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The Phoenix GPS Receiver - A Practical Example of the Successful Application of a COTS-Based Navigation Sensor in Different Space Missions

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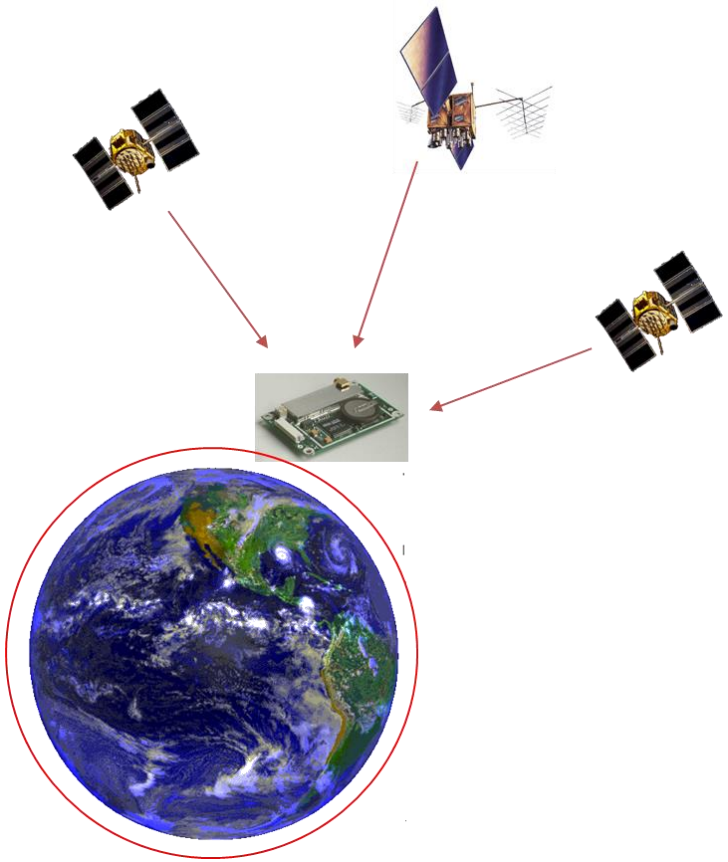


1. Background and Motivation

Background and Motivation

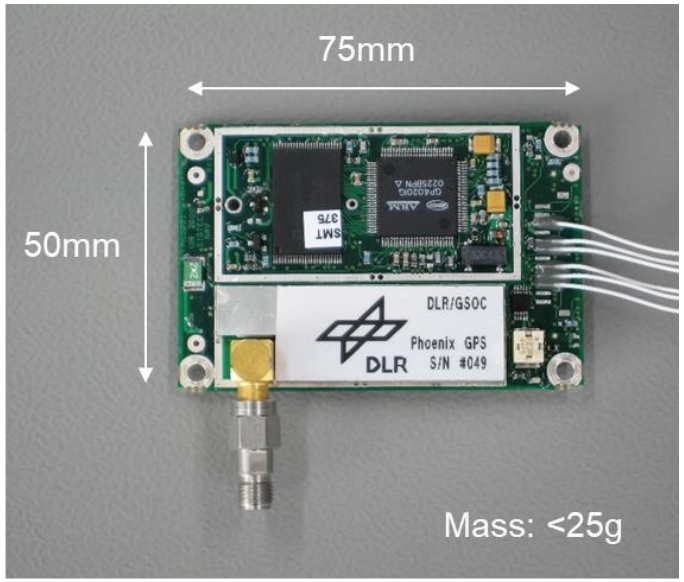
- GPS has become a „standard“ sensor in almost every space mission over the last two decades
- Fully space-qualified GNSS receivers are expansive (>1M€) - unaffordable for many projects due to limited budgets
- COTS-based GPS receivers are typically the only alternative for such missions
- However, use of COTS-based technology requires thorough testing and good understanding of reliability and failure mechanisms

- DLR designs, builds and operates satellites and sounding rockets
- Strong in-house need for affordable GPS/GNSS technology
- DLR’s Space Flight Technology group commenced to explore, develop, and test COTS-based GPS receiver in the late 1990s.
- Phoenix GPS receiver for space missions as one outcome of these works

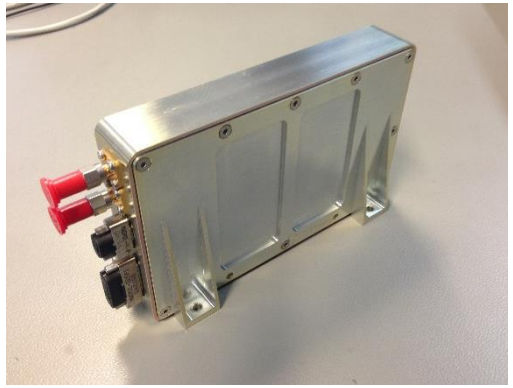
2. Phoenix GPS Receiver

Hardware Platform

- 12 channel L1 single-frequency receiver for high-dynamics applications
- Entirely based on COTS technology
- Commercial H/W platform (SigTec MG5001)
  - Approx. 70 x 47 x 11 mm3
  - Mass < 25 g
  - Power Consumption ~0.7-0.9 W
- Only minor modifications necessary for use in rockets and LEO satellites applications(battery, connectors)
- Additional I/F electronic required (Power and signal conditioning, latch-up protection, etc.)



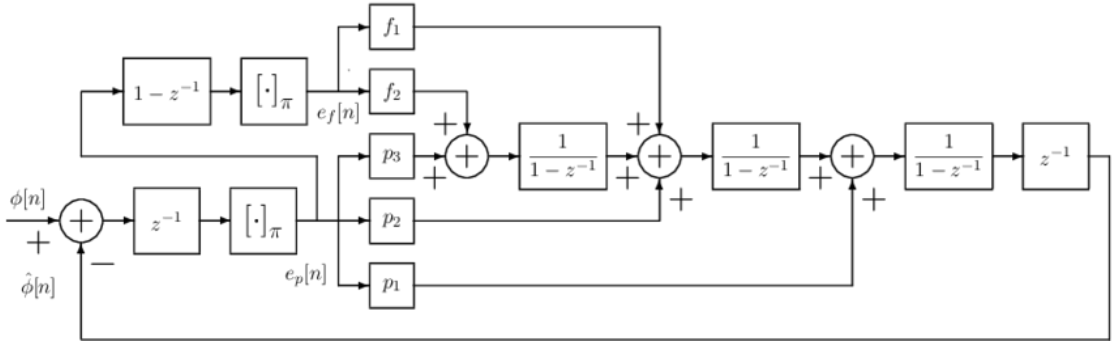
Top side of the Phoenix GPS receiver board



