

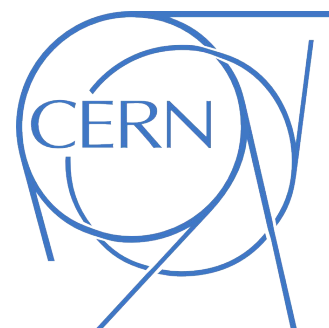
TORCH: Pattern recognition and particle identification performance

11th International Workshop on Ring Imaging Cherenkov Detectors

12th-16th of September 2022

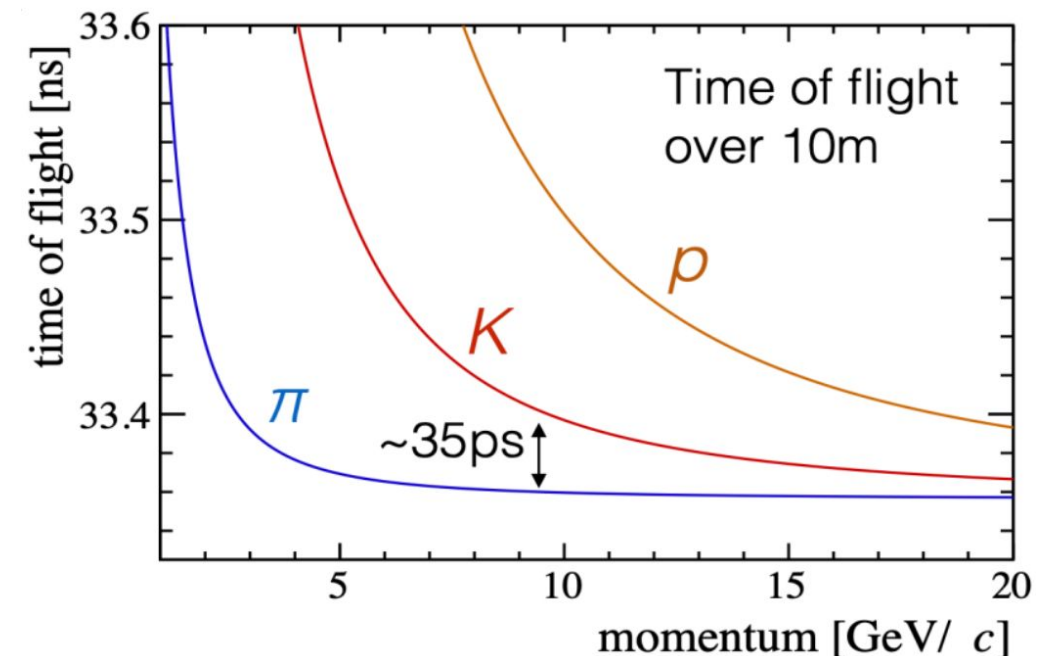
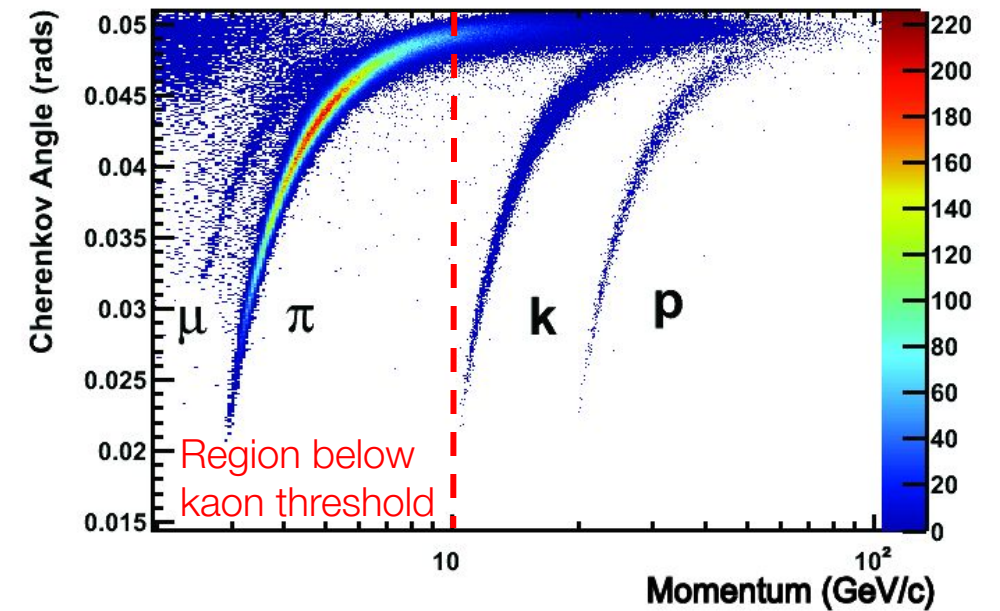
Luis Miguel Garcia Martin

On behalf of the TORCH collaboration



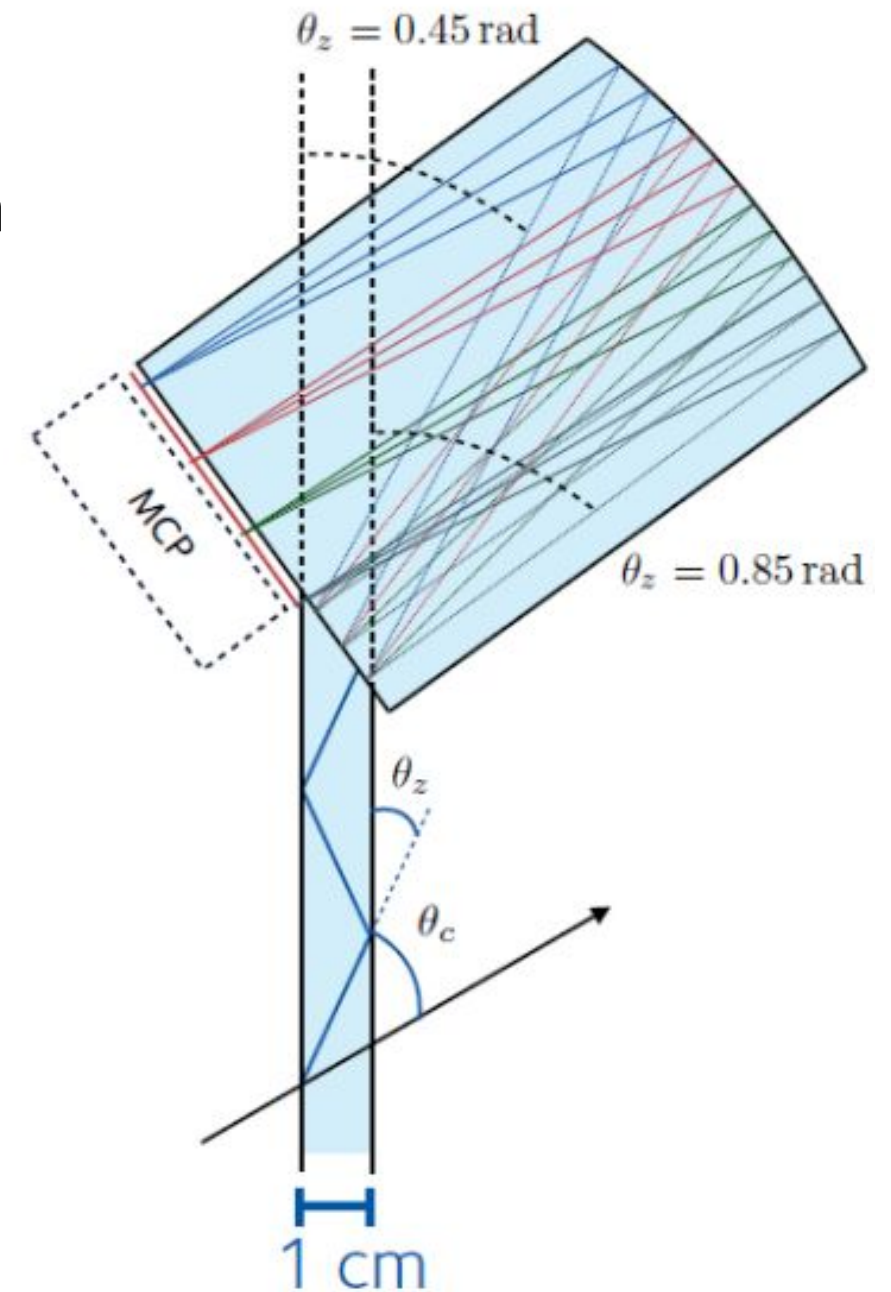
Introduction

- PID at LHCb currently provided by 2 RICH detectors
- **TORCH:** Proposed solution to enhance low momentum (2-20 GeV/c) particle identification at LHCb:
 - Covers region where kaons are below threshold in the LHCb RICH detectors
- **Exploit time-of-flight (ToF) for particle ID:**
 - $\Delta\text{ToF}(K-\pi) \sim 35\text{ps}$ for a 10m flight path
 - Aim for $\sim 10\text{-}15\text{ps}$ per track for 3σ K/ π separation



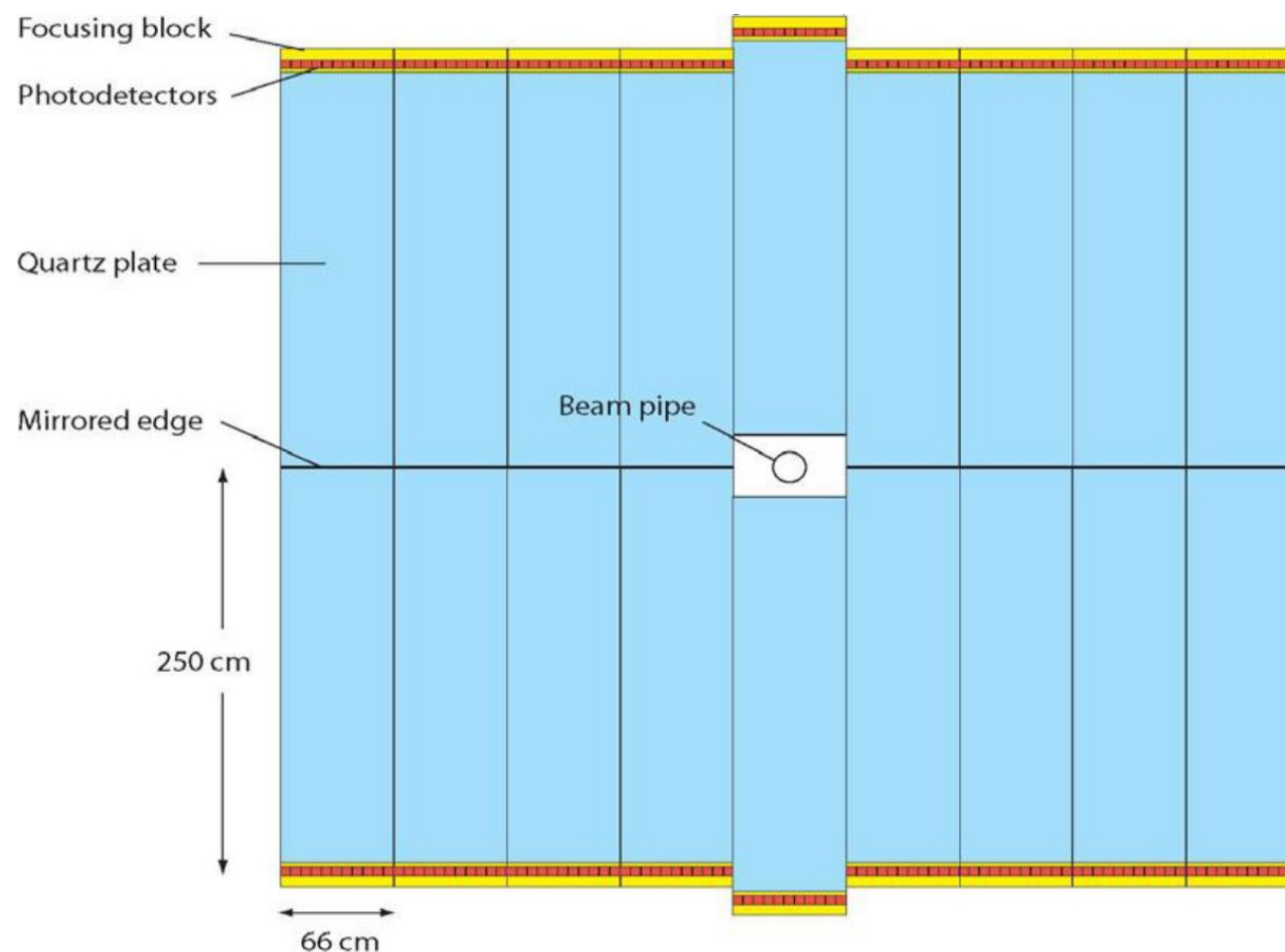
The TORCH principle

- Charged particles passing through a quartz plate generate prompt Cherenkov photons
- Photons are propagated via total internal reflection to the periphery of the detector
- A cylindrical focusing block focuses the photons onto an array of photon detectors
 - MCP position maps to θ_z
- Photon arrival time and position is measured to derive:
 - Cherenkov angle and path length
 - Photon propagation time
 - Expect ~ 30 detected photons per track ($\sigma_t = 70\text{ps}$)
- Method is related to that used by the BaBar DIRC and Belle II TOP



TORCH design

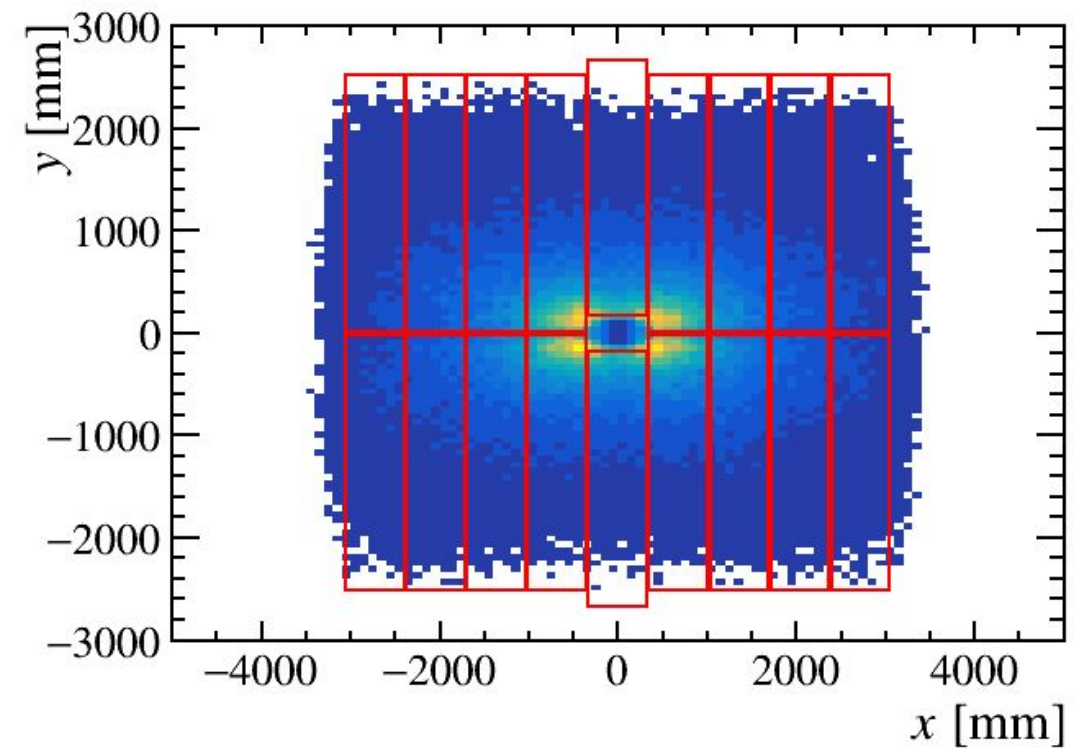
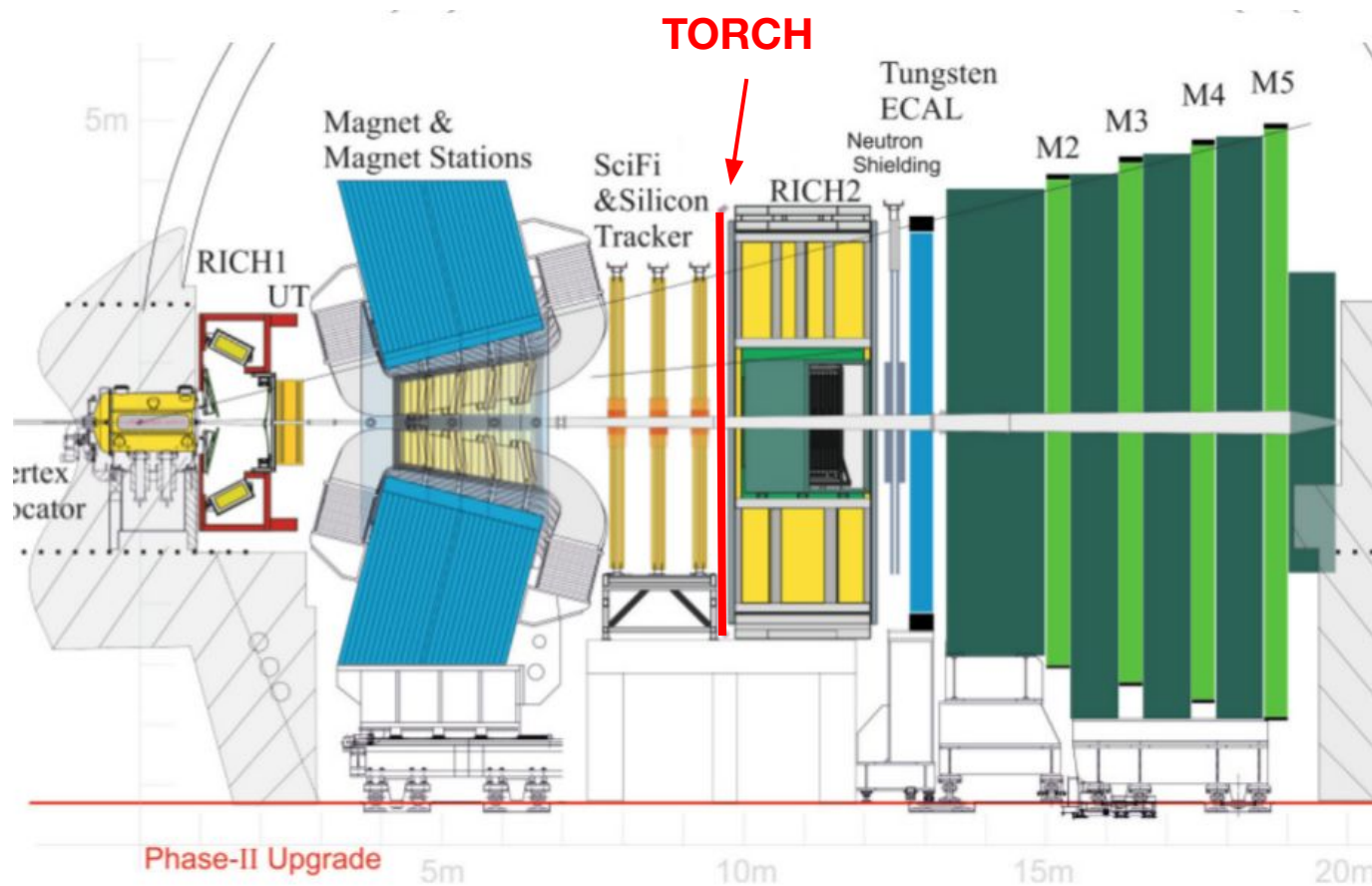
- 18 identical modules $250 \times 66 \times 1 \text{ cm}^3$ (covering and area of $\sim 5 \times 6 \text{ m}^2$)
- Full TORCH implementation now planned for future LHCb upgrade at the HL-LHC ([LHCb upgrade II framework TDR \[LHCB-TDR-023\]](#))
- See Maarten Van Dijk's talk tomorrow for more details on design and photon detectors



