

Pushing the Loop Frontier in non-planar $\mathcal{N} = 4$ sYM

Alex Edison

6 Loops with JJ Carrasco & H. Johansson: 2112.05178

6 Points with S. He, H. Johansson, O. Schlotterer, F. Teng, Y. Zhang: 22xx.xxxxx



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Part 1: Non-Planar Six Loop Integrand

Motivations

Goal of program: UV behavior of 7 loop $\mathcal{N} = 8$ SUGRA

Why?

- SUSY arguments predict $L = 7$ counterterm in $D_C = 4$ (Bossard, Howe, Stelle; Green, Russo, Vanhove; Beisert, Elvang, Freedman, Kiermaier, Morales, Stieberger; many more)
- Similar counterterms proven absent for $\mathcal{N} = 4, 5$ at $L = \mathcal{N} - 1$ (Bossard, Howe, Stelle, Vanhove; Bern, Davies, Dennen; Bern, Davies, Dennen, Huang)
- Improved behavior observed in $D = 4$ kinematics (AE, Hermann, Parra-Martinez, Trnka)

History of direct calculations:

- 1&2 loops '80 - '90s (Green, Schwarz, Brink; Bern, Dixon, Dunbar, Perelstein, Rozowsky)
- 3 loops '07-'10 (Bern, Carrasco, Dixon, Johansson, Kosower, Roiban)
- 4 loops '09-'12 (Bern, Carrasco, Dixon, Johansson, Roiban)
- 5 loops 2018 (Bern, Carrasco, Chen, AE, Johansson, Parra-Martinez, Roiban, Zeng)

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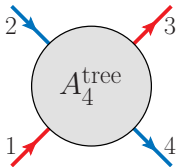
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X Identity

Four-point ordered YM tree amplitudes only have s and t channel poles.

What if we try to “sit on the u pole” anyway, via $p_3 \rightarrow p_1, p_4 \rightarrow p_2$?



e.g.:

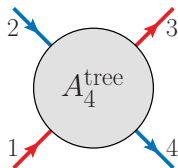
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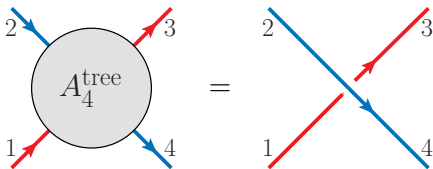
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Dimensionless, must respect all symmetries: Can only get identity insertions! The diagram disconnects!



e.g.:

$$A_4^{\text{tree, YM}} = \frac{t_8 F^4}{s t} \xrightarrow{p_3=p_1} (\epsilon_1 \cdot \epsilon_3)(\epsilon_2 \cdot \epsilon_4)$$

Same for all other supersymmetric states

H Identity

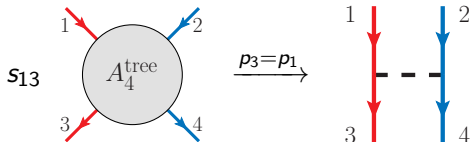
Can we find a similar identity that maintains planarity?

- Consider $s_{13}A(1, 3, 2, 4)|_{p_3=p_1}$: cut with zero momentum exchange
- Apply $s_{13}A(1, 3, 2, 4) = -s_{12}A(1, 2, 3, 4)$
- Use X ID on RHS: $s_{12}A(1, 2, 3, 4) \rightarrow -s_{14}A(1, 3)A(2, 4)$

