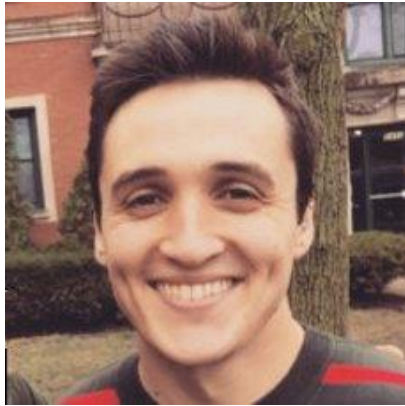


Truncated Marginal Neural Ratio Estimation

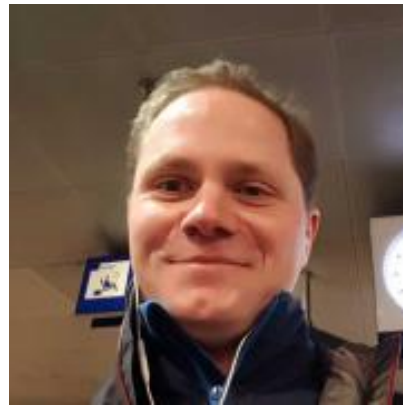
Empirically testable, simulation efficient & simulation-based posterior approximation.



Benjamin Kurt Miller



Alex Cole



Patrick Forré



Gilles Louppe



Christoph Weniger

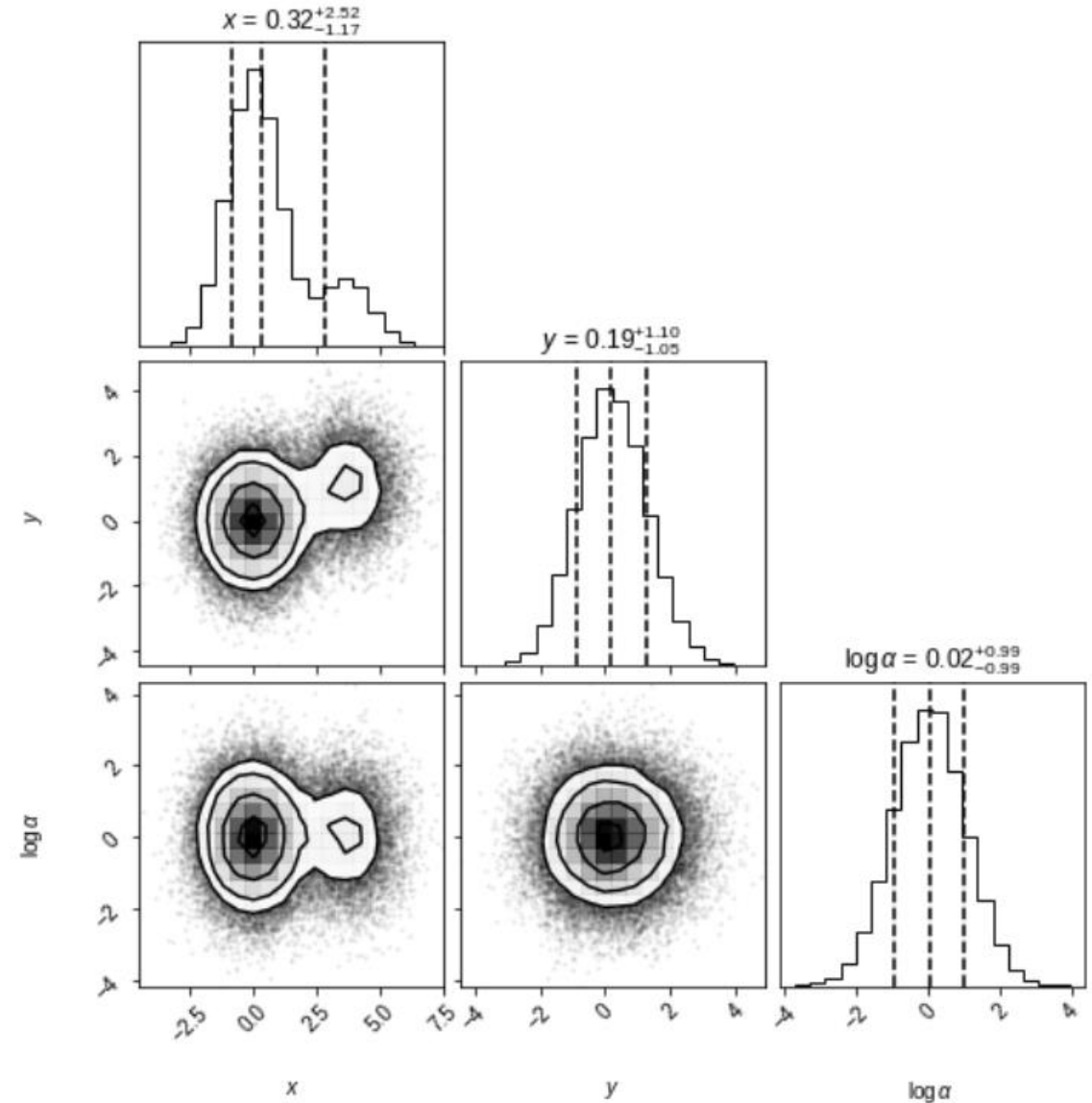
5th Inter-experiment Machine
Learning Workshop, CERN 2022



Marginal Inference

The posterior quantifies the uncertainty about parameters θ given data x .