TORCH design

- Proposal to install TORCH in front of RICH2, in LS4 (for ~2033)
- TORCH will be located at 9.5m of the interaction point
- Need to cover a wide area

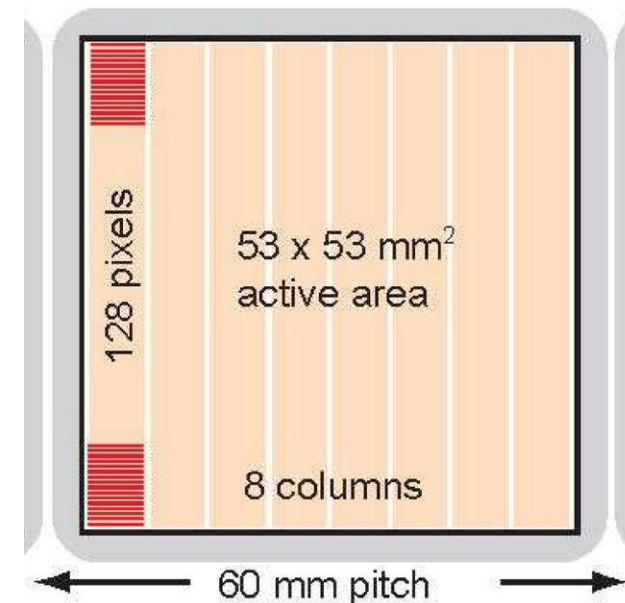
Extrapolated reconstructed track position of
2-20 GeV/c tracks to TORCH



Simulation

- TORCH detector simulated using GEANT4 in the LHCb framework
- Simple simulation of the quartz radiator and focussing block:
 - Free-standing (no support structure)

- Simulation includes processes for:
 - Cherenkov emission
 - Reflection and refraction
 - Rayleigh scattering
 - Surface roughness




- Simplified model of the digitisation with charge-spread and deadtime
 - 64x8 pixels of 0.8 x 6.4 mm²
 - Achieved effective granularity of 128x8 via charge-sharing
- 25ns time window (some photons will arrive out of time)

[\[JINST 10 \(2015\) C05003\]](#)

Reconstruction

- **Time-of-flight** derived from:

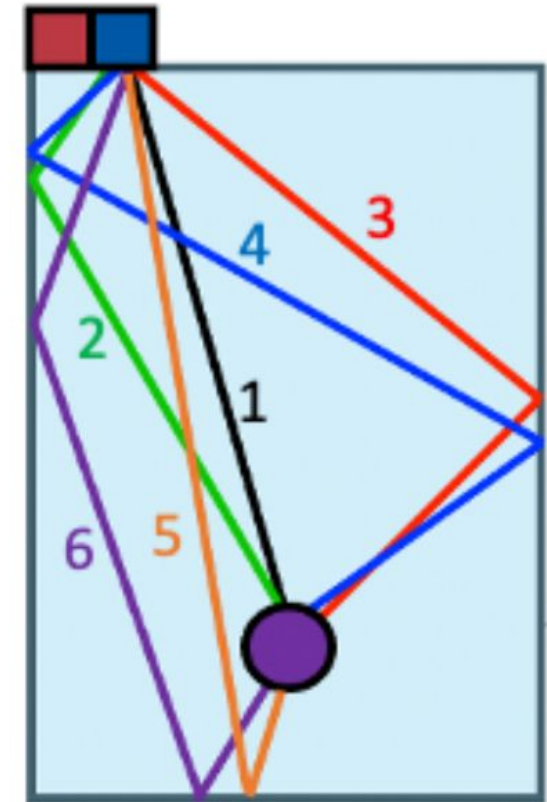
Photon arrival time (measured) 

$$t_{\text{arrival}} = t_0 + \frac{d_{\text{track}}}{\beta c} + \frac{d_{\text{prop}}}{v_{\text{group}}}$$

- **Production time**: Derived from TORCH
 - Expected to have timing from VELO: Fast timing in a small region around the vertex (LHCb Upgrade II)
- **Time-of-flight**: Test different mass hypotheses (β)
 - Determine the path length of the track by spline interpolation between track measurements
 - Extrapolate tracks to TORCH radiator (equation of motion considering mult. scat.)
- **Photon propagation**: Affected by chromatic dispersion, $n_{\text{group}}(E_\gamma)$
 - d_{prop} is the photon path length
 - v_{group} is derived from θ_c

Reconstruction

- Each hit (photon in the MCP) is back-propagated and associated to a track
 - Analytical photon back-propagation
 - Considering several reflections (sides/bottom) → ambiguity
 - Most combinations (order reflections) discarded do not give a valid solution (hit position not compatible with measured time)

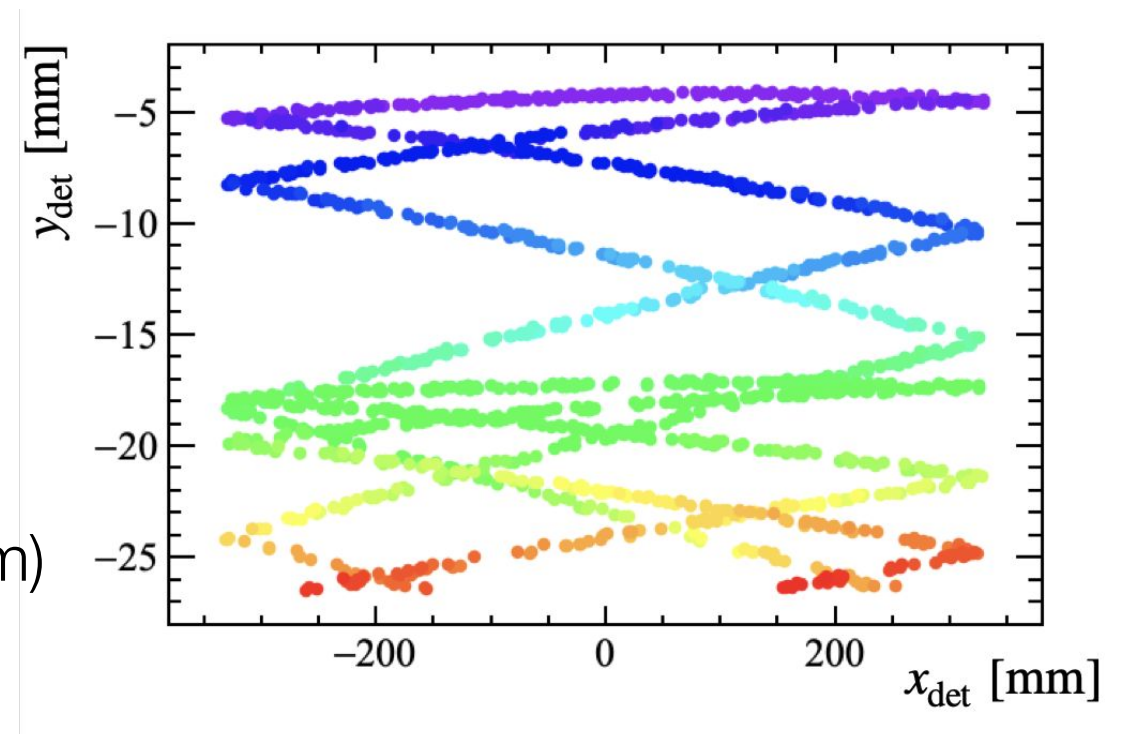


front-back reflections not visible here (no ambiguity for them)

Reconstruction

- Each hit (photon in the MCP) is back-propagated and associated to a track
 - Analytical photon back-propagation
 - Considering several reflections (sides/bottom) → ambiguity
 - Most combinations (order reflections) discarded do not give a valid solution (hit position not compatible with measured time)
- Cherenkov cone results in hyperbola-like patterns (folded by reflections) in x-y plane

Photons at the MCP from a single (repeated) track



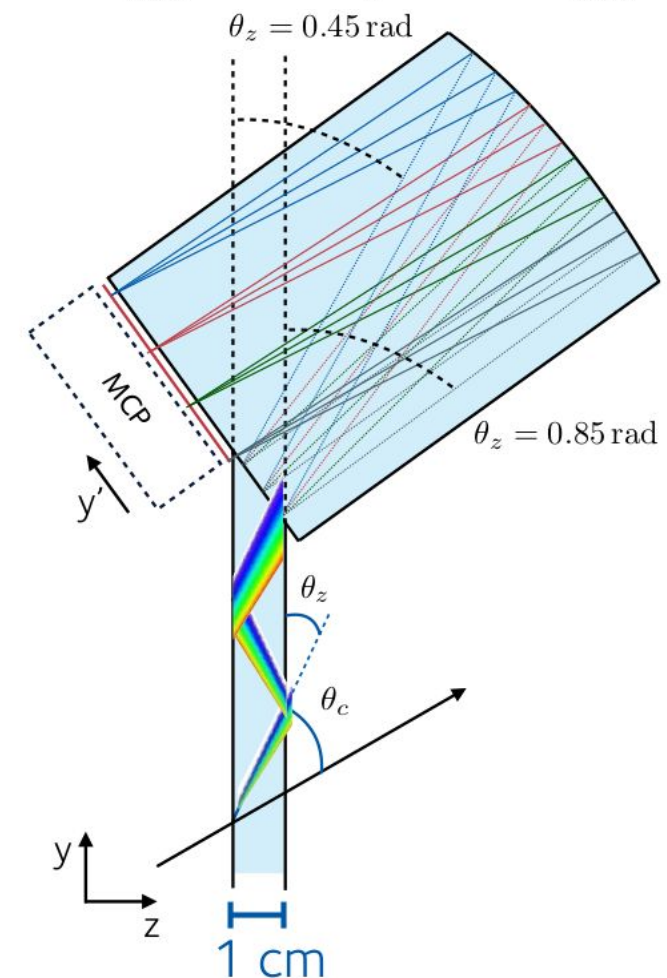
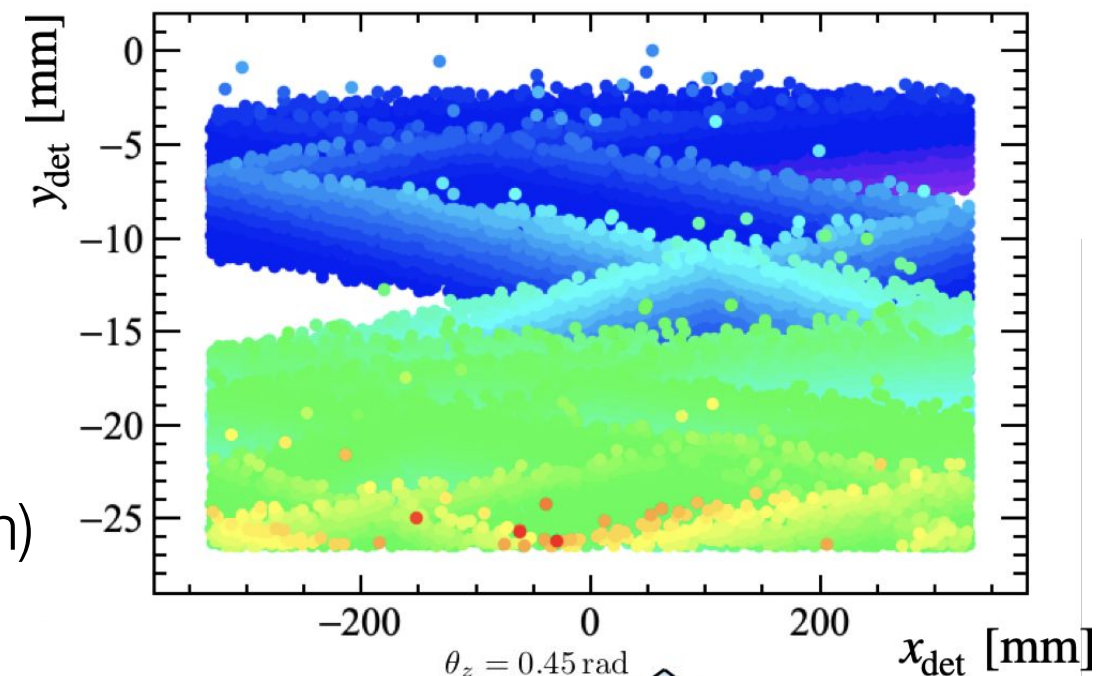
Color codes the time or arrival of the photon:

- **Early arriving (~15ns)**
- **Late arriving (~25ns)**

Reconstruction

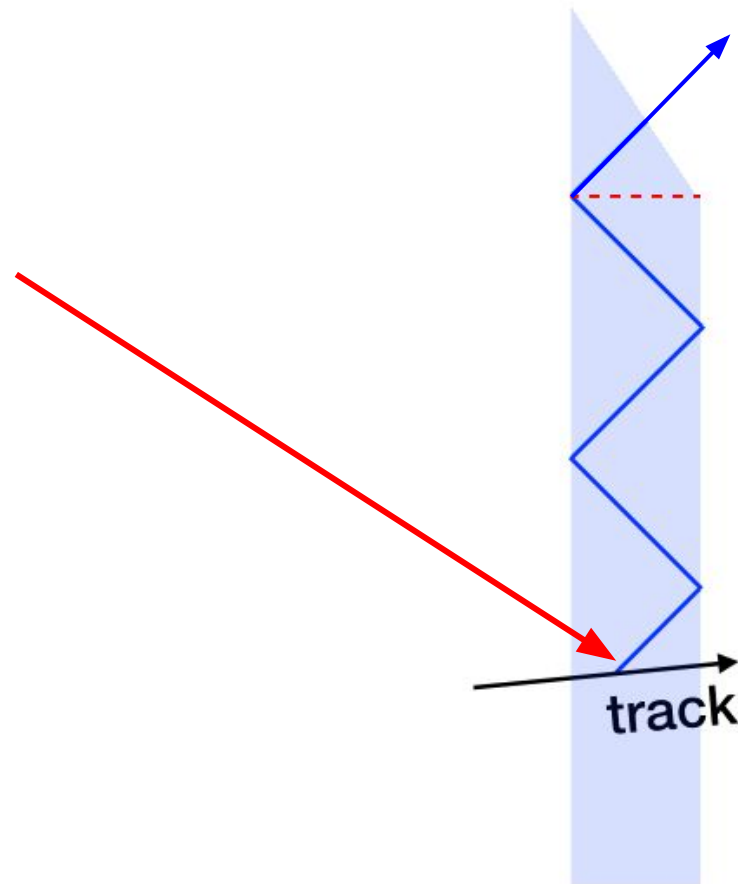
- Each hit (photon in the MCP) is back-propagated and associated to a track
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 - Considering several reflections (sides/bottom) → ambiguity
 - Most combinations (order reflections) discarded do not give a valid solution (hit position not compatible with measured time)
- Cherenkov cone results in hyperbola-like patterns (folded by reflections) in x-y plane
- Chromatic dispersion spreads line into band

