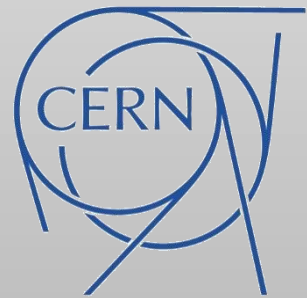




EP-R&D Silicon Working Group 1.1

Hybrid Detectors



Small pitch 3D Timing (& planar 😊)

Evangelos –Leonidas Gkougkousis

CERN EP-R&D



Lecce – June 22nd, 2022

• Introduction, EP-R&D W.P. 1.1 – Hybrid Sensors

Planar Sensors (J. Haimberger, V. Gkougkousis)

- ✓ Radiation damage and trapping model validation through TCAD
- ✓ Timing and efficiency at $< 1e17 n_{eq}/cm^2$ using fast neutrons and ps protons (thicknesses 50, 100, 200, 300 μm)

LGADs (V. Gkougkousis)

- ✓ Radiation damage mechanisms and modeling on different dopant types ([TIPP2021](#), [ArXiv Preprint](#), [PicoSecond Workshop 2021](#))
- ✓ Indium-Lithium gain layer radiation hardness investigations ([Trento2021](#))
- ✓ Process simulations and SiMS – Carbon/Boron ([LINK](#))

Silicon Electron Multiplier (M. Halvorsen, [LINK](#), [ArXiv Preprint](#), [IEEE](#))

- ✓ Structure optimization and electrostatic simulations
- ✓ Timing and transient Simulations
- ✓ Process iterations (Metal Assisted Etching)

Talks @ Trento 2022

Small Pitch 3Ds for tracking and timing (V. Gkougkousis, [LINK](#))

- ✓ β particles timing studies on irradiated and unirradiated devices
- ✓ Test beam with SPS pions (Tracking + Timing)
- ✓ Proton and neutron irradiations $> 1e17 n_{eq}/cm^2$
- ✓ New small pitch production optimized for gain at electrode region



Vagelis Gkougkousis



Jakob Haimberger



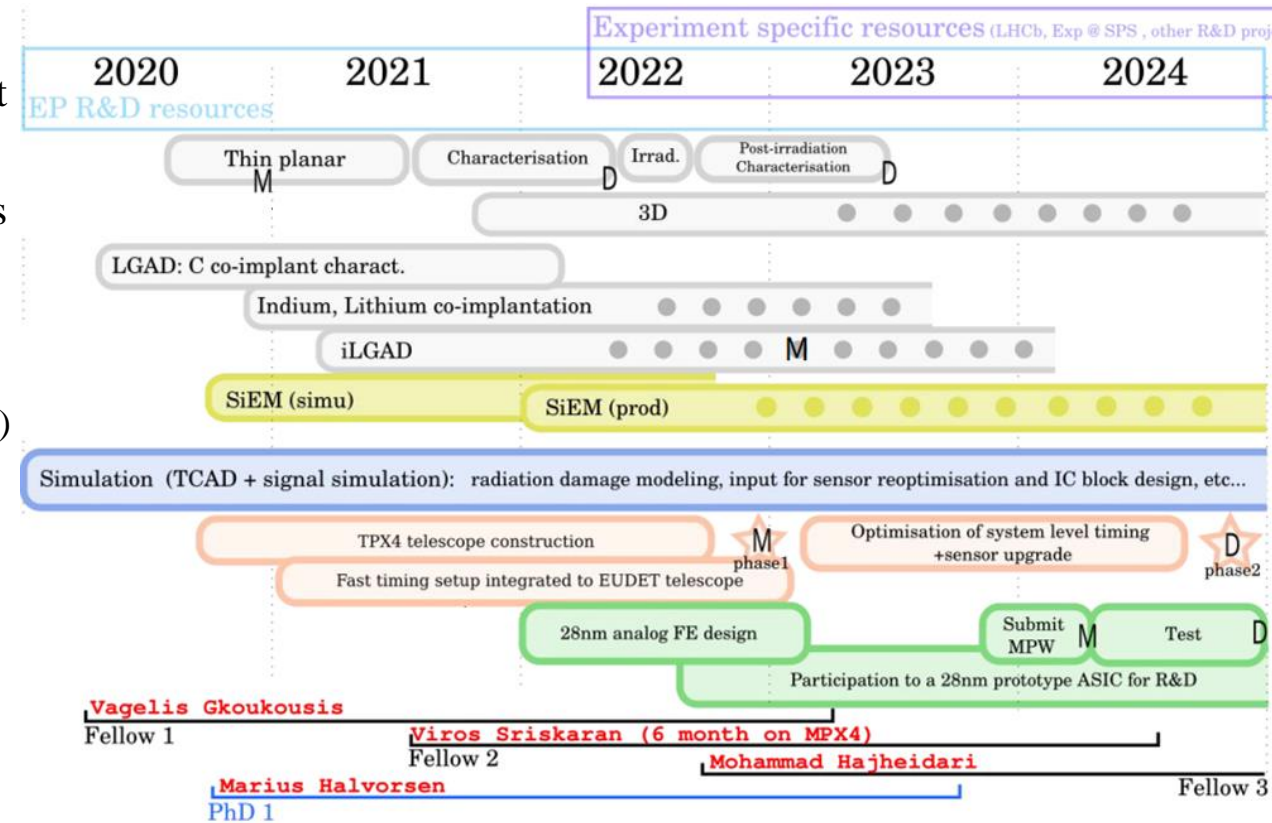
Marius Halvorsen



Victor Coco



Paula Cliins



•3D Sensors

Timing at Extreme Fluences

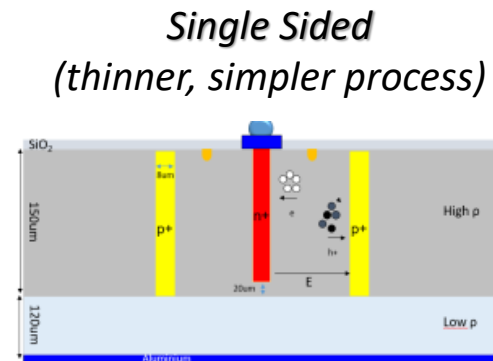
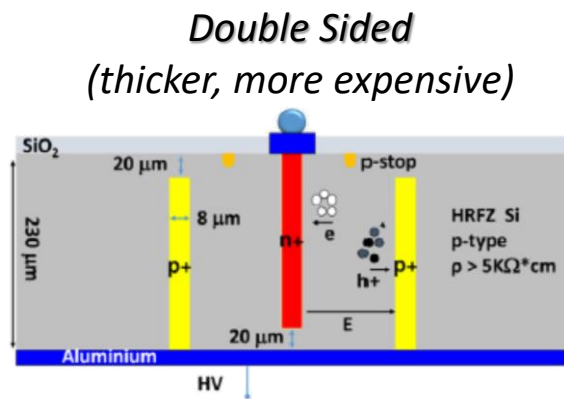
3D Sensors: Decoupling of charge generation and drift volume
(Standard columns, TimeSpot, Hex geometries ect.)

Pros

- High radiation tolerance up to several times $10^{16} n_{eq}/cm^2$
- Short drift distances with fast rise times
- Reduced Landau fluctuation, practically non-existent for perpendicular tracks

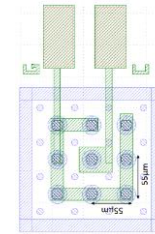
Cons

- Non-uniform field geometry
- High cost
- Increased cell capacitance



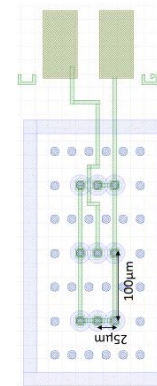
Pixel Size vs Field Uniformity

ATLAS IBL Type

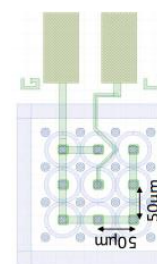


- ✓ Double sided n-on-p process
- ✓ Pixel Size $55 \times 55 \mu m^2$
- ✓ Active thickness $230 \mu m$
- ✓ High Resistivity ($> 2 k\Omega m \times cm$) Fz silicon

ATLAS Pre-Production type



- ✓ Single sided n-on-p process
- ✓ Pixel Size $25 \times 100 \mu m^2$
- ✓ Active thickness $150 \mu m$
- ✓ High Resistivity ($> 2 k\Omega m \times cm$) Fz silicon

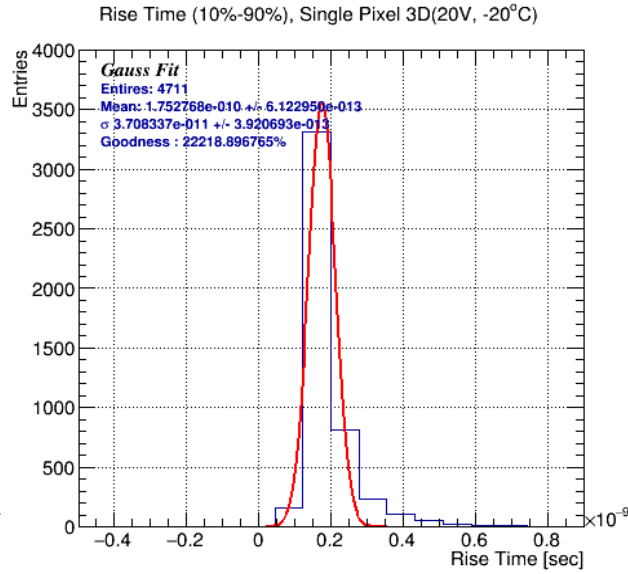
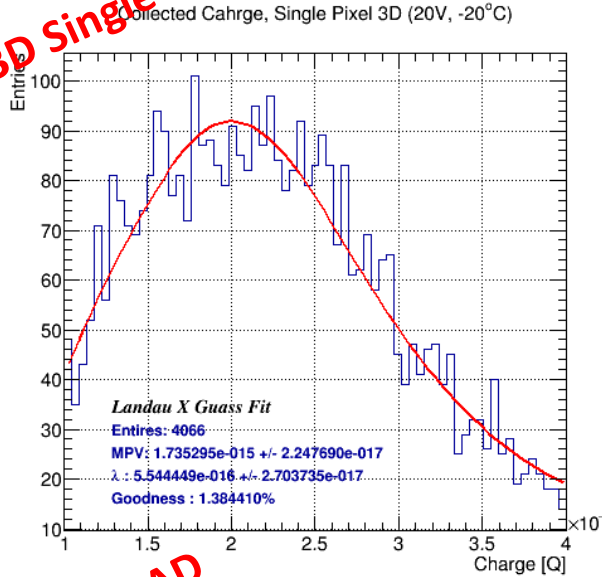


- ✓ Single sided n-on-p process
- ✓ Pixel Size $50 \times 50 \mu m^2$
- ✓ Active thickness $150 \mu m$
- ✓ High Resistivity ($> 2 k\Omega m \times cm$) Fz silicon

•3D Sensors - Timing

Presentation: V. Gkougkousis, "Single cell 3D timing: Time resolution assessment and Landau contribution evaluation via test-beam and laboratory measurements", 17th Trento workshop on advanced radiation silicon detectors ([link](#))

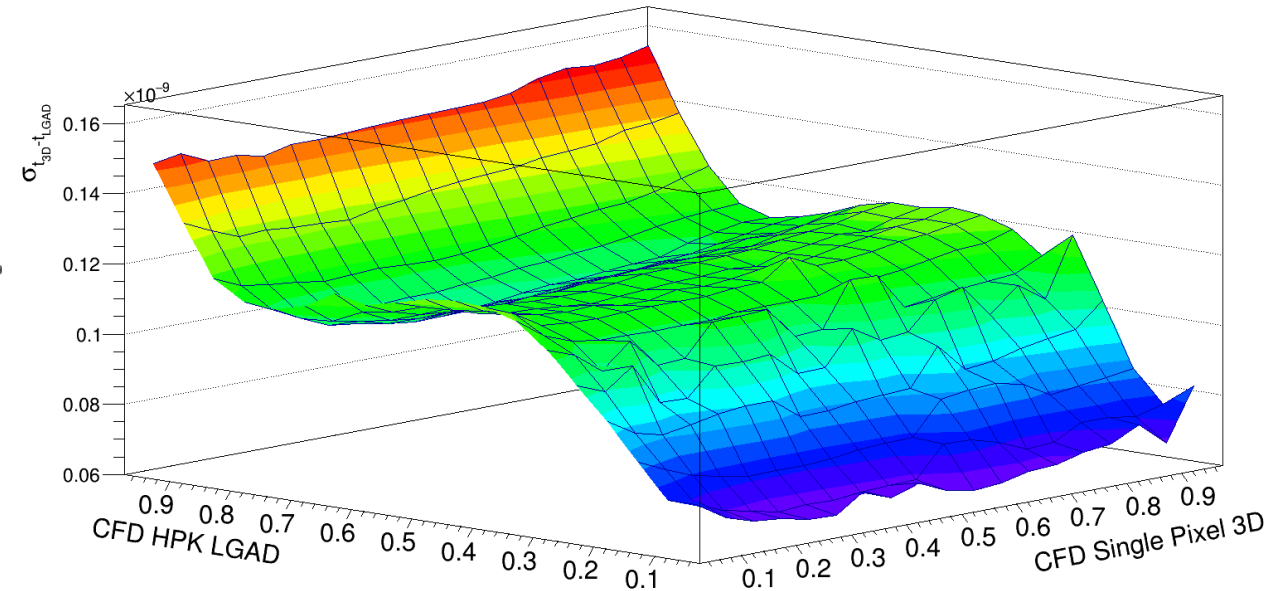
3D Single Cell



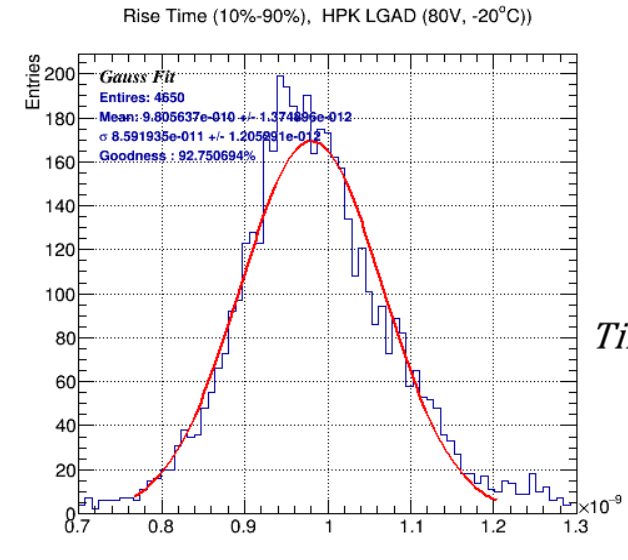
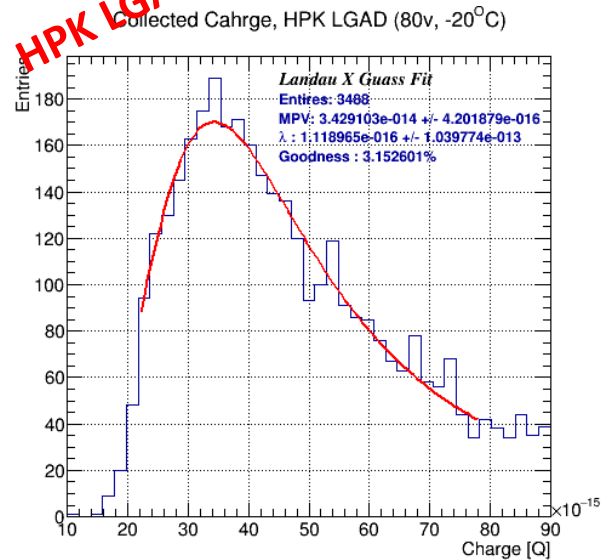
- Extremely fast rising edge (< 180 psec)
- Linear stable behavior with CFD, good SNR control

$$(\sigma_{Dut})_{CFD_{ij}} = \sqrt{(\sigma_{Tot}^2)_{CFD_{ij}} - (\sigma_{Ref}^2)_{CFD_i}}$$

