UA9 Crystal Experiment Controls and Acquisition Software Overview

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The UA9 (SPS) experiment is composed of:

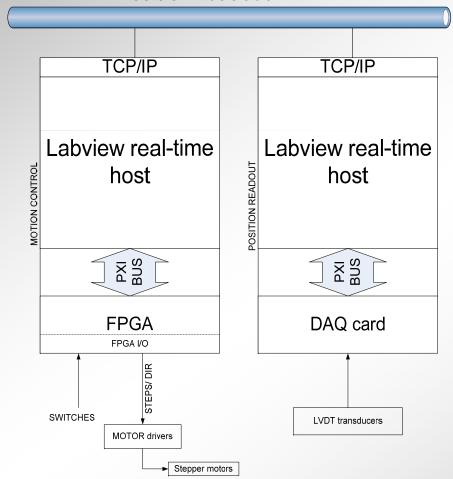
- 16 scintillators
- 14 stepper axes (stepper motor and LVDT)
- 1 DC axis (DC motor and potentiometer)
- 4 Medipix
- 2 GEM
- 4 SPS collimators (stepper motors)
- 1 LHC phase 2 collimator (stepper motors)



2- Control and acquisition architecture

Motorization low-level control

- Based on Labview real-time PXI chassis
- Two PXI: 1. Motion control
 - 2. Position readout







Various software platforms:

- 1. Labview software for scintillators acquisition (Windows XP)
- 2. Labview software for GEM acquisition (Windows XP)
- 3. Pixelman software for Medipix readout (Windows XP)
- 4. Labview real-time for stepper axes controls (Pharlap ETS)
- 5. Linux software for SPS collimator controls (LynxOS)
- 6. PLC software for TAC controls (Siemens Step 7)
 - → Need to unify and synchronize data publication over the network

2- Control and acquisition architecture

FESA (Front End Software Architecture)

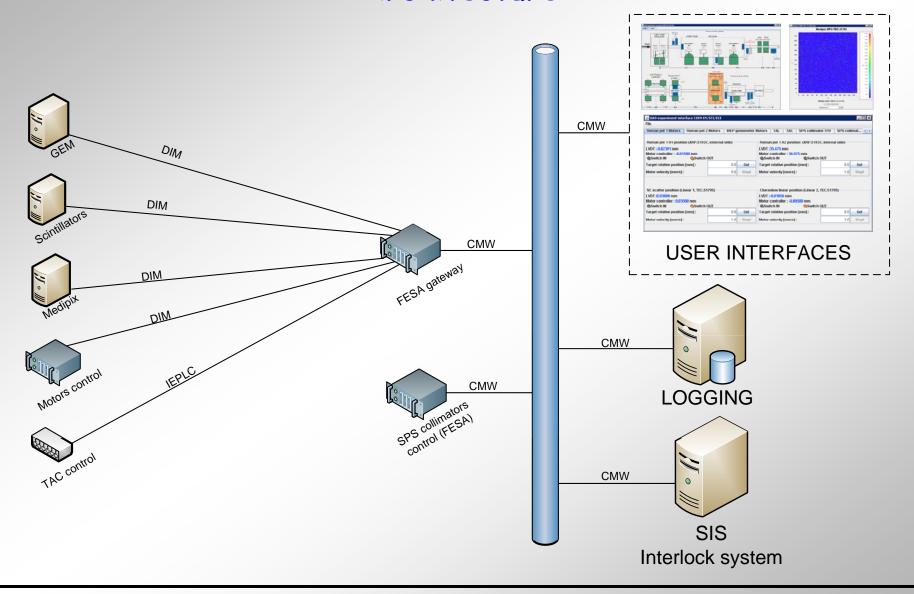
- CERN standard for devices acquisition and controls
- Provides uniform devices communication (CMW)
- Only compatible with Linux

DIM (Distributed Information Management System)

- Used by LHC experiments (DIP)
- Light footprint
- Multi-platforms (Linux, Windows, HP-UX...)