$$p(\theta | x) = \frac{p(x | \theta)}{p(x)} p(\theta)$$



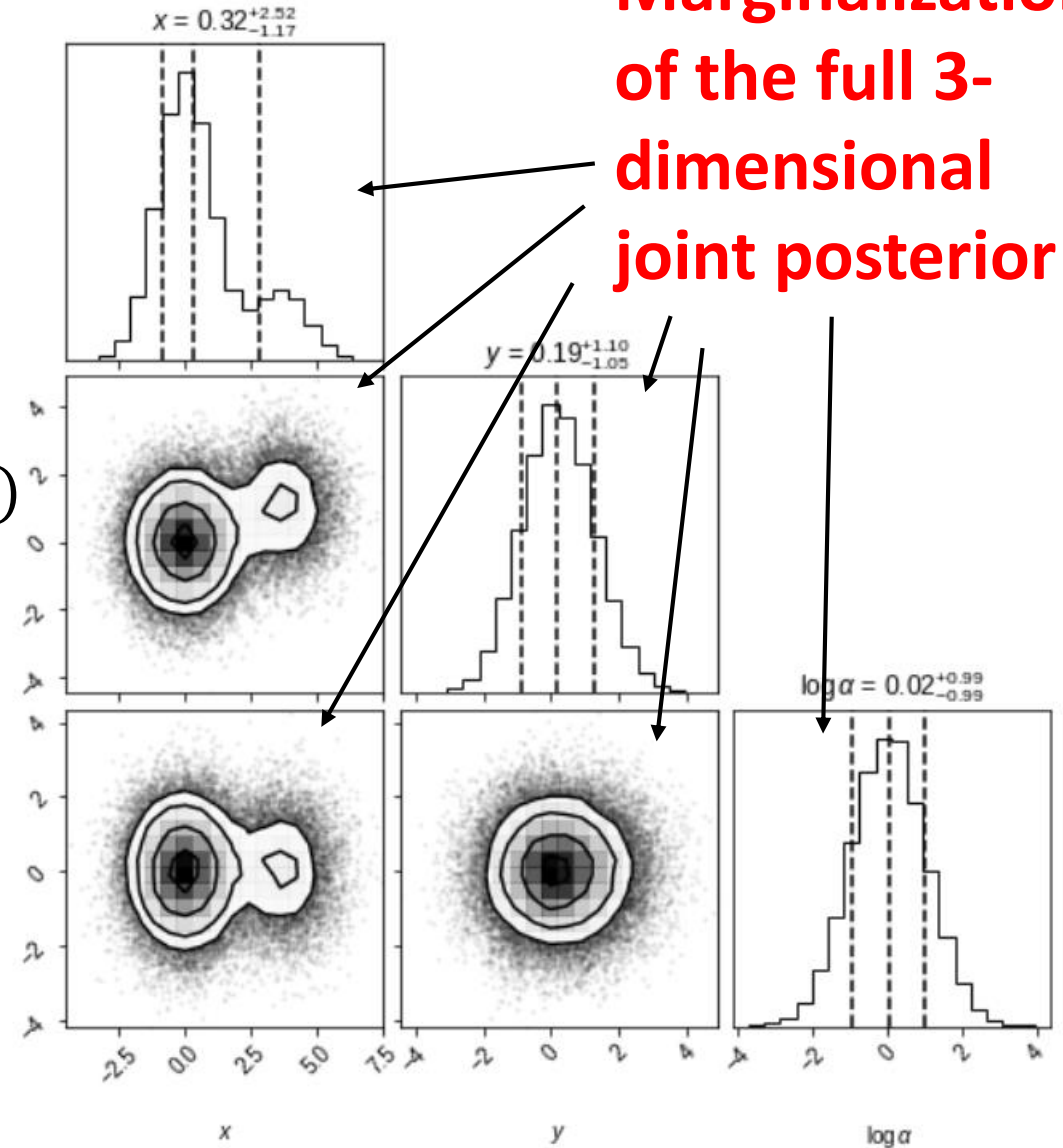
Marginal Inference

Marginal Inference: Estimate the marginal posteriors of interest directly.

$$p(\vartheta | x) = \frac{\int p(x | \vartheta, \eta) p(\vartheta, \eta) d\eta}{p(x)} = \frac{p(x | \vartheta)}{p(x)} p(\vartheta)$$

Also see: Justin Alsing and Benjamin Wandelt. Nuisance hardened data compression for fast likelihood-free inference. [arXiv:1903.01473](https://arxiv.org/abs/1903.01473)

Niall Jeffrey and Benjamin Wandelt. Solving high-dimensional parameter inference: . [arXiv: 2011.05991](https://arxiv.org/abs/2011.05991)



Neural Ratio Estimation

We train a classifier and extract a likelihood-to-evidence ratio...

The classifier distinguishes between samples drawn jointly vs marginally

$$p(x, \theta | y) = \begin{cases} p(x, \theta) & \text{if } y = 1 \\ p(x)p(\theta) & \text{if } y = 0 \end{cases}$$

The posterior for the “switching” variable y is

$$p(y = 1 | x, \theta) = \frac{p(x, \theta | y = 1)}{p(x, \theta | y = 0) + p(x, \theta | y = 1)} = \frac{p(x, \theta)}{p(x)p(\theta) + p(x, \theta)}$$

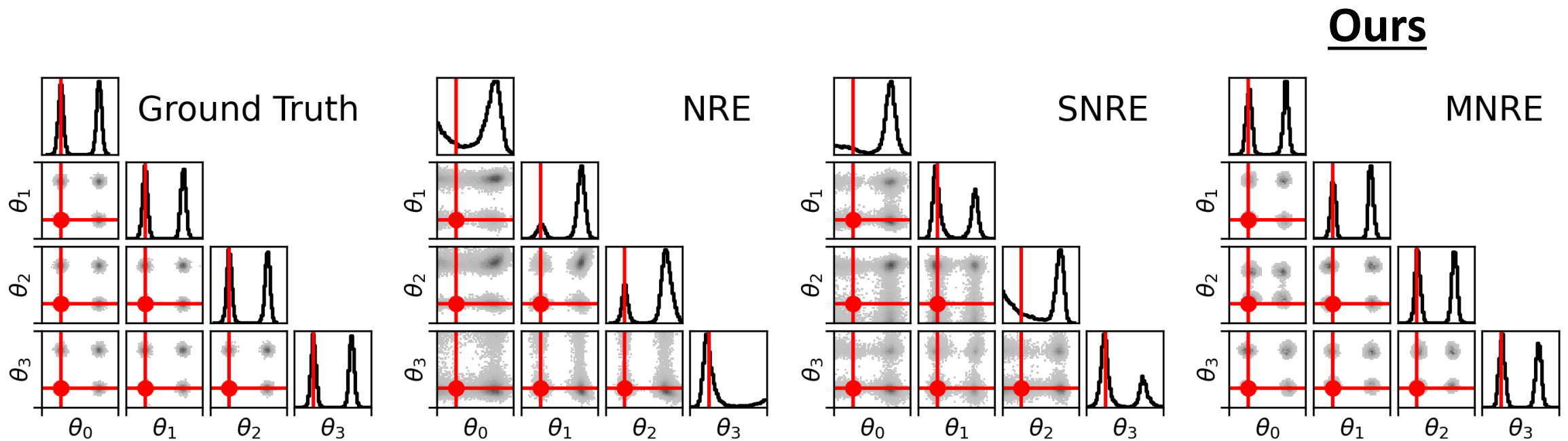
Let $r(x, \theta) = \frac{p(x, \theta | y=1)}{p(x, \theta | y=0)} = \frac{p(x, \theta)}{p(x)p(\theta)} = \frac{p(x | \theta)}{p(x)}$ i.e., the likelihood to evidence ratio.

That means $p(y = 1 | x, \theta) = \frac{r(x, \theta)}{r(x, \theta) + 1} = \sigma(\log r(x, \theta))$.

