

[Approaches to Analyze Behavior]
**Sparse Semi-Supervised Action
Recognition with Active Learning**

Presenter: Jingyuan Li {jingyli6@uw.edu},
Faculty Advisor: Eli Shlizerman {shlizee@uw.edu}
NeuroAI Shlizerman Lab
Electrical and Computer Engineering Department

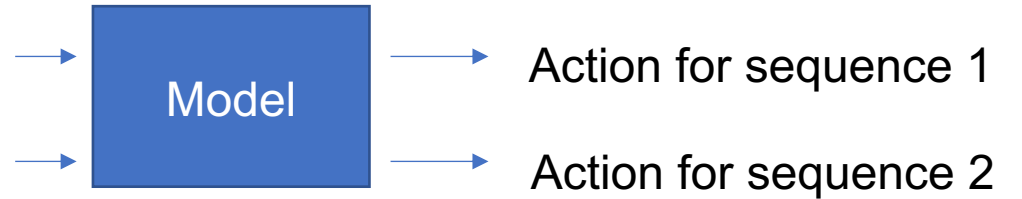
Background and Motivation

Action Recognition

Sequence 1



Sequence 2



Action for sequence 1

Action for sequence 2

Application of Action Recognition

Robotic Surveillances



Wildlife Monitoring



Action Evaluation

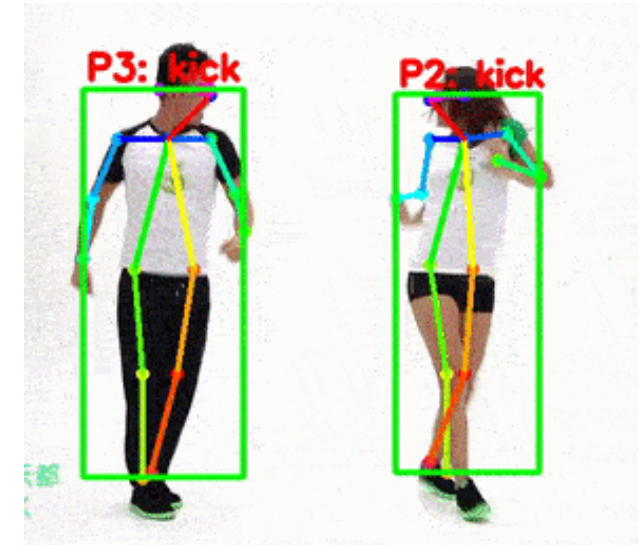


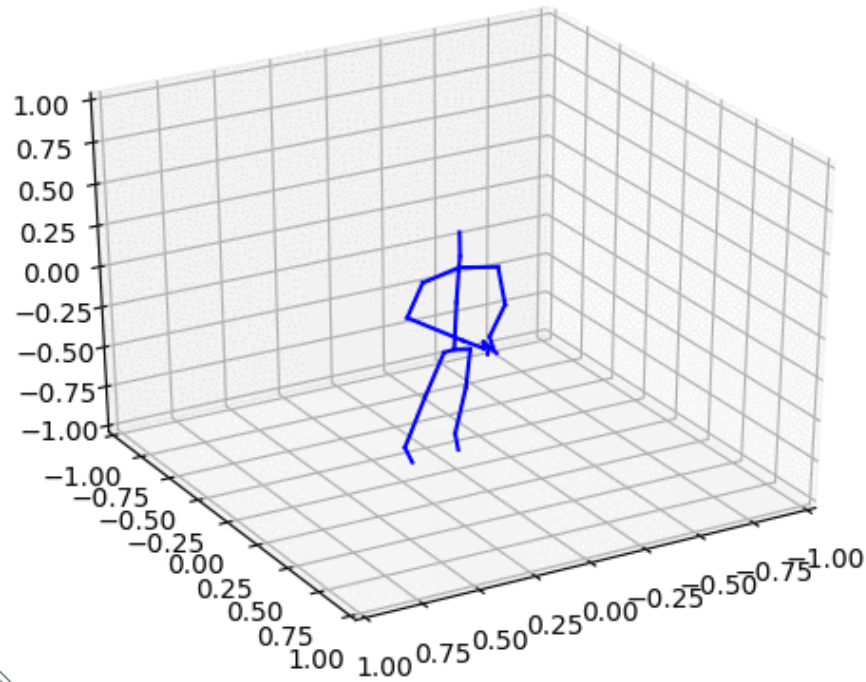
Image Source:

Left: Boston Dynamics

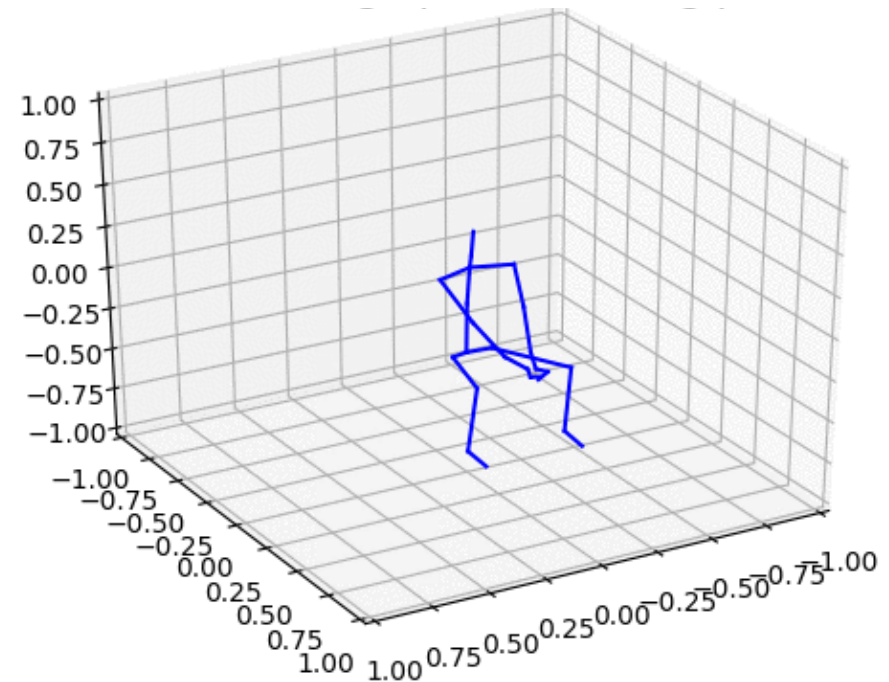
Middle: <https://www.conservationnw.org/our-work/wildlife/wildlife-monitoring/>

