



# CEPC mechanics design

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IAS Mini-workshop: Accelerator Physics - Key Beam Physics and  
Technologies Issues for Colliders

1.13-1.14, 2022

# Outline

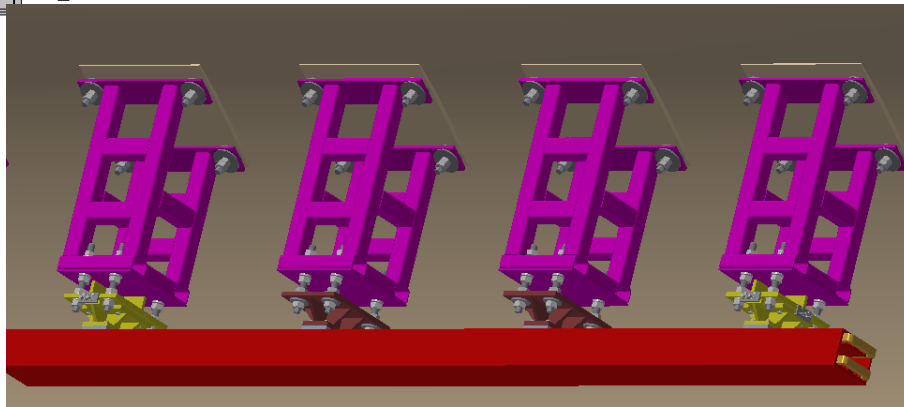
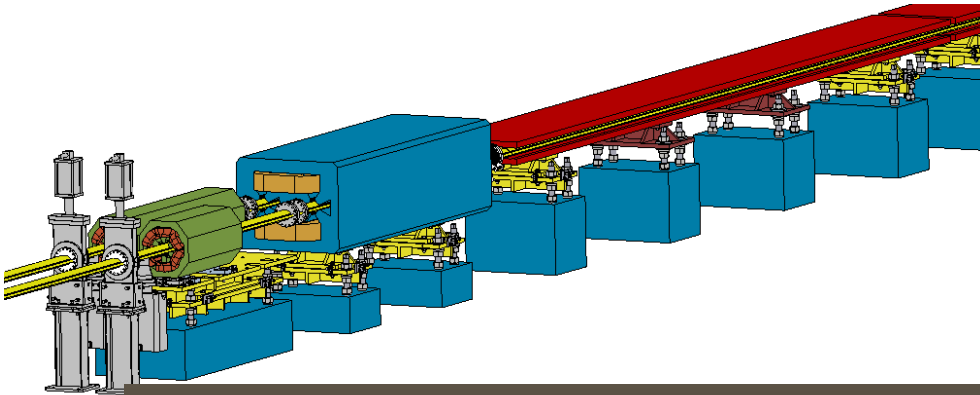
- Magnet supports
- MDI mechanics
- Collimators and machine protection scheme
- Summary

# Magnet supports

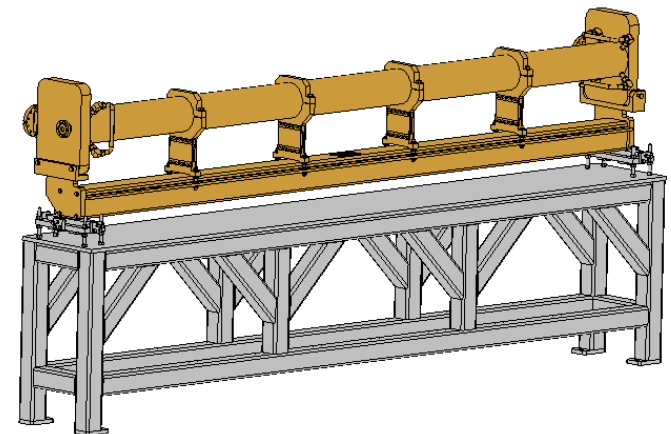
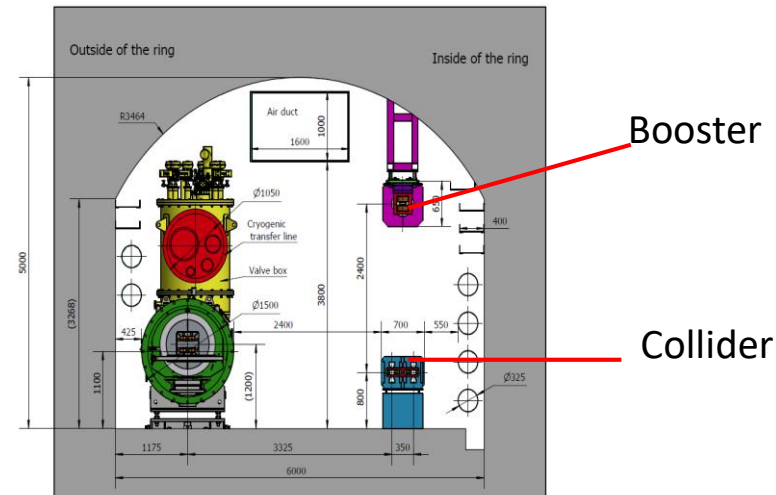
- Over 80% of the length is covered by magnets of about 138 types.

## Adjustment Ranges of magnets

X	$\geq \pm 20$ mm	$\Delta\theta_x$	$\geq \pm 10$ mrad
Y	$\geq \pm 30$ mm	$\Delta\theta_y$	$\geq \pm 10$ mrad
Z	$\geq \pm 20$ mm	$\Delta\theta_z$	$\geq \pm 10$ mrad

