

SPL

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Cryostat and tooling

Patxi DUTHIL

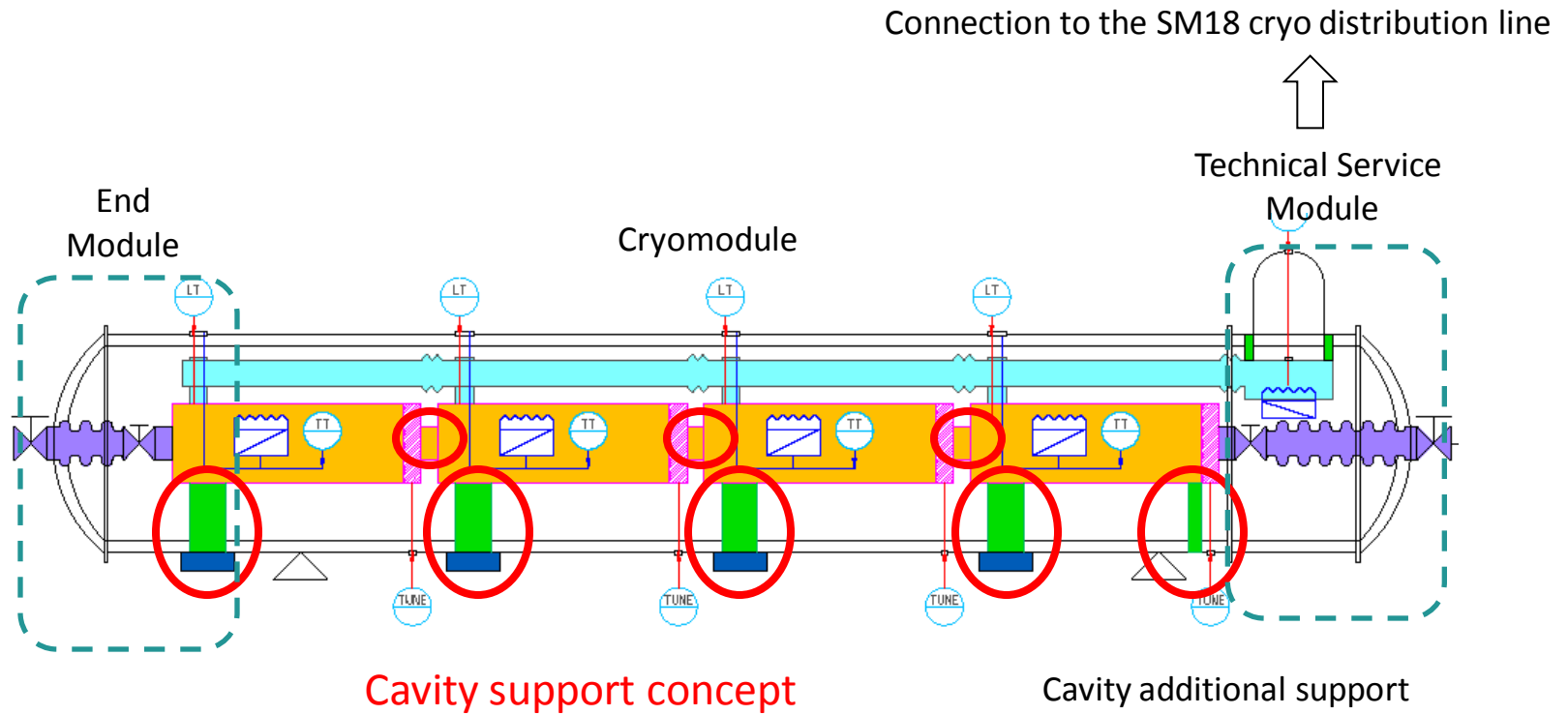
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SPL 5th Collaboration Meeting, CERN, Geneva
November 26th 2010

- ✦ **Cryostat layout**
- ✦ **Organization**
- ✦ **Vacuum vessel conceptual design**
- ✦ **Cavity support system conceptual design**
 - Coupler / vessel interface
 - Inter-cavity connection
- ✦ **Cryotating procedure**

Cryostat - General layout



1.7% Slope (adjustable 0-2%)

A.Vande Craen (MSC-CI)

Transversal position specification

BUDGET OF TOLERANCE			
Step	Sub-step	Tolerances (3σ)	Total envelopes
Cryo-module assembly	Cavity and He vessel assembly	$\pm 0.1 \text{ mm}$	Positioning of the cavity w.r.t. beam axis $\pm 0.5 \text{ mm}$
	Supporting system assembly	$\pm 0.2 \text{ mm}$	
	Vacuum vessel construction	$\pm 0.2 \text{ mm}$	
Transport and handling ($\pm 0.5 \text{ g}$ any direction)	N.A.	$\pm 0.1 \text{ mm}$	Stability of the cavity w.r.t. beam axis $\pm 0.3 \text{ mm}$
Testing/operation	Vacuum pumping	$\pm 0.2 \text{ mm}$	
	Cool-down		
	RF tests		
	Warm-up		
	Thermal cycles		

Construction precision

Long-term stability

☀ CNRS centralizes the CAD models of :

- the cryostat
- the CERN cavity and its CEA Helium tank
- of the CEA tuner

(validated during the CEA/CERN/IN2P3 meeting : October 15th 2010)

☀ CNRS integrated and updated the CEA tank, tuner and the CERN cavity : 15/11/2010

⇒ CNRS proposes the required modifications on

- . the helium tank
- . the tuner

to make the integration within the cryostat

⇒ Proposes have to be approved (or not) by CERN and CEA

⇒ Facilitate the integration

☀ Grid of analysis

- Analysis of the cryostating method
- Analysis of the stress/deformation in regards of the specifications (alignment spec.)
- Construction constrains and specifications

☀ 2 types of the cryostat vacuum vessel were studied

- Non-cylindrical cryostat allowing a vertical cryostating
 - More complex vessel design (need of a large opened window)
 - Simpler tooling for cryostating (to be discussed)
 - Smaller tank diameter : 1020mm (see cryostating method)
- Cylindrical allowing a longitudinal cryostating (LHC type)
 - Intrinsic better mechanical behaviour (inertia, vacuum)
 - Simpler construction
 - Larger diameter of the tank : 1500mm (see cryostating method)
 - Needs of windows for the accessibility of the cryostat components
 - Involves a more complex set of tooling (needs of lateral displacement)