Right: <https://pythonawesome.com/multi-person-real-time-action-recognition-based-on-human-skeleton/>

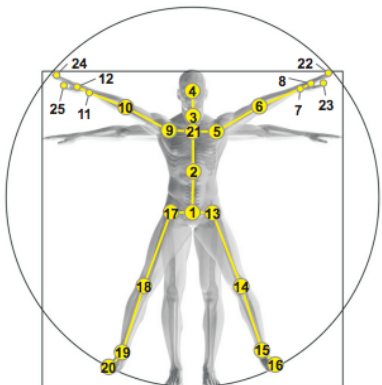
Skeleton Based Action Recognition



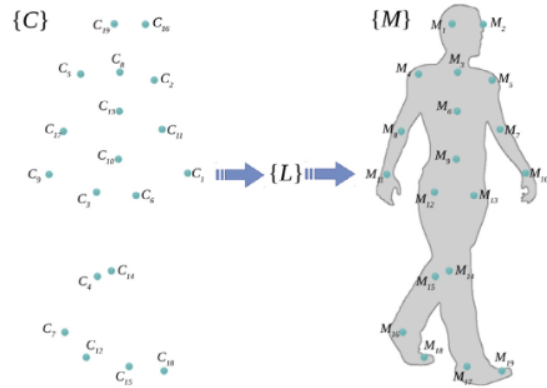
Drinking Water



Standing Up



Skeleton Data Sources



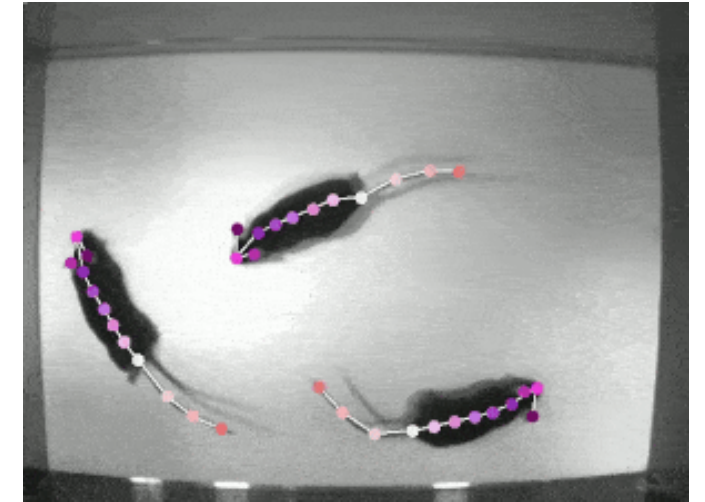
Motion Tracking with Marker

J.L. Jimenez Bascones et al., 2019



Human motion video with skeleton

Zhe Cao et al., 2017



Animal motion video with skeleton

Alexander Mathis et al., 2018

Advantageous for skeleton based action recognition:

- Reducing interference from the background
- Learning dynamics movement

Earlier Methods on Prepared Dataset

- Supervised Learning:
 - > Achieving high performance with a large labeled dataset.
- Semi-Supervised Learning:
 - > Achieving reasonable performance with partially randomly labeled data.

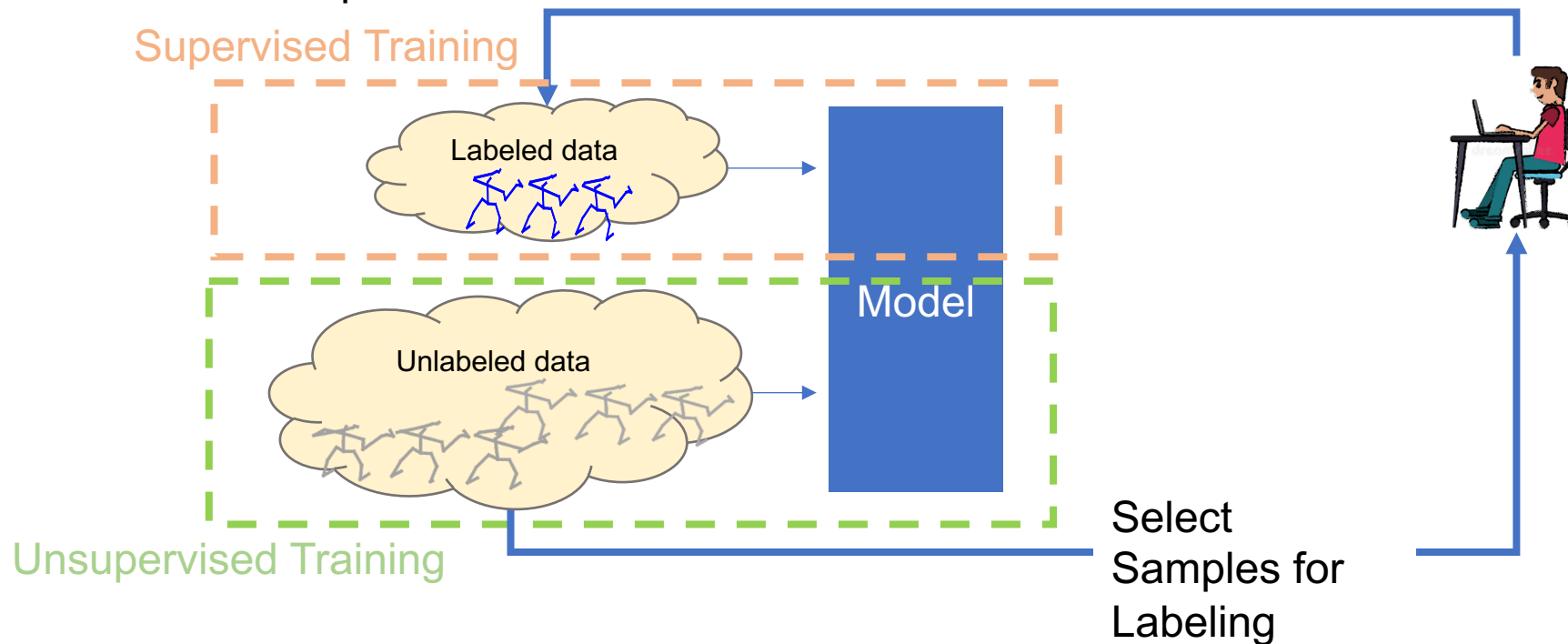
No consideration of which samples should be labeled.



