

Solenoid modeling for the FCC-ee IR

2T solenoid, strongest magnet in the lattice arc bends 0.016 T at Z-energies
average transverse component $0.015 \times 2T = \mathbf{0.03\ T}$ **2 × stronger**
peak fringe fields depending on geometry details **~10 × stronger** than main bends

Model : input $\mathbf{B(x, y, z)}$ shown here for ideal analytical solenoid and 3D fieldmap by M.K.

determine the trackjectory numerically (FieldStep)

reproduce on MAD-X level by orbit correctors $\propto x'', y''$ + thin solenoid slices $\propto B_z$

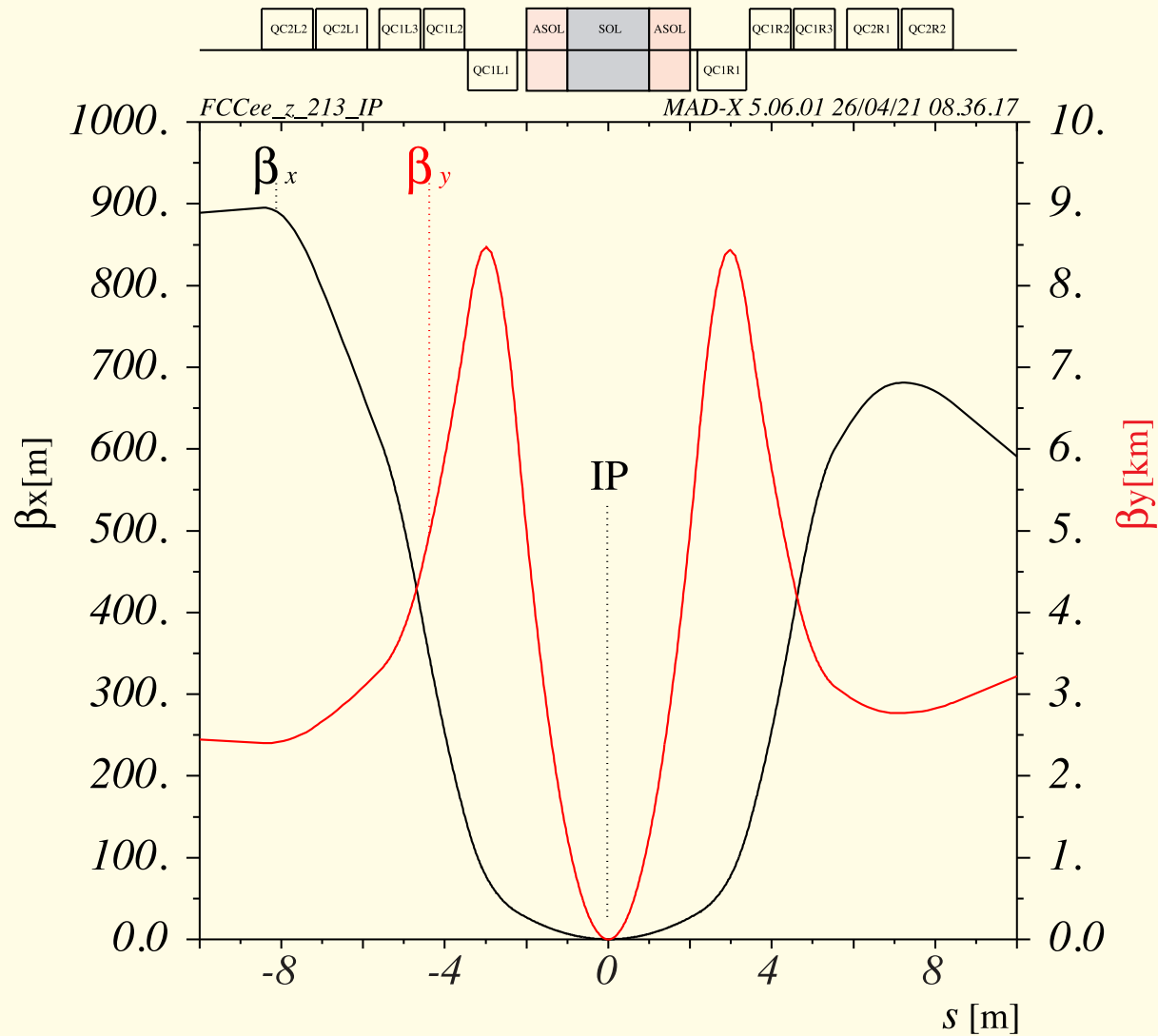
~ factorization ;

tilt generates bump modelled with corrector slices

+ coupling + focusing as in untilted solenoid

Acknowledgement : many fruitful discussions with CERN/FCC colleagues including

Rogelio Tomas, Tobias Persson, Leon van Riesen-Haupt, Riccardo de Maria, Laurent Deniau, Katsunobu Oide, Frank Zimmermann, Anton Bogomyagkov, Dmitry Shatilov, Kyrre Sjobaek, Manuela Boscolo, Barbara Dalena, Mike Koratzinos

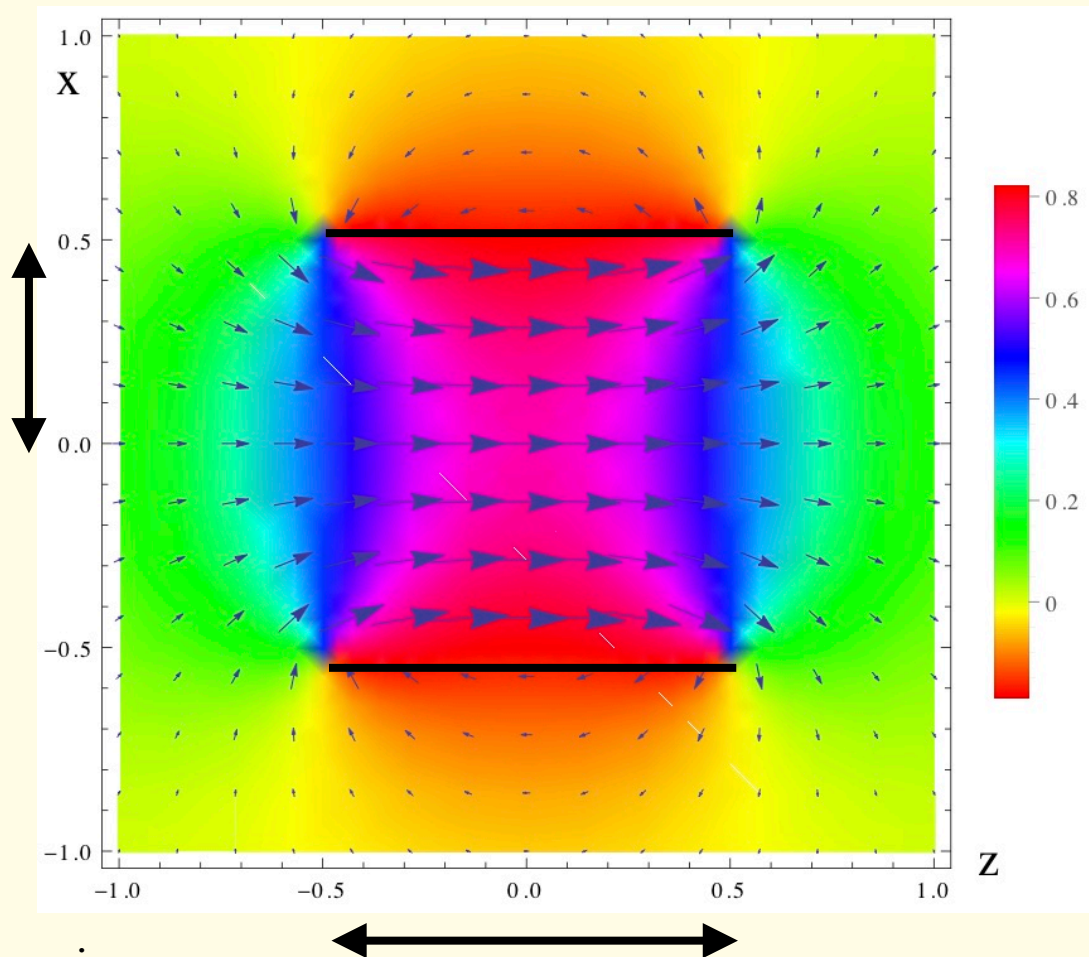
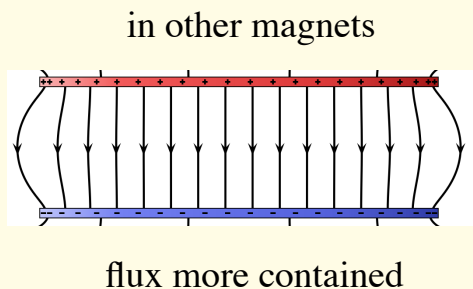


β_y max = 8471m
 β_y min = 0.8 mm
 10**7 variation

IP region : **strongly varying** twiss parameters

here illustrated using MAD-X with **many slices** to get smooth curves

Analytic expression of solenoid field
in terms of complete elliptic integrals
of 1st, 2nd, 3rd kind K, E, Π
available in Mathematica, SymPi and C++17



Vector potential

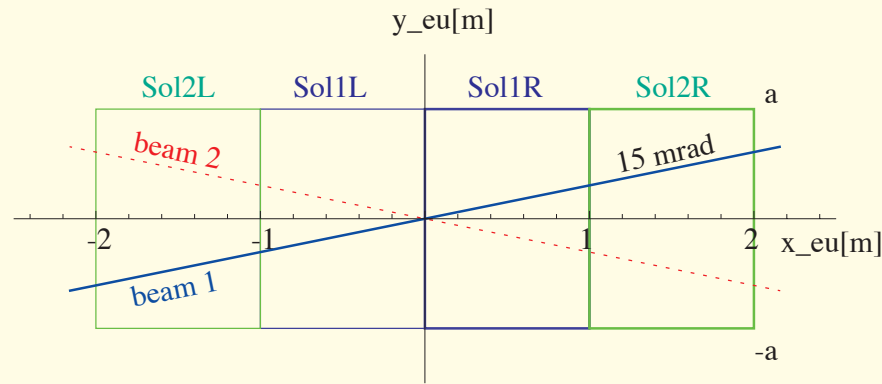
cylindrical coordinates z, ρ - distance from axis

$$A_{\phi}(\rho, z) = \frac{\mu_0 I}{2} \frac{z k}{2 \pi L} \sqrt{\frac{R}{\rho}} \left[\frac{k^2 + h^2 - h^2 k^2}{h^2 k^2} K(k^2) - \frac{1}{k^2} E(k^2) + \frac{h^2 - 1}{h^2} \Pi(h^2, k^2) \right]_{z-L/2}^{z+L/2}$$