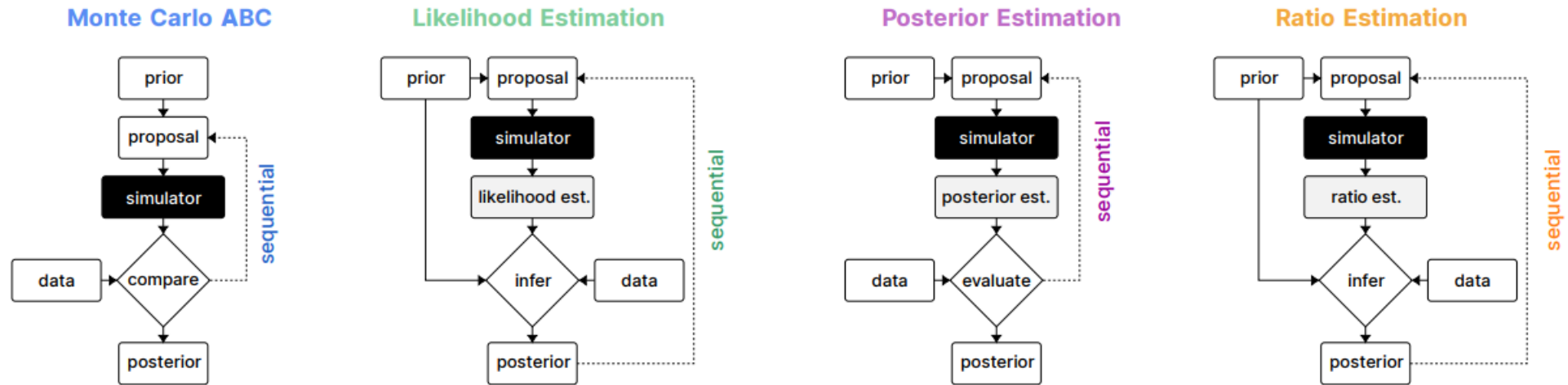
Eggbox: Is marginal ratio estimation simulation efficient?

10-dimensional, $2^{10} = 1024$ modes, 10,000 simulations.

Compare marginal estimation (MNRE) to joint estimations (NRE, SNRE).



Sidenote: what are amortized vs. sequential methods?



Jan-Matthis Lueckmann, et. al. Benchmarking Simulation-Based Inference.

<https://arxiv.org/abs/2101.04653>

```
README.md
```

pypi package 0.18.0 contributions welcome Tests passing codecov 77% license AGPL-3.0 JOSS 10.21105/joss.02505

sbi: simulation-based inference

[Getting Started](#) | [Documentation](#)

sbi is a PyTorch package for simulation-based inference. Simulation-based inference is the process of finding parameters of a simulator from observations.

sbi takes a Bayesian approach and returns a full posterior distribution over the parameters, conditional on the observations. This posterior can be amortized (i.e. useful for any observation) or focused (i.e. tailored to a particular observation), with different computational trade-offs.

<https://github.com/mackelab/sbi>

Truncated Marginal Neural Ratio Estimation

- Estimates marginal posteriors directly...
- Extends *Neural Ratio Estimation*, which estimates the likelihood-to-evidence ratio $\frac{p(x | \theta)}{p(x)}$ by training a classifier. Hermans, et. al. 2019. Likelihood-free MCMC with Amortized Approximate Ratio Estimators. [arXiv: 1903.04057](https://arxiv.org/abs/1903.04057).
- Truncates uninformative regions where $p(\theta | x_0) \approx 0$...
- Enables consistency checks through local amortization...

Hermans and Delaunoy, et. al. 2021. Averting A Crisis In Simulation-Based Inference. [arXiv: 2110.06581](https://arxiv.org/abs/2110.06581).

Truncated Bayesian Inference

Posteriors can be quite narrow compared to priors.

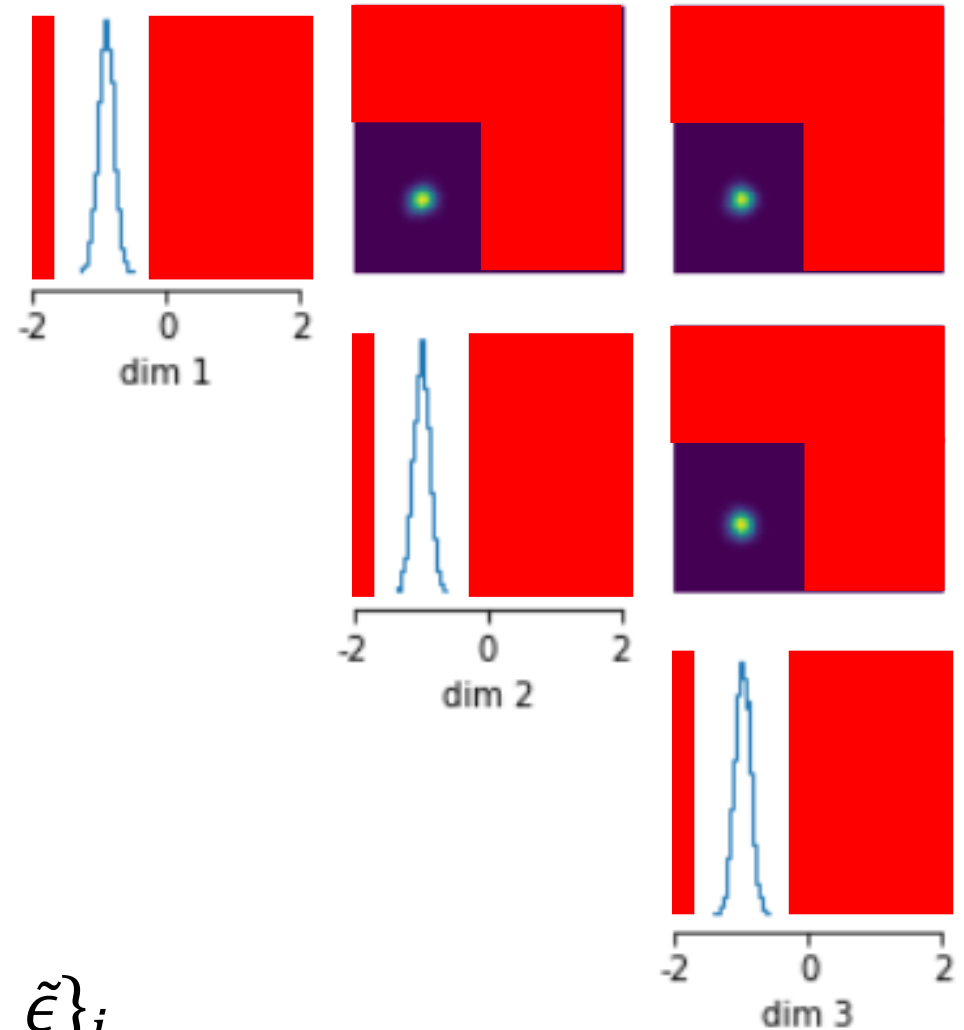
Truncated Inference: Sample only regions near the posterior mass.

“Ideal” truncated region?

$$\Gamma := \{\theta \in \text{supp } p(\theta) \mid p(\theta \mid x_o) > \epsilon\}$$

Our component-wise marginal estimate.