CFD Map, LGAD - Single Pixel 3D (-20°C, 20V)



HPK LGAD



2D optimization plot – 0.5% binning

Time Resolution: $\sigma_{tot}^2 = \underbrace{\sigma_{timewalk}^2}_{\sigma_{Dist.}^2 + \sigma_{Landau}^2} + \underbrace{\sigma_{jitter}^2}_{\left(\frac{t_{rise}}{S/N}\right)^2} + \underbrace{\sigma_{conversion}^2}_{\left(\frac{TDC_{bin}}{\sqrt{12}}\right)^2} + \underbrace{\sigma_{Clock}^2}_{\text{Fixed Term } \sim 5-7 \text{ psec}}$

Planar Sensors

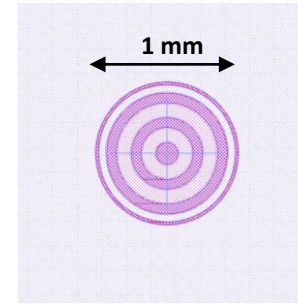
Sensors: CERN EP-R&D n-on-p planar sensor run with ADVACAM at 50, 100, 200 and 300 μm active thickness (TimePix4 bonded sensors also from this run, see Kazu's talk [here](#))

Test Structures

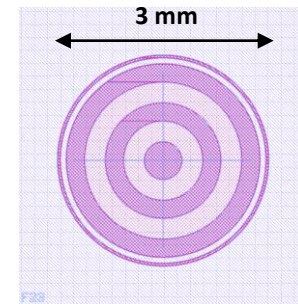
- Small diodes (3.14 mm² active area) Circular diodes for timing studies due to lower capacitance
- Big diodes (28.27 mm² active area) Circular diodes for radiation damage studies
- 5x5 Pixel matrix (0.003 mm² active area) for charge sharing and interpixel efficiency – timing studies

Issues

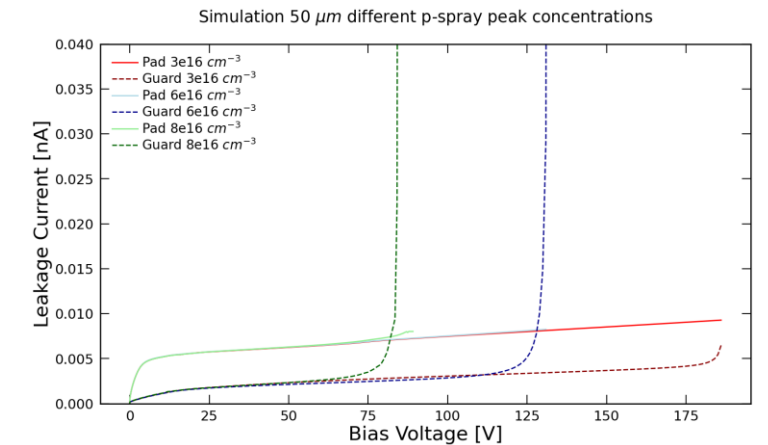
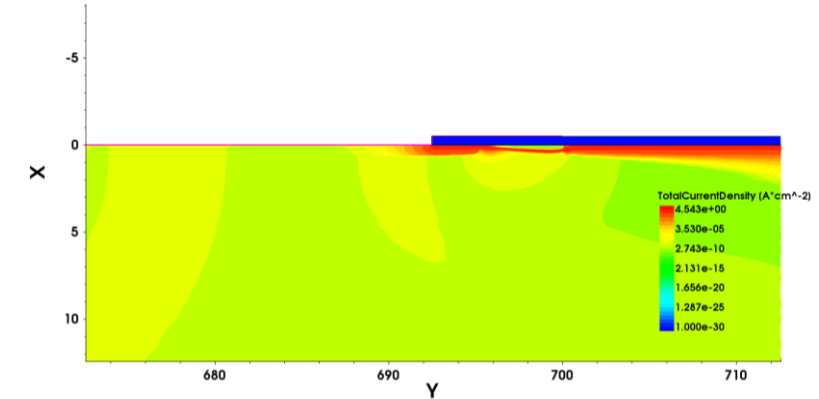
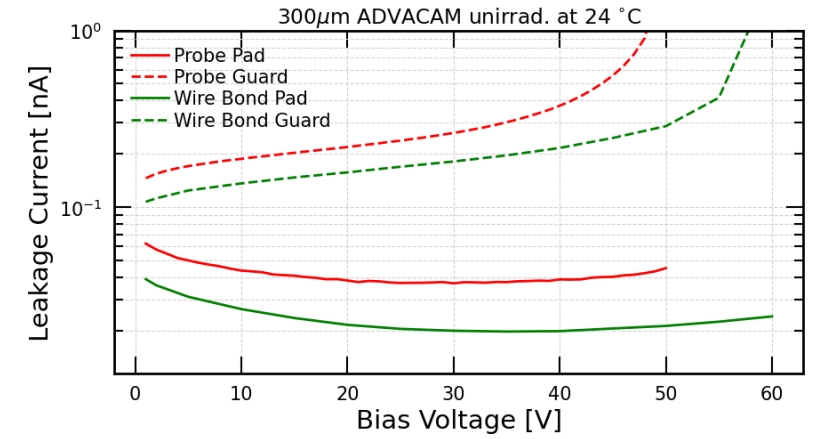
- Early breakdown due to high p-spray concentration leading to impact ionisation at the interface between p-spray and electrode implant
- Breakdown first visible in guard ring due to bigger interface region compared to pad



Small Diode



Big Diode



Irradiations

(both 3D and planar)

Neutron @ JSI (Ljubljana)

- ✓ $1 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$
- ✓ $8 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$
- ✓ $6 \times 10^{16} \text{ n}_{\text{eq}}/\text{cm}^2$
- ✓ $1 \times 10^{17} \text{ n}_{\text{eq}}/\text{cm}^2$

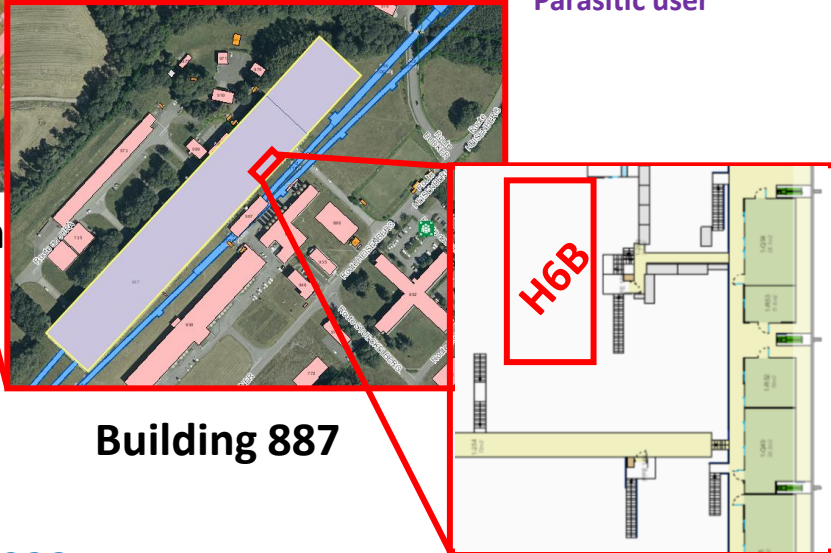
Proton @ PS

- ✓ $1 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$
- ✓ $8 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$
- ✓ $6 \times 10^{16} \text{ n}_{\text{eq}}/\text{cm}^2$
- ✓ $1 \times 10^{17} \text{ n}_{\text{eq}}/\text{cm}^2$

•Test Beam Planning



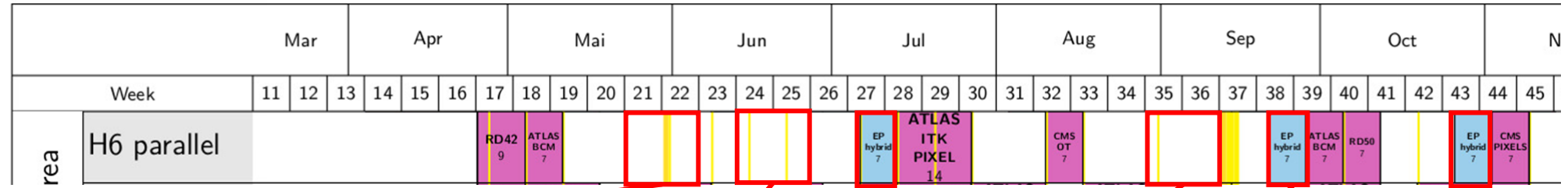
CERN Preveessin



Building 887

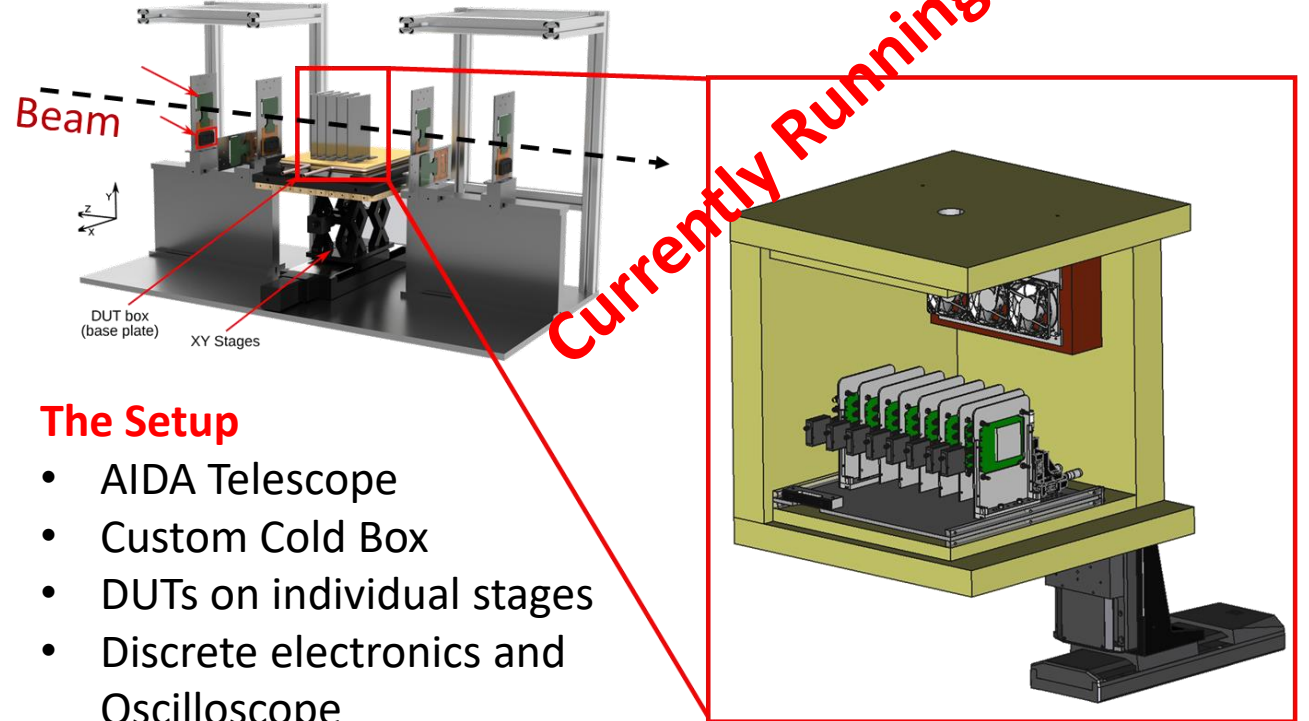
Tet Beams 2022

- Several periods but only two as primary user
- Main target irradiated Planar / 3D sensors
- No / Limited possibility of extension
- Extensive infrastructure developments



