# Robotics at



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What the main projects are



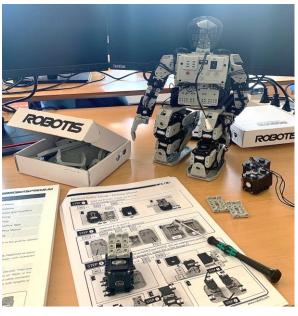


What the main projects are



- It's the synergy between science, engineering and technology.
- Robots <u>undertake complex tasks</u> in harsh and radioactive environments, replacing human involvement.
- Mainly, they carry out <u>maintenance</u> and safe handling of materials.









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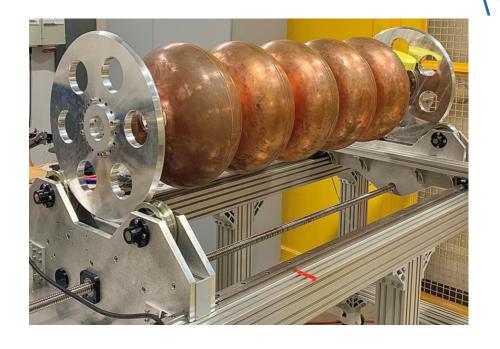


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 KUKA milling robot, which shapes the workpiece as desired.



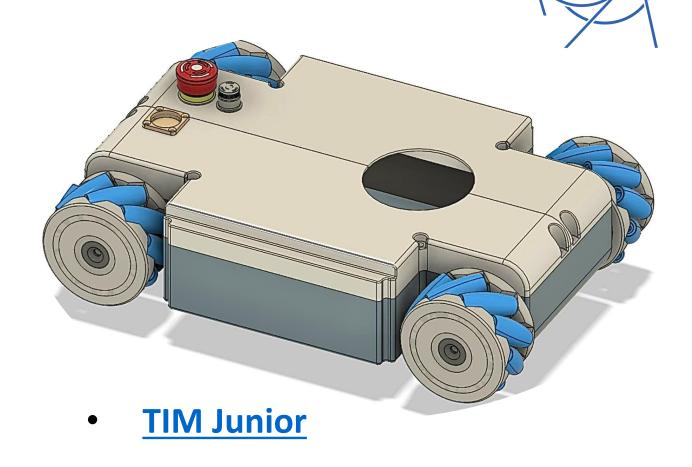


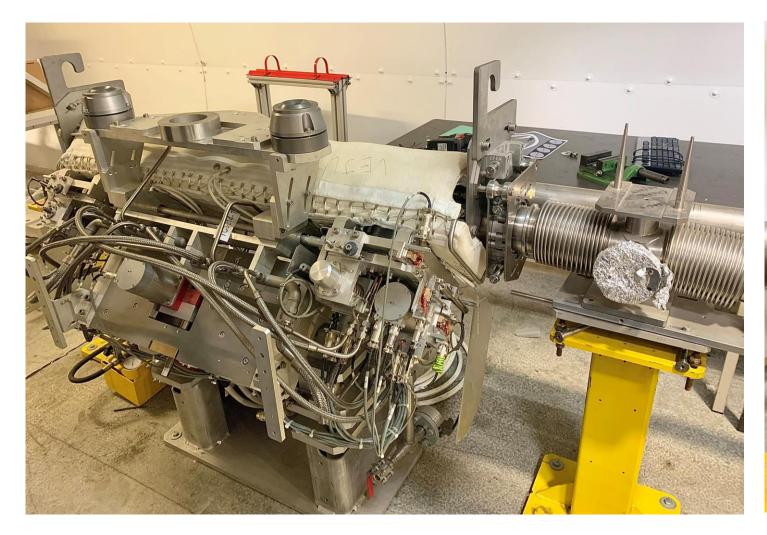
 Radio Frequency (RF) Cavity, which accelerates the beams that pass through it.

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• <u>The Train Inspection Monorail (TIM</u>), used for real-time monitoring of the LHC tunnel.











The <u>Collimator</u>, which cleans the particles dispersed around the beam.

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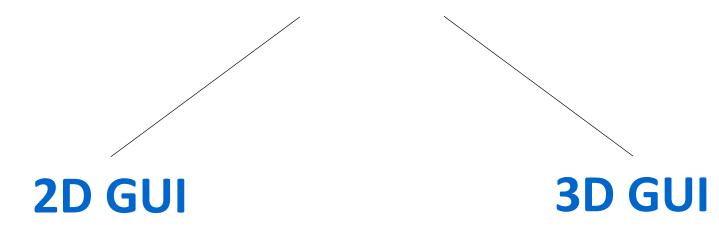


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#### How the robots are controlled



- A GUI (Graphical User Interface) is a system of interactive visual components: it conveys information and represent actions that can be taken by the user.
- There are two leading methods of GUI:



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### 2D GUI



It displays the controls on a normal

computer screen and

the actions and movement can be controlled directly from the computer's keyboard.



## 3D GUI

It requires a pair of headsets for augmented reality, which allow the user to control the virtual and real robot with their own hands, eyes and voice.





It provides <u>more awareness</u>
of the environment than the
2D GUI.



• This touchless system is the <u>basis of</u> the MARCHESE Project: its goal is monitoring, in a contactless way, human parameters, such as the heart rate, breathing and the body temperature.