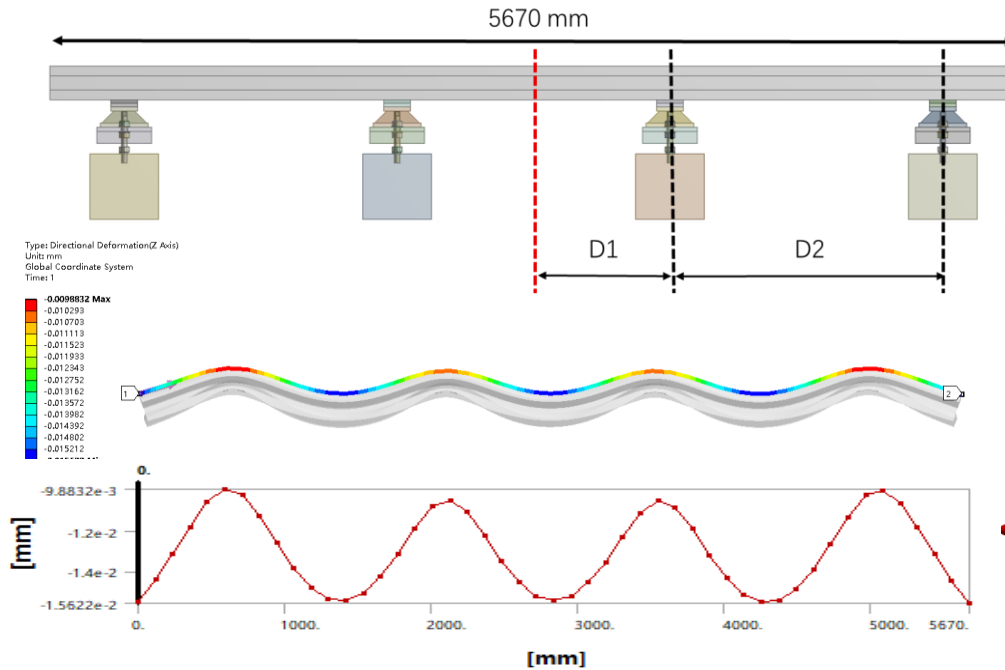


TUNNEL CROSS SECTION OF THE ARC AREA



# Magnet supports

## Optimization for dipole supports



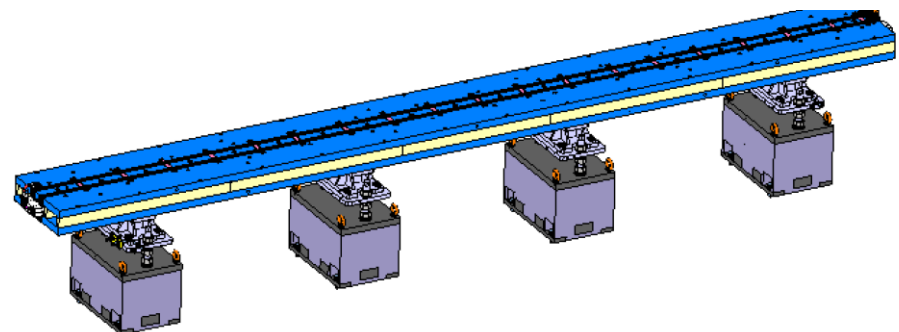
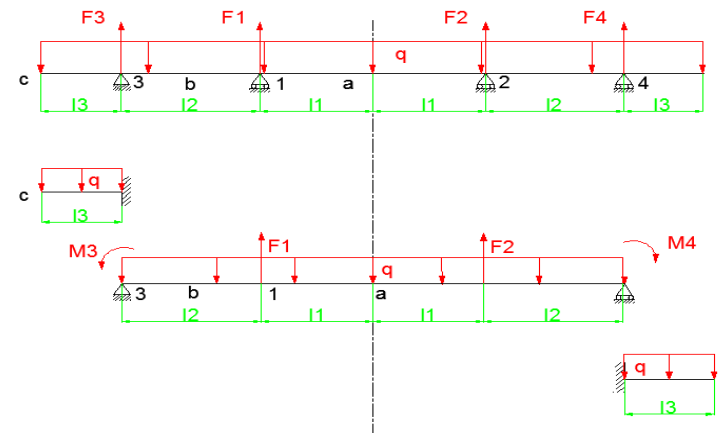
### Methods:

- Theoretical derivation
- Deformation optimization

### Tools:

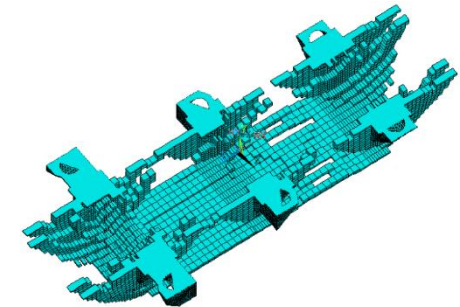
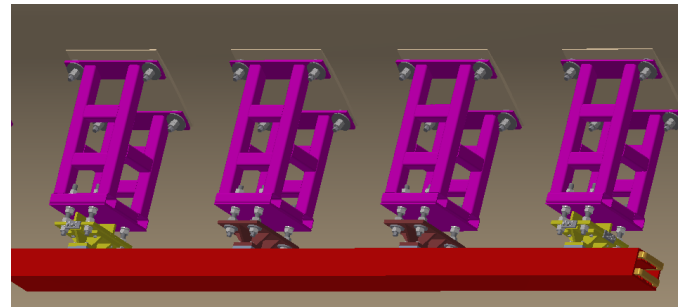
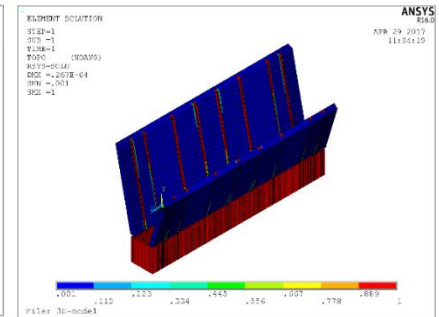
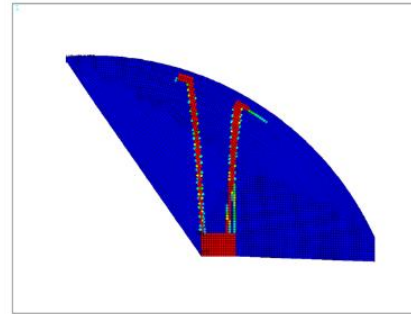
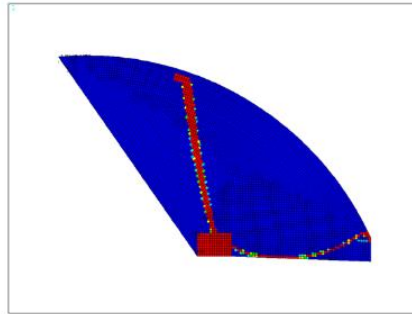
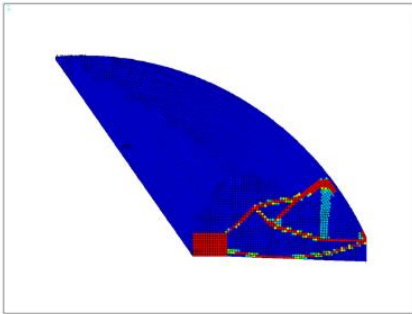
- Matlab
- Workbench-Response surface
- Inventor

No. of supports	Max. deformation (um)
3	19
4	7
5	5



# Magnet supports

## Optimization for dipole supports in Booster



### Methods:

- Theoretical derivation
- Deformation optimization
- Topology optimization

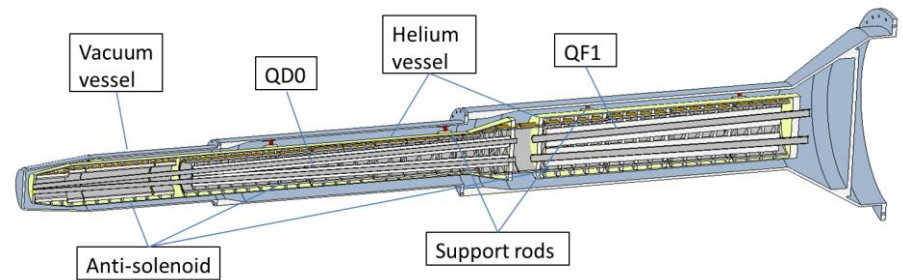
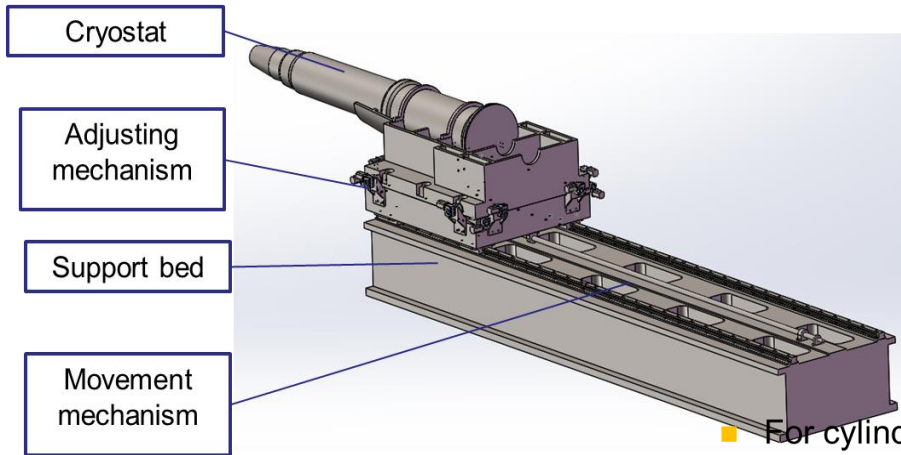
### Tools:

- Matlab
- Workbench-Response surface
- ANSYS APDL
- Inventor

Topology optimization was first used in girder design by our team on HEPS-TF

# Magnet supports

## Optimization for SC magnet supports



■ For cylinder cantilever under gravity

➤ Max. deformation  $y_{\max}$

➤ First natural frequency  $\omega_1$

$$y_{\max} = -\frac{ql^4}{8EI} = \frac{64l^4\rho}{\pi ED^2} \quad \omega_1 = 3.5 \sqrt{\frac{EI}{\rho Al^4}} = \frac{3.5D}{4l^2} \sqrt{\frac{E}{\rho}}$$

➤ Shape factors:  $l, D$ ; material factors:  $E/\rho$

■ For concentric cylindrical cantilever under gravity

$$y_{\max} \sim \frac{\rho l^4}{32EI} (D^2 - d^2 + \frac{\rho'}{\rho} d^2)$$

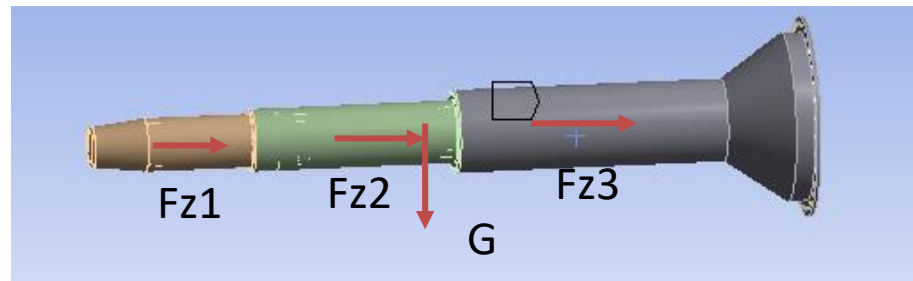
■  $\rho'$ : equivalent density of inside cylinder

### ■ Methods:

- Theoretical derivation
- Deformation optimization
- Stability optimization
- Material optimization

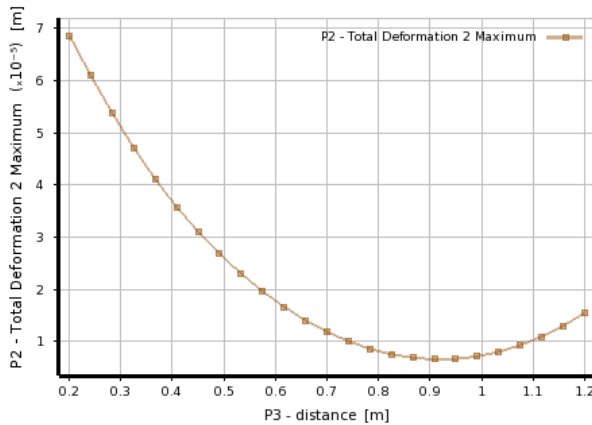
### ■ Tools:

- Matlab
- Workbench
- Inventor

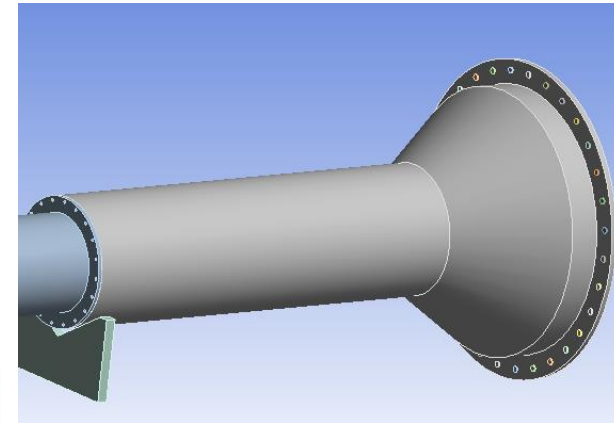
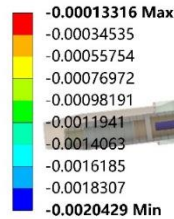


# Magnet supports

## Optimization for SC magnet supports



**G: 1gravity+2magnet-bonded**  
 Directional Deformation  
 Type: Directional Deformation(X Axis)  
 Unit: m  
 Global Coordinate System  
 Time: 2

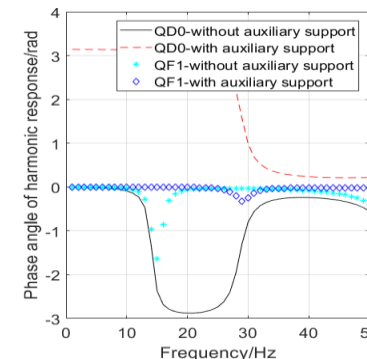
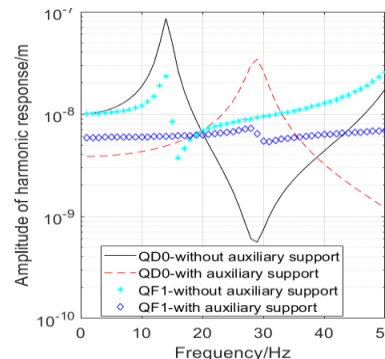
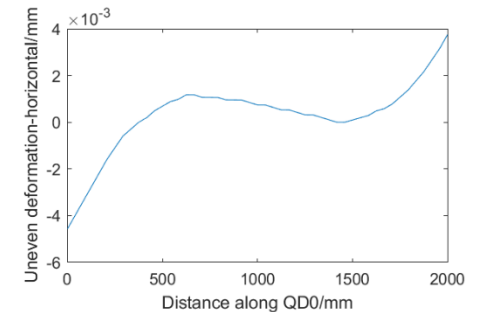
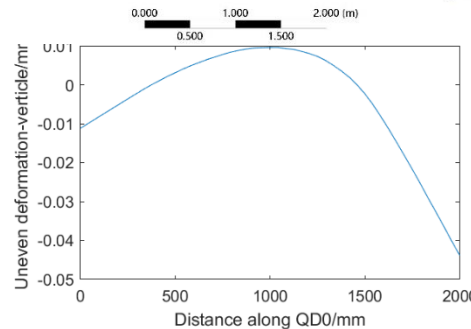


### Methods:

- Theoretical derivation
- Deformation optimization
- Stability optimization
- Material optimization

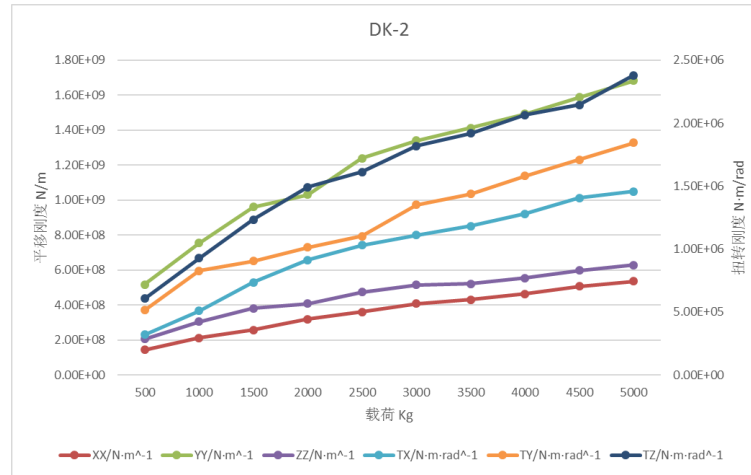
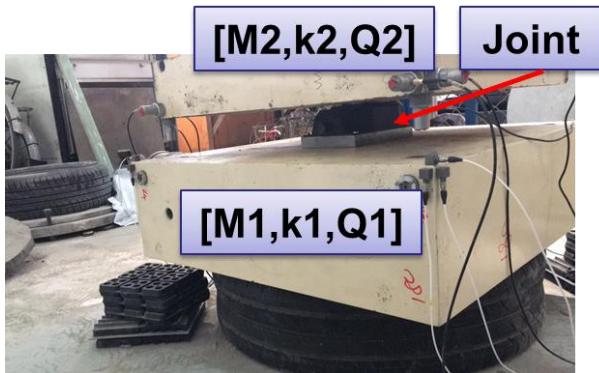
### Tools:

- Matlab
- Workbench
- Inventor



# Magnet supports

Stiffness study for adjusting joints: very important for stability evaluation



A new method used in HEPS

- High efficiency
- High accuracy
- Simple

- Methods:
  - FEA-based hammering method
- Tools:
  - ANSYS APDL
  - Matlab
  - Test devices

载荷KG	XX/%	YY/%	ZZ/%	TX/%	TY/%	TZ/%
500	1	2	2	19	1	2
1000	3	4	0	23	8	6
1500	0	2	3	28	3	8
2000	2	0	5	20	0	5
2500	0	1	2	15	3	5
3000	2	0	5	10	1	6
3500	1	4	6	9	0	3
4000	2	5	9	6	0	2
4500	3	7	8	8	0	1
5000	5	8	10	4	1	0

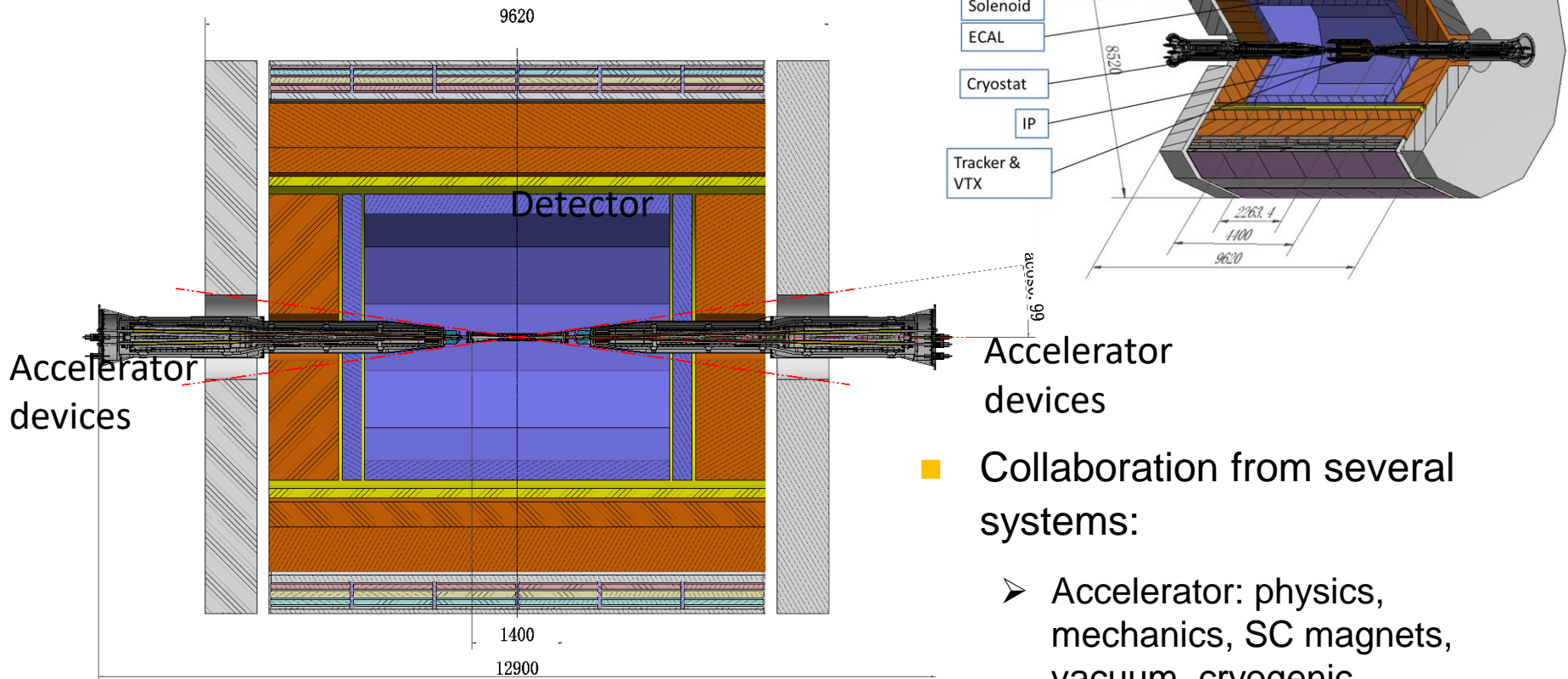


# Magnet supports

- Main parameters obtained in analysis
  - Regular dipoles in Collider: 5670 mm long, uneven deformation < 10um (under gravity )
  - QD0: 2000 mm long, uneven deformation < 30 um (under gravity and Lorentz force in anti-solenoid )
- More detailed works are under-going
  - Further optimization in SC magnet support
  - Common girder design for regular quadrupoles and sextupoles, and optimization

