

FUTURE CIRCULAR COLLIDER



COORDINATE REFERENCE AND NETWORKS

FCC week 2022, June 1st, 2022, Paris, France

Dr. Matej Varga

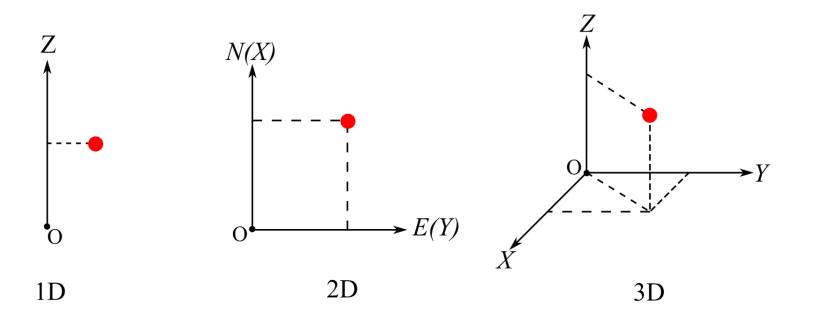
ETH Zürich Institute of Geodesy and Photogrammetry Geosensors and Engineering Geodesy





Outline

- Why coordinate reference systems and geodetic networks are needed for FCC 1.
- 2. Summary of CERN's existing solutions
- 3.



Cartesian coordinate systems

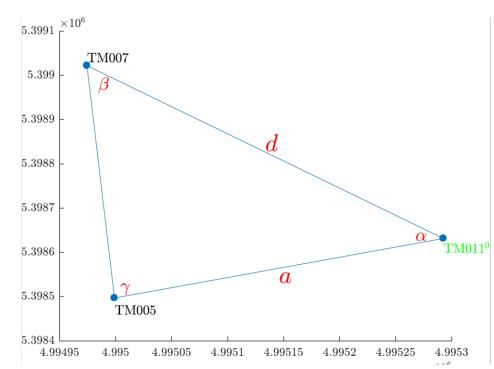
An ellipsoid: the fundamental geodetic surface



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How coordinate reference systems and geodetic networks should be designed and implemented



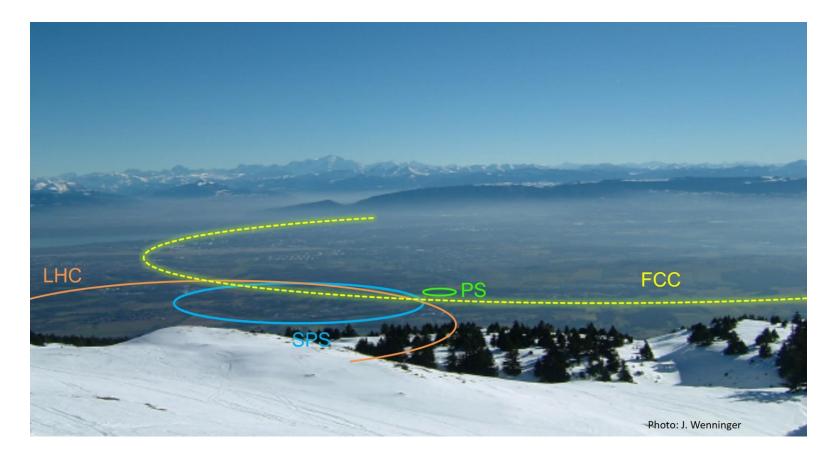


The example of simple geodetic network consisting from 3 points



Background: FCC-Geodesy project

- Project of CERN, ETHZ, HEIG-VD and swisstopo (2021-2024)
- French and Swiss national mapping agencies in Advisory Board
- Main objective: propose solutions and conceptually develop geodetic infrastructure for the construction, operation and maintainance of the FCC
- Geodetic infrastructure includes:
 - 1. Coordinate reference system (CRS)
 - 2. Geodetic networks (GN)
 - 3. Documentation
 - 4. Tools



The illustration of the FCC tunnel over the wider Geneva area



Geodetic equipment, @GSEG, ETHZ



Use of CRS at CERN

Purposes

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- 1. Civil engineering including tunnelling
- 2. Installation and maintenance of infrastructure above/below ground
- 3. Monitoring crustal deformations
- 4. Connecting facilities to others (locally, nationally, internationally)
- 5. Accelerator alignment

