



FUTURE  
CIRCULAR  
COLLIDER

# COORDINATE REFERENCE AND NETWORKS

FCC week 2022, June 1st, 2022, Paris, France

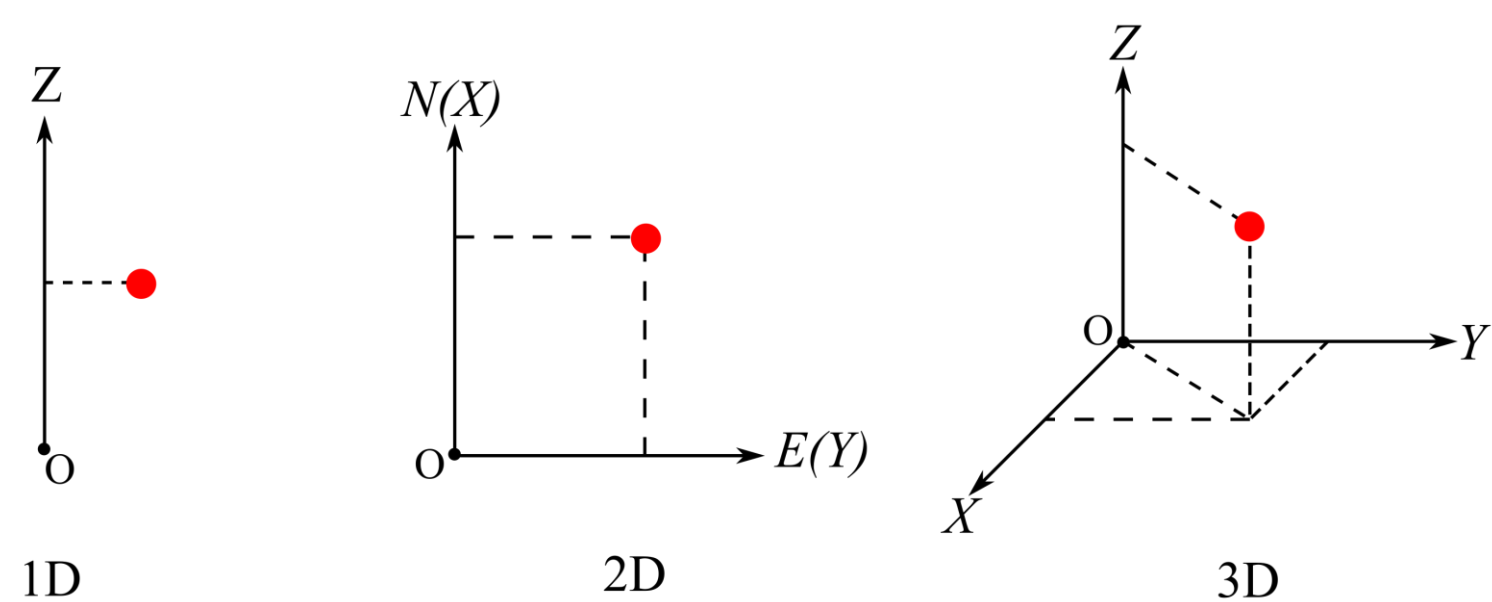
**Dr. Matej Varga**

ETH Zürich

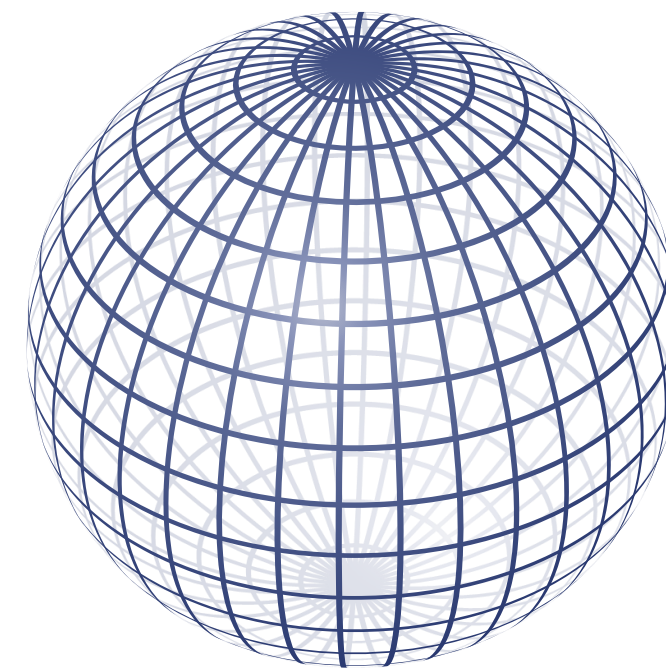
Institute of Geodesy and Photogrammetry  
Geosensors and Engineering Geodesy

# Outline

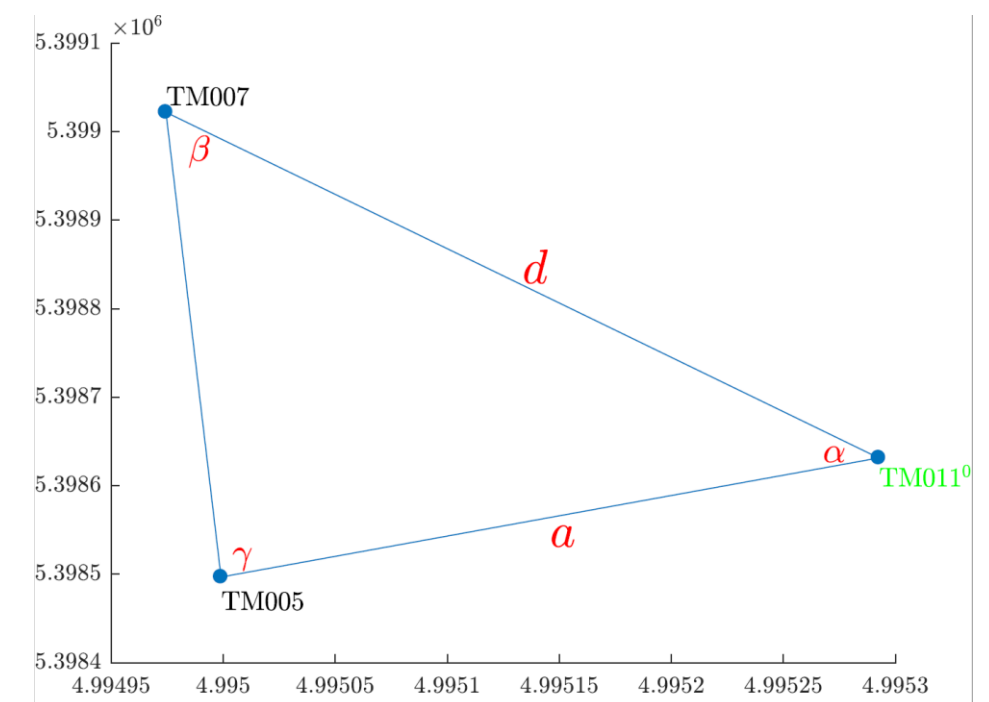
1. Why coordinate reference systems and geodetic networks are needed for FCC
2. Summary of CERN's existing solutions
3. How coordinate reference systems and geodetic networks should be designed and implemented



*Cartesian coordinate systems*



*An ellipsoid: the fundamental geodetic surface*



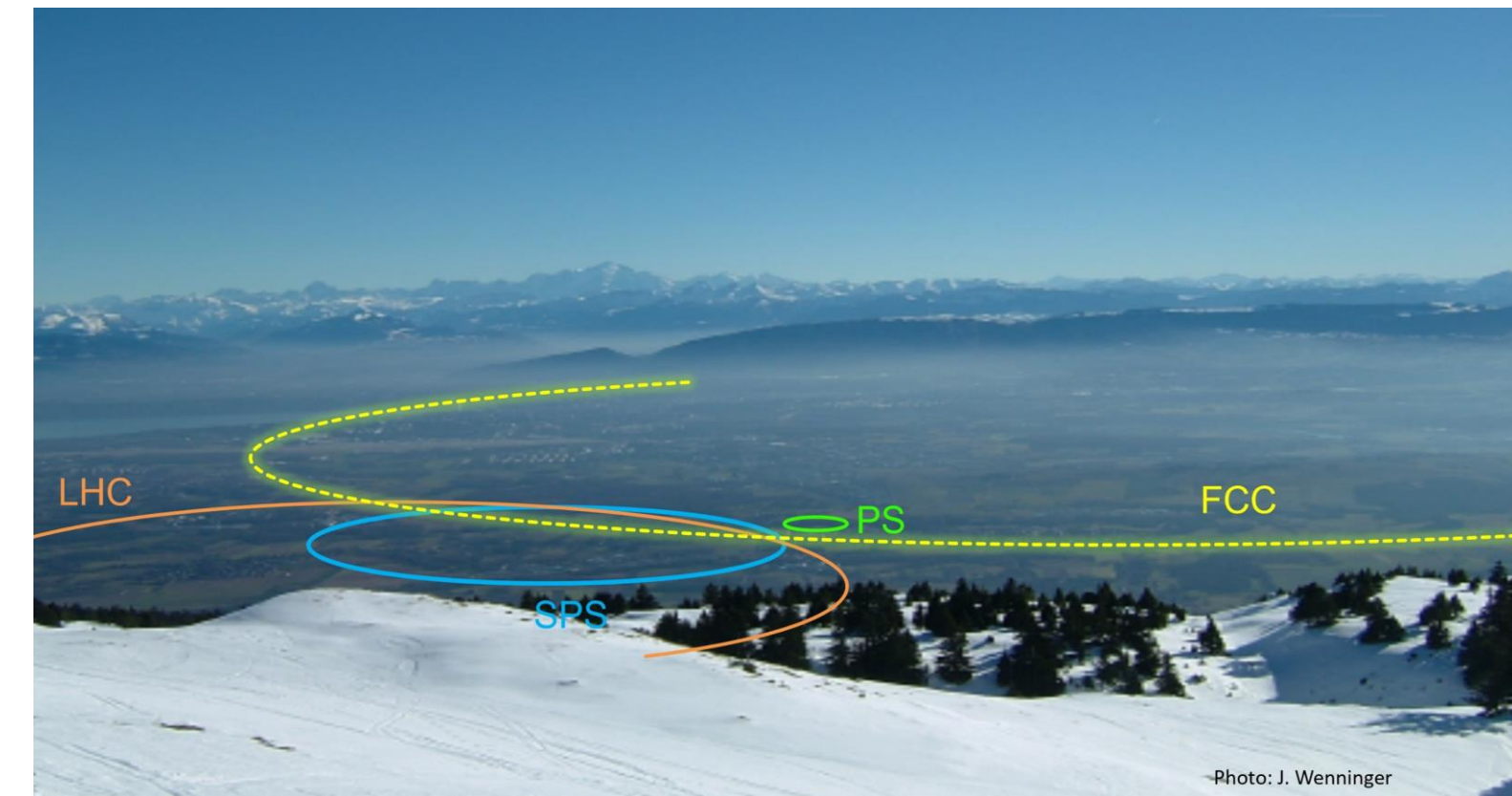
*The example of simple geodetic network consisting from 3 points*