# MDI mechanics

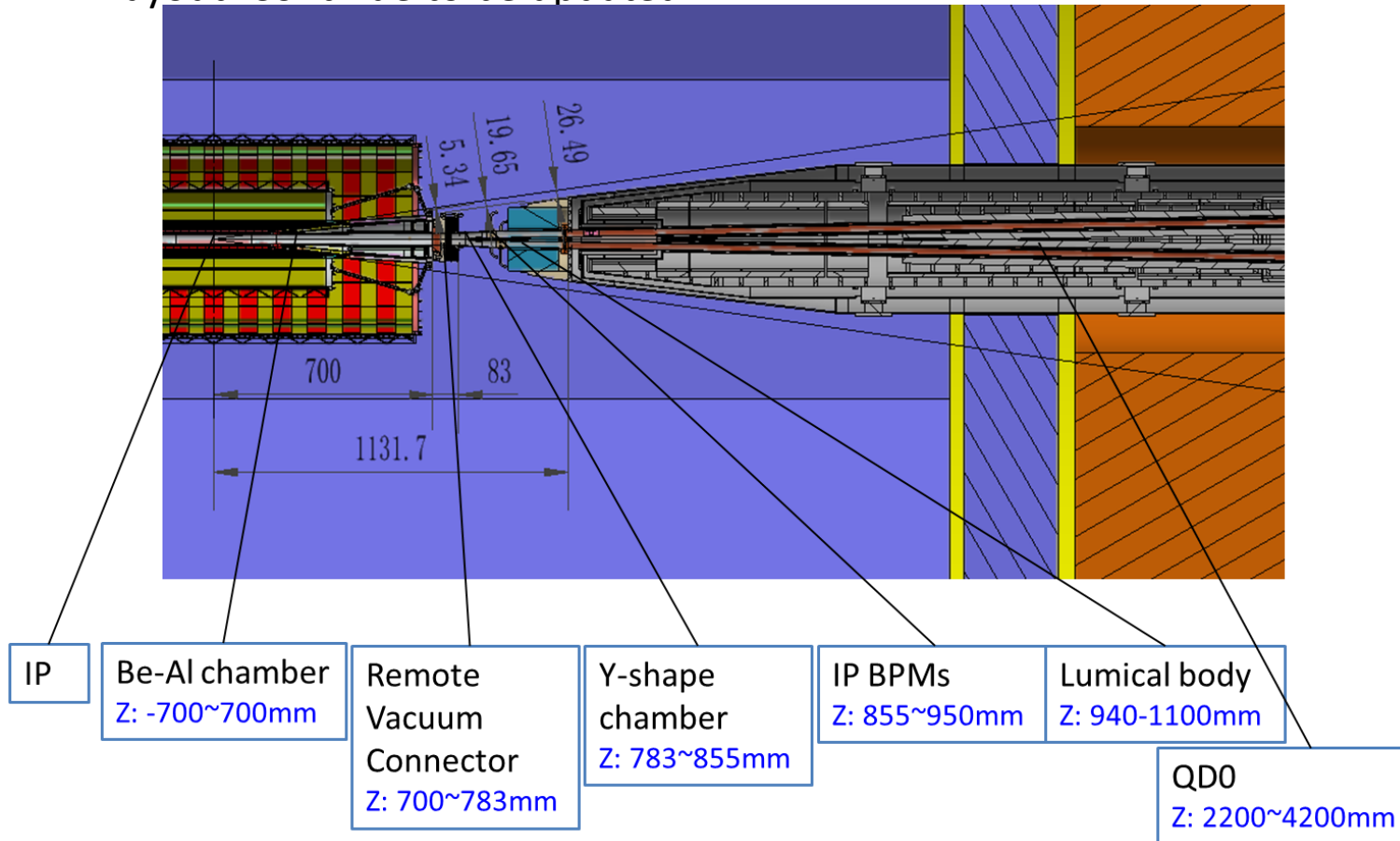
MDI layout: Continue to be updated



- Collaboration from several systems:
  - Accelerator: physics, mechanics, SC magnets, vacuum, cryogenic, instruments...
  - Detector: physics, mechanics, VTX, Yoke, shielding...

# MDI mechanics

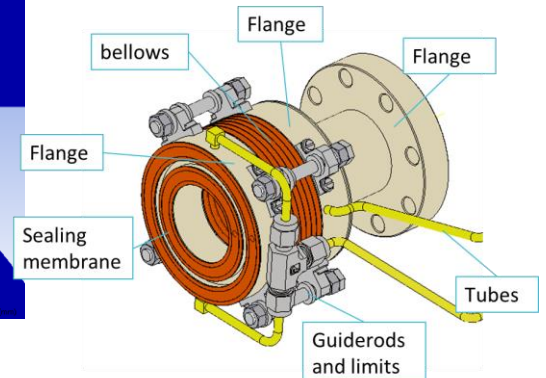
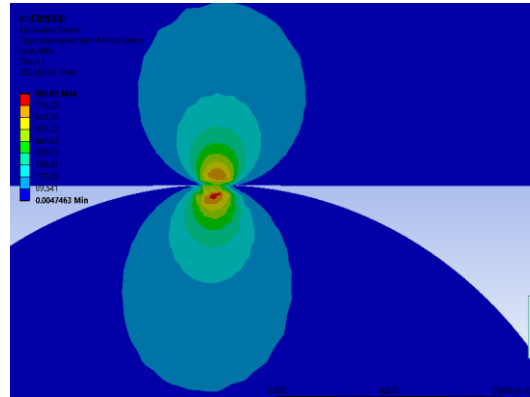
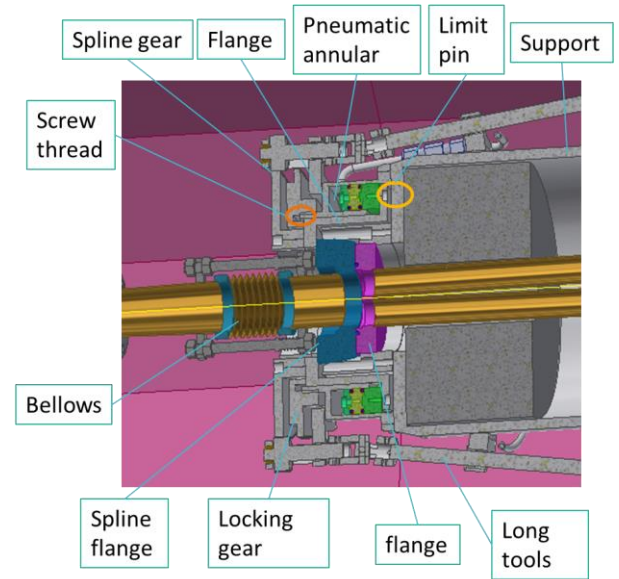
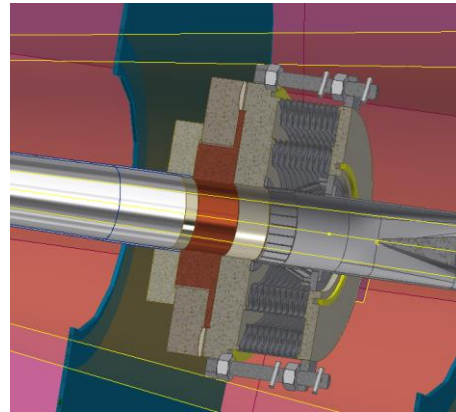
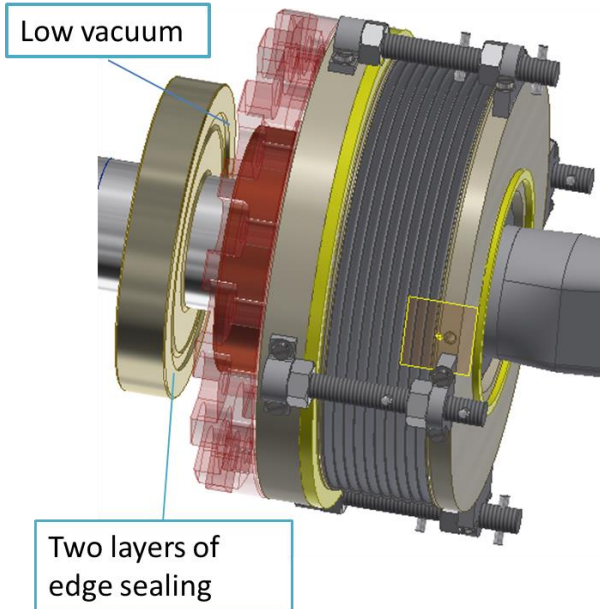
MDI layout: Continue to be updated



- Tools: Inventor, solidworks...
- Phased achievements: a workable layout for CDR

# MDI mechanics

## Remote vacuum connector



- **Methods:**
  - Theoretical derivation
  - Two layers of edge sealing
  - Space optimization
  - FEA
- **Tools:**
  - Workbench
  - Inventor

# MDI mechanics

Remote vacuum connector

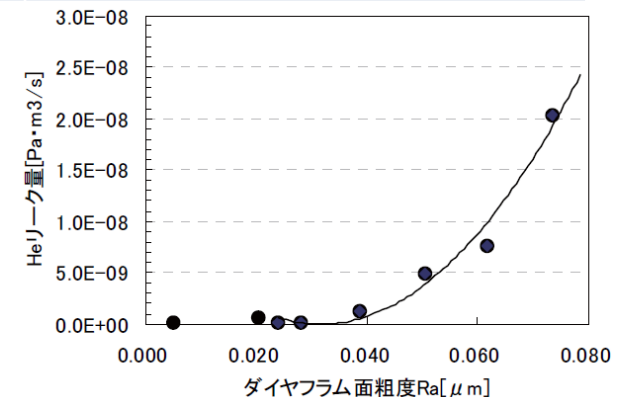
## ■ Difficulties:

➤ Space limitation, leak rate, thermal dissipation...