Cryostat – Vacuum vessel conceptual study

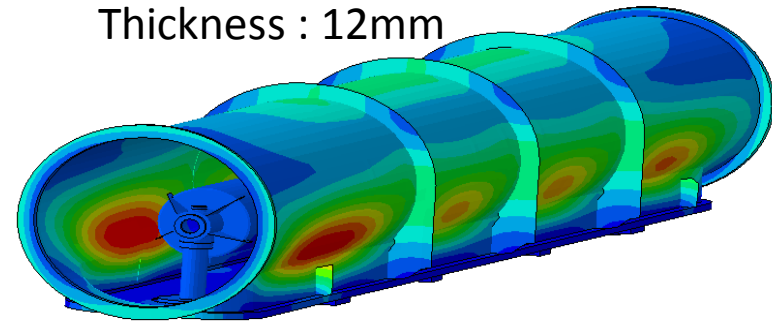
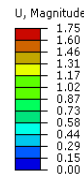
★ (Non-)cylindrical vessel allowing a vertical cryostating

- Preliminary vessel concept :
the geometry was taken from a pipe (→ **cut cylinder**)

Calculation of the displacements on the coupler flanges :

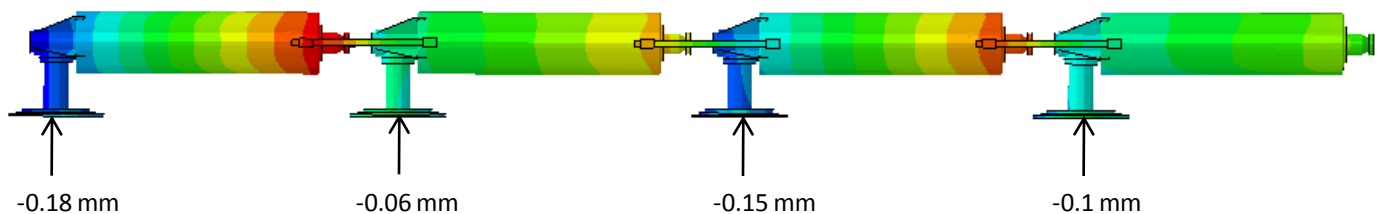
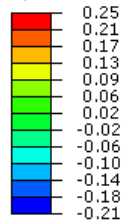
- external pressure of 1 bar (vacuum)
- acceleration : 1g
- with the load of 4 cavities & 4 tuners

$\varnothing_{ext} = 1020\text{mm}$
Thickness : 12mm



z ↓

U, U3



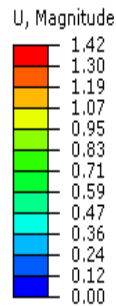
- ⇒ The weight of 4 cavities has a little influence on the deflexion
- ⇒ Maximum displacement obtained on coupler flange : 0.12 mm

★ Non-cylindrical vessel allowing a vertical cryostating

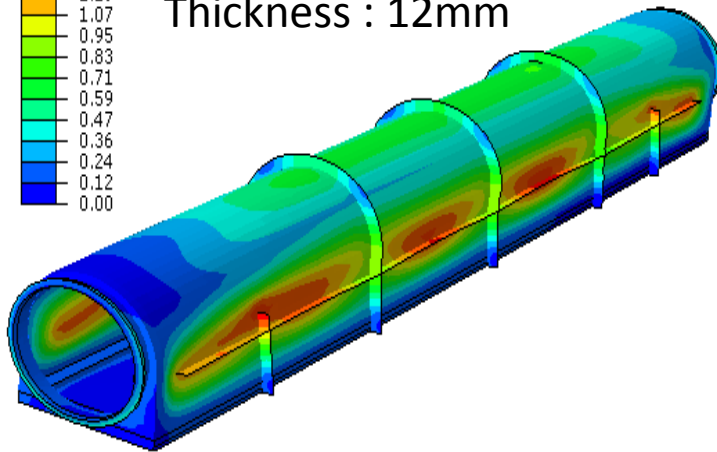
- Preliminary vessel concept → fabrication consideration :

use of a 12mm thick rolled metal sheet (→ **U shape**)

- external pressure of 1 bar on the tank to simulate vacuum constrain + 1g:



$\varnothing_{\text{ext}} = 1020\text{mm}$
Thickness : 12mm



Maximum displacement on the coupler flanges : 0.12mm

⇒ Rigidity can be at least as good as the cut cylinder

- ⇒ Thus, with some optimization, it seems realistic to achieve the specs.
- ⇒ But the fabrication seems not to be easy (interface of the tank closing)
- ⇒ It probably deeply impacts the fabrication tolerances

Cryostat – Vacuum vessel conceptual study

★ Cyl. vessel allowing a longitudinal cryostating (LHC type)

(→ **cylinder** : Intrinsic better mechanical behaviour)

- Example : external pressure of 1 bar on the tank to simulate vacuum constrain + 1g

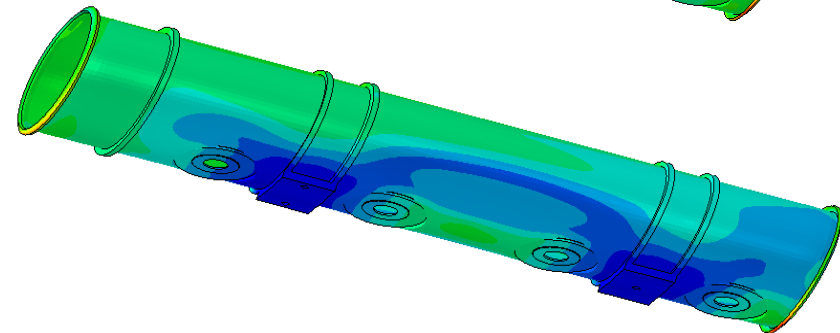
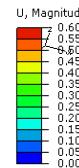
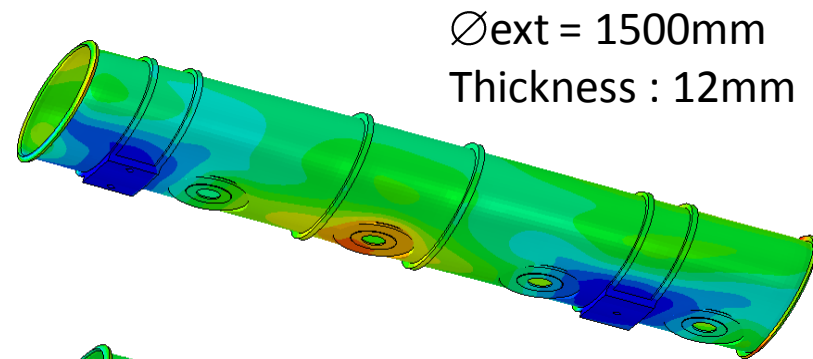
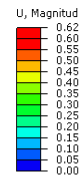
Distance between pods = 4500mm

