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# Integration of the scattering chamber of the NUMEN experiment

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#### Presentation overview

- NUMEN project introduction
- Scattering chamber design requests
- Scattering chamber overview
- ▶ Testing setup in Turin



#### NUMEN project @ LNS

NUMEN (NUclear Matrix Elements of Neutrinoless double beta decay)

This project aims to study the nuclear matrix elements of Double Charge Exchange (DCE) reactions induced by heavy ions and particular isotopes in the context of Neutrinoless Double Beta decay research.

First exploratory experimental runs were performed (until 2020) using the existing large acceptance magnetic spectrometer MAGNEX with ion beams up to 10<sup>10</sup> pps provided by the cyclotron at Laboratori Nazionali del Sud (INFN-LNS), in Catania.



Laboratori Nazionali del Sud Outside view



#### MAGNEX @ Laboratori Nazionali del Sud

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MAGNEX room picture taken on April 2019

Scattering Beam Line chamber

Quadrupole

Dipole

Focal Plane Detector

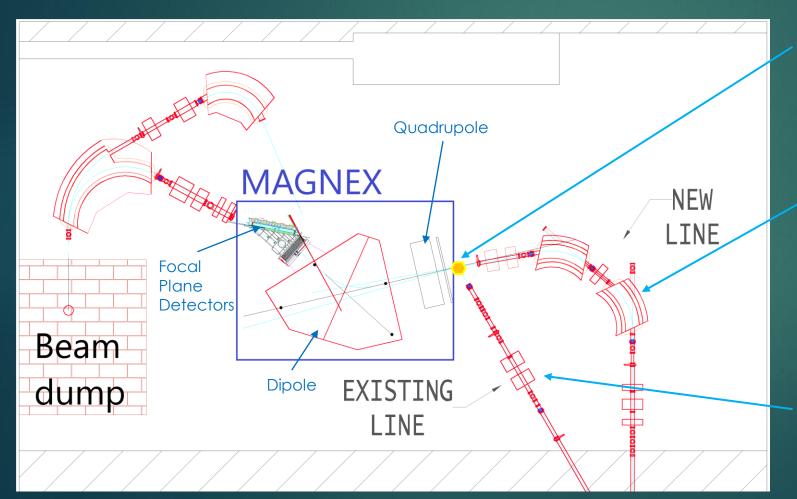
MAGNEX platform



#### NUMEN project layout

To get accurate values of tiny DCE cross sections and to speed up a systematic study of all the isotopes foreseen, the superconducting cyclotron is being fully refurbished featuring ion beams with energies from 15 up to 70 MeV/u and intensities up to  $10^{13}$  pps .

This implies a complete upgrade of MAGNEX.



Target positioned inside scattering chamber

New High Intensity ion beam lines (10<sup>13</sup> pps):

- 18
- 20Ne

Low Intensity beam line (10<sup>10</sup> pps):

- Existing line
- Oriented by 70° from the high intensity line



#### Scattering chamber integration request

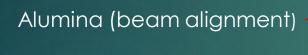
#### Main features requested to integration:

- Target adapted to new experimental conditions (higher intensity beam)
- Alternative connection to Low Intensity and High Intensity beam lines, with relative position of the MAGNEX platform
- External manipulation system for the target (high radiation level, up to 10<sup>6</sup> Gy around the target)
- High vacuum inside scattering chamber and connected systems (10-6 mbar)
- Positioning of the instrumentation for diagnostic and calibration (thermal camera, alumina, Faraday cup, ...)
- Positioning of around 110 gamma detectors around scattering chamber (G-NUMEN)



#### Target and target holder

- Target is composed by a thin isotope film (few hundreds of nm) deposited on a graphite layer (High Oriented Pyrolytic Graphite, HORPG, thickness 2 μm)
- Graphite is clamped on a target holder made of copper (OFHC Oxygen Free High thermal Conductivity)
- ▶ Target holder is cooled by a cryocooler (to less than 40 K) connected in the lowest part
- ▶ There is a system to vertically move cryocooler to align all the spot of the target holder

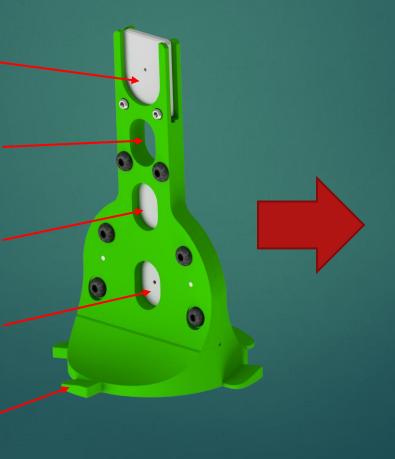


Free hole (background from frame)