Self-contained GPS unit developed for Eu:CROPIS satellite mission

Receiver Firmware

- Originates from sample source code of an earlier available GPS development kit
- Received extensive revision and enhancements
- Added Carrier tracking
  - Carrier phase smoothing (reduced position noise)
  - Range-rate from carrier phase (accurate velocity)
- Advanced tracking loops for robust tracking under high signal dynamics
- Flexible TM/TC interface
- Integer second synchronization and 1PPS signal
- Hot start capability (30s)
  - Non-volatile memory and real-time clock
  - Aiding with two-line elements
- Available in two versions:
  - Phoenix-HD for high dynamic applications (launchers and rockets)
  - Phoenix-S for LEO satellites

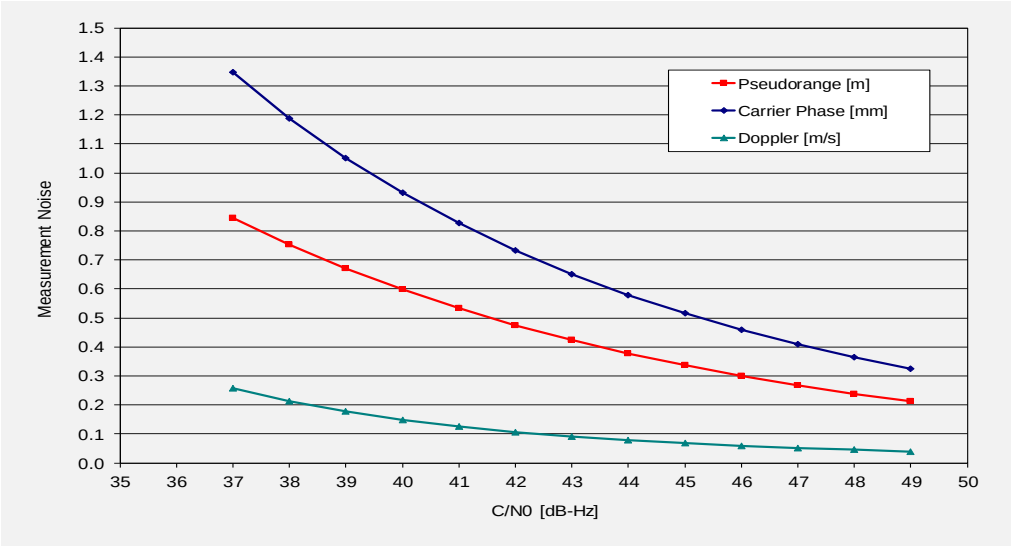


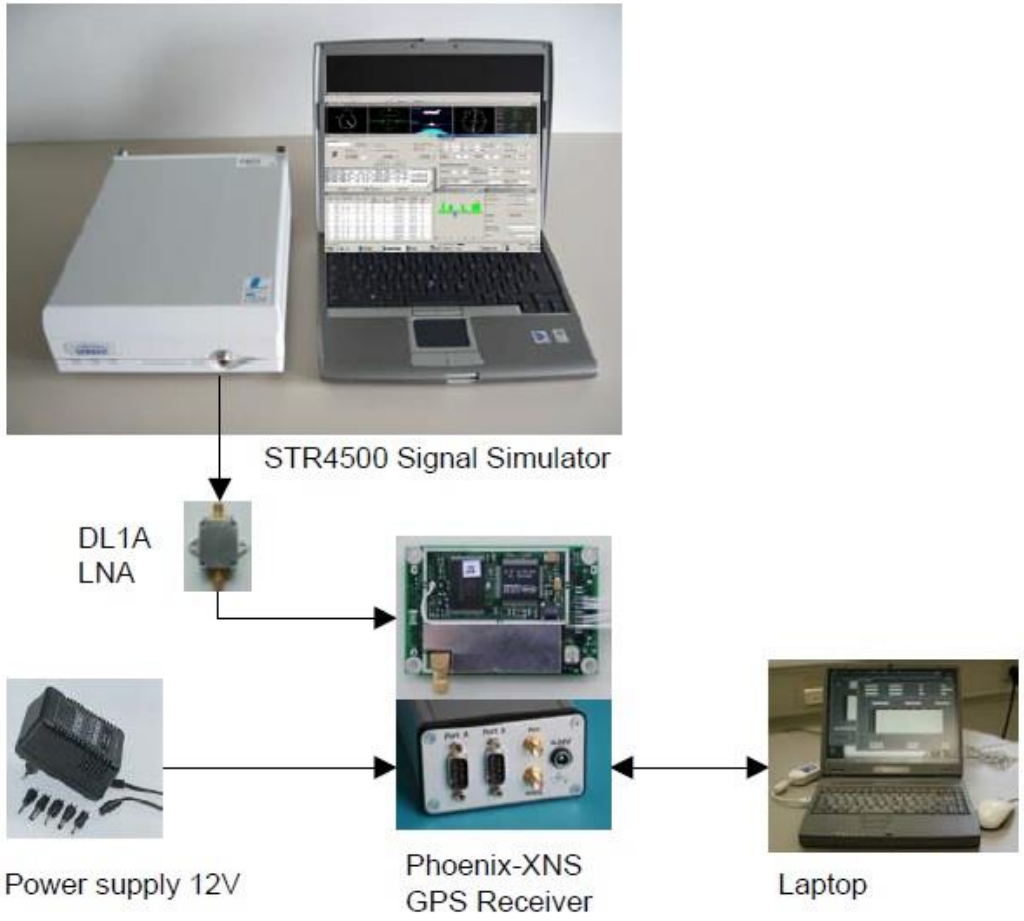
Block diagram of the FLL-assisted-PLL

3.1 Performance Assessment

Simulator Testing

- Hardware-in-the-loop test bed
- Use of a GNSS signal simulator
- Simulation of representative R/F signals
- Assessment of:
  - Acquisition and tracking performance
  - Navigation accuracy
  - Raw data accuracy



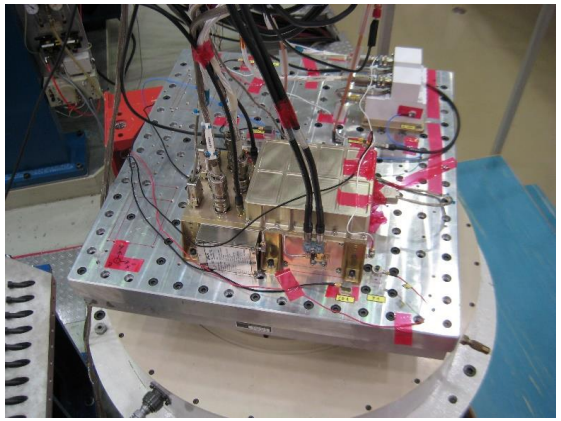


GNSS signal simulator test setup

3.2 Environmental Qualification

Vibration & Shock

- Tests conducted for wide range of load profiles (Soyuz, Ariane-5, Vega…)
- Both, on sub-system and system level
- Testing in operational mode (HiL)
- Stimulation of receiver with signals from a GNSS signal simulator or roof top antenna
- Study of impact of vibration onto tracking and navigation behavior and performance