Photons at the MCP from a single (repeated) track



Reconstruction: Assumptions

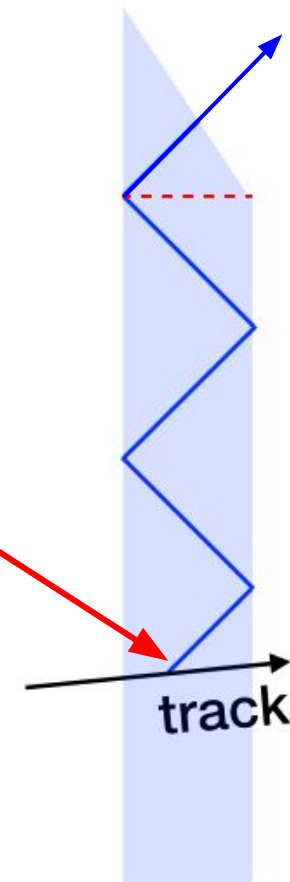
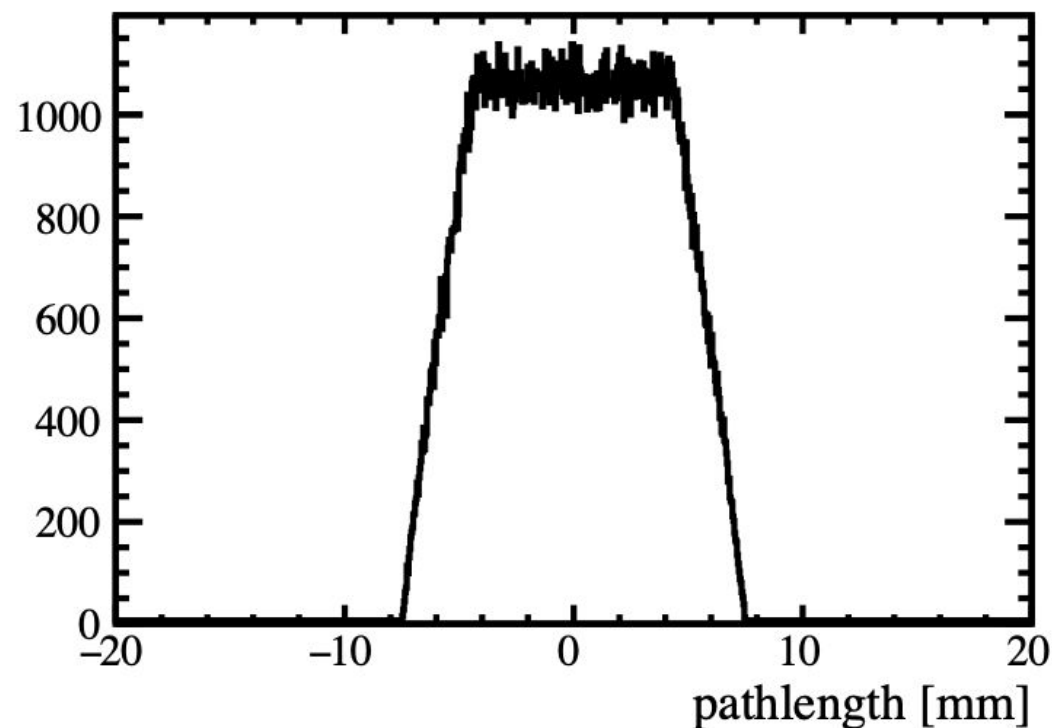
- Assume each photon:
 - Emitted in the centre of the radiator



Reconstruction: Assumptions

- Assume each photon:
 - Emitted in the centre of the radiator
- Results in a smearing in time due to the incorrect path length assumptions of $O(20\text{ps})$

path length difference [mm]

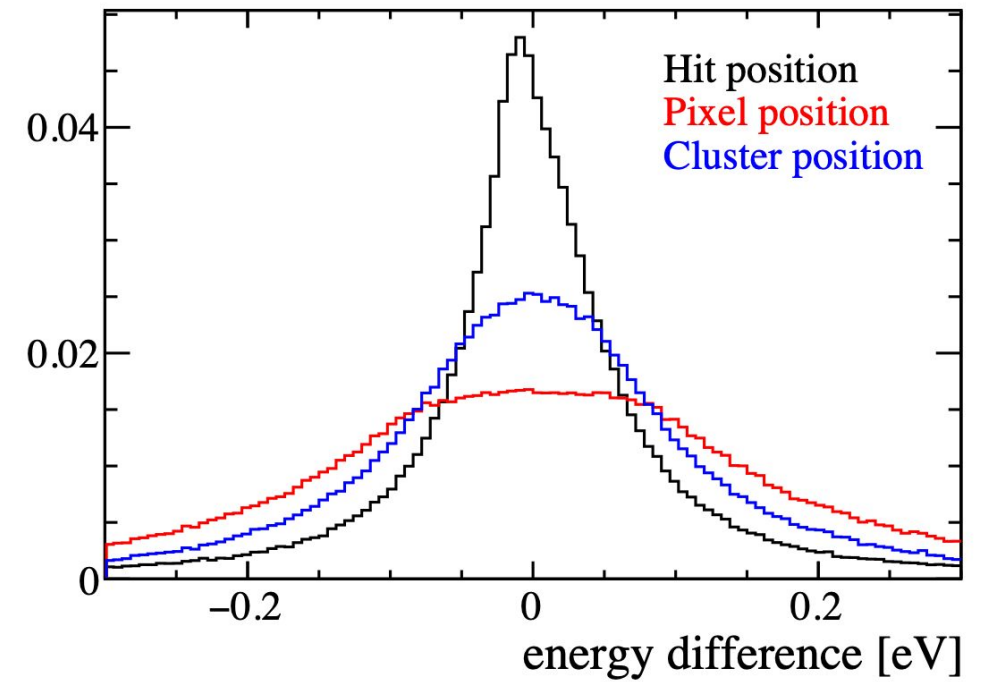
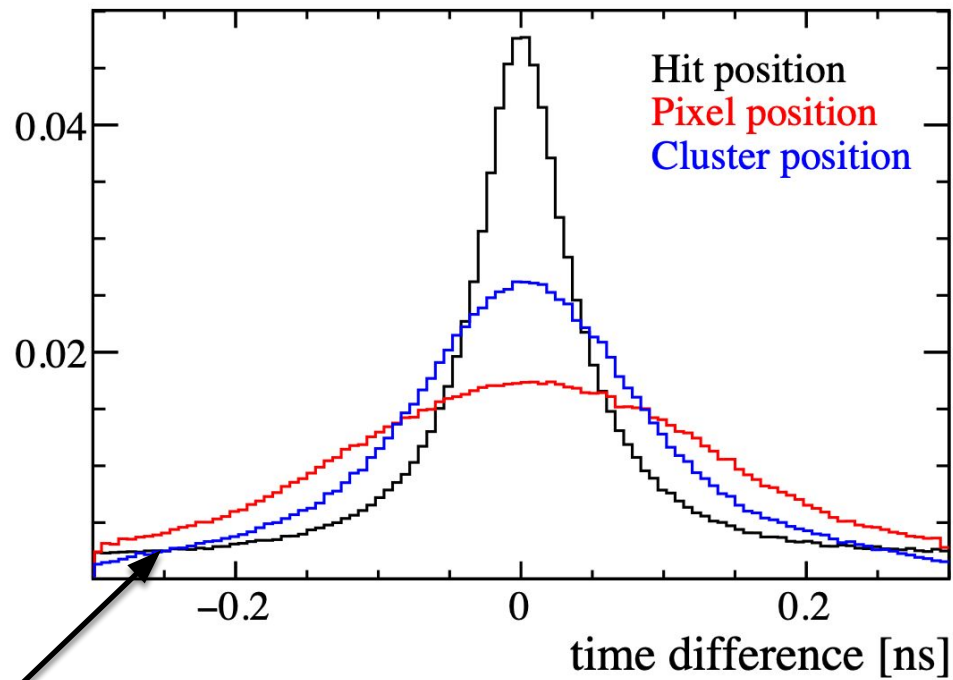


Reconstruction: Photon resolution

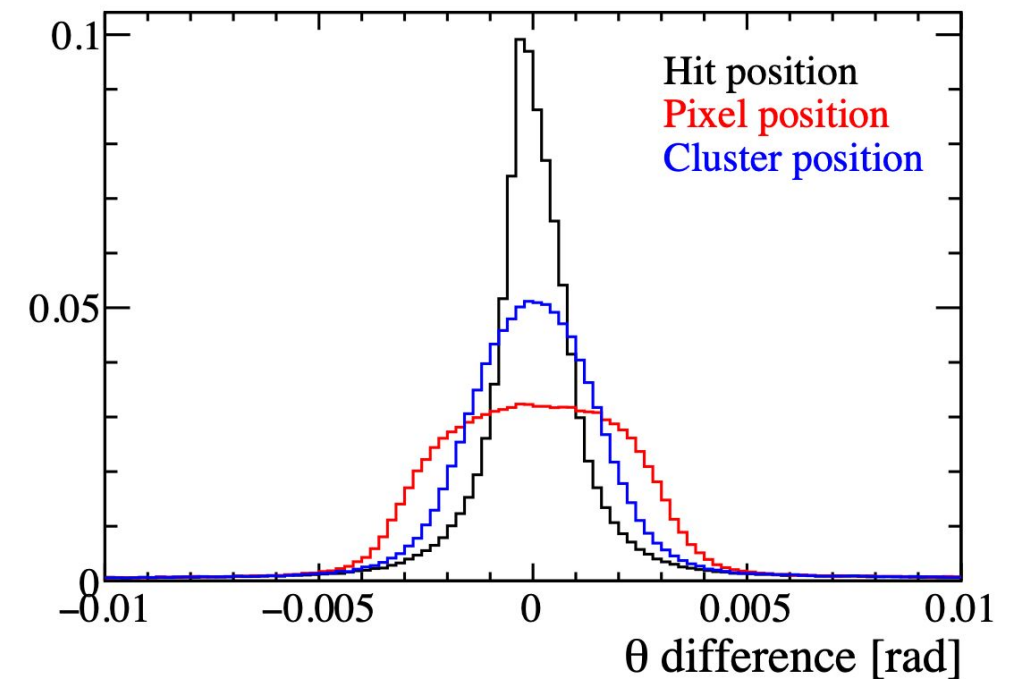
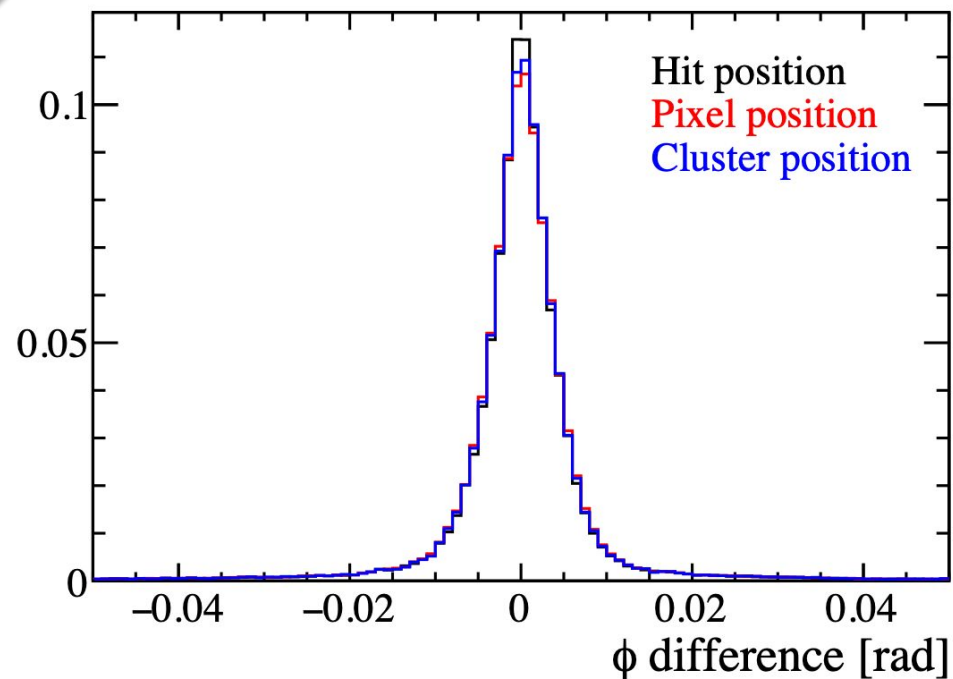
Hit: True photon arrival position

Pixel: Pixel hit by the photon arrival

Cluster: Weighted charge-average of all pixels fired by the photon (~1-2 pixels)

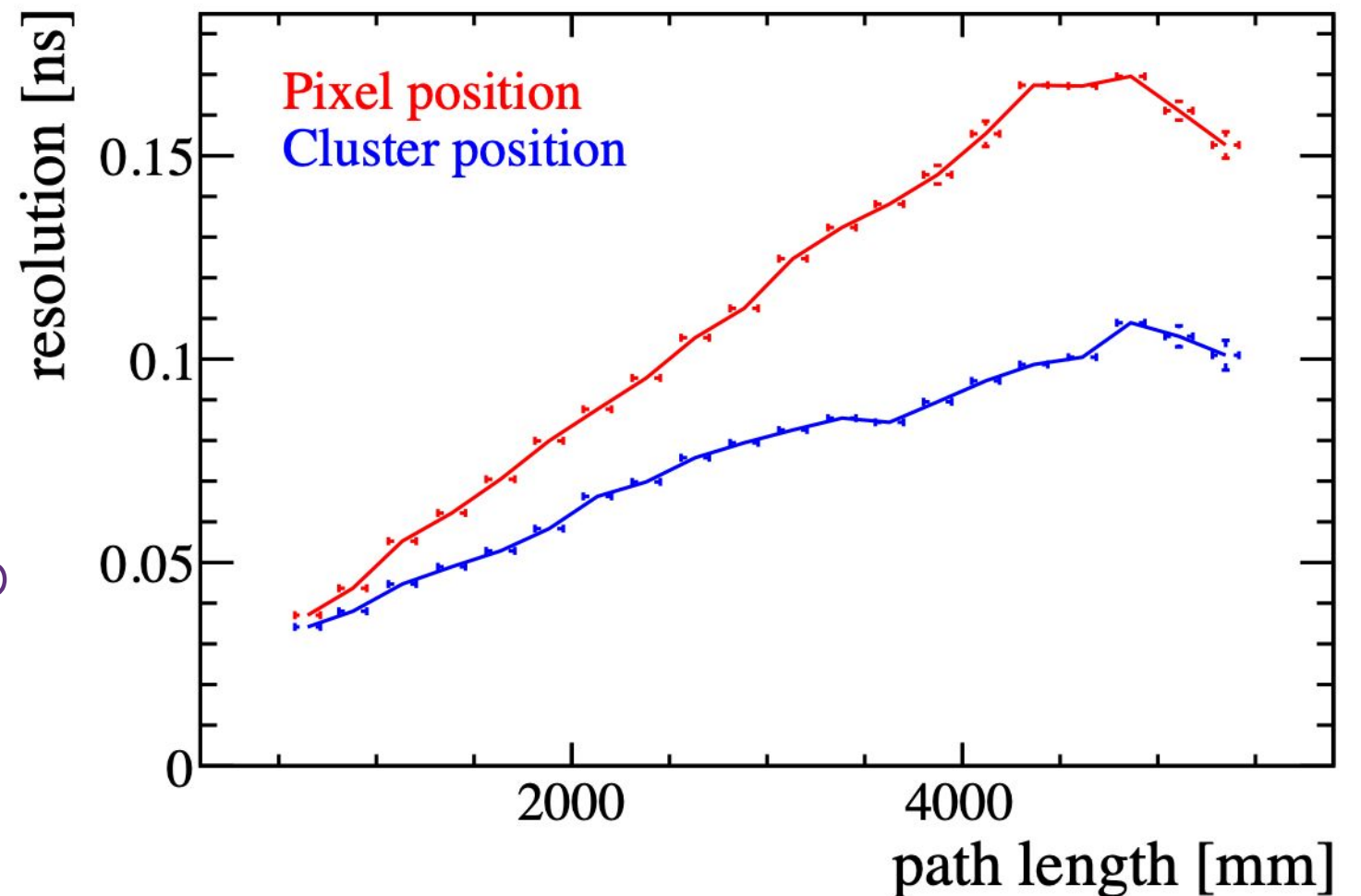


Long tails due to incorrect assumption on the number of reflections



Reconstruction: resolution

- See (expected) linear dependence on path length due to chromatic dispersion and finite pixel size.
- Limited resolution is due to:
 - ▶ The unknown emission point and entrance point to the focusing block.
 - ▶ Resolution on the track slope and multiple scattering in the radiator.