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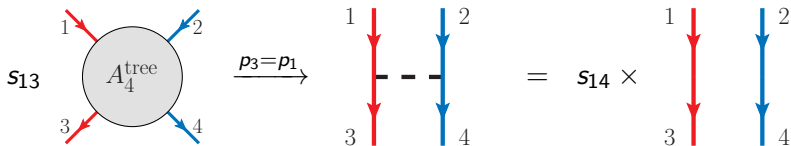
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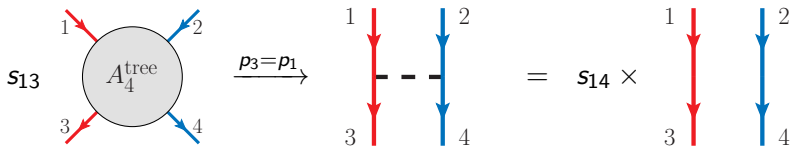
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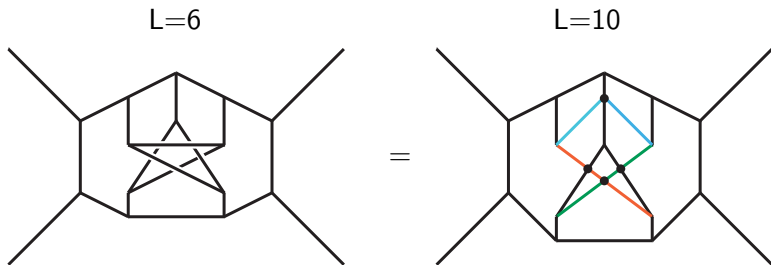


$$\text{e.g.: } s_{13}A(1, 3, 2, 4) = \frac{t_8 F^4}{s_{23}} \xrightarrow{p_3=p_1} s_{14}(\epsilon_1 \cdot \epsilon_3)(\epsilon_2 \cdot \epsilon_4)$$

Same for all other supersymmetric states. Extends to (super)gravity.
 N.B.: Physical identity (soft factorization), not heuristic rule.

Applications of X ID in MMC

X Identity: Evaluate $\mathcal{C}_{\gamma(k)}$ *directly* from limit of **higher-loop** cut



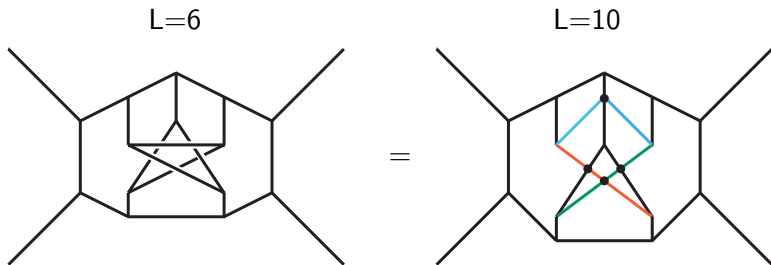
Challenges:

- 1 Edge crossing is NP-Hard¹
- 2 Quickly outpace known planar cuts ($L \geq 11$ loops)
- 3 Only works for color-ordered cuts

¹ex: There're better crossing schemes than in the diagram. Can you find one?

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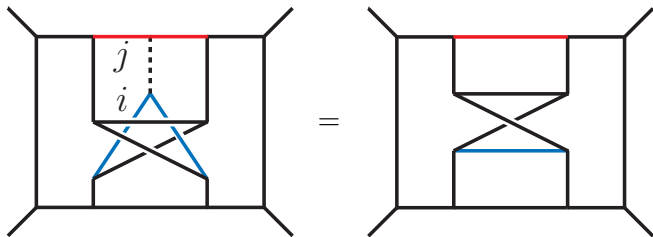
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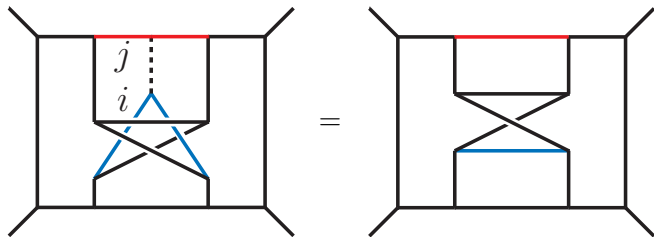
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- ① Need to merge conditions
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$\lim_{\ell_m \rightarrow 0}$ realized as projection on invariants: π_{ℓ_m}