The Future Circular Collider Innovation Study (FCCIS) project has received funding from the European Union's Horizon 2020 research and innovation programme under grant No 951754. The information herein only reflects the views of its authors and the European Commission is not responsible for any use that may be made of the information.

# Background: FCC-Geodesy project

- Project of CERN, ETHZ, HEIG-VD and swisstopo (2021-2024)
- French and Swiss national mapping agencies in Advisory Board
- Main objective: **propose solutions and conceptually develop geodetic infrastructure for the construction, operation and maintainance of the FCC**
- **Geodetic infrastructure includes:**
  1. Coordinate reference system (CRS)
  2. Geodetic networks (GN)
  3. Documentation
  4. Tools



*The illustration of the FCC tunnel over the wider Geneva area*



*Geodetic equipment, @GSEG, ETHZ*

# Use of CRS at CERN

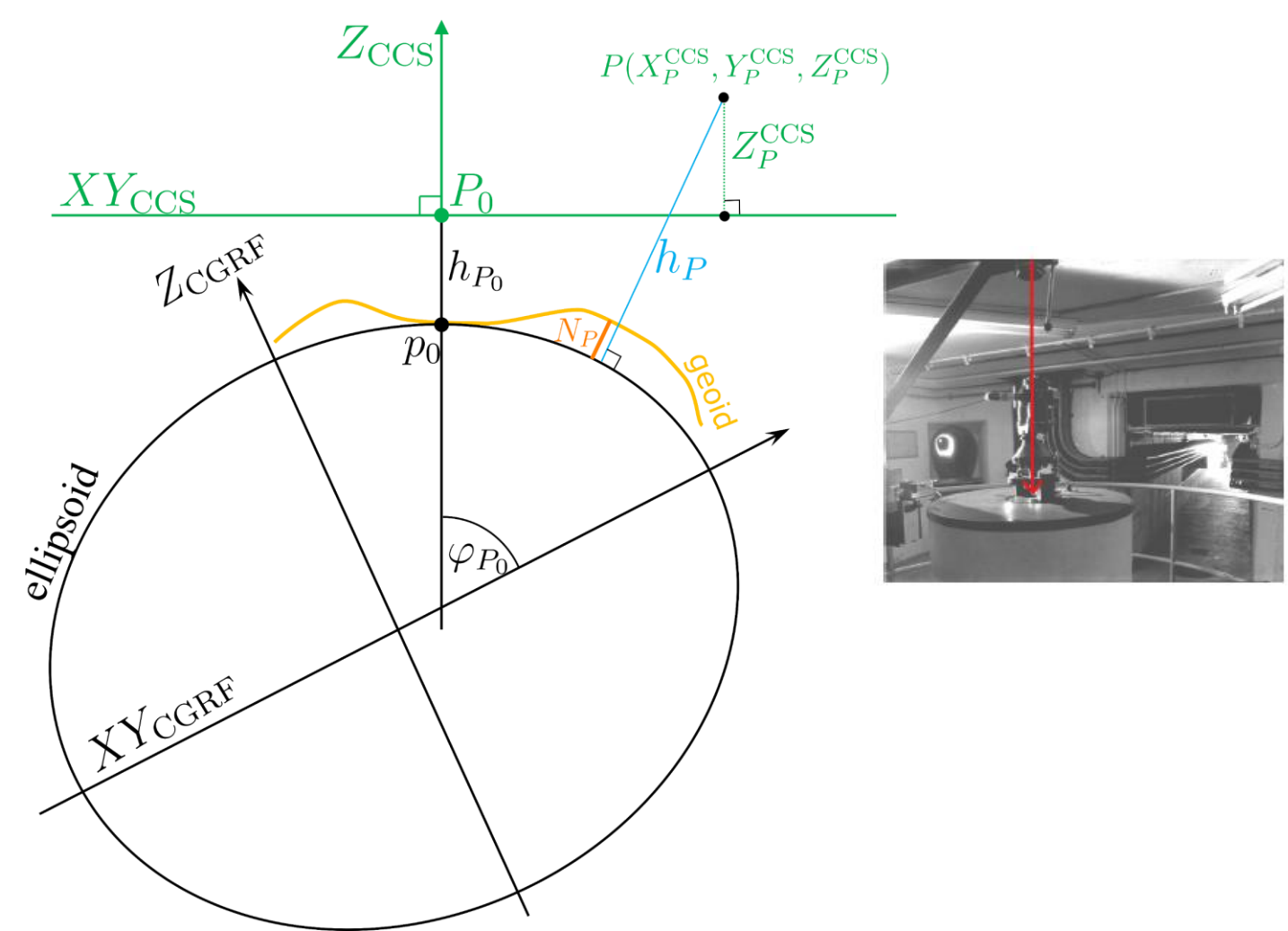
## Purposes

1. Civil engineering including tunnelling
2. Installation and maintenance of infrastructure above/below ground
3. Monitoring crustal deformations
4. Connecting facilities to others (locally, nationally, internationally)
5. Accelerator alignment

## Practical requirements

1. Reusability of existing infrastructure and solutions
2. Unambiguous conversions and transformations between all systems
3. Update possible if needed
4. Complete and clear definition according to international standards