Primary user
Parallel user
Parasitic user

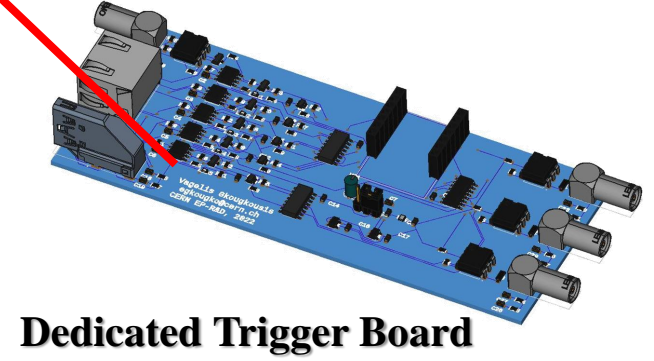
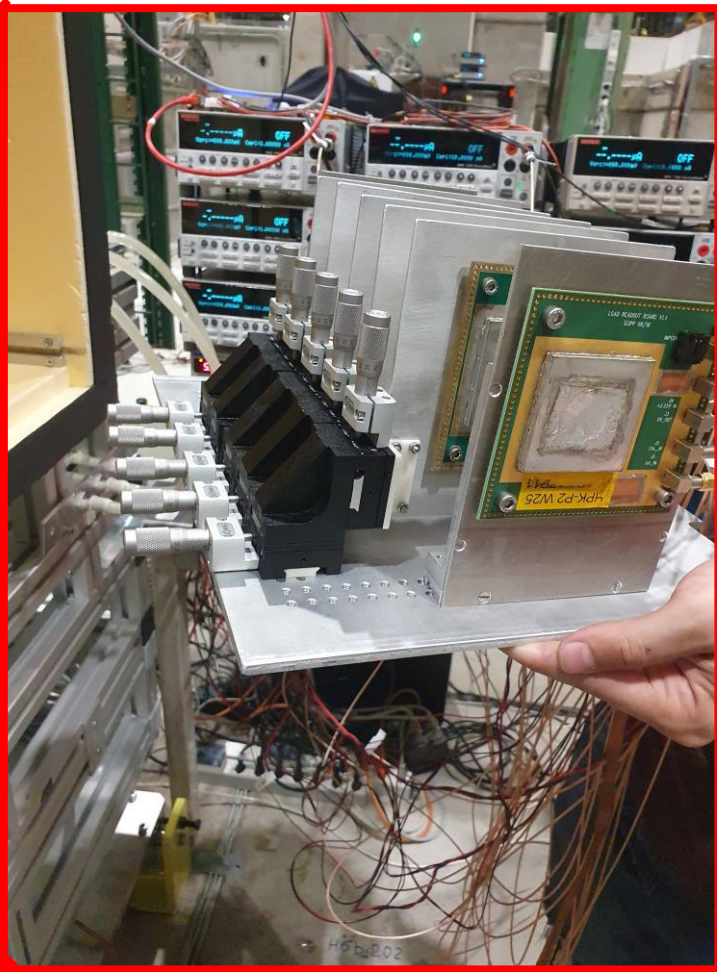
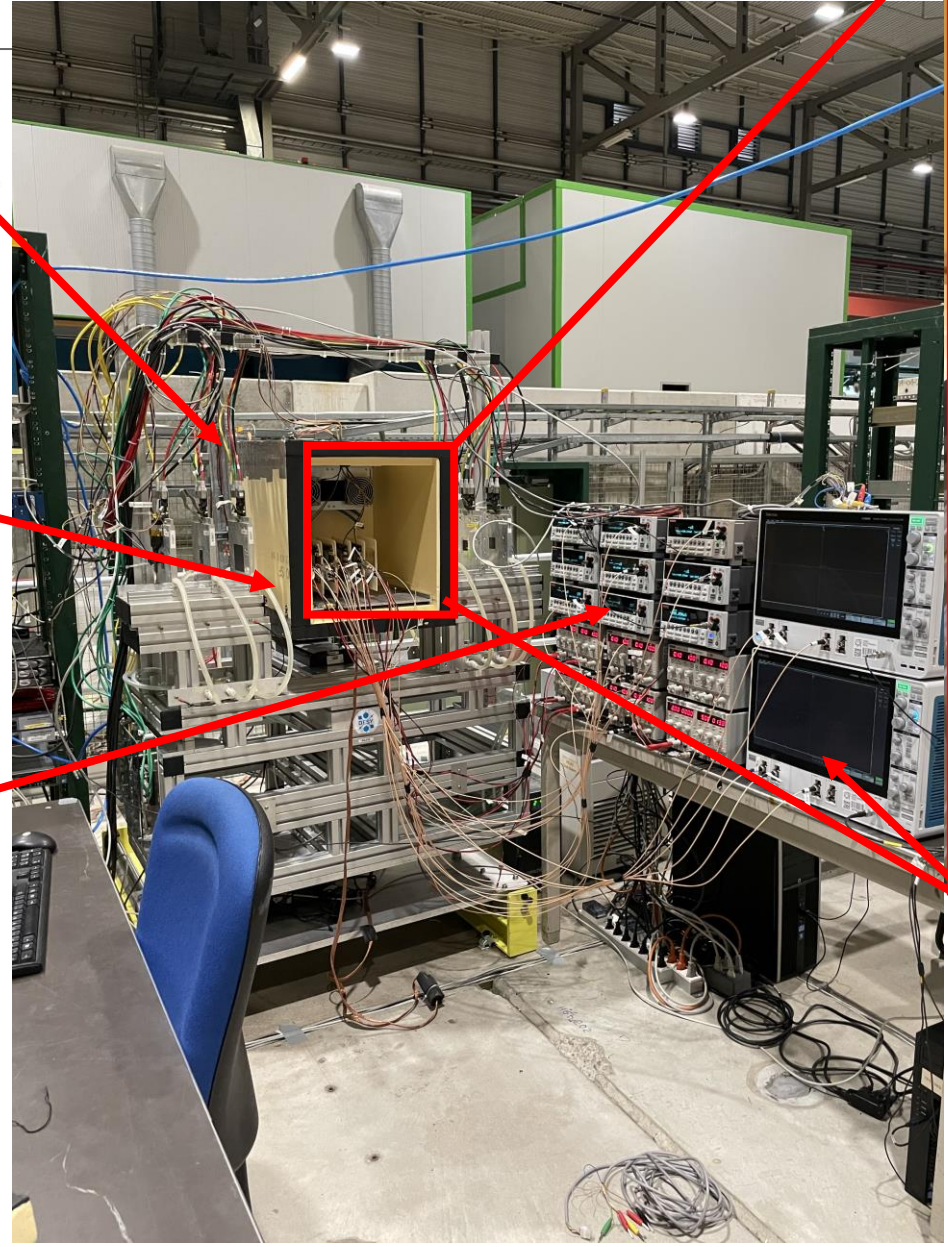
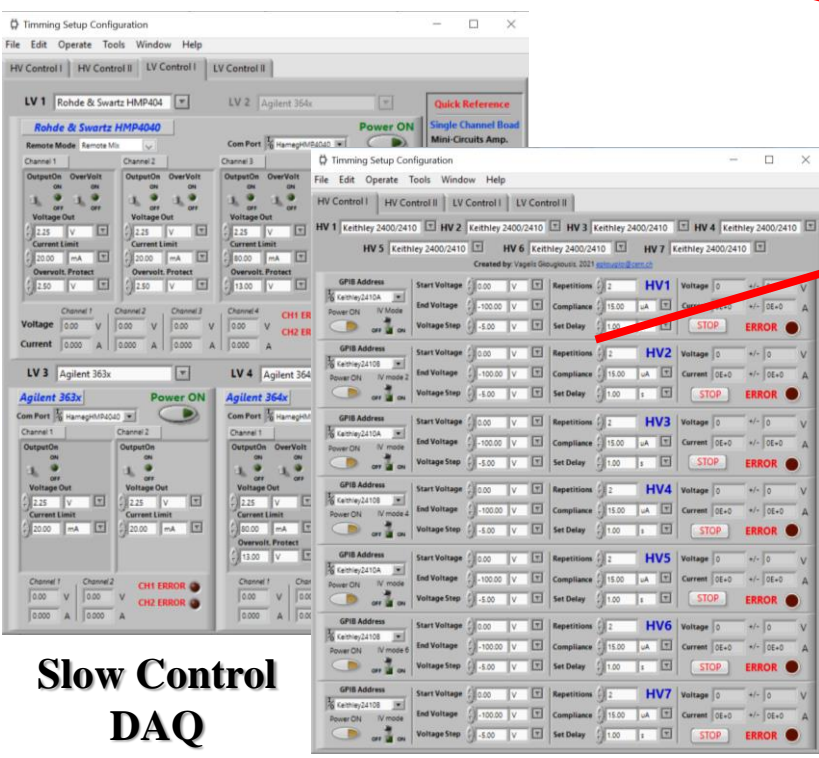
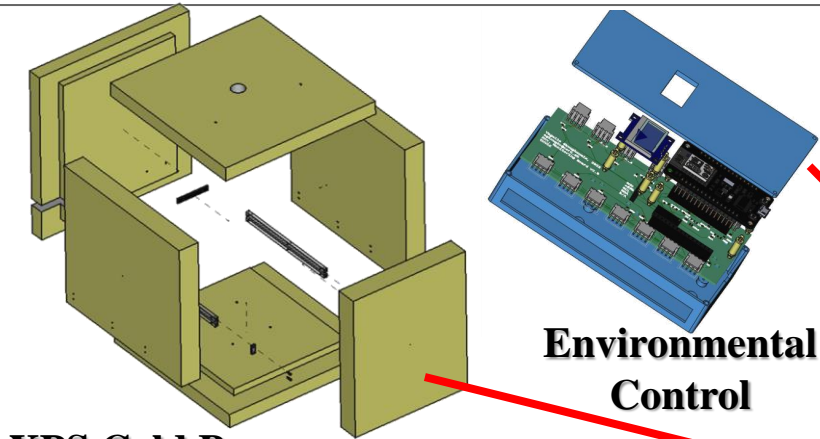
25 May – 8 June
15 – 29 June
6 July – 13 July
31 August - 14 September
20 - 27 September
17 – 24 October



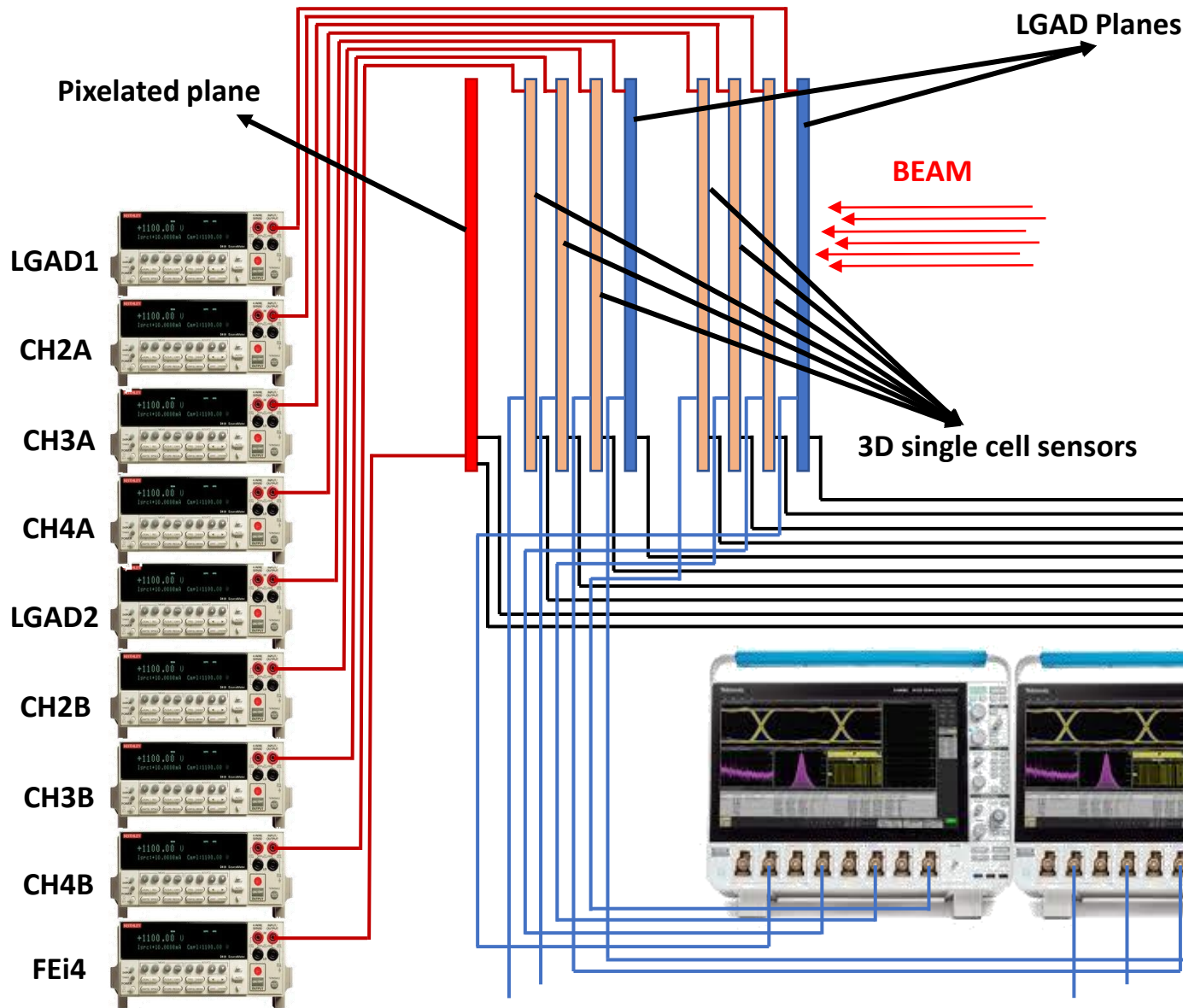
The Setup

- AIDA Telescope
- Custom Cold Box
- DUTs on individual stages
- Discrete electronics and Oscilloscope

•Setup @ SPS



•Test Beam Configuration



June Test Beam Planning

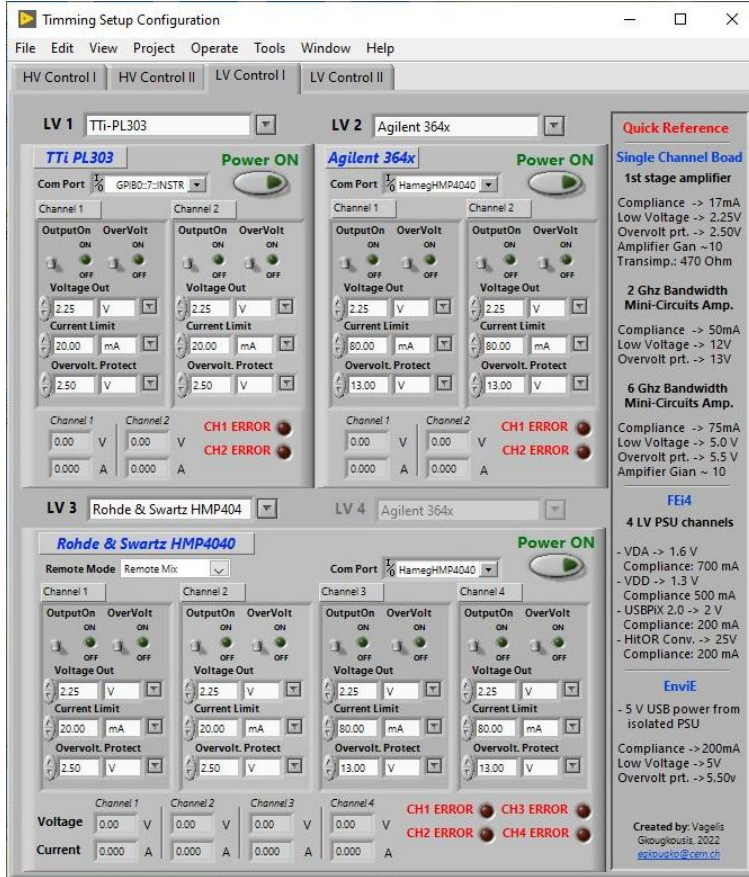
| Sample type | Sample no. | Fluence (n_{eq}/cm^2) |
|--|-----------------------|---------------------------|
| Reference LGADs | 2 | Unirradiated |
| Single Cell 3D, n-in-p, 2-sided, High Res. 285 μm thick 55 μm pitch | 1 | Unirradiated |
| | 1 | 1×10^{15} |
| | 1 | 8×10^{15} |
| 1 mm ² planar diodes | 1 x 50 μm thick | Unirradiated |
| | 1 x 100 μm thick | Unirradiated |

Equipment List

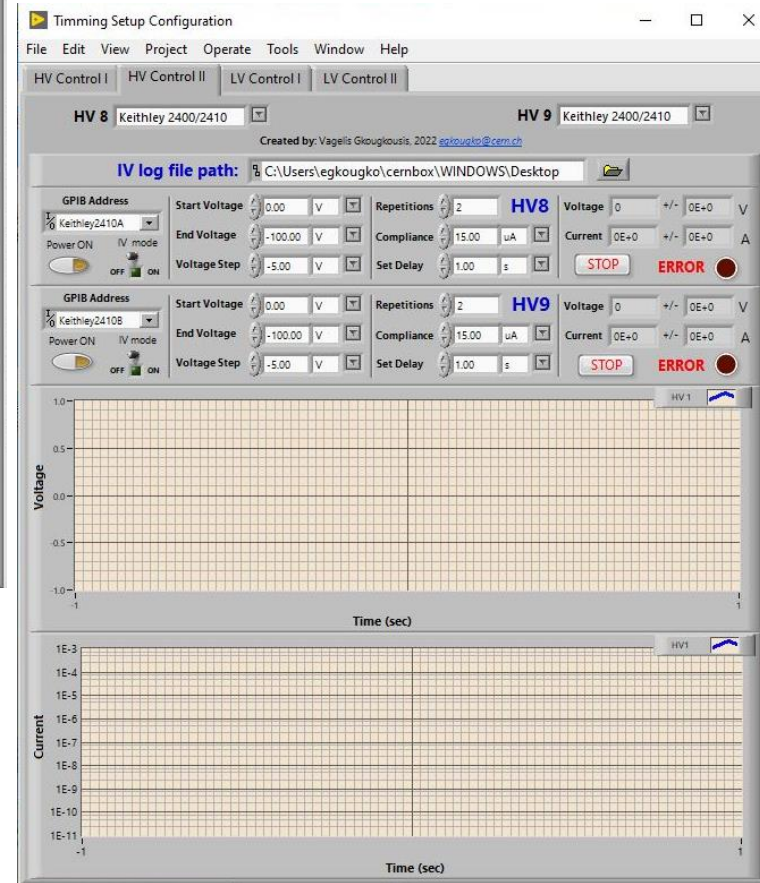
- 2 x Oscilloscopes
- 9 x Keithley 2410
- 6 x TTI PL303
- 8 Second stage amplifiers
- 6 micro-positioning stages
- Humidity – Temperature monitoring system (EnViE)
- Cold Box for -20°C operation
- Trigger Interface Board V2.0
- SMA Cables