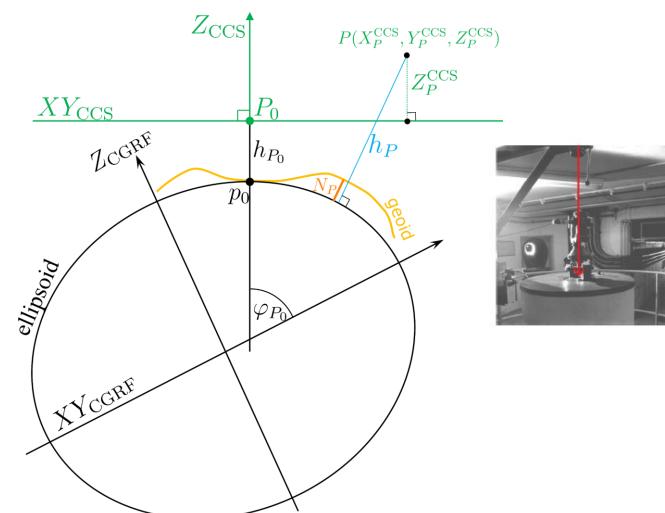
Practical requirements

- 1. Reusability of existing infrastructure and solutions
- 2. Unambiguous conversions and transformations between all systems
- 3. Update possible if needed
- 4. Complete and clear definition according to international standards

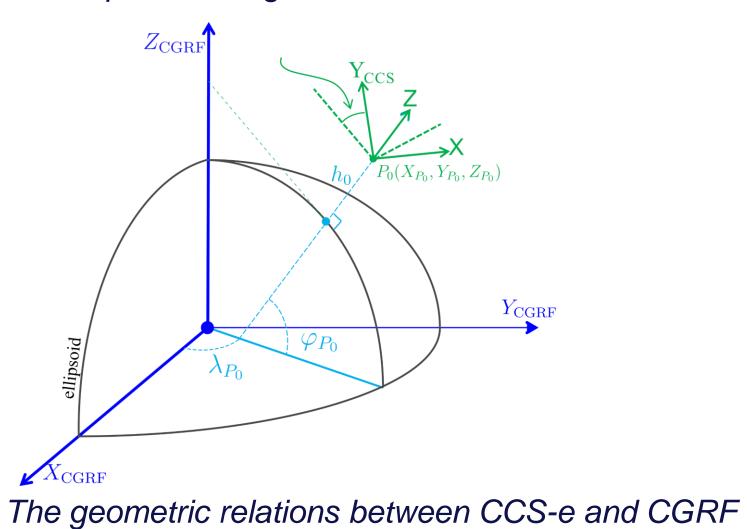




CRS at CERN: current situation



The geometric relations between plane, ellipsoid, and geoid in CCS-e.



