

# 3d Loop Quantum Gravity with a cosmological constant

Maité Dupuis  
Friday, June 22 2022

*In collaboration with V. Bonzom, L. Freidel, F. Girelli, E. Livine, A. Osumanu, Q. Pan and J. Rennert*

LOOPS'22

# 3d Loop Quantum Gravity with a cosmological constant

- Motivations
- The Program
- Latest results - see also Qiaoyin Pan's talk



## Motivations

- Geometrically
- From other approaches

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- Geometrically
- From other approaches

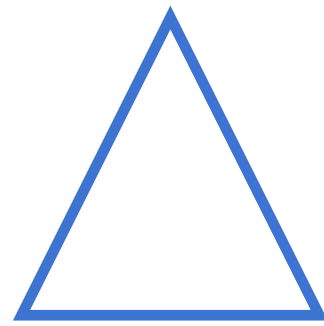
## Regge calculus with curved simplices

[B. Bahr, B. Dittrich '09]

Regge calculus when  $\Lambda \neq 0$

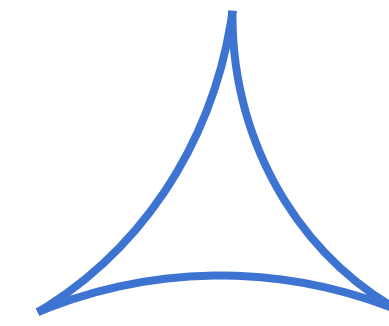
Comparison between

Flat simplices



&

Simplices with homogeneous curvature



to approximate the (homogeneously) curved space



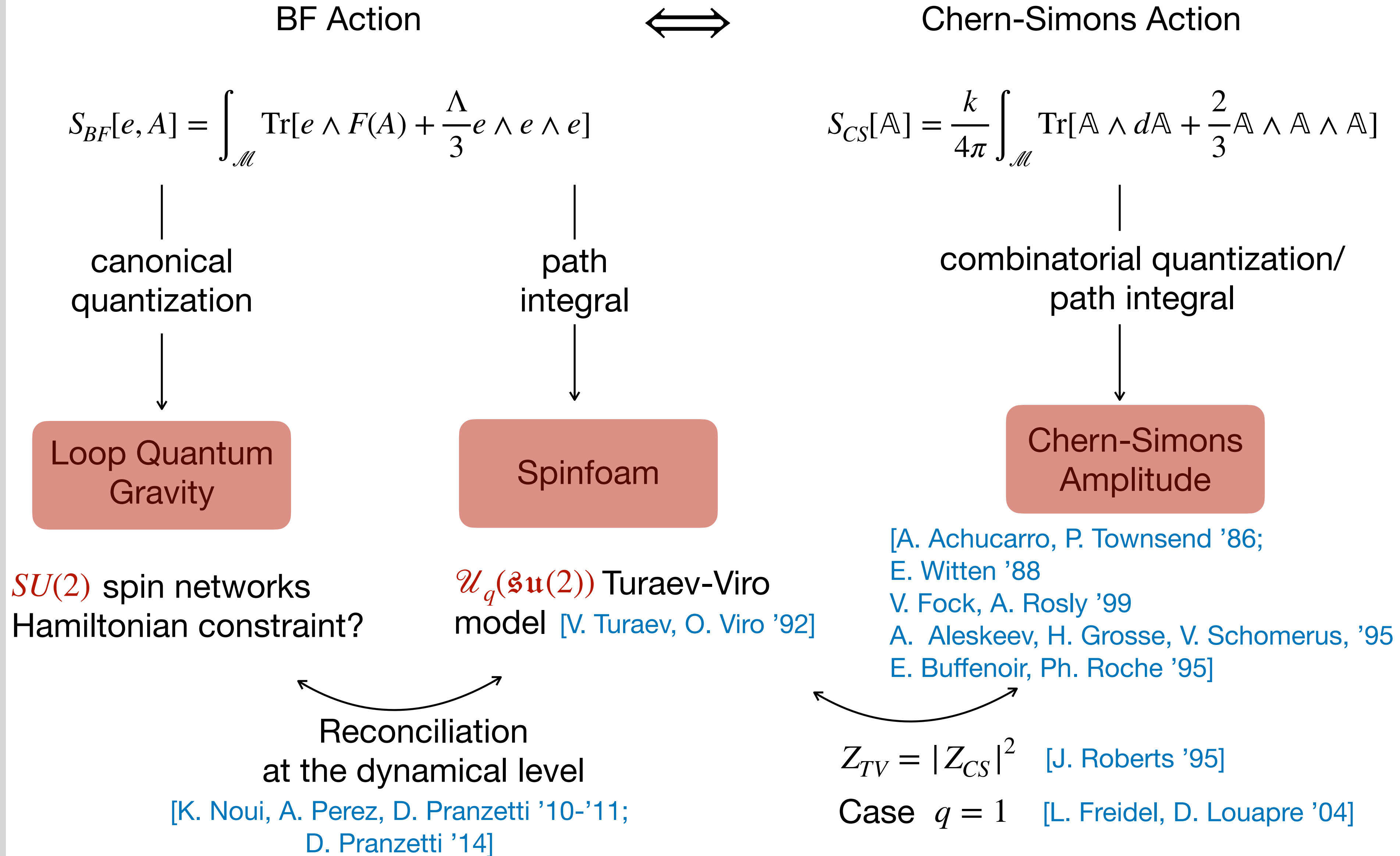
Better approximation of the continuum

(Perfect action - reflecting the dynamics and the symmetries of the continuum - can be computed)

# Motivations

- Geometrically
- From other approaches

# The cosmological constant in 3d quantum gravity



# The Program

*For Euclidean 3D gravity with a negative cosmological constant*

- Continuous theory
- Classical discrete theory
- Quantum Theory

Seminal work on LQG with a quantum group using loop variables: S. Major, L. Smolin '94.

# The Program

$$\Lambda = 0$$

- Continuous theory  $\longrightarrow$  BF theory
- Classical discrete theory
- Quantum Theory

Example: Euclidean signature,  $\Lambda = 0$

$$S_{BF}[e, A] = \int_{\mathcal{M}} \text{Tr}[e \wedge F(A)]$$

- EOM
- Torsion-free  $d_A e = 0$
  - Flatness  $F(A) = 0$

Canonical analysis

$$\mathcal{M} = \Sigma \times \mathbb{R}$$

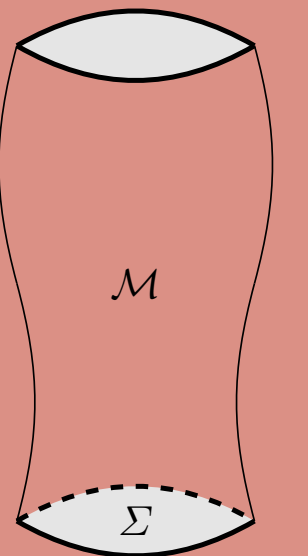
Phase space

$$\{A_a^j(x), E_k^b(y)\} = \delta_k^j \delta_a^b \delta(x, y)$$

$$E_j^a = \frac{\delta S}{\delta(\partial_0 A_a^j(x, t))} = \tilde{\epsilon}^{ab} e_{bj}$$

Constraints

Gauss constraint and Flatness constraint

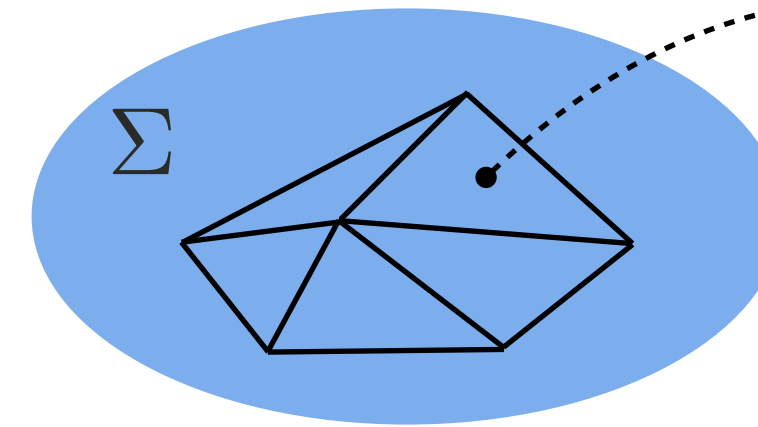


# The Program

$$\Lambda = 0$$

- Continuous theory
- Classical discrete theory
- Quantum Theory

discretization  
&  
truncation



interior of the 2-cells:

$$\mathcal{G} = \mathcal{F} = 0$$

L. Freidel, M. Geiller, J. Ziprick, '13  
MD, L.Freidel, F. Girelli, '17

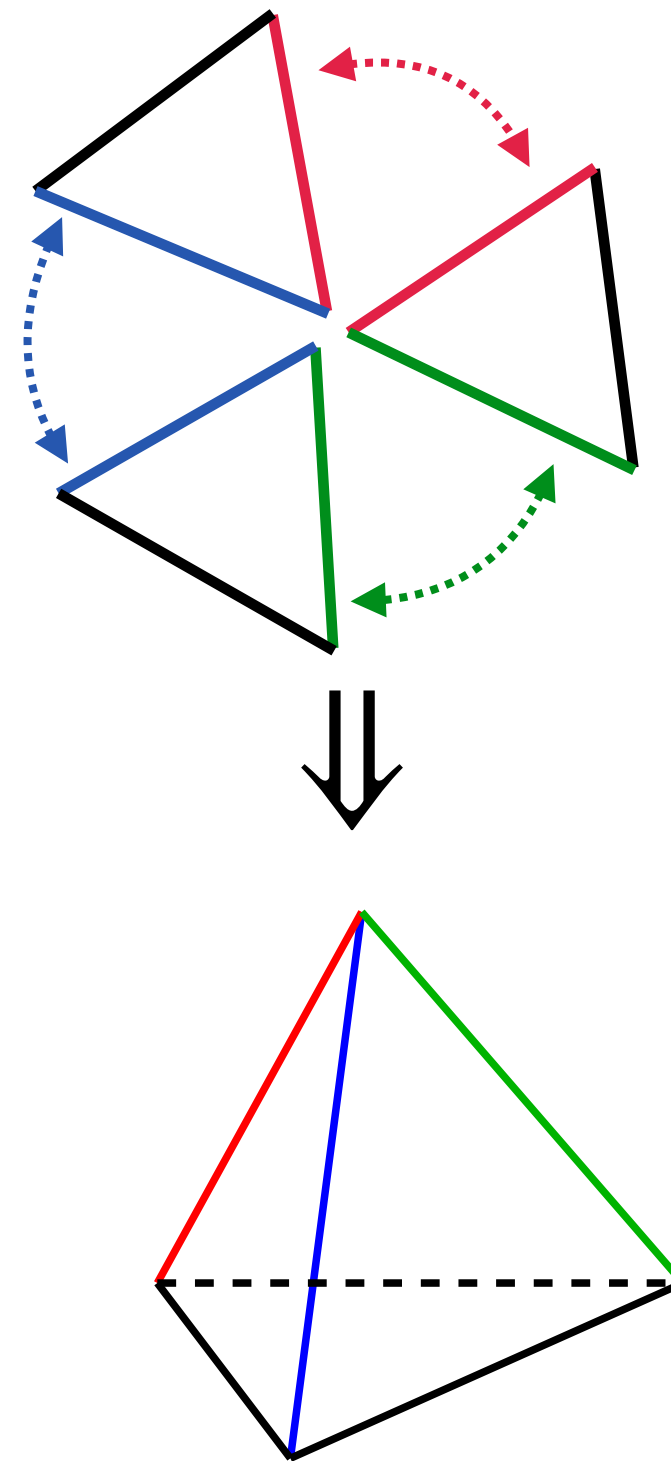


# The Program

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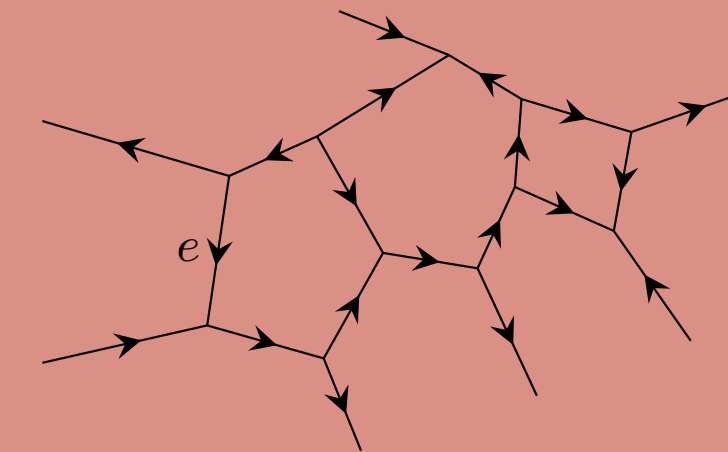
- Continuous theory
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→ Loop gravity  
Model of discrete geometries



Example: Euclidean signature,  $\Lambda = 0$

Discrete phase space  $\times_e T^*SU(2)_e$

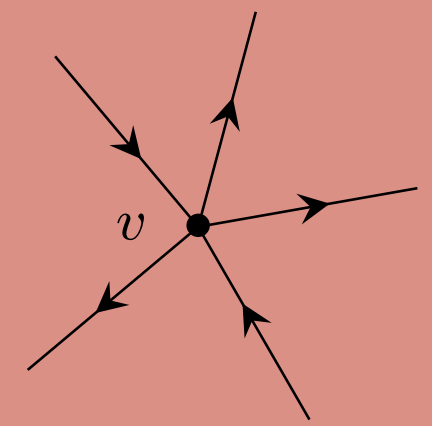


holonomy-flux variables  
 $(g_e, x_e) \in SU(2) \times \mathfrak{su}(2)$

Discrete constraints

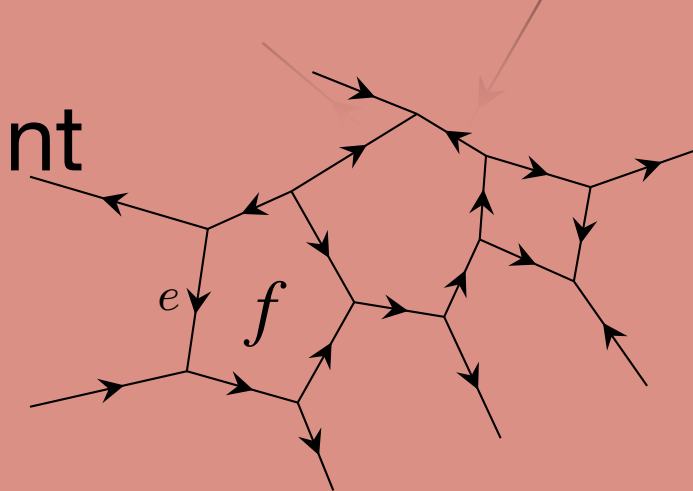
- Gauss constraint

$$\sum_{e|v=s(e)} x_e - \sum_{e|v=t(e)} \tilde{x}_e = 0$$



- Flatness constraint

$$\prod_{e \in f} g_e = \mathbb{1}$$



Model of discrete flat geometries

V. Bonzom, L. Freidel, '11

# The Program

$$\Lambda = 0$$

- Continuous theory
- Classical discrete theory
- Quantum Theory

quantization - Dirac quantization

# The Program

$$\Lambda = 0$$

- Continuous theory
- Classical discrete theory
- Quantum Theory  $\longrightarrow$  Loop Quantum gravity

Example: Euclidean signature,  $\Lambda = 0$

Kinematical Hilbert space

$$\mathcal{H}_\Gamma^{\text{kin}} := L^2(SU(2)^E, dg)$$

- Gauss constraint  $\longrightarrow \mathcal{H}_G^{\text{kin}}$

**spinnetwork states**

- The Flatness constraint  $\longrightarrow \mathcal{H}^{\text{phys}}$

Loop Quantum Gravity



Ponzano-Regge Spinfoam model

## The Program

- Continuous theory

↓ discretization  
&  
truncation

- Classical discrete theory

↓ quantization

- Quantum Theory

## BF action with a non-zero cosmological constant

[Dupuis, Freidel, Girelli, Osumanu, Rennert '20]

$$S_{BF}[e, A] = \int_{\mathcal{M}} e^I \wedge \left( F_I[A] + \frac{\Lambda}{6} \epsilon_{IJK} e^J \wedge e^K \right) \xrightarrow{\text{EOM}} \begin{cases} d_A e = 0 \\ F(A) + \frac{\Lambda}{2} [e \wedge e] = 0 \end{cases}$$

# The Program

• Continuous theory

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Change of variable

$$e^I P_I \in \mathbb{R}^3 \longrightarrow e^I \tau_I \in \mathfrak{sb}(2, \mathbb{C})$$

$$A_I J^I \longrightarrow \omega_I J^I = (A^I + (n \times e)^I) J_I \quad n^2 = -\Lambda$$

Here:  
Euclidean signature  
Negative cosmological constant

$$S[e, \omega] = \int_M e \cdot F(\omega) - \frac{1}{2} (e \times e) \cdot d_\omega n$$

EOM

$$\mathcal{T}' = d_\omega e + \frac{1}{2} [[e \wedge e], n] = 0$$

$$\mathcal{C}' = F[\omega] - [e \wedge d_\omega n] = 0$$

Phase space analysis

$$\{\omega_a^i(x), e_j^b(y)\} = \epsilon_i^j \delta_b^a \delta^2(x - y)$$

$$\{\omega_a^i(x), \omega_b^j(y)\} = \{e_i^a(x), e_j^b(y)\} = 0$$

# The Program

- Continuous theory

↓ discretization & truncation

- Classical discrete theory

↓ quantization

- Quantum Theory

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EOM

$$\mathcal{T}' = d_A \mathbf{e} + \frac{1}{2} [[\mathbf{e} \wedge \mathbf{e}], \mathbf{n}] \simeq 0$$