2- Control and acquisition architecture

Architecture



1. Logging system

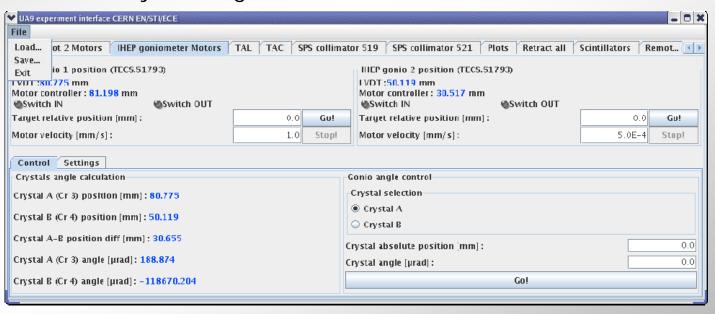
- ⇒ JAVA application
- ⇒ Connects to devices using CMW
- ⇒ Save CSV (text) files every minute
- ⇒ Notification system in case of failure (via e-mail and SMS)

<u>≰</u> RDA properties logger						
File						
-00						
Status	Device name	Property name	Last write	Notification	Size (kB)	File path
Active	UA9Gem1	Acquisition	22/10/10 09:30:31	22/10/10 09:30:38	14645	ber2010\Detectors Data\Gem1.csv_0.csv
Active	UA9Gem2	Acquisition	22/10/10 09:30:31	22/10/10 09:30:38	19526	ber2010\Detectors Data\Gem2.csv_0.csv
Active	UA9Scintillators	Acquisition	22/10/10 09:30:31	22/10/10 09:30:39	8357	10\Detectors Data\Scintillators.csv_2.csv
Active	TAC.LSS5	Acquisition	22/10/10 09:30:31	22/10/10 09:30:39	3987	\Detectors Data\TAC_position.csv_0.csv
Active	Medi.XRP.51937-H1	Acquisition	22/10/10 09:30:31	22/10/10 09:30:36	26759	Data\Medipix.XRP.51973-H1.csv_25.csv
Active	Medi.XRP.51937-H2	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	5763	Data\Medipix.XRP.51973-H2.csv_25.csv
Active	Medi.MPX-BLM.51900	Acquisition	22/10/10 09:30:32	22/10/10 09:30:38	29454	ata\Medipix.MPX-BLM.51900.csv_54.csv
Active	Medi.MPX-TEC.51795	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	43897	ata\Medipix.MPX-TEC.51795.csv_78.csv
Active	TCSM.51934	MeasuredCornerPo	22/10/10 09:30:31	22/10/10 09:30:39	19920	ctors Data\Phase2_Collimator.csv_0.csv
Active	TEC.51795.CERNLIN1	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4652	s Data\TEC.51795.CERNLIN1.csv_0.csv
Active	TEC.51795.CERNANG	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4912	Data\TEC.51795.CERNANGL1.csv_0.csv
Active	TEC.51795.CERNLIN2	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4583	s Data\TEC.51795.CERNLIN2.csv_0.csv
Active	TEC.51795.CERNANG	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4480	Data\TEC.51795.CERNANGL2.csv_0.csv
Active	TEC.51795.CHK	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4550	\Motors Data\TEC.51795.CHK.csv_0.csv
Active	TEC.51795.SCATTER	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4484	rs Data\TEC.51795.SCATTER.csv_0.csv
Active	TECS.51793.LINUP	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4956	tors Data\TECS.51793.LINUP.csv_0.csv
Active	TECS.51793.LINDW	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4765	tors Data\TECS.51793.LINDW.csv_0.csv
Active	XRP.51937.H1	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4644	10\Motors Data\XRP.51937.H1.csv_0.csv
Active	XRP.51937.H2	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4480	10\Motors Data\XRP.51937.H2.csv_0.csv
Active	XRPH.51991.H1	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4282	\Motors Data\XRPH.51991.H1.csv_0.csv
Active	XRPH.51991.H2	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	4595	\Motors Data\XRPH.51991.H2.csv_0.csv
Active	TAL.52193.LIN1	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	5520	0\Motors Data\TAL.52193.LIN1.csv_0.csv
Active	TAL.52193.LIN2	Acquisition	22/10/10 09:30:32	22/10/10 09:30:39	5425	0\Motors Data\TAL.52193.LIN2.csv_0.csv