Resolution from the MCP and readout electronics is not included here

Reconstruction

- The log-likelihood for a given track/hypothesis combination is given by:

$$\log L = \sum_{\text{pixel } i} \log \left(\sum_{\substack{\text{track } j \\ j \neq t}} \frac{N_j}{N_{\text{tot}}} P_j(\vec{x}_i'' | h_j^{\text{best}}) + \frac{N_t}{N_{\text{tot}}} P_t(\vec{x}_i'' | h_t) + \frac{N_{\text{bkg}}}{N_{\text{tot}}} P_{\text{bkg}}(\vec{x}_i'') \right)$$

PDF for "best" hypothesis assignment for other tracks

PDF for considered track

Background contribution (assumed flat)

Reconstruction: Unbinned

- The log-likelihood for a given track/hypothesis combination is given by:

$$\log L = \sum_{\text{pixel } i} \log \left(\sum_{\substack{\text{track } j \\ j \neq t}} \frac{N_j}{N_{\text{tot}}} P_j(\vec{x}_i'' | h_j^{\text{best}}) + \frac{N_t}{N_{\text{tot}}} P_t(\vec{x}_i'' | h_t) + \frac{N_{\text{bkg}}}{N_{\text{tot}}} P_{\text{bkg}}(\vec{x}_i'') \right)$$

- Best hypothesis determined by iteration
 - Initially assigned the pion hypothesis
 - In n-iteration, assigned best hypothesis from (n-1)-iteration
- Converges after 3-4 iterations

Reconstruction

- The log-likelihood for a given track/hypothesis combination is given by:

$$\log L = \sum_{\text{pixel } i} \log \left(\sum_{\substack{\text{track } j \\ j \neq t}} \frac{N_j}{N_{\text{tot}}} P_j(\vec{x}_i'' | h_j^{\text{best}}) + \frac{N_t}{N_{\text{tot}}} P_t(\vec{x}_i'' | h_t) + \frac{N_{\text{bkg}}}{N_{\text{tot}}} P_{\text{bkg}}(\vec{x}_i'') \right)$$

Component fractions are fixed

- Estimate N_j by forward propagating 1000 photons through the optics
 - Position computed analytically (no need to ray-trace)
- Can't afford to find the yields in a fit (fractions fixed)

- Need to assume $N_{\text{bkg}} = N_{\text{tot}} - \sum_j N_j$

Reconstruction

- The log-likelihood for a given track/hypothesis combination is given by:

$$\log L = \sum_{\text{pixel } i} \log \left(\sum_{\substack{\text{track } j \\ j \neq t}} \frac{N_j}{N_{\text{tot}}} P_j(\vec{x}_i'' | h_j^{\text{best}}) + \frac{N_t}{N_{\text{tot}}} P_t(\vec{x}_i'' | h_t) + \frac{N_{\text{bkg}}}{N_{\text{tot}}} P_{\text{bkg}}(\vec{x}_i'') \right)$$

- Determine the PDF for a given track/hypothesis combination from:

$$P(\vec{x}'' | h) = |J| P(E_\gamma, \phi_c, t_0)$$

- Initial PDF factorizes

$$P(E_\gamma, \phi_c, t_0) = P(E_\gamma) P(\phi) P(t_0)$$

Frank-Tamm +
efficiency

Normal distribution with
experimental time resolution

Reconstruction

- The log-likelihood for a given track/hypothesis combination is given by:

$$\log L = \sum_{\text{pixel } i} \log \left(\sum_{\substack{\text{track } j \\ j \neq t}} \frac{N_j}{N_{\text{tot}}} P_j(\vec{x}_i'' | h_j^{\text{best}}) + \frac{N_t}{N_{\text{tot}}} P_t(\vec{x}_i'' | h_t) + \frac{N_{\text{bkg}}}{N_{\text{tot}}} P_{\text{bkg}}(\vec{x}_i'') \right)$$

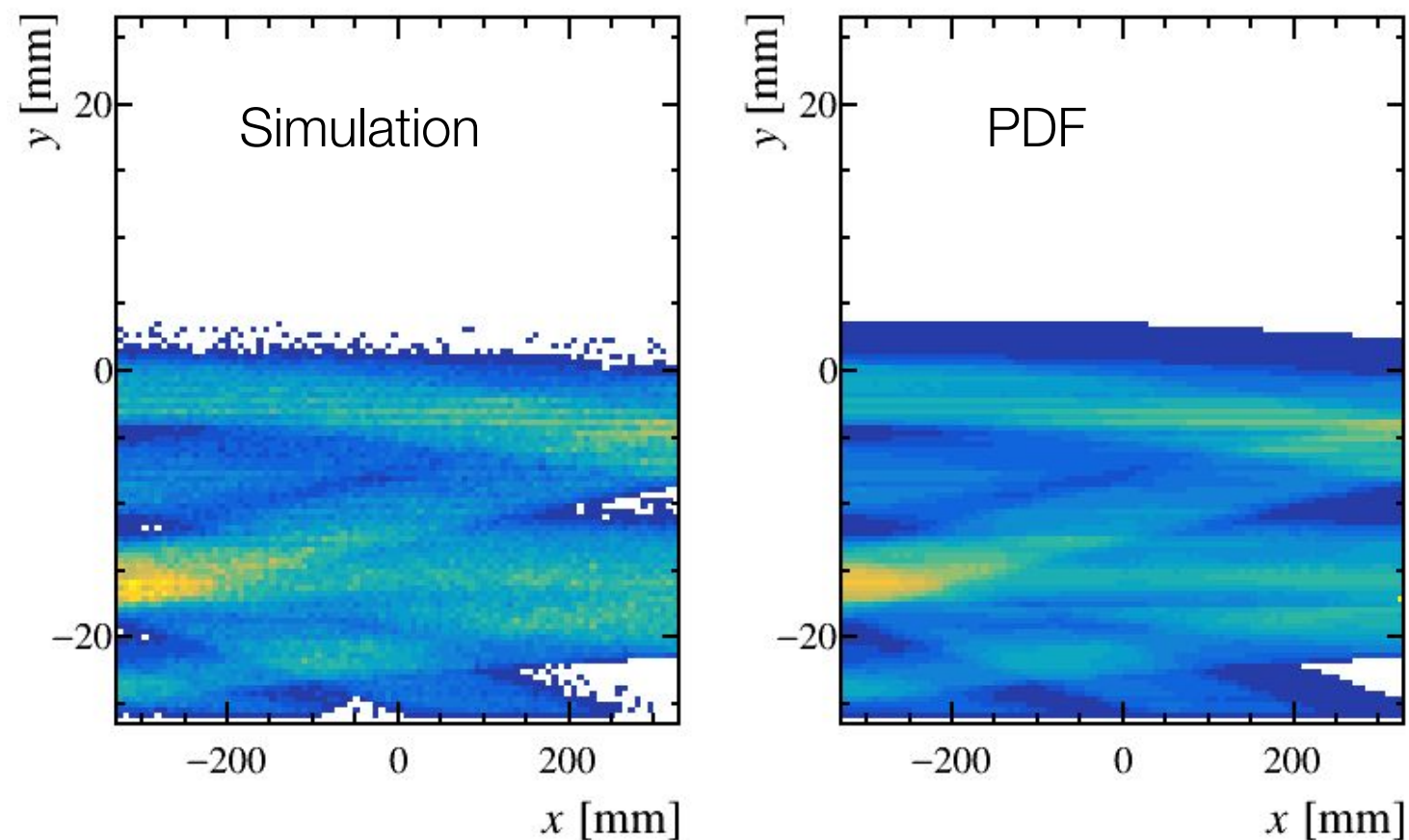
- Determine the PDF for a given track/hypothesis combination from:

$$P(\vec{x}'' | h) = |J| P(E_\gamma, \phi_c, t_0)$$

$$\text{with } J = \left| \begin{array}{cc} \frac{\partial y_d''}{\partial E_\gamma} & \frac{\partial x_d''}{\partial \phi_c} \\ \frac{\partial x_d''}{\partial E_\gamma} & \frac{\partial y_d''}{\partial \phi_c} \end{array} \right|$$

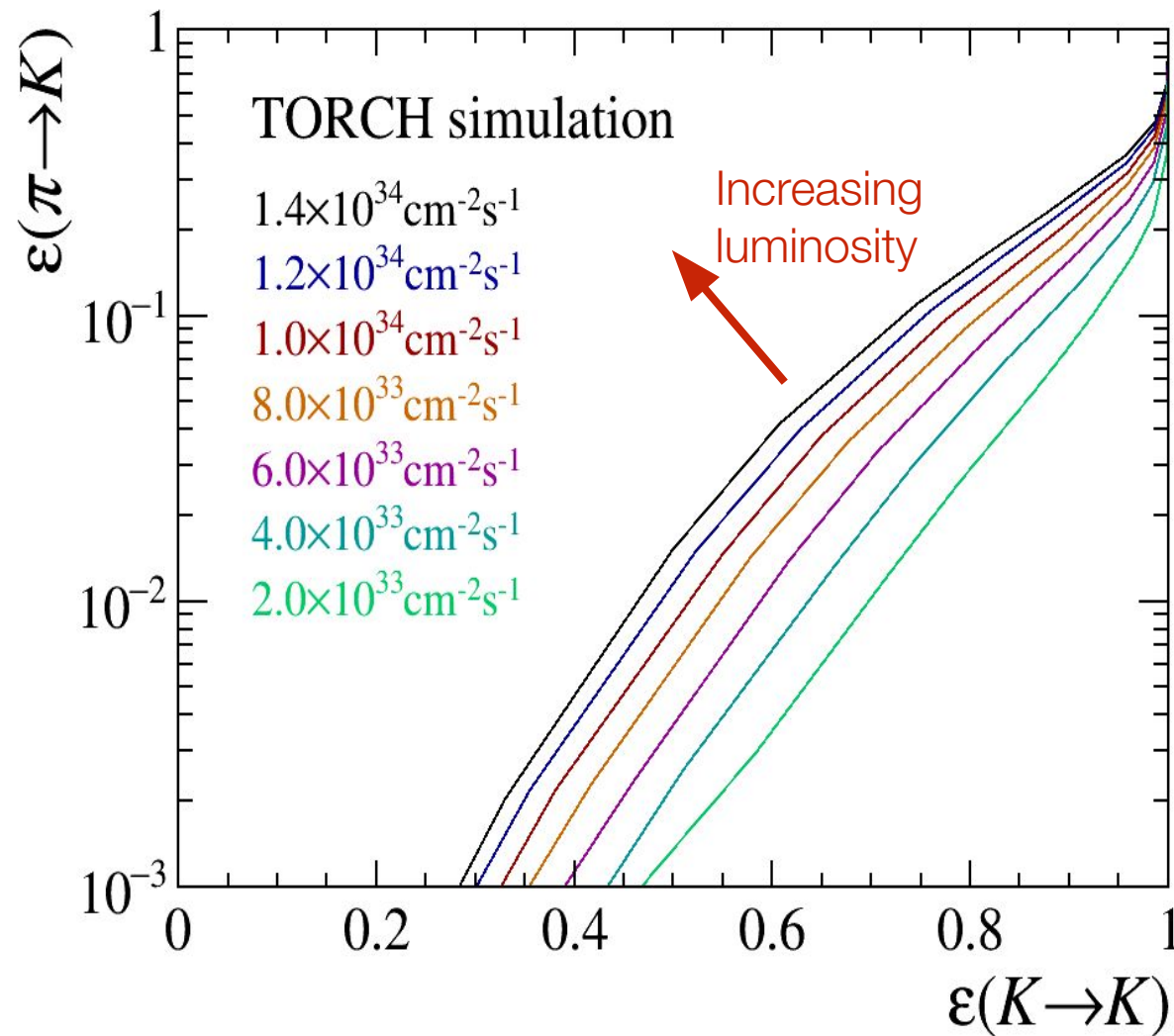
Reconstruction

- It is possible to check the correctness of the reconstructed PDF:
 - Propagate (simulate) a large number of photons ($\sim 10^6$) for each track
 - Compare simulation and analytical PDF
- Good agreement (even able to replicate complex structures)

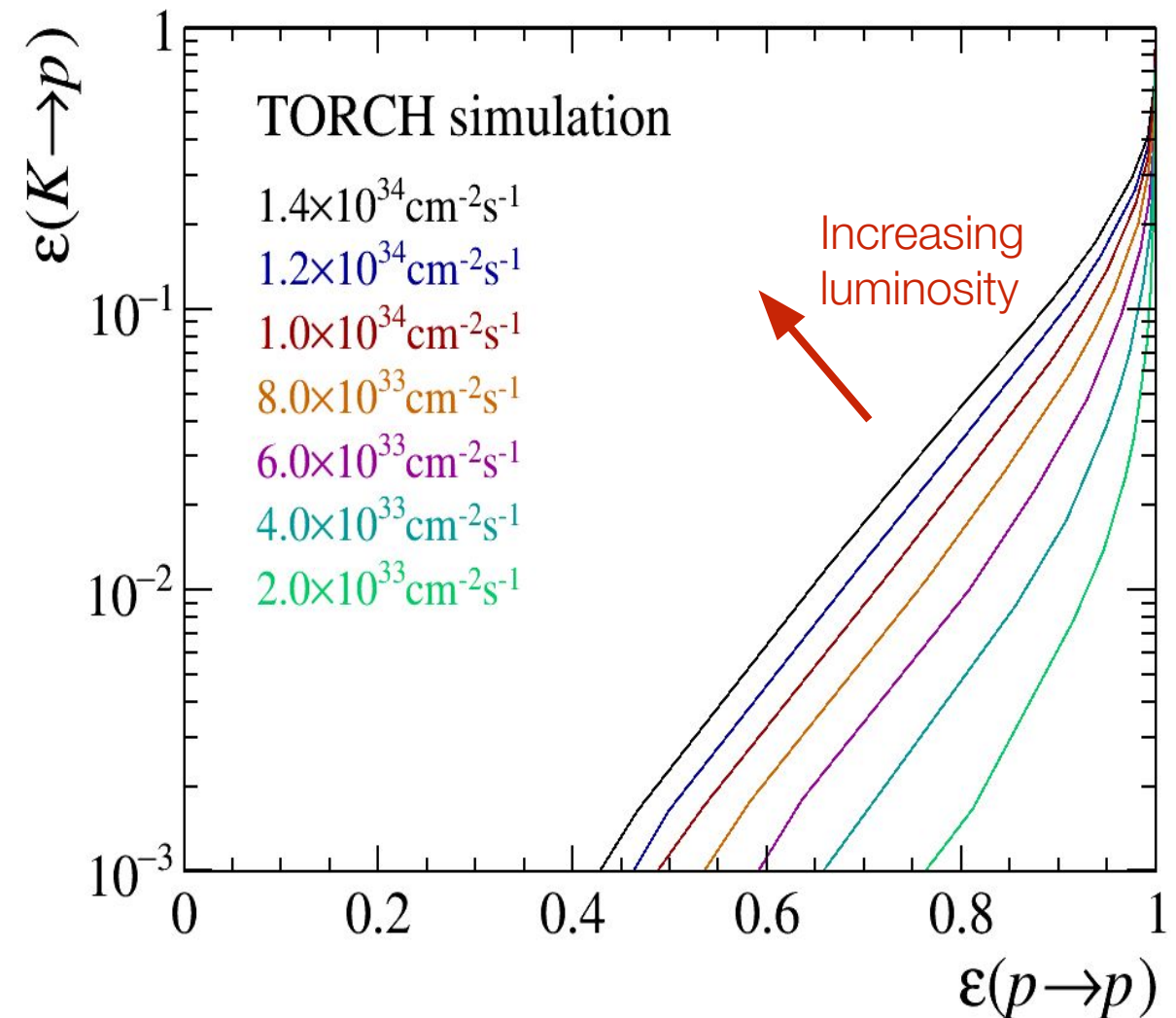


Performance versus luminosity

K- π separation

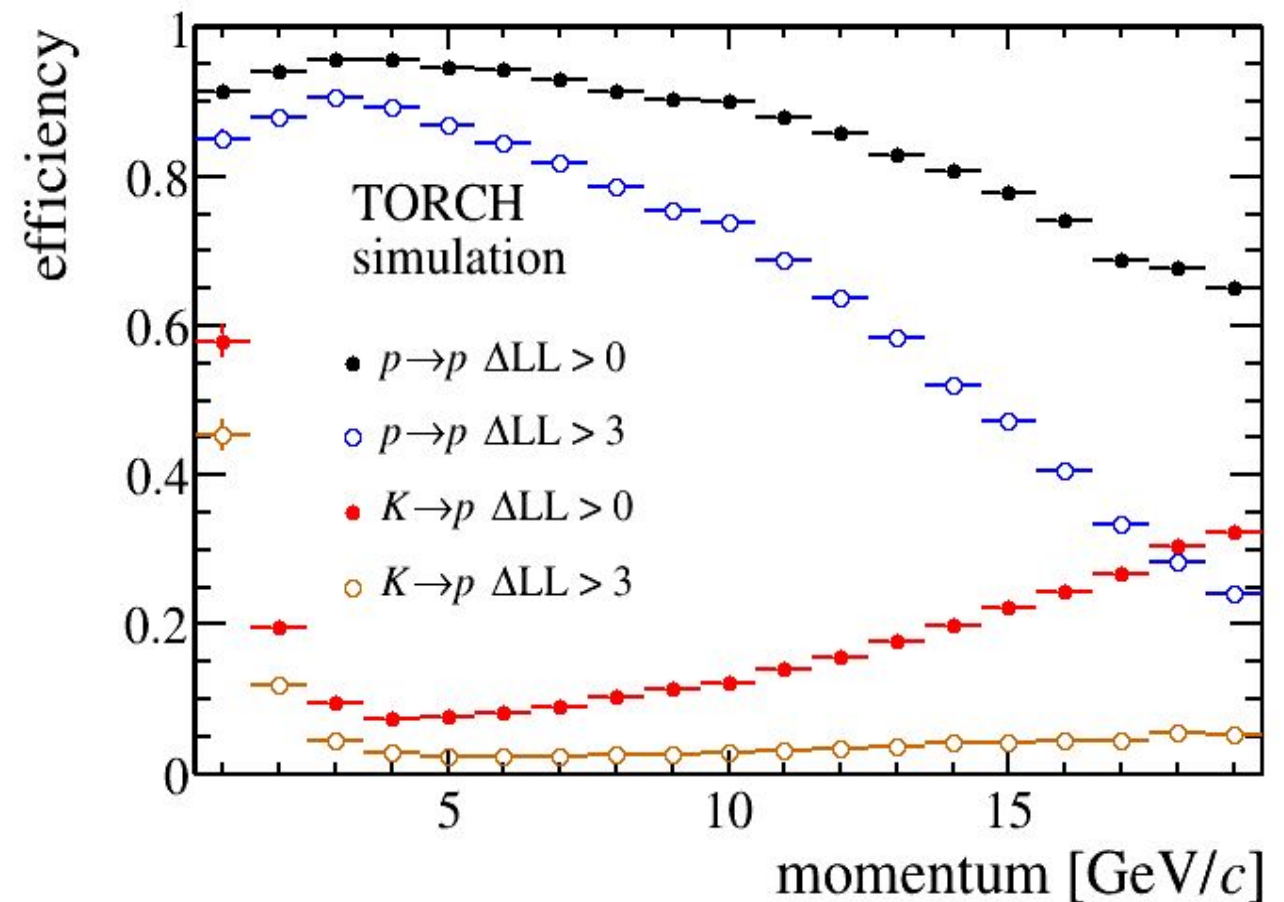
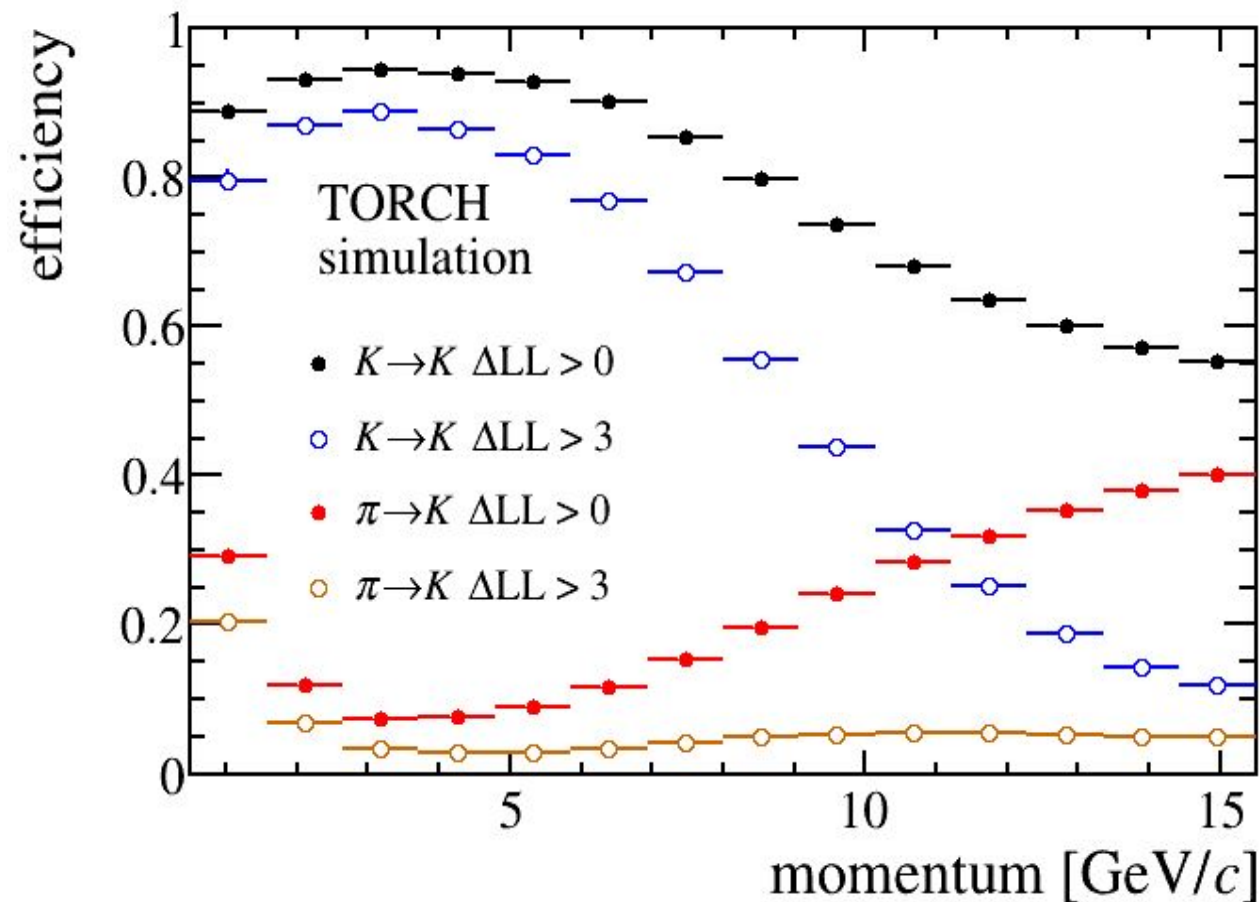