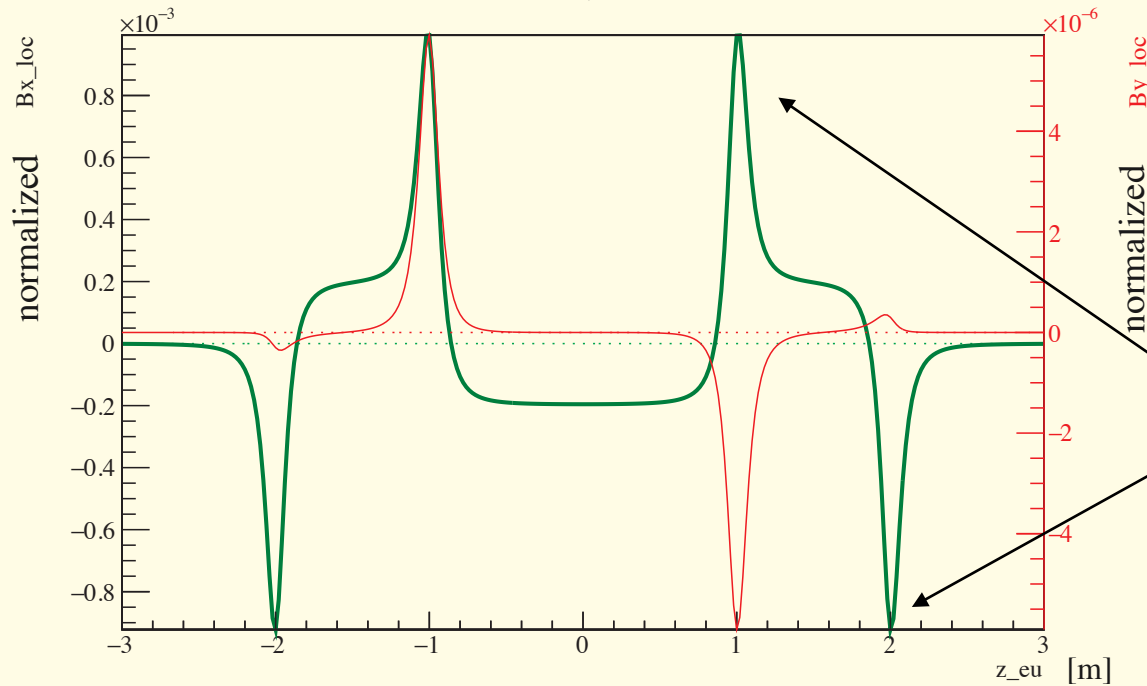
$$h^2 = \frac{4R\rho}{(R + \rho)^2} \quad k^2(\rho, z) = \frac{4R\rho}{(R + \rho)^2 + z^2}$$

K.F. Müller, Berechnung der Induktivität von Spulen
01/05/1926, doi = [10.1007/BF01655986](https://doi.org/10.1007/BF01655986)

four 1m solenoid
anti-solenoid
pieces, 2T field



fields in
local system
main field Bx
vertical bump



peaks and SR
by fringe increase
when R (here 0.1 m)
is reduced

	Min	Max		
Bx/Brho	-0.9221e-3	0.99422e-3		kick y
By/Brho	-0.0059e-3	0.00591e-3	170× smaller	kick -x

$B_p = 152.1 \text{ Tm}$ max Bx = 0.15 T nearly 10× the 0.016 T of arc bends
at IP $\sim 0.015 \times 2 \text{ T} = 0.03 \text{ T}$ 2× arc bends

Maps from **Hamiltonian in presence of fields** $-\sqrt{p_t^2/c^2 - m^2c^2 - (p_x - qA_x)^2 - (p_y - qA_y)^2 - qA_z}$
 symplectic for canonical coordinates derived from the Hamiltonian V. Arnold, H. Goldstein, Landau-Lifschitz
 standard machine magnets (quadrupole) have mainly A_z and small (ideally 0) A_x, A_y
 the analytic **solenoid** has only nonzero A_ϕ (A_x, A_y)

Transformation in **transport (real space) coordinates** with separate edges ([Talman lectures](#))

$$R_{\text{sol}} = \underbrace{\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -K & 0 \\ 0 & 0 & 1 & 0 \\ K & 0 & 0 & 1 \end{pmatrix}}_{\text{edge1}} \underbrace{\begin{pmatrix} 1 & \frac{SC}{K} & 0 & \frac{S^2}{K} \\ 0 & C^2 - S^2 & 0 & 2CS \\ 0 & -\frac{S^2}{K} & 1 & \frac{SC}{K} \\ 0 & -2CS & 0 & C^2 - S^2 \end{pmatrix}}_{\text{solenoid body}} \underbrace{\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & K & 0 \\ 0 & 0 & 1 & 0 \\ -K & 0 & 0 & 1 \end{pmatrix}}_{\text{edge2}}$$

the product R_{sol} is symplectic, the individual matrices are not

Dragt [ebook](#), in chapter 16.2 : *It is therefore highly desirable, in the case of a solenoid, to treat fringe-field effects with care (which must be done numerically) using realistic profiles $b[n](z)$*

Willeke, Ripken Methods of beam optics, [AIP Proc. 184, 758 \(1989\)](#), Matrix U, Coupled case, Eq. (3.51)

```
label: SOLENOID, L=length, KS=ksval;           ! thick version
label: SOLENOID, L=0, Lrad=length, KS=ksval, KSI:=ksval*Lrad; ! thin version
```

more recently also possible to add permanent dtheta tilt

Note : currently in MAD-X no information about solenoid radius — extend of fringe fields

fringe field effect taken into account as seen from outside

Example, FCC-ee solenoid pieces, $B_{sol} = 2 \text{ T}$ beam pc = 45.6 GeV

Thick $L = 1 \text{ m}$, $ksval := B_{sol} / \text{beam} \rightarrow brho = 0.0131488$

Slicing, MAD-X module MAKETHIN

Thin solenoid, $lrad := \text{length} / nslices$, $ks := ksval$, $ksi := ksval * lrad$;

Literature :

[MAD8 Physics Guide](#)

On The Implementation Of Experimental Solenoids In MAD-X And Their Effect On Coupling In The LHC,
A. Koschik, H. Burkhardt, T. Risselada, F. Schmidt [EPAC 2006](#)

Upgrade of slicing and tracking in MAD-X, H. Burkhardt, L. Deniau, A. Latina, [IPAC2014](#)

Thin solenoid

converges well to reproduce the thick solenoid

noted in our [EPAC 2006 paper](#) :

slicing a thick solenoid into several thin ones ...

converges to the thick lens solution ...

does in general not give the correct edge focusing effect

The MAD-X thin solenoid transfer matrix can be written as product of a rotation about the s-axis and “a thin quadrupole” focusing in both x, y

$$\begin{bmatrix} \cos(\psi) & 0 & \sin(\psi) & 0 & 0 & 0 \\ 0 & \cos(\psi) & 0 & \sin(\psi) & 0 & 0 \\ -\sin(\psi) & 0 & \cos(\psi) & 0 & 0 & 0 \\ 0 & -\sin(\psi) & 0 & \cos(\psi) & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{f} & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{f} & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

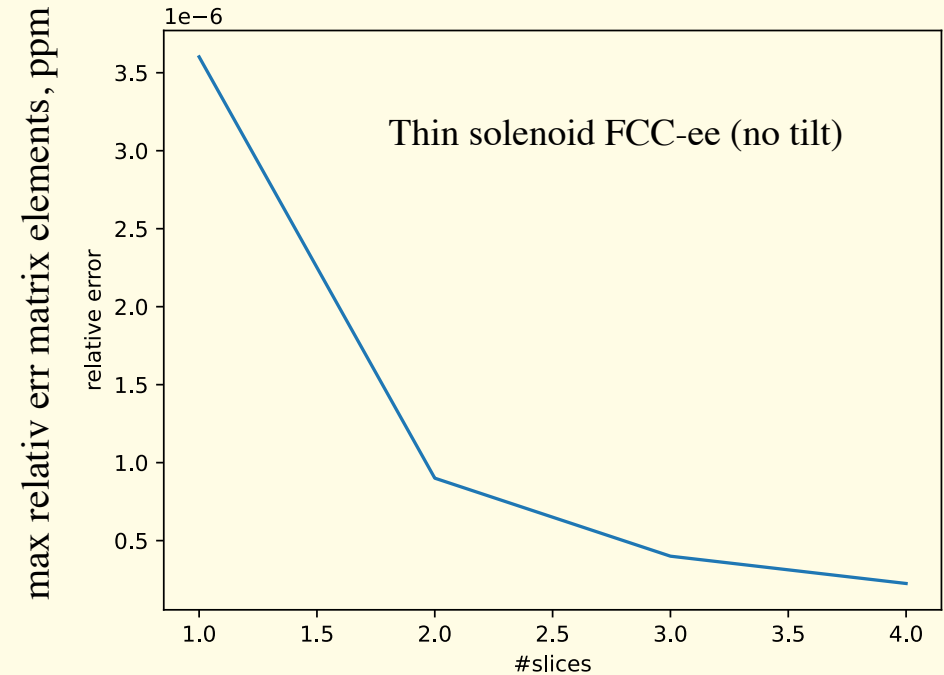
$$\psi = L KS/2 = KSI/2$$

$$6.5744 \text{ mrad} \quad \text{FCC-ee Z}$$

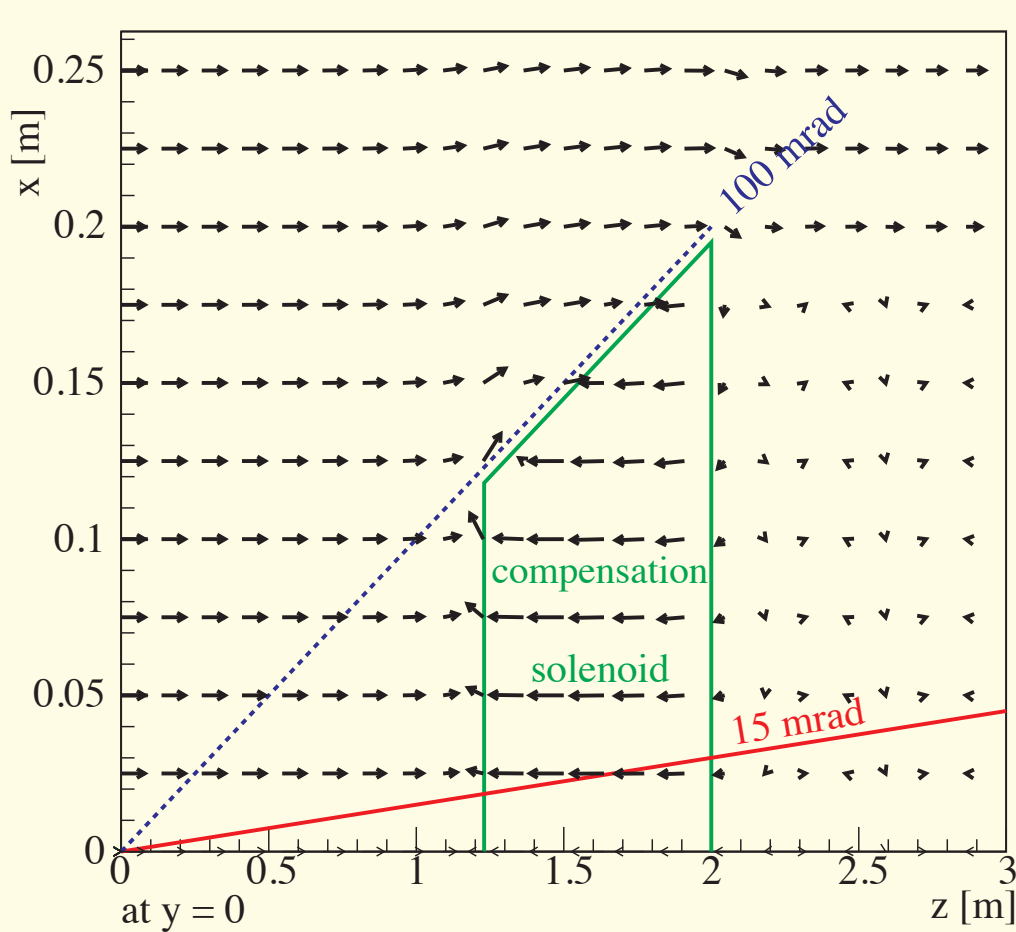
$$\frac{1}{f} = \frac{KS}{2} \frac{KSI}{2}$$