Tackle the problem with Active Learning

What is Active Learning (AL)

“Active learning is a special case of machine learning in which a learning algorithm can interactively query a user (or some other information source) to label new data points with the desired outputs”



Methods

1. 'Cold Start' in AL
2. Semi-Supervised Training for Action Recognition
3. Selection with Partially Labeled Dataset

Methods

1. 'Cold Start' in AL
2. Semi-Supervised Training for Action Recognition
3. Selection with Partially Labeled Dataset

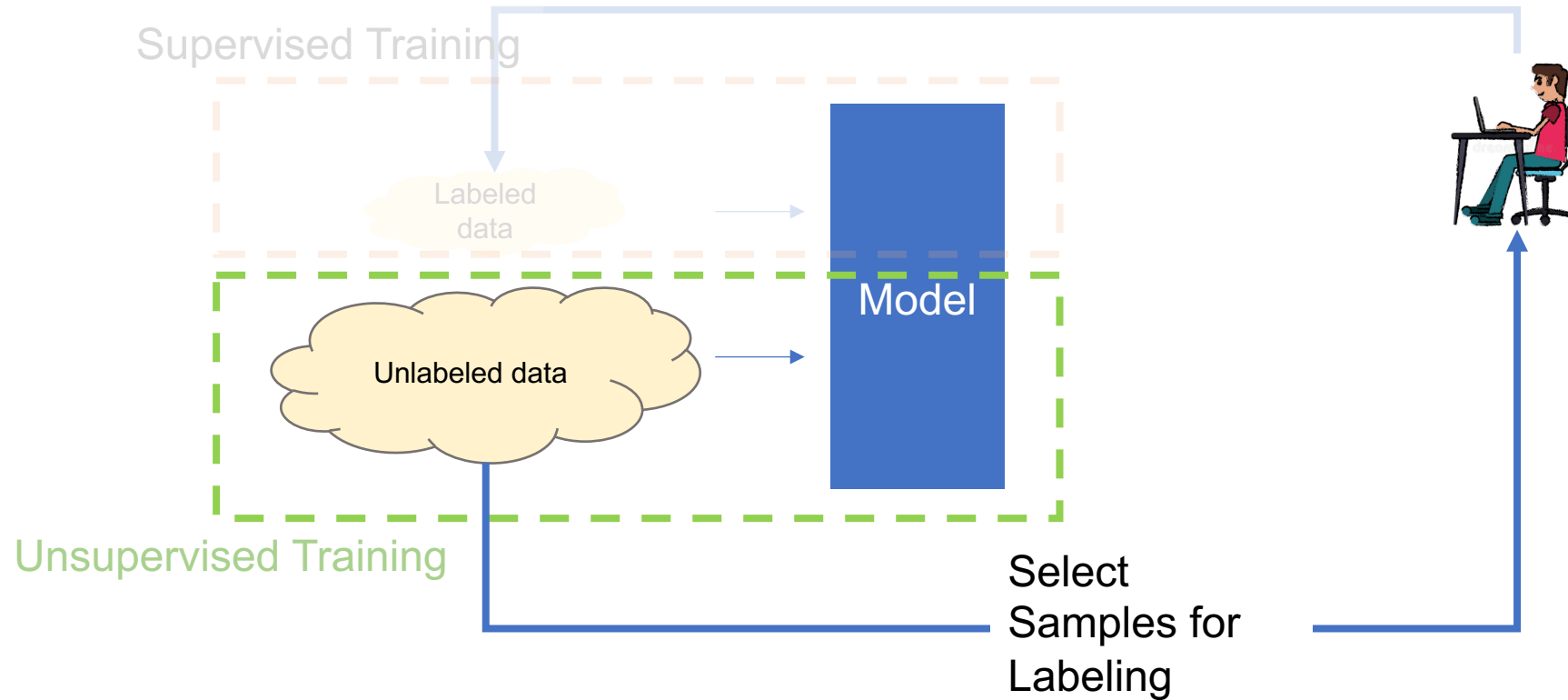
'Cold Start' in Initial Selection

- None of the samples is labeled at initial selection.

'Cold Start' in Initial Selection

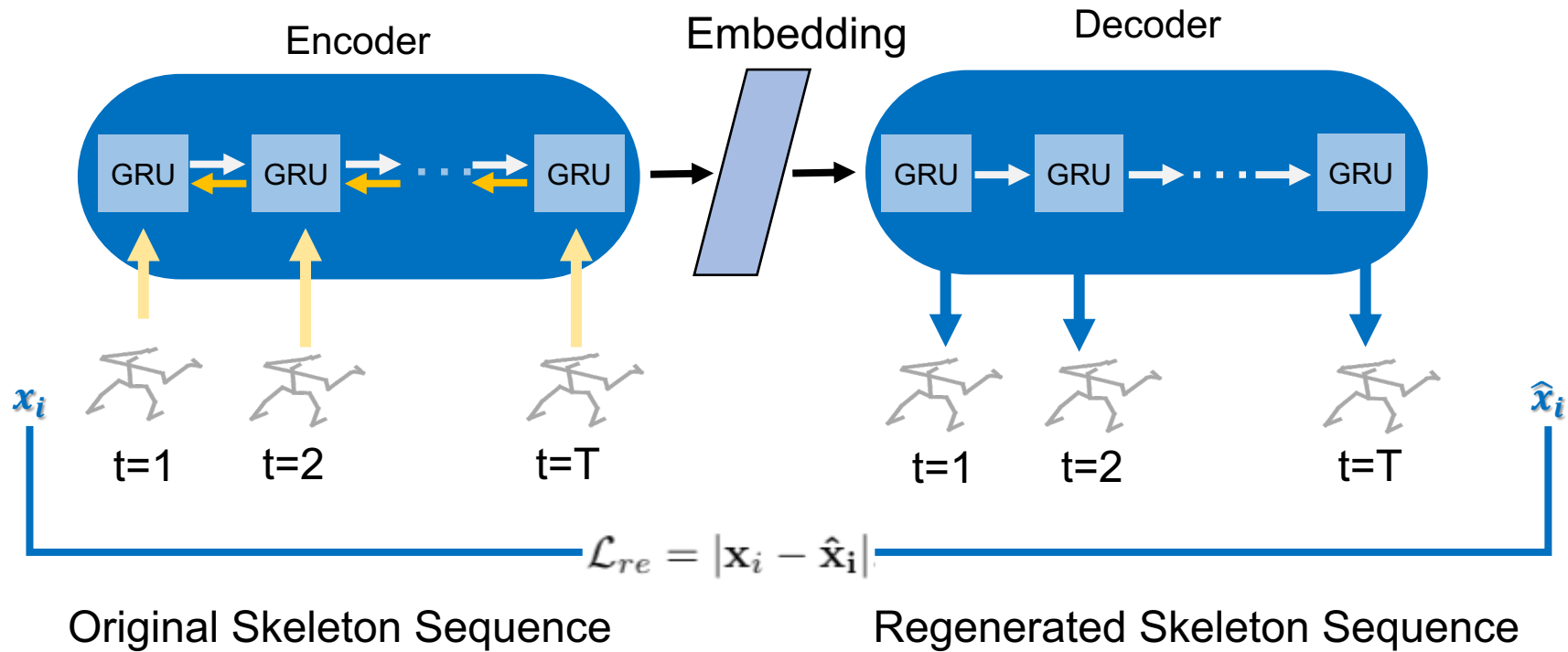
- None of the samples is labeled at initial selection.
- Quality of initial selection affects future selection.
 - Bad initialization can lead to wrong class boundary.