Know that

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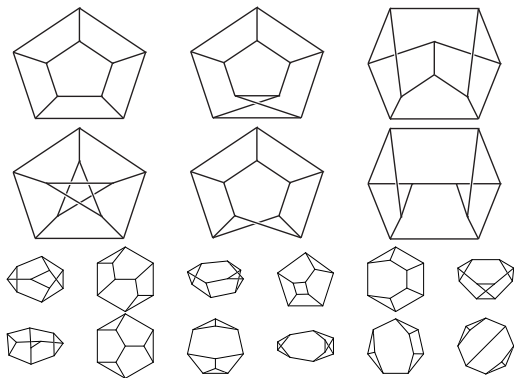
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(Almost) always find that lowest degree generator of $\mathcal{I}_{\gamma^{(k)}}$ is **unique** and **the correct degree** to be \mathcal{P} . Significantly faster than solving ansatz.

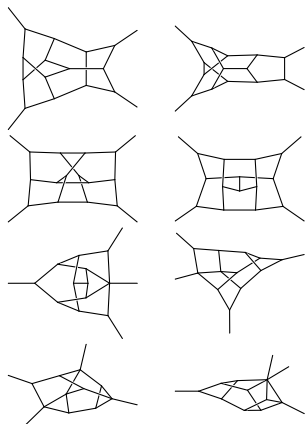
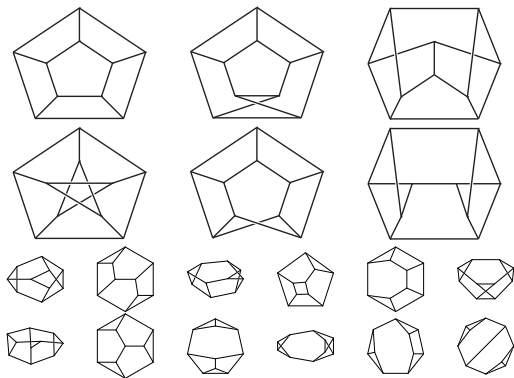
Integrand Construction

DOI: 10.5281/zenodo.5765781



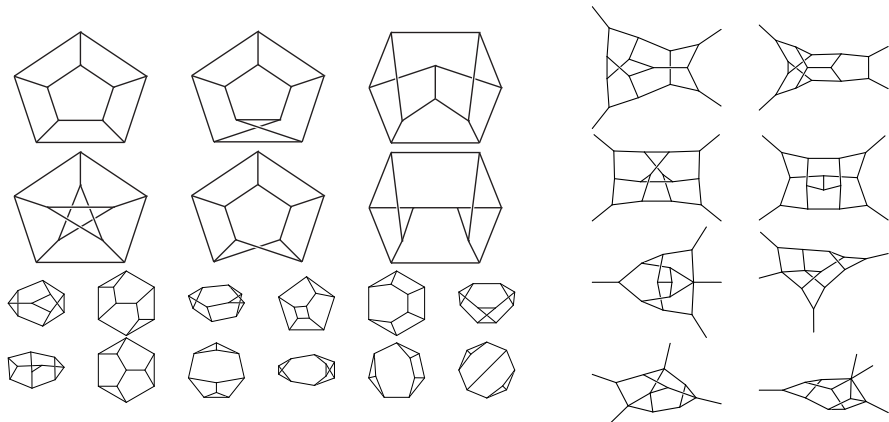
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$N^k M$	0	1	2	3	4	Σ
cuts	5548	41649	156853	363963	576582	1,144,595
non-zero contacts	4420	16776	37653	56717	36087	151653

Integrand exists, but obviously too large to put on slides

Looking Forward

- Improve representation: diagram power counting, generalized double copy
- Prepping tools for SUGRA: gravity cuts, IBPs
- Improve efficiency for 7 loops: 6L MCs take seconds, 7L MCs take hours
 - Intersection of ideals is sensitive to many superficial choices
 - Better diagram parameterization
 - Minimize number of limits to evaluate
- Other applications: higher points, QCD and lower SUSY, open string EFT