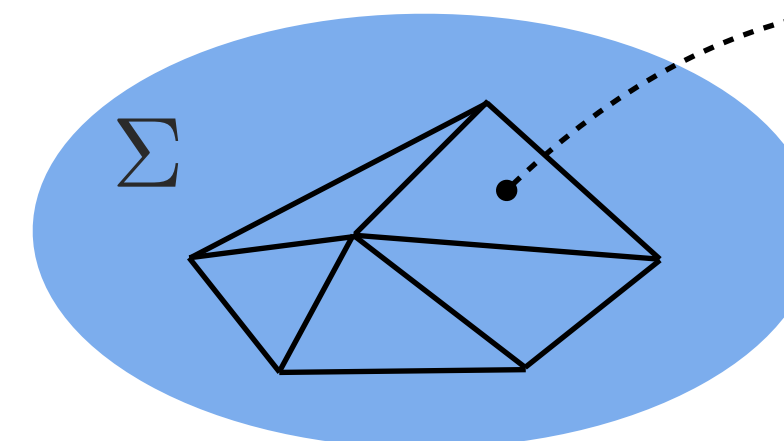
$$\mathcal{C}' = F[A] - [\mathbf{e} \wedge d_A \mathbf{n}] \simeq 0$$

Phase space analysis

$$\{A_a^i(x), \mathbf{e}_j^b(y)\} = \epsilon_i^j \delta_b^a \delta^2(x - y)$$

$$\{A_a^i(x), A_b^j(y)\} = \{\mathbf{e}_i^a(x), \mathbf{e}_j^b(y)\} = 0$$

discretization & truncation



interior of the 2-cells:  
 $\mathcal{T}' = \mathcal{C}' = 0$

**The Program**

**3D Loop Gravity phase space**

Here:  
Euclidean signature  
Negative cosmological constant

- Continuous theory
- ↓ discretization & truncation
- Classical discrete theory
- ↓ quantization
- Quantum Theory

**LQG**       $\Lambda = 0$

---

$T^*SU(2)$

$x_e \xrightarrow{g_e} \tilde{x}_e = g_e \triangleright x_e$

$(g_e, x_e) \in SU(2) \times \mathfrak{su}(2)$

$$\{x_e^a, g_e\} = \frac{i}{2} \sigma^a g_e, \{x_e^a, x_e^b\} = \epsilon^{abc} x_e^c, \{g_e, g_e\} = 0$$

$$\{x_e^a, \tilde{x}_e^b\} = 0, \{\tilde{x}_e^a, g_e\} = \frac{i}{2} g_e \sigma^a, \{\tilde{x}_e^a, \tilde{x}_e^b\} = -\epsilon^{abc} \tilde{x}_e^c$$

**LQG**       $\Lambda < 0$

---

$SL(2, \mathbb{C})$

$\ell \uparrow \xrightarrow{u} \tilde{\ell} \uparrow$

$\ell u \tilde{\ell}^{-1} \tilde{u}^{-1} = \mathbb{1}$

$\tilde{u} \leftarrow$

$(\ell, u) \in SB(2, \mathbb{C}) \times SU(2) / D = \ell u \in SL(2, \mathbb{C})$

$$\{\ell_1, \ell_2\} = -[r, \ell_1 \ell_2], \quad \{\ell_1, u_2\} = -\ell_1 r u_2,$$

$$\{u_1, \ell_2\} = \ell_2 r^t u_1, \quad \{u_1, u_2\} = -[r^t, u_1 u_2]$$

# The Program

• Continuous theory

↓  
discretization  
&  
truncation

• Classical discrete theory

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quantization

• Quantum Theory

# 3D Loop Gravity phase space

Here:  
Euclidean signature  
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 $g_e$

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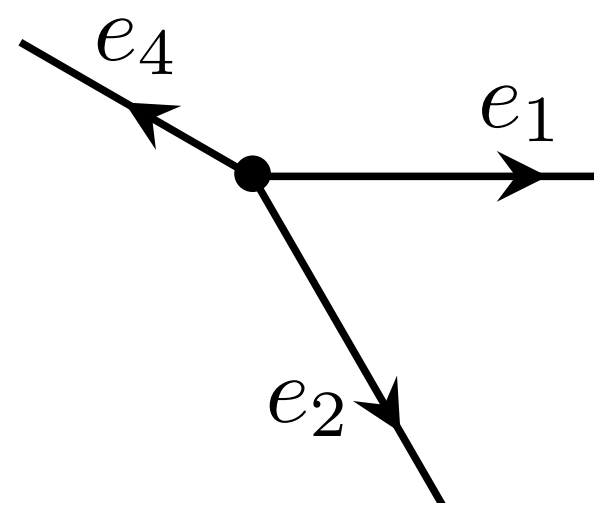
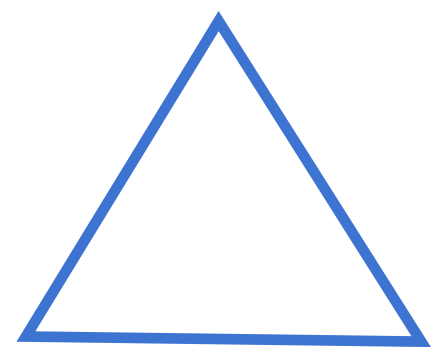
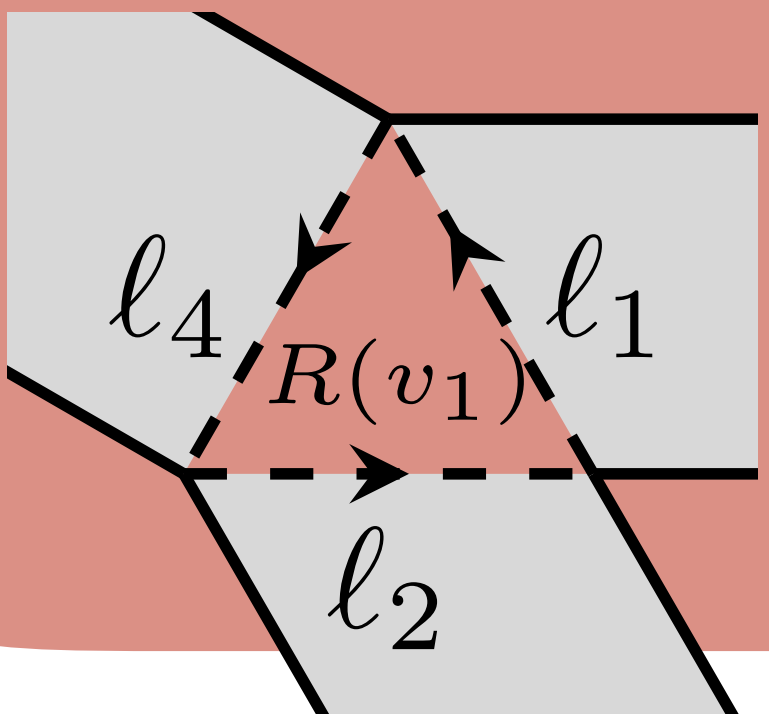
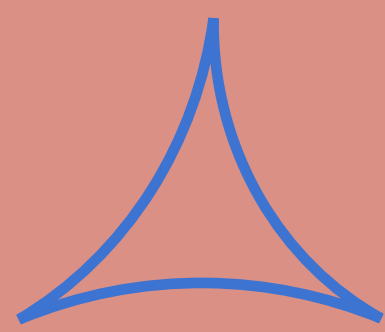
$SL(2, \mathbb{C})$

$\ell \xrightarrow{u} \tilde{\ell}$   
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**Gauss constraint**


⇔

⇔

⇔




# The Program

# 3D Loop Gravity phase space

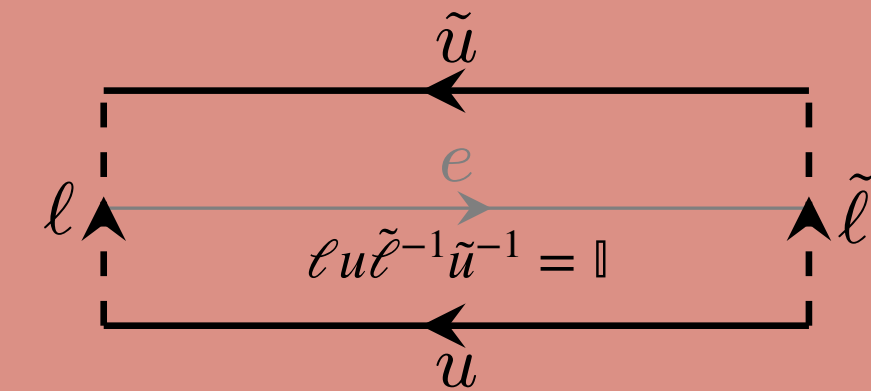
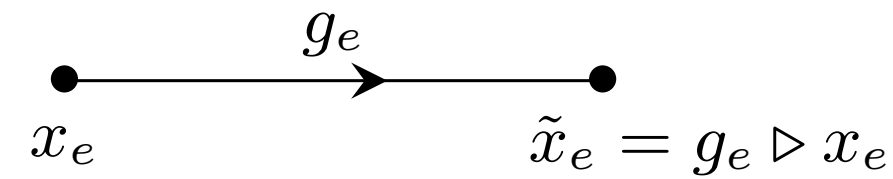
Here:  
Euclidean signature  
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**LQG**  $\Lambda = 0$