'Cold Start' in Initial Selection



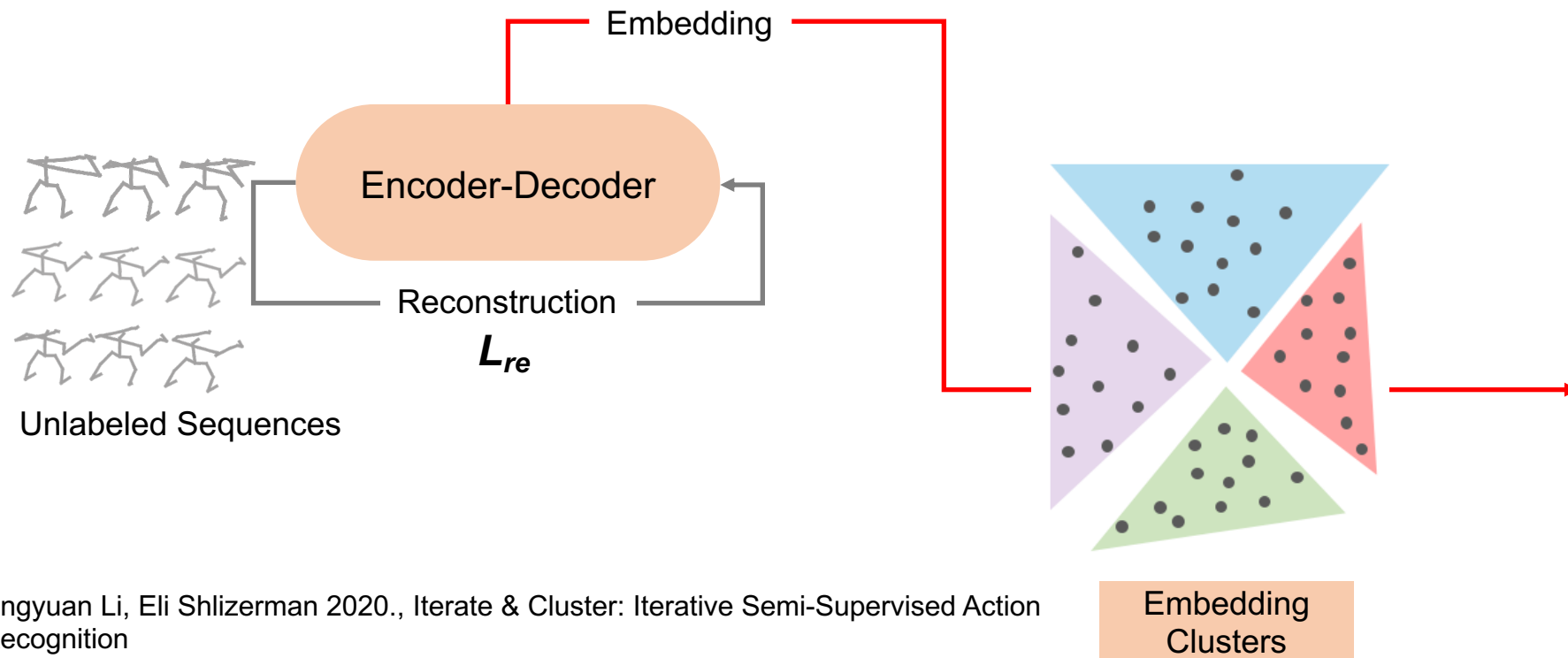
Solve the 'Cold Start' Problem

- Embeddings from unsupervised regeneration shown to form meaningful embedding space