Part 2: Color-Kinematics Duality at $n = 6, L = 1$

Motivations

BCJ form at 6 points has long eluded multiple approaches:

- 4D: hexagon maximal cut impossible; Bjerrum-Bohr, Dennen, Monteiro, O'Connell '13: spurious poles in numerator...
- Brute force ansatz: degree-6 polynomial over $\epsilon_i \cdot \epsilon_j, \epsilon_i \cdot p_j, p_i \cdot p_j$ – hundreds of thousands of terms
- String theoretic/forward limit approach – prescriptive, but...
 - Mafra & Schlotterer '14: via pure spinors
Works well for five point. Six point numerators break BCJ
 - He, Schlotterer & Zhang '17: forward limit, only on linear propagators
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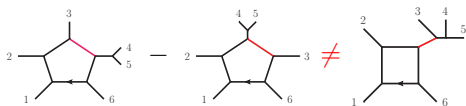
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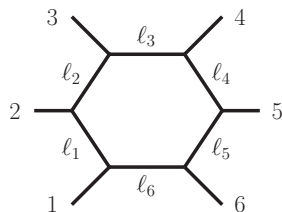
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Mixing approaches

Use covariant structures that appear in
forward limit/max cut:

(AE, He, Schlotterer, Teng)

$$N_{\text{hex}} \supset \{ (\varepsilon_1 \cdot l_1)(\varepsilon_2 \cdot l_2) t_8(f_3, f_4, f_5, f_6) + \text{perms}, \\ (\varepsilon_1 \cdot l_1) t_8(f_2, f_{[3,4]}, f_5, f_6) + \text{perms}, \\ t_8(f_1, f_{[2,3]}, f_{[4,5]}, f_6) + \text{perms}, \\ t_8(f_1, f_{[2,[3,4]]}, f_5, f_6) + \text{perms}, \\ t_{12}(f_1, f_2, f_3, f_4, f_5, f_6) \}$$



$$f_i^{\mu\nu} = k_i^\mu \varepsilon_i^\nu - k_i^\nu \varepsilon_i^\mu \\ f_{[i,j]} = f_i f_j - f_j f_i$$

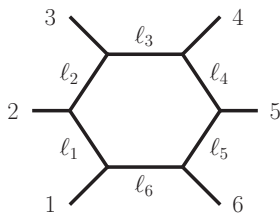
$$t_8(f_w, f_x, f_y, f_z) = \text{tr}(f_w f_x f_y f_z) \\ - \frac{1}{4} \text{tr}(f_w f_x) \text{tr}(f_y f_z) \\ + \text{cyc}(x, y, z)$$

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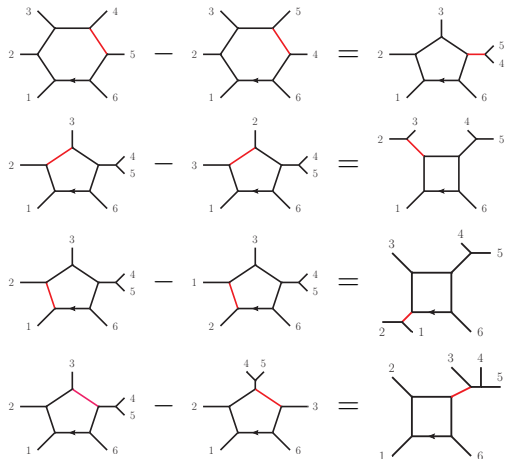
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But allow contact freedom

