Warsaw University of Technology



LPCC Fastsim

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Fast simulation application / accuracy

ALICE Run3:

- in general, no ML fast sim used in production. In process of R&D
- no real outstanding sensitive detector apart from ZDC (zero degree calorimeter)
 - currently ZDC not used in all MC productions
- ZDC also appears to be ideal for ML, since it has 2D readout structure (n*m optical fibers collecting photons)
 - o a response is a 2D image with pixels encoding photon count
 - the final output are 5 digits calculated from the image (5 channels)
 - Almost no material / other detectors in front of ZDC
 - Approach:
 - generate response directly from primary (no transport at all involved; main one followed up until now)
 - generate response from impinging track (transport involved)
- We target to replace detailed sim with fast sim for ZDC and use in all analysis (if possible)
- Training on actual data not done (possibly not easy; could be interesting idea)



120m



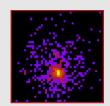
120m













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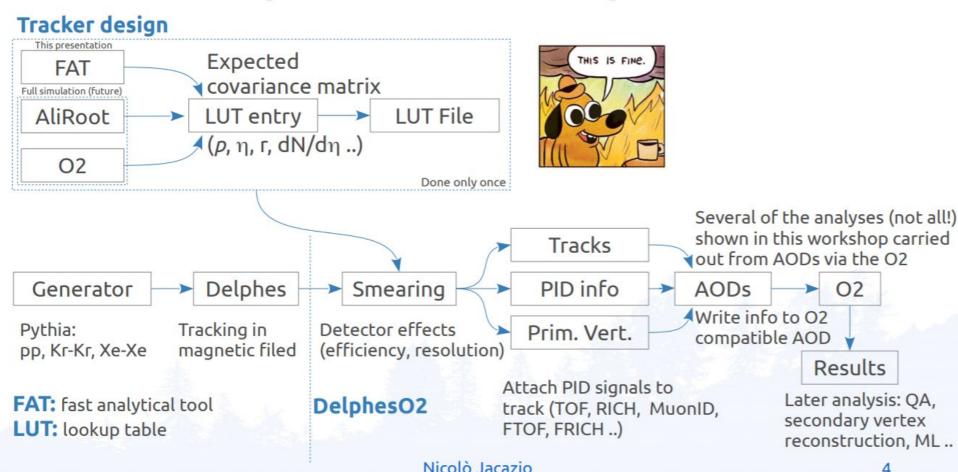