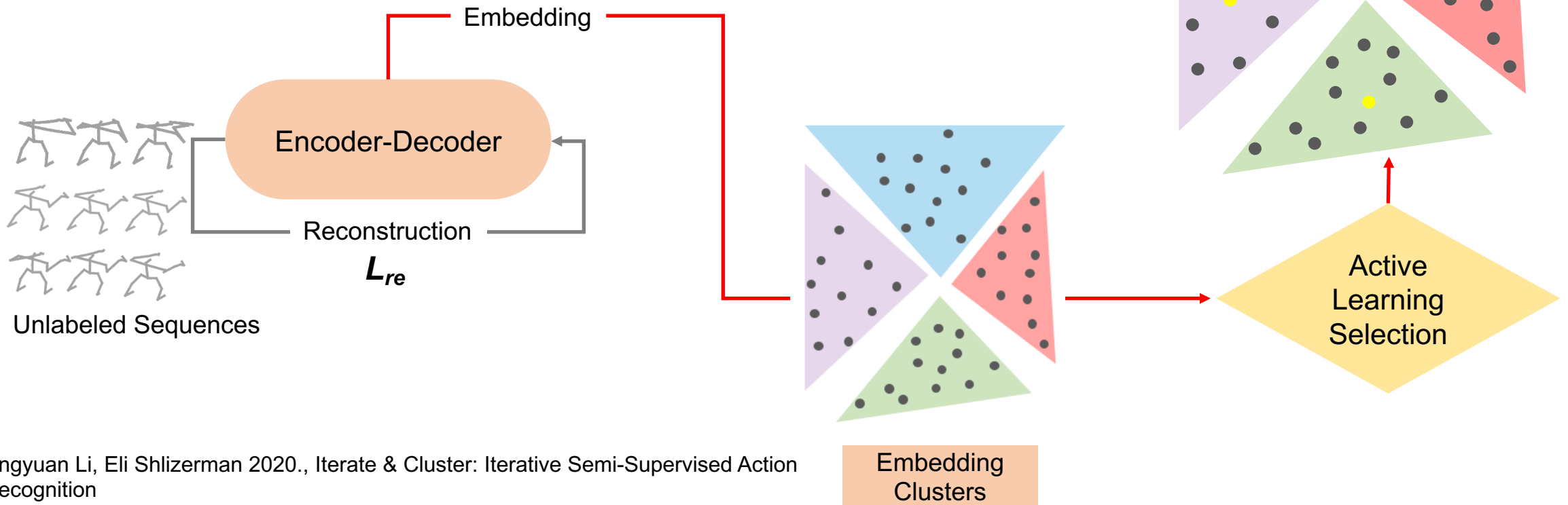
Solve the 'Cold Start' Problem

- Clustering samples in the embedding space



Solve the 'Cold Start' Problem

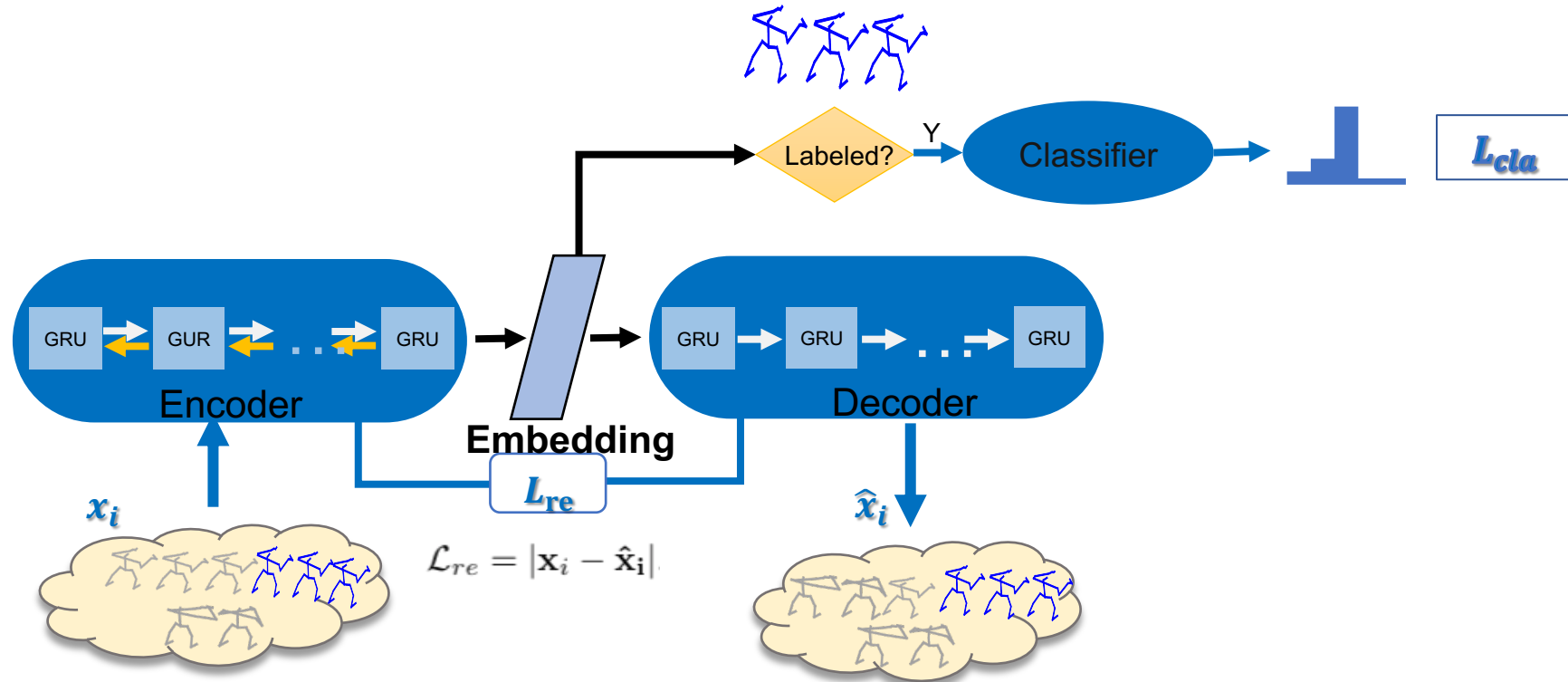
- Clustering samples in the embedding space
- Selecting samples closest to cluster centers



Methods

1. 'Cold Start' in AL
- 2. Semi-Supervised Training for Action Recognition**
3. Selection with Partially Labeled Dataset

Semi-Supervised Learning with Partially Labeled Samples

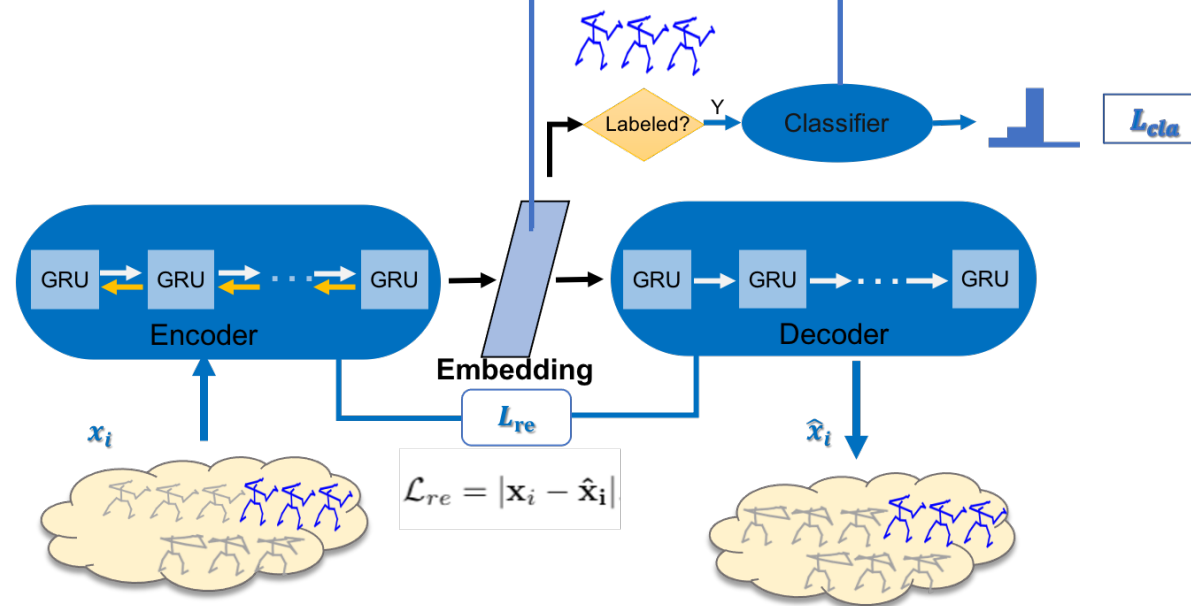


Training with loss: $L_{re} + L_{cla}$

Two Representations

1. Embedding from encoder

2. Probability distribution



Methods

1. 'Cold Start' in AL
2. Semi-Supervised Training for Action Recognition
3. Selection with Partially Labeled Dataset
(Distance & Uncertainty)

Selecting According to Distance

- Step 1: Form clusters in embedding space.