$$4.32e-5 / \text{m}$$

for the 1m long solenoid piece

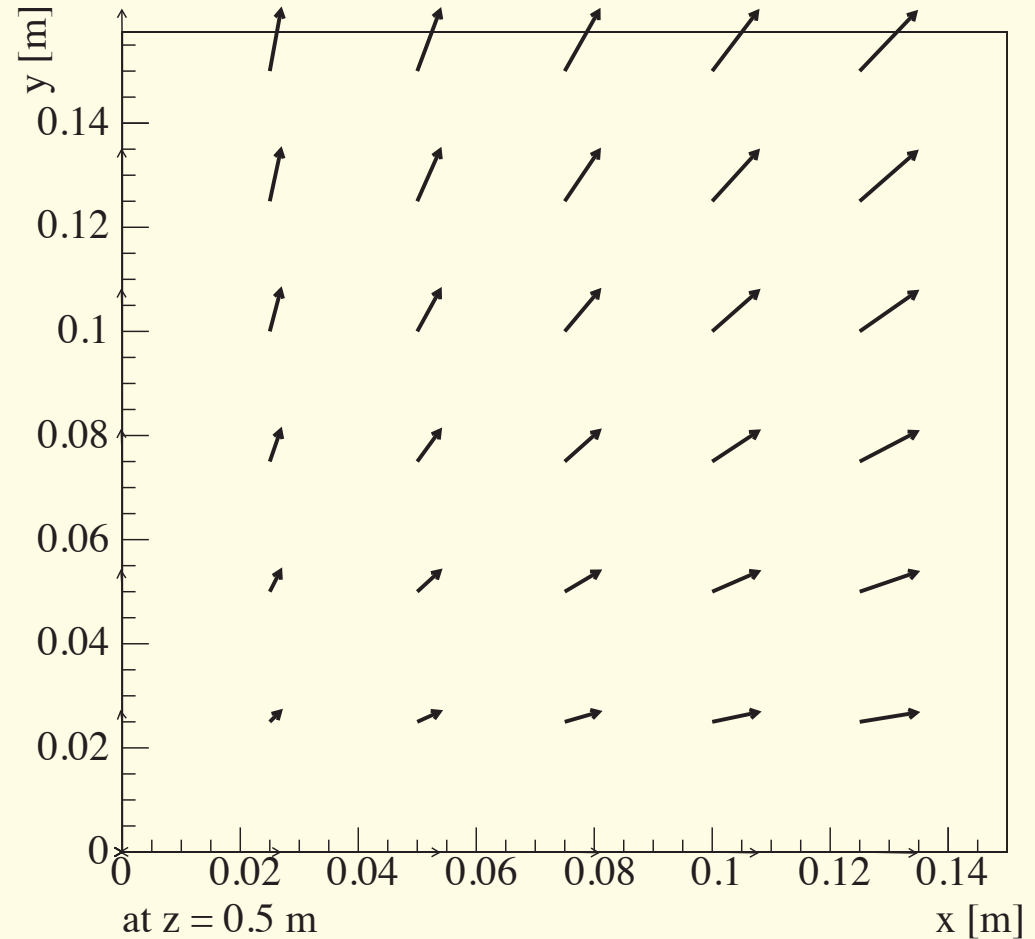


3D_map_compantation_only_best_so_far.xls Mike Koratzinos 26/11/2021
defined for 0 to 0.5 m in x,y and 0 to 3 m in z, in steps of 0.025 m