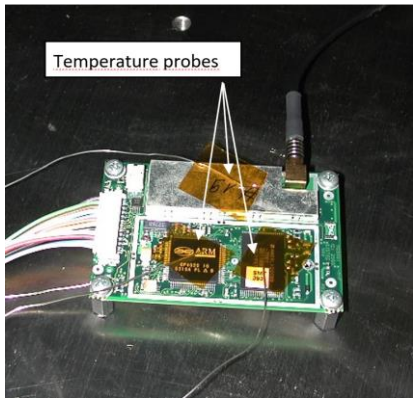
OCAM-G Payload mounted to the shaker table at IABG, Germany.

Sounding rocket payload during a vibration test at Airbus Ottobrunn, Germany

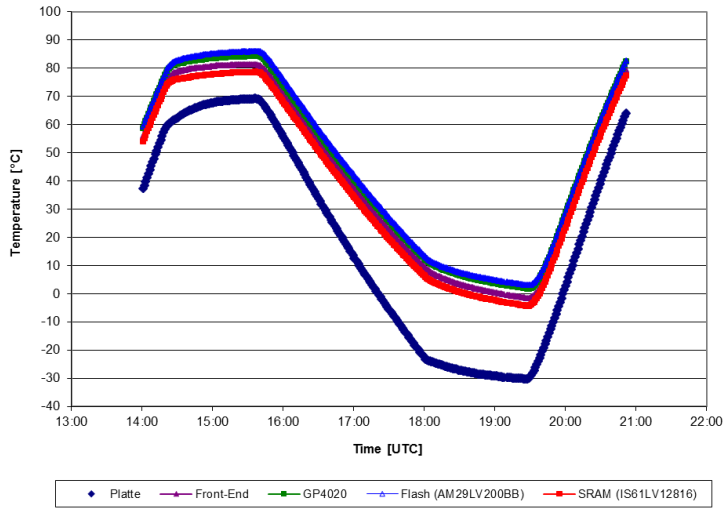
Thermal-Vacuum

Thermal-vacuum Test chamber at GSOC

- Test conducted at DLR's own test facilities in Oberpfaffenhofen in close accord with ECSS testing standards
- Atmospheric pressure as well as vacuum conditions
- Thermal cycling in operational and passive mode
- Temperature range:
  - -30° to +70° operational
  - -40° and +80° non-operational (storage)
- Increase of power consumption at higher temperatures (ca. +8%/100K)
- No impact on navigation performance found