Selecting According to Distance

- Step 1: Form clusters in embedding space.
- Step 2: Measure the **distance** of unlabeled samples to the labeled samples **within the same cluster** with predicted class probability.

Selecting According to Distance

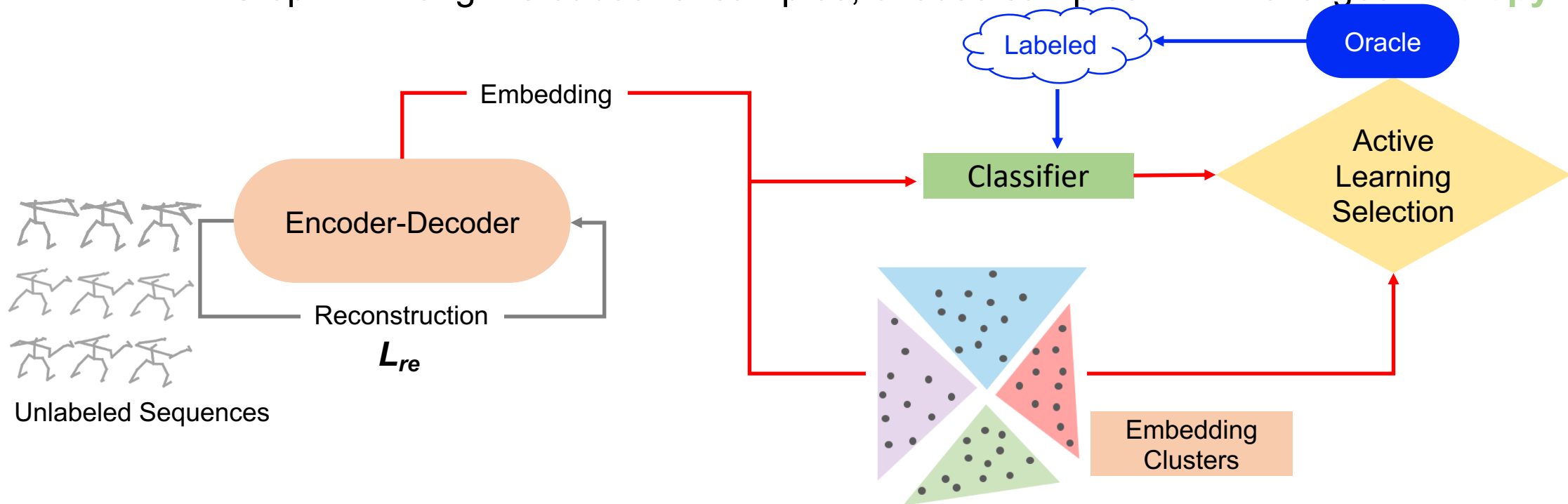
- Step 1: Form clusters in embedding space.
- Step 2: Measure the **distance** of unlabeled samples to the labeled samples **within the same cluster** with predicted class probability.
- Step 3: For each cluster, select a subset of samples with the largest distance.

Selecting According to Uncertainty

- Step 1: Form clusters in embedding space.
- Step 2: Measure the **distance** of unlabeled samples to the labeled samples **within the same cluster** with predicted class probability.
- Step 3: For each cluster, select a subset of samples with largest distance.
- Step 4: Among the subset of samples, choose samples with the largest **entropy**.

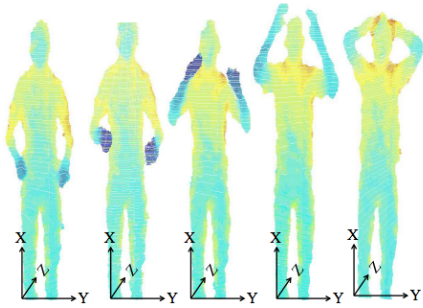
Selection According to Distance & Uncertainty

- Step 1: Form clusters in embedding space.
- Step 2: Measure **distance** of unlabeled samples to the labeled samples **within the same cluster** with predicted class probability.
- Step 3: For each cluster, select a subset of samples with largest distance.
- Step 4: Among the subset of samples, choose samples with the largest **entropy**.

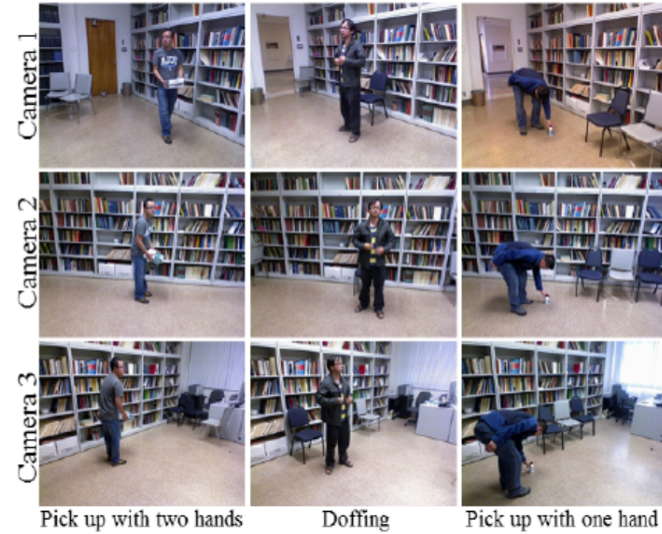


Experiments

Datasets



UWA3D
30 Classes



NW-UCLA
10 Classes



NTU RGBD
60 Classes

Compare with Semi-supervised and other AL Methods

UWA3D VIEW3					
	% Labels	5%	10%	20%	50%
	#Labels	25	50	100	250
SSL	C	18.3	21.9	32.1	44.3
	RC	19.5	30.0	26.9	46.3
	IRC	20.0	36.4	37.6	51.1
	SESAR-DIS	18.5	29.2	40.9	55.6
AL(our)	SESAR-U	21.8	31.3	41.0	55.8
	SESAR-CS	26.9	37.1	41.2	55.8
	SESAR-KT	22.8	34.6	51.8	58.8
AL+K(our)	SESAR-KJS	28.3	36.0	49.5	59.5

Table 1. Performance of different semi-supervised approaches (top), SESAR with STOA AL methods (middle) SESAR with AL+K methods (bottom) on UWA3D dataset.

