Modelling the high-energy curvature radiation for the Vela pulsar using a general particle dynamics approach.

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Standard Pulsar Model

- ► The large rotating magnetic field induces an electric field
- The induced electric field rips particles from the star's surface
- ► The last closed magnetic field lines touch the light cylinder at $R_{\rm LC} = \frac{cP}{2\pi}$
- ▶ In the braking model the change in rotational energy is equated to the luminosity radiated by a magnetic dipole in a vacuum
- This may be written as the equation $\dot{\Omega} = -k\Omega^n$

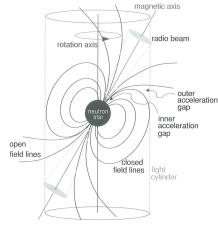


Figure: Lorimer and Kramer (2005)

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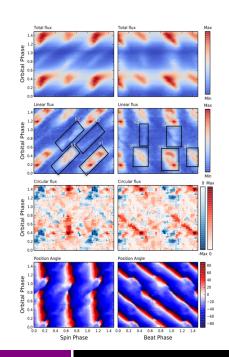
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Aims

Develop a new general emission model to work for a WD binary scenario:

- Solve particle dynamics generally without assuming super-relativistic particles and small pitch angles.
- Calculate the broadband light curves and spectra at different orbital phases.
- Calculate Stokes parameters, PPA, and degree of polarisation at different orbital phases.
- Calibrate our code with the millisecond pulsar emission code of Harding and collaborators.



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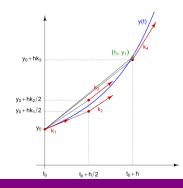
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Adaptive ODE Solver

► Solve Lorentz equation:

$$\frac{d\mathbf{p}}{dt} = q \left(\mathbf{E} + \frac{c\mathbf{p} \times \mathbf{B}}{\sqrt{m^2 c^4 + \mathbf{p}^2 c^2}} \right). \tag{1}$$

- ▶ Do n-stage evaluations to solve the ODE depending on method accuracy.
- ▶ One can calculate the next value by weighing stages, $y_{n+1} = y_n + h \sum_{i=1}^{s} b_i k_i$.
- ▶ One can use a method with embedded lower order to get a truncation error, $\tau_{n+1} = y_{n+1} y_{n+1}^* = \sum_{i=1}^s (b_i b_i^*) k_i$.
- ightharpoonup Calculate the adaptive next step size using au_{n+1} and a given accuracy threshold.



$k_1 = f(t_n, y_n),$ $k_2 = f(t_n + c_2h, y_n + h(a_{21}k_1)),$ $k_3 = f(t_n + c_3h, y_n + h(a_{31}k_1 + a_{32}k_2)),$ \vdots $k_s = f(t_n + c_sh, y_n + h(a_{s1}k_1 + a_{s2}k_2 + \dots + a_{s,s-1}k_{s-1}))$								
c_1	a_{11}	a_{12}		a_{1s}				
c_2	a_{21}	a_{22}		a_{2s}				
:	:	:	٠.	:	_	c	A	
c_s	a_{s1}	a_{s2}		a_{ss}	_		$\mathbf{b^T}$	
	b_1	b_2		b_s				
	b_1^*	b_2^*		b_s^*				

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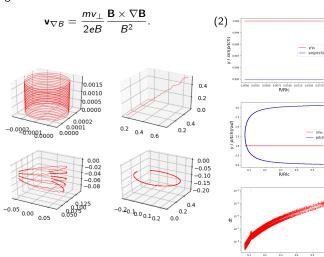
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Calibration of ODE Solver

- ▶ Set *E* = 0.
- Conserved energy and constant pitch angle for:
 - Constant B-field
 - Changing B-field strength.
- Conserved energy for static magnetic dipole and see if the obtained magnetic mirror effect as well as drift are correct.



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▶ The ODE schemes implemented in the code:

- Runge-Kutta Fehlberg 4(5): 5 stage.

- DVERK 6(5): 8 stage.

- Prince-Dormand 8(7): 12 stage.

Adaptive Curtis 10(8): 18 stage.