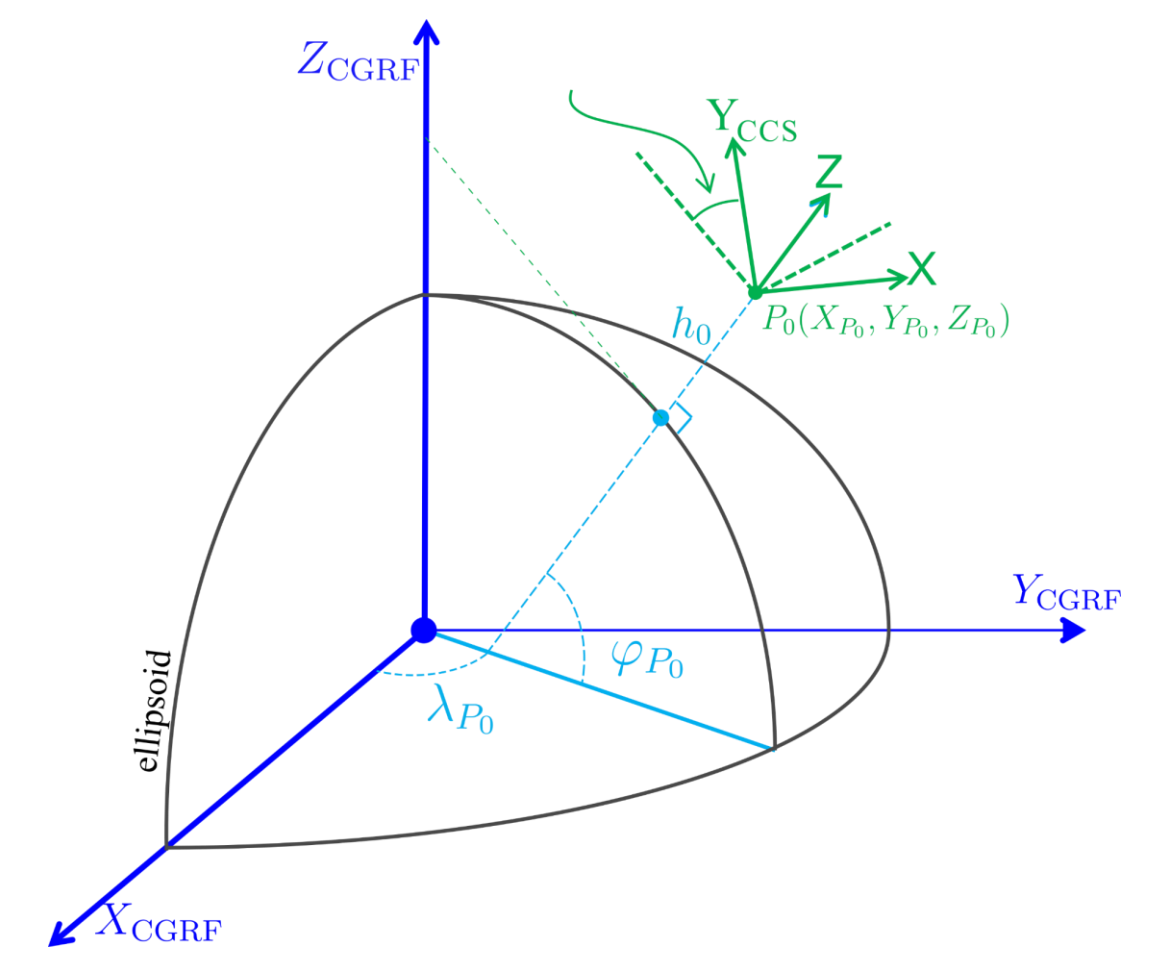
# CRS at CERN: current situation



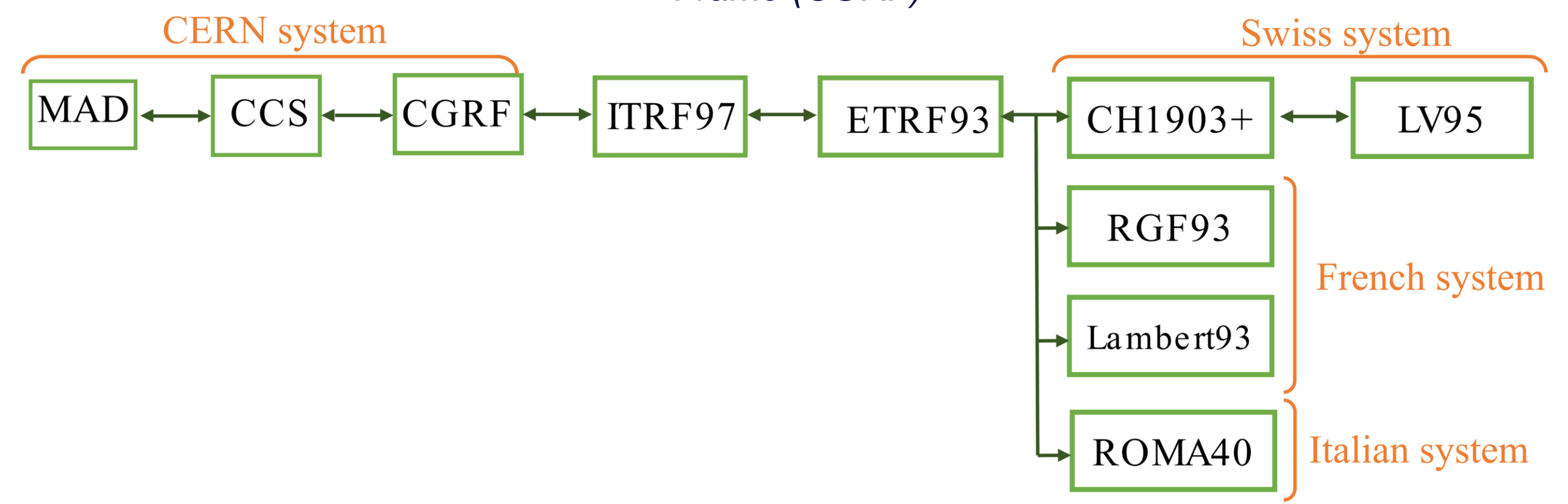
The geometric relations between plane, ellipsoid, and geoid in CCS-e.

Parameter	Symbol	CERN coordinate system			
		CCS-plane (CCS-p)	CCS-sphere (CCS-s)	CCS-ellipsoid (CCS-e) [est. in 2001]	CCS-e [est. in 2016]
Datum for horizontal coordinates	$X, Y$	plane	plane	plane	plane
Datum for vertical coordinates	$Z$	plane	plane	plane	plane
Datum for vertical coordinates	$h$	plane	sphere	ellipsoid	ellipsoid
Datum for vertical coordinates	$H$	plane	geoid/pseudo-geoid	geoid/pseudo-geoid	geoid/pseudo-geoid
Local topocentric Cartesian coordinates of $P_0$		in CCS			
	$X_{P_0}$ [m]	2000.00000	2000.00000	2000.00000	2000.00000
	$Y_{P_0}$ [m]	2097.79265	2097.79265	2097.79265	2097.79265
	$Z_{P_0}$ [m]	2433.66000	2433.66000	2000.00079	2000.00079
Global geodetic Coordinates of $P_0$ in CGRF					
Datum	—	—	sphere	ellipsoid	ellipsoid
Geodetic latitude of $P_0$	$\varphi_{P_0}$ [°]	—	—	51.36920	51.36734
Geodetic longitude of $P_0$	$\lambda_{P_0}$ [°]	—	—	6.72124	6.722515
Geodetic height of $P_0$	$h_{P_0}$ [m]	433.65921	433.65921	433.65921	433.65921
Geoid undulation of $P_0$	$N_{P_0}$ [m]	—	—	0.00000	0.00000
Orientation of reference surface (sphere, ellipsoid)					
Azimuth of the Y-axis CERN :	$\alpha_{P_0}$ [°]	—	—	37.77864	37.779033
N-S component of DOV in $P_0$	$\xi_{P_0}$ [°]	—	0.00000	0.00000	0.00000
W-E component of DOV in $P_0$	$\eta_{P_0}$ [°]	—	0.00000	0.00000	0.00000

Numerical definition of CERN coordinate system (CCS) and CERN Geodetic Reference Frame (CGRF)

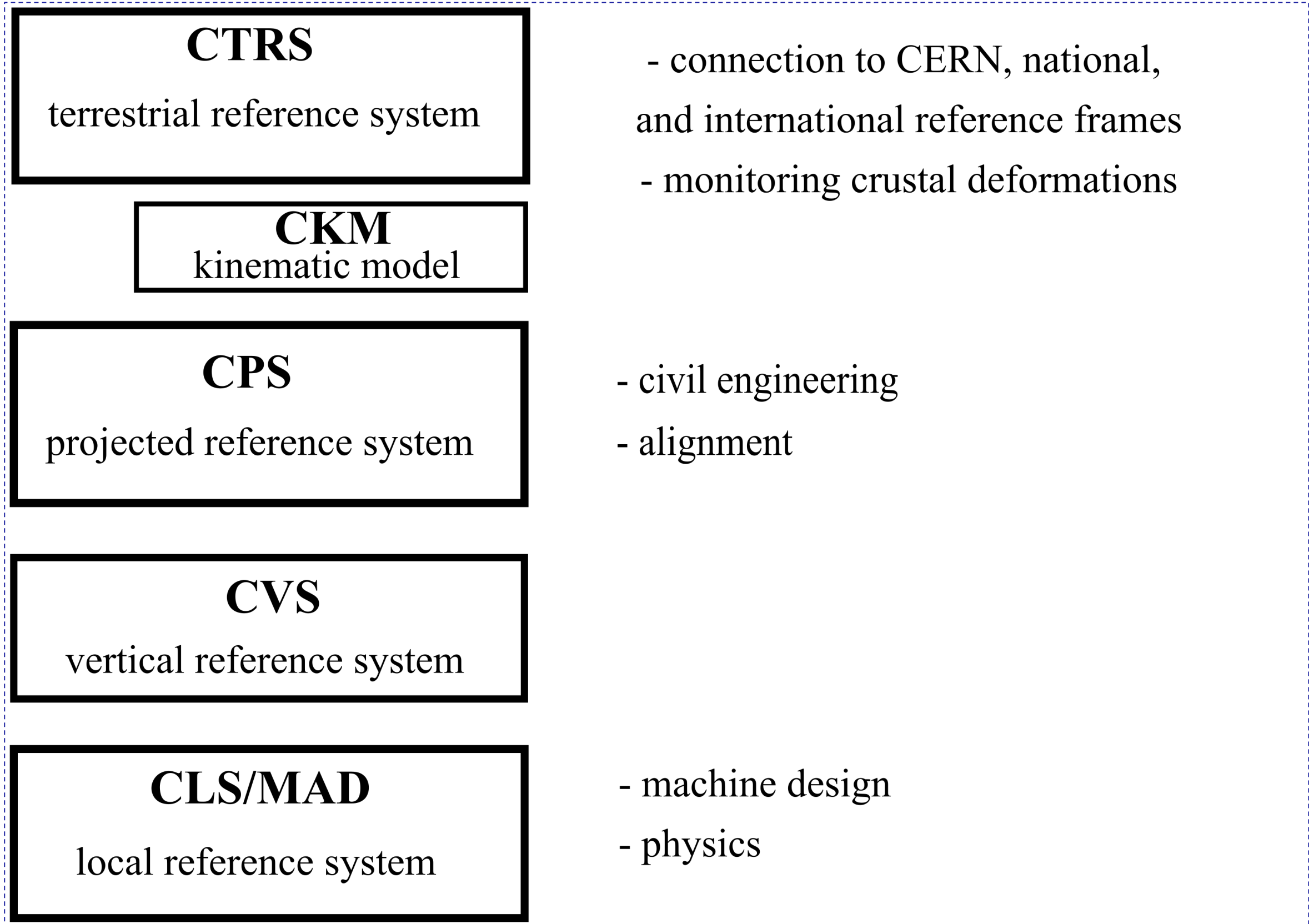


The geometric relations between CCS-e and CGRF



Different coordinate reference systems (CRS) in use by CERN

# CRS for FCC: proposed conceptual solution

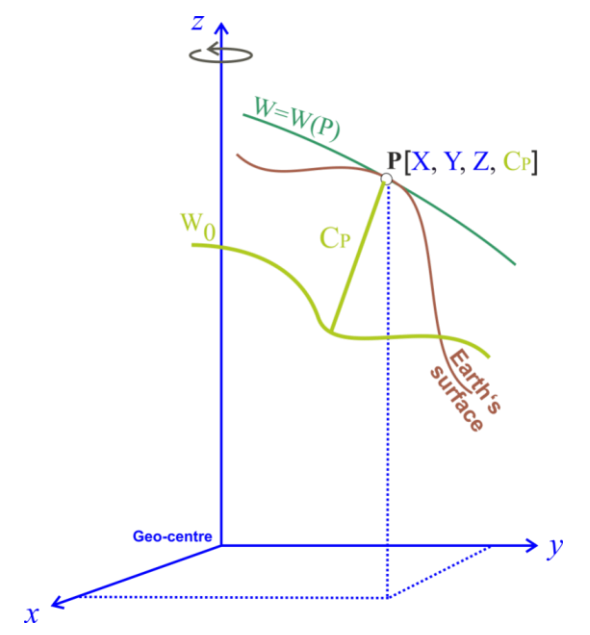


*Proposed coordinate reference systems*

```
GEOGCS["CTRS21",
  DATUM["CERN_Terrestrial_Reference_System_2021",
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      AUTHORITY["EPSG","7019"]],
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      AUTHORITY["EPSG","8901"]],
    UNIT["degree",0.0174532925199433,
      AUTHORITY["EPSG","9122"]],
    AUTHORITY["EPSG","NNNNN"]]
```