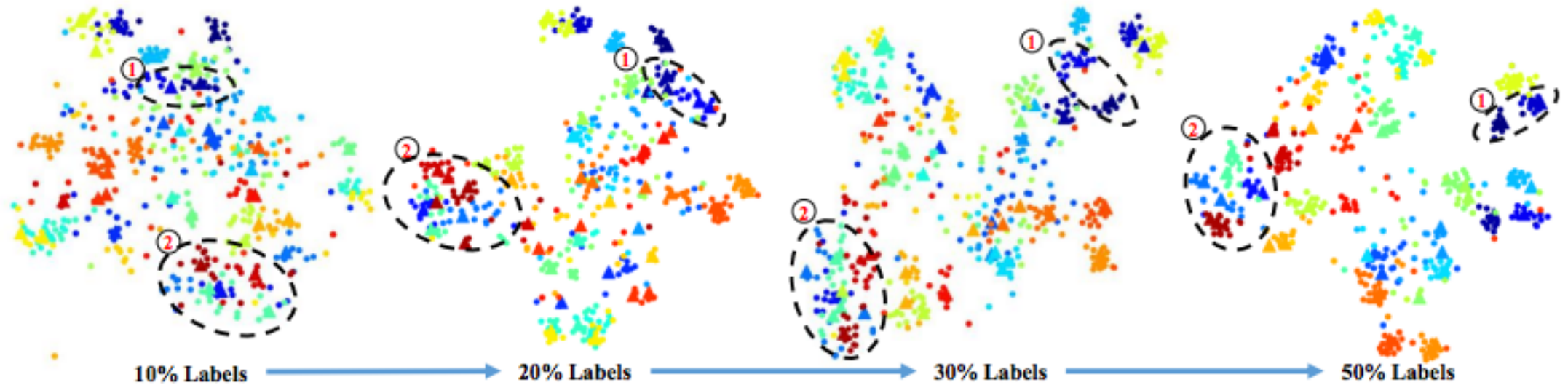
NW-UCLA					
	% Labels	5%	15%	30%	40%
	# Labels	50	150	300	400
SSL	C	44.6	56.0	70.9	72.9
	RC	51.5	63.1	77.0	76.7
	ASSL[26]	52.6	74.8	78.0	78.4
	RIC	56.2	70.5	73.5	81.0
	MS ² L[14]	–	60.5	–	–
	SESAR-DIS	55.3	73.3	80.3	83.3
AL(our)	SESAR-U	62.7	74.0	77.9	80.3
	SESAR-CS	63.9	71.5	77.5	82.3
	SESAR-KJS	58.1	76.6	80.0	85.0
AL+K(our)	SESAR-KT	63.6	76.8	77.2	78.9

Table 2. Performance of different semi-supervised approaches (top), SESAR with STOA AL methods (middle) SESAR with AL+K methods (bottom) on NW-UCLA dataset.

NTU RGB+D 60 Cross Subject					
	% Labels	1%	2%	5%	10%
	# Labels	400	800	2K	4K
SSL	C	21.8	37.2	49.6	56.7
	MS ² L[14]	33.1	–	–	65.2
	RC	33.8	41.6	47.8	60.0
	IRC	36.7	42.7	53.9	61.2
	ASSL[26]	–	–	57.3	64.3
	SESAR-CS	17.6	23.1	37.0	49.6
AL(our)	SESAR-DIS	34.9	39.5	53.8	60.4
	SESAR-U	36.1	42.5	53.9	60.8
	SESAR-KJS	38.2	45.0	57.8	62.9
AL+K(our)	SESAR-KT	41.8	46.1	55.0	58.2

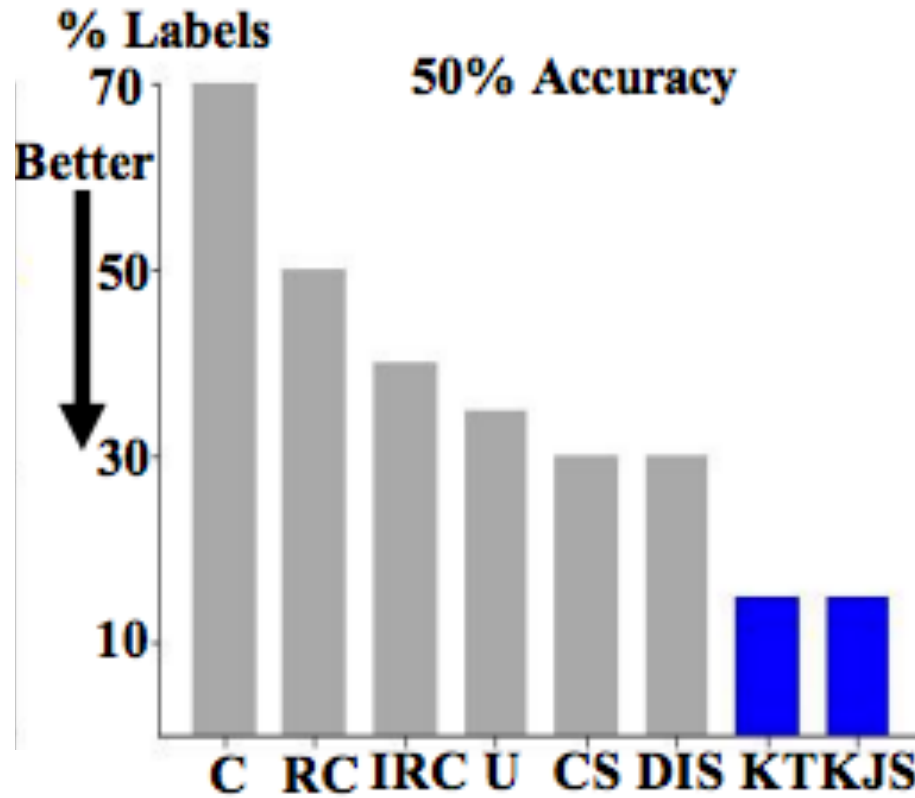
Table 3. Performance of different semi-supervised approaches (top), SESAR with STOA AL methods (middle) SESAR with AL+K methods (bottom) on NTU RGB+D 60 dataset.

