Lecture 18 Radiofrequency Cavities II

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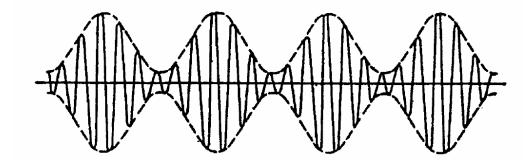


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Group Velocity

- Energy (and information) travel with wave group velocity.
- Interference of two continuous waves of slightly different frequencies described by:



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E = E_0 \sin \left[ (k + dk)x - (\omega + d\omega)t \right] + E_0 \sin \left[ (k - dk)x - (\omega - d\omega)t \right]
= E_0 \sin \left[ kx - \omega t \right] \cos \left[ dk \ x - d\omega \ t \right]
= 2E_0 f_1(x, t) f_2(x, t)
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Group Velocity

Mean wavenumber & frequency represented by continuous wave

$$f_1(x,t) = \sin\left[kx - \omega t\right]$$

- □ Any given phase in this wave is propagated such that kx ωt remains constant.
- Phase velocity of wave is thus

$$v_p = -\frac{\partial f_1(x,t)/\partial t}{\partial f_1(x,t)/\partial x} = \frac{\omega}{k}$$

Envelope of pattern described by

$$f_2(x,t) = \cos[dkx - d\omega t]$$

□ Any point in the envelope propagates such that x dt - t dω remains constant and its velocity, i.e. group velocity, is

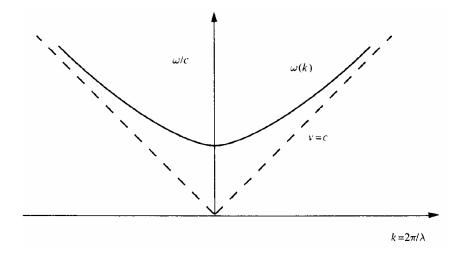
$$v_g = -\frac{\partial f_2(x,t)/\partial t}{\partial f_2(x,t)/\partial x} = \frac{d\omega}{dk}$$

Dispersion Diagramme for Waveguide

- Description of wave propagation down a waveguide by plotting graph of frequency, ω, against wavenumber, k = 2π/λ
 - Imagine experiment in which signals of different frequencies are injected down a waveguide and the wavelength of the modes transmitted are measured.
- Measurables
 - □ Phase velocity for given frequency: ω/k
 - ☐ Group velocity: slope of tangent

Dispersion Diagramme for Waveguide

- Observations
 - However small the *k*, the frequency is always greater than the cut-off frequency.
 - The longer the wavelength or lower the frequency, the slower is the group velocity.
 - At cut-off frequency, no energy flows along the waveguide.
 - \square Also $v_{ph}v_g = c^2$



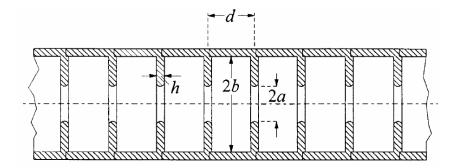
Dispersion diagramme for waveguide is the hyperbola

$$\left(\frac{\omega}{c}\right)^2 = k^2 + \left(\frac{\omega_c}{c}\right)^2$$

Iris-loaded Structures

- Acceleration in a waveguide is not possible as the phase velocity of the wave exceeds that of light.
 - Particles, which are travelling slower, undergo acceleration from the passing wave for half the period but then experience an equal deceleration.
 - Averaged over long time interval results in no net transfer of energy to the particles.

- •Need to modify waveguide to reduce phase velocity to match that of the particle (less than speed of light).
- •Install iris-shaped screens with a constant separation in the waveguide.

