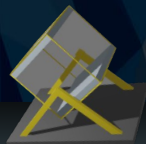


Detection system for muography applications

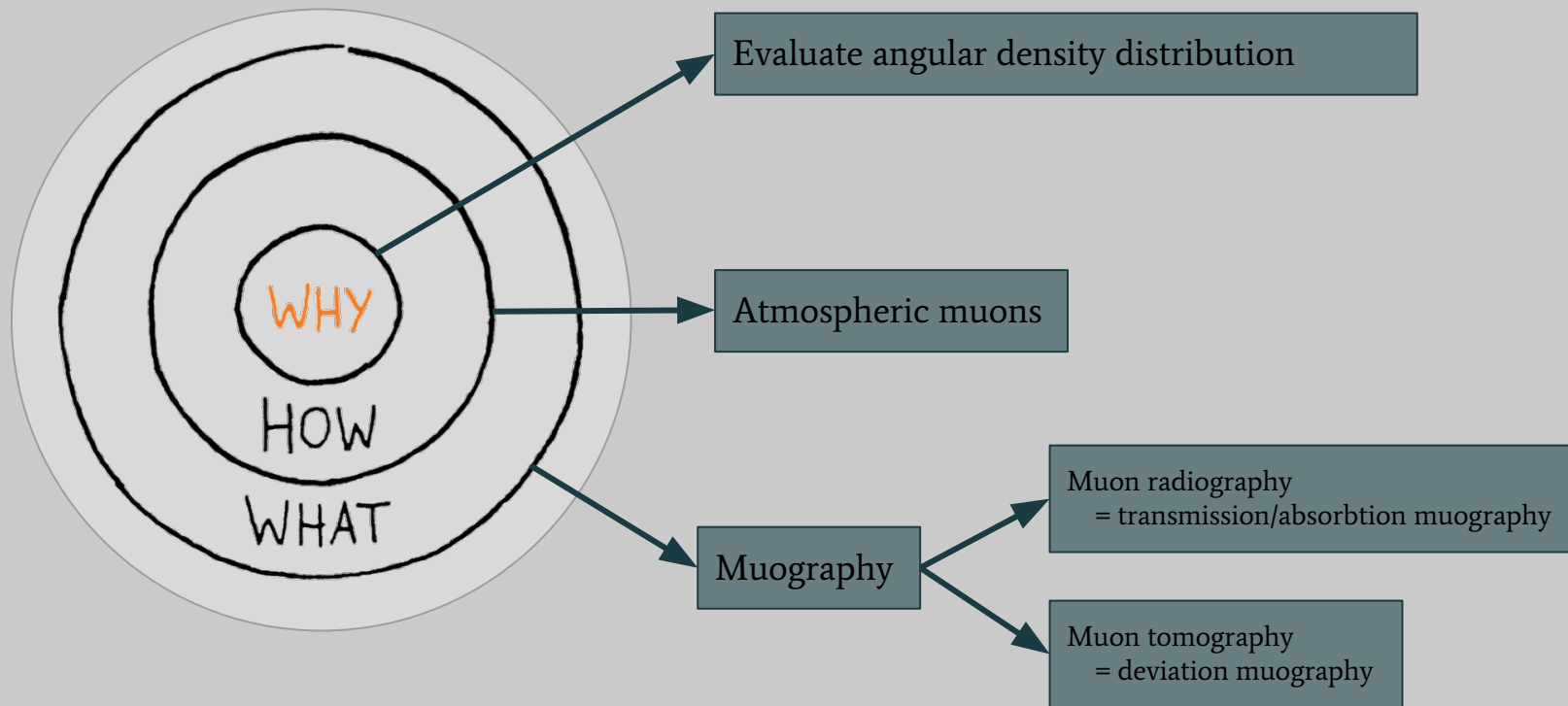
~ design and testing ~



Raluca Ioana SMĂU^(1,2)

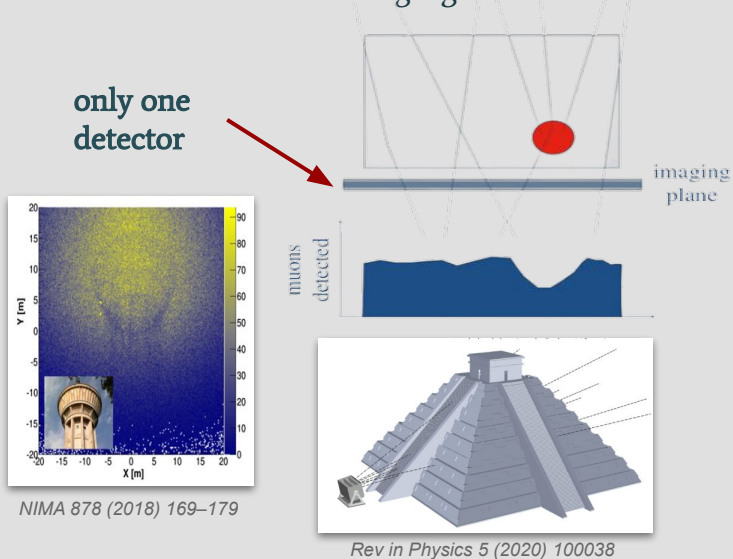
European Nuclear Physics Conference 2022 (EuNPC 2022)
Oct 24 – 28, 2022 University of Santiago de Compostela

1. Introduction to muography



Muon radiography

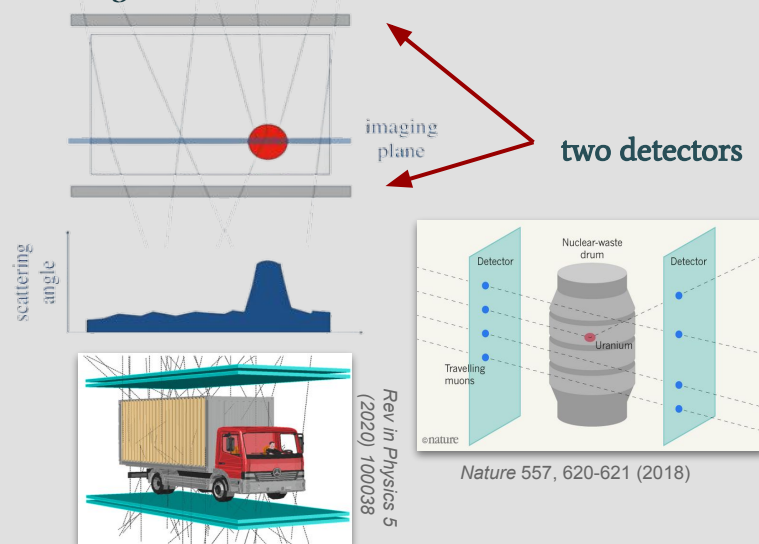
- based on muon flux attenuation (inelastic collisions with atomic electrons)
- records the direction and counts the number of muons **after** crossing a given structure



Applications: geological, archaeological and subsoil prospecting applications in civil and mining fields.

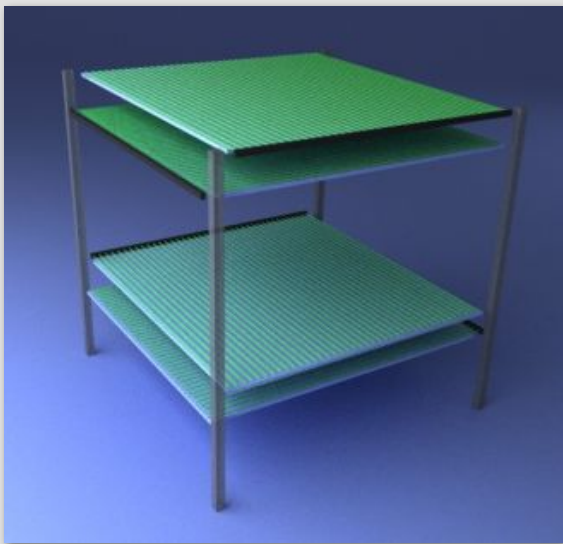
Muon tomography

- based on angular deflection of incident muon direction (elastic scattering on nuclei)
- records the direction and counts the number of muons both **before** and **after** crossing a given structure



Applications: nuclear security, transport control

SHOGUN - Scintillator HOdoscope for Geophysical and UNderground applications

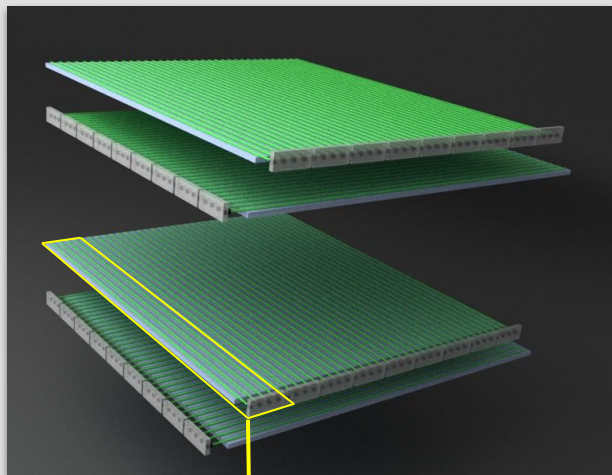


- absorption/transmission muography
- plastic bar scintillators
- SiPM devices
- trajectory information
- developed at IFIN-HH, Magurele, Romania within the Astroparticle Physics Group

SHOGUN - Scintillator HOdoscope for Geophysical and UNderground applications

2. Detector description

3D representation



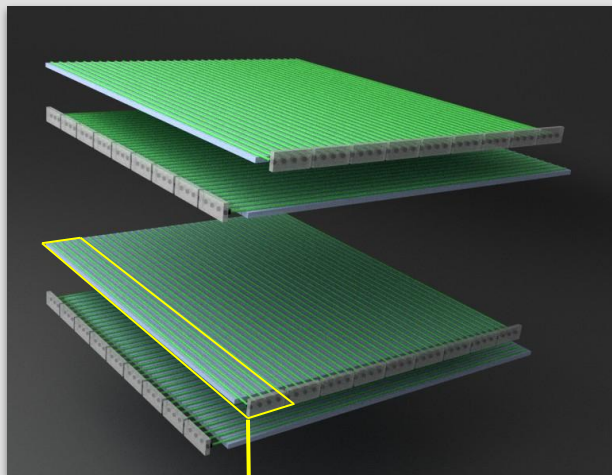
- 935 cm² active surface
- 36 plastic scintillator strips per layer
- 4 layers with orthogonal scintillators
- one optic fiber on each plastic scintillator
- collected light is readout by a SiPM device for each plastic bar
- 1296 pixels on each layer
- spatial resolution : 2.5 x 2.5 cm²
- coincidence condition between the planes