p-K separation



Performance with weighting

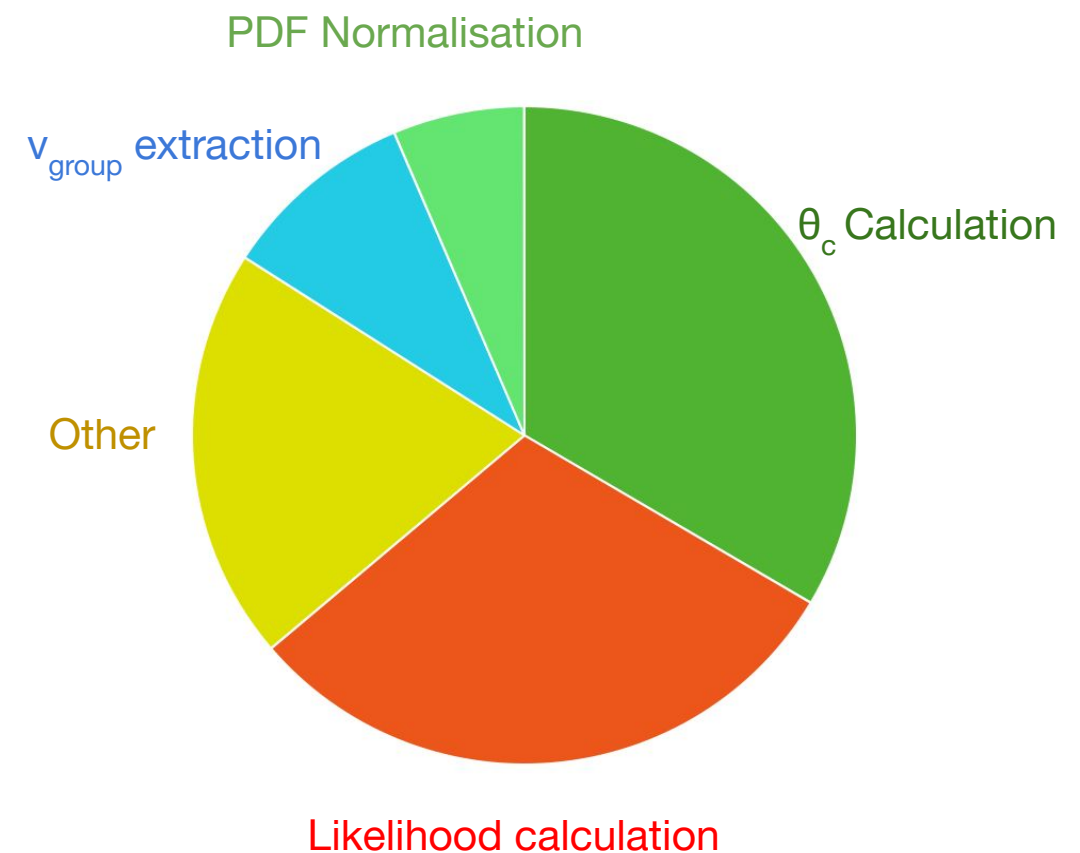
LHCb Upgrade II luminosity



- Combining samples to realistic LHCb Upgrade II instantaneous luminosity profile

CPU timing

- Current reconstruction takes ~1 second per event (Intel Core i5-10500 3.10GHz)
- Effort to optimise the algorithm:
 - Compiler optimisation options (-O).
 - Vectorisation
 - Change storage to avoid cache misses.
 - Look-up tables instead of expensive calculations
- Further optimisation can be possible
 - Using explicit SIMD data types
 - Use *const* functions and avoid control-flow (allow compiler optimisation)
 - Remove redundant calculations
 - “local” likelihood



CPU timing

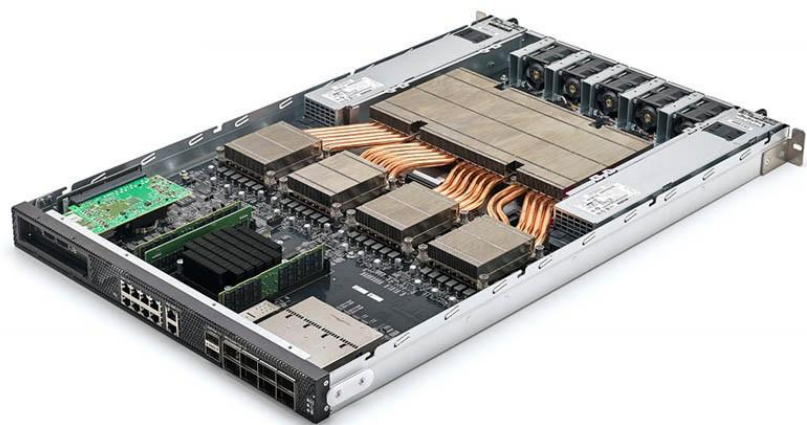
- The “local” approach of the likelihood:
 - Consider each track in isolation

$$\log L = \sum_{\text{pixel } i} \log \left(\frac{N_t}{N_{\text{tot}}} P_t(\vec{x}_i'' | h_t) + \frac{N_{\text{bkg}}}{N_{\text{tot}}} P_{\text{bkg}}(\vec{x}_i'') \right)$$

- no need to iterate in the likelihood calculation
- less optimal treatment of the background
 - However, performance is not significantly worse than in the global approach because there are backgrounds from e.g. γ conversions that do not have associated tracks
- Better suited to running on hardware accelerators than the nominal approach

Developments for IPUs/GPUs

- Significant speed-up could be possible using hardware accelerators (IPUs and GPUs)
- TORCH likelihood calculation is well suited to parallelisation:
 - Modules are independent
 - Probabilities for given hit/track/hypothesis combinations could be determined independently
- Memory access could be a bottleneck
- Development of TORCH photon mapping as proof-of-principle



IPU: Graphcore m2000



GPU: NVIDIA RTX A5000

Outlook

- The TORCH detector provides particle identification in the 2-20 GeV/c momentum range
- Good performance is seen for LHCb Upgrade II conditions
[\[CERN-LHCb-PUB-2022-006\]](#)
- Reconstruction algorithms developed and tested
[\[CERN-LHCb-PUB-2022-004\]](#) [\[CERN-LHCb-PUB-2022-007\]](#)
- Plan to submit documentation to journals
- Further improvements (speed-up) are on the way



Thanks for your attention



Photon time of propagation

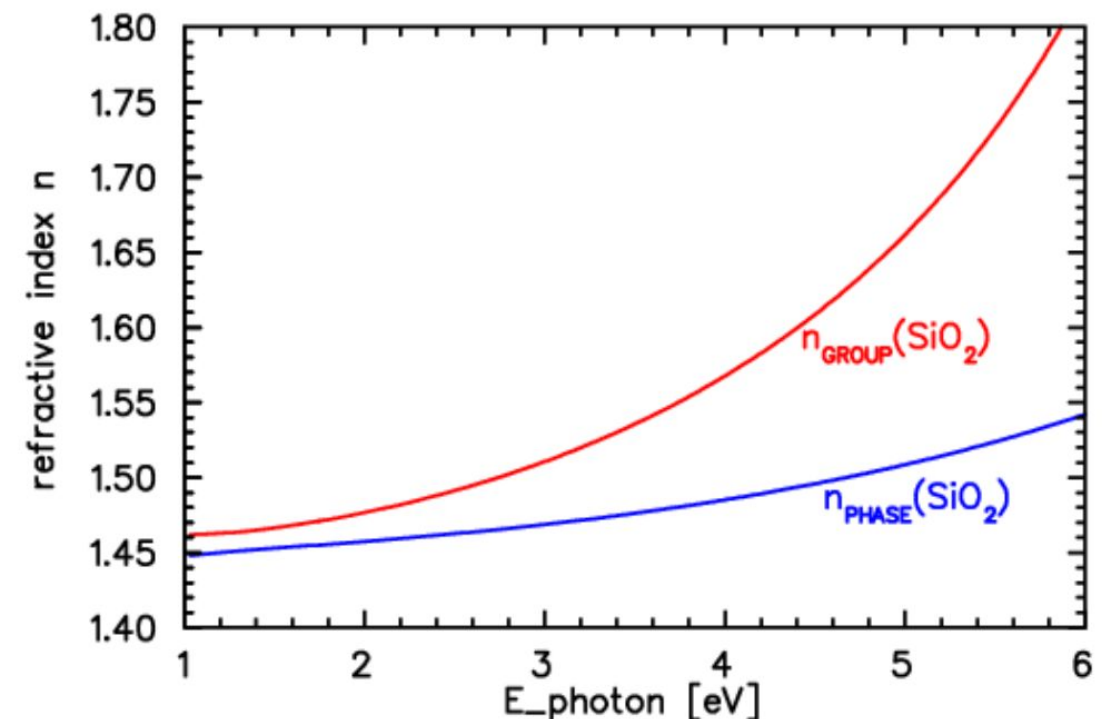
- Time of propagation (ToP) in quartz depends on the photon energy:

$$t = L/v_{\text{group}} = Ln_{\text{group}}/c$$

- Cherenkov angle (θ_c) and arrival time (t_{arrival}) measured at the top of a bar radiator
- Derive n_{phase} from θ_c for K, π , ρ hypotheses

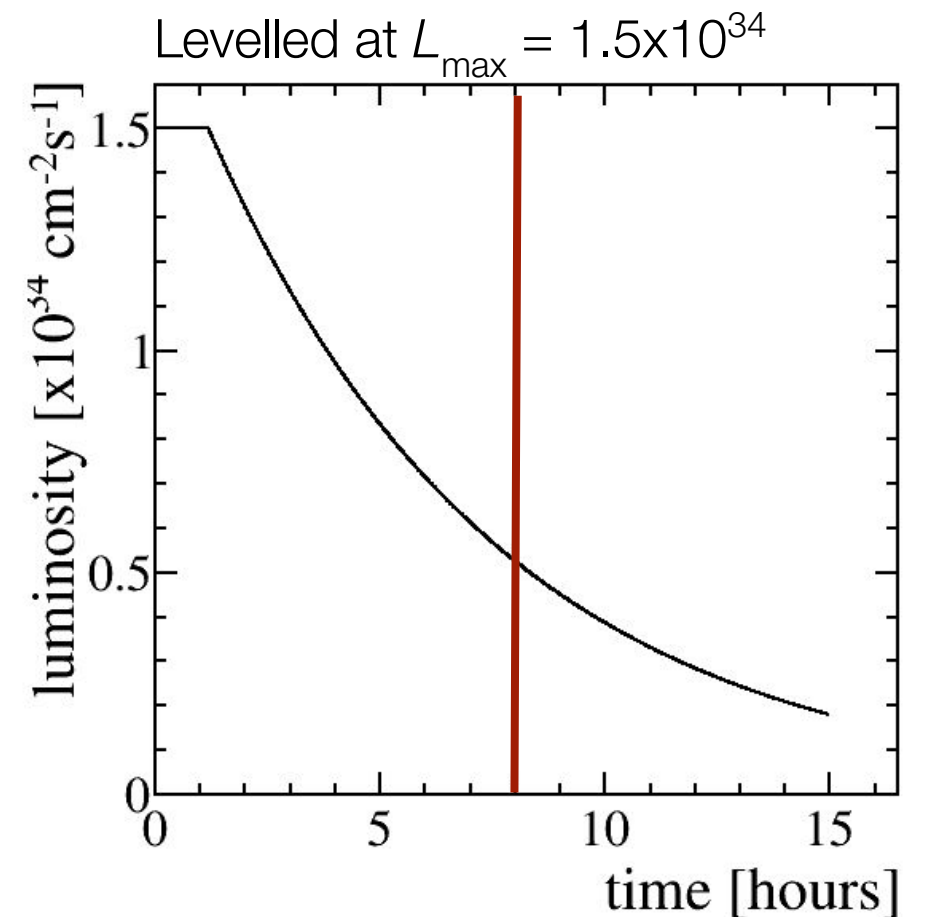
$$\cos \theta_c = (\beta n_{\text{phase}})^{-1}$$

- Use dispersion relation for to get n_{group}
- Determine the ToP from the reconstructed photon path length and n_{group}



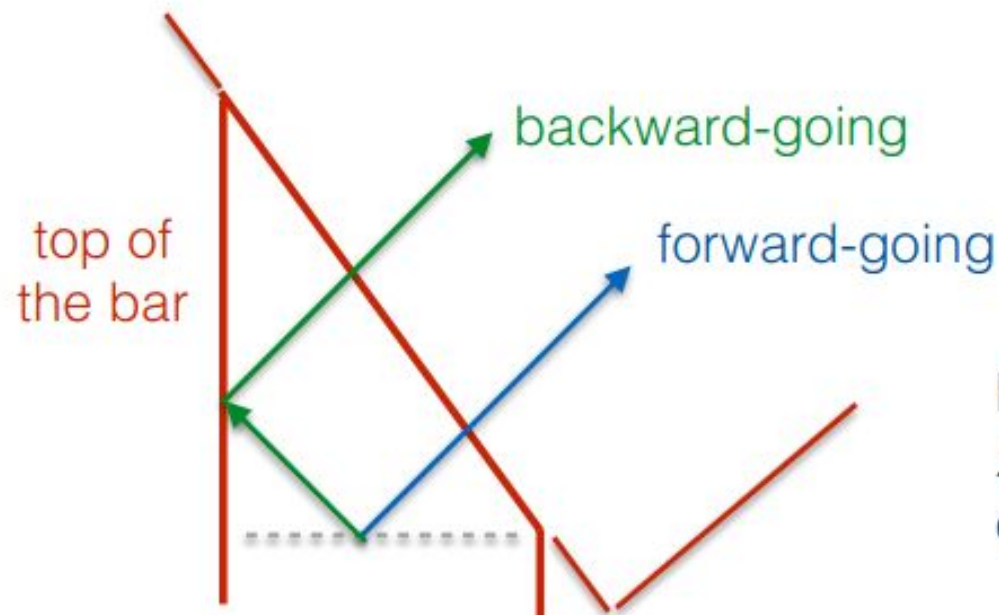
Instantaneous luminosity in Upgrade II

- Approximate the luminosity profile with an exponential function.
 - ➔ Luminosity decays quickly with time.
- From the FTDR, the virtual peak luminosity is 1.8×10^{34} and the fill duration is 8 hours.
- Average luminosity is $1.01 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$.
- We can only produce sample in multiples of $2.0 \times 10^{33} \text{ cm}^2 \text{ s}^{-1}$.
- Approximate a fill using 2.6 hours at 1.4×10^{34} , 1.6 hours at 1.0×10^{34} , 1.8 hours at 8.0×10^{33} and 1.8 hours at $6.0 \times 10^{33} \text{ cm}^2 \text{ s}^{-1}$.