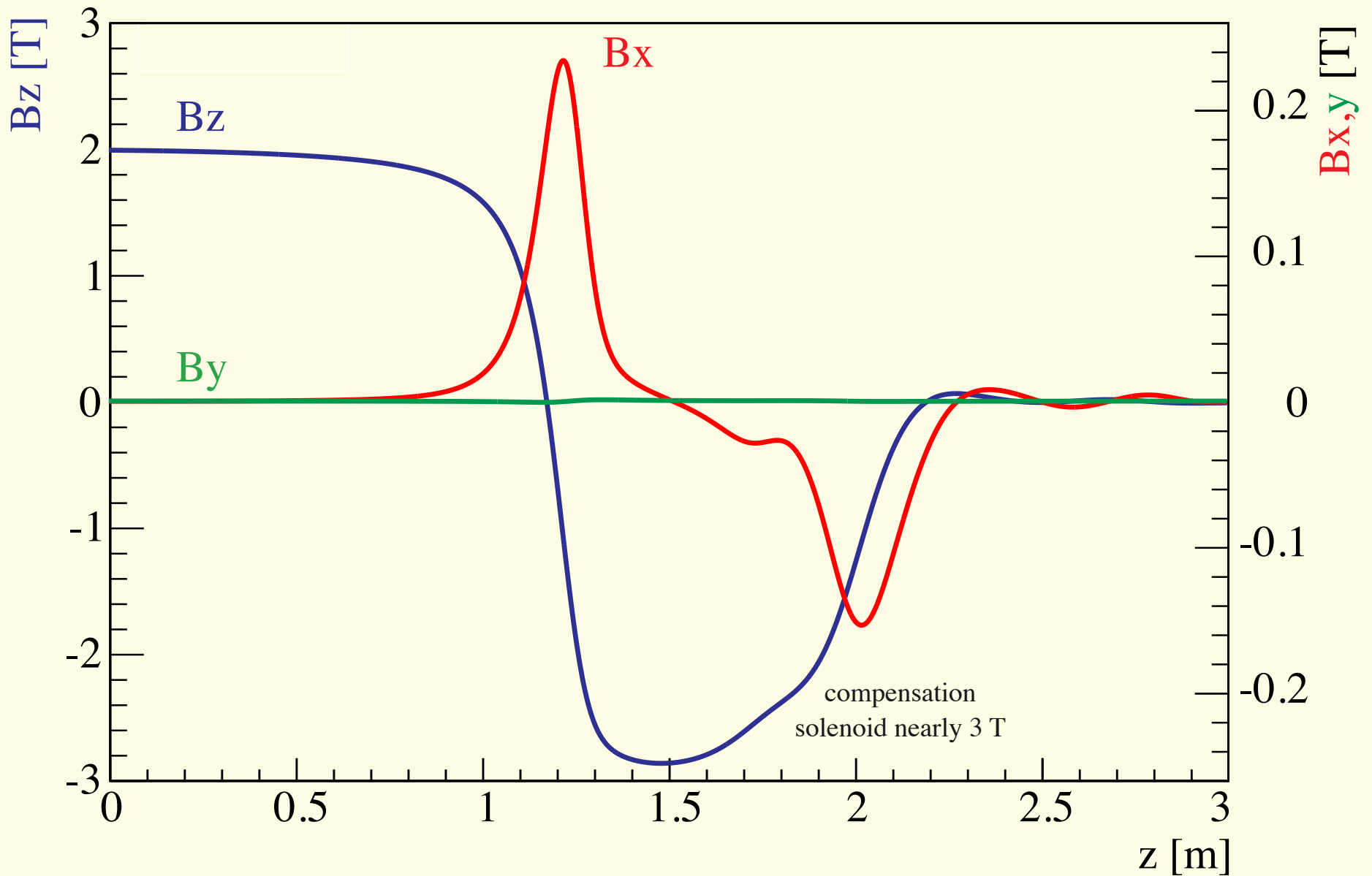


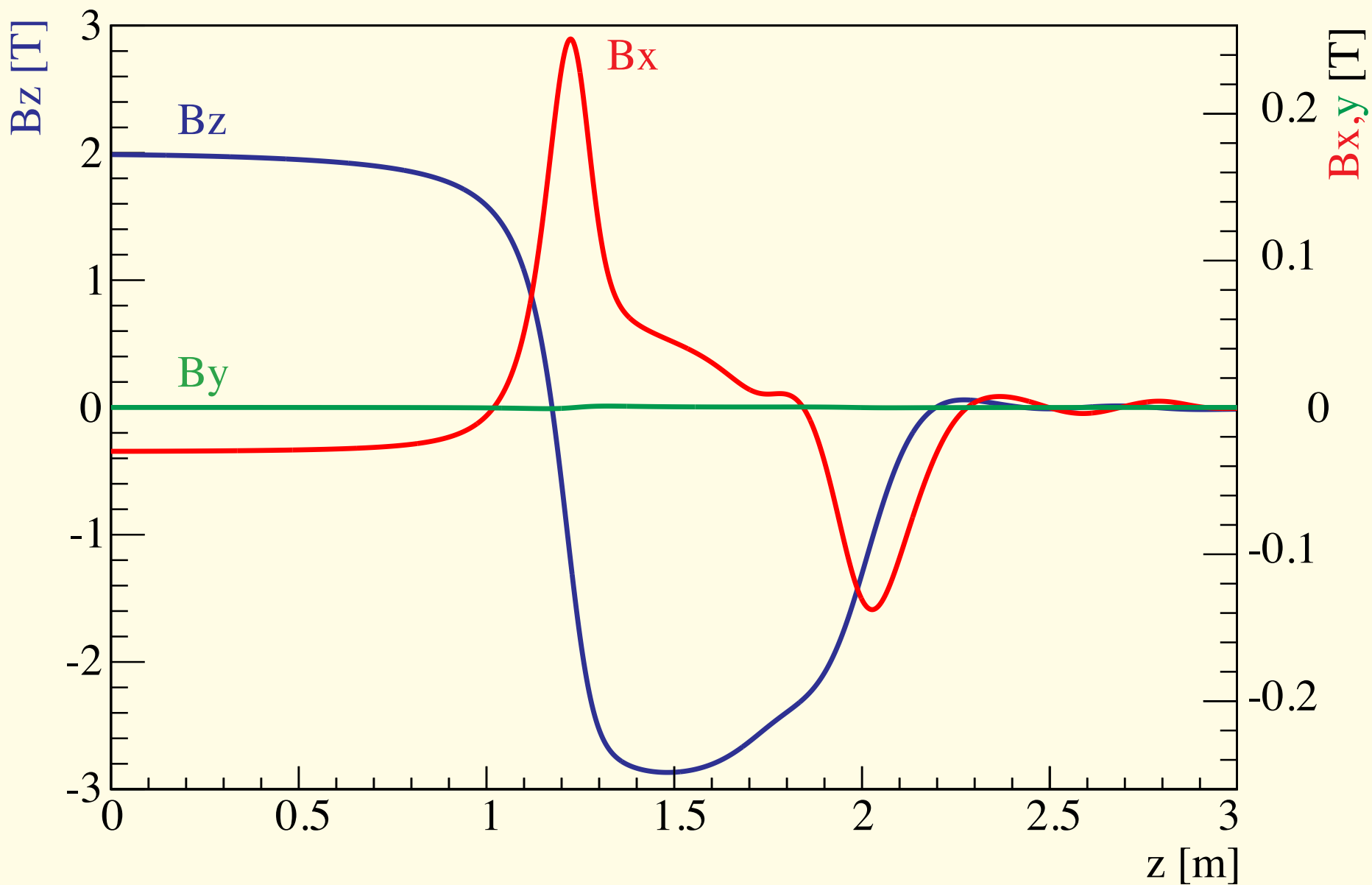
0 side view

3 m



look in z-direction along the solenoid axis





numerical solution of equations of motion:

input : $B(x,y,z)$

determine design passage by tracking

converges quickly, excellent agreement with GEANT4 and (my) FieldStep

very fast for small lattice sections like ± 5 m around IP

$$\begin{aligned} \mathbf{x}'' &= \mathbf{x}' \times \mathbf{B}_n \\ \mathbf{x}'_+ &= \Delta s \mathbf{x}'' \\ \mathbf{x}_+ &= \Delta s \mathbf{x}' \end{aligned}$$

output :

track coordinates at every step

optionally track design particle and 6 particles with small offsets in all coordinates

(multi-treading, \sim same speed as single particle)

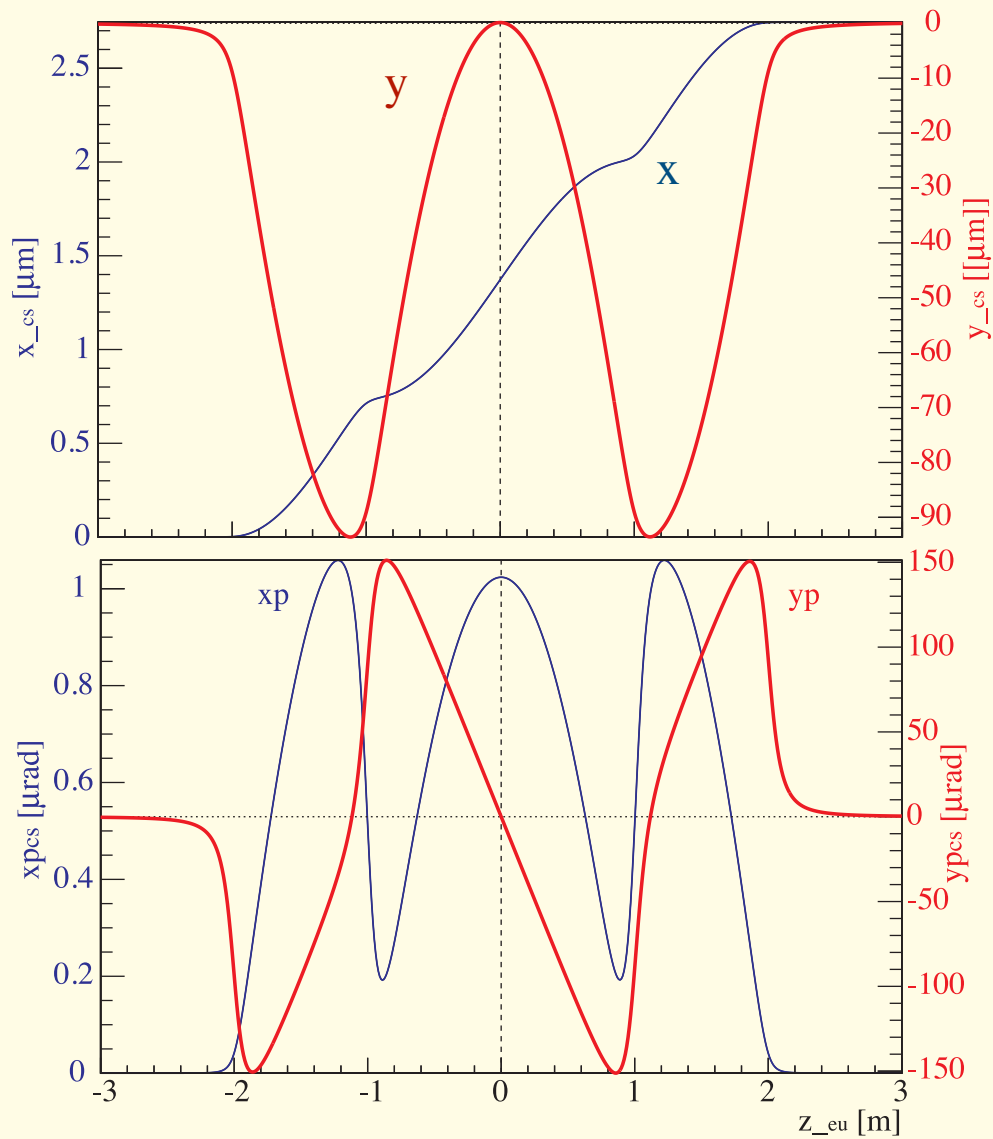
transfer matrices in real space coordinates from numerical Jacobian, symplectic when $A_x = A_y = 0$

outside : reproducing the Solenoid map (for small solenoid radius)

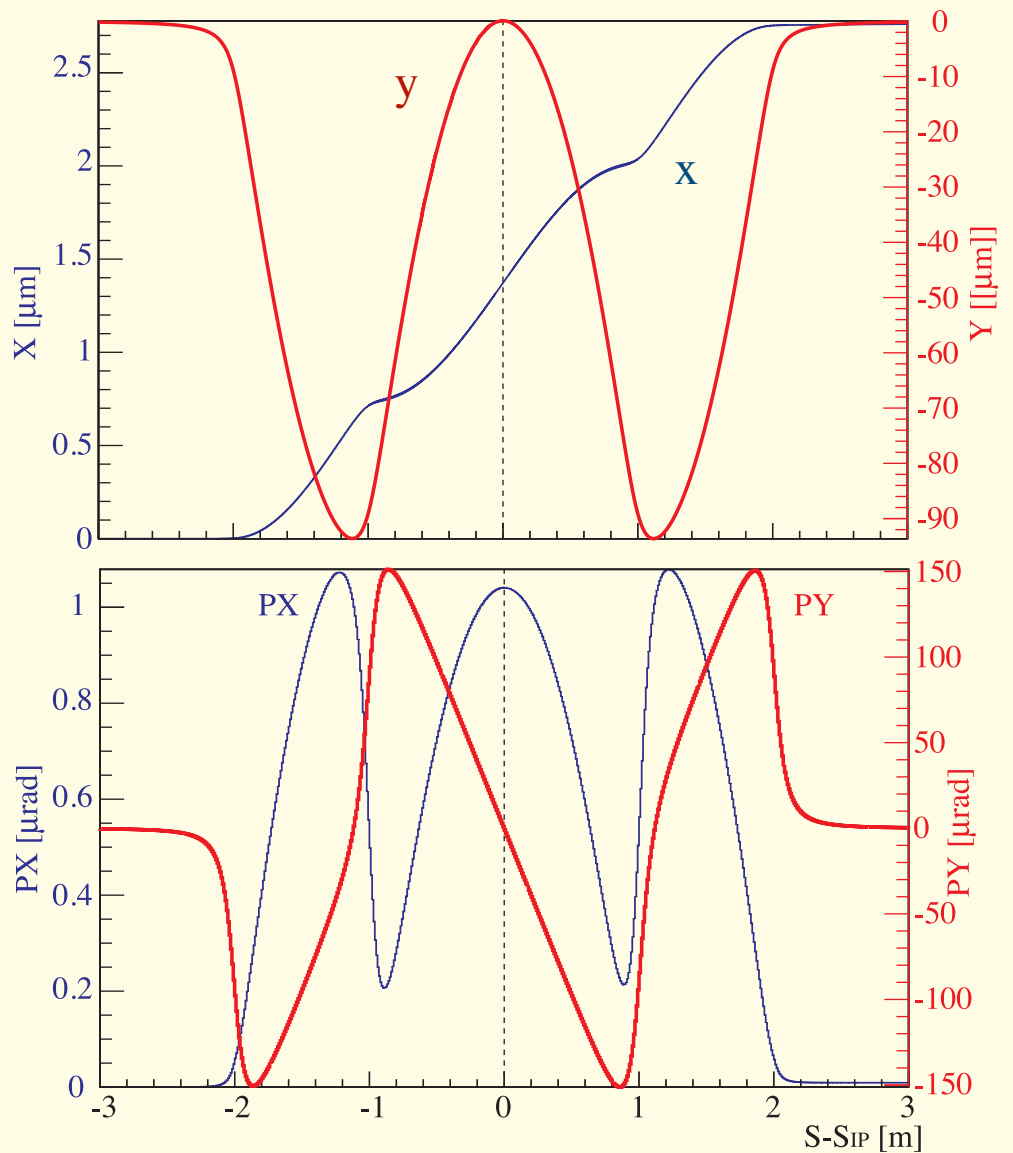
inside : transport (real space) positions and angles x, x'