Param

Datum for horizo Datum for verti Datum for verti Datum for vertic

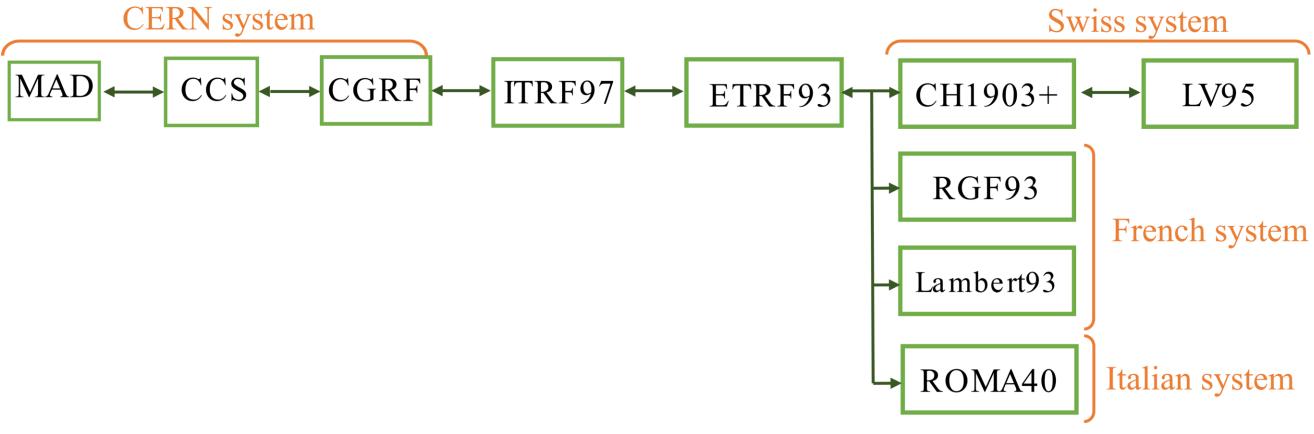
Local topocentric (

Global geodetic Co

Dati Geodetic lat Geodetic lon Geodetic he Geoid undul

Orientation of refe

Azimuth of the N-S component W-E component



ameter	Symbol	CERN coordinate system					
		CCS-plane (CCS-p)	CCS-sphere (CCS-s)	CCS-ellipsoid (CCS-e) [est. in 2001]	CCS-e [est. in 2016]		
zontal coordinates	X, Y	plane	plane	plane	plane		
tical coordinates	Z	plane	plane	plane	plane		
tical coordinates	h	plane	sphere ellipsoid		ellipsoid		
tical coordinates	H	plane	geoid/pseudo-geoid	geoid/pseudo-geoid	geoid/pseudo-geoid		
c Cartesian coordinat	tes of P_0	in CCS					
	X_{P_0} [m]	2000.00000	2000.00000	2000.00000	2000.00000		
	Y_{P_0} [m]	2097.79265	2097.79265	2097.79265	2097.79265		
	Z_{P_0} [m]	2433.66000	2433.66000	2000.00079	2000.00079		
Coordinates of P_0 in	CGRF						
atum		_	sphere	ellipsoid	ellipsoid		
atitude of P_0	$\varphi_{P_0}\left[^g\right]$	_	_	51.36920	51.36734		
ngitude of P_0	λ_{P_0} [^g]	_	_	6.72124	6.722515		
height of P_0	h_{P_0} [m]	433.65921	433.65921	433.65921	433.65921		
ulation of P_0	N_{P_0} [m]	—	—	0.00000	0.00000		
ference surface (sphe	re, ellipsoid	l)					
e Y-axis CERN :	$\alpha_{P_0} \left[\begin{array}{c} g \end{array} \right]$	_	_	37.77864	37.779033		
nt of DOV in P_0	ξ_{P_0} [cc]	_	0.00000	0.00000	0.00000		
nt of DOV in P_0	η_{P_0} [^{cc}]	—	0.00000	0.00000	0.00000		

Numerical definition of CERN coordinate system (CCS) and CERN Geodetic Reference Frame (CGRF)

Different coordinate reference systems (CRS) in use by CERN





CRS for FCC: proposed conceptual solution



terrestrial reference system

CKM kinematic model

CPS

projected reference system

connection to CERN, national,
and international reference frames
monitoring crustal deformations

- civil engineering

- alignment

CVS

vertical reference system

CLS/MAD

local reference system

- machine design
- physics

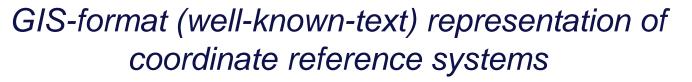
Proposed coordinate reference systems

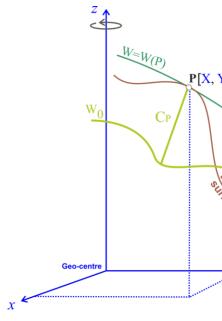
Acronyms: CTRS: CERN terrestrial reference system, CKM: CERN kinematic model, CPS: CERN projection system, CVS: CERN vertical system, CLS: CERN local system, MAD: Machine Aided Design

GEOGCS["CTRS21", DATUM["CERN_Terrestrial_Reference_System_2021", SPHEROID["GRS 1980",6378137,298.257222101, AUTHORITY["EPSG","7019"]], PRIMEM["Greenwich",0, AUTHORITY["EPSG","8901"]], UNIT["degree",0.0174532925199433, AUTHORITY["EPSG","9122"]], AUTHORITY["EPSG","NNNNN"]]