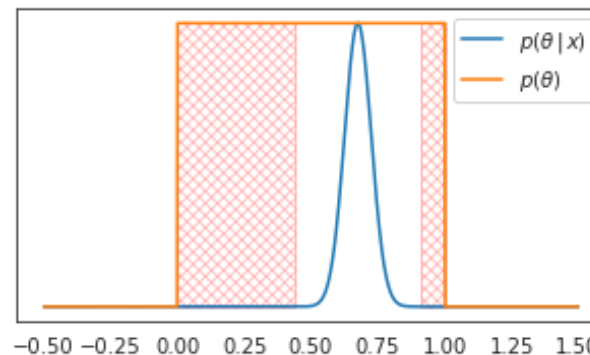
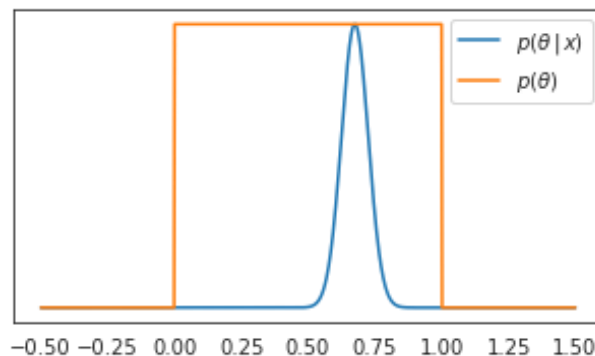
$$\Gamma_{rec,i} := \{\theta_i \in \text{supp } p_i(\theta_i) \mid \hat{p}(\theta_i \mid x_o) > \tilde{\epsilon}\}_i$$



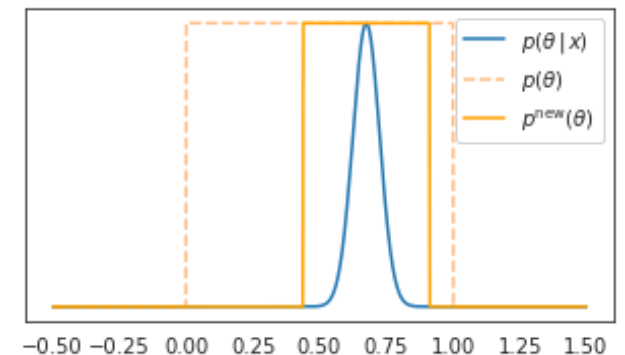
Sketch of truncation scheme

1. Sample from the joint $(\boldsymbol{x}, \boldsymbol{\theta}) \sim p(\boldsymbol{x} | \boldsymbol{\theta}) p(\boldsymbol{\theta})$.
2. Learn all component-wise likelihood-to-evidence ratios $\frac{p(\boldsymbol{x} | \boldsymbol{\vartheta}_i)}{p(\boldsymbol{x})}$.
3. Truncate prior $p(\boldsymbol{\theta}) \rightarrow p_{\Gamma_{rec}}(\boldsymbol{\theta})$ with $\Gamma_{rec,i} = \{\boldsymbol{\theta}_i \in \text{supp } p_i(\boldsymbol{\theta}_i) \mid \hat{p}(\boldsymbol{\theta}_i | \boldsymbol{x}_o) > \tilde{\epsilon}\}_i$.
4. Simulate more data $(\boldsymbol{x}, \boldsymbol{\theta}) \sim p(\boldsymbol{x} | \boldsymbol{\theta}) p_{\Gamma_{rec}}(\boldsymbol{\theta})$.
5. Repeat 2-4 until prior volume stabilizes.
6. Return truncated region Γ_{rec} , samples within, learn (marginal) posterior.

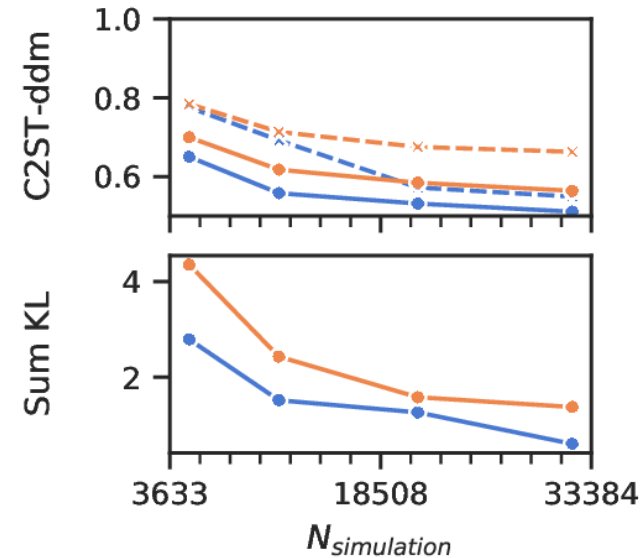
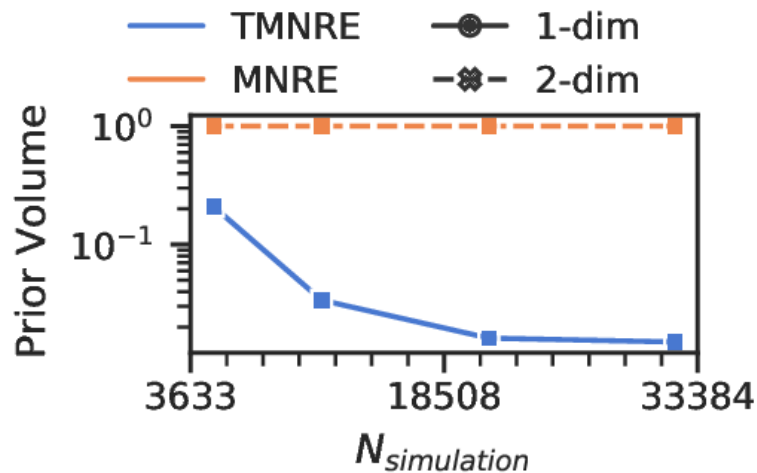
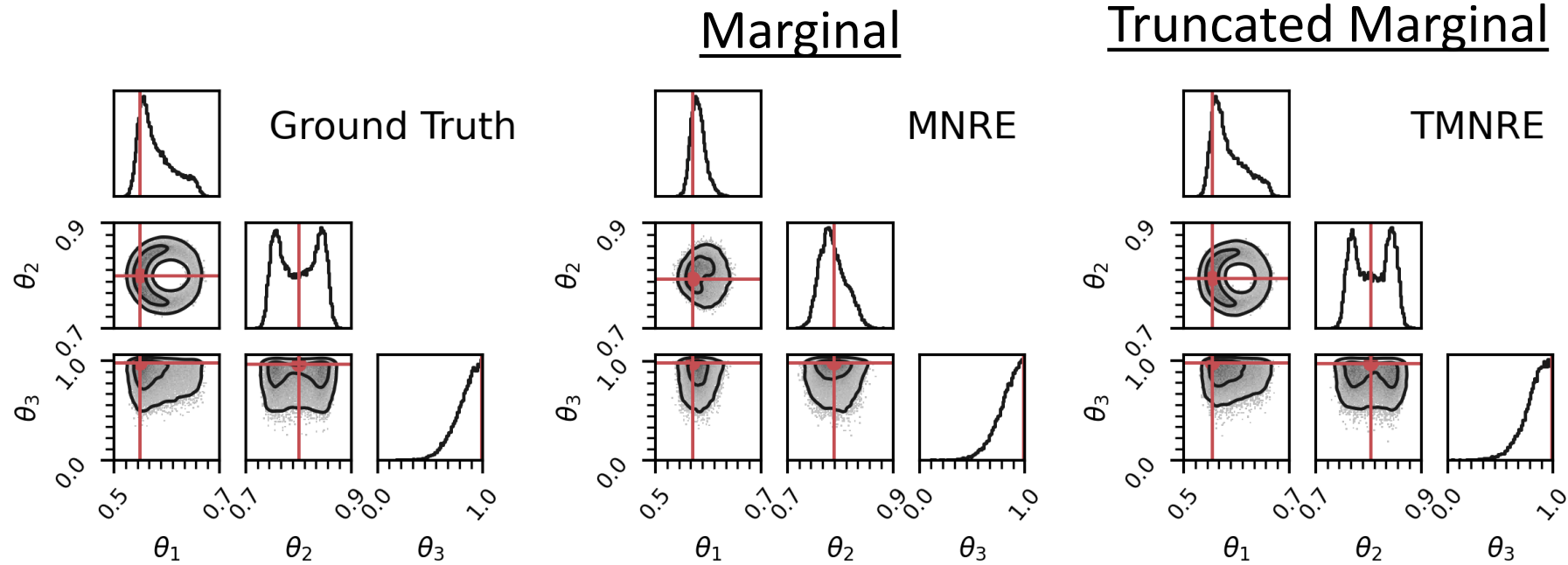
Truncation Visualization