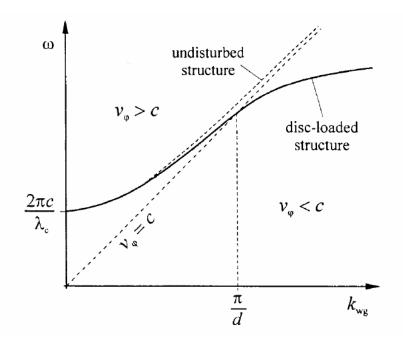


Iris-loaded Structures

 Recall that the dispersion relation in a waveguide is

$$\omega = c_{\sqrt{k_z^2 + \left(\frac{2\pi}{\lambda_c}\right)^2}}$$

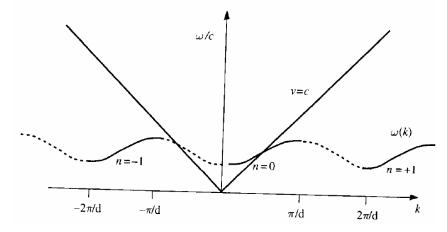
With the installation of irises, curve flattens off and crosses boundary at v_φ=c at k_z=π/2



With suitable choice of iris separation *d* the phase velocity can be set to any value

Iris-loaded Structures

- Waveguides cannot be used for sustained acceleration as all points on dispersion curve lie above diagonal in dispersion diagramme.
 - ☐ Phase velocity > *c*
- An iris-loaded structure slows down the phase velocity.



Dispersion diagramme for a loaded waveguide

The *k*-value for each space harmonic is

$$k_n = k_0 + \frac{2n\pi}{d}$$

By choosing any frequency in dispersion diagramme it will intercept dispersion curve at k values spaced by $2n\pi/d$

First rising slope used for acceleration.

Resonant Cavities

General solution of wave equation

$$W(r,t) = Ae^{i(\omega t + k \bullet r)} + Be^{i(\omega t - k \bullet r)}$$

- Describes sum of two waves one moving in one direction and another in opposite direction
- If wave is totally reflected at surface then both amplitudes are the same, A=B, and

$$W(r,t) = Ae^{i\omega t}(e^{ik \cdot r} + e^{-ik \cdot r})$$
$$= 2A\cos(k \cdot r)e^{i\omega t}$$

□ Describes field configuration which has a static amplitude $2A\cos(k \cdot r)$, i.e. a standing wave.

Resonant Cavities

- Resonant Wavelengths
 - Stable standing wave forms in fully-closed cavity if

$$l = q \frac{\lambda_z}{2} \quad with \quad q = 0, 1, 2, \dots$$

- where I = distance between entrance and exit of waveguide after being closed off by two perpendicular sheets.
- \rightarrow only certain well-defined wavelengths λ_r are present in the cavity.
- General resonant condition $\frac{1}{\lambda_r^2} = \frac{1}{\lambda_c^2} + \frac{1}{4} \left(\frac{q}{l} \right)^2$
- Near the resonant wavelength, resonant cavity behaves like electrical oscillator but with much higher Q-value and corresponding lower losses of resonators made of individual coils and capacitors.
 - Exploited to generate high-accelerating voltages

Rectangular Resonant Cavities

Inserting

$$\left(\frac{2}{\lambda_c}\right)^2 = \left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2$$

into the resonance condition yields

$$\lambda_r = \frac{2}{\sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2 + \left(\frac{q}{l}\right)^2}} \quad with \quad m, n, q = \text{int } egers$$

- Integers m,n,and q define modes in resonant cavity.
 - Number of modes is unlimited but only a few of them used in practical situations.
 - m, n, and q between 0 and 2