**LQG**  $\Lambda \neq 0$

$T^*SU(2)$

$SL(2, \mathbb{C})$



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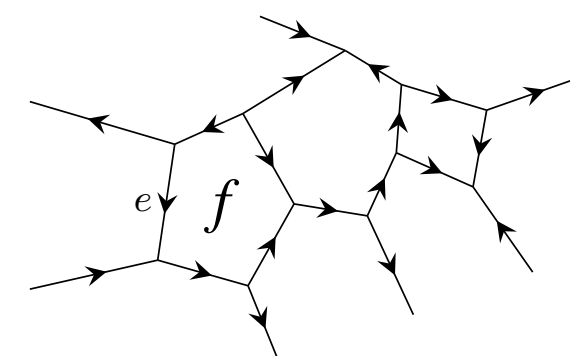
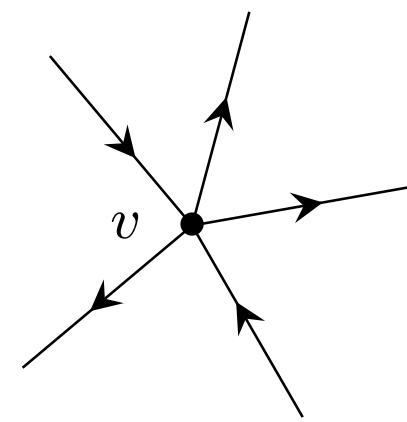
$$\{x_e^a, \tilde{x}_e^b\} = 0, \quad \{\tilde{x}_e^a, g_e\} = \frac{i}{2} g_e \sigma^a, \quad \{\tilde{x}_e^a, \tilde{x}_e^b\} = -\epsilon^{abc} \tilde{x}_e^c$$

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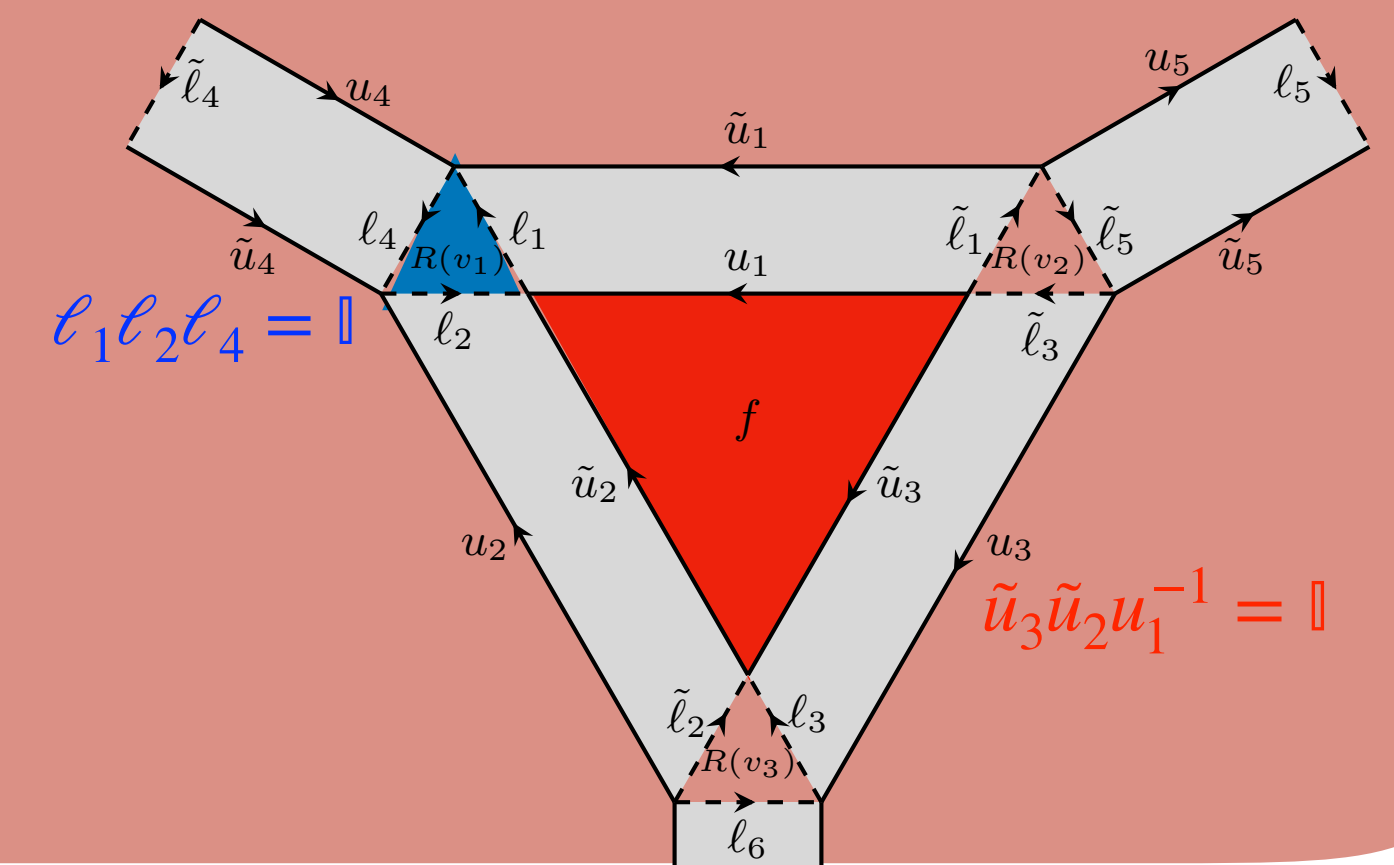
## Constraints

Gauss constraint + Flatness constraint



$$\mathcal{G}_v = \sum_{e|v=s(e)} x_e - \sum_{e|v=t(e)} \tilde{x}_e$$

$$\prod_{e \in f} g_e = \mathbb{1}$$



• Continuous theory

discretization  
&  
truncation

• Classical discrete theory

quantization

• Quantum Theory

# The Program

## Loop Gravity phase space Geometrical interpretation

- Loop Quantum Gravity  $\Lambda = 0 \xrightarrow{?}$  Loop Quantum Gravity  $\Lambda \neq 0$

Deformation parameter in the Euclidean case with  $\kappa = \frac{G\sqrt{|\Lambda|}}{c}$  :

Curvature introduced in the momentum space:

$$T^*SU(2) \sim ISU(2) = SU(2) \ltimes \mathfrak{su}(2) \longrightarrow SL(2, \mathbb{C}) = SU(2) \ltimes \mathfrak{sb}(2, \mathbb{C})$$

$\kappa$  appears in the  $\mathfrak{sb}(2, \mathbb{C})$  generators, the  $\tau$ 's

Symplectic structure defined through the r-matrix,  $r = \frac{1}{4} \sum_a \tau^a \otimes \sigma^a$

= Heisenberg Double  $(D(G) = G \ltimes G^*, \pi_H)$

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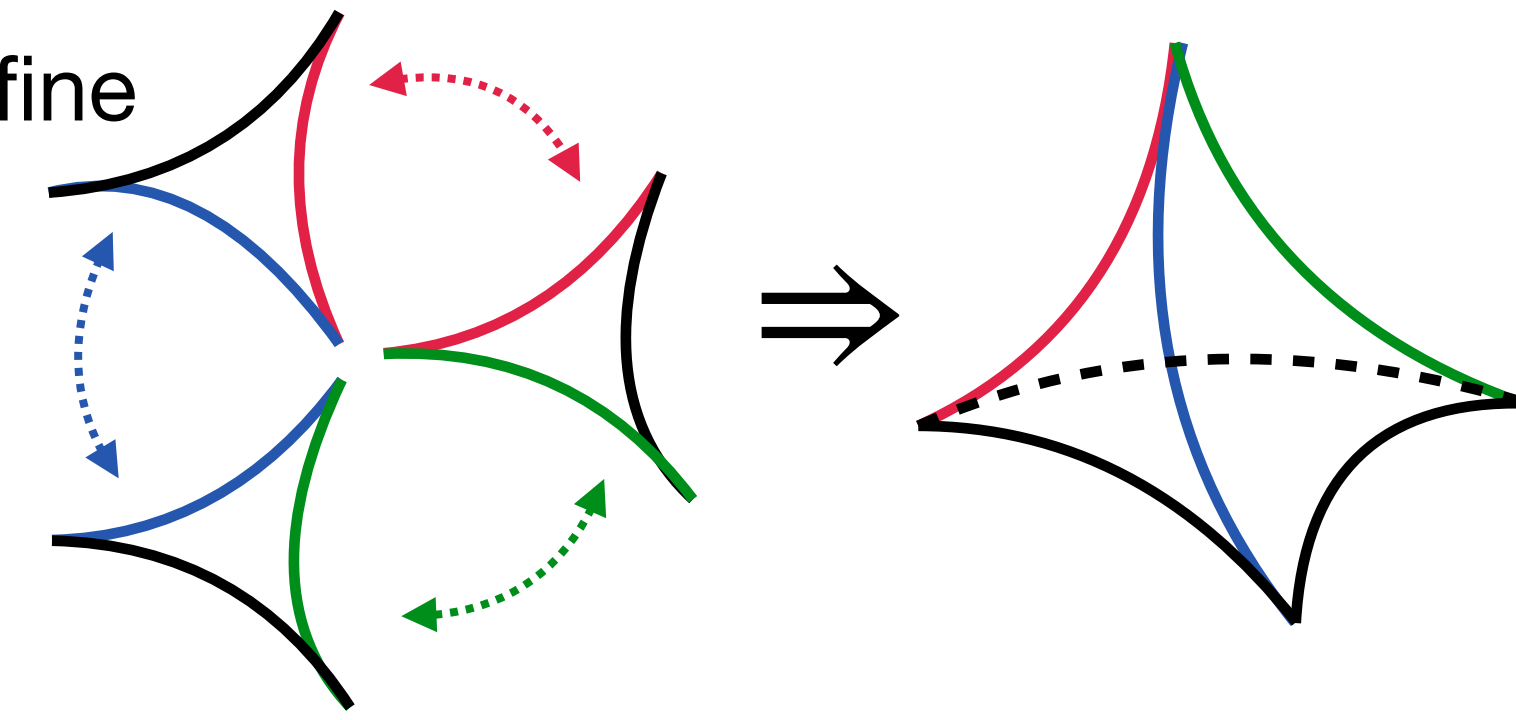
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Symplectic structure defined through the r-matrix,  $r = \frac{1}{4} \sum_a \tau^a \otimes \sigma^a$