→ ΔU_{max} (couplers flanges) = 0.3mm

- Way of optimization :
position of the pods

Distance between pods = 3000mm

→ ΔU_{max} (couplers flanges) < 0.1mm



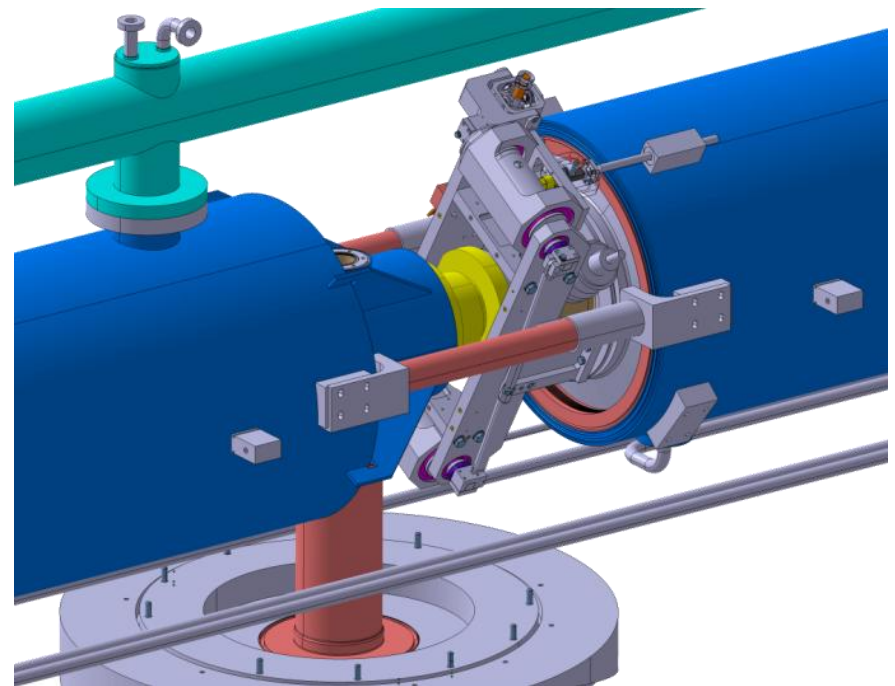
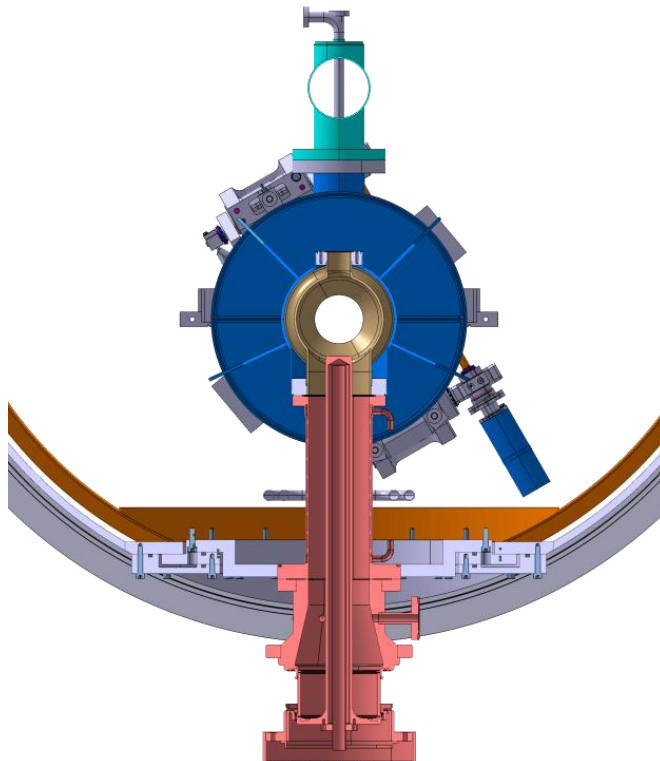
⇒ Optimization will aim at gaining on the estimated alignment tolerances

⇒ Optimization will be carried out in the frame of the detail study

Cryostat – Cavity Support system

☀ Based on :

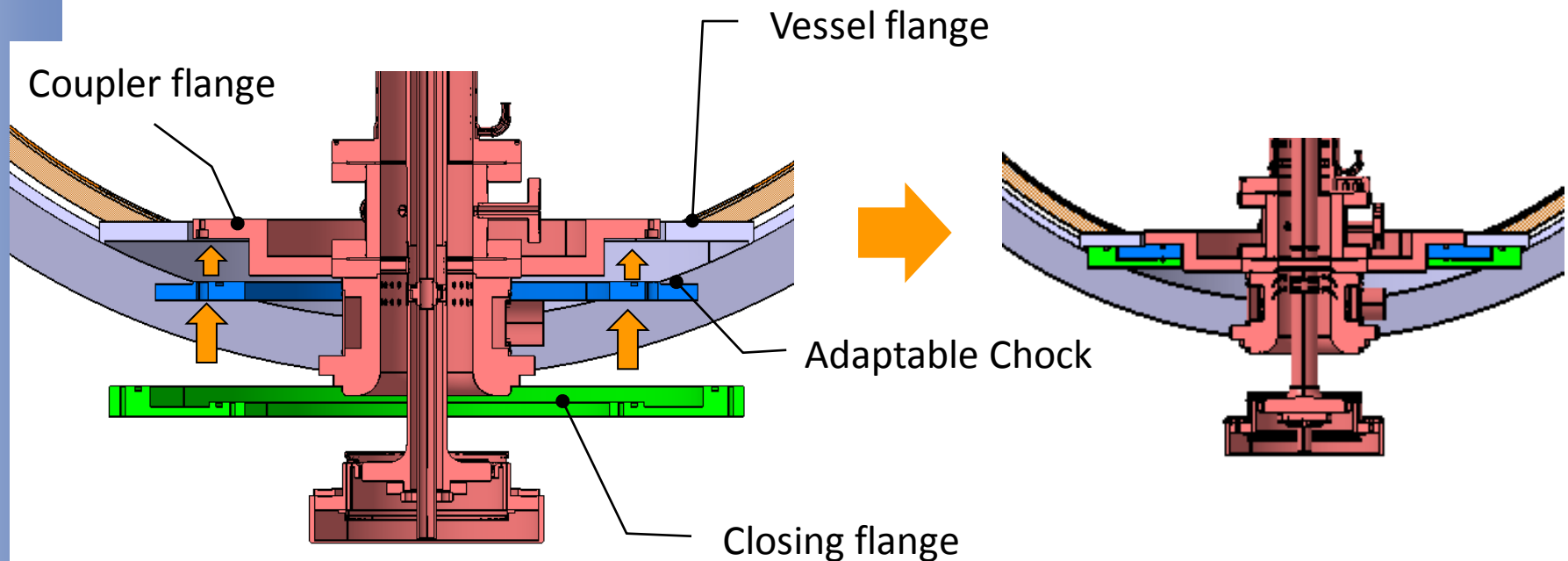
- Coupler bi-tube supporting
- Cavities inter-connections