Phoenix receiver with attached thermal probes

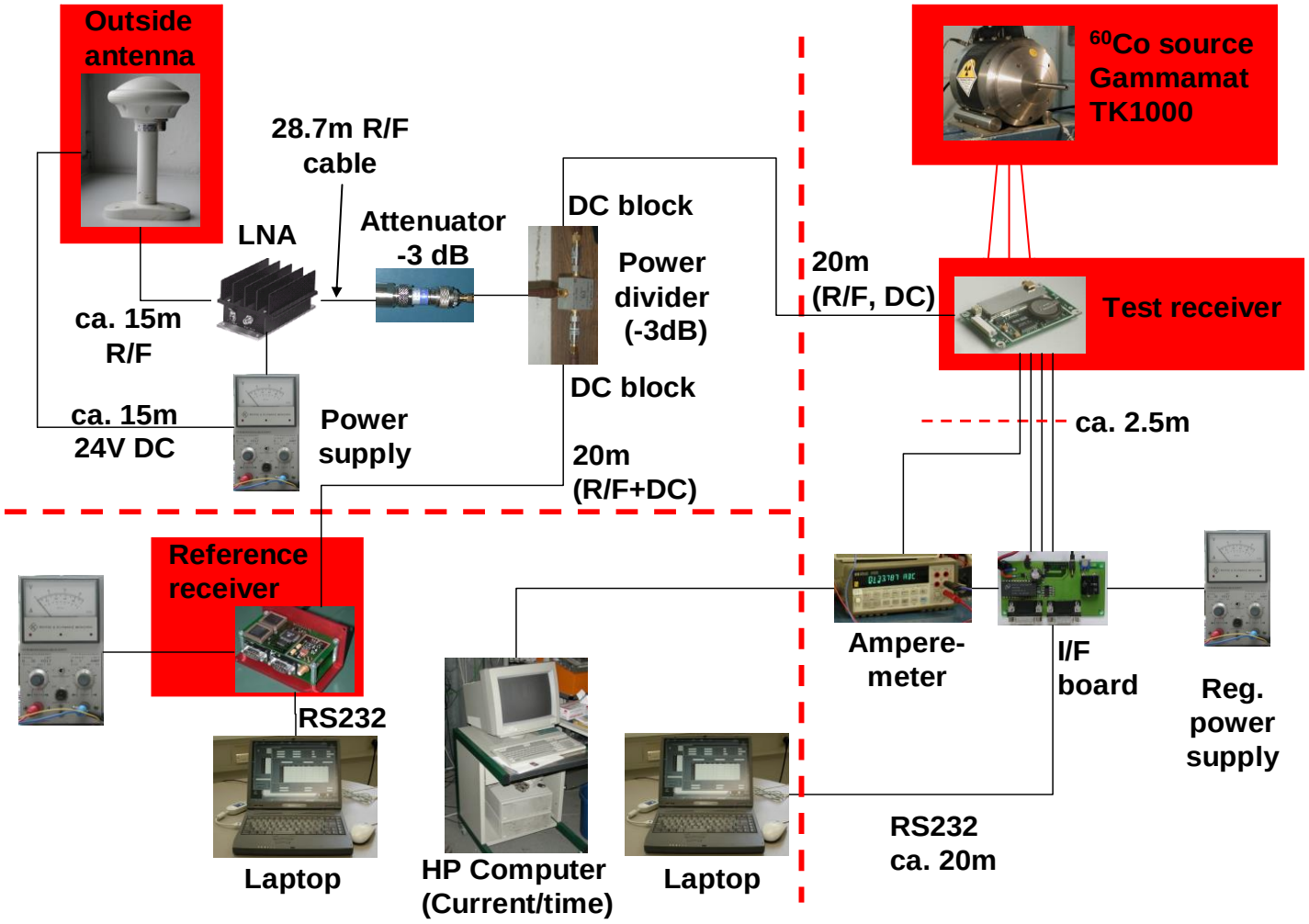


Example for one conducted thermal cycle

3.3 Radiation Effects Testing

Total Ionizing Dose

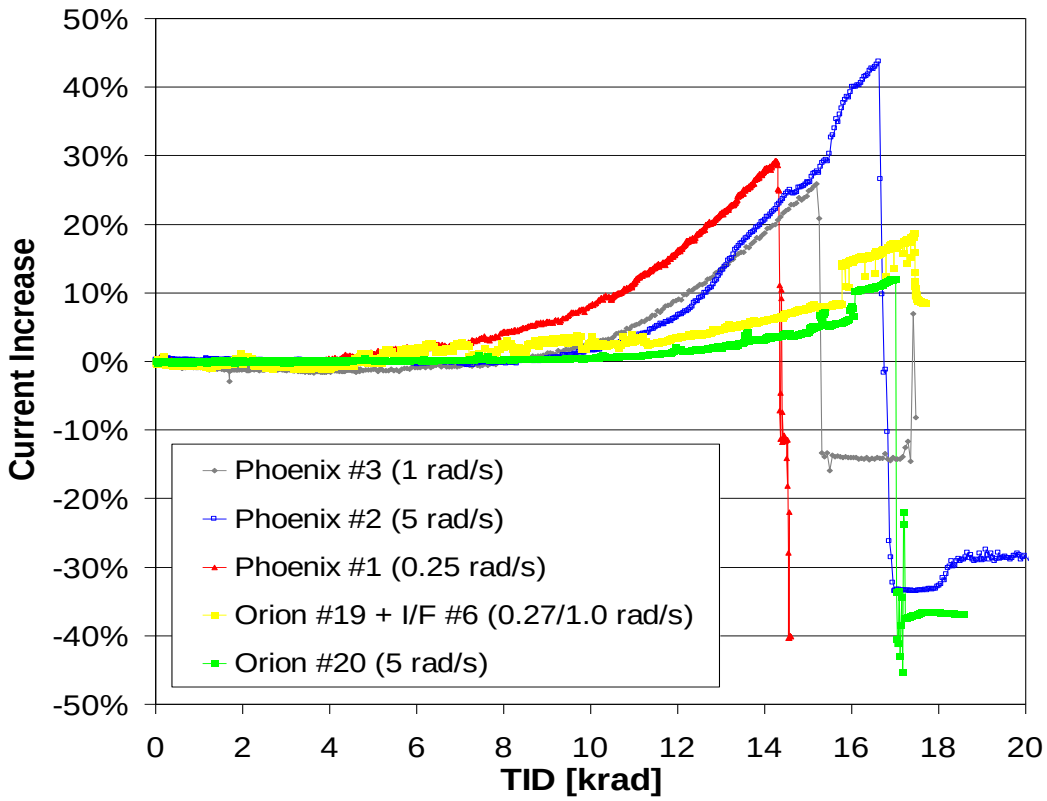
- Total Ionizing Dose (TID) test using Co-60 source
- Conducted at Fraunhofer Institute for Technological Trend Analysis (FhG/INT), Euskirchen, Germany
- Hardware-in-the-loop test setup
- Open-sky GPS signals via roof-top antenna
- Reference receiver operated outside test chamber
- Comparison of navigation solution as well as raw data



Total Ionizing Dose (cont'd)

- Dose rate 0.25 – 5 rad/s
  - Gradual increase of power consumption (25-40%)
  - Receiver break-down at 14-17 krad
  - Osc. frequency shift -1.1ppm/krad
  - Increased risk of cycle slips (oscillator?)
- Observed effects are dose rate dependent
- Self-healing after end of exposure