Sealing methods	Within detection angle	Leak rate estimation	Remarks
RVC	NO	★★★★	Successful used in S-KEKB
Remote chain	Yes	★	Eliminated
Inflatable seal*	Yes	★★	Experience from CSNS
Improved inflatable seal	Yes	★★★	Mainly focused on

## ● Our experience:

- Single-layer → double layer, leak rate can be improved from  $1e-6$  Pa.m<sup>3</sup>/s to  **$8.5e-10$  Pa.m<sup>3</sup>/s**.
- Replace membrane sealing by edge sealing



# Collimators and machine protection scheme

- 4 collimators per IP per ring for background decreasing

- Horizontal aperture

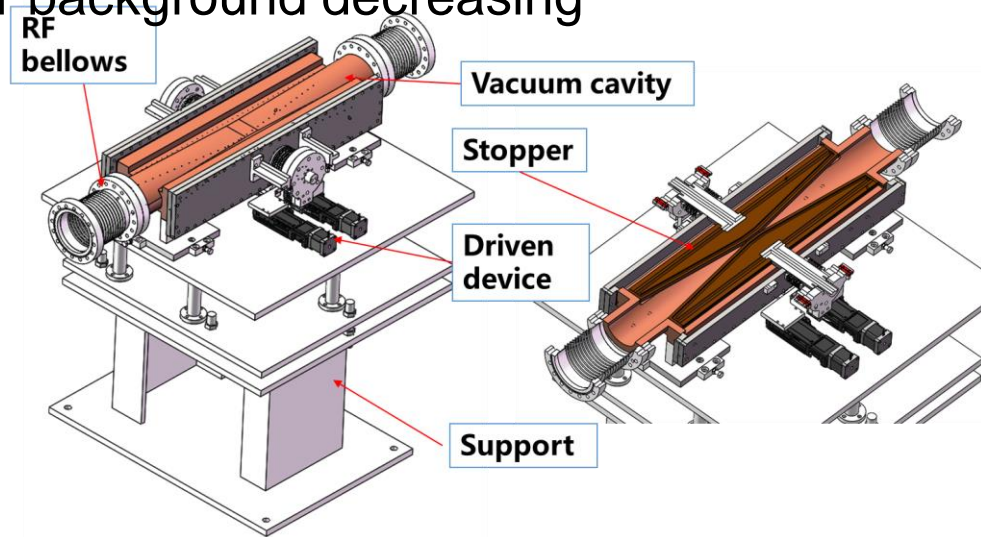
- 4.4 mm~20 mm

- Methods:

- FEA
- Thermal deposition analysis
- Impedance analysis
- Kinetic design

- Tools:

- ANSYS/Workbench
- Inventor
- Geant4
- CST

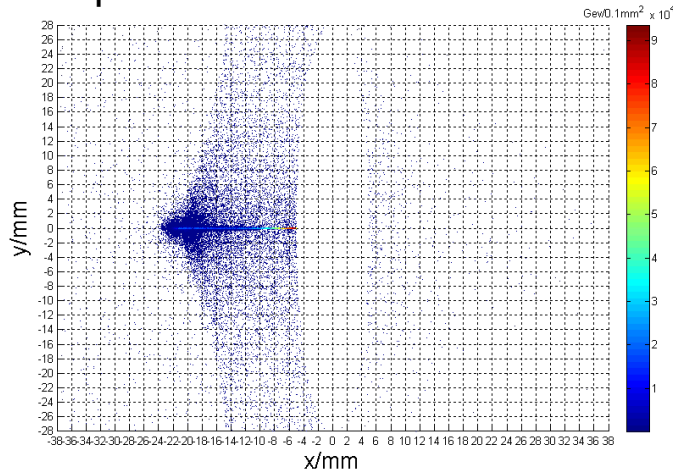


name	Position	Distance to IP/m	Beta function/m	Horizontal Dispersion/m
APT1	D11.1897	2139.06	113.83	0.24
APT2	D11.1894	2207.63	113.83	0.24
APT3	D10.10	1832.52	113.83	0.24
APT4	D10.14	1901.09	113.83	0.24

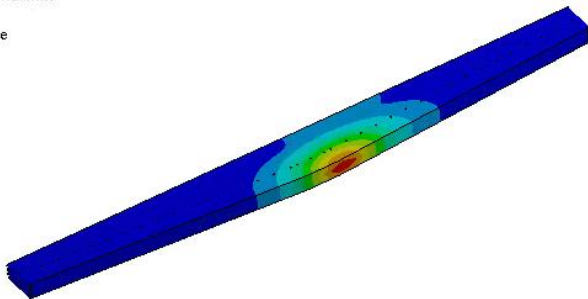
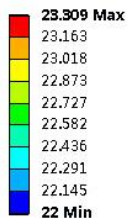
# Collimators and machine protection scheme

## Particle deposition

- Jaw material: Cu
- Total heat generation: **91.6 W**
- Maximum temperature raise by particle-material reaction: **2°C**

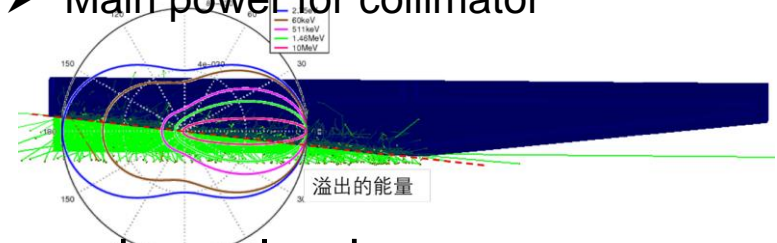


**B: Steady-State Thermal**  
Temperature  
Type: Temperature  
Unit: °C  
Time: 1



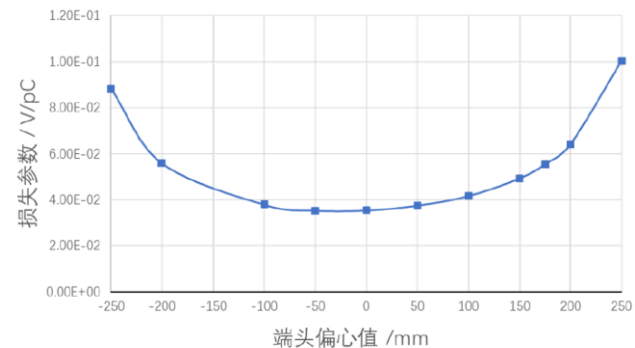
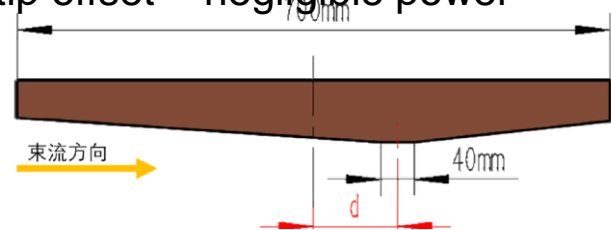
## SR load

- **9.3 kW**@30 MW, Higgs
- Main power for collimator



## Impedance<sup>TM</sup> load

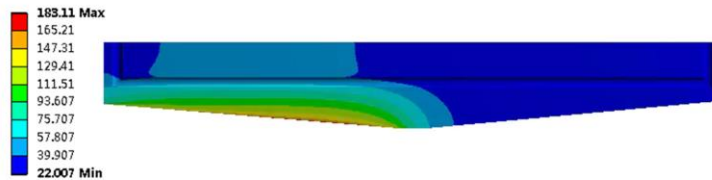
- Loss factor can be optimized with tip offset ~ negligible power