use x'' as corrector strength to reproduce solenoid bump on the MAD-X level

FieldStep



MAD-X

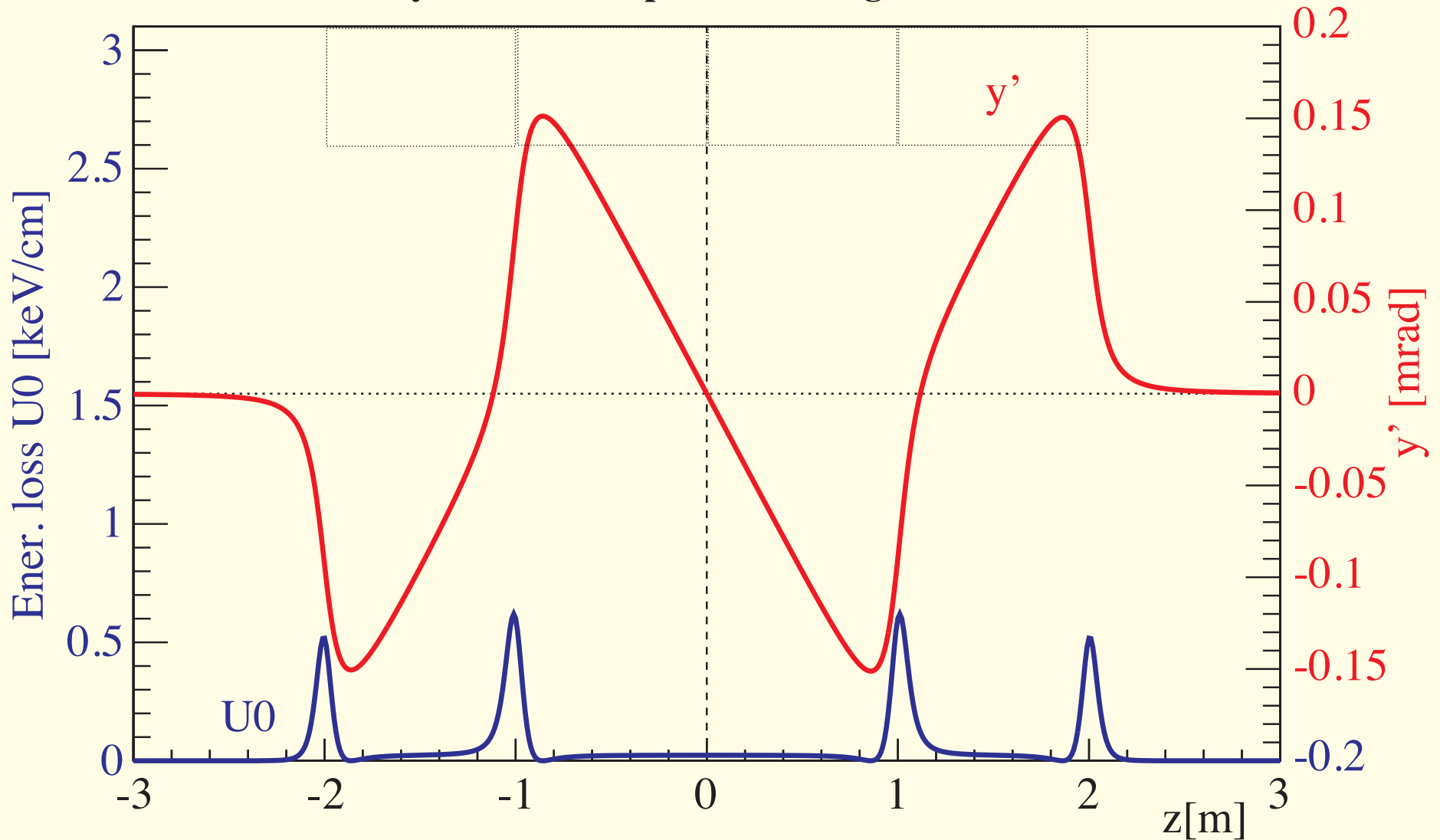


excellent agreement in bump shape

x : 0 to 2.7 μm 0 to 1.05 μrad

y : 0 to -94 μm ± 151 μrad

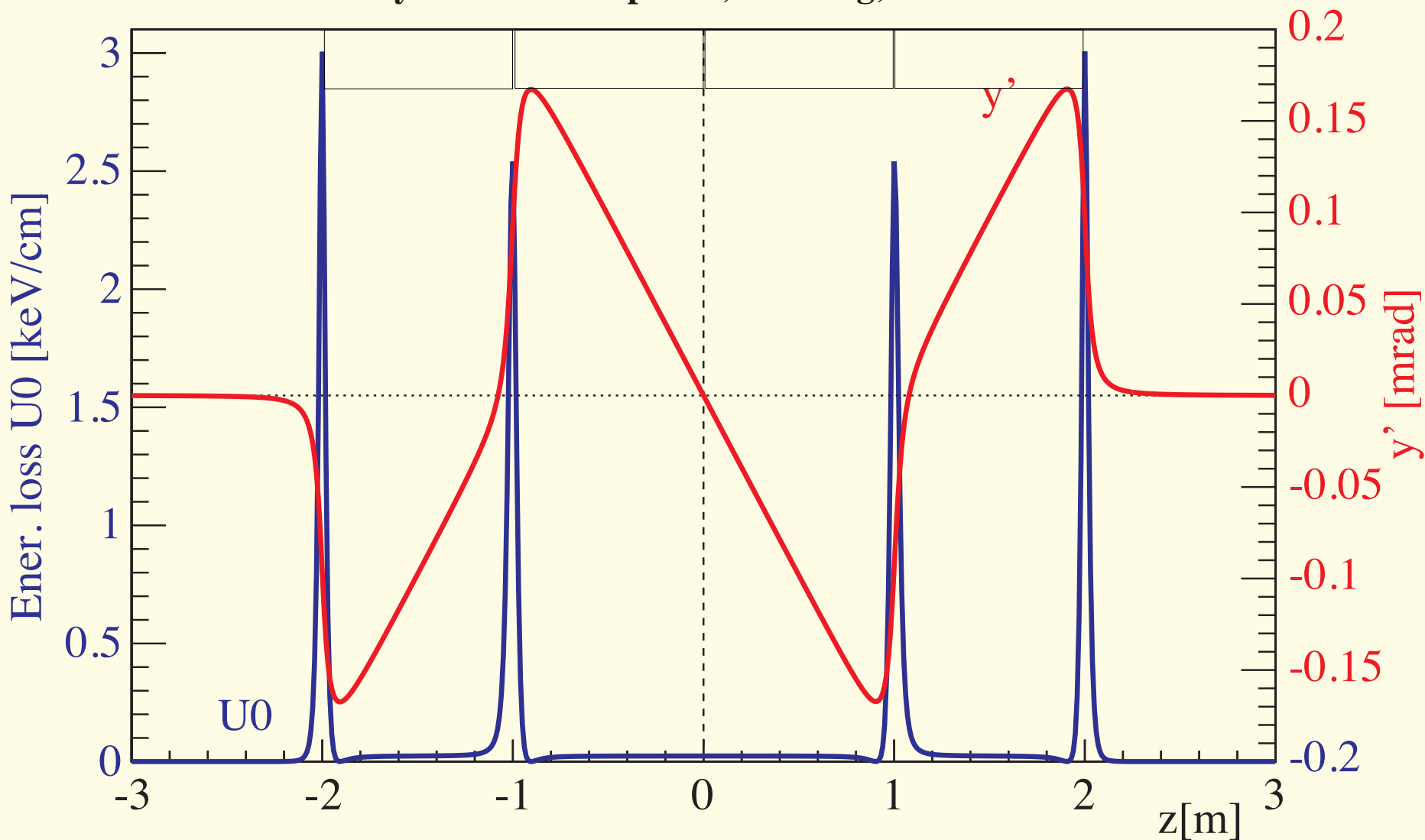
analytical solenoid pieces, 1m long, radius 0.1 m



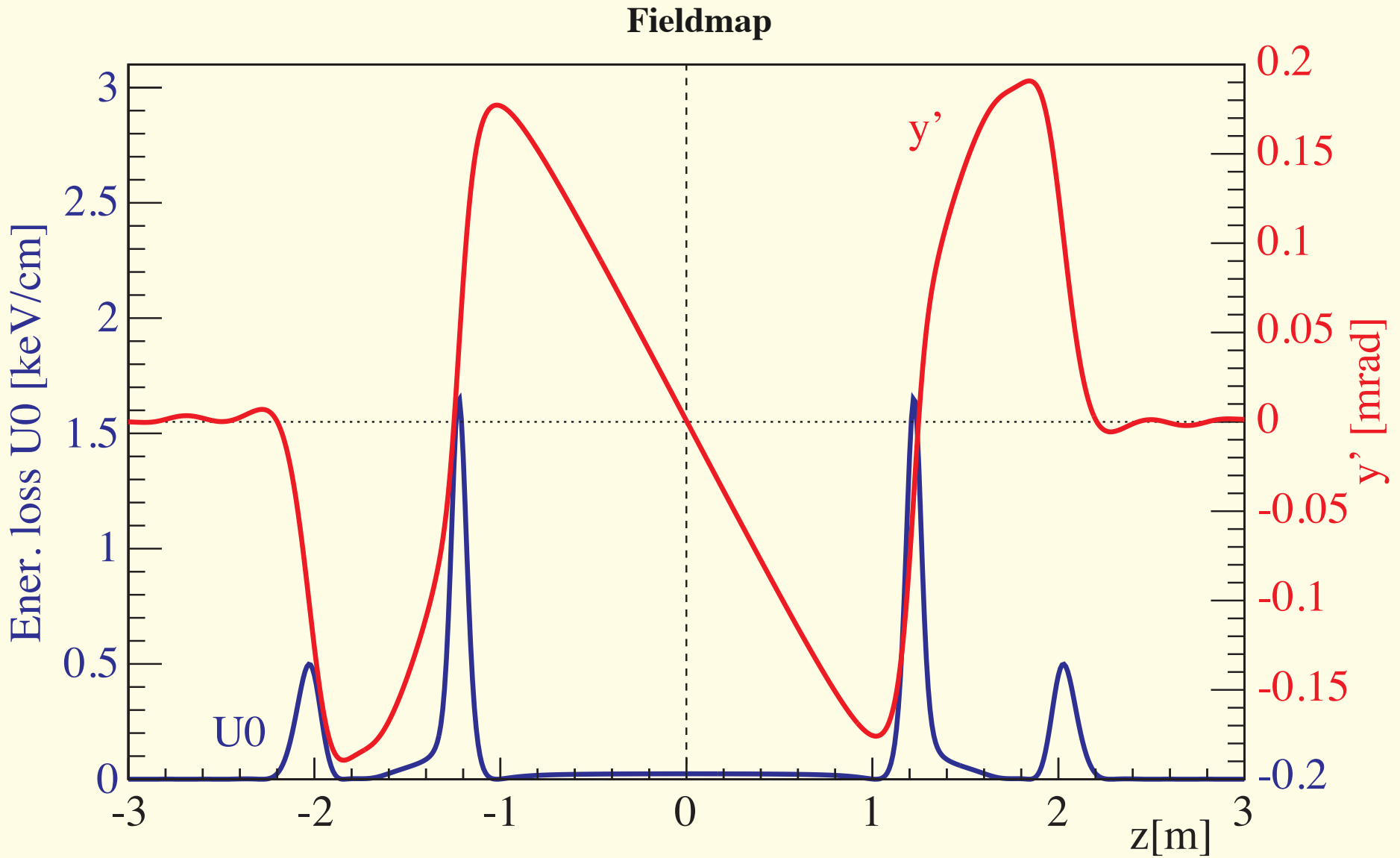
FCC-ee Z, 1.28 A beam current IR solenoid SR **41 kW / beam**