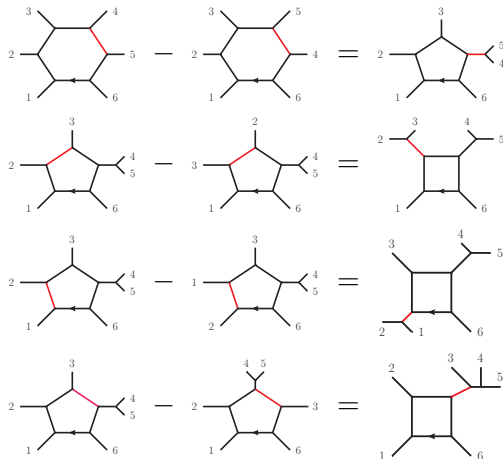
$$N_{\text{hex}} \supset \{ \varepsilon_1 \cdot \varepsilon_2 t_8(f_3, f_4, f_5, f_6) \{ l_7^2, l_1^2, l_2^2 \}, \\ \varepsilon_1 \cdot \varepsilon_3 t_8(f_2, f_4, f_5, f_6) \{ l_7^2, l_1^2, l_2^2, l_3^2 \}, \\ \varepsilon_1 \cdot \varepsilon_4 t_8(f_2, f_3, f_5, f_6) \{ l_7^2, l_1^2, l_3^2, l_4^2 \} \} \\ + \text{cyc}$$

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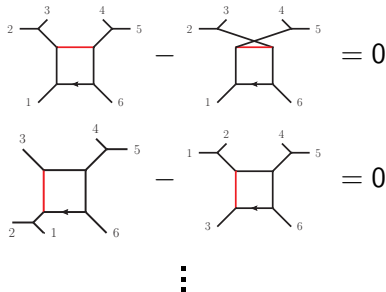
Color-kinematics duality relations

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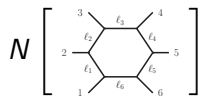
No-Triangle Jacobis



Relations lock contact terms to each other

The hexagon numerator

- Fixed by hexagon maximal cut
- Contact term corrections; related by no-triangle
- Related by gauge invariance of pentagon max cut



$$\begin{aligned}
 N \left[\begin{array}{c} 3 \\ \ell_2 \\ 2 \\ \ell_1 \\ 1 \end{array} \begin{array}{c} \ell_3 \\ \ell_4 \\ \ell_5 \\ \ell_6 \end{array} \begin{array}{c} 4 \\ 5 \\ 6 \end{array} \right] = & (\varepsilon_1 \cdot \ell_1)(\varepsilon_2 \cdot \ell_2)t_8(f_3, f_4, f_5, f_6) - \frac{1}{2}(\varepsilon_1 \cdot \ell_1)t_8(f_2, f_{[3,4]}, f_5, f_6) \\
 & + \frac{1}{4}t_8(f_1, f_{[2,3]}, f_{[4,5]}, f_6) + \frac{1}{6}t_8(f_1, f_{[2,[3,4]]}, f_5, f_6) + \text{perms} \\
 & + t_{12}(f_1, f_2, f_3, f_4, f_5, f_6) \\
 & + \frac{1}{40} \left[\varepsilon_1 \cdot \varepsilon_2 (3\ell_6^2 - 10\ell_1^2 + 3\ell_2^2)t_8(f_3, f_4, f_5, f_6) \right. \\
 & + \varepsilon_3 \cdot \varepsilon_3 (\ell_6^2 - 3\ell_1^2 - 3\ell_2^2 + \ell_3^2)t_8(f_2, f_4, f_5, f_6) \\
 & \left. - \varepsilon_1 \cdot \varepsilon_4 (\ell_6^2 + \ell_1^2)t_8(f_2, f_3, f_5, f_6) + \text{cyc}(1, 2, 3, 4, 5, 6) \right]
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$$N \left[\begin{array}{c} 3 \\ \ell_2 \quad \ell_3 \\ 2 \quad \ell_4 \\ \ell_1 \quad \ell_5 \\ 1 \quad \ell_6 \quad 6 \\ 5 \end{array} \right] = \begin{aligned} & (\varepsilon_1 \cdot \ell_1)(\varepsilon_2 \cdot \ell_2) t_8(f_3, f_4, f_5, f_6) - \frac{1}{2}(\varepsilon_1 \cdot \ell_1) t_8(f_2, f_{[3,4]}, f_5, f_6) \\ & + \frac{1}{4} t_8(f_1, f_{[2,3]}, f_{[4,5]}, f_6) + \frac{1}{6} t_8(f_1, f_{[2,[3,4]]}, f_5, f_6) + \text{perms} \\ & + t_{12}(f_1, f_2, f_3, f_4, f_5, f_6) \\ & + \frac{1}{40} \left[\varepsilon_1 \cdot \varepsilon_2 (3\ell_6^2 - 10\ell_1^2 + 3\ell_2^2) t_8(f_3, f_4, f_5, f_6) \right. \\ & + \varepsilon_3 \cdot \varepsilon_3 (\ell_6^2 - 3\ell_1^2 - 3\ell_2^2 + \ell_3^2) t_8(f_2, f_4, f_5, f_6) \\ & \left. - \varepsilon_1 \cdot \varepsilon_4 (\ell_6^2 + \ell_1^2) t_8(f_2, f_3, f_5, f_6) + \text{cyc}(1, 2, 3, 4, 5, 6) \right] \end{aligned}$$

