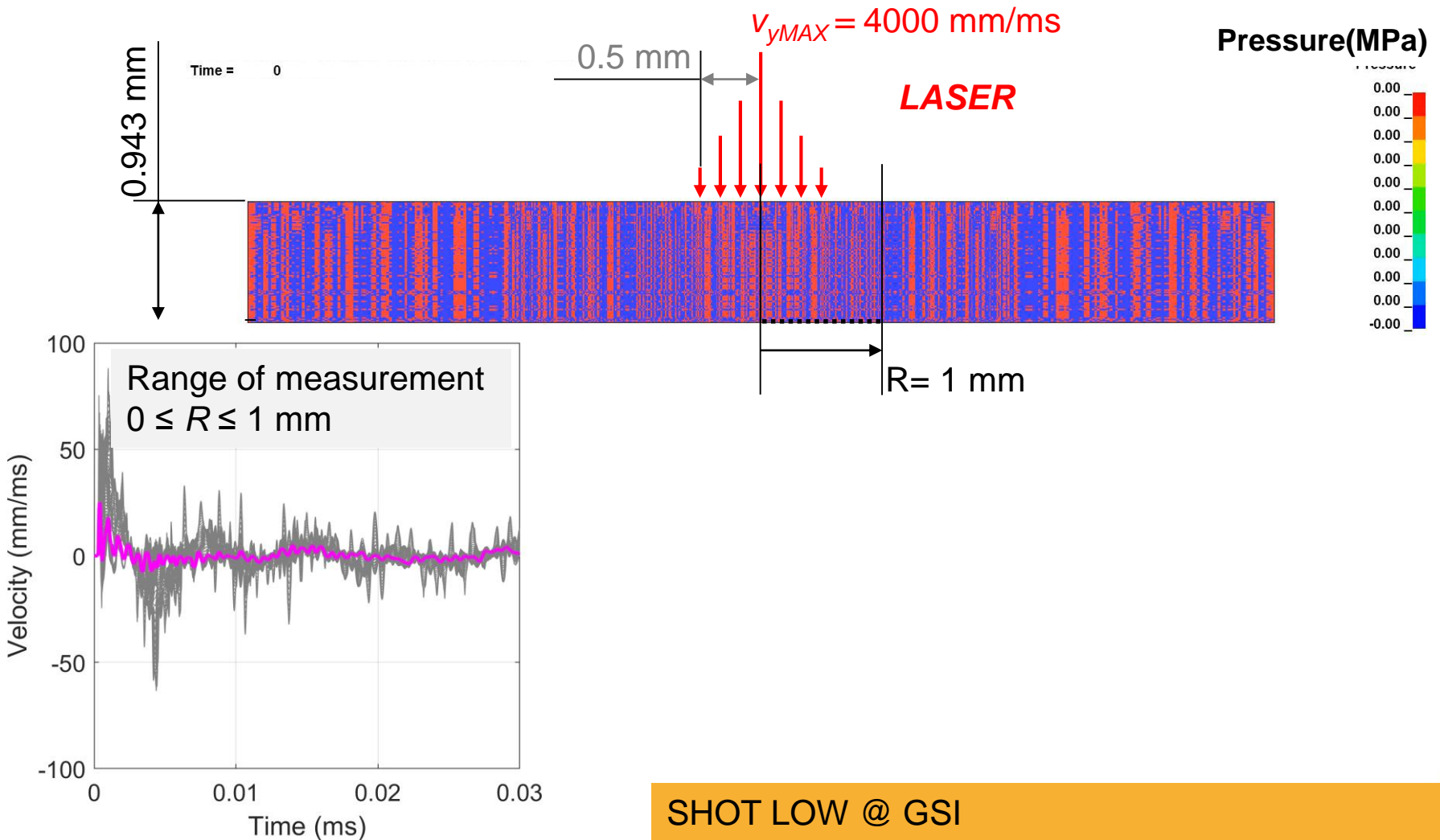


SHOT 15 @ CEA

Target → material: porous graphite; thickness: 0.75 mm

Laser → energy: 259 J; pulse duration: 5 ns

# LS-DYNA GSI Prediction 5 ns



SHOT LOW @ GSI