other FCC-ee energies	80 GeV, 135 mA, 13.3 kW
2T solenoid	120 GeV, 26.7 mA, 5.9 kW
	182.5 GeV, 5 mA, 2.6 kW

analytical solenoid pieces, 1m long, radius 0.05 m

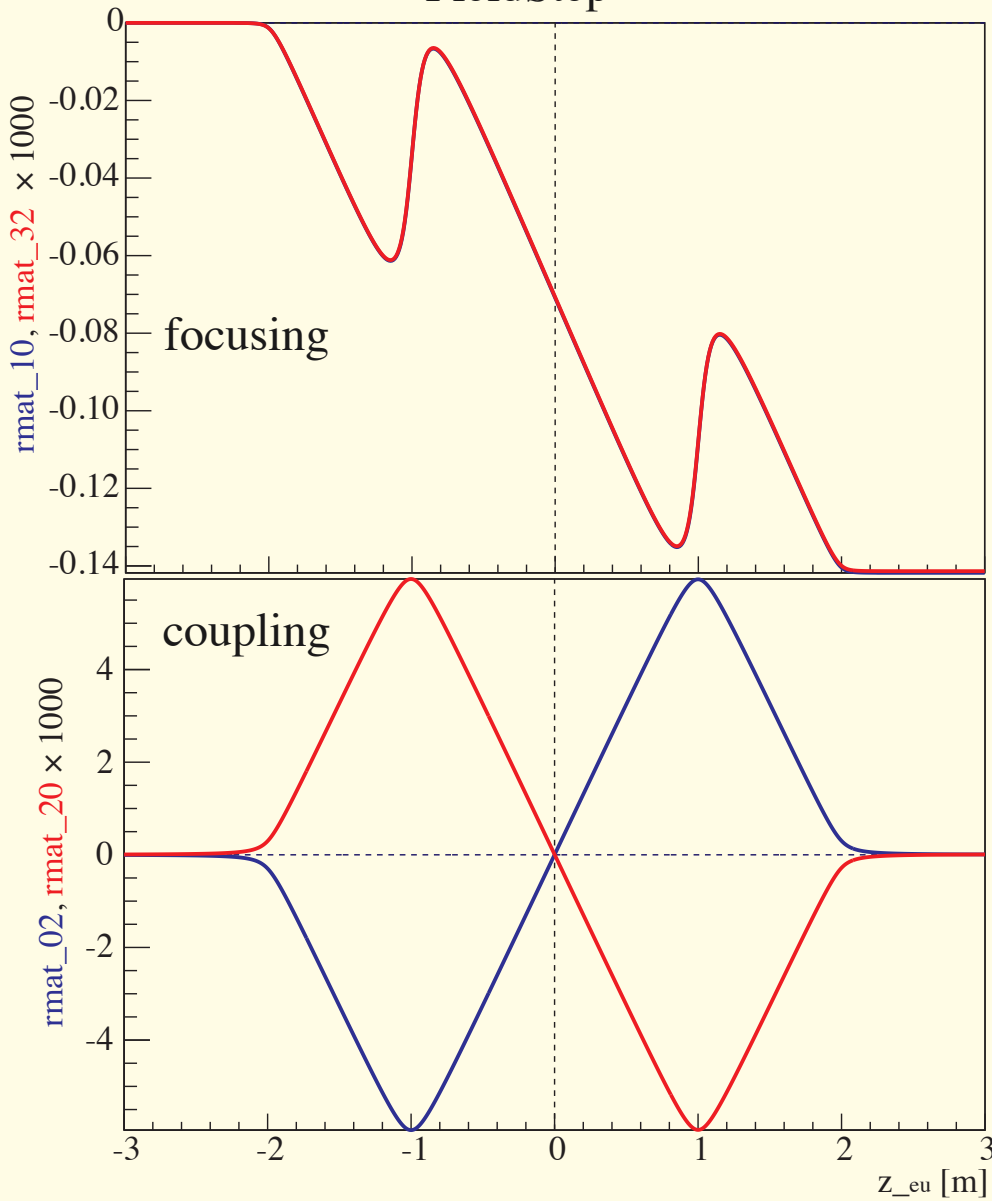


FCC-ee Z, 1.28 A beam current IR solenoid SR **81 kW / beam**

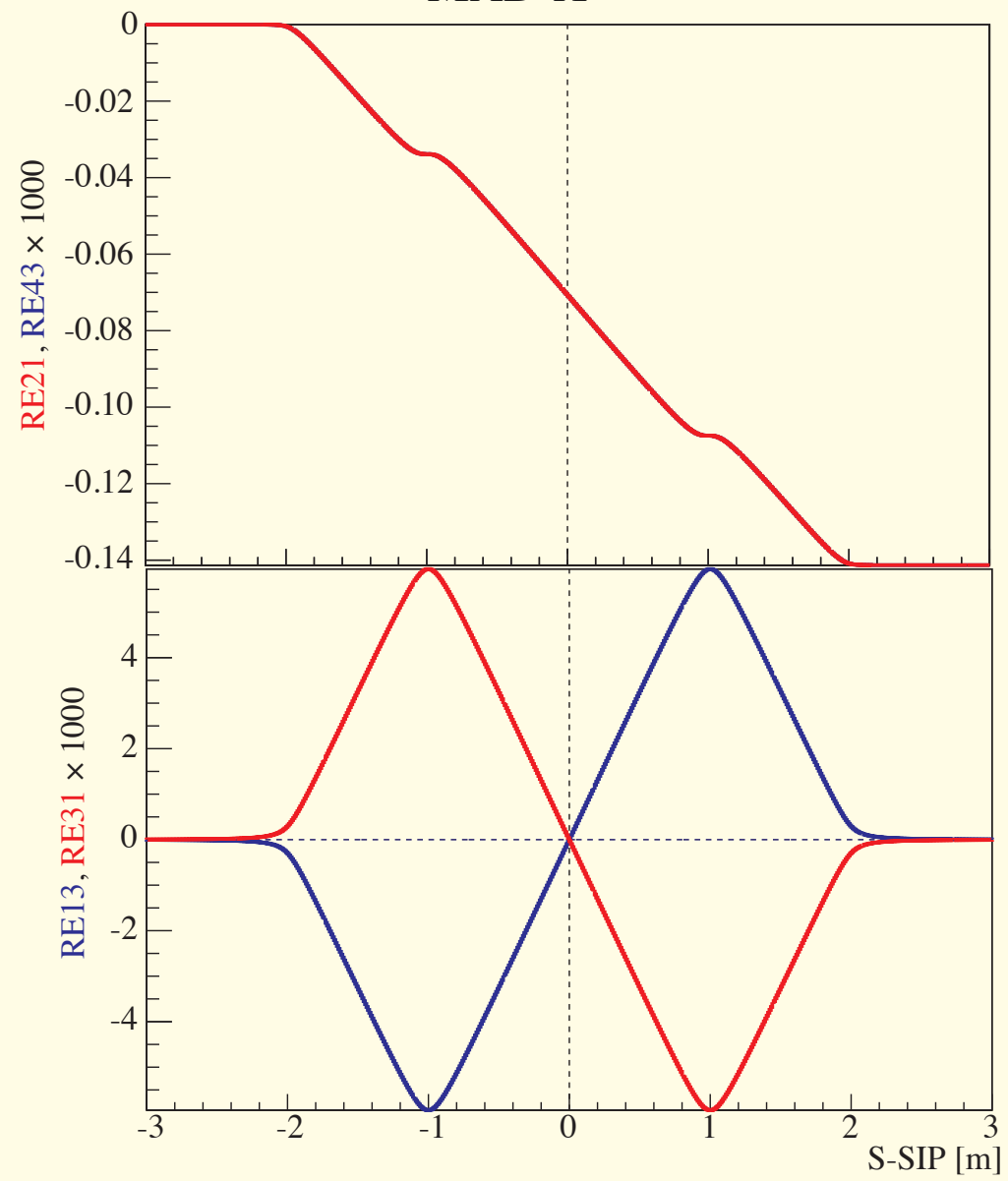


FCC-ee Z, 1.28 A beam current IR solenoid SR **77 kW / beam**

FieldStep

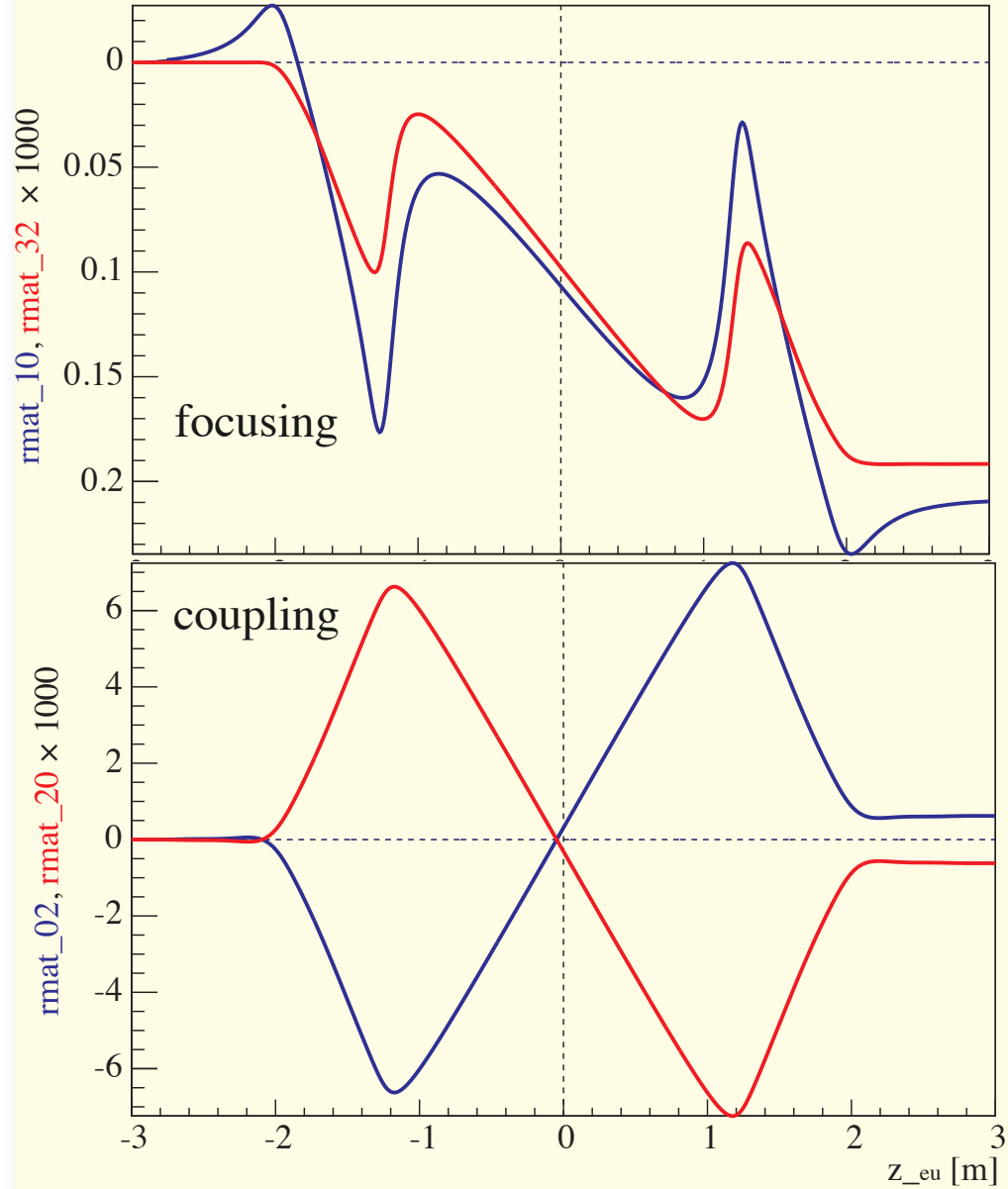


MAD-X

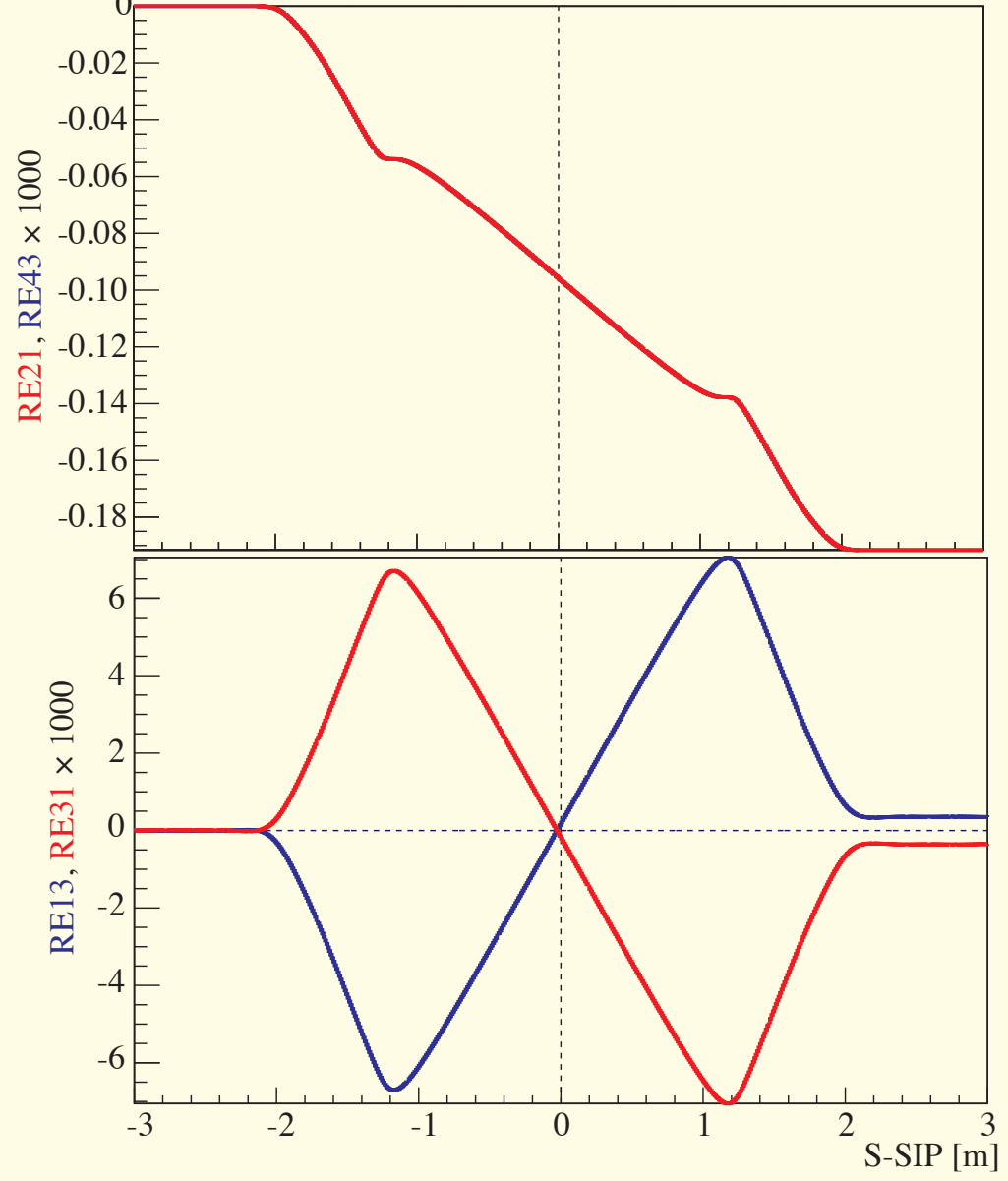


coupling well reproduced. overall (weak) focusing correct on average, ok as seen from outside

FieldStep



MAD-X



3D fieldmap : imperfections visible, radial symmetry and closure not exact

Given $\mathbf{B}(x, y, z)$ (analytical formulas or fieldmap)

the passage through the interaction region can be well modelled on the MAD-X level

with orbit correctors (kicker elements, describing the bump generated by the tilted solenoid detailed fringe fields)

+ thin solenoid slices (coupling + overall focusing)

positions, directions, dispersion and energy loss agree very well with numerical fieldstepping

in and outside the solenoid

Backup



Sliced sequences generated, insert in IR with seqedit



hv_corr_install.madx

```

..
install,element=hv_corr_m00020,at =-0.02/cos(0.015),from=IP;
install,element=hv_corr_m00010,at =-0.01/cos(0.015),from=IP;
install,element=hv_corr_p00000,at = 0/cos(0.015),from=IP;
install,element=hv_corr_p00010,at = 0.01/cos(0.015),from=IP;
install,element=hv_corr_p00020,at = 0.02/cos(0.015),from=IP;

..
hv_corr_def.madx
hv_corr_m00020 :kicker,lrad:=0.01/cos(0.015), hkick:= 5.0977934605683e-10*h_on , vkick:= -1.95543847556181e-06*v_on ;
hv_corr_m00010 :kicker,lrad:=0.01/cos(0.015), hkick:= 2.54894409450189e-10*h_on , vkick:= -1.95547204643059e-06*v_on ;
hv_corr_p00000 :kicker,lrad:=0.01/cos(0.015), vkick:= -1.95548319190777e-06*v_on ;
hv_corr_p00010 :kicker,lrad:=0.01/cos(0.015), hkick:= -2.54894409450189e-10*h_on , vkick:= -1.9554719453329e-06*v_on ;