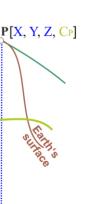
PROJCS["CPS21",

GEOGCS["CTRS21", **DATUM**["CERN_Terrestrial_Reference_System_2021" **SPHEROID**["GRS 1980",6378137,298.257222101, AUTHORITY["EPSG","7019"]], **PRIMEM**["Greenwich",0, AUTHORITY["EPSG","8901"]], **UNIT**["degree",0.0174532925199433, AUTHORITY["EPSG","9122"]], AUTHORITY["EPSG", "NNNNN"]], **PROJECTION**["Transverse_Mercator"], **PARAMETER**["latitude_of_origin",0.00], **PARAMETER**["central_meridian", 6.14], **PARAMETER**["scale_factor",1.00006], **PARAMETER**["false_easting",0.0], **PARAMETER**["false_northing", 0.0], **UNIT**["metre",1, AUTHORITY["EPSG","9001"]], **AXIS**["Easting", EAST], **AXIS**["Northing", NORTH], AUTHORITY["EPSG","NNNNN"]]





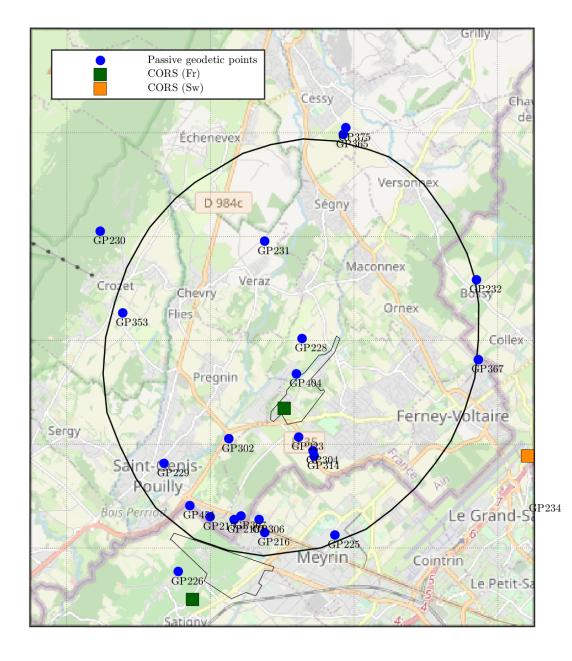
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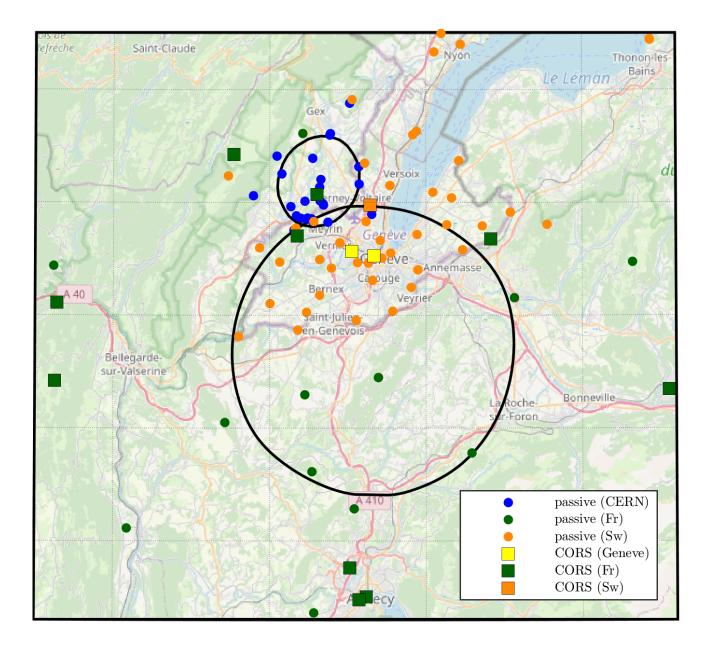
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Geodetic networks: introduction

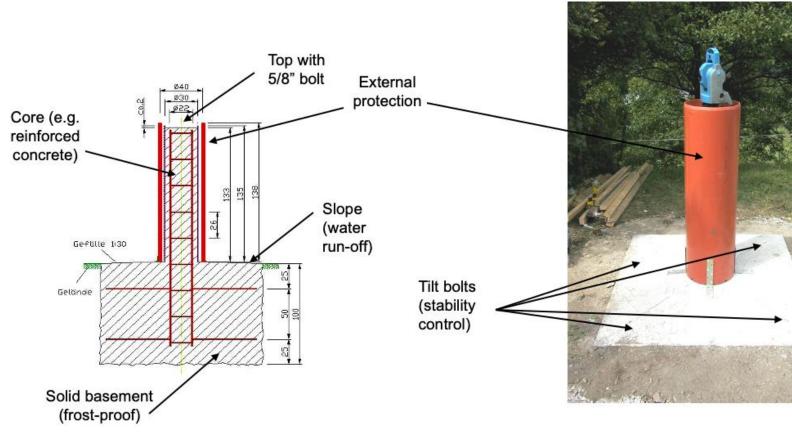
- Geodetic networks enable users an access to coordinates
- Consist from physically materialized points with precisely determined coordinates
- Basis: geodetic instruments and techniques
 - (total-stations, GNSS, levels, laser trackers, ...)