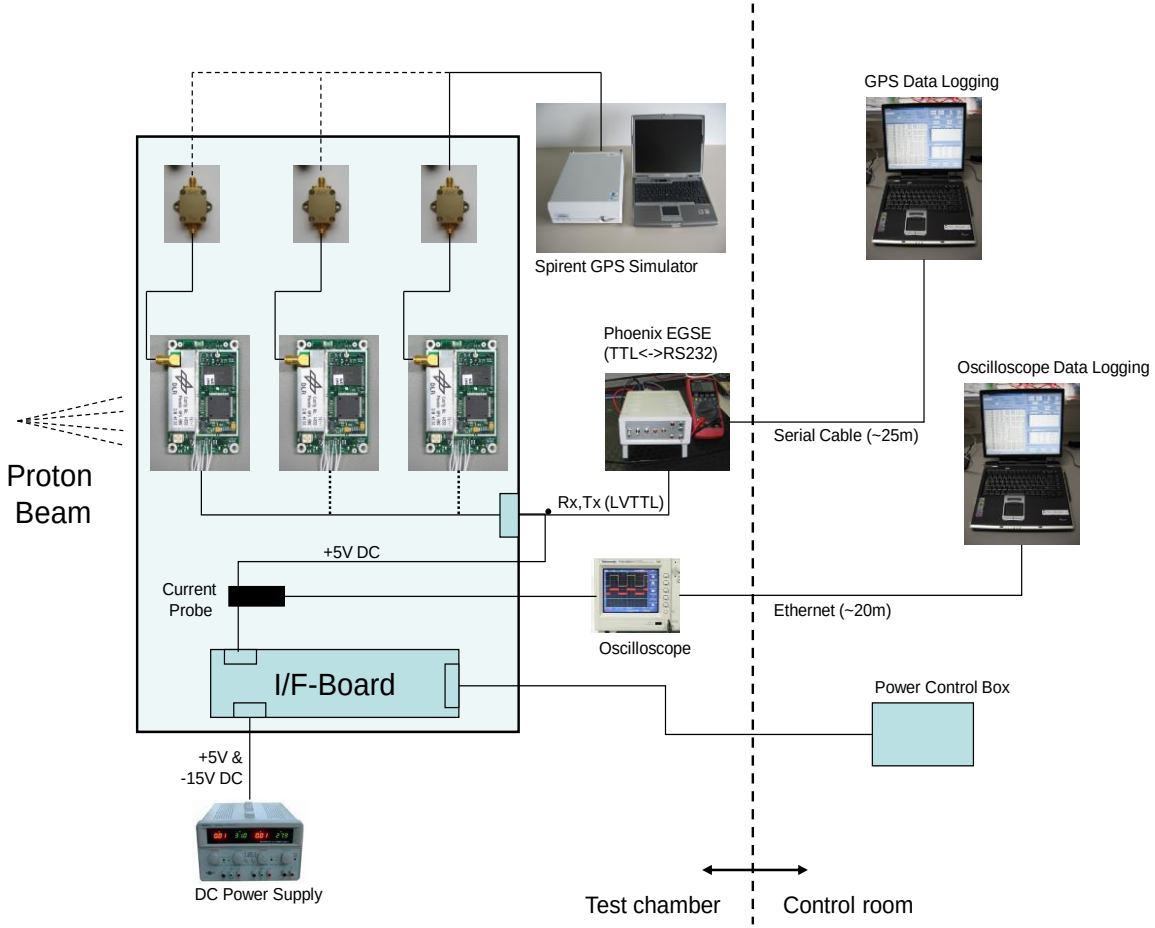
Test setup with DUT and Co-60 source



Current increase as function of the accumulated radiation dose

Single Event Effect

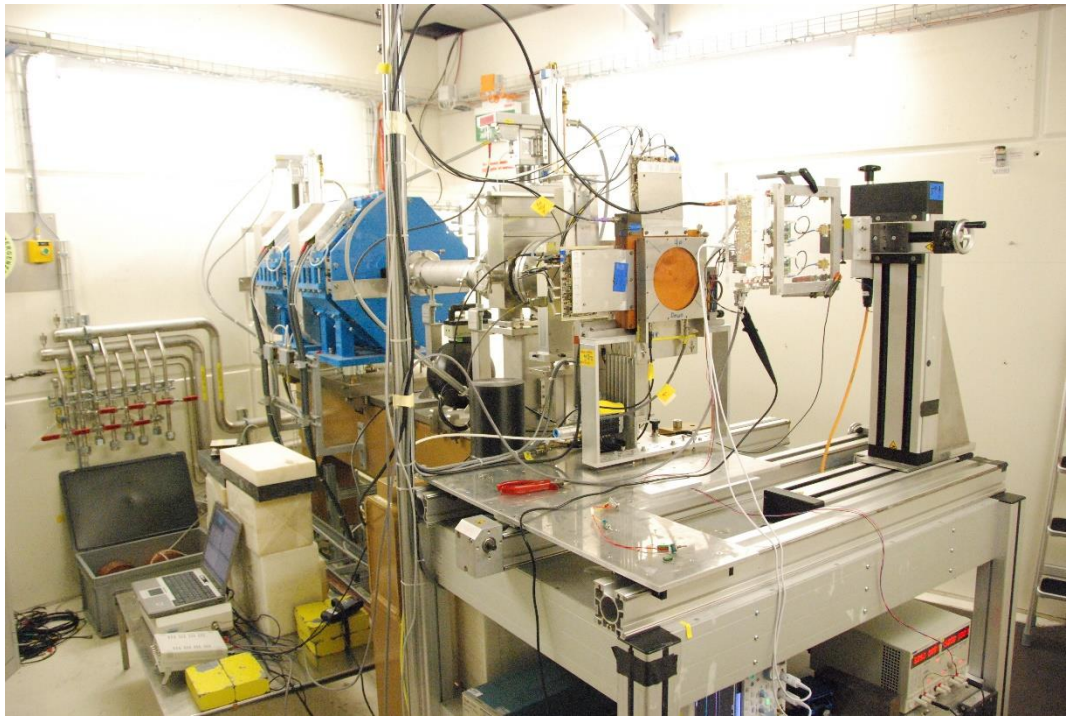
- SEE proton characterization performed:
  - at the JULIC proton cyclotron of the Research Center Jülich, Germany (together with Fraunhofer-INT)
  - at the Paul Scherrer Institute (PSI) in Villigen, Switzerland (together with ESA/ESTEC)
- Key objectives of the test campaign were:
  - Verify anomalies observed in previous satellite missions
  - Identify sensitive component(s)
  - Characterize nature of the anomalies and assess usability of the receiver for future space missions
- All tests performed on board level.
- Test boards connected to GPS signal simulator



Test setup used for the proton radiation tests conducted with the Phoenix GPS receiver

Single Event Effect (Cont'd)

- Two different versions of Phoenix boards tested
  - Only difference in size of SRAM chip
- Broad beam irradiation of entire board
- Narrow beam irradiation of different regions
- Receiver generally sensitive to SELs
- Latch-ups were found to be non-destructive
- SRAM chip identified as radiation-critical component
- SEL rate estimation performed for Proba-2 orbit (near-circular, sun-synchronous, 725 km altitude)
  - 0.01 /device/day for "standard" SRAM
  - 0.1 /device/day for extended SRAM
- No SEUs observed (probably due to "masking" by SELs)



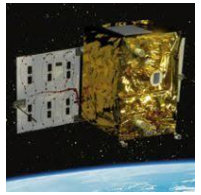
Radiation chamber at the Paul Scherrer Institute, Villigen, Switzerland

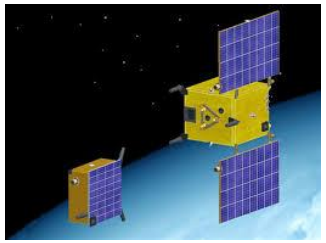
4. Flight Heritage

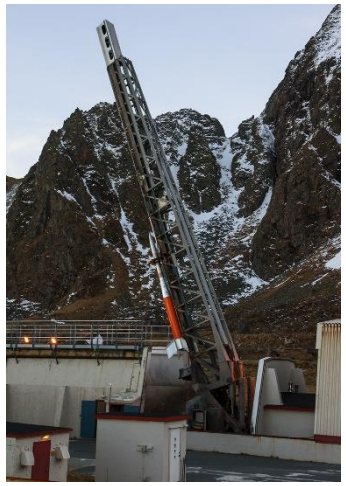
Phoenix GPS – Flight Heritage

Non-exhaustive list of missions and projects using Phoenix GPS receiver

LEO Satellites		
Mission/Project	Launch Date	Purpose
Proba-2 (ESA)	11/2009 - today	orbit determination, flight dynamic services, time synchronization
Proba-V (ESA)	5/2013 - today	orbit determination, flight dynamic services, time synchronization
Prisma (SSC)	06/2010 – (status unknown)	orbit determination, time synchronization, autonomous orbit and formation control
TET-1 (DLR)	07/2012 - 2019	orbit determination, flight dynamic services, time synchronization
BIROS/BEESAT-4 (DLR & TU Berlin)	06/2016 - 2019	orbit determination, flight dynamic services, time synchronization, formation flying
EuCROPIS (DLR)	12/2018 - 2020	orbit determination, flight dynamic services, time synchronization