hv_corr_p00020 :kicker,lrad:=0.01/cos(0.015), hkick:= -5.0977934605683e-10*h_on , vkick:= -1.95543827316283e-06*v_on ;

```

sol_install.madx

```

..
install,element=avesol_m00020 ,at =-0.02/cos(0.015),from=IP;
install,element=avesol_m00010 ,at =-0.01/cos(0.015),from=IP;
install,element=avesol_p00000 ,at = 0/cos(0.015),from=IP;
install,element=avesol_p00010 ,at = 0.01/cos(0.015),from=IP;
install,element=avesol_p00020 ,at = 0.02/cos(0.015),from=IP;

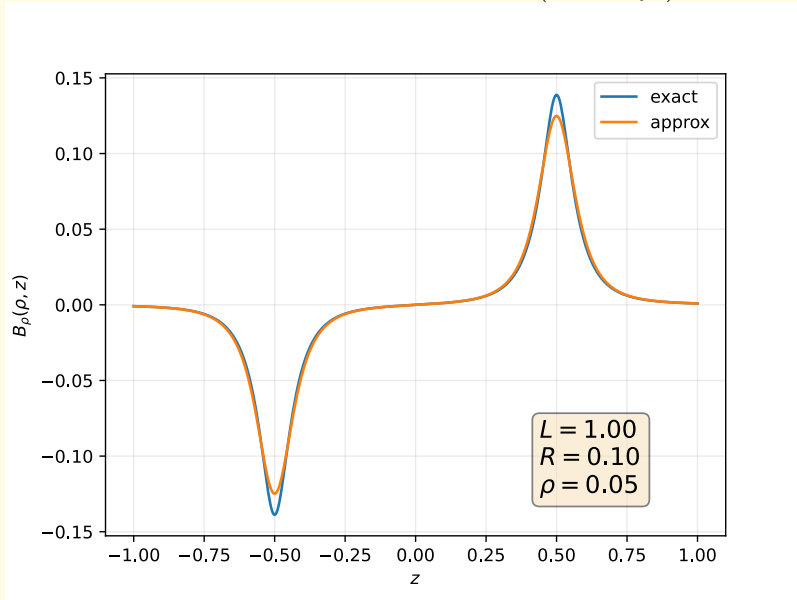
..
avesol_m00020:solenoid, lrad:= 0.0100011251054784, ks:= 0.0130330719303976*ksi_on, ksi:= 0.000130345382884605*ksi_on;
avesol_m00010:solenoid, lrad:= 0.0100011251054784, ks:= 0.0130331837298234*ksi_on, ksi:= 0.00013034650100465*ksi_on;
avesol_p00000:solenoid, lrad:= 0.0100011251054784, ks:= 0.0130332209718128*ksi_on, ksi:= 0.000130346873466445*ksi_on;
avesol_p00010:solenoid, lrad:= 0.0100011251054784, ks:= 0.0130331837305903*ksi_on, ksi:= 0.000130346501012319*ksi_on;
avesol_p00020:solenoid, lrad:= 0.0100011251054784, ks:= 0.0130330719319335*ksi_on, ksi:= 0.000130345382899966*ksi_on;

..
select, flag=error, range=avesol_m00020; ealign,dx:= 1.3520966226094e-06*dx_on ,dy:= 9.12901013449553e-08*dy_on, dphi:= 3.9320328843862e-06*dphi_on; select, flag=error, clear;
select, flag=error, range=avesol_m00010; ealign,dx:= 1.36233178875816e-06*dx_on ,dy:= 1.20738713487934e-07*dy_on, dphi:= 1.97657591949412e-06*dphi_on; select, flag=error, clear;
select, flag=error, range=avesol_p00000; ealign,dx:= 1.37256953163144e-06*dx_on ,dy:= 1.30630423739617e-07*dy_on, dphi:= 2.10964898685578e-08*dphi_on; select, flag=error, clear;
select, flag=error, range=avesol_p00010; ealign,dx:= 1.38280730200639e-06*dx_on ,dy:= 1.20965120604878e-07*dy_on, dphi:= -1.93438300117683e-06*dphi_on; select, flag=error, clear;
select, flag=error, range=avesol_p00020; ealign,dx:= 1.39304255065988e-06*dx_on ,dy:= 9.17429165901021e-08*dy_on, dphi:= -3.88984015056126e-06*dphi_on; select, flag=error, clear;

..

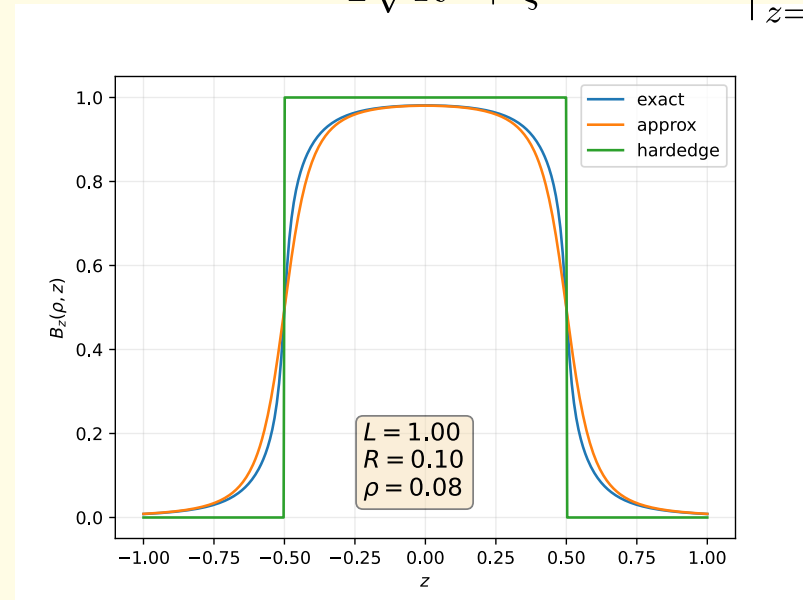
```