Cylindrical Resonant Cavities

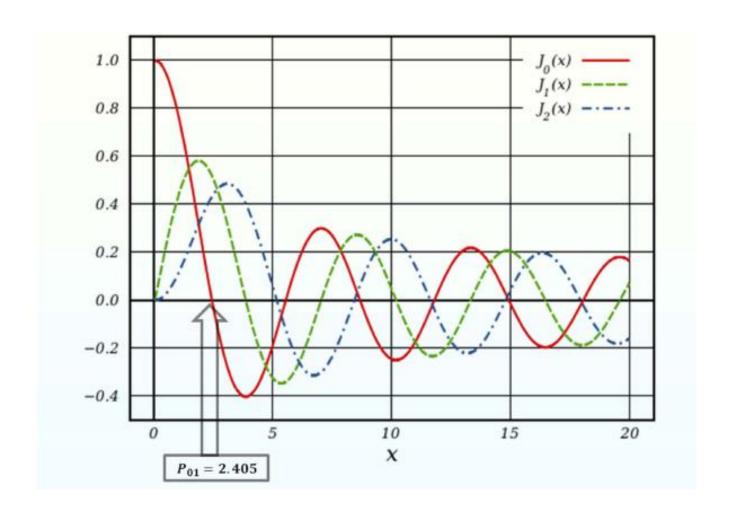
 Inserting the expression for cut-off frequency into general resonance condition yields

$$\frac{1}{\lambda_r^2} = \left(\frac{x_1}{\pi D}\right)^2 + \frac{1}{4} \left(\frac{q}{l}\right)^2 \quad with \quad q = 0,1,2,\dots$$

- where x_1 =2.0483 is the first zero of the Bessel function.
- For the case of q=0, termed the TM₀₁₀ mode, the resonant wavelength reduces to

$$\lambda_r = \frac{\pi D}{x_1}$$

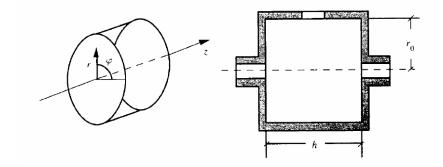
Bessel Functions

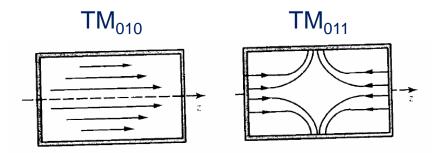


Pill-box Cylindrical Cavity

- ☐ The simplest RF cavity type
- \Box The accelerating modes of this cavity are TM_{olm}
- Indices refer to the polar co-ordinates φ, r and z

Cylindrical pill-box cavity with holes for beam and coupler.





Lines of force for the electrical field.

Pill-box Cylindrical Cavity

The modes with no φ variation are:

$$\begin{split} &\nabla^{2}E + \Lambda^{2}E = 0 \\ &\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial E}{\partial r}\right) + \frac{1}{r^{2}}\frac{\partial E}{\partial r} + \frac{\partial^{2}E}{\partial z^{2}} + \Lambda^{2}E = 0 \\ &E_{z} = E_{0}J_{0}\left(\frac{P_{0l}}{r_{0}}r\right)\cos\left(\frac{m\pi}{h}z\right) \\ &E_{r} = E_{0}\frac{m\pi}{P_{0l}}\frac{r_{0}}{h}J_{1}\left(\frac{P_{0l}}{r_{0}}r\right)\sin\left(\frac{m\pi}{h}z\right) \\ &\Lambda^{2}_{0lm} = \left(\frac{P_{0l}}{r_{0}}\right)^{2} + \left(\frac{m\pi}{h}\right)^{2} \end{split}$$

- Indicates the radial variation while m controls the number of wavelengths in the z-direction.
- P₀₁ is the argument of the Bessel function when it crosses zero for the *lth* time.

$$J_0(P_{0l}) = 0$$
 for $P_{0l} = 2.405$

Pill-box Cylindrical Cavity

TM₀₁₀ Mode

$$E = E_0 J_0 \left(\frac{2.405}{r_0} r \right); \quad \Lambda_{010} = \frac{2.405}{r_0}; \quad \omega_{010} = \frac{\Lambda_{010}}{\sqrt{\varepsilon \mu}};$$

$$\nu_{010} = \frac{\omega_{010}}{2\pi}; \quad \lambda_{010} = \frac{1}{\nu_{010} \sqrt{\varepsilon \mu}}$$

 Ratio of stored energy to energy dissipated per cycle divided by 2π

$$Q = \frac{W_s}{W_d} = \omega \frac{W_s}{P_d}$$

 W_s = stored energy in cavity W_d = energy dissipated per cycle divided by 2π P_d = power dissipated in cavity walls ω = frequency

Stored energy over cavity volume is

$$W_{s} = \frac{\mathcal{E}_{0}}{2} \int \left| E \right|^{2} dv \qquad W_{s} = \frac{\mu_{0}}{2} \int \left| H \right|^{2} dv$$

where the first integral applies to the time the energy is stored in the *E*-field and the second integral as it oscillates back into the *H*-field.