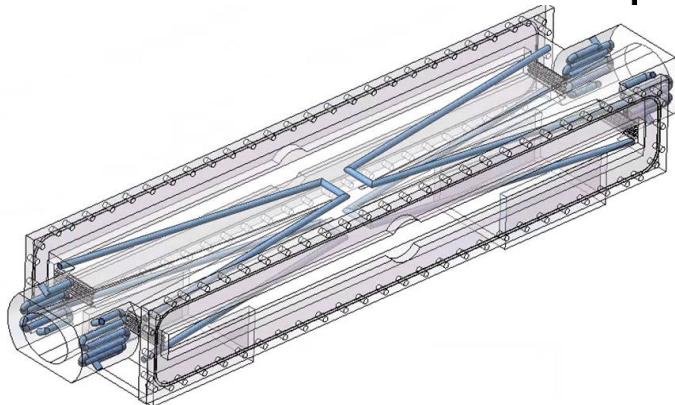
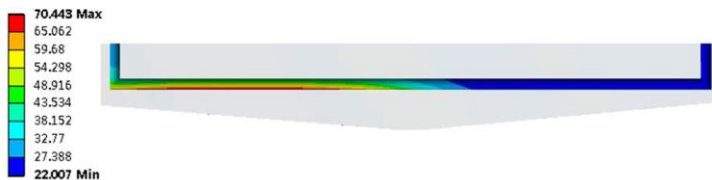
# Collimators and machine protection scheme

- Highest temperature in jaws: 183 °C
- Highest temperature in chamber: 143 °C

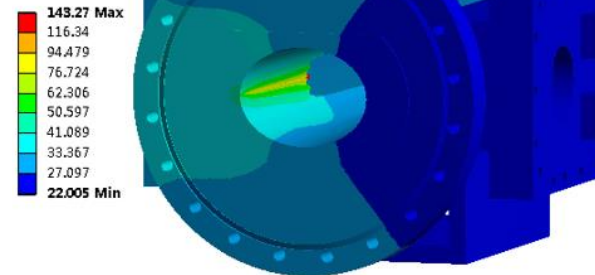
**B: Steady-State Thermal**  
Temperature  
Type: Temperature  
Unit: °C  
Time: 1



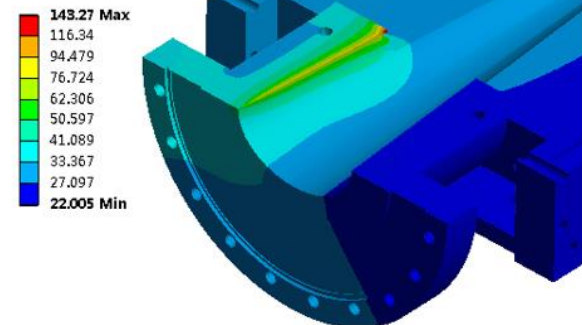
**B: Steady-State Thermal**  
水冷壁面温度  
Type: Temperature  
Unit: °C  
Time: 1



**B: Steady-State Thermal**  
Temperature  
Type: Temperature  
Unit: °C  
Time: 1



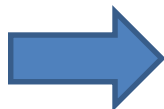
**B: Steady-State Thermal**  
Temperature  
Type: Temperature  
Unit: °C  
Time: 1

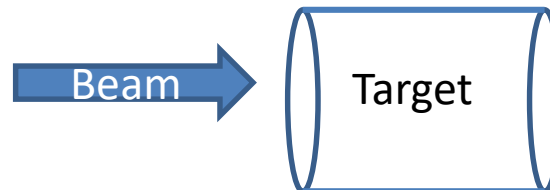




# Collimators and machine protection scheme

## ■ If the beam loss happens:

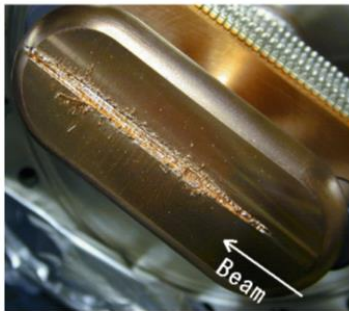
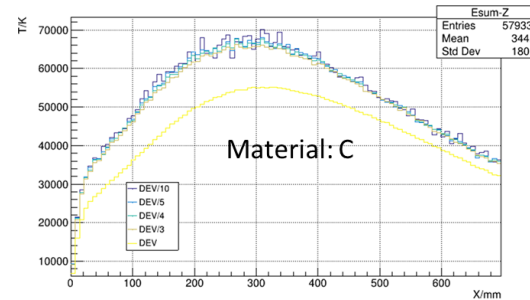
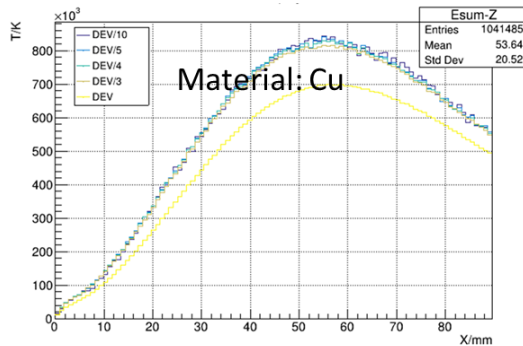
- 242 bunches,  $15 \times 10^{10}$  particles per bunch, 120 GeV. From CDR.
- $242 \times 15 \times 10^{10} \times 1.602 \times 10^{-19} \times 120 \times 10^9 = 697.831 \text{ kJ}$
- Equal to  $\sim 1.7 \text{ kg}$  copper from 20 °C to melting point or  $\sim 131 \text{ g}$  copper to gasification point.
- $4.6 \text{ m}$  long copper of the cross section (165, 35.7)  $\mu\text{m}$  will be gasified.
- $\Delta T = Q / (c \cdot m)$    $\Delta T = q * \frac{V}{(c \cdot \rho \cdot V)} = \frac{q}{\rho} * \frac{1}{c} = \frac{D}{c}$
- $\sim 0.3$  bunches for copper melting
- The facility should be protected from the mad beams, especially at IR.



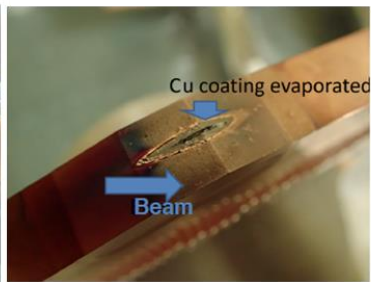
# Collimators and machine protection scheme

## ■ Beam loss failure of CEPC

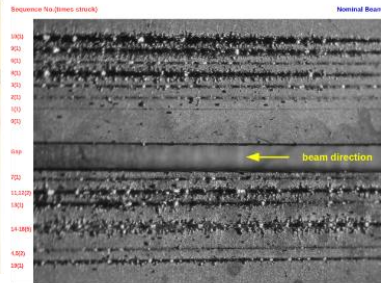
- If dipoles have powering failure, **The beam will be lost in 1 turn**, on collimators or on vacuum chamber. From accelerator physics.



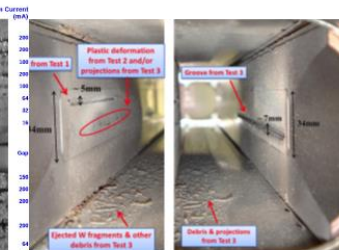
Broken collimator of KEKB



Broken collimator of Super KEKB



Experiments of APS-U



Experiments of LHC

- Beam loss failure on vacuum chamber or magnets should be avoided.

# Preliminary design on machine protection

- Machine protection—KEKB
  - Beam abort system, to avoid **direct hit on movable collimators**.
  - Response time: **~100 us (~10 turns)**.
- Machine protection —Super KEKB
  - Deliver the stored beam into a beam dump and prevent spewing beam **everywhere** in the ring.
  - Response time: less than **20 us. (~2 turns)**
- Machine protection-LHC
  - Collimators are used for **passive protection**. 99.99% of the lost protons were intercepted. 100 collimators.
  - Dump delay: **270 us (3 turns)**

Abe, Tetsuo, et al. "Achievements of KEKB." *Progress of Theoretical and Experimental Physics* 2013.3 (2013).