In the image, $p^{new}(\theta)$ is not normalized



Torus: Is truncation with marginals efficient?

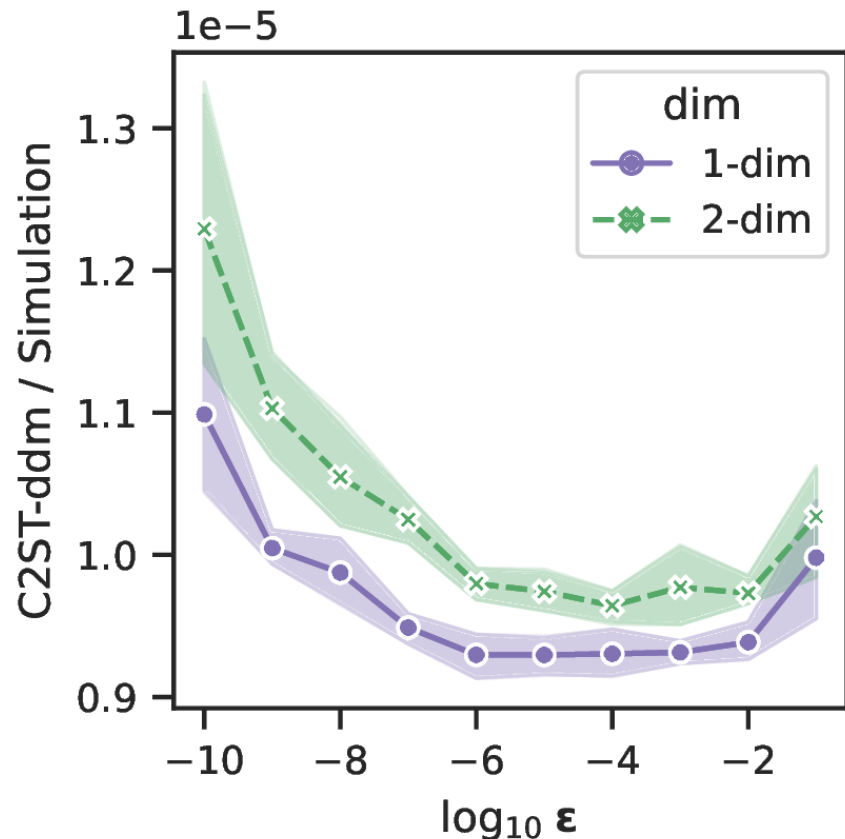


Classifier 2-Sample Test (C2ST)

Kullback-Leibler (KL) divergence.

Prior volume reduction

Torus: How did we select our cutoff?