Graphite layer (for reference measure)

Target

Connection elements to cryocooler (bayonet coupling)







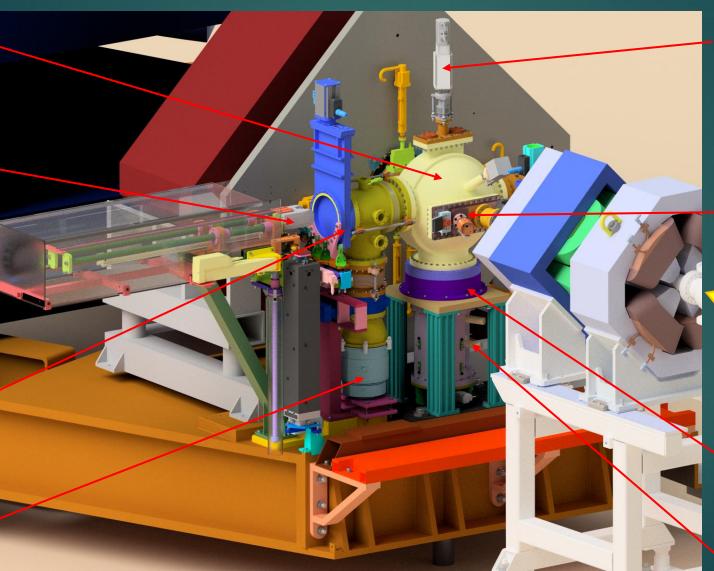
#### Scattering chamber with High Intensity beam

Scattering chamber

Target manipulator

Gate valves connections

Vacuum pumping system



Faraday cup actuator

Connection to High Intensity beam line

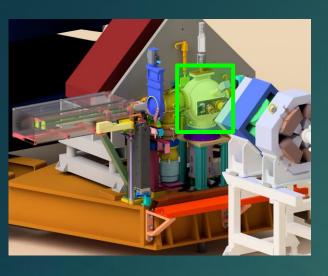
Beam HI direction

Scattering chamber sustain

Cryocooler



#### Scattering chamber



Main body in Al series 5000 external diameter: 466mm sphere thickness: 6mm

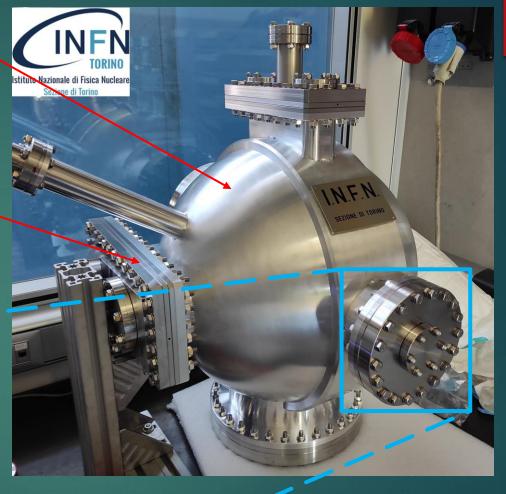
All Flanges in stainless steel



SS 304L (chamber side)

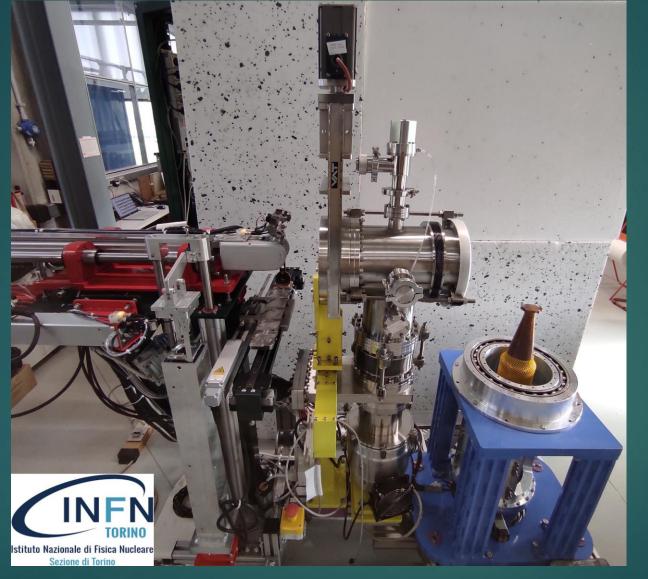
SS 316L (flange)