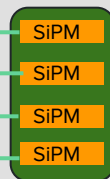
SHOGUN - Scintillator HOdoscope for Geophysical and UNderground applications

2. Detector description

3D representation



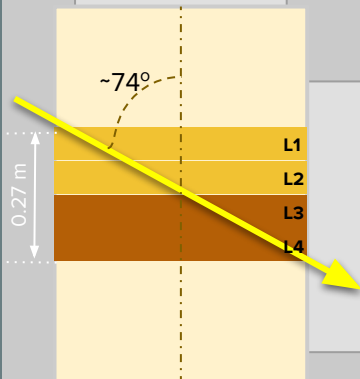
- 935 cm² active surface
- 36 plastic scintillator strips per layer
- 4 layers with orthogonal scintillators
- one optic fiber on each plastic scintillator
- collected light is readout by a SiPM device for each plastic bar
- 1296 pixels on each layer
- spatial resolution : 2.5 x 2.5 cm²
- coincidence condition between the planes



front end
electronics

**MUON
TRACKING**

solid angle: 4.55 Sr
angular resolution: 97.9 mrad



minimum distance
between the planes
9 cm

By increasing the distance between detection planes

- angular resolution is improving
- maximum solid angle is reducing

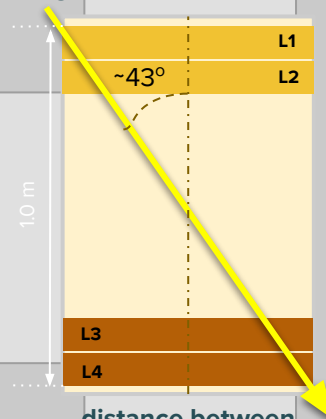
! useful when the object of interest is small and well located

Spatial resolution for a distance of 1 km

- 98 m for an angular resolution of 98 mrad
- 17 m for an angular resolution of 17 mrad
- 8 m for an angular resolution of 8 mrad

- the customizable spatial configuration makes the detector suitable for various application cases

solid angle: 1.66 Sr
angular resolution: 17 mrad



distance between
the planes 73 cm

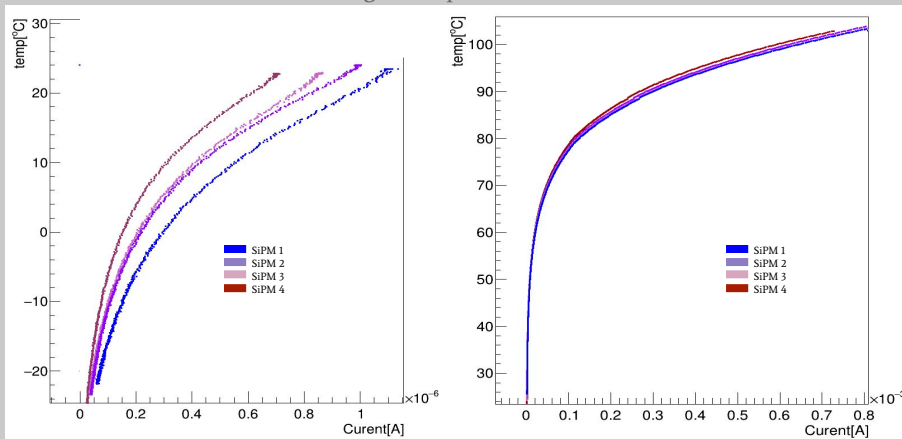
Basic unit

- scintillator bar with optical fiber waveguide
- two SiPM devices collecting the light signal at both ends of the fiber

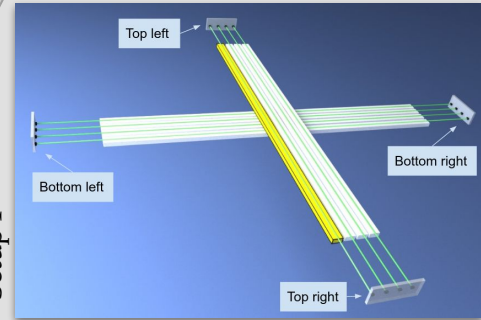
What we inspected

- signal propagation
- data acquisition
- time of flight
- temperature dependence

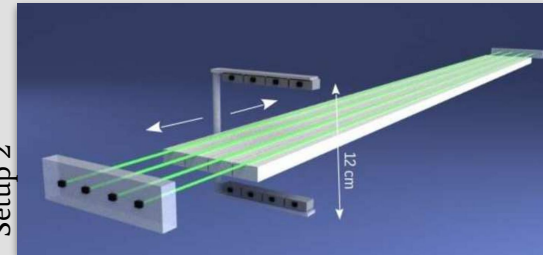
Temperature dependence of SiPM current for 4 different devices. Left: temperature was lowered from 24°C to -25°C. Right: temperature was raised from 24°C to over 100°C



Setup 1

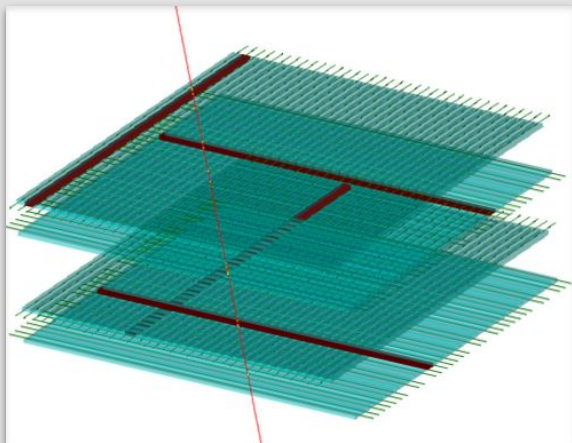


Setup 2

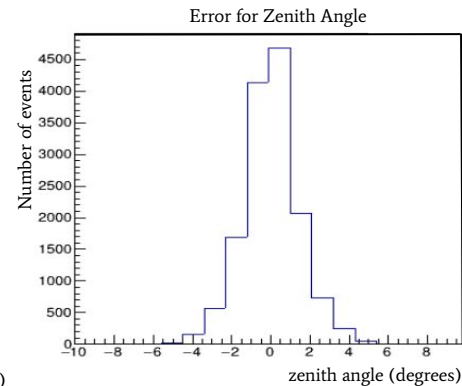
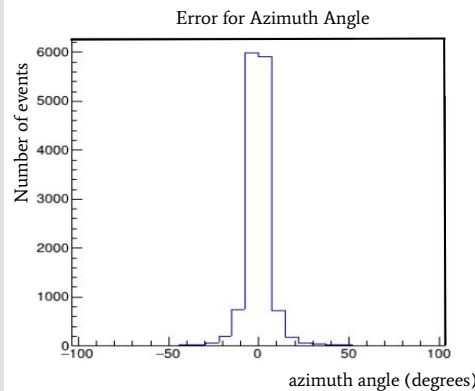
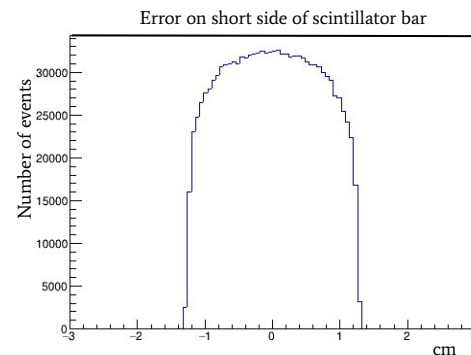
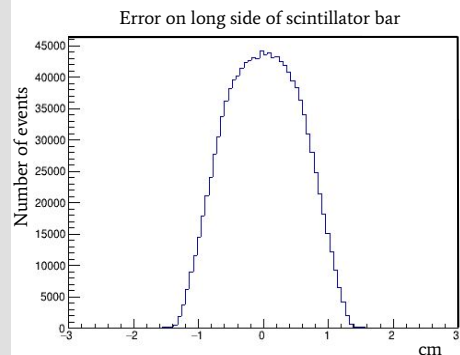


Results:

- At constant temperature, bias voltage and threshold, differences of up to 40% were observed between the counting rates of the SiPM devices utilised in the tests
- results are reported in *Balaceanu A. et al, Characterization of the basic unit in a multi-channel SiPM muography detector using cosmic muons* (in press at NIMA)

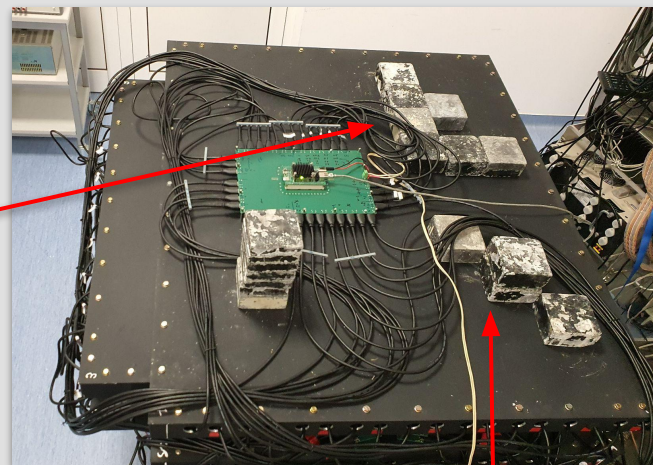
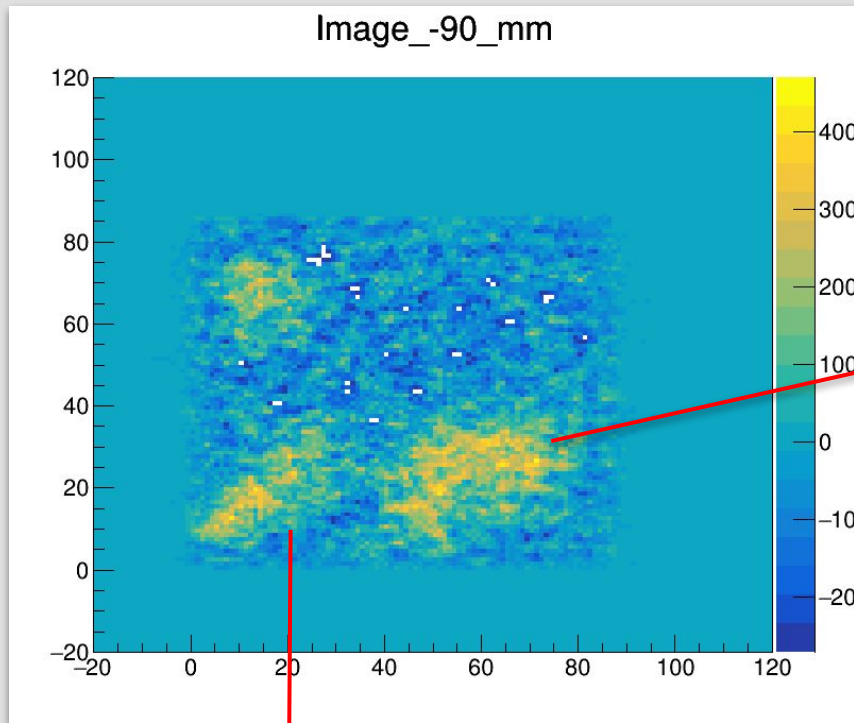