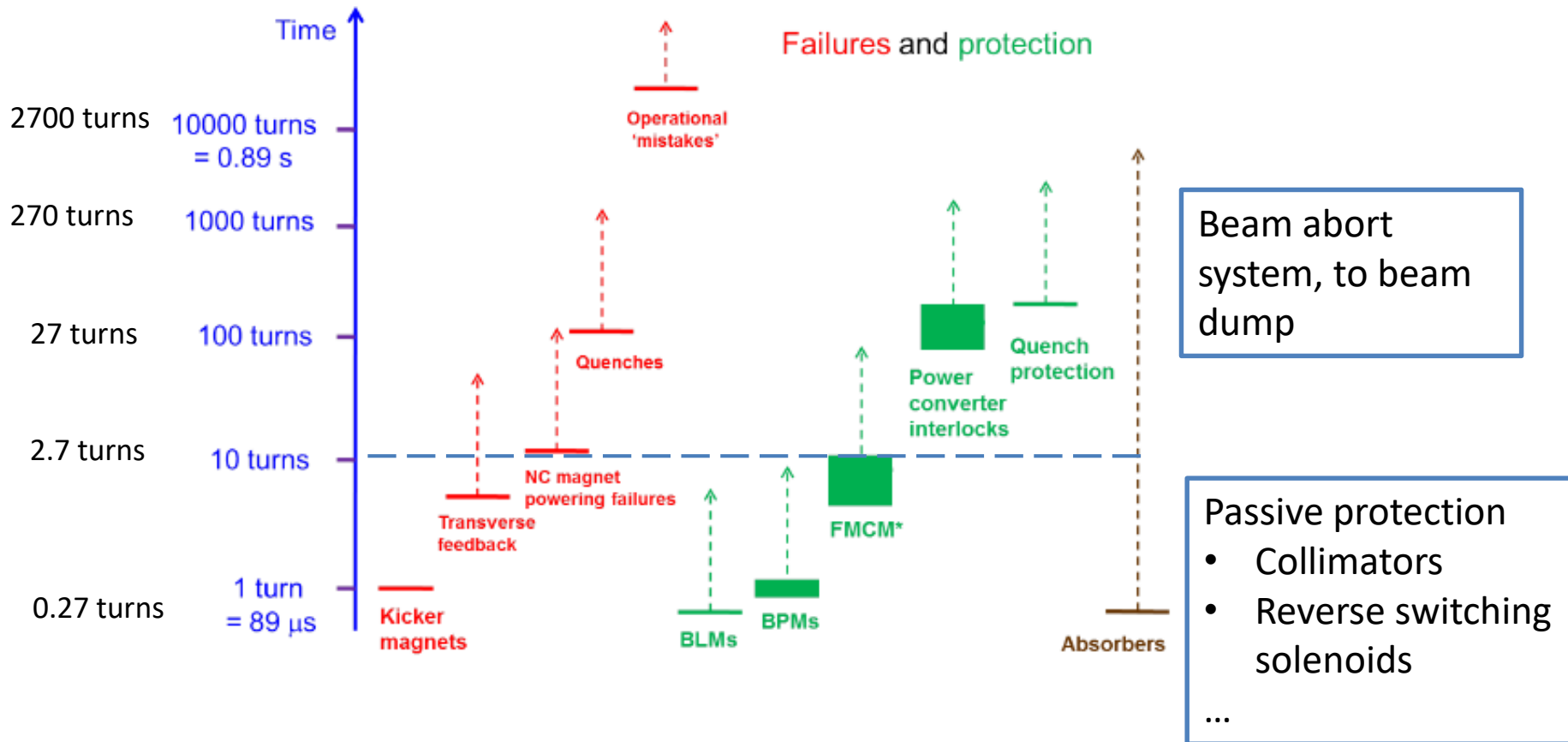
Akai, Kazunori, Kazuro Furukawa, and Haruyo Koiso. "SuperKEKB collider." *Nuclear Instruments and Methods in Physics Research Section A: Accelerators, Spectrometers, Detectors and Associated Equipment* 907 (2018): 188-199.

Mimashi, Toshihiro, et al. "SuperKEKB beam abort system." *Proc. IPAC 14* (2014): 116.

Wenninger, Jörg. "Machine protection and operation for LHC." *arXiv preprint arXiv:1608.03113* (2016).

# Preliminary design on machine protection

## ■ Preliminary scheme



# Preliminary design on machine protection

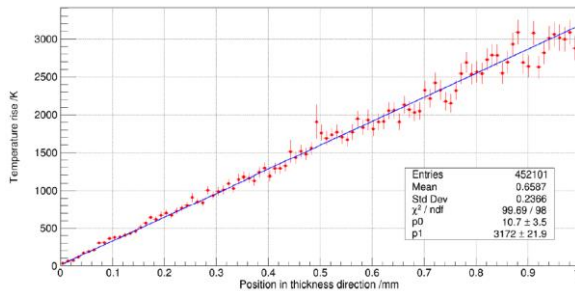
## ■ Possible method for passive protection

### ➤ By collimators

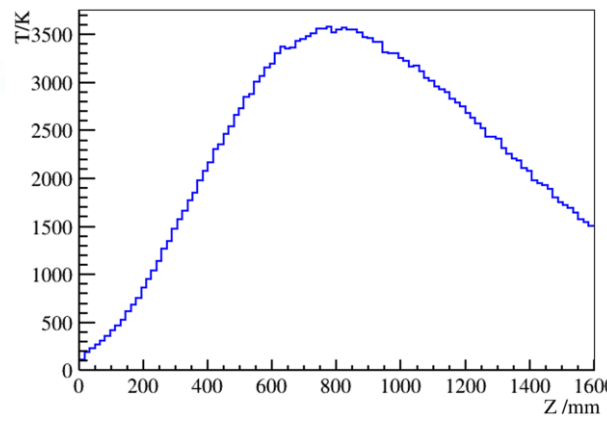
- Primary collimator: diamond, **1 mm** in thickness
- Secondary collimator: graphite, **200 meters** after
- The collimators can **endure the 242 bunches without melting.**
- Collimator distribution and impedances haven't been studied.

### ➤ By reverse switches

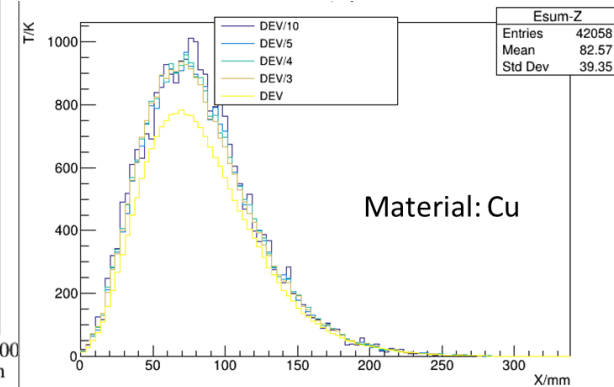
- Scale up the beam size three times larger, the **copper chamber** will not melt.
- **Auxiliary solenoids** on the vacuum chamber **with a reverse switching** with dipoles may be used to dilute each bunch.
- Response time and technical flexibility should be studied.



Temperature in 1 mm diamond



Temperature in graphite



# Summary

- Theoretical derivation, deformation optimization, topology optimization have been adopted in the magnet girder design, more detailed optimization works are on-going.
- We have made a workable MDI layout. Some key devices such as remote vacuum connector are designed.
- The collimators for background decreasing are designed. The beam loss failure has been considered and preliminary protection scheme with abort system, collimators and reverse switching solenoids are considered.

**Thanks for your attention!**