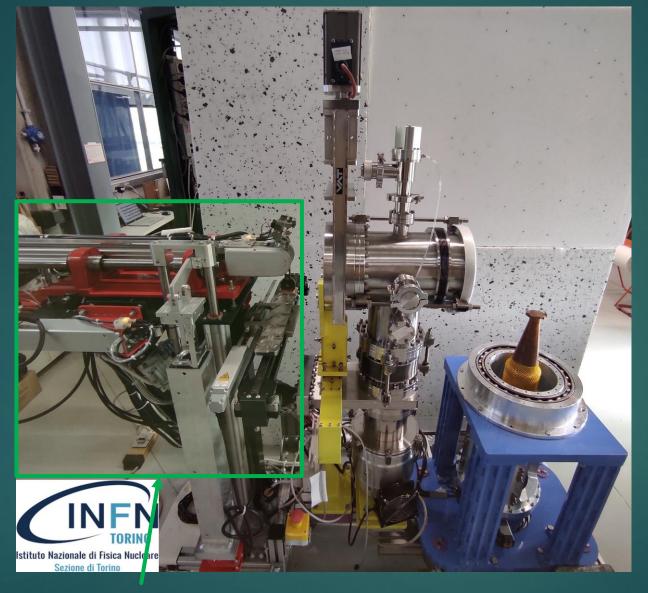






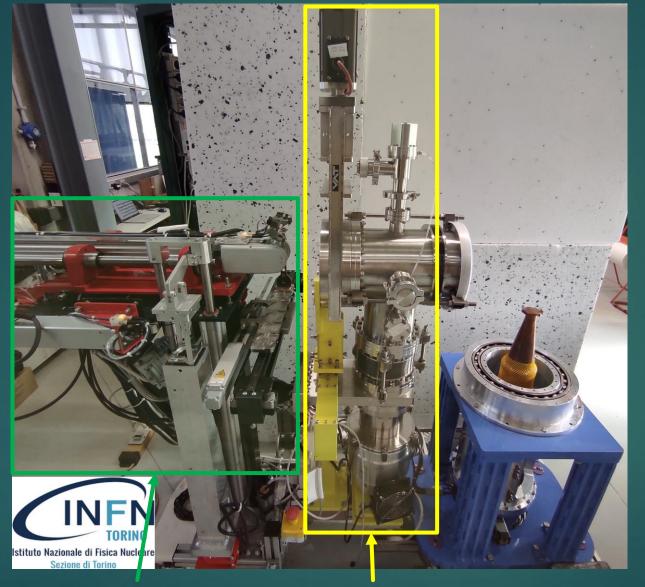






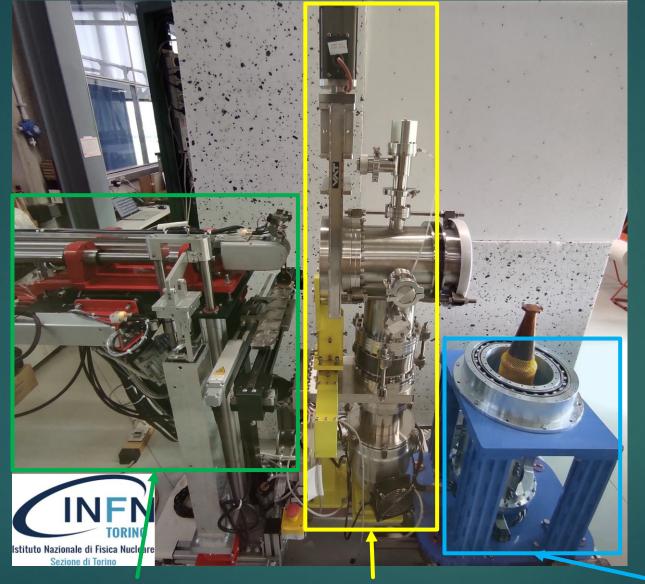
Target manipulator





Target manipulator Gate valves + pumping system



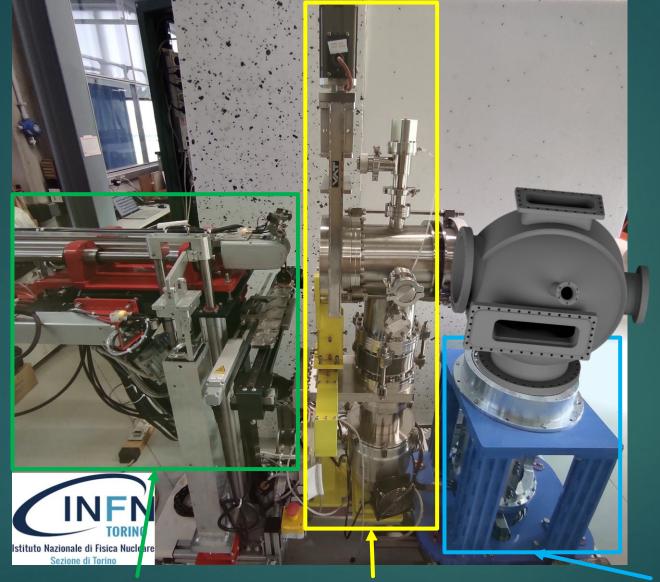


Target manipulator

Gate valves + pumping system

Scattering chamber + cryocooler + sustains





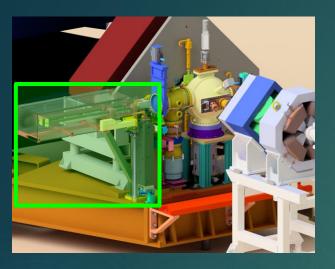
Target manipulator

Gate valves + pumping system

Scattering chamber + cryocooler + sustains



#### Target manipulator



- Manipulation of the target holders must be done remotely when experimental run is stopped
- System composed by three main groups: Manipulator, storage and control
- The manipulator consist of a pneumatic gripper, directed by two axis wrist and introduced in chamber by pneumatic cylinder