•HV & LV Control/monitoring

➤ Precompiled executable available on GitLab: [here](#)



Labview based



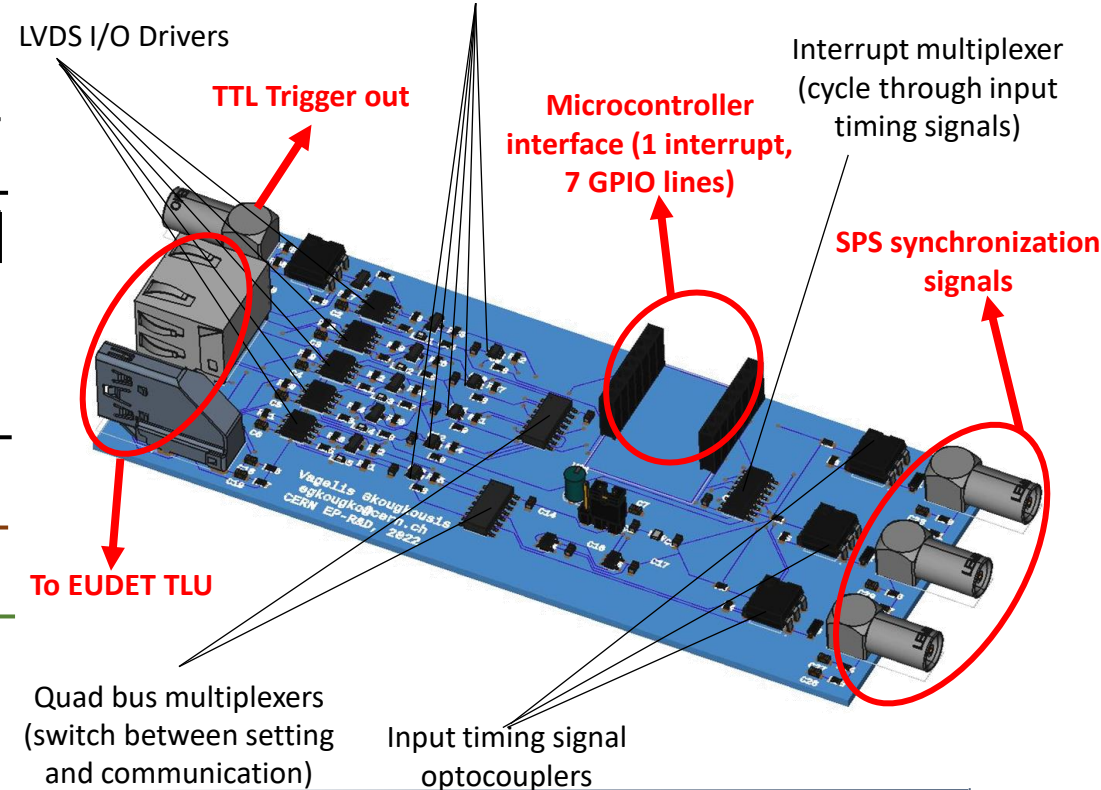
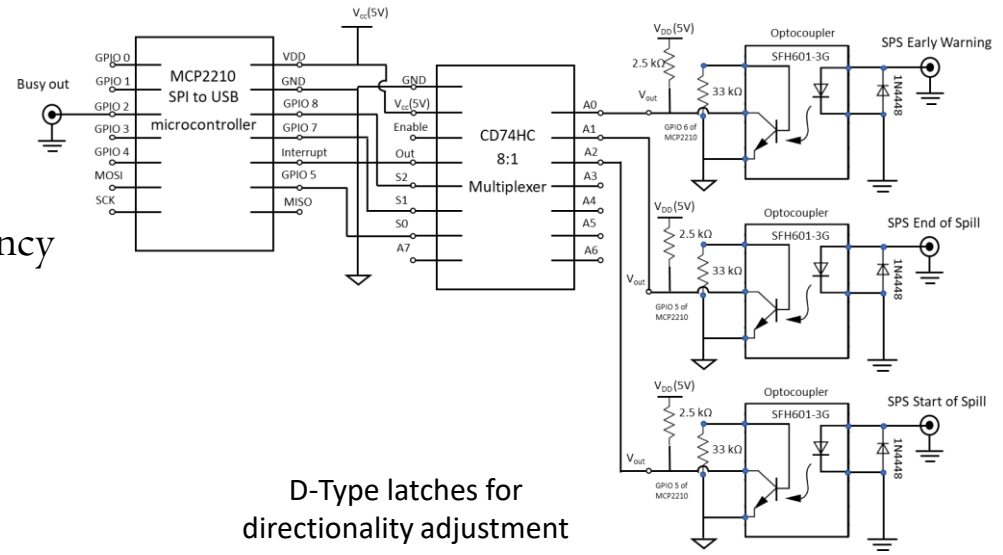
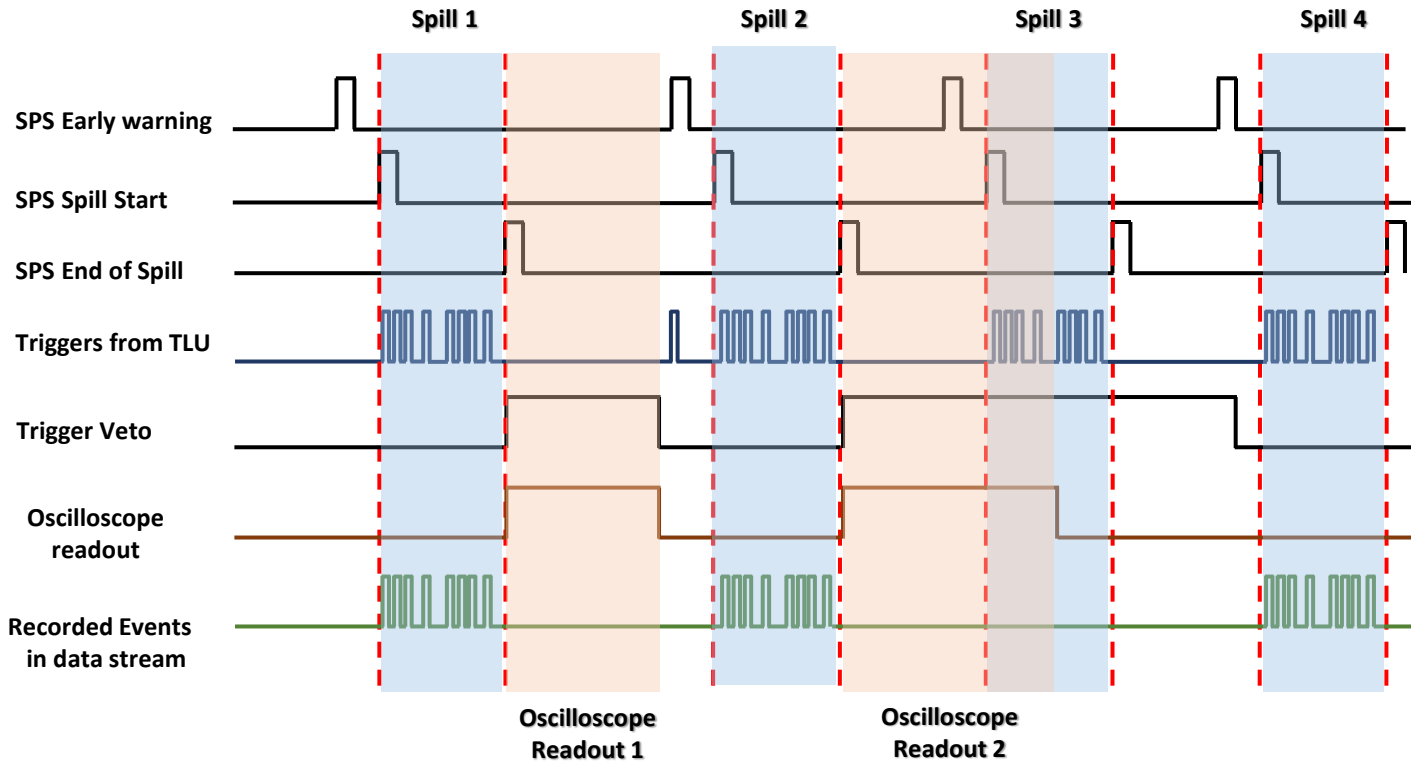
Multi-model Support with Polymorphic UI



- 9x HV channels
- 16x LV channels
- Constant monitoring & logging
- Live protection

•Trigger Interface Board (TiB)

- Oscilloscope in fast readout mode with binary format
- Event readout only between SPS-spills or when event buffer full to increase efficiency
- TLU Synchronization by vetoing data taking during read-out
- RJ-45 or HDMI for EUDET TLU communication (EUDET 2 compatible)
- **Versatile design**, I/Os **Reconfigurable** and microcontroller **Reprogrammable** via USB



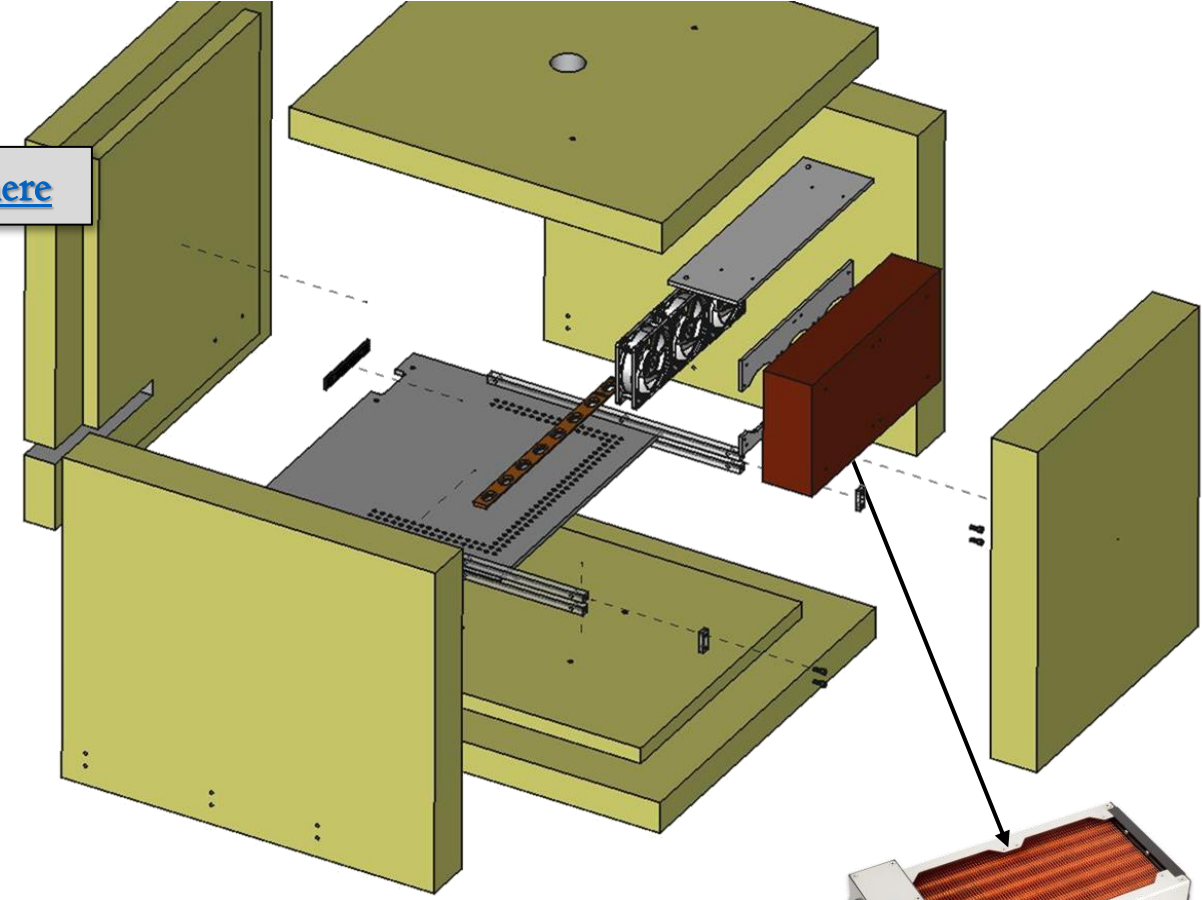
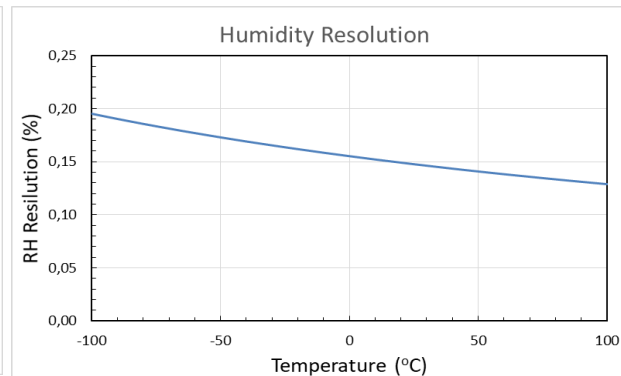
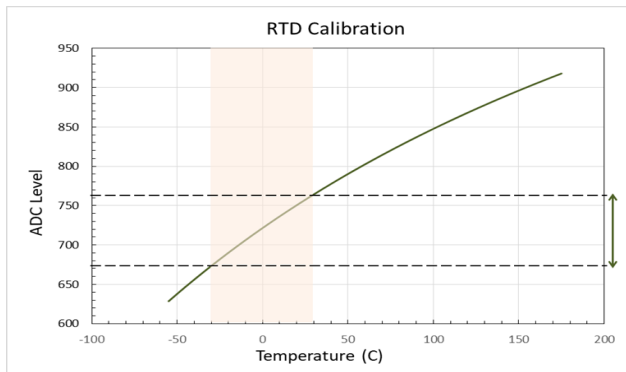
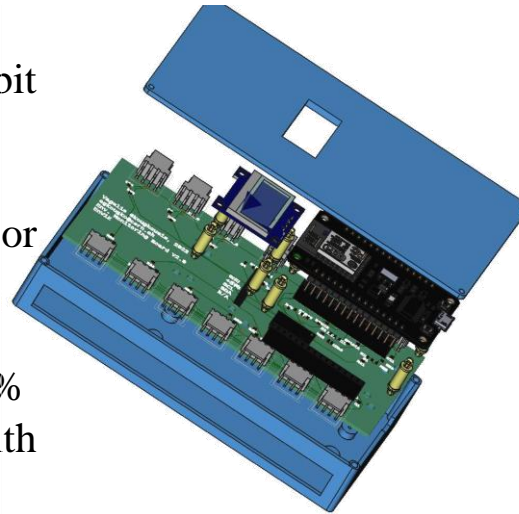
•Temperature Regulation

- Running at a crisp **-18 °C**
- Glycol cooling with temperature feedback - Labview control
- Humidity regulation though N₂ feeds

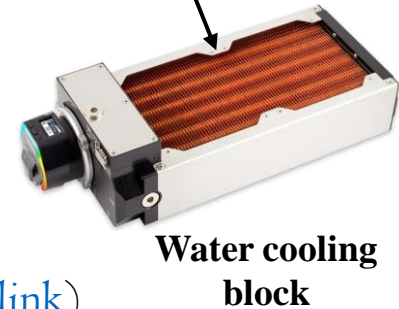
➤ EnviE GitLab with schematics: [here](#)

Environmental Expander V2.0 (EnviE)

- ESP8266 based with integrated 10-bit ADC, I2C and WiFi 802.11b
- Integrated OLED 128X64 pixel screen
- High precision voltage dividers and sensor decoupling
- ARDUINO / LoUA core web interface
- Temperature resolution of 0.8 °C ± 0.06 %
- Humidity resolution 0.1 % with temperature compensation