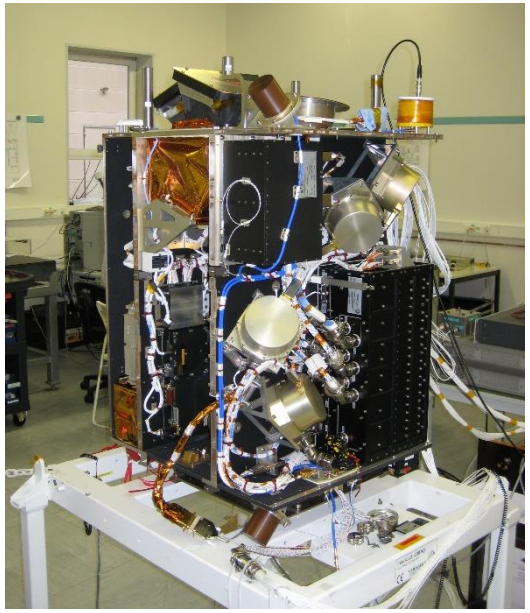


Sounding Rockets		
Mission/Project	Launch Date	Purpose
Texus 39 – 56 (ESA/DLR)	2001 - today	Flight safety, recovery, trajectory determination, time-synchronization
Maxus 4 – 9 (ESA)	2001 - 2017	Flight safety, recovery, trajectory determination, time-synchronization, GNC
Rexus 4 – 26 (DLR/SSC)	2008 - today	Flight safety, recovery, trajectory determination, time-synchronization
Shefex-I & -II (DLR)	2005 & 2012	Flight safety, recovery, trajectory determination, time-synchronization, GNC
WADIS 1 & 2 (DLR)	2013 & 2015	Flight safety, recovery, trajectory determination, time-synchronization, experiment support
MaxiDusty 1 & 2 (DLR/ASC)	2016	Flight safety, recovery, trajectory determination, time-synchronization (flight validation of a new rocket motor)
Launch Vehicles		
Ariane-V (VA 219) (ESA & OHB)	2014	Technology demonstration, Flight experiment, trajectory determination

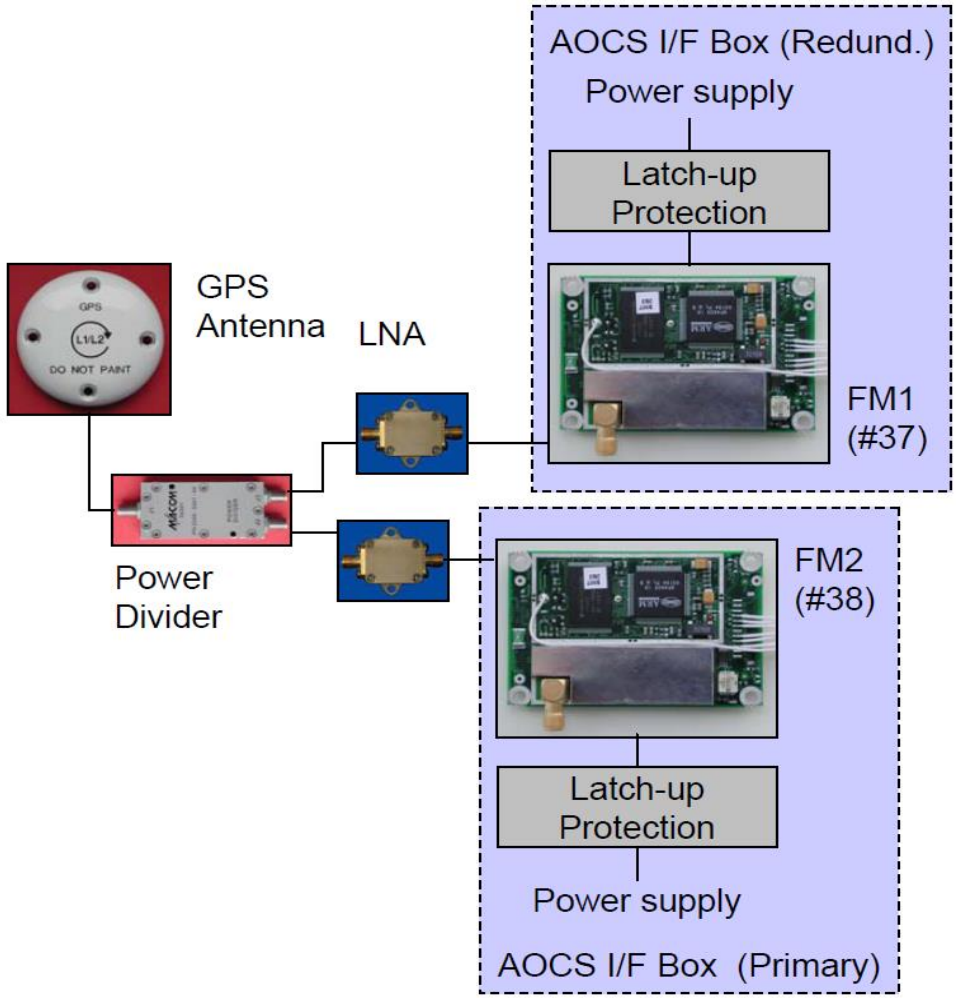
5. Proba-2 LEO Mission

Mission Outline

- Second spacecraft in ESA's **PR**oject for **O**n**B**oard **A**utonomy
- Micro-satellite platform for technology demonstration and science:
  - Scientific goals: Sun observation and study of space environment
  - Novel technology components: Sun and star sensors, two GPS receivers, propulsion and power system components, data handling system, etc…
- Built by QinetiQ Space Technology
- Launched on 2nd Nov. 2009 01:50 UTC from Plesetsk onboard Rockot
- Sun-synchronous dusk-dawn orbit at approx. 725 km altitude