2. Motorization devices control

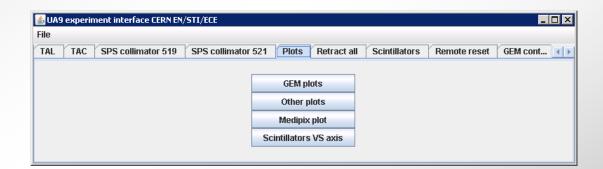
- ⇒ JAVA application
- ⇒ Connects to devices using CMW and PLC communication
- ⇒ Controls and acquisition of all UA9 devices : UA9 motors, SPS collimators reset, GEM gas
- ⇒ Detectors plot integrated into the application
- ⇒ Possibility to save and restore motors positions settings
- ⇒ Calculation of IHEP crystals angle



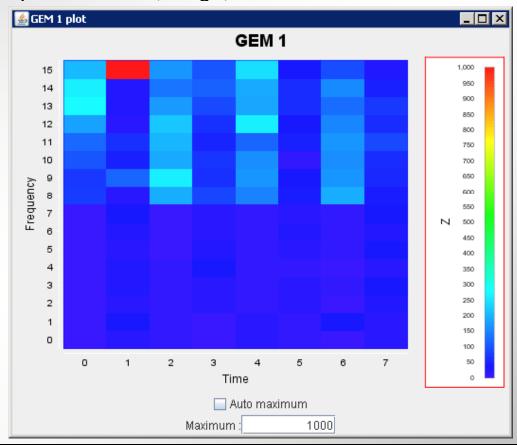


⇒Plots available :

- ⇒ GEM
- ⇒ Scintillators versus time
- ⇒ Motors position versus time
- ⇒ Medipix plots
- ⇒ Scintillators versus motor position

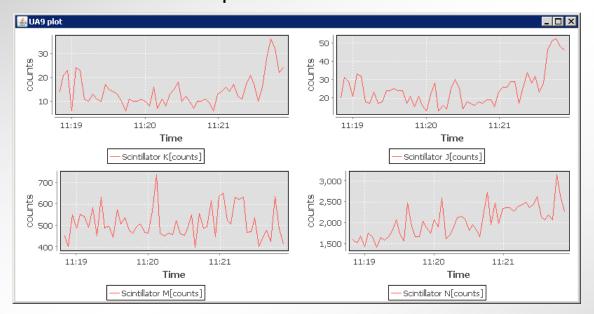


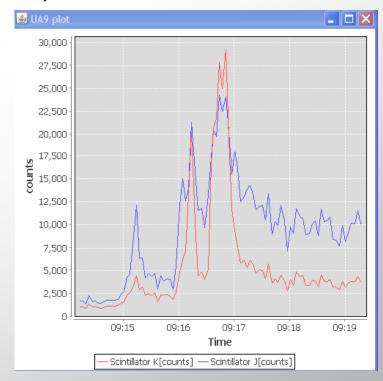
- **⇒** GEM plot
 - ⇒ XYZ chart (Y : frequency, X : Time)
 - ⇒ Possibility to save plot as PNG (image) file





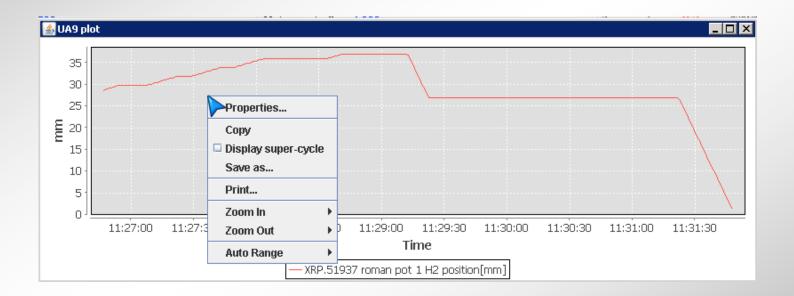
- **⇒** Scintillators versus time
 - ⇒ XY plot (X : Time, Y : scaller rate)
 - ⇒ Possibility to plot more than one scintillator at time
 - ⇒ Plot can be saved into PNG (picture) or CSV (points)
 - ⇒ Zoom-able plot