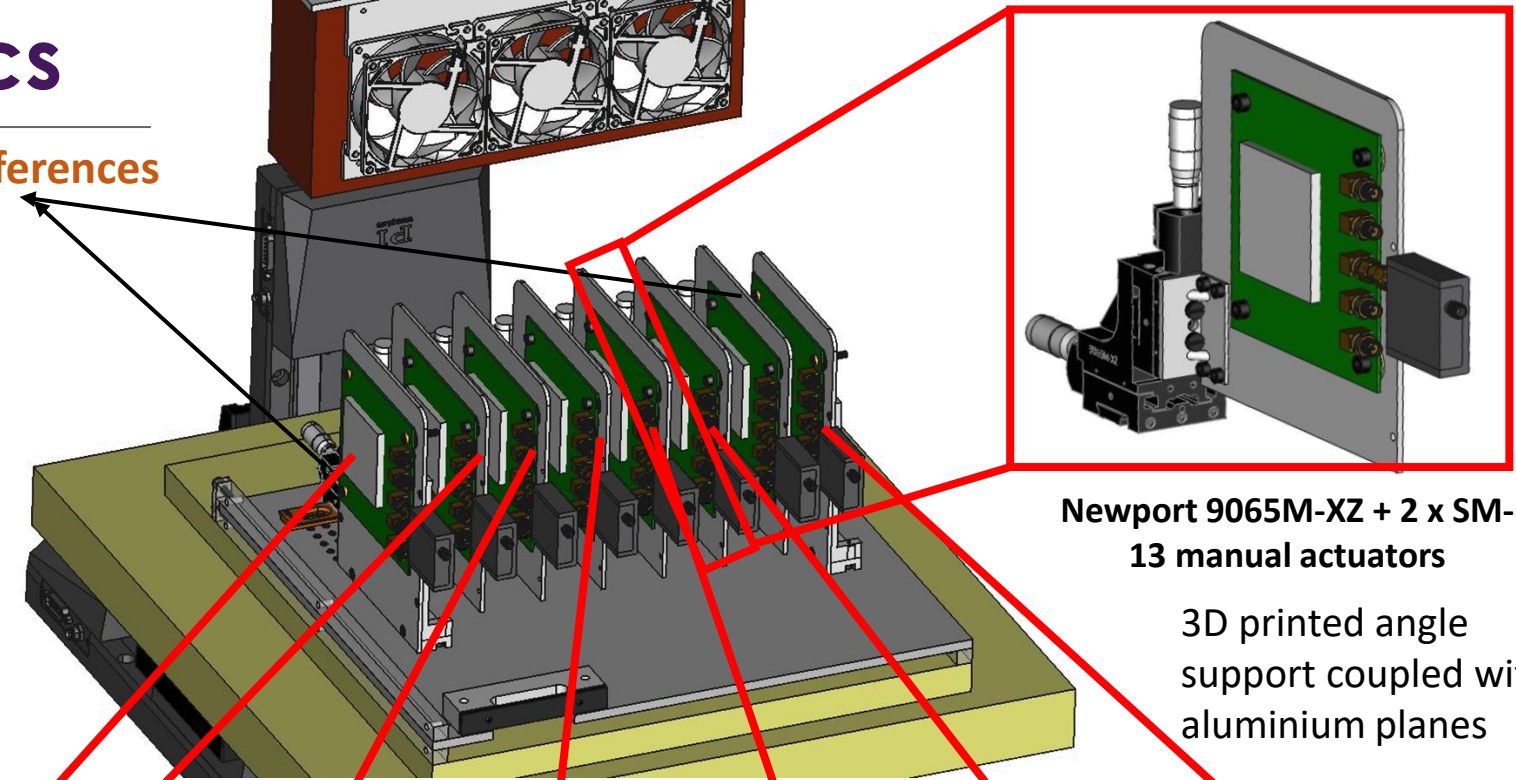
- 6 c.m. thick XPS foam insulation
- Outer dimensions of 50 x 48 x 48 cm³
- Use of commercial water-cooling block ([link](#))
- 3 x Axial Fan DC 80x80x25mm 24V 111.6m³/h – low temperature tested to -20°C ([link](#))
- Total cost ~ 400 CHF



• Alignment & Mechanics

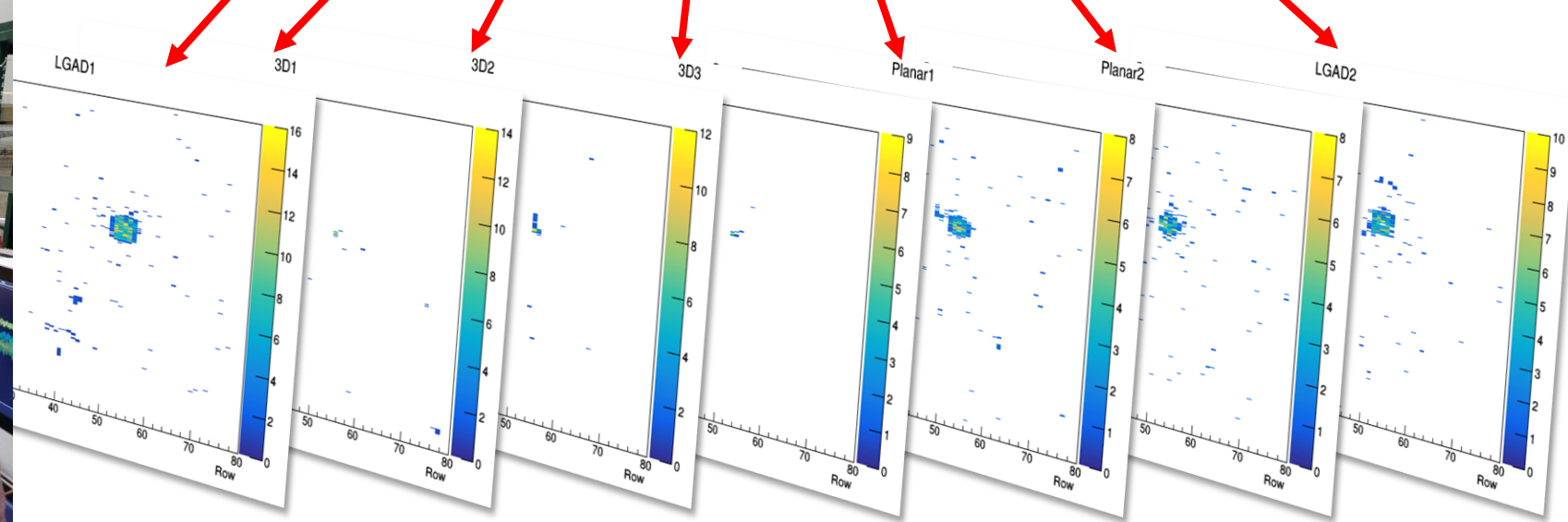
HPK LGAD Timing references

- Coincidences between DUTs and LGADs required for timing
- Alignment crucial to increase data efficiency
- Efficiency defined by largest overlapping region
- Micrometric on-line alignment using projections on FEi4 matrix
- ROI defined in addition to other trigger conditions

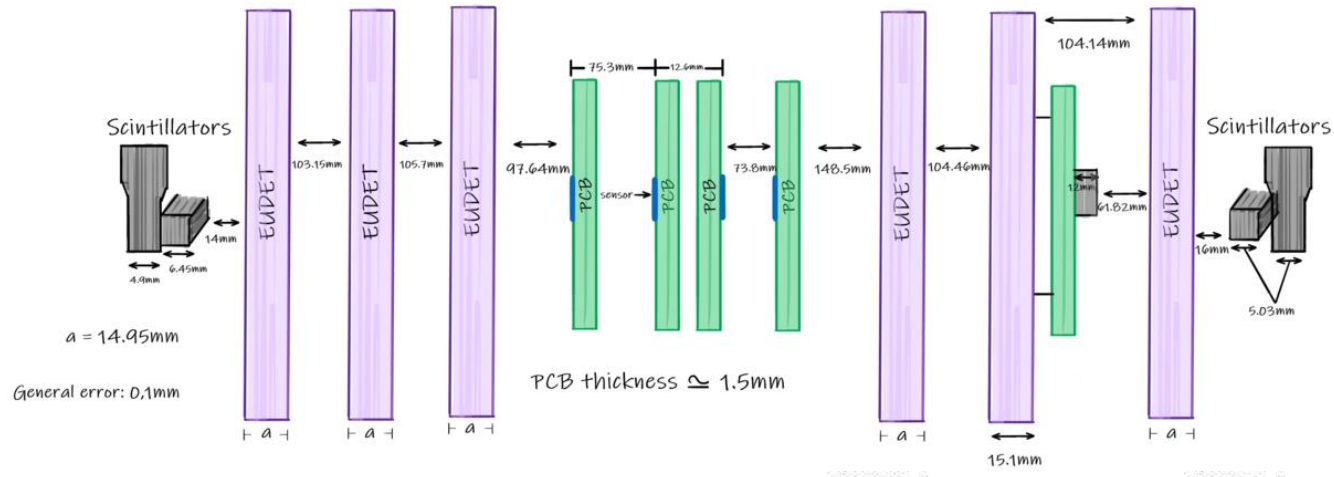


Newport 9065M-XZ + 2 x SM-13 manual actuators

3D printed angle support coupled with aluminium planes

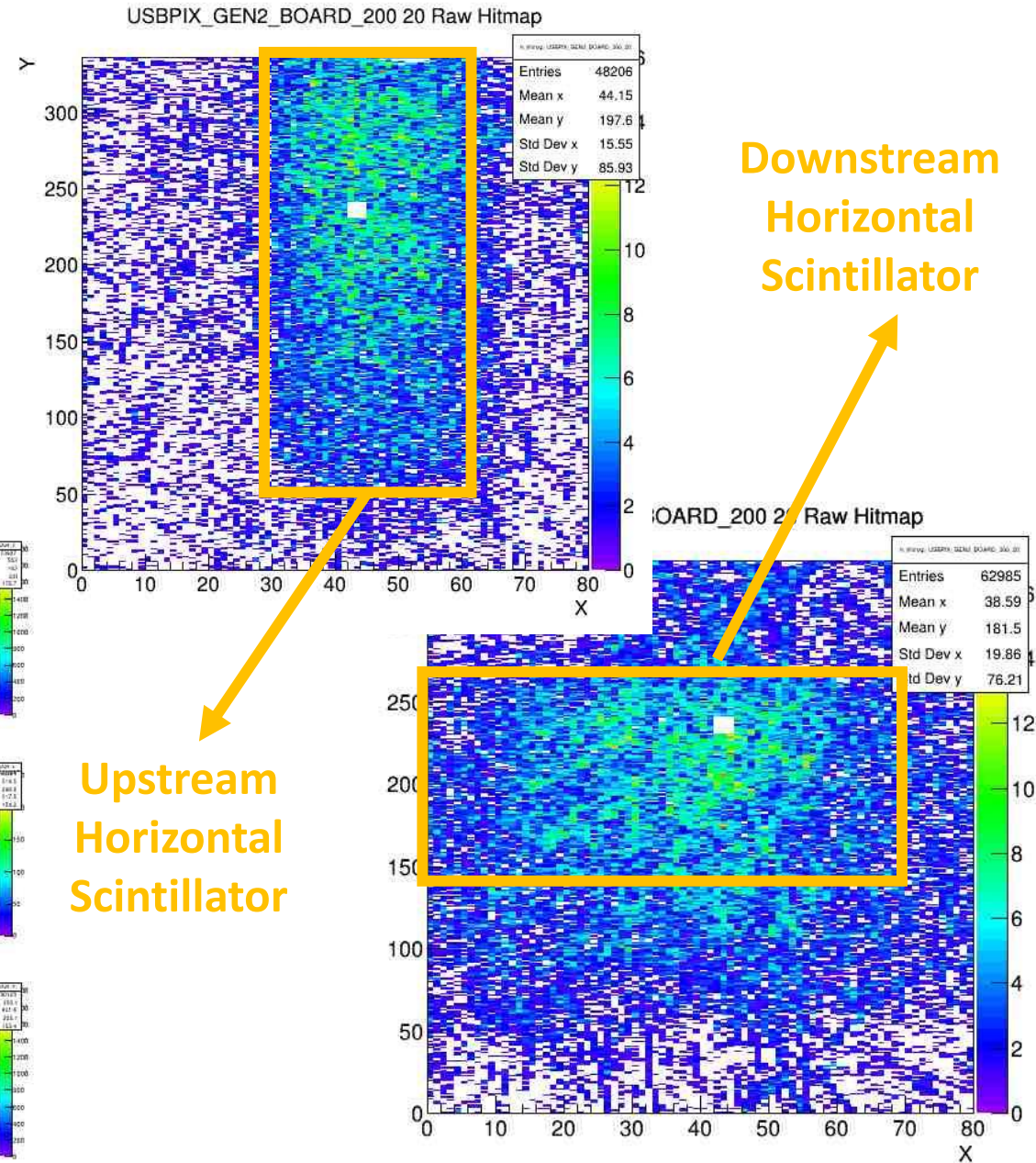
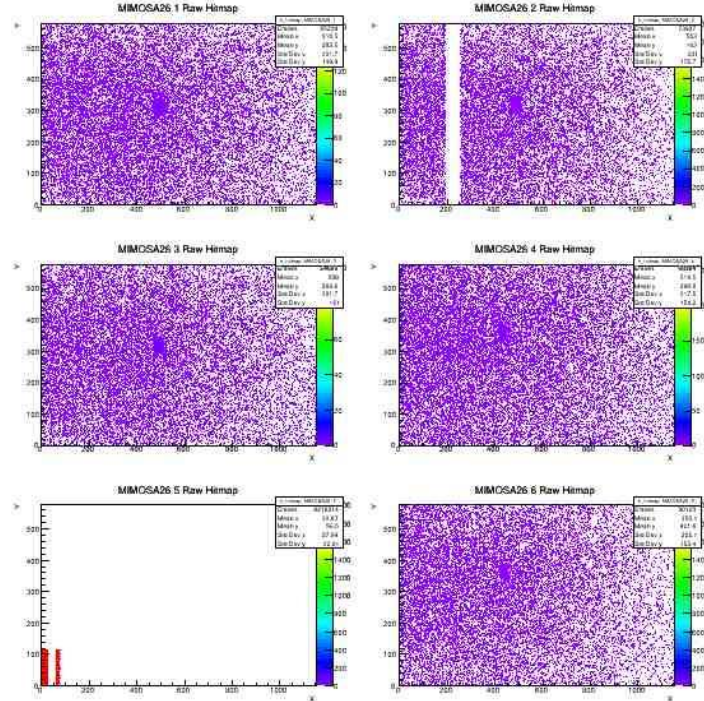


Tracking and ROI



Telescope Planes

- 6 MIMOSA planes for tracking
- Plane no. 5 known to be bad
- Expected $5\mu\text{m}$ tracking resolution
- Estimated acquired number of events $\sim 1\text{M}$
- Limited beam control as parasitic user
- Suffer from low intensity and low data rates of EUDAQ