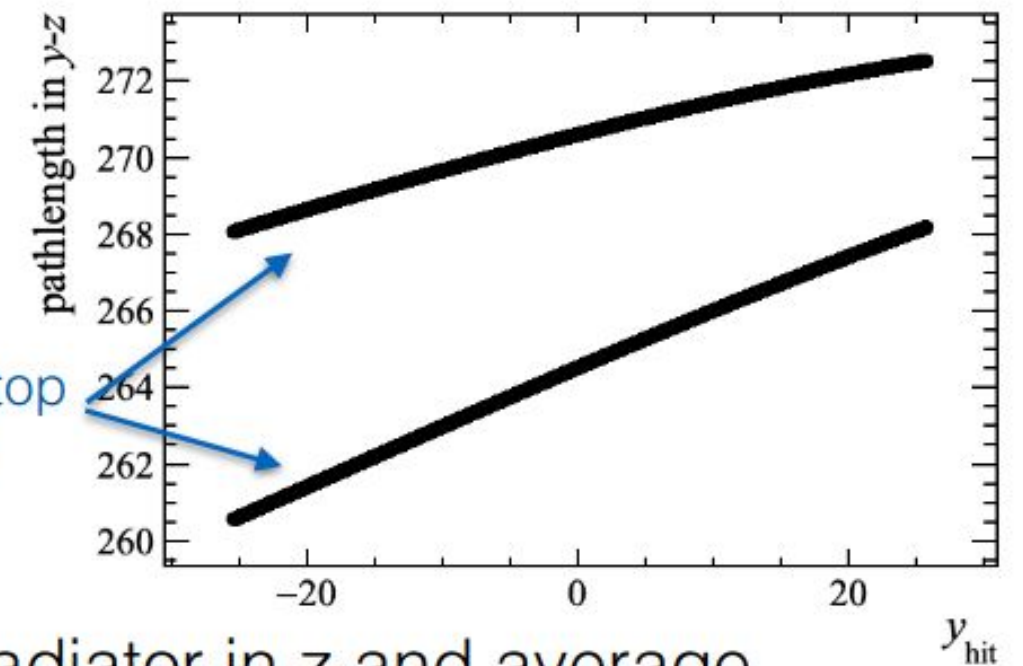
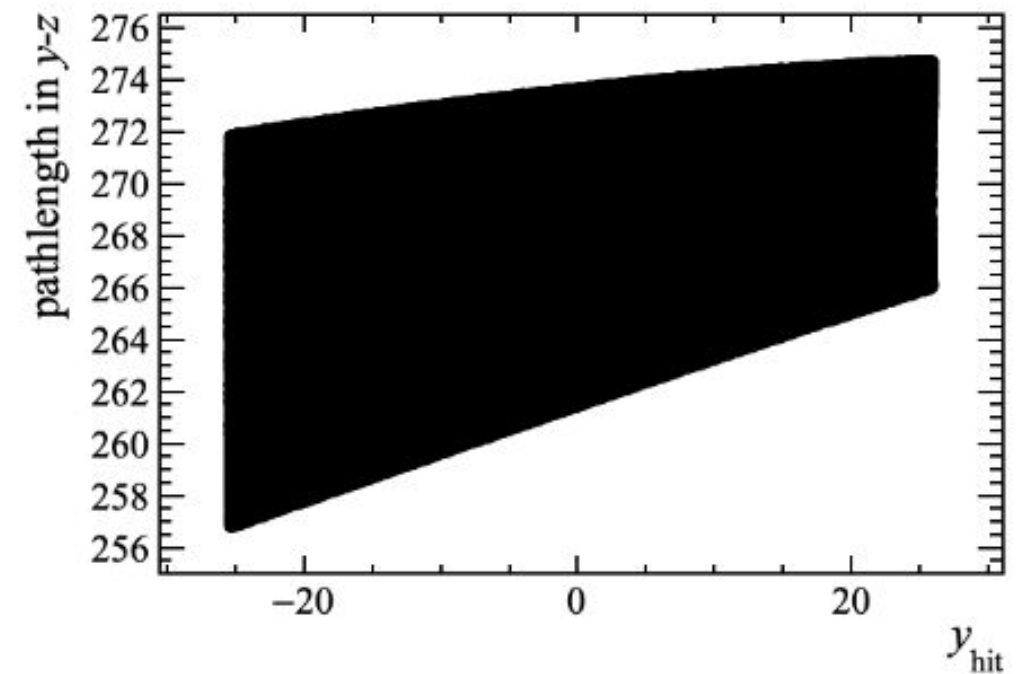


Effect of the focussing block

- However, the path length in the focus is not unique for a given hit position.
- The path length depends on the photon position in z at the top of the bar and whether or not the photon is forward or backward going.



Photons with $z=5\text{mm}$ at the top of the radiator

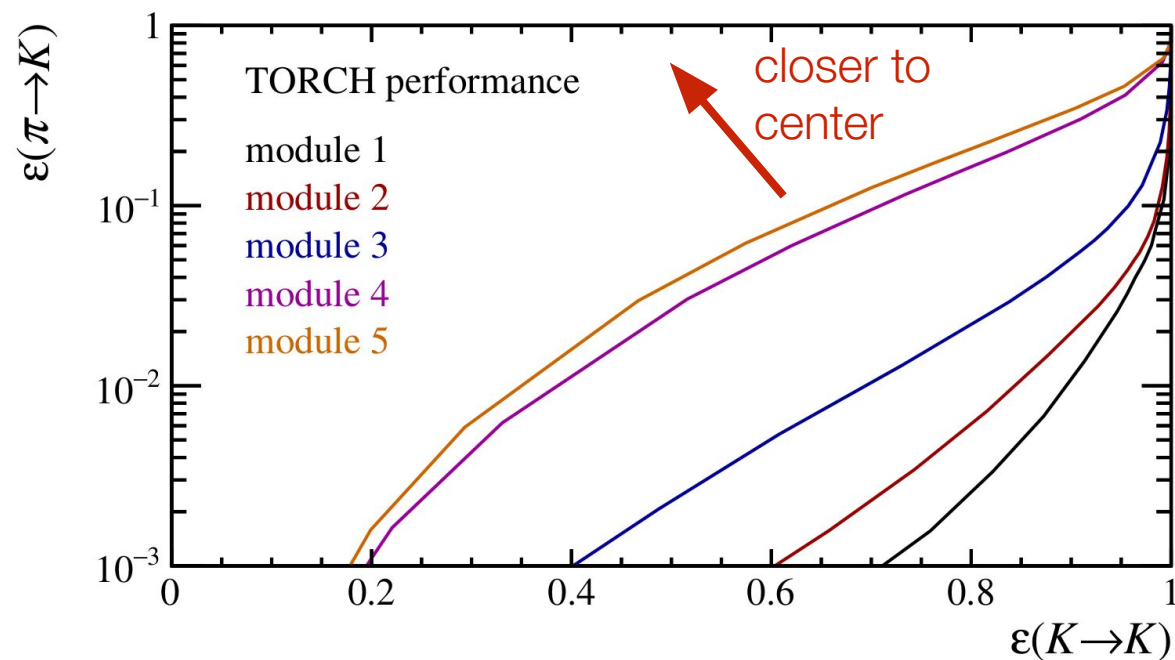


- Assume photons are at the middle of the radiator in z and average the forward- and backward-going path lengths.

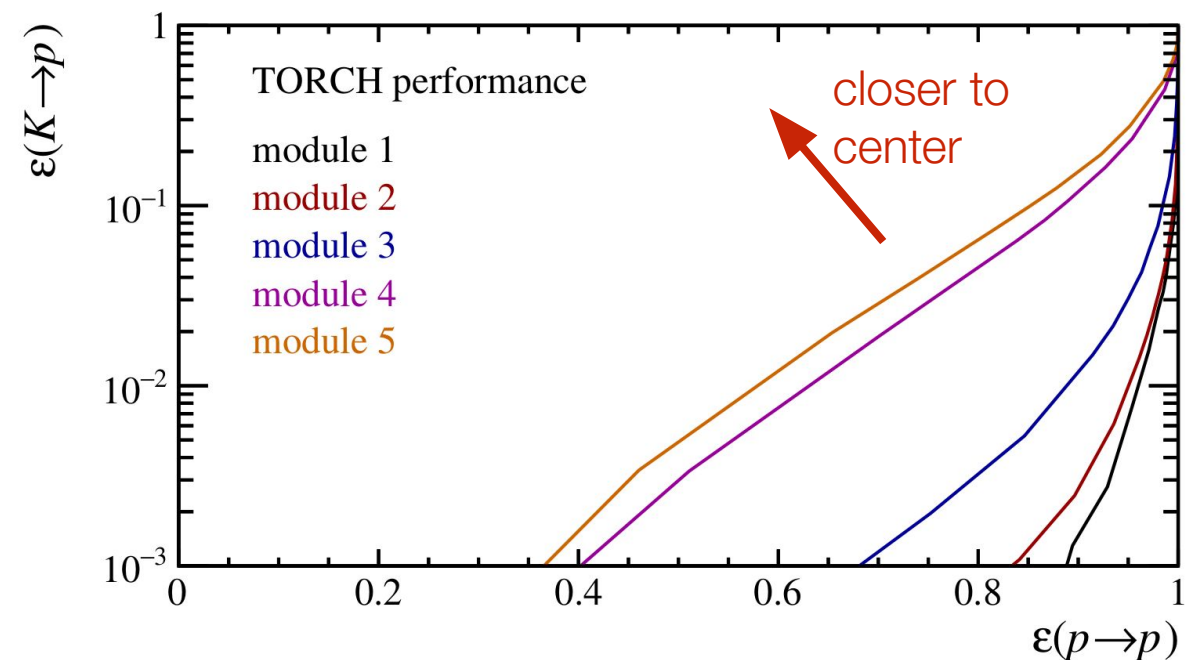
Performance versus module

- The performance is worst in module 5 (central, highest occupancy)
- Rapidly improves towards the periphery of the detector (module 1)

K- π separation

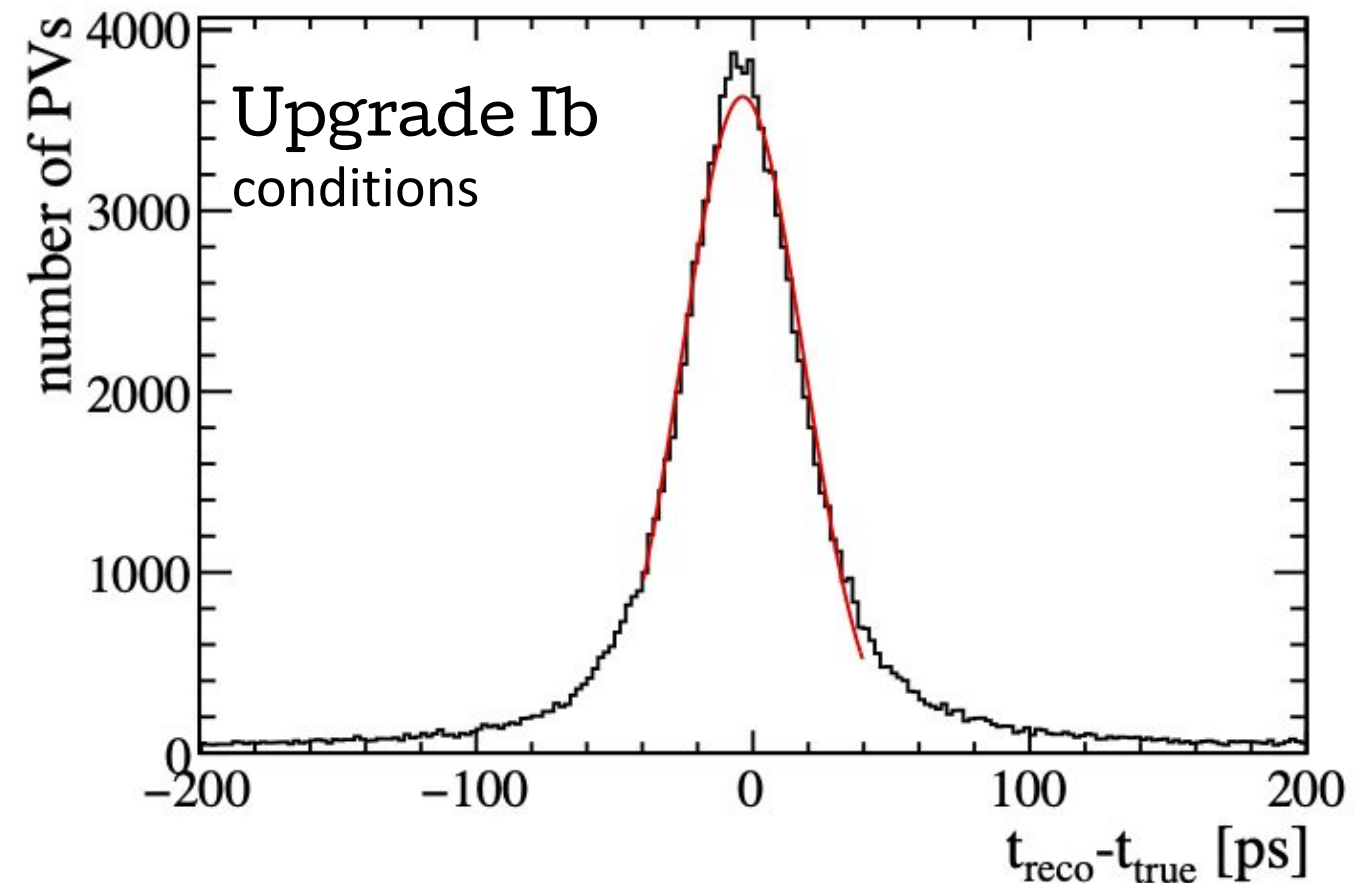


p-K separation



t_0 reconstruction

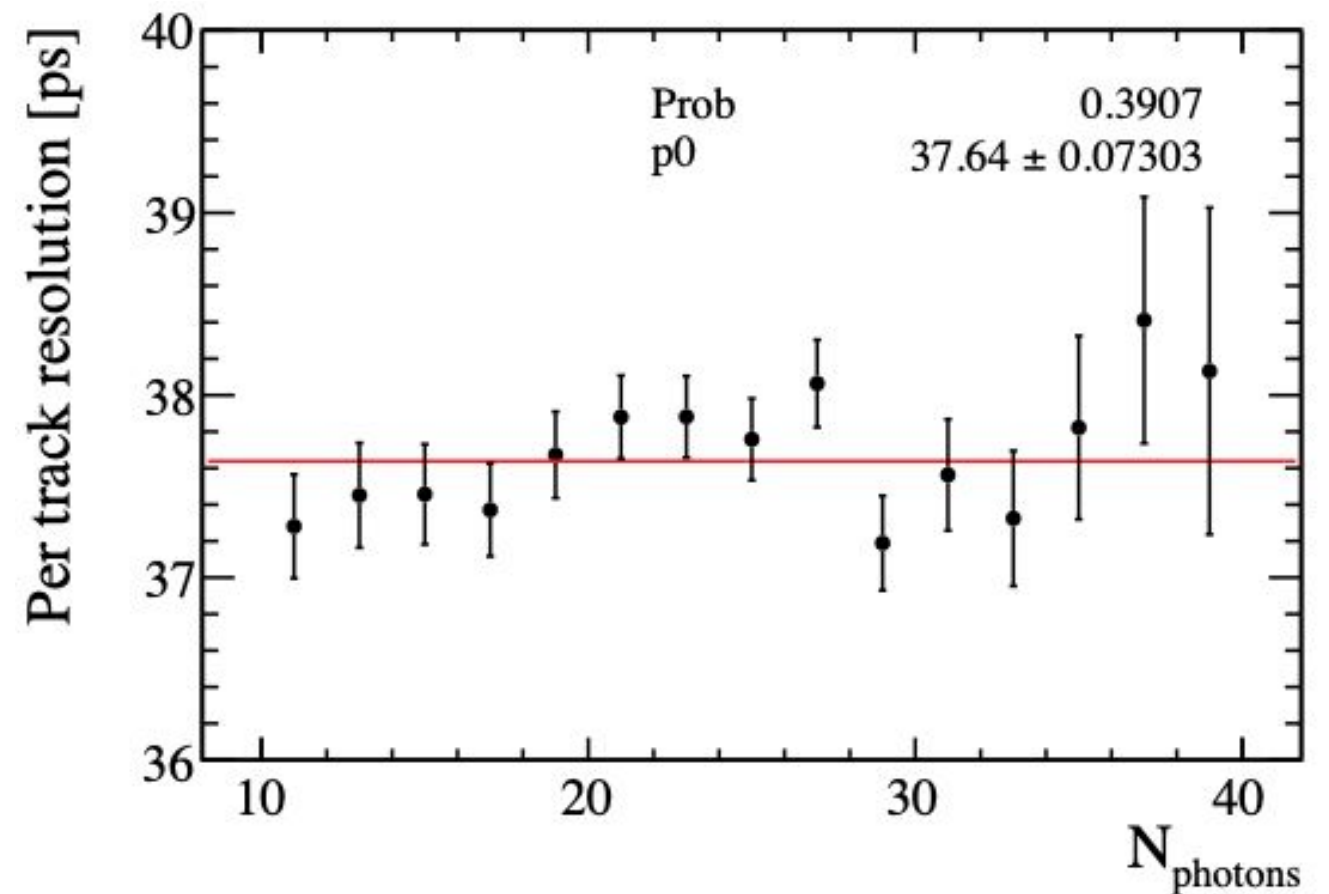
- Obtain likelihood profile for each track (under different PID hypothesis) as a function of t_0 .
- Combine likelihoods for all tracks assigned to vertex.
 - ➔ Choose the hypothesis for each track which fits best with the other tracks.
- Core of the distribution has width of about 22 ps.
- Time resolution of 70 ps per photon should translate to 10-15 ps per track with 20-30 photons.



Per track t_0 resolution

- Determine track level t_0 using true PID hypothesis.
- Resolution of 37.6 ps with little dependence on N_{photons}
- Significant variation seen across modules. Suggests that:
 - ➔ Likelihood is dominated by background hits.
 - ➔ Occupancy is driving t_0 resolution.