GPS Sub-system Architecture

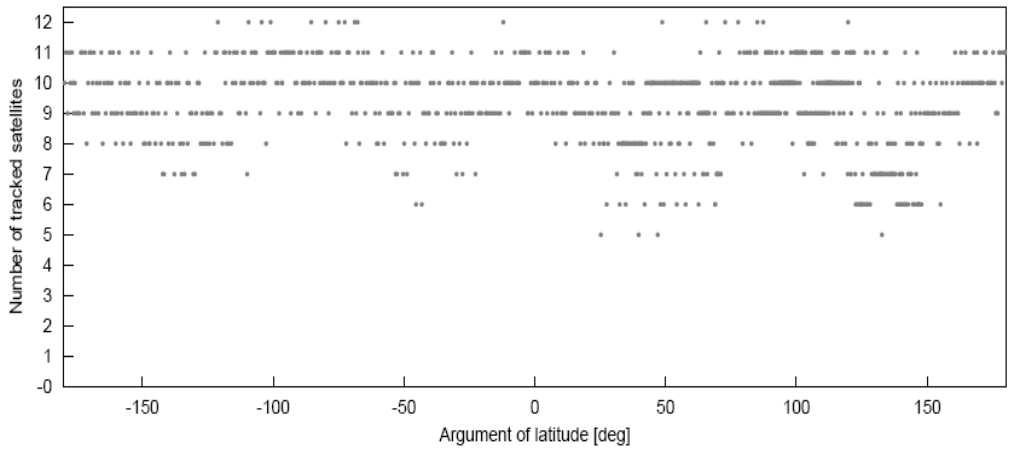


- Cold redundant GPS system
- Phoenix receivers integrated in AOCS Interface boxes
  - Power conditioning
  - Line drivers
  - Latch-up protection
- Common antenna, but independent LNAs
- Independent measurements from prototype Topstar3000G2 receiver (by Alcatel)
- Laser Retro Reflector

Flights Results

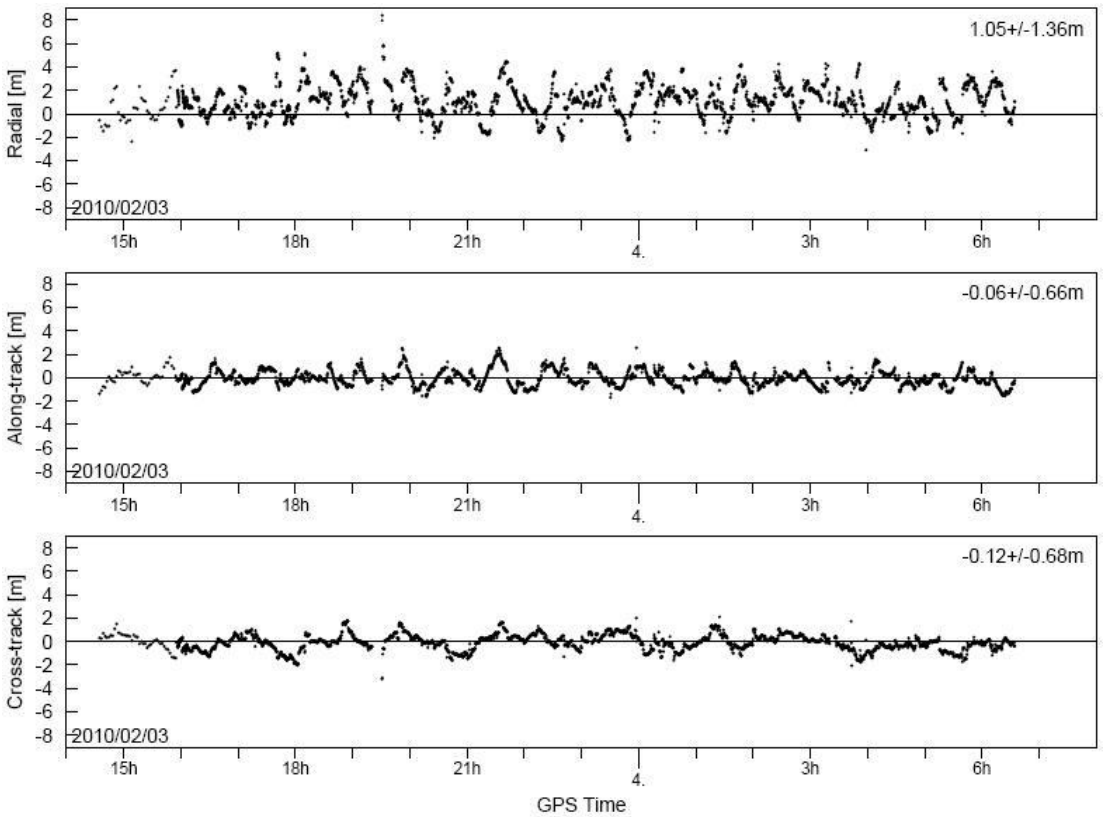
Acquisition and Tracking

- Typical Times-To-First-Fix in standard Sun pointing attitude mode :
  - Cold-start: 5..15 min
  - Assisted boot: < 2 min
- On average 9 GPS satellites tracked
- 3D rms position accuracy of ~2 m (with peak errors up to 10m)