Target → material: porous graphite; thickness: 1 mm

Laser → energy: 180 J; pulse duration: 5 ns

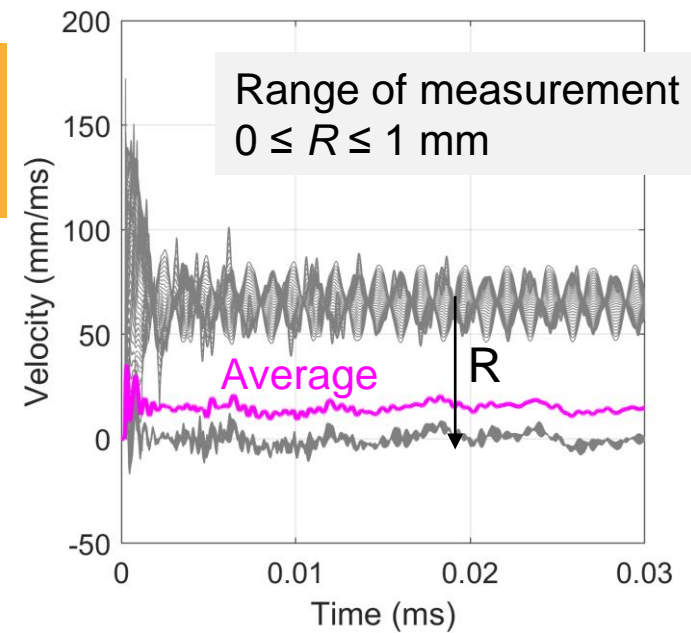
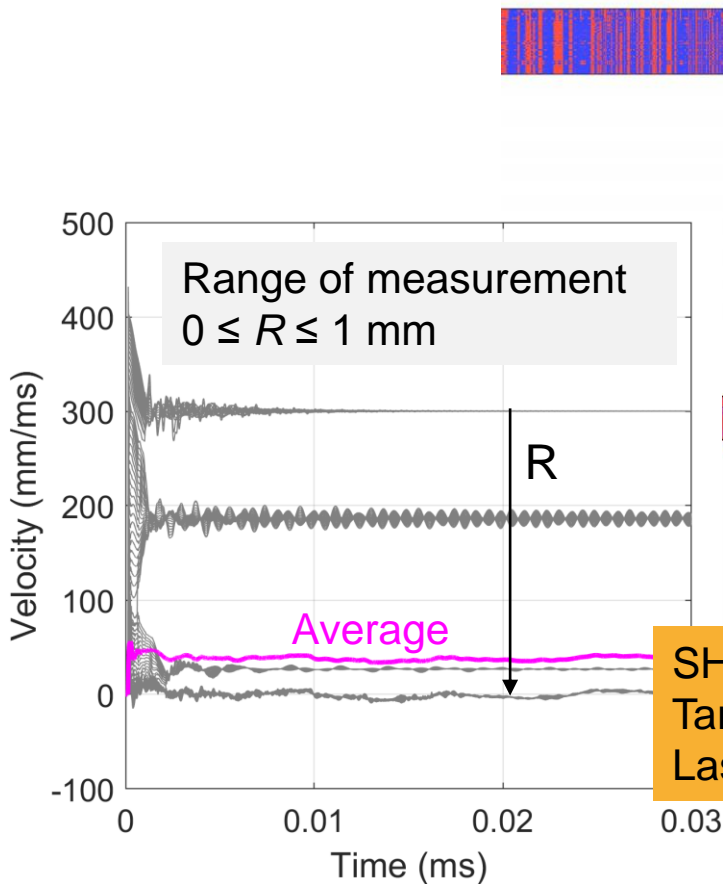