$$\frac{B_\rho(\zeta, \rho)}{\rho} = B_{\rho\text{-over-}\rho}(\zeta) \approx -\frac{R^2}{4(R^2 + \zeta^2)^{3/2}}$$



$$B_z(\zeta) \approx \frac{\zeta}{2\sqrt{R^2 + \zeta^2}}$$

$$\left. \begin{array}{l} z = \zeta + L/2 \\ z = \zeta - L/2 \end{array} \right\}$$



related by

$$\frac{dB_z(\rho, \zeta)}{d\zeta} = \frac{R^2}{2(R^2 + \zeta^2)^{3/2}} = -2 B_{\rho\text{-over-}\rho}$$

$$\begin{aligned} B_\rho &= -\frac{\partial A_\phi}{\partial z} \\ B_\phi &= 0 \\ B_z &= \frac{1}{\rho} \frac{\partial(\rho A_\phi)}{\partial \rho} \end{aligned}$$

as expected for
only non-zero A_ϕ

$$\int_{-\infty}^{\infty} B_\rho(\zeta, \rho) dz = \mp \frac{2}{\rho} \quad \text{fringe field kick close to axis}$$

cartesian close to axis $\mathbf{B}(x, y, z) = (x B_{\rho\text{-over-}\rho}, y B_{\rho\text{-over-}\rho}, B_z)_{z-L/2}^{z+L/2}$

good for insight and solving equations of motion in real space coordinates

not needed for numerical evaluation, very fast to evaluate exact formulas or later to use measured field map

Example **no tilt single L = 1m solenoid, R = 0.1 m, 2 T,**
 Jacobian from tracking with small offsets
 done in 6D, numbers here just for the 4D part

s=0.5 solenoid entry

1	-0.5	-3.2196e-05	1.5952e-05
-1.5004e-07	1	-0.00327	0.0016026
3.2196e-05	-1.5952e-05	1	-0.5
0.00327	-0.0016026	-1.5004e-07	1

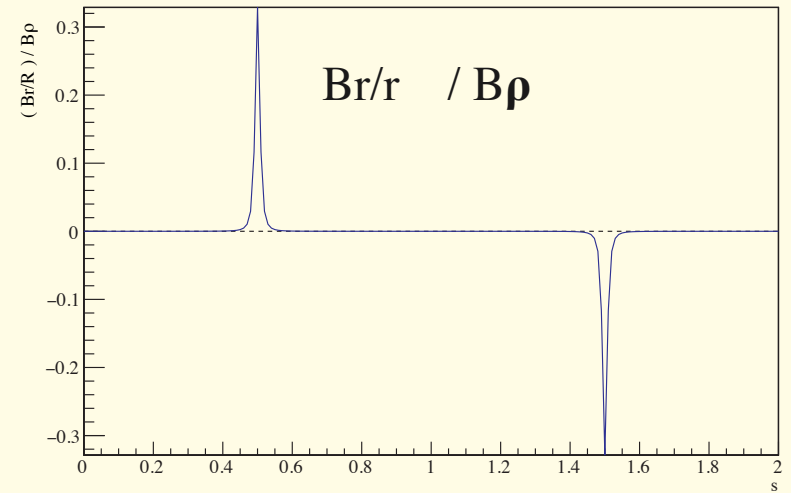
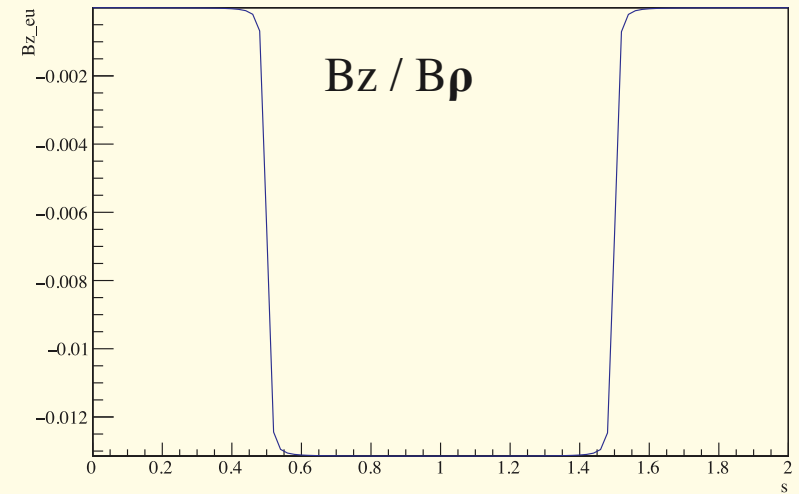
s=1 solenoid center

0.99999	1.7235e-06	-0.0032864	-5.8978e-07
-4.2867e-05	1	-0.0065724	-0.0032869
0.0032864	5.8978e-07	0.99999	1.7235e-06
0.0065724	0.0032869	-4.2867e-05	1

s=2 0.5 meter from solenoid back symplectic

0.99994	0.99998	-0.0065725	-0.0065751
-4.2547e-05	0.99998	2.794e-07	-0.0065751
0.0065725	0.0065751	0.99994	0.99998
-2.794e-07	0.0065751	-4.2547e-05	0.99998

always det = 1



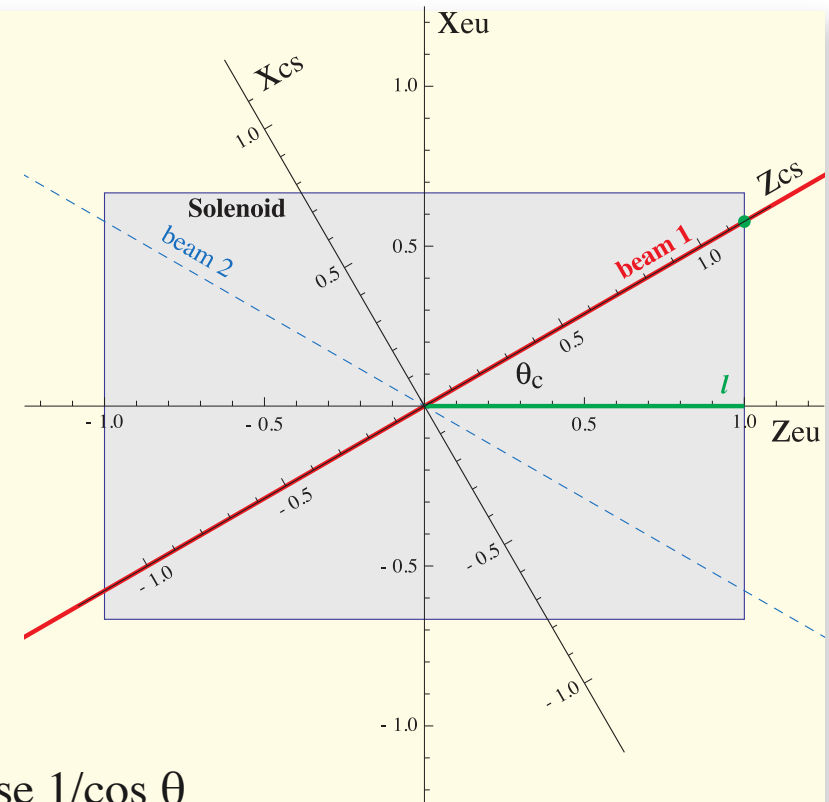
possible to read these into MAD-X and use with option, sympl=false; consequences with SR and emit would need reconsideration, maybe not such a good idea for an overall small effect ?

Of some interest for other applications where SR not essential like solenoid focusing at low energy ?

Illustrated for $\theta_c = \pi/6 = 30^\circ$

$$\text{Rot}_{y,3D}(\theta_c) = \begin{bmatrix} \cos(\theta_c) & 0 & \sin(\theta_c) \\ 0 & 1 & 0 \\ -\sin(\theta_c) & 0 & \cos(\theta_c) \end{bmatrix}$$

$$\mathbf{x}_{cs} = \begin{bmatrix} x_{cs} \\ y_{cs} \\ z_{cs} \end{bmatrix} \quad \mathbf{x}_{eu} = \text{Rot}_{y,3D}(\theta_c) \mathbf{x}_{cs} = \begin{bmatrix} x_{cs} \cos(\theta_c) + z_{cs} \sin(\theta_c) \\ y_{cs} \\ -x_{cs} \sin(\theta_c) + z_{cs} \cos(\theta_c) \end{bmatrix}$$



eu : detector system, solenoid axis z_{eu}

cs : beam reference system, solenoid rotated, length increase $1/\cos \theta$

FCC-ee : beam divergence $\sim 40 \mu\text{rad}$ small compared to (half) crossing angle $\theta_c = 15 \text{ mrad}$

fields seen and main effects of tilted solenoid similar for all beam particles

possible to approximate rather well using MAD-X with

- 1) orbit correctors reproducing the design particle trajectory determined with tracking
- 2) slices of on axis-solenoid aligned to design particle track (work in progress)

Using [MDISim](#) ([GEANT4](#), geometry automatically generated from MAD-X, display with ROOT)

hitting beam pipe in first downstream bend BC1

~ 49 - 55 m from IP