- Losses on cavity walls are introduced by taking into account the finite conductivity σ of the walls.
- Since, for a perfect conductor, the linear density of the current j along walls of structure is

$$j = n \times H$$

we can write

$$P_d = \frac{R_{surf}}{2} \int_s |H|^2 ds$$
 with s = inner surface of conductor

 R_{surf} = surface resistance δ = skin depth

$$\mathbf{R}_{surf} = \sqrt{\frac{\pi f \, \mu_0 \mu_{\tau}}{\sigma}} = \frac{1}{\sigma \delta}$$

For Cu,
$$R_{surf} = 2.61 \times 10^{-7} \sqrt{\omega} \Omega$$

Shunt Impedance - R_s

- Figure of merit for an accelerating cavity
 - Relates accelerating voltage to the power P_d to be provided to balance the dissipation in the walls.
- Voltage along path followed by beam in electric field E₂ is

$$V = \int_{path} |E_z(x,y,z)| dI$$

from which (peak-to-peak)

$$R_s = \frac{V^2}{2P_d}$$

Shunt Impedance - R_s

$$R_{s} = 5.12 \times 10^{8} \frac{\beta_{z} (1 - \eta)^{2}}{p + 2.61 \beta_{z} (1 - \eta)} \left(\frac{\sin D/2}{D/2} \right)^{2}$$

with

$$\beta_z \equiv \frac{v_{\varphi}}{c}$$
 (phase velocity)

$$\eta \equiv \frac{h}{d}$$
 (h = thickness, d = iris separation)

 $p \equiv$ number of irises per wavelength (equal to mode number)

$$D \equiv \frac{2\pi}{p} \left(1 - \eta \right)$$

Energy Gain

Energy gain of particle as it travels a distance through linac structure depends only on potential difference crossed by particle:

$$U = K \sqrt{P_{RF} l R_s}$$

where

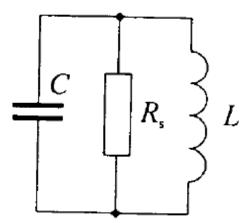
 $P_{RF} \equiv \text{supplied RF power}$
 $l \equiv \text{length of linac structure}$
 $R_s \equiv \text{shunt impedance}$
 $K \equiv \text{correction factor} (\approx 0.8)$

Analogous to Electrical Oscillator

Cavity behaves as an electrical oscillator but with very high quality factor (sharp resonance)

$$Q = \frac{\omega_r}{\Delta \omega} = \frac{R_s}{Z}$$

 ω_r resonant frequency $\Delta \omega$ = frequency shift at which amplitude is reduced by -3 dB relative to resonance peak



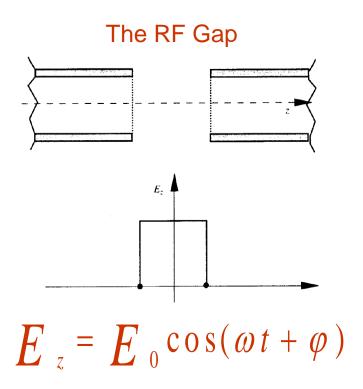
Electrical response of cavity described by parallel circuit containing C, L, and R_s

On resonance the impedance is

$$Z = \omega L = \frac{1}{\omega C}$$

Transit-Time Factor

- Accelerating gap
 - □ Space between drift tubes in linac structure
 - Space between entrance and exit orifices of cavity resonator
- Field is varying as the particle traverses the gap
 - Makes cavity less efficient and resultant energy gain which is only a fraction of the peak voltage