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PROJCS["CPS21",
  GEOGCS["CTRS21",
    DATUM["CERN_Terrestrial_Reference_System_2021",
      SPHEROID["GRS 1980",6378137,298.257222101,
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          AUTHORITY["EPSG","8901"]],
          UNIT["degree",0.0174532925199433,
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            AUTHORITY["EPSG","NNNNN"]],
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        UNIT["metre",1,
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        AXIS["Northing",NORTH],
        AUTHORITY["EPSG","NNNNN"]]
```

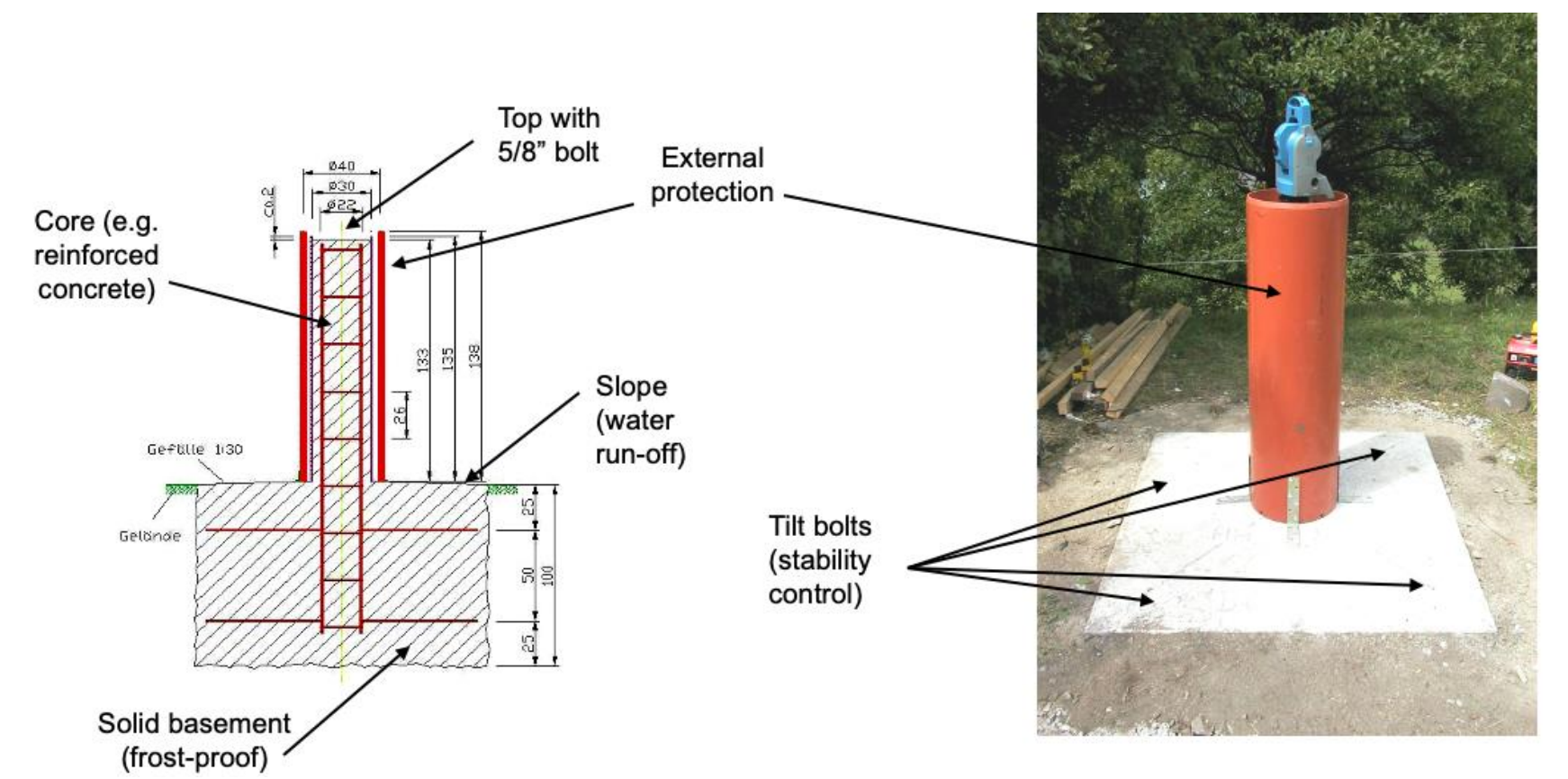
*GIS-format (well-known-text) representation of coordinate reference systems*



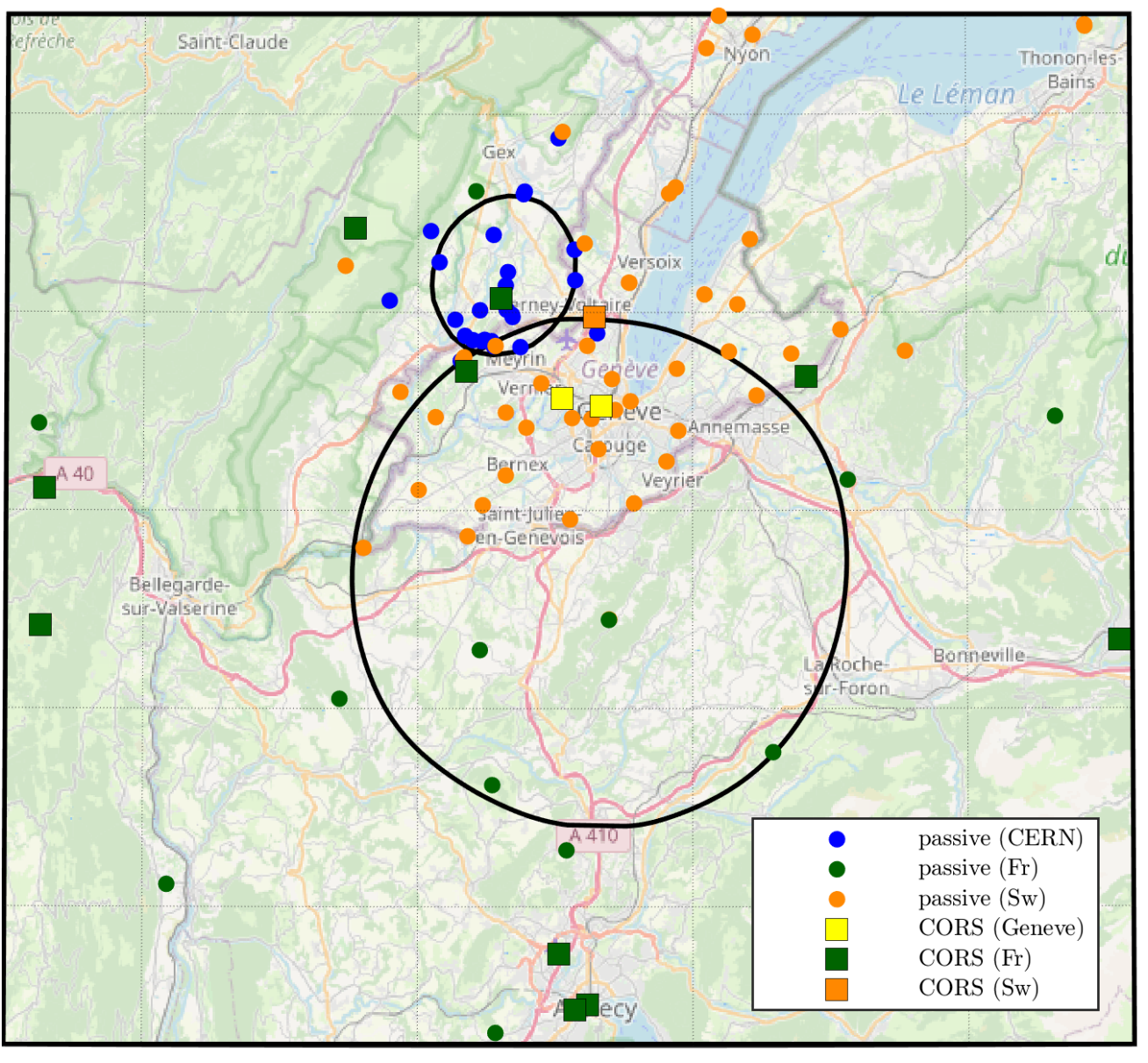
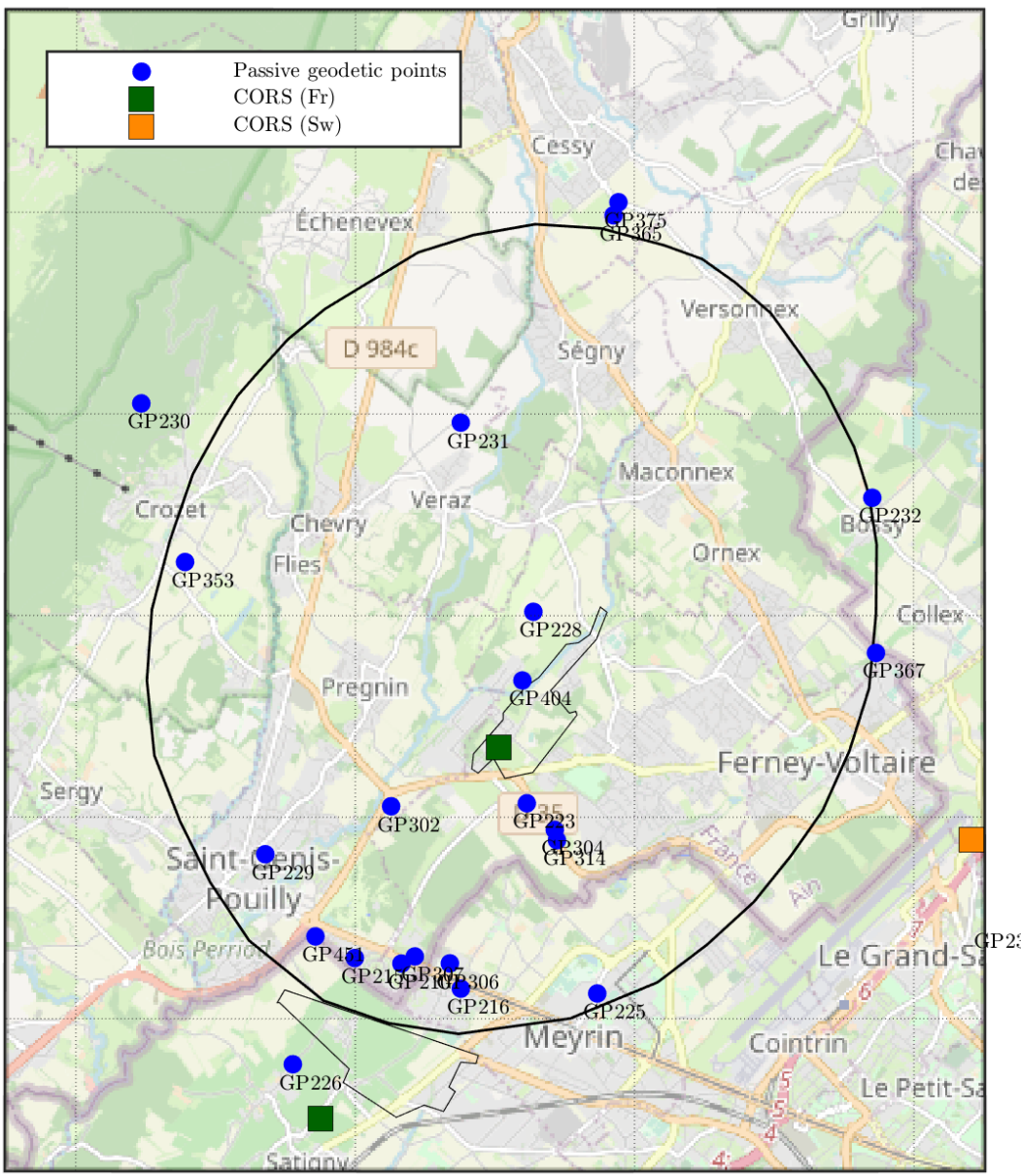
Acronyms: CTRS: CERN terrestrial reference system, CKM: CERN kinematic model, CPS: CERN projection system, CVS: CERN vertical system, CLS: CERN local system, MAD: Machine Aided Design

# Geodetic networks: introduction

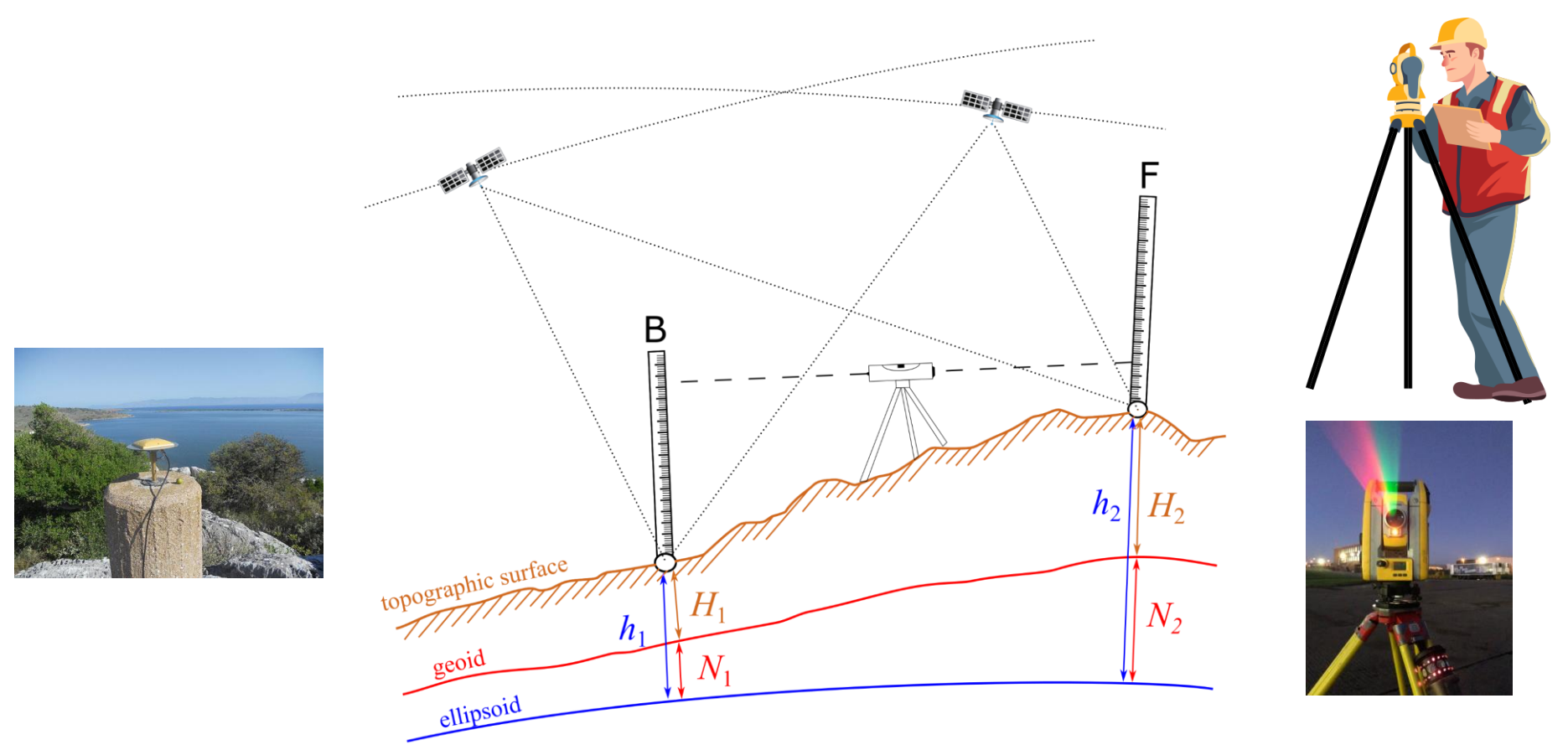