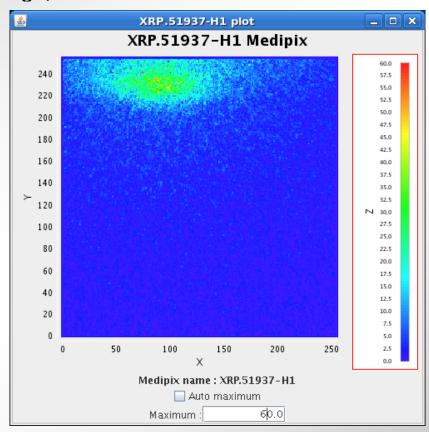


- **⇒ Motors position versus time**
 - ⇒ XY plot (X : Time, Y : absolute position)
 - ⇒ Same features as scintillators plot

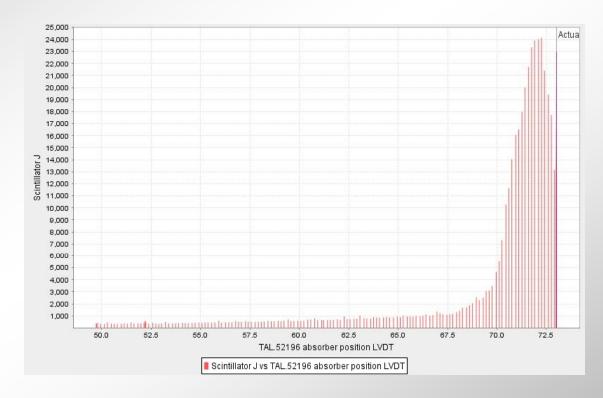




- **⇒** Medipix plot
 - ⇒ ZXY plot (full Medipix frame)
 - ⇒ Export to PNG (image)



- ⇒ Scintillator versus axis plot
 - ⇒ XY bar plot (Y: scintillator rate, X: Axis position)
 - ⇒ Export to PNG (image), JPG or CSV file
 - ⇒ Very useful for scans





3- User interfaces overview

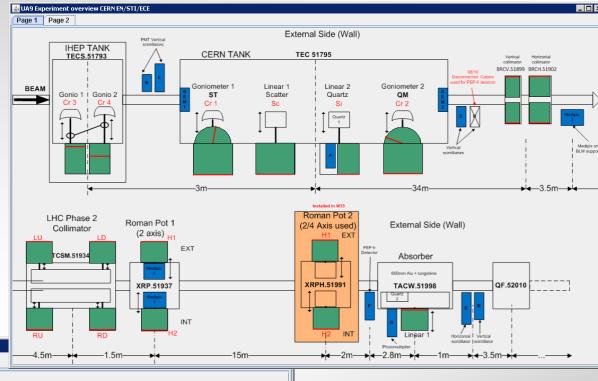
4. UA9 fixed display

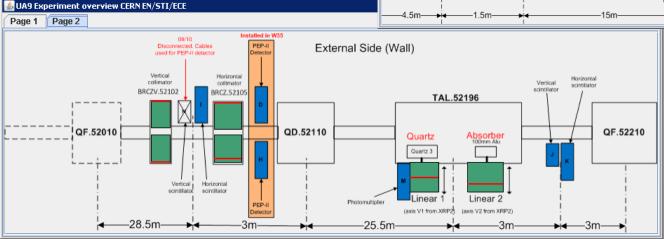
- ⇒ Provides an overview of motorizations position used by experiment :
 - ⇒ Crystals position
 - ⇒ Crystals angle
 - ⇒ Absorbers position
 - ⇒ SPS collimators position
 - ⇒ LHC phase 2 collimator position
 - ⇒ Roman pots position
 - ⇒ Quartz position
- ⇒ Positions displayed according to layout and minimum/maximum allowed range

3- User interfaces overview

4. UA9 fixed display

⇒ Screenshot







Thank you!