Field is uniform along gap axis and depends sinusoidally on time

Phase ϕ refers to particle in middle of gap z=0 at t=0

Transit-Time Factor

- Transit-Time Factor is ratio of energy actually given to a particle passing the cavity centre at peak field to the energy that would be received if the field were constant with time at its peak value
- The energy gained over the gap G is:

$$V = \int_{-G/2}^{+G/2} E_0 \cos(\omega t + \varphi) dz = \frac{\sin(\omega G/2\beta c)}{\omega G/2\beta c} (E_0 G \cos \varphi)$$

Transit-Time Factor

The Transit Gap Factor is defined as

Transit Gap Factor
$$\Gamma \equiv \frac{\sin(\omega G/2\beta c)}{\omega G/2\beta c}$$

Defining a transit angle

Transit Angle
$$\equiv \theta = \omega G / \beta c = 2\pi G / \beta \lambda$$

the Transit Gap Factor becomes

$$\Gamma = \frac{\sin \theta/2}{\theta/2} \quad \text{with } 0 < \theta < 1$$

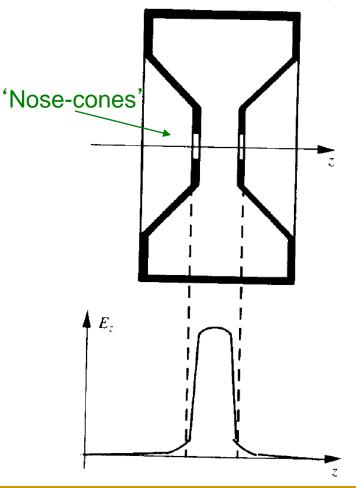
The Transit-Time Factor

- Observations
 - \square At relativistic energies, cavity dimensions are comparable with $\lambda/2$
 - Reduction in efficiency due to transit-time factor is acceptable.
- ☐ At low energies, this is not the case
 - □ Cavities have strange re-entrant configuration to keep G short compared to dimensions of its resonant volume.

The Transit-Time Factor

- Compromise cavity design
 - Increasing ratio of volume/surface area
 - Reduces ohmic losses
 - Increases Q factor
 - Minimise gap factor

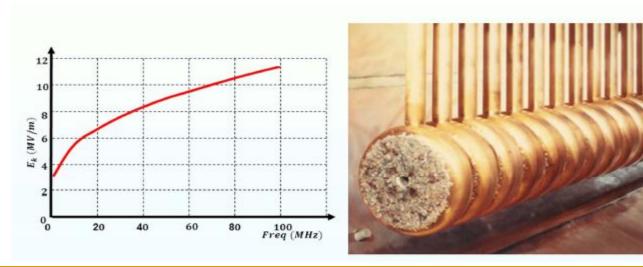
Field in resonant cavity



Kilpatrick Limit

- RF breakdown observed at very high fields.
- Kilpatrick Limit expresses empirical relation between accelerating frequency and E-field

•
$$f = 1.64E_k^2 e^{-8.5/E_k}$$



Software for Cavity Design

- Poisson and Superfish are the main solver programs in a collection of programs from LANL for calculating static magnetic and electric fields and radio-frequency electromagnetic fields in either 2-D Cartesian coordinates or axially symmetric cylindrical coordinates.
- Finite Element Method



Solvers:

- Automesh generates the mesh (always the first program to run)
- Fish RF solver
- Cfish version of Fish that uses complex variables for the rf fields, permittivity, and permeability.
- Poisson magnetostatic and electrostatic field solver
- Pandira another static field solver (can handle permanent magnets)
- SFO, SF7 postprocessing
- Autofish combines Automesh, Fish and SFO
- DTLfish, DTLCells, CCLfish, CCLcells, CDTfish, ELLCAV, MDTfish, RFQfish, SCCfish – for tuning specific cavity types.
- Kilpat, Force, WSFPlot, etc.
- http://laacg1.lanl.gov/laacg/services/download_sf.phtml

Structures usually solved by Finite Element Analysis