- Geodetic networks enable users an access to coordinates
- Consist from physically materialized points with precisely determined coordinates
- Basis: geodetic instruments and techniques (total-stations, GNSS, levels, laser trackers, ...)



Example of geodetic pillars (source: TU Graz, Institute for Engineering Geodesy and Measurement Systems)



Passive and active geodetic points over the CERN area

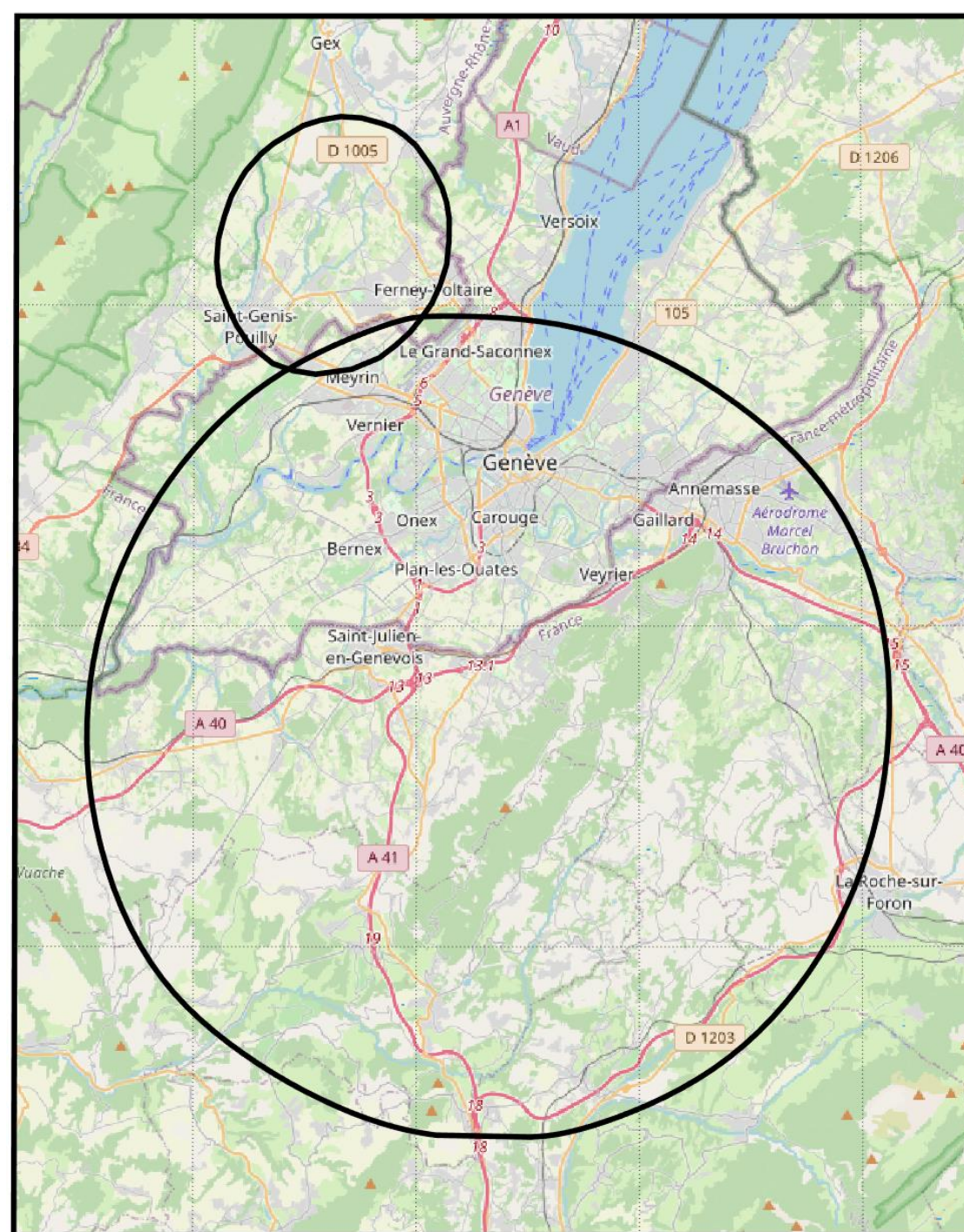


Tachymmetry, GNSS and levelling as precise geodetic measurement techniques

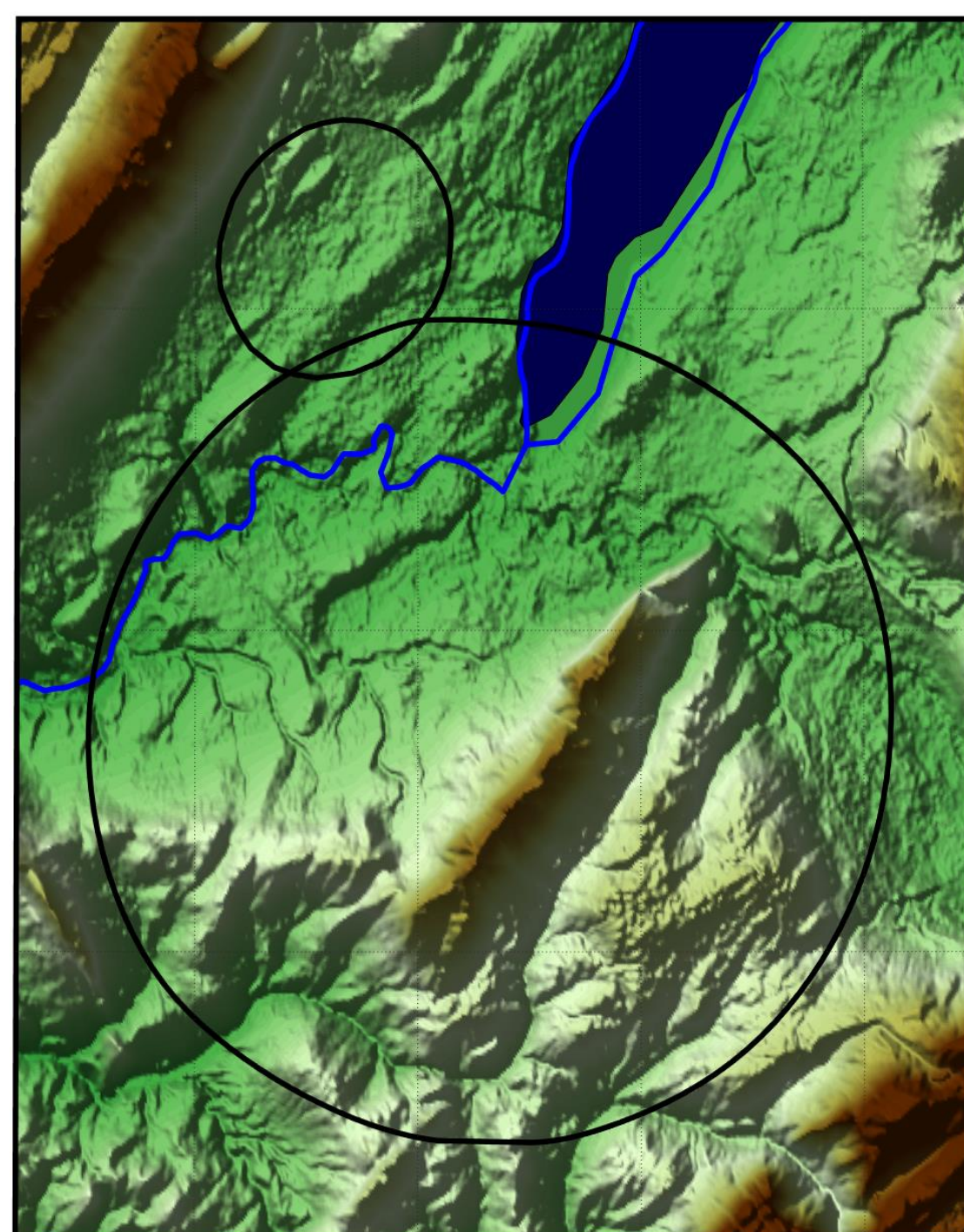


# Geodetic networks: design constraints

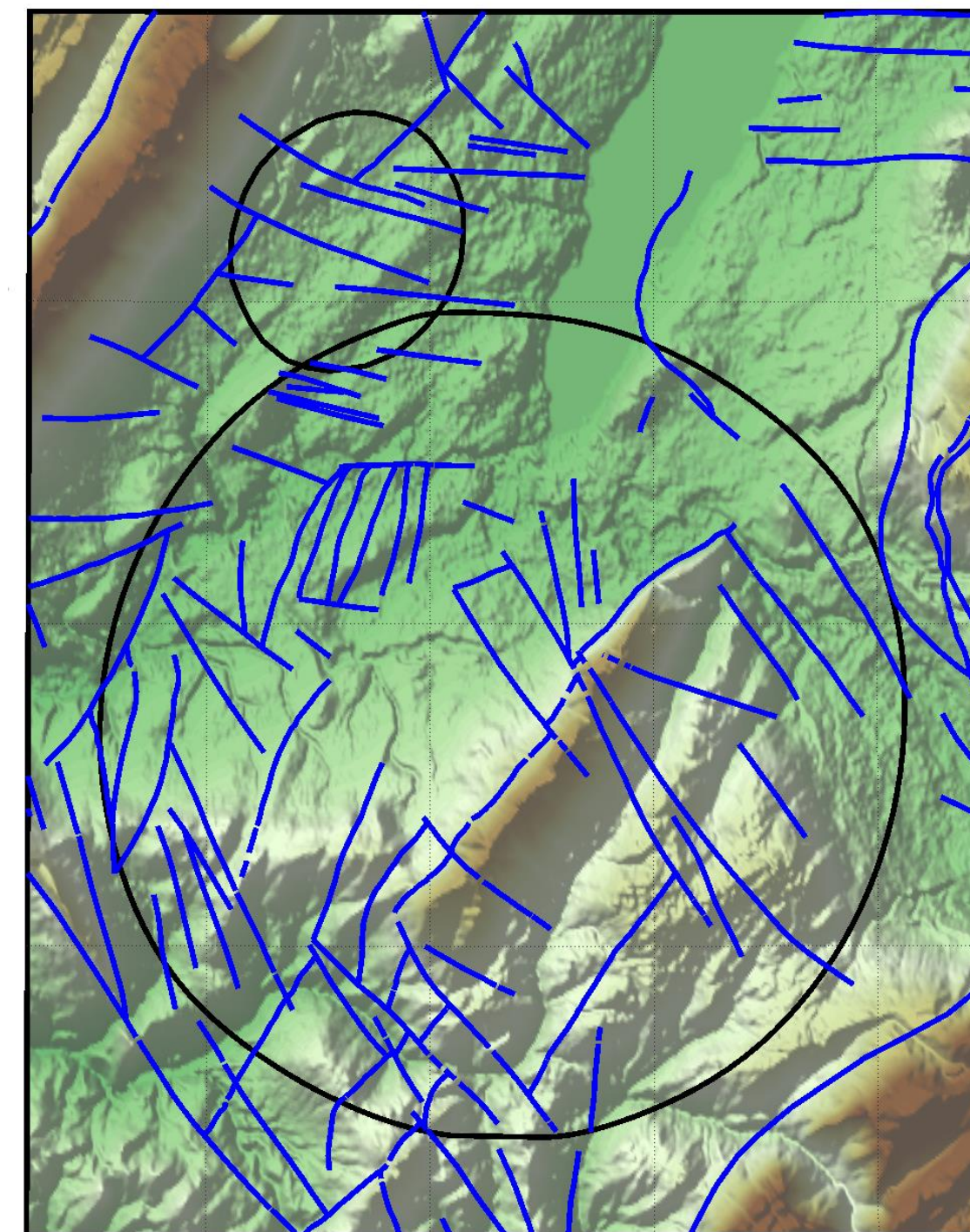
- many constraints exist when choosing locations of geodetic points
- optimal configuration for geodetic network have to be found



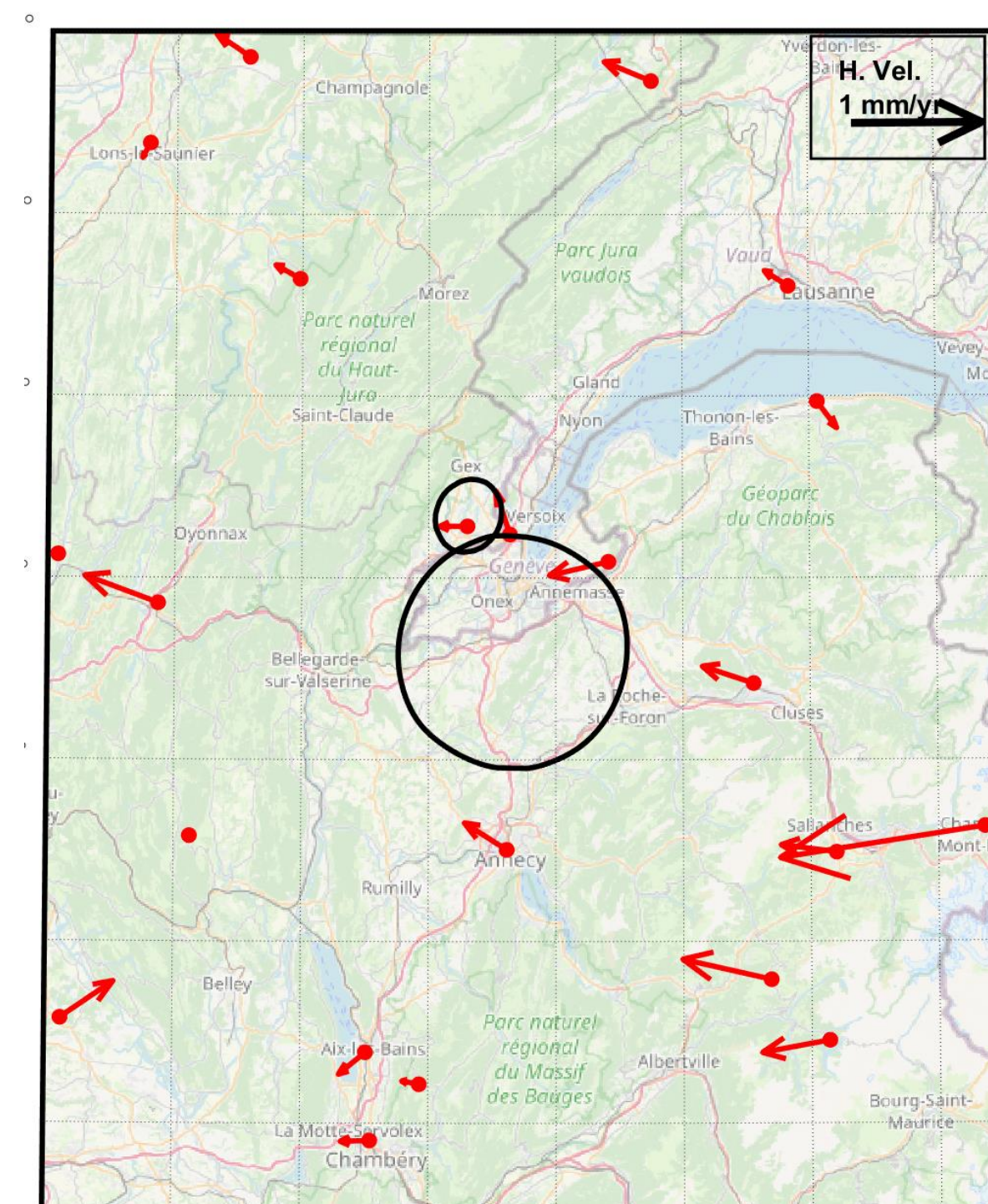
*Geographic features (borders, municipalities, roads, ...)*



*Topographic features (mountains, lakes, rivers, valleys, ...)*



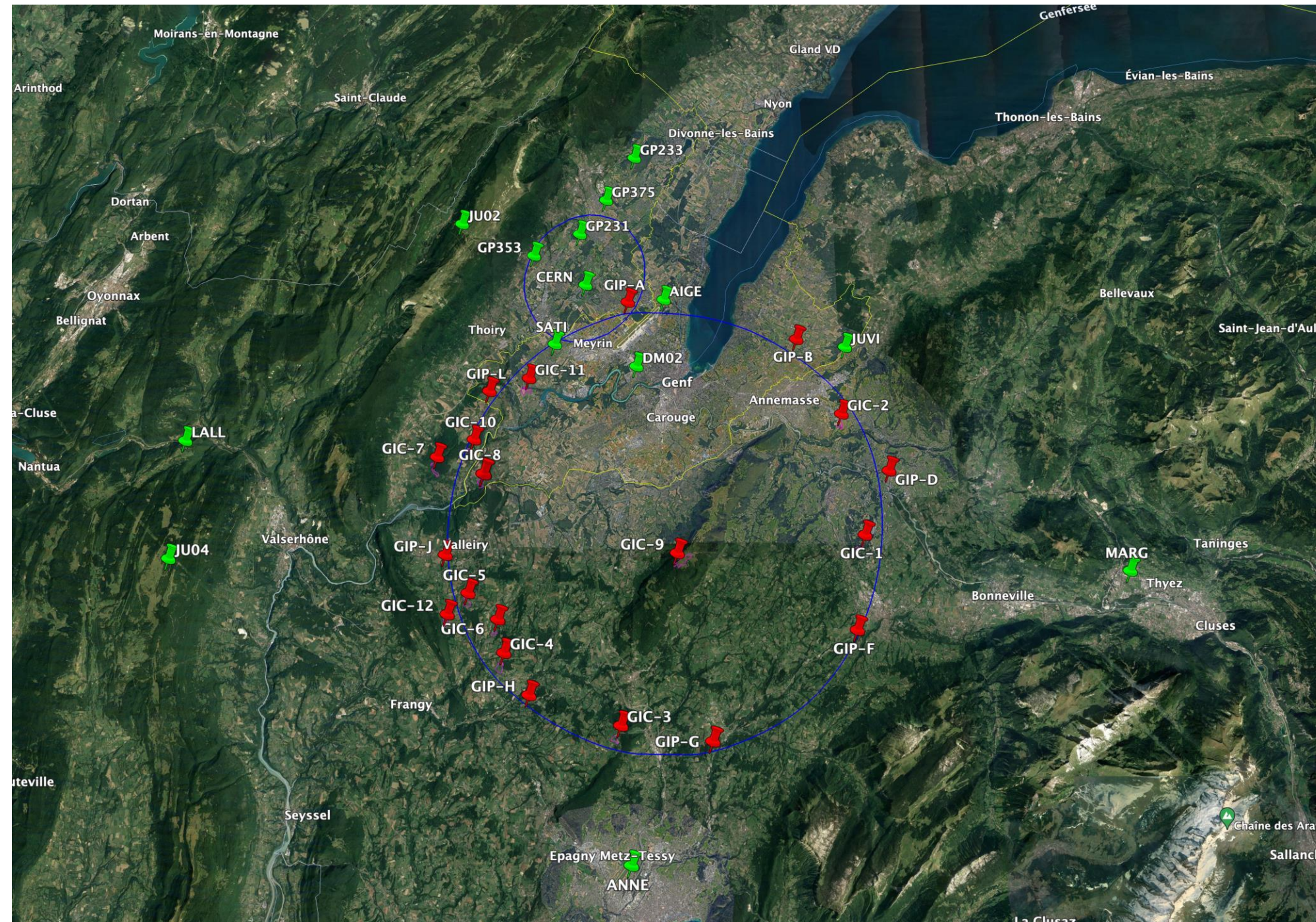
*Geological faults*