Adaptive Hiroshi 12(9): 29 stage.

▶ Benchmark of schemes:

Tol 1e ⁻¹²	RKF	DV	PD	CR	HR
Time vs RKF	1	0.82	0.36	0.32	0.65
$\delta\gamma$	0.4	0.25	0.001	0.014	0
T 1 1 -14	DIZE	DV/	DD	CD	LID I

Tol 1e ⁻¹⁴	RKF	DV	PD	CR	HR
Time vs RKF	1	0.82	0.29	0.23	0.48
$\delta\gamma$	0.01	0.008	0	0	0

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Radiation-Reaction Force

▶ Use equation from Landau and Lifshitz for general radiation-reaction force:

$$\begin{split} \mathbf{f} &= \frac{2e^3\gamma}{3mc^3} \left\{ \left(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right) \mathbf{E} + \frac{1}{c} \mathbf{v} \times \left(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right) \mathbf{H} \right\} \\ &+ \frac{2e^4}{3m^2c^4} \left\{ \mathbf{E} \times \mathbf{H} + \frac{1}{c} \mathbf{H} \times (\mathbf{H} \times \mathbf{v}) + \frac{1}{c} \mathbf{E} (\mathbf{v} \cdot \mathbf{E}) \right\} \\ &- \frac{2e^4\gamma^2}{3m^2c^5} \mathbf{v} \left\{ \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{H} \right)^2 - \frac{1}{c^2} (\mathbf{E} \cdot \mathbf{v})^2 \right\}. \end{split} \tag{3}$$

- ▶ The first term of Equation 3 requires 9, 18 or 36 evaluations of the B-field per stage to find the derivatives.
- ▶ This first term is $\sim 10^8 10^{10}$ times smaller than the largest component.
- ► The super-relativistic form of Equation 3 is given by:

$$f_{x} = -\frac{2e^{4}\gamma^{2}}{3m^{2}c^{4}}\left\{ (E_{y} - H_{z})^{2} + (E_{z} + H_{y}^{2}) \right\}$$
(4)

ightharpoonup Equation 3 and 4 converge at a Lorentz factor around 10^4-10^5 .

$$P_{rad} = \mathbf{F}_{rad} \cdot \mathbf{v},$$

$$E_{rad} = \int \mathbf{F}_{rad} \cdot \mathbf{v}.dt$$
(5)

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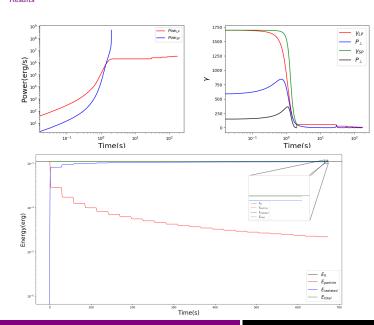
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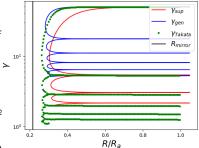
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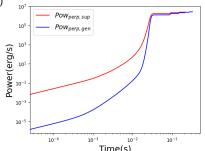
Takata uses rewritten forms of equations from Harding et al. (2005).

$$\frac{d\gamma}{dt} = -\frac{P_{\perp}^2}{t_c}$$

$$\frac{d}{dt}\left(\frac{P_{\perp}^{2}}{B}\right) = -2\frac{B}{t_{s}\gamma}\left(\frac{P_{\perp}^{2}}{B}\right)^{2}$$
(6)

- ► Where $t_s = 3m_e^3 c^5/2e^4 B^2$.
- They predict the mirror at $r_m \sim a \sin^{2/3} \theta_p$
- ► The super-relativistic case agrees with Takata's γ_{loss} but not the mirror point.
- ► The general case disagrees largely with Takata's results.