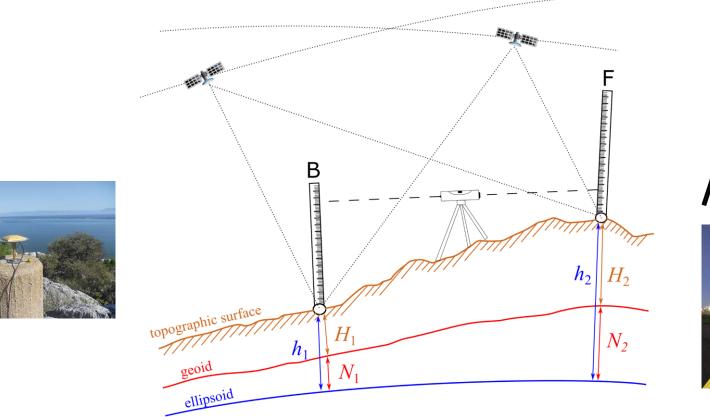
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Passive and active geodetic points over the CERN area



Example of geodetic pillars (source: TU Graz, Institute for Engineering Geodesy and Measurement Systems)



Tachymmetry, GNSS and levelling as precise geodetic measurement techniques







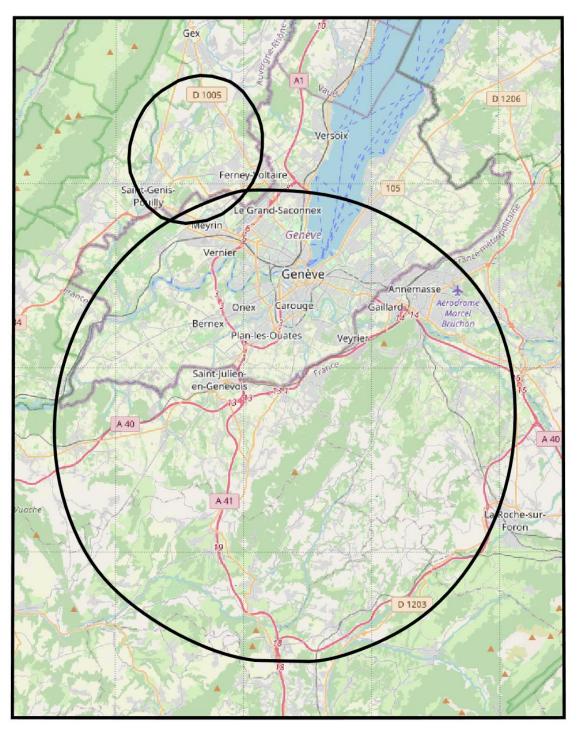




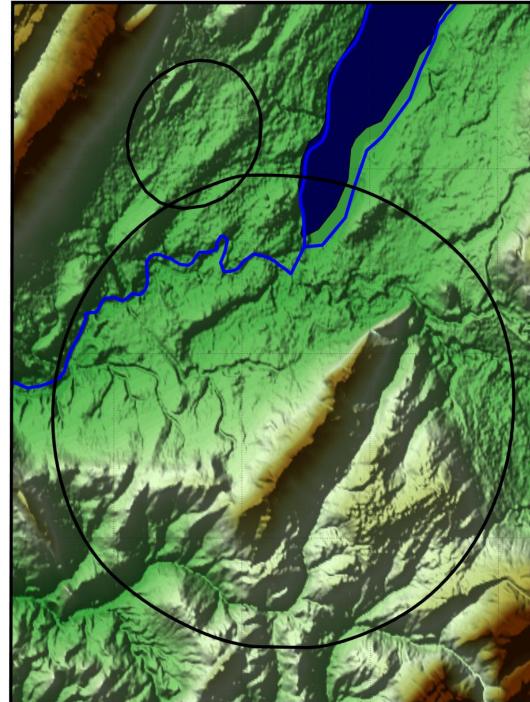


Geodetic networks: design constraints

- many constraints exist when choosing locations of geodetic points
- optimal configuration for geodetic network have to be found