# LS-DYNA GSI Prediction 5 ns

## SHOT LOW @ GSI

Target → material: porous graphite; thickness: **0.75 mm**

Laser → energy: 180 J; pulse duration: 5

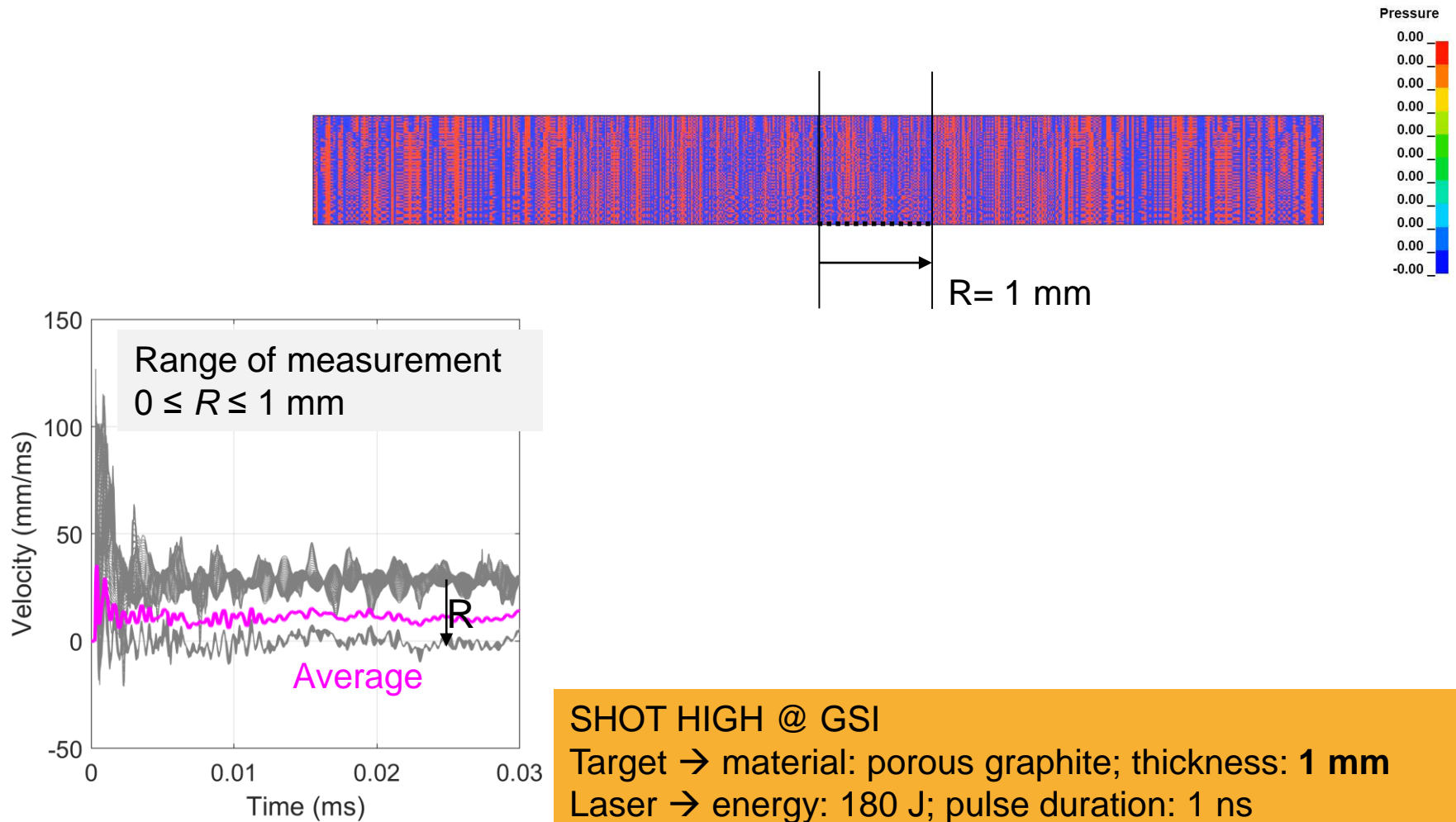


## SHOT LOW @ GSI

Target → material: porous graphite; thickness: **0.5 mm**

Laser → energy: 180 J; pulse duration: 5

# LS-DYNA GSI Prediction 1 ns



# Conclusions and outcomes

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- Following the preliminary ELI-NP results the laser deposition phase could be simulated with 1D code HELIOS
- The obtained velocity at the plasma-solid interface could be used as boundary condition for the LS-DYNA model in order to assess the conditions at the back surface taking into account the strength and failure model of the material
- Different modelling techniques were tested (2D FE, 3D FE, SPH, FE-SPH) and 2D axisymmetric model results as the much effective solution (fast and enough accurate)
- The results are strongly dependent from the adopted damping and failure model
- Velocity measurements on the back surface could strongly vary in function of the portion of the sample considered and the dimensions of the measuring spot



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**Thank you for your attention!**