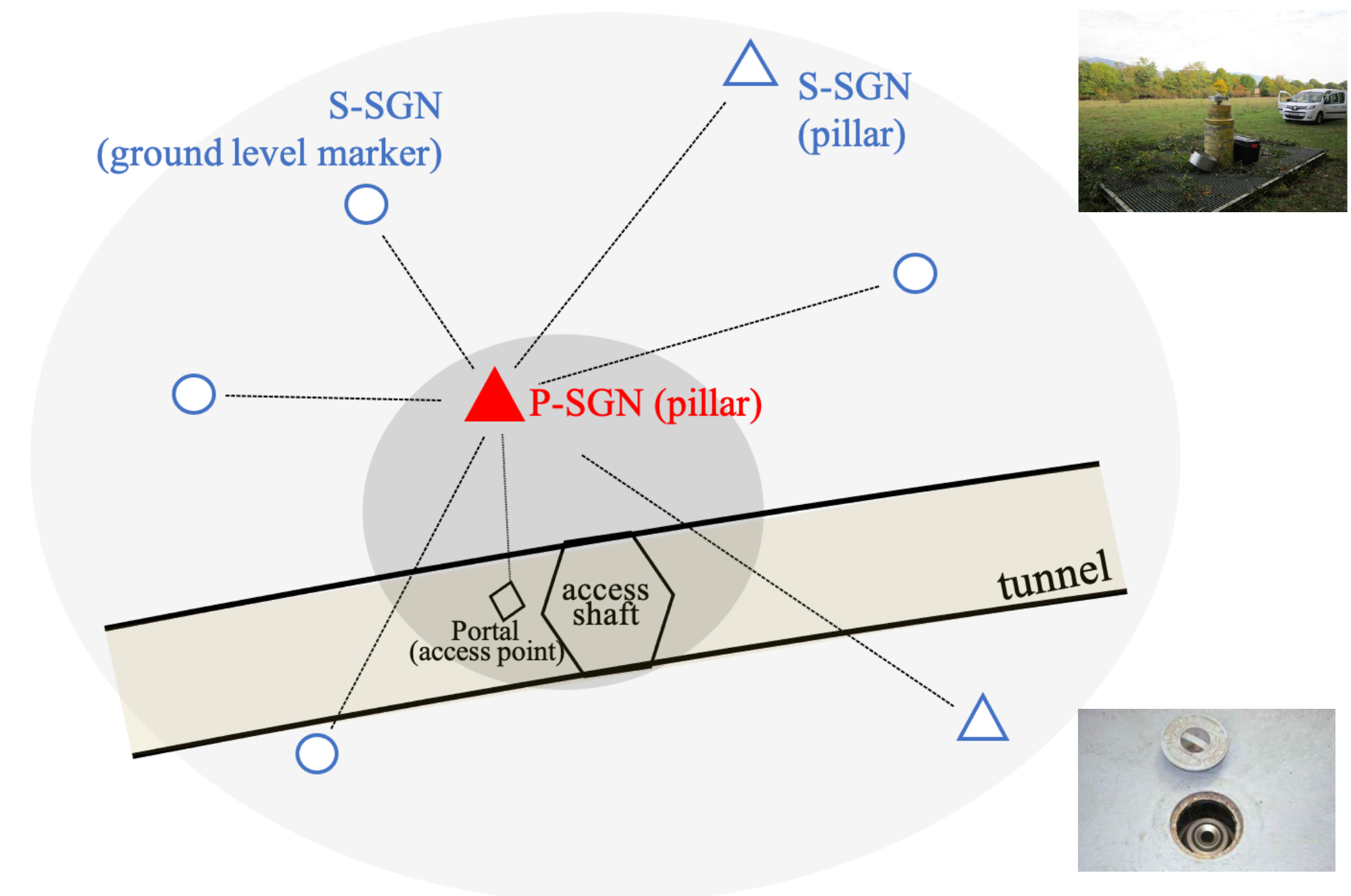
*Surface kinematics*

# Geodetic network for FCC: conceptual solution (1)

- Active, semi-active (campaign) and passive geodetic points
- Strategically distributed in important locations (e.g. around tunnel access shafts)
- Ensure ideal support during pre-construction and construction phases, as well as full life-time of the FCC



*Proposal for newly established (red) and existing (green) surface geodetic points (note: locations are only approximate and may change).*



*Schematic layout of a portal surface geodetic network for one tunnel access shaft*

*Acronyms: P-SGN: primary surface geodetic network, S-SGN: secondary surface geodetic network*

# Geodetic network for FCC: conceptual solution (2)

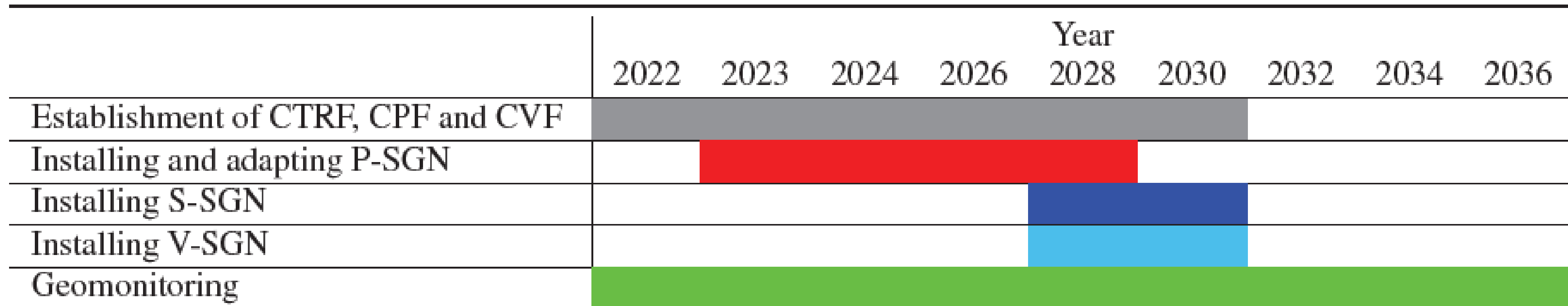
*Key characteristics of the various types of surface geodetic network (SGN) points*

	P-SGN	S-SGN	V-SGN
Purposes	Realize CTRF Determine CKM Main tunnel network	Densification Geomonitoring Construction Portal networks	Realize CVF Geomonitoring Construction