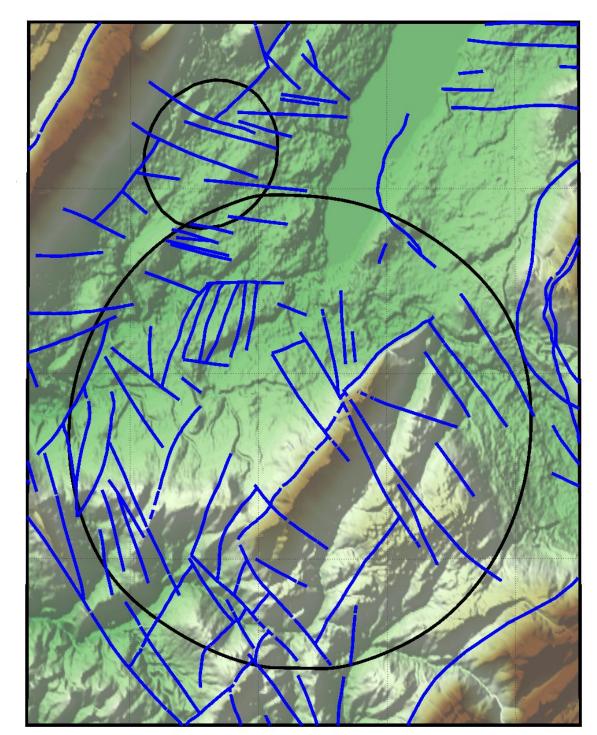


Geographic features (borders, municipalities, roads, ...)

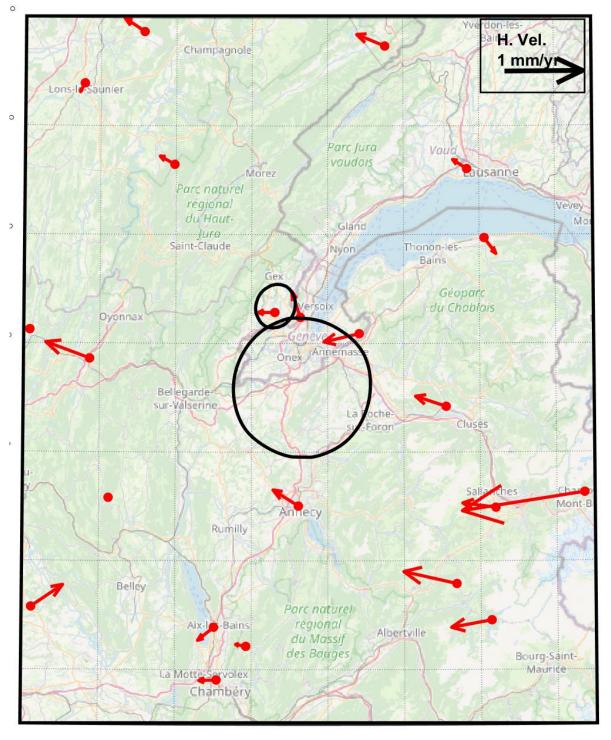


Topographic features (mountains, lakes, rivers, valleys, ...)