- trajectory reconstruction on simulation data
- position error $< \pm 2.5$ cm on x and y axes



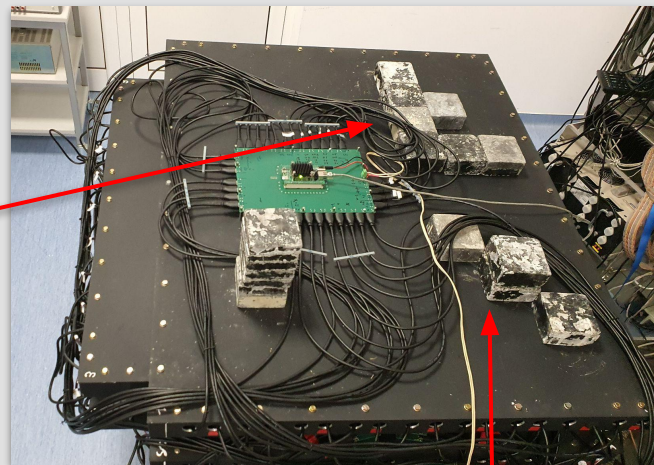
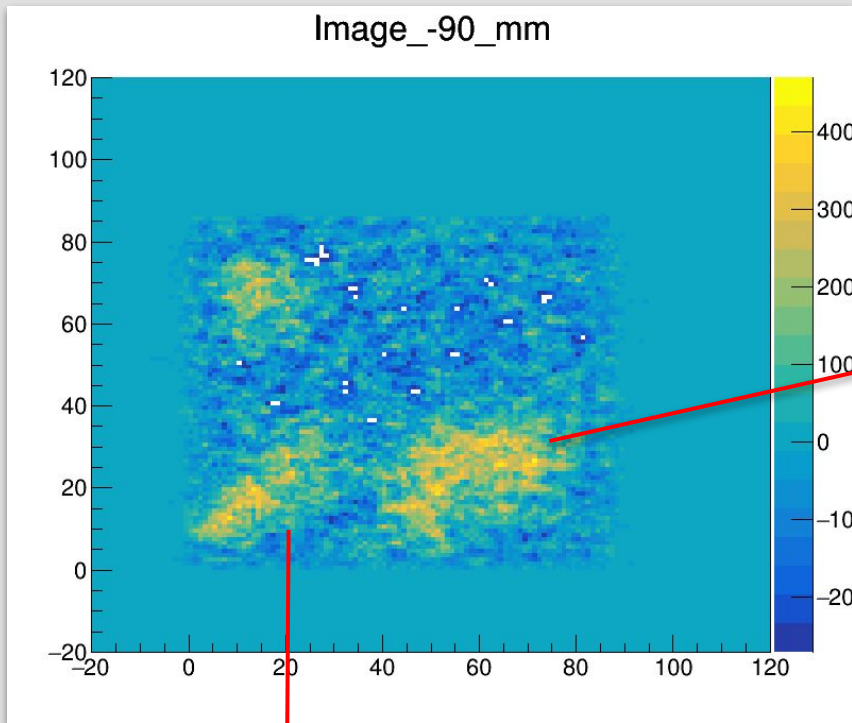
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

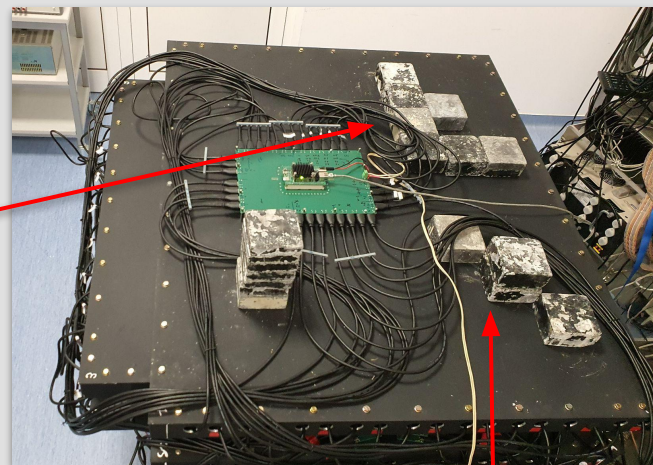
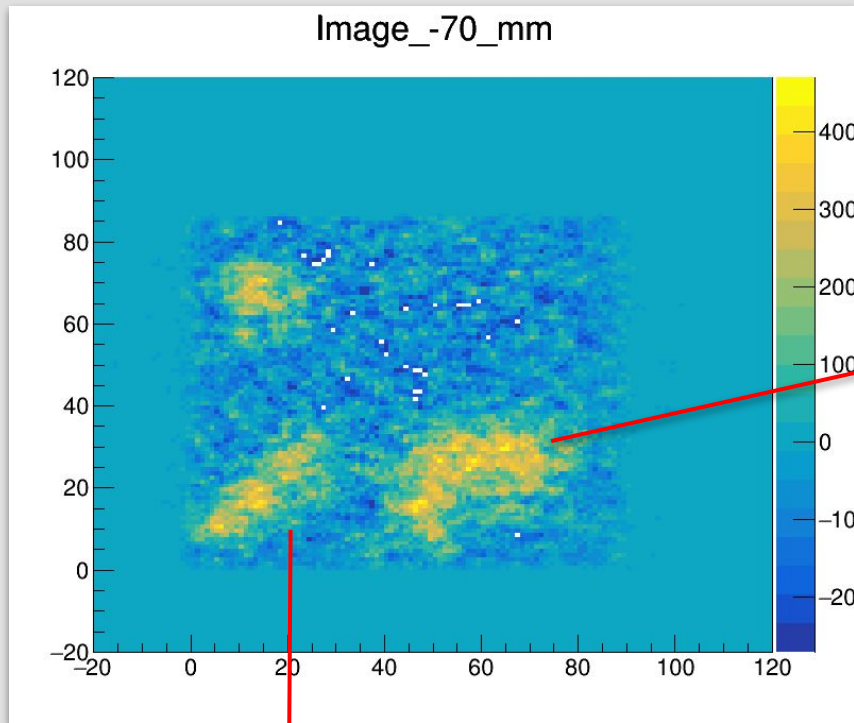


4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

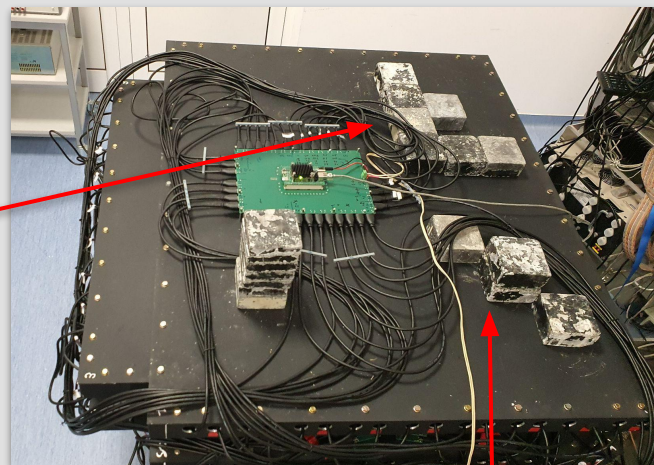
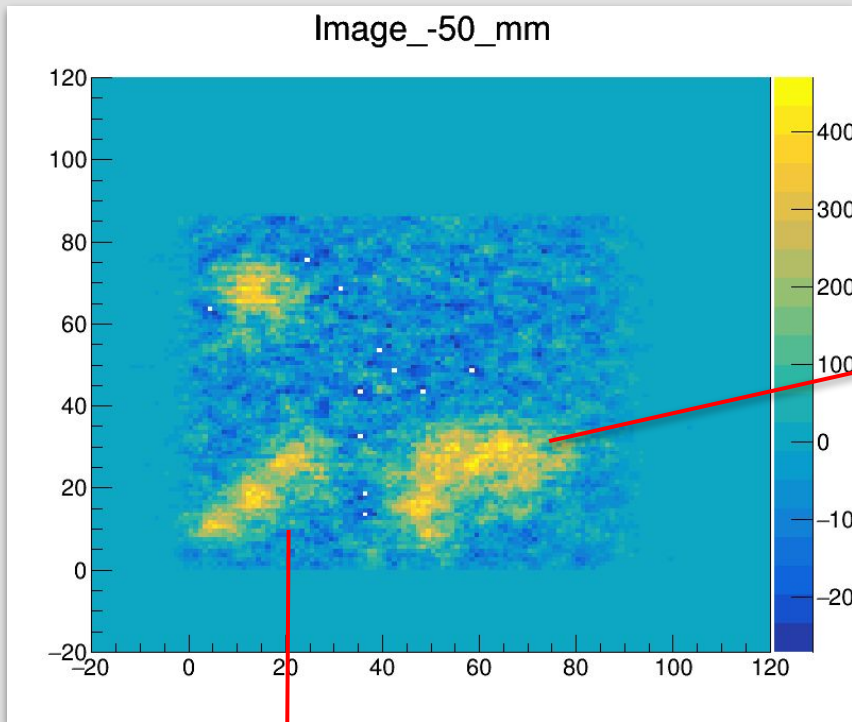


- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



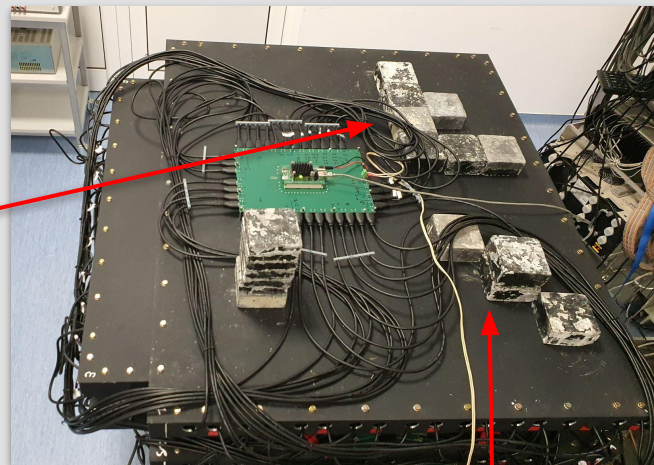
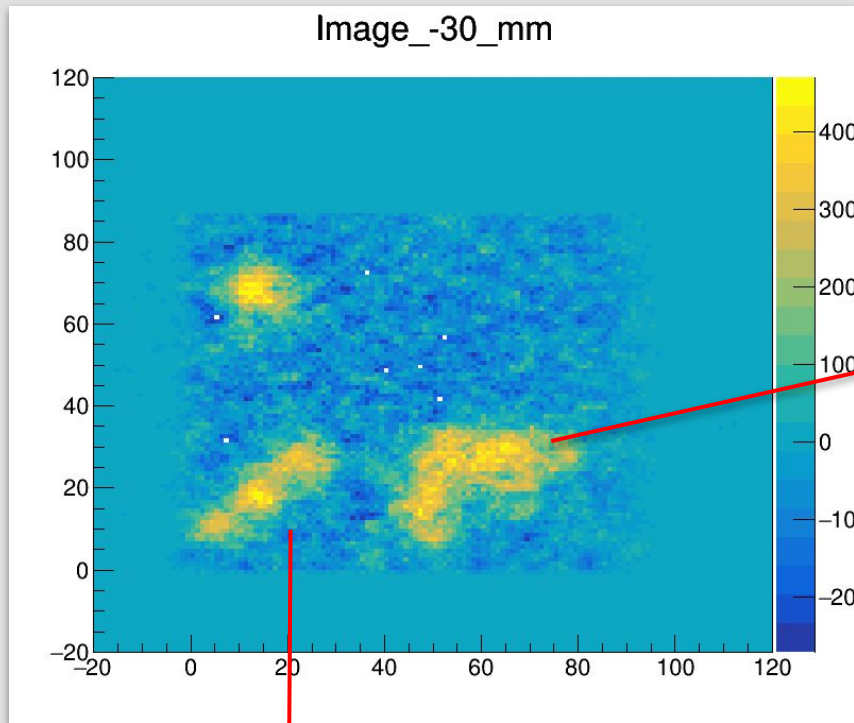
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

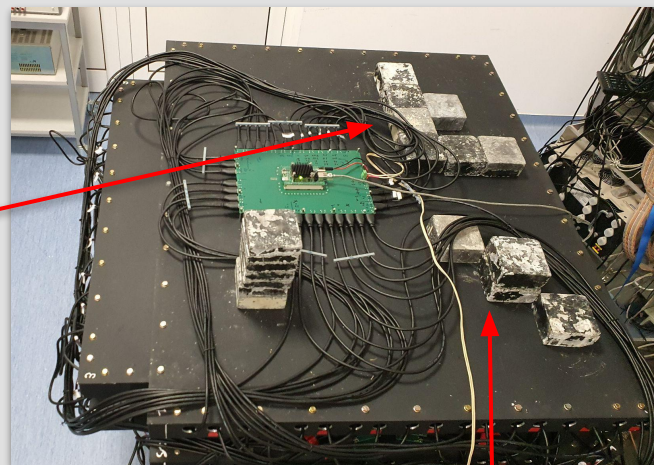
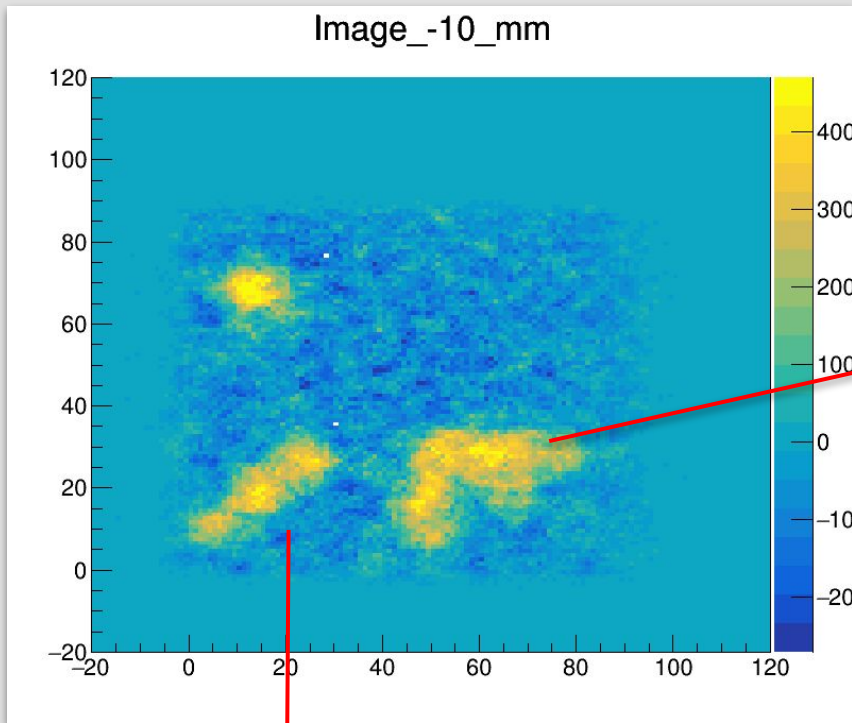


4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

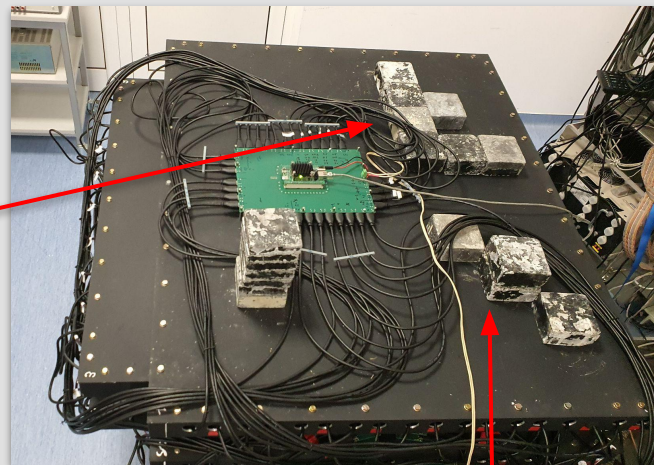
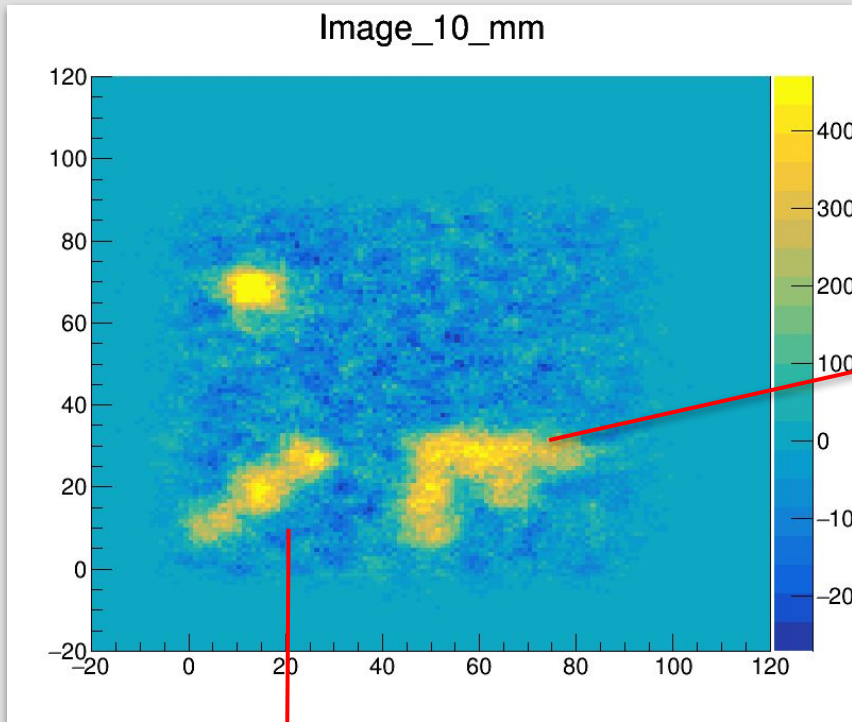


- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



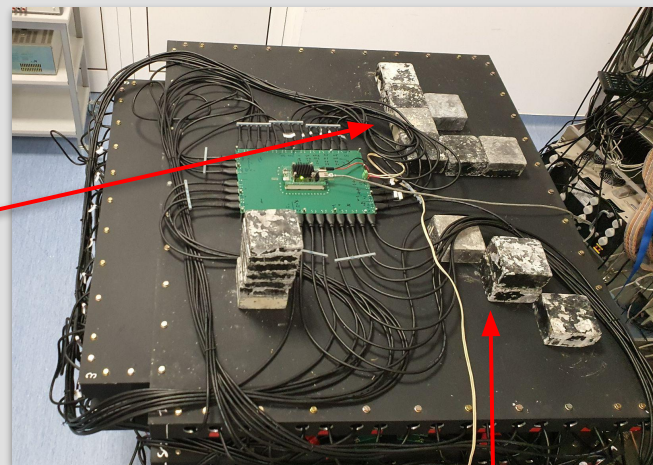
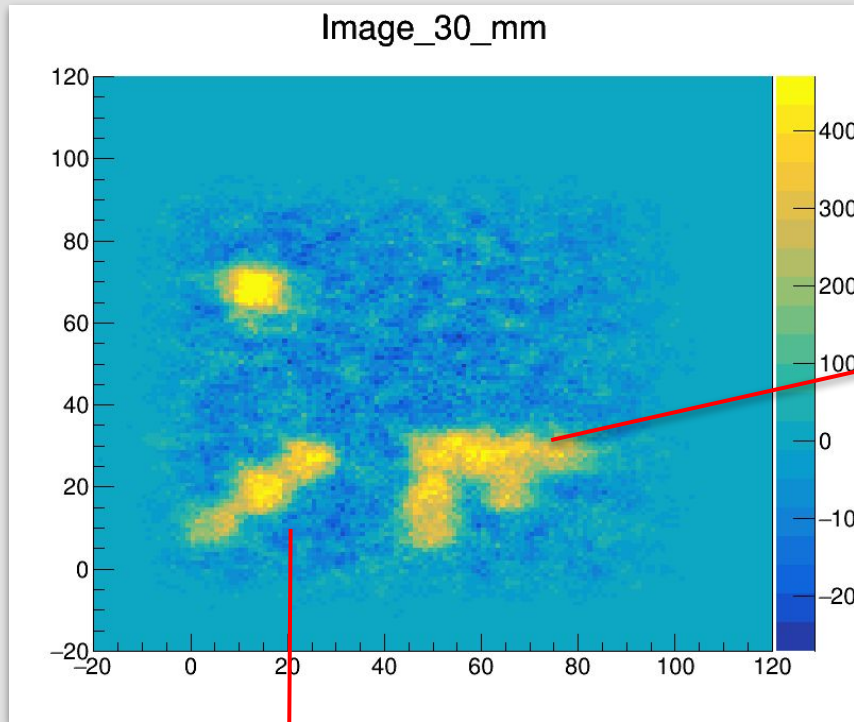
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