- ► The storage contains new target holders and activated ones in a specific shielded container (radioprotection)







Target holder storage

Manipulator lateral view



#### Testing setup in Turin - Manipulator



Target manipulator in working position

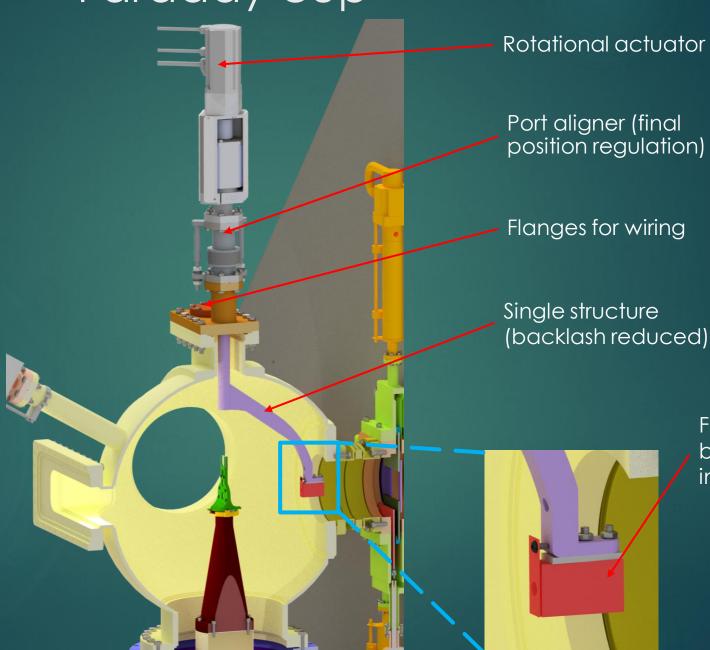
Target holder in position above cryocooler



### Faraday cup



- ► To be used with Low Intensity beams
- Rotation allows automatic positioning of the Faraday cup on line (on line also during manipulator operations)
- Required positioning precision of 0,1mm



Faraday cup with boron nitride (BN) insulation



#### Faraday cup test

以上

Rotational motor

Vacuum coupling for rotation

Port aligner (static regulation)

Test support

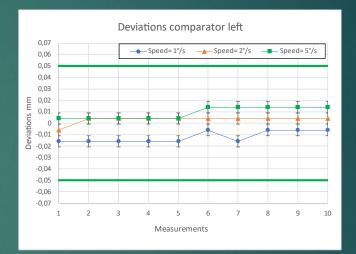
Arc structure

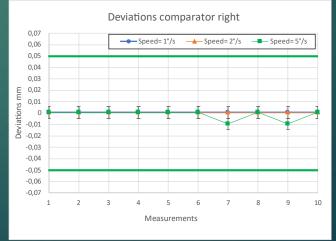
Comparators (resolution 0,01mm)