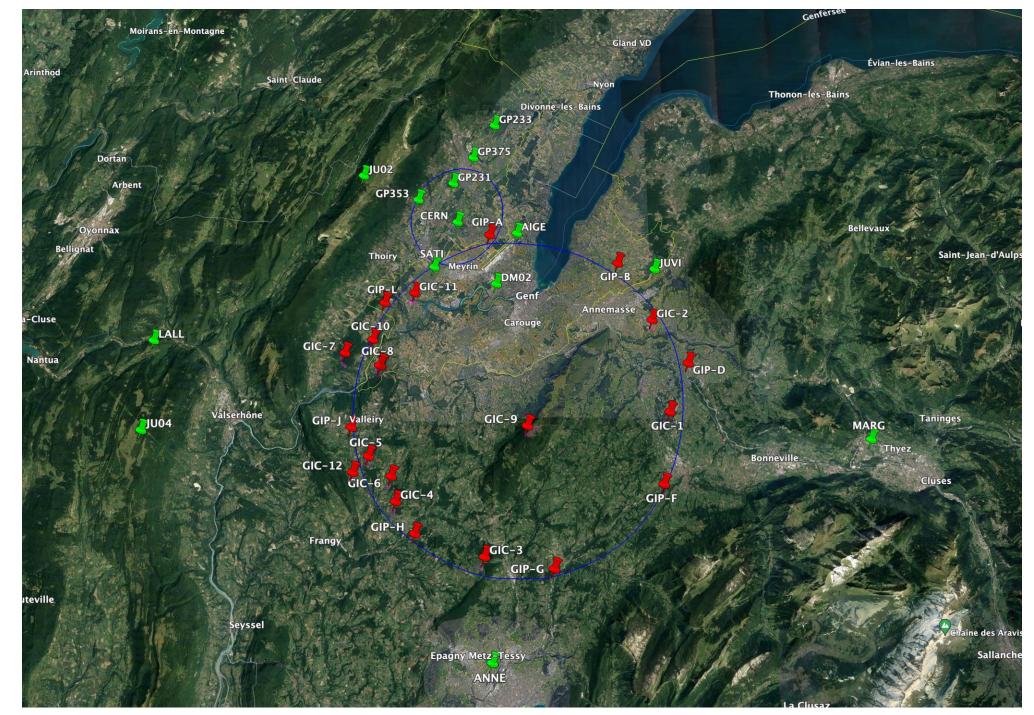
Geological faults



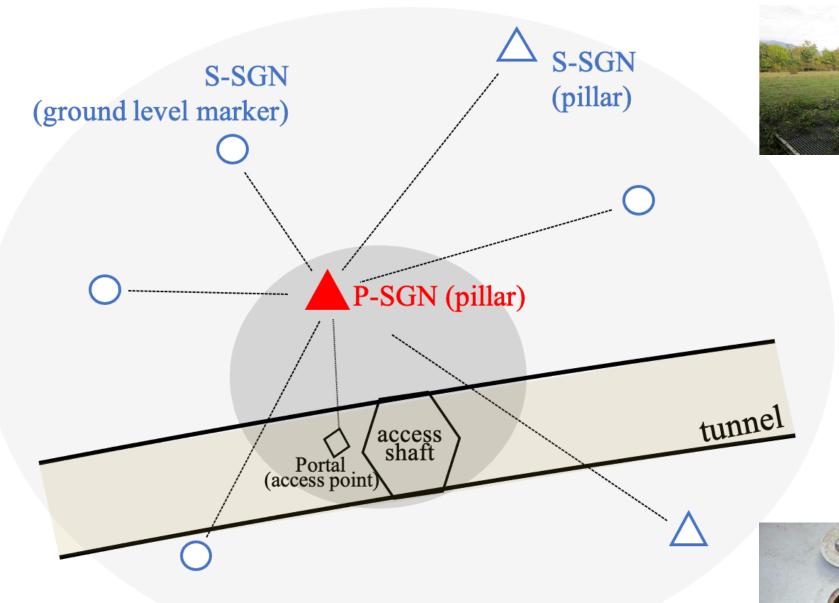
Surface kinematics

Geodetic network for FCC: conceptual solution (1)

- Active, semi-active (campaign) and passive geodetic points
- Strategically distributed in important locations (e.g. around tunnel access shafts) •
- Ensure ideal support during pre-construction and construction phases, as well as full life-time of the FCC



Proposal for newly established (red) and existing (green) surface geodetic points (note: locations are only approximate and may change).



Schematic layout of a portal surface geodetic network for one tunnel access shaft

Acronyms: P-SGN: primary surface geodetic network, S-SGN: secondary surface geodetic network







Geodetic network for FCC: conceptual solution (2)