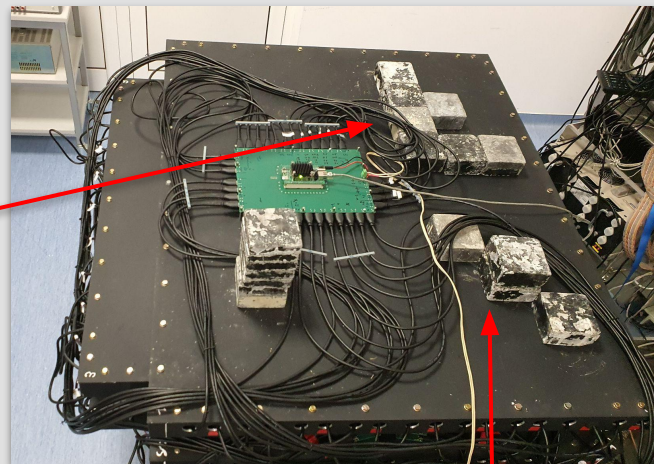
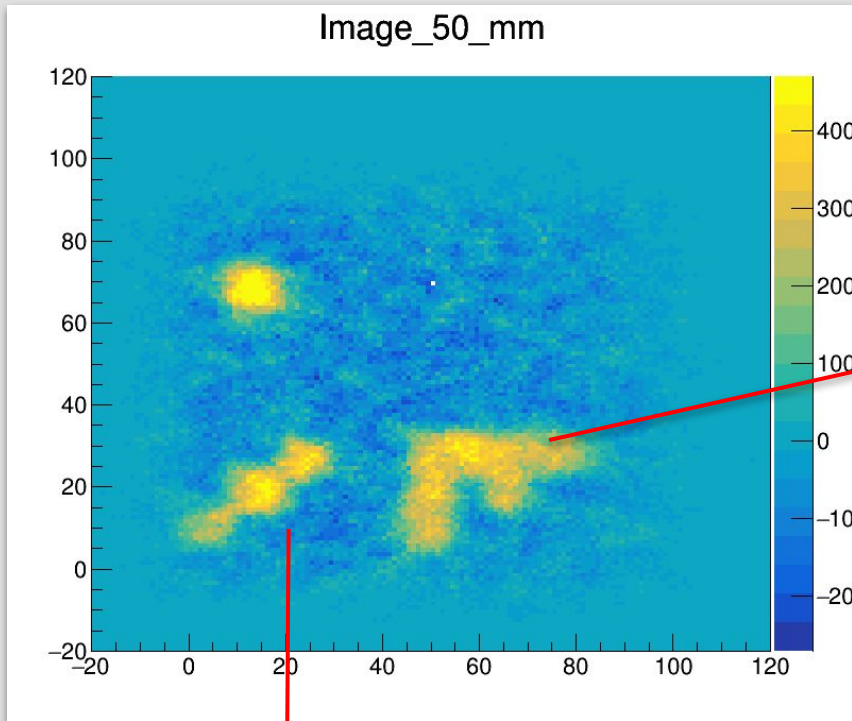
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



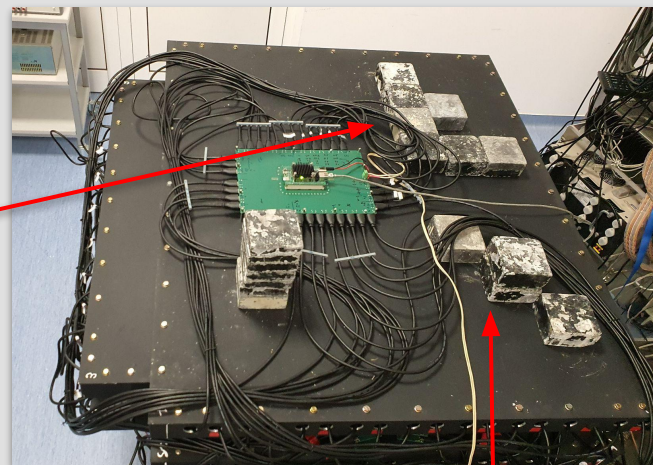
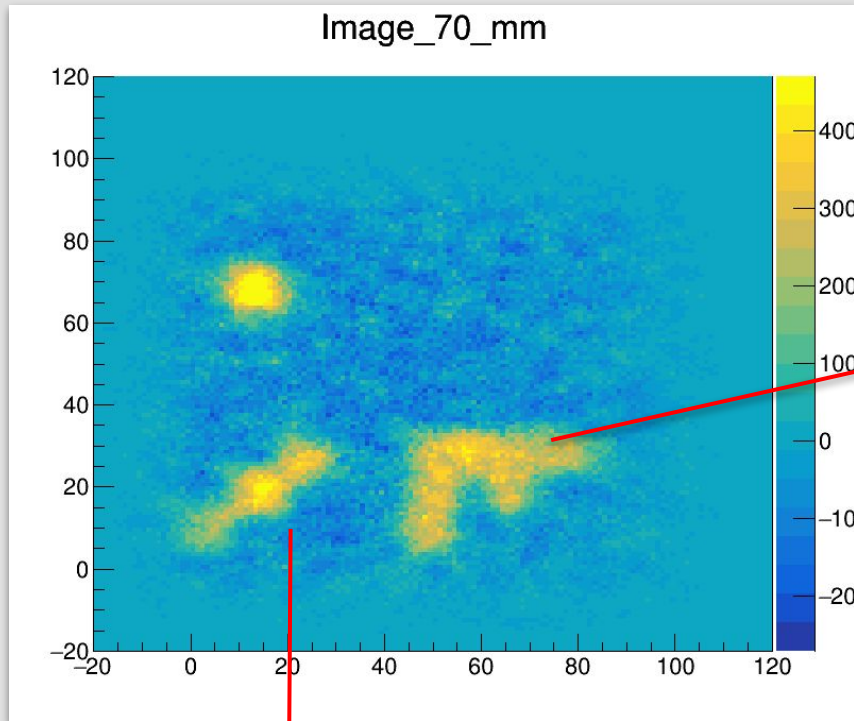
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



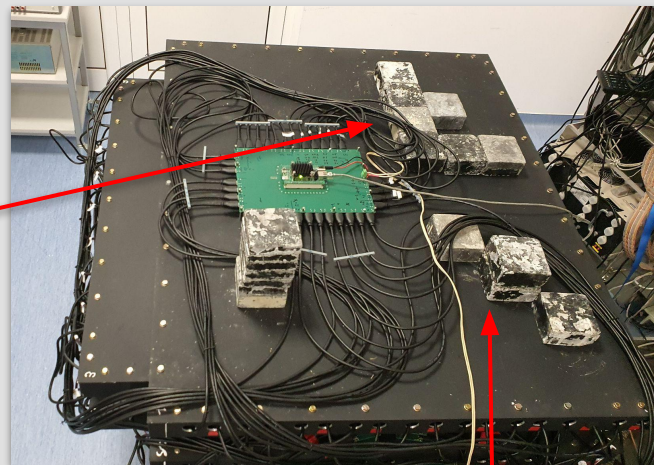
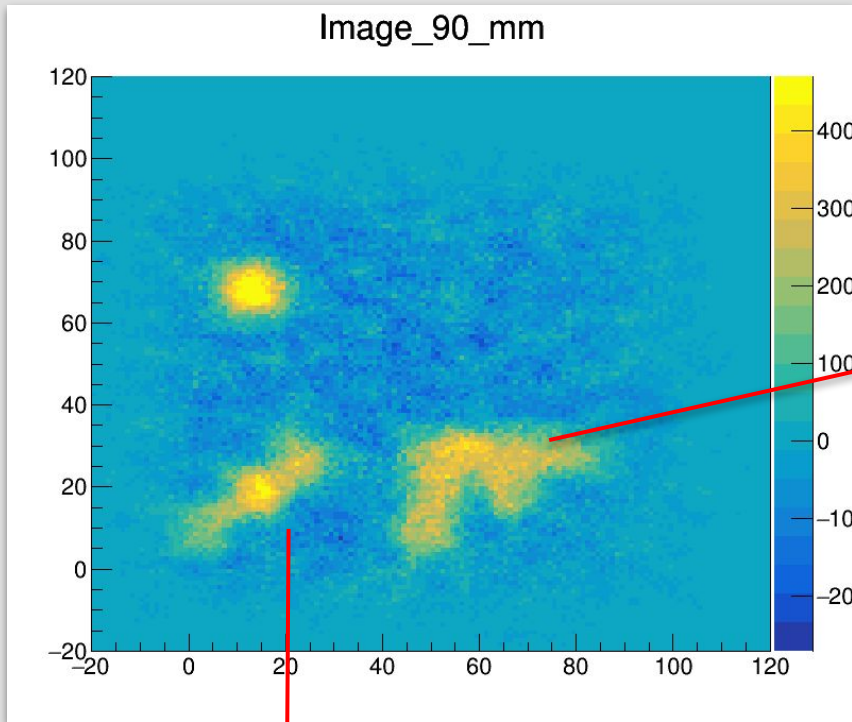
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



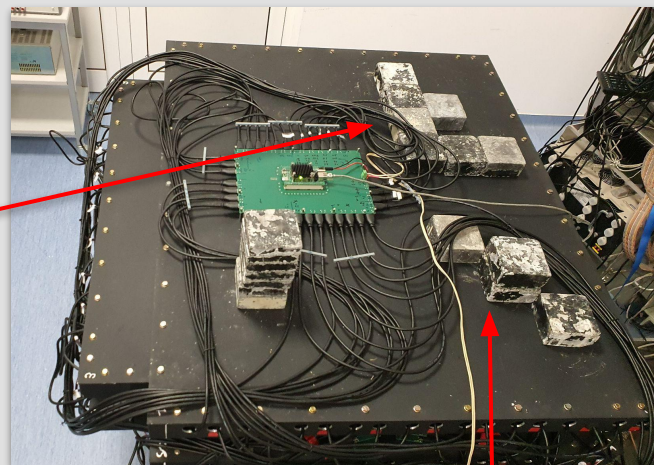
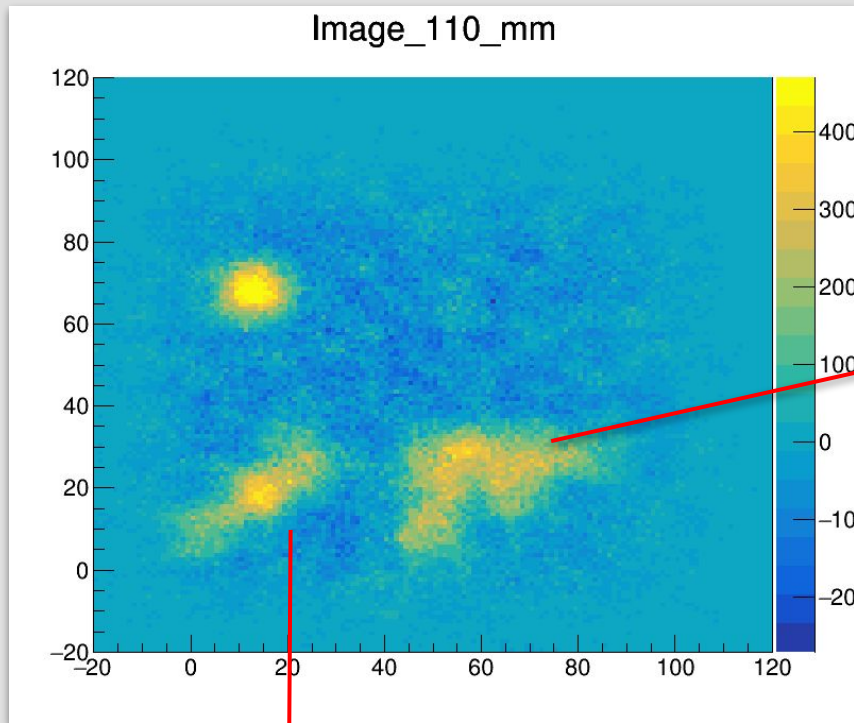
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



