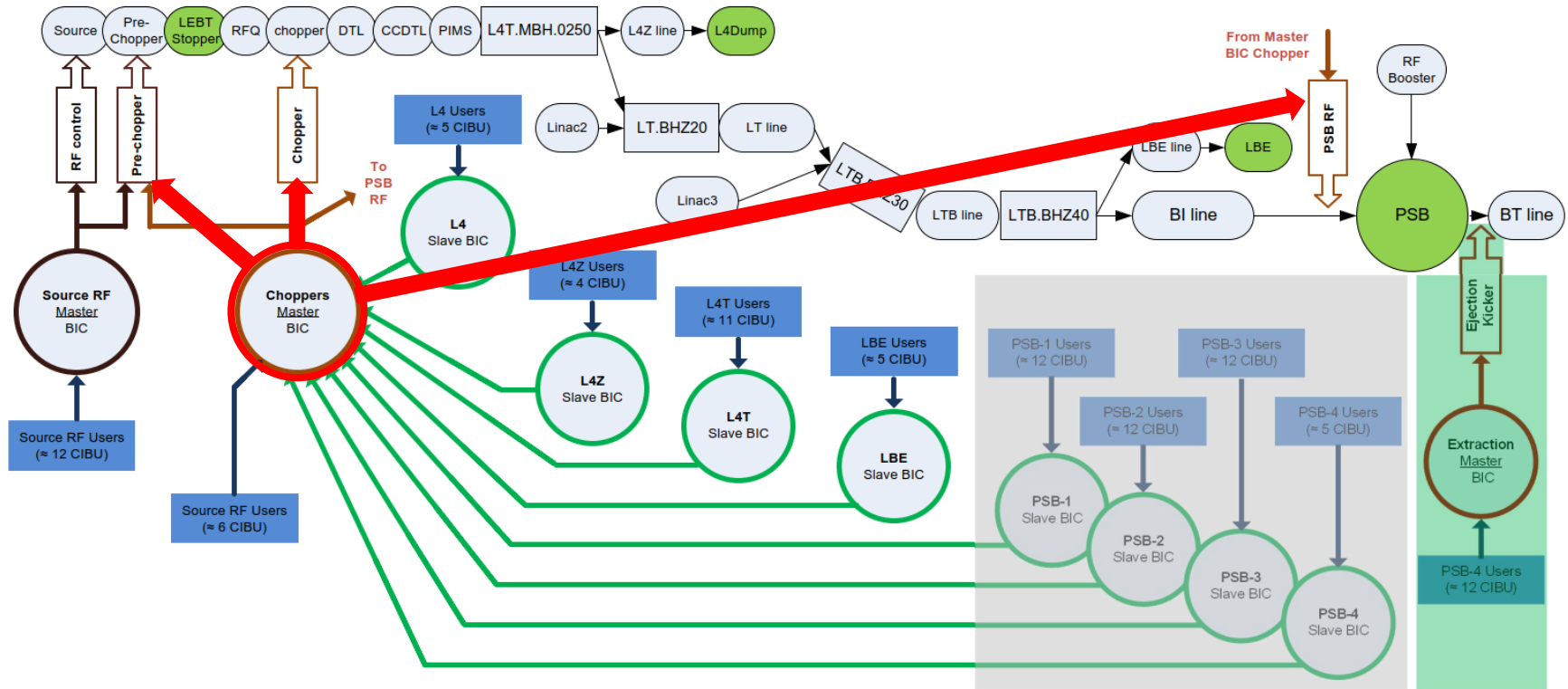


# Linac4 BIS modification

## Linac4 BIS layout before modification



In the original specification the Master Chopper BIC acts on 3 actuators :

- The Chopper as main actuator
- The Pre-chopper as first redundancy
- The PSB RF as second redundancy

The Beam Permit pulse length delivered by the Chopper Master BIC depends on the different User system connected to it:

Ch.	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	OUT	
Interlock Users	SIS	Source Beam Stoppers Out / Mov_CH	Source Beam Stoppers In_CH	Linac4 OK	AQN L4T.MBH_DUMP	L4Z OK	AQN L4T.MBH_LT	Linac4 Transfer OK	AQN L.TB.BHZ40_LBE	LBE OK	AQN L.TB.BHZ40_PSB	PSB 1 OK	PSB 2 OK	PSB 3 OK	PSB 4 OK	Choppers Master Beam_Permit	
Matrix Equation	1	0	1	x	x	x	x	x	x	x	x	x	x	x	x	1	Beam to Stoppers
	1	1	0	1	1	1	0	x	x	x	x	x	x	x	x	1	Beam to Dump
	1	1	0	1	0	x	1	1	1	1	0	x	x	x	x	1	Beam to LBE
	1	1	0	1	0	x	1	1	0	x	1	1	1	1	1	1	Beam to PSB

Figure 5 : Truth table of the 'Choppers' Master BIC.

## The same Beam Permit is delivered to all actuators

This Beam Permit has a typical duration of 600us (depending on the Linac4 configuration). The pulse duration is too short for the PSB RF actuator and is not synchronised on the PSB RF timing.

The RF electronic should have been modified to take into account this Beam Permit (extend the length, resynchronise on PSB RF ...)

As the PSB RF actuator is a "second" redundancy, it has been decided to not connect the Chopper Master BIC output to the PSB RF.

The BIS Linac4 engineering specification has been modified and is under approval (no ECR, just new version to be approved by involved experts)

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**Engineering Specification**

**BEAM INTERLOCK SYSTEM  
SPECIFICATIONS FOR LINAC4, TRANSFER  
LINES AND PS BOOSTER**

*Abstract*

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**History of Changes**

<b>Rev. No.</b>	<b>Date</b>	<b>Pages</b>	<b>Description of Changes</b>
2.2	13/08/2021	All	Removed BIS connection to the PS Booster RF actuator.