ALICE3: Fast simulation in Delphes spaces

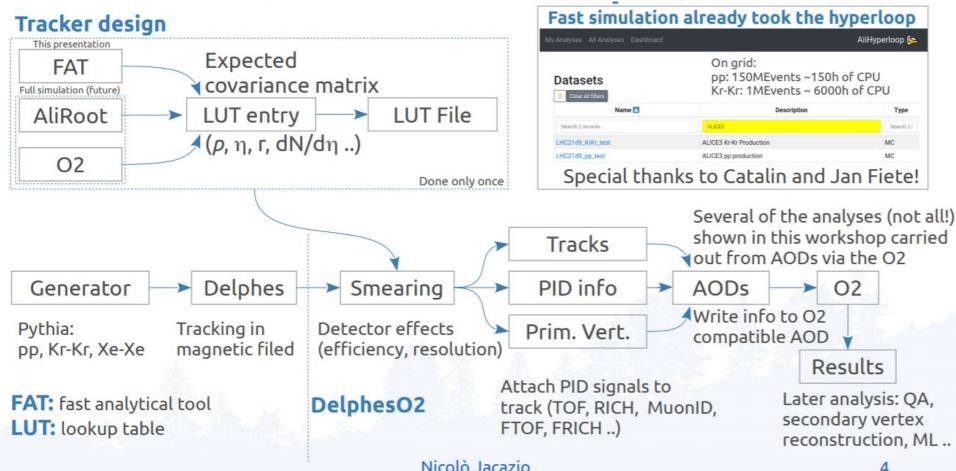
ALICE 3 Upgrade studies

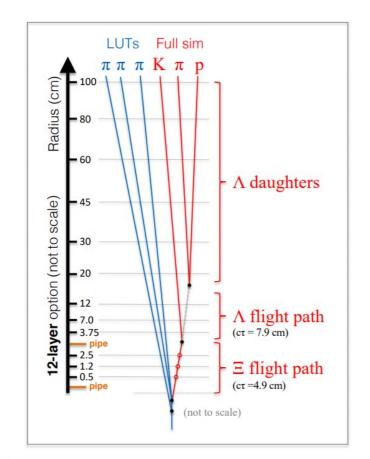
- new fast-simulation framework developed on purpose (DelphesO2)
 - o based on Delphes
 - o and on ALICE-O2 (simulation and reconstruction for Run3/4)
 - o plus custom routines for simulation of signal of specific detectors
 - time-of-flight layers
 - RICH detectors
 - EMCal
 - muon identification layer
 - GRID enabled, extremely large data samples (billions of HI collisions)
- produce analysis objects in the ALICE data format
 - convert output of fast simulation into AOD data
 - o can run same identical analysis code as normal simulation / reconstruction
 - GRID analysis of very large data samples
- input to DelphesO2
 - o event generator output (pythia8, HepMC, ...)
 - LUTs with tracking parameterisation (see later)
 - o parameters for fast-simulation of signal of other (i.e. PID) detectors
 - time-of-flight layer(s): time resolution, location, ...
 - RICH detector(s): refractive index, Ipe angular resolution, PDE, ...

Practical implementation: DelphesO2

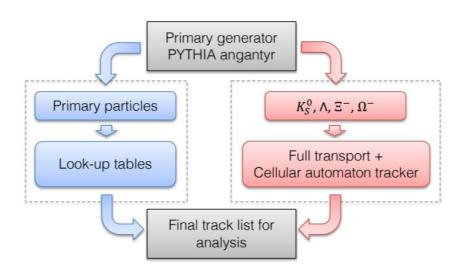


Practical implementation: DelphesO2









- LUTs: adequate for primary particles
- Full simulation: adequate for secondaries
- Combination yields high speed: reasonable objective is that time in tracking + smearing is less than analysis and event generation
- Full preservation of weak decay selections vs LUT approach!





LUTs Full sim $\pi \pi \pi K \pi p$

speedup factors (numbers for 100 min.bias Pb-Pb events)

	Full sim	Fraction	Hybrid sim	Fraction
Event generation + transport (measured)	15 minutes	14%	3 minutes	26.5%
Event generation (estimated)	~2.5 minutes	2.3%	~2.5 minutes	22.1%
Transport (estimated)	~12.5 minutes	5.8%	~30 seconds	4.4%
Track determination (full tracking + smearing)	85 minutes	78.7%	20 seconds	2.9%
Analysis time (Ξ_{cc}^{++})	~8 minutes	7.4%	~8 minutes	70.8%
Total time	108 minutes	100%	11.3 minutes	100%
should remove the analysis time to see speedup	100 minutes		3.3 minutes	30x faster

(not to scale)

generation

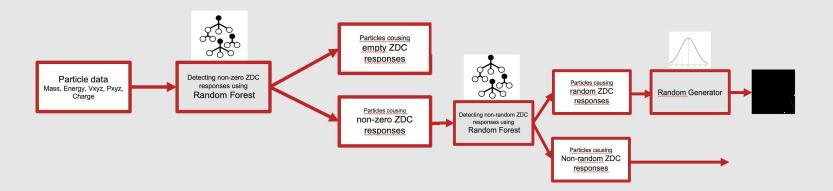
Full preservation of weak decay selections vs LUT approach!





Data preprocessing

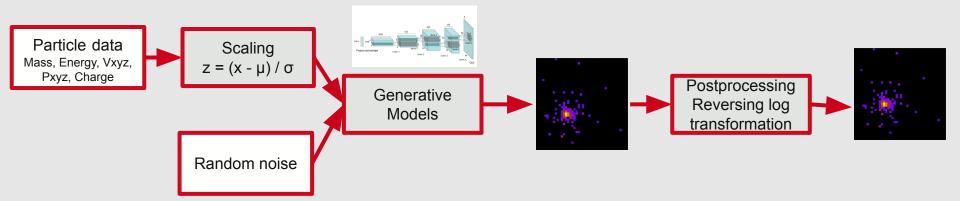
- Dataset consists of 10 million particle examples with conditional parameters
 (Energy, primary vertex position (x, y, z), momenta (x, y, z), mass, charge)
- Instead of inputting particle id (pdg code) we convert them to mass and charge
- We exclude particles producing "empty" or "nearly empty" outputs using trained Random Forest models
- We store preprocessed data as .npz files (zipped archive with numpy arrays)