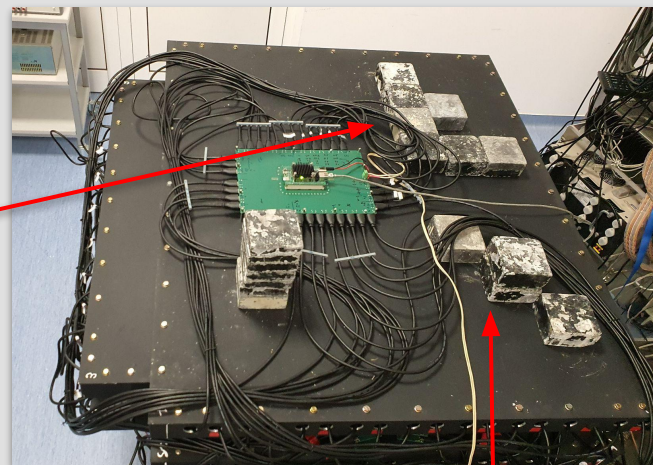
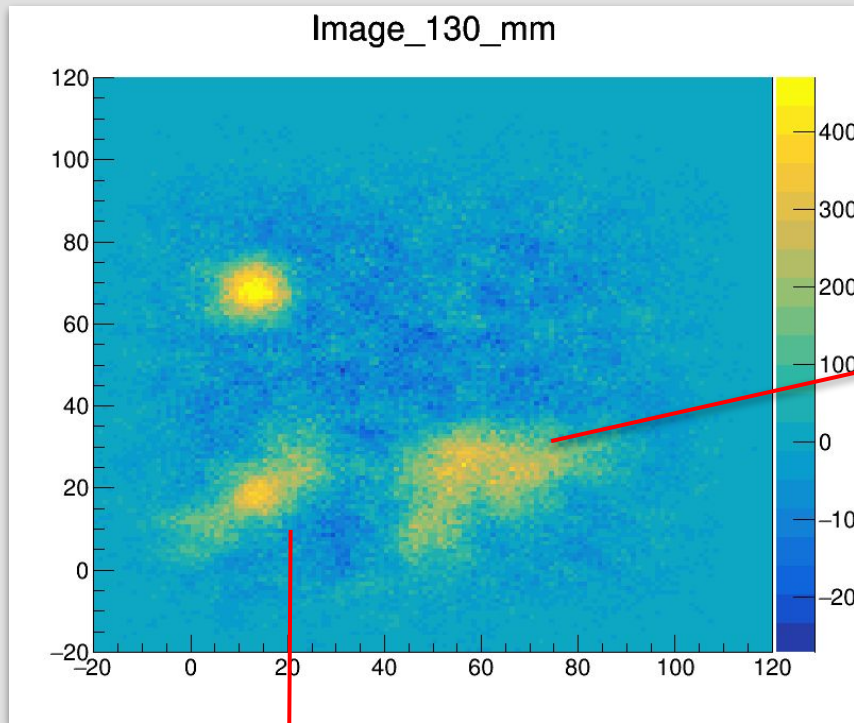
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



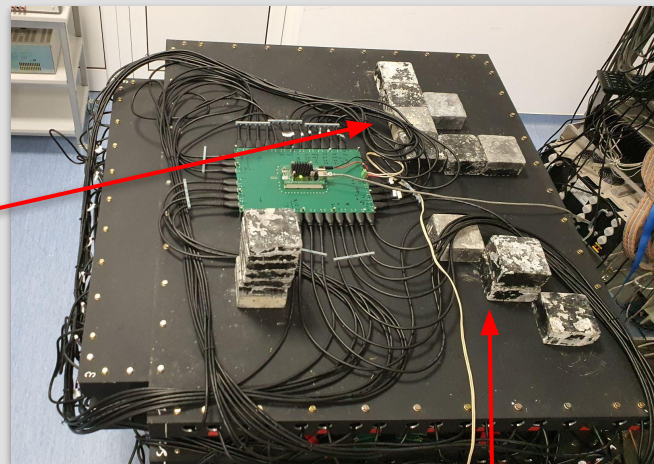
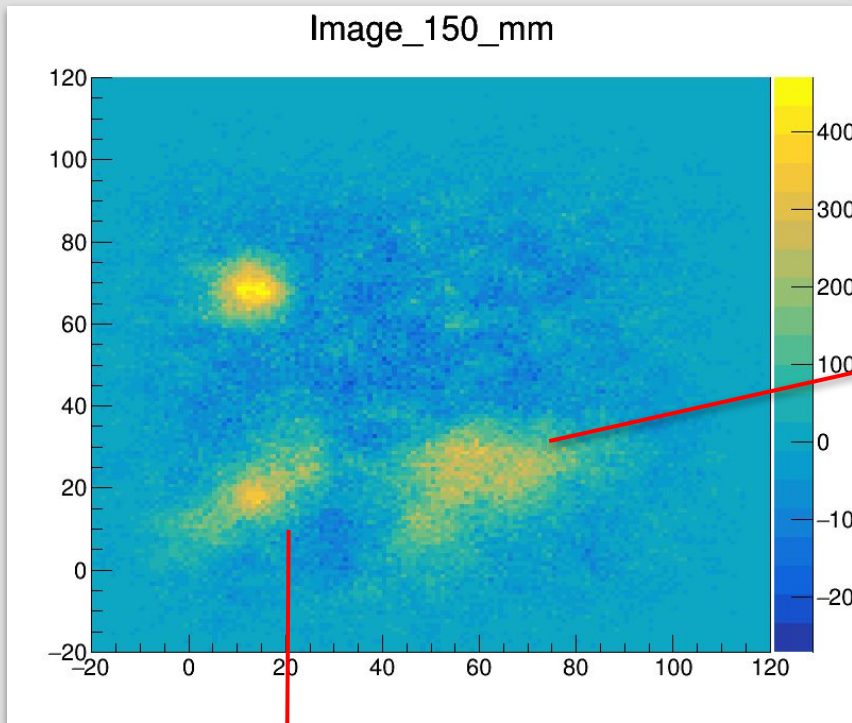
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



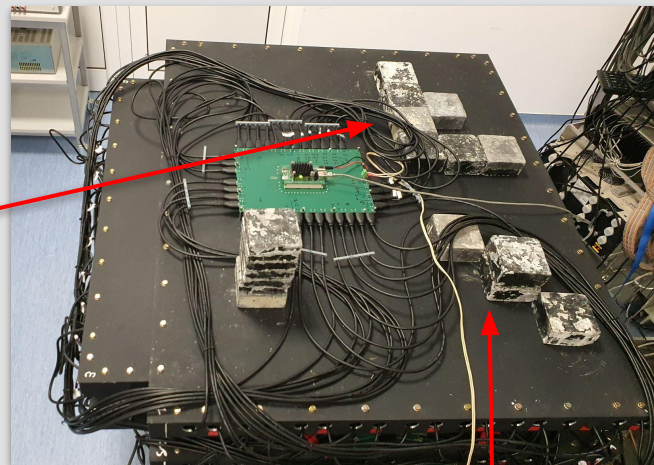
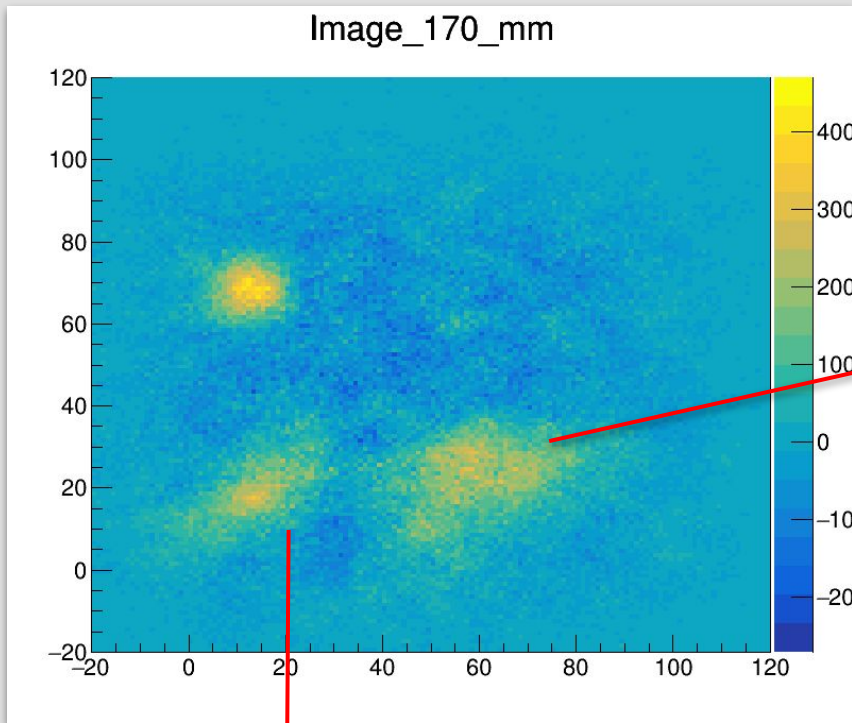
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