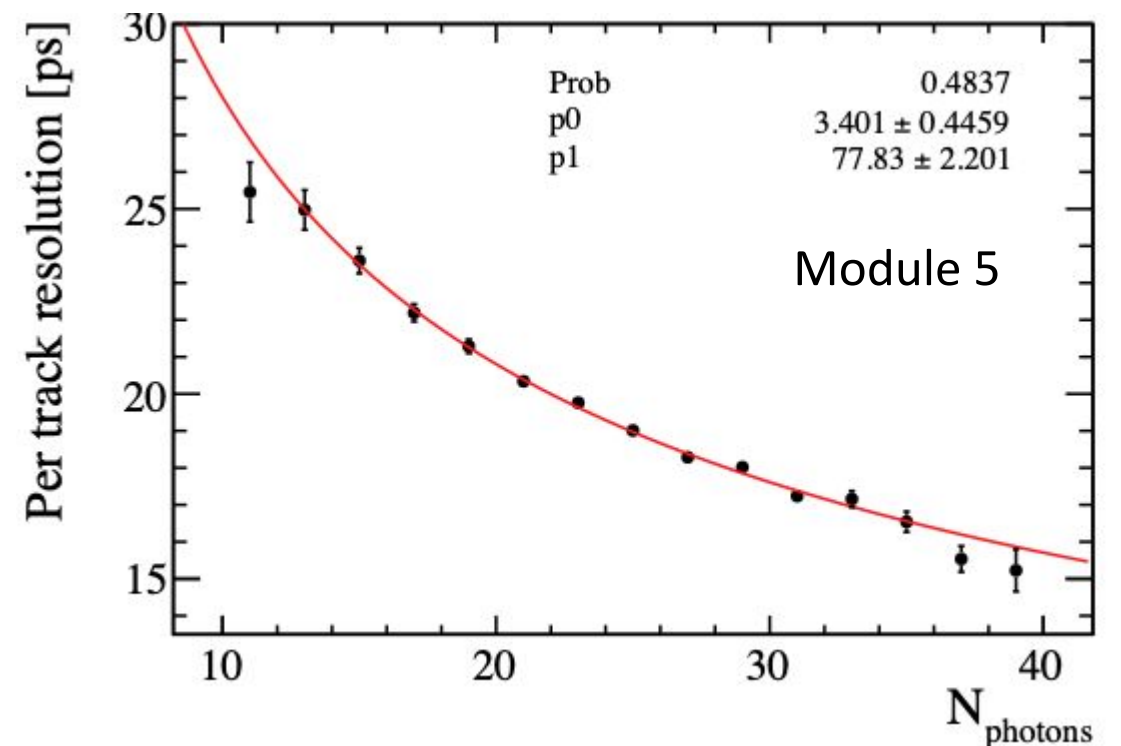
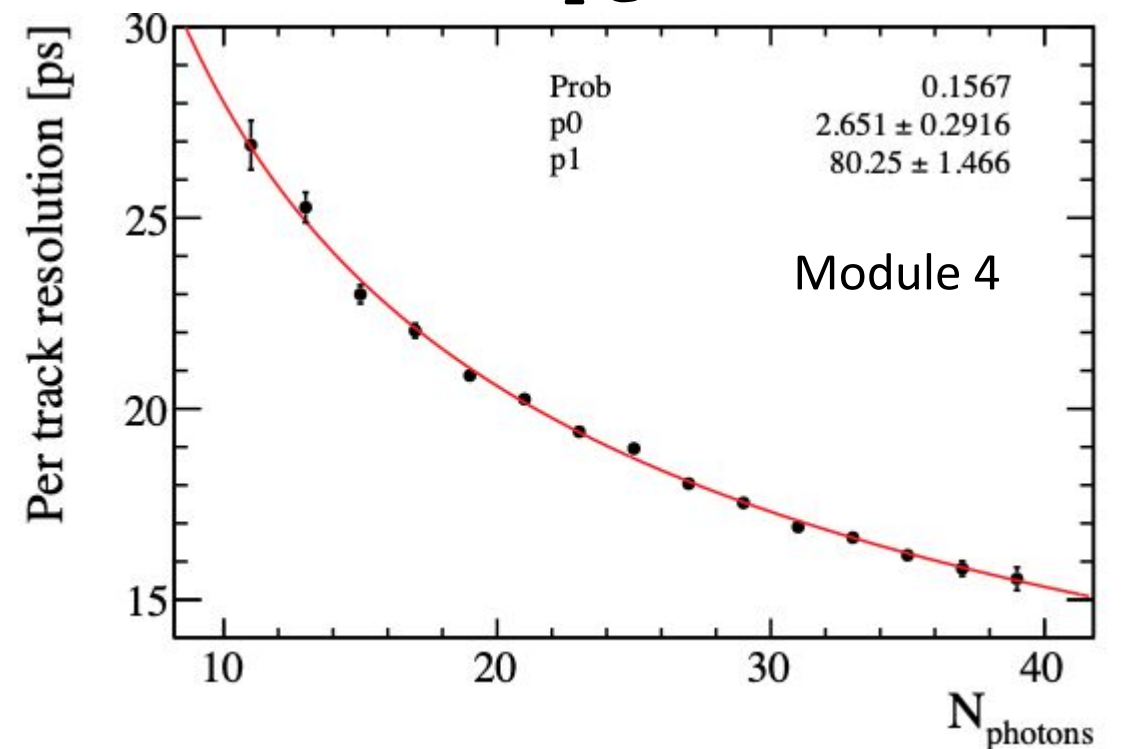
Upgrade Ib conditions



Per track t_0 resolution

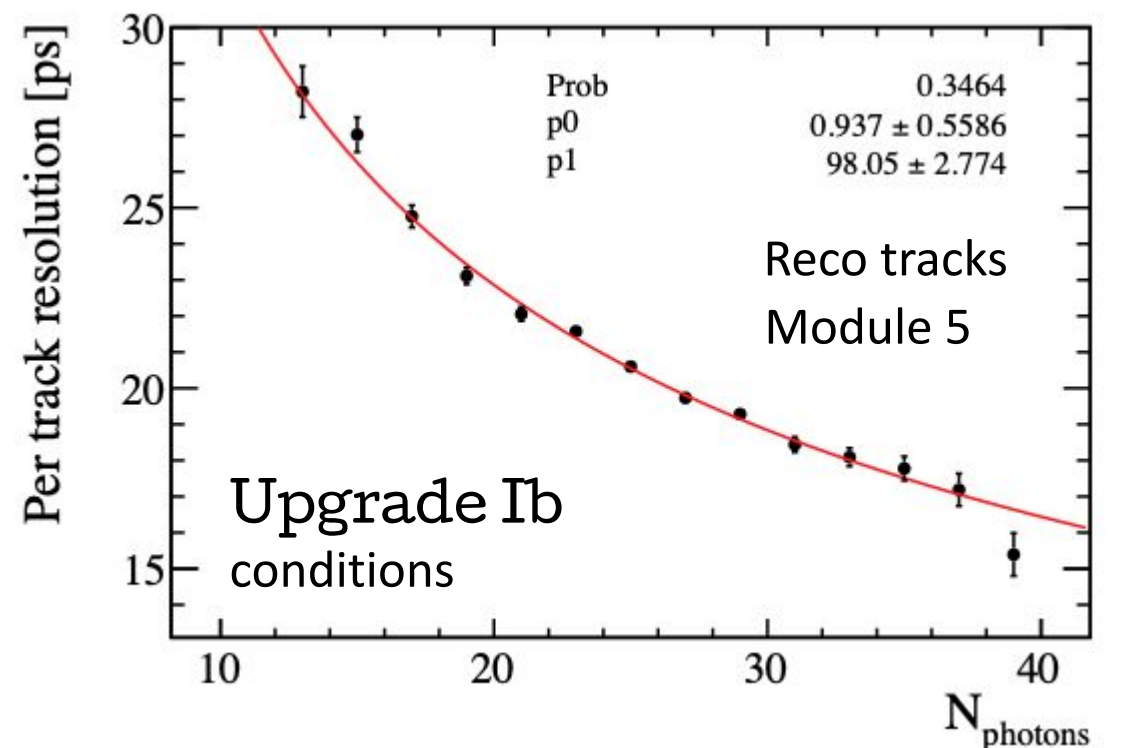
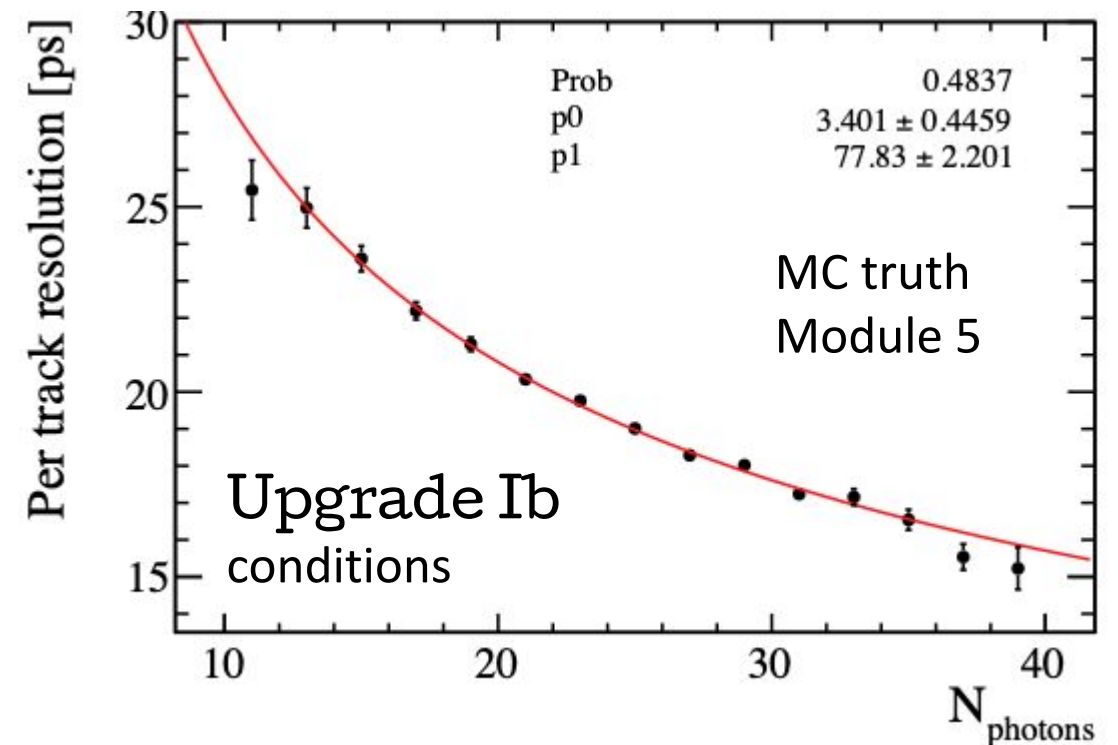
- Test occupancy issue by reconstructing t_0 when removing all photons except those from given track.
- Use true track entry position/angle.
- Use correct PID hypothesis.
- Fit with Gaussian in $\pm 3^*$ expected resolution.
- Dependence of per-track resolution described by:
$$p_0 + p_1/\sqrt{N_{\text{photons}}}$$

Upgrade Ib conditions

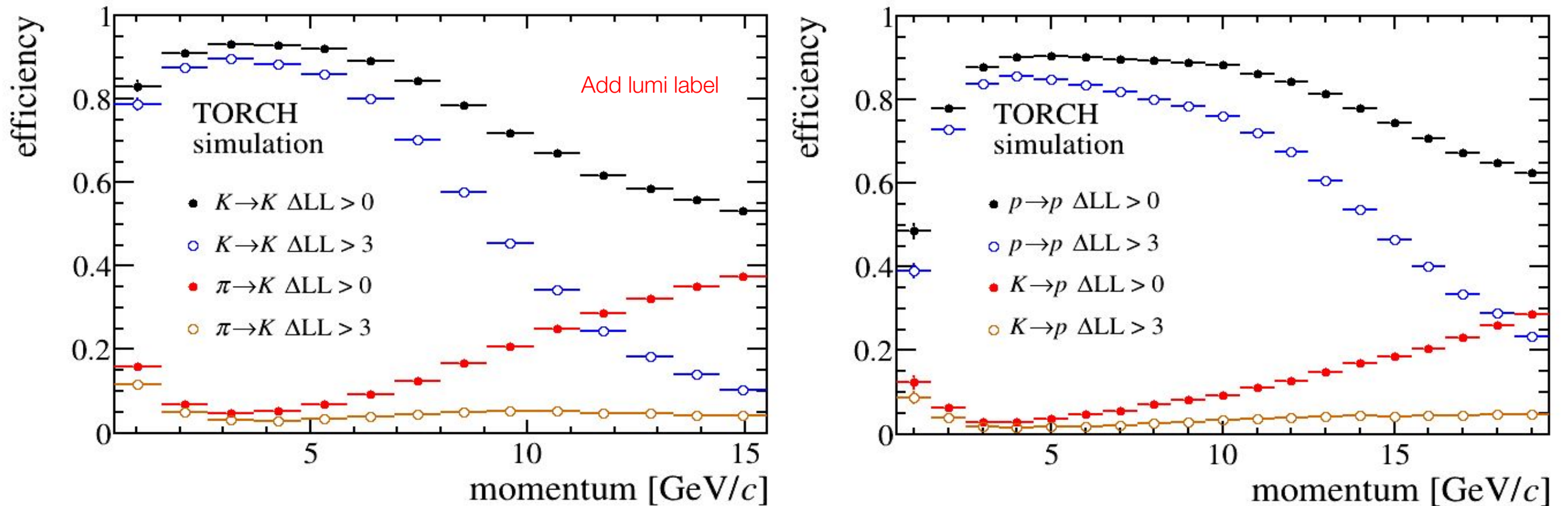


Track reconstruction effect on t_0

- When using the reconstructed track entry position and angle, the resolution gets worse:
 - ➔ Precision on the track parameters decreases the resolution by about 20 ps per photon.
- The MC true tracking is still affected by:
 - ➔ Multiple scattering in the radiator bar.
 - ➔ Surface scattering due to surface roughness.
 - ➔ Photon pathlength dependence/pixel size.



Performance in the FTDR

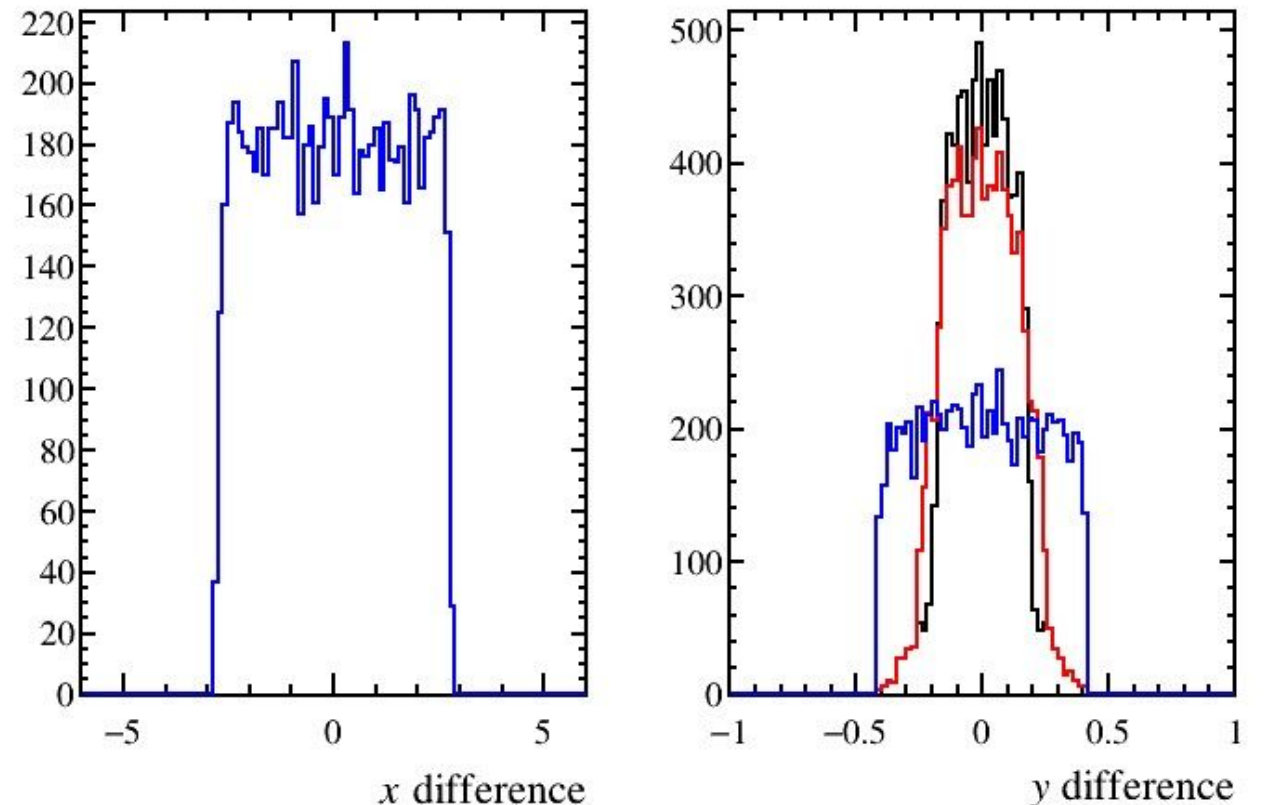


- Uses an 8-by-128 effective pixelation in outer modules and 16-by-128 effective pixelation in the central region.
- No charge-sharing or deadtime is used.

Pixelisation

- Also checked to see if we can go beyond the 8-by-128 by using charge weighting.
- The conclusion strongly depends on the gain-to-threshold ratio and the point spread.

Using standard 650k gain, 30fC threshold and 0.8mm point spread.