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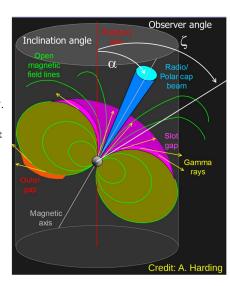
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Tracing out the particle trajectory incorporating E × B drift from Kalapotharakos et al. (2014).

$$\mathbf{v}/c = \mathbf{E} \times \mathbf{B}/(B^2 + E_0^2) + f\mathbf{B}/B.$$

- Solving transport equations from Harding et al (2005) to calculate emission.
- $d\gamma/dt = eE_{\parallel}/mc 2e^4B^2p_{\perp}^2/3m^3c^5,$
- $dp_{\perp}/dt = -3cp_{\perp}/2r 2e^4B^2p_{\perp}^3/3m^3c^5\gamma.$
- Gyrocentre approach with average particle pitch angle.



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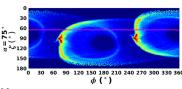
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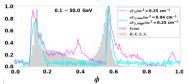
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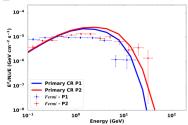
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Emission Map Calculations

- We are only looking at curvature radiation for the calibration.
- We temporarily use the analytical formula for the static dipole curvature radius.
- The perpendicular E-field for a co-rotating plasma in the retarded-dipole scenario is given by:
- $\blacktriangleright \ \mathbf{E}_{\perp} = (-\mathbf{\Omega} \times \mathbf{r})/\mathbf{c} \times \mathbf{B}.$
- ► The phase corrections are given by:
- $\phi_{obs} = \\ \phi_{em} r_{em} \times \eta_{em} / R_{LC} \Delta \phi_{rot}$
- Drift velocity is calculated using:
- $\mathbf{v}/c = \mathbf{E} \times \mathbf{B}/B^2$.
- ► Figures from Barnard et al.(2021).







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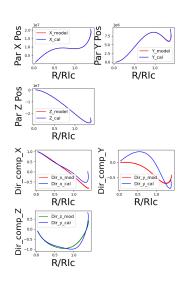
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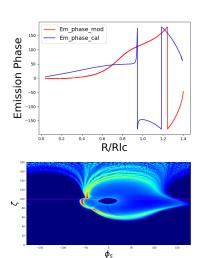
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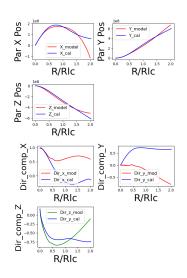
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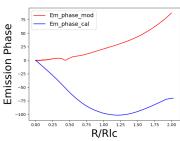
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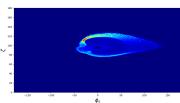
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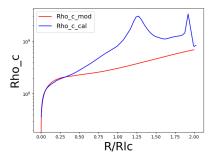
► The particle curvature radius can be calculated using:

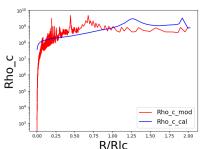
$$\rho_c = \frac{1/\sqrt{(x'')^2 + (y'')^2 + (z'')^2}}{1/\sqrt{(x'')^2 + (y'')^2 + (z'')^2}}.$$

► Using numerical differentiation we calculate x_i" using:

$$x_{i}^{"} = (-3x_{i-1}^{'} + 4x_{i}^{'} - x_{i+1}^{'})/2ds.$$

- What difference does including the gyroradius have on the curvature radius?
- Use the effective curvature radius calculation employed in synchro-curvature radiation models





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Future Work

- ▶ Write up results for ApJ/MNRAS article.
- Calibrate with Harding and collaborators' emission maps and particle trajectories for pulsar scenario.
- Use appropriate E-field (force-free fields) to get E × B drift. Study effect of new WD scenario on model outputs.
- Implement polarisation calculations to produce phase plots.
- Determine how to scale particles' emission to have significant statistics. Invoke magic trickery to get code running in a reasonable time.
- Run code for orbital time scale, investigate different B-fields and E-fields, and investigate different particle pitch-angle distributions.

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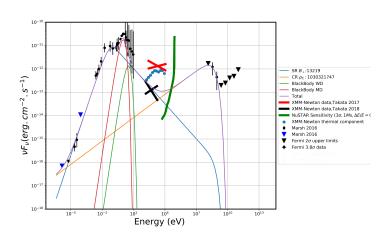
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