The hexagon numerator

- Fixed by hexagon maximal cut
- Contact term corrections; related by no-triangle
- Related by gauge invariance of pentagon max cut

$$N \left[\begin{array}{c} 3 \\ \ell_2 \quad \ell_3 \\ 2 \quad \quad 4 \\ \ell_1 \quad \ell_4 \\ 1 \quad \quad 5 \\ \ell_6 \quad \ell_5 \\ 6 \end{array} \right] = \begin{aligned} & (\varepsilon_1 \cdot \ell_1)(\varepsilon_2 \cdot \ell_2) t_8(f_3, f_4, f_5, f_6) - \frac{1}{2}(\varepsilon_1 \cdot \ell_1) t_8(f_2, f_{[3,4]}, f_5, f_6) \\ & + \frac{1}{4} t_8(f_1, f_{[2,3]}, f_{[4,5]}, f_6) + \frac{1}{6} t_8(f_1, f_{[2,[3,4]]}, f_5, f_6) + \text{perms} \\ & + t_{12}(f_1, f_2, f_3, f_4, f_5, f_6) \\ & + \frac{1}{40} \left[\varepsilon_1 \cdot \varepsilon_2 (3\ell_6^2 - 10\ell_1^2 + 3\ell_2^2) t_8(f_3, f_4, f_5, f_6) \right. \\ & \quad + \varepsilon_3 \cdot \varepsilon_3 (\ell_6^2 - 3\ell_1^2 - 3\ell_2^2 + \ell_3^2) t_8(f_2, f_4, f_5, f_6) \\ & \quad \left. - \varepsilon_1 \cdot \varepsilon_4 (\ell_6^2 + \ell_1^2) t_8(f_2, f_3, f_5, f_6) + \text{cyc}(1, 2, 3, 4, 5, 6) \right] \end{aligned}$$

No free parameters remaining!

Going beyond

- Seven Points: Need new classes of contact terms

$$N_{\text{hept}} \supset \{(\varepsilon_1 \cdot \varepsilon_2)(\varepsilon_3 \cdot \ell_j) \ell_k^2 t_8(f_4, f_5, f_6, f_7), \\ \varepsilon_1 \cdot \varepsilon_2 \ell_k^2 t_8(f_3, f_{[4,5]}, f_6, f_7), \dots\}$$

Heptagon cut + color-kinematics + gauge invariance leaves 30 free params; hexa-,penta-,tetra-gon cuts no extra info

- Eight Points: Will have double-contacts $\ell_i^2 \ell_j^2$. Interesting to see if n -gon+CK+GI is still everything.
- Two loops: MCs accessible via direct sewing \rightarrow test limits of H-identity construction

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Summary

- 1 New methods for dimension-agnostic cut recursion, applied to non-planar 6-loop sYM. Making progress towards 7-loop SUGRA
- 2 11-parameter BCJ construction of 6 pt 1-loop sYM, solving decade-old problem
- 3 Opens door to studying non-planar higher points and higher loops in d dimensions

Thanks!