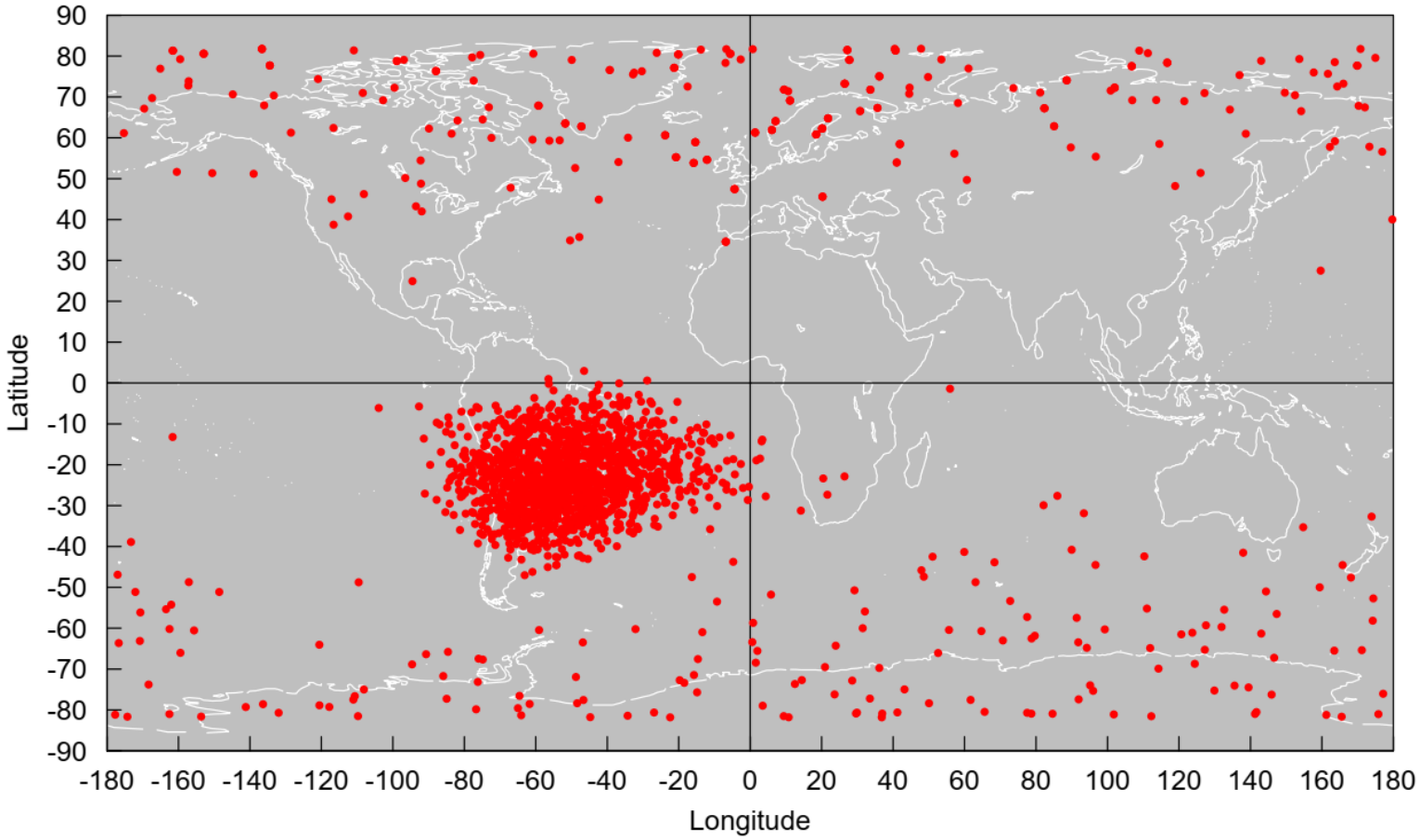


Navigation Accuracy

- 3D rms navigation accuracy of about
  - 2 m pos
  - 5 cm/s vel
- Peak errors up to 10m



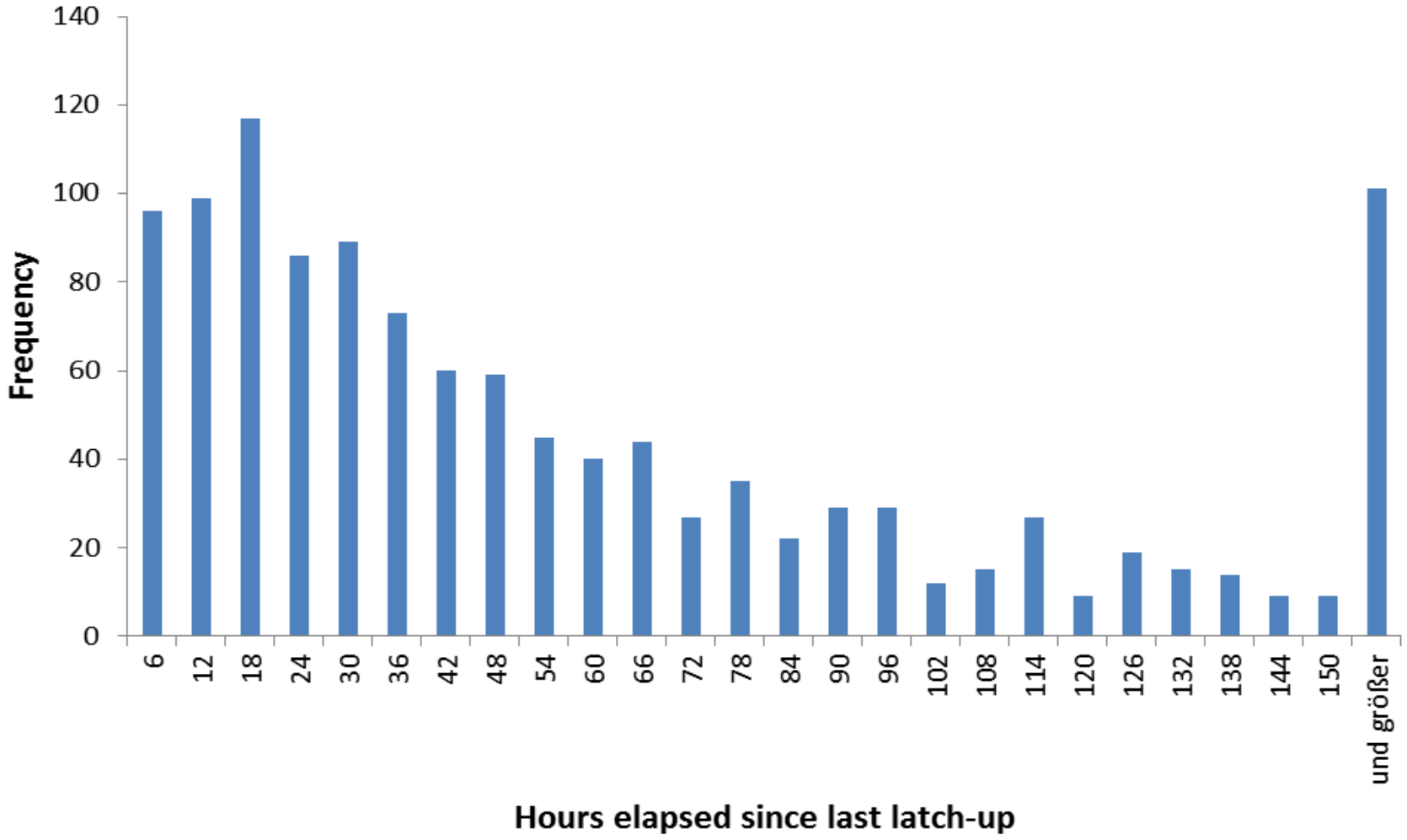
Radiation Effects



Proba-2 latch-up events 2009-2022

- Numerous SELs in almost regular intervals from beginning of operation
- In average one to two latch-up events every 48 hours
- Majority of latch-ups can be associated with the South Atlantic Anomaly
- Remaining events occurred at high latitudes in the North and South Pole region
- Also SEUs observed but less frequent
- Both receivers onboard Proba-2 still performing nominal (~13 years in orbit!!)

Radiation Effects (cont'd)



Statistical analysis of the times between two subsequent latch-up events (2009-2019).

6. Summary and Conclusions

Summary and Conclusions

- The Phoenix GPS receiver has been developed as an affordable alternative to fully space qualified GPS/GNSS receivers.
- A test and qualification program has been conducted with the receiver to ensure a proper operation in space.
- During these tests a relatively high sensitivity to space radiation has been detected (mainly SEL).
- Latch-ups were found to be entirely non-destructive.
- Receiver successfully flying in orbit onboard numerous LEO satellite (13 years aboard PROBA-2!!)

- This example demonstrates that COTS electronics can be an alternative to expensive space-qualified hardware.
- However, environmental testing is essential!
- One should not underestimate the costs and effort associated with the qualification of a COTS system for space use.