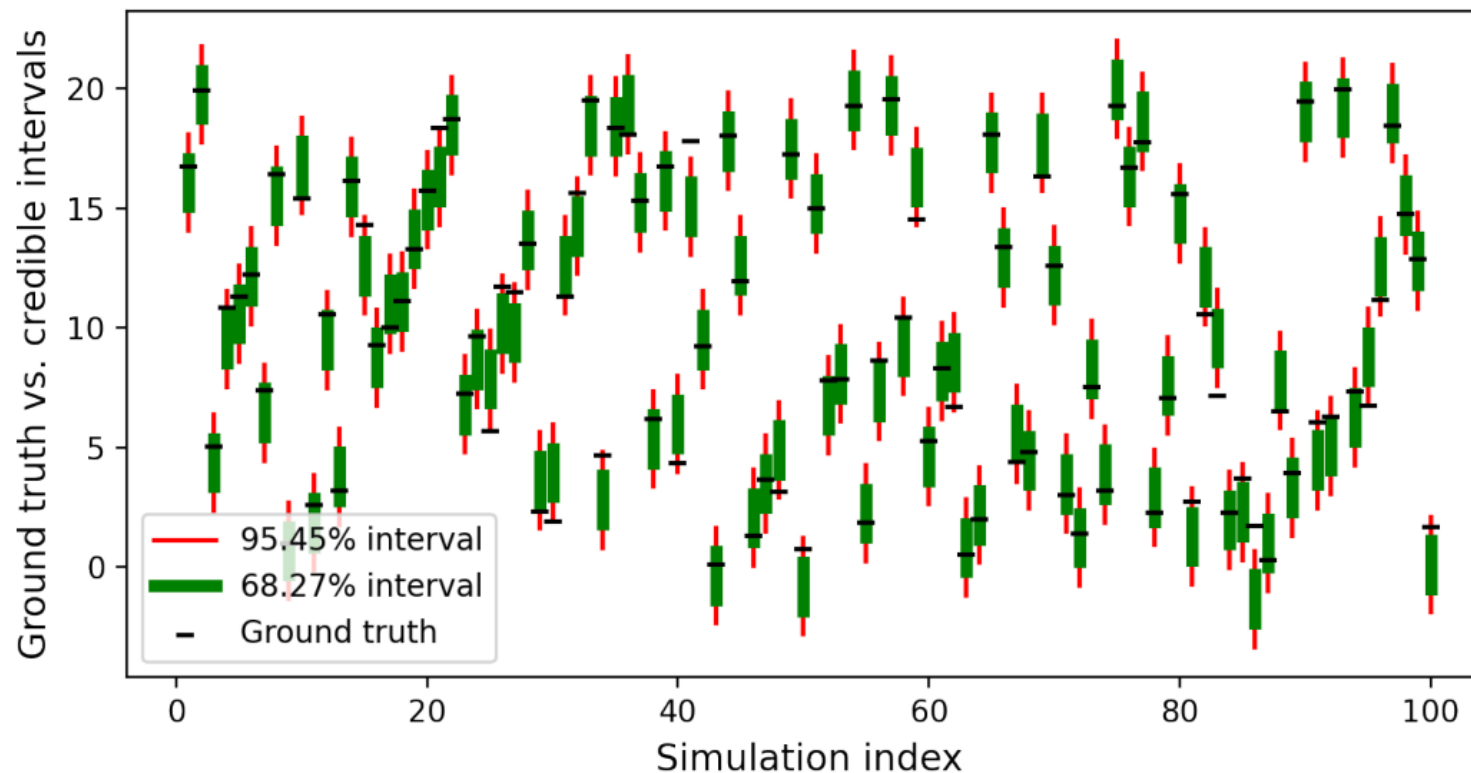


- Grid search on 10 values of the truncation cutoff ϵ .
- $\epsilon_0 = 10^{-6}$ conservatively minimized C2ST / simulation.
- Truncates a gaussian posterior at $\pm \sqrt{-2 \ln \epsilon_0} \sigma \approx 5.26 \sigma$. **Truncation affects only very-low probability credibility contours!**

Empirical tests with local amortization

How do we know we got the inference right
(when we don't have the truth)?

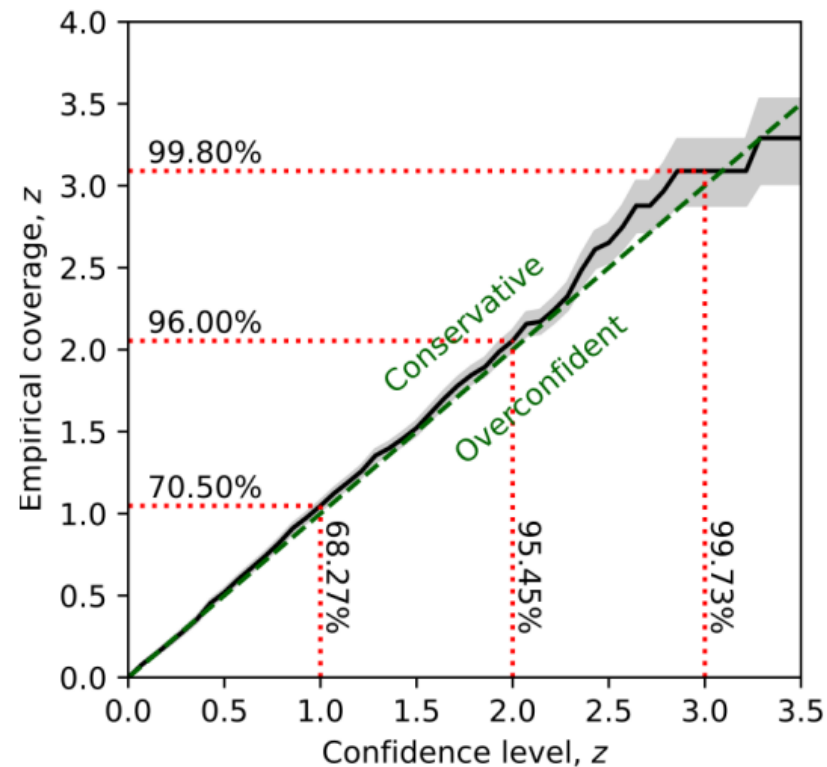
$$\text{Check } p(\theta) = E_{x \sim p(x)} [p(\theta | x)]!$$



Empirical tests with local amortization

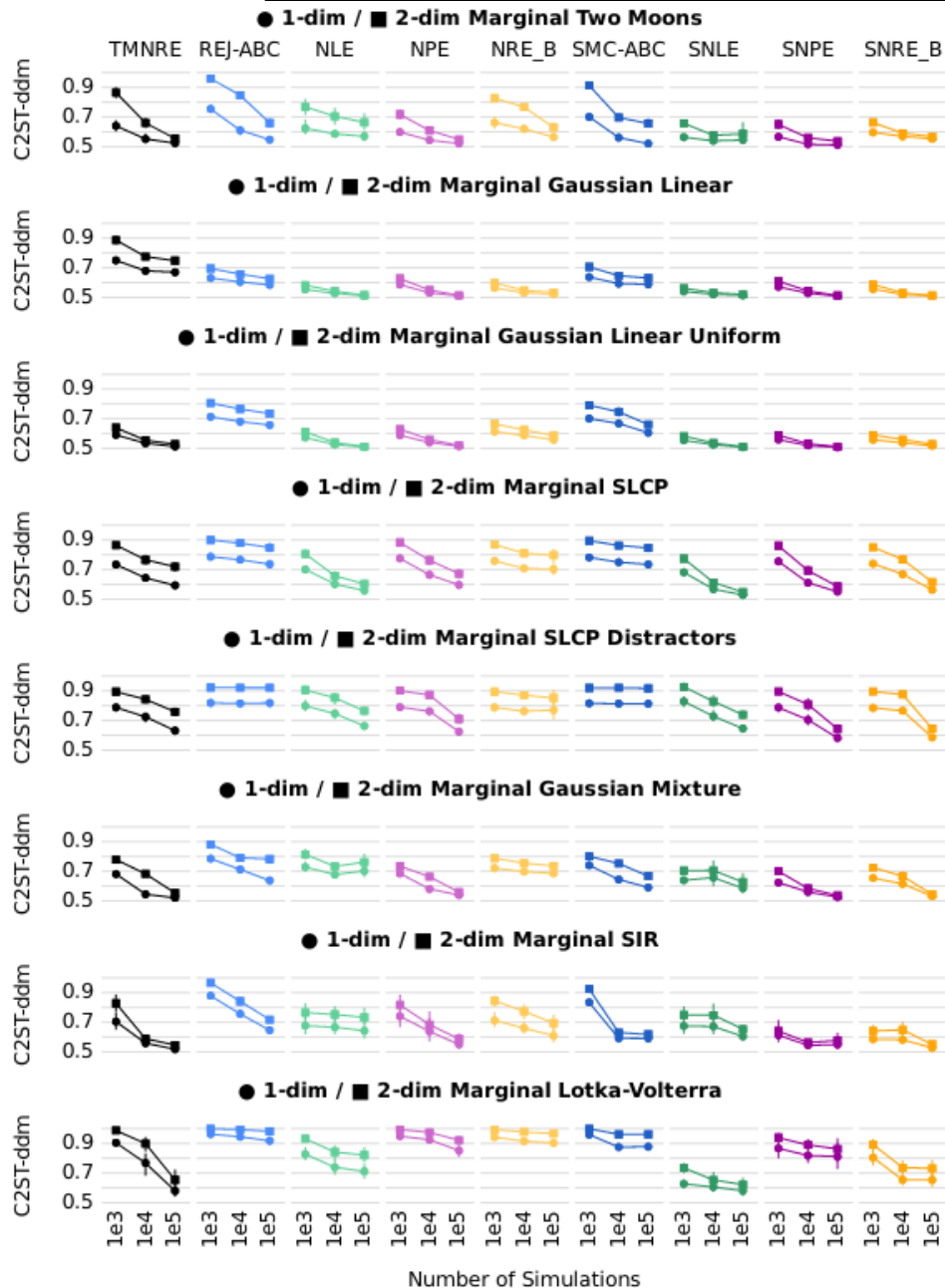
Simulation-based inference *constrains* parameters within compact regions using *credible intervals*.