- $\text{SL}(2, \mathbb{C}) = \text{SU}(2) \ltimes \mathfrak{SB}(2, \mathbb{C})$  with the symplectic defined through  $r = \frac{1}{4} \sum_a \tau^a \otimes \sigma^a$

and the “deformed” Gauss and flatness constraints define

*a model of discrete hyperbolic geometries.*



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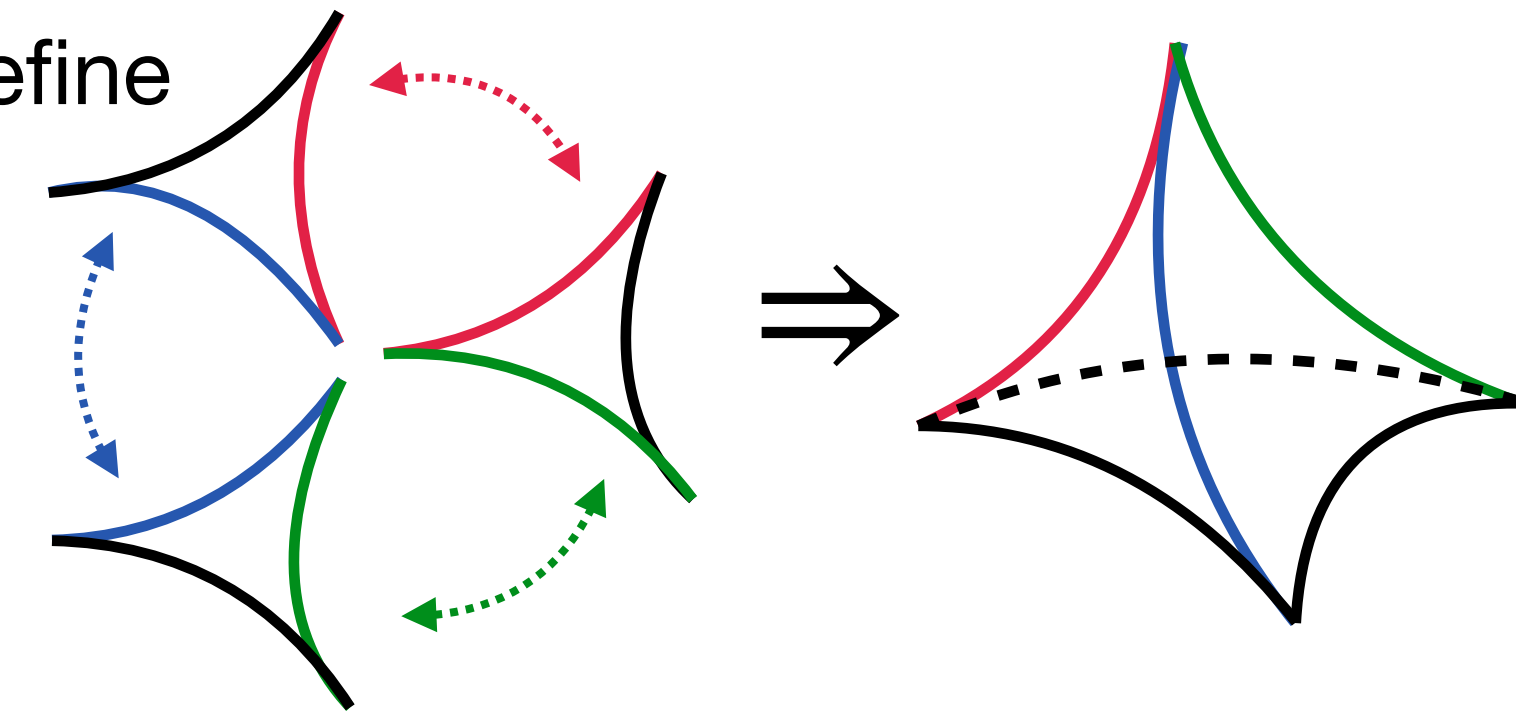
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and the “deformed” Gauss and flatness constraints define *a model of discrete hyperbolic geometries.*



- $\kappa \rightarrow 0, \Lambda = 0$  Loop Quantum Gravity is recovered.

• Continuous theory

discretization  
&  
truncation

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# The Program

- Continuous theory

↓  
discretization  
&  
truncation

- Classical discrete theory

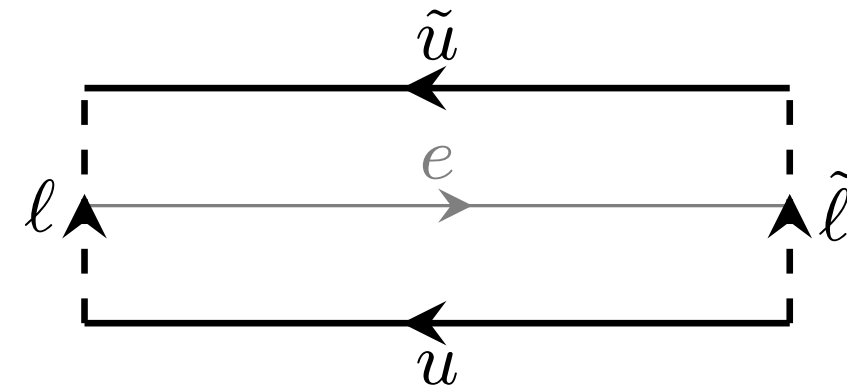
↓  
quantization

- Quantum Theory

# Quantization LQG $\Lambda \neq 0$

Bonzom, MD, Girelli, Pan, '22

Phase space



$$(\ell, u) \in \text{SB}(2, \mathbb{C}) \times \text{SU}(2) / D = \ell u \in \text{SL}(2, \mathbb{C})$$

$$\{\ell_1, \ell_2\} = -[r, \ell_1 \ell_2], \quad \{\ell_1, u_2\} = -\ell_1 r u_2,$$

$$\{u_1, \ell_2\} = \ell_2 r^t u_1, \quad \{u_1, u_2\} = -[r^t, u_1 u_2]$$

## Quantization

r-matrix

$$r \longrightarrow \mathcal{R}$$

$$R = \begin{pmatrix} q^{\frac{1}{4}} & 0 & 0 & 0 \\ 0 & q^{-\frac{1}{4}} & q^{-\frac{1}{4}}(q^{\frac{1}{2}} - q^{-\frac{1}{2}}) & 0 \\ 0 & 0 & q^{-\frac{1}{4}} & 0 \\ 0 & 0 & 0 & q^{\frac{1}{4}} \end{pmatrix} \approx \mathbf{1} \otimes \mathbf{1} + i\hbar r + O(\hbar^2)$$

**Poisson brackets** given by the  $r$ -matrix  $\rightarrow$  **commutators** given by the  $\mathcal{R}$ -matrix

$$[\hat{A}, \hat{B}] = i\hbar \widehat{\{A, B\}}$$

# The Program

- Continuous theory

↓ discretization  
& truncation

- Classical discrete theory

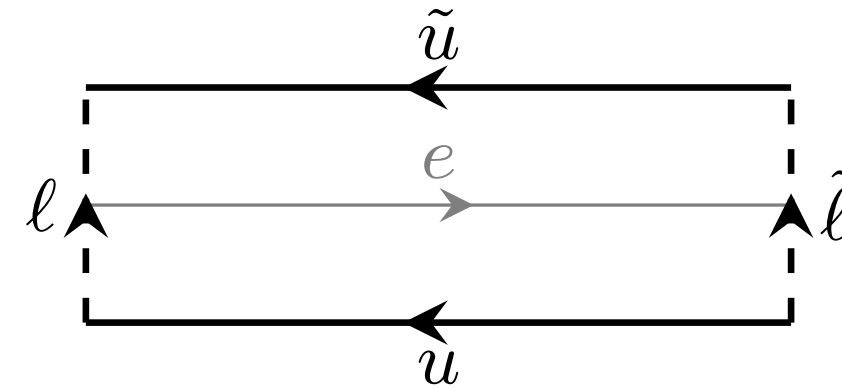
↓ quantization

- Quantum Theory

# Quantization LQG $\Lambda \neq 0$

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## Quantization

- r-matrix

$$r \longrightarrow \mathcal{R}$$

$$R = \begin{pmatrix} q^{\frac{1}{4}} & 0 & 0 & 0 \\ 0 & q^{-\frac{1}{4}} & q^{-\frac{1}{4}}(q^{\frac{1}{2}} - q^{-\frac{1}{2}}) & 0 \\ 0 & 0 & q^{-\frac{1}{4}} & 0 \\ 0 & 0 & 0 & q^{\frac{1}{4}} \end{pmatrix} \approx \mathbf{1} \otimes \mathbf{1} + i\hbar r + O(\hbar^2)$$