Cryostat – Cavity Support system

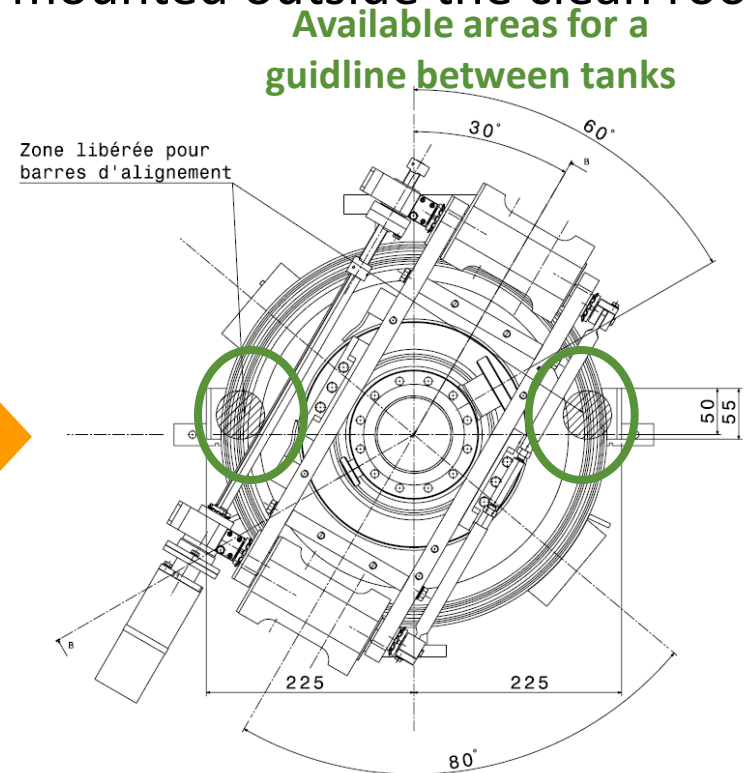
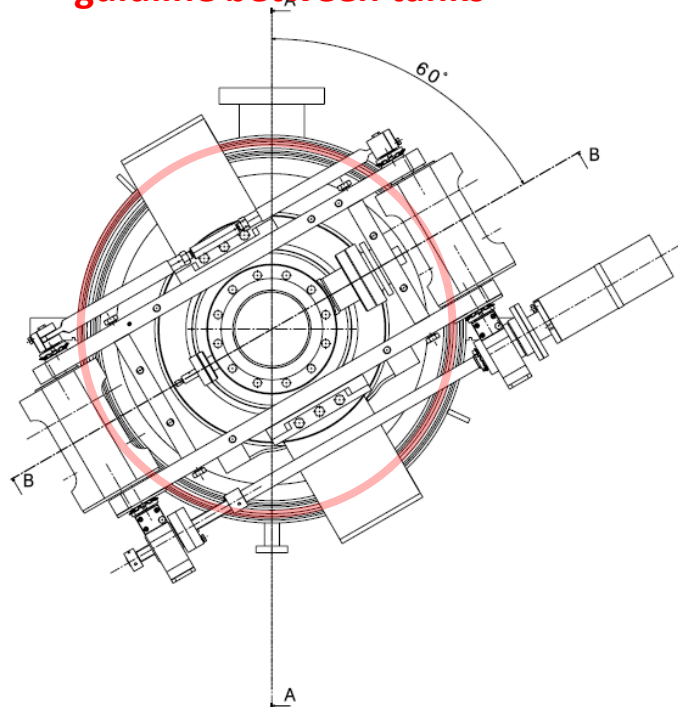
★ Coupler supporting

- Definition of the vacuum tank / coupler flange interface
 - in regards with the cryostating method