(Local) amortization enables us to check whether nominal credibility is calibrated.



$$1 - \hat{\alpha} = \mathbb{E}_{p(\boldsymbol{\vartheta}, \mathbf{x})} [\mathbb{1} [\boldsymbol{\vartheta} \in \Theta_{\hat{p}(\boldsymbol{\vartheta}|\mathbf{x})}(1 - \alpha)]]$$

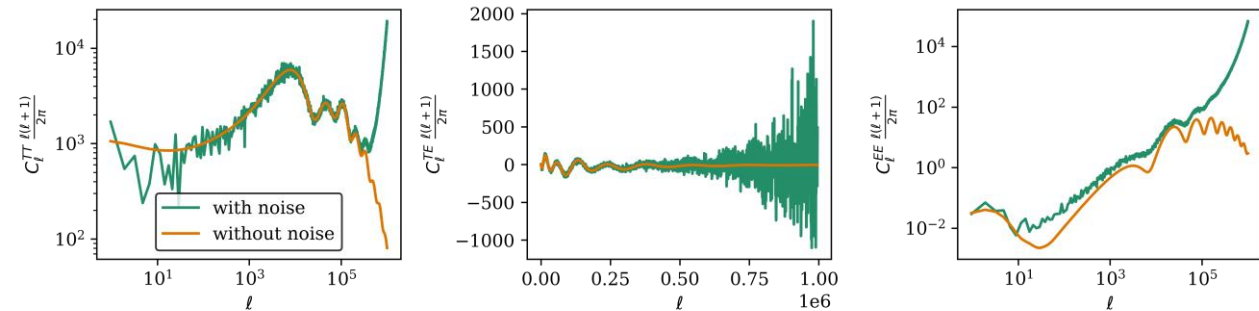
Simulation-based Inference Benchmark



- Tested TMNRE on modified *sbibm*.
- Other methods (not TMNRE) trained to learn $p(\vartheta, \eta \mid \mathcal{X})$. Results on marginalized posterior samples.
- Mean & 95% CI of Classifier 2-Sample Test (C2ST) for 10 simulated \mathcal{X}_0 .
- **TMNRE competitive results to sequential methods.**

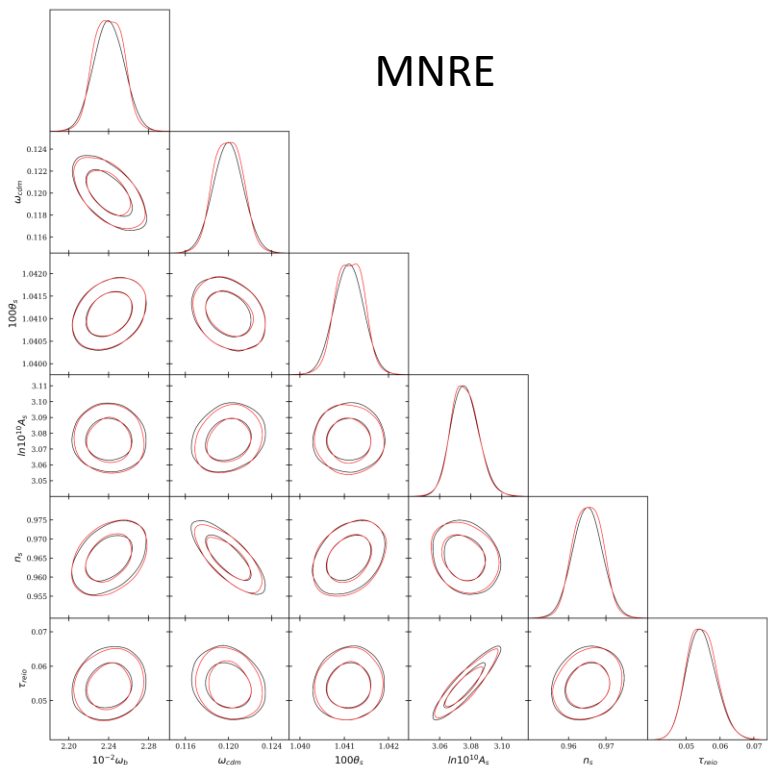
Cosmology

Cosmological Power Spectra Samples

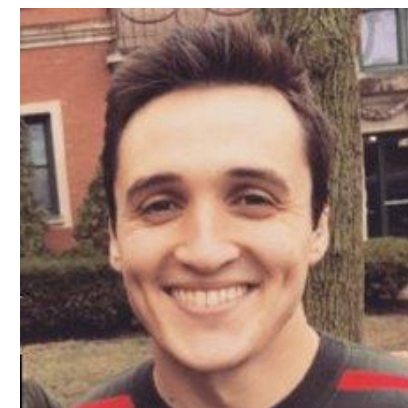
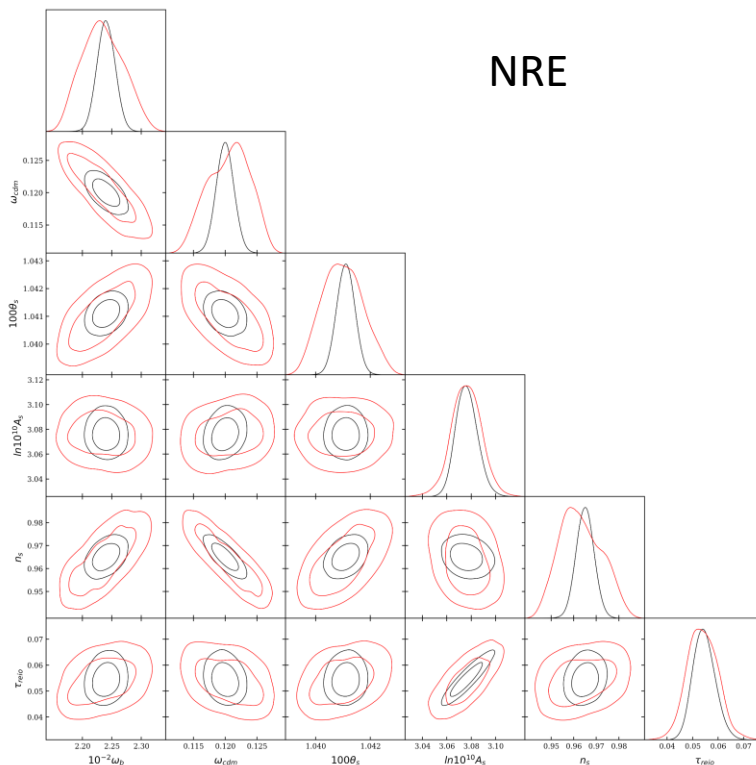


- Six parameters specify the lambda-CDM model.
- Data are power spectra (left) from the CMB.
- Simulator utilized to forecast the expected constraining power of future experiments.
- Budget of 5,000 simulations.