Generating non-random ZDC responses

- The input of the simulation is random noise and conditional parameters (Energy, primary vertex position (x, y, z), momenta (x, y, z), mass, charge)
- The final dataset consists of 295867 examples
- We scale the conditional input with standard scaler
- We transform the ZDC response images with logarithm before using them as real training data





Tuning

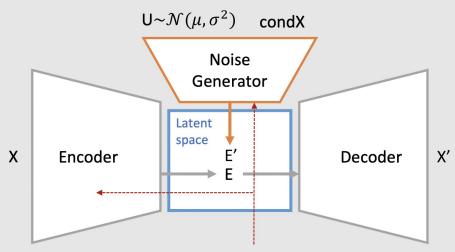
- We reviewed different generative architectures: VAE, GAN and our own idea e2e SAE (see IML presentation and article)
- The final decision was based on the wasserstein distance between channels of original and fast simulation
- Current state of the art architectures:
 - end-to-end Sinkhorn autoencoder (<u>paper</u> and <u>code</u>)
 - deep convolutional GAN with auxiliary regressor and postprocessing (<u>code</u>)
- Manual hyperparameters tuning



end-to-end Sinkhorn autoencoder

- No implicit regularisation of autoencoder's latent space
- Approximation of original data embeddings with deterministic neural network
- Joint optimisation of both neural networks
- Conditional information added to noise generator
- Wasserstein distance between embeddings concatenated with conditional values
- Original data distribution on latent space

Trained with Adam(Ir=0.001)



 $\mathcal{L}_{1} = S_{c,\epsilon}([E,condX],[E'(condX),condX])$

Encode	d data		
E1	E2	CondX	
0.1	0.2	0	
0.9	0.8	1	
0.15	0.1	0	

	Lincoaca moise			
4	E'1	E'2	C	
Wasserstein	0.16	0.12	C	
dist.	0.88	0.82	1	
	0.11	0.18	C	

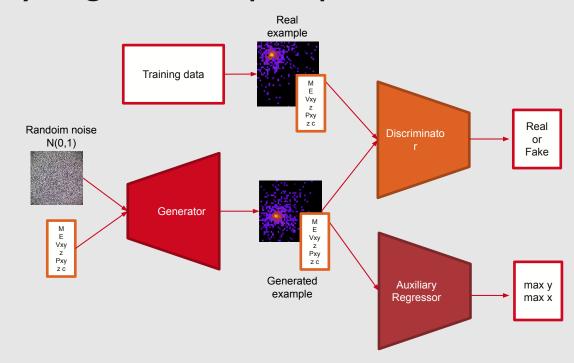
E'1	E'2	CondX		
0.16	0.12	0		
0.88	0.82	1		
0.11	0.18	0		

Encoded noise



cDC-GAN + auxiliary regressor + postproc

- An auxiliary regressor has been added to the pair Discriminator and Generator
- The auxiliary regressor was trained on the task of returning the position coordinates of the maximum number of photons in the input image. After training, the weights of the model were frozen.
- The regressor provides an additional source of loss to the generator by comparing the coordinates of the maximum of the generated examples with the maximum coordinates of corresponding sample in the training set.



• Trained with Adam(lr=0.001)

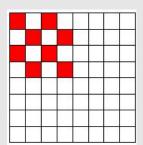


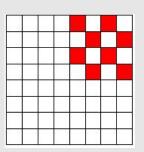
Validation

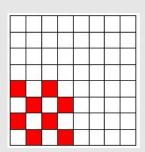
We started with validation on the basis of standard metrics (MSE, differences between placement of central hit for generated and original simulations), but simulations are too random

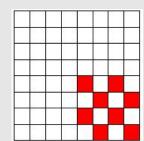
Statistical comparison of output values:

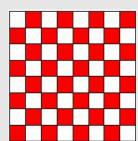
• 5 Channel values are calculated by summing pixels (photons) that are located at the specific fields of a checkerboard grid