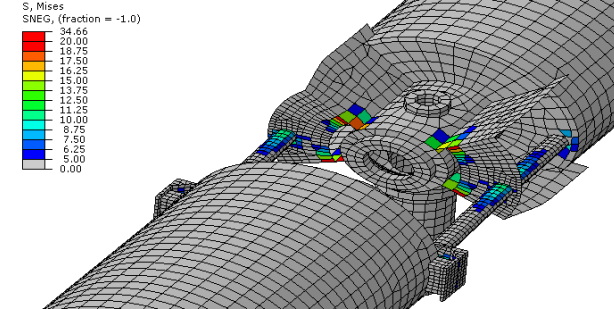
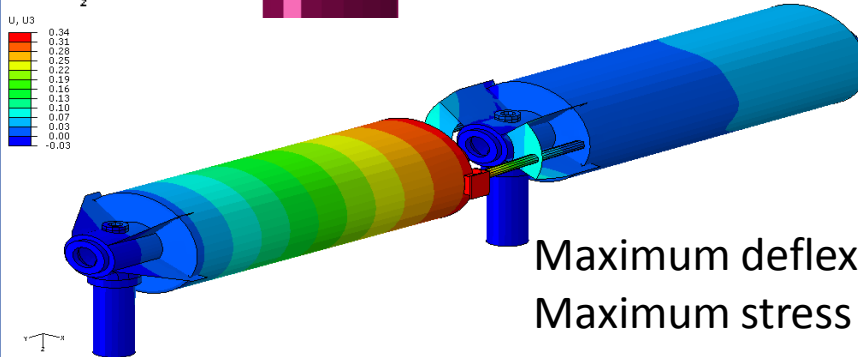
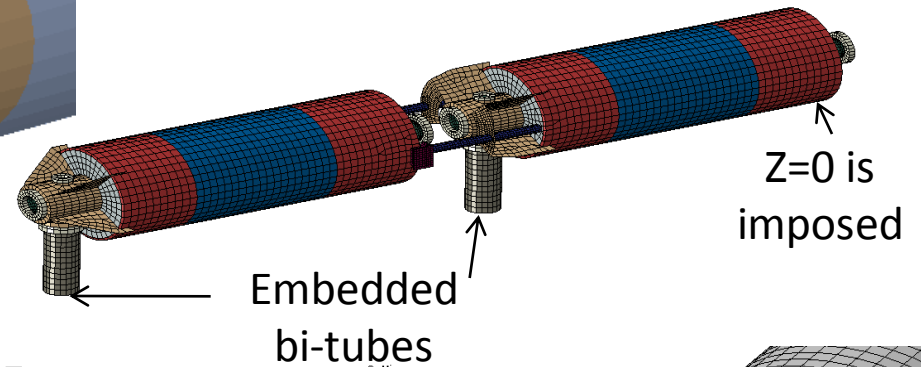
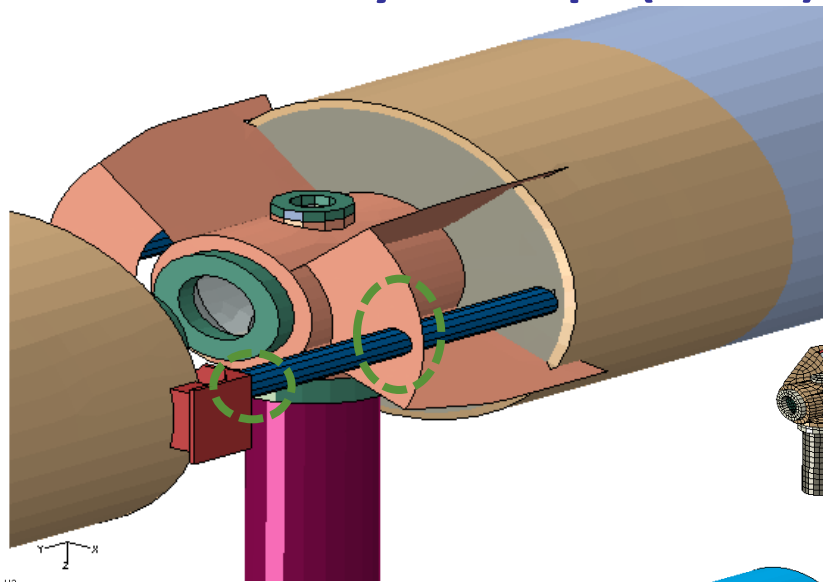


☀ Cavities inter-connection problematic

- Magnetic shield + Tuner + HOM + RF pick-up → obstruction → needs of a compact inter-connection
- LHe tank : weld between the elbow and the tank shell
- Inter-connection needs to be mounted outside the clean room
No available areas for a guideline between tanks

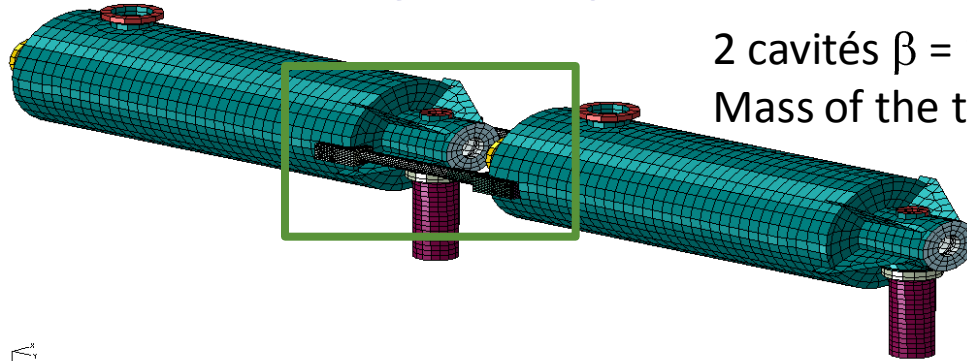


- ★ **Preliminary concept (CERN) :**
 - 2 x stainless steel $\varnothing=35\text{mm}$ rods
 - Reinforcing plates on the helium tank to reduce the deflexion of the rods
 - Sliding without friction and no gap



- ⇒ Compact inter-connection
- ⇒ Critical links between : plates/rods ; rods/tank gasket (different materials, welded areas, mounting procedure during the cryosating)

☀ Preliminary concept 2



2 cavités $\beta = 1$ fixed at the bottom of their couplers
 Mass of the tuner is taken into account



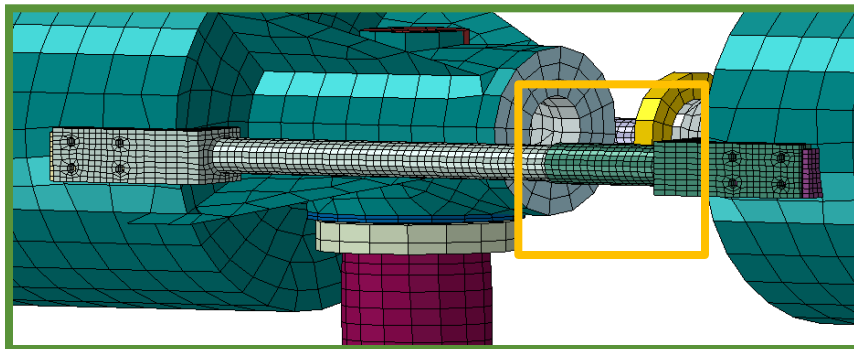
Assumptions :

Stainless steel tubes ($\varnothing_{ext} = 40\text{mm}$; $e=3\text{mm}$)