MNRE



NRE



See Alex Cole's presentation at 16:30!

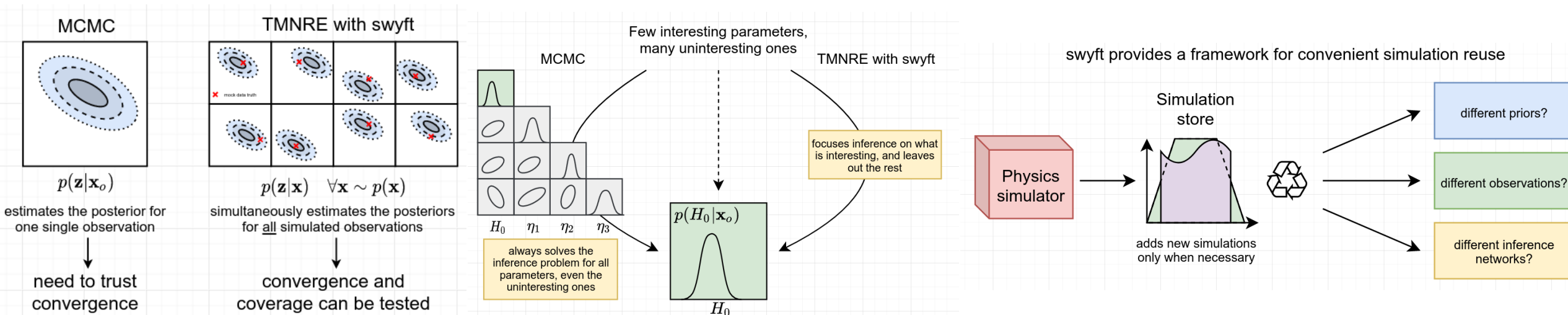
Conclusions

- Marginal Neural Ratio Estimation for *totally* amortized marginal inference.
- Proposed an iterative scheme (Truncated Marginal NRE) to focus on $p(\theta | x_0)$.
 - Increases simulation efficiency with truncation.
 - Enables empirical testing through *local* amortization.
 - **A method with both properties is unique.**

Packages:

swyft – implementation of method – <https://github.com/undark-lab/swyft>

tmnre – experimental results – <https://github.com/bkmi/tmnre>



Extra Slides

Hopefully, the answer to your question can be found in the next few slides...

Truncating the prior, based on the estimate posterior

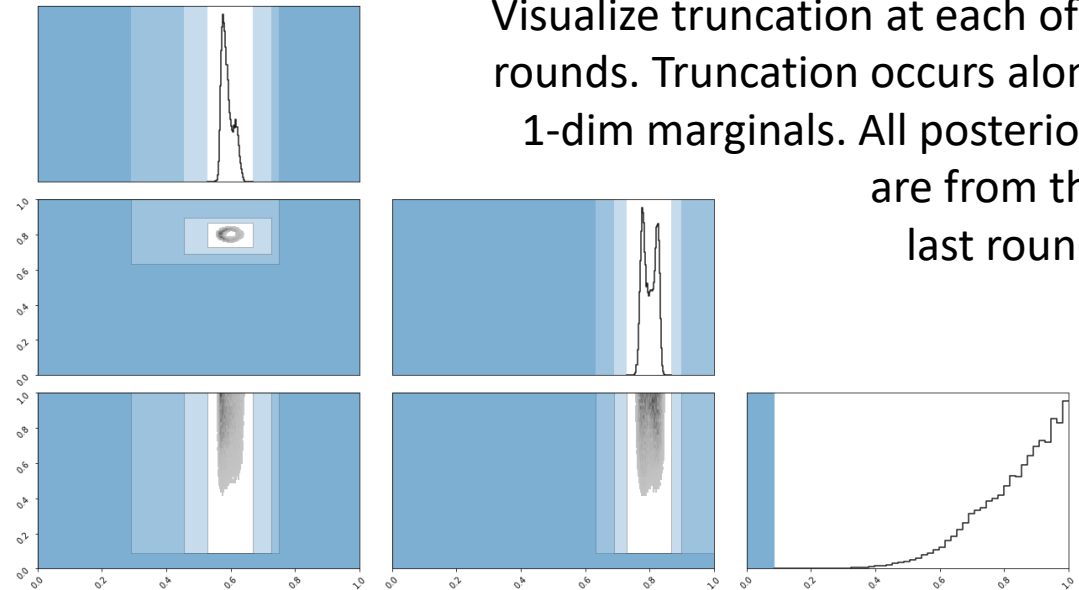
Why amortize the posterior when our focus is $p(\theta | x_o)$? --> Local amortization.

Determine region of interest: (*) $\Gamma = \{\theta \in \Omega \mid \forall d = 1, \dots, D: \frac{p(\theta_d | x_o)}{\max_{\theta_d} p(\theta_d | x_o)} > \delta\}$.

Discard parameters which lie outside this region (far tails).

Estimate Γ in a sequence of rounds:

1. Initialize $\Gamma^{(1)} = \Omega$.
2. Simulate data in $\Gamma^{(m)}$ & Train a ratio estimator on every 1-dim marginal.
3. Approximate (*) with the previous round's estimator and truncate.
4. Repeat until $\frac{\int 1_{\Gamma^{(m)}}(\theta)p(\theta)d\theta}{\int 1_{\Gamma^{(m-1)}}(\theta)p(\theta)d\theta} > \beta$.
5. Learn arbitrary marginal posteriors in the Γ estimate.



We use $\epsilon_0 = 10^{-6}$, for a gaussian joint posterior this truncates at $\pm\sqrt{-2 \ln \epsilon_0} \sigma$.
Truncation affects only very-low probability credibility contours.

C2ST-ddm

Classifier 2-Sample Test per d-Dimensional Marginal (C2ST-ddm) is a test statistic which reports the average *Classifier 2-Sample Test (C2ST)* across a set of d-dimensional marginals.

$X \sim P(X), Y \sim Q(Y)$ with $X, Y \in R^D$ and hyperparameter $1 \leq d \leq D$ that represents the marginal dimensionality of interest.

Let $(S_P, S_Q) := \{(S_{P_k}, S_{Q_k}) : k \in \{1, 2, \dots, \binom{D}{d}\}\}$ where $S_{P_k} := \{x_k^{(1)}, \dots, x_k^{(n)} \sim P(X_k)$ and $S_{Q_k} := \{y_k^{(1)}, \dots, y_k^{(n)} \sim P(Y_k)$ are sets of n samples drawn from the kth d-dimensional marginal of P and Q respectively.

$$C2ST - ddm(S_P, S_Q) := \frac{1}{K} \sum_{k=1}^K C2ST(S_{P_k}, S_{Q_k}), \text{ with } K = \binom{D}{d}.$$