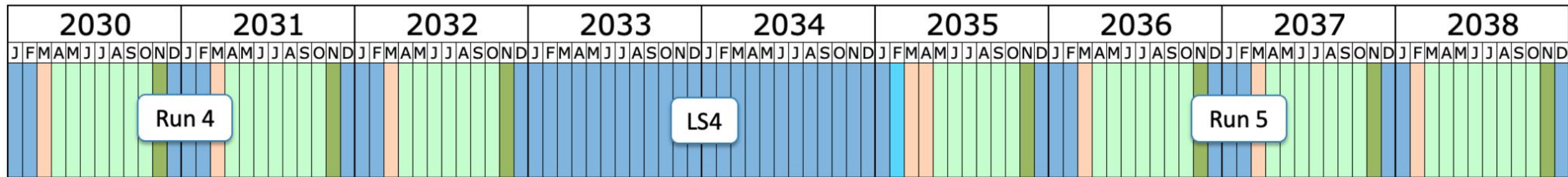


8-by-64 pixel

Naive cluster centre

Charge weighted cluster centre

LHC Schedule



Last updated: January 2022

- Shutdown/Technical stop
- Protons physics
- Ions
- Commissioning with beam
- Hardware commissioning/magnet training

Test beam results

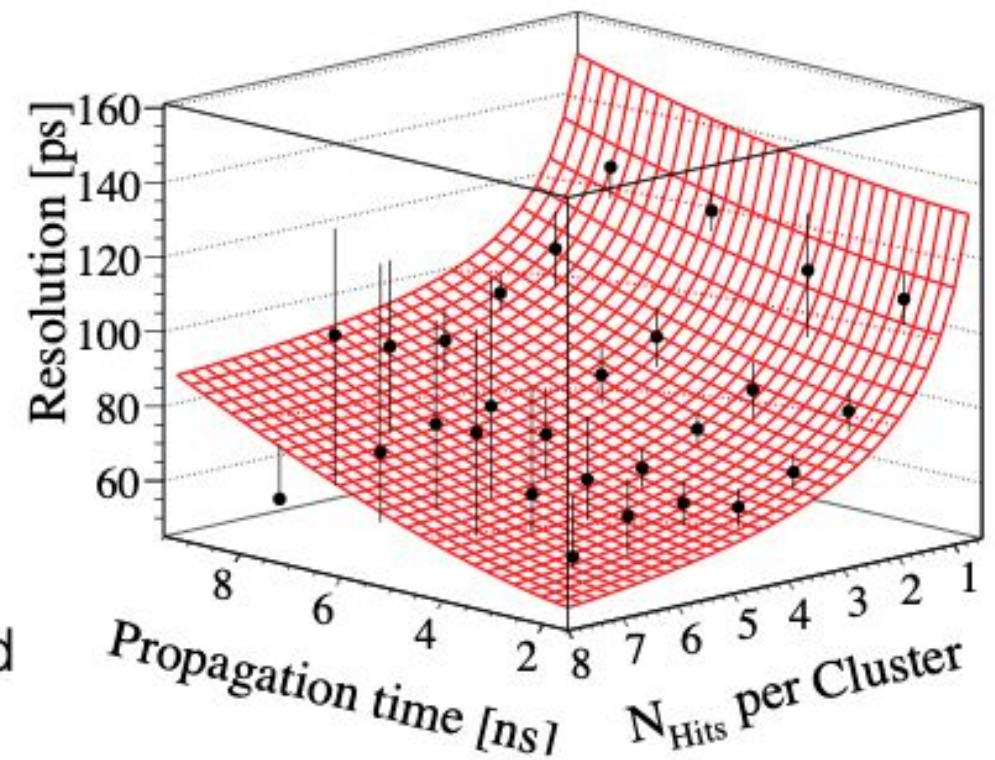
- Can parametrise resolution in 2D

$$\sigma_{\text{TORCH}}^2 = \sigma_{\text{const}}^2 + \sigma_{\text{prop}}^2(t) + \sigma_{\text{RO}}^2(N_{\text{hits}})$$

MCP

Propagation time
dependent effects

Cluster size and
readout



Measured

$$\sigma_{\text{const}} = 33.0 \pm 7.1 \text{ ps}$$

$$\sigma_{\text{prop}}(t) = (7.8 \pm 0.7) \times t[\text{ns}] \text{ ps}$$

$$\sigma_{\text{RO}}(N_{\text{hits}}) = \frac{100.5 \pm 5.7}{\sqrt{N_{\text{hits}}}} \text{ ps}$$

Expected

$$\sigma_{\text{const}} \approx 33 \text{ ps}$$

$$\sigma_{\text{prop}}(t) \approx (3.75 \pm 0.8) \times t[\text{ns}] \text{ ps}$$

$$\sigma_{\text{RO}}(N_{\text{hits}}) \approx \frac{60}{\sqrt{N_{\text{hits}}}} \text{ ps}$$

Resolution expected to improve with better electronics calibration

Comparison with RICH

Similarities:

- Reconstruction uses a similar approach to the RICH detectors
 - Optimisation from RICH reconstruction can be imported to TORCH
- A 3D image (x,y,t) image is measured
 - Ring (RICH) and Hyperbola (TORCH)

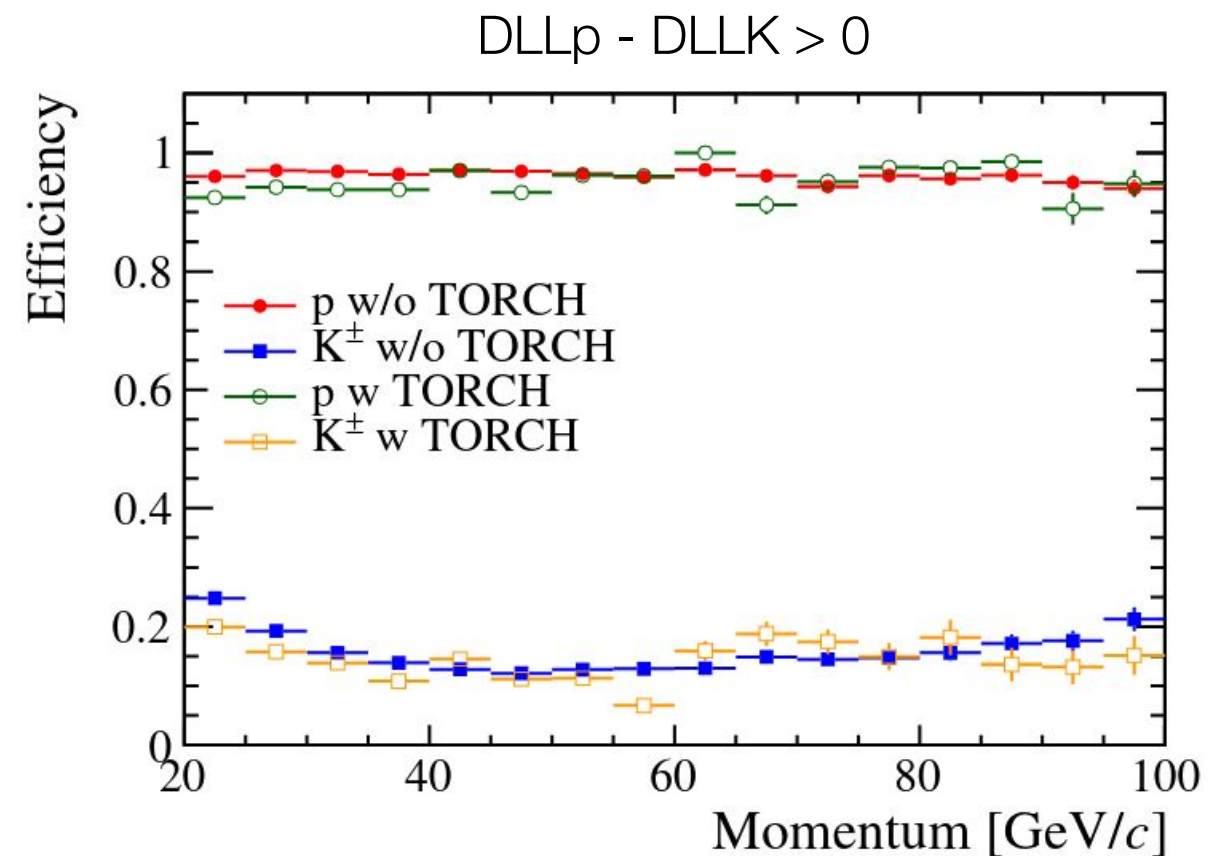
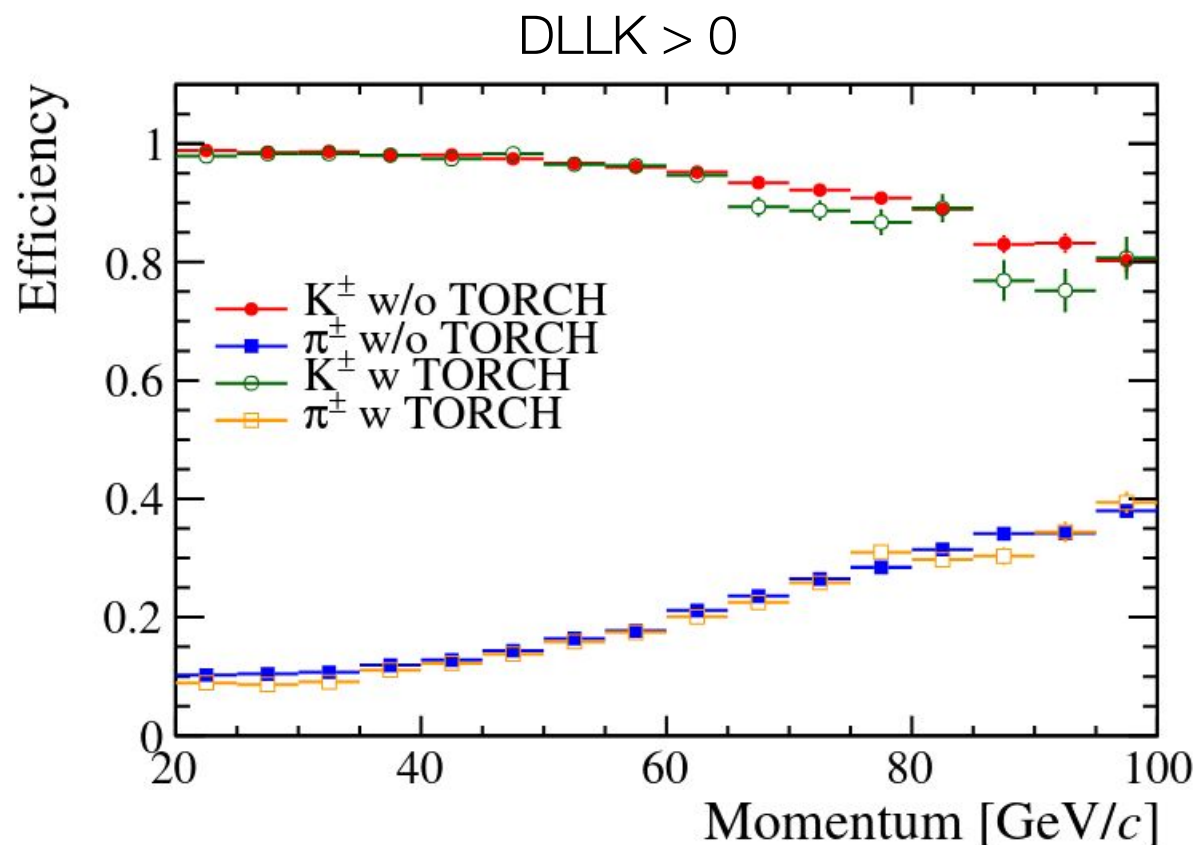
Differences:

- Photons from a track spread over 25ns window in TORCH
 - Narrow time window for RICH

Impact of TORCH material

- Placing TORCH in front of RICH 2 slightly increases the material budget
- Effect on RICH2 PID performance is negligible

RICH2 PID performance with and without TORCH



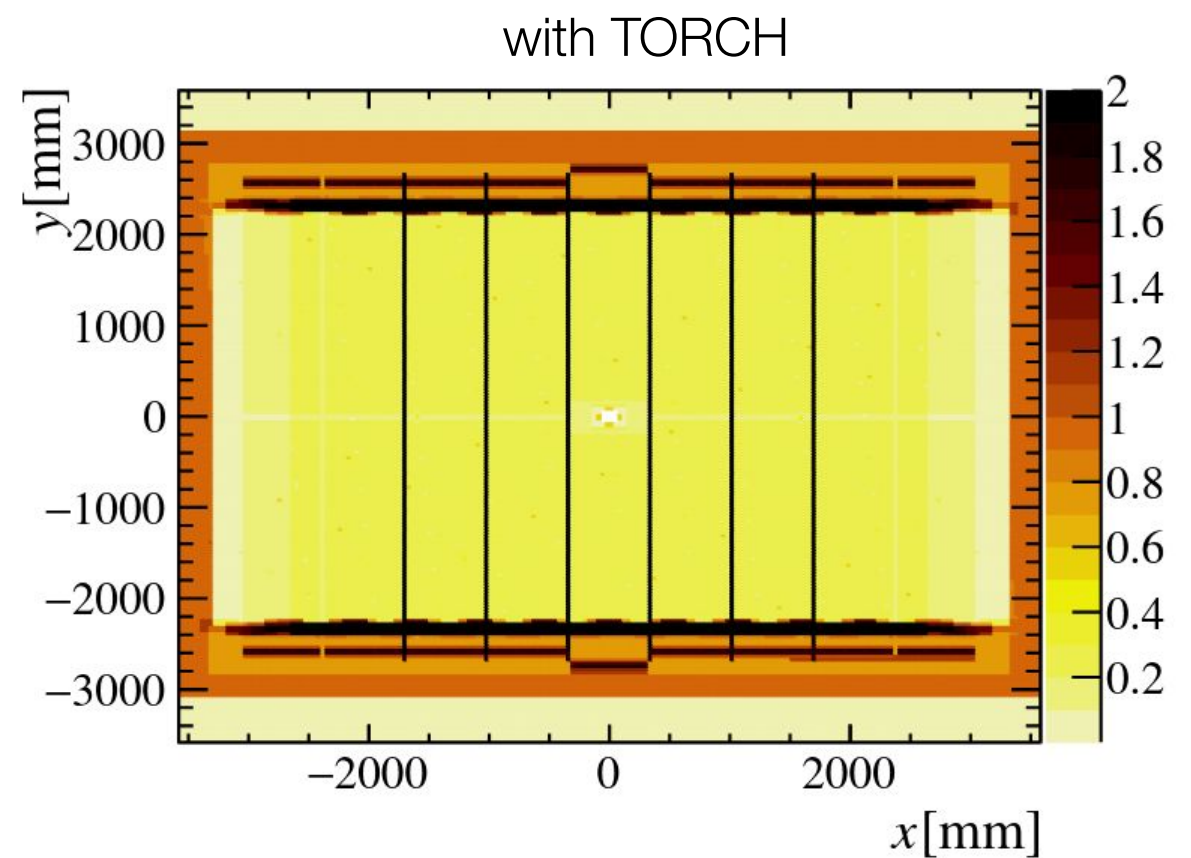
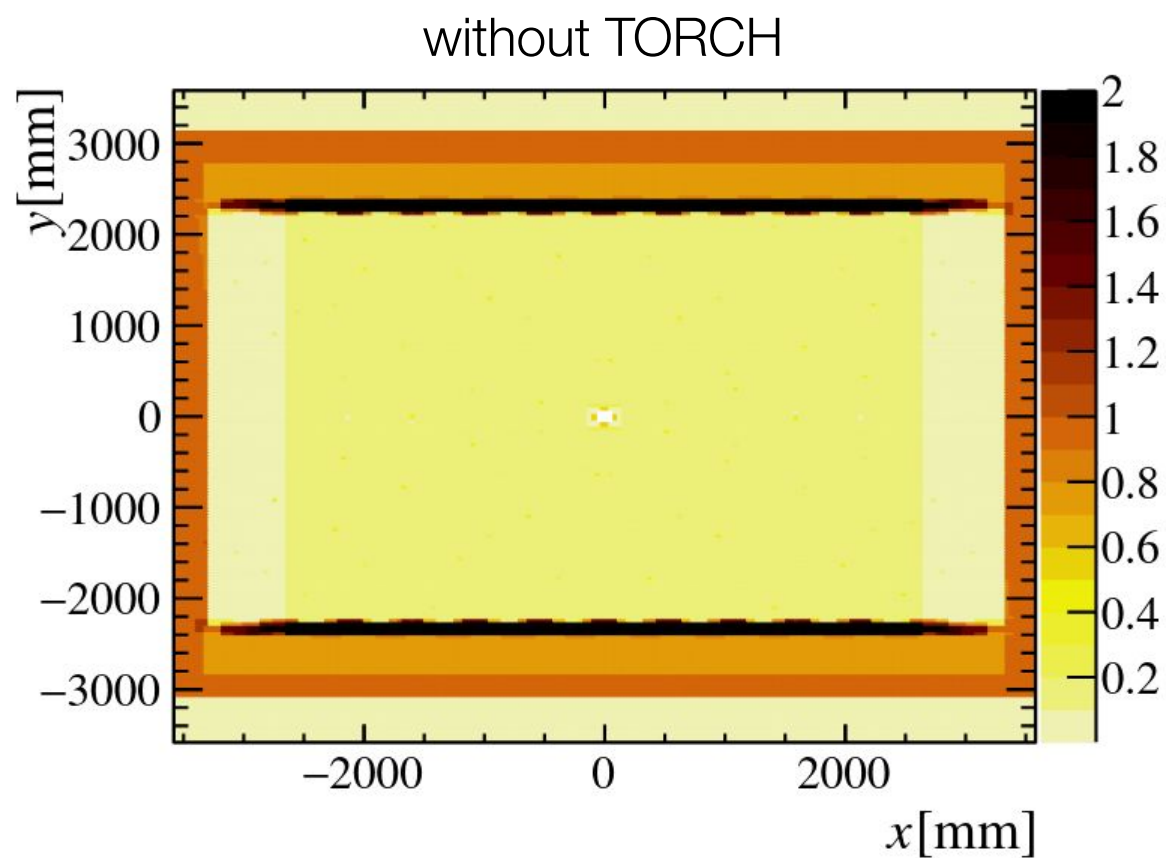
Reconstruction

- Use two different algorithms to compute hit/track/hypothesis probabilities:
 - **Binned:** Based on simulating large numbers of photons (ray-tracing)
 - **Unbinned:** Semi-analytic approach based on back-propagation
- The semi-analytic approach is faster and works with either pixel hits (integrating over the pixel size) or clusters.
- Two different approaches to consider the likelihood:
 - **Local:** Consider each track in isolation
 - **Global:** Consider all track hypothesis together

Impact of TORCH material

- Placing TORCH in front of RICH 2 slightly increases the material budget

Material in terms of radiation length from start of FT to entry to RICH2 volume:



Track resolution

Track resolution using LHCb Upgrade I