Learning to Form Clearer Clusters



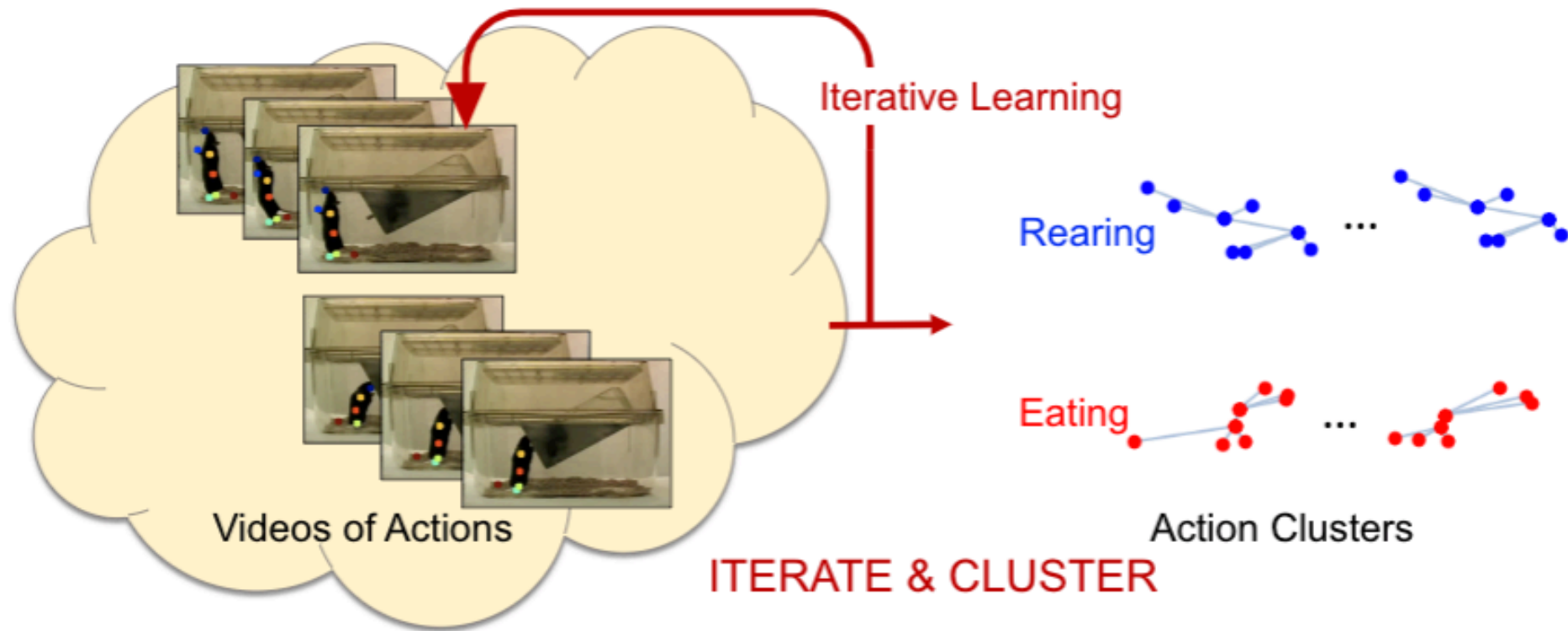
2D latent embedding (with t-SNE) for UWA-3D dataset across three training iterations.

Label Efficiency



Label requirement to achieve 80% accuracy on UWA-3D dataset.

Application: GUI DeepLabCluster



Application

Welcome | Manage Project | Cluster Data | Iterative Action Recognition

DeepLabCluster - Step 1. Create a New Project or Load a Project

Please choose an option:

New Project Load Project

Project Name:

Keypoints Data:

Load Keypoints Data

Choose Training Videos List File:

Choose Training Videos List

Optional Attributes

Select the directory where project will be created

Ok

Help

Reset

Edit Config File

Application

Welcome | Manage Project | **Cluster Data** | Iterative Action Recognition

DeepLabCluster - Step 2. Form Data into Clusters (Train Predict&Cluster Net)

Update Cluster Map Every (Epochs) Save Cluster Map Every (Epochs) Maximum Epochs

Cluster Map Epoch 9

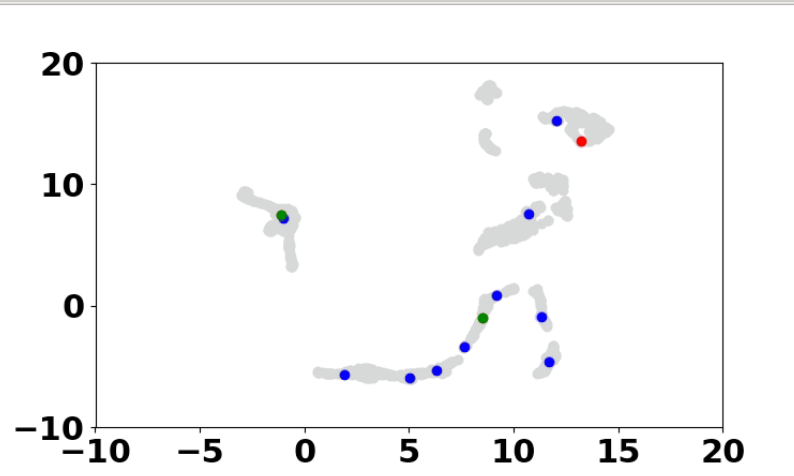
X	Y
-5	15
-4	12
-3	10
-2	9
-1	8
0	-4
1	-5
2	-6
3	-7
4	-8
5	-7
6	-6
7	-5
8	-4
9	-3
10	-2
11	-1
12	0
13	1
14	2
15	3
16	4
17	5
18	6
19	7
10	12
11	13
12	14
13	15
14	16
15	17
16	18
17	19
18	20

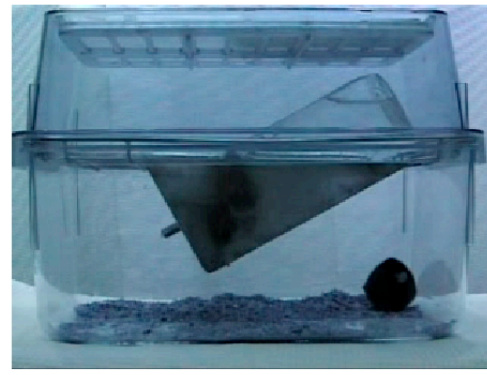
Application

Welcome | Manage Project | Cluster Data | Iterative Action Recognition

DeepLabCluster - Step 3. Iterative Action Recognition with Sampled Annotation

Selection Method: # Samples per Selection:





Class name

- drinking
- eating
- grooming
- hanging
- heading
- rearing
- resting
- walking

Perform Action Recognition

Stop Action Recognition

Next Selection

Reset

Help

Save Selection

Load videos | Replay | >>Next

Thanks!