Block simulating Faraday Cup (same weight =150 g)

#### Tests conducted:

- ▶ 10x rotations of 90° with different speed (1, 2, 5 °/s)
- ► 50x rotations with speed of 1°/s



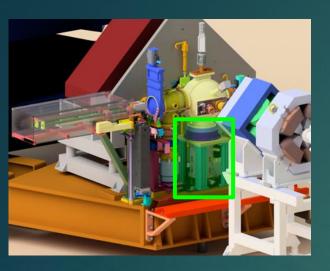




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Scattering chamber sustain and cryocooler



- Target holder and cryocooler are fixed during platform rotation
- Cryocooler vertical movement created by a lower jack
- System to regulate target position on beam

Target holder

Bearings for rotation

Bellows to compensate cryocooler translation

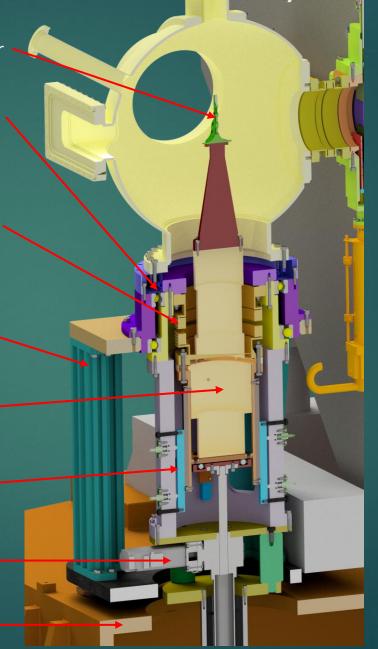
Chamber sustain

Cryocooler

Guides to vertical translation

Jack for target lifting

MAGNEX platform

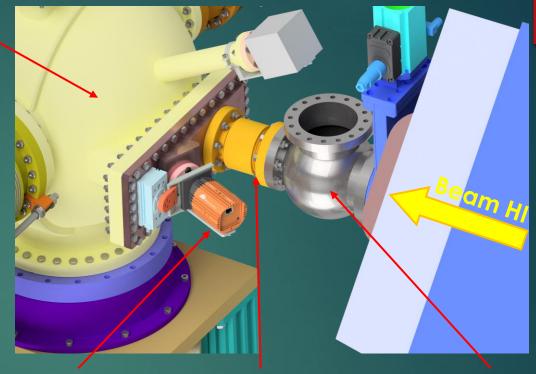




#### Connection to high intensity beam line

Scattering chamber

- High Intensity beam line is connected to the chamber thought a rectangular flange
- Since the rotation of MAGNEX platform will be different for <sup>18</sup>O and <sup>20</sup>Ne (+3° and -3°) two flanges are designed
- Beam diagnostics is positioned upstream to the chamber
- Rectangular flange holds in position also thermal camera with lead screen protector



Thermal camera

Connection bellows

Diagnostics
upstream to
scattering chamber

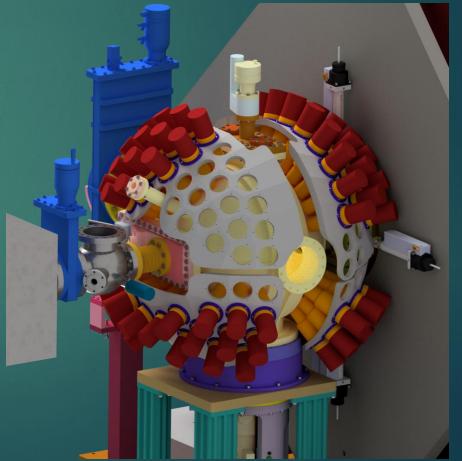


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Sartirana Diego – INFN Turin

#### Ongoing and future works

- Mount <u>scattering chamber in position</u> and validate an automatic procedure to manage vacuum systems
- Test <u>cooling</u> of the target with final setup
- Repeat manipulator test with complete procedure for cooling the target and pumping vacuum
- Complete automatic procedures for integration of all the operations of the system
- Design and integrate the complete <u>G-NUMEN</u> <u>detectors</u> sustain





## Thank you for attention