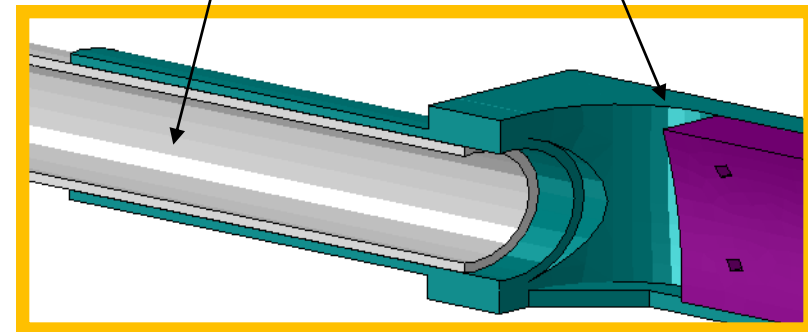
and support

Titanium He tank

Possibility of adding 2 chocks for the y and z alignment procedure

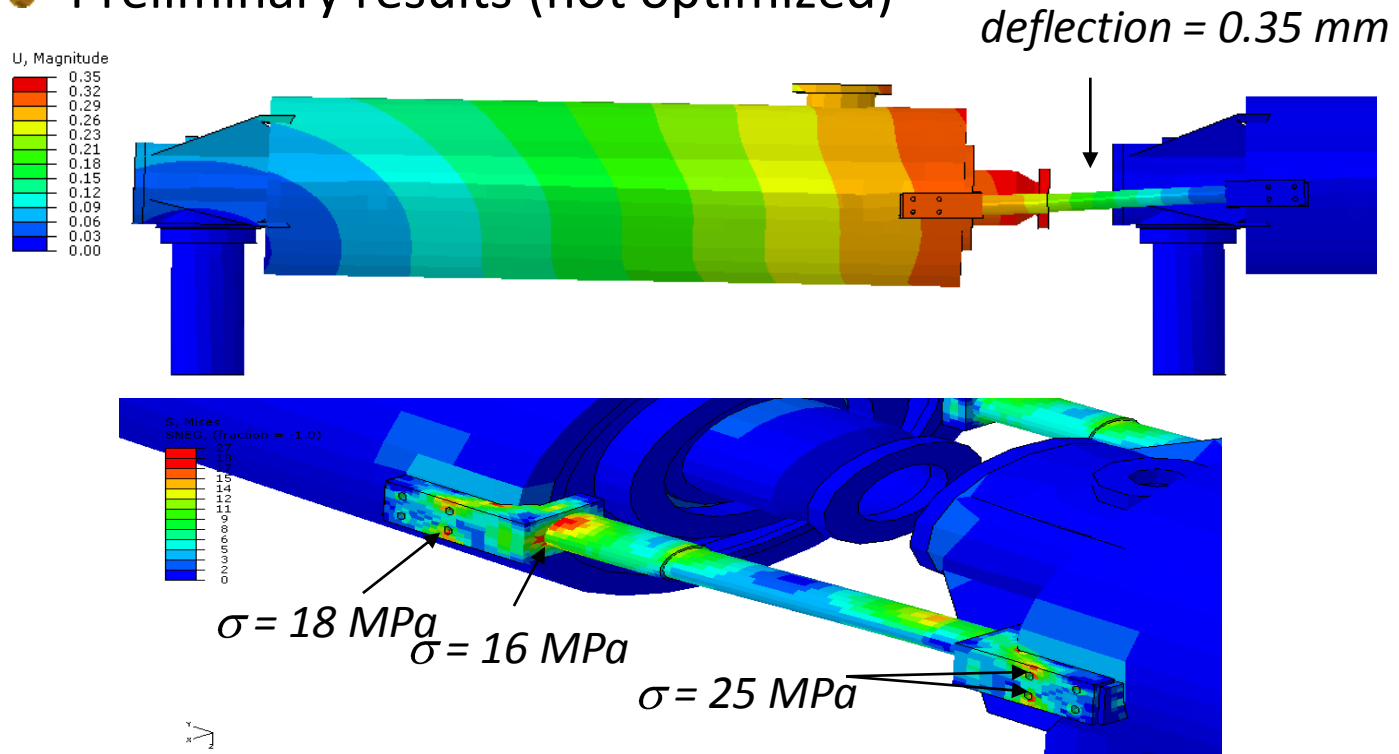


Sliding without friction - No gap



☀ Preliminary concept 2

● Preliminary results (not optimized)

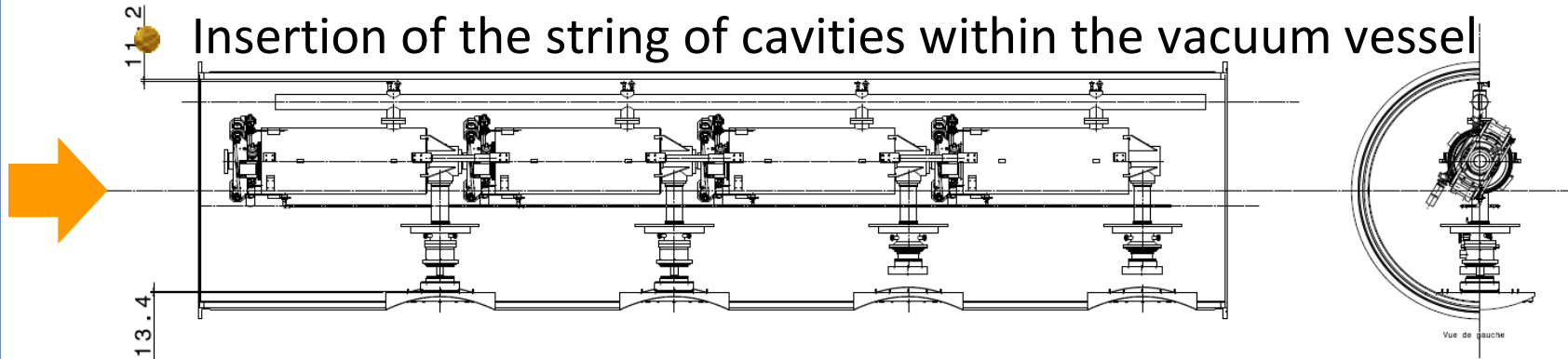


- ⇒ Small stress (elastic domain) ; but shear stress in the screws
- ⇒ Optimization :
 - . stress (including shear stress) : shape of the brackets (U-shape)
 - . deflection : tube diameters / length of the slider / material

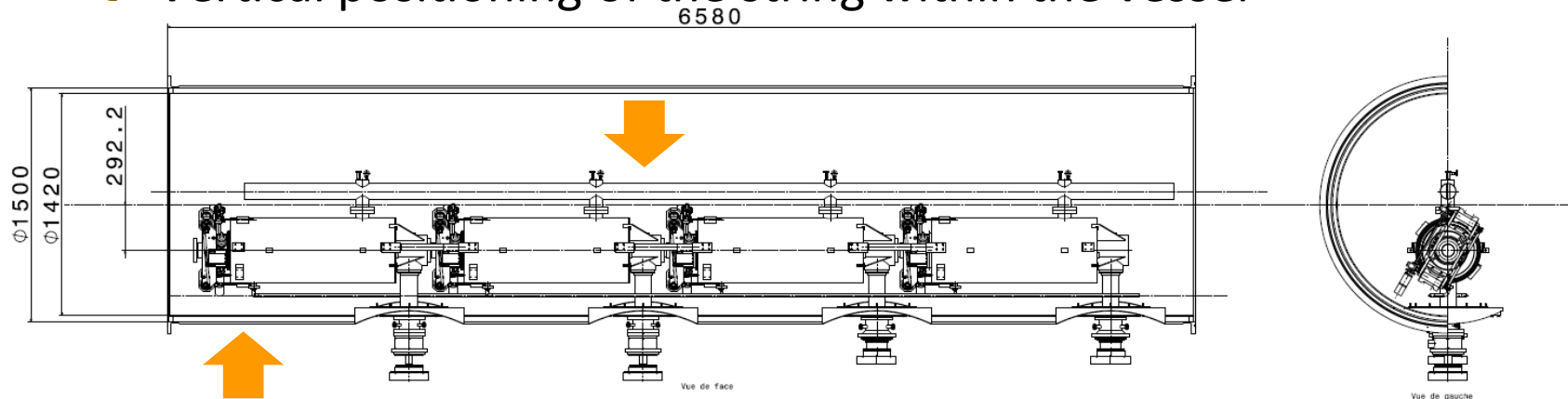
Cryostating procedure for a cylindrical vacuum vessel