- Phase space variables  $D = \ell u = \tilde{u} \tilde{\ell} \in SL(2, \mathbb{C})$

## Quantization

$$\tilde{\ell} \in SB(2, \mathbb{C}) \longrightarrow \tilde{L} \in Fun_q(SB(2, \mathbb{C})) \cong \mathfrak{U}_q(\mathfrak{su}(2))$$

$$\tilde{u} \in SU(2) \longrightarrow \tilde{U} \in SU_q(2)$$

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## Quantum Groups

Hopf algebra  $\mathcal{U}_q(\mathfrak{su}(2))$

• Generators  $\mathbb{1}, J_{\pm}, K = q^{\frac{J_z}{2}}$

• Commutation relations

$$KJ_{\pm}K^{-1} = q^{\pm 1/2}J_{\pm}, \quad [J_+, J_-] = [2J_z], \quad \text{with } [n] \equiv \frac{q^{\frac{n}{2}} - q^{-\frac{n}{2}}}{q^{\frac{1}{2}} - q^{-\frac{1}{2}}}$$

• Hopf algebra with coproduct, antipode and counit

$$\Delta(J_{\pm}) := J_{\pm} \otimes K + K^{-1} \otimes J_{\pm}, \quad \Delta(K) := K \otimes K, \quad S(J_{\pm}) := -q^{\pm 1/2}J_{\pm}, \quad S(K) := K^{-1}, \quad \epsilon K = 1, \quad \epsilon J_{\pm} = 0$$

• Quasitriangular Hopf algebra with R-matrix

$$\mathcal{R} = q^{J_z \otimes J_z} \sum_{n=0}^{\infty} \frac{(1 - q^{-1})^n}{[n]!} q^{\frac{n(n-1)}{4}} \left( q^{\frac{J_z}{2}} J_+ \right)^n \otimes \left( q^{-\frac{J_z}{2}} J_- \right)^n$$

satisfying the quantum Yang-Baxter equation

$$\mathcal{R}_{12}\mathcal{R}_{13}\mathcal{R}_{23} = \mathcal{R}_{23}\mathcal{R}_{13}\mathcal{R}_{12}$$

Hopf algebra  $SU_q(2)$

$$T = \begin{pmatrix} \hat{a} & \hat{b} \\ \hat{c} & \hat{d} \end{pmatrix}$$

$$\text{with } \det_q T := \hat{a}\hat{b} - q^{-\frac{1}{2}}\hat{c}\hat{d} = \mathbb{1}$$

• Commutation relations

$$\begin{aligned} \hat{a}\hat{b} &= q^{-\frac{1}{2}}\hat{b}\hat{a}, & \hat{a}\hat{c} &= q^{-\frac{1}{2}}\hat{c}\hat{a}, & \hat{b}\hat{d} &= q^{-\frac{1}{2}}\hat{d}\hat{b}, \\ \hat{c}\hat{d} &= q^{-\frac{1}{2}}\hat{d}\hat{c}, & \hat{b}\hat{c} &= \hat{c}\hat{b}, & [\hat{a}, \hat{d}] &= -(q^{\frac{1}{2}} - q^{-\frac{1}{2}})\hat{b}\hat{c} \end{aligned}$$

# The Program

## q-deformed LQG

$$\Lambda \neq 0$$

Bonzom, MD, Girelli, Pan, '22

Variables

$$\ell \in SB(2, \mathbb{C}) \longrightarrow L \in Fun_{q^{-1}}(SB(2, \mathbb{C})) \cong \mathfrak{U}_{q^{-1}}(\mathfrak{su}(2))$$

$$u \in SU(2) \longrightarrow U \in SU_{q^{-1}}(2)$$

$$\tilde{\ell} \in SB(2, \mathbb{C}) \longrightarrow \tilde{L} \in Fun_q(SB(2, \mathbb{C})) \cong \mathfrak{U}_q(\mathfrak{su}(2))$$

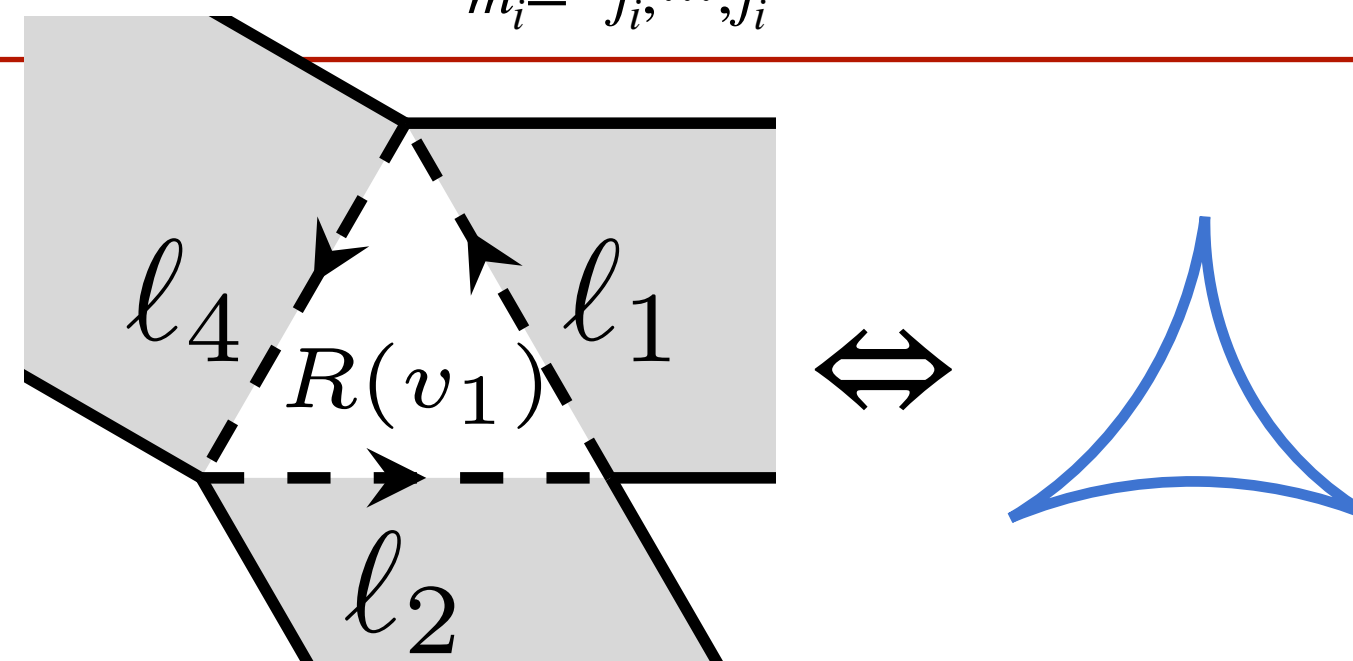
$$\tilde{u} \in SU(2) \longrightarrow \tilde{U} \in SU_q(2)$$

Gauss law at "vertex"  $v$

$$\tilde{\ell}_{e_{nv}} \cdots \tilde{\ell}_{e_{1v}} = \mathbb{1} \longrightarrow \tilde{L}_{e_{nv}} \cdots \tilde{L}_{e_{1v}}$$

$$\Delta \tilde{\ell}_{ij} = \sum_k \tilde{\ell}_{kj} \otimes \tilde{\ell}_{ik} \longrightarrow \Delta \tilde{L} = \begin{pmatrix} \tilde{K} \otimes \tilde{K} & 0 \\ \alpha(q)(\tilde{J}_+ \otimes \tilde{K} + \tilde{K}^{-1} \otimes \tilde{J}_+) & \tilde{K}^{-1} \otimes \tilde{K}^{-1} \end{pmatrix}$$

$$\tilde{L}_3 \tilde{L}_2 \tilde{L}_1 i_{j_1 j_2 j_3} = i_{j_1 j_2 j_3} \Rightarrow i_{j_1 j_2 j_3} = \sum_{m_i = -j_i, \dots, j_i} (-1)^{j_3 - m_3} q^{-\frac{m_3}{2}} C_{m_1 m_2 - m_3}^{j_1 j_2 j_3} |j_1, m_1\rangle \otimes |j_2, m_2\rangle \otimes |j_3, m_3\rangle$$