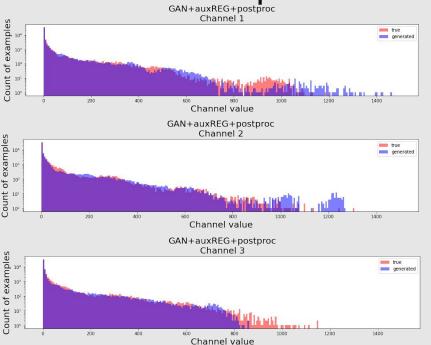


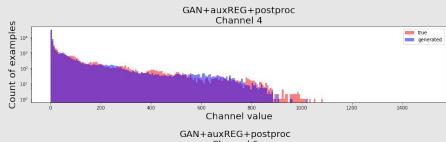


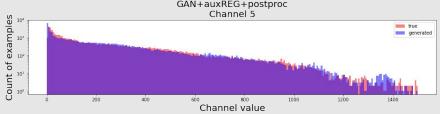


GAN + auxREG + postproc – channel comparision

GAN+auxREG+postproc Channel 1







model	WS	WS	WS	WS	WS	WS
	MEAN	CH1	CH2	CH3	CH4	CH5
GAN + auxREG + postproc	5.16	2.71	4.63	4.89	6.71	8.59



Integration (work in progress)

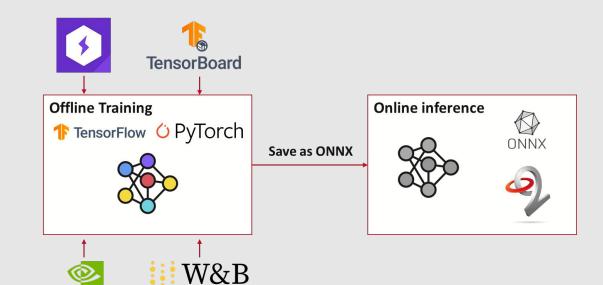
- We are currently integrating the models into O2
- Models will be stored in ONNX format
- During development and training they are stored in raw TF or PyTorch format
- Generating one particle takes on average 1674 µs on CPU.
- Simulation was not tested on GPU.
- ~ 100MB memory requirements for the whole process marginal compared to rest of data processing





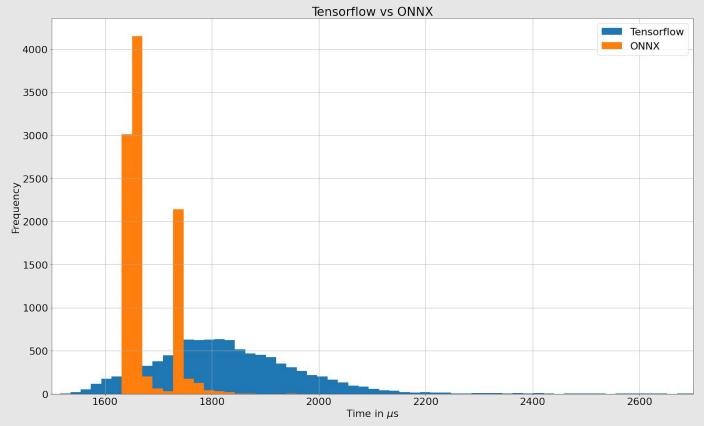
Integration overview

- Offline training where we can use most common ML libraries with addons, and available resources (e.g. GPUs)
- Online inference through ONNX integrated to O2



NVIDIA。







Valuable lessons and plans

- We can recommend ONNX as an integration tool
- Software we develop is very ZDC specific

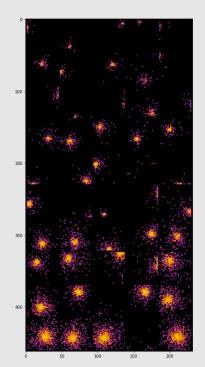
- We might want to think about how we want to retrain model with additional data - we don't want to do it from scratch every time we have some changes
- Preliminary results with our continual learning method are promising

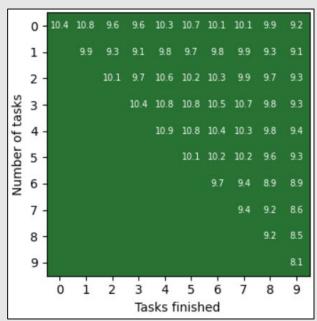


Continual learning - preliminary results

Training with continuously increasing amount of data

Without the assumption of i.i.d. data





Wasserstein distance on all channels with continuously increased amount of data