• Analysis Framework

➤ Code available on git: <https://gitlab.cern.ch/egkougko/lgadutils>

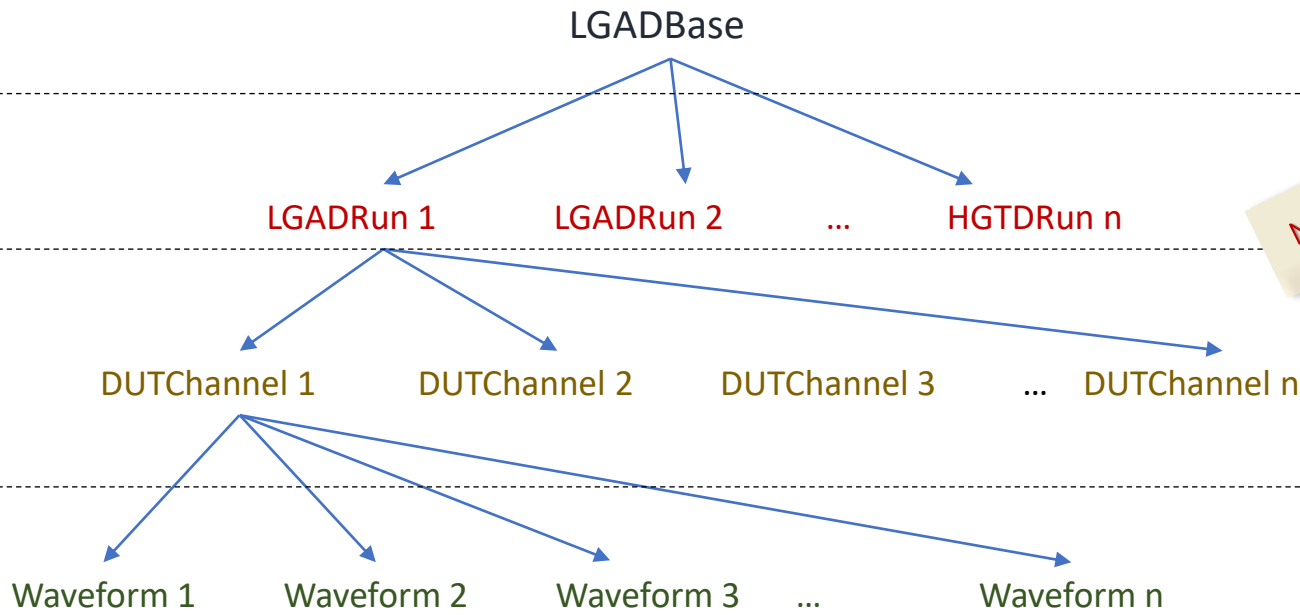
➤ Four main classes with dedicated header and implementation files, one wrapper class handling user interaction

- **LGADUtils** → Wrapper to handle user I/O and pass arguments
- **LGADBase** → Basic framework function and infrastructure
- **LGADRun** → Timing resolution, CFD maps, multi DUT operations
- **LGADChannel** → Mean pulse shape, mean pulse properties form entire run
- **WaveForm** → Single Waveform properties and time walk corrections
- **Bonus: LGADSel** → **Selector Class with auto-set 64 channel support**

C++ 11

- Iterative re-fitting and re-binning algorithm
- Fitting of discrete and variable binning quantities
- Bayesian uncertainties at efficiency level
- Event by event FFT transimpedance correction

4th level 3rd level 2nd level 1st level



$N/(dV/dt) \cdot T_{Rise}/SNR$

| Quantity | Applied Fit type |
|-------------------------------------|---------------------------|
| Min, Max voltage : | Gauss, Gauss x Landau fit |
| Start, stop, min, max indices : | Gauss, Gaussian fit |
| Noise / pedestal : | Gaussian fit |
| Min, Max, Rise, Trigger time : | Gaussian fit |
| Charge, dV/dT, <u>Jitter</u> , ToT: | Gauss x Landau fit |
| FFT: | Variable bin Gaussian |

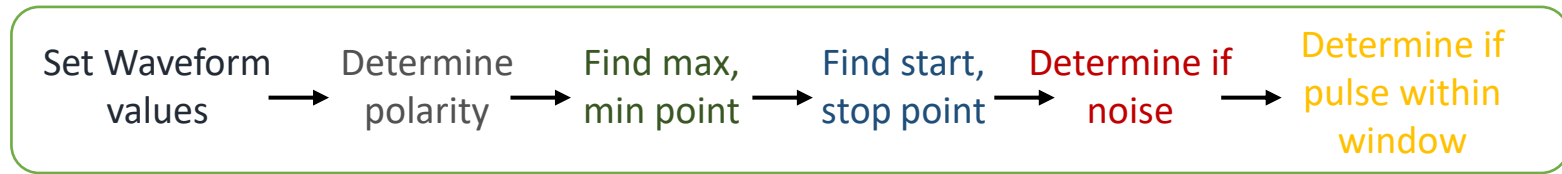
•Event by Event Strategy

File: WaveForm.cxx

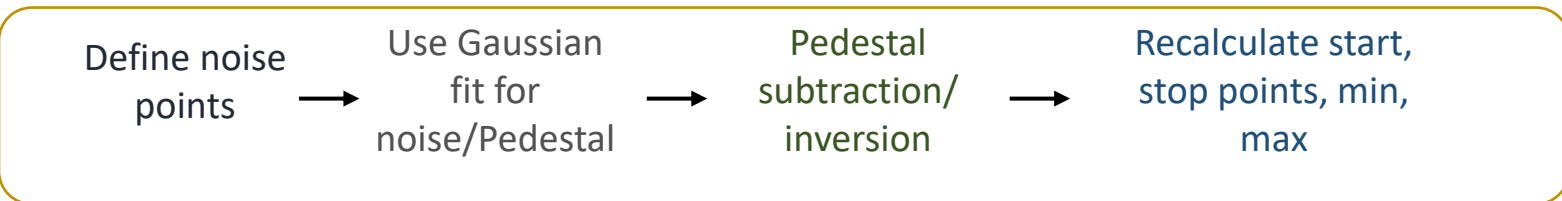
- A four sequential step analysis approach
- Analysis escalates in a pyramid structure

Five preliminary sequential steps before we even start looking at the waveform

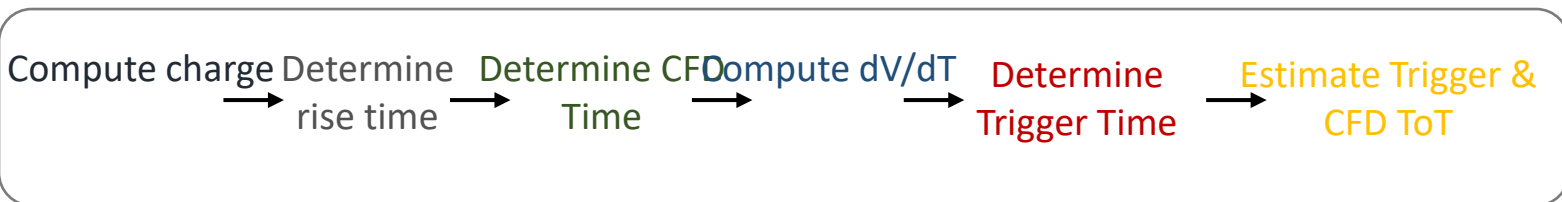
Step 1



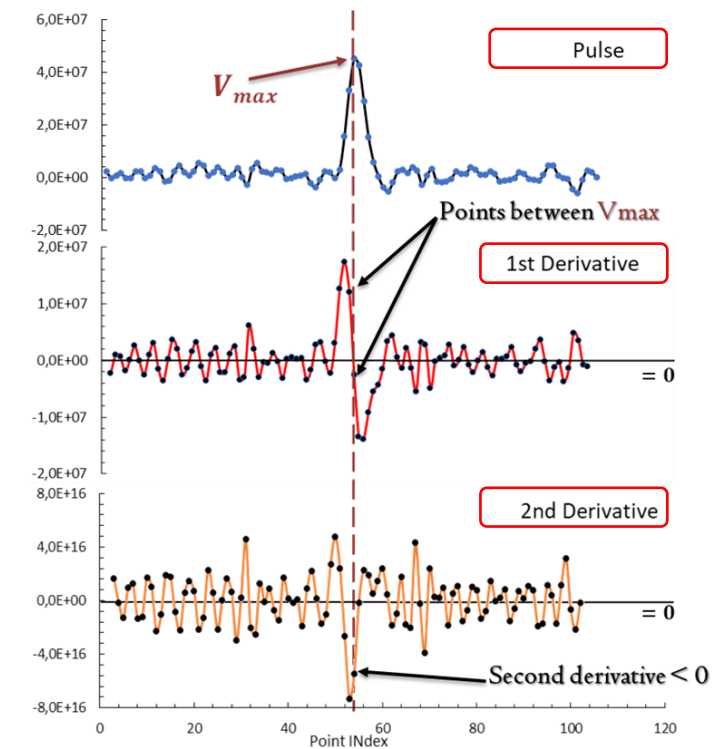
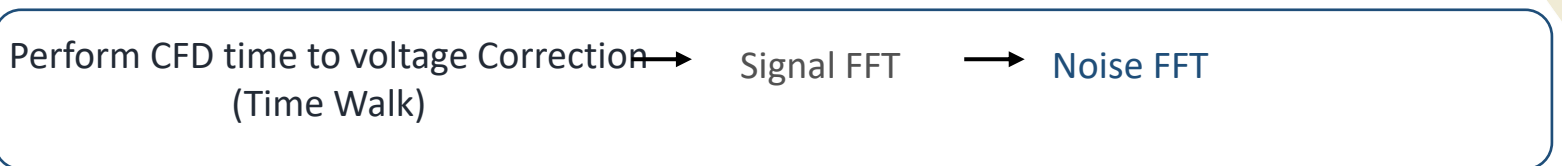
Step 2



Step 3



Step 4



- If $SD_{maxima} > SD_{minima}$
 $D_m(max) > D_m(min)$
 - or $SD_{maxima} < 1.05 * SD_{minima}$
 $D_m(max) > D_m(min)$
- } Positive polarity

IsNoise Algorithm

- Number of points with $0.8 \cdot V_{max}$
- If $N_{points} > 2$ test 0.7, 0.6 & $0.5 \cdot V_{max}$ to account for wavy waveforms
- If $N_{points} > 2$ then require $dN_{points} < 8/12/16/20$

Iterative Re-fitter & signal templates

File: LGAD Fits.cxx

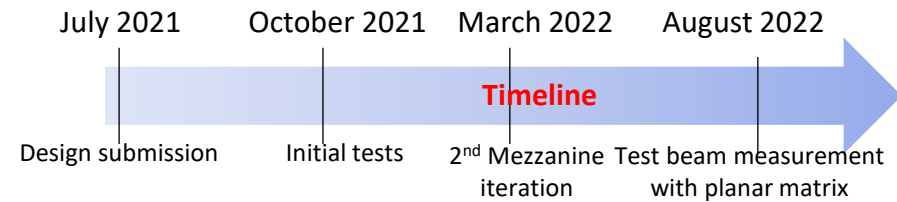
- Centralized fitter engine for all fits
- Fully automated, including limits, method and Minuit minimization
- 36 Iterations per fit with limits and bin size variation to determine best combination
- Over-binning protection, automatic variable discreteness test
- Variable binning for FFT, frequency histograms
- Supported ROOFit, Standalone Minuit, Integral optimization or Shape

Template Method

- Point by Point projection of all time-walk corrected (though CFD) signal pulses
- Landau X Gauss fit on projected point by point distribution
- Extraction of a “characteristic” signal composed of the MPVs of the Point by point projection fits
- RooKeyPdf for analytical description of signal
- Re-iteration on all events and fit of each waveform with the extrapolated analytical signal description
- Re-calculate all quantities

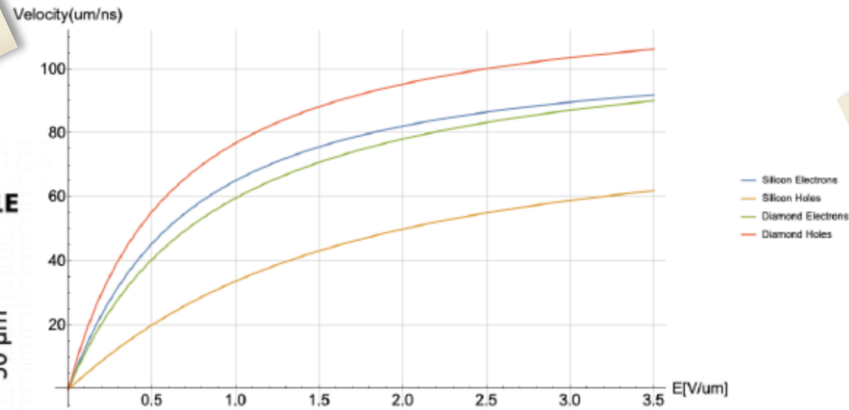
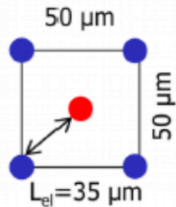
| Dataset Type | Statistic Categorization | Bin Selection Criteria | | |
|---------------------|--|--|---|--|
| | | Lower 3 bin number variations | Optimum Bin number | Higher 3 bin number variations |
| Discrete Datasets | $\frac{ \lim High - \lim Low }{\sigma_{fit}} < \sqrt{N_{elements}} < N_{bins_max}$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor - n \times \left\lfloor \frac{\sqrt{N_{elements}} - \frac{ \lim High - \lim Low }{\sigma_{fit}}}{3} \right\rfloor$ with $1 < n < 3$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor + n \times \left\lfloor \frac{N_{bins_max} - \sqrt{N_{elements}}}{3} \right\rfloor$ with $1 < n < 3^{**}$ |
| | $\sqrt{N_{elements}} \leq \frac{ \lim High - \lim Low }{\sigma_{fit}} < N_{bins_max}$ | Lowest bin number | Rest of the bin number array | |
| | $\sqrt{N_{elements}} \leq N_{bins_max} < \frac{ \lim High - \lim Low }{\sigma_{fit}}$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor + n \times \left\lfloor \frac{N_{bins_max} - \sqrt{N_{elements}}}{6} \right\rfloor$ with $1 < n < 6^{**}$ | |
| | $N_{bins_max} \leq \sqrt{N_{elements}}$ | $n \times \lfloor N_{bins_max} / 7 \rfloor$ with $1 < n < 7$ | | |
| Continuous Datasets | $\frac{ \lim High - \lim Low }{\sigma_{fit}} < \sqrt{N_{elements}}$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor - n \times \left\lfloor \frac{\sqrt{N_{elements}} - \frac{ \lim High - \lim Low }{\sigma_{fit}}}{3} \right\rfloor$ with $1 < n < 3$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor$ | $\left\lfloor \sqrt{N_{elements}} \right\rfloor + n \times \left\lfloor \frac{\frac{ \lim High - \lim Low }{\sigma_{fit}}}{3} \right\rfloor$ with $1 < n < 3$ |
| | $\sqrt{N_{elements}} \leq \frac{ \lim High - \lim Low }{\sigma_{fit}}$ | $\left\lfloor \frac{ \lim High - \lim Low }{\sigma_{fit}} \right\rfloor - n \times \left\lfloor \frac{\frac{ \lim High - \lim Low }{\sigma_{fit}} - \sqrt{N_{elements}}}{3} \right\rfloor$ with $1 < n < 3$ | $\left\lfloor \frac{ \lim High - \lim Low }{\sigma_{fit}} \right\rfloor$ | $\left\lfloor \frac{ \lim High - \lim Low }{\sigma_{fit}} \right\rfloor + n \times \left\lfloor \frac{\sqrt{N_{elements}}}{3} \right\rfloor$ with $1 < n < 3$ |

•16 Channel Board



The issue....