• Continuous theory

discretization  
&  
truncation

• Classical discrete theory

quantization

• Quantum Theory



# The Program

- Continuous theory

↓  
discretization  
&  
truncation

- Classical discrete theory

↓  
quantization

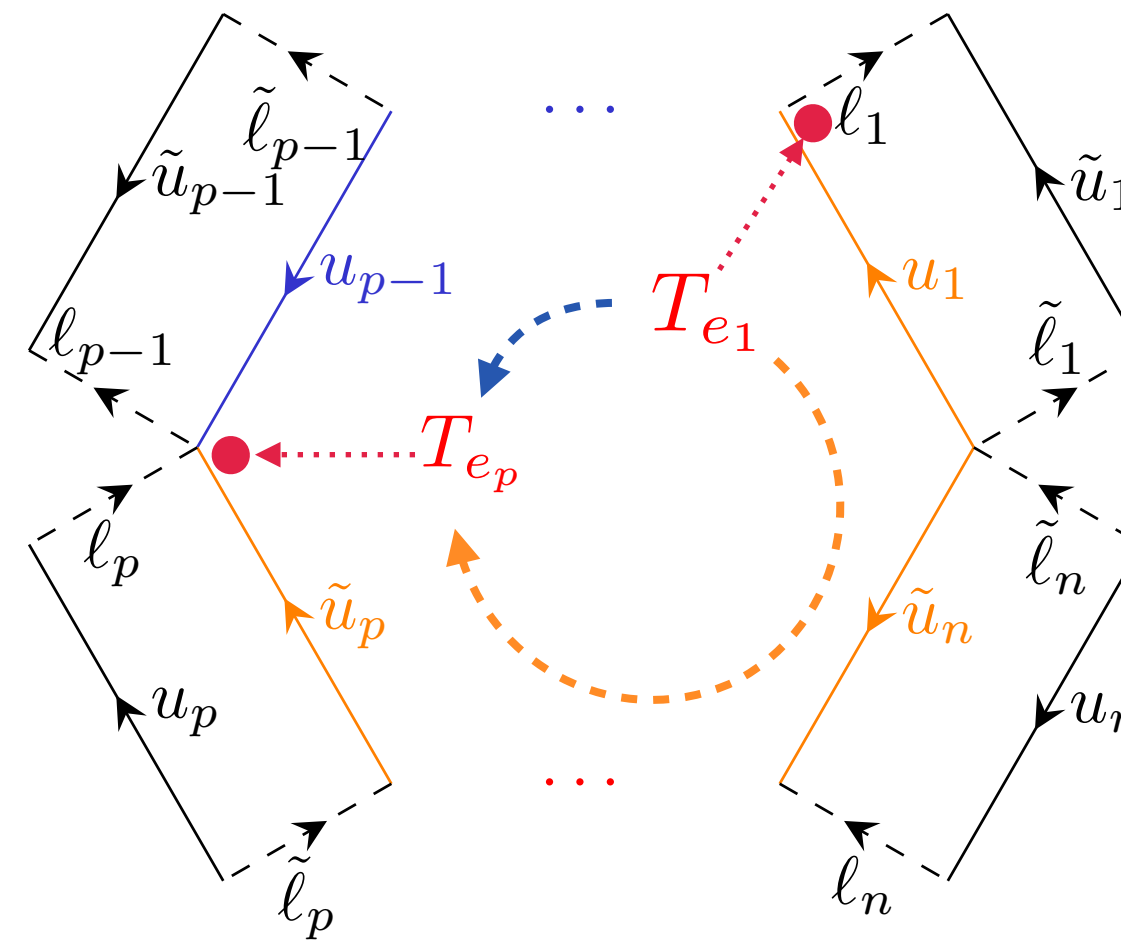
- Quantum Theory

# q-deformed LQG

$\Lambda \neq 0$

Bonzom, MD, Pan, '21

(Classical) Flatness constraint  $\mathcal{F}_f = \overrightarrow{\prod}_{e \in f} u_e^{o_e} = \begin{cases} u_e & \text{if } o_e = + \\ \tilde{u}_e^{-1} & \text{if } o_e = - \end{cases}$



# The Program

• Continuous theory

↓  
discretization  
&  
truncation

• Classical discrete theory

↓  
quantization

• Quantum Theory

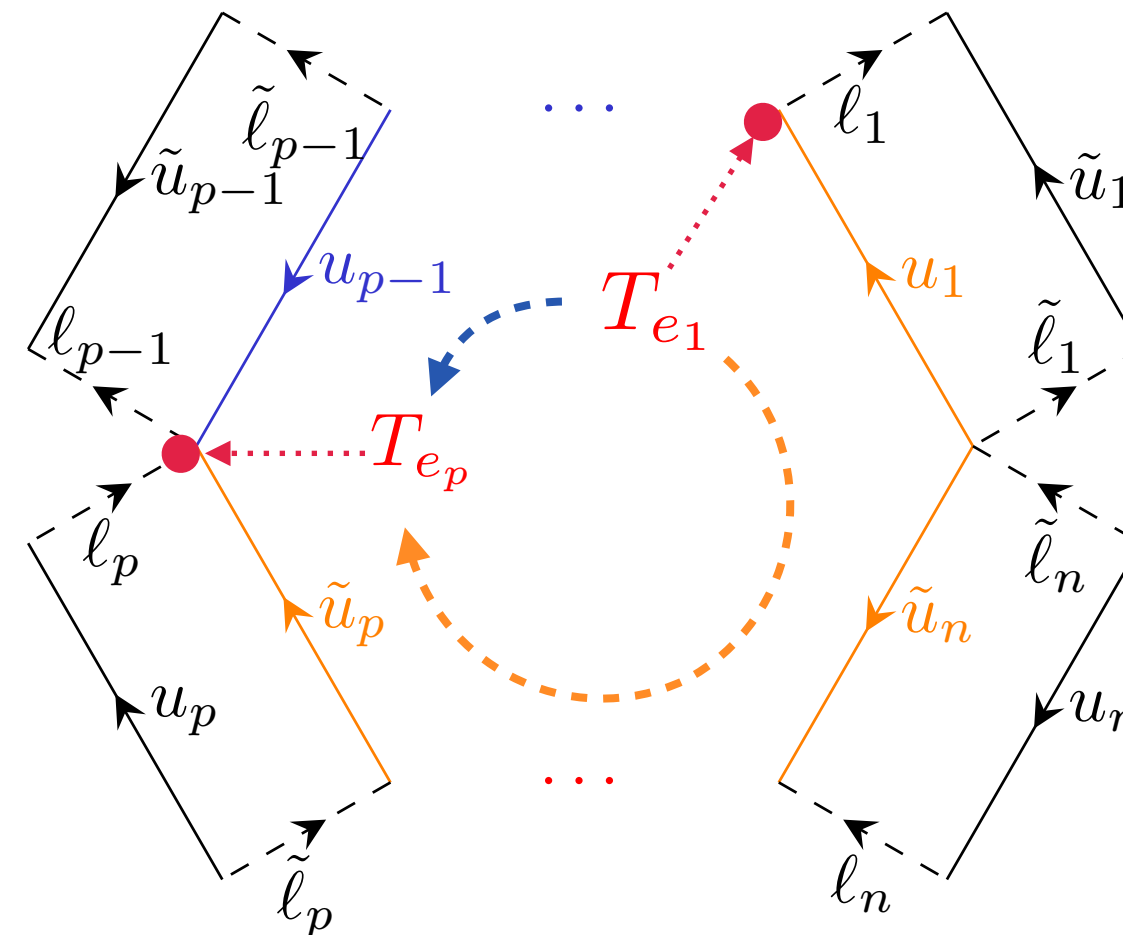
## q-deformed LQG

$$\Lambda \neq 0$$

Bonzom, MD, Pan, '21

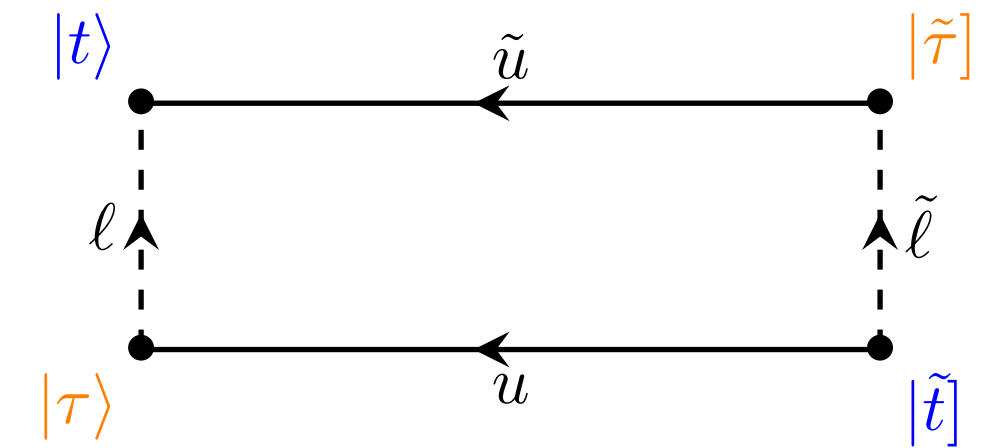
(Classical) Flatness constraint

$$\mathcal{F}_f = \prod_{e \in f} \vec{u}_e^{o_e} = \begin{cases} u_e & \text{if } o_e = + \\ \tilde{u}_e^{-1} & \text{if } o_e = - \end{cases}$$



 [Qiaoyin's talk]