Coordinates	3D in CTRF 2D in CPF option: 1D in CVF	3D in CTRF 2D in CPF option: 1D in CVF	1D in CVF
Materialization	Pillar, or ground level foundation with precision marker	Various, typically ground level marker	Height bolt
Suitability	GNSS optionally also other surveying equipment	various surveying equipment	geometric levelling
Precision	individually specified all: $\sigma_{N,E} \leq 3.5 \text{ mm}$ $\sigma_U \leq 5.0 \text{ mm}$ in CTRF	individually specified typ.: $\sigma_{N,E} \leq 3.5 \text{ mm}$ $\sigma_U \leq 5.0 \text{ mm}$ in CTRF	individually specified all: $\sigma_{\Delta H} \leq 0.5 \text{ mm/km}^{\frac{1}{2}}$ w.r.t. V-SGN (up to 5 km)
Reliability	$AZ \leq 3$ for $\alpha_0 = 1\%$ , $\beta = 10\%$	$AZ \leq 3$ for $\alpha_0 = 1\%$ , $\beta = 10\%$	$AZ \leq 3$ for $\alpha_0 = 1\%$ , $\beta = 10\%$

*Acronyms: P-SGN primary SGN, S-SGN secondary SGN, V-SGN vertical surface geodetic network, GNSS: Global Navigation Satellite System*

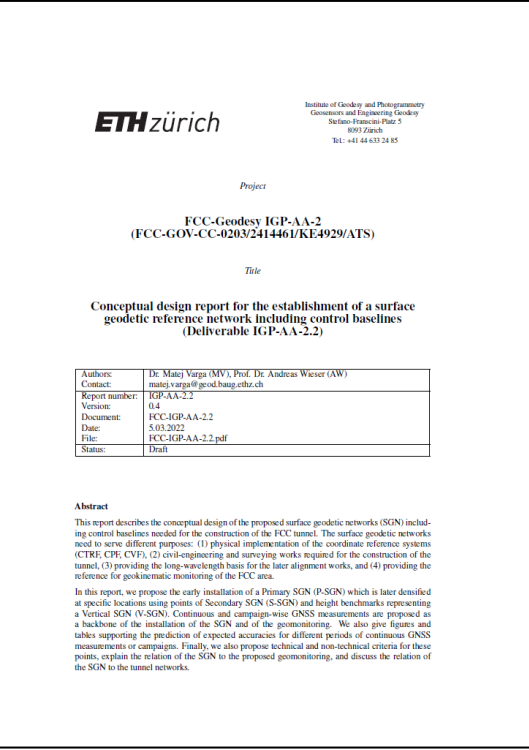
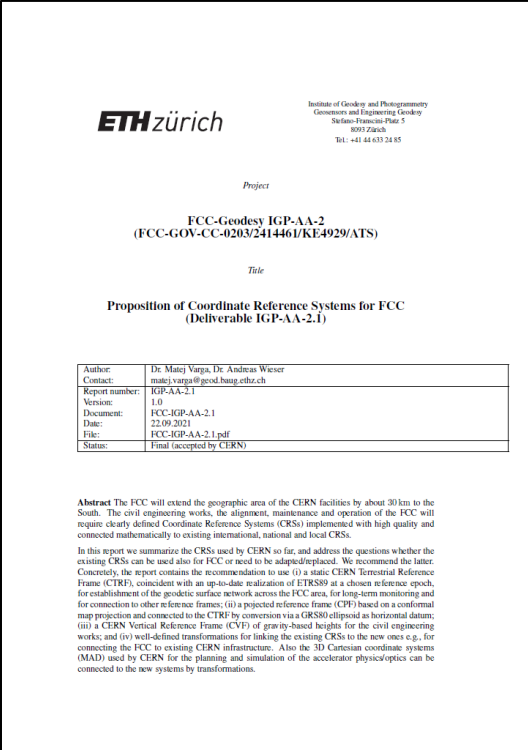
# Theoretically proposed timeline for implementation

- Relative time-periods between activities can be predicted more reliable than absolute time-periods.
- Possible delays in each activity can be expected due to many reasons.



# Conclusion

1. Conceptual solutions of CRS and geodetic networks have been proposed
2. The practical solutions planned to be implemented in the next few years
3. Two scientific reports summarize the proposed concept of CRS and surface network
  - Varga M., Wieser A. (2021): **Proposition of Coordinate Reference Systems for FCC**
  - Varga M., Wieser A. (2021): **Conceptual design report for the establishment of a surface geodetic reference network including control baseline**
4. Presented information have mainly scientific and consultative value
5. Decisions on adoption and details of practical (*real-world*) implementation are made by CERN
6. The results will have positive impact on everyday work of many other participants (physicists, metrologists, civil-engineers, etc.)





Thank you for your attention.