General principle : longitudinal procedure

● Insertion of the string of cavities within the vacuum vessel

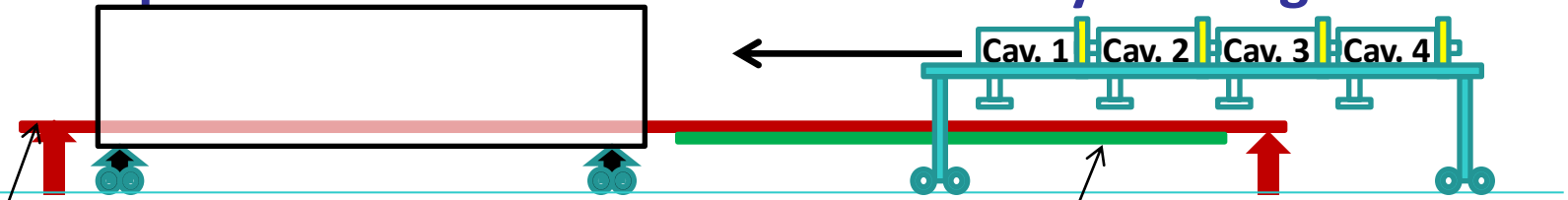


● Vertical positioning of the string within the vessel



Cryostating procedure for a cylindrical vacuum vessel

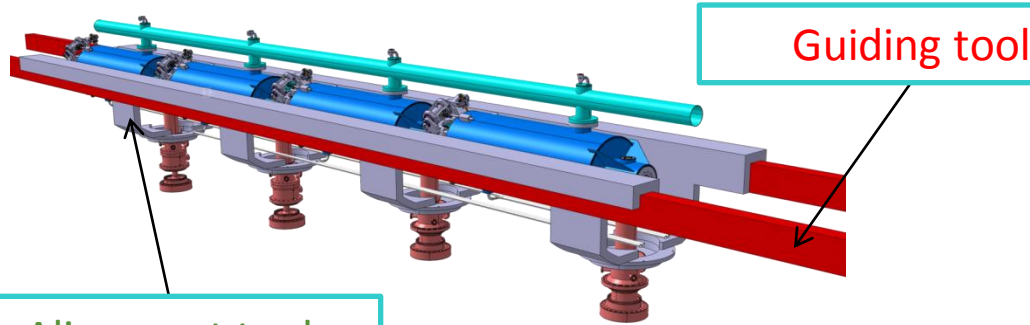
- ☀ Transport out of the clean room to the cryostating bench