	P-SGN	S-SGN	V-SGN
Purposes	Realize CTRF	Densification	Realize CVF
	Determine CKM	Geomonitoring	Geomonitoring
	Main tunnel network	Construction	Construction
		Portal networks	
Coordinates	3D in CTRF	3D in CTRF	1D in CVF
	2D in CPF	2D in CPF	
	option: 1D in CVF	option: 1D in CVF	
Materialization	Pillar, or ground level	Various, typically	Height bolt
	foundation with	ground level marker	
	precision marker		
Suitability	GNSS	various surveying	geometric levelling
	optionally also other	equipment	
	surveying equipment		
Precision	individually specified	individually specified	individually specified
	all: $\sigma_{N,E} \leq 3.5 \mathrm{mm}$	typ.: $\sigma_{N,E} \leq 3.5 \mathrm{mm}$	all: $\sigma_{\Delta H} \leq 0.5 \mathrm{mm/km^{\frac{1}{2}}}$
	$\sigma_U^{\prime} \leq 5.0 \mathrm{mm}$	$\sigma_U \leq 5.0 \mathrm{mm}$	w.r.t. V-SGN (up to 5 km)
	in CTRF	in CTRF	
Reliability	$AZ \le 3$	$AZ \le 3$	$AZ \leq 3$
	for $\alpha_0 = 1\%, \beta = 10\%$	for $\alpha_0 = 1\%, \beta = 10\%$	for $\alpha_0 = 1\%, \beta = 10\%$

Acronyms: P-SGN primary SGN, S-SGN secondargy SGN, V-SGN vertical surface geodetic network, GNSS: Global Navigation Satellite System

Key characteristics of the various types of surface geodetic network (SGN) points





Theoretically proposed timeline for implementation

- Relative time-periods between activities can be predicted more reliable than absolute time-periods. Possible delays in each activity can be expected due to many reasons.

	2022	2023	2024	2026	Year 2028	2030	2032	2034	2036
Establishment of CTRF, CPF and CVF									
Installing and adapting P-SGN									
Installing S-SGN									
Installing V-SGN									
Geomonitoring									



Conclusion

- 1. Conceptual solutions of CRS and geodetic networks have been proposed
- 2. The practical solutions planned to be implemented in the next few years
- 3. Two scientific reports summarize the proposed concept of CRS and surface network
 - Varga M., Wieser A. (2021): Proposition of Coordinate Reference Systems for FCC
 - Varga M., Wieser A. (2021): Conceptual design report for the establishment of a surface geodetic reference network including control baseline
- 4. Presented information have mainly scientific and consultative value
- 5. Decisions on adoption and details of practical (*real-world*) implementation are made by CERN
- 6. The results will have positive impact on everyday work of many other participants (physicists, metrologists, civil-engineers, etc.)

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Project	Project
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Tute	Tute
Proposition of Coordinate Reference Systems for FCC (Deliverable IGP-AA-2.1)	Conceptual design report for the establishment of a surface geodetic reference network including control baselines (Deliverable IGP-A.A-2.2)
Author: Dr. Malej Varga, Dr. Andreas Weiser Cortact: madij varga @goch barg.eftic.ch Report number: (Dr. An.A.2.1 Usensent: (C. GJR-AA.2.1 Document: (C. GJR-AA.2.1 File: (FCC-GRP-AA.2.1) File: (FCC-GRP-AA.2.1) Status: Final (accepted by CDRN)	Authors Dr. Manj Varga (MV), Porf. Dr. Andreas Weiser (AW) Contact maij varga of good baug edu. ch Report number: IGPAA-22 Version: 0.4 Document: FCC.0FQAA-2.2 Date: 5.03.202 File: FCC.0FQAA-2.2.pdf Stame: Draft
Abstrart The FCC will extend the geographic area of the CERN facilities by about 30 km to the South. The civil engineering works, the alignment, maintenance and operation of the FCC will require clearly defined Coordinate Reference Systems (CRS) implemented with high quality and connected mathematically to existing international, national and local CRSs. In this property assummarize the CRS were dep CRS to far, and address the questions whether the existing CRSs can be used also for FCC or need to be adapted/opticed. We recommend the latter, Concrucitly the spot contains the recommendation to use (1) as address the question of the farther for establishment of the goodetic surface networks across the FCC area, for long-term monitoring and for connection in domestical matching the concrustion via a GRSBM elipsical as horizontial during works, and (via well-facilitated transmission) with a GRSBM elipsical as horizontial during works, and (via well-facilitated transmission) with a GRSBM elipsical as horizontial during works, and (via well-facilitated transmission). Also the 3D Cartesian coordinate systems (MAD) used by CERN for the planning and simulation of the accelerator physicol/optics can be connected to the new systems by transformations.	Abstract This report discribes the conceptual design of the proposed surface geodetic networks (SGN) includ- ing control baselines needed for the constraints of the contraints of the so-that ference system and the second second second second second second second second second second tunnel. (J) providing the long-wavelength basis for the later alignment works, and (4) providing the reference of gookinemic incomising of the PGC second





Thank you for your attention.