Spinorial formalism  
for q-deformed loop gravity



Invariant Scalars

$$E_{e_1 \rightarrow e_p} = \sum_{A,B} T_{e_p, -A} \left( u_{e_{p-1}}^{o_{p-1}} \cdots u_{e_2}^{o_2} \right)_{AB} T_{e_1, B} = \sum_{A,B} T_{e_p, -A} \left( u_{e_1}^{o_1} \cdots u_{e_p}^{o_p} \right)_{AB}^{-1} T_{e_1, B}$$

Hamiltonian

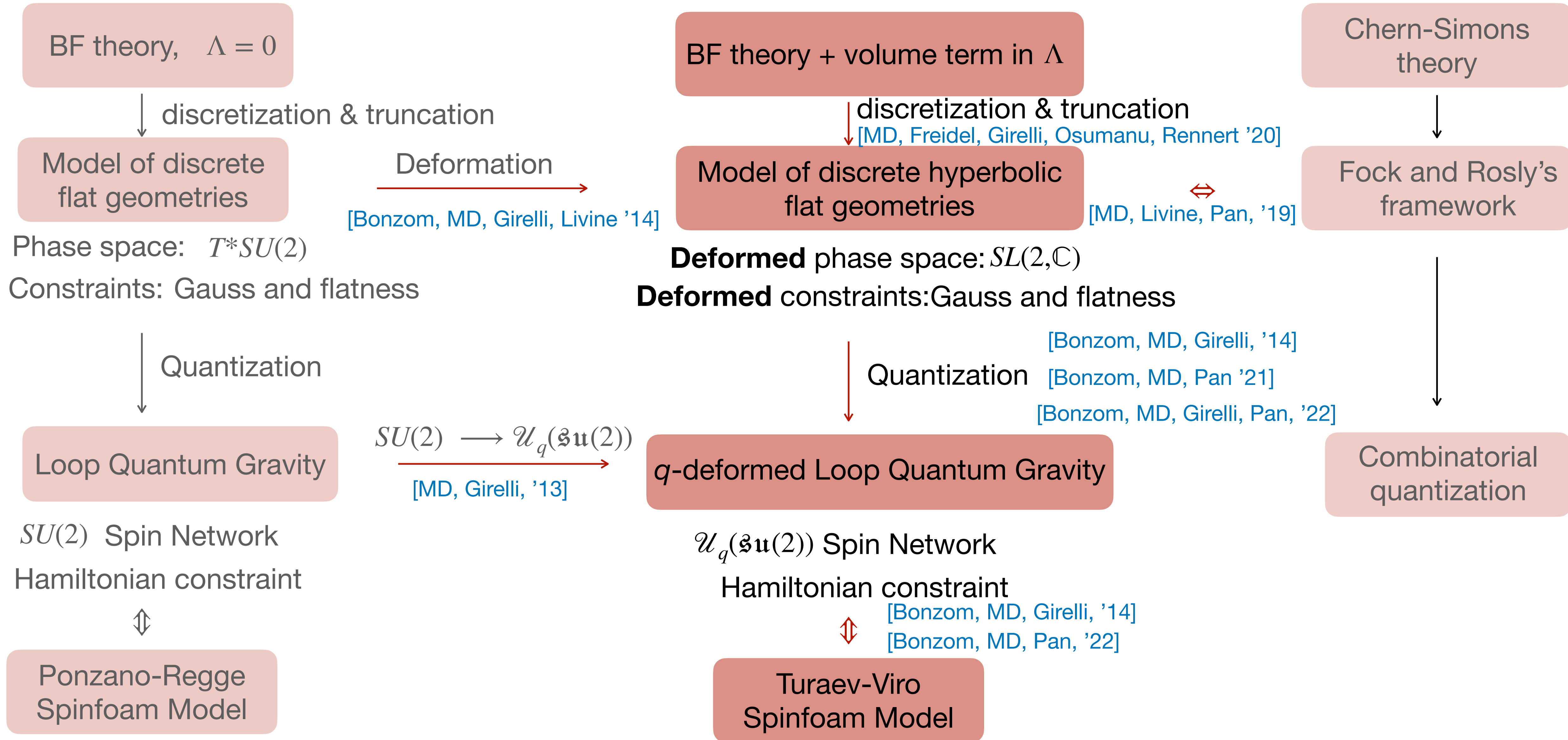
for face  $f$   
and edges

$$h_{f, e_1, e_p}^{\epsilon_1, \epsilon_p} = \sum_{\epsilon_2, \dots, \epsilon_{p-1} = \pm} \prod_{i=2}^p \frac{o_i \epsilon_i}{N_{e_i}} E_{e_i e_{i-1}}^{\epsilon_i, \epsilon_{i-1}} - (-1)^{d-p} o_1 o_p \epsilon_1 \epsilon_p \frac{N_{e_1}}{N_{e_p}} \sum_{\epsilon_{p+1}, \dots, \epsilon_d = \pm} \prod_{i=p+1}^{d+1} \frac{o_i \epsilon_i}{N_{e_i}} E_{e_i e_{i-1}}^{-\epsilon_i, -\epsilon_{i-1}}$$

→ Quantum version: **quantum deformed Hamiltonian**  
invariant under Pachner moves and related with the Turaev-Viro model

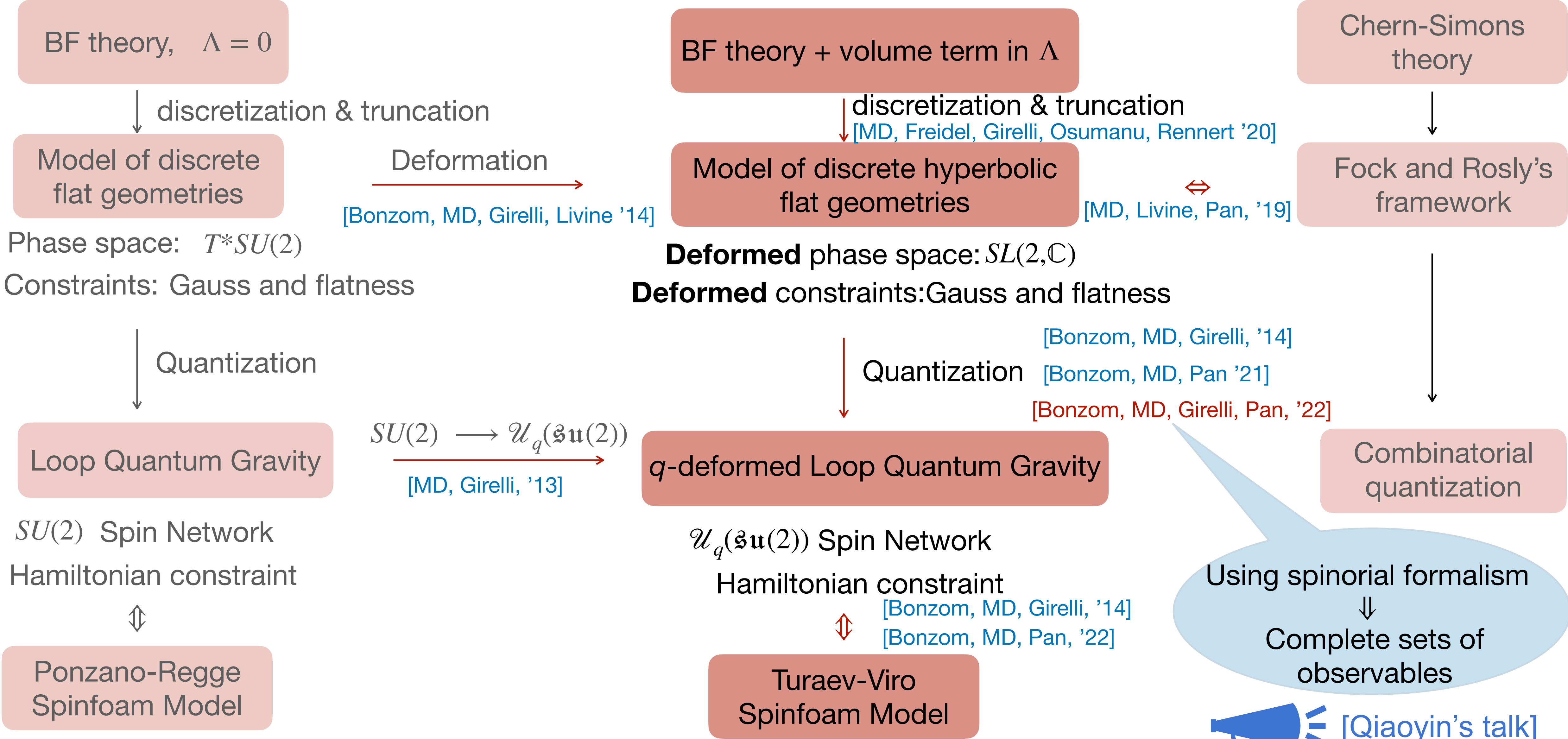
# q-deformed Loop Quantum Gravity

A quantum theory for 3d Euclidean gravity with a negative cosmological constant



# q-deformed Loop Quantum Gravity

A quantum theory for 3d Euclidean gravity with a negative cosmological constant



## Some open questions

- Other cases of signatures, sign of cosmological constant
- Framework to study the BTZ black hole?
- What can we learn for the 4d case?
- Use of geometrical technics in other approaches?

Thank you!

Thank to Qiaoyin for the nice pictures!

Next:  [Qiaoyin's talk]