50x50 μm^2 , 1E



The solution

- ❖ High frequency multichannel versatile board
- ❖ Mezzanine design for fast sensor interchangeability
- ❖ Suitable for matrices (AC-LGAD applications) but also for single pad devices

- Assuming a linear field dependence and a -15 V operation point at 35 μm column distance:
 $|E| \cong 0.43 \text{ V}/\mu\text{m}$

- Estimating drift velocity for electrons:

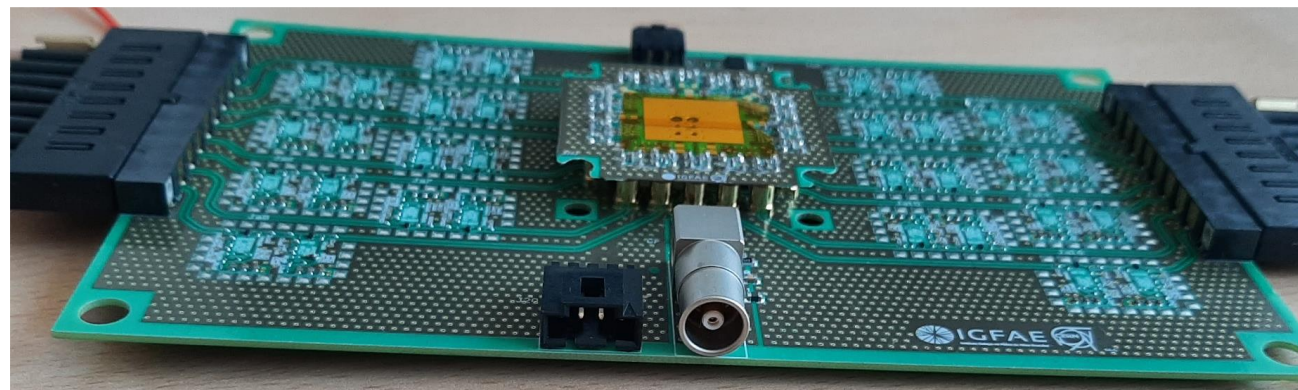
$$v_{drift}^e = \frac{\mu_{0,e} \times E}{\left[1 + \left(\frac{\mu_{0,e} \times E}{v_{sat}^e} \right)^{\beta_e} \right]^{1/\beta_e}}$$

with $v_{sat}^e = 107 \mu\text{m}/\text{ns}$, $\mu_{0,e} = 1417 \frac{\text{cm}^2}{\text{Vs}}$, $\beta_e = 1.109$

$$v_{drift}^e \approx 41.4 \mu\text{m}/\text{ns}$$

- Extrapolated Rise time and Frequency:

$$t_{Rise} \approx \frac{1}{3} \times t_s = \frac{1}{3} \times \frac{d/2}{v_{drift}^e} \approx 140 \text{ psec} \Rightarrow \mathbf{2.3 \text{ GHz}}$$

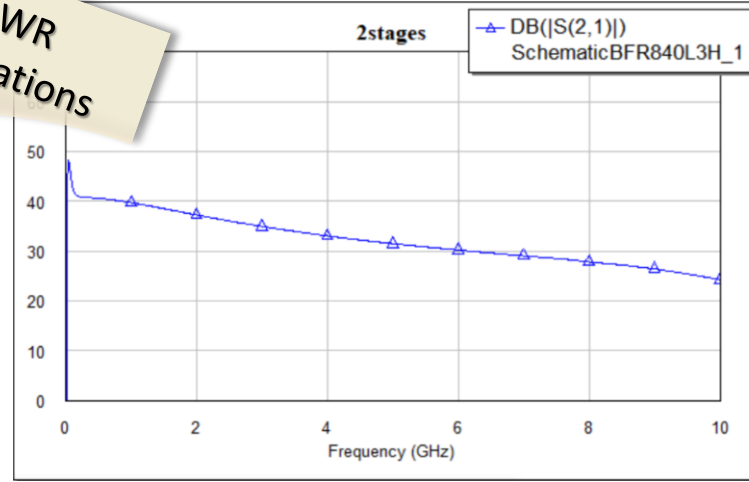
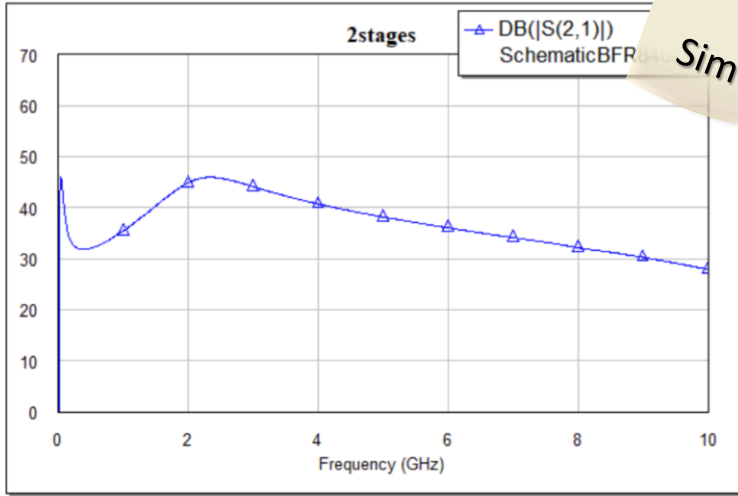


• Simulations and performance

Initial design

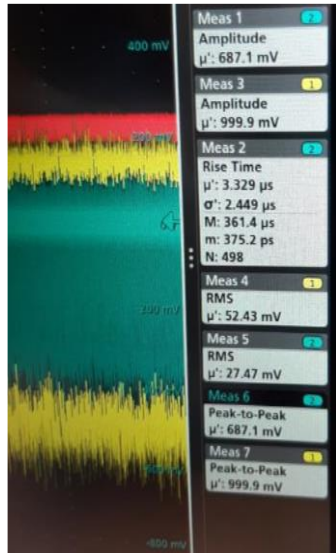
Modified –Uniform design

AWR Simulations

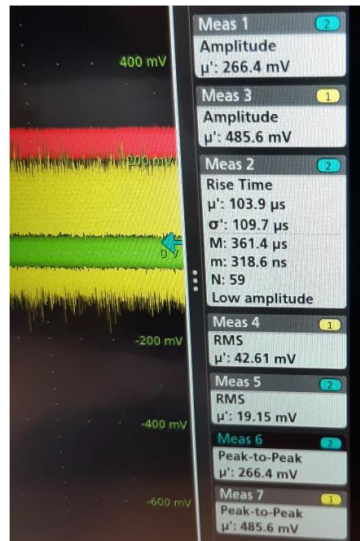


- Optimized design for uniform response with frequency
- No sharp gain change discontinuities
- No undershoot/overshoot observed
- Gain moderated to ~ 70 for a two-stage configuration
- 20% Higher SNR than UCSC board (with both stages)
- 2 x SNR with respect to UCSC board + miniCircuits second stage amplifier
- On going energy and transimpedance simulation

With signal injection

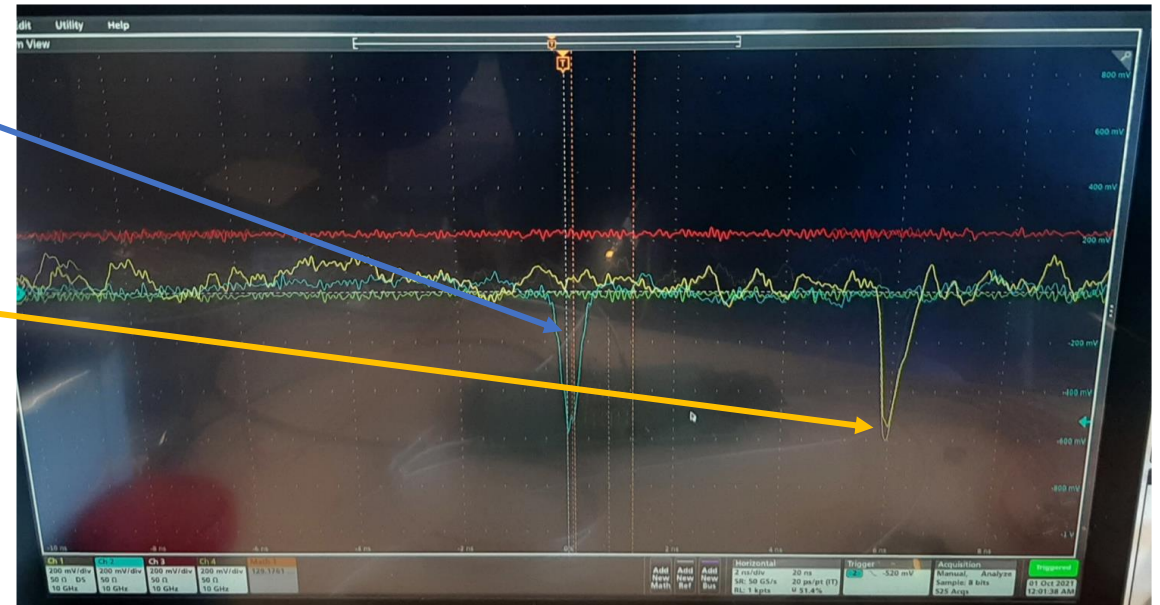


Without signal injection



Blue: 16 channel board

Yellow: UCSC board (only one stage)



•Towards the Future: Samplic

The ASIC (SAMPIC)

- Technology: AMS 0.18 μ m
- Sampling: between 3 and 8.4 GS/sec on 16 channels (depends on DAC setting)
- 16 channels per chip
- Signal Bandwidth of 1.6GHz
- Discrimination noise 2 mV, chip noise < 1.3 mV RMS
- Max input Signal: 1V unipolar (0.1V to 1.1V)

ADC

- 8 to 11 bit Wilkinson ADC at 1.3GHz
- Upon triggering 64 samples digitalized in parallel per channel
- Resolution adjustment possible to improve timing by reducing bit count
- Time resolution between 5 ps (calibrated) and 15ps (uncalibrated)

Calibration

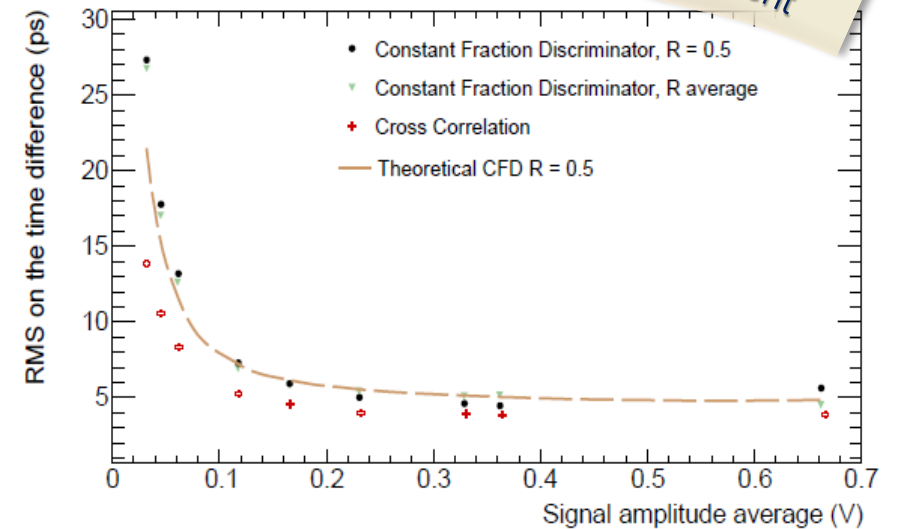
- Calibration files provided for all operational points of the ADC
- Channel by channel calibration to be performed by user
- 64 channels x 4 operation points = 256 calibration runs

Connectivity

- USB2.0 + LabWindows based software (provided)
- UDP Based Ethernet, direct PC connection – no router support



No minimum ToT Requirement



• Conclusions

3D Pixels - Planar measurement campaign

- Several productions under investigation of different pixel size and thickness
- ***Estimate field non-uniformity impact on time resolution vs pixel size***
- ***Determine minimal acceptable thickness for time resolution applications (SNR)***
- ***Investigate effects after irradiation up to $1e17 n_{eq}/cm^2$ in protons and neutrons***

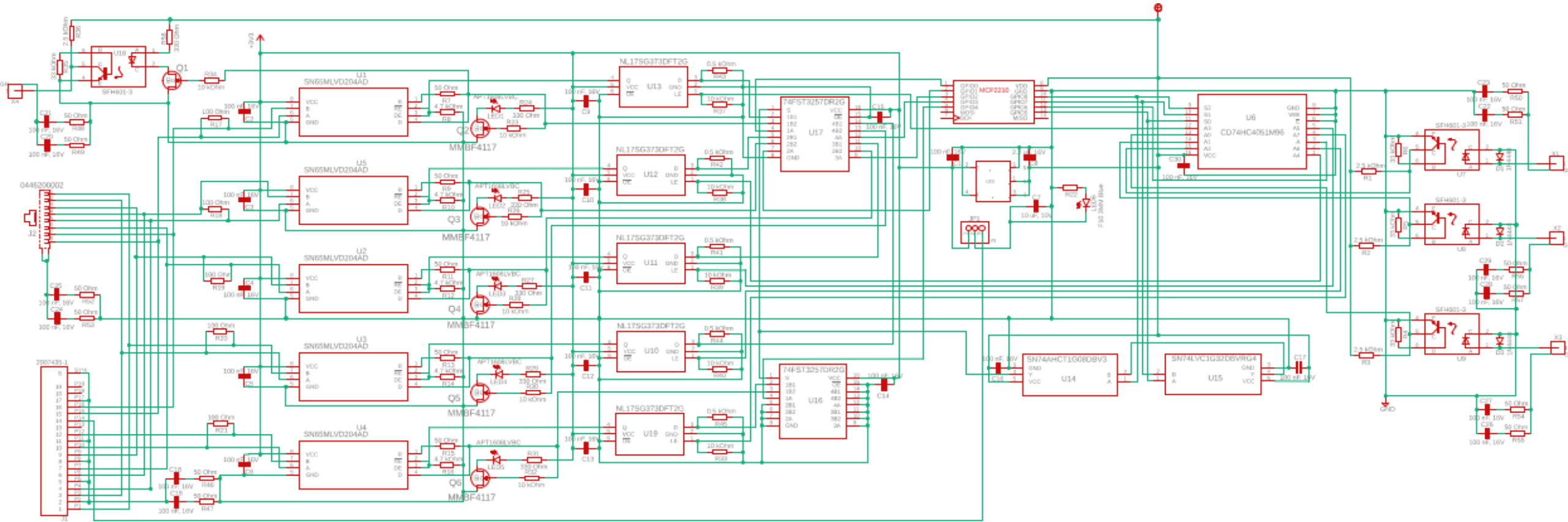
Primary Goals

Test-Beam Setup

- ***Trigger Interface board:*** Versatile, allows interfacing any acquisition instrument with EUDET
- ***Control Software:*** Polymorphic UI with seamless multi-instrument support
- ***Cooling:*** XPS cold box with web interface temperature controllable system @ -18°C
- ***Mechanics:*** Micrometric alignment with individual DUT stages
- ***Analysis Framework:*** Advanced framework with signal shapes, iterative re-fitting and shape-based noise rejection

•Backup

•TIB Schematics



•Fits infrastructure

Available fitting options



- Root multi-iterative automatic fitting for:

I. Gauss

II. Gauss X Landau

```
int IterativeFit (std::vector<double> *w, std::pair<double, double> &gmean, std::pair<double, double> &gsigma,
                 TH1D* &FitHist, double &minchi2, std::string methode = "Gauss", std::pair<int, int> points =
                 std::make_pair(-1, -1))
```

- Unpinned 2-dimensional Linear fitting through RooFit and Minuit:

```
int LinearFit (std::vector<double>* vec, std::pair<double, double> &slope, std::pair<double, double> &intersept,
              std::vector<double>* vecErr = NULL);
```

- Roofit Convolution fitting (no iterative readjustment) for:

I. Gauss X Landau

II. Gauss X Linear

```
int RooConvFit (std::vector<double>* vec, std::pair<double, double> &magMPV, std::pair<double, double>
               &magSigma, std::string conv);
```

- Two point linear interpolation:

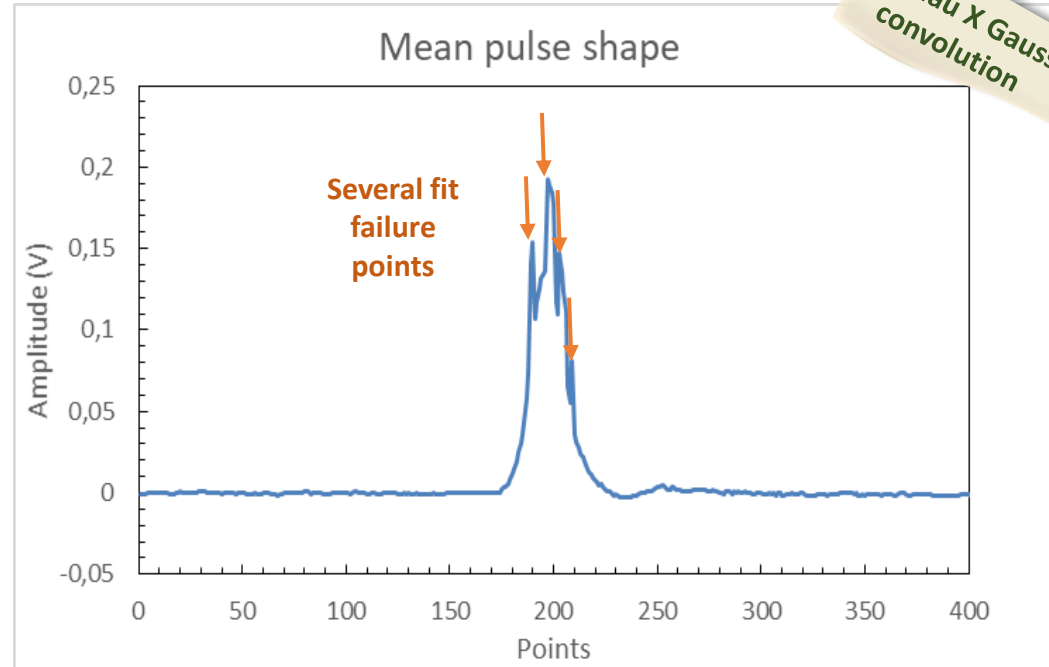
```
double LinearInter(double x1, double y1, double x2, double y2, double y3);
```

- Fast Fourier transform algorithm: `double FFT(std::vector<double> *w, Long64_t snrate, int start, int stop);`

•Average pulse shape (RooFit)

Starting point, Non-optimized RooFit Convolution

- I. Average calculated from 100 events
- II. Each waveform is time aligned at 20% CFD
- III. For all events, the same point of each waveform projected in TH1F
 - ✓ as many TH1F as points in waveform
 - ✓ each with as many entries as events (100 here)
- IV. Each TH1F fitted with a Landau X Gauss distribution
- V. MPV, sigma and uncertainty extracted
- VI. Fitting performed in RooFit using RooFit Convolution and Minuit
- VII. No starting parameters or optimization
- VIII. Plot the MPVs of each point in a single waveform



•Average pulse shape (RooFit)

Initial RooFit Optimization

I. Fit Binning:

- ✓ Symmetric fit limits: $\mathbf{x_{av.} \pm (5 \times \sigma)}$
- ✓ Bin width defined as: $\sigma / 3$
- ✓ High statistics re-optimization, increase no. of bins if: $\mathbf{N_{points} > 1.5 \times N_{bins}}$

II. Parameter constraints:

- ✓ Asymmetric limits for Landau MVP:
 $\mathbf{-4 \times |x_{RMS}| < x_{fit} < 2 \times |x_{RMS}|}$
- ✓ Asymmetric limits for Landau sigma:
 $\mathbf{-0.001 \times \sigma < \sigma_{fit} < 2 \times \sigma}$
- ✓ Symmetric limits for Gauss mean:
 $\mathbf{-2 \times \sigma < \sigma_{fit} < 2 \times \sigma}$

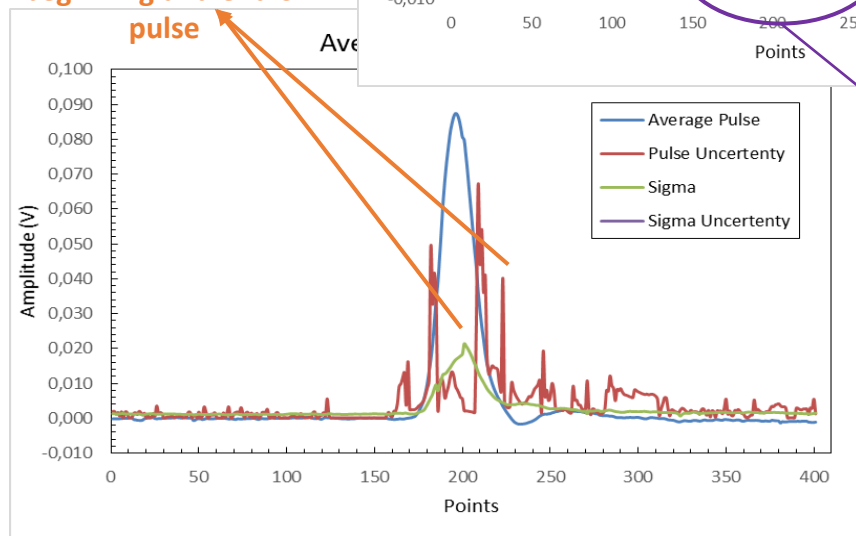
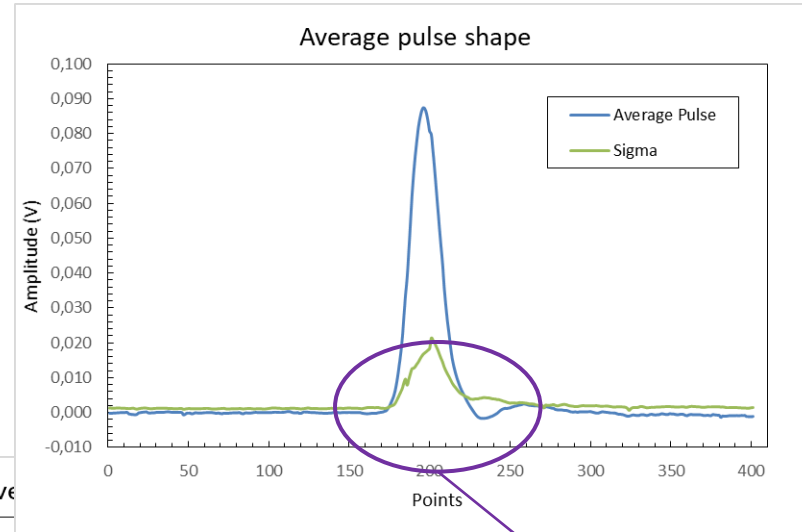
III. Parameter Initial values:

- ✓ Landau **MPV** = $\mathbf{x_{RMS}}$
- ✓ Gauss **sigma** = $\mathbf{0}$

IV. No re-iteration implementation

Smooth pulse shape

High uncertainties at the beginning and end of pulse

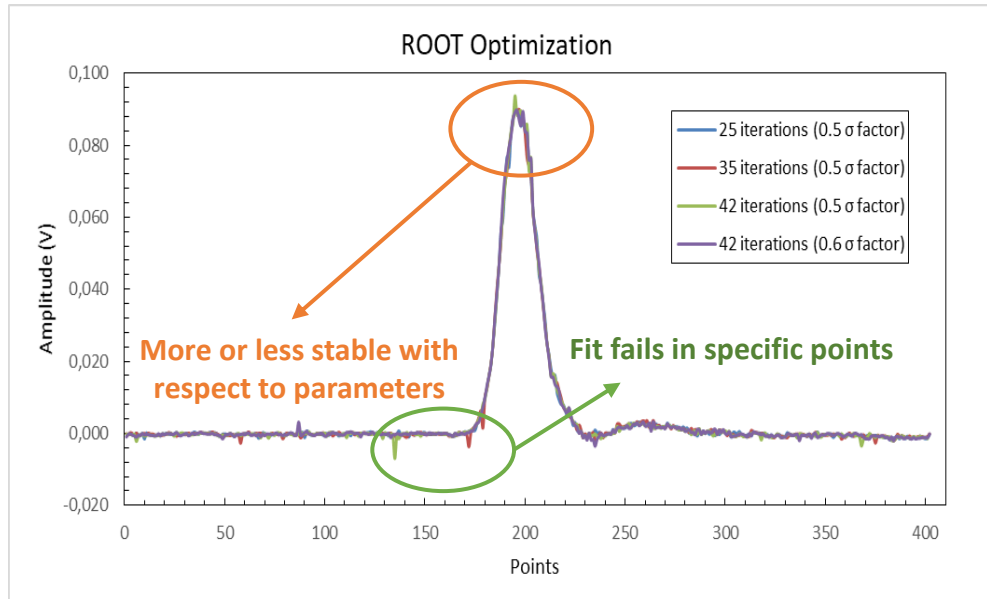


Reasonable sigma with respect to MPV, no outliers

•Average pulse shape (Root)

Root Optimization (no RooFit)

- Constraint parameter values but not fixed
- Manually defined convolution function
- 1000 convolution steps
- Select the fit with the best agreement (minimization of $|1-x^2/NDF|$)



I. Iterative approach

II. Fit Binning:

- ✓ Asymmetric fit limits:

$$\text{lower: } x_{\min} - ((n-5)/10) \times \sigma$$

$$\text{upper: } x_{\max} - ((n-5)/2) \times \sigma$$

where $7 < n < 2$

→ 6 cases

- ✓ Bin number defined at least as:

$$N_{\text{bins}} = \sqrt{N_{\text{events}}}$$

augmented by:

$$(x_{\max} - x_{\min}) / (0.5 \times \sigma \times \alpha/4)$$

where $14 < \alpha < 7$

→ 7 cases

III. Parameter constraints:

- ✓ Asymmetric limits for Landau MVP:

$$x_{\text{RMS}} - 3 \times \sigma < x_{\text{RMS}} < x_{\text{RMS}} + 3 \times \sigma$$

42 total iterations

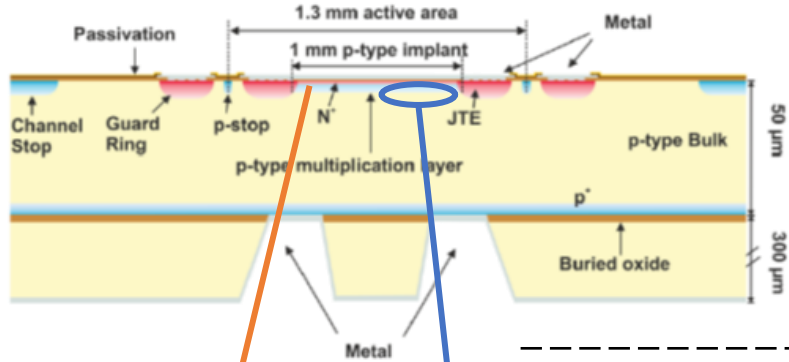
- ✓ Function integral limits set to:

$$0.1 \times \text{Int.} < X < 10 \times \text{Int.}$$

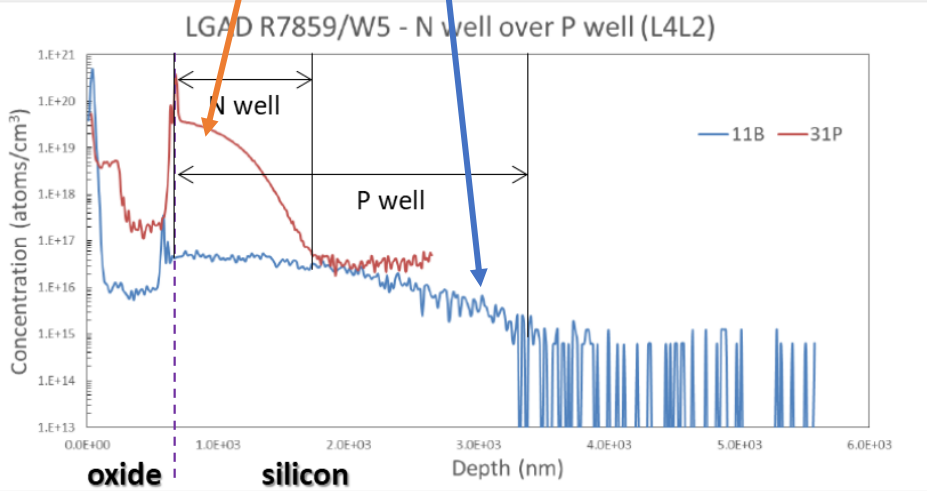
IV. Initial values:

- ✓ Landau MPV = x_{RMS}
- ✓ Convolution **Integral** = **distribution integral**
- ✓ Convolved sigma set to : $\sigma / 4$

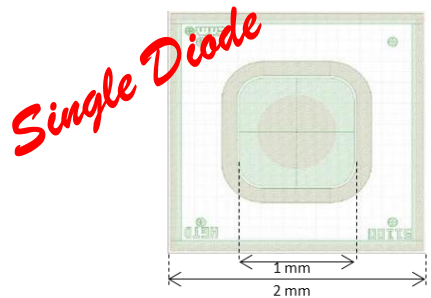
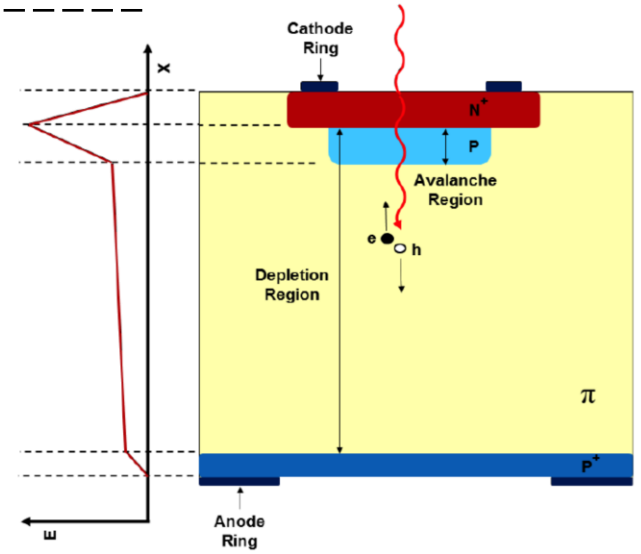
•LGAD Time Reference



- ✓ Invented at CNM, initially considered for tracking by IFAE, proposed for timing by UCSC
- ✓ Secondary p implant under collection electrode introducing moderate gain (10 -50)
- ✓ Up to 35 μm thickness on SoI or wafer to wafer bonding (typically 50 μm)
- ✓ HPK, CNM, FBK, MiCRON, BNL (USA), NDL (China)



- ✓ Requires precise diffusion control for layer thickness:
 - ✓ Thin highly doped n-well layer (~ 1 – 1.5 μm)
 - ✓ Gain layer ~ 2 μm
 - ✓ p-stop ~3 -3.5 μm
- ✓ Different gain layer species possible:
 - ✓ Boron (standard)
 - ✓ Gallium
 - ✓ Boron +Carbon



- 4" Si-on-Si wafers (High Resistivity ~2 kΩ•cm)
- 50 μm thickness on 250 μm support wafer
- Different implantation species
- Single diodes of active area 0.7 x 0.7 mm

Standard Boron
Boron + Carbon Spray (not confined)
Gallium