Guiding tool

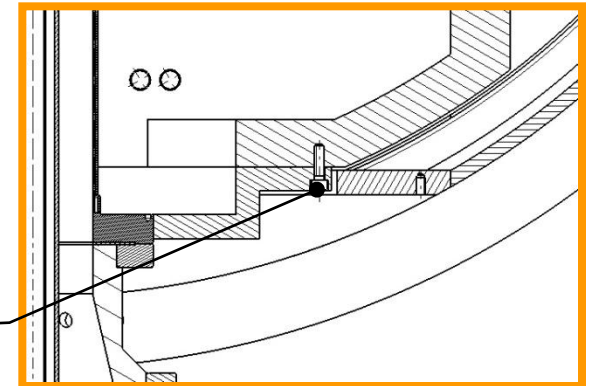
Alignment tool

- ☀ Lift of the and alignment guiding tools



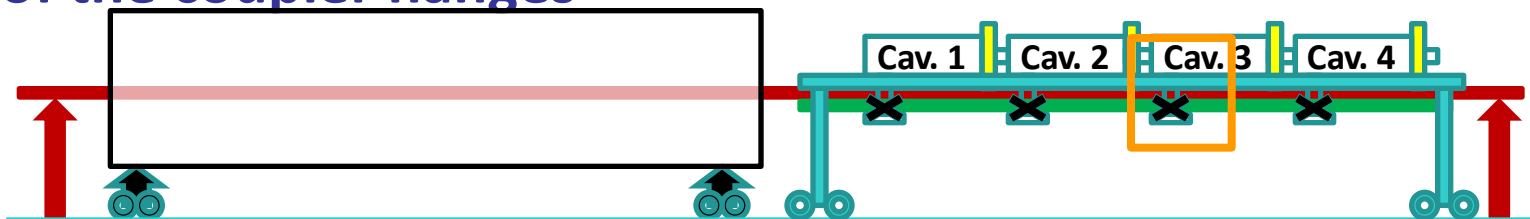
Alignment tool

Guiding tool



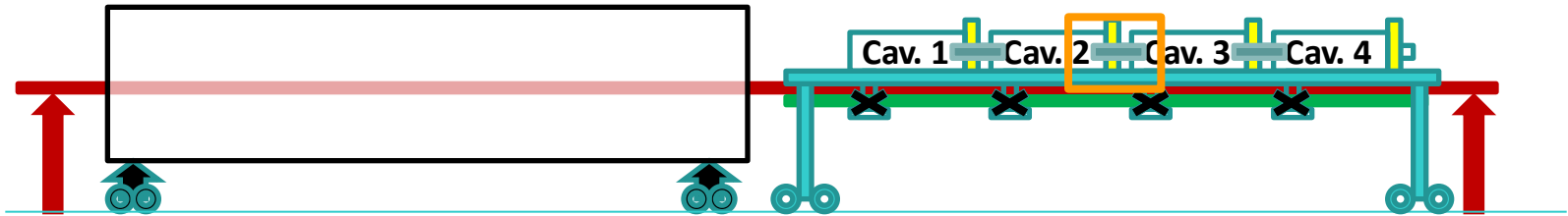
Adjustable stop
+ fixation

- ☀ Vertical positioning of the coupler flanges

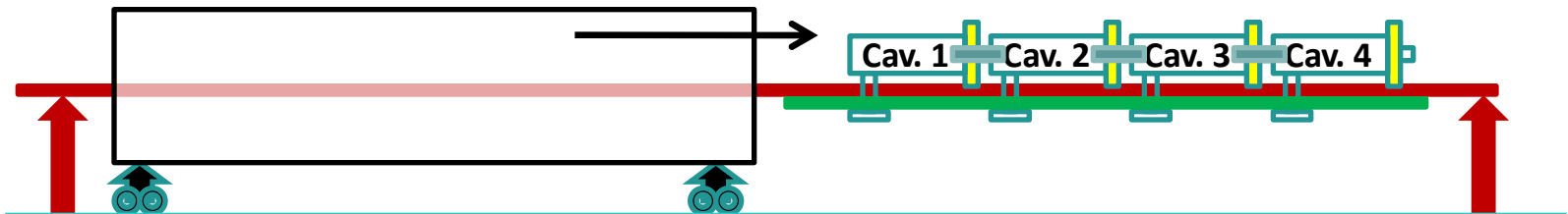


Cryostating procedure for a cylindrical vacuum vessel

- ☀ Lift of each cavity individually for alignment (not shown)
- ☀ Fixation of the support rods

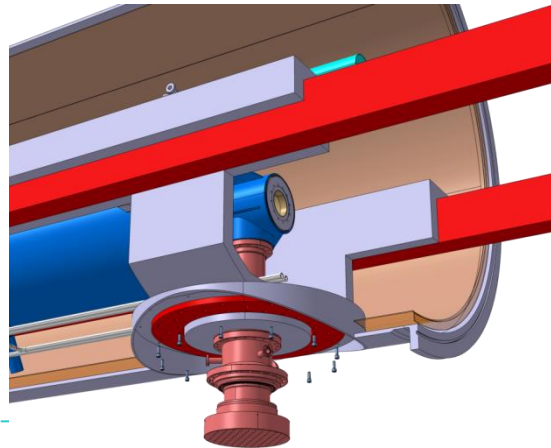


- ☀ Removing of the clean room trolley
- ☀ Moving of the vacuum vessel

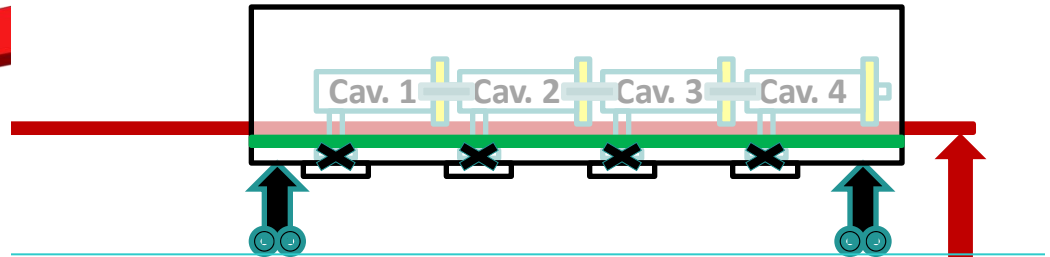


Cryostating procedure for a cylindrical vacuum vessel

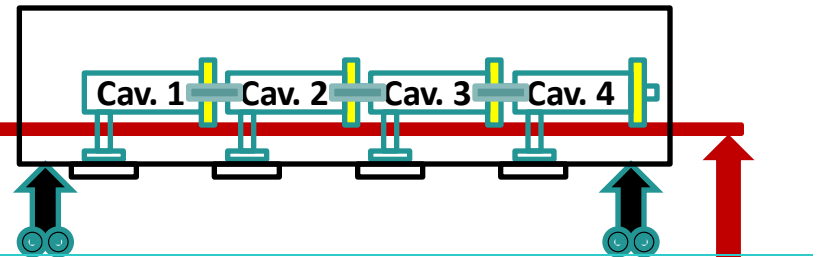
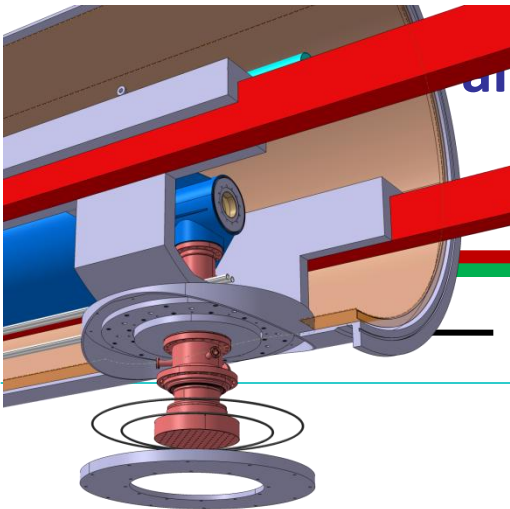
Lift of the vacuum vessel



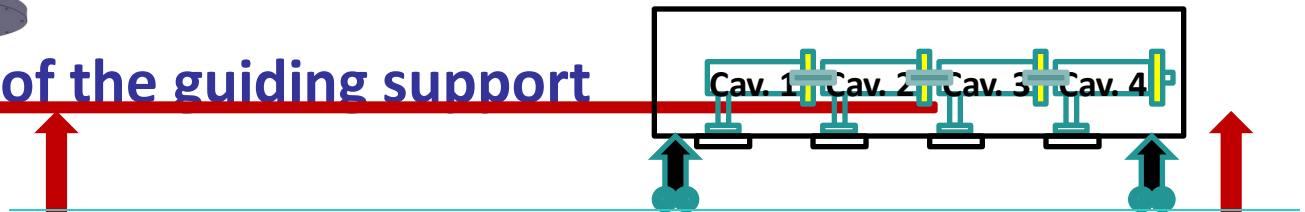
Indicated chocks at the coupler/vessel



Alignment tool and closing of the vacuum



Removing of the guiding support



- ✦ **Conceptual design is still under progress :**
 - Cryostating procedure
 - Vacuum vessel design
 - Analysis of the cryostating method
 - Analysis of the stress/deformation in regards of the specifications (alignment spec.)
 - Construction constrains
 - Support design
 - Coupler flange / vacuum vessel interface
 - Inter-connection cavity
 - CNRS centralizes CAD models and makes propositions

Thank you for your attention