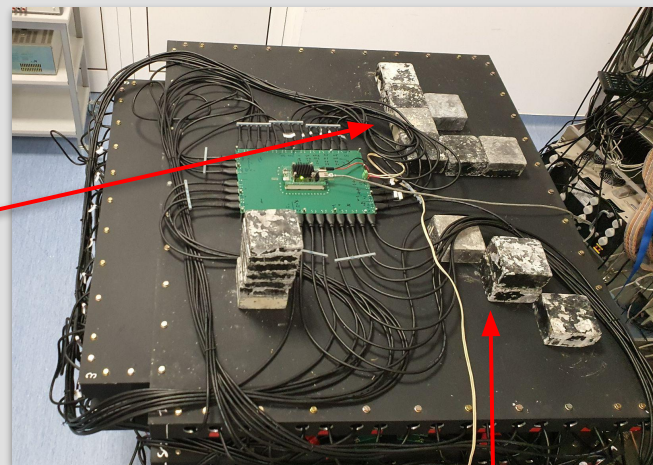
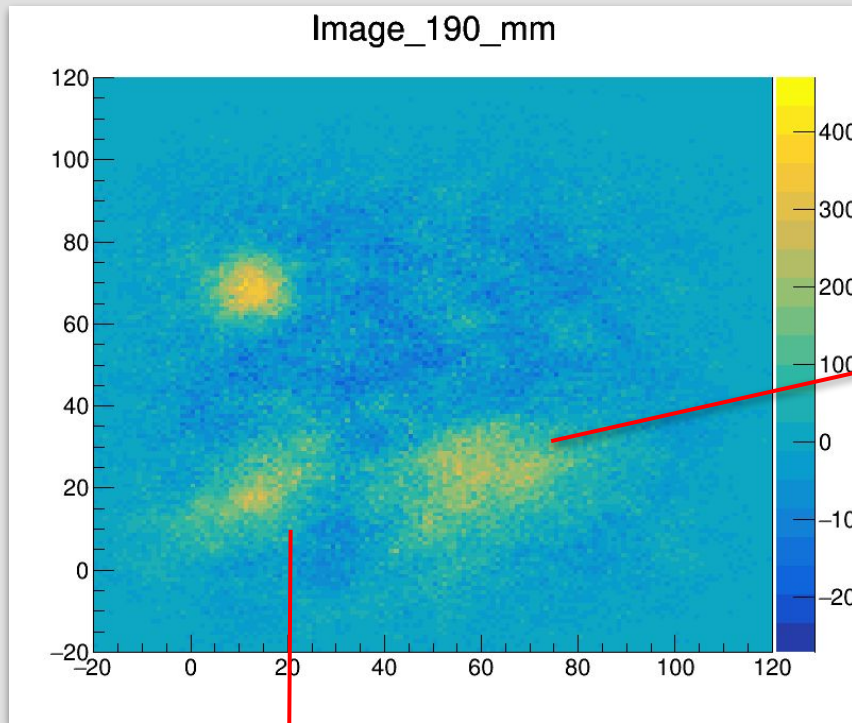
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



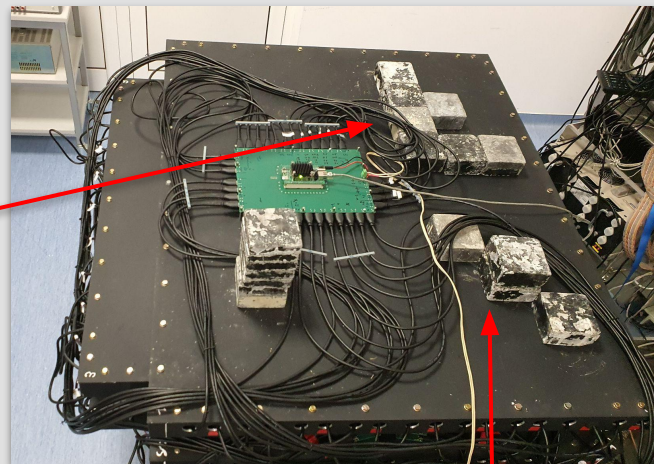
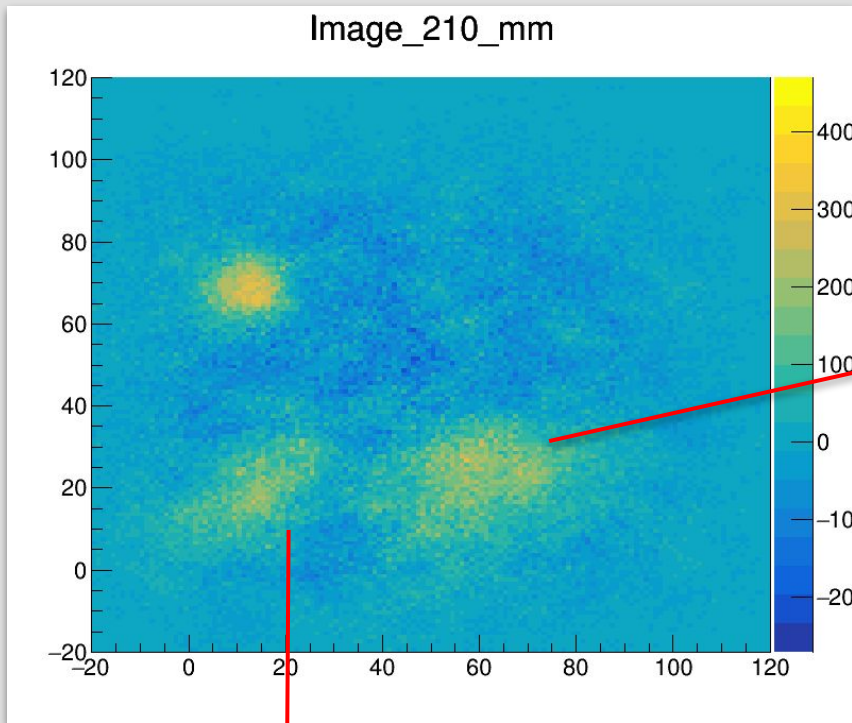
4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

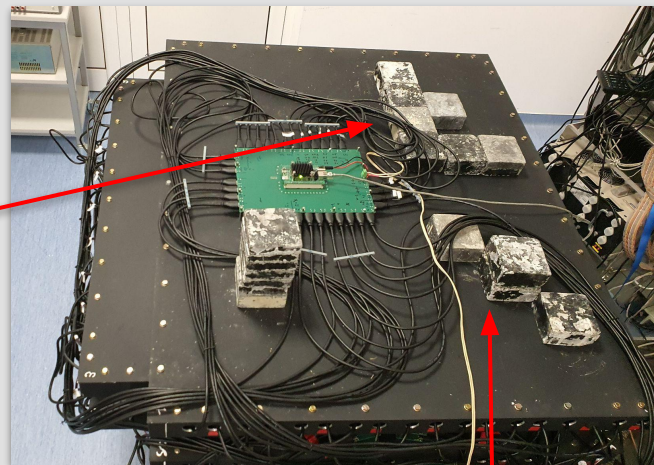
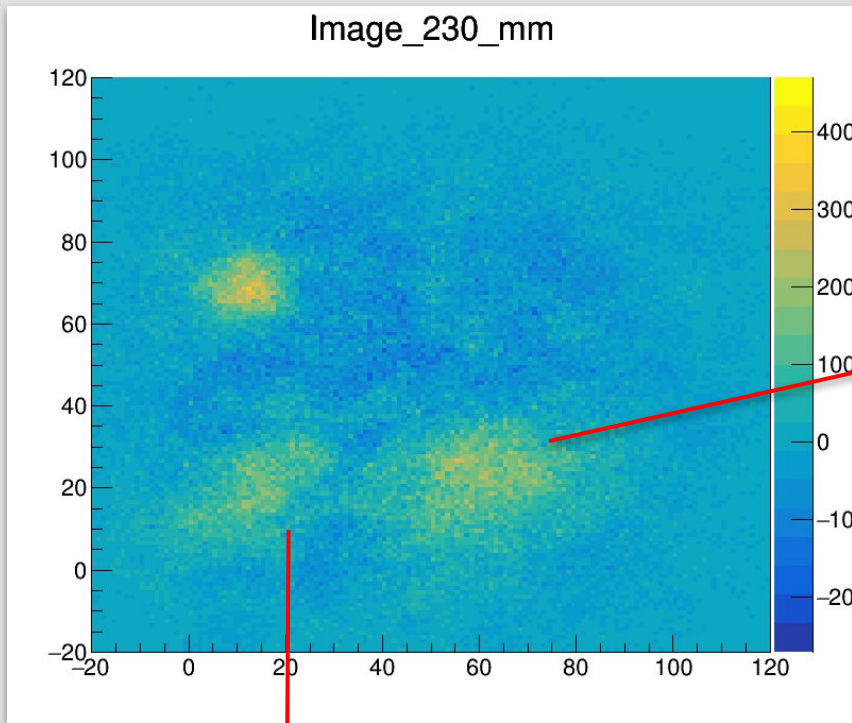


4. Preliminary reconstruction algorithm

- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

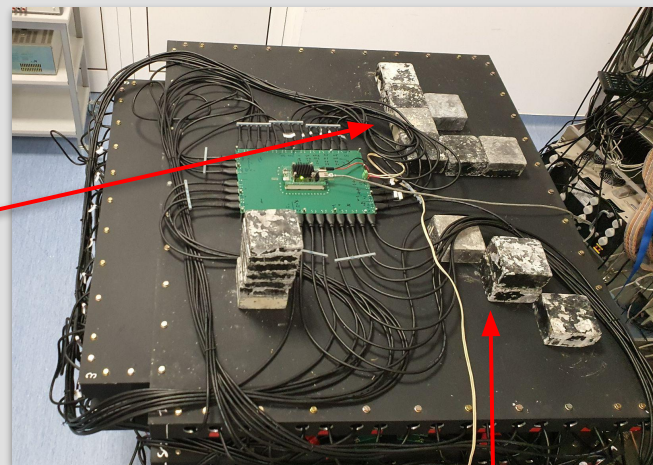
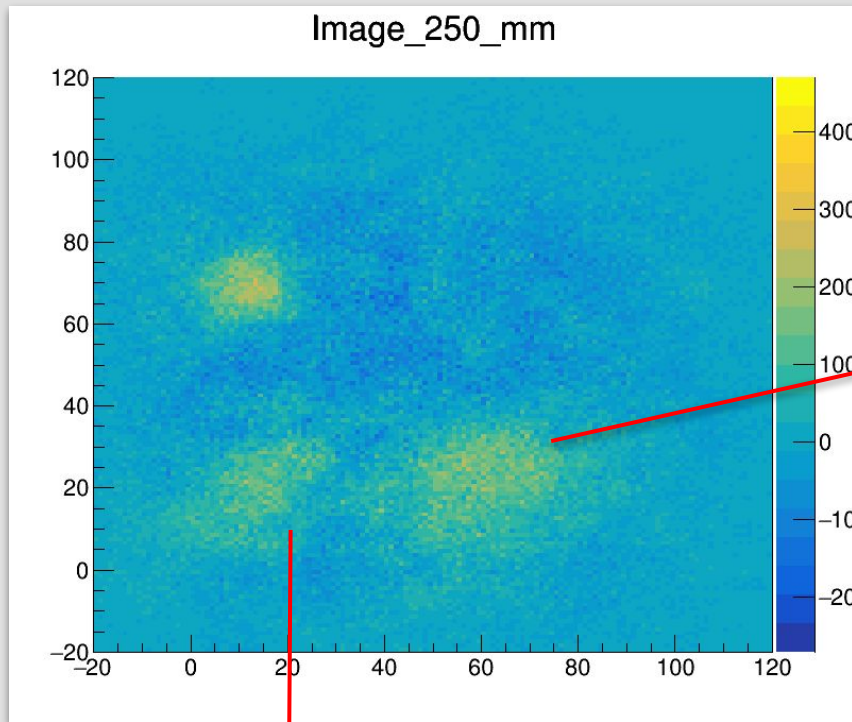


- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one

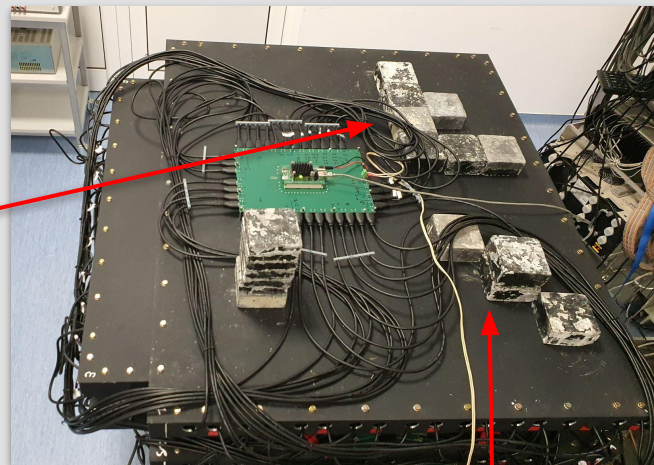
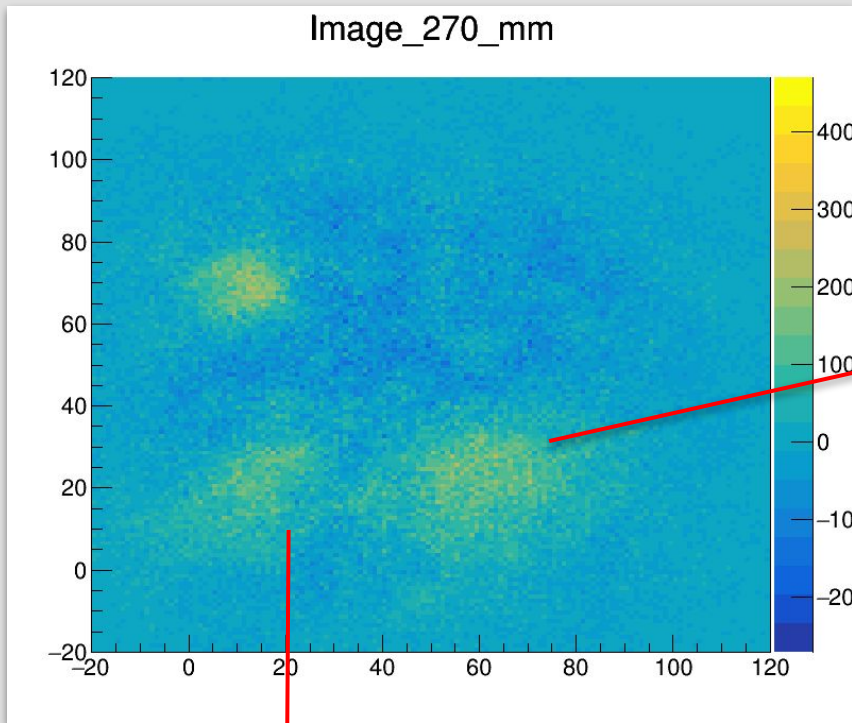


4. Preliminary reconstruction algorithm

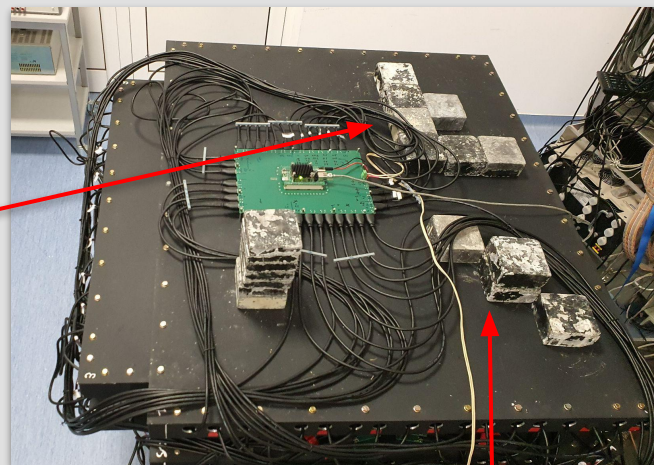
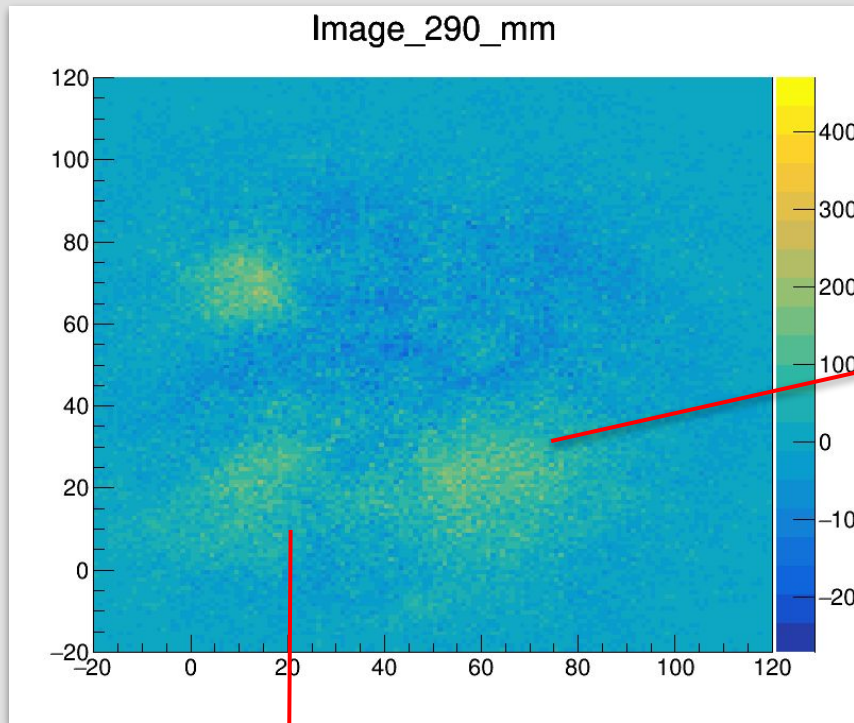
- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



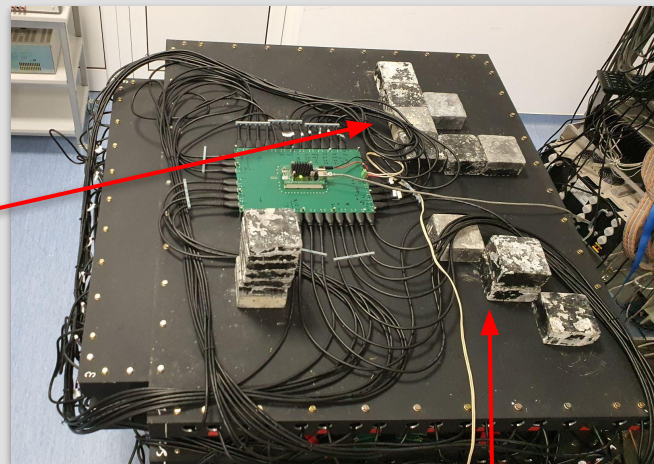
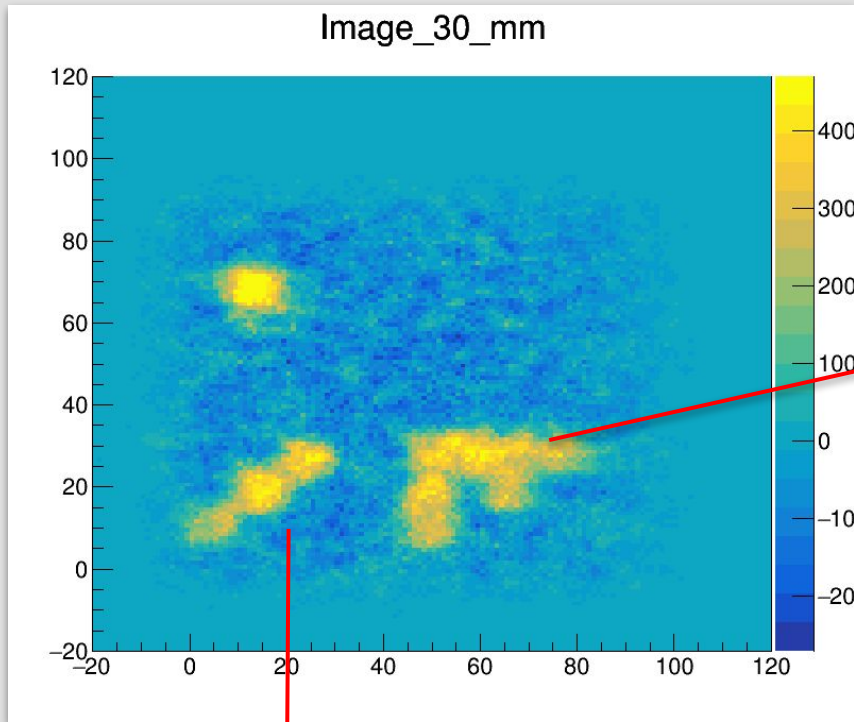
- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one



- the reconstruction algorithm makes a projection of trajectory points on different heights above the detector
- looking at reconstruction for different heights, we observe that the image is focusing as the presumed height is approaching the real one → **30 mm**



- detector has been tested in our lab
- trajectory reconstruction algorithm has minimal errors
- reconstruction method was applied on a basic set up and the results are in agreement with the predictions

CONCLUSIONS

- measurement campaigns for various applications
 - geophysical
 - archeological
 - mine safety
- develop and test other reconstruction methods
- automatic temperature stabilisation of SiPM response

OUTLOOK

Thank you for your attention!



Beware